Advance Information

64K x 18 Bit BurstRAM Synchronous Fast Static RAM

With Burst Counter and Self-Timed Write

The MCM67M618B is a 1,179,648 bit synchronous static random access memory designed to provide a burstable, high–performance, secondary cache for the MC68040 and PowerPC™ microprocessors. It is organized as 65,536 words of 18 bits, fabricated using Motorola's high–performance silicon–gate BiCMOS technology. The device integrates input registers, a 2–bit counter, high speed SRAM, and high drive capability outputs onto a single monolithic circuit for reduced parts count implementation of cache data RAM applications. Synchronous design allows precise cycle control with the use of an external clock (K). BiCMOS circuitry reduces the overall power consumption of the integrated functions for greater reliability.

Addresses (A0 – A15), data inputs (DQ0 – DQ17), and all control signals, except output enable (G), are clock (K) controlled through positive–edge–triggered noninverting registers.

Bursts can be initiated with either transfer start processor (TSP) or transfer start cache controller (TSC) input pins. Subsequent burst addresses are generated internally by the MCM67M618B (burst sequence imitates that of the MC68040) and controlled by the burst address advance (BAA) input pin. The following pages provide more detailed information on burst controls.

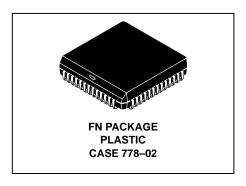
Write cycles are internally self-timed and are initiated by the rising edge of the clock (K) input. This feature eliminates complex off-chip write pulse generation and provides increased flexibility for incoming signals.

Dual write ena<u>bles</u> (LW and UW) are provided to allow individu<u>ally</u> writeable bytes. LW controls DQ0 – DQ8 (the lower bits), while UW controls DQ9 – DQ17 (the upper bits).

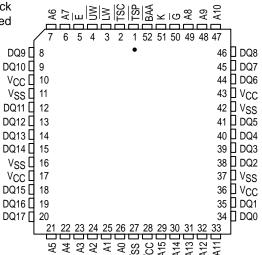
This device is ideally suited for systems that require wide data bus widths and cache memory.

- Single 5 V ± 5% Power Supply
- Fast Access Times: 9/10/12 ns Max
- Byte Writeable via Dual Write Strobes
- Internal Input Registers (Address, Data, Control)
- Internally Self-Timed Write Cycle
- TSP, TSC, and BAA Burst Control Pins
- Asynchronous Output Enable Controlled Three-State Outputs
- Common Data Inputs and Data Outputs
- High Board Density 52–PLCC Package
- 3.3 V I/O Compatible

MCM67M618B



PIN ASSIGNMENT



PIN NAMES
A0 - A15 Address Inputs K Clock BAA Burst Address Advance LW Lower Byte Write Enable UW Upper Byte Write Enable TSP, TSC Transfer Start E Chip Enable G Output Enable DQ0 - DQ17 Data Input/Output VCC + 5 V Power Supply VSS Ground

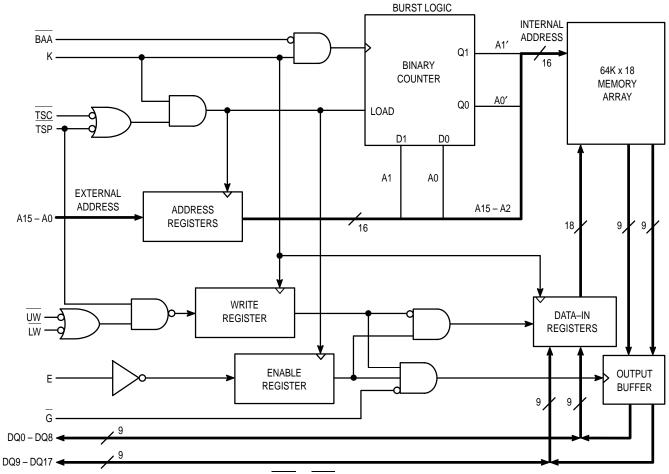
All power supply and ground pins must be connected for proper operation of the device.

