



**EM78P468N**  
**OTP ROM**

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# **EM78P468N**

**8-BIT MICRO-CONTROLLER**

**Version 1.0**



***Specification Revision History***

<b><i>Version</i></b>	<b><i>Content</i></b>	
<i>1.0</i>	<i>Initial version</i>	<i>2004/4/10</i>

**Application Note**



## 1. GENERAL DESCRIPTION

The EM78P468N is an 8-bit RISC type microprocessor with high speed CMOS technology and low power consumption. Integrated onto a single chip are on chip watchdog (WDT), Data RAM, ROM, programmable real time clock counter, internal/external interrupt, power down mode, LCD driver IROUT function, and tri-state I/O. It provides a PROTECTION bit to protect against intrusion of user's code in the OTP memory and a 10-OPTION bit to accommodate user's requirements. It also provides a special 13 bits customer ID option.

With its OTP-ROM feature, the EM78P468N offers a convenient way of developing and verifying user's programs. Moreover, user developed code can be easily programmed with the ELAN writer.

## 2. FEATURES

### CPU

- Operating voltage range : 2.2V ~ 5.5V
- Operating temperature range: -40°C ~ +85°C.
- Dual clock operation
  - ◇ High frequency oscillator can select between Crystal, RC, or PLL (phase lock loop)
  - ◇ Low frequency oscillator can select between Crystal or RC mode
- Totally 272 bytes SRAM
  - ◇ 144 bytes general purpose register
  - ◇ 128 bytes bits on chip data RAM
- 4K\*13 bits on chip Electrical OTP-ROM (One Time Programmable Read Only Memory).
- Up to 28 bi-directional tri-state I/O ports
  - ◇ Typically, 12 bi-directional tri-state I/O ports.
  - ◇ 16 bi-directional tri-state I/O ports shared with LCD segment output pin.
- 8-level stack for subroutine nesting
- 8-bit real time clock/counter (TCC)
- One IROUT/PWM generator
- Four sets of 8 bit auto reload counter/timer can be used as interrupt sources
  - ◇ Counter 1: independent counter
  - ◇ Counter 2, High Pulse Width Timer (HPWT), and Low Pulse Width Timer (LPWT) shared with IR function



- Programmable free running on chip watchdog timer (WDT)
- Low voltage detector (LVD)
- Operation modes
  - ◇ Normal mode :CPU operate on high frequency oscillator
  - ◇ Green mode :CPU operate on low frequency oscillator
  - ◇ Idle mode :CPU idle, LCD display remains working
  - ◇ Sleep mode :whole chip stop working
- Input port wake up function (PORT6, PORT8)
- 9 interrupt sources, 3 external, 6 internal
  - ◇ Internal: TCC; Counter1, 2; High pulse width timer; Low pulse width timer; & Low voltage detector
  - ◇ External: INT0, INT1, & Pin change wake-up (Port 6 and Port 8)
- 59 pin dice/ 64 pin QFP package

## **LCD**

- Common driver pins: 4
- Segment driver pins: 32
- 1/3, 1/2 bias
- 1/4, 1/3, 1/2 duty

## **Applications**

- Remote control for air conditioner
- Health care
- Home appliances



### 3. PIN ASSIGNMENTS

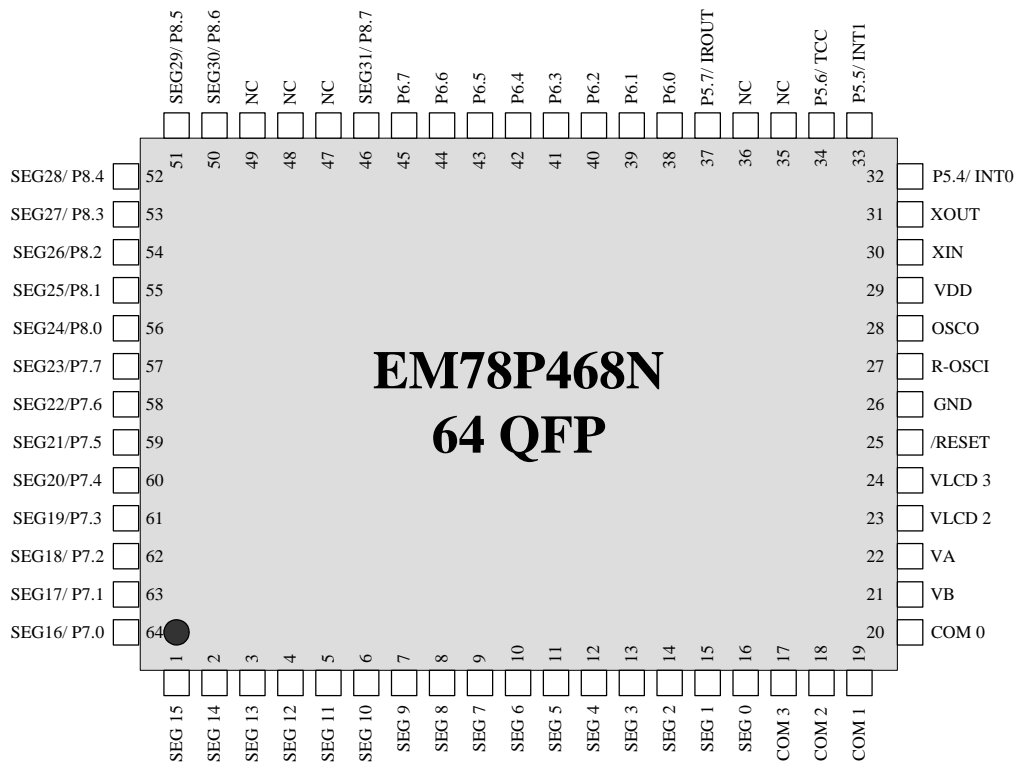


Fig. 1 EM78P468N Pin Configuration for 64 Pin QFP Package

Table 1 Pin Description

PIN	PIN number	I/O type	Description
VDD	29	I	* Power supply pin
GND	26	I	* System ground pin
R-OSCI	27	I	* In crystal mode: crystal input * In RC mode: resistor pull high. * In PLL mode: connect 0.01 $\mu$ F capacitance to GND * Must be pull high or low when high frequency is not use
OSCO	28	O	* In crystal mode: crystal output * In RC mode: instruction clock output * Must be pull high or low when high frequency is not use.
Xin	30	I	*In crystal mode: Input pin for sub-oscillator. Connect to a 32.768KHz crystal * RC mode: this pin is connected with a resistor to high level.
Xout	31	O	* In crystal: Connect to a 32.768KHz crystal * In RC mode: instruction clock output
/RESET	25	I	* Low active. If set as /RESET and remains at logic low, the devices will be reset



# EM78P468N OTP ROM

PIN	PIN number	I/O type	Description
P5.4/INT0 P5.5/INT1	32 33	I/O	* General purpose I/O pin. /external interrupt. * INT0 interruption source can be set to falling or rising edge by IOC81 register bit 7 (INT_EDGE). * INT1 interruption source is a falling edge signal. * All pins wake up from sleep mode when the pin status changes.
P5.6/TCC	34	I/O	* General purpose I/O/ external counter input * This pin works in idle mode.
P5.7/IROUT	37	I/O	* General purpose I/O pin or IR mode output pin, * Capable of sinking 20mA/5V.
P6.0 ~ P6.7	38~45	I/O	* General purpose I/O pin. * Pull-high/ pull-low/ Open drain function support. * All pins can wake up from sleep and idle modes when the pin status changes.
COM3~0	17~20	O	* LCD common output pin.
SEG0~SEG15	16~1	O	* LCD segment output pin.
SEG16/P7.0 ~ SEG23/P7.7	64 ~ 57	O/(I/O)	* LCD segment output pin. Can be shared with general purpose I/O pin
SEG24/P8.0 ~ SEG30/P8.6 SEG31/P8.7	56 ~ 50 46	O/(I/O)	* LCD segment output pin. Can be shared with general I/O pin * For general purpose I/O use, can wake up from sleep mode and idle mode when the pin status changes. * For general purpose I/O use, supports pull-low function.
VB	21		* Connect capacitors for LCD bias voltage
VA	22		* Connect capacitors for LCD bias voltage
VLCD2	23	I/O (Power)	* One of LCD bias voltage
VLCD3	24	I/O (Power)	* One of LCD bias voltage

## 4. FUNCTION DESCRIPTION

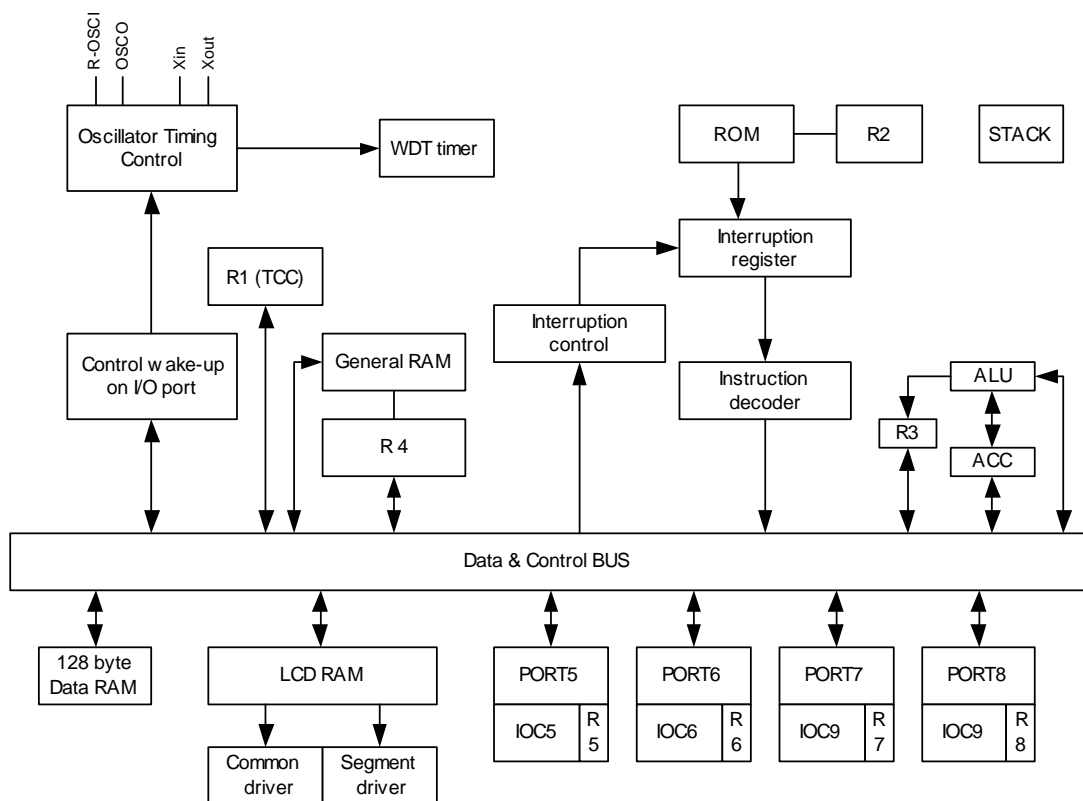
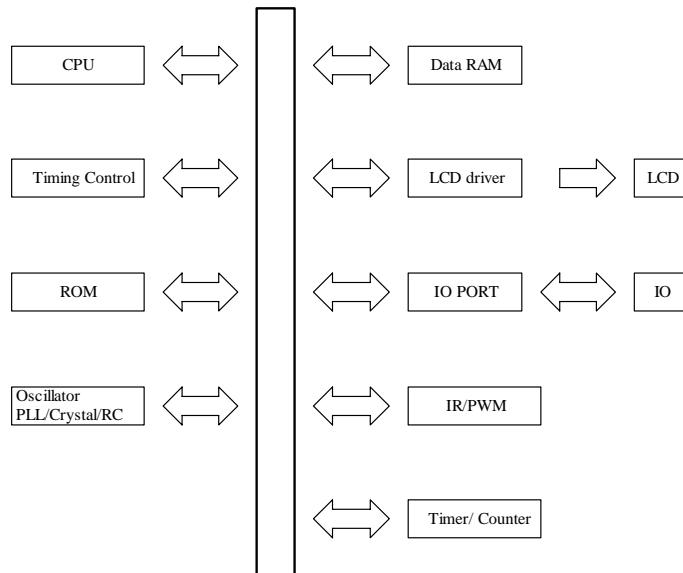


Fig. 2 System Block Diagram

## 4.1 Operational Registers

### 1. R0 (Indirect Addressing Register)

R0 is not a physically implemented register. It is used as indirect addressing pointer. Any instruction using R0 as register actually accesses the data pointed by the RAM Select Register (R4).

### 2. R1 (Time Clock /Counter)

Increases by an external signal edge applied to TCC, or by the instruction cycle clock.

Written and read by the program as any other register.

### 3. R2 (Program Counter)

\* The structure is depicted in Fig. 3

\* Generates 4K × 13 on-chip ROM addresses to the relative programming instruction codes.

\* "JMP" instruction allows direct loading of the low 10 program counter bits.

\* "CALL" instruction loads the low 10 bits of the PC and PC+1, then push it into the stack.

\* "RET" ("RETL k", "RETI") instruction loads the program counter with the contents at the top of stack.

\* "MOV R2, A" allows the loading of an address from the A register to the PC. The contents of the ninth and tenth bits do not change.

\* "ADD R2, A" allows a relative address be added to the current PC. The contents of the ninth and tenth bits do not change.

\* The most significant bit (A10~A11) will be loaded with the content of bits PS0~PS1 in the Status register (R3) upon execution of a "JMP" or "CALL" instruction.

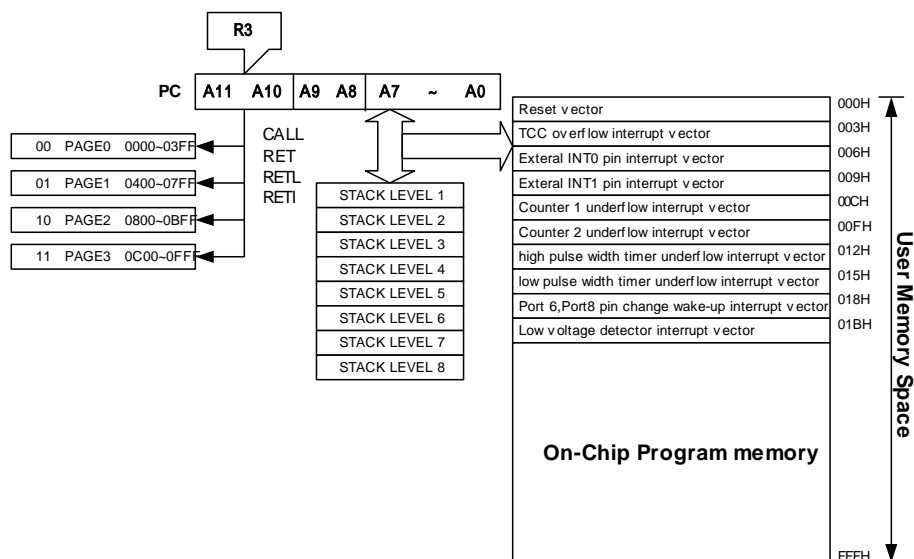


Fig. 3 Program Counter Organization



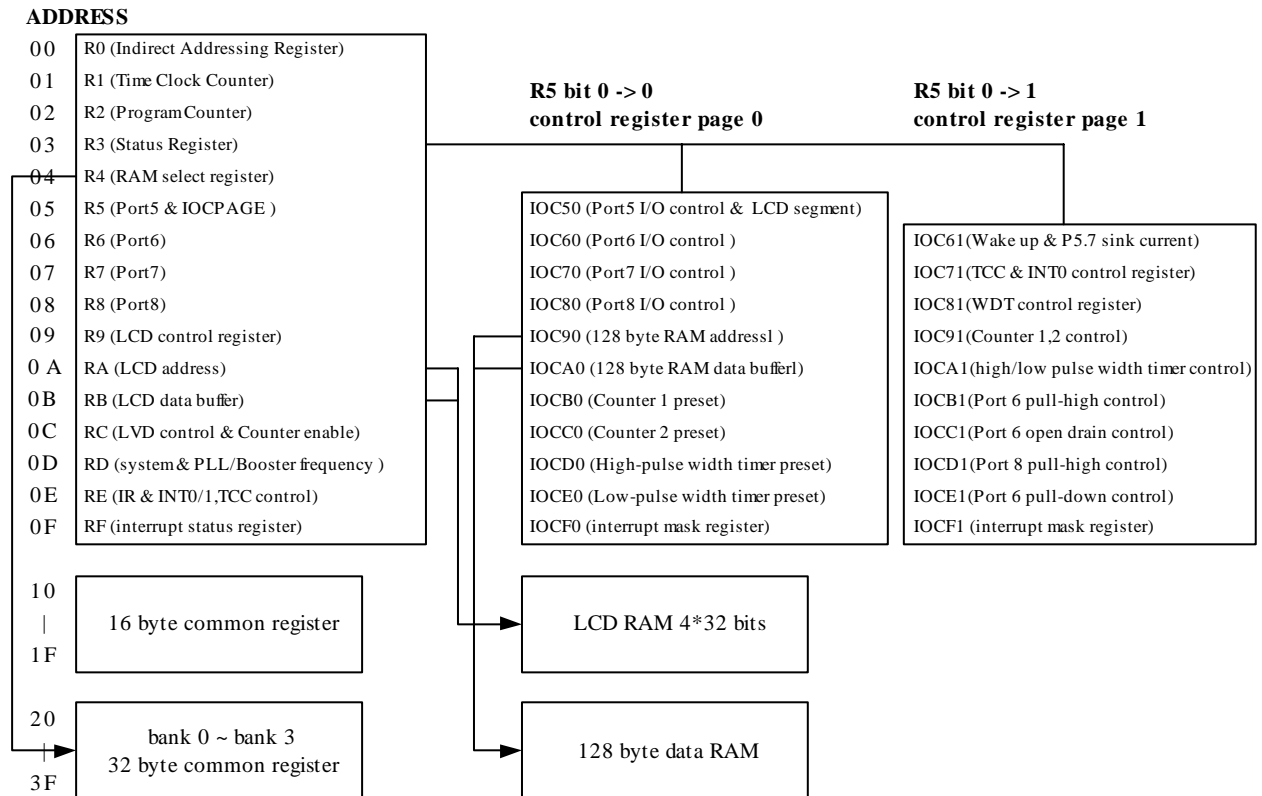


Fig. 4 Data Memory Configuration

#### 4. R3 (Status Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
--	PS1	PS0	T	P	Z	DC	C

**Bit 7:** Not used

**Bit 6, 5 (PS1, 0):** Page select bits

PS1	PS0	Program memory page (Address)
0	0	Page 0
0	1	Page 1
1	0	Page 2
1	1	Page 3

User can use PAGE instruction to change page and maintains the program page. Otherwise, user can use "far jump" (FJMP) or "far call" (FCALL) MACRO to program user's code. The program page is maintained by EMC's compiler. It changes the user's program by inserting instructions within the program.



