# **SIEMENS AG**

# **IC-SPECIFICATION**

# **TDA 4321 XS**

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# FM-IF IC with counter output, analog STS, field strength indicator, noise detector and mute setting

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#### This specification replaces the previous editions

DOK-Nr.	date	DOK-Nr.	date
V66047-S1665-B100-V1	24.7.98		

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# **IC-SPECIFICATION**

#### **TDA 4321 XS**

### **Functional Description, Application**

The FM-IF-Demodulator TDA 4321 XS has been developed especially for car radio applications. The on-chip multipath identification circuit activates an interference suppression circuit in case of multipath interferences.

The TDA 4321 XS includes an:

- 7stage limiter amplifier
- Coincidence demodulator
- Counter output with request input
- Field strength output
- Analog Multipath identification circuit
- Adjustable muting depth (with full muting ≥80dB)
- STS function.

This device is ESD protected.

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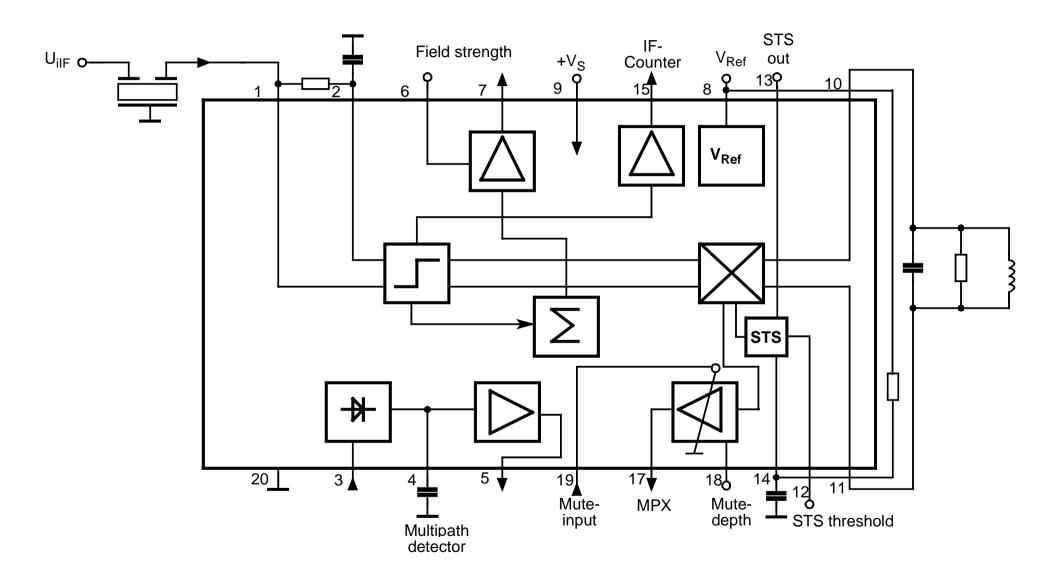
#### **Circuit Description**

The IC includes a 7 stage capacitive coupled-limiter amplifier with coincidence demodulator and AF output. The AF output signal can be continuously attenuated to decrease the noise.

In case of multipath interferences, the TDA 4321 XS includes an identification circuitry with analog output.

There is a field strength output (with min. 76 dB dynamic range, typ.  $\pm 1$  dB nonlinearity and typ.  $\pm 3$  dB temperature drift), an IF-Counter output and an adjustable muting (with full muting  $\geq 80$ dB). An STS output with adjustable threshold and stop window is available.

#### **Block Diagram**



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## **Pin Assignment**

		_	
1		in	nııt
	II	ш	put

- 2 IF input bias
- 3 Multipath identification input
- 4 Rectifier time constant
- 5 Multipath identification output
- 6 Field strength adjust
- 7 Field strength output
- 8 Reference voltage output
- 9 Supply voltage
- 10 Demodulator circuit
- 11 Demodulator circuit
- 12 STS threshold
- 13 STS output
- 14 STS filter time constant and stop window width
- 15 IF-Counter output
- 16 NC
- 17 MPX output
- 18 Mute depth
- 19 Mute input
- 20 Ground

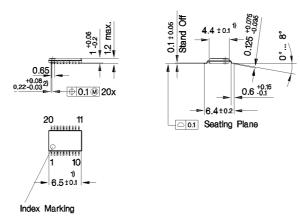
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#### **Package Outline**

Plastic-Package TSSO-P 20-1



- 1) Does not include plastic or metal protrusion of 0.15 max. per side
- 2) Does not include dambar protrusion of 0.08 max. per side

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# **Absolute Maximum Ratings**

The maximal ratings may not be exceeded under any circumstances, not even momentarily and individually, as permanent damage to the IC will result.