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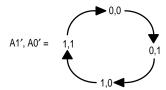




NOTE: All registers are positive-edge triggered. The TSC or TSP signals control the duration of the burst and the start of the next burst. When TSP is sampled low, any ongoing burst is interrupted and a read (independent of W and TSC) is performed using the new external address. Alternatively, a TSP-initiated two cycle WRITE can be performed by asserting TSP and a valid address on the first cycle, then negating both TSP and TSC and asserting LW and/or UW with valid data on the second cycle (see Single Write Cycle in WRITE CYCLES timing diagram).

When TSC is sampled low (and TSP is sampled high), any ongoing burst is interrupted and a read or write (dependent on W) is performed using the new external address. Chip enable (E) is sampled only when a new base address is loaded. After the first cycle of the burst, BAA controls subsequent burst cycles. When BAA is sampled low, the internal address is advanced prior to the operation. When BAA is sampled high, the internal address is not advanced, thus inserting a wait state into the burst sequence accesses. Upon completion of a burst, the address will wrap around to its initial state. See BURST SEQUENCE TABLE. Write refers to either or both byte write enables (LW, UW).

BURST SEQUENCE GRAPH (See Note)



NOTE: The external two values for A1 and A0 provide the starting point for the burst sequence graph. The burst logic advances A1 and A0 as shown above.

MCM67M618B MOTOROLA FAST SRAM

SYNCHRONOUS TRUTH TABLE (See Notes 1, 2, and 3)

E	TSP	TSC	BAA	LW or UW	K	Address	Operation
Н	L	Х	Х	Х	L–H	N/A	Deselected
Н	Х	L	Х	Х	L–H	N/A	Deselected
L	L	Х	Х	Х	L–H	External Address	Read Cycle, Begin Burst
L	Н	L	Х	L	L–H	External Address	Write Cycle, Begin Burst
L	Н	L	Х	Н	L–H	External Address	Read Cycle, Begin Burst
Х	Н	Н	L	L	L–H	Next Address	Write Cycle, Continue Burst
Х	Н	Н	L	Н	L–H	Next Address	Read Cycle, Continue Burst
Х	Н	Н	Н	L	L–H	Current Address	Write Cycle, Suspend Burst
Х	Н	Н	Н	Н	L–H	Current Address	Read Cycle, Suspend Burst

NOTES:

- 1. X means Don't Care.
- 2. All inputs except G must meet setup and hold times for the low-to-high transition of clock (K).
- 3. Wait states are inserted by suspending burst.

ASYNCHRONOUS TRUTH TABLE (See Notes 1 and 2)

Operation	G	I/O Status	
Read	ad L Data Out		
Read	Н	High–Z	
Write	te X High–Z — Data In		
Deselected	Х	High–Z	

NOTES:

- 1. X means Don't Care.
- 2. For a write operation following a read operation, \overline{G} must be high before the input data required setup time and held high through the input data hold time.

ABSOLUTE MAXIMUM RATINGS (Voltages Referenced to $V_{SS} = 0 \text{ V}$)

Rating	Symbol	Value	Unit
Power Supply Voltage	Vcc	- 0.5 to + 7.0	V
Voltage Relative to V _{SS} for Any Pin Except V _{CC}	V _{in} , V _{out}	- 0.5 to V _{CC} + 0.5	V
Output Current (per I/O)	l _{out}	± 30	mA
Power Dissipation	PD	1.6	W
Temperature Under Bias	T _{bias}	- 10 to + 85	°C
Ambient Temperature	TA	0 to +70	°C
Storage Temperature	T _{stg}	– 55 to + 125	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPER-ATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high–impedance circuit.

This BiCMOS memory circuit has been designed to meet the dc and ac specifications shown in the tables, after thermal equilibrium has been established.

This device contains circuitry that will ensure the output devices are in High–Z at power up.