**Bit 4 (T):** Time-out bit. Set to 1 by the "SLEP" and "WDTC" commands or during power up and reset to 0 by WDT timeout.

EVENT	T	P	REMARK
WDT wake up from sleep mode	0	0	
WDT time out (not sleep mode)	0	1	
/RESET wake up from sleep	1	0	
Power up	1	1	
Low pulse on /RESET	X	X	X: don't care

**Bit 3 (P):** Power down bit. Set to 1 during power on or by a "WDTC" command and reset to 0 by a "SLEP" command.

**Bit 2 (Z):** Zero flag

**Bit 1 (DC):** Auxiliary carry flag

**Bit 0 (C):** Carry flag

## 5. R4 (RAM Select Register)

**Bits 7 ~ 6** determine which bank is activated among the 4 banks. See the configuration of the data memory in Fig.4. Use BANK instruction to change bank.

**Bits 5 ~ 0** are used to select up to 64 registers in the indirect addressing mode.

## 6. R5 (PORT5 and Program Page Select Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R57	R56	R55	R54	--	--	--	IOCPAGE

**Bit 7~4:** 4-bit I/O registers of PORT5

**Bit 3~1:** Not used

**Bit 0 (IOCPAGE):** change IOC8 ~ IOCF to another page, 0/1 => page0 / page1

## 7. R6 (PORT6)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R67	R66	R65	R64	R63	R62	R61	R60

**Bit 7~0:** PORT 6 8-bit I/O registers

## 8. R7 (PORT7)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R77	R76	R75	R74	R73	R72	R71	R70

**Bit 7~0:** PORT 7 8-bit I/O registers

## 9. R8 (PORT8)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
R87	R86	R85	R84	R83	R82	R81	R80

**Bit 7~0:** PORT 8 8-bit I/O registers



**10. R9 (LCD Control Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
BS	DS1	DS0	LCDEN	--	LCDDTYPE	LCDF1	LCDF0

**Bit 7 (BS):** LCD bias select bit, 0/1=>(1/2 bias) / (1/3 bias)

**Bit 6,5 (DS1, 0):** LCD duty select

DS1	DS0	LCD duty
0	0	1/2 duty
0	1	1/3 duty
1	X	1/4 duty

**Bit 4 (LCDEN):** LCD enable bit: 0/1 -> LCD circuit disable/enable. When LCD function is disabled, all common/segment outputs are set to ground (GND) level.

**Bit 3:** Not used

**Bit 2 (LCDDTYPE):** LCD drive waveform type select bit

0: A type waveform

1: B type waveform

**Bit 1, 0(LCDF1, 0):** LCD clock pre-scaler ratio control bit

LCDF1	LCDF0	LCD frame frequency (Fs=32.768KHz)		
		1/2 duty	1/3 duty	1/4 duty
0	0	$Fs/(256*2)=64.0$	$Fs/(172*3)=63.5$	$Fs/(128*4)=64.0$
0	1	$Fs/(280*2)=58.5$	$Fs/(188*3)=58.0$	$Fs/(140*4)=58.5$
1	0	$Fs/(304*2)=53.9$	$Fs/(204*3)=53.5$	$Fs/(152*4)=53.9$
1	1	$Fs/(232*2)=70.6$	$Fs/(156*3)=70.0$	$Fs/(116*4)=70.6$

Fs: sub-oscillator frequency

**11. RA (LCD Address)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	0	0	LCD_A4	LCD_A3	LCD_A2	LCD_A1	LCD_A0

**Bit 7 ~ 5:** Not used, fixed to "0"

**Bit 4~0 (LCDA4~0):** LCD RAM address

RA (LCD address)	RB (LCD data buffer)								Segment
	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3 (LCD_D3)	Bit 2 (LCD_D2)	Bit 1 (LCD_D1)	Bit 0 (LCD_D0)	
00H	--	--	--	--					SEG0
01H	--	--	--	--					SEG1
02H	--	--	--	--					SEG2
	--	--	--	--					SEG29
1EH	--	--	--	--					SEG30
1FH	--	--	--	--					SEG31
Common	X	X	X	X	COM3	COM2	COM1	COM0	



**12. RB (LCD Data Buffer)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
--	--	--	--	LCD_D 3	LCD_D 2	LCD_D 1	LCD_D 0

**Bit 7 ~ 4:** Not used

**Bit 3~0 (LCD\_D3~0):** LCD RAM data transfer register

**13. RC (LVD Control and Counter Enable Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
LV DEN	/LV	LVDF	LVD0	LPWTEN	HPWTEN	CNT2EN	CNT1EN

**Bit 7(LVDEN):** Enable low voltage detector.

**1:** enable LVD function.

**0:** disable LVD function.

**Bit 6(/LV):** Low voltage detector. This is a read only bit. When the VDD pin voltage is lower than Vdet (selected by LVD0), this bit will be cleared.

**0:** the low voltage is detected.

**1:** the low voltage is not detected or LVD function is disabled.

**Bit 5 (LVDF):** interrupt flag of Low voltage detector.

**Bit 4(LVD0):** the low voltage detector select bits

LVD0	Vdet
0	2.1 V
1	2.3 V

LVD0=0: if Vdet voltage drops lower than 2.1V or rises higher than 2.3V, then interrupt occurs.

LVD0=1: if Vdet voltage drops lower than 2.3V or rises higher than 2.5V, then interrupt occur.

**Bit 3(LPWTEN):** low pulse width time enable bit, 0/1 => disable/enable

**Bit 2(HPWTEN):** high pulse width timer enable bit, 0/1 => disable/enable

**Bit 1(CNT2EN):** counter 2 enable bit, 0/1 => disable/enable

**Bit 0(CNT1EN):** counter 1 enable bit, 0/1 => disable/enable

**14. RD (System Clock, Booster Frequency, and PLL Frequency Control Registers)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
--	CLK2	CLK1	CLK0	IDLE	BF1	BF0	CPUS

**Bit 7:** Not used

**Bit 6~4 (CLK2~0):** main clock select bit for PLL mode (code option select)

CLK2	CLK1	CLK0	Main clock
0	0	0	32.768K*130=4.26 MHz
0	0	1	32.768K*65=2.13 MHz
0	1	0	2.13MHz/2
0	1	1	2.13MHz/4
1	--	--	32.768K*244=8 MHz

**Bit 3 (IDLE):** idle mode enable bit. This bit will decide the intended mode of the SLEP instruction.

IDLE="0"+SLEP instruction => sleep mode

IDLE="1"+SLEP instruction => idle mode

**Bit 2,1 (BF1, 0):** LCD booster frequency select bit

BF1	BF0	Booster frequency
0	0	Fs
0	1	Fs/4
1	0	Fs/8
1	1	Fs/16

**Bit 0 (CPUS):** CPU oscillator source select, 0/1=> sub-oscillator (Fs)/ main oscillator (Fm)

When CPUS=0, the CPU oscillator select sub-oscillator and the main oscillator is stopped.

### CPU Operation Mode

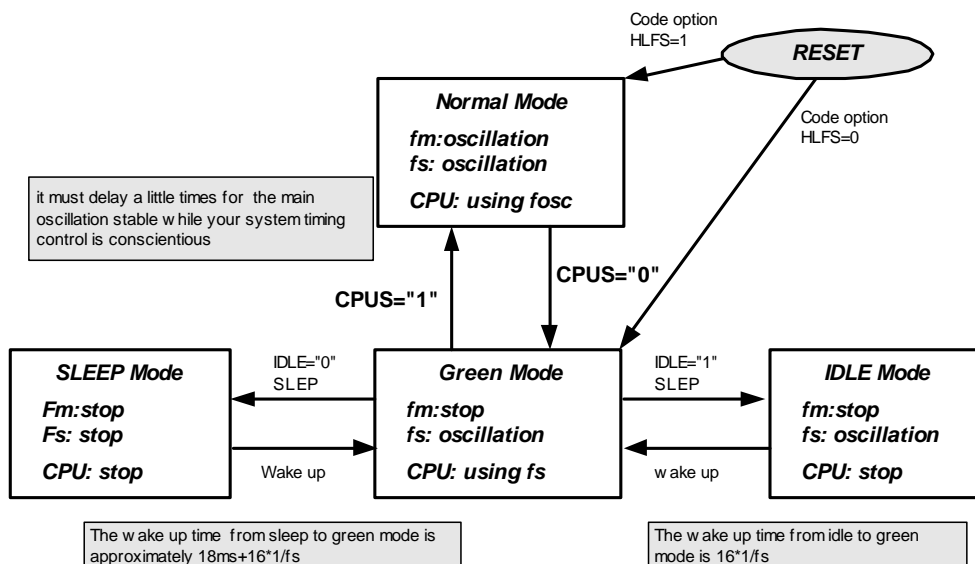


Fig. 5 CPU Operation Mode



### 15. RE (IR Control and PORT5 Function Pins Set Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IRE	HF	LGP	--	IROUTE	TCCE	EINT1	EINT0

**Bit 7 (IRE):** Infrared Remote Enable bit

**0:** Disable IRE. Disable H/W Modulator Function. IROUT pin fixed to high level

**1:** Enable IRE. Enable H/W Modulator Function. Pin 6.7 defined as IROUT.

**Bit 6 (HF):** High frequency.

**0:** For PWM application, IROUT waveform is created according to high-pulse and low-pulse width time as determined by the high pulse and low pulse width timers respectively.

**1:** For IR application mode, the low time sections of the generated pulse is modulated with the frequency  $F_{carrier}$ ,

**Bit 5 (LGP):** long pulse.

**0:** the high-pulse timer register and low-pulse width timer is valid.

**1:** The high-pulse width timer register is ignored. So the IROUT waveform is dependent on low-pulse width timer register only

**Bit 4:** Not used

**Bit 3 (IROUTE):** control bit is used to define the function of P5.7 (IROUT) pin.

**0:** P5.7, bi-directional I/O pin.

**1:** IROUT, in this case, the I/O control bit of P5.7 (bit 7 of IOC5) must be set to "0"

**Bit 2 (TCCE):** control bit is used to define the function of P5.6 (TCC) pin.

**0:** P5.6, bi-directional I/O pin.

**1:** TCC, external input pin of TCC. In this case, the I/O control bit of P5.6 (bit 6 of IOC5) must be set to "1"

**Bit 1 (EINT1):** control bit is used to define the function of P5.5 (INT1) pin.

**0:** P5.5, bi-directional I/O pin.

**1:** INT1, external interrupt pin. In this case, the I/O control bit of P5.5 (bit 5 of IOC5) must be set to "1"

**Bit 0 (EINT0):** control bit is used to define the function of P5.4 (INT0) pin.

**0:** P5.4, bi-directional I/O pin.

**1:** INT0, external interrupt pin. In this case, the I/O control bit of P5.4 (bit 4 of IOC5) must be set to "1"



## 16. RF (Interrupt Status Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ICIF	LPWTF	HPWTF	CNT2F	CNT1F	INT1F	INT0F	TCIF

**Bit 7 (ICIF):** Port 6, Port 8, input status changed interrupt flag. Set when PORT6, PORT8 input changes.

**Bit 6 (LPWTF):** interrupt flag of internal low-pulse width timer underflow.

**Bit 5 (HPWTF):** interrupt flag of internal high-pulse width timer underflow.

**Bit 4 (CNT2):** interrupt flag of internal counter 2 under-flow.

**Bit 3 (CNT1):** interrupt flag of internal counter 1 underflow.

**Bit 2 (INT1F):** external INT1 pin interrupt flag.

**Bit 1 (INT0F):** external INT0 pin interrupt flag.

**Bit 0 (TCIF):** TCC timer overflow interrupt flag. Set when TCC timer overflows.

## 17. R10~R3F (General Purpose Register)

R10~R31F and R20~R3F (Banks 0~3) are general purposes register.

## 4.2 Special Purpose Registers

### 1. A (Accumulator)

\* Internal data transfer, or instruction operand holding

\* This is not an addressable register.

### 2. IOC50 (PORT5 I/O Control and PORT7, 8 for LCD Segment Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IOC57	IOC56	IOC55	IOC54	P8HS	P8LS	P7HS	P7LS

**Bit 7~4(IOC57~4):** PORT5 I/O direction control register

**0:** set the relative I/O pins as output

**1:** set the relative I/O pin into high impedance (input pin)

**Bit 3(P8HS):** Switch to high nibble I/O of Port8 or to LCD segment output as share pins  
SEGxx/P8.x pins

**0:** select high nibble of PORT8 as normal P8.4~P8.7

**1:** select LCD SEGMENT output as SEG28~SEG31 output

**Bit 2(P8LS):** Switch to low nibble I/O of Port8 or to LCD segment output as share pins  
SEGxx/P8.x pins

**0:** select low nibble of PORT8 as normal P8.0~P8.3

**1:** select LCD SEGMENT output as SEG24~SEG27 output



**Bit 1(P7HS):** Switch to high nibble I/O of Port7 or to LCD segment output as share pins  
SEGxx/P7.x pins

- 0:** select high nibble of PORT7 as normal P7.4~P7.7
- 1:** select LCD SEGMENT output as SEG20~SEG23 output

**Bit 0(P7LS):** Switch to low nibble I/O of PORT7 or to LCD segment output as share pins  
SEGxx/P7.x pins

- 0:** select low nibble of PORT7 as normal P7.0~P7.3
- 1:** select LCD SEGMENT output as SEG16~SEG19 output

### 3. IOC60 (PORT6 I/O Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IOC67	IOC66	IOC65	IOC64	IOC63	IOC62	IOC61	IOC60

**Bit 7 (IOC67)~Bit 0(IOC60):** PORT6 I/O direction control register

- 0:** set the relative I/O pins as output
- 1:** set the relative I/O pin into high impedance (input pin)

### 4. IOC70 (PORT7 I/O Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IOC77	IOC76	IOC75	IOC74	IOC73	IOC72	IOC71	IOC70

**Bit 7 (IOC77)~Bit 0(IOC70):** PORT7 I/O direction control register

- 0:** set the relative I/O pins as output
- 1:** set the relative I/O pin into high impedance (input pin)

### 5. IOC80 (PORT8 I/O Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IOC87	IOC86	IOC85	IOC84	IOC83	IOC82	IOC81	IOC80

**Bit 7 (IOC87)~Bit 0(IOC80):** PORT8 I/O direction control register

- 0:** set the relative I/O pins as output
- 1:** set the relative I/O pin into high impedance (input pin)

### 6. IOC90 (128 Bytes RAM Address)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	RAM_A6	RAM_A5	RAM_A4	RAM_A3	RAM_A2	RAM_A1	RAM_A0

- Bit 7:** Not used, fixed at "0"
- Bit 6~0:** 128 bytes RAM address





### 7. IOCA0 (128 Bytes RAM Data Buffer)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RAM_D7	RAM_D6	RAM_D5	RAM_D4	RAM_D3	RAM_D2	RAM_D1	RAM_D0

**Bit 7~0:** 128 bytes RAM data transfer register

### 8. IOCB0 (Counter 1 Preset Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0

**Bit 7 ~ Bit 0:** All are Counter 1 buffer that user can read and write. Counter 1 is an 8-bit down-counter with 8-bit pre-scaler that is used as IOCB to preset the counter and read preset value. After an interruption, it will auto reload the preset value.