#	Max. Ratings for ambient temperature T <sub>amb</sub>	Symbol	Min	Max	Units	Remarks
-40 °C	to +85 °C					
1	Supply voltage	$V_S$	0	+13.5	V	
2	Junction temperature	$T_j$		+150	°C	
3	Storage temperature	$T_s$		+125	°C	
4	ESD voltage, HBM	$V_{ESD}$	-4	+4	kV	
	(1.5 kΩ ,100pF)					
5	Thermal Resistance	Rthsa		115	K/W	

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# **Operational Range**

Within the operational range the IC operates as described in the circuit description. The AC / DC characteristic limits are not guaranteed.

#	Parameter	Symbol	Min	Max	Units	Remarks
1	Supply voltage	$V_S$	+7.5	+11	V	
2	Ambient temperature	$T_{amb}$	-40	+85	°C	

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#### AC / DC Characteristics

AC / DC characteristics involve the spread of values guaranteed within the specified supply voltage and ambient temperature range. Typical characteristics are the median of the production.

#	Parameter	Symbol	Test	Test	Min	Тур	Max	Units
			Conditions	Circuit				

#### Measuring condition:

 $V_S$ = 10 V;  $f_{iIF}$ =10.7 MHz;  $\Delta f$ = 75 kHz;  $f_{mod}$ = 1 kHz;  $V_{iIF}$  =10 m $V_{rms}$ ;  $T_{amb}$ = +25°C

1	Current consumption	I <sub>9</sub>	V <sub>19</sub> =4.8V;V <sub>18</sub> =4V	1		33	41	mA
2	Stabilized voltage	$V_8$	V <sub>19</sub> =4.8V;V <sub>18</sub> =4V	1	4.5	4.8	5.1	V
3	Field strength output -dynamic range -nonlinearity -temperature drift -Load capacitance -Load resistance	V <sub>7</sub>	V <sub>19</sub> =4.8V;V <sub>18</sub> =4V	D1 D2 D3	74	80 ±1	±3 50	dB dB dB pF kΩ
		$V_7$	V <sub>1rms</sub> =200mV	1	5	5.4	5.8	V
		$V_7$	V <sub>1rms</sub> =1mV	1	2.3	2.7	3.1	V
		V <sub>7</sub>	V <sub>1rms</sub> =0mV	1	0		1.1	V
4	Input voltage for limiter threshold	V <sub>1</sub>	V <sub>17</sub> =- 3dB	1		20	30	$\mu V_{\text{rms}}$
5	AF-output voltage	V <sub>17</sub>	V <sub>19</sub> =4.8V;V <sub>18</sub> =4V	1	460	550	640	$mV_{rms}$
6	AF-output voltage	V <sub>17</sub>	$V_{19}$ =4.8V; $V_{18}$ =4V $R_{10-11}$ =2k; $\Delta f$ = 22,5 kHz	Lab		80		$mV_{rms}$
7	Total harmonic distoriton	THD <sub>17</sub>	V <sub>19</sub> =4.8V;V <sub>18</sub> =4V	1			0.8	%
8	AM-suppression	a <sub>AM</sub>	m=80 %	1	60			dB
			m=30 %	1	70			dB
9	Signal-to-noise ratio	a <sub>S/N</sub>	V <sub>19</sub> =4.8V;V <sub>18</sub> =4V	1	76	84		dB
10	Counter-output voltage	V <sub>15</sub>	C <sub>L</sub> =5pF;R <sub>i15</sub> =1.5k	1	50	80		$\mathrm{mV}_{\mathrm{rms}}$

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#### AC / DC Characteristics

AC / DC characteristics involve the spread of values guaranteed within the specified supply voltage and ambient temperature range. Typical characteristics are the median of the production.

