$64 \text{ k SRAM } (8\text{-kword} \times 8\text{-bit})$ 

# HITACHI

ADE-203-618C (Z) Rev. 3.0 Nov. 1997

#### **Description**

The Hitachi HM9264B is 64k-bit static RAM organized 8-kword  $\times$  8-bit. It realizes higher performance and low power consumption by 1.5  $\mu$ m CMOS process technology. The device, packaged in 450 mil SOP (foot print pitch width), 600 mil plastic DIP, is available for high density mounting.

#### **Features**

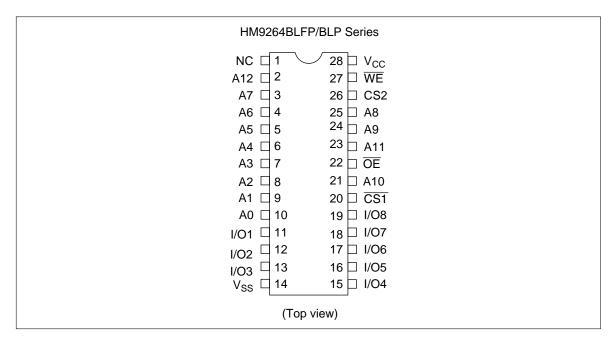
- High speed
  - Fast access time: 85/100 ns (max)
- Low power
  - Standby: 10 μW (typ)
  - Operation: 15 mW (typ) (f = 1 MHz)
- Single 5 V supply
- Completely static memory
  - No clock or timing strobe required
- Equal access and cycle times
- Common data input and output
  - Three state output
- Directly TTL compatible
  - All inputs and outputs
- Battery backup operation capability

Note: HM9264B series can't be applied for Aerospace, Aircraft, Nucleus Plants, Main Flame Computers, Medical Life-support System, and Automobile Engine Control and Industrial machines. (e.g. Communication Hubs, NC, and others.)

#### **Ordering Information**

Type No.	Access time	Package
HM9264BLFP-8L HM9264BLFP-10L	85 ns 100 ns	450-mil, 28-pin plastic SOP(FP-28DA)
HM9264BLP-8L HM9264BLP-10L	85 ns 100 ns	600-mil, 28-pin plastic DIP (DP-28)

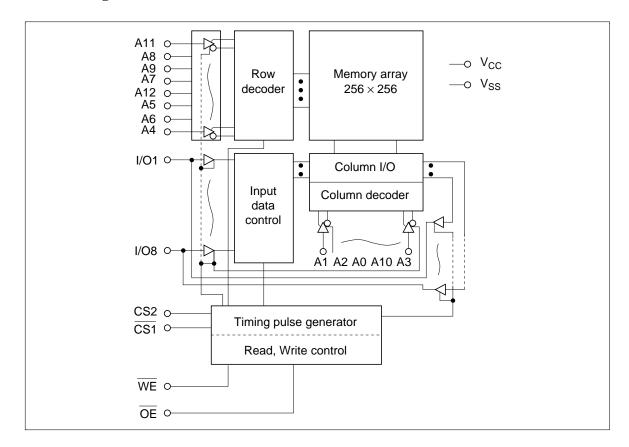
#### **Pin Arrangement**



### **Pin Description**

Function
Address input
Data input/output
Chip select 1
Chip select 2
Write enable
Output enable
No connection
Power supply
Ground

### **Block Diagram**



#### **Function Table**

WE	CS1	CS2	OE	Mode	V <sub>cc</sub> current	I/O pin	Ref. cycle
×	Н	×	×	Not selected (power down)	$I_{SB}, I_{SB1}$	High-Z	_
×	×	L	×	Not selected (power down)	I <sub>SB</sub> , I <sub>SB1</sub>	High-Z	<del>_</del>
Н	L	Н	Н	Output disable	I <sub>cc</sub>	High-Z	_
Н	L	Н	L	Read	I <sub>cc</sub>	Dout	Read cycle (1)–(3)
L	L	Н	Н	Write	I <sub>cc</sub>	Din	Write cycle (1)
L	L	Н	L	Write	I <sub>cc</sub>	Din	Write cycle (2)

