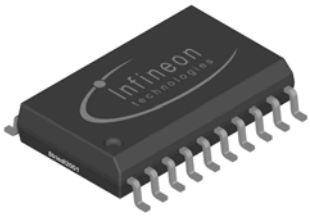
Dual Half Bridge Driver IC

Features

- Compatible to very low ohmic normal level input N-Channel MOSFETs
- Separate input for each MOSFET
- PWM frequency up to 50 kHz
- Operates down to 7.5V supply voltage
- Low EMC sensitivity and emission
- Adjustable dead time with shoot through protection
- Deactivation of dead time and shoot through protection possible
- Short circuit protection for each Mosfet
- Driver undervoltage shut down
- Reverse polarity protection for the driver IC
- Disable function
- Input with TTL characteristics
- 1 bit diagnosis
- Integrated bootstrap diodes

Product Summary

Turn on current	$I_{Gxx(on)}$	850	mA
Turn off current	$I_{Gxx(off)}$	580	mA
Supply voltage range	V_{Vs}	7.5 … 60	V
Gate Voltage	V_{GS}	10	V
Temperature range	T_J	-40...+150	°C



P-DSO 20

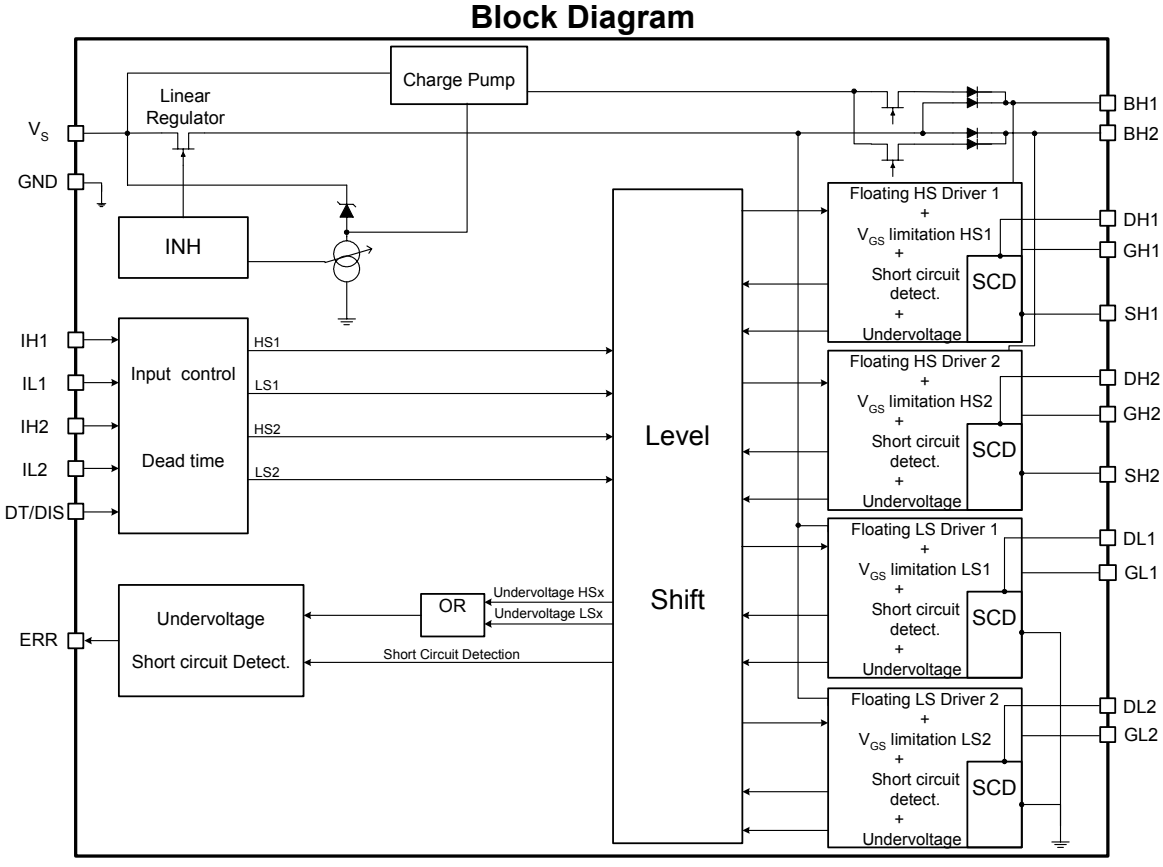
Application

- Dedicated for DC-brush high current motor bridges in PWM control mode and adapted for use in injector and valve applications for 12, 24 and 42V powernet applications. Useable as four fold lowside driver for unipolar 4 phase motor drives.
- The two half bridges can operate independently. The two half bridges can even operate at different supply voltages.

