

Multiformat 11-Bit Triple DAC Video Encoder

ADV7330

FEATURES

High Definition Input Formats

8-Bit or 16-Bit (4:2:2) Parallel YCrCb Compliant with:

SMPTE 293M (525p)

BTA T-1004 EDTV2 525p

ITU-R BT.1358 (525p/625p)

ITU-R BT.1362 (525p/625p)

SMPTE 274M (1080i) at 30 Hz and 25 Hz

SMPTE 296M (720p)

Other High Definition Formats Using Async

Timing Mode

High Definition Output Formats

YPrPb Progressive Scan (EIA-770.1, EIA-770.2)

YPrPb HDTV (EIA 770.3)

RGB, RGBHV

CGMS-A (720p/1080i)

Macrovision® Rev 1.1 (525p/625p)

CGMS-A (525p)

Standard Definition Input Formats

CCIR-656 4:2:2 8-Bit or 16-Bit Parallel Input

Standard Definition Output Formats

Composite NTSC M/N

Composite PAL M/N/B/D/G/H/I, PAL-60

SMPTE 170M NTSC Compatible Composite Video

ITU-R BT.470 PAL Compatible Composite Video

S-Video (Y/C)

EuroScart RGB

Component YPrPb (Betacam, MII, SMPTE/EBU N10)

Macrovision Rev 7.1.L1

CGMS/WSS

Closed Captioning

GENERAL FEATURES

Programmable DAC Gain Control

Sync Outputs in All Modes

On-Board Voltage Reference

Three 11-Bit Precision Video DACs

2-Wire Serial I²C[®] Interface, Open Drain Configuration

Dual I/O Supply 2.5 V/3.3 V Operation

Analog and Digital Supply 2.5 V

On-Board PLL

64-Lead LQFP Package

Lead (Pb) Free Product

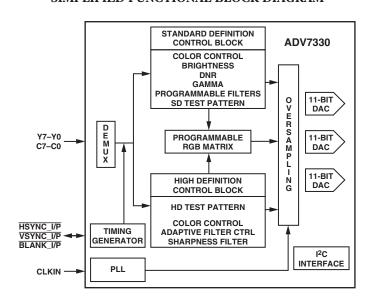
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APPLICATIONS
SD/PS DVD Recorders/Players
SD/Prog Scan/HDTV Display Devices
SD/HDTV Set Top Boxes

SIMPLIFIED FUNCTIONAL BLOCK DIAGRAM



GENERAL DESCRIPTION

The ADV®7330 is a high speed, digital-to-analog encoder on a single monolithic chip. It includes three high speed video D/A converters with TTL compatible inputs.

The ADV7330 has separate 8-bit or 16-bit input ports that accept data in high definition or standard definition video format. For all standards, external horizontal, vertical, and blanking signals or EAV/SAV timing codes control the insertion of appropriate synchronization signals into the digital data stream and therefore the output signal.

DETAILED FEATURES

High Definition Programmable Features (720p/1080i)

2× Oversampling (148.5 MHz)

Internal Test Pattern Generator

(Color Hatch, Black Bar, Flat Field/Frame)

Fully Programmable YCrCb to RGB Matrix

Gamma Correction

Programmable Adaptive Filter Control

Programmable Sharpness Filter Control

CGMS-A (720p/1080i)

Programmable Features (525p/625p)

8× Oversampling

Internal Test Pattern Generator

(Color Hatch, Black Bar, Flat Frame)

Individual Y and PrPb Output Delay

Gamma Correction

Programmable Adaptive Filter Control

Fully Programmable YCrCb to RGB/Matrix

Undershoot Limiter

Macrovision Rev 1.1 (525p/625p)

CGMS-A (525p)

Standard Definition Programmable Features

16× Oversampling

Internal Test Pattern Generator

(Colorbars, Black Bar)

Controlled Edge Rates for Sync, Active Video

Individual Y and PrPb Output Delay

Gamma Correction

Digital Noise Reduction (DNR)

