INTEGRATED CIRCUITS

DATA SHEET

TDA8927 Power stage 2×80 W class-D audio amplifier

Preliminary specification
Supersedes data of 2001 Dec 11

2002 Oct 22





TDA8927

CONTENT	re	15	TEST AND APPLICATION INFORMATION
1 2 3 4 5	FEATURES APPLICATIONS GENERAL DESCRIPTION QUICK REFERENCE DATA ORDERING INFORMATION	15.1 15.2 15.3 15.4 15.5 15.6	BTL application Package ground connection Output power Reference design Reference design bill of materials Curves measured in reference design PACKAGE OUTLINES
6	BLOCK DIAGRAM	17	SOLDERING
7 8 8.1 8.2 8.2.1 8.2.2 8.3 9	PINNING FUNCTIONAL DESCRIPTION Power stage Protection Overtemperature Short-circuit across the loudspeaker terminals BTL operation LIMITING VALUES	17.1 17.2 17.3 17.4 18	Introduction to soldering through-hole mount packages Soldering by dipping or by solder wave Manual soldering Suitability of through-hole mount IC packages for dipping and wave soldering methods DATA SHEET STATUS DEFINITIONS
10 11 12 13 14 14.1	THERMAL CHARACTERISTICS QUALITY SPECIFICATION DC CHARACTERISTICS AC CHARACTERISTICS SWITCHING CHARACTERISTICS Duty factor	20	DISCLAIMERS

Power stage 2×80 W class-D audio amplifier

TDA8927

1 FEATURES

- High efficiency (>94%)
- Operating voltage from ±15 to ±30 V
- · Very low quiescent current
- · High output power
- Short-circuit proof across the load, only in combination with controller TDA8929T
- · Diagnostic output
- Usable as a stereo Single-Ended (SE) amplifier or as a mono amplifier in Bridge-Tied Load (BTL)
- Electrostatic discharge protection (pin to pin)
- Thermally protected, only in combination with controller TDA8929T.

2 APPLICATIONS

- Television sets
- · Home-sound sets
- Multimedia systems
- · All mains fed audio systems
- Car audio (boosters).

3 GENERAL DESCRIPTION

The TDA8927 is the switching power stage of a two-chip set for a high efficiency class-D audio power amplifier system. The system is split into two chips:

- TDA8927J; digital power stage in a DBS17P package
- TDA8929T; analog controller chip in a SO24 package.

With this chip set a compact 2×80 W audio amplifier system can be built, operating with high efficiency and very low dissipation. No heatsink is required, or depending on supply voltage and load, a very small one. The system operates over a wide supply voltage range from ±15 up to ±30 V and consumes a very low quiescent current.

4 QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT	
General; $V_P = \pm 25$	V						
V _P	supply voltage		±15	±25	±30	V	
I _{q(tot)}	total quiescent current	no load connected	_	35	45	mA	
η	efficiency	P _o = 30 W	_	94	_	%	
Stereo single-end	led configuration						
Po	output power	$R_L = 4 \Omega$; THD = 10%; $V_P = \pm 25 V$	60	65	_	W	
		$R_L = 4 \Omega$; THD = 10%; $V_P = \pm 27 V$	74	80	_	W	
Mono bridge-tied load configuration							
Po	output power	$R_L = 4 \Omega$; THD = 10%; $V_P = \pm 17 V$	90	110	_	W	
		$R_L = 8 \Omega$; THD = 10%; $V_P = \pm 25 \text{ V}$	120	150	_	W	

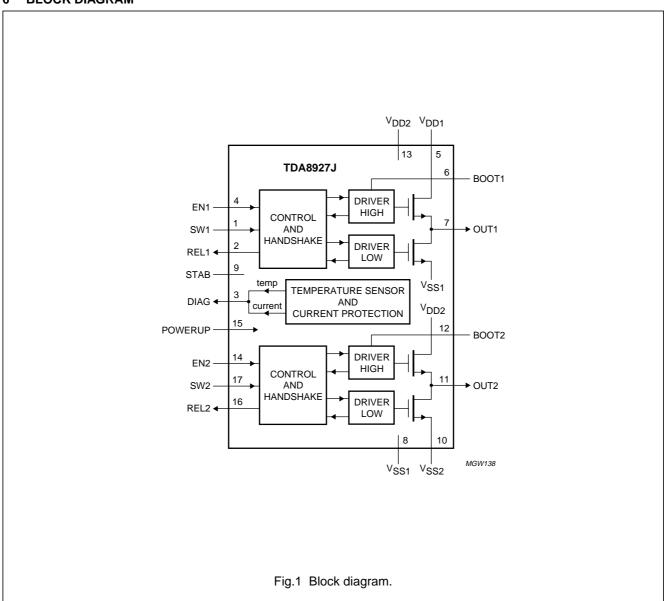
5 ORDERING INFORMATION

TYPE NUMBER		PACKAGE			
I TPE NOWBER	NAME	DESCRIPTION	VERSION		
TDA8927J	DBS17P	plastic DIL-bent-SIL power package; 17 leads (lead length 12 mm)	SOT243-1		

Power stage $2 \times 80 \text{ W}$ class-D audio amplifier

TDA8927

6 BLOCK DIAGRAM

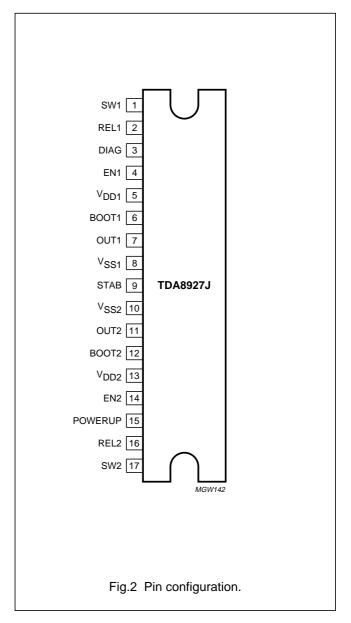


Power stage $2 \times 80 \text{ W}$ class-D audio amplifier

TDA8927

7 PINNING

SYMBOL	PIN	DESCRIPTION
SW1	1	digital switch input; channel 1
REL1	2	digital control output; channel 1
DIAG	3	digital open-drain output for overtemperature and overcurrent report
EN1	4	digital enable input; channel 1
V_{DD1}	5	positive power supply; channel 1
BOOT1	6	bootstrap capacitor; channel 1
OUT1	7	PWM output; channel 1
V _{SS1}	8	negative power supply; channel 1
STAB	9	decoupling internal stabilizer for logic supply
V _{SS2}	10	negative power supply; channel 2
OUT2	11	PWM output; channel 2
BOOT2	12	bootstrap capacitor; channel 2
V _{DD2}	13	positive power supply; channel 2
EN2	14	digital enable input; channel 2
POWERUP	15	enable input for switching on internal reference sources
REL2	16	digital control output; channel 2
SW2	17	digital switch input; channel 2



Power stage 2×80 W class-D audio amplifier

TDA8927

8 FUNCTIONAL DESCRIPTION

The combination of the TDA8927 and the TDA8929T produces a two-channel audio power amplifier system using the class-D technology (see Fig.3). In the TDA8929T controller the analog audio input signal is converted into a digital Pulse Width Modulation (PWM) signal.