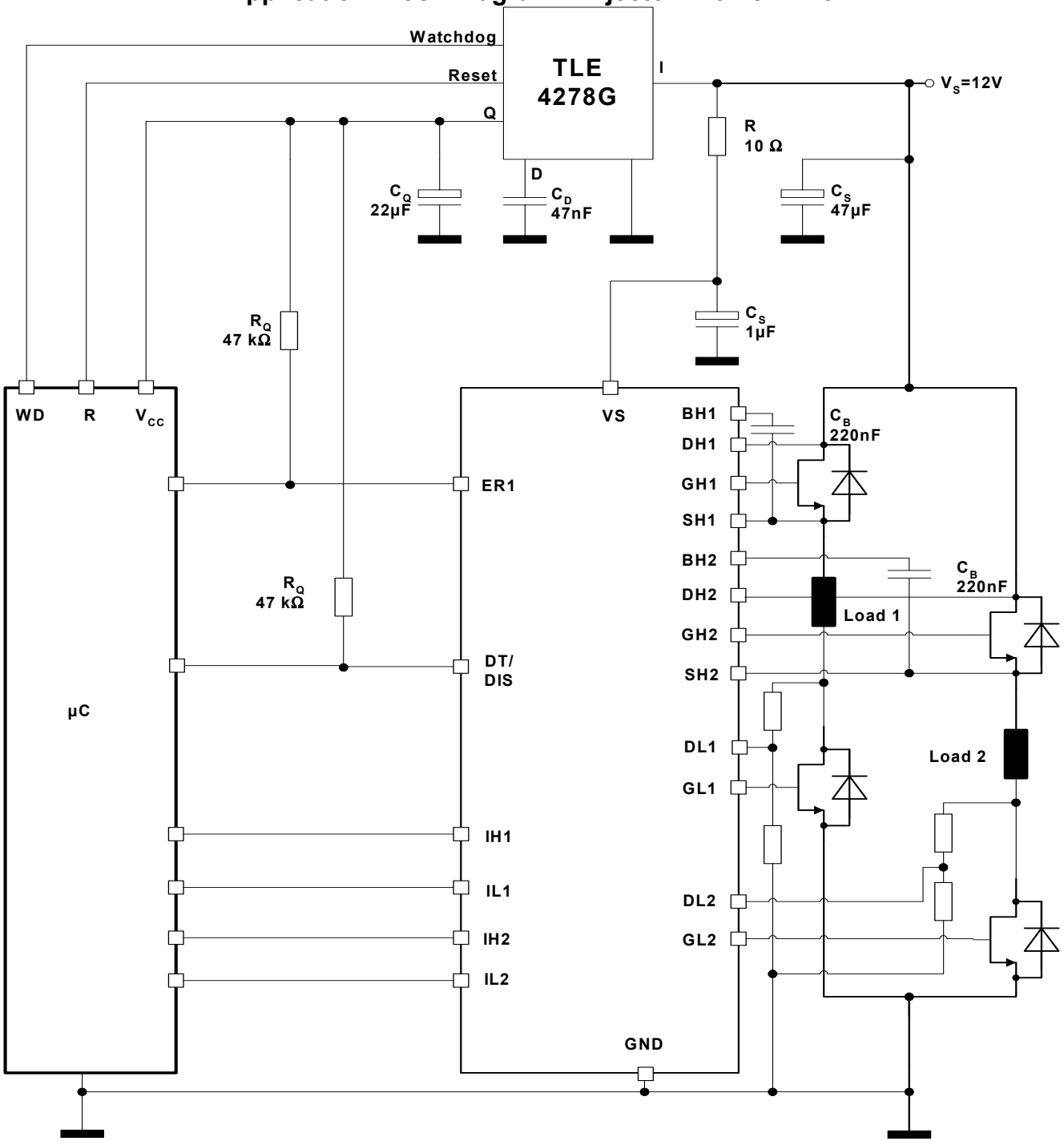
General Description

Dual half bridge driver IC for MOSFET power stages with multiple protection functions.