Note: x: H or L

### **Absolute Maximum Ratings**

Parameter	Symbol	Value	Unit
Power supply voltage <sup>*1</sup>	V <sub>cc</sub>	-0.5 to +7.0	V
Terminal voltage <sup>*1</sup>	V <sub>T</sub>	$-0.5^{*2}$ to $V_{CC} + 0.3^{*3}$	V
Power dissipation	P <sub>T</sub>	1.0	W
Operating temperature	Topr	0 to + 70	°C
Storage temperature	Tstg	-55 to +125	°C
Storage temperature under bias	Tbias	-10 to +85	°C

Notes: 1. Relative to V<sub>ss</sub>

2.  $V_T$  min: -3.0 V for pulse half-width  $\leq 50$  ns

3. Maximum voltage is 7.0 V

### **Recommended DC Operating Conditions** ( $Ta = 0 \text{ to } +70^{\circ}C$ )

Parameter	Symbol	Min	Тур	Max	Unit
Supply voltage	V <sub>cc</sub>	4.5	5.0	5.5	V
	V <sub>ss</sub>	0	0	0	V
Input high voltage	V <sub>IH</sub>	2.2	_	V <sub>cc</sub> + 0.3	V
Input low voltage	V <sub>IL</sub>	-0.3 <sup>*1</sup>	<del>_</del>	0.8	V

Note: 1.  $V_{IL}$  min: -3.0 V for pulse half-width  $\leq 50$  ns

### DC Characteristics (Ta = 0 to +70°C, $V_{CC}$ = 5 V ±10%, $V_{SS}$ = 0 V)

Parameter	Symbol	Min	Typ <sup>*1</sup>	Max	Unit	Test conditions
Input leakage current	I <sub>LI</sub>	_	_	2	μΑ	$Vin = V_{SS} to V_{CC}$
Output leakage current	I <sub>LO</sub>	_	_	2	μΑ	$\overline{\text{CS1}} = \text{V}_{\text{IH}} \text{ or CS2} = \text{V}_{\text{IL}} \text{ or } \overline{\text{OE}} = \text{V}_{\text{IH}} \text{ or } \overline{\text{WE}} = \text{V}_{\text{IL}}, \text{ V}_{\text{I/O}} = \text{V}_{\text{SS}} \text{ to V}_{\text{CC}}$
Operating power supply current	I <sub>CCDC</sub>	_	7	15	mA	$\overline{\text{CS1}} = \text{V}_{\text{IL}}, \text{CS2} = \text{V}_{\text{IH}}, \text{I}_{\text{I/O}} = 0 \text{ mA}$ others = $\text{V}_{\text{IH}}/\text{V}_{\text{IL}}$
Average operating power supply current	I <sub>cc1</sub>	_	30	45	mA	$\frac{\text{Min cycle, duty} = 100\%,}{\overline{\text{CS1}} = \text{V}_{\text{IL}}, \text{CS2} = \text{V}_{\text{IH}}, \text{I}_{\text{I/O}} = 0 \text{ mA}}{\text{others} = \text{V}_{\text{IH}}/\text{V}_{\text{IL}}}$
	I <sub>CC2</sub>	_	3	5	mA	$\begin{split} & \frac{\text{Cycle time}}{\text{CS1}} = 1  \mu\text{s},  \text{duty} = 100\%,  I_{\text{I/O}} = 0  \text{mA} \\ & \frac{\text{CS1}}{\text{CS}} \leq 0.2 \text{ V},  \text{CS2} \geq \text{V}_{\text{CC}} - 0.2 \text{ V}, \\ & \text{V}_{\text{IH}} \geq \text{V}_{\text{CC}} - 0.2 \text{ V},  \text{V}_{\text{IL}} \leq 0.2 \text{ V} \end{split}$
Standby power supply current	I <sub>SB</sub>	_	1	3	mA	$\overline{\text{CS1}} = \text{V}_{\text{IH}}, \text{CS2} = \text{V}_{\text{IL}}$
	I <sub>SB1</sub>	_	2	50	μΑ	$\label{eq:cstate} \begin{split} \overline{CS1} &\geq V_{\text{CC}} - 0.2 \text{ V, CS2} \geq V_{\text{CC}} - 0.2 \text{ V or } \\ 0 \text{ V} &\leq \text{CS2} \leq 0.2 \text{ V, 0 V} \leq \text{Vin} \end{split}$
Output low voltage	$V_{OL}$	_		0.4	V	I <sub>OL</sub> = 2.1 mA
Output high voltage	V <sub>OH</sub>	2.4	_	_	V	$I_{OH} = -1.0 \text{ mA}$

