

# FS8107E Low Power Phase-Locked Loop IC

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# Description

The FS8107E is a serial data input, phase-locked loop IC with programmable input and reference frequency dividers. When combined with a VCO, the FS8107E becomes the core of a very low power frequency synthesizer well-suited for mobile communication applications such as paging systems. **Compared to the FS8100, the FS8107E is housed in a smaller package and also implements a separate pin for stand-by control.** 

### Features

- High maximum input operating frequency 100 MHz at  $V_{DD1} = 1.0 V$
- Up to 22 MHz internal crystal oscillator reference frequency at  $V_{DD1} = 1.0 \text{ V}$
- Extremely low current consumption ( $I_{DD,total}$  typically 0.4 mA at  $f_{FIN} = 90$  MHz)
- ♦ 16-bit programmable input frequency divider (including a ÷ 32/33 prescaler) with divide ratio range from 992 to 65535
- ◆ 13-bit programmable reference frequency divider (including a ÷ 8 prescaler) with divide ratio range from 40 to 65528
- Optional lock detector output
- Charge pump output for passive low-pass filter
- Quick-lock signal output for faster locking
- Separate pin for stand-by control
- TSSOP 16L package (0.65mm pitch)

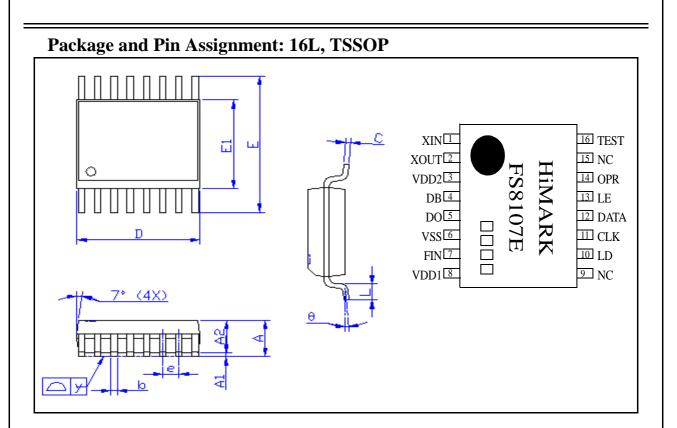
#### Applications

- Pager
- Wireless communication system

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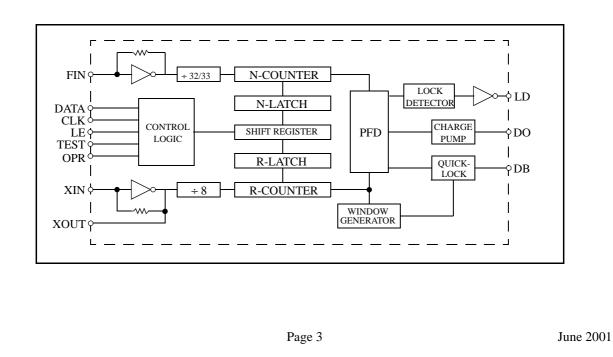
Symbols	Dimensions in mm			Dimensions in inch			
Symbols	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	
А			1.20			0.048	
A1	0.05		0.15	0.002		0.006	
A2	0.80	1.00	1.05	0.031	0.039	0.041	
b	0.19		0.30	0.007		0.012	
С	0.09		0.20	0.004		0.008	
D	4.90	5.00	5.10	0.193	0.197	0.201	
Е		6.40			0.252		
E1	4.30	4.40	4.50	0.169	0.173	0.177	
e		0.65			0.026		
L	0.45	0.60	0.75	0.018	0.024	0.030	
У			0.10			0.004	
θ	0°		8°	$0^{\circ}$		8°	

