## Power driver IC for CD changer

## BD7961FM

BD7961FM is a 6-channel driver IC developed for CD changer. In addition to the 4-channel BTL driver and the 2-channel loading driver, the 3.3 V regulator and 5.0 V regulator used in the peripheral circuit are also incorporated. The size reduction of the set is achieved by integrating functions that were used in two chips into a single chip.

## - Applications

CD changer

## -Features

1) This circuit is a 6-channel driver IC consisting of four BTL drivers and two loading drivers.
2) Two wide dynamic range loading drivers of MOS output ( $R$ on=1.0 2 ).
3) The circuit is provided with loading driver voltage setting terminals.
4) A 5.0 V regulator and a 3.3 V regulator are built in.
(Each regulator has an external PNP transistor and an ON/OFF switch)
5) The circuit has a mute switch.
6) A thermal shutdown circuit is built in.
7) Since HSOP-M36 power package is used, the set requires a reduced space.

- Absolute maximum ratings $\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right)$

| Parameter | Symbol | Limits | Unit |
| :--- | :---: | :---: | :---: |
| Supply voltage | Vcc | 15 | V |
| Power dissipation | Pd | $2200^{*}$ | mW |
| Operating temperature range | Topr | -35 to +85 | ${ }^{\circ} \mathrm{C}$ |
| Storage temperature range | Tstg | -55 to +150 | ${ }^{\circ} \mathrm{C}$ |

* Reduced by 17.6 mW for each increase in Ta of $1^{\circ} \mathrm{C}$ over $25^{\circ} \mathrm{C}$, on less than $3 \%$
(percentage occupied by copper foil), $70 \mathrm{~mm} \times 70 \mathrm{~mm}, \mathrm{t}=1.6 \mathrm{~mm}$, glass epoxy mounting.
- Recommended operating conditions $\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right)$

| Parameter | Symbol | Min. | Typ. | Max. | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Supply voltage 1 | Vcc1 | 4.5 | 8.0 | 14.0 | V |
| Supply voltage 2 | $\mathrm{Vcc2}$ | 4.5 | 8.0 | 14.0 | V |
| Supply voltage 3* $^{*}$ | $\mathrm{Vcc3}$ | 6.0 | 8.0 | 14.0 | V |

[^0]-Block diagram


## -Pin descriptions

| Pin No. | Pin name | Function | Pin No. | Pin name | Function |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | GND2 | POW GND (loading driver unit) | 19 | OUT3+ | BTL driver (CH3) output + |
| 2 | OUT5- | Loading driver (CH5) output - | 20 | OUT3- | BTL driver ( CH 3 ) output - |
| 3 | OUT5+ | Loading driver (CH5) output + | 21 | OUT4+ | BTL driver (CH4) output + |
| 4 | IN5FWD | Loading driver (CH5) FWD input | 22 | OUT4- | BTL driver ( CH 4 ) output - |
| 5 | IN5REV | Loading driver (CH5) REV input | 23 | LDCONT2 | Loading driver (CH6) voltage setting terminal |
| 6 | IN6REV | Loading driver (CH6) REV input | 24 | LDCONT1 | Loading driver (CH5) voltage setting terminal |
| 7 | IN6FWD | Loading driver (CH6) FWD input | 25 | Vcc1 | Supply voltage (BTL driver unit) |
| 8 | REG2SW | Regulator 2 switch terminal | 26 | Vcc3 | Supply voltage (regulator unit) |
| 9 | REG1SW | Regulator 1 switch terminal | 27 | GND3 | REG GND (regulator unit) |
| 10 | IN4 | CH4 input | 28 | Vcc2 | Supply voltage (loading driver unit) |
| 11 | IN3 | CH3 input | 29 | REG1OUT | Regulator 1 output |
| 12 | IN1 | CH1 input | 30 | REG1_B | Regulator 1 Tr base |
| 13 | IN2 | CH2 input | 31 | REG2_B | Regulator 2 Tr base |
| 14 | GND1 | POW GND (BTL driver unit) | 32 | REG2OUT | Regulator 2 output |
| 15 | OUT2- | BTL driver ( CH 2$)$ output - | 33 | MUTE | BTL driver mute terminal |
| 16 | OUT2+ | BTL driver ( CH 2$)$ output + | 34 | OUT6+ | Loading driver (CH6) output + |
| 17 | OUT1- | BTL driver (CH1) output - | 35 | OUT6- | Loading driver (CH6) output - |
| 18 | OUT1+ | BTL driver (CH1) output + | 36 | BIAS | BIAS terminal |