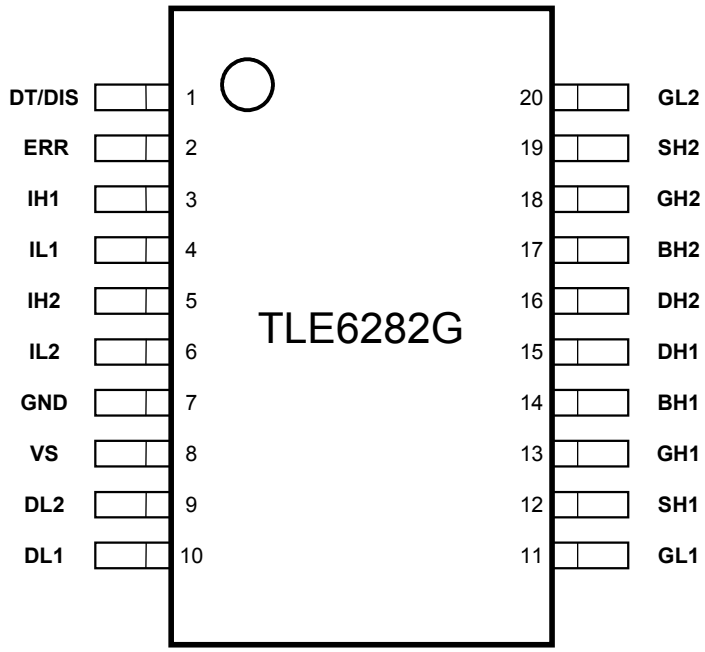
Block Diagram



Application Block Diagram – Injector / Valve Drive



This application diagram shows the principle schematics of a typical injector / valve drive. Other configurations are possible as well. Freewheeling diodes are not considered. The 10 mΩ resistor is not needed by the Driver IC, but may be needed for load current measurement. The voltage devider networks, e.g. R = 10 kΩ, across the two Low Side MOSFETs are an example as well; they allow to increas the current limit threshold for Short Circuit protection SCD for the Low Side MOSFETs. As they pull down the Sources of the High Side MOSFETs (while the Low Side MOSFETs are off), they allow to pre-charge the C_{Bx} capacitors during start-up (before the Driver IC gets enabled). The SCD current limit threshold can be increased for the High Side MOSFETs as well by using voltage devider networks across the High Side MOSFETs. SCD can also be disabled (High Side and / or Low Side MOSFETs).



Pin	Symbol		Function
1	DT/DIS		a) Set adjustable dead time by external resistor b) Deactivate deadtime and shoot through protection by connecting to 0V c) Reset ERR register d) Disable output stages
2	ERR		Error flag for driver shut down
3	IH1		Control input for high side switch 1
4	IL1		Control input for low side switch 1
5	IH2		Control input for high side switch 2
6	IL2		Control input for low side switch 1
7	GND		Ground
8	VS		Voltage supply
9	DL2		Sense contact for short circuit detection low side 2
10	DL1		Sense contact for short circuit detection low side 1
11	GL1		Output to gate low side switch 1
12	SH1		Connection to source high side switch 1
13	GH1		Output to gate high side switch 1
14	BH1		Bootstrap supply high side switch 1
15	DH1		Sense contacts for short circuit detection high side 1
16	DH2		Sense contacts for short circuit detection high side 2
17	BH2		Bootstrap supply high side switch 2
18	GH2		Output to gate high side switch 2
19	SH2		Connection to source high side switch 2
20	GL2		Output to gate low side switch 2

Maximum Ratings at T_j=-40…+150°C unless specified otherwise

Parameter	Symbol	Limits Values		Unit
Supply voltage [1]	V_S	-4	60	V
Operating temperature range	T_j	-40	150	°C
Storage temperature range	T_{stg}	-55	150	
Max. voltage range at Ixx; DT/DIS		-1	6	V
Max. voltage range at ERR		-0.3	6	V
Max. voltage range at BHx	V_{BHx}	-0.3	90	V
Max. voltage range at DHx[2]	V_{DHx}	-4	75	V
Max. voltage range at GHx[3]	V_{GHx}	-7	86	V
Max. voltage range at SHx[3]	V_{SHx}	-7	75	V
Max. voltage range at DLx	V_{DLx}	-7	75	V
Max. voltage range at GLx	V_{GLx}	-2	12	V
Max. voltage difference BHx - SHx	V_{BHx}-V_{SHx}	-0.3	17	V
Max. voltage difference GHx – SHx; GLx	V_{Gxx}-V_{Sxx}	-0.3	11	V
Power dissipation (DC) @ T_A=125°C / min.footprint	P_{tot}		0.33	W
Power dissipation (DC) @ T_A=85°C / min.footprint	P_{tot}		0.85	W
Electrostatic discharge voltage (Human Body Model) according to MIL STD 883D, method 3015.7 and EOS/ESD assn. standard S5.1 – 1993	V_{ESD}[4]		2	kV
Jedec Level			3	
Thermal resistance junction - ambient (minimal foot-print with thermal vias)	R_{thJA}		75	K/W
Thermal resistance junction - ambient (6 cm^2)	R_{thJA}		75	K/W

Functional range

Parameter and Conditions at T_j = –40…+150 °C, unless otherwise specified	Symbol	Values		Unit
Supply voltage	V_S	7.5	60	V
Operating temperature range	T_j	-40	150	°C
Max. voltage range at Ixx, DT/DIS		-0.3	5.5	V
Max. voltage range at ERR		-0.3	5.5	V
Max. voltage range at BHx	V_{BHx}	-0.3	90	V
Max. voltage range at DHx[2]	V_{DHx}	-4	75	V
Max. voltage range at GHx[3]	V_{GHx}	-7	86	V
Max. voltage range at SHx[3]	V_{SHx}	-7	75	V

[1] With external resistor (≥10 Ω) and capacitor
[2] The min value -4V is increased to –(V_{BHx} - V_{SHx}) in case of bootstrap voltages <4V
[3] The min value -7V is reduced to –(V_{BHx}-V_{SHx}-1V) in case of bootstrap voltages <8V
[4] All test involving Gxx pins V_{ESD}=1 kV!

