#### **General Description**

The MAX7318 2-wire-interfaced expander provides 16bit parallel input/output (I/O) port expansion for SMBus<sup>TM</sup> and I<sup>2</sup>C<sup>TM</sup> applications. The MAX7318 consists of input port registers, output port registers, polarity inversion registers, configuration registers, a bus timeout register, and an I<sup>2</sup>C-compatible serial interface logic compatible with SMBus. The system master can invert the MAX7318 input data by writing to the activehigh polarity inversion register.

Any of the 16 I/O ports can be configured as an input or output. A power-on reset (POR) initializes the 16 I/Os as inputs. Three address select pins configure one of 64 slave ID addresses.

The MAX7318 supports hot insertion. All port pins, the  $\overline{INT}$  output, SDA, SCL, and the slave address inputs AD0–2 remain high impedance in power-down (V+ = 0V) with up to 6V asserted upon them.

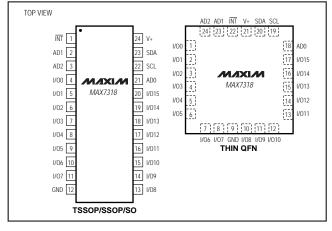
The MAX7318 is available in 24-pin SO, SSOP, TSSOP, and thin QFN packages and is specified over the -40°C to  $+125^{\circ}$ C automotive temperature range.

For applications requiring an SMBus timeout function, refer to the MAX7311 data sheet.

#### **Applications**

Servers RAID Systems Industrial Control Medical Equipment PLCs Instrumentation and Test Measurement

#### Pin Configurations



#### 

Maxim Integrated Products 1

Features MAX7378

# Ordering Information

PART	TEMP RANGE	PIN-PACKAGE	PKG CODE
MAX7318AWG	-40°C to +125°C	24 Wide SO	_
MAX7318AAG	-40°C to +125°C	24 SSOP	_
MAX7318ATG	-40°C to +125°C	24 Thin QFN (4mm × 4mm)	T2444-4
MAX7318AUG	-40°C to +125°C	24 TSSOP	_

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 $l^2C$  is a trademark of Philips Corp.

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For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

♦ 400kbps I<sup>2</sup>C-Compatible Serial Interface

♦ 16 I/O Pins that Default to Inputs on Power-Up

2V to 5.5V Operation

Supports Hot Insertion

Polarity Inversion

100kΩ Pullup on Each I/O

♦ -40°C to +125°C Operation

♦ 5.5V Overvoltage-Tolerant I/Os

Open-Drain Interrupt Output (INT)

Noise Filter on SCL/SDA Inputs

♦ 64 Slave ID Addresses Available

Low Standby Current (5.4µA typ)

♦ 4mm × 4mm, 0.8mm Thin QFN Package

#### **ABSOLUTE MAXIMUM RATINGS**

V+ to GND I/O0–I/O15 as Inputs	(GND - 0.3V) to +6V
SCL, SDA, AD0, AD1, AD2, INT	(GND - 0.3V) to +6V
Maximum V+ Current	+250mA
Maximum GND Current	250mA
DC Input Current on I/O0-I/O15	±20mA
DC Output Current on I/O0-I/O15	±80mA

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### DC ELECTRICAL CHARACTERISTICS

 $(V + 2V \text{ to } 5.5V, T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}, \text{ unless otherwise noted. Typical values are at V + 3.3V, T_A = +25^{\circ}\text{C}.)$  (Note 1)

PARAMETER	PARAMETER SYMBOL CONDITIONS		TIONS	MIN	TYP	MAX	UNITS
Supply Voltage	V+			2.0		5.5	V
			V + = 2V		24	36	
Supply Current	Ι+	All I/Os unloaded, f <sub>SCL</sub> = 400kHz	V + = 3.3V		45	62	μA
		13CL - 400KHZ	V + = 5.5V		83	124	
			V + = 2V		4.8	12.1	
Standby Current	ISTBY	All I/Os unloaded, f <sub>SCL</sub> = 0	V + = 3.3V		5.4	14.4	μA
		ISCE U	V + = 5.5V		6.4	19.4	
Power-On Reset Voltage	VPOR				1.4	1.7	V
SCL, SDA							
Input Voltage Low	VIL					0.3 x V+	V
Input Voltage High	VIH			0.7 x V+			V
Low-Level Output Voltage	Vol	I <sub>SINK</sub> = 6mA				0.4	V
Leakage Current	١L			-1		+1	μA
Input Capacitance					10		рF
I/O_		·					
Input Voltage Low	VIL					0.8	V
Input Voltage High	VIH			1.8			V
Input Leakage Current		$T_A = -40^{\circ}C$ to $+85^{\circ}C$ ; in pullup current, $V_{IO} = V$				1	μA
Internal Pullup Current		$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$ , V	/ <sub>IO</sub> = 0		34	100	μA
		$V + = 2V, V_{OL} = 0.5V$		8.5	17		
Low-Level Output Current	ISINK	V+ = 3.3V, V <sub>OL</sub> = 0.5V		17	32		mA
		V+ = 5V, V <sub>OL</sub> = 0.5V			43		
		V+ = 3.3V, V <sub>OH</sub> = 2.4V		29	41		
High Output Current	ISOURCE	V+ = 5V, V <sub>OH</sub> = 4.5V			31		mA
AD0, AD1, AD2	4			-			
Input Voltage Low	VIL					0.3 x V+	V
Input Voltage High	VIH			0.7 x V+			V

