

100-Pin TQFP
Commercial Temp
Industrial Temp

1M x 18, 512K x 32, 512K x 36
18Mb Sync Burst SRAMs

350 MHz–150 MHz
1.8 V V_{DD}
1.8 V I/O

Features

- $\overline{FT}$ pin for user-configurable flow through or pipeline operation
- Dual Cycle Deselect (DCD) operation
- 1.8 V +10%/–10% core power supply
- 1.8 V I/O supply
- $\overline{LBO}$ pin for Linear or Interleaved Burst mode
- Internal input resistors on mode pins allow floating mode pins
- Default to Interleaved Pipeline mode
- Byte Write ($\overline{BW}$) and/or Global Write ($\overline{GW}$) operation
- Internal self-timed write cycle
- Automatic power-down for portable applications
- JEDEC-standard 100-lead TQFP package

Functional Description

Applications

The GS8160EV18/32/36AT is an 18,874,368-bit (16,777,216-bit for x32 version) high performance synchronous SRAM with a 2-bit burst address counter. Although of a type originally developed for Level 2 Cache applications supporting high performance CPUs, the device now finds application in synchronous SRAM applications, ranging from DSP main store to networking chip set support.

Controls

Addresses, data I/Os, chip enables ($\overline{E1}$, $E2$, $\overline{E3}$), address burst control inputs ($\overline{ADSP}$, $\overline{ADSC}$, $\overline{ADV}$), and write control inputs ($\overline{Bx}$, $\overline{BW}$, $\overline{GW}$) are synchronous and are controlled by a positive-edge-triggered clock input (CK). Output enable ($\overline{G}$) and power down control (ZZ) are asynchronous inputs. Burst cycles can be initiated with either $\overline{ADSP}$ or $\overline{ADSC}$ inputs. In Burst mode, subsequent burst addresses are generated internally and are controlled by $\overline{ADV}$. The burst address counter may be configured to count in either linear or interleave order with the Linear Burst Order ($\overline{LBO}$) input. The Burst function need not be used. New addresses can be loaded

on every cycle with no degradation of chip performance.

Flow Through/Pipeline Reads

The function of the Data Output register can be controlled by the user via the $\overline{FT}$ mode pin (Pin 14). Holding the $\overline{FT}$ mode pin low places the RAM in Flow Through mode, causing output data to bypass the Data Output Register. Holding $\overline{FT}$ high places the RAM in Pipeline mode, activating the rising-edge-triggered Data Output Register.

DCD Pipelined Reads

The GS8160EV18/32/36AT is a DCD (Dual Cycle Deselect) pipelined synchronous SRAM. SCD (Single Cycle Deselect) versions are also available. DCD SRAMs pipeline disable commands to the same degree as read commands. DCD RAMs hold the deselect command for one full cycle and then begin turning off their outputs just after the second rising edge of clock.

Byte Write and Global Write

Byte write operation is performed by using Byte Write enable ($\overline{BW}$) input combined with one or more individual byte write signals ($\overline{Bx}$). In addition, Global Write ($\overline{GW}$) is available for writing all bytes at one time, regardless of the Byte Write control inputs.

Sleep Mode

Low power (Sleep mode) is attained through the assertion (High) of the ZZ signal, or by stopping the clock (CK). Memory data is retained during Sleep mode.

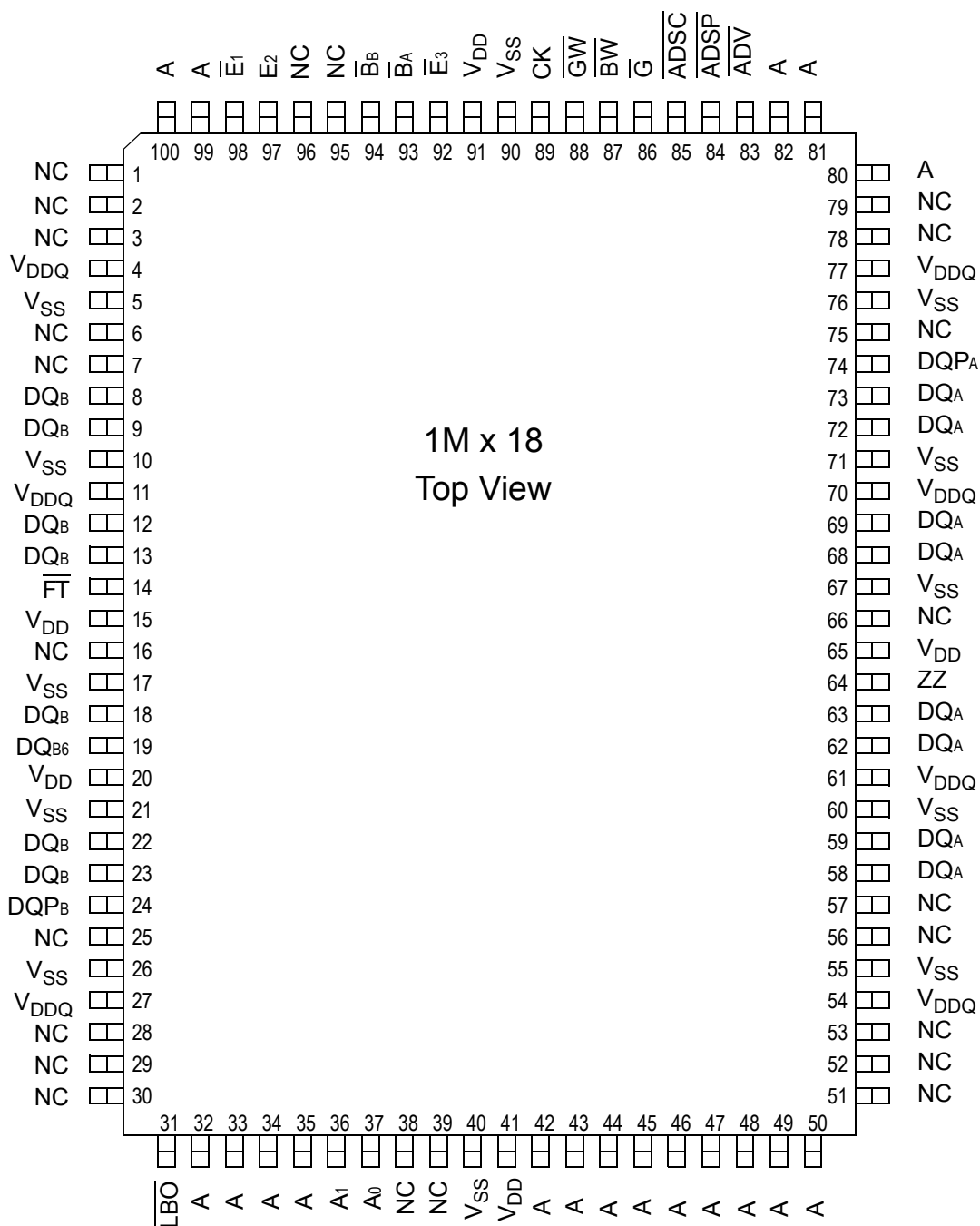
Core and Interface Voltages

The GS8160EV18/32/36AT operates on a 1.8 V power supply. All input are 1.8 V compatible. Separate output power (V_{DDQ}) pins are used to decouple output noise from the internal circuits and are 1.8 V compatible.