### 9. IOCC0 (Counter 2 Preset Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0

**Bit 7 ~ Bit 0:** All are Counter 2 buffer that user can read and write. The Counter 2 is an 8-bit down-counter with 8-bit pre-scaler that is used as IOCC to preset the counter and read preset value. After an interruption, it will reload the preset value.

When IR output is enabled, this control register can obtain carrier frequency output.

If the Counter 2 clock source is equal to FT–

$$\text{Carrier frequency (F}_{\text{carrier}}) = \text{FT} / [2 * (\text{preset value} + 1) * \text{prescaler}]$$

### 10. IOCD0 (High-Pulse Width Timer Preset Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0

**Bit 7 ~ Bit 0:** All are high-pulse width timer buffer that user can read and write. High-pulse width timer preset register is an eight-bit down-counter with 8-bit pre-scaler that is used as IOCD to preset the counter and read preset value. After an interruption, it will reload the preset value.

For PWM or IR application, this control register is set as high pulse width.

If the high-pulse width source clock is FT–

$$\text{the high pulse width} = \text{prescaler} * (\text{high-pulse width preset value} + 1) / \text{FT}$$



**11. IOCE0 (Low-Pulse Width Timer Preset Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0

**Bit 7 ~ Bit 0:** All are low-pulse width timer buffer that user can read and write. Low-pulse width timer preset is an eight-bit down-counter with 8-bit pre-scaler that is used as IOCE to preset the counter and read preset value. After an interruption, it will reload the preset value.

For PWM or IR application, this control register is set as low pulse width.

If the low-pulse width timer source clock is FT–

$$\text{the low pulse width} = \text{prescaler} * (\text{preset value} + 1) / \text{FT}$$

**12. IOCF0 (Interrupt Mask Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ICIE	LPWTE	HPWTE	CNT2E	CNT1E	INT1E	INT0E	TCIE

**Bit 7~Bit 0:** interrupt enable bit.

**0:** disable interrupt

**1:** enable interrupt

IOCF0 register is readable and writable.

**13. IOC61 (Wake Up Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IROCS	--	--	--	/WUE8H	/WUE8L	/WUE6H	/WUE6L

**Bit 7:** IROCS: IROUT/PORT5.7 output sink current set

IROCS	P5.7/IROUT Sink current	
	VDD=5V	VDD=3V
0	10 mA	7 mA
1	20 mA	14 mA

**Bit 6,5,4:** Not used

**Bit 3 (/WUE8H):** 0/1=> enable/disable P8.4~P8.7 pin change wake up function

**Bit 2 (/WUE8L):** 0/1=> enable/disable P8.0~P8.3 pin change wake up function

**Bit 1 (/WUE8H):** 0/1=> enable/disable P6.4~P6.7 pin change wake up function

**Bit 0 (/WUE8L):** 0/1=> enable/disable P6.0~P6.3 pin change wake up function

**14. IOC71 (TCC Control Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
INT_EDGE	INT	TS	TE	PSRE	TCCP2	TCCP1	TCCP0

**Bit 7 (INT\_EDGE):**

**0:** P5.4 's (INT0) interruption source is a rising edge signal.

**1:** P5.4 's (INT0) interruption source is a falling edge signal.

**Bit 6 (INT):** INT enable flag, this bit is read only

**0:** interrupt masked by DISI or hardware interrupt

**1:** interrupt enabled by ENI/RETI instructions

**Bit 5 (TS):** TCC signal source

**0:** internal instruction cycle clock

**1:** transition on TCC pin, TCC period > internal instruction clock period

**Bit 4 (TE):** TCC signal edge

**0:** increment by TCC pin rising edge

**1:** increment by TCC pin falling edge

**Bit 3 (PSRE):** Prescaler Register enable bit

**0:** TCC rate 1:1

**1:** as indicated in the table below:

**Bit 2~0 (TCCP2~0):** TCC pre-scaler bits.

TCCP2	TCCP1	TCCP0	TCC rate
0	0	0	1:2
0	0	1	1:4
0	1	0	1:8
0	1	1	1:16
1	0	0	1:32
1	0	1	1:64
1	1	0	1:128
1	1	1	1:256

**15. IOC81 (WDT Control Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
--	--	--	--	WDTE	WDTP2	WDTP1	WDTP0

**Bit 7 ~ 4:**Not used

**Bit 3 (WDTE):** watchdog timer enable. This control bit is used to enable the Watchdog timer,

**0:** Disable WDT function.

**1:** enable WDT function.



**Bit 2~0 (WDTP2~0):** watchdog timer pre-scaler bits. The WDT source clock is sub-oscillation frequency.

WDTP2	WDTP1	WDTP0	WDT rate
0	0	0	1:1
0	0	1	1:2
0	1	0	1:4
0	1	1	1:8
1	0	0	1:16
1	0	1	1:32
1	1	0	1:64
1	1	1	1:128

### 16. IOC91 (Counter 1, 2 Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CNT2S	CNT2P2	CNT2P1	CNT2P0	CNT1S	CNT1P2	CNT1P1	CNT1P0

**Bit 7(CNT2S):** Counter 2 clock source select 0/1 => Fs/ Fm\*

(\*Fs: sub-oscillator clock, Fm: main-oscillator clock)

**Bit 6~4(CNT2P2~0):** Counter 2 prescaler select bits

CNT2P2	CNT2P1	CNT1P0	Counter 2 scale
0	0	0	1:2
0	0	1	1:4
0	1	0	1:8
0	1	1	1:16
1	0	0	1:32
1	0	1	1:64
1	1	0	1:128
1	1	1	1:256

**Bit 3(CNT1S):** Counter 1 clock source select 0/1 => Fs/ Fm\*

(\*Fs: sub-oscillator clock, Fm: main-oscillator clock)

**Bit 2~0 (CNT1P2~0):** Counter 1 prescaler select bits

CNT1P2	CNT1P1	CNT1P0	Counter 1 scale
0	0	0	1:2
0	0	1	1:4
0	1	0	1:8
0	1	1	1:16
1	0	0	1:32
1	0	1	1:64
1	1	0	1:128
1	1	1	1:256



**17. IOCA1 (High-Pulse Width Timer, Low-Pulse Width Timer Control Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
LPWTS	LPWTP2	LPWTP1	LPWTP0	HPWTS	HPWTP2	HPWTP1	HPWTP0

**Bit 7(LPWTS):** low-pulse width timer clock source select 0/1 -> Fs/ Fm\*

(\*Fs: sub-oscillator clock, Fm: main-oscillator clock)

**Bit 6~4 (LPWTP2~0):** low-pulse width timer prescaler select bits

LPWTP2	LPWTP1	LPWTP0	Low--pulse width timer scale
0	0	0	1:2
0	0	1	1:4
0	1	0	1:8
0	1	1	1:16
1	0	0	1:32
1	0	1	1:64
1	1	0	1:128
1	1	1	1:256

**Bit 3(HPWTS):** high-pulse width timer clock source select 0/1 -> Fs/ Fm\*

(\*Fs: sub-oscillator clock, Fm: main-oscillator clock)

**Bit 2~0(HPWTP2~0):** high-pulse width timer prescaler select bits

HPWTP2	HPWTP1	HPWTP0	High-pulse width timer scale
0	0	0	1:2
0	0	1	1:4
0	1	0	1:8
0	1	1	1:16
1	0	0	1:32
1	0	1	1:64
1	1	0	1:128
1	1	1	1:256

**18. IOCB1 (PORT 6 Pull High Control Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PH67	PH66	PH65	PH64	PH63	PH62	PH61	PH60

**Bit 7 ~ Bit 0:** The enable bits of Port 6 pull high function.

**0:** disable internal pull-high resistor function

**1:** enable internal pull-high resistor function

**19. IOCC1 (PORT 6 Open Drain Control Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
OP67	OP66	OP65	OP64	OP63	OP62	OP61	OP60

**Bit 7 ~ Bit 0:** The enable bits of Port 6 open drain function.

**0:** disable open drain function

**1:** enable open drain function



### 20. IOCD1 (PORT 8 Pull High Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PH87	PH86	PH85	PH84	PH83	PH82	PH81	PH80

**Bit 7 ~ Bit 0:** The enable bits of Port 8 pull-high function.

**0:** disable internal pull-high resistor function

**1:** enable pull-high resistor function

### 21. IOCE1 (PORT 6 Pull-Down Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PL67	PL66	PL65	PL64	PL63	PL62	PL61	PL60

**Bit 7 ~ Bit 0:** The enable bits of port 6 pull low function.

**0:** disable internal pull-down resistor function

**1:** enable internal pull-down resistor function

### 22. IOCF1 (Interrupt Mask register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
--	--	--	--	--	--	--	LVDE

**Bit 7~1:** Not used

**Bit 0:** interrupt enable bit for low voltage detector function.

**0:** disable interrupt

**1:** enable interrupt

IOCF1 register is readable and writable.

## 4.3 TCC and WDT Pre-scaler

Two 8-bit counters are available as pre-scalers for the TCC (Time Clock Counter) and WDT (Watch Dog Timer). The TCCP2~TCCP0 bits of the IOC71 register are used to determine the ratio of the TCC pre-scaler. Likewise, the WDTP2~WDTP0 bits of the IOC81 register are used to determine the WDT pre-scaler. The TCC pre-scaler (TCCP2~TCCP0) is cleared by the instructions each time they are written into TCC, while the WDT pre-scaler is cleared by the "WDTC" and "SLEP" instructions. Fig.7 depicts the circuit diagram of TCC and WDT.

R1 (TCC) is an 8-bit timer/counter. The clock source of TCC can be selected by internal instruction clock or external signal input (edge selectable from the TCC control register). If TCC signal source is from internal instruction clock, TCC will increase by 1 at every instruction cycle (without pre-scaler). If TCC signal source is from external clock input, TCC will increase by 1 at every falling edge or rising edge of the TCC pin.

The watchdog timer is a free running on-chip RC oscillator. The WDT will keep on running even after the oscillator driver has been turned off. During Normal mode, Green mode, or Idle mode operation, a WDT time-out (if enabled) will cause the device to reset. The WDT can be enabled or disabled at any time during the Normal mode and Green mode by software programming. Refer to WDTE bit of IOC81 register. With no pre-scaler, the WDT time-out period is equal to  $(\text{prescaler} * 256 / F_s)$

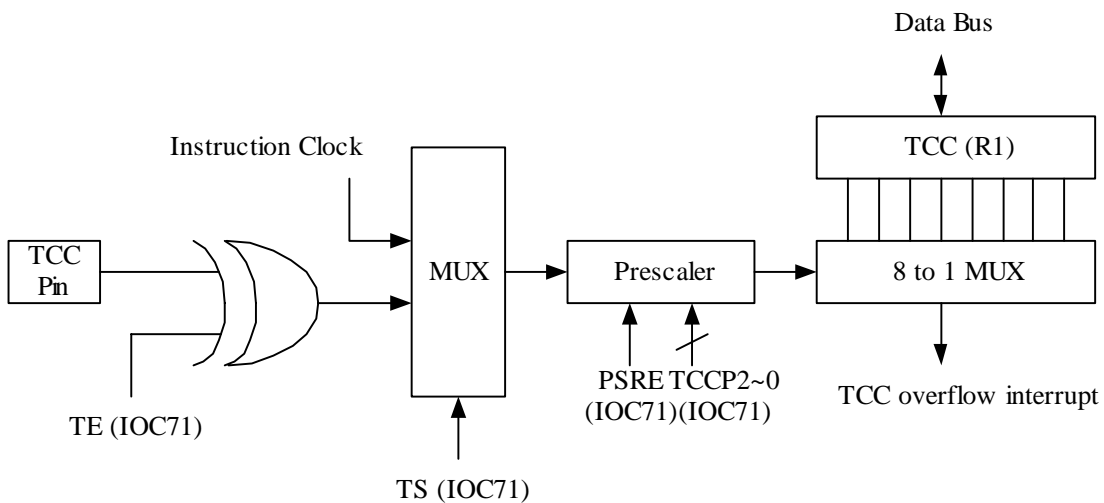


Fig. 7(a) Block Diagram of TCC

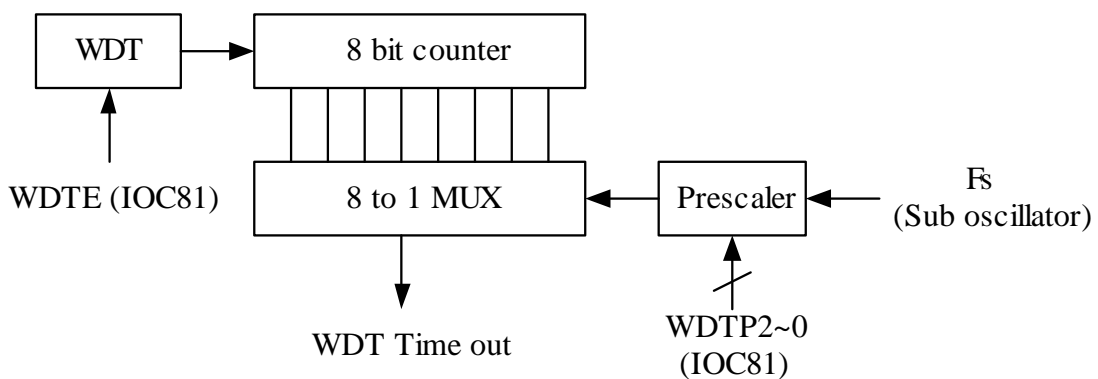
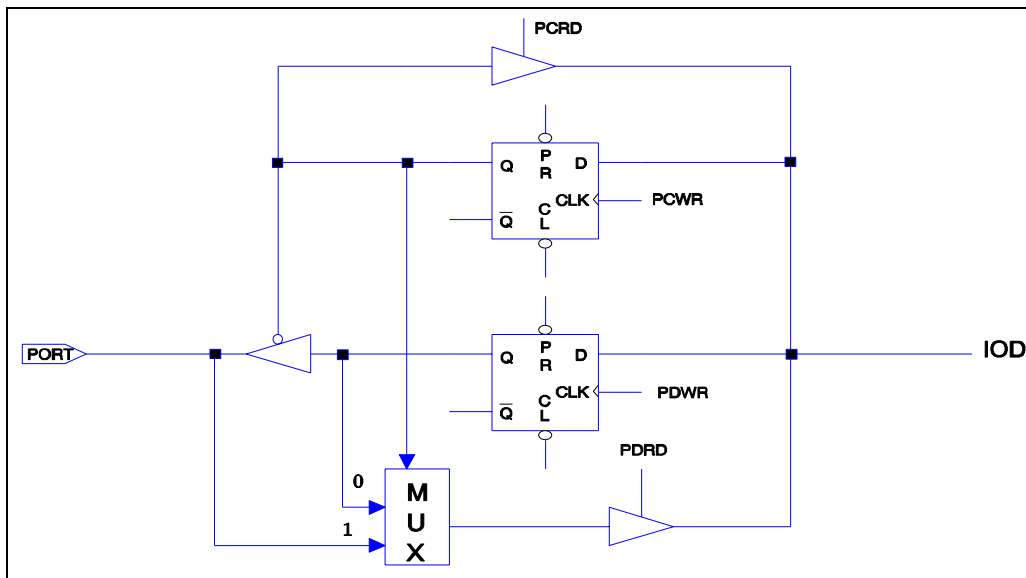


Fig. 7(b) Block Diagram of WDT

## 4.4 I/O Ports

The I/O registers, (Port 5, Port 6, Port 7, and Port 8), are bi-directional tri-state I/O ports. Port 6 and Port 8 are pulled-high internally by software; Port 6 is also pulled-low internally by software. Furthermore, Port 6 has its open-drain output also through software. Port 6 and Port 8 features an input status changed interrupt (or wake-up) function and is pulled-high by software. Each I/O pin can be defined as "input" or "output" pin by the I/O control register (IOC5 ~ IOC8). The I/O registers and I/O control registers are both readable and writable. The I/O interface circuits are shown in Fig. 8



**NOTE:** Open-drain, pull high, and pull down are not shown in the figure.

Fig. 8 The Circuit of I/O Port and I/O Control Register for Port 5, Port 6, Port 7 and Port 8

## 4.5 RESET and Wake-up

A RESET can be activated by

- ✧ Power on reset
- ✧ WDT timeout. (if enabled)
- ✧ /RESET pin pull low

**Note:** The power on reset circuit is always enabled. It will reset CPU at about 1.9V and consumed about 0.5uA.

Once RESET occurs, the following functions are performed

- ✧ The oscillator is running, or will be started.
- ✧ The Program Counter (R2) is set to all "0".
- ✧ All I/O port pins are configured as input mode (high-impedance state).
- ✧ The TCC/Watchdog timer and pre-scaler are cleared.
- ✧ When power on, the Bit 6 of R3 and the upper 2 bits of R4 are cleared.
- ✧ Bits of the IOC71 register are set to all "1" except for Bit 6 (INT flag).
- ✧ For other registers, see Table 2 below.





