

No. 5232

LB1951V

3-phase Brushless Motor Driver for Portable VCR Capstan Use

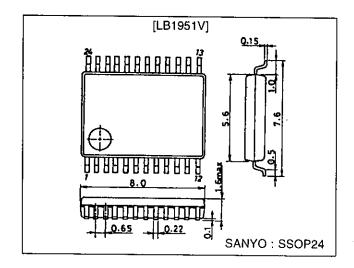
Functions

- 3-phase full-wave current linear drive system (120 ° voltage linear drive system).
- Torque ripple correction circuit built in (overlap correction).
- Speed control system using motor supply voltage control.
- FG comparator built in.
- · Thermal shutdown circuit built in.

Package Dimensions

unit: mm

3175A-SSOP24



Specifications

Absolute Maximum Ratings at Ta = 25 °C

Parameter	Symbol	Conditions	Ratings	Unit
	V _{CC} 1 max		10	
Maximum supply voltage	V _{CC} 2 max		11	V
	Vs max	≦V _{CC} 2	11	V
Applied output voltage	V _O max		V _S + 2	
Maximum output current	I _O max		1.0	A
Allowable power dissipation	Pd max	Independent IC	440	mW
Operating temperature	Topr		-20 to +75	•C
Storage temperature	Tstg		-55 to +150	<u>-</u>

Allowable Operating Ranges at Ta = 25 °C

Parameter	Symbol	Conditions	Ratings	Unit
	V _{CC} 1		2.7 to 6.0	V
Supply voltage	V _{CC} 2		3.5 to 9.0	
	Vs		to V _{CC} 2	V
Hall input amplitude	V _{HALL}	Between Hall inputs	±20 to ±80	mV ₀ -p

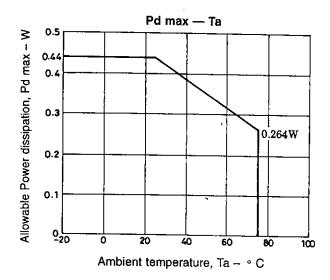
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Electrical Characteristics at Ta = 25 °C, $V_{CC}1$ = 3 V, $V_{CC}2$ = 4.75 V, V_S = 1.5 V