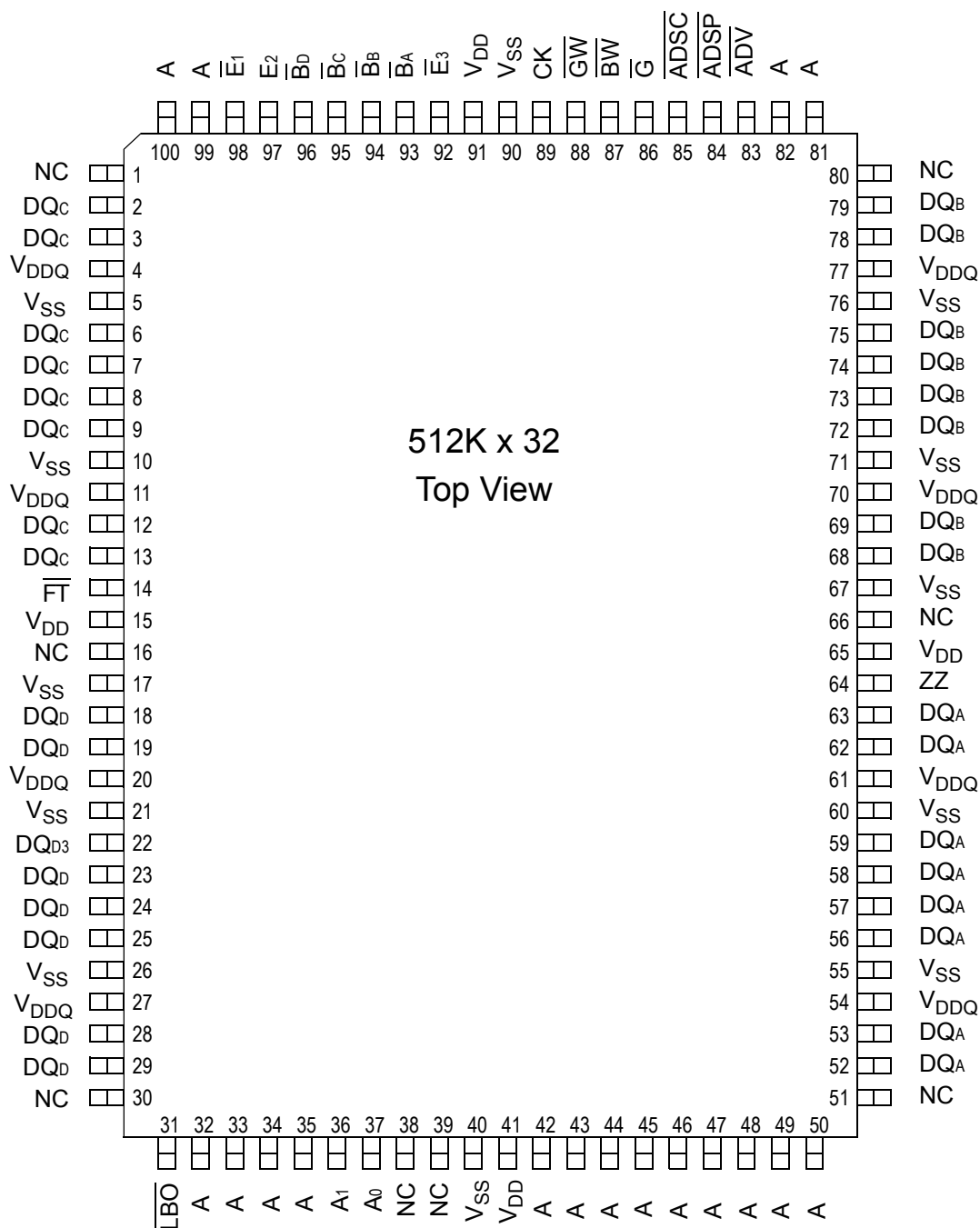
Parameter Synopsis

		-350	-333	-300	-250	-200	-150	Unit
Pipeline 3-1-1-1	t_{KQ}	1.8	2.0	2.2	2.3	2.7	3.3	ns
	t_{Cycle}	2.85	3.0	3.3	4.0	5.0	6.7	ns
	Curr (x18)	395	370	335	280	230	185	mA
	Curr (x32/x36)	455	430	390	330	270	210	mA
Flow Through 2-1-1-1	t_{KQ}	4.5	4.7	5.0	5.5	6.5	7.5	ns
	t_{Cycle}	4.5	4.7	5.0	5.5	6.5	7.5	ns
	Curr (x18)	270	250	230	210	185	170	mA
	Curr (x32/x36)	305	285	270	240	205	190	mA