The power stage TDA8927 is used for driving the low-pass filter and the loudspeaker load. It performs a level shift from the low-power digital PWM signal, at logic levels, to a high-power PWM signal that switches between the main supply lines. A 2nd-order low-pass filter converts the PWM signal into an analog audio signal across the loudspeaker.

For a description of the controller, see data sheet "TDA8929T, Controller class-D audio amplifier".

8.1 Power stage

The power stage contains the high-power DMOS switches, the drivers, timing and handshaking between the power switches and some control logic. For protection, a temperature sensor and a maximum current detector are built-in on the chip.

For interfacing with the controller chip the following connections are used:

- Switch (pins SW1 and SW2): digital inputs; switching from V_{SS} to V_{SS} + 12 V and driving the power DMOS switches
- Release (pins REL1 and REL2): digital outputs to indicate switching from V_{SS} to V_{SS} + 12 V, follow pins SW1 and SW2 with a small delay
- Enable (pins EN1 and EN2): digital inputs; at a level of V_{SS} the power DMOS switches are open and the PWM outputs are floating; at a level of V_{SS} + 12 V the power stage is operational and controlled by the switch pin if pin POWERUP is at V_{SS} + 12 V
- Power-up (pin POWERUP): must be connected to a continuous supply voltage of at least V_{SS} + 5 V with respect to V_{SS}
- Diagnostics (pin DIAG): digital open-drain output; pulled to V_{SS} if the temperature or maximum current is exceeded.

8.2 Protection

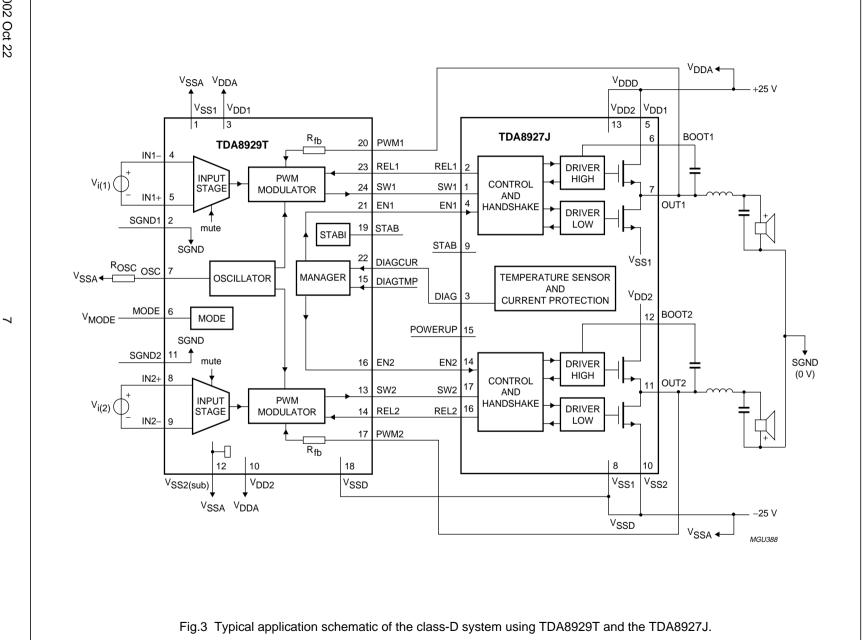
Temperature and short-circuit protection sensors are included in the TDA8927 power stage. The protection circuits are operational only in combination with the TDA8929T. In the event that the maximum current or maximum temperature is exceeded the diagnostic output is activated. The controller has to take appropriate measures by shutting down the system.

8.2.1 OVERTEMPERATURE

If the junction temperature (T_j) exceeds 150 °C, then pin DIAG becomes LOW. The diagnostic pin is released if the temperature is dropped to approximately 130 °C, so there is a hysteresis of approximately 20 °C.

8.2.2 SHORT-CIRCUIT ACROSS THE LOUDSPEAKER TERMINALS

When the loudspeaker terminals are short-circuited this will be detected by the current protection. If the output current exceeds the maximum output current of 7.5 A, then pin DIAG becomes LOW. The controller should shut down the system to prevent damage. Using the TDA8929T the system is shut down within 1 μs , and after 220 ms it will attempt to restart the system again. During this time the dissipation is very low, therefore the average dissipation during a short-circuit is practically zero.



Power stage 2×80 W class-D audio amplifier

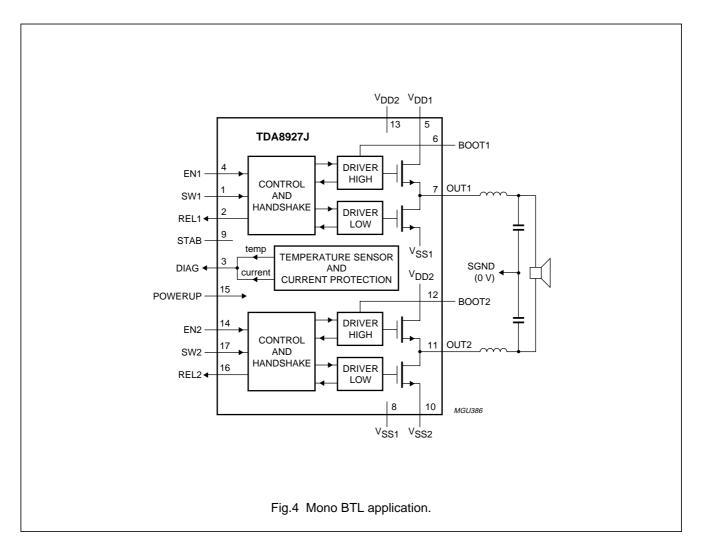
TDA8927

8.3 BTL operation

BTL operation can be achieved by driving the audio input channels of the controller in the opposite phase and by connecting the loudspeaker with a BTL output filter between the two PWM output pins of the power stage (see Fig.4).

In this way the system operates as a mono BTL amplifier and with the same loudspeaker impedance a four times higher output power can be obtained.

For more information see Chapter 15.