**Table 2 Summary of the Initialized Values for Registers**

Address	Name	Reset Type	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
N/A	IOC50	Bit Name	IOC57	IOC56	IOC55	IOC54	P8HS	P8LS	P7HS	P7LS
		Power-On	1	1	1	1	0	0	0	0
		/RESET and WDT	1	1	1	1	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOC60	Bit Name	IOC67	IOC66	IOC65	IOC64	IOC63	IOC62	IOC61	IOC60
		Power-On	1	1	1	1	1	1	1	1
		/RESET and WDT	1	1	1	1	1	1	1	1
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOC70	Bit Name	IOC77	IOC76	IOC75	IOC74	IOC73	IOC72	IOC71	IOC70
		Power-On	1	1	1	1	1	1	1	1
		/RESET and WDT	1	1	1	1	1	1	1	1
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOC80	Bit Name	IOC87	IOC86	IOC85	IOC84	IOC83	IOC82	IOC81	IOC80
		Power-On	1	1	1	1	1	1	1	1
		/RESET and WDT	1	1	1	1	1	1	1	1
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOC90	Bit Name	X	RAM_A6	RAM_A5	RAM_A4	RAM_A3	RAM_A2	RAM_A1	RAM_A0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCA0	Bit Name	RAM_D7	RAM_D6	RAM_D5	RAM_D4	RAM_D3	RAM_D2	RAM_D1	RAM_D0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCB0	Bit Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCC0	Bit Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCD0	Bit Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCE0	Bit Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCF0	Bit Name	ICIE	LPWTE	HPWTE	CNT2E	CNT1E	INT1E	INT0E	TCIE
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOC61	Bit Name	IROCS	X	X	X	/WUE8H	/WUE8L	/WUE6H	/WUE6L
		Power-On	0	U	U	U	0	0	0	0
		/RESET and WDT	0	U	U	U	0	0	0	0
		Wake-Up from Pin Change	P	U	U	U	P	P	P	P



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Address	Name	Reset Type	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
N/A	IOC71	Bit Name	INT_EDGE	INT	TS	TE	PSRE	TCCP2	TCCP1	TCCP0
		Power-On	1	0	1	1	1	1	1	1
		/RESET and WDT	1	0	1	1	1	1	1	1
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOC81	Bit Name	X	X	X	X	WDTE	WDTP2	WDTP1	WDTP0
		Power-On	U	U	U	U	0	1	1	1
		/RESET and WDT	U	U	U	U	0	1	1	1
		Wake-Up from Pin Change	U	U	U	U	P	P	P	P
N/A	IOC91	Bit Name	CNT2S	CNT2P2	CNT2P1	CNT2P0	CNT1S	CNT1P2	CNT1P1	CNT1P0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCA1	Bit Name	LPWTS	LPWTP2	LPWTP1	LPWTP0	HPWTS	HPWTP2	HPWTP1	HPWTP0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCB1	Bit Name	PH67	PH66	PH65	PH64	PH63	PH62	PH61	PH60
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCC1	Bit Name	OP67	OP66	OP65	OP64	OP63	OP62	OP61	OP60
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCD1	Bit Name	PH87	PH86	PH85	PH84	PH83	PH82	PH81	PH80
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCE1	Bit Name	PL67	PL66	PL65	PL64	PL63	PL62	PL61	PL60
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
N/A	IOCF1	Bit Name	X	X	X	X	X	X	X	LVDE
		Power-On	U	U	U	U	U	U	U	0
		/RESET and WDT	U	U	U	U	U	U	U	0
		Wake-Up from Pin Change	U	U	U	U	U	U	U	P
0x00	R0(IAR)	Bit Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Power-On	U	U	U	U	U	U	U	U
		/RESET and WDT	P	P	P	P	P	P	P	P
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
0x01	R1(TCC)	Bit Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
0x02	R2(PC)	Bit Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	Jump to address 0x0018 or continue to execute next instruction							



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Address	Name	Reset Type	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x03	R3(SR)	Bit Name	X	PS1	PS0	T	P	Z	DC	C
		Power-On	U	0	0	1	1	U	U	U
		/RESET and WDT	U	0	0	t	t	P	P	P
		Wake-Up from Pin Change	U	P	P	t	t	P	P	P
0x04	R4(RSR)	Bit Name	Bank1	Bank0	--	--	--	--	--	--
		Power-On	0	0	U	U	U	U	U	U
		/RESET and WDT	0	0	P	P	P	P	P	P
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
0x05	R5	Bit Name	R57	R56	R55	R54	X	X	X	IOCPAGE
		Power-On	1	1	1	1	U	U	U	0
		/RESET and WDT	1	1	1	1	U	U	U	0
		Wake-Up from Pin Change	P	P	P	P	U	U	U	P
0x06	R6	Bit Name	R67	R66	R65	R64	R63	R62	R61	R60
		Power-On	1	1	1	1	1	1	1	1
		/RESET and WDT	1	1	1	1	1	1	1	1
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
0x07	R7	Bit Name	R77	R76	R75	R74	R73	R62	R71	R70
		Power-On	1	1	1	1	1	1	1	1
		/RESET and WDT	1	1	1	1	1	1	1	1
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
0x08	R8	Bit Name	R87	R86	R85	R84	R83	R82	R81	R80
		Power-On	1	1	1	1	1	1	1	1
		/RESET and WDT	1	1	1	1	1	1	1	1
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
0x09	R9	Bit Name	BS	DS1	DS0	LCDEN	X	LCDDTYPE	LCDF1	LCDF0
		Power-On	1	1	0	0	U	0	0	0
		/RESET and WDT	1	1	0	0	U	0	0	0
		Wake-Up from Pin Change	P	P	P	P	U	P	P	P
0xA	RA	Bit Name	X	X	X	LCD_A4	LCD_A3	LCD_A2	LCD_A1	LCD_A0
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P
0xB	RB	Bit Name	X	X	X	X	LCD_D 3	LCD_D 2	LCD_D 1	LCD_D 0
		Power-On	U	U	U	U	0	0	0	0
		/RESET and WDT	U	U	U	U	0	0	0	0
		Wake-Up from Pin Change	U	U	U	U	P	P	P	P
0xC	RC	Bit Name	LV DEN	/LV	LVDF	LVD	LPWTEN	HPWTEN	CNT2EN	CNT1EN
		Power-On	0	1	0	0	0	0	0	0
		/RESET and WDT	0	1	0	0	0	0	0	0
		Wake-Up from Pin Change	P	P	0	P	P	P	P	P
0xD	RD	Bit Name	X	CLK2	CLK1	CLK0	IDLE	BF1	BF0	CPUS
		Power-On	U	0	0	0	1	0	0	*1
		/RESET and WDT	U	0	0	0	1	0	0	*1
		Wake-Up from Pin Change	U	P	P	P	P	P	P	P
0xE	RE	Bit Name	IRE	HF	LGP	X	IROUTE	TCCE	EINT1	EINT0
		Power-On	0	0	0	U	0	0	0	0
		/RESET and WDT	0	0	0	U	0	0	0	0
		Wake-Up from Pin Change	P	P	P	U	P	P	P	P



Address	Name	Reset Type	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0xF	RF (ISR)	Bit Name	ICIF	LPWTF	HPWTF	CNT2F	CNT1F	INT1F	INT0F	TCIF
		Power-On	0	0	0	0	0	0	0	0
		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-Up from Pin Change	N	P	P	P	P	P	P	P
0x10~0x3F	R10~R3F	Bit Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Power-On	U	U	U	U	U	U	U	U
		/RESET and WDT	U	U	U	U	U	U	U	U
		Wake-Up from Pin Change	P	P	P	P	P	P	P	P

**X**: not used. **U**: unknown or don't care. **P**: previous value before reset. **-**: Not defined

**t** : check R3 register explain. **N**: Monitors interrupt operation status; **1**=running; **P**=not running

**Note 1**: This bit is equal to code option HLFS bit data

The controller can be awakened from sleep mode and idle mode. The wake-up signals are listed as follows:

Wake-up signal	Sleep mode	Idle mode	Green mode	Normal mode
TCC time out IOCF bit0=1	X	*2 Wake-up + interrupt + next instruction	Interrupt	Interrupt
INT0 pin IOCF bit1=1	Wake-up + interrupt + next instruction	Wake-up + interrupt + next instruction	Interrupt	Interrupt
INT1 pin IOCF bit2=1	Wake-up + interrupt + next instruction	Wake-up + interrupt + next instruction	Interrupt	Interrupt
Counter 1 IOCF bit3=1	X	Wake-up + interrupt + next instruction	Interrupt	Interrupt
Counter 2 IOCF bit4=1	X	Wake-up + interrupt + next instruction	Interrupt	Interrupt
High-pulse timer IOCF bit5=1	X	Wake-up + interrupt + next instruction	Interrupt	Interrupt
Low-pulse timer IOCF bit6=1	X	Wake-up + interrupt + next instruction	Interrupt	Interrupt
Port6, Port 8 (input status change wake-up)	<b>IOCF bit7=0</b> Wake-up + next instruction	<b>IOCF bit7=0</b> Wake-up + next instruction	X	X
	<b>IOCF bit7=1+ENI instruction</b> Wake-up + interrupt + next instruction	<b>IOCF bit7=1+ENI instruction</b> Wake-up + interrupt + next instruction		
WDT time out	X	RESET	RESET	RESET

**Note 2**: Only external TCC pin can Wake-up from idle mode.

## 4.6 Oscillator

### 4.6.1. Oscillator Modes

The EM78P468N can operate in the three different oscillator modes from main oscillator (R-OSCI, OSCO), such as RC oscillator with external resistor and Internal capacitor mode (IC); crystal oscillator mode; and PLL operation mode. User can select one of them by programming FMMD1 and FMMD0 in the CODE options register. The sub-oscillator can be operated in crystal mode and ERIC mode. Table3 below shows how these three modes are defined.

Table 3 Oscillator Modes as defined by FSMD, FMMD1, FMMD0.

FSMD	FMMD1	FMMD0	Main clock	Sub-clock
0	0	0	RC type (ERIC)	RC type (ERIC)
0	0	1	Crystal type	RC type (ERIC)
0	1	X	PLL type	RC type (ERIC)
1	0	0	RC type (ERIC)	Crystal type
1	0	1	Crystal type	Crystal type
1	1	X	PLL type	Crystal type

Table 4 Summary of maximum operating speeds

Conditions	VDD	Fxt max.(MHz)
Two clocks	2.3	4
	3.0	8
	5.0	10

### 4.6.2. Crystal Oscillator/Ceramic Resonators (XTAL)

EM78P468N can be driven by an external clock signal through the R-OSCI pin as shown in Fig.9 below.

In most applications, the R-OSCI pin and the OSCO pin can be connected with a crystal or ceramic resonator to generate oscillation. Fig. 10 depicts such circuit. Table 5 provides the recommended values of C1 and C2. Since each resonator has its own attribute, user should refer to its specification for appropriate values of C1 and C2. RS, a serial resistor, may be necessary for AT strip cut crystal or low frequency mode.

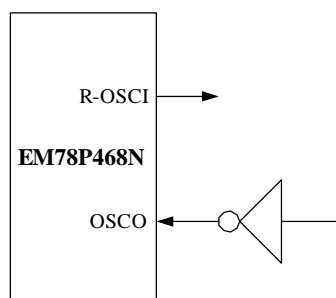


Fig.9 Circuit for External Clock Input

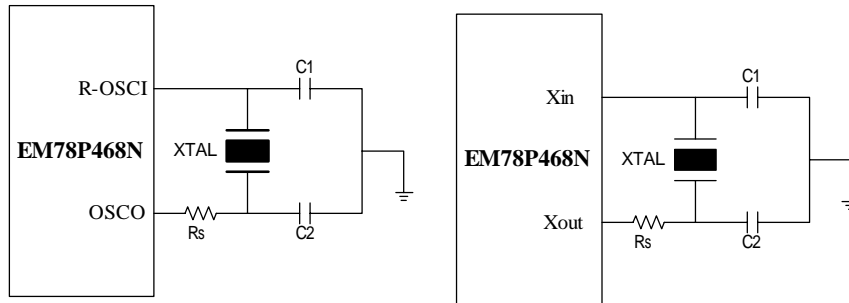


Fig. 10 Circuit for Crystal/Resonator

Table 5 Capacitor Selection Guide for Crystal Oscillator or Ceramic Resonators

Oscillator source	Oscillator Type	Frequency	C1 (pF)	C2(pF)
Main oscillator	Ceramic Resonators	455 kHz	100~150	100~150
		2.0 MHz	20~40	20~40
		4.0 MHz	10~30	10~30
	Crystal Oscillator	455KHz	20~40	20~150
		1.0MHz	15~30	15~30
		2.0MHz	15	15
Sub-oscillator	Crystal Oscillator	4.0MHz	15	15
		32.768kHz	25	25

#### 4.6.3. RC Oscillator Mode with Internal Capacitor

If both precision and cost are taken into consideration, EM78P468N also offers a special oscillation mode, which is equipped with an internal capacitor and an external resistor connected to VDD. The internal capacitor functions as temperature compensator. In order to obtain more accurate frequency, a precise resistor is recommended.

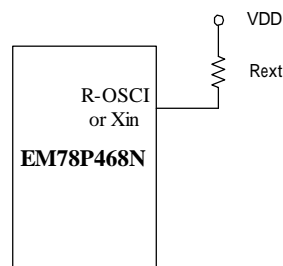


Fig. 11 Circuit for Internal C Oscillator Mode

Table 6 RC Oscillator Frequencies

Pin	Rext	Average Fosc 5V, 25°C	Average Fosc 3V, 25°C
R-OSCI	51k	2.2221 MHz	2.1972 MHz
	100k	1.1345 MHz	1.1203 MHz
	300k	381.36KHz	374.77 KHz
Xin	2.2M	32.768KHz	32.768KHz

**Note:** Measured from QFP packages with frequency drift of about  $\pm 30\%$ .  
Values provided are for design reference only

## 4.7 Power-on Considerations

Any microcontroller (as with i EM78P468N ) s not warranted to start operating properly before the power supply stabilizes in steady state. The EM78P468N is equipped with Power On Reset (POR) with detection level range of 1.9V to 2.1V. The circuitry eliminates the extra external reset circuit but will work well only if the VDD rises quickly enough (50 ms or less). However, under critical applications, extra devices are still required to assist in solving power-on problems.

### 4.7.1. External Power-on Reset Circuit

This circuit implements an external RC to produce a reset pulse (see Fig.12). The pulse width (time constant) should be kept long enough to allow VDD to reach minimum operation voltage. This circuit is used when the power supply rise time is slow. Because the current leakage from the /RESET pin is about  $\pm 5\mu\text{A}$ , it is recommended that R should not be great than 40K. In this way, the voltage at Pin /RESET is held below 0.2V. The diode (D) acts as a short circuit at power-down. The capacitor, C, is discharged rapidly and fully. Rin, the current-limited resistor, prevents high current discharge or ESD (electrostatic discharge) from flowing into Pin /RESET.