Notes: 1. Typical values are at  $V_{cc}$  = 5.0 V, Ta = +25°C and not guaranteed.

### **Capacitance** (Ta = 25°C, f = 1.0 MHz)

Parameter	Symbol	Min	Тур	Max	Unit	Test conditions
Input capacitance*1	Cin	_	_	5	pF	Vin = 0 V
Input/output capacitance*1	C <sub>I/O</sub>		_	7	pF	V <sub>I/O</sub> = 0 V

Note: 1. This parameter is sampled and not 100% tested.

**AC Characteristics** (Ta = 0 to +70°C,  $V_{CC}$  = 5 V ± 10%, unless otherwise noted.)

#### **Test Conditions**

• Input pulse levels: 0.8 V to 2.4 V

• Input and output timing reference level: 1.5 V

• Input rise and fall time: 10 ns

• Output load: 1 TTL Gate + C<sub>L</sub> (100 pF) (Including scope & jig)

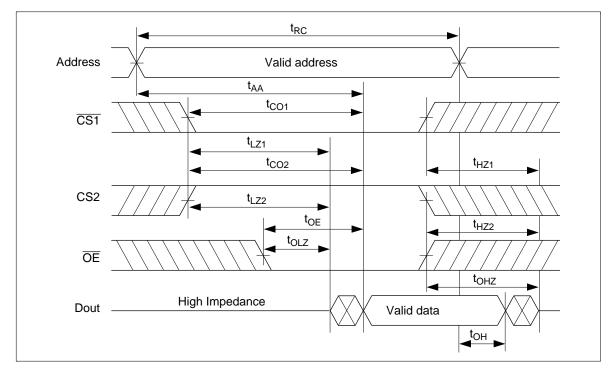
#### Read Cycle

			HM9264B-8L		HM9264B-10L			
Parameter		Symbol	Min	Max	Min	Max	Unit	Notes
Read cycle time		t <sub>RC</sub>	85	_	100	_	ns	
Address access time		t <sub>AA</sub>		85		100	ns	
Chip select access time	CS1	t <sub>co1</sub>	_	85	_	100	ns	
	CS2	t <sub>CO2</sub>	_	85		100	ns	
Output enable to output valid		t <sub>OE</sub>	_	45	_	50	ns	
Chip selection to output in low-Z	CS1	t <sub>LZ1</sub>	10	_	10	_	ns	2
	CS2	t <sub>LZ2</sub>	10		10		ns	2
Output enable to output in low-Z		t <sub>OLZ</sub>	5	_	5		ns	2
Chip deselection in to output in high-Z	CS1	t <sub>HZ1</sub>	0	30	0	35	ns	1, 2
	CS2	t <sub>HZ2</sub>	0	30	0	35	ns	1, 2
Output disable to output in high-Z		t <sub>OHZ</sub>	0	30	0	35	ns	1, 2
Output hold from address change		t <sub>oH</sub>	10	_	10	_	ns	

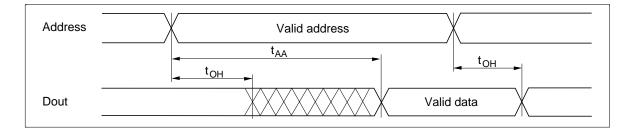
Notes: 1. t<sub>HZ</sub> is defined as the time at which the outputs achieve the open circuit conditions and are not referred to output voltage levels.