Power stage $2 \times 80 \text{ W}$ class-D audio amplifier

TDA8927

9 LIMITING VALUES

In accordance with the Absolute Maximum Rate System (IEC 60134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V _P	supply voltage		_	±30	V
V _{P(sc)}	supply voltage for short-circuits across the load		_	±30	V
I _{ORM}	repetitive peak current in output pins		_	7.5	А
T _{stg}	storage temperature		-55	+150	°C
T _{amb}	ambient temperature		-40	+85	°C
T _{vj}	virtual junction temperature		_	150	°C
V _{es(HBM)}	electrostatic discharge	note 1			
	voltage (HBM)	all pins with respect to V _{DD} (class 1a)	-500	+500	V
		all pins with respect to V _{SS} (class 1a)	-1500	+1500	V
		all pins with respect to each other (class 1a)	-1500	+1500	V
V _{es(MM)}	electrostatic discharge	note 2			
	voltage (MM)	all pins with respect to V _{DD} (class B)	-250	+250	V
		all pins with respect to V _{SS} (class B)	-250	+250	V
		all pins with respect to each other (class B)	-250	+250	V

Notes

- 1. Human Body Model (HBM); R_s = 1500 Ω ; C = 100 pF.
- 2. Machine Model (MM); R_s = 10 Ω ; C = 200 pF; L = 0.75 μH .

10 THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	CONDITIONS	VALUE	UNIT
R _{th(j-a)}	thermal resistance from junction to ambient	in free air	40	K/W
R _{th(j-c)}	thermal resistance from junction to case	in free air	1.0	K/W

11 QUALITY SPECIFICATION

In accordance with "SNW-FQ611-part D" if this type is used as an audio amplifier (except for ESD, see also Chapter 9).

Power stage $2 \times 80 \text{ W}$ class-D audio amplifier

TDA8927

12 DC CHARACTERISTICS

 $V_P = \pm 25 \text{ V}$; $T_{amb} = 25 \,^{\circ}\text{C}$; measured in test diagram of Fig.6; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply				•	-	•
V _P	supply voltage	note 1	±15	±25	±30	V
I _{q(tot)}	total quiescent current	no load connected	_	35	45	mA
		outputs floating	_	5	10	mA
Internal stabili	izer logic supply (pin STAB)					
V _{O(STAB)}	stabilizer output voltage		11	13	15	V
	(pins SW1 and SW2)			•	•	'
V _{IH}	HIGH-level input voltage	referenced to V _{SS}	10	_	V _{STAB}	V
V _{IL}	LOW-level input voltage	referenced to V _{SS}	0	_	2	V
Control outpu	ts (pins REL1 and REL2)		•	•	•	•
V _{OH}	HIGH-level output voltage	referenced to V _{SS}	10	_	V _{STAB}	V
V _{OL}	LOW-level output voltage	referenced to V _{SS}	0	_	2	V
Diagnostic ou	tput (pin DIAG, open-drain)		•	•	•	•
V _{OL}	LOW-level output voltage	I _{DIAG} = 1 mA; note 2	0	_	1.0	V
I _{LO}	output leakage current	no error condition	_	_	50	μΑ
Enable inputs	(pins EN1 and EN2)		•	•	•	
V _{IH}	HIGH-level input voltage	referenced to V _{SS}	_	9	V _{STAB}	V
V _{IL}	LOW-level input voltage	referenced to V _{SS}	0	5	_	V
V _{EN(hys)}	hysteresis voltage		_	4	_	V
I _{I(EN)}	input current		_	_	300	μΑ
Switching-on	input (pin POWERUP)					
V _{POWERUP}	operating voltage	referenced to V _{SS}	5	_	12	V
I _{I(POWERUP)}	input current	V _{POWERUP} = 12 V	_	100	170	μΑ
Temperature p	protection					
T _{diag}	temperature activating diagnostic	$V_{DIAG} = V_{DIAG(LOW)}$	150	_	_	°C
T _{hys}	hysteresis on temperature diagnostic	$V_{DIAG} = V_{DIAG(LOW)}$	_	20	-	°C

Notes

- 1. The circuit is DC adjusted at $V_P = \pm 15$ to ± 30 V.
- 2. Temperature sensor or maximum current sensor activated.

Power stage 2×80 W class-D audio amplifier

TDA8927

13 AC CHARACTERISTICS

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Single-ended	application; note 1	-	'	!		-
Po	output power	$R_L = 4 \Omega; V_P = \pm 25 V$				
		THD = 0.5%	50 ⁽²⁾	55	_	W
		THD = 10%	60 ⁽²⁾	65	_	w
		$R_L = 4 \Omega; V_P = \pm 27 V$				
		THD = 0.5%	60(2)	65	_	w
		THD = 10%	74 ⁽²⁾	80	_	w
THD	total harmonic distortion	P _o = 1 W; note 3				
		f _i = 1 kHz	_	0.01	0.05	%
		f _i = 10 kHz	_	0.1	_	%
G _{v(cl)}	closed-loop voltage gain		29	30	31	dB
η	efficiency	$P_0 = 30 \text{ W}; f_i = 1 \text{ kHz}; \text{ note 4}$	_	94	_	%
Mono BTL ap	plication; note 5	•		•	•	
Po	output power	$R_L = 8 \Omega; V_P = \pm 25 V$				
		THD = 0.5%	100 ⁽²⁾	112	_	W
		THD = 10%	128(2)	140	_	W
		$R_L = 4 \Omega; V_P = \pm 17 V$				
		THD = 0.5%	80(2)	87	_	w
		THD = 10%	100(2)	110	_	w
THD	total harmonic distortion	P _o = 1 W; note 3				
		f _i = 1 kHz	_	0.01	0.05	%
		f _i = 10 kHz	_	0.1	_	%
G _{v(cl)}	closed loop voltage gain		35	36	37	dB
η	efficiency	$P_0 = 30 \text{ W}; f_i = 1 \text{ kHz}; \text{ note 4}$	_	94	_	%

Notes

- 1. $V_P = \pm 25 \text{ V}$; $R_L = 4 \Omega$; $f_i = 1 \text{ kHz}$; $f_{osc} = 310 \text{ kHz}$; $R_s = 0.1 \Omega$ (series resistance of filter coil); $T_{amb} = 25 \text{ °C}$; measured in reference design (SE application) shown in Fig.7; unless otherwise specified.
- 2. Indirectly measured; based on R_{ds(on)} measurement.
- 3. Total Harmonic Distortion (THD) is measured in a bandwidth of 22 Hz to 22 kHz. When distortion is measured using a low-order low-pass filter a significantly higher value will be found, due to the switching frequency outside the audio hand.
- 4. Efficiency for power stage; output power measured across the loudspeaker load.
- 5. $V_P = \pm 25 \text{ V}$; $R_L = 8 \Omega$; $f_i = 1 \text{ kHz}$; $f_{osc} = 310 \text{ kHz}$; $R_s = 0.1 \Omega$ (series resistance of filter coil); $T_{amb} = 25 \,^{\circ}\text{C}$; measured in reference design (BTL application) shown in Fig.7; unless otherwise specified.