Max. voltage range at DLx[3]	V_{DLx}	-7	75	V
Max. voltage range at GLx	V_{GLx}	-2	12	V
Max. voltage difference BHx - SHx	V_{BHx}-V_{SHx}	-0.3	12	V
Max. voltage difference GHx – SHx; GLx	V_{Gxx}-V_{Sxx}	-0.3	11	V
PWM frequency	F_{PWM}	0	50	kHz
Minimum on time external lowside switch – static condition @ 20 kHz; Q_{Gate} = 200nC	$t_{p(min)}$		2	µs

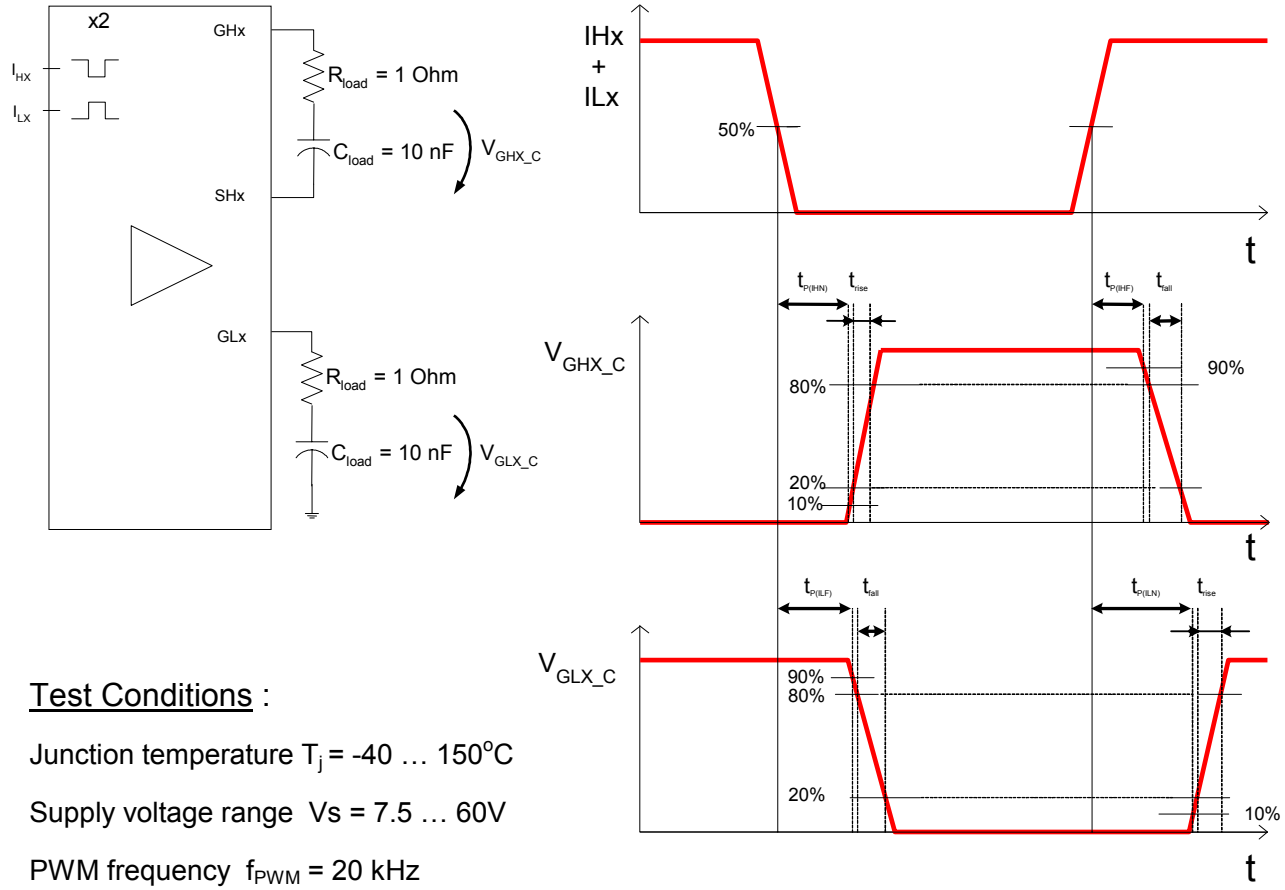
Electrical Characteristics

Parameter and Conditions at T_j = –40…+150 °C, unless otherwise specified and supply voltage range V_S = 7.5 ... 60V; f_{PWM} = 20kHz	**Symbol**	**Values** min	typ	max	**Unit**
Static Characteristics					
Low level output voltage (V_{GSxx}) @ I=10mA	ΔV_{LL}	--	60	150	mV
High level output voltage (V_{GSxx}) @ I=-10mA; Vs>12V	ΔV_{HL}	8	10	11	V
Supply current at VS (device disabled) @ V_{bat}= V_S =14V R_{DT}=400kΩ	$I_{VS(dis)14V}$	--	4	8	mA
Supply current at VS (device disabled) @ V_{bat}= V_S =42V R_{DT}=400kΩ	$I_{VS(dis)42V}$	--	4	8	mA
Supply current at V_S @ V_{bat}= V_S =14V 20kHz (Outputs open)	$I_{VS(open)14V}$	--	7	15	mA
Supply current at V_S @ V_{bat}= V_S =14V 50kHz (Outputs open)	$I_{VS(open)14V}$	--	7	15	mA
Supply current at V_S @ V_{bat}= V_S =42V 20kHz (Outputs open)	$I_{VS(open)42V}$	--	7	15	mA
Low level input voltage	$V_{IN(LL)}$	--	--	1.0	V
High level input voltage	$V_{IN(HL)}$	2.0	--	--	V
Input hysteresis	ΔV_{IN}	100	170		mV