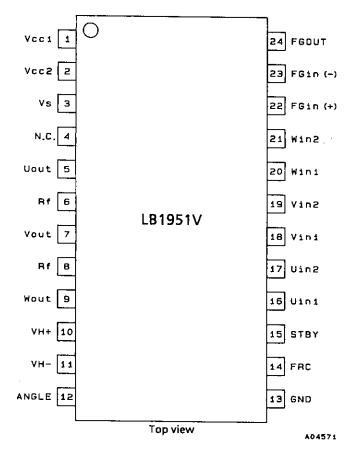
Symbol	Conditions lout = 100 mA	min	typ	max	Unit
	lout = 100 mA				
	lout = 100 mA				
l _{CC} 2			3.0	5.0	mΑ
	lout = 100 mA		7.0	10.0	mA
lccq1	V _{STBY} = 0 V		1.5	3.0	mA
lccq2	V _{STBY} = 0 V			100	μΑ
	V _{STBY} = 0 V		40		μA
			·		
V _{XH} 1	lout = 0.2 A	0.15	0.22	0.29	V
V _{XL} 1	lout = 0.2 A	0.16			V
		<u></u>			
∀ _{XH} 2	lout = 0.5 A		0.25	0.40	٧
	lout = 0.5 A				V
Vosat	- 		0120		v
O.L		70	77		%
	1		.,,	<u> </u>	
	N o			· ·	
VHOFF	Note 2	-5		+5	mV -
	Barria con o				
AHCM	H angle = 20 kΩ	0.95		2.4	V
V_{GVH}	R angle = 20 kΩ	24.5	27.5	30.5	dB
17					
VSTH		2.5			V
V _{STL}				0.4	v
	V _{STBY} = 3 V		25	40	μΑ
				-30	μA
			·····		
V _{ERCH}		2.5			V
				0.4	V
	V _{FRC} = 3 V		20	30	μA
		- .			μA
,					
V _{HALL}	$I_{H} = 5 \text{ mA}, V_{H}(+) - V_{H}(-)$	0.85	0.95	1.05	٧
V _H (–)	I _H = 5 mA	0.81	0.88	0.95	V
· · · · · ·					
V _{EGOEE}		-3		+3	mV
	$V_{EGIN}^{+} = V_{EGIN}^{-} = 1.5 \text{ V}$	<u> </u>			nA
		-100			nA
	1 Sus J Sus				V
	At internal pull-up				V
VEGOI				0.0	V
VGEG			100	J.E	dB
					mA
·rgU\$	Trial output pin to				шА
T-TSD	(Design target value) Note 2		100		°C
		 	100		-0
ΔTSD	(Design target value) Note 2		20		۰C
	V _{XH} 2 V _{XL} 2 Vosat O.L VHOFF VHCM VGVH VSTH VSTL ISTIN ISTLK VFRCH VFRCL IFRCIN IFRCLK VHALL	V _{XH} 1 Iout = 0.2 A V _{XL} 1 Iout = 0.2 A V _{XL} 2 Iout = 0.5 A Vosat Iout = 0.8 A, Sink + Source O.L R _L = 39 Ω × 3, R angle = 20 kΩ Note 1 VHOFF Note 2 VHCM R angle = 20 kΩ V _{STH} V _{STBY} = 3 V ISTIN V _{STBY} = 3 V ISTIN V _{STBY} = 0 V VFRCH V _{FRCL} I _{FRCIK} V _{FRC} = 3 V I _{FRCIK} V _{FRC} = 0 V VHALL I _H = 5 mA, V _H (+) - V _H (-) V _H (-) I _H = 5 mA V _{FGOFF} I _b G V _{FGIN} ⁺ = V _{FGIN} ⁻ = 1.5 V ΔI _b G V _{FGIN} ⁺ = V _{FGIN} ⁻ = 1.5 V ΔI _b G V _{FGIN} + V _{FGIN} = 1.5 V V _{FGOL} At internal pull-up V _{FGOL} At internal pull-up V _{GFG} (Design target) Note 2 I _{FGOS} With output pin "L" T-TSD (Design target value) Note 2	V _{XH} 1 Iout = 0.2 A 0.15 V _{XL} 1 Iout = 0.2 A 0.16 V _{XL} 2 Iout = 0.5 A V _{Sat} Iout = 0.8 A, Sink + Source O.L R _L = 39 Ω × 3, R angle = 20 kΩ Note 1 70 VHOFF Note 2 V _{HOM} R angle = 20 kΩ 0.95 V _{GVH} R angle = 20 kΩ 24.5 V _{STH} 2.5 V _{STI} I _{STIN} V _{STBY} = 3 V I _{STIN} V _{STBY} = 0 V V _{FRC} V _{FRC} V _{FRC} V _{FRC} V _{HALL} I _H = 5 mA, V _H (+) - V _H (-) 0.85 V _H (-) I _H = 5 mA 0.81 V _{FGOFF} I _{PFG} V _{FGIN} * = V _{FGIN} * = 1.5 V Δ _I _{bFG} V _{FGIN} * = V _{FGIN} * = 1.5 V Δ _I _{bFG} (Des	V _{XH} 1 Iout = 0.2 A 0.15 0.22 V _{XL} 1 Iout = 0.2 A 0.16 0.21 V _{XL} 2 Iout = 0.5 A 0.25 V _{XL} 2 Iout = 0.8 A, Sink + Source 0.25 O.L R _L = 39 Ω × 3, R angle = 20 kΩ Note 1 70 77 VHOFF Note 2 -5 -5 VHCM R angle = 20 kΩ 0.95 0.95 V _{STH} 2.5 24.5 27.5 V _{STH} 2.5 25 I _{STIN} V _{STBY} = 3 V 25 I _{STIN} V _{STBY} = 3 V 25 I _{STIL} V _{STBY} = 0 V 20 V _{FRCL} 2.5 20 I _{FRCLK} V _{FRC} = 3 V 20 I _{FRCLK} V _{FRC} = 0 V 20 V _{HALL} I _H = 5 mA, V _H (+) - V _H (-) 0.85 0.95 V _H (-) I _H = 5 mA 0.81 0.88 V _{FG} (-) I _H = 5 mA 0.81 0.88 V _{FG} (-) I _H = 5 mA 0.81 0.89	V _{XH} 1 lout = 0.2 A 0.15 0.22 0.28 V _{XL} 1 lout = 0.2 A 0.16 0.21 0.28 V _{XL} 2 lout = 0.5 A 0.25 0.40 V _{XL} 2 lout = 0.8 A, Sink + Source 1.40 O.L R _L = 39 Ω × 3, R angle = 20 kΩ Note 1 70 77 84 VHOFF Note 2 -5 +5 V _{HCM} R angle = 20 kΩ 0.95 2.4 V _{GVH} R angle = 20 kΩ 24.5 27.5 30.5 V _{STH} 2.5

Note 1: Overlapping specifications are assumed to be test specifications.

Note 2: For parameters which have an entry of (Design target value) in the "Conditions" column, no measurements are made.