## Optical disc ICs

## - Input output circuit

(N1/IN2/IN3/IN4
(20)

## Optical disc ICs

## －Electrical characteristics

（unless otherwise noted， $\mathrm{Ta}=25^{\circ} \mathrm{C}, \mathrm{Vcc} 1, \mathrm{Vcc} 2, \mathrm{Vcc} 3=8 \mathrm{~V}, \mathrm{BIAS}=2.5 \mathrm{~V}, \mathrm{RL}=8 \Omega$ ）

| Parameter | Symbol | Min． | Typ． | Max． | Unit | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Quiescent current | Icc1 | 12 | 25 | 38 | mA | Under no load |
| Quiescent current（BTL MUTE） | Icc2 | 5 | 10 | 15 | mA | Under no load |
| 〈 BTL driver CH 1 to CH 4 〉 |  |  |  |  |  |  |
| Output offset voltage | Vofs | －70 | 0 | ＋70 | mV |  |
| Max．output amplitude | Vom | 5.4 | 6.0 | － | V |  |
| Closed circuit voltage gain | Gvc | 16 | 18 | 20 | dB | $\mathrm{V}_{\mathrm{I}=}=\mathrm{BIAS} \pm 0.5 \mathrm{~V}$ |
| Difference between positive and nagative voltage gains | $\Delta$ Grc | －2．0 | 0 | 2.0 | dB |  |
| 〈 Loading driver CH 5 and CH 6 〉 |  |  |  |  |  |  |
| Output offset voltage | VofsL | －35 | 0 | ＋35 | mV | When brake is applied |
| Output saturation voltage H | Vo나 | － | 0.32 | 0.48 | V | $1 \mathrm{l}=500 \mathrm{~mA}$ |
| Output saturation voltage L | Voll | － | 0.18 | 0.27 | V | $1 \mathrm{l}=500 \mathrm{~mA}$ |
| Voltage gain | Gvld | 4.0 | 6.0 | 8.0 | dB | LDCONT＝1V |
| Difference between positive and nagative voltage gains | $\Delta$ Gvid | －2．0 | 0 | 2.0 | dB |  |
| ＜Regulator 1＞ |  |  |  |  |  |  |
| Output voltage | Vregi | 3.135 | 3.300 | 3.465 | V |  |
| Output load stability | $\Delta V_{\text {RL1 }}$ | 5 | 10 | 20 | mV | $\mathrm{l}=0 \sim 200 \mathrm{~mA}$ |
| Supply voltage stability | $\Delta \mathrm{V} \mathrm{Vcc}^{1}$ | 5 | 10 | 20 | mV | $\mathrm{V} \mathrm{cc}=6 \sim 10 \mathrm{~V}$ Io $=100 \mathrm{~mA}$ |
| REG1＿B terminal sink current | Iregsi1 | 2 | － | － | mA |  |
| ＜Regulator 2＞ |  |  |  |  |  |  |
| Output voltage | Vreg2 | 4.75 | 5.00 | 5.25 | V |  |
| Output load stability | $\Delta V_{\text {RL2 }}$ | 5 | 10 | 20 | mV | $\mathrm{lo}=0 \sim 200 \mathrm{~mA}$ |
| Supply voltage stability | $\Delta \mathrm{VV} \mathrm{cc}^{2}$ | 5 | 10 | 20 | mV | $\mathrm{Vcc}=7 \sim 10 \mathrm{~V}$ lo $=100 \mathrm{~mA}$ |
| RE2＿B terminal sink current | Ireasiz | 2 | － | － | mA |  |