DC OPERATING CONDITIONS AND CHARACTERISTICS

 $(V_{CC} = 5.0 \text{ V} \pm 5\%, T_A = 0 \text{ to} + 70^{\circ}\text{C}, \text{Unless Otherwise Noted})$

RECOMMENDED OPERATING CONDITIONS (Voltages Referenced to $V_{SS} = 0 V$)

Parameter	Symbol	Min	Max	Unit
Supply Voltage (Operating Voltage Range)	Vcc	4.75	5.25	V
Input High Voltage	VIH	2.2	V _{CC} + 0.3**	V
Input Low Voltage	V _{IL}	- 0.5*	0.8	V

DC CHARACTERISTICS AND SUPPLY CURRENTS

Parameter	Symbol	Min	Max	Unit
Input Leakage Current (All Inputs, V _{in} = 0 to V _{CC})	l _{lkg(l)}	_	± 1.0	μΑ
Output Leakage Current (G = V _{IH})	l _{lkg(O)}	_	± 1.0	μΑ
AC Supply Current (Device Selected, All Outputs Open, Freq = Max) MCM67M618B-1 MCM67M618B-1		_	TBD	mA
CMOS Standby Supply Current (Device Deselected, Freq = 0, V_{CC} = Max, All Inputs Static at CMOS Levels $V_{in} \le V_{SS} + 0.2 \text{ V or } \ge V_{CC} - 0.2 \text{ V}$)	I _{SB2}	_	TBD	mA
Clock Running (Device Deselected, Freq = Max, V_{CC} = Max, All Inputs Toggling at CMOS Levels $V_{in} \le V_{SS} + 0.2 \text{ V or } \ge V_{CC} - 0.2 \text{ V}$)	I _{SB4}	_	TBD	mA
Output Low Voltage (I _{OL} = + 8.0 mA)	V _{OL}	_	0.4	V
Output High Voltage (I _{OH} = - 4.0 mA)	VOH	2.4	3.3	V

NOTE: Good decoupling of the local power supply should always be used. DC characteristics are guaranteed for all possible 68040 and PowerPC bus cycles.

$\textbf{CAPACITANCE} \; (\text{f} = 1.0 \; \text{MHz}, \; \text{dV} = 3.0 \; \text{V}, \; \text{T}_{\mbox{A}} = 25 ^{\circ} \mbox{C}, \; \text{Periodically Sampled Rather Than 100\% Tested)} \; \\$

Parameter	Symbol	Min	Тур	Max	Unit
Input Capacitance	C _{in}		4	5	pF
Input/Output Capacitance	C _{I/O}		6	8	pF

 $[\]label{eq:VIL} \begin{subarray}{l} *V_{IL} (min) = -0.5 \ V \ dc; \ V_{IL} (min) = -2.0 \ V \ ac \ (pulse \ width \le 20.0 \ ns) \ for \ I \le 20.0 \ mA. \\ \begin{subarray}{l} *^*$V_{IH} (max) = V_{CC} + 0.3 \ V \ dc; \ V_{IH} \ (max) = V_{CC} + 2.0 \ V \ ac \ (pulse \ width \le 20.0 \ ns) \ for \ I \le 20.0 \ mA. \\ \end{subarray}$

AC OPERATING CONDITIONS AND CHARACTERISTICS

 $(V_{CC} = 5.0 \text{ V} \pm 5\%, \text{ T}_{A} = 0 \text{ to} + 70^{\circ}\text{C}, \text{ Unless Otherwise Noted})$

Input Timing Measurement Reference Level 1.5 V	Output Timing Reference Level 1.5 V
Input Pulse Levels 0 to 3.0 V	Output Load See Figure 1 Unless Otherwise Noted
Input Rise/Fall Time	

READ/WRITE CYCLE TIMING (See Notes 1, 3, and 4)

			MCM67M618B-9		MCM67N	l618B-10	MCM67M618B-12			
Parameter		Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Cycle Time		tKHKH	15	_	16.6	_	20	_	ns	
Clock Access Time		tKHQV	_	9	_	10	_	12	ns	5
Output Enable to Output Val	d	tGLQV	_	5	_	5	_	6	ns	
Clock High to Output Active		tKHQX1	6	_	6	_	6	_	ns	
Clock High to Output Chang	е	tKHQX2	3	_	3	_	3	_	ns	
Output Enable to Output Act	ive	^t GLQX	0	_	0	_	0	_	ns	
Output Disable to Q High–Z		^t GHQZ	_	6	_	7	_	7	ns	6
Clock High to Q High–Z		^t KHQZ	3	6	3	7	3	7	ns	6
Clock High Pulse Width		^t KHKL	5	_	5	_	6	_	ns	
Clock Low Pulse Width		^t KLKH	5	_	5	_	6	_	ns	
Address	ata In Write vance	tavkh ttsvkh tovkh twvkh tbavkh tevkh	2.5	_	2.5	_	2.5	_	ns	7
Address	ata In Write vance	†KHAX †KHTSX †KHDX †KHWX †KHBAX †KHEX	0.5	_	0.5	_	0.5	_	ns	7