Multiple Chroma and Luma Filters

Luma-SSAF™ Filter with Programmable

Gain/Attenuation

PrPb SSAF™

Separate Pedestal Control on Component and

Composite/S-Video Outputs

VCR FF/RW Sync Mode

Macrovision Rev 7.1.L1

CGMS/WSS

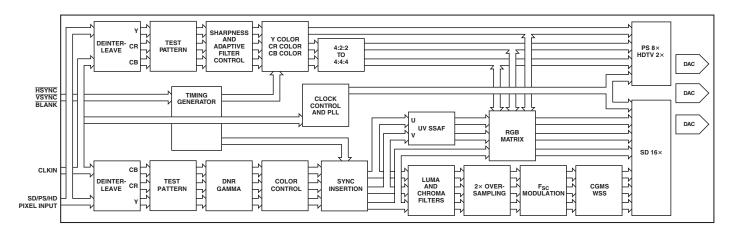
Closed Captioning

Standards Directly Supported

Resolution	Frame Rate (Hz)	Clk Input (MHz)	Standard
720×480	29.97	27	ITU-R BT.656
720×576	25	27	ITU-R BT.656
720×483	59.94	27	SMPTE 293M
720×480	59.94	27	BTA T-1004
720×576	50	27	ITU-R BT.1362
1280×720	60	74.25	SMPTE 296M
1920×1080	30	74.25	SMPTE 274M
1920×1080	25	74.25	SMPTE 274M*

Other standards are supported in Async Timing Mode.

DETAILED FUNCTIONAL BLOCK DIAGRAM



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^{*}SMPTE 274M-1998: System No. 6

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ADV7330-SPECIFICATIONS

(V_{AA} = 2.375 V to 2.625 V, V_{DD} = 2.375 V to 2.625 V; V_{DD_10} = 2.375 V to 3.6 V, V_{REF} = 1.235 V, R_{SET} = 3040 Ω , R_{LOAD} = 300 Ω . All specifications T_{MIN} to T_{MAX} (0°C to 70°C), unless otherwise noted.)

Parameter	Min	Тур	Max	Unit	Conditions
STATIC PERFORMANCE ¹ (With No Oversampling Ratio) Resolution Integral Nonlinearity Differential Nonlinearity ² , +ve Differential Nonlinearity ² , -ve		11 1.5 0.5 1.0		Bits LSB LSB LSB	
DIGITAL OUTPUTS Output Low Voltage, V _{OL} Output High Voltage, V _{OH} Three-State Leakage Current Three-State Output Capacitance	2.4 [2.0] ³	±1.0 2	0.4 [0.4] ³	V V μA pF	$I_{SINK} = 3.2 \text{ mA}$ $I_{SOURCE} = 400 \mu\text{A}$ $V_{IN} = 0.4 \text{ V}, 2.4 \text{ V}$
	2	3 2	0.8	V V μA pF	V_{IN} = 2.4 V
ANALOG OUTPUTS Full-scale Output Current Output Current Range DAC to DAC Matching Output Compliance Range, V _{OC} Output Capacitance, C _{OUT}	4.1 4.1 0	4.33 4.33 1.0 1.0	4.6 4.6 1.4	mA mA % V pF	
VOLTAGE REFERENCE Internal Reference Range, V_{REF} External Reference Range, V_{REF} V_{REF} Current ⁴	1.15 1.15	1.235 1.235 ±10	1.3 1.3	V V μA	
POWER REQUIREMENTS Normal Power Mode I_{DD}^{5} $I_{DD IO}$		170 110 95 1.0	190 ⁶	mA mA mA	SD (16x) PS (8x) HDTV (2x)
$I_{\mathrm{DD_IO}}$ $I_{\mathrm{AA}}^{7,8}$ Sleep Mode I_{DD} I_{AA} $I_{\mathrm{DD_IO}}$		24 200 10 250	28	mA μA μA μA	
Power Supply Rejection Ratio		0.01		%/%	

NOTES

Specifications subject to change without notice.