#	Parameter	Symbol	Test	Test	Min	Тур	Max	Units
			Conditions	Circuit				

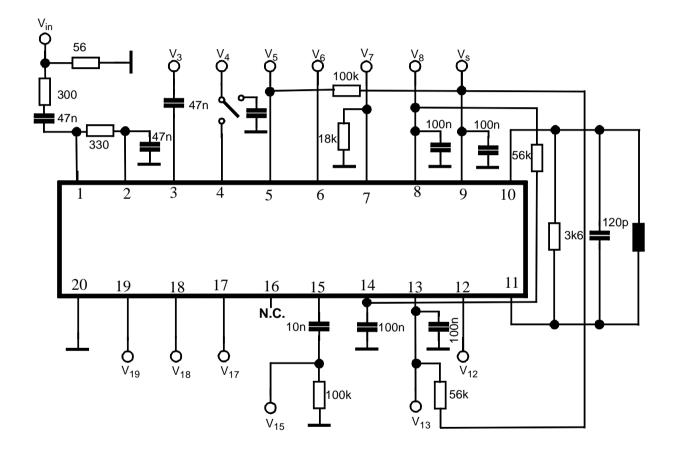
Measuring condition:

 $V_S$ = 10 V;  $f_{iIF}$ =10.7 MHz;  $\Delta f$ = 75 kHz;  $f_{mod}$ = 1 kHz;  $V_{iIF}$  =10 m $V_{rms}$ ;  $T_{amb}$ = +25°C

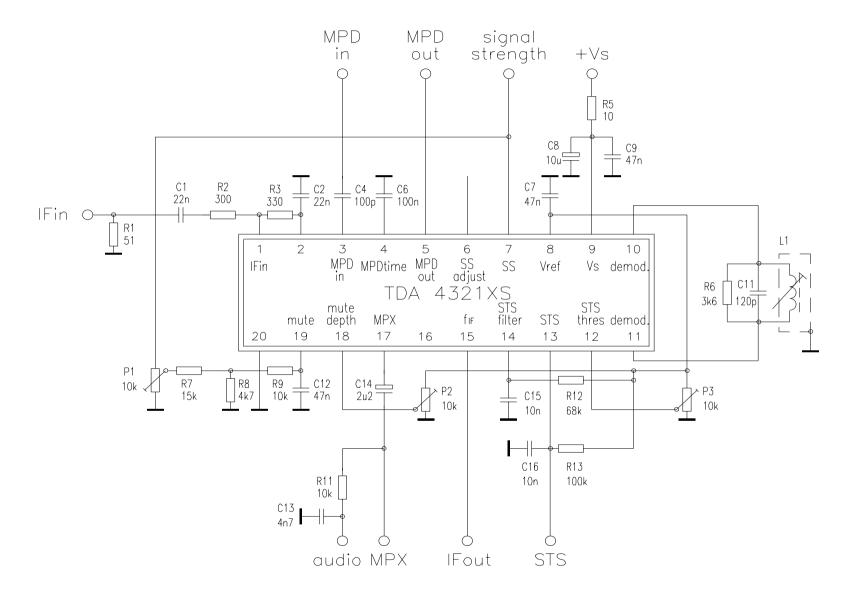
14	Attack current	l <sub>4</sub> *)	V <sub>3AC</sub> =1V <sub>p</sub>	<sub>op</sub> ; V <sub>m</sub> =5.0V	1	700	900	1100	μΑ
15	Recovery current	l <sub>4</sub> *)	V <sub>3AC</sub> =0V;	V <sub>m</sub> =3.6V	1	-6	-9	-12	μΑ
16	Start voltage	V <sub>5Def</sub>	V <sub>3AC</sub> =0V		1	4.4	4.7		V
17	Detector characteristic	$V_5$	V <sub>3</sub> =100m	$V_{pp}$	1	V <sub>5Def-3.5V</sub>	V <sub>5Def-3V</sub>	V <sub>5Def-2.5V</sub>	V
18	Detector characteristic	$V_5$	V <sub>3</sub> =350m	$V_{pp}$	1			500	mV
19	AF mute	$a_{AF}$	V <sub>19</sub> =4.8V	;V <sub>18</sub> =4.8V	D4		0		dB
			V <sub>19</sub> =0V	;V <sub>18</sub> =4.8V	D4	-2		2	dB
			V <sub>19</sub> =0V	;V <sub>18</sub> =2.4V	D4	32	38	44	dB
			V <sub>19</sub> =4.8V	;V <sub>18</sub> ≤1.0V	D4	80			dB
			V <sub>19</sub> =0V	;V <sub>18</sub> ≤ 1.0V	D4	80			dB
20	Voltage for mute off	$V_{19}$			1	0.5			V
21	Voltage for mute on	$V_{19}$			1	0		0.1	V
22	Search tuning stop window	f <sub>STS13</sub>	$R_{8-14} = 50$	6kΩ	1			±25	kHz
23	Search tuning stop offset	f <sub>SToffs</sub>	$R_{8-14} = 56$	6kΩ; THD = min	1			±10	kHz
24	Search tuning stop threshold FM	V <sub>iST1</sub> V <sub>iST1</sub>	V <sub>12</sub> =oper V <sub>12</sub> =2.4V		1 1	50 0.65	100 1.3	200 2.6	$\begin{array}{c} \mu V_{rms} \\ m V_{rms} \end{array}$