Power stage $2 \times 80 \text{ W}$ class-D audio amplifier

TDA8927

14 SWITCHING CHARACTERISTICS

 $V_P = \pm 25 \text{ V}$; $T_{amb} = 25 \,^{\circ}\text{C}$; measured in Fig.6; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT		
PWM outputs (PWM outputs (pins OUT1 and OUT2); see Fig.5							
t _r	rise time		_	30	_	ns		
t _f	fall time		_	30	_	ns		
t _{blank}	blanking time		_	70	_	ns		
t _{PD}	propagation delay	from pin SW1 (SW2) to pin OUT1 (OUT2)	_	20	_	ns		
t _{W(min)}	minimum pulse width	note 1	_	220	270	ns		
R _{ds(on)}	on-resistance of the output transistors		_	0.2	0.3	Ω		

Note

1. When used in combination with TDA8929T controller, the effective minimum pulse width during clipping is 0.5t_{W(min)}.

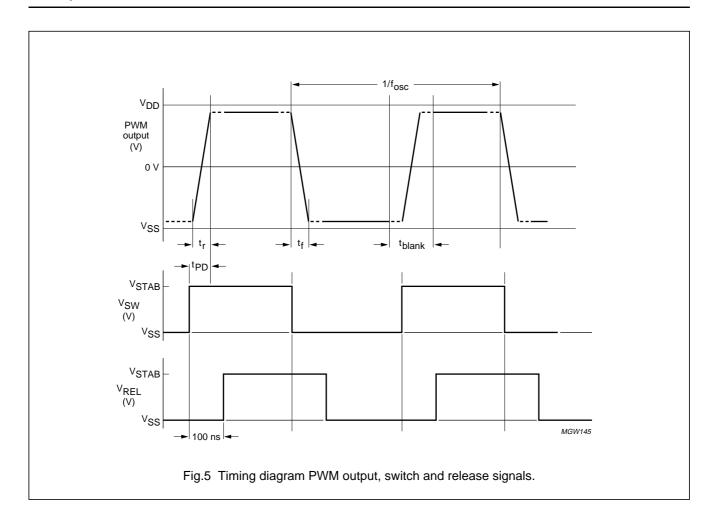
14.1 Duty factor

For the practical useable minimum and maximum duty factor (δ) which determines the maximum output power:

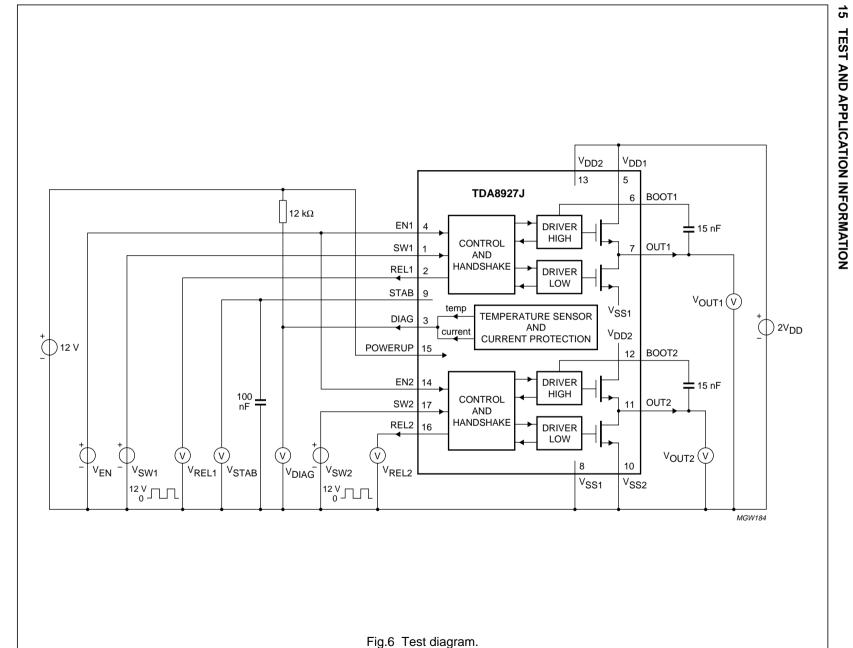
$$\frac{t_{W(min)} \times f_{osc}}{2} \times 100\% < \delta < \left(1 - \frac{t_{W(min)} \times f_{osc}}{2}\right) \times 100\%$$

Using the typical values: $3.5\% < \delta < 96.5\%$.

TDA8927



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Power stage 2×80 W class-D audio amplifier

TDA8927

15.1 BTL application

When using the system in a mono BTL application (for more output power), the inputs of both channels of the PWM modulator must be connected in parallel; the phase of one of the inputs must be inverted. In principle the loudspeaker can be connected between the outputs of the two single-ended demodulation filters.

15.2 Package ground connection

The heatsink of the TDA8927J/ST is connected internally to V_{SS}.

15.3 Output power

The output power in single-ended applications can be estimated using the formula

$$P_{o(1\%)} = \frac{\left[\frac{R_L}{(R_L + R_{ds(on)} + R_s)} \times V_P \times (1 - t_{W(min)} \times f_{osc})\right]^2}{2 \times R_L}$$

The maximum current $I_{O(max)} = \frac{[V_P \times (1 - t_{W(min)} \times f_{osc})]}{R_L + R_{ds(on)} + R_s}$ should not exceed 7.5 A.

The output power in BTL applications can be estimated using the formula

$$\textbf{P}_{o(1\%)} = \frac{\left[\frac{\textbf{R}_{L}}{\textbf{R}_{L} + 2 \times (\textbf{R}_{ds(on)} + \textbf{R}_{s})} \times 2\textbf{V}_{P} \times (1 - t_{W(min)} \times \textbf{f}_{osc})\right]^{2}}{2 \times \textbf{R}_{L}}$$

 $\label{eq:energy_equation} \text{The maximum current } I_{O(\text{max})} \, = \, \frac{[2V_P \times (1 - t_{W(\text{min})} \times f_{\text{osc}})]}{R_L + 2 \times (R_{ds(\text{on})} + R_s)} \, \, \text{should not exceed 7.5 A.}$

Where:

R_L = load impedance

R_s = series resistance of filter coil

 $P_{o(1\%)}$ = output power just at clipping

The output power at THD = 10%: $P_{o(10\%)} = 1.25 \times P_{o(1\%)}$.

