

24-Bit, Multi-Standard D/A Converter for Digital Audio

Features

- 24 Bit Conversion
- Up to 192 kHz Sample Rates
- 120 dB Dynamic Range
- -100 dB THD+N
- Supports PCM, DSD and External Interpolation filters
- Advanced Dynamic-Element Matching
- Low Clock Jitter Sensitivity
- Digital De-emphasis for 32 kHz, 44.1 kHz and 48 kHz
- External Reference Input

Description

The CS4397 is a complete high performance 24-bit 48/96/192 kHz stereo digital-to-analog conversion system. The device includes a digital interpolation filter followed by a oversampled multi-bit delta-sigma modulator which drives dynamic-element-matching (DEM) selection logic. The output from the DEM block controls the input to a multi-element switched capacitor DAC/low-pass filter, with fully-differential outputs. This multi-bit architecture features significantly lower out-of-band noise and jitter sensitivity than traditional 1-bit designs, and the advanced DEM guarantees low noise and distortion at all signal levels.

ORDERING INFORMATION

| | | |
|-----------|---------------|---------------------|
| CS4397-KS | -10° to 70° C | 28-pin Plastic SOIC |
| CDB4397 | | Evaluation Board |

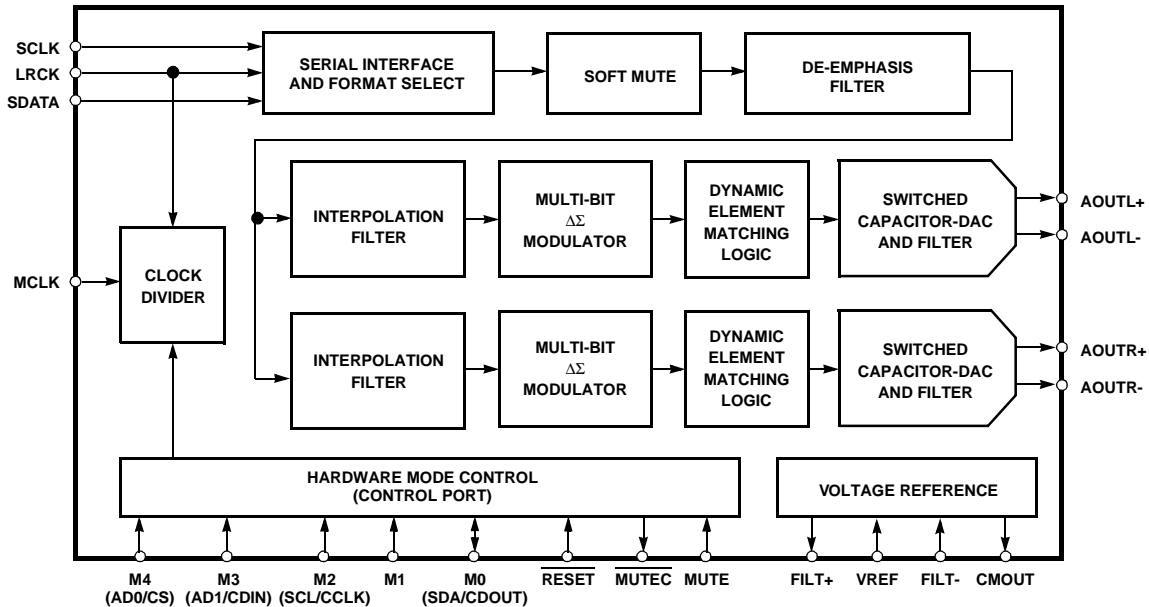


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<http://www.cirrus.com/corporate/contacts/>

"The I²C-Bus Specification: Version 2.0" Philips Semiconductors, December 1998.
<http://www.semiconductors.philips.com>

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1.0 CHARACTERISTICS/SPECIFICATIONS
ANALOG CHARACTERISTICS

($T_A = 25\text{ }^\circ\text{C}$; Logic "1" = $V_D = 5\text{ V}$; $V_A = 5\text{ V}$; Logic "0" = DGND;
 Full-Scale Output Sine Wave, 997 Hz; MCLK = 12.288 MHz; SCLK = 3.072 MHz, Measurement Bandwidth 10 Hz to 20 kHz, unless otherwise specified. Test load $R_L = 1\text{ k}\Omega$, $C_L = 10\text{ pF}$)

| Parameter | Symbol | Min | Typ | Max | Unit | |
|---|------------------------|-------|-----|------|------|----|
| Dynamic Performance - Single Speed Mode - F_s equal to 48 kHz | | | | | | |
| Dynamic Range 24-Bit (Note 2) | (Note 1) unweighted | TBD | 117 | - | dB | |
| | A-Weighted | TBD | 120 | - | dB | |
| | unweighted | - | 95 | - | dB | |
| | A-Weighted | - | 98 | - | dB | |
| Total Harmonic Distortion + Noise 24-Bit (Note 2) | (Note 1) 0 dB | THD+N | - | -100 | TBD | dB |
| | -20 dB | | - | -97 | TBD | dB |
| | -60 dB | | - | -57 | TBD | dB |
| | 16-Bit 0 dB | | - | -95 | - | dB |
| | -20 dB | | - | -75 | - | dB |
| | -60 dB | | - | -35 | - | dB |
| Dynamic Performance - Double Speed Mode - F_s equal to 96 kHz | | | | | | |
| Dynamic Range 24-Bit 40 kHz bandwidth 16-Bit (Note 2) | (Note 1) unweighted | TBD | 117 | - | dB | |
| | A-Weighted | TBD | 120 | - | dB | |
| | unweighted | TBD | 114 | - | dB | |
| | unweighted | - | 92 | - | dB | |
| | A-Weighted | - | 98 | - | dB | |
| Total Harmonic Distortion + Noise 24-Bit (Note 2) | (Note 1) 0 dB | THD+N | - | -100 | TBD | dB |
| | -20 dB | | - | -97 | TBD | dB |
| | -60 dB | | - | -57 | TBD | dB |
| | 16-Bit 0 dB | | - | -95 | - | dB |
| | -20 dB | | - | -75 | - | dB |
| | -60 dB | | - | -35 | - | dB |
| Dynamic Performance - Quad-Speed Mode - F_s equal to 192 kHz | | | | | | |
| Dynamic Range 24-Bit 40 kHz bandwidth 16-Bit (Note 2) | (Note 1) unweighted | TBD | 117 | - | dB | |
| | A-Weighted | TBD | 120 | - | dB | |
| | unweighted | TBD | 114 | - | dB | |
| | unweighted | - | 92 | - | dB | |
| | A-Weighted | - | 98 | - | dB | |
| Total Harmonic Distortion + Noise 24-Bit (Note 2) | (Note 1) 0 dB | THD+N | - | -100 | TBD | dB |
| | -20 dB | | - | -97 | TBD | dB |
| | -60 dB | | - | -57 | TBD | dB |
| | 16-Bit 0 dB | | - | -95 | - | dB |
| | -20 dB | | - | -75 | - | dB |
| | -60 dB | | - | -35 | - | dB |

- Notes: 1. Triangular PDF dithered data.
 2. Performance limited by 16-bit quantization noise.

ANALOG CHARACTERISTICS (Continued)

| Parameter | | Symbol | VD = 3 V | | | VD = 5 V | | | Unit |
|--------------------------------------|----------------------|-------------|----------|-----|-----|----------|-----|-----|---------|
| | | | Min | Typ | Max | Min | Typ | Max | |
| Power Supplies | | | | | | | | | |
| Supply Current VA = 5 V | normal operation | I_A | - | 20 | TBD | - | 20 | TBD | mA |
| | normal operation | I_D | - | TBD | TBD | - | TBD | TBD | mA |
| | power-down state | $I_D + I_A$ | - | 60 | - | - | 30 | - | μ A |
| Power Dissipation VA = 5 V | normal operation | | - | TBD | TBD | - | TBD | TBD | mW |
| | power-down | | - | 0.3 | - | - | 0.3 | - | mW |
| Power Supply Rejection Ratio (1 kHz) | (Note 3) (120 Hz) | PSRR | - | 60 | - | - | 60 | - | dB |
| | | | - | 40 | - | - | 40 | - | dB |

| Parameter | | Symbol | Min | Typ | Max | Unit |
|--|--|--------|-----|---------|-----|-------------------|
| Analog Output | | | | | | |
| Full Scale Differential Output Voltage | | | TBD | 1.4VREF | TBD | Vpp |
| Common Mode Voltage | | | - | 0.5VREF | - | VDC |
| Interchannel Gain Mismatch | | | - | 0.1 | - | dB |
| Gain Drift | | | - | 100 | - | ppm/ $^{\circ}$ C |
| Differential DC Offset | | | - | 2.0 | TBD | mV |
| AC-Load Resistance | | R_L | 1 | - | - | k Ω |
| Load Capacitance | | C_L | - | - | 100 | pF |
| Interchannel Isolation (1 kHz) | | | - | 90 | - | dB |

Notes: 3. Valid with the recommended capacitor values on FILT+ and CMOUT as shown in Figure 1. Increasing the capacitance will also increase the PSRR.

ANALOG CHARACTERISTICS (Continued)

| Parameter | Symbol | Min | Typ | Max | Unit |
|--|---------------|--------|-------|----------|------|
| Combined Digital and On-chip Analog Filter Response - Single Speed Mode | | | | | |
| Passband (Note 4) to -0.1 dB corner to -3 dB corner | | - | - | 0.470 | Fs |
| | | - | - | 0.492 | Fs |
| Frequency Response 10 Hz to 20 kHz | | -0.020 | - | +0.015 | dB |
| Passband Ripple | | - | - | ±0.0001 | dB |
| StopBand | | .5465 | - | - | Fs |
| StopBand Attenuation (Note 5) | | 102 | - | - | dB |
| Group Delay (Note 6) | tgd | - | 37/Fs | - | s |
| De-emphasis Error (Note 7) (Relative to 1 kHz) | | - | - | ±0.10 | dB |
| | Fs = 32 kHz | - | - | ±0.10 | dB |
| | Fs = 44.1 kHz | - | - | ±0.10 | dB |
| | | - | - | ±0.13 | dB |
| Combined Digital and On-chip Analog Filter Response - Double Speed Mode | | | | | |
| Passband (Note 4) to -0.1 dB corner to -3 dB corner | | 0 | - | 0.448 | Fs |
| | | 0 | - | 0.486 | Fs |
| Frequency Response 10 Hz to 20 kHz | | -0.017 | - | 0.035 | dB |
| Passband Ripple | | - | - | ±0.0008 | dB |
| StopBand | | .570 | - | - | Fs |
| StopBand Attenuation (Note 5) | | 82 | - | - | dB |
| Group Delay | tgd | - | 20/Fs | - | s |
| Combined Digital and On-chip Analog Filter Response - Quad-Speed Mode | | | | | |
| Passband (Note 4) to -0.1 dB corner to -3 dB corner | | - | - | 0.385 | Fs |
| | | - | - | 0.472 | Fs |
| Frequency Response 10 Hz to 20 kHz | | 0 | - | +0.015 | dB |
| Passband Ripple | | - | - | ±0.00065 | dB |
| StopBand | | 0.635 | - | - | Fs |
| StopBand Attenuation (Note 5) | | 83 | - | - | dB |
| Group Delay | tgd | - | 11/Fs | - | s |

- Notes:
- Response is clock dependent and will scale with Fs. Note that the response plots (**Figures 9-28**) have been normalized to Fs and can be de-normalized by multiplying the X-axis scale by Fs.
 - For Single-Speed Mode, the Measurement Bandwidth is 0.5465 Fs to 1.4 Fs.
For Double-Speed Mode, the Measurement Bandwidth is 0.570 Fs to 1.4 Fs.
For Quad-Speed Mode, the Measurement Bandwidth is 0.635 Fs to 1.3 Fs.
 - Group Delay for Fs=48 kHz 37/48 kHz=770 μs
 - De-emphasis is available only in Single Speed Mode.

