

# Low Noise Angular Rate Sensor

# **Preliminary Technical Data**

Low Noise Density, .013°/s/√Hz, over Full Range

ADIS16120

#### **FEATURES**

300°/sec Dynamic Range
Z-axis, yaw rate, response
Calibrated Offset and Sensitivity
320 Hz Bandwidth
External adjustment with a single component
Digital Self-Test
High Vibration Rejection
High Shock Survivability
Embedded Temperature Sensor Output
Precision Voltage Reference Output
Highly integrated, requiring minimal external components
5V single supply operation
-40°C to 85°C

#### **APPLICATIONS**

Guidance and Control Instrumentation Inertial measurement units Stabilization

#### **GENERAL DESCRIPTION**

The ADIS16120 is a Low Noise and power efficient Angular Rate Sensor (gyroscope). The circuit includes embedded signal conditioning to provide low noise operation over the entire 300°/s dynamic range, as well as excellent offset and gain accuracy over temperature. The surface-micromachining manufacturing technology is the same high volume BIMOS process used by Analog Devices for its high reliability automotive airbag sensor line.

The output signal, RATE OUT, is a voltage proportional to angular rate about the axis normal to the top surface of the package. A precision reference and a temperature output are available for system-level use and a digital self-test feature is available to electromechanically excite the sensor and verify proper operation. Variations in Range, Sensitivity, and Bandwidth can be addressed (consult the factory).

The fully integrated design eases system implementation, and minimizes overall power consumption to 500mW. The 36mm x 42mm (plus mounting extensions) package provides the convenience of a standard geometry 24-pin interface and four mounting holes.

#### **FUNCTIONAL BLOCK DIAGRAM**

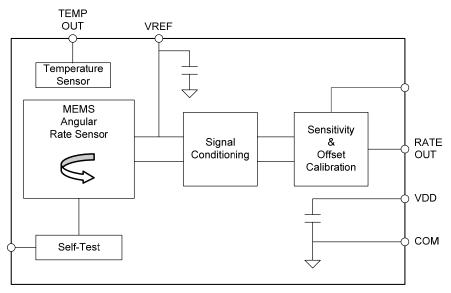


Figure 1.

# **ADIS16120**

# **Preliminary Technical Data**

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### **REVISION HISTORY**

11/16/05—PSD1 - Preliminary version

1/5/06 - Pr.A - Preliminary Draft

### **SPECIFICATIONS**

@ $T_A = 25$ °C, VCC = 5 V, Angular Rate = 0°/s,  $C_{OUT} = 0 \mu F$ ,  $\pm 1 g$ , unless otherwise noted.

Table 1.

|   |   |                  | ADIS16120 |                  |         |
|---|---|------------------|-----------|------------------|---------|
| Parameter                                     | Conditions  | Min <sup>1</sup> | Тур       | Max <sup>1</sup> | Unit    |
| SENSITIVITY                                   | Clockwise rotation is positive output                           |                  |           |                  |         |
| Dynamic Range <sup>2</sup>                    | Full-scale range over specifications range                      | ±300             |           |                  | °/s     |
| Initial                                       | @25°C   | 4.95             | 5         | 5.05             | mV/°/s  |
| Over Temperature <sup>3</sup>                 | $V_S = 4.75 \text{ V to } 5.25 \text{ V}$                       | TBD              | 5         | TBD              | mV/°/s  |
| Nonlinearity                                  | Best fit straight line  |                  | TBD       |                  | % of FS |
| NULL  |   |                  |           |                  |         |
| Initial Null                                  |   | 2.475            | 2.50      | 2.525            | V       |
| Over Temperature <sup>3</sup>                 | $V_S = 4.75 \text{ V to } 5.25 \text{ V}$                       | 2.45             |           | 2.55             | V       |
| Turn-On Time                                  | Power on to ±1/2°/s of final value, 80Hz bandwidth <sup>4</sup> |                  | 35        |                  | ms      |
| Linear Acceleration Effect                    | Any axis  |                  | TBD       |                  | °/s/g   |
| Voltage Sensitivity                           | $V_{CC} = 4.75 \text{ V to } 5.25 \text{ V}$                    |                  | 1         |                  | °/s/V   |
| NOISE PERFORMANCE                             |   |                  |           |                  |         |
| Rate Noise Density                            | @25°C   |                  | 0.013     |                  | °/s/√Hz |
| FREQUENCY RESPONSE                            |   |                  |           |                  |         |
| 3 dB Bandwidth (User Selectable) <sup>5</sup> | No external capacitance   |                  | 320       |                  | Hz      |
| Sensor Resonant Frequency                     | '   |                  | 14        |                  | kHz     |
| SELF-TEST INPUTS                              |   |                  |           |                  |         |
| ST RATEOUT Response <sup>6</sup>              | ST pin from Logic 0 to 1  | +150             | +270      | +450             | mV      |
| Logic 1 Input Voltage                         | Standard high logic level definition                            | 3.3              |           |                  | V       |
| Logic 0 Input Voltage                         | Standard low logic level definition                             |                  |           | 1.7              | V       |
| Input Impedance                               | To common   |                  | 3.1       |                  | kΩ      |
| TEMPERATURE SENSOR                            |   |                  |           |                  |         |
| V <sub>OUT</sub> at 298°K                     |   |                  | 2.50      |                  | V       |
| Max Current Load on Pin                       | Source to common  |                  |           | 50               | μΑ      |
| Scale Factor                                  | Proportional to absolute temperature                            |                  | 8.4       |                  | mV/°K   |
| OUTPUT DRIVE CAPABILITY                       | ·   |                  |           |                  |         |
| Output Voltage Swing                          | $I_{OUT} = \pm 100 \mu\text{A}$                                 | 0.25             |           | $V_{S} - 0.25$   | V       |
| Capacitive Load Drive                         |   | 1000             |           |                  | pF      |
| 2.5 V REFERENCE                               |   |                  |           |                  | 1       |
| Voltage Value                                 |   | 2.45             | 2.5       | 2.55             | V       |
| Load Drive to Ground                          | Source  |                  | 200       |                  | uА      |
| Load Regulation                               | 0 < Ιουτ < 200 μΑ   |                  | 5.0       |                  | mV/mA   |
| Power Supply Rejection                        | 4.75 V <sub>s</sub> to 5.25 V <sub>s</sub>                      |                  | 1.0       |                  | mV/V    |
| Temperature Drift                             | Delta from 25°C   |                  | 5.0       |                  | mV      |
| POWER SUPPLY                                  |   |                  |           |                  |         |
| Operating Voltage Range                       |   | 4.75             | 5.00      | 5.25             | V       |
| Quiescent Supply Current                      |   |                  | 100       | 132              | mA      |
| TEMPERATURE RANGE                             |   |                  |           | -                | -       |
| Specified Performance Grade A                 | Temperature tested to max and min specifications                | -40              |           | +85              | °C      |