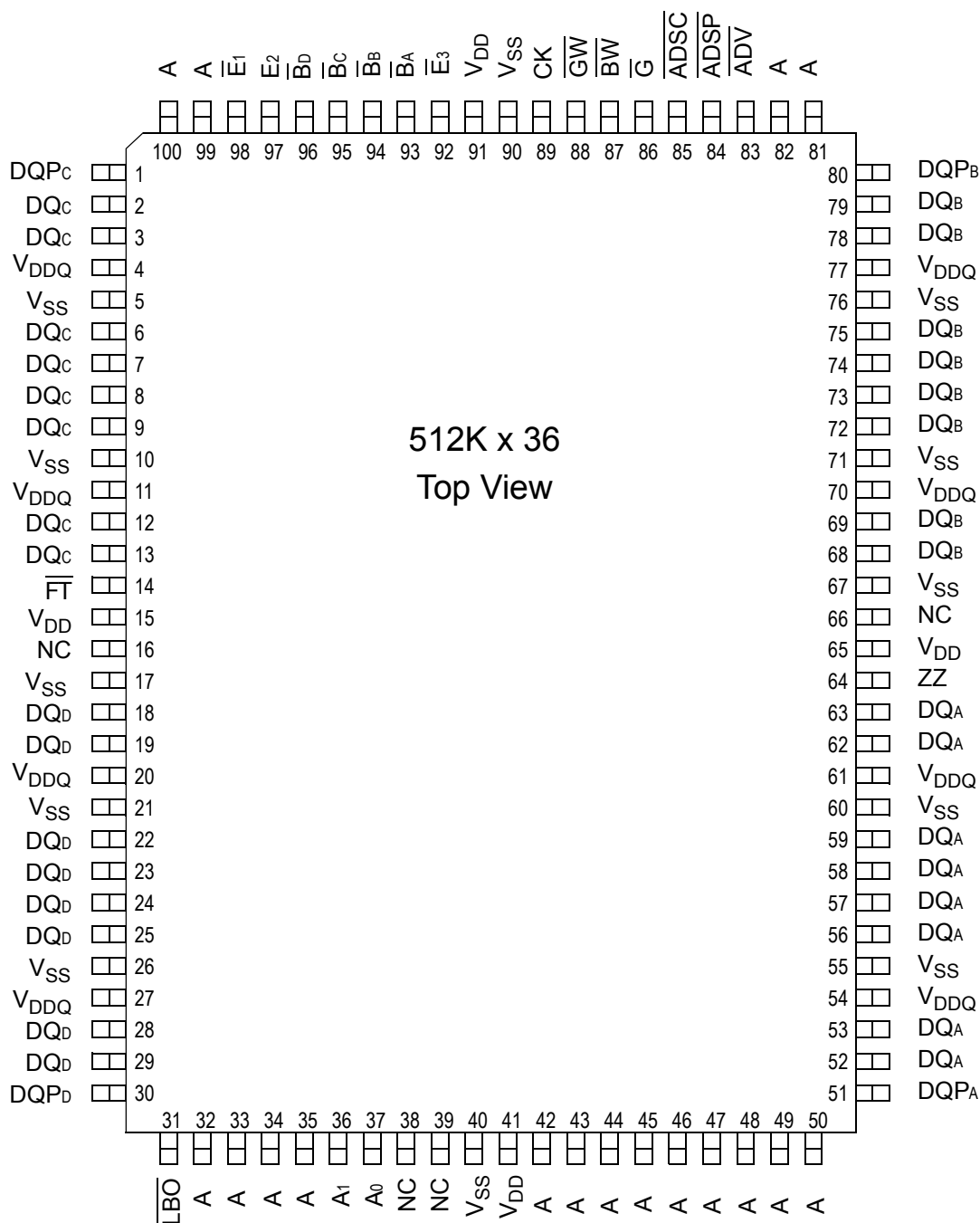
GS8160EV18A 100-Pin TQFP Pinout



GS8160EV32A 100-Pin TQFP Pinout



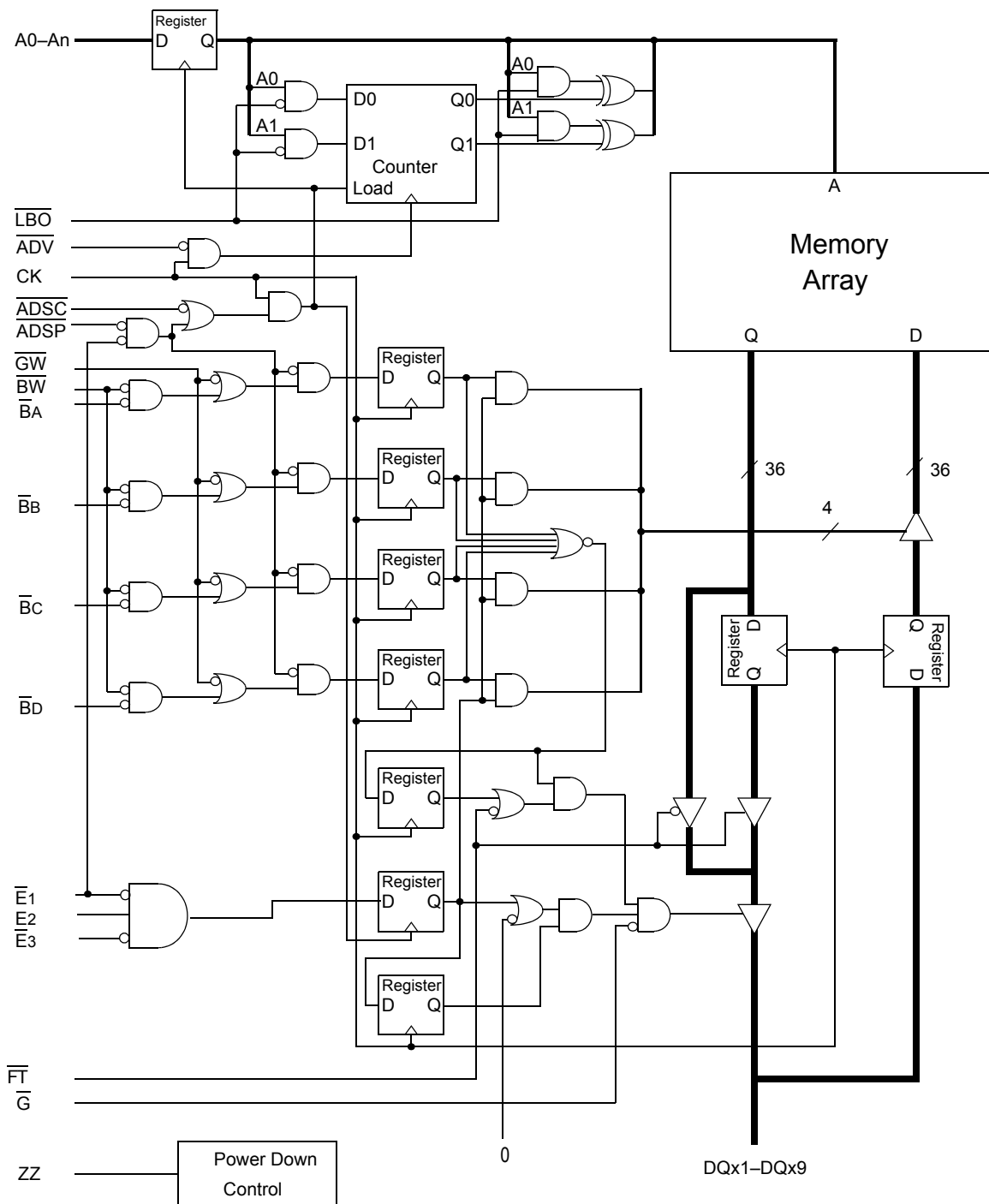
GS8160EV36A 100-Pin TQFP Pinout



TQFP Pin Description

Symbol	Type	Description
A ₀ , A ₁	I	Address field LSBs and Address Counter preset Inputs
A	I	Address Inputs
DQ _A DQ _B DQ _C DQ _D	I/O	Data Input and Output pins
NC	—	No Connect
BW	I	Byte Write—Writes all enabled bytes; active low
$\overline{B_A}$, $\overline{B_B}$, $\overline{B_C}$, $\overline{B_D}$	I	Byte Write Enable for DQ _A , DQ _B Data I/Os; active low
CK	I	Clock Input Signal; active high
GW	I	Global Write Enable—Writes all bytes; active low
$\overline{E_1}$	I	Chip Enable; active low
E ₂	I	Chip Enable; active high
$\overline{E_3}$	I	Chip Enable; active low
$\overline{G}$	I	Output Enable; active low
ADV	I	Burst address counter advance enable; active low
ADSP, ADSC	I	Address Strobe (Processor, Cache Controller); active low
ZZ	I	Sleep Mode control; active high
LBO	I	Linear Burst Order mode; active low
V _{DD}	I	Core power supply
V _{SS}	I	I/O and Core Ground
V _{DDQ}	I	Output driver power supply

GS8160EV18/32/36A Block Diagram



Note: Only x36 version shown for simplicity.

Mode Pin Functions

Mode Name	Pin Name	State	Function
Burst Order Control	$\overline{\text{LBO}}$	L	Linear Burst
		H	Interleaved Burst
Output Register Control	$\overline{\text{FT}}$	L	Flow Through
		H or NC	Pipeline
Power Down Control	ZZ	L or NC	Active
		H	Standby, $I_{DD} = I_{SB}$

Note:

There pull-up device on the $\overline{\text{FT}}$ pin and a pull-down device on the ZZ pin, so those input pins can be unconnected and the chip will operate in the default states as specified in the above tables.

Burst Counter Sequences

Linear Burst Sequence

	A[1:0]	A[1:0]	A[1:0]	A[1:0]
1st address	00	01	10	11
2nd address	01	10	11	00
3rd address	10	11	00	01
4th address	11	00	01	10

Note: The burst counter wraps to initial state on the 5th clock.

Interleaved Burst Sequence

	A[1:0]	A[1:0]	A[1:0]	A[1:0]
1st address	00	01	10	11
2nd address	01	00	11	10
3rd address	10	11	00	01
4th address	11	10	01	00

Note: The burst counter wraps to initial state on the 5th clock.

BPR 1999.05.18

Byte Write Truth Table

Function	$\overline{GW}$	$\overline{BW}$	$\overline{BA}$	$\overline{BB}$	$\overline{BC}$	$\overline{BD}$	Notes
Read	H	H	X	X	X	X	1
Read	H	L	H	H	H	H	1
Write byte a	H	L	L	H	H	H	2, 3
Write byte b	H	L	H	L	H	H	2, 3
Write byte c	H	L	H	H	L	H	2, 3, 4
Write byte d	H	L	H	H	H	L	2, 3, 4
Write all bytes	H	L	L	L	L	L	2, 3, 4
Write all bytes	L	X	X	X	X	X	

Note:

1. All byte outputs are active in read cycles regardless of the state of Byte Write Enable inputs.
2. Byte Write Enable inputs $\overline{BA}$, $\overline{BB}$, $\overline{BC}$ and/or $\overline{BD}$ may be used in any combination with $\overline{BW}$ to write single or multiple bytes.
3. All byte I/Os remain High-Z during all write operations regardless of the state of Byte Write Enable inputs.
4. Bytes "C" and "D" are only available on the x32 and x36 versions.