ANALOG CHARACTERISTICS - DSD MODE ($T_A = 25\text{ }^\circ\text{C}$; Logic "1" = $V_D = 5\text{ V}$; $V_A = 5\text{ V}$; Logic "0" = AGND; Full-Scale Output Sine Wave, 997 Hz; Measurement Bandwidth 10 Hz to 20 kHz, unless otherwise specified. Test load $R_L = 1\text{ k}\Omega$, $C_L = 10\text{ pF}$)

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|-------------------|--------|---------|------|-----------------------|
| Dynamic Performance - DSD Mode | | | | | |
| Dynamic Range (Note 1) | unweighted | TBD | 117 | - | dB |
| | A-Weighted | TBD | 120 | - | dB |
| Total Harmonic Distortion + Noise (Note 1) | THD+N | | | | |
| | 0 dB | - | -100 | TBD | dB |
| | -20 dB | - | -94 | TBD | dB |
| | -60 dB | - | -54 | TBD | dB |
| Analog Output - DSD Mode | | | | | |
| Full Scale Differential Output Voltage (Note 8) | | TBD | 1.2VREF | TBD | Vpp |
| Common Mode Voltage | | - | 0.5VREF | - | VDC |
| Interchannel Gain Mismatch | | - | 0.1 | - | dB |
| Gain Drift | | - | 100 | - | ppm/ $^\circ\text{C}$ |
| Differential DC Offset | | - | 2.0 | TBD | mV |
| Combined Digital and On-chip Analog Filter Response - DSD Mode | | | | | |
| Passband (Note 4) | | | | | |
| | to -0.1 dB corner | - | - | 0.95 | Fs |
| | to -3 dB corner | - | - | 2.70 | Fs |
| Frequency Response 10 Hz to 20 kHz | | -0.013 | - | 0 | dB |
| Group Delay | tgd | - | 0.2/Fs | - | s |

Notes: 8. Assumes a DSD modulation index of 0.7.

ANALOG CHARACTERISTICS - 8X INTERPOLATOR MODE ($T_A = 25\text{ }^\circ\text{C}$; Logic "1" = $V_D = 5\text{ V}$; $V_A = 5\text{ V}$; Logic "0" = AGND; Full-Scale Output Sine Wave, 997 Hz; Base Band $F_s = 48\text{ kHz}$, SCLK = 6.144 MHz, Measurement Bandwidth 10 Hz to 20 kHz, unless otherwise specified. Test load $R_L = 1\text{ k}\Omega$, $C_L = 10\text{ pF}$)

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|-------------------------------|---------|---------|------|-----------------------|
| Dynamic Performance Mode | | | | | |
| Dynamic Range | (Note 1) unweighted | TBD | 117 | - | dB |
| | A-Weighted | TBD | 120 | - | dB |
| Total Harmonic Distortion + Noise | (Note 1) 0 dB | - | -100 | TBD | dB |
| | -20 dB | - | -97 | TBD | dB |
| | -60 dB | - | -57 | TBD | dB |
| Analog Output | | | | | |
| Full Scale Differential Output Voltage | | TBD | 0.7VREF | TBD | Vpp |
| Common Mode Voltage | | - | 0.5VREF | - | VDC |
| Interchannel Gain Mismatch | | - | 0.1 | - | dB |
| Gain Drift | | - | 100 | - | ppm/ $^\circ\text{C}$ |
| Differential DC Offset | | - | 2.0 | TBD | mV |
| Combined Digital and On-chip Analog Filter Response - 8x Interpolator Mode | | | | | |
| Passband | (Note 4) to -0.1 dB corner | - | - | 2.10 | Fs |
| | to -3 dB corner | - | - | 3.52 | Fs |
| Frequency Response 10 Hz to 20 kHz | | -0.0008 | - | 0 | dB |
| Passband Ripple | | - | - | 0 | dB |
| StopBand | | 6.08 | - | - | Fs |
| StopBand Attenuation | (Note 9) | 56 | - | - | dB |
| Group Delay | tgd | - | 0.9/Fs | - | s |

Notes: 9. Measurement Bandwidth is 6.08 to 9.6 Fs

DIGITAL CHARACTERISTICS ($T_A = 25^\circ\text{C}$; $V_D = 3.0\text{V} - 5.25\text{V}$)

| Parameters | Symbol | Min | Typ | Max | Units | |
|------------------------------|--------------------|----------|-----|----------|---------------|---|
| High-Level Input Voltage | $V_D = 5\text{ V}$ | V_{IH} | 2.0 | - | - | V |
| | $V_D = 3\text{ V}$ | | 2.0 | - | - | V |
| Low-Level Input Voltage | $V_D = 5\text{ V}$ | V_{IL} | - | - | 0.8 | V |
| | $V_D = 3\text{ V}$ | | - | - | 0.8 | V |
| Input Leakage Current | I_{in} | - | - | ± 10 | μA | |
| Input Capacitance | | - | 8 | - | pF | |
| Maximum MUTE C Drive Current | | - | 3 | - | mA | |

ABSOLUTE MAXIMUM RATINGS ($AGND = 0\text{ V}$, all voltages with respect to ground.)

| Parameter | Symbol | Min | Max | Unit |
|---|-----------|------|-------------|------------------|
| DC Power Supply: Positive Analog | VA | -0.3 | 6.0 | V |
| | VD | -0.3 | 6.0 | V |
| | VREF | -0.3 | VA | V |
| Reference Voltage | | | | |
| Input Current, Any Pin Except Supplies | I_{in} | - | ± 10 | mA |
| Digital Input Voltage | V_{IND} | -0.3 | $(V_D)+0.4$ | V |
| Ambient Operating Temperature (power applied) | T_A | -55 | 125 | $^\circ\text{C}$ |
| Storage Temperature | T_{stg} | -65 | 150 | $^\circ\text{C}$ |

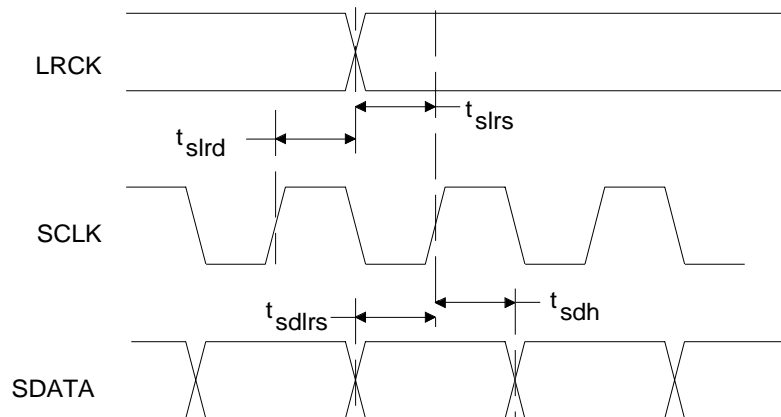
WARNING: Operation at or beyond these limits may result in permanent damage to the device. Normal operation is not guaranteed at these extremes.

RECOMMENDED OPERATING CONDITIONS ($DGND = 0\text{V}$; all voltages with respect to ground)

| Parameter | Symbol | Min | Typ | Max | Unit |
|-----------------------------------|--------|------|-----|------|------------------|
| DC Power Supply: Positive Digital | VD | 3.0 | 3.3 | 5.25 | V |
| | VA | 4.75 | 5.0 | 5.25 | V |
| | VREF | TBD | 5.0 | VA | V |
| Positive Analog | | | | | |
| Reference Voltage | | | | | |
| Specified Temperature Range | T_A | -10 | - | 70 | $^\circ\text{C}$ |

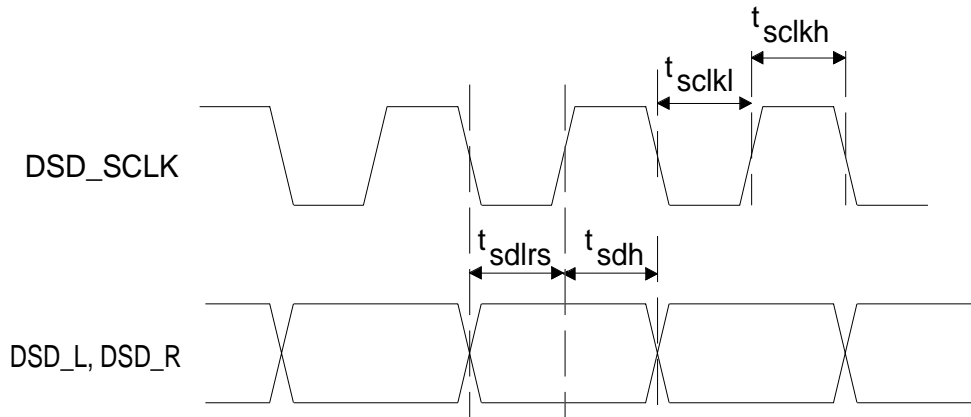
SWITCHING CHARACTERISTICS ($T_A = -10$ to 70°C ; Logic 0 = AGND = DGND; Logic 1 = VD = 5.25 to 3.0 Volts; $C_L = 20$ pF)

| Parameter | Symbol | Min | Typ | Max | Unit |
|--|------------|--------|-----|------------------|------|
| Input Sample Rate (Single-speed mode) | F_s | 16 | - | 50 | kHz |
| (Double-speed mode) | F_s | 50 | - | 100 | kHz |
| (Quad-speed mode) | F_s | 100 | - | 200 | kHz |
| LRCK Duty Cycle | | 45 | 50 | 55 | % |
| MCLK Frequency (Single-speed 256 F_s , Double speed 128 F_s or Quad-speed 64 F_s) | | 4.096 | - | 12.8 | MHz |
| MCLK Frequency (Single-speed 384 F_s , Double speed 192 F_s or Quad-speed, 96 F_s) | | 6.144 | - | 19.2 | MHz |
| MCLK Frequency (Single-speed 512 F_s , Double speed 256 F_s or Quad-speed, 128 F_s) | | 8.192 | - | 25.6 | MHz |
| MCLK Frequency (Single-speed 768 F_s , Double speed 384 F_s or Quad-speed, 192 F_s) | | 12.288 | - | 38.4 | MHz |
| MCLK Duty Cycle | | 40 | 50 | 60 | % |
| SCLK Frequency (Single-speed mode) | | - | - | $256 \times F_s$ | Hz |
| (Double-speed mode) | | - | - | $128 \times F_s$ | Hz |
| (Quad-speed mode) | | - | - | $64 \times F_s$ | Hz |
| SCLK rising to LRCK edge delay | t_{slrd} | 20 | - | - | ns |
| SCLK rising to LRCK edge setup time | t_{slrs} | 20 | - | - | ns |
| SDATA valid to SCLK rising setup time | t_{sdls} | 20 | - | - | ns |
| SCLK rising to SDATA hold time | t_{sdh} | 20 | - | - | ns |