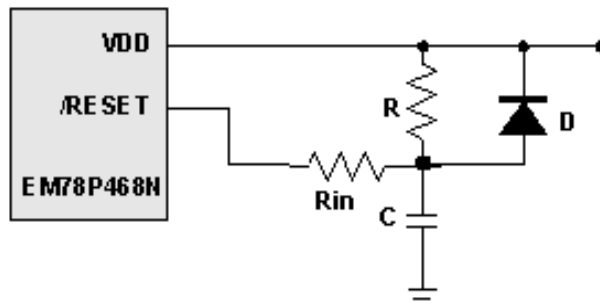


Fig. 12 External Power on Reset Circuit

### 7.7.2. Residue-Voltage Protection

When battery is replaced, device power (VDD) is disconnected but residue-voltage remains. The residue-voltage may trips below minimum VDD, but above zero. This condition may cause poor power on reset. Fig.13 and Fig.14 show how to build a residue-voltage protection circuit

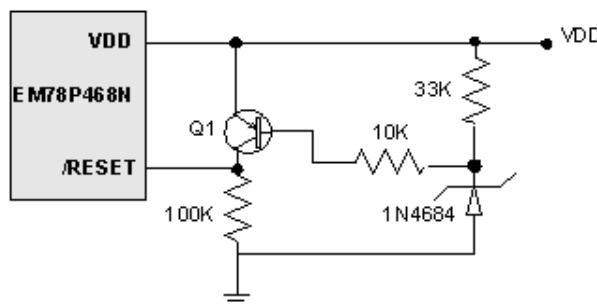


Fig. 13 Circuit 1 for the Residue Voltage Protection

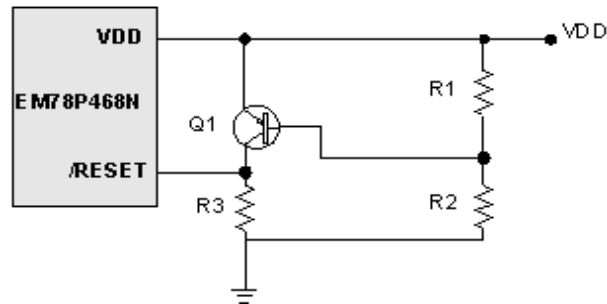


Fig. 14 Circuit 2 for the Residue Voltage Protection

## 4.8 Interrupt

The EM78P468N has nine interrupt sources as listed below:

- ✧ TCC overflow interrupt.
- ✧ External interrupt P5.4/INT0 pin
- ✧ External interrupt P5.5/INT1 pin
- ✧ Counter 1 underflow interrupt
- ✧ Counter 2 underflow interrupt
- ✧ High-pulse width timer underflow interrupt
- ✧ Low-pulse width timer underflow interrupt
- ✧ Port 6, Port 8 input status change wake-up
- ✧ Low voltage detector

This IC has internal interrupts which are falling edge triggered or as follows:

- ✧ TCC timer overflow interrupt,
- ✧ Four 8-bits down counter/timer underflow interrupt
- ✧ VDD level down to less than LVD setting level

If these interrupt sources change signal from high to low, the RF register will generate "1" flag to corresponding register if the IOCF0 or IOCF1 register is enabled.

RF is the interrupt status register. It records the interrupt request in flag bit. IOCF is the interrupt mask register. Global interrupt is enabled by ENI instruction and disabled by DISI instruction. When one of the interrupts (when enabled) is generated, it will cause the next instruction to be fetch from address 0003H~001BH according to interrupt source.



With EM78P468N, each individual interrupt source has its own interrupt vector as depicted in Table 3. Before the interrupt subroutine is executed, the contents of ACC and the R3 register are initially saved by hardware. After the interrupt service routine is completed, ACC and R3 are restored. The existing interrupt service routine does not allow other interrupt service routine to be executed. So if other interrupts occur while the existing interrupt service routine is being executed, the hardware will save the later interrupts. Only after the existing interrupt service routine is completed that the next interrupt service routine is executed.

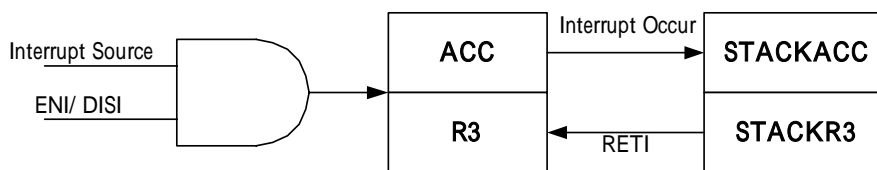


Fig. 15. Interrupt Backup Diagram

Table 3 Interrupt Vector

Interrupt Vector	Interrupt Status
0003H	TCC overflow interrupt.
0006H	External interrupt P5.4/INT0 pin
0009H	External interrupt P5.5/INT1 pin
000CH	Counter 1 underflow interrupt
000FH	Counter 2 underflow interrupt
0012H	High-pulse width timer underflow interrupt
0015H	Low-pulse width timer underflow interrupt
0018H	Port 6, Port 8 input status change wake-up
001BH	Low voltage detector

## 4.9 LCD Driver

The EM78P468N can drive LCD of up to 32 segments and 4 commons that can drive a total of 4\*32 dots. LCD block is made up of LCD driver, display RAM, segment output pins, common output pins, and LCD operating power supply pins. This circuit works on normal mode, green mode, and idle mode. The LCD duty, bias, the number of segment, the number of common, and frame frequency are determined by the LCD controller register.

The basic structure contains a timing control that uses a subsystem clock to generate the proper timing for different duty and display accesses. The R9 register is a command register for LCD driver which includes LCD enable/disable, bias (1/2 and 1/3), duty (1/2, 1/3, 1/4), and LCD frame frequency control. The register RA is an LCD contrast and LCD RAM address control register. The register RB is an LCD RAM data buffer. LCD booster circuit can change operation frequency to improve VLCD2 and VLCD3 drive capability. The control register is explained as follows.



**R9 (LCD Control Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
BS	DS1	DS0	LCDEN	--	LCDDTYPE	LCDF1	LCDF0

**Bit 7 (BS):** LCD bias select bit, 0/1=>(1/2 bias) / (1/3 bias)

**Bit 6, 5 (DS1, 0):** LCD duty select

DS1	DS0	LCD Duty
0	0	1/2 duty
0	1	1/3 duty
1	X	1/4 duty

**Bit 4 (LCDEN):** LCD enable bit: 0/1 -> LCD circuit disable/enable

When LCD function is disabled, all common/segment output is set to ground (GND) level

**Bit 3:** Not used

**Bit 2 (LCDDTYPE):** LCD drive waveform type select bit

0: "A" type waveform

1: "B" type waveform

**Bit 1, 0(LCDF1, 0):** LCD clock pre-scaler ratio control bits

LCDF1	LCDF0	LCD frame frequency (Fs=32.768KHz)		
		1/2 duty	1/3 duty	1/4 duty
0	0	$Fs/(256*2)=64.0$	$Fs/(172*3)=63.5$	$Fs/(128*4)=64.0$
0	1	$Fs/(280*2)=58.5$	$Fs/(188*3)=58.0$	$Fs/(140*4)=58.5$
1	0	$Fs/(304*2)=53.9$	$Fs/(204*3)=53.5$	$Fs/(152*4)=53.9$
1	1	$Fs/(232*2)=70.6$	$Fs/(156*3)=70.0$	$Fs/(116*4)=70.6$

Fs: sub-oscillator frequency

**RA (LCD Address)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	0	0	LCD_A4	LCD_A3	LCD_A2	LCD_A1	LCD_A0

**Bit 7 ~ 5:** Not used, fixed to "0"

**Bit 4~0 (LCDA4~0):** LCD RAM address

RA (LCD Address)	RB (LCD Data Buffer)								Segment
	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3 (LCD_D3)	Bit 2 (LCD_D2)	Bit 1 (LCD_D1)	Bit 0 (LCD_D0)	
00H	--	--	--	--					SEG0
01H	--	--	--	--					SEG1
02H	--	--	--	--					SEG2
	--	--	--	--					SEG29
1EH	--	--	--	--					SEG30
1FH	--	--	--	--					SEG31
Common	X	X	X	X	COM3	COM2	COM1	COM0	

**RB (LCD Data Buffer)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
--	--	--	--	LCD_D 3	LCD_D 2	LCD_D 1	LCD_D 0

Bit 7 ~ 4: Not used

Bit 3~0 (LCD\_D3~0): LCD RAM data transfer registers

**RD (System Clock, Booster Frequency and PLL Frequency Control Register)**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
--	CLK2	CLK1	CLK0	IDLE	BF1	BF0	CPUS

Bit 2, 1 (BF1, 0): LCD booster frequency select bits

BF1	BF0	Booster frequency
0	0	Fs
0	1	Fs/4
1	0	Fs/8
1	1	Fs/16

The initial setting flowchart for LCD function

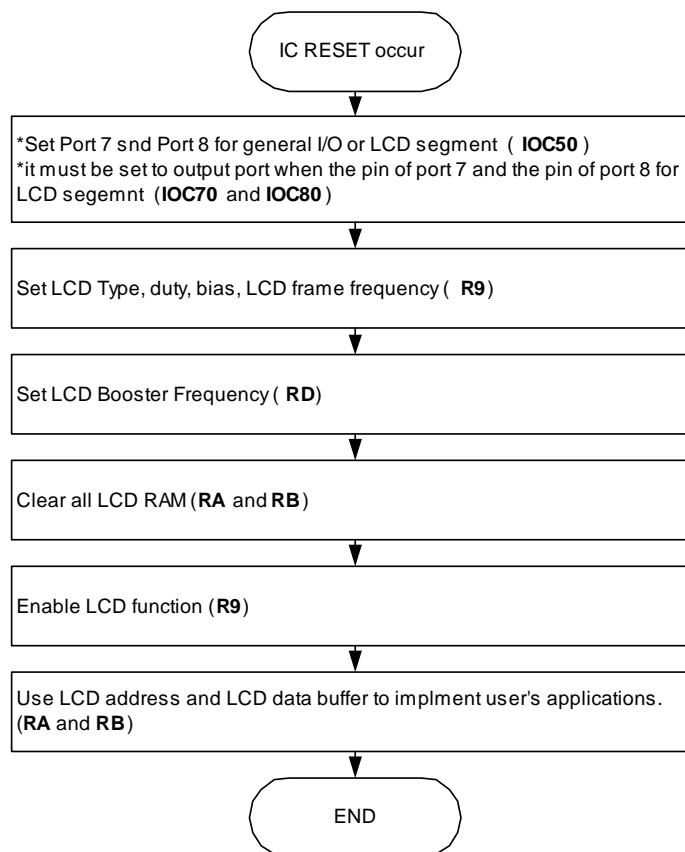
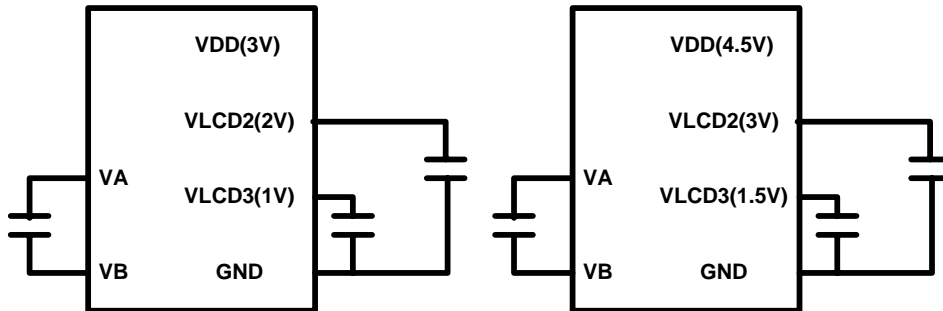


Fig.16. The Initial Setting Flowchart for LCD Function

The connecting of boosting circuits for LCD voltage is as below:

**1/3 Bias**



**1/2 Bias**

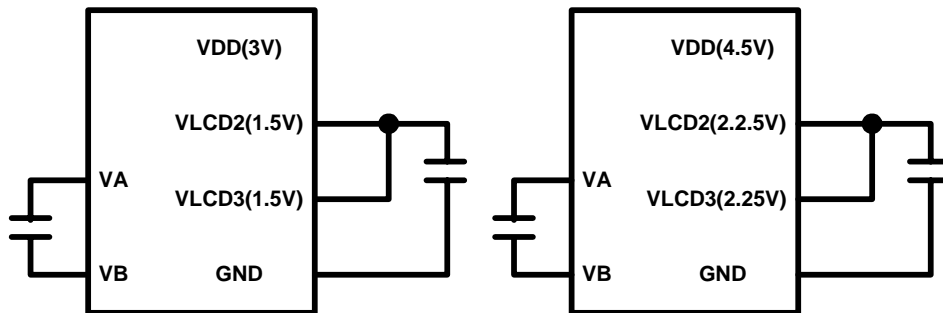


Fig. 17 The Connection of Charge Bump Circuit

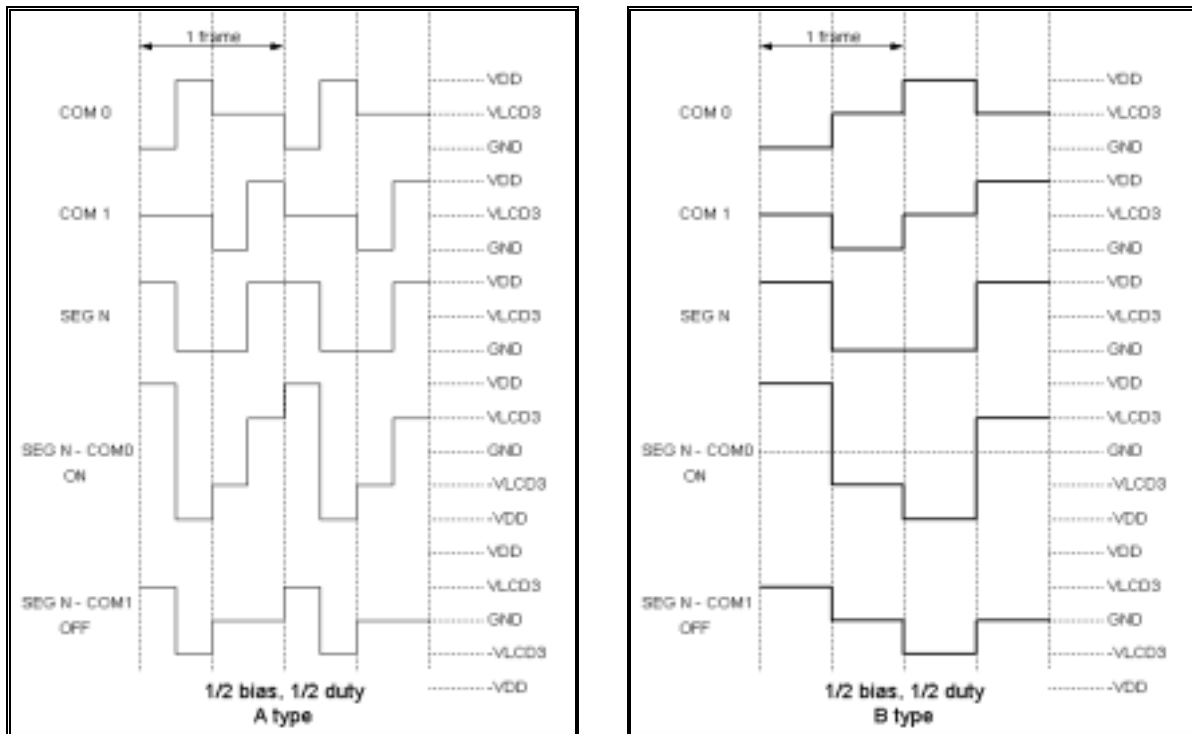


Fig. 18 LCD Waveform for 1/2 Bias, 1/2 Duty

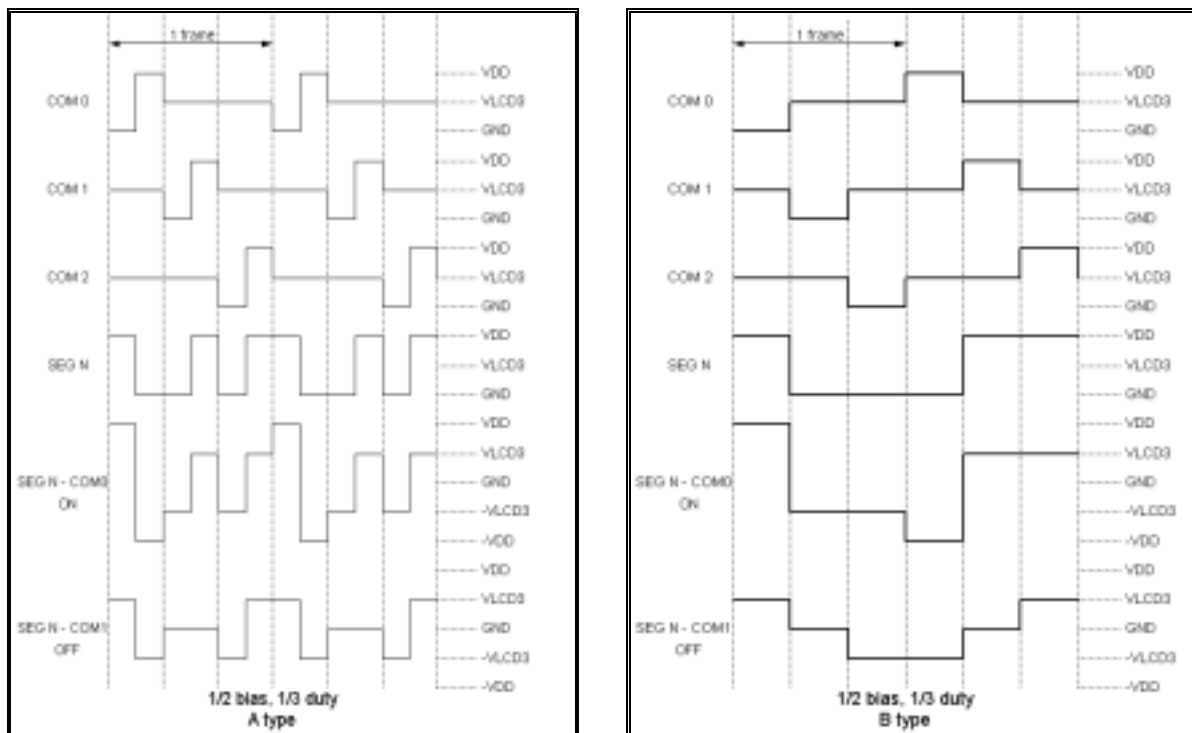


Fig. 19 LCD Waveform for 1/2 Bias, 1/3 Duty

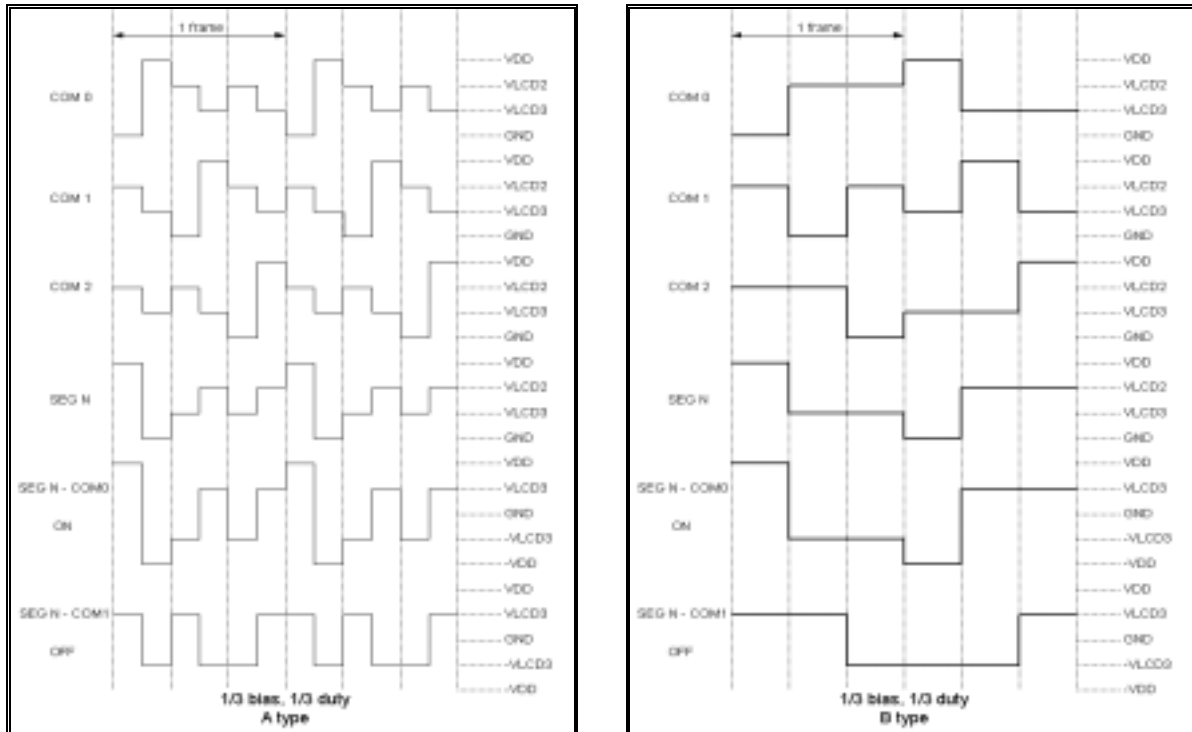


Fig. 20 LCD Waveform for 1/3 Bias, 1/3 Duty

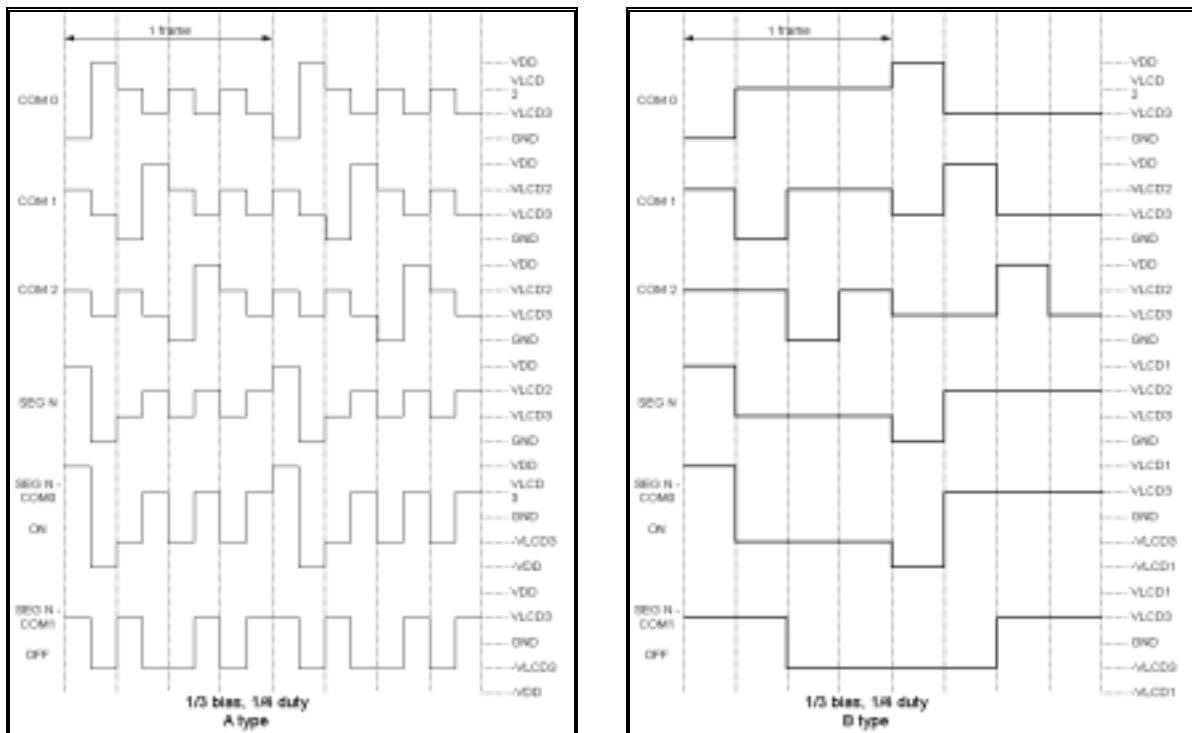


Fig. 21 LCD Waveform for 1/3 Bias, 1/4 Duty



#### **4.10 Infrared Remote Control Application / PWM Waveform Generate**

This LSI can output infrared carrier in a friendly manner or in PWM standard waveform. The IR and PWM waveform generated functions include an 8-bit down count timer/counter, high-pulse width timer, low-pulse width timer, and IR control register. The IR system block diagram is show in Fig.21, The IROUT pin waveform is determined by IR control register (RE), IOC90 (Counter 1, 2 control register), IOCA0 (high-pulse width timer, low-pulse width timer control register), IOCC0 (Counter 2 preset), IOCD0 (high-pulse width timer preset register), and IOCE0 (low-pulse width timer preset register). Details on Fcarrier, high-pulse time, and low pulse time are explained as follows:

If Counter 2 source clock is FT (this clock source can set by IOC91);

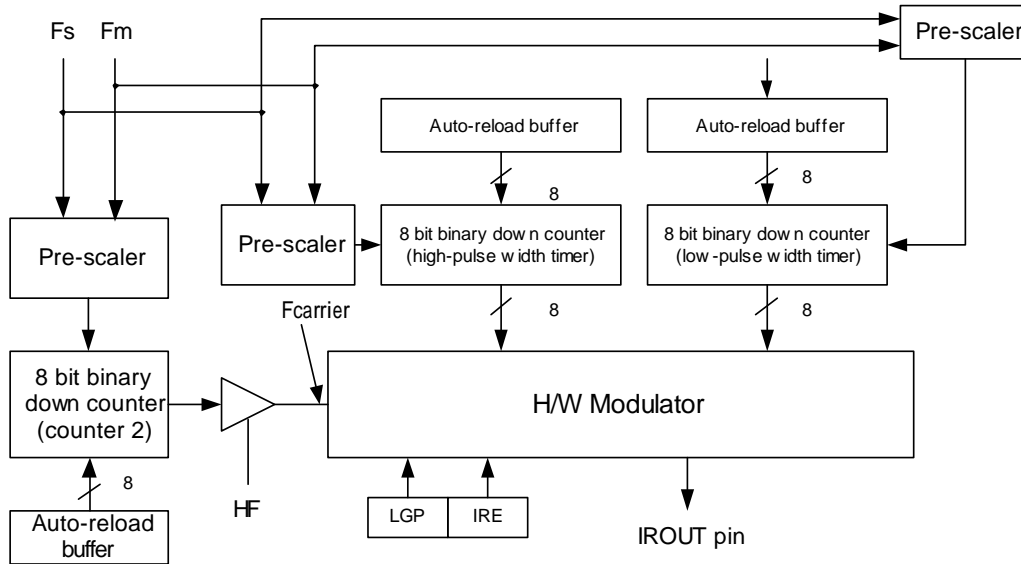
$$F_{\text{carrier}} = \text{FT} / (2^* [1 + \text{decimal counter 2 preset value (IOCC0)} * \text{prescaler}])$$

If high-pulse width timer source clock is FT (this clock source can set by IOCA1);

$$\text{High-pulse time} = \text{prescaler} * [1 + \text{decimal high-pulse width timer value (IOCD0)}] / \text{FT}$$

If low-pulse width timer source clock is FT (this clock source can set by IOCA1);

$$\text{Low-pulse time} = \text{prescaler} * [1 + \text{decimal low-pulse width timer value (IOCE0)}] / \text{FT}$$



**Fm:** Internal instruction cycle clock; **Fs:** sub-oscillator frequency

Fig. 21 IR/PWM System Block Diagram

The IROUT output waveform is further explained in the following figures:

Fig. 22 LGP=0, HF=1, the IROUT waveform can modulate Fcarrier waveform when in low-pulse width time.

Fig. 23 LGP=0, HF=0, the IROUT waveform cannot modulate Fcarrier waveform when in low-pulse width time. So IROUT waveform is determined by high-pulse time and low-pulse time. This mode can produce standard PWM waveform

Fig. 24 LGP=0, HF=1, the IROUT waveform can modulate Fcarrier waveform when in low-pulse width time. When IRE goes from high to low, the output waveform of IROUT will keep on transmitting till high-pulse width timer interrupt occurs.

Fig. 25 LGP=0, HF=0, the IROUT waveform can not modulate Fcarrier waveform when in low-pulse width time. So IROUT waveform is determined by high-pulse time and low-pulse time. This mode can produce standard PWM waveform. When IRE goes from high to low, the output waveform of IROUT will keep on transmitting till high-pulse width timer interrupt occurs.

Fig.26 LGP=1, when this bit is set to high level, the high-pulse width timer is ignored. So IROUT waveform output from low-pulse width timer is established.