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¹Oversampling disabled. Static DAC performance will be improved with increased oversampling ratios.

²DNL measures the deviation of the actual DAC output voltage step from the ideal. For +ve DNL, the actual step value lies above the ideal step value; for -ve DNL, the actual step value lies below the ideal step value.

 $^{^{3}}$ Value in brackets for $V_{\rm DD_IO} = 2.375$ V to 2.75 V.

⁴External current required to overdrive internal V_{REF}.

⁵I_{DD}, the circuit current, is the continuous current required to drive the digital core.

⁶Guaranteed maximum by characterization.

⁷I_{AA} is the total current required to supply all DACs including the V_{REF} circuitry and the PLL circuitry.

⁸All DACs on.

Parameter	Min Typ	Max	Unit	Conditions			
PROGRESSIVE SCAN MODE							
Luma Bandwidth	12.5		MHz				
Chroma Bandwidth	5.8		MHz				
SNR	65.6		dB	Luma ramp unweighted			
	72		dB	Flat field full bandwidth			
HDTV MODE							
Luma Bandwidth	30		MHz				
Chroma Bandwidth	13.75		MHz				
STANDARD DEFINITION MODE							
Hue Accuracy	0.4		Degrees				
Color Saturation Accuracy	0.4		%				
Chroma Nonlinear Gain	1.2		±%	Referenced to 40 IRE			
Chroma Nonlinear Phase	-0.2		±Degrees				
Chroma/Luma Intermodulation	0		±%				
Chroma/Luma Gain Inequality	97.0		±%				
Chroma/Luma Delay Inequality	-1.1		ns				
Luminance Nonlinearity	0.5		±%				
Chroma AM Noise	84		dB				
Chroma PM Noise	75.2		dB				
Differential Gain	0.20		%	NTSC			
Differential Phase	0.15		Degrees	NTSC			
SNR	59.1		dB	Luma ramp			
	77.7		dB	Flat field full bandwidth			

Specifications subject to change without notice.

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ADV7330

Parameter		Тур	Max	Unit	Conditions			
MPU PORT ¹								
SCLOCK Frequency	0		400	kHz				
SCLOCK High Pulsewidth, t ₁	0.6			μs				
SCLOCK Low Pulsewidth, t ₂	1.3			μs				
Hold Time (Start Condition), t ₃	0.6			μs	After this period, the first clock is generated			
Setup Time (Start Condition), t ₄	0.6			μs	Relevant for repeated start condition			
Data Setup Time, t ₅	100			ns				
SDATA, SCLOCK Rise Time, t ₆			300	ns				
SDATA, SCLOCK Fall Time, t ₇			300	ns				
Setup Time (Stop Condition), t ₈	0.6			μs				
RESET Low Time	100			ns				
ANALOG OUTPUTS								
Analog Output Delay ²		7		ns				
Output Skew		1		ns				
CLOCK CONTROL AND PIXEL PORT ³								
f_{CLK}			27	MHz	Progressive scan mode			
f_{CLK}		81		MHz	HDTV mode/async mode			
Clock High Time, to	40			% of one clk cycle				
Clock Low Time, t ₁₀	40			% of one clk cycle				
Data Setup Time, t ₁₁ ¹	2.0			ns				
Data Hold Time, t_{12}^{1}	2.0			ns				
SD Output Access Time, t ₁₃			15	ns				
SD Output Hold Time, t ₁₄	5.0			ns				
HD Output Access Time, t ₁₃			14	ns				
HD Output Hold Time, t ₁₄	5.0			ns				
PIPELINE DELAY ⁴		63		clk cycles	SD (2×, 16×)			
		76		clk cycles	SD component mode (16×)			
		35		clk cycles	PS (1×)			
		41		clk cycles	PS (8×)			
		36		clk cycles	HD (2×, 1×)			

NOTES

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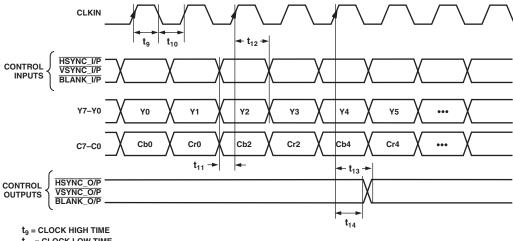
¹Guaranteed by characterization.