NOTES:

- 1. In setup and hold times, W (write) refers to either one or both byte write enables LW and UW.
- 2. A read cycle is defined by UW and LW high or TSP low for the setup and hold times. A write cycle is defined by LW or UW low and TSP high for the setup and hold times.
- 3. All read and write cycle timings are referenced from K or G.
- 4. G is a don't care when UW or LW is sampled low.
- 5. Maximum access times are guaranteed for all possible MC68040 and PowerPC external bus cycles.
- 6. Transition is measured ± 500 mV from steady-state voltage. This parameter is sampled rather than 100% tested. At any given voltage and temperature, t_{KHQZ1} max is less than t_{KHQZ1} min for a given device and from device to device.
- 7. This is a synchronous device. All addresses must meet the specified setup and hold times for **ALL** rising edges of K whenever TSP or TSC is low, and the chip is selected. All other synchronous inputs must meet the specified setup and hold times for **ALL** rising edges of K when the chip is enabled. Chip enable must be valid at each rising edge of clock for the device (when TSP or TSC is low) to remain enabled.

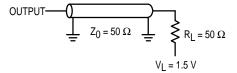
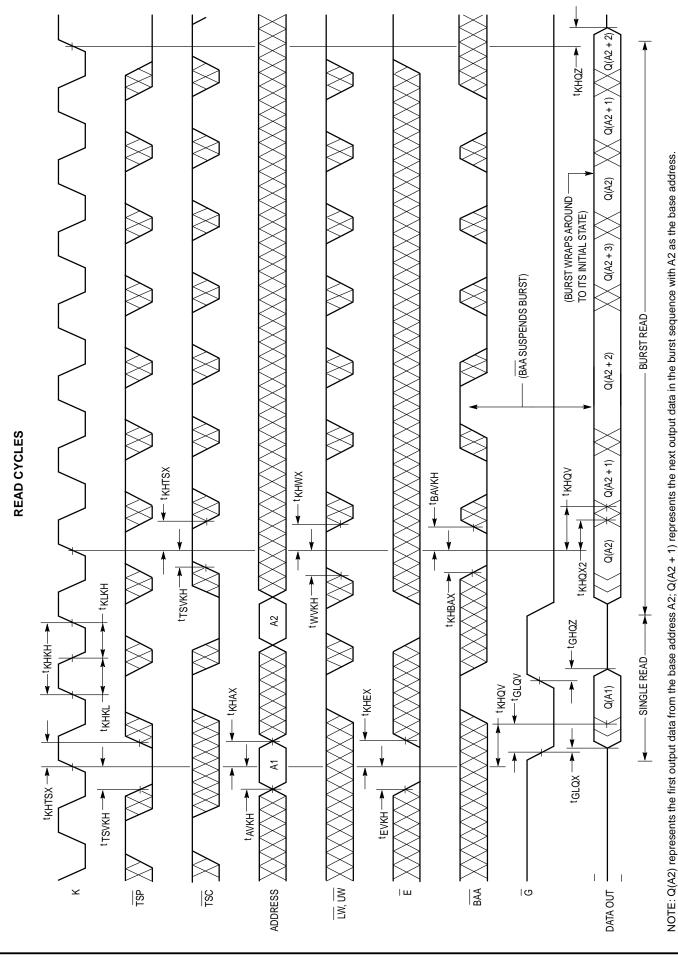
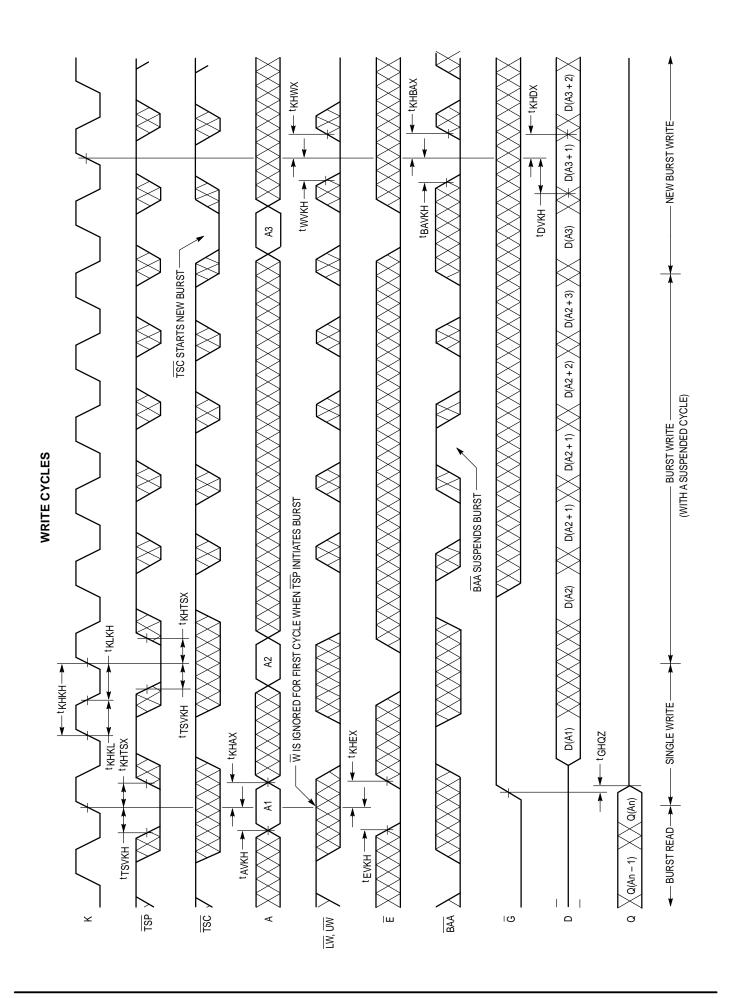