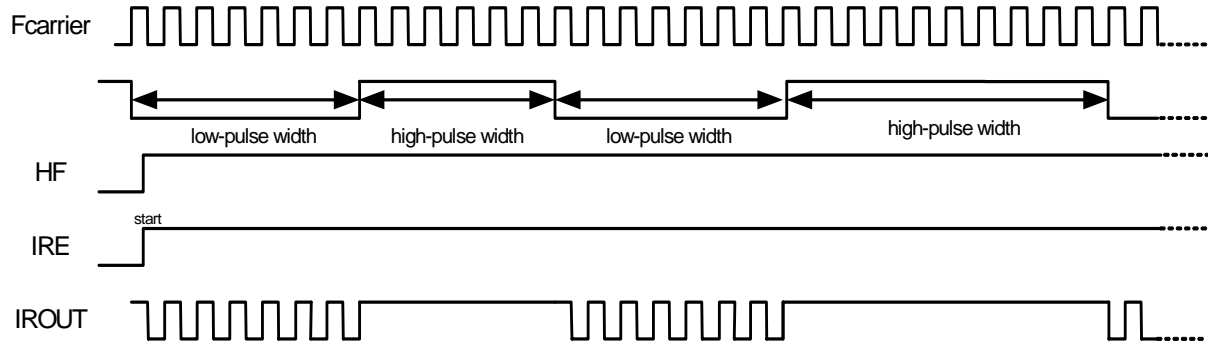


Fig. 22 LGP=0, IROUT Pin Output Waveform

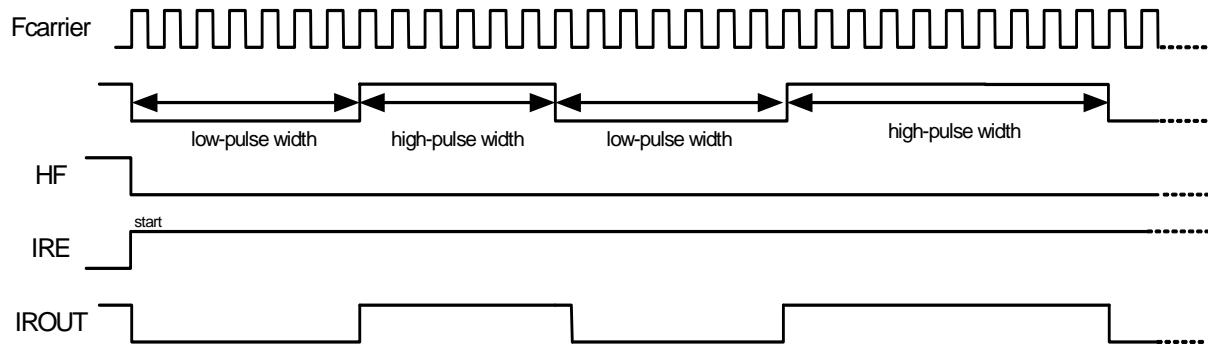


Fig. 23 LGP=0, IROUT Pin Output Waveform

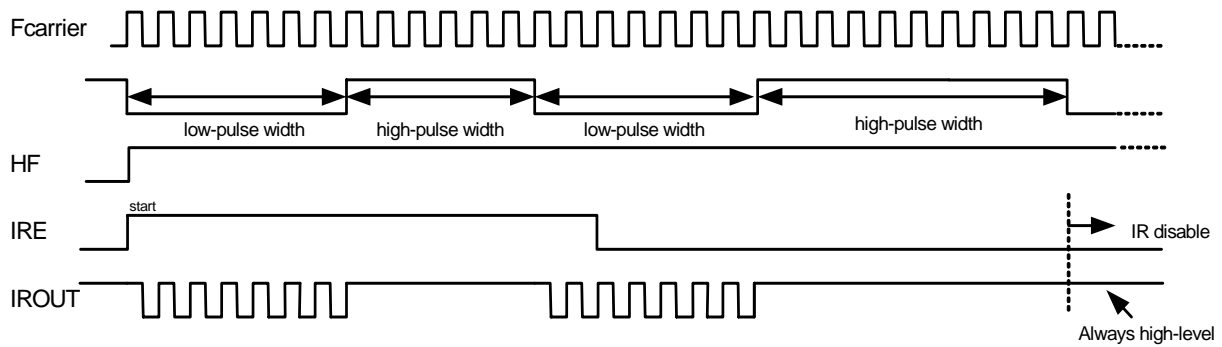


Fig. 24 LGP=0, IROUT Pin Output Waveform

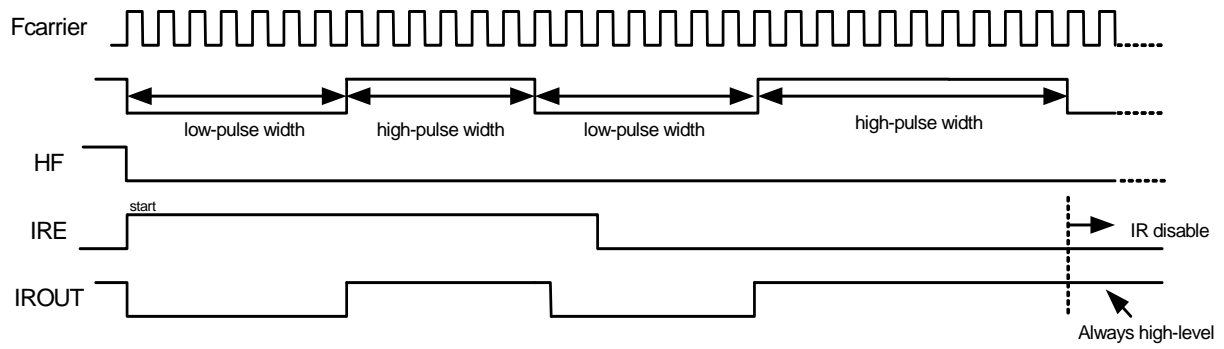


Fig. 25 LGP=0, IROUT Pin Output Waveform

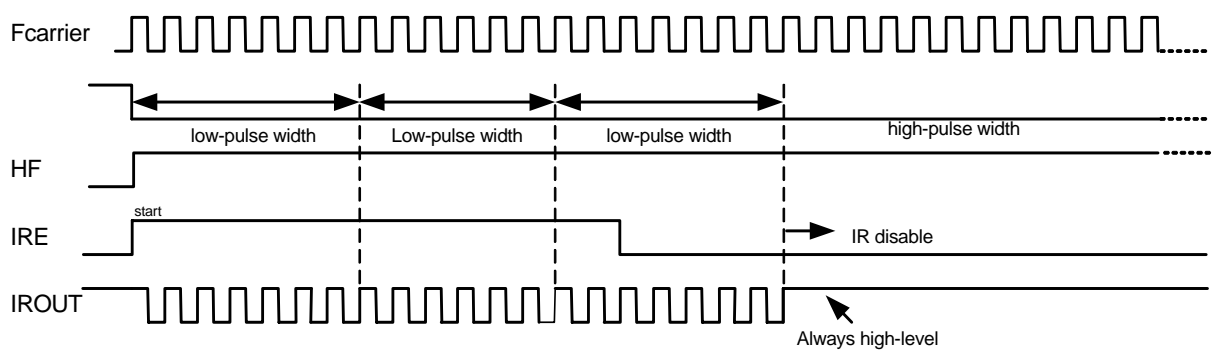
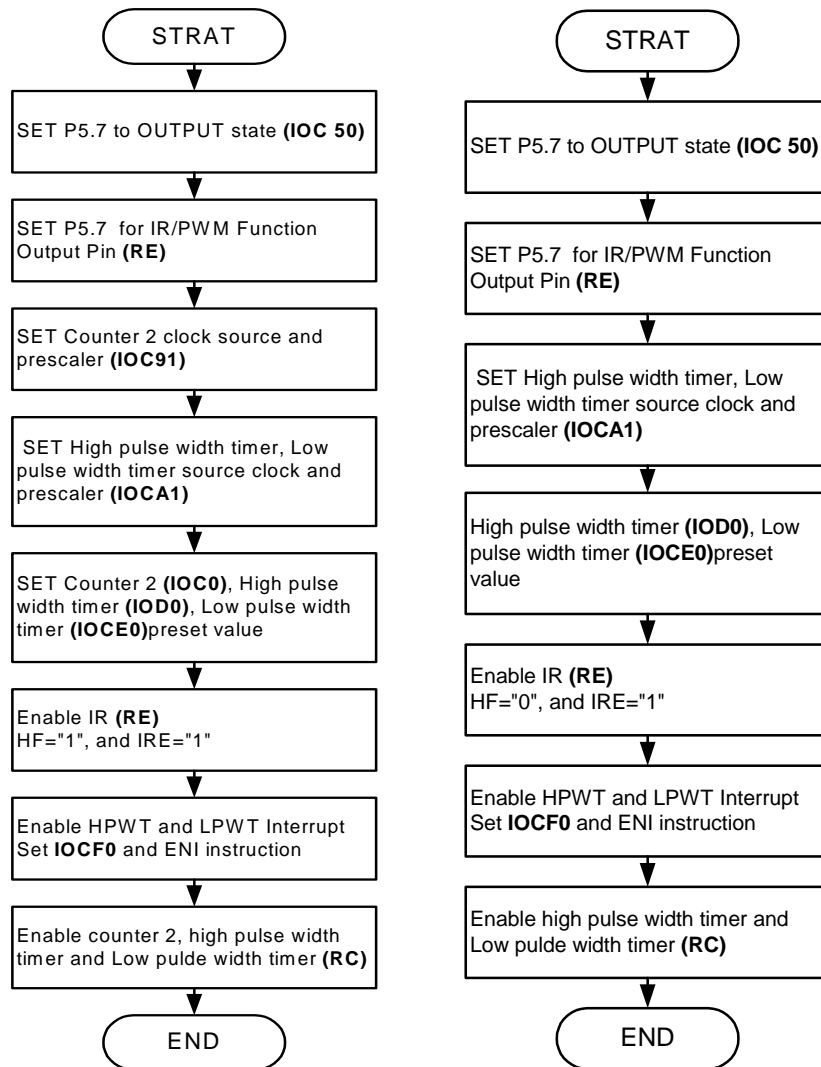


Fig. 26 LGP=1, IROUT Pin Output Waveform

IR/PWM function enable flowchart



(a) IR application

(b) PWM application

Fig. 27 IR/PWM Function Enable Flowchart



## 4.11 Code Options

The EM78P468N has one CODE option word that is not a part of the normal program memory. The option bits cannot be accessed during normal program execution.

Code Option Register and Customer ID Register arrangement distribution:

Word1 of code options is for customer ID code application.

Word 1
Bit12~Bit 0

Word0 of Code Options is for IC function setting. The following are the settings for OTP IC programming:

Word 0										
Bit12~10	Bit9	Bit8	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
1	CYES	HLFS	ENWDTB	FSMD	FMMD1	FMMD0	HLP	PR2	PR1	PR0

- **Bit 12 ~ 10:** Not used.  
These bits are set to "1" all the time.
- **Bit 9 (CYES):** Cycle select for JMP and CALL instructions  
  - 0: only one instruction cycle (JMP or CALL) can be executed
  - 1: two instructions cycles (JMP and CALL) can be executed
- **Bit 8 (HLFS):** main or sub-oscillator select  
  - 0: CPU is set to select sub-oscillator when reset occurred.
  - 1: CPU is set to select main-oscillator when reset occurred.
- **Bit 7 (ENWDTB):** Watchdog timer enable/disable bit.  
  - 0: Enable
  - 1: Disable
- **Bit 6 (FSMD):** sub-oscillator type selection.  
  - 0: RC type (internal C)
  - 1: XTAL type (Xin and Xout)
- **Bit 5, 4 (FMMD1, 0):** main Oscillator type selection.

FMMD1	FMMD0	Main Oscillator Type
0	0	RC type (external R, internal C)
0	1	XTAL type (R-OSCI, OSCO)
1	X	PLL type



• **Bit 3 (HLP):** Power consumption selection. If your system usually runs in green mode, it must be set to low power consumption. Take note and help support the energy saving issue. We recommend that low power consumption mode is selected.

**0:** Low power consumption mode

**1:** High power consumption mode

• **Bit 2~0 (PR2~PR0):** Protect Bit

PR2~PR0 are protect bits as explained below:

PR2	PR1	PR0	Protect
1	1	1	Disable
others			Enable

## 4.12 Instruction Set

Each instruction in the instruction set is a 13-bit word divided into an OP code and one or more operands. Normally, all instructions are executed within one single instruction cycle (one instruction consists of 2 oscillator periods), unless the program counter is changed by instruction "MOV R2,A", "ADD R2,A", or by instructions of arithmetic or logic operation on R2 (e.g. "SUB R2,A", "BS(C) R2,6", "CLR R2", ...). In this case, the execution takes two instruction cycles.

If for some reasons, the specification of the instruction cycle is not suitable for certain applications, try modifying the instruction as follows:

Execute within two instruction cycles the "JMP", "CALL", "RET", "RETL", & "RETI" instructions, or the conditional skip instructions ("JBS", "JBC", "JZ", "JZA", "DJZ", "DJZA") which were tested to be true. Also execute within two instruction cycles the instructions that are written to the program counter.

Additionally, the instruction set offers the following features:

- (1) Every bit of any register can be set, cleared, or tested directly.
- (2) The I/O register can be regarded as general register. That is, the same instruction can operate on I/O register.

The symbol "R" represents a register designator that specifies which one of the registers (including operational registers and general purpose registers) is to be utilized by the instruction. "b" represents a bit field designator that selects the value for the bit that is located in the register "R", and affects operation. "k" represents an 8 or 10-bit constant or literal value.



# EM78P468N OTP ROM

INSTRUCTION BINARY	HEX	MNEMONIC	OPERATION	STATUS AFFECTED
0 0000 0000 0000	0000	NOP	No Operation	None
0 0000 0000 0001	0001	DAA	Decimal Adjust A	C
0 0000 0000 0011	0003	SLEP	0 → WDT, Stop oscillator	T, P
0 0000 0000 0100	0004	WDTC	0 → WDT	T, P
0 0000 0000 rrrr	000r	IOW R	A → IOCR	None <Note1>
0 0000 0001 0000	0010	ENI	Enable Interrupt	None
0 0000 0001 0001	0011	DISI	Disable Interrupt	None
0 0000 0001 0010	0012	RET	[Top of Stack] → PC	None
0 0000 0001 0011	0013	RETI	[Top of Stack] → PC, Enable Interrupt	None
0 0000 0001 rrrr	001r	IOR R	IOCR → A	None <Note1>
0 0000 01rr rrrr	00rr	MOV R, A	A → R	None
0 0000 1000 0000	0080	CLRA	0 → A	Z
0 0000 11rr rrrr	00rr	CLR R	0 → R	Z
0 0001 00rr rrrr	01rr	SUB A, R	R-A → A	Z, C, DC
0 0001 01rr rrrr	01rr	SUB R, A	R-A → R	Z, C, DC
0 0001 10rr rrrr	01rr	DECA R	R-1 → A	Z
0 0001 11rr rrrr	01rr	DEC R	R-1 → R	Z
0 0010 00rr rrrr	02rr	OR A, R	A ∨ R → A	Z
0 0010 01rr rrrr	02rr	OR R, A	A ∨ R → R	Z
0 0010 10rr rrrr	02rr	AND A, R	A & R → A	Z
0 0010 11rr rrrr	02rr	AND R, A	A & R → R	Z
0 0011 00rr rrrr	03rr	XOR A, R	A ⊕ R → A	Z
0 0011 01rr rrrr	03rr	XOR R, A	A ⊕ R → R	Z
0 0011 10rr rrrr	03rr	ADD A, R	A + R → A	Z, C, DC
0 0011 11rr rrrr	03rr	ADD R, A	A + R → R	Z, C, DC
0 0100 00rr rrrr	04rr	MOV A, R	R → A	Z
0 0100 01rr rrrr	04rr	MOV R, R	R → R	Z
0 0100 10rr rrrr	04rr	COMA R	/R → A	Z
0 0100 11rr rrrr	04rr	COM R	/R → R	Z
0 0101 00rr rrrr	05rr	INCA R	R+1 → A	Z
0 0101 01rr rrrr	05rr	INC R	R+1 → R	Z
0 0101 10rr rrrr	05rr	DJZA R	R-1 → A, skip if zero	None
0 0101 11rr rrrr	05rr	DJZ R	R-1 → R, skip if zero	None
0 0110 00rr rrrr	06rr	RRCA R	R(n) → A(n-1), R(0) → C, C → A(7)	C
0 0110 01rr rrrr	06rr	RRC R	R(n) → R(n-1), R(0) → C, C → R(7)	C
0 0110 10rr rrrr	06rr	RLCA R	R(n) → A(n+1), R(7) → C, C → A(0)	C
0 0110 11rr rrrr	06rr	RLC R	R(n) → R(n+1), R(7) → C, C → R(0)	C
0 0111 00rr rrrr	07rr	SWAPA R	R(0-3) → A(4-7), R(4-7) → A(0-3)	None
0 0111 01rr rrrr	07rr	SWAP R	R(0-3) ↔ R(4-7)	None
0 0111 10rr rrrr	07rr	JZA R	R+1 → A, skip if zero	None



INSTRUCTION BINARY	HEX	MNEMONIC	OPERATION	STATUS AFFECTED
0 0111 11rr rrrr	07rr	JZ R	R+1 → R, skip if zero	None
0 100b brrr rrrr	0xxx	BC R, b	0 → R(b)	None <Note2>
0 101b brrr rrrr	0xxx	BS R, b	1 → R(b)	None <Note3>
0 110b brrr rrrr	0xxx	JBC R, b	if R(b)=0, skip	None
0 111b brrr rrrr	0xxx	JBS R, b	if R(b)=1, skip	None
1 00kk kkkk kkkk	1kkk	CALL k	PC+1 → [SP], (Page, k) → PC	None
1 01kk kkkk kkkk	1kkk	JMP k	(Page, k) → PC	None
1 1000 kkkk kkkk	18kk	MOV A, k	k → A	None
1 1001 kkkk kkkk	19kk	OR A, k	A ∨ k → A	Z
1 1010 kkkk kkkk	1Akk	AND A, k	A & k → A	Z
1 1011 kkkk kkkk	1Bkk	XOR A, k	A ⊕ k → A	Z
1 1100 kkkk kkkk	1Ckk	RETL k	k → A, [Top of Stack] → PC	None
1 1101 kkkk kkkk	1Dkk	SUB A, k	k-A → A	Z, C, DC
1 1110 1000 00kk	1E8k	PAGE k	k->R5(1:0)	None
1 1110 1001 00kk	1E9K	BANK k	k->R4(7:6)	None
1 1111 kkkk kkkk	1Fkk	ADD A, k	k+A → A	Z, C, DC

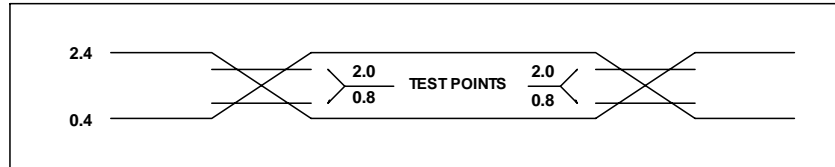
<Note1> This instruction is applicable to IOC5 ~ IOCF

<Note2> This instruction is not recommended for R3F operation.

<Note3> This instruction cannot operate under R3F.

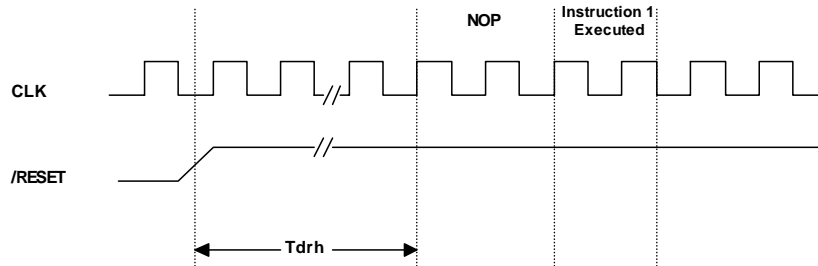
### 4.13 Timing Diagram

AC Test Input/Output Waveform

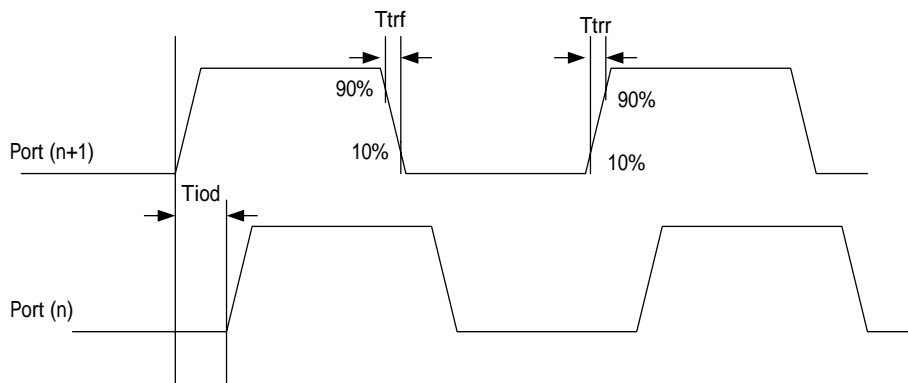
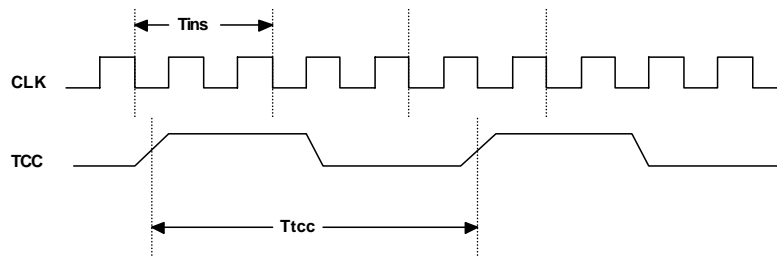


AC Testing : Input is driven at 2.4V for logic "1",and 0.4V for logic "0".Timing measurements are made at 2.0V for logic "1",and 0.8V for logic "0".