<sup>1</sup> All minimum and maximum specifications are guaranteed. Typical specifications are not tested or guaranteed.

<sup>&</sup>lt;sup>2</sup> Dynamic range is the maximum full-scale measurement range possible, including output swing range, initial offset, sensitivity, offset drift, and sensitivity drift at 5 V supplies.

 $<sup>^3</sup>$  Specification refers to the maximum extent of this parameter as a worst-case value of  $T_{\text{MIN}}$  or  $T_{\text{MAX}}$ .

<sup>&</sup>lt;sup>4</sup> Dependent on bandwidth

<sup>&</sup>lt;sup>5</sup> Frequency at which response is 3 dB down from dc response with specified compensation capacitor value. Internal pole forming resistor is 180 kΩ. See the section titled, "SETTING THE BANDWIDTH."

<sup>&</sup>lt;sup>6</sup> Self-test response varies with temperature..

## ADIS16120

### **ABSOLUTE MAXIMUM RATINGS**

#### Table 2.

| 1 11010 21  |                  |
|---|------------------|
| Parameter   | Rating           |
| Acceleration (Any Axis, Unpowered, 0.5 ms)        | 2000 g           |
| Acceleration (Any Axis, Powered, 0.5 ms)          | 2000 <i>g</i>    |
| +V <sub>S</sub>                                   | -0.3 V to +6.0 V |
| Output Short-Circuit Duration (Any Pin to Common) | Indefininte      |
| Operating Temperature Range                       | −55°C to +125°C  |
| Storage Temperature                               | −65°C to +150°C  |

Stresses above those listed under the Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Drops onto hard surfaces can cause shocks of greater than 2000 *g* and exceed the absolute maximum rating of the device. Care should be exercised in handling to avoid damage.

#### **RATE SENSITIVE AXIS**

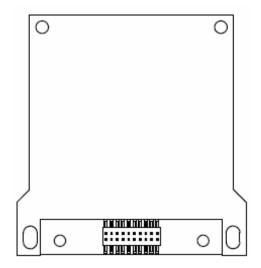
This is a Z-axis rate-sensing device that is also called a yaw rate sensing device. It produces a positive going output voltage for clockwise rotation about the axis normal to the package top, i.e., clockwise when looking down at the package lid.

#### **ESD CAUTION**

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



# PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



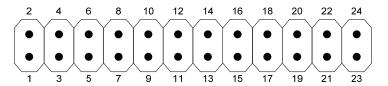


Figure 2 – ADIS16120 Pin Assignment (Connector-up View)

#### Table 3 – Pin Definitions

| PIN | NAME | DESCRIPTION         | PIN | NAME    | DESCRIPTION                |
|-----|------|---------------------|-----|---------|----------------------------|
| 1   | ST   | Self Test           | 2   | ST      | Self Test                  |
| 3   | ST   | Self Test           | 4   | ST      | Self Test                  |
| 5   | ST   | Self Test           | 6   | ST      | Self Test                  |
| 7   | ST   | Self Test           | 8   | COM     | Power supply ground        |
| 9   | ST   | Self Test           | 10  | TEMPOUT | Temperature sensor output  |
| 11  | COM  | Power supply ground | 12  | REFOUT  | Reference voltage          |
| 13  | VCC  | Power Supply        | 14  | COM     | Power supply ground        |
| 15  | VCC  | Power Supply        | 16  | СОМ     | Power supply ground        |
| 17  | COM  | Power supply ground | 18  | RATEOUT | Angular rate output signal |
| 19  | COM  | Power supply ground | 20  | SUMJ    | Summing Junction           |
| 21  | DNC  | Do not connect      | 22  | DNC     | Do not connect             |
| 23  | COM  | Power supply ground | 24  | DNC     | Do not connect             |