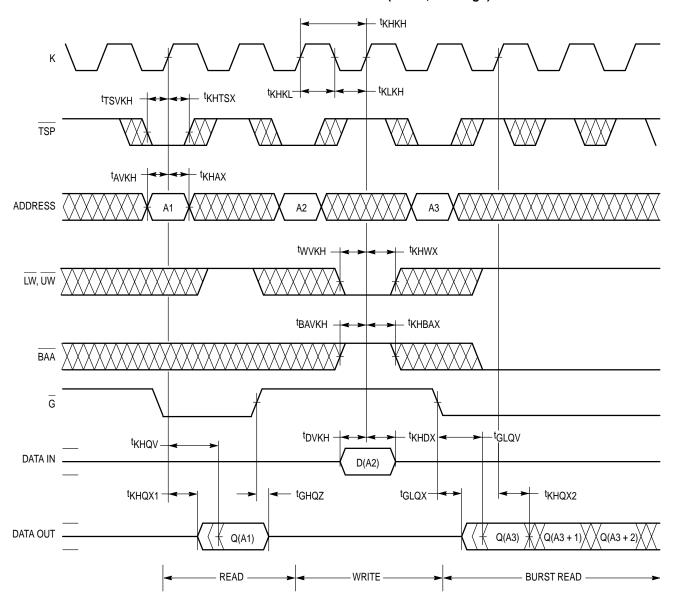
Figure 1.Test Load



MOTOROLA FAST SRAM

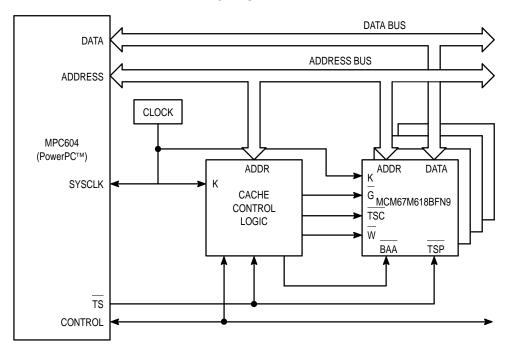


COMBINATION READ/WRITE CYCLE (E Low, TSC High)



MCM67M618B MOTOROLA FAST SRAM

APPLICATION EXAMPLE



512K Byte Burstable, Secondary Cache
Using Four MCM67M618BFN9s with a 66 MHz MPC604 PowerPC™

Figure 2.