RESET Timing (CLK="0")



TCC Input Timing (CLKS="0")



\*n=0, 2, 4, 6





## 5. ABSOLUTE MAXIMUM RATINGS

Items	Symbol	Condition	Rating		Unit
			Min.	Max.	
Supply voltage	VDD		GND-0.3	+7.0	V
Input voltage	V <sub>I</sub>	Port5, Port6, Port7, Port8	GND-0.3	VDD+0.3	V
Output voltage	V <sub>O</sub>	Port5, Port6, Port7, Port8	GND-0.3	VDD+0.3	V
Operation temperature	T <sub>OPR</sub>		-40	85	
Storage temperature	T <sub>STG</sub>		-65	150	
Power dissipation	P <sub>D</sub>			500	mW
Operating Frequency			32.768K	10M	Hz



## 6. ELECTRICAL CHARACTERISTIC

### 6.1 DC ELECTRICAL CHARACTERISTICS

(Ta= 25 °C, VDD= 5.0V, GND= 0V)

Symbol	Parameter	Condition	Min.	Typ.	Max.	Unit
FXT	XTAL: VDD to 5V	Two cycle with two clocks	32.768K	8M	10M	Hz
Fs	Sub-oscillator	Two cycle with two clocks		32.768		KHz
ERIC	External R, internal C for sub-oscillator	R: 300KΩ, internal capacitance	270	384	500	KHz
	External R, internal C for sub-oscillator	R: 2.2MΩ, internal capacitance	29.5	32.768	42.6	KHz
IIL	Input Leakage Current for input pins	VIN = VDD, GND	-1	0	1	μA
VIH1	Input High Voltage	Ports 5, 6, 7, 8	2.0			V
VIL1	Input Low Voltage	Ports 5, 6, 7, 8			0.8	V
VIHT1	Input High Threshold Voltage (Schmitt trigger)	/RESET	2.0			V
VILT1	Input Low Threshold Voltage (Schmitt trigger)	/RESET			0.8	V
VIHT2	Input High Threshold Voltage (Schmitt trigger)	TCC, INT0, INT1	2.0			V
VILT2	Input Low Threshold Voltage (Schmitt trigger)	TCC, INT0, INT1			0.8	V
Vdet	Low voltage detector voltage	The voltage of Vdet is determined by RC control register	Vdet-0.2	Vdet	Vdet+0.2	V
IOH1	Output High Voltage (Ports 5, 6, 7, 8)	VOH = 2.4V	-10			mA
IOL1	Output Low Voltage (Ports 5, 6, 7, 8)	VOL = 0.4V			10	mA
IOH1	Output high voltage (IROUT pin)	VOH = 2.4V	-20			mA
IOL2	Output Low Voltage (IR OUT pin)	VOL = 0.4V			20	mA
IPH	Pull-high current	Pull-high active, input pin at GND	-55	-75	-95	μA
IPL	Pull-low current	Pull-low active, input pin at VDD	55	75	5	μA
ISB	Sleep mode current	All input and I/O pins at VDD, output pin floating, WDT disabled		0.3	1	μA
ICC1	Idle mode current	/RESET= 'High', CPU OFF, sub-oscillator clock (32.768KHz) ON, output pin floating, LCD enable, no load		12	16	μA
ICC2	Green mode current	/RESET= 'High', CPU ON, used sub-oscillator clock (32.768KHz), output pin floating, WDT enabled, LCD enable		22	30	μA
ICC3	Normal mode	/RESET= 'High', Fosc=4MHz (Crystal type, CLKS="0"), output pin floating		2.2	2.5	mA
ICC4	Normal mode	/RESET= 'High', Fosc=10MHz (Crystal type, CLKS="0"), output pin floating		3.1	3.5	mA



# EM78P468N OTP ROM

(Ta= 25 °C, VDD= 3.0V, GND= 0V)

Symbol	Parameter	Condition	Min.	Typ.	Max.	Unit
FXT	XTAL: VDD to 5V	Two cycle with two clocks	32.768K	8M	10M	Hz
Fs	Sub-oscillator	Two cycle with two clocks		32.768		KHz
ERIC	External R, internal C for sub-oscillator	R: 300KΩ, internal capacitance	270	384	500	KHz
	External R, internal C for sub-oscillator	R: 2.2MΩ, internal capacitance	29.5	32.768	42.6	KHz
IIL	Input Leakage Current for input pins	VIN = VDD, GND	-1	0	1	μA
VIH1	Input High Voltage	Ports 5, 6, 7, 8	1.6			V
VIL1	Input Low Voltage	Ports 5, 6, 7, 8			0.6	V
VIHT1	Input High Threshold Voltage (Schmitt trigger)	/RESET	1.6			V
VILT1	Input Low Threshold Voltage (Schmitt trigger)	/RESET			0.6	V
VIHT2	Input High Threshold Voltage (Schmitt trigger)	TCC, INT0, INT1	1.6			V
VILT2	Input Low Threshold Voltage (Schmitt trigger)	TCC, INT0, INT1			0.6	V
Vdet	Low voltage detector voltage	The voltage of Vdet is determined by RC control register	Vdet-0.2	Vdet	Vdet+0.2	V
IOH1	Output High Voltage (Ports 5, 6, 7, 8)	VOH = 2.4V	-1.8			mA
IOL1	Output Low Voltage (Ports 5, 6, 7, 8)	VOL = 0.4V			7	mA
IOH1	Output high voltage (IROUT pin)	VOH = 2.4V	-3.5			mA
IOL2	Output Low Voltage (IR OUT pin)	VOL = 0.4V			14	mA
IPH	Pull-high current	Pull-high active, input pin at GND	-16	-23	-30	μA
IPL	Pull-low current	Pull-low active, input pin at VDD	16	23	30	μA
ISB	Sleep mode current	All input and I/O pins at VDD, output pin floating, WDT disabled		0.1	1	μA
ICC1	Idle mode current	/RESET= 'High', CPU OFF, sub-oscillator clock (32.768KHz) ON, output pin floating, LCD enable, no load		4	8	μA
ICC2	Green mode current	/RESET= 'High', CPU ON, used sub-oscillator clock (32.768KHz), output pin floating, WDT enabled, LCD enable		10	20	μA
ICC3	Normal mode	/RESET= 'High', Fosc=4MHz (Crystal type, CLKS="0"), output pin floating		0.73	1.2	mA



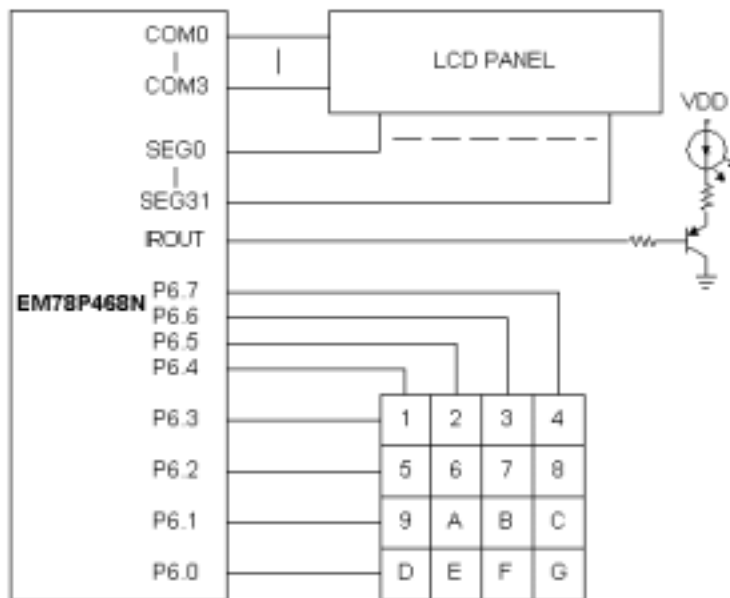
## 6.2 AC Electrical Characteristics

(Ta = -40°C ~ 85 °C, VDD=5V±5%, GND=0V)

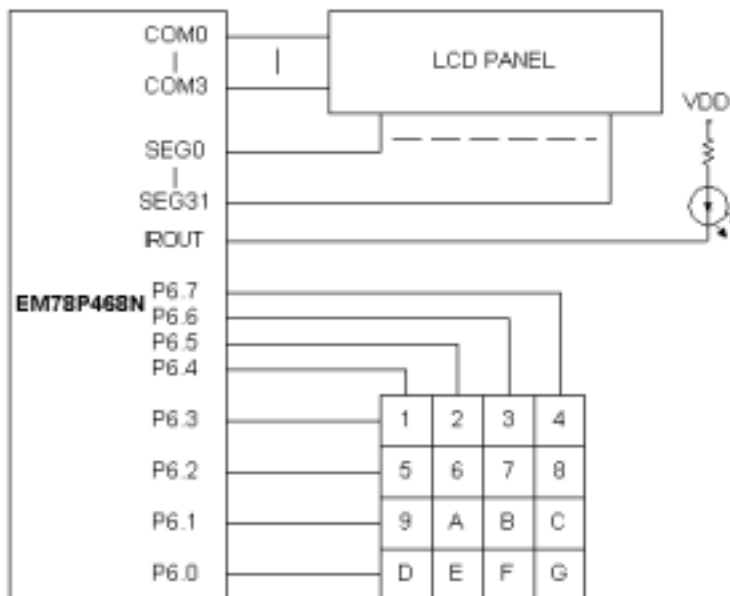
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Dclk	Input CLK duty cycle		45	50	55	%
Tins	Instruction cycle time (CLKS="0")	Crystal type	100		DC	ns
		RC type	500		DC	ns
Ttcc	TCC input period		(Tins+20)/N*			ns
Tdrh	Device reset hold time	Ta = 25°C	11.3	16.2	21.6	ms
Trst	/RESET pulse width	Ta = 25°C	2000			ns
Twdt	Watchdog timer period	Ta = 25°C	11.3	16.2	21.6	ms
Tset	Input pin setup time			0		ns
Thold	Input pin hold time			20		ns
Tdelay	Output pin delay time	Cload=20pF		50		ns
Tiod	I/O delay for EMI enable	Cload=150pF	4	5	6	ns
Ttrr1	Through rate for EMI enable(rising)	Cload=150pF	45	50	55	ns
Ttrf1	Through rate for EMI enable(falling)	Cload=150pF	45	50	55	ns
Ttrr2	Through rate for EMI enable(rising)	Cload=300pF	90	100	110	ns
Ttrf2	Through rate for EMI enable(falling)	Cload=300pF	90	100	110	ns

\* N= selected pre-scaler ratio.

## 7. Application Circuit



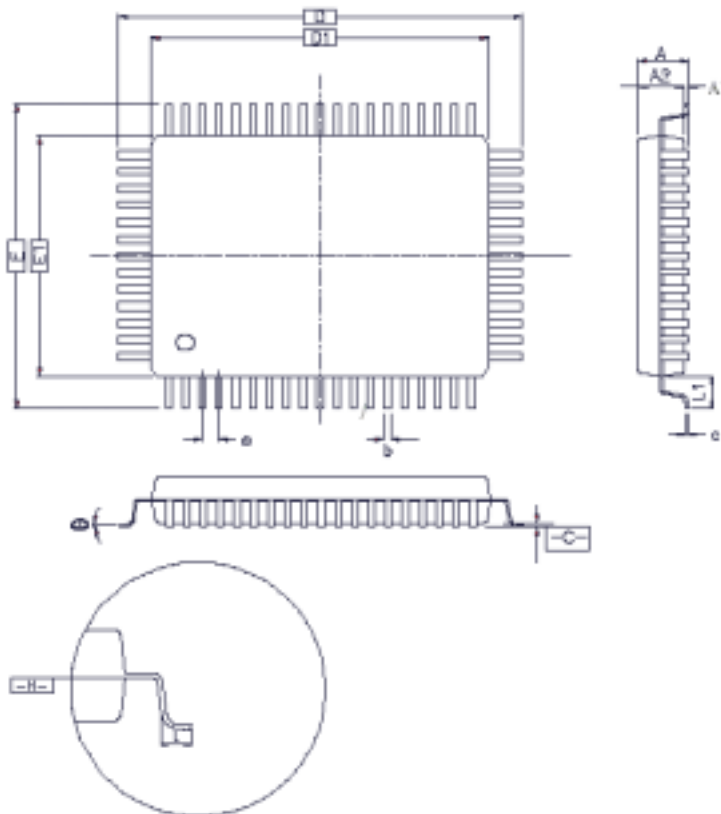
IROUT control external BJT circuit to drive infrared emitting diodes



IROUT direct drive infrared emitting diodes

**APPENDIX A:**

**Package information**



Symbol	Min	Normal	Max
A	—	—	3.40
A1	0.25	—	—
A2	2.55	2.80	3.05
D	23.29 BASIC		
D1	20.00 BASIC		
E	17.90 BASIC		
E1	14.00 BASIC		
$\beta$	0°	—	7°
c	0.10	0.15	0.25
L	0.73	0.88	1.03
L1	1.95 REF		
b	0.35	0.42	0.5
e	1.00 BSC		

TITLE: QFP-64 (14PINS) MICRO FOOTPRINT 1mm PACKAGE OF EM78P468N	
File: QFP64L	Edition: A
	Unit: mm
	Scale: Free
	Material:
Sheet 1 of 1	



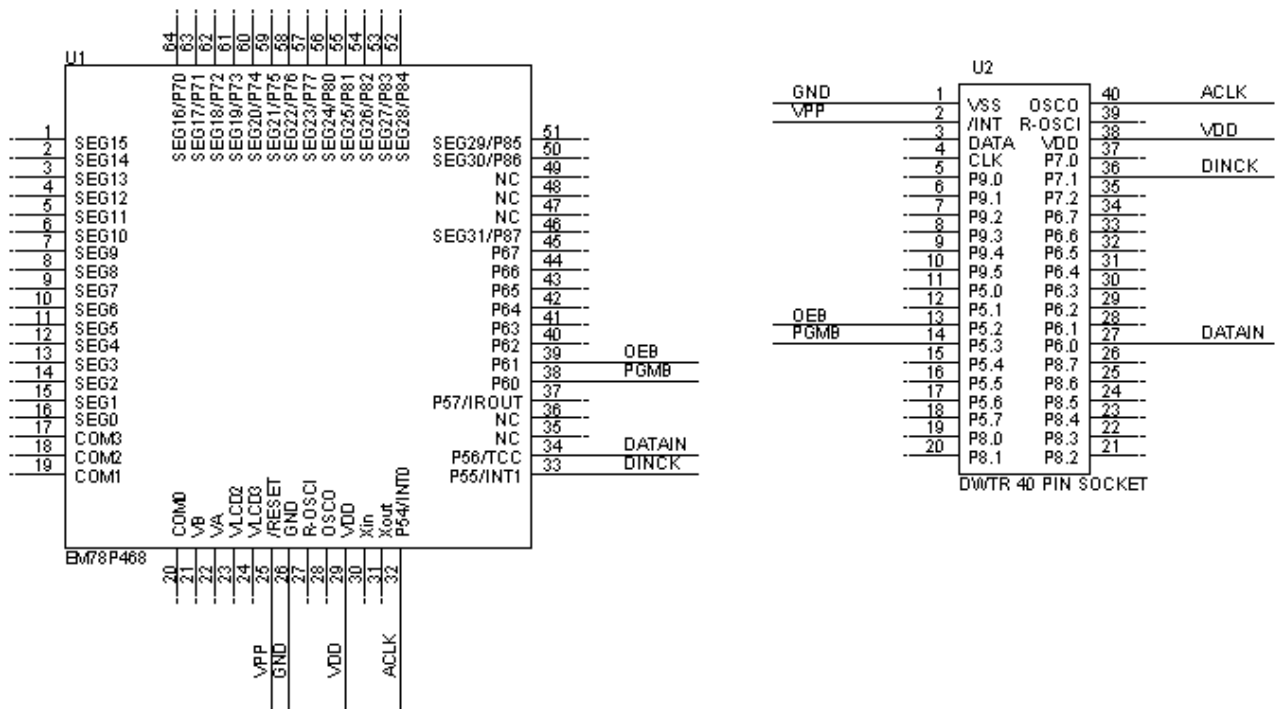
## APPENDIX B:

### EM78P468N Program Pin List

It uses DWTR to program EM78P468N IC's. The DWTR connector is selected by CON4 (EM78P451), and software is selected by EM78P468N.

Program Pin Name	QFP Pin Number	IC Pin Name
VPP	25	/RESET
ACLK	32	P54/INT0
DINCLK	33	P55/INT1
DATAIN	34	P56/TCC
/PGMB	38	P60
/OEB	39	P61
VDD	29	VDD
GND	26	GND

Wiring diagram for DWTR (Display writer).





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