Dynamic characteristics (pls. see test circuit and timing diagram)

Turn on current @ V_{Gxx} -V_{Sxx} = 0V; T_j=25°C @ V_{Gxx} -V_{Sxx} = 4V; T_j=125°C @ C_{Load}=22nF; R_{Load}=0Ω	$I_{Gxx(on)}$	-- --	850 700	-- --	mA
Turn off current @ V_{Gxx} -V_{Sxx} = 10V; T_j=25°C @ V_{Gxx} -V_{Sxx} = 4V; T_j=125°C @ C_{Load}=22nF; R_{Load}=0Ω	$I_{Gxx(off)}$	-- --	580 300	-- --	mA
Dead time (adjustable) @ R_{DT} = 1 kΩ @ R_{DT} = 10 kΩ @ R_{DT} = 50 kΩ @ R_{DT} = 200 kΩ @ C_{Load}=10nF ; R_{load}=1Ω	t_{DT}	-- 0.05 0.40 --	0 0.24 1.0 3.1	-- 0.38 2.50 --	µs
Rise time @ C_{Load}=10nF ; R_{load}=1Ω (20% to 80%)	t_{rise}	--	100	300	ns
Fall time @ C_{Load}=10nF ; R_{load}=1Ω (80% to 20%)	t_{fall}	--	150	440	ns
Disable propagation time @ C_{Load}=10nF ; R_{load}=1Ω	$t_{P(DIS)}$	3.4	5	7	µs
Reset time of diagnosis @ C_{Load}=10nF ; R_{load}=1Ω	$t_{P(CL)}$	1	2	3.1	µs
Input propagation time (low side turns on, 0% to 10%)	$t_{P(ILN)}$	--	160	500	ns
Input propagation time (low side turns off, 100% to 90%)	$t_{P(ILF)}$	--	100	500	ns
Input propagation time (high side turns on, 0% to 10%)	$t_{P(IHN)}$	--	120	500	ns
Input propagation time (high side turns off, 100% to 90%)	$t_{P(IHF)}$	--	120	500	ns
Input propagation time difference (all channels turn on)	$t_{P(Diff)}$	20	40	70	ns
Input propagation time difference (all channels turn off)	$t_{P(Diff)}$	--	20	50	ns
Input propagation time difference (one channel; low on – high off)	$t_{P(Diff)}$	--	40	150	ns
Input propagation time difference (one channel; high on – low off)	$t_{P(Diff)}$	--	20	150	ns
Input propagation time difference (all channels; low on – high off)	$t_{P(Diff)}$	--	40	150	ns
Input propagation time difference (all channels; high on – low off)	$t_{P(Diff)}$	--	20	150	ns

Test Circuit and Timing Diagram



Test Conditions :

Junction temperature T_j = -40 … 150°C

Supply voltage range Vs = 7.5 … 60V

PWM frequency f_{PWM} = 20 kHz

Diagnosis and Protection Functions

Short circuit protection filter time	$t_{SCP(off)}$	6	9	12	µs
Short circuit criteria (V_{DS} of Mosfets) For Low Sides For High Sides	$V_{DS(SCP)}$	 0.5 0.45	 0.75 0.75	 1.0 1.05	 V
Disable input level	V_{DIS}	3.3	3.7	4.0	V
Disable input hysteresis	ΔV_{DIS}		180		mV
Deactivation level for dead time and shoot through protection	V_{DIS}	0.6	0.85	1.1	V
Deactivation input hysteresis	ΔV_{DIS}		170		mV
Error level @ 1.6mA I_{ERR}	V_{ERR}	--	--	1.0	V
Under voltage lock out for highside output – boot-strap voltage	$V_{BHx\ (uvlo)}$		3.7	4.6	V
Under voltage lock out for lowside output – supply voltage	$V_{Vs\ (uvlo)}$		4.8	5.9	V

Remarks:

Default status of input pins:

To assure a defined status of all input pins in case of disconnection, these pins are internally secured by pull up / pull down current sources with approx. 20µA.
The following table shows the default status of each input pin.

Input pin	Default status
ILx (active high)	Low
IHx (active low)	High
DT/DIS (active high)	High

Definition:

In this datasheet a duty cycle of 98% means that the GLx pin is 2% of the PWM period in high condition.

Functional description

Description of Dead Time Pin / Disable Pin / Reset

In the range between 1.5 and 3.5 V the dead time is varied from 100ns to 3.1µs typ. In the range below 1.0V the dead time is disabled / shoot through is allowed. Both external Mosfets of the same half bridge can be switched on simultaneously. This function allows the use of a half bridge for valves and injectors. In the range above 4.0V the device is disabled.
If DIS is pulled up to 5V for 3.1 to 3.4µs only the ERR register is cleared (reset), no output stage is shut down. A shut down of all external Mosfets occurs if DIS is pulled up for longer than 7µs.