Note: Tolerance  $\pm 0.1$  mm unless otherwise specified

# **Pin Descriptions**

Number	Name	I/O	Description
1	XIN	Ι	Reference crystal oscillator or external clock input with internally biased amplifier (any external input to XIN must be ac-coupled)
2	XOUT	0	Reference crystal oscillator or external clock output
3	VDD2	POWER	Nominal 3.0 V supply voltage
4	DB	0	Single-ended quick-lock output for faster locking
5	DO	0	Single-ended charge pump output for passive low pass filter
6	VSS	GND	Ground
7	FIN	Ι	VCO frequency input with internally biased input amplifier (any external input to FIN must be ac-coupled)
8	VDD1	POWER	Nominal 1.0 V supply voltage
9	NC	NC	No connection
10	LD	0	Lock detector output (high when PLL is locked)
11	CLK	Ι	Shift register clock input
12	DATA	Ι	Serial data input
13	LE	Ι	Latch enable input
14	OPR	Ι	Battery-save control input; normal operation when high, stand-by mode when low
15	NC	NC	No connection
16	TEST	Ι	Test mode control input with internal pull-down resistor

# **Block Diagram**



## **Absolute Maximum Ratings**

 $V_{SS} = 0 V$ 

Parameter	Symbol	Rating	Unit
Supply voltage	V <sub>DD1</sub>	$V_{SS}$ – 0.3 to $V_{SS}$ + 2.0	V
Supply voltage	V <sub>DD2</sub>	$V_{SS}{-}0.3$ to $V_{SS}{+}7.0$	V
Input voltage range	$V_{\text{FIN}}$	$V_{SS}{-}0.3$ to $V_{DD}{+}0.3$	V
Operating temperature range	T <sub>OPR</sub>	-10 to 60	°C
Storage temperature range	T <sub>STG</sub>	-40 to 125	°C
Soldering temperature range	T <sub>SLD</sub>	255	°C
Soldering time range	t <sub>SLD</sub>	10	s

# **Recommended Operating Conditions**

 $V_{ss} = 0 V$ 

Parameter	Symbol	Value			Unit	
Parameter		min.	typ.	max.	Unit	
Supply voltage range	$V_{DD1}$	0.95	1.0	2.0	v	
Supply voltage range	V <sub>DD2</sub>	2.0	3.0	3.3	v	
Operating temperature	T <sub>A</sub>	-10	25	60	°C	

# **Electrical Characteristics**

 $(V_{DD1} = 0.95 \text{ to } 2.0 \text{ V}, V_{DD2} = 2.7 \text{ to } 3.3 \text{ V}, V_{SS} = 0 \text{ V}, T_A = 0 \text{ to } 60^{\circ}\text{C}$  unless otherwise noted)

Demonster	Symbol	Condition	Value			TT '4
Parameter		Condition	min.	typ.	max.	Unit
Current consumption	$I_{DD,total}$	$\begin{split} \mathbf{V}_{\mathrm{DD1}} &= 1.0 \text{ V}, \text{OPR}="\text{H"}, \\ \mathbf{V}_{\mathrm{FIN}} &= 0.3 \text{ V}_{\mathrm{pk-pk}} \text{ sinusoid}, \\ \mathbf{f}_{\mathrm{FIN}} &= 100 \text{ MHz}, \\ \mathbf{V}_{\mathrm{XIN}} &= 0.3 \text{ V}_{\mathrm{pk-pk}} \text{ sinusoid}, \\ \mathbf{f}_{\mathrm{XIN}} &= 12.8 \text{ MHz} \end{split}$		0.40	1.10	mA
Standby current consumption $(I_{DD2})$	I <sub>DD,standby</sub>	$V_{DD1} = 0$ V, OPR="L"			10	μΑ
FIN max. operating frequency	f <sub>FIN,max</sub>	$V_{FIN} = 0.3 V_{pk-pk}$ sinusoid	100			MHz
FIN min. operating frequency	f <sub>FIN,min</sub>	$V_{FIN} = 0.3 V_{pk-pk}$ sinusoid			40	MHz
XIN max. operating frequency	f <sub>XIN,max</sub>	$V_{XIN} = 0.3 V_{pk-pk}$ sinusoid	22			MHz
XIN min. operating frequency	f <sub>XIN,min</sub>	$V_{XIN} = 0.3 V_{pk-pk}$ sinusoid			7	MHz
FIN input voltage swing	V <sub>FIN</sub>		0.3			V <sub>pk-pk</sub>
XIN input voltage swing	V <sub>XIN</sub>		0.3			V <sub>pk-pk</sub>
CLK, DATA, LE logic LOW input voltage	V <sub>IL</sub>				0.3	V
CLK, DATA, LE logic HIGH input voltage	V <sub>IH</sub>		1.5			V
XIN logic LOW input current	I <sub>IL,XIN</sub>	$V_{IL} = 0 V$			10	μΑ
XIN logic HIGH input current	I <sub>IH,XIN</sub>	$V_{IH} = V_{DD1}$			10	μΑ
FIN logic LOW input current	I <sub>IL,FIN</sub>	$V_{IL} = 0 V$			60	μΑ
FIN logic HIGH input current	I <sub>IH,FIN</sub>	$\mathbf{V}_{\mathrm{IH}} = \mathbf{V}_{\mathrm{DD1}}$			60	μΑ
DO logic LOW output current	I <sub>OL,DOP</sub>	$V_{OL} = 0.4 V$	1.0			mA
DO logic HIGH output current	I <sub>OH,DOP</sub>	$V_{OH} = V_{DD2} - 0.4 V$	1.0			mA
LD, FV, FR logic LOW output current	I <sub>OL</sub>	$V_{OL} = 0.4 V$	0.1			mA
LD, FV, FR logic HIGH output current	I <sub>OH</sub>	$V_{OH} = V_{DD2} - 0.4 V$	0.1			mA
DATA to CLK setup time	t <sub>su1</sub>		2			μs
CLK to LE setup time	t <sub>SU2</sub>		2			μs
Hold time	t <sub>HOLD</sub>		2			μs