Pin Assignment



Pin Functions

Pin No.	Pin name	I/O equivalent circuit	Function
1	V _{CC} 1		Power supply pin for supplying power to all circuits except amplitude control section in output section in IC.
2	V _{CC} 2		Power supply pin for supplying power to all circuits of the amplitude control section and the output control section in IC.
3	V _S		Power supply pin for motor drive. Apply a voltage of $V_{CC}2$ or lower to this pin.
5 7	U-OUT V-OUT	2 Vcc2	
9	W-OUT	3 Vs 5 U-DUT 7 V-OUT	U-phase output pin V-phase output pin W-phase output pin (Spark killer diode built in)
6, 8	Rf	9 W-OUT	Pin for grounding output power transistor.
		6 Rf B	
10	VH+ VH-	Approx. 0.9 V (13) VH-	Pins for supplying the Hall element bias voltage. Voltage of 0.95 V (typ.) is generated between VH+ and VH (when I _H = 5 mA)
12	ANGLE	20kg	Pins for controlling the Hall input-output gain. The gain is controlled by a resistor between this pin and GND.
16 17 18 19 20 21	Uin1 Uin2 Vin1 Vin2 Win1 Win2	1.2YYYP	U-phase Hall element input pin; Logic "H" represents IN* > IN*. V-phase Hall element input pin; Logic "H" represents IN* > IN*. W-phase Hall element input pin; Logic "H" represents IN* > IN*.
13	GND		Pin for grounding other than output transistors. Minimum potential of output transistors is equal to the level at Rf pin.
14	FRC	Vcc1	Forward/reverse select pin. The voltage on this pin is used for forward/reverse select. (with Hysteresis)
15	STBY	100kg 100kg 100kg 100kg	Pin for selecting the bias supply for all circuits except the FG comparator. "L" level on this pin cuts the bias supply.

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Pin No.	Pin name	I/O equivalent circuit	Function		
22	FGin+	15k0 ₹20k0	Noninverting input pin for the FG comparator. No bias is applied internally.		
23	FGin-	FGin- 23 2000 2000 22000 230000 2300000 230000 23000000 23000 23000 23000 23000 23000 23000 23000 23000 23000 23000 2300000000	Inverting input pin for the FG comparator. No bias is applied internally.		
24	FGout	50k D \$	FG comparator output pin. A resistive load of 20 $k\Omega$ is provided internally.		

Truth Table

	Source → Sink		Hall inpu	t	500	
	Oddice - Silik	υ	V	W	FRC	
1	$V \rightarrow W$	н	Н	L	Н	
	W → V	<u> </u>			L	
2	U → Ŵ	Н	L	L	Н	
	$W \rightarrow U$				L	
3	$U \rightarrow V$	H	L	н	Н	
	V → U]_''			L	
4	$V \rightarrow V$		L	н	Н	
	$V \rightarrow W$				L	
5	W → U		L H	н	Н	
	$U \rightarrow W$	-			L	
6	$V \rightarrow U$	L	H	_	Н	
	U → V			-	L	

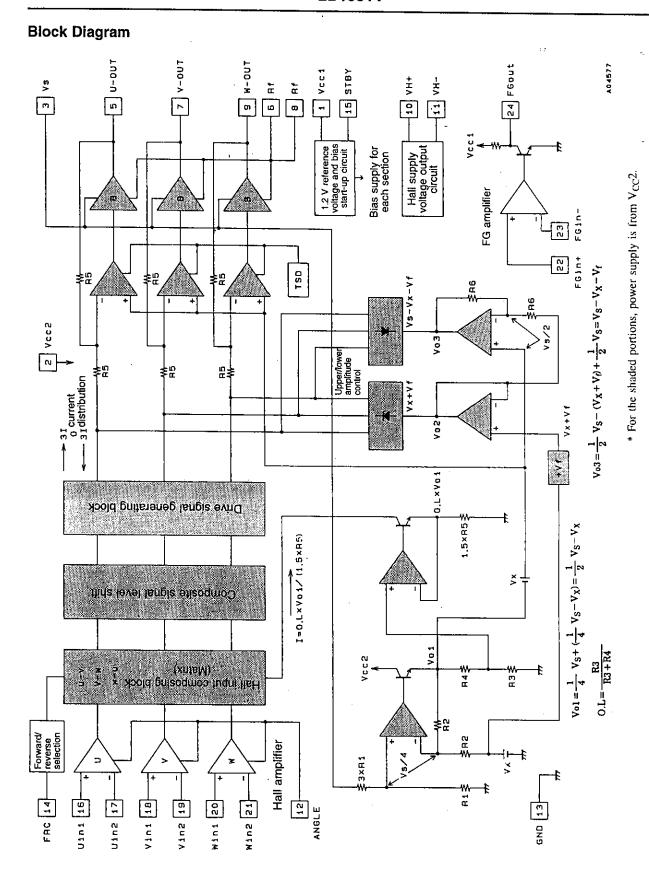
Note: "H" in the FRC column represents a voltage of 2.5 V or more; "L" represents a voltage of 0.4 V or less.