Figure 1. Serial Audio Input Timing

DSD - SWITCHING CHARACTERISTICS ($T_A = -10$ to 70°C ; Logic 0 = AGND = DGND; Logic 1 = VD = 5.25 to 3.0 Volts; $C_L = 20$ pF)

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|--------------|----------------|--------|--------------|--------------|
| Input Bit Rate per Channel (64x Oversampled) (128x Oversampled) | | 1.024 2.048 | - - | 3.2 6.4 | Mb/s Mb/s |
| Master Clock Frequency (CLKMODE = 0) (CLKMODE = 1) | | 4.096 6.144 | - - | 12.8 19.2 | MHz MHz |
| MCLK Duty Cycle (All DSD modes) | | 40 | - | 60 | % |
| DSD_SCLK Pulse Width Low | t_{sckl} | 20 | - | - | ns |
| DSD_SCLK Pulse Width High | t_{sckh} | 20 | - | - | ns |
| DSD_SCLK Frequency (64x Oversampled) (128x Oversampled) | | 1.024 2.048 | - - | 3.2 6.4 | MHz MHz |
| DSD_LI_R valid to DSD_SCLK rising setup time | t_{sdllrs} | 20 | - | - | ns |
| DSD_SCLK rising to DSD_L or DSD_R hold time | t_{sdh} | 20 | - | - | ns |


Figure 2. Direct Stream Digital - Serial Audio Input Timing

8X INTERPOLATOR - SWITCHING CHARACTERISTICS ($T_A = -10$ to 70°C ;
 Logic 0 = AGND = DGND; Logic 1 = VD = 5.25 to 3.0 Volts; $C_L = 20$ pF)

| Parameter | Symbol | Min | Typ | Max | Unit |
|---------------------------------------|-------------|--------|-----|-----------|------|
| Input Sample Rate (Note 10) | F_s | 128 | - | 400 | kHz |
| MCLK Frequency (MCLK = 32x F_s) | | 4.096 | - | 12.8 | MHz |
| (MCLK = 48x F_s) | | 6.144 | - | 19.2 | MHz |
| (MCLK = 64x F_s) | | 8.192 | - | 25.6 | MHz |
| (MCLK = 96x F_s) | | 12.288 | - | 28.4 | MHz |
| MCLK Duty Cycle | | 40 | - | 50 | % |
| WCKI Duty Cycle | | 25 | - | 75 | % |
| BCKI Frequency | | | | 32x F_s | MHz |
| BCKI rising to WCKI edge delay | t_{slrd} | 20 | - | - | ns |
| BCKI rising to WCKI edge setup time | t_{slrs} | 20 | - | - | ns |
| SDATA valid to BCKI rising setup time | t_{sdlrs} | 20 | - | - | ns |
| BCKI rising to DIL/DIR hold time | t_{sdh} | 20 | - | - | ns |

Notes: 10. F_s refers to the input sample rate to the Digital-to-Analog converter, i.e. $F_s = 44.1 \text{ kHz} \times 8 = 352.8 \text{ kHz}$.

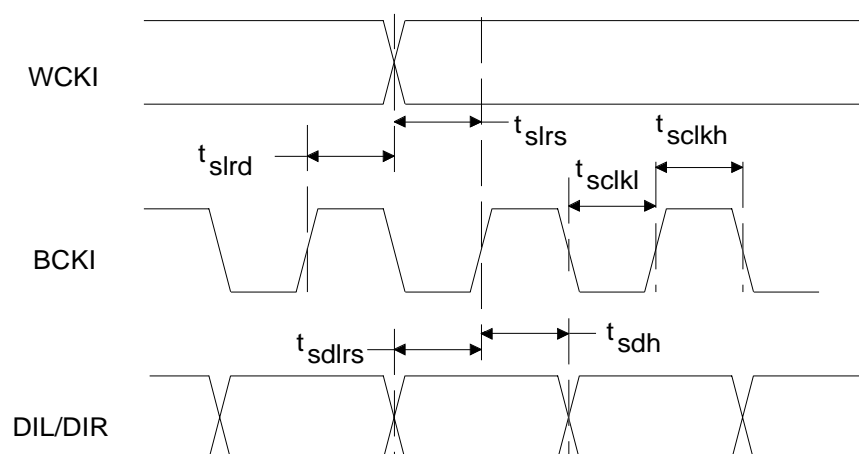


Figure 3. Serial Audio Input Timing

SWITCHING CHARACTERISTICS - CONTROL PORT

($T_A = 25\text{ }^\circ\text{C}$; $V_D = 5.25\text{ V}$ to 3.0 Volts ; Inputs: logic 0 = AGND, logic 1 = V_D , $C_L = 30\text{ pF}$)

| Parameter | Symbol | Min | Max | Unit |
|--|------------|-----|-----|---------------|
| <i>I²C[®] Mode</i> | | | | |
| SCL Clock Frequency | f_{scl} | - | 100 | KHz |
| RST Rising Edge to Start | t_{irs} | 500 | - | ns |
| Bus Free Time Between Transmissions | t_{buf} | 4.7 | - | μs |
| Start Condition Hold Time (prior to first clock pulse) | t_{hdst} | 4.0 | - | μs |
| Clock Low time | t_{low} | 4.7 | - | μs |
| Clock High Time | t_{high} | 4.0 | - | μs |
| Setup Time for Repeated Start Condition | t_{sust} | 4.7 | - | μs |
| SDA Hold Time from SCL Falling (Note 11) | t_{hdd} | 0 | - | μs |
| SDA Setup time to SCL Rising | t_{sud} | 250 | - | ns |
| Rise Time of Both SDA and SCL Lines | t_r | - | 1 | μs |
| Fall Time of Both SDA and SCL Lines | t_f | - | 300 | ns |
| Setup Time for Stop Condition | t_{susp} | 4.7 | - | μs |

Notes: 11. Data must be held for sufficient time to bridge the 300 ns transition time of SCL.

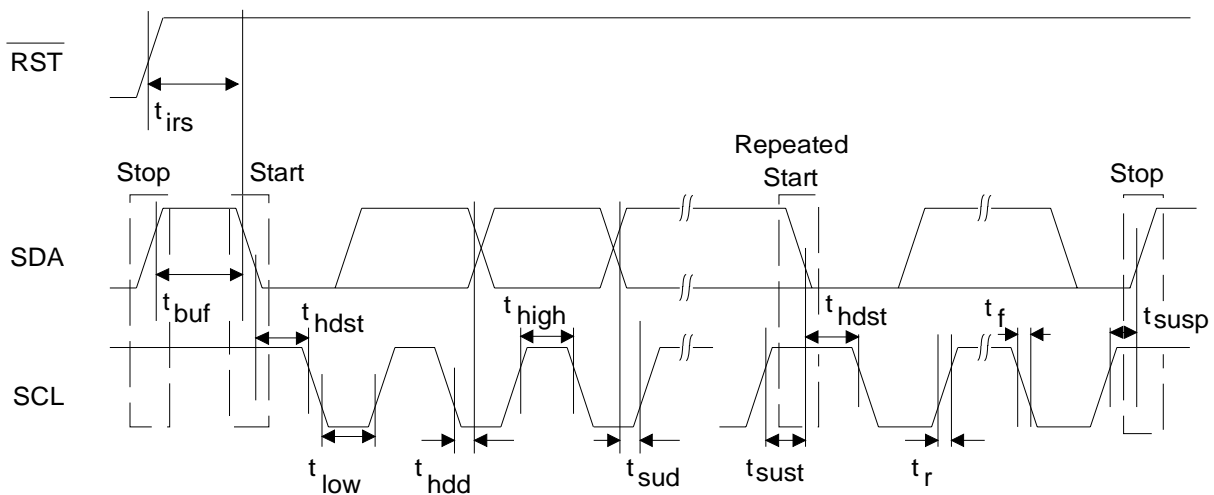


Figure 4. I²C Control Port Timing

SWITCHING CHARACTERISTICS - CONTROL PORT

($T_A = 25\text{ }^\circ\text{C}$; $V_D = 5.25\text{ V}$ to 3.0 Volts ; Inputs: logic 0 = AGND, logic 1 = V_D , $C_L = 30\text{ pF}$)

| Parameter | Symbol | Min | Max | Unit |
|--|-------------------|-----|-----|---------------|
| SPI Mode | | | | |
| CCLK Clock Frequency | f_{sclk} | - | 6 | MHz |
| RST Rising Edge to CS Falling | t_{srs} | 500 | - | ns |
| CCLK Edge to $\overline{\text{CS}}$ Falling (Note 12) | t_{spi} | 500 | - | ns |
| $\overline{\text{CS}}$ High Time Between Transmissions | t_{csh} | 1.0 | - | μs |
| $\overline{\text{CS}}$ Falling to CCLK Edge | t_{css} | 20 | - | ns |
| CCLK Low Time | t_{scl} | 66 | - | ns |
| CCLK High Time | t_{sch} | 66 | - | ns |
| CDIN to CCLK Rising Setup Time | t_{dsu} | 40 | - | ns |
| CCLK Rising to DATA Hold Time (Note 13) | t_{dh} | 15 | - | ns |
| Rise Time of CCLK and CDIN (Note 14) | t_{r2} | - | 100 | ns |
| Fall Time of CCLK and CDIN (Note 14) | t_{f2} | - | 100 | ns |
| CCLK Falling to CDOOUT valid | t_{ov} | 45 | - | ns |

Notes: 12. t_{spi} only needed before first falling edge of $\overline{\text{CS}}$ after $\overline{\text{RST}}$ rising edge. $t_{\text{spi}} = 0$ at all other times.