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## - Measurement circuits



Fig. 1


Fig. 2


Fig. 3

## Optical disc ICs

## －Switch table for measuring circuit diagrams

（unless otherwise noted， $\mathrm{Ta}=25^{\circ} \mathrm{C}, \mathrm{Vcc} 1, \mathrm{Vcc} 2, \mathrm{Vcc} 3=8 \mathrm{~V}, \mathrm{BIAS}=2.5 \mathrm{~V}, \mathrm{RL}=8 \Omega$ Unless otherwise specified，the switch 1 is used．）

| Parameter | Symbol | SWITCH |  | Conditions | Measurement circuit |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 1 | 2 |  |  |
| Quiescent current | Icc1 |  |  | ＊1 | Fig． 1 |
| Quiescent current（BTL MUTE） | lcc2 |  |  | ＊2 | Fig． 1 |
| 〈BTLdriver CH 1 to CH 4 〉 |  |  |  |  |  |
| Output offset voltage | Vofs |  |  | V In $=\mathrm{VB}$ ，VOFS $=\mathrm{VO}$ | Fig． 2 |
| Max．output amplitude | Vом |  |  | V in＝$=\mathrm{Vcc}$ ， $\mathrm{VOM}=\mathrm{VO}$ | Fig． 2 |
| Closed circuit voltage gain（ CH 1 to CH 4 ） | Gvc |  |  | $\mathrm{V} \mathrm{IN}=\mathrm{VB} \pm 0.5 \mathrm{~V}, \mathrm{GVC}=20 \log (\mathrm{VO} / 0.5)$ | Fig． 2 |
| Difference between positive and negative voltage gains（CH1 to CH 4 ） | $\Delta \mathrm{Gvc}$ |  |  |  | Fig． 2 |
| Mute terminal sink current | Imute |  |  | VMUTE＝5V，IMUTE＝IMUTE | Fig． 1 |
| Bias terminal sink current | Ibias |  |  | $\mathrm{VB}=2.5 \mathrm{~V}$ ，IBIAS＝IQB | Fig． 1 |
| ＜Loading driver CH 5 and CH 6 〉 |  |  |  |  |  |
| Output offset voltage | VofsL |  |  | LDINF＝LDINR＝5V，VOFSL＝VOLD | Fig． 3 |
| Output saturation voltage H | Volh | 2 |  | ＊3 | Fig． 3 |
| Output saturation voltage L | Voll | 2 |  | LDINF＝5V，LDINR＝0V，IDR＝500mA，VOLL＝VOLR | Fig． 3 |
| Voltage gain（Loading） | Gvid |  |  | ＊ 4 | Fig． 1 |
| Difference between positive and negative voltage gains（Loading） | $\Delta$ GvLD |  |  |  | Fig． 1 |
| Input terminal sink current | lint |  |  | LDINF＝LDINR＝5V，IINL＝IQ5F，IQ5R，IQ6F，IQ6R | Fig． 1 |
| LDCONT terminal source current | ILDC |  |  | LDCONT＝5V，ILDC＝ILDC | Fig． 1 |
| 〈Regulator 1〉 |  |  |  |  |  |
| Output voltage | Vreg1 |  |  |  | Fig． 1 |
| Output load stability | $\Delta \mathrm{V}_{\text {RL1 }}$ |  | 2 | IREG＝0～200mA | Fig． 1 |
| Supply voltage stability | $\Delta \mathrm{VVcc} 1$ |  | 2 | $\mathrm{Vcc}=6 \sim 10 \mathrm{~V}$ ，IREG＝100mA | Fig． 1 |
| REG1＿B terminal sink current | Iregsil |  | 3 | REGOUT＝2．5V，IREGSI1＝IQREGSW1 | Fig． 1 |
| REG1SW terminal sink current | Ireg1 |  |  | REGSW＝5V，IREGSI1＝IQREGSW1 | Fig． 1 |
| 〈Regulator 2＞ |  |  |  |  |  |
| Output voltage | Vregr |  |  |  | Fig． 1 |
| Output load stability | $\Delta \mathrm{V}_{\mathrm{RL} 2}$ |  | 2 | IREG＝0～200mA | Fig． 1 |
| Supply voltage stability | $\Delta \mathrm{VV}$ cc2 |  | 2 | $\mathrm{Vcc}=7 \sim 10 \mathrm{~V}$ ，IREG＝100mA | Fig． 1 |
| REG2＿B terminal sink current | IREGSI2 |  | 3 | REGOUT＝4V，IREGSI2＝IQREGSW2 | Fig． 1 |
| REG2SW terminal sink current | Ireg2 |  |  | REGSW＝5V，IREGSI2＝IQREGSW2 | Fig． 1 |