15.4 Reference design

The reference design for a two-chip class-D audio amplifier for TDA8927J and TDA8929T is shown in Fig.7. The Printed-Circuit Board (PCB) layout is shown in Fig.8. The bill of materials is given in Table 1.

 V_{DDA}

mode select

Preliminary specification

Philips Semiconductors

2 80 ≶ class-D audio

C2 220 nF 1 C11 R19 39 kΩ R20 C10. 560 pF 560 pF V_{DD1} V_{DD2} QGND 39 kΩ C18 1 nF T on 10 12 MODE 5.6 Ω L2 5.6 Ω ☐ C44 ☐ 220 nF SW2 SW2 OUT2-- S1 off REL2 REL2 OUT2 L C8 Sumida 33 uH 4 or 8 Ω SE CDRH127-330 EN2 EN2 GND OSC ------27 kΩ U2 U1 12 R15 24 Ω VDDD OUT2+ BOOT2 C14 470 nF V_{SSA} • C3 R24 V_{DD1} 200 kΩ ► V_{DDD} TDA8929T STAB TDA8926J POWERUP 220 nF V_{DD2} OUT2-SGND1 D2 ± 220 nF TDA8927J (7.5 V) C5 STAB C7 220 nF __ C6 220 nF [/]SSD GND ← ► GND → V_{SSA} V_{SSD} ◆ SGND2 ± C43 220 nF QGND OUT1+ V_{SS2} R10 180 pF DIAG C17 220 nF V_{SS1} DIAGCUR 1 kΩ C20 1 CONTROLLER POWER STAGE VSSD C16 470 nF C22 330 pF ⊤ R16 24 Ω IN1-OUT1-BOOT1 EN1 21 REL1 REL1 _ C9 Sumida 33 μH CDRH127-330 IN2-10UT1+ 4 or 8 Ω 23 15 nF SE SW1 SW1 C23 ± 24 C21 InF QGND 330 pF PWM1 OUT1+ IN2-20 R14 5.6 Ω 5.6 Ω outputs C24 470 nF C26 C27 C13 ± С1ა 〒 560 pF ″ V_{DDD} VSSD R6 10 kΩ L7 QGND 10 kΩ 10 kΩ C30 Ϊ bead C28 C29 L5 bead → V_{DDA} 1 nF C40 1 nF 1 nF QQQ^V . C36 C37 ± 47 μF C34 1500 μF +25 V V_{DD} 220 nF R21 10 kΩ C32 220 nF 220 nF 0 1 input 1 input 2 GND 0 2 ► GND 0 3 R22 C33 1500 μF (35 V) 9.1 kΩ 220 nF . C38 C39 -25 V Vss 47 μF QGND QGND 220 nF 220 nF (35 V) → V_{SSD} , J2 bead L6 C31 1 nF inputs · V_{SSA} Vss power supply MLD633

 V_{SSD} V_{DDD}

R21 and R22 are necessary only in BTL applications with asymmetrical supply.

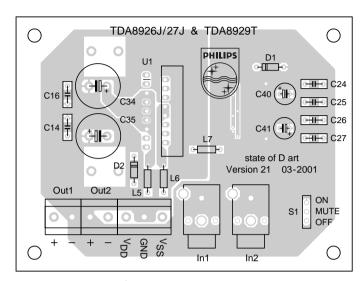
BTL: remove R6, R7, C23, C26 and C27 and close J5 and J6.

C22 and C23 influence the low-pass frequency response and should be tuned with the real load (loudspeaker).

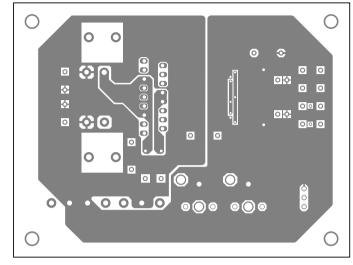
C1 220 nF

Inputs floating or inputs referenced to QGND (close J1 and J4) or referenced to V_{SS} (close J2 and J3) for an input signal ground reference.

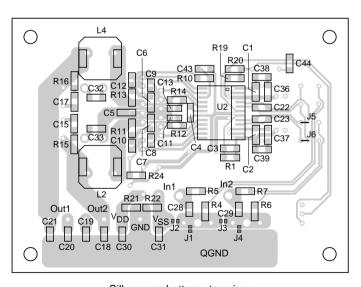
Fig.7 Two-chip class-D audio amplifier application diagram for TDA8927J and TDA8929T.



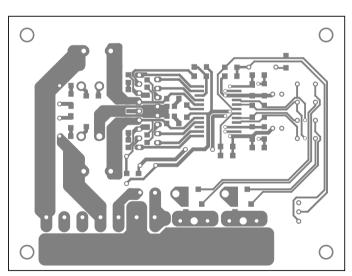
Silk screen top, top view



Copper top, top view



Silk screen bottom, top view



Copper bottom, top view

MLD634

Fig.8 Printed-circuit board layout for TDA8927J and TDA8929T.

Power stage $2 \times 80 \text{ W}$ class-D audio amplifier

TDA8927

15.5 Reference design bill of materials

Table 1 Two-chip class-D audio amplifier PCB (Version 2.1; 03-2001) for TDA8927J and TDA8929T (see Figs 7 and 8)