13. Data must be held for sufficient time to bridge the transition time of CCLK.

14. For $F_{\text{SCK}} < 1\text{ MHz}$

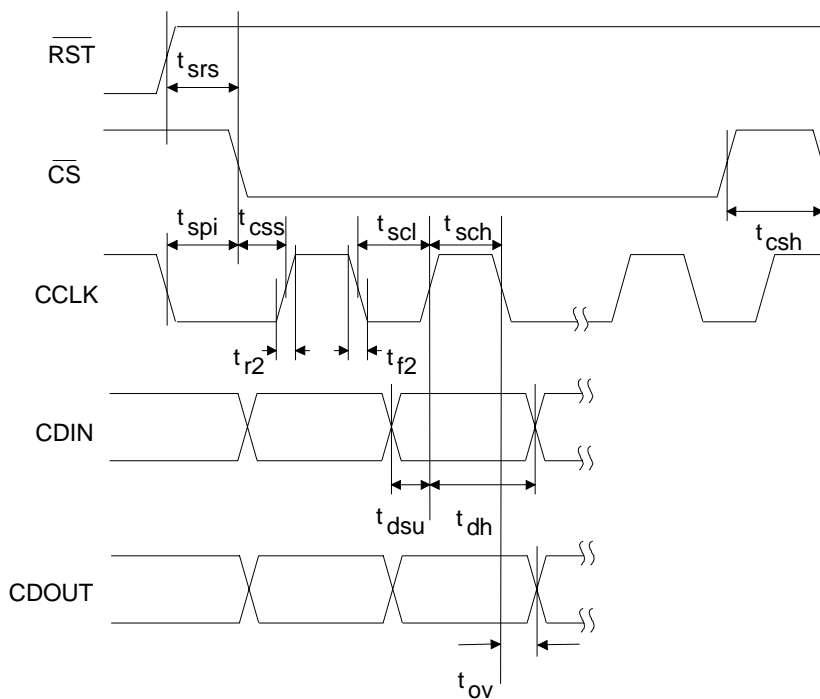


Figure 5. SPI Control Port Timing

2.0 TYPICAL CONNECTION DIAGRAM

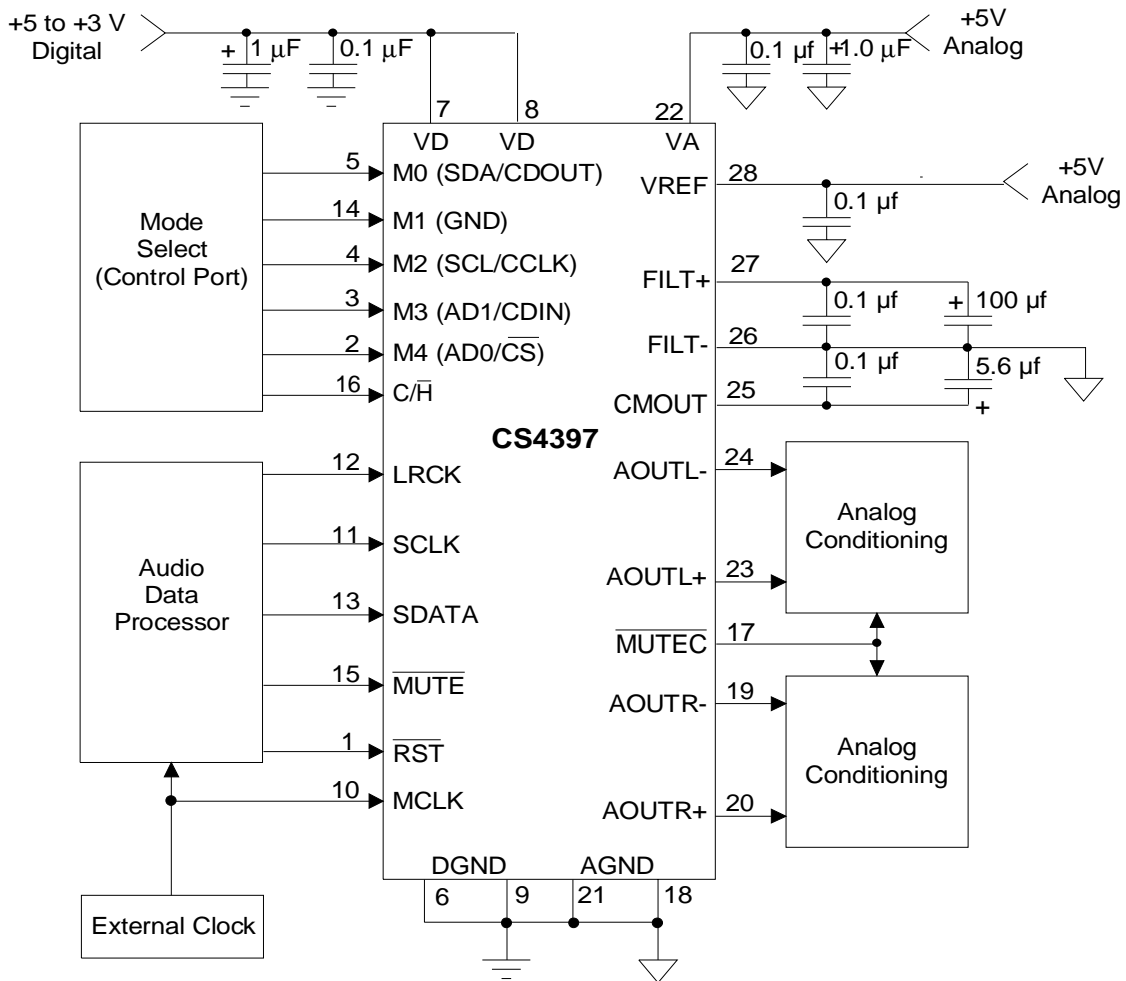


Figure 6. Typical Connection Diagram - Hardware Mode (Control Port Mode)

3.0 REGISTER DESCRIPTION

3.1 DIFFERENTIAL DC OFFSET CALIBRATION

Mode Control Register (address 01h)

| | | | | | | | |
|-----|--------------------------|----|----|----|----|----|-----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| CAL | $\overline{\text{MUTE}}$ | M4 | M3 | M2 | M1 | M0 | PDN |

Access:

R/W in I²C and SPI.

Default:

0 - Disabled

Function:

Enabling this function will initiate a calibration to minimize the differential DC offset. This function will be automatically reset following completion of the calibration sequence.

| CAL | MODE |
|-----|-------------------------|
| 0 | Disabled : CAL complete |
| 1 | Enabled : CAL initiated |

Table 1.

3.2 SOFT MUTE

Mode Control Register (address 01h)

| | | | | | | | |
|-----|--------------------------|----|----|----|----|----|-----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| CAL | $\overline{\text{MUTE}}$ | M4 | M3 | M2 | M1 | M0 | PDN |

Access:

R/W in I²C and SPI.

Default:

0 - Enabled

Function:

The analog outputs will ramp to a muted state when enabled. The ramp requires 1152 left/right clock cycles in Single Speed, 2304 cycles in Double Speed and 4608 cycles in Quad Speed mode. The bias voltage on the outputs will be retained and MUTE_{EC} will go low at the completion of the ramp period.

The analog outputs will ramp to a normal state when this function transitions from the enabled to disabled state. The ramp requires 1152 left/right clock cycles in Single Speed, 2304 cycles in Double Speed and 4608 cycles in Quad Speed mode. The MUTE_{EC} will go high immediately on disabling of MUTE.

| $\overline{\text{MUTE}}$ | MODE |
|--------------------------|----------|
| 0 | Enabled |
| 1 | Disabled |

Table 2.

3.3 MODE SELECT

Mode Control Register (address 01h)

| | | | | | | | |
|-----|------|----|----|----|----|----|-----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| CAL | MUTE | M4 | M3 | M2 | M1 | M0 | PDN |

Access:

R/W in I²C and SPI.

Default:

00000

Function:

The Mode Select pins determine the operational mode of the device as detailed in Tables 9-14. The options include:

Selection of the Digital Interface Format which determines the required relationship between the Left/Right clock, serial clock and serial data as detailed in Figures 29-33

Selection of the standard 15 μ s/50 μ s digital de-emphasis filter response, Figure 28, which requires re-configuration of the digital filter to maintain the proper filter response for 32, 44.1 or 48 kHz sample rates.

Selection of the appropriate clocking mode to match the input sample rates.

Access to the Direct Stream Digital Mode

Access to the 8x Interpolation Input Mode

3.4 POWER DOWN

Mode Control Register (address 01h)

| | | | | | | | |
|-----|------|----|----|----|----|----|-----|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| CAL | MUTE | M4 | M3 | M2 | M1 | M0 | PDN |

Access:

R/W in I²C and SPI.

Default:

1 - Powered Down

Function:

The analog and digital sections will be placed into a power-down mode when this function is enabled. This bit must be cleared to resume normal operation.

| PDN | MODE |
|-----|----------|
| 0 | Disabled |
| 1 | Enabled |

Table 3.

4.0 PIN DESCRIPTION - PCM MODE

| | | | | | |
|------------------|----------------------|------|------|--------------------------------------|------------------------------|
| Reset | RST | □ 1 | 28 □ | VREF | Voltage Reference |
| See Description | M4(AD0/CS) | □ 2 | 27 □ | FILT+ | Reference Filter |
| See Description | M3(AD1/CDIN) | □ 3 | 26 □ | FILT- | Reference Ground |
| See Description | M2(SCL/CCLK) | □ 4 | 25 □ | CMOUT | Common ModeS Voltage |
| See Description | M0(SDA/CDOUT) | □ 5 | 24 □ | AOUTL- | Differential Output |
| Digital Ground | DGND | □ 6 | 23 □ | AOUTL+ | Differential Output |
| Digital Power | VD | □ 7 | 22 □ | VA | Analog Power |
| Digital Power | VD | □ 8 | 21 □ | AGND | Analog Ground |
| Digital Ground | DGND | □ 9 | 20 □ | AOUTR+ | Differential Output |
| Master Clock | MCLK | □ 10 | 19 □ | AOUTR- | Differential Output |
| Serial Clock | SCLK | □ 11 | 18 □ | AGND | Analog Ground |
| Left/Right Clock | LRCK | □ 12 | 17 □ | MUTE\overline{C} | Mute Control |
| Serial Data | SDATA | □ 13 | 16 □ | C/H | Control port/Hardware select |
| See Description | M1 | □ 14 | 15 □ | MUTE | Soft Mute |

Reset - \overline{RST}

Pin 1, Input

Function:

The device enters a low power mode and all internal state machines registers are reset when low. When high, the device will be in a normal operation mode .

| \overline{RST} | DESCRIPTION |
|------------------|-----------------------|
| 0 | Enabled |
| 1 | Normal operation mode |

Digital Ground - DGND

Pins 6 and 9, Inputs

Function:

Digital ground reference.

Digital Power - VD

Pins 7 and 8, Input

Function:

Digital power supply. Typically 5.0 to 3.0 VDC.