### **Functional Description**

#### **Programmable Input Frequency Divider**

The VCO input to the FIN pin is divided by the programmable divider and then internally output to the phase/frequency detector (PFD) as  $f_V$ . The programmable input frequency divider consists of a  $\div$  32/33 (*P*/*P*+1) dual-modulus prescaler and a 16-bit (*N*) counter, which is further comprised of a 5-bit swallow (*A*) counter, and a 11-bit main (*B*) counter. The total divide ratio, *M*, is related to values for *P*, *A*, and *B* through the relation

 $M = (P+1) \times A + P \times (B-A) = P \times B + A,$ 

with  $B \ge A$ . The minimum programmable divisor for continuous counting is given by  $P \times (P-1) = 32 \times 31 = 992$ , and the valid total divide ratio range for the input divider is M = 992 to 65535.

#### **Programmable Reference Frequency Divider**

The crystal oscillator output is divided by the programmable divider and then internally output to the PFD as  $f_R$ . The programmable reference frequency divider consists of a fixed  $\div 8$  (*S*) prescaler and a 13-bit reference (*R*) counter. The total divide ratio, *T*, is related to values for *S* and *R* through the relation

$$T = S \times R = 8 \times R.$$

The usable divisor range of reference counter is R = 5 to 8191, and therefore, the valid total divide ratio range for the reference divider is T = 40 to 65528 (in steps of 8.)

#### Serial Input Data Format

The divide ratios for the input and reference dividers are input using a 17-bit serial interface consisting of separate clock (CLK), data (DATA), and latch enable (LE) lines. The format of the serial data is shown in Fig. 1. The data on the DATA line is written to the shift register on the rising edge of the CLK signal and is input with MSB first, and the last (17th) bit is used as the latch select control bit. The data on the DATA line should be changed on the falling edge of CLK, and LE should be held low while data is being written to the shift register. Data is transferred from the shift register to one of the frequency divider latches when LE being set high. When the 17th bit is set low, data is loaded to the 16-bit *N*-counter latch, and when the 17th bit is set high, the 13 MSBs are loaded to the

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13-bit *R*-counter latch and the remaining 3 LSBs are used to control testing modes and should be set as follows for normal operation: R14 = high, R15 = low, R16 = low. To disable LD output (i.e. set LD low), R14 should be set low.

Serial input data timing waveforms are shown in Fig. 2.