<sup>\*)</sup> Integrator currents are measured between the output pin (- Pole  $\,$  of the measurement equipment) and a voltage source  $V_m$  (+ Pole)

#### **Test Circuit**

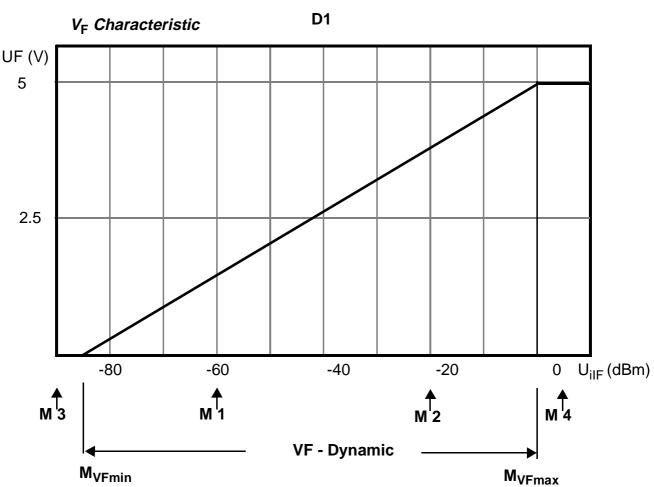


#### **Application Circuit**



#### **TDA 4321 XS**

# **Diagrams**



**V<sub>F</sub> - Dynamic**: The dynamic range of VF voltage is determined by the test points M1 through M4 as follows:

M1: test point (at  $V_{iIF}$ = -60 dBm) supplies  $V_F$  (M1) M2: test point (at  $V_{iIF}$ = -20 dBm) supplies  $V_F$  (M2) M3: test point (at  $V_{iIF}$ = -90 dBm) supplies  $V_F$  (M3) M4: test point (at  $V_{iIF}$ = +5 dBm) supplies  $V_F$  (M4)

#### Hence follows:

$$M_{VFmax}$$
:= - 20 dBm+  $U_F (M4) - U_F (M2)$   
 $U_F (M2) - U_F (M1)$ 

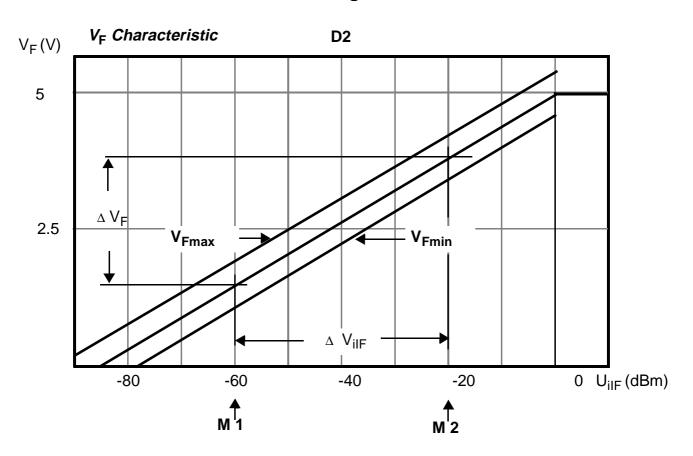
$$M_{VFmin} := -60 \text{ dBm } - \frac{U_F (M1) - U_F (M3)}{U_F (M2) - U_F (M1)} \times 40 \text{ dB}$$