Master Clock - MCLK

Pin 10, Input

Function:

The master clock frequency must be either 256x, 384x, 512x or 768x the input sample rate in Single Speed Mode; either 128x, 192x 256x or 384x the input sample rate in Double Speed Mode; or 64x, 96x 128x or 192x the input sample rate in Quad Speed Mode. Tables 4-6 illustrate the standard audio sample rates and the required master clock frequencies.

| Sample Rate (kHz) | MCLK (MHz) | | | |
|----------------------|------------|---------|---------|---------|
| | 256x | 384x | 512x | 768x |
| 32 | 8.1920 | 12.2880 | 16.3840 | 24.5760 |
| 44.1 | 11.2896 | 16.9344 | 22.5792 | 33.8688 |
| 48 | 12.2880 | 18.4320 | 24.5760 | 36.8640 |

Table 4. Single Speed (16 to 50 kHz sample rates) Common Clock Frequencies

| Sample Rate (kHz) | MCLK (MHz) | | | |
|----------------------|------------|---------|---------|---------|
| | 128x | 192x | 256x | 384x |
| 64 | 8.1920 | 12.2880 | 16.3840 | 24.5760 |
| 88.2 | 11.2896 | 16.9344 | 22.5792 | 33.8688 |
| 96 | 12.2880 | 18.4320 | 24.5760 | 36.8640 |

Table 5. Double Speed (50 to 100 kHz sample rates) Common Clock Frequencies

| Sample Rate (kHz) | MCLK (MHz) | | | |
|----------------------|------------|---------|---------|---------|
| | 64x | 96x | 128x | 192x |
| 176.4 | 11.2896 | 16.9344 | 22.5792 | 33.8688 |
| 192 | 12.2880 | 18.4320 | 24.5760 | 36.8640 |

Table 6. Quad Speed (100 to 200 kHz sample rates) Common Clock Frequencies
Serial Clock - SCLK
Pin 11, Input
Function:

Clocks individual bits of serial data into the SDATA pin. The required relationship between the Left/Right clock, serial clock and serial data is defined by either the Mode Control Byte in Control Port Mode or the M0 - M4 pins in Hardware Mode. The options are detailed in Figures 29-33

Left/Right Clock - LRCK
Pin 12, Input
Function:

The Left/Right clock determines which channel is currently being input on the serial audio data input, SDATA. The frequency of the Left/Right clock must be at the input sample rate. Audio samples in Left/Right sample pairs will be simultaneously output from the digital-to-analog converter whereas Right/Left pairs will exhibit a one sample period difference. The required relationship between the Left/Right clock, serial clock and serial data is defined by the Mode Control Byte and the options are detailed in Figures 29-33

Serial Audio Data - SDATA
Pin 13, Input
Function:

Two's complement MSB-first serial data is input on this pin. The data is clocked into SDATA via the serial clock and the channel is determined by the Left/Right clock. The required relationship between the Left/Right clock, serial clock and serial data is defined by the Mode Control Byte and the options are detailed in Figures 29-33

Soft Mute - $\overline{\text{MUTE}}$
Pin 15, Input
Function:

The analog outputs will ramp to a muted state when enabled. The ramp requires 1152 left/right clock cy-

cles in Single Speed, 2304 cycles in Double Speed and 4608 cycles in Quad Speed mode. The bias voltage on the outputs will be retained and MUTE \overline{C} will go active at the completion of the ramp period.

The analog outputs will ramp to a normal state when this function transitions from the enabled to disabled state. The ramp requires 1152 left/right clock cycles in Single Speed, 2304 cycles in Double Speed and 4608 cycles in Quad Speed mode. The MUTE \overline{C} will release immediately on setting MUTE = 1.

The converter analog outputs will mute when enabled. The bias voltage on the outputs will be retained and MUTE \overline{C} will go active during the mute period.

| Mute | DESCRIPTION |
|------|-----------------------|
| 0 | Enabled |
| 1 | Normal operation mode |

Control Port / Hardware Mode Select - C/H $\overline{}$

Pin 16, Input

Function:

Determines if the device will operate in either the Hardware Mode or Control Port Mode.

| C/H $\overline{}$ | DESCRIPTION |
|-------------------|---------------------------|
| 0 | Hardware Mode Enabled |
| 1 | Control Port Mode Enabled |

Mute Control - MUTE \overline{C}

Pin 17, Output

Function:

The Mute Control pin goes low during power-up initialization, reset, muting, master clock to left/right clock frequency ratio is incorrect or power-down. This pin is intended to be used as a control for an external mute circuit to prevent the clicks and pops that can occur in any single supply system. Use of Mute Control is not mandatory but recommended for designs requiring the absolute minimum in extraneous clicks and pops.

Analog Ground - AGND

Pins 18 and 21, Inputs

Function:

Analog ground reference.

Differential Analog Output - AOUTR $\overline{-}$, AOUTR $\overline{+}$ and AOUTL $\overline{-}$, AOUTL $\overline{+}$

Pins 19, 20, 23 and 24, Outputs

Function:

The full scale differential analog output level is specified in the Analog Characteristics specifications table.

Analog Power - VA

Pin 22, Input

Function:

Power for the analog and reference circuits. Typically 5VDC.

Common Mode Voltage - CMOUT

Pin 25, Output

Function:

Filter connection for internal bias voltage, typically 50% of VREF. Capacitors must be connected from CMOUT to analog ground, as shown in Figure 6. CMOUT has a typical source impedance of 25 k Ω and any current drawn from this pin will alter device performance

Reference Ground - FILT-

Pin 26, Input

Function:

Ground reference for the internal sampling circuits. Must be connected to analog ground.

Reference Filter - FILT+

Pin 27, Output

Function:

Positive reference for internal sampling circuits. External capacitors are required from FILT+ to analog ground, as shown in Figure 6. The recommended values will typically provide 60 dB of PSRR at 1 kHz and 40 dB of PSRR at 120 Hz. FILT+ is not intended to supply external current.

Voltage Reference Input- VREF

Pin 28, Input

Function:

Analog voltage reference. Typically 5VDC.

HARDWARE MODE**Mode Select - M0, M1, M2, M3, M4**

Pins 2, 3, 4, 5 and 14, Inputs

Function:

The Mode Select pins determine the operational mode of the device as detailed in Tables 9-14. The options include;

Selection of the Digital Interface Format which determines the required relationship between the Left/Right clock, serial clock and serial data as detailed in Figures 29-33

Selection of the standard 15 μ s/50 μ s digital de-emphasis filter response, Figure 28, which requires re-configuration of the digital filter to maintain the proper filter response for 32, 44.1 or 48 kHz sample rates.

Selection of the appropriate clocking mode to match the input sample rates.

Access to the Direct Stream Digital Mode

Access to the 8x Interpolation Input Mode

CONTROL PORT MODE**Address Bit 0 / Chip Select - AD0 / $\overline{\text{CS}}$**

Pin 2, Input

Function:

In I²C mode, AD0 is a chip address bit. $\overline{\text{CS}}$ is used to enable the control port interface in SPI mode. The device will enter the SPI mode at anytime a high to low transition is detected on this pin. Once the device has entered the SPI mode, it will remain until either the part is reset or undergoes a power-down cycle.

Address Bit 1 / Control Data Input - AD1/CDIN

Pin 3, Input

Function:

In I²C mode, AD1 is a chip address bit. CDIN is the control data input line for the control port interface in SPI mode.

Serial Control Interface Clock - SCL/CCLK

Pin 4, Input

Function:

In I²C mode, SCL clocks the serial control data into or from SDA/CDOOUT.

In SPI mode, CCLK clocks the serial data into AD1/CDIN and out of SDA/CDOOUT.

Serial Control Data I/O - SDA/CDOOUT

Pin 5, Input/Output

Function:

In I²C mode, SDA is a data input/output. CDOOUT is the control data output for the control port interface in SPI mode.

M1 - Mode Select

Pin 14, Input

Function:

This pin is not used in Control Port Mode and must be terminated to ground.

5.0 PIN DESCRIPTION - DSD MODE

| | | | | | |
|--------------------|----------------------|----|----|-------------------------|-------------------|
| Refer to PCM mode | RST | 1 | 28 | VREF | Refer to PCM mode |
| Refer to PCM mode | M4(ADO/CS) | 2 | 27 | FILT+ | Refer to PCM mode |
| Refer to PCM mode | M3(AD1/CDIN) | 3 | 26 | FILT- | Refer to PCM mode |
| Refer to PCM mode | M2(SCL/CCLK) | 4 | 25 | CMOUT | Refer to PCM mode |
| Refer to PCM mode | M0(SDA/CDOUT) | 5 | 24 | AOUTL- | Refer to PCM mode |
| Refer to PCM mode | DGND | 6 | 23 | AOUTL+ | Refer to PCM mode |
| Refer to PCM mode | VD | 7 | 22 | VA | Refer to PCM mode |
| Refer to PCM mode | VD | 8 | 21 | AGND | Refer to PCM mode |
| Refer to PCM mode | DGND | 9 | 20 | AOUTR+ | Refer to PCM mode |
| Master Clock | MCLK | 10 | 19 | AOUTR- | Refer to PCM mode |
| DSD Serial Clock | DSD_SCLK | 11 | 18 | AGND | Refer to PCM mode |
| Master Clock Mode | CLKMODE | 12 | 17 | MUTE_C | Refer to PCM mode |
| Left Channel Data | DSD_L | 13 | 16 | C/H | Refer to PCM mode |
| Right Channel Data | DSD_R | 14 | 15 | MUTE | Refer to PCM mode |

Master Clock - MCLK

Pin 10, Input

Function:

The master clock frequency must be either 4x or 6x the DSD data rate for 64x oversampled DSD data and 2x or 3x the DSD data rate for 128x oversampled DSD data, refer to Table 7.

CLKMODE

Pin 12, Input

Function:

This pin determines the allowable Master Clock to DSD data ratio as defined in Table 7.

| | | CLKMODE | |
|-------------------------|------|---------|----|
| | | 0 | 1 |
| DSD Over-Sampling Ratio | 64x | 4x | 6x |
| | 128x | 2x | 3x |

Table 7. MCLK to DSD Data Rate Clock Ratios

DSD Serial Clock - DSD_SCLK

Pin 11, Input

Function:

Clocks the individual bits of the DSD audio data into the DSD_L and DSD_R pins.

Audio Data - DSD_L and DSD_R

Pins 13 and 14, Inputs

Function:

Direct Stream Digital audio data is clocked into DSD_L and DSD_R via the DSD serial clock.

6.0 PIN DESCRIPTION - 8X INTERPOLATOR MODE

| | | | | | |
|--------------------|----------------------|----|----|-------------------------|-------------------|
| Refer to PCM mode | RST | 1 | 28 | VREF | Refer to PCM mode |
| Refer to PCM mode | M4(AD0/CS) | 2 | 27 | FILT+ | Refer to PCM mode |
| Refer to PCM mode | M3(AD1/CDIN) | 3 | 26 | FILT- | Refer to PCM mode |
| Refer to PCM mode | M2(SCL/CCLK) | 4 | 25 | CMOUT | Refer to PCM mode |
| Refer to PCM mode | M0(SDA/CDOUT) | 5 | 24 | AOUTL- | Refer to PCM mode |
| Refer to PCM mode | DGND | 6 | 23 | AOUTL+ | Refer to PCM mode |
| Refer to PCM mode | VD | 7 | 22 | VA | Refer to PCM mode |
| Refer to PCM mode | VD | 8 | 21 | AGND | Refer to PCM mode |
| Refer to PCM mode | DGND | 9 | 20 | AOUTR+ | Refer to PCM mode |
| Master Clock | MCLK | 10 | 19 | AOUTR- | Refer to PCM mode |
| Bit Clock | BCKI | 11 | 18 | AGND | Refer to PCM mode |
| Word Clock | WCKI | 12 | 17 | MUTE^C | Refer to PCM mode |
| Left Channel Data | DIL | 13 | 16 | C/H | Refer to PCM mode |
| Right Channel Data | DIR | 14 | 15 | MUTE | Refer to PCM mode |

Master Clock - MCLK

Pin 10, Input

Function:

The master clock frequency must be either 32x, 48x, 64x or 96x the input sample rate. Table 8 illustrates the standard audio sample rates and the required master clock frequencies.

| Sample Rate (kHz) | MCLK (MHz) | | | |
|-------------------|------------|---------|--------|--------|
| | 32x | 48x | 64x | 96x |
| 32 x 8 | 8.1920 | 12.2880 | 16.384 | 24.576 |
| 44.1 x 8 | 11.2896 | 16.9344 | 22.579 | 33.869 |
| 48 x 8 | 12.2880 | 18.4320 | 24.576 | 36.864 |

Table 8. Common Clock Frequencies

Bit Clock - BCKI

Pin 11, Input

Function:

Clocks the individual serial data bits into the DIL and DIR pins. Refer to Figure 33

Word Clock - WCKI

Pin 12, Input

Function:

The word clock determines which channel is currently being input on the serial audio data input, SDATA. The frequency of the word clock must be at 8x the baseband sample rate. Refer to Figure 33.