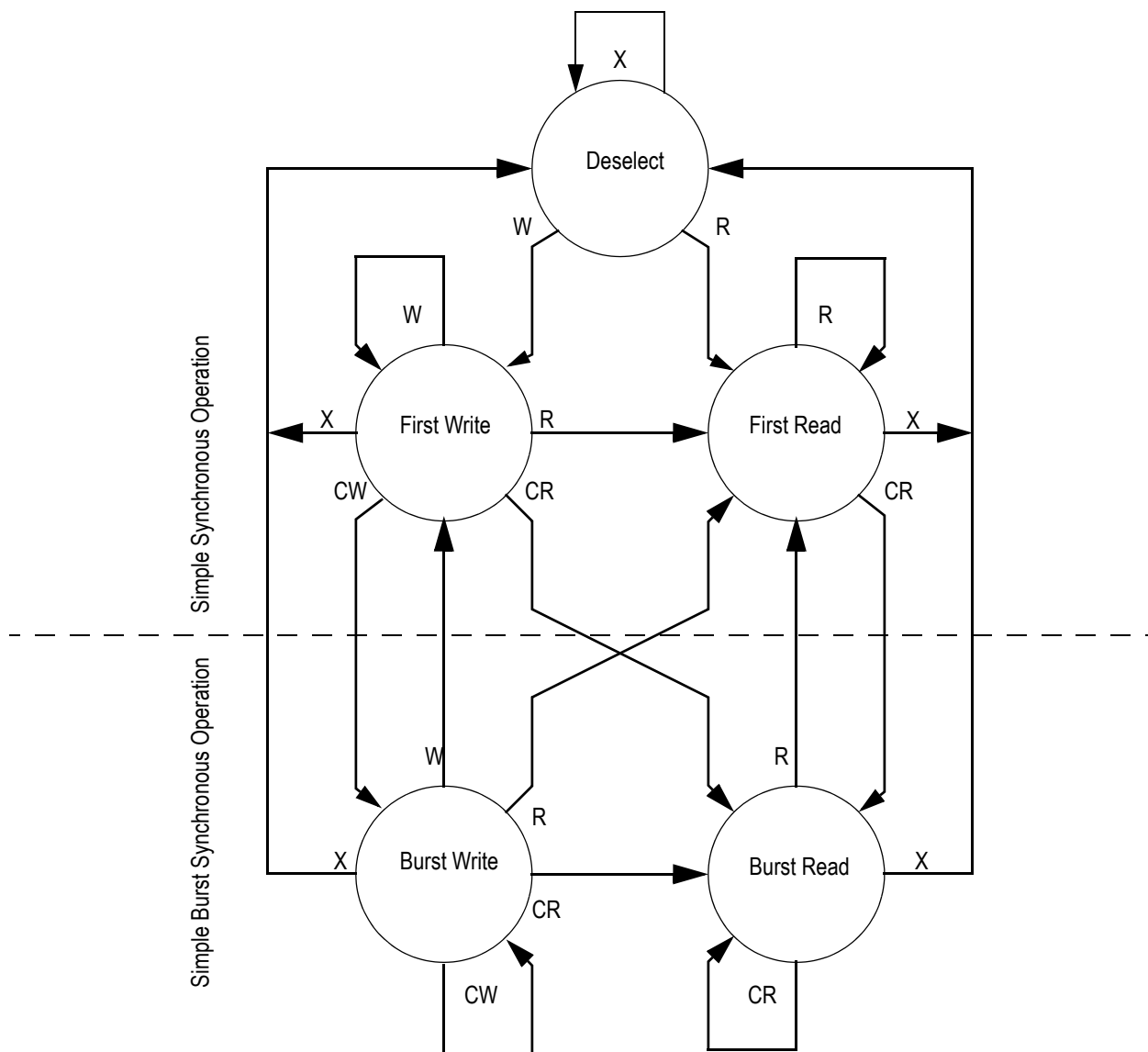
Synchronous Truth Table

Operation	Address Used	State Diagram Key ⁵	$\bar{E}_1$	E^2	$\overline{ADSP}$	$\overline{ADSC}$	$\overline{ADV}$	$\bar{W}^3$	DQ ⁴
Deselect Cycle, Power Down	None	X	H	X	X	L	X	X	High-Z
Deselect Cycle, Power Down	None	X	L	F	L	X	X	X	High-Z
Deselect Cycle, Power Down	None	X	L	F	H	L	X	X	High-Z
Read Cycle, Begin Burst	External	R	L	T	L	X	X	X	Q
Read Cycle, Begin Burst	External	R	L	T	H	L	X	F	Q
Write Cycle, Begin Burst	External	W	L	T	H	L	X	T	D
<i>Read Cycle, Continue Burst</i>	<i>Next</i>	<i>CR</i>	X	X	H	H	L	F	Q
Read Cycle, Continue Burst	Next	CR	H	X	X	H	L	F	Q
<i>Write Cycle, Continue Burst</i>	<i>Next</i>	<i>CW</i>	X	X	H	H	L	T	D
Write Cycle, Continue Burst	Next	CW	H	X	X	H	L	T	D
Read Cycle, Suspend Burst	Current		X	X	H	H	H	F	Q
Read Cycle, Suspend Burst	Current		H	X	X	H	H	F	Q
Write Cycle, Suspend Burst	Current		X	X	H	H	H	T	D
Write Cycle, Suspend Burst	Current		H	X	X	H	H	T	D

Notes:

1. X = Don't Care, H = High, L = Low
2. E = T (True) if $E_2 = 1$ and $\bar{E}_3 = 0$; E = F (False) if $E_2 = 0$ or $\bar{E}_3 = 1$
3. $\bar{W} = T$ (True) and F (False) is defined in the Byte Write Truth Table preceding.
4. $\bar{G}$ is an asynchronous input. $\bar{G}$ can be driven high at any time to disable active output drivers. $\bar{G}$ low can only enable active drivers (shown as "Q" in the Truth Table above).
5. All input combinations shown above are tested and supported. Input combinations shown in gray boxes need not be used to accomplish basic synchronous or synchronous burst operations and may be avoided for simplicity.
6. Tying $\overline{ADSP}$ high and $\overline{ADSC}$ low allows simple non-burst synchronous operations. See **BOLD** items above.
7. Tying $\overline{ADSP}$ high and $\overline{ADV}$ low while using $\overline{ADSC}$ to load new addresses allows simple burst operations. See *ITALIC* items above.

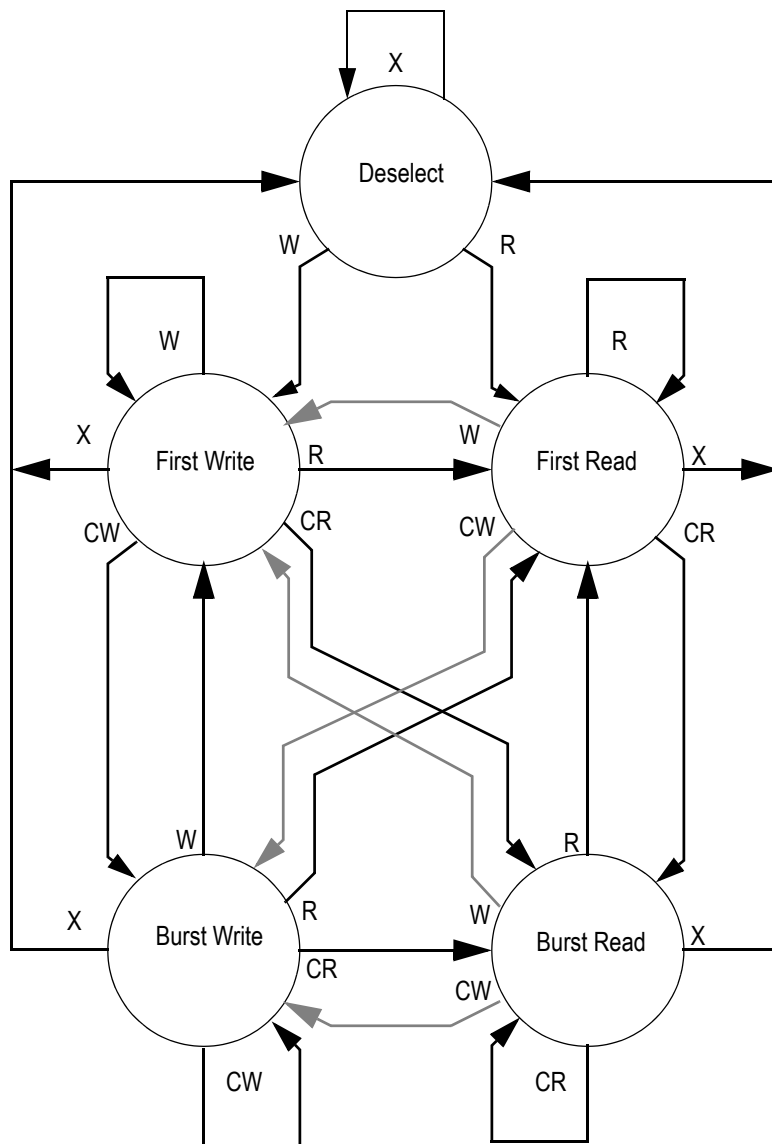
Simplified State Diagram



Notes:

1. The diagram shows only supported (tested) synchronous state transitions. The diagram presumes $\overline{G}$ is tied low.
2. The upper portion of the diagram assumes active use of only the Enable ($\overline{E1}$, $\overline{E2}$, and $\overline{E3}$) and Write ($\overline{BA}$, $\overline{BB}$, $\overline{BC}$, $\overline{BD}$, $\overline{BW}$, and $\overline{GW}$) control inputs, and that $\overline{ADSP}$ is tied high and $\overline{ADSC}$ is tied low.
3. The upper and lower portions of the diagram together assume active use of only the Enable, Write, and $\overline{ADSC}$ control inputs, and assumes $\overline{ADSP}$ is tied high and $\overline{ADV}$ is tied low.

Simplified State Diagram with $\overline{G}$



Notes:

1. The diagram shows supported (tested) synchronous state transitions plus supported transitions that depend upon the use of $\overline{G}$.
2. Use of "Dummy Reads" (Read Cycles with $\overline{G}$ High) may be used to make the transition from Read cycles to Write cycles without passing through a Deselect cycle. Dummy Read cycles increment the address counter just like normal read cycles.
3. Transitions shown in gray tone assume $\overline{G}$ has been pulsed high long enough to turn the RAM's drivers off and for incoming data to meet Data Input Set Up Time.

Absolute Maximum Ratings

(All voltages reference to V_{SS})

Symbol	Description	Value	Unit
V_{DD}	Voltage on V_{DD} Pins	−0.5 to 3.6	V
V_{DDQ}	Voltage in V_{DDQ} Pins	−0.5 to 3.6	V
$V_{I/O}$	Voltage on I/O Pins	−0.5 to $V_{DDQ} + 0.5$ (≤ 3.6 V max.)	V
V_{IN}	Voltage on Other Input Pins	−0.5 to $V_{DD} + 0.5$ (≤ 3.6 V max.)	V
I_{IN}	Input Current on Any Pin	+/−20	mA
I_{OUT}	Output Current on Any I/O Pin	+/−20	mA
P_D	Package Power Dissipation	1.5	W
T_{STG}	Storage Temperature	−55 to 125	°C
T_{BIAS}	Temperature Under Bias	−55 to 125	°C

Note:

Permanent damage to the device may occur if the Absolute Maximum Ratings are exceeded. Operation should be restricted to Recommended Operating Conditions. Exposure to conditions exceeding the Absolute Maximum Ratings, for an extended period of time, may affect reliability of this component.

Power Supply Voltage Ranges

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
1.8 V Supply Voltage	V_{DD1}	1.6	1.8	2.0	V	
1.8 V V_{DDQ} I/O Supply Voltage	V_{DDQ1}	1.6	1.8	2.0	V	

Notes:

- The part numbers of Industrial Temperature Range versions end the character "I". Unless otherwise noted, all performance specifications quoted are evaluated for worst case in the temperature range marked on the device.
- Input Under/overshoot voltage must be $-2\text{ V} > V_i < V_{DDn} + 2\text{ V}$ not to exceed 3.6 V maximum, with a pulse width not to exceed 20% tKC.

V_{DDQ} Range Logic Levels

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
V_{DD} Input High Voltage	V_{IH}	$0.6 \cdot V_{DD}$	—	$V_{DD} + 0.3$	V	1
V_{DD} Input Low Voltage	V_{IL}	-0.3	—	$0.3 \cdot V_{DD}$	V	1
V_{DDQ} I/O Input High Voltage	V_{IHQ}	$0.6 \cdot V_{DD}$	—	$V_{DDQ} + 0.3$	V	1,3
V_{DDQ} I/O Input Low Voltage	V_{ILQ}	-0.3	—	$0.3 \cdot V_{DD}$	V	1,3

Notes:

- The part numbers of Industrial Temperature Range versions end the character "I". Unless otherwise noted, all performance specifications quoted are evaluated for worst case in the temperature range marked on the device.
- Input Under/overshoot voltage must be $-2\text{ V} > V_i < V_{DDn} + 2\text{ V}$ not to exceed 3.6 V maximum, with a pulse width not to exceed 20% tKC.
- V_{IHQ} (max) is voltage on V_{DDQ} pins plus 0.3 V.

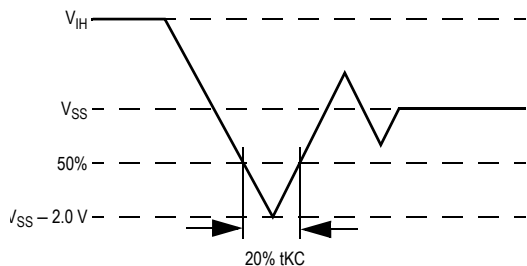
Recommended Operating Temperatures

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
Ambient Temperature (Commercial Range Versions)	T_A	0	25	70	°C	2
Ambient Temperature (Industrial Range Versions)	T_A	-40	25	85	°C	2

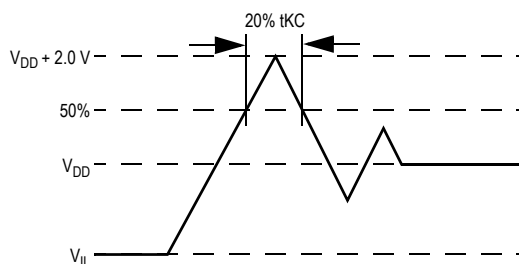
Note:

- The part numbers of Industrial Temperature Range versions end the character "I". Unless otherwise noted, all performance specifications quoted are evaluated for worst case in the temperature range marked on the device.
- Input Under/overshoot voltage must be $-2\text{ V} > V_i < V_{DDn} + 2\text{ V}$ not to exceed 3.6 V maximum, with a pulse width not to exceed 20% tKC.

Undershoot Measurement and Timing



Overshoot Measurement and Timing



Capacitance

($T_A = 25^\circ\text{C}$, $f = 1\text{ MHz}$, $V_{DD} = 2.5\text{ V}$)

Parameter	Symbol	Test conditions	Typ.	Max.	Unit
Input Capacitance	C_{IN}	$V_{IN} = 0\text{ V}$	4	5	pF
Input/Output Capacitance	$C_{I/O}$	$V_{OUT} = 0\text{ V}$	6	7	pF

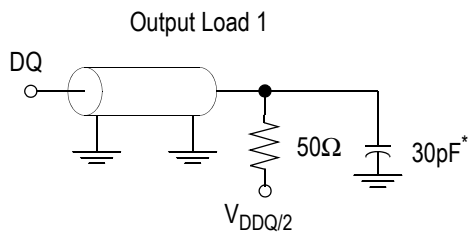
Note: These parameters are sample tested.

AC Test Conditions

Parameter	Conditions
Input high level	$V_{DD} - 0.2\text{ V}$
Input low level	0.2 V
Input slew rate	1 V/ns
Input reference level	$V_{DD}/2$
Output reference level	$V_{DDQ}/2$
Output load	Fig. 1

Notes:

1. Include scope and jig capacitance.
2. Test conditions as specified with output loading as shown in **Fig. 1** unless otherwise noted.
3. Device is deselected as defined by the Truth Table.