- 2. At any given temperature and voltage condition,  $t_{HZ}$  maximum is less than  $t_{LZ}$  minimum both for a given device and from device to device.
- 3. Address must be valid prior to or simultaneously with CS1 going low or CS2 going high.

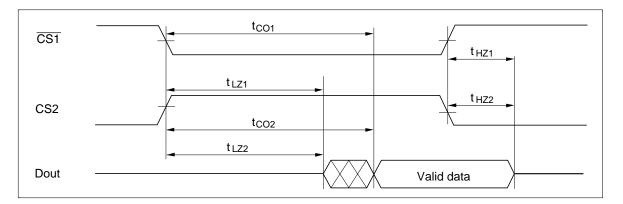
### Read Timing Waveform (1) $(\overline{WE} = V_{IH})$



### Read Timing Waveform (2) $(\overline{WE} = V_{IH}, \overline{OE} = V_{IL})$



Read Timing Waveform (3)  $(\overline{WE} = V_{IH}, \overline{OE} = V_{IL})^{*3}$ 



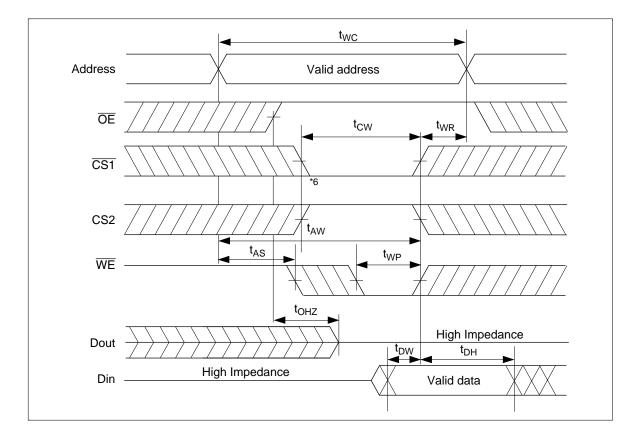
#### Write Cycle

		HM9264B-8L		HM9264B-10L			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
Write cycle time	t <sub>wc</sub>	85	_	100	_	ns	
Chip selection to end of write	t <sub>cw</sub>	75	_	80	_	ns	2
Address setup time	t <sub>AS</sub>	0	_	0	_	ns	3
Address valid to end of write	t <sub>AW</sub>	75	_	80	_	ns	
Write pulse width	t <sub>WP</sub>	55	_	60	_	ns	1, 9
Write recovery time	t <sub>wR</sub>	0	_	0	_	ns	4
WE to output in high-Z	t <sub>wHZ</sub>	0	30	0	35	ns	5
Data to write time overlap	t <sub>DW</sub>	40	_	40	_	ns	
Data hold from write time	t <sub>DH</sub>	0	_	0	_	ns	
Output active from end of write	t <sub>ow</sub>	5	_	5	_	ns	
Output disable to output in high-Z	t <sub>OHZ</sub>	0	30	0	35	ns	5