COMPONENT	DESCRIPTION	VALUE	COMMENTS
In1 and In2	Cinch input connectors		2 × Farnell: 152-396
Out1, Out2, V _{DD} ,	supply/output connectors		2 × Augat 5KEV-02;
GND and V _{SS}	and the state of the second state of		1 × Augat 5KEV-03
S1	on/mute/off switch	TD 4 0000 1/07 1	PCB switch Knitter ATE 1 E M-O-M
U1	power stage IC	TDA8926J/27J	DBS17P package
U2	controller IC	TDA8929T	SO24 package
L2 and L4	demodulation filter coils	33 μΗ	2 × Sumida CDRH127-330
L5, L6 and L7	power supply ferrite beads		3 × Murata BL01RN1-A62
C1 and C2	supply decoupling capacitors for V _{DD} to V _{SS} of the controller	220 nF/63 V	2 × SMD1206
C3	clock decoupling capacitor	220 nF/63 V	SMD1206
C4	12 V decoupling capacitor of the controller	220 nF/63 V	SMD1206
C5	12 V decoupling capacitor of the power stage	220 nF/63 V	SMD1206
C6 and C7	supply decoupling capacitors for V _{DD} to V _{SS} of the power stage	220 nF/63 V	SMD1206
C8 and C9	bootstrap capacitors	15 nF/50 V	2 × SMD0805
C10, C11, C12 and C13	snubber capacitors	560 pF/100 V	4 × SMD0805
C14 and C16	demodulation filter capacitors	470 nF/63 V	2 × MKT
C15 and C17	resonance suppress capacitors	220 nF/63 V	2 × SMD1206
C18, C19, C20 and C21	common mode HF coupling capacitors	1 nF/50 V	4 × SMD0805
C22 and C23	input filter capacitors	330 pF/50 V	2 × SMD1206
C24, C25, C26 and C27	input capacitors	470 nF/63 V	4 × MKT
C28, C29, C30 and C31	common mode HF coupling capacitors	1 nF/50 V	2 × SMD0805
C32 and C33	power supply decoupling capacitors	220 nF/63 V	2 × SMD1206
C34 and C35	power supply electrolytic capacitors	1500 μF/35 V	2 × Rubycon ZL very low ESR (large switching currents)
C36, C37, C38 and C39	analog supply decoupling capacitors	220 nF/63 V	4 × SMD1206
C40 and C41	analog supply electrolytic capacitors	47 μF/35 V	2 × Rubycon ZA low ESR
C43	diagnostic capacitor	180 pF/50 V	SMD1206
C44	mode capacitor	220 nF/63 V	SMD1206
D1	5.6 V Zener diode	BZX79C5V6	DO-35
D2	7.5 V Zener diode	BZX79C7V5	DO-35
R1	clock adjustment resistor	27 kΩ	SMD1206

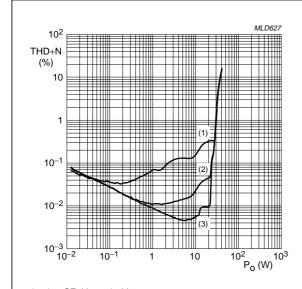
Power stage $2 \times 80 \text{ W}$ class-D audio amplifier

TDA8927

COMPONENT	DESCRIPTION	VALUE	COMMENTS
R4, R5, R6 and R7	input resistors	10 kΩ	4 × SMD1206
R10	diagnostic resistor	1 kΩ	SMD1206
R11, R12, R13 and R14	snubber resistors	5.6 Ω; >0.25 W	4 × SMD1206
R15 and R16	resonance suppression resistors	24 Ω	2 × SMD1206
R19	mode select resistor	39 kΩ	SMD1206
R20	mute select resistor	39 kΩ	SMD1206
R21	resistor needed when using an asymmetrical supply	10 kΩ	SMD1206
R22	resistor needed when using an asymmetrical supply	9.1 kΩ	SMD1206
R24	bias resistor for powering-up the power stage	200 kΩ	SMD1206

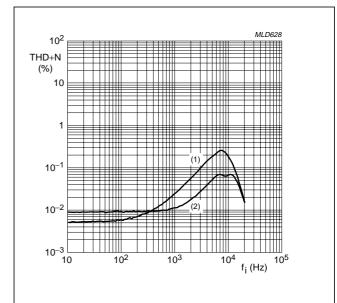
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15.6 Curves measured in reference design



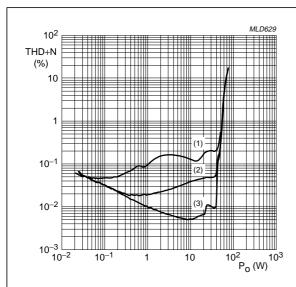
- $2 \times 8 \Omega$ SE; $V_P = \pm 25 V$.
- (1) 10 kHz.
- (2) 1 kHz.
- (3) 100 Hz.

Fig.9 Total harmonic distortion plus noise as a function of output power.



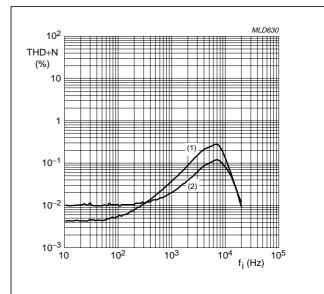
- $2 \times 8 \Omega$ SE; $V_P = \pm 25 V$.
- (1) $P_0 = 10 \text{ W}.$
- (2) $P_0 = 1 W$.

Fig.10 Total harmonic distortion plus noise as a function of input frequency.



- $2 \times 4 \Omega$ SE; $V_P = \pm 25 V$.
- (1) 10 kHz.
- (2) 1 kHz.
- (3) 100 Hz.

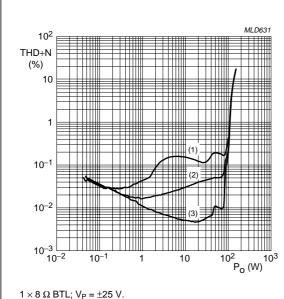
Fig.11 Total harmonic distortion plus noise as a function of output power.



- $2 \times 4 \Omega$ SE; $V_P = \pm 25 \text{ V}.$
- (1) $P_0 = 10 \text{ W}.$
- (2) $P_0 = 1 W$.

Fig.12 Total harmonic distortion plus as a function of input frequency.

TDA8927



- (1) 10 kHz.
- (2) 1 kHz.
- (3) 100 Hz.

Fig.13 Total harmonic distortion plus noise as a function of output power.

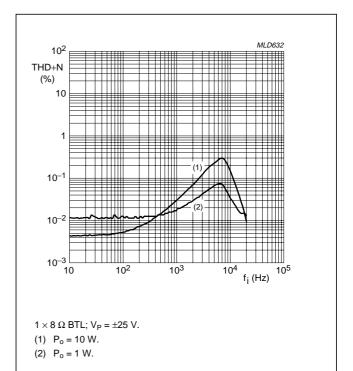
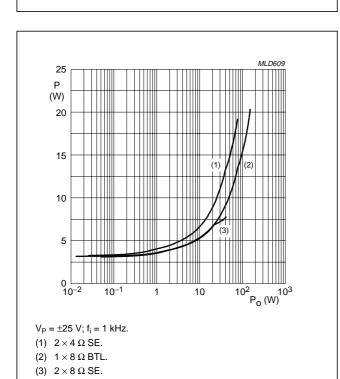
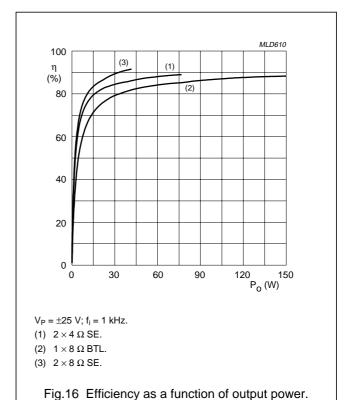


Fig.14 Total harmonic distortion plus noise as a

function of input frequency.