#### DC ELECTRICAL CHARACTERISTICS (continued)

 $(V + = 2V \text{ to } 5.5V, T_A = -40^{\circ}\text{C to } + 125^{\circ}\text{C}, \text{ unless otherwise noted. Typical values are at } V + = 3.3V, T_A = +25^{\circ}\text{C}.)$  (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Leakage Current			-1		+1	μΑ
Input Capacitance				4		рF
ÎNT						
Low-Level Output Current	IOL	$V_{OL} = 0.4V$	6			mA

#### AC ELECTRICAL CHARACTERISTICS

(V+ = 2V to 5.5V,  $T_A$  = -40°C to +125°C, unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITI	ONS	MIN	ТҮР	MAX	UNITS
SCL Clock Frequency	f <sub>SCL</sub>					400	kHz
Bus Free Time Between STOP and START Conditions	tBUF	Figure 2	1.3			μs	
Hold Time (Repeated) START Condition	<sup>t</sup> hd,sta	Figure 2	0.6			μs	
Repeated START Condition Setup Time	tsu,sta	Figure 2	0.6			μs	
STOP Condition Setup Time	tsu,sto	Figure 2		0.6			μs
Data Hold Time	thd,dat	Figure 2 (Note 2)			0.9	μs	
Data Setup Time	t <sub>SU,DAT</sub>	Figure 2	100			ns	
SCL Low Period	tLOW	Figure 2		1.3			μs
SCL High Period	thigh	Figure 2		0.7			μs
SDA Fall Time	tF	Figure 2 (Notes 3, 4)	$V + < 3.3V$ $V + \ge 3.3V$			500 250	ns
Pulse Width of Spike Suppressed	tsp	(Note 5)			50		ns
PORT TIMING							
Output Data Valid	tpv	Figure 7				3	μs
Input Data Setup Time				27			μs
Input Data Hold Time				0			μs
INTERRUPT TIMING							
Interrupt Valid	t <sub>IV</sub>	Figure 9				30.5	μs
Interrupt Reset	t <sub>IR</sub>	Figure 9				2	μs

Note 1: All parameters are 100% production tested at  $T_A = +25^{\circ}$ C. Specifications over temperature are guaranteed by design.

**Note 2:** A master device must internally provide a hold time of at least 300ns for the SDA signal (referred to the V<sub>IL</sub> of the SCL signal) to bridge the undefined region SCL's falling edge.

**Note 3:**  $C_B$  = total capacitance of one bus line in pF.

**Note 4:** The maximum t<sub>F</sub> for the SDA and SCL bus lines is specified at 300ns. The maximum fall time for the SDA output stage t<sub>F</sub> is specified at 250ns. This allows series protection resistors to be connected between the SDA and SCL pins and the SDA/SCL bus lines without exceeding the maximum specified t<sub>F</sub>.

Note 5: Input filters on the SDA and SCL inputs suppress noise spikes less than 50ns.