ORDERING INFORMATION (Order by Full Part Number)

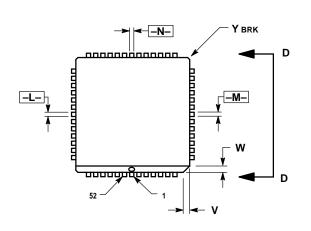
<u> </u>	MÇM_	67M618B	<u>XX</u>	<u> </u>	
Motorola Memory Prefix ————				Speed (9 = 9 ns, 10 = 10 ns, 12 = 12 n	າຣ)
Part Number				Package (FN = PLCC)	

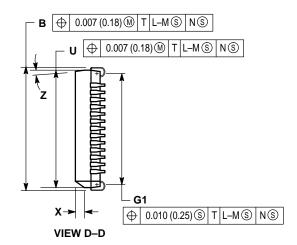
Full Part Numbers — MCM67M618BFN9 MCM67M618BFN10 MCM67M618BFN12

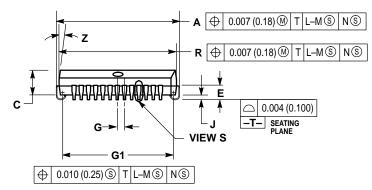
MCM67M618B MOTOROLA FAST SRAM

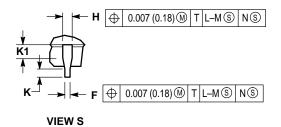
PACKAGE DIMENSIONS

FN PACKAGE 52-LEAD PLCC CASE 778-02









- NOTES:

 1. DATUMS -L-, -M-, AND -N- DETERMINED WHERE TOP OF LEAD SHOULDER EXITS PLASTIC BODY AT MOLD PARTING LINE.
- 2. DIMENSION G1, TRUE POSITION TO BE MEASURED AT DATUM -T-, SEATING PLANE.

 3. DIMENSIONS R AND U DO NOT INCLUDE MOLD
- FLASH. ALLOWABLE MOLD FLASH IS 0.010 (0.250) PER SIDE.
- 4. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- 5. CONTROLLING DIMENSION: INCH.
 6. THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOTTOM BY UP TO 0.012 (0.300).
 DIMENSIONS R AND U ARE DETERMINED AT THE
 OUTERMOST EXTREMES OF THE PLASTIC BODY
 EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD FLASH, BUT INCLUDING
- BURKS AND IN ERLEAD FASTS, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.

 7. DIMENSION H DOES NOT INCLUDE DAMBAR PROTRUSION OR INTRUSION. THE DAMBAR PROTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE GREATER THAN 0.037 (0.940). THE DAMBAR INTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE SMALLER THAN 0.025 (0.635).

	INC	HES	MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.785	0.795	19.94	20.19
В	0.785	0.795	19.94	20.19
С	0.165	0.180	4.20	4.57
Е	0.090	0.110	2.29	2.79
F	0.013	0.019	0.33	0.48
G	0.050	BSC	1.27	BSC
Н	0.026	0.032	0.66	0.81
J	0.020		0.51	
K	0.025		0.64	
R	0.750	0.756	19.05	19.20
U	0.750	0.756	19.05	19.20
٧	0.042	0.048	1.07	1.21
W	0.042	0.048	1.07	1.21
Х	0.042	0.056	1.07	1.42
Υ	_	0.020	-	0.50
Z	2 °	10°	2°	10°
G1	0.710	0.730	18.04	18.54
K1	0.040		1.02	

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MCM67M618B/D