＊4 LDINF＝5V，LDINR＝0V，LDCONT＝1V，GVLD＝20log（VOLD／LDCONT）

## Optical disc ICs



Fig. 4

## -Operation notes

(1) BD7961FM has a built-in thermal shutdown circuit.

When the chip temperature reaches $175^{\circ} \mathrm{C}$ (Typ.), the output current from all drivers is muted.
When the chip temperature returns to $150^{\circ} \mathrm{C}$ (Typ.), the circuit of the driver unit starts up.
(2) When the mute terminal (pin33) is opened or the terminal voltage is reduced to 0.5 V or less, the output current of the BTL driver unit is muted.
In the normal state of use, pull up the voltage to 2.0 V or more.
(3) When the voltage of the regulator switch terminals (pin8 and 9) is increased to 2.0 V or more, the output from the regulator is muted. In the normal state of use, pull down the voltage to 0.5 V or less.
(4) When the bias terminal (pin36) voltage is reduced to 0.7 V or less, the BTL driver unit is muted. In the normal state of use, set the voltage to 1.1 V or more.
(5) Thermal shutdown mutes all drivers. When the mute ON voltage and the bias terminal voltage are reduced, only the BTL drivers are muted. When the drivers are muted, the BTL driver output terminal voltage becomes the internal bias voltage (Vcc1-0.7)/2V.

## Optical disc ICs

(6) The loading drivers operate according to the following logic.

| INPUT |  | OUTPUT |  | Function |
| :---: | :---: | :---: | :---: | :---: |
| FWD | REV | OUT + | OUT- |  |
| L | L | Hi Z | Hi Z | High impedance |
| L | H | L | H | REV mode |
| H | L | H | L | FWD mode |
| H | H | L | L | Brake mode |

The output voltage can be changed by adjusting the voltage input to the LDCONT terminal (gain of 6 dB Typ.).
However, even if the input voltage is increased excessively, the output voltage will not exceed the max. output voltage that depends on the supply voltage.
(7) Supply the same voltage to $\mathrm{Vcc}_{\mathrm{c}} 1$ (pin25), Vcc 2 (pin28) and Vcc 3 (pin26).

Insert by the pass capacitor (approx. $0.1 \mu \mathrm{~F}$ ) between Vcc pin and GND pin of IC as near as possible.
(8) Connect the radiating fin with external GND.
(9) Output pin is to avoid short-circuit with Vcc, GND and other output pins. An integrated circuit is damaged, and smoke may come out by the case.

## - Electrical characteristic curves



Fig. 5 Circuit current characteristic


LDCONT VOLTAGE: Vld (V)
Fig. 8 Input-output characteristic


Fig. 6 Input-output characteristic


Fig. 7 Output load current regulation


LOAD CURRENT : IL (mA)
Fig. 9 Output load current regulation


Fig. 10 Reg1 power supply characteristic


Fig. 11 Reg2 power supply characteristic


Fig. 12 Power dissipation

- External dimensions (Units : mm)

|  |
| :---: |
| HSOP-M36 |

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[^0]:    * When REG2 (5.0-V regulator) is not used, the supply voltage3 (VCC3) is 4.5 to 14.0 V .