**MAX7318** 

#### **Typical Operating Characteristics**

 $(T_A = +25^{\circ}C, unless otherwise noted.)$ 

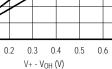
SUPPLY CURRENT STANDBY SUPPLY CURRENT SUPPLY CURRENT vs. TEMPERATURE vs. TEMPERATURE vs. SUPPLY VOLTAGE 100 100 12 f<sub>SCL</sub> = 400kHz ALL I/Os UNLOADED SCL = V+ í<sub>SCL</sub> = 400kHz 90 ALL I/OS UNLOADED 90 ALL I/OS UNLOADED 10 80 80 = 5V V+ V + = 5V(M) SUPPLY CURRENT (MA) SUPPLY CURRENT (µA) 70 70 8 3.31/ SUPPLY CURRENT 60 60 6 50 50  $V_{+} = 3.3V$ 40 40 4 30 30 V + = 2V20 20  $V_{+} = 2V$ 2 10 10 0 0 0 -25 -25 2.5 -50 0 25 50 75 100 125 -50 0 25 50 75 100 125 2.0 3.0 3.5 4.0 4.5 5.0 SUPPLY VOLTAGE (V) TEMPERATURE (°C) TEMPERATURE (°C) **I/O SINK CURRENT I/O SINK CURRENT I/O SINK CURRENT** vs. OUTPUT LOW VOLTAGE vs. OUTPUT LOW VOLTAGE vs. OUTPUT LOW VOLTAGE 24 50 50  $V_{+} = 2V_{-}$ V+ = 3.3V V+ = 5V 22 45 45 TΑ 40°C -40° 20 TΔ 40 40  $T_{A} = -40^{\circ}$ 18 35 35  $T_A = +25^{\circ}C$ 16 Isink (mA) 30 Isink (mA) 30 14 I<sub>SINK</sub> (mA)  $T_A = +25^\circ$ 12 25 25 10 T<sub>A</sub> = +125°C 20 20 T<sub>A</sub> = +125°C T<sub>A</sub> = +125°C 8 15 15 6 10 10 4 5 5 2 0 0 0 0.1 0.2 0.3 0.4 0.5 0.6 0 0.1 0.1 0.2 0.3 0.4 0.5 0.6 0 0.2 0.3 0.4 0 V<sub>OL</sub> (V)  $V_{OL}$  (V) V<sub>OL</sub> (V) **I/O SOURCE CURRENT I/O OUTPUT LOW VOLTAGE I/O SOURCE CURRENT** vs. OUTPUT HIGH VOLTAGE vs. TEMPERATURE vs. OUTPUT HIGH VOLTAGE 400 25 50 V+ = 3.3V V + = 2V45 350  $T_A = -40^{\circ}C$  $T_A = -40^{\circ}C$ V+ = 5V, ISINK = 10mA 20 40 300 35 +25° TΑ 250 Isource (mA) Isource (mA) 30 +25° 15 T<sub>A</sub> = V<sub>OL</sub> (mV) 25 200 2V, I<sub>SINK</sub> = 10mA 20 10 150 = +125°C TΔ 15 +125°C 100  $V_{+} = 5V$ ,  $I_{SINK} = 1mA$ 10 5 V+ = 2V, I<sub>SINK</sub> = 1mA 50 5

0

0

0.1 0.2 0.3 0.4 0.5 0.6 0.7

V+ - V<sub>OH</sub> (V)



/N/XI/N

0

0 0.1

5.5

0.5

0.7

4

0

-50

-25

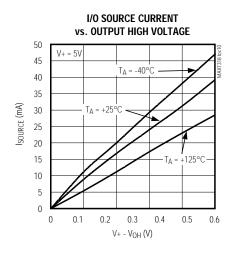
0

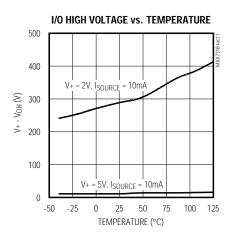
25 50 75 100 125

TEMPERATURE (°C)

#### **Typical Operating Characteristics (continued)**

 $(T_A = +25^{\circ}C, \text{ unless otherwise noted.})$ 





# MAX7318

#### Pin Description

PI	N		
TSSOP/ SSOP/SO	THIN QFN	NAME	FUNCTION
1	22	ĪNT	Interrupt Output (Open Drain)
2	23	AD1	Address Input 1
3	24	AD2	Address Input 2
4–11	1–8	1/00-1/07	Input/Output Port 1
12	9	GND	Supply Ground
13–20	10–17	I/08-I/015	Input/Output Port 2
21	18	AD0	Address Input 0
22	19	SCL	Serial Clock Line
23	20	SDA	Serial Data Line
24	21	V+	Supply Voltage. Bypass with a 0.047µF capacitor to GND.
_	_	EP	Exposed Pad on Package Underside. Connect to GND.