### THEORY OF OPERATION

The base sensor in the ADIS16120 operates on the principle of a resonator gyroscope. Two polysilicon sensing structures each contain a dither frame, which is electrostatically driven to resonance. This produces the necessary velocity element that creates a Coriolis force during angular motion. At the two outer extremes of each frame, orthogonal to the dither motion, are movable fingers that are placed between fixed pickoff fingers to form a capacitive pickoff structure that senses Coriolis motion. The resulting signal is fed to a series of gain and demodulation stages that produce the electrical rate signal output. One advantage of the core dual-sensor design approach is that it provides improved immunity against external *g*-forces and vibration.

The ADIS16120 signal conditioning circuit provides an optimized filtering network that controls the resonator's influence on noise density while supporting a nominal bandwidth of 320Hz. Another feature that helps reduce sensitivity to power supply noise is the integration of approximately 1.8uF of decoupling capacitance inside the ADIS16120's package.

The offset and sensitivity performance is factory calibrated across temperature and the internal reference voltage used in this calibration process is offered for external use. A temperature sensor is also provided for system-level use, where appropriate.

#### **SETTING THE BANDWIDTH**

An important trade-off in angular rate measurement applications is the one between total system noise and bandwidth. The ADIS16120 offers the flexibility to optimize this trade-off at the system level. The ADIS16120's signal processing circuit provides a three-pole, low pass filter, as described in Figure 3.

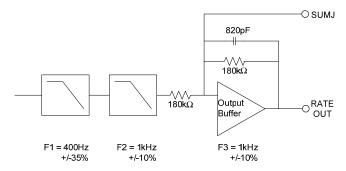


Figure 3 –Simplified Filtering Network

The bandwidth of the third stage can be reduced by installing a single capacitor across the RATE OUT and SUMJ pins. Figure 4 provides a relationship for selecting the appropriate capacitor value. The initial bandwidth of the ADIS16120 is dominated by the first stage, which is dependent on the sensor's process variation. By reducing the bandwidth of the third filter stage, the influence of the first stage is reduced, providing a method for tighter bandwidth tolerances.

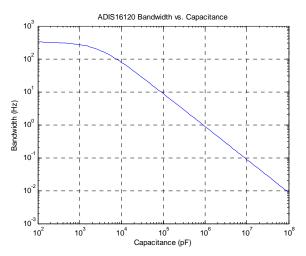


Figure 4 – Bandwidth vs. Capacitance

#### **SUPPLY AND COMMON CONSIDERATIONS**

The ADIS16120 provides approximately 1.8uF of decoupling capacitance internally, eliminating the need for local decoupling capacitors in most systems.

#### **SELF TEST FUNCTION**

The ADIS16120 provides a self test function that exercises the sensor's mechanical structure. In order to use this function, pins 1-7 and 9 must be tied together and driven to a "high" logic state.

#### USING THE ADIS16120 WITH A SUPPLY-RATIOMETRIC ADC

The ADIS16120's RATEOUT signal is nonratiometric, i.e., neither the null voltage nor the rate sensitivity is proportional to the supply. Rather they are nominally constant for dc supply changes within the 4.75 V to 5.25 V operating range. If the ADIS16120 is used with a supply-ratiometric ADC, the ADIS16120's 2.5 V output can be converted and used to make corrections in software for the supply variations.

## **OUTLINE DIMENSIONS**

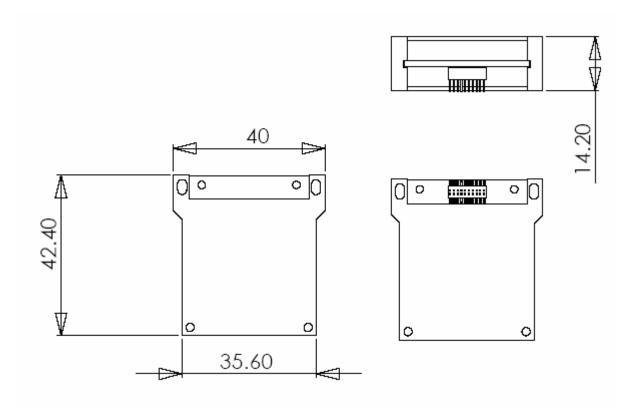


Figure 5.
Dimensions shown in millimeters

### **ORDERING GUIDE**

| Model         | Temperature Range | Package Description | Package Outline |
|---------------|-------------------|---------------------|-----------------|
| ADIS16120AML  | -40°C to +85°C    |                     |                 |
| ADIS16120/PCB |                   | Evaluation Board    |                 |