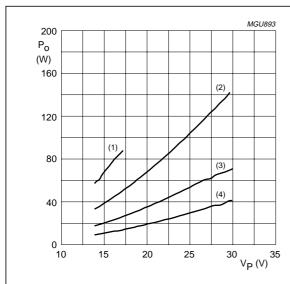


2002 Oct 22 21

Fig.15 Power dissipation as a function of output

power.

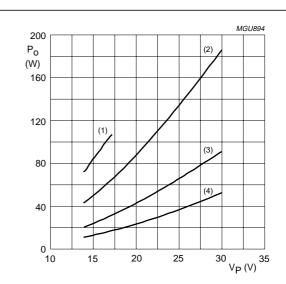
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THD + N = 0.5%; $f_i = 1 \text{ kHz}$.

- (1) $1 \times 4 \Omega$ BTL.
- (2) $1 \times 8 \Omega$ BTL.
- (3) $2 \times 4 \Omega$ SE.
- (4) $2 \times 8 \Omega$ SE.

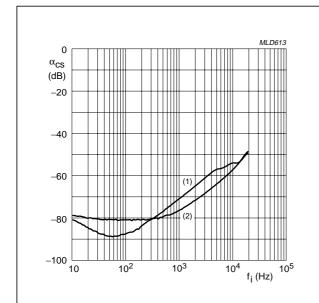
Fig.17 Output power as a function of supply voltage.



THD + N = 10%; $f_i = 1 \text{ kHz}$.

- (1) $1 \times 4 \Omega$ BTL.
- (2) $1 \times 8 \Omega$ BTL.
- (3) $2 \times 4 \Omega$ SE.
- (4) $2 \times 8 \Omega$ SE.

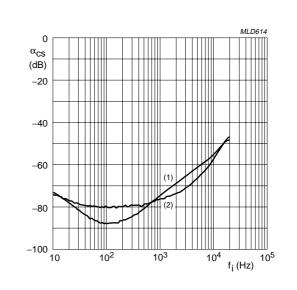
Fig.18 Output power as a function of supply voltage.



 $2 \times 8~\Omega$ SE; $V_P = \pm 25~V$.

- (1) $P_0 = 10 \text{ W}.$
- (2) $P_0 = 1 W$.

Fig.19 Channel separation as a function of input frequency.

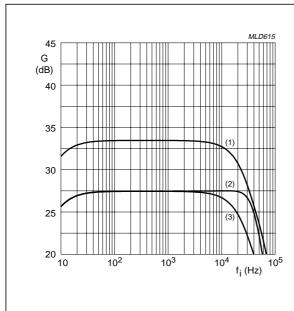


 $2 \times 4 \Omega$ SE; $V_P = \pm 25 V$.

- (1) $P_0 = 10 \text{ W}.$
- (2) $P_0 = 1 W$.

Fig.20 Channel separation as a function of input frequency.

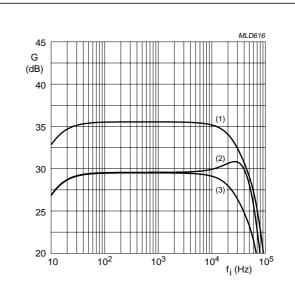
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 $V_P = \pm 25 \text{ V}$; $V_i = 100 \text{ mV}$; $R_s = 10 \text{ k}\Omega/C_i = 330 \text{ pF}$.

- (1) $1 \times 8 \Omega$ BTL.
- (2) $2 \times 8 \Omega$ SE.
- (3) $2 \times 4 \Omega$ SE.

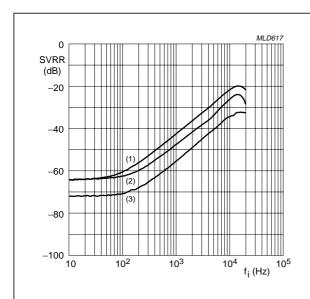
Fig.21 Gain as a function of input frequency.



 V_P = ±25 V; V_i = 100 mV; R_s = 0 Ω .

- (1) $1 \times 8 \Omega$ BTL.
- (2) $2 \times 8 \Omega$ SE.
- (3) $2 \times 4 \Omega$ SE.

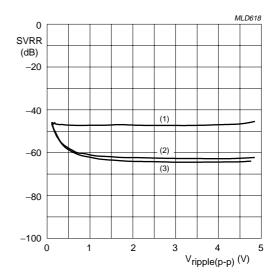
Fig.22 Gain as a function of input frequency.



 $V_P = \pm 25 \text{ V}; V_{ripple(p-p)} = 2 \text{ V}.$

- (1) Both supply lines in antiphase.
- (2) Both supply lines in phase.
- (3) One supply line rippled.

Fig.23 Supply voltage ripple rejection as a function of input frequency.



 $V_P = \pm 25 \text{ V}.$

- (1) $f_{ripple} = 1 \text{ kHz}.$
- (2) $f_{ripple} = 100 \text{ Hz}.$
- (3) $f_{ripple} = 10 \text{ Hz}.$

Fig.24 Supply voltage ripple rejection as a function of ripple voltage (peak-to-peak value).

TDA8927

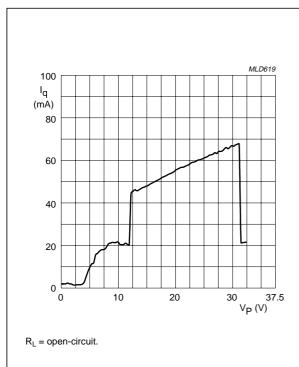


Fig.25 Quiescent current as a function of supply voltage.

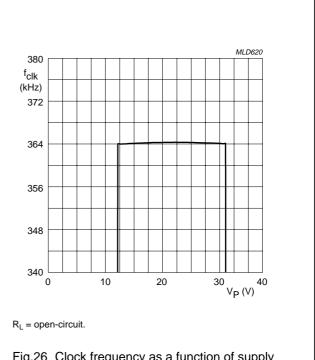
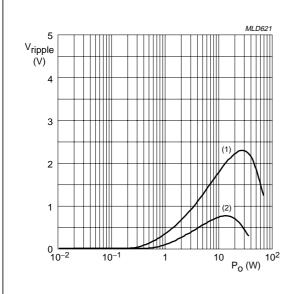


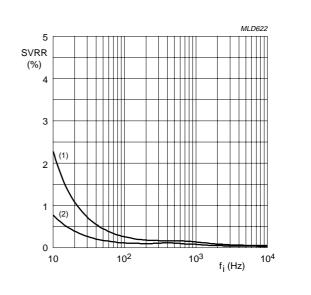
Fig.26 Clock frequency as a function of supply voltage.



 $V_P=\pm 25~V;\, 1500~\mu F$ per supply line; f_i = 10 Hz.