²Output delay measured from the 50% point of the rising edge of CLOCK to the 50% point of the DAC output full-scale transition.

 $^{^3}Data: C \ \underline{[9:0]; Y \ [9:0], S[9:0].} \\ Control: \overline{HSYNC_I/P}, \overline{VSYNC_I/P}, \overline{BLANK_I/P}, \overline{HSYNC_O/P}, \overline{VSYNC_O/P}, \overline{BLANK_O/P}.$

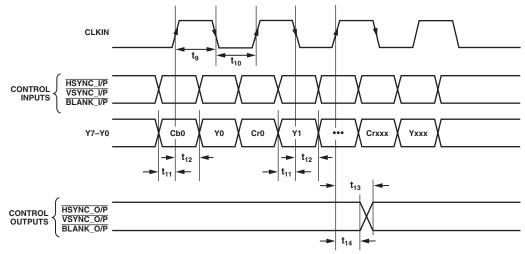
⁴SD, PS = 27 MHz, HD = 74.25 MHz.

Specifications subject to change without notice.



 t_9 = CLOCK HIGH TIME t_{10} = CLOCK LOW TIME t_{11} = DATA SETUP TIME t_{12} = DATA HOLD TIME

Figure 1. HD/PS 4:2:2 Input Mode (HD: Input Mode 010) (PS: Input Mode 001)



 $\begin{array}{l} t_9 = \text{CLOCK HIGH TIME} \\ t_{10} = \text{CLOCK LOW TIME} \\ t_{11} = \text{DATA SETUP TIME} \\ t_{12} = \text{DATA HOLD TIME} \end{array}$

Figure 2. PS 4:2:2 1× 8-Bit Interleaved at 27 MHz Hsync/Vsync Input Mode (Input Mode 100)

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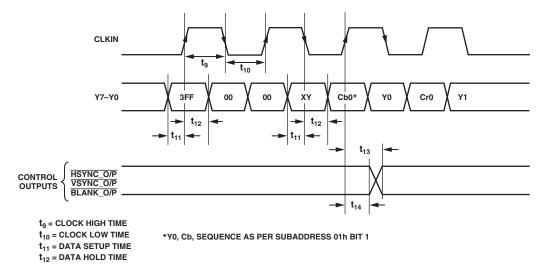
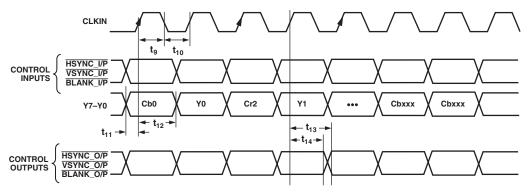


Figure 3. PS 4:2:2 1× 8-Bit Interleaved at 27 MHz EAV/SAV Input Mode (Input Mode 100)



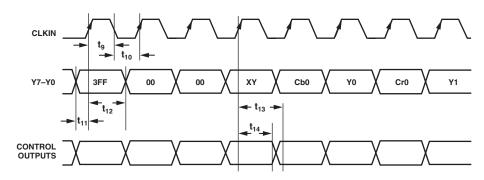
 t_9 = CLOCK HIGH TIME

t₁₀ = CLOCK LOW TIME

t₁₁ = DATA SETUP TIME

t₁₂ = DATA HOLD TIME

Figure 4. PS 4:2:2 1× 8-Bit Interleaved at 54 MHz Hsync/Vsync I/P Mode (Input Mode 011)



 $\begin{array}{l} t_9 = \text{CLOCK HIGH TIME} \\ t_{10} = \text{CLOCK LOW TIME} \\