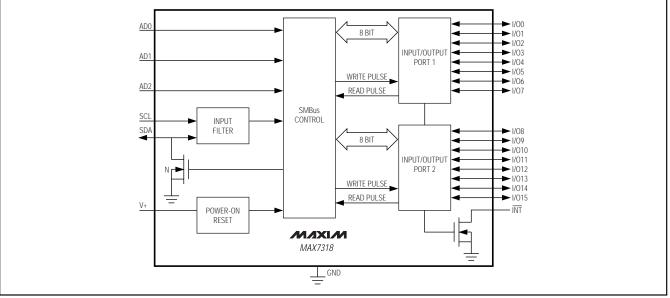


Figure 1. MAX7318 Block Diagram

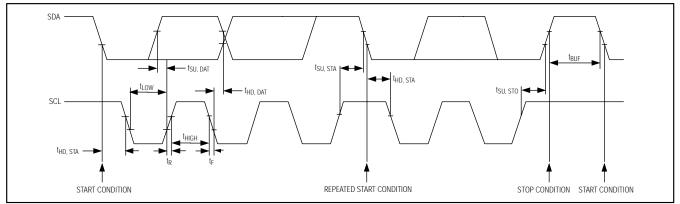


Figure 2. 2-Wire Serial Interface Timing Diagram

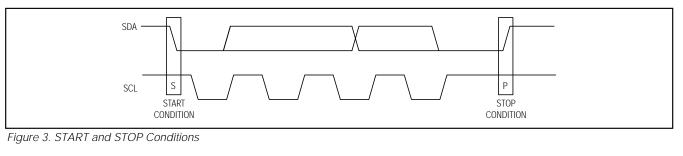
#### **Detailed Description**

The MAX7318 general-purpose input/output (GPIO) peripheral provides up to 16 I/O ports, controlled through an I<sup>2</sup>C-compatible serial interface. The MAX7318 consists of input port registers, output port registers, polarity inversion registers, and configuration registers. Upon power-on, all I/O lines are set as inputs. Three slave ID address select pins, AD0, AD1, and AD2, choose one of 64 slave ID addresses, including the eight addresses supported by the Phillips PCA9555. Table 1 is the register address table. Tables 2–5 show detailed register information.

#### Serial Interface

#### Serial Addressing

The MAX7318 operates as a slave that sends and receives data through a 2-wire interface. The interface uses a serial data line (SDA) and a serial clock line (SCL) to achieve bidirectional communication between master(s) and slave(s). A master, typically a microcontroller, initiates all data transfers to and from the MAX7318, and generates the SCL clock that synchronizes the data transfer (Figure 2).



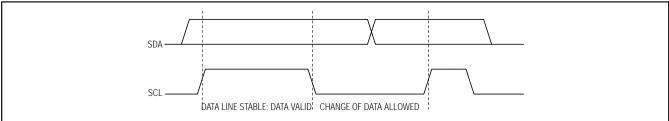


Figure 4. Bit Transfer

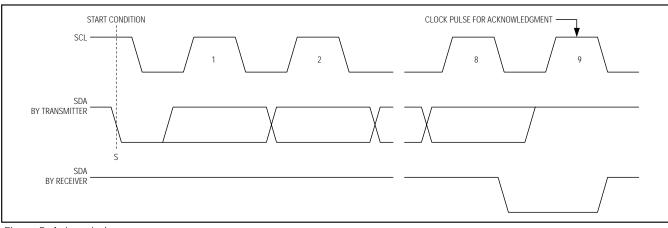


Figure 5. Acknowledge

Each transmission consists of a START condition sent by a master, followed by the MAX7318 7-bit slave address plus R/W bit, a register address byte, 1 or more data bytes, and finally a STOP condition (Figure 3).

#### **START and STOP Conditions**

Both SCL and SDA remain high when the interface is not busy. A master signals the beginning of a transmission with a START (S) condition by transitioning SDA from high to low while SCL is high. When the master has finished communicating with the slave, it issues a STOP (P) condition by transitioning SDA from low to high while SCL is high. The bus is then free for another transmission (Figure 3).

#### Bit Transfer

**MAX7318** 

One data bit is transferred during each clock pulse. The data on SDA must remain stable while SCL is high (Figure 4).

#### Acknowledge

The acknowledge bit is a clocked 9th bit, which the recipient uses as a handshake receipt of each byte of data (Figure 5). Thus, each byte transferred effectively requires 9 bits. The master generates the 9th clock pulse, and the recipient pulls down SDA during the acknowledge clock pulse, such that the SDA line is stable low during the high period of the clock pulse. When the master is transmitting to the MAX7318, the MAX7318

generates the acknowledge bit since the MAX7318 is the recipient. When the MAX7318 is transmitting to the master, the master generates the acknowledge bit.

#### Slave Address

The MAX7318 has a 7-bit-long slave address (Figure 6). The 8th bit following the 7-bit slave address is the R/W bit. Set this bit low for a write command and high for a read command.

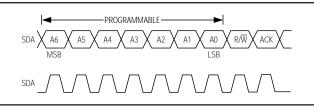


Figure 6. Slave Address

#### Table 1. Command-Byte Register

Slave address pins AD2, AD1, and AD0 choose 1 of 64 slave ID addresses (Table 7).

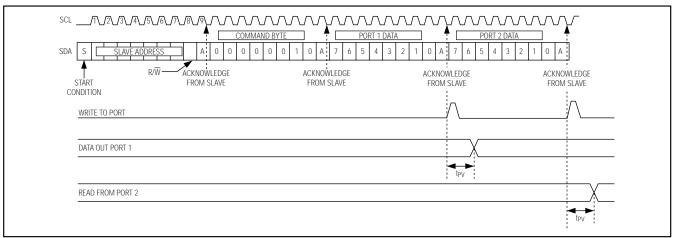
#### **Data Bus Transaction**

The command byte is the first byte to follow the 8-bit device slave address during a write transmission (Table 1, Figure 7). The command byte is used to determine which of the following registers are written or read.