Condition of DT/DIS pin	Function
0 - 1V	Disable of dead time; Shoot through is allowed
1.5 - 3.5V	Adjust dead time between 100ns and 3.1µs typ.
> 4V	a) Reset of diagnosis register if DT/DIS voltage is higher than 4V for a time between 3.1µs and 3.4µs
	b) Shut down of output stages if DT/DIS voltage is higher than 4V for a time above 7µs (Active pull down of gate voltage)

Description of Diagnosis

The ERR pin is an open collector output and has to be pulled up with external pull up resistors to 5V. In normal conditions the ERR signal is high. In case of shutdown of any output stage the ERR is pulled down. This shut down can be caused by undervoltage or short circuit.

Recommended Start-up procedure

The following procedure is recommended whenever the Driver IC is powered up:

- Disable the Driver IC via DT/DIS pin
- After the supply voltage has ramped up, wait for several ms to pre-charge the bootstrap capacitors of the High Side MOSFETs C_{Bx} through the resistors R on the DLx

pins (voltage devider network, pls. see Application block diagram on pg. 2)
$t_{WAIT} \approx 3 \times C_{Bx} \times 2 \times R$, whereas R = 10 kΩ
- Enable the Driver IC via DT/DIS pin
- Start the operation by applying the desired pulse patterns. Do not apply any pulse patterns to the IHx or ILx pins, before the C_{Bx} capacitors are charged up.

Alternatively, the Driver IC can be enabled via the DT/DIS pin right after ramping up the supply voltage V_S. Now, the two Low Side MOSFETs are turned on via the ILx control inputs (to pull down the Sources of the High Side MOSFETs and to charge up the bootstrap capacitors C_{Bx} within several 10 µs). The regular operation can be started when the bootstrap capacitors are charged up.

Short Circuit protection

The current threshold limit to activate the Short Circuit protection function can be adjusted to larger values, it can not be adjusted to lower values. This can be done by external resistors to form voltage deviders across the “sense element” (pls. see Application block diagram on pg. 2), consisting of the Drain-Source-Terminals, a fraction of the PCB trace and – in some cases – current sense resistors (used by the µC not by the Driver IC).
The Short Circuit protection can be disabled for the High Side MOSFETs by shorting DH1 with SH1 and DH2 with SH2 on the PCB; in this case the DHx pins may not be connected to the Drains of the associated MOSFETs. To disable Short Circuit protection for the Low Side MOSFETs the DL1 and DL2 pin should be connected to the Driver IC´s Ground.

Shut down of the driver

A shut down can be caused by undervoltage or short circuit.
A short circuit will shut down only the affected Mosfet until a reset of the error register by a disable of the driver occurs. A shut down due to short circuit will occur only when the Short Circuit criteria $V_{DS(SCP)}$ is met for a duration equal to or longer than the Short Circuit filter time $t_{SCP(off)}$. Yet, the exposure to or above $V_{DS(SCP)}$ is not counted or accumulated. Hence, repetitive Short Circuit conditions shorter than $t_{scp(off)}$ will not result in a shut down of the affected MOSFET.
An undervoltage shut down shuts only the affected output down. The affected output will auto restart after the undervoltage situation is over.

Operation at Vs<12V

If Vs<11.5V the gate voltage will not reach 10V. It will reach approx. Vs-1.5V, dependent on duty cycle, total gate charge and switching frequency.

Operation at different voltages for Vs, DH1 and DH2

If DH1 and DH2 are used with a voltage higher than Vs, a duty cycle of 100% can not be guaranteed. In this case the driver is acting like a normal driver IC based on the bootstrap principle. This means that after a maximum “On” time of the highside switch of more than 1ms a refresh pulse to charge the bootstrap capacitor of about 1µs is needed to avoid undervoltage lock out of this output stage.

Operation at extreme duty cycle:

The integrated charge pump allows an operation at 100% duty cycle. The charge pump is strong enough to replace leakage currents during “on”-phase of the highside switch. The gate charge for fast switching of the highside switches is supplied by the bootstrap capacitors. This means, that the bootstrap capacitor needs a minimum charging time of about 1µs, if the highside switch is operated in PWM mode (e.g. with 20kHz a maximum duty cycle of 96% can be reached). The exact value for the upper limit is given by the RC time formed by

the impedance of the internal bootstrap diode and the capacitor formed by the external Mosfet ($C_{Mosfet}=Q_{Gate} / V_{GS}$). The size of the bootstrap capacitor has to be adapted to the external MOSFET the driver IC has to drive. Usually the bootstrap capacitor is about 10-20 times bigger then C_{Mosfet}. External components at the Vs Pin have to be considered, too.