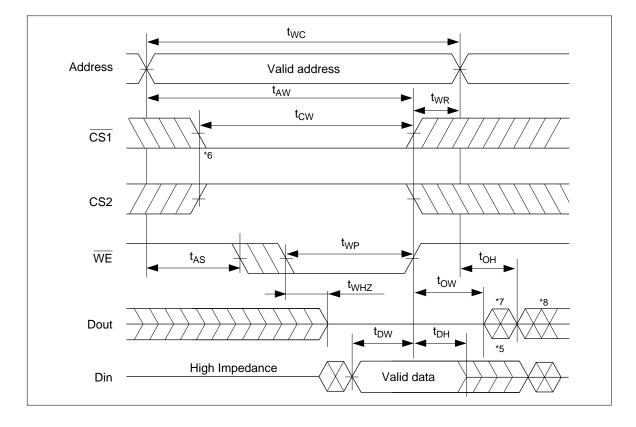
- Notes: 1. A write occurs during the overlap of a low  $\overline{CS1}$ , and high  $\overline{CS2}$ , and a high  $\overline{WE}$ . A write begins at the latest transition among  $\overline{CS1}$  going low,CS2 going high and  $\overline{WE}$  going low. A write ends at the earliest transition among  $\overline{CS1}$  going high CS2 going low and  $\overline{WE}$  going high. Time  $t_{WP}$  is measured from the beginning of write to the end of write.
  - 2.  $t_{CW}$  is measured from the later of  $\overline{CS1}$  going low or CS2 going high to the end of write.
  - 3.  $\,t_{\mbox{\tiny AS}}$  is measured from the address valid to the beginning of write.
  - 4.  $t_{WR}$  is measured from the earliest of  $\overline{CS1}$  or  $\overline{WE}$  going high or CS2 going low to the end of write cycle.
  - 5. During this period, I/O pins are in the output state, therefore the input signals of the opposite phase to the outputs must not be applied.
  - 6. If  $\overline{\text{CS1}}$  goes low simultaneously with  $\overline{\text{WE}}$  going low after  $\overline{\text{WE}}$  goes low, the outputs remain in high impedance state.
  - 7. Dout is the same phase of the written data in this write cycle.
  - 8. Dout is the read data of the next address
  - In the write cycle with OE low fixed, t<sub>WP</sub> must satisfy the following equation to avoid a problem of data bus contention

 $t_{WP} \ge t_{WHZ} \max + t_{DW} \min$ .

#### Write Timing Waveform (1) $(\overline{OE} \operatorname{Clock})$



### Write Timing Waveform (2) $(\overline{OE} Low Fixed) (\overline{OE} = V_{IL})$



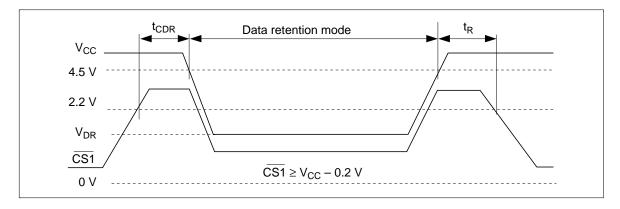
#### **Low V**<sub>CC</sub> **Data Retention Characteristics** (Ta = 0 to +70°C)

Parameter	Symbol	Min	Typ <sup>*1</sup>	Max	Unit	Test conditions <sup>4</sup>
V <sub>cc</sub> for data retention	$V_{DR}$	2.0	_	_	V	$\overline{\text{CS1}} \ge \text{V}_{\text{CC}} - 0.2 \text{ V},$ $\text{CS2} \ge \text{V}_{\text{CC}} - 0.2 \text{ V or CS2} \le 0.2 \text{ V}$
Data retention current	I <sub>CCDR</sub>		1*1	25*2	μА	$\begin{array}{c} V_{\text{CC}} = 3.0 \text{ V}, \ 0 \text{ V} \leq \text{Vin} \leq \text{V}_{\text{CC}} \\ \hline \text{CS1} \geq \text{V}_{\text{CC}} - 0.2 \text{ V}, \ \text{CS2} \geq \text{V}_{\text{CC}} - 0.2 \text{ V} \\ \text{or } 0 \text{ V} \leq \text{CS2} \leq 0.2 \text{ V} \end{array}$
Chip deselect to data retention time	t <sub>CDR</sub>	0	_	_	ns	See retention waveform
Operation recovery time	t <sub>R</sub>	t <sub>RC</sub> *3	_	_	ns	

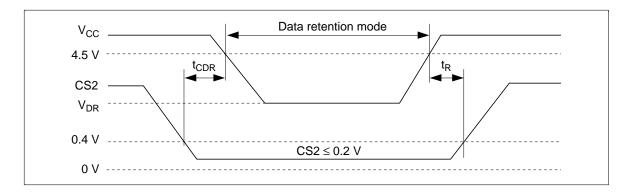
Notes: 1. Reference data at Ta = 25°C.