Serial Audio Data - DIR and DIL

Pins 12 and 13, Inputs

Function:

Two's complement MSB-first serial data is input on these pins. The data is clocked into DIL and DIR via the bit clock. Refer to Figure 33.

7.0 APPLICATIONS

7.1 Recommended Power-up Sequence

1. Hold $\overline{\text{RST}}$ low until the power supplies, master, and left/right clocks are stable.
2. Bring $\overline{\text{RST}}$ high.

8.0 CONTROL PORT INTERFACE

The control port is used to load all the internal settings of the CS4397. The operation of the control port may be completely asynchronous to the audio sample rate. However, to avoid potential interference problems, the control port pins should remain static if no operation is required.

The control port has 2 modes: SPI and I²C, with the CS4397 operating as a slave device in both modes. If I²C operation is desired, AD0/ $\overline{\text{CS}}$ should be tied to VD or DGND. If the CS4397 ever detects a high to low transition on AD0/ $\overline{\text{CS}}$ after power-up, SPI mode will be selected.

8.1 SPI Mode

In SPI mode, $\overline{\text{CS}}$ is the CS4397 chip select signal, CCLK is the control port bit clock, CDIN is the input data line from the microcontroller, CDOUT is the data output and the chip address is 0010000. The data is clocked on the rising edge of CCLK.

Figure 7 shows the operation of the control port in SPI mode. To write to a register, bring $\overline{\text{CS}}$ low. The first 7 bits on CDIN form the chip address, and must be 0010000. The eighth bit is a read/write indicator ($\overline{\text{R/W}}$). The next 8 bits form the Memory Address Pointer (MAP), which is set to 01h. The next 8 bits are the data which will be placed into the register designated by the MAP.

8.2 I²C Mode

In I²C mode, SDA is a bi-directional data line. Data is clocked into and out of the part by the clock, SCL, with the clock to data relationship as shown in Figure 3. There is no $\overline{\text{CS}}$ pin. Pins AD0 and AD1 form the partial chip address and should be tied to VD or DGND as required. The 7-bit address field, which is the first byte sent to the CS4397, must be 00100(AD1)(AD0) where (AD1) and (AD0) match the setting of the AD0 and AD1 pins. The eighth bit of the address byte is the $\overline{\text{R/W}}$ bit (high for a read, low for a write). If the operation is a write, the next byte is the Memory Address Pointer, MAP, which selects the register to be read or written. The MAP is then followed by the data to be written. If the operation is a read, then the contents of the register pointed to by the MAP will be output after the chip address.

For more information on I²C, please see “The I²C-Bus Specification: Version 2.0”, listed in the References section.

Memory Address Pointer (MAP)

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|----------|----------|----------|----------|------|------|------|
| INCR | Reserved | Reserved | Reserved | Reserved | MAP2 | MAP1 | MAP0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

INCR (Auto MAP Increment Enable)
 Default = '0'
 0 - Disabled
 1 - Enabled

MAP0-2 (Memory Address Pointer)
 Default = '001'

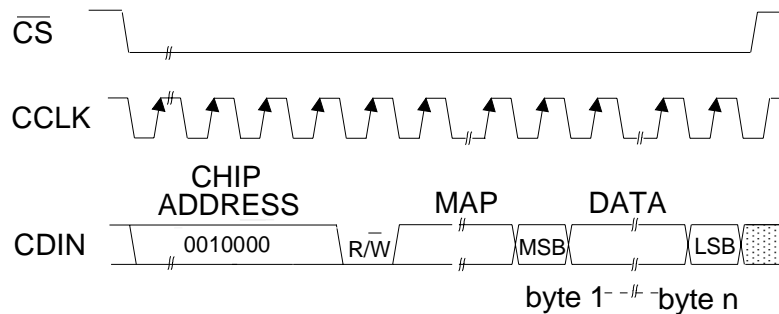
Schematic & Layout Review Service

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Before Building Your Board.



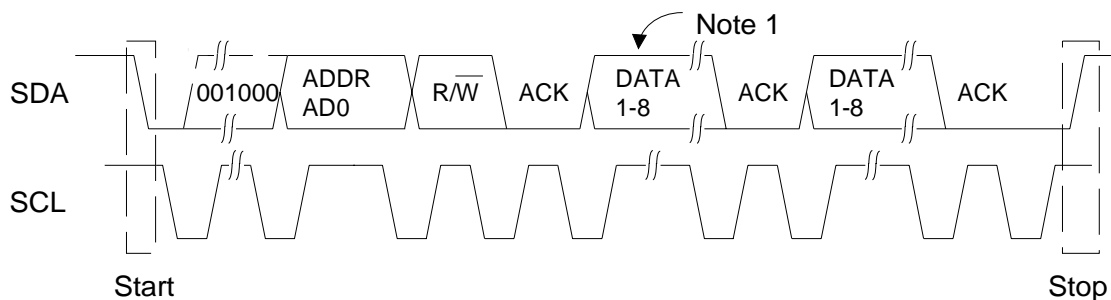
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Call Applications Engineering.

C a l l : (5 1 2) 4 4 5 - 7 2 2 2



MAP = Memory Address Pointer = 0

Figure 7. Control Port Timing, SPI mode



Note: If operation is a write, this byte contains the Memory Address Pointer, MAP.

Figure 8. Control Port Timing, I²C Mode

| M4 | M1 (DIF1) | M0 (DIF0) | DESCRIPTION | FORMAT | FIGURE |
|----|-----------|-----------|-------------------------------------|--------|--------|
| 0 | 0 | 0 | Left Justified, up to 24-bit data | 0 | 29 |
| 0 | 0 | 1 | I ² S, up to 24-bit data | 1 | 30 |
| 0 | 1 | 0 | Right Justified, 16-bit Data | 2 | 31 |
| 0 | 1 | 1 | Right Justified, 24-bit Data | 3 | 33 |

Table 9. Single Speed (16 to 50 kHz) Digital Interface Format Options

| M4 | M3 (DEM1) | M2 (DEM0) | DESCRIPTION | FIGURE |
|----|-----------|-----------|----------------------|--------|
| 0 | 0 | 0 | 32 kHz De-Emphasis | 28 |
| 0 | 0 | 1 | 44.1 kHz De-Emphasis | 28 |
| 0 | 1 | 0 | 48 kHz De-Emphasis | 28 |
| 0 | 1 | 1 | De-Emphasis Disabled | - |

Table 10. Single Speed (16 to 50 kHz) De-Emphasis Options

| M4 | M3 | M2 | M1 | M0 | DESCRIPTION |
|----|----|----|----|----|--|
| 1 | 1 | 1 | 0 | 0 | Left Justified up to 24-bit data, Format 0 |
| 1 | 1 | 1 | 0 | 1 | I ² S up to 24-bit data, Format 1 |
| 1 | 1 | 1 | 1 | 0 | Right Justified 16-bit data, Format 2 |
| 1 | 1 | 1 | 1 | 1 | Right Justified 24-bit data, Format 3 |

Table 11. Double Speed (50 to 100 kHz) Sample Rate Mode Options

| M4 | M3 | M2 | M1 | M0 | DESCRIPTION |
|----|----|----|----|----|--|
| 1 | 1 | 0 | 0 | 0 | Left Justified up to 24-bit data, Format 0 |
| 1 | 1 | 0 | 0 | 1 | I ² S up to 24-bit data, Format 1 |
| 1 | 1 | 0 | 1 | 0 | Right Justified 16-bit data, Format 2 |
| 1 | 1 | 0 | 1 | 1 | Right Justified 24-bit data, Format 3 |

Table 12. Quad (100 to 200 kHz) Sample Rate Mode Options

| M4 | M3 | M2 | M1 | M0 | DESCRIPTION |
|----|----|----|---------|----|-----------------------------|
| 1 | 0 | 0 | 0 | 0 | Right Justified 20-bit data |
| 1 | 0 | 0 | 0 (DIR) | 1 | Right Justified 24-bit data |

Table 13. 8x Interpolated Input Mode Options

| M4 | M3 | M2 | M1 | M0 | DESCRIPTION |
|----|----|----|-----------|----|----------------------|
| 1 | 0 | 1 | 0 (DSD_R) | 0 | 64x Oversampled DSD |
| 1 | 0 | 1 | 0 (DSD_R) | 1 | 128x Oversampled DSD |