General remark:

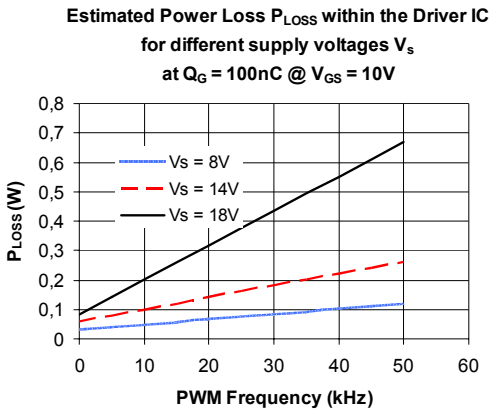
It is assured that after the removal of any fault condition, which did not damage the device, the device will return to normal conditions without external trigger. Only short circuit condition needs restart by reset.

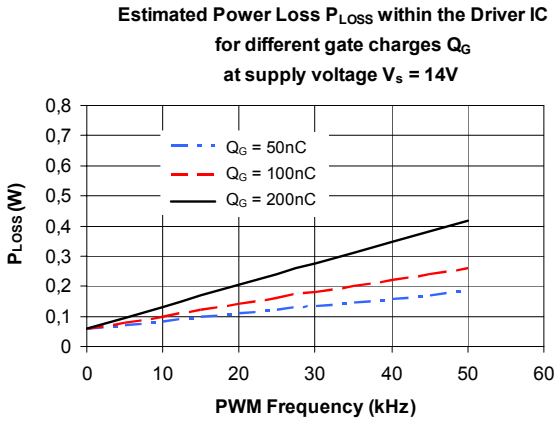
Estimation of power loss within the Driver IC

The power loss within the Driver IC is strongly dependent on the use of the driver and the external components. Nevertheless a rough estimation of the worst case power loss is possible.
Worst case calculation is:

$P_{Loss} = (Q_{gate}*n*const* f_{PWM} + I_{VS(open)}/20kHz)* V_{Vs} - P_{RGate}$
With:
P_{Loss} = Power loss within the Driver IC
f_{PWM} = Switching freqency
Q_{gate} = Total gate charge of used MOSFETs at 10V V_{GS}
n = Number of switched MOSFETs
const = Constant considering some leakage current in the driver (about 1.2)
$I_{VS(open)}$ = Current consumption of driver without connected Mosfets during switching
V_{VS} = Voltage at Vs
P_{RGate} = Power dissipation in the external gate resistors

This value can be reduced dramatically by usage of external gate resistors.

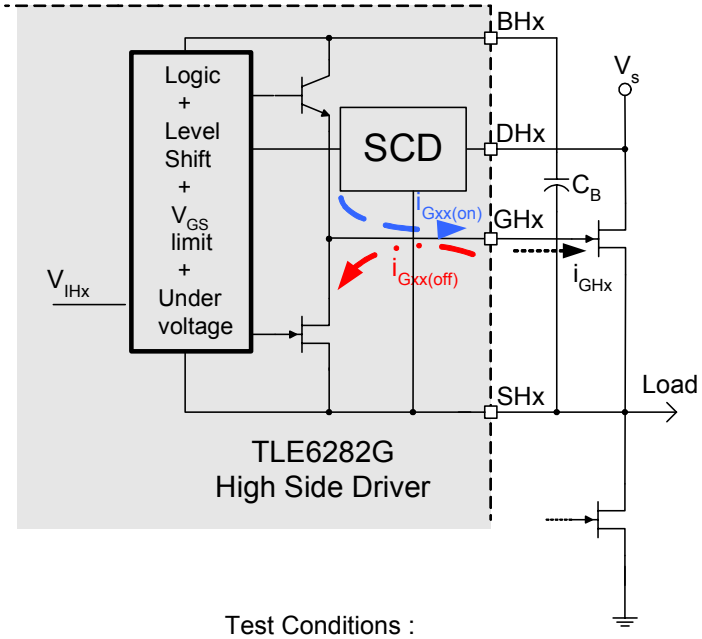




Conditions :

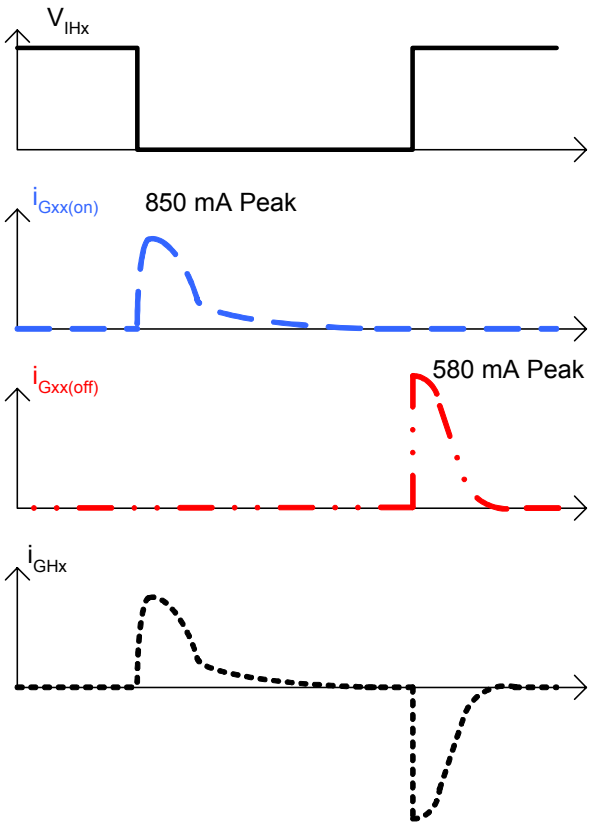
Junction temperature $T_j = 25^oC$
Number of switched MOSFET n = 2
Power dissipation in the external gate resistors $P_{RGate} = 0,2*P_{Loss}$

Gate Drive characteristics



Test Conditions :
- Turn On : V_{GS} = 0V, T_j = 25°C
- Turn Off : V_{GS} = 10V, T_j = 25°C

This figure represents the simplified internal circuit of one high side gate drive. The drive circuit of the low sides looks similar.