- 2.  $10 \mu A \text{ max at Ta} = 0 \text{ to} + 40 ^{\circ} \text{C}.$
- 3.  $t_{RC}$  = read cycle time.
- 4. CS2 controls address buffer, WE buffer, CS1 buffer, OE buffer, and Din buffer. If CS2 controls data retention mode, Vin levels (address, WE, OE, CS1, I/O) can be in the high impedance state. If CS1 controls data retention mode, CS2 must be CS2 ≥ V<sub>cc</sub> − 0.2 V or 0 V ≤ CS2 ≤ 0.2 V. The other input levels (address, WE, OE, I/O) can be in the high impedance state.

#### $Low~V_{CC}~Data~Retention~Timing~Waveform~(1)~(\overline{CS1}~Controlled)$



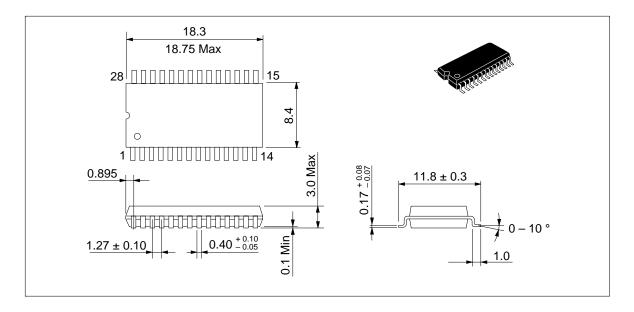
Low V<sub>CC</sub> Data Retention Timing Waveform (2) (CS2 Controlled)



### **Package Dimensions**

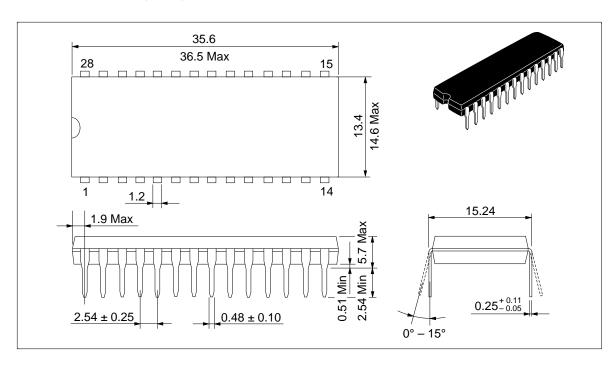
#### HM9264BLFP Series (FP-28DA)

Unit: mm



#### HM9264BLP Series (DP-28)

Unit: mm



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# HITACHI

#### Hitachi, Ltd.

Semiconductor & IC Div. Nippon Bldg., 2-6-2, Ohte-machi, Chiyoda-ku, Tokyo 100, Japan Tel: Tokyo (03) 3270-2111

Fax: (03) 3270-5109

#### For further information write to:

Hitachi America, Ltd. Semiconductor & IC Div. 2000 Sierra Point Parkway Brisbane, CA. 94005-1835 U S A

Tel: 415-589-8300 Fax: 415-583-4207 Hitachi Europe GmbH Electronic Components Group Continental Europe Dornacher Straße 3 D-85622 Feldkirchen München Tel: 089-9 91 80-0 Fax: 089-9 29 30 00 Hitachi Europe Ltd.
Electronic Components Div.
Northern Europe Headquarters
Whitebrook Park
Lower Cookham Road
Maidenhead
Berkshire SL6 8YA
United Kingdom

Tel: 0628-585000 Fax: 0628-778322 Hitachi Asia Pte. Ltd. 16 Collyer Quay #20-00 Hitachi Tower Singapore 0104 Tel: 535-2100 Fax: 535-1533

Hitachi Asia (Hong Kong) Ltd. Unit 706, North Tower, World Finance Centre, Harbour City, Canton Road Tsim Sha Tsui, Kowloon Hong Kong

Tel: 27359218 Fax: 27306071