Table 14. Direct Stream Digital Options

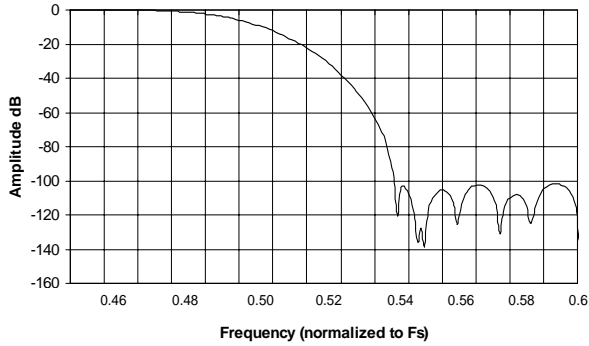


Figure 9. Single-speed Transition Band

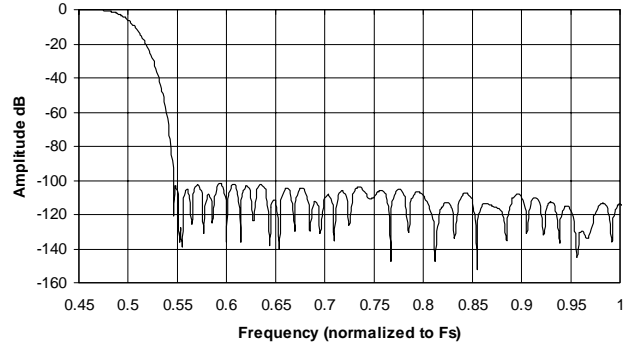


Figure 10. Single-speed Stopband Rejection

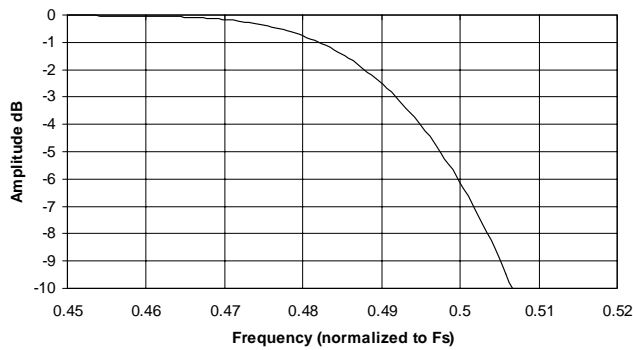


Figure 11. Single-speed Transition Band

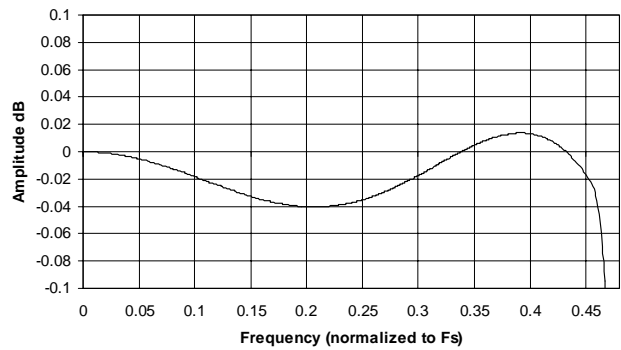


Figure 12. Single-speed Frequency Response

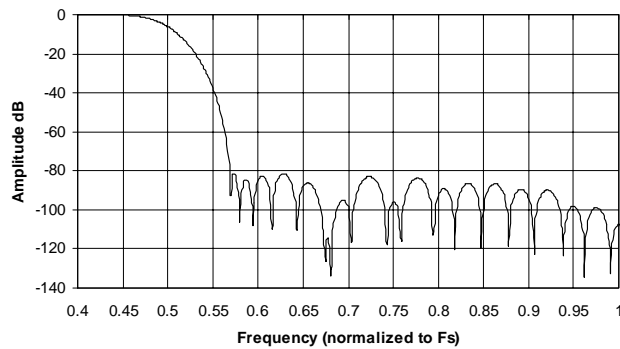


Figure 13. Double-speed Stopband

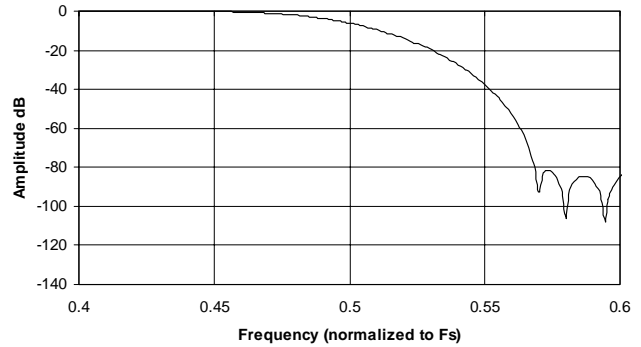


Figure 14. Double-speed Transition Band

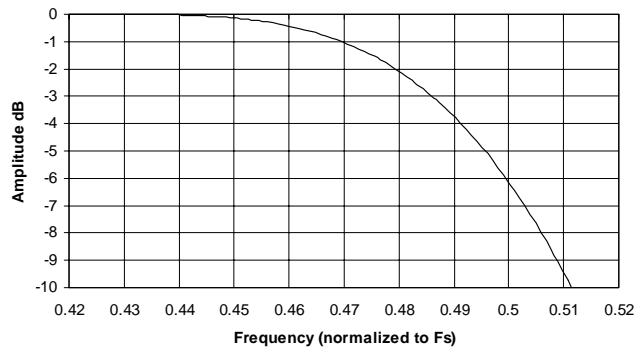


Figure 15. Double-speed Transition Band

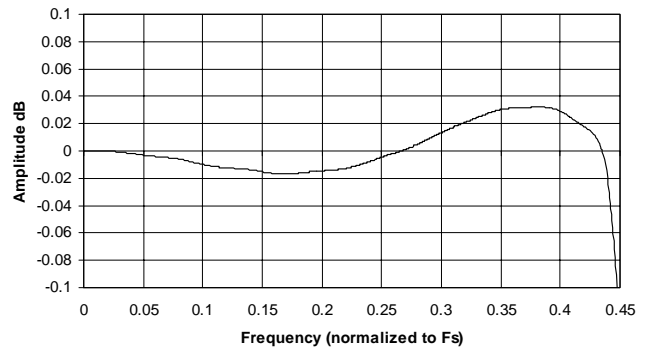


Figure 16. Double-speed Frequency Response

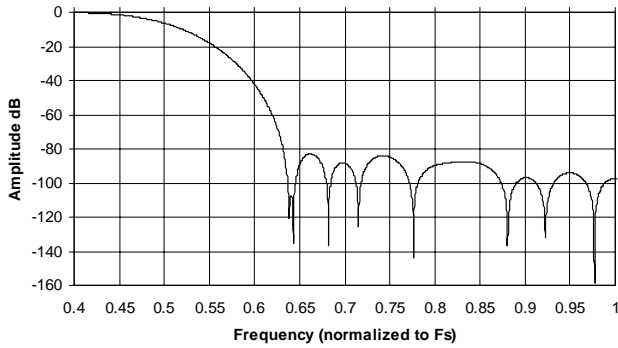


Figure 17. Quad-speed Stopband Rejection

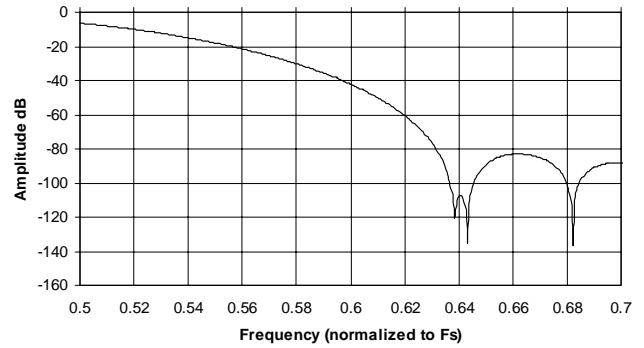


Figure 18. Quad-speed Transition Band

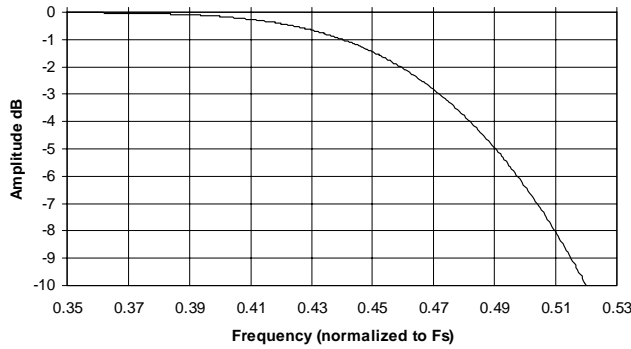


Figure 19. Quad-speed Transition Band

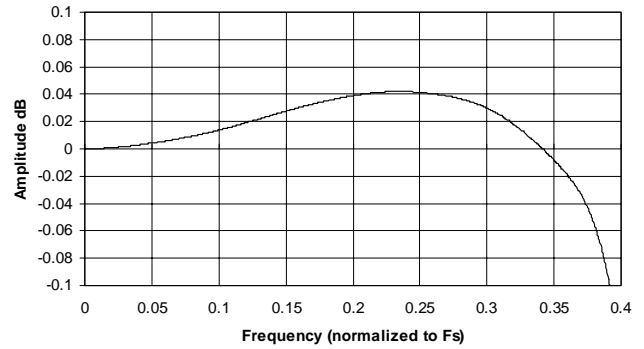


Figure 20. Quad-speed Frequency Response

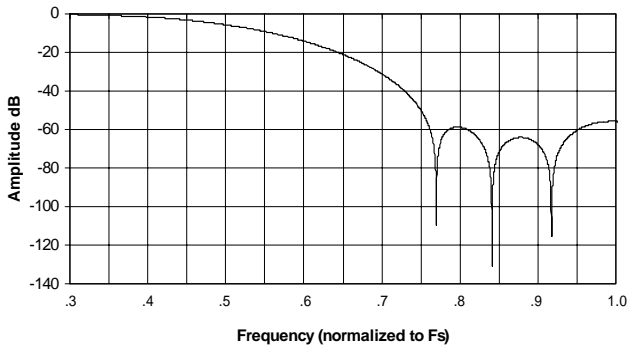


Figure 21. 8x Interpolator Stop Band

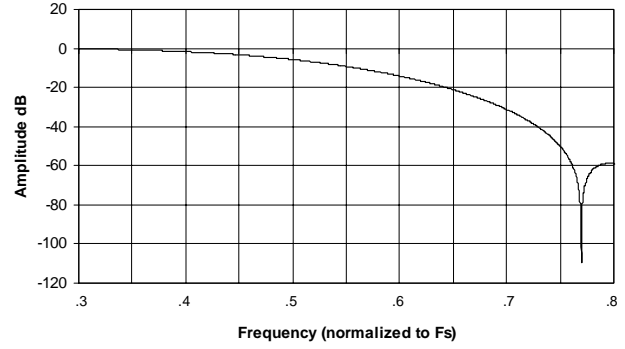


Figure 22. 8x Interpolator Transition Band

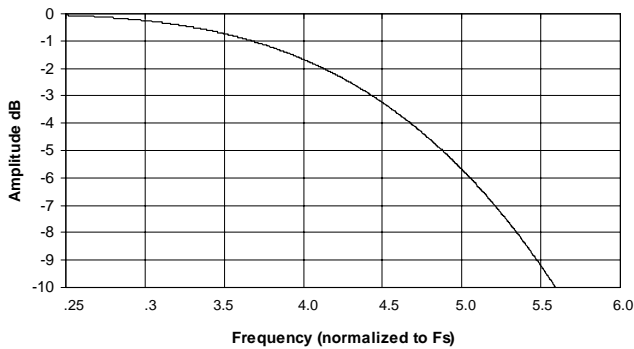


Figure 23. 8x Interpolator Transition Band

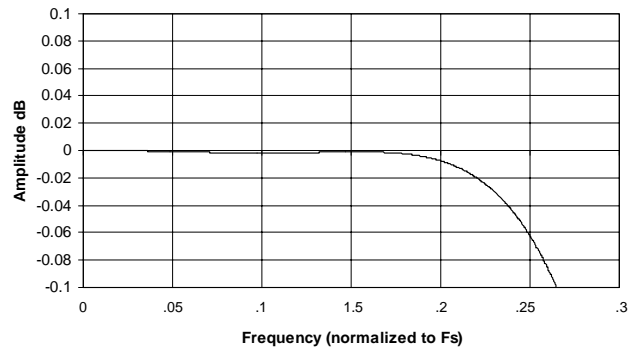


Figure 24. 8x Interpolator Frequency Response

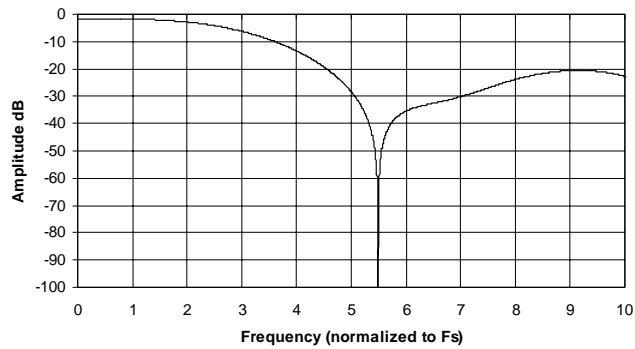


Figure 25. DSD Frequency Response

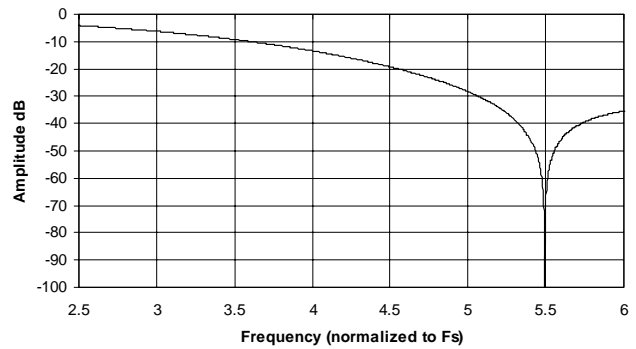


Figure 26. DSD Transition Band

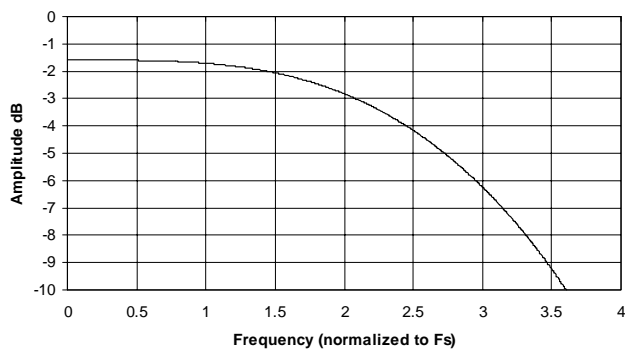


Figure 27. DSD Transition Band

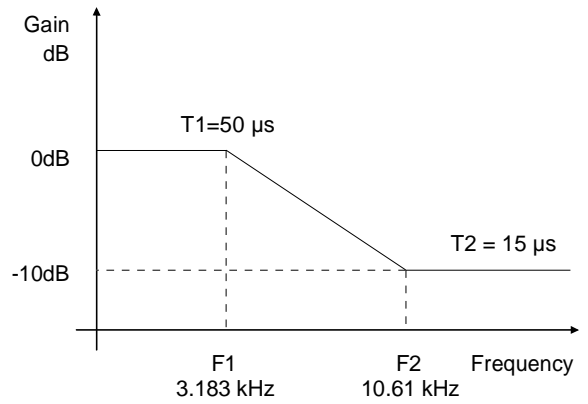


Figure 28. De-Emphasis Curve

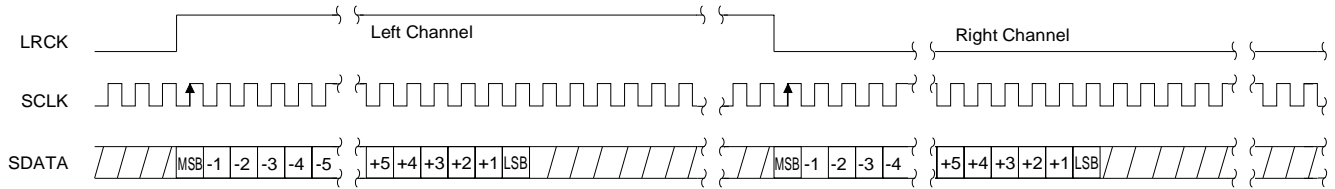


Figure 29. Format 0, Left Justified

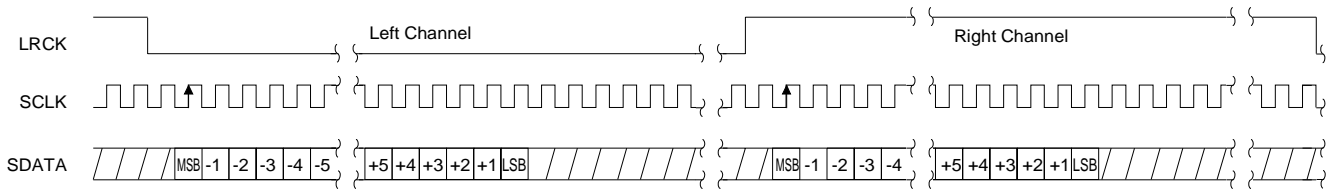


Figure 30. Format 1, I²S

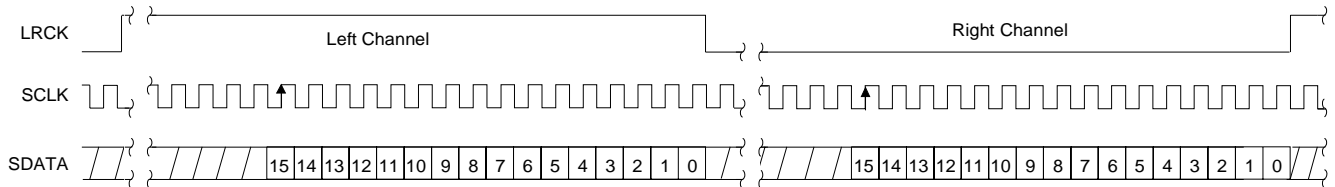


Figure 31. Format 2, Right Justified, 16-Bit Data

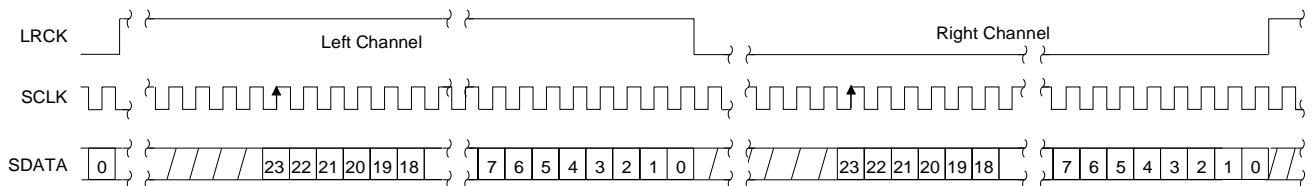


Figure 32. Format 3, Right Justified, 24-Bit Data

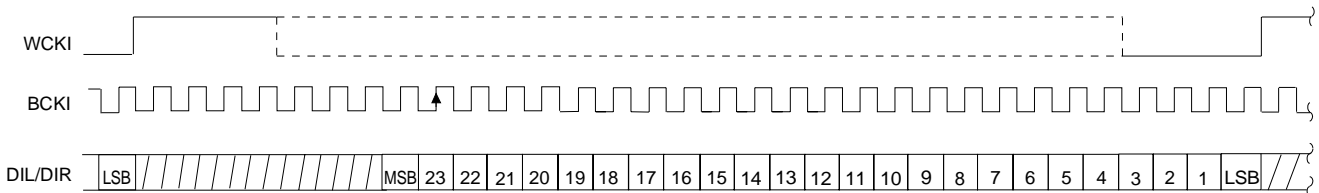


Figure 33. Format 4, 8x Interpolator Mode

9.0 PARAMETER DEFINITIONS

Total Harmonic Distortion + Noise (THD+N)

The ratio of the rms value of the signal to the rms sum of all other spectral components over the specified bandwidth (typically 10Hz to 20kHz), including distortion components. Expressed in decibels.