#### Writing to Port Registers

Transmit data to the MAX7318 by sending the device slave address and setting the LSB to a logic zero. The command byte is sent after the address and determines which registers receive the data following the command byte (Figure 7).

COMMAND BYTE ADDRESS (hex)	FUNCTION	PROTOCOL	POWER-UP DEFAULT		
0x00	Input port 1	Read byte	XXXX XXXX		
0x01	Input port 2	Read byte	XXXX XXXX		
0x02	Output port 1	Read/write byte	1111 1111		
0x03	Output port 2	Read/write byte	1111 1111		
0x04	Port 1 polarity inversion	Read/write byte	0000 0000		
0x05	Port 2 polarity inversion	Read/write byte	0000 0000		
0x06	Port 1 configuration	Read/write byte	1111 1111		
0x07	Port 2 configuration	Read/write byte	1111 1111		
OxFF	Factory reserved. (Do not write to this register.)	—	_		







The MAX7318's eight registers are configured to operate as four register pairs: input ports, output ports, polarity inversion ports, and configuration ports. After sending 1 byte of data to one register, the next byte is sent to the other register in the pair. For example, if the first byte of data is sent to output port 2, then the next byte of data is stored in output port 1. An unlimited number of data bytes can be sent in one write transmission. This allows each 8-bit register to be updated independently of the other registers.

#### **Reading Port Registers**

**MAX7318** 

To read the device data, the bus master must first send the MAX7318 address with the R/W bit set to zero, followed by the command byte, which determines which register is accessed. After a restart, the bus master must then send the MAX7318 address with the R/W bit set to 1. Data from the register defined by the command byte is then sent from the MAX7318 to the master (Figures 8, 9).

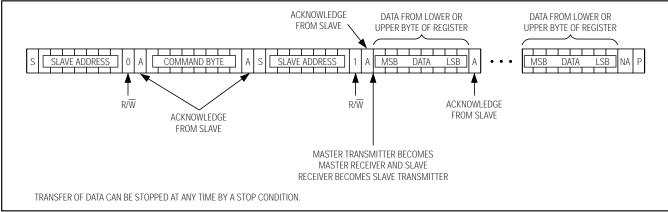


Figure 8. Read from Register

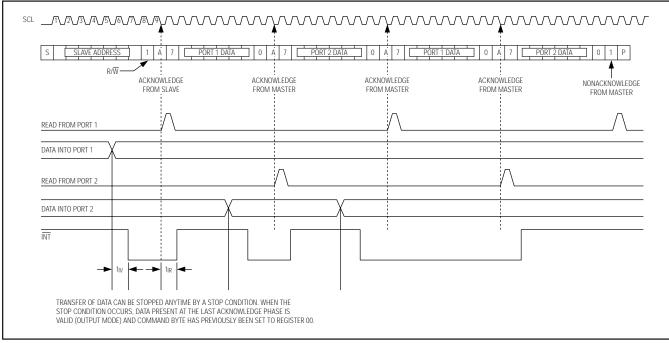


Figure 9. Read from Input Registers

M/XI/M

9

Data is clocked into a register on the falling edge of the acknowledge clock pulse. After reading the first byte, additional bytes may be read and reflect the content in the other register in the pair. For example, if input port 1 is read, the next byte read is input port 2. An unlimited number of data bytes can be read in one read transmission, but the final byte received must not be acknowledged by the bus master.

Interrupt (INT)

The open-drain interrupt output, INT, activates when one of the port pins changes states and only when the pin is configured as an input. The interrupt deactivates when the input returns to its previous state or the input register is read (Figure 9). A pin configured as an output does not cause an interrupt. Each 8-bit port register is read independently; therefore, an interrupt caused by port 1 is not cleared by a read of port 2's register.

Changing an I/O from an output to an input may cause a false interrupt to occur if the state of that I/O does not match the content of the input port register.

#### Input/Output Port

When an I/O is configured as an input, FETs Q1 and Q2 are off (Figure 10), creating a high-impedance input with a nominal 100k $\Omega$  pullup to V+. All inputs are overvoltage protected to 5.5V, independent of supply voltage. When a port is configured as an output, either Q1 or Q2 is on, depending on the state of the output port register. When V+ powers up, an internal power-on reset sets all registers to their respective defaults (Table 1).

#### Input Port Registers

The input port registers (Table 2) are read-only ports. They reflect the incoming logic levels of the pins, regardless of whether the pin is defined as an input or an output by the respective configuration register. A read of the input port 1 register latches the current value of I/OO–I/O7. A read of the input port 2 register latches the current value of I/O8–I/O15. Writes to the input port registers are ignored.