* Distributed Test Jig Capacitance

DC Electrical Characteristics

Parameter	Symbol	Test Conditions	Min	Max
Input Leakage Current (except mode pins)	I_{IL}	$V_{IN} = 0 \text{ to } V_{DD}$	-1 μ A	1 μ A
ZZ Input Current	I_{IN1}	$V_{DD} \geq V_{IN} \geq V_{IH}$ $0 \text{ V} \leq V_{IN} \leq V_{IH}$	-1 μ A -1 μ A	1 μ A 100 μ A
$\overline{FT}$ Input Current	I_{IN2}	$V_{DD} \geq V_{IN} \geq V_{IL}$ $0 \text{ V} \leq V_{IN} \leq V_{IL}$	-100 μ A -1 μ A	1 μ A 1 μ A
Output Leakage Current	I_{OL}	Output Disable, $V_{OUT} = 0 \text{ to } V_{DD}$	-1 μ A	1 μ A
Output High Voltage	V_{OH}	$I_{OH} = -4 \text{ mA}$, $V_{DDQ} = 1.6 \text{ V}$	$V_{DDQ} - 0.4 \text{ V}$	—
Output Low Voltage	V_{OL}	$I_{OL} = 4 \text{ mA}$, $V_{DD} = 1.6 \text{ V}$	—	0.4 V

Operating Currents

Parameter	Test Conditions	Mode	Symbol	-350		-333		-300		-250		-200		-150		Unit
				0 to 70°C	-40 to 85°C	0 to 70°C	-40 to 85°C	0 to 70°C	-40 to 85°C	0 to 70°C	-40 to 85°C	0 to 70°C	-40 to 85°C	0 to 70°C	-40 to 85°C	
Operating Current	Device Selected; All other inputs $\geq V_{IH}$ or $\leq V_{IL}$ Output open	(x32/ x36)	Pipeline	400	410	380	390	345	355	290	300	240	250	190	200	mA
			Flow Through	270	280	255	265	240	250	220	230	190	200	175	185	
		(x18)	Pipeline	360	370	340	350	310	320	260	270	215	225	170	180	mA
			Flow Through	250	260	235	245	215	225	200	210	175	185	160	170	
Standby Current	ZZ $\geq V_{DD} - 0.2$ V	—	Pipeline	40	50	40	50	40	50	40	50	40	50	40	50	mA
Deselect Current	Device Deselected; All other inputs $\geq V_{IH}$ or $\leq V_{IL}$	—	Flow Through	40	50	40	50	40	50	40	50	40	50	40	50	mA
			Pipeline	90	95	90	95	85	90	85	90	75	80	60	65	mA
Deselect Current		—	Flow Through	70	75	70	75	60	65	60	65	50	55	50	55	mA

Notes:

1. I_{DD} and I_{DDQ} apply to any combination of V_{DD3} , V_{DD2} , V_{DDQ3} , and V_{DDQ2} operation.
2. All parameters listed are worst case scenario.