VF - Dynamic =  $M_{VFmax}$  -  $M_{VFmin}$ 

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#### **Diagrams**



#### Test points to determine VF linearity

VF - Linearity:is determined at 25 °C

Slope : 
$$m = \frac{V_F (M2) - V_F (M1)}{40 \text{ dB}}$$

The tolerance range of the VF - linearity is determined by two parallel lines:

$$V_{Fmax} = V_{F} (M1) + m (M + 60 dB + 1dB)$$

$$V_{Fmin} = V_F (M1) + m (M + 60 dB - 1dB)$$

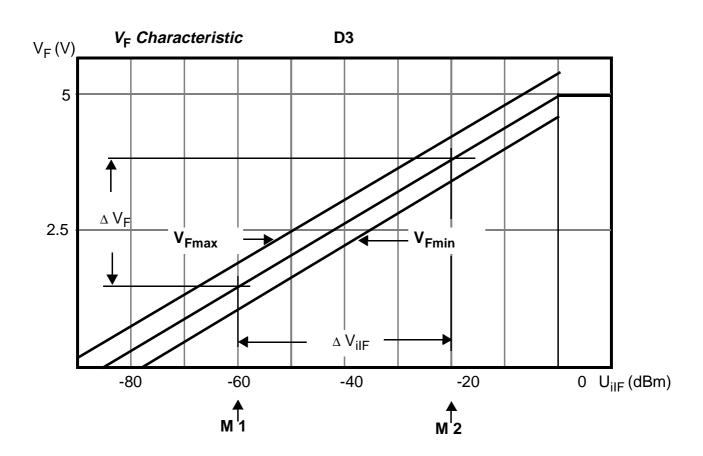
The  $V_F$  values within the  $V_F$  dynamic range  $(M_{VFmin}\!\!\leq\!\!M\!\!\leq\!\!M_{VFmax})$  must be inside the predetermined tolerance range:

$$V_{Fmin} \le V_F (M) \le V_{Fmax}$$

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#### **Diagrams**



#### Test points to determine V<sub>F</sub> temperature drift

V<sub>F</sub> -Temperatur - Drift : It is determined within -40 bis +85 °C

Slope : 
$$m = \frac{U_{F (M2)} - U_{F (M1)}}{40 \text{ dB}}$$
 (at 25 °C)

The tolerance range of the  $V_{\mbox{\scriptsize F}}$  temperature drift is determined by two parallel lines:

$$V_{Fmax} = V_{F} (M1) + m (M + 60 dB + 3dB)$$

$$V_{Fmin} = V_F (M1) + m (M + 60 dB - 3dB)$$

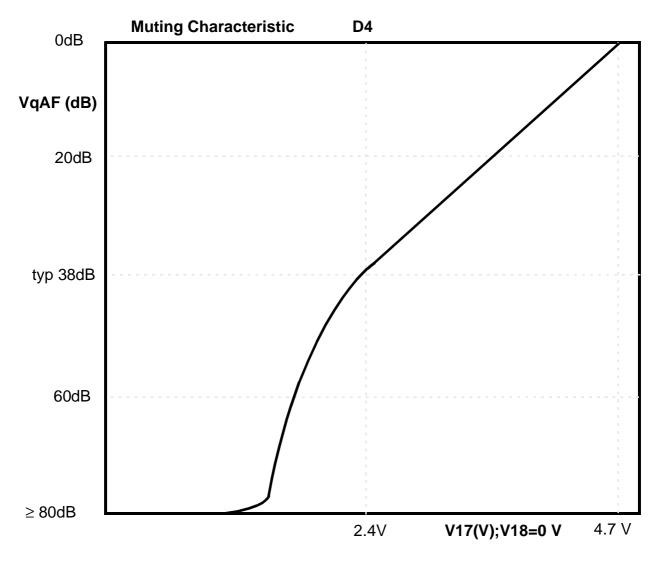
The V<sub>F</sub> values for temperatures between -40 to +85 °C within the V<sub>F</sub> dynamic range (M<sub>VFmin</sub> $\leq$ VF $\leq$ M<sub>VFmax</sub>) must be inside the predetermined tolerance field:

$$V_{Fmin} \le VF (M) \le V_{Fmax}$$

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# **Diagrams**



**Diagram of Mute Characteristic**