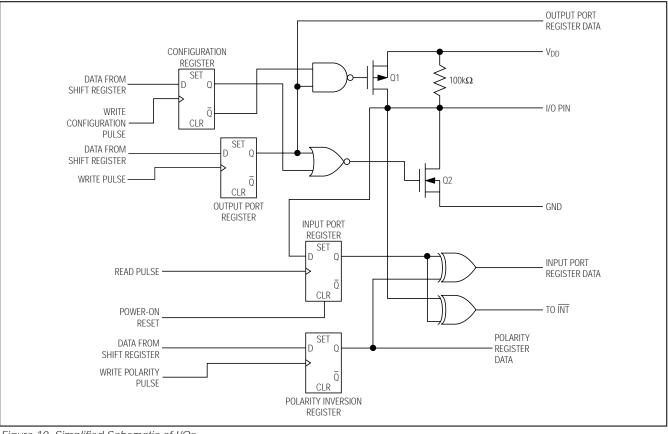


Figure 10. Simplified Schematic of I/Os



#### Table 2. Registers 0x00, 0x01—Input Port Registers

DIT	17	16	15	14	13	12	l1	10
BIT	I15	114	113	112	111	110	19	18

#### Table 3. Registers 0x02, 0x03—Output Port Registers

BIT	07	O6	O5	04	O3	02	01	00
	015	014	013	012	011	O10	O9	08
Power-up default	1	1	1	1	1	1	1	1

#### Table 4. Registers 0x04, 0x05—Polarity Inversion Registers

ВІТ	I/07	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1	I/O0
	I/O15	I/O14	I/O13	I/O12	I/O11	I/O10	I/O9	I/O8
Power-up default	0	0	0	0	0	0	0	0

#### Table 5. Registers 0x06, 0x07—Configuration Registers

BIT	I/07	I/O6	I/O5	I/O4	I/O3	I/O2	I/O1	I/O0
	I/O15	I/O14	I/O13	I/O12	I/O11	I/O10	I/O9	I/O8
Power-up default	1	1	1	1	1	1	1	1

#### **Output Port Registers**

The output port registers (Table 3) set the outgoing logic levels of the I/Os defined as outputs by the respective configuration register. Reads from the output port registers reflect the value that is in the flip-flop controlling the output selection, not the actual I/O value.

#### Polarity Inversion Registers

The polarity inversion registers (Table 4) enable polarity inversion of pins defined as inputs by the respective port configuration registers. Set the bit in the polarity inversion register to invert the corresponding port pin's polarity. Clear the bit in the polarity inversion register to retain the corresponding port pin's original polarity.

#### **Configuration Registers**

The configuration registers (Table 5) configure the directions of the I/O pins. Set the bit in the respective configuration register to enable the corresponding port as an input. Clear the bit in the configuration register to enable the corresponding port as an output.

#### Standby

The MAX7318 goes into standby when the I<sup>2</sup>C bus is idle. Standby supply current is typically 5.4µA.

#### \_Applications Information

#### Hot Insertion

The I/O ports I/OO–I/O15, interrupt output  $\overline{INT}$ , and serial interface SDA, SCL, AD0–2 remain high impedance with up to 6V asserted on them when the MAX7318 is powered down (V+ = 0V). The MAX7318 can therefore be used in hot-swap applications. Note that each I/O's 100k $\Omega$  pullup effectively becomes a 100k $\Omega$  pulldown when the MAX7318 is powered down.

#### **Power-Supply Consideration**

The MAX7318 operates from a supply voltage of 2V to 5.5V. Bypass the power supply to GND with a  $0.047\mu$ F capacitor as close to the device as possible. For the QFN version, connect the exposed pad to GND.

#### Table 6. MAX7318 Address Map

AD2	AD1	AD0	A6	A5	A4	A3	A2	A1	A0	ADDRESS (hex)
GND	SCL	GND	0	0	1	0	0	0	0	0x20
GND	SCL	V+	0	0	1	0	0	0	1	0x22
GND	SDA	GND	0	0	1	0	0	1	0	0x24
GND	SDA	V+	0	0	1	0	0	1	1	0x26
V+	SCL	GND	0	0	1	0	1	0	0	0x28
V+	SCL	V+	0	0	1	0	1	0	1	0x2A
V+	SDA	GND	0	0	1	0	1	1	0	0x2C
V+	SDA	V+	0	0	1	0	1	1	1	0x2E
GND	SCL	SCL	0	0	1	1	0	0	0	0x30
GND	SCL	SDA	0	0	1	1	0	0	1	0x32
GND	SDA	SCL	0	0	1	1	0	1	0	0x34
GND	SDA	SDA	0	0	1	1	0	1	1	0x36
V+	SCL	SCL	0	0	1	1	1	0	0	0x38
V+	SCL	SDA	0	0	1	1	1	0	1	0x3A
V+	SDA	SCL	0	0	1	1	1	1	0	0x3C
V+	SDA	SDA	0	0	1	1	1	1	1	0x3E
GND	GND	GND	0	1	0	0	0	0	0	0x40
GND	GND	V+	0	1	0	0	0	0	1	0x42
GND	V+	GND	0	1	0	0	0	1	0	0x44
GND	V+	V+	0	1	0	0	0	1	1	0x46
V+	GND	GND	0	1	0	0	1	0	0	0x48
V+	GND	V+	0	1	0	0	1	0	1	0x4A
V+	V+	GND	0	1	0	0	1	1	0	0x4C
V+	V+	V+	0	1	0	0	1	1	1	0x4E
GND	GND	SCL	0	1	0	1	0	0	0	0x50
GND	GND	SDA	0	1	0	1	0	0	1	0x52
GND	V+	SCL	0	1	0	1	0	1	0	0x54
GND	V+	SDA	0	1	0	1	0	1	1	0x56
V+	GND	SCL	0	1	0	1	1	0	0	0x58
V+	GND	SDA	0	1	0	1	1	0	1	0x5A
V+	V+	SCL	0	1	0	1	1	1	0	0x5C
V+	V+	SDA	0	1	0	1	1	1	1	0x5E