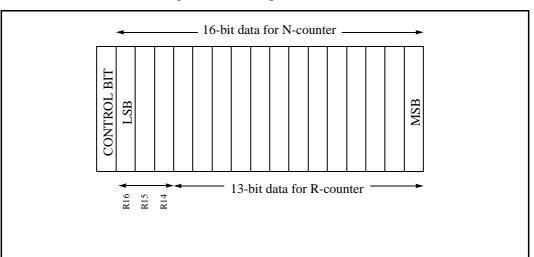
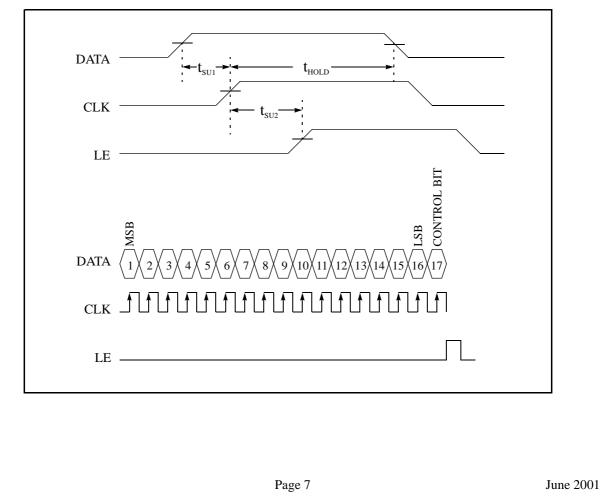


Fig. 1 – Serial input data format

#### Fig. 2 – Serial input data timing waveforms

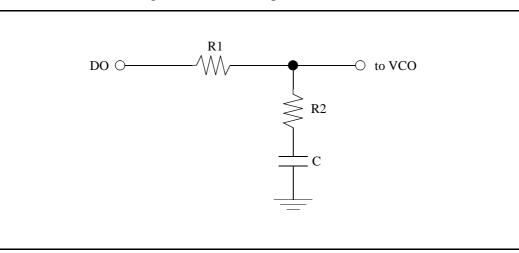


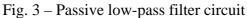
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### **Phase/Frequency Detector (PFD)**

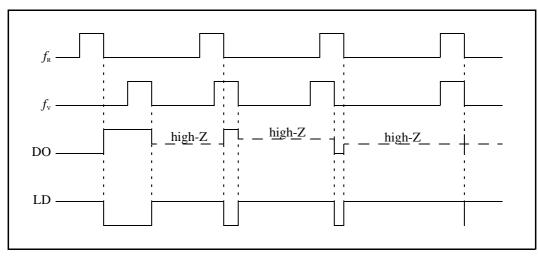
The PFD compares an internal input frequency divider output signal,  $f_V$ , with an internal reference frequency divider output signal,  $f_R$ , and generates an error signal, DO, which is proportional to the phase error between  $f_V$  and  $f_R$ . The DO output is intended for use with a passive filter as shown in Fig. 3.

The input/output waveforms for the PFD are shown in Fig. 4.





#### Fig. 4 – PFD input/output waveforms



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### Quick-lock Signal (DB)

The quick-lock output signal, DB, is provided so that the PLL may achieve higher speed locking. When connected, the DB output effectively doubles the charge pump current output to the loop filter during the initial start-up of the PLL (when OPR first goes high). Once the PLL phase error is within a specific tolerance, the quick-lock circuitry sets the DB output to a high impedance state and the PLL continues toward lock with its normal charge pump current.

#### Stand-by Mode

The stand-by mode for the PLL is entered by setting the OPR pin low and  $V_{DD1}$  to 0 V while the circuit is in operation. In the stand-by mode, the XIN and FIN amplifiers, *N*-counter, and *R*-counter are stopped, the *N*- and *R*-counters are also reset, and the DO and DB outputs are set to the high impedance state. As long as voltage is supplied to  $V_{DD2}$ , data loaded to the latches is kept. To exit from stand-by mode to normal operation, the OPR pin must be set high and voltage must again be supplied to  $V_{DD1}$ .

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# **Application Circuit**