This figure illustrates typical voltage and current waveforms of the high side gate drive; the associated waveforms of the low side drives look similar.

Truth Table

Input			Conditions		Output		
ILx	IHx	DT / DIS	UV	SC	GLx	GHx	ERR
1	1	<3.5V	0	0	1	0	5V
0	0	<3.5V	0	0	0	1	5V
1	0	1.5-3.5V	0	0	A	A	5V
1	0	<1V	0	0	1	1	5V
0	1	<3.5V	0	0	0	0	5V
1	1	<3.5V	1	0	B	0	C
0	0	<3.5V	1	0	0	B	C
1	0	1.5-3.5V	1	0	D	D	C
1	0	<1V	1	0	B	B	C
0	1	<3.5V	1	0	0	0	C
1	1	<3.5V	0	1	E	0	F
0	0	<3.5V	0	1	0	E	F
1	0	1.5-3.5V	0	1	D	D	F
1	0	<1V	0	1	E	E	F
0	1	<3.5V	0	1	0	0	F
X	X	X	X	X	0	0	5V
X	X	>4V	X	X	0	0	5V

A) stays in the condition before the shoot throught command occurs (see also dead time diagrams)
B) 0 when affected; 1 when not affected; self recovery
C) 0V when output does not correspond to input patterns; 5V when output corresponds to input patterns.
D) stays in the condition before the shoot throught command occurs (see also dead time diagrams); 0 when affected
E) 0 when affected– the outputs of the affected halfbridge are shut down and stay latched until reset; 1 when not affected
F) 0V when output does not correspond to input patterns – the outputs of the affected half-bridge are shut down and stay latched until reset; 5V when output corresponds to input patterns.
X) Condition has no influence

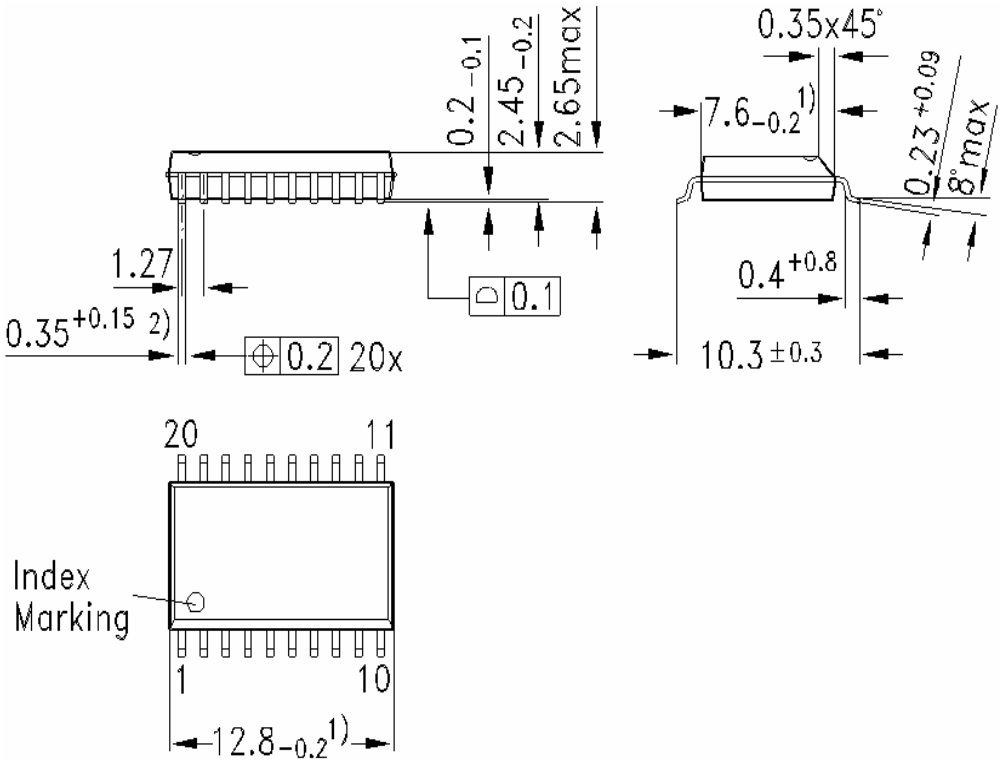
Remark: Please consider the influence of the dead time for your input duty cycle

Package and Ordering Code

(all dimensions in mm)

Package Code

P-DSO 20



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