Dynamic Range

The ratio of the full scale rms value of the signal to the rms sum of all other spectral components over the specified bandwidth. Dynamic range is a signal-to-noise measurement over the specified bandwidth made with a -60 dBFS signal. 60 dB is then added to the resulting measurement to refer the measurement to full scale. This technique ensures that the distortion components are below the noise level and do not effect the measurement. This measurement technique has been accepted by the Audio Engineering Society, AES17-1991, and the Electronic Industries Association of Japan, EIAJ CP-307.

Interchannel Isolation

A measure of crosstalk between the left and right channels. Measured for each channel at the converter's output with all zeros to the input under test and a full-scale signal applied to the other channel. Units in decibels.

Interchannel Gain Mismatch

The gain difference between left and right channels. Units in decibels.

Gain Error

The deviation from the nominal full scale analog output for a full scale digital input.

Gain Drift

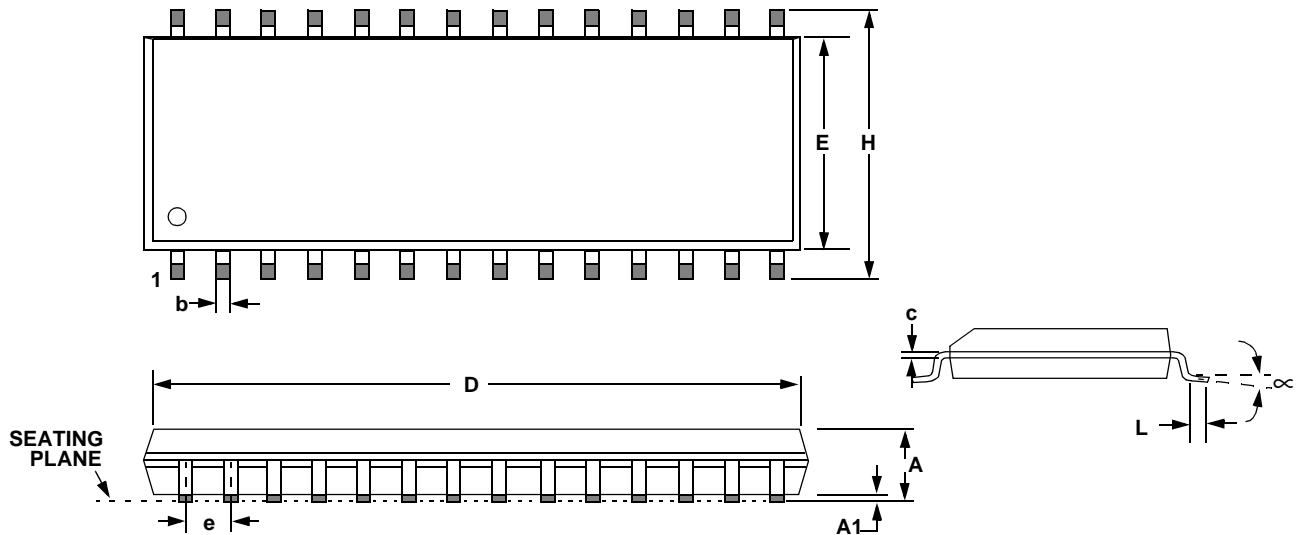
The change in gain value with temperature. Units in ppm/°C.

10.0 REFERENCES

- 1) "How to Achieve Optimum Performance from Delta-Sigma A/D & D/A Converters" by Steven Harris. Paper presented at the 93rd Convention of the Audio Engineering Society, October 1992.
- 2) CDB4397 Evaluation Board Datasheet
- 3) "The I²C-Bus Specification: Version 2.0" Philips Semiconductors, December 1998.
<http://www.semiconductors.philips.com>

11.0 PACKAGE DIMENSIONS

28L SOIC (300 MIL BODY) PACKAGE DRAWING



| DIM | INCHES | | MILLIMETERS | |
|----------|---------|-------|-------------|-------|
| | MIN | MAX | MIN | MAX |
| A | 0.093 | 0.104 | 2.35 | 2.65 |
| A1 | 0.004 | 0.012 | 0.10 | 0.30 |
| B | 0.013 | 0.020 | 0.33 | 0.51 |
| C | 0.009 | 0.013 | 0.23 | 0.32 |
| D | 0.697 | 0.713 | 17.70 | 18.10 |
| E | 0.29G10 | 0.299 | 7.40 | 7.60 |
| | 1 | | | |
| e | 0.040 | 0.060 | 1.02 | 1.52 |
| H | 0.394 | 0.419 | 10.00 | 10.65 |
| L | 0.016 | 0.050 | 0.40 | 1.27 |
| ∞ | 0° | 8° | 0° | 8° |

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• **Notes** •

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