AD2	AD1	AD0	A6	A5	A4	A3	A2	A1	A0	ADDRESS (hex)
SCL	SCL	GND	1	0	1	0	0	0	0	0xA0
SCL	SCL	V+	1	0	1	0	0	0	1	0xA2
SCL	SDA	GND	1	0	1	0	0	1	0	0xA4
SCL	SDA	V+	1	0	1	0	0	1	1	0xA6
SDA	SCL	GND	1	0	1	0	1	0	0	0xA8
SDA	SCL	V+	1	0	1	0	1	0	1	0xAA
SDA	SDA	GND	1	0	1	0	1	1	0	0xAC
SDA	SDA	V+	1	0	1	0	1	1	1	OxAE
SCL	SCL	SCL	1	0	1	1	0	0	0	0xB0
SCL	SCL	SDA	1	0	1	1	0	0	1	0xB2
SCL	SDA	SCL	1	0	1	1	0	1	0	0xB4
SCL	SDA	SDA	1	0	1	1	0	1	1	0xB6
SDA	SCL	SCL	1	0	1	1	1	0	0	0xB8
SDA	SCL	SDA	1	0	1	1	1	0	1	0xBA
SDA	SDA	SCL	1	0	1	1	1	1	0	0xBC
SDA	SDA	SDA	1	0	1	1	1	1	1	0xBE
SCL	GND	GND	1	1	0	0	0	0	0	0xC0
SCL	GND	V+	1	1	0	0	0	0	1	0xC2
SCL	V+	GND	1	1	0	0	0	1	0	0xC4
SCL	V+	V+	1	1	0	0	0	1	1	0xC6
SDA	GND	GND	1	1	0	0	1	0	0	0xC8
SDA	GND	V+	1	1	0	0	1	0	1	0xCA
SDA	V+	GND	1	1	0	0	1	1	0	0xCC
SDA	V+	V+	1	1	0	0	1	1	1	0xCE
SCL	GND	SCL	1	1	0	1	0	0	0	0xD0
SCL	GND	SDA	1	1	0	1	0	0	1	0xD2
SCL	V+	SCL	1	1	0	1	0	1	0	0xD4
SCL	V+	SDA	1	1	0	1	0	1	1	0xD6
SDA	GND	SCL	1	1	0	1	1	0	0	0xD8
SDA	GND	SDA	1	1	0	1	1	0	1	0xDA
SDA	V+	SCL	1	1	0	1	1	1	0	0xDC
SDA	V+	SDA	1	1	0	1	1	1	1	0xDE

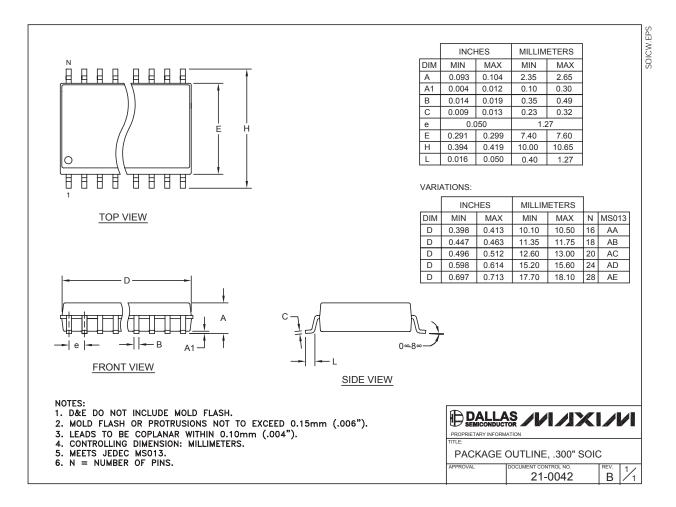
#### Table 6. MAX7318 Address Map (continued)