- (1) $1 \times 4 \Omega$ SE.
- (2) $1 \times 8 \Omega$ SE.

Fig.27 Supply voltage ripple as a function of output power.



 $V_P = \pm 25 \text{ V}$; 1500 μF per supply line.

- (1) $P_0 = 30 \text{ W into } 1 \times 4 \Omega \text{ SE}.$
- (2) $P_0 = 15 \text{ W into } 1 \times 8 \Omega \text{ SE.}$

Fig.28 Supply voltage ripple rejection as a function of input frequency.

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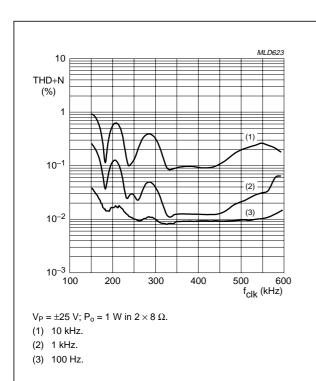
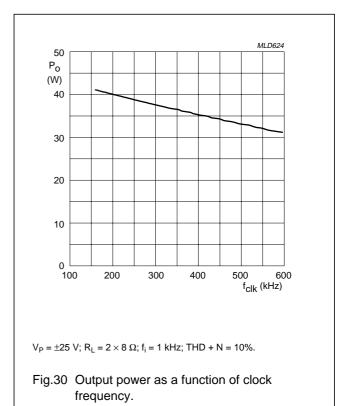
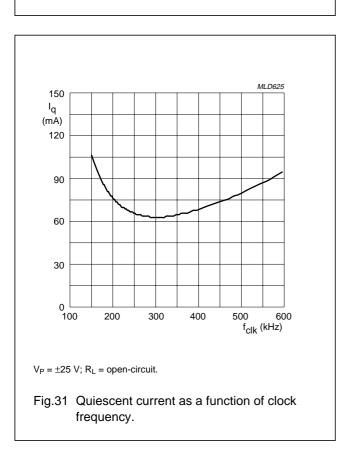
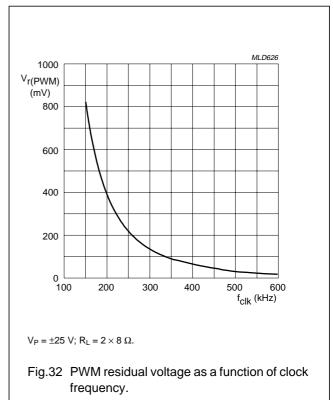


Fig.29 Total harmonic distortion plus noise as a function of clock frequency.





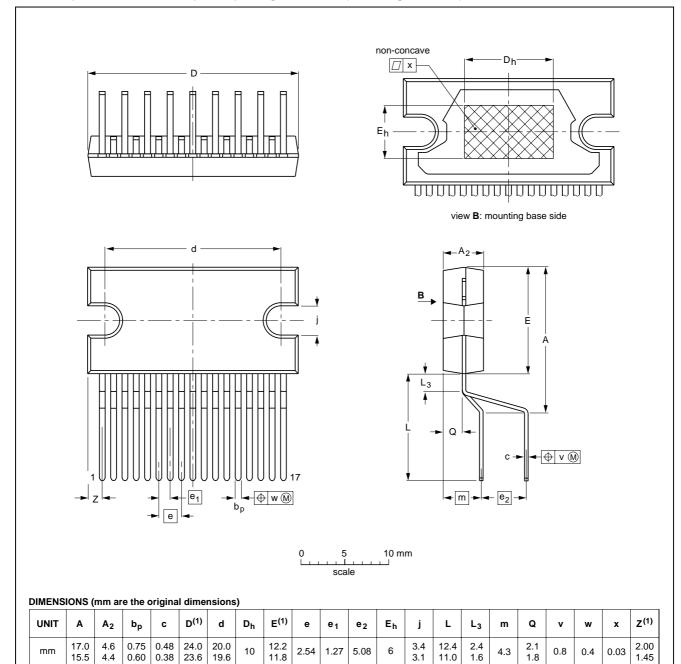


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16 PACKAGE OUTLINES

DBS17P: plastic DIL-bent-SIL power package; 17 leads (lead length 12 mm)

SOT243-1



Note

4.4

0.60

0.38

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

23.6

19.6

OUTLINE		REFERENCES			EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	EIAJ		PROJECTION	ISSUE DATE	
SOT243-1						97-12-16 99-12-17	

2.54

1.27

4.3

1.6

11.0

0.03

2002 Oct 22 26

Power stage 2×80 W class-D audio amplifier

TDA8927

17 SOLDERING

17.1 Introduction to soldering through-hole mount packages

This text gives a brief insight to wave, dip and manual soldering. A more in-depth account of soldering ICs can be found in our "Data Handbook IC26; Integrated Circuit Packages" (document order number 9398 652 90011).

Wave soldering is the preferred method for mounting of through-hole mount IC packages on a printed-circuit board.

17.2 Soldering by dipping or by solder wave

The maximum permissible temperature of the solder is $260~^{\circ}\text{C}$; solder at this temperature must not be in contact with the joints for more than 5 seconds.

The total contact time of successive solder waves must not exceed 5 seconds.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified maximum storage temperature ($T_{stg(max)}$). If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

17.3 Manual soldering

Apply the soldering iron (24 V or less) to the lead(s) of the package, either below the seating plane or not more than 2 mm above it. If the temperature of the soldering iron bit is less than 300 °C it may remain in contact for up to 10 seconds. If the bit temperature is between 300 and 400 °C, contact may be up to 5 seconds.

17.4 Suitability of through-hole mount IC packages for dipping and wave soldering methods

PACKAGE	SOLDERING METHOD	
PACKAGE	DIPPING	WAVE
DBS, DIP, HDIP, SDIP, SIL	suitable	suitable ⁽¹⁾

Note

1. For SDIP packages, the longitudinal axis must be parallel to the transport direction of the printed-circuit board.

Power stage 2×80 W class-D audio amplifier

TDA8927

18 DATA SHEET STATUS

LEVEL	DATA SHEET STATUS ⁽¹⁾	PRODUCT STATUS(2)(3)	DEFINITION
I	Objective data	Development	This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.
II	Preliminary data	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
III	Product data	Production	This data sheet contains data from the product specification. Philips Semiconductors reserves the right to make changes at any time in order to improve the design, manufacturing and supply. Relevant changes will be communicated via a Customer Product/Process Change Notification (CPCN).

Notes

- 1. Please consult the most recently issued data sheet before initiating or completing a design.
- 2. The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.
- 3. For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

19 DEFINITIONS

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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SCA74

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