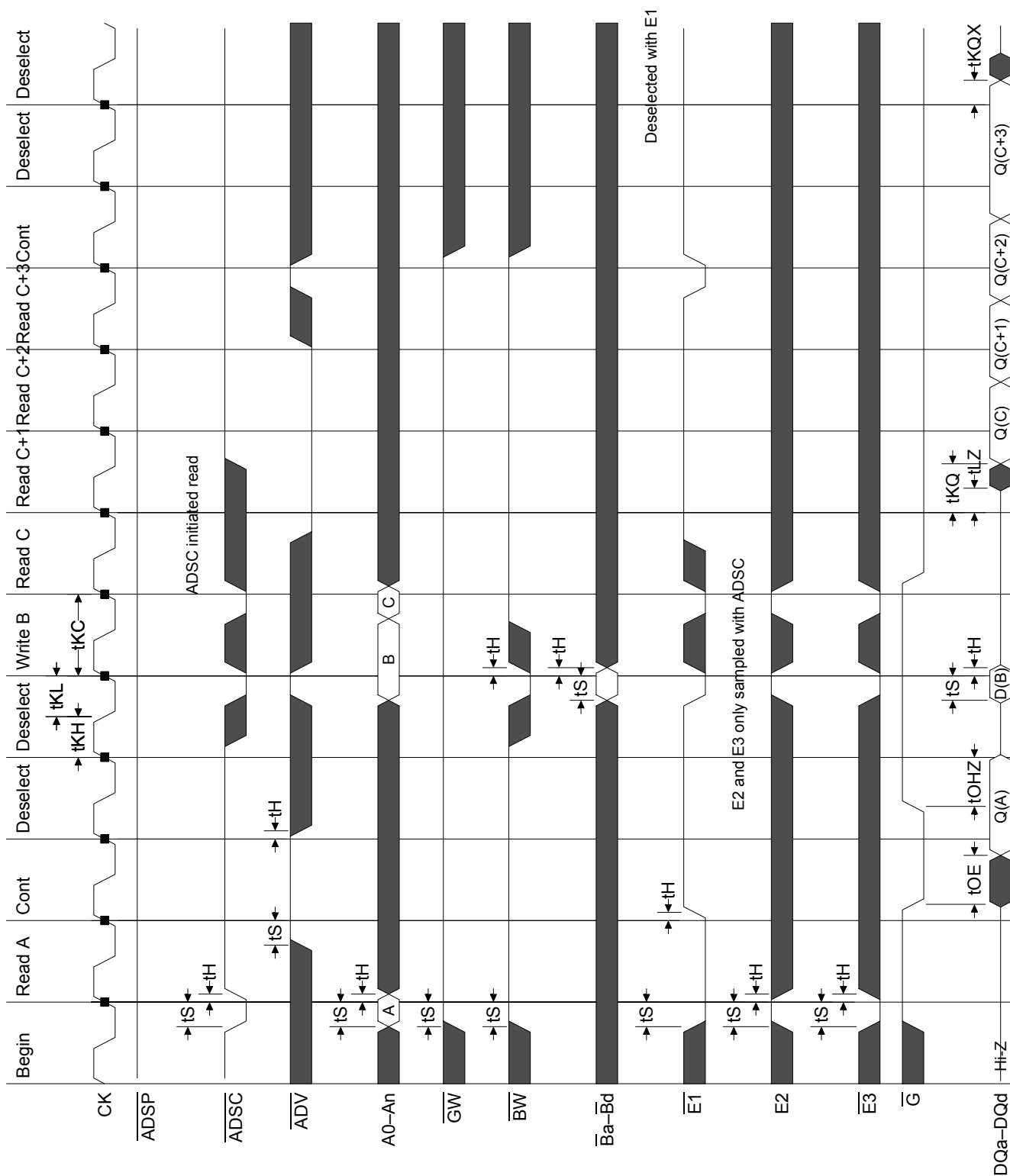
AC Electrical Characteristics

	Parameter	Symbol	-350		-333		-300		-250		-200		-150		Unit
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
Pipeline	Clock Cycle Time	t _{KC}	2.85	—	3.0	—	3.3	—	4.0	—	5.0	—	6.7	—	ns
	Clock to Output Valid	t _{KQ}	—	1.8	—	2.0	—	2.2	—	2.3	—	2.7	—	3.3	ns
	Clock to Output Invalid	t _{KQX}	1.0	—	1.0	—	1.0	—	1.0	—	1.0	—	1.0	—	ns
	Clock to Output in Low-Z	t _{LZ} ¹	1.0	—	1.0	—	1.0	—	1.0	—	1.0	—	1.0	—	ns
	Setup time	t _S	1.0	—	1.0	—	1.0	—	1.2	—	1.4	—	1.5	—	ns
	Hold time	t _H	0.1	—	0.1	—	0.1	—	0.2	—	0.4	—	0.5	—	ns
Flow Through	Clock Cycle Time	t _{KC}	4.5	—	4.7	—	5.0	—	5.5	—	6.5	—	7.5	—	ns
	Clock to Output Valid	t _{KQ}	—	4.5	—	4.7	—	5.0	—	5.5	—	6.5	—	7.5	ns
	Clock to Output Invalid	t _{KQX}	3.0	—	3.0	—	3.0	—	3.0	—	3.0	—	3.0	—	ns
	Clock to Output in Low-Z	t _{LZ} ¹	3.0	—	3.0	—	3.0	—	3.0	—	3.0	—	3.0	—	ns
	Setup time	t _S	1.3	—	1.4	—	1.4	—	1.5	—	1.5	—	1.5	—	ns
	Hold time	t _H	0.3	—	0.4	—	0.4	—	0.5	—	0.5	—	0.5	—	ns
	Clock HIGH Time	t _{KH}	1.0	—	1.0	—	1.3	—	1.3	—	1.3	—	1.5	—	ns
	Clock LOW Time	t _{KL}	1.2	—	1.2	—	1.5	—	1.5	—	1.5	—	1.7	—	ns
	Clock to Output in High-Z	t _{HZ} ¹	1.0	1.8	1.0	2.0	1.0	2.2	1.0	2.3	1.0	2.7	1.0	3.0	ns
	$\overline{G}$ to Output Valid	t _{OE}	—	1.8	—	2.0	—	2.2	—	2.3	—	2.7	—	3.3	ns
	$\overline{G}$ to output in Low-Z	t _{OLZ} ¹	0	—	0	—	0	—	0	—	0	—	0	—	ns
	$\overline{G}$ to output in High-Z	t _{OHZ} ¹	—	1.8	—	2.0	—	2.2	—	2.3	—	2.7	—	3.0	ns
	ZZ setup time	t _{ZZS} ²	5	—	5	—	5	—	5	—	5	—	5	—	ns
	ZZ hold time	t _{ZZH} ²	1	—	1	—	1	—	1	—	1	—	1	—	ns
	ZZ recovery	t _{ZZR}	20	—	20	—	20	—	20	—	20	—	20	—	ns

Notes:

- These parameters are sampled and are not 100% tested.
- ZZ is an asynchronous signal. However, in order to be recognized on any given clock cycle, ZZ must meet the specified setup and hold times as specified above.

Pipeline Mode Timing (DCD)



The timing diagram for the AD9080 illustrates the sequence of operations and associated timing parameters. The signals shown are CK, ADSP, ADSC, ADV, A0-An, GW, BW, Ba-Bd, E1, E2, E3, G, and Qa-Qd. The diagram is divided into several sections, each representing a different operation or state.

Key Timing Parameters and Events:

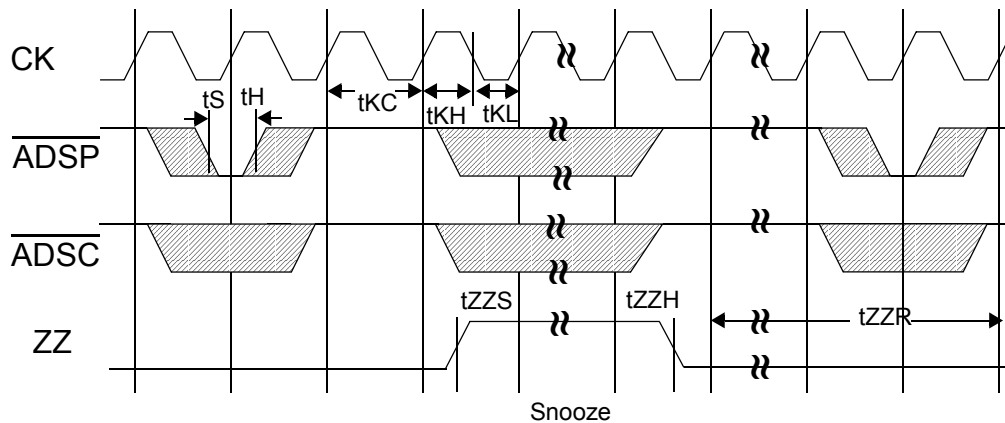
- Read A:** The first read operation, occurring after the initial setup. Timing parameters include t_S (setup time) and t_H (hold time).
- Cont:** The control signal, which is active during the Read A operation. Timing parameters include t_{KH} (hold time) and t_{KL} (low time).
- Deselect:** The signal is active during the Read A operation. Timing parameters include t_{KC} (clock-to-deselect time).
- Write B:** The second read operation, occurring after the initial setup. Timing parameters include t_S (setup time) and t_H (hold time).
- Read C:** The third read operation, occurring after the initial setup. Timing parameters include t_S (setup time) and t_H (hold time).
- Read C+1, Read C+2, Read C+3:** Subsequent read operations, each occurring after the initial setup. Timing parameters include t_S (setup time) and t_H (hold time).
- Read C:** The final read operation, occurring after the initial setup. Timing parameters include t_S (setup time) and t_H (hold time).
- ADSP:** The ADSP signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- ADSC:** The ADSC signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- ADV:** The ADV signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- A0-An:** The address signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- GW:** The GW signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- BW:** The BW signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- Ba-Bd:** The Ba-Bd signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- E1:** The E1 signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- E2:** The E2 signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- E3:** The E3 signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- G:** The G signal, which is active during the Read A operation. Timing parameters include t_S (setup time) and t_H (hold time).
- Qa-Qd:** The data signals, which are active during the Read A operation. Timing parameters include t_{OE} (output enable time), t_{KQ} (clock-to-output time), t_{LZ} (low-to-high time), t_{HZ} (high-to-low time), and t_{KQX} (clock-to-output time).

Sleep Mode

During normal operation, ZZ must be pulled low, either by the user or by its internal pull down resistor. When ZZ is pulled high, the SRAM will enter a Power Sleep mode after 2 cycles. At this time, internal state of the SRAM is preserved. When ZZ returns to low, the SRAM operates normally after ZZ recovery time.

Sleep mode is a low current, power-down mode in which the device is deselected and current is reduced to I_{SB2} . The duration of Sleep mode is dictated by the length of time the ZZ is in a High state. After entering Sleep mode, all inputs except ZZ become disabled and all outputs go to High-Z. The ZZ pin is an asynchronous, active high input that causes the device to enter Sleep mode. When the ZZ pin is driven high, I_{SB2} is guaranteed after the time t_{ZZI} is met. Because ZZ is an asynchronous input, pending operations or operations in progress may not be properly completed if ZZ is asserted. Therefore, Sleep mode must not be initiated until valid pending operations are completed. Similarly, when exiting Sleep mode during t_{ZZR} , only a Deselect or Read commands may be applied while the SRAM is recovering from Sleep mode.