#### Chip Information

TRANSISTOR COUNT: 12,994 PROCESS: BICMOS

#### Package Information

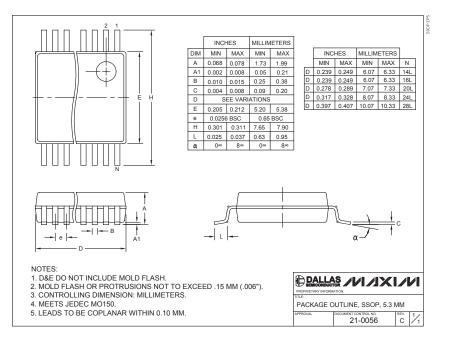
(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)

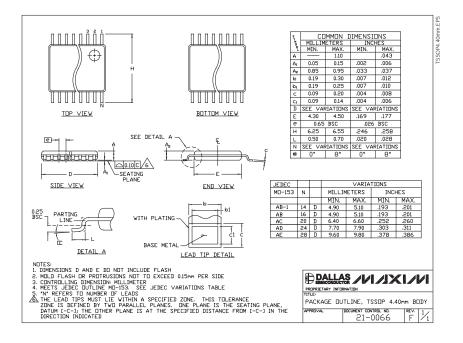


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#### Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)





(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to <u>www.maxim-ic.com/packages</u>.)

#### THIN.EP <u>∕5∖</u> •⊕+0.1000/CAB 2X OFN 7 -D/2 D2/2 | -PIN #1 I.D. 👍 INDEX AREA (D/2 X E/2) 2A \_\_\_\_\_0.15[C] (0.35 X 45\*) 24L ∕₽ E/2 ∕∆ E2 /2 ត៍ 🖞 🗆 🗆 🗠 DETAIL ∔œ ḉ 向 (ND−1) X @ Ģ BOTTOM VIEW TOP VIEW DETAIL A ▣ • // 0.10 C EVEN TER 1 \_\_\_\_\_ SEATING PLANE ¢ BDALLAS /VI/IXI/VI SIDE VIEW OEN 4 21-0139 C 1/2 EXPOSED PAD VARIATIONS COMMON DIMENSIONS PKG 12L 4×4 16L 4×4 20L 4×4 24L 4×4 D2 E2 PKG. CODES MDN. NDM. NAX. NIN. NDM. MAX. NIN. NIN. NDM. MAX. NIN. NDM. MAX. NDM. MAX. MAX. NDM. MAX. <th MEN, NOM, MAX, MEN, NOM, MAX, REF. T1244-2 1.95 2.10 2.25 1.95 2.10 2.25 Α ND T1244-3 1.95 2.10 2.25 1.95 2.10 2.25 T1244-4 1.95 2.10 2.25 1.95 2.10 2.25 T1244-4 1.95 2.10 2.25 1.95 2.10 2.25 000</th YES A2 ND T1644-2 1.95 2.10 2.25 1.95 2.10 2.25 ND 400 4.10 3.90 4.00 4.11 3.90 4.00 4.10 1.95 2.10 2.25 1.95 2.10 2.25 1.95 2.10 2.25 1.95 2.10 2.25 T1644-3 YES T1644-4.00 4.00 · ND T2044-1 1.95 2.10 2.25 1.95 2.10 2.25 ND T2044-2 1.95 2.10 2.25 1.95 2.10 2.25 T2044-3 1.95 2.10 2.25 1.95 2.10 2.25 YES ND 0.25 - 0.25 0.25 - 0.25 0.45 0.55 0.65 0.45 0.55 0.65 0.45 0.55 0.65 0.30 0.40 0.50 N 16 T2444-1 2.45 2.60 2.63 2.45 2.60 2.63 ND 12 20 24 T2444-2 1.95 2.10 2.25 1.95 2.10 2.25 T2444-3 2.45 2.60 2.63 2.45 2.60 2.63 YES ND YES WGGI WGGD-1 WGGD-T2444-4 2.45 2.60 2.63 2.45 2.60 2.63 ND NOTES DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994. 2. ALL DIMENSIONS ARE IN MILLIMETERS, ANGLES ARE IN DEGREES. N IS THE TOTAL NUMBER OF TERMINALS N IS THE TOTAL MORE OF LEMINULS. THE TERNINAL ∯I DENTIFIER MOT TERNINAL NUMBERING CONVENTION SHALL CONFORM TO JEED 95-1 SPF-012. DETALS OF TERNINAL ∯I DENTIFIER MAY BE ETHER A MOLD OR MARKED FEATURE. A A DIMENSION & APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25 mm AND 0.30 mm

- AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.
- DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.
  COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
- <u>ZBA</u> COPLANANTIT APPLIES TO THE EXPOSED THAT SINK SLUG AS WELL AS THE LEMANALS.
  9. DRAWING CONFORMS TO JEDEC M0220, EXCEPT FOR T2444-1, T2444-3 AND T2444-4.

Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

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