(At V_{CC}1 = 3 V)

Note: "H" in the Hall input columns represents a state in

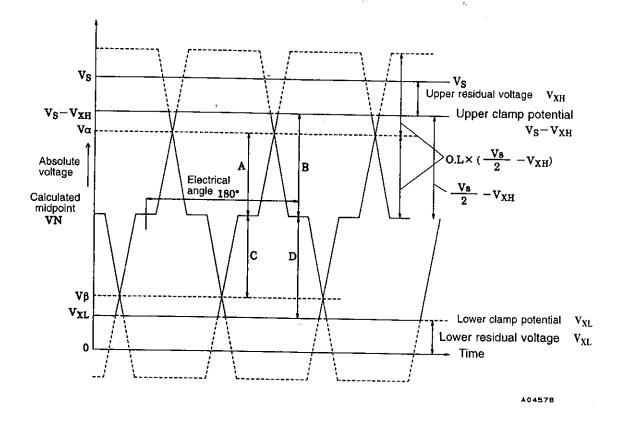
which "+" has a potential which is higher by 0.02 V or more than that of the "-" phase inputs.

Conversely, "L" represents a state in which "+" has a potential which is lower by 0.02 V or more than that of the "-" phase input.



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Overlap Creation and Calculation



i) Overlap creation

Because the voltage generated in the amplitude controller is: $2 \times O.L. \times (1/2 V_S - V_X)$ for each side, (using the midpoint as the reference point), the point at which the two waveforms cross each other is O.L. $(1/2 V_S - V_X)$ from the midpoint.

Because that waveform is clamped at $(1/2 V_S - V_X)$ with the midpoint as the reference point, the overlap equals A/B × 100, which equals O.L. × 100 (%).

ii) Overlap calculation

(1) Upper overlap amount

Calculated midpoint VN =
$$\frac{(V_S - V_{XH} - V_{XL})}{2} + V_{XL} = \frac{(V_S - V_{XH} + V_{XL})}{2}$$

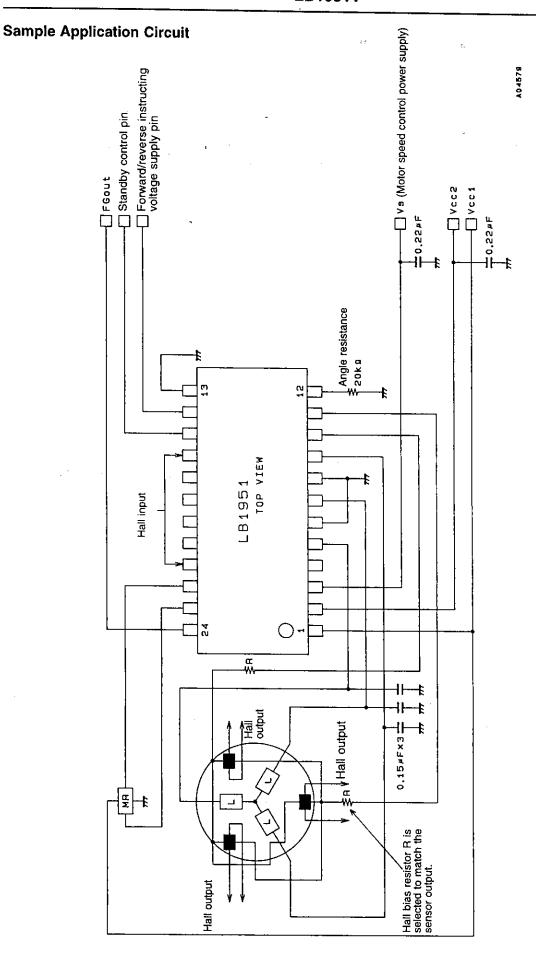
Because $A = V\alpha - VN$ and $B = V_S - V_{XH} - VN$, the upper overlap amount is calculated as follows:

Overlap amount =
$$\frac{A}{B}$$
 = $\frac{V\alpha - \{(V_S - V_{XH} + V_{XL})/2\}}{V_S - V_{XH} - \{(V_S - V_{XH} + V_{XL})/2\}} \times 100$
 = $\frac{2V\alpha - (V_S - V_{XH}) - V_{XL}}{(V_S - V_{XH}) - V_{XL}} \times 100 (\%)$

(2) Lower overlap amount

Because $C = VN - V\beta$ and $D = VN - V_{XL}$, the lower overlap amount is calculated as follows:

Overlap amount =
$$\frac{C}{D}$$
 = $\frac{\{(V_S - V_{XH} + V_{XL})/2\} - V\beta}{\{(V_S - V_{XH} + V_{XL})/2\} - V_{XL}} \times 100}$
= $\frac{(V_S - V_{XH}) + V_{XL} - 2V\beta}{(V_S - V_{XH}) - V_{XL}} \times 100 (\%)$



Note: It should be noted that the constants specified herein are for example only, with no guarantee for characteristics implied.

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