Sleep Mode Timing Diagram



Application Tips

Single and Dual Cycle Deselect

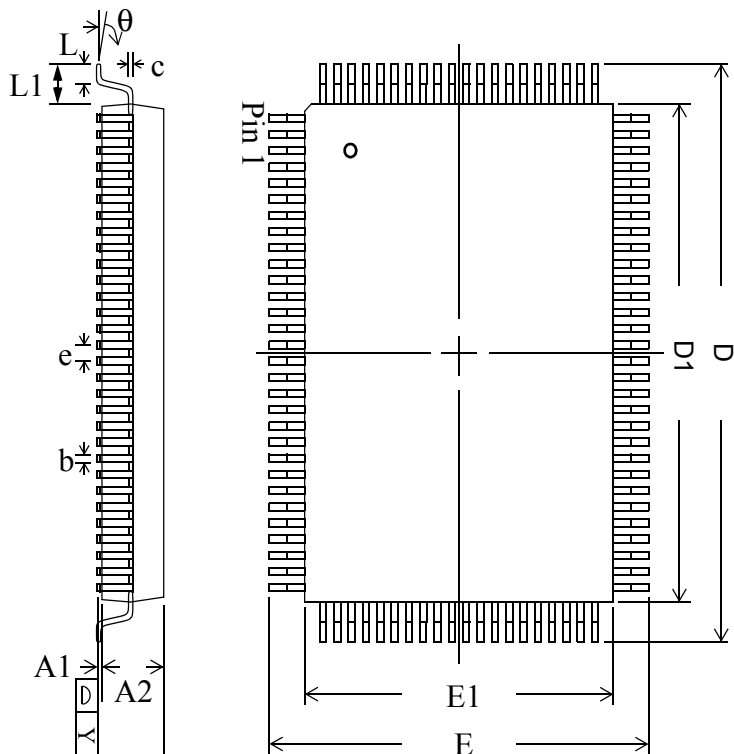
SCD devices force the use of “dummy read cycles” (read cycles that are launched normally, but that are ended with the output drivers inactive) in a fully synchronous environment. Dummy read cycles waste performance, but their use usually assures there will be no bus contention in transitions from reads to writes or between banks of RAMs. DCD SRAMs (like this one) do not waste bandwidth on dummy cycles and are logically simpler to manage in a multiple bank application (wait states need not be inserted at bank address boundary crossings), but greater care must be exercised to avoid excessive bus contention.

TQFP Package Drawing

Symbol	Description	Min.	Nom.	Max
A1	Standoff	0.05	0.10	0.15
A2	Body Thickness	1.35	1.40	1.45
b	Lead Width	0.20	0.30	0.40
c	Lead Thickness	0.09	—	0.20
D	Terminal Dimension	21.9	22.0	22.1
D1	Package Body	19.9	20.0	20.1
E	Terminal Dimension	15.9	16.0	16.1
E1	Package Body	13.9	14.0	14.1
e	Lead Pitch	—	0.65	—
L	Foot Length	0.45	0.60	0.75
L1	Lead Length	—	1.00	—
Y	Coplanarity	—	—	0.10
θ	Lead Angle	0°	—	7°

Notes:

1. All dimensions are in millimeters (mm).
2. Package width and length do not include mold protrusion.



Ordering Information for GSI Synchronous Burst RAMs

Org	Part Number ¹	Type	Package	Speed ² (MHz/ns)	T _A ³	Status
1M x 18	GS8160EV18AT-350	DCD Pipeline/Flow Through	TQFP	350/4.5	C	
1M x 18	GS8160EV18AT-333	DCD Pipeline/Flow Through	TQFP	333/4.7	C	
1M x 18	GS8160EV18AT-300	DCD Pipeline/Flow Through	TQFP	300/5	C	
1M x 18	GS8160EV18AT-250	DCD Pipeline/Flow Through	TQFP	250/5.5	C	
1M x 18	GS8160EV18AT-200	DCD Pipeline/Flow Through	TQFP	200/6.5	C	
1M x 18	GS8160EV18AT-150	DCD Pipeline/Flow Through	TQFP	150/7.5	C	
512K x 32	GS8160EV32AT-350	DCD Pipeline/Flow Through	TQFP	350/4.5	C	
512K x 32	GS8160EV32AT-333	DCD Pipeline/Flow Through	TQFP	333/4.7	C	
512K x 32	GS8160EV32AT-300	DCD Pipeline/Flow Through	TQFP	300/5	C	
512K x 32	GS8160EV32AT-250	DCD Pipeline/Flow Through	TQFP	250/5.5	C	
512K x 32	GS8160EV32AT-200	DCD Pipeline/Flow Through	TQFP	200/6.5	C	
512K x 32	GS8160EV32AT-150	DCD Pipeline/Flow Through	TQFP	150/7.5	C	
512K x 36	GS8160EV36AT-350	DCD Pipeline/Flow Through	TQFP	350/4.5	C	
512K x 36	GS8160EV36AT-333	DCD Pipeline/Flow Through	TQFP	333/4.7	C	
512K x 36	GS8160EV36AT-300	DCD Pipeline/Flow Through	TQFP	300/5	C	
512K x 36	GS8160EV36AT-250	DCD Pipeline/Flow Through	TQFP	250/5.5	C	
512K x 36	GS8160EV36AT-200	DCD Pipeline/Flow Through	TQFP	200/6.5	C	
512K x 36	GS8160EV36AT-150	DCD Pipeline/Flow Through	TQFP	150/7.5	C	
1M x 18	GS8160EV18AT-350I	DCD Pipeline/Flow Through	TQFP	350/4.5	I	
1M x 18	GS8160EV18AT-333I	DCD Pipeline/Flow Through	TQFP	333/4.7	I	
1M x 18	GS8160EV18AT-300I	DCD Pipeline/Flow Through	TQFP	300/5	I	
1M x 18	GS8160EV18AT-250I	DCD Pipeline/Flow Through	TQFP	250/5.5	I	
1M x 18	GS8160EV18AT-200I	DCD Pipeline/Flow Through	TQFP	200/6.5	I	
1M x 18	GS8160EV18AT-150I	DCD Pipeline/Flow Through	TQFP	150/7.5	I	
512K x 32	GS8160EV32AT-350I	DCD Pipeline/Flow Through	TQFP	350/4.5	I	
512K x 32	GS8160EV32AT-333I	DCD Pipeline/Flow Through	TQFP	333/4.7	I	
512K x 32	GS8160EV32AT-300I	DCD Pipeline/Flow Through	TQFP	300/5	I	
512K x 32	GS8160EV32AT-250I	DCD Pipeline/Flow Through	TQFP	250/5.5	I	
512K x 32	GS8160EV32AT-200I	DCD Pipeline/Flow Through	TQFP	200/6.5	I	
512K x 32	GS8160EV32AT-150I	DCD Pipeline/Flow Through	TQFP	150/7.5	I	

Notes:

- Customers requiring delivery in Tape and Reel should add the character "T" to the end of the part number. Example: GS8160EV18A-T.
- The speed column indicates the cycle frequency (MHz) of the device in Pipeline mode and the latency (ns) in Flow Through mode. Each device is Pipeline/Flow through mode-selectable by the user.
- T_A = C = Commercial Temperature Range. T_A = I = Industrial Temperature Range.
- GSI offers other versions this type of device in many different configurations and with a variety of different features, only some of which are covered in this data sheet. See the GSI Technology web site (www.gsistechnology.com) for a complete listing of current offerings.

Org	Part Number ¹	Type	Package	Speed ² (MHz/ns)	T _A ³	Status
512K x 36	GS8160EV36AT-350I	DCD Pipeline/Flow Through	TQFP	350/4.5	I	
512K x 36	GS8160EV36AT-333I	DCD Pipeline/Flow Through	TQFP	333/4.7	I	
512K x 36	GS8160EV36AT-300I	DCD Pipeline/Flow Through	TQFP	300/5	I	
512K x 36	GS8160EV36AT-250I	DCD Pipeline/Flow Through	TQFP	250/5.5	I	
512K x 36	GS8160EV36AT-200I	DCD Pipeline/Flow Through	TQFP	200/6.5	I	
512K x 36	GS8160EV36AT-150I	DCD Pipeline/Flow Through	TQFP	150/7.5	I	

Notes:

1. Customers requiring delivery in Tape and Reel should add the character "T" to the end of the part number. Example: GS8160EV18A-.
2. The speed column indicates the cycle frequency (MHz) of the device in Pipeline mode and the latency (ns) in Flow Through mode. Each device is Pipeline/Flow through mode-selectable by the user.
3. T_A = C = Commercial Temperature Range. T_A = I = Industrial Temperature Range.
4. GSI offers other versions this type of device in many different configurations and with a variety of different features, only some of which are covered in this data sheet. See the GSI Technology web site (www.gsistechnology.com) for a complete listing of current offerings.

18Mb Sync SRAM Datasheet Revision History

DS/DateRev. Code: Old; New	Types of Changes Format or Content	Page;Revisions;Reason
GS8160EVxxA_r1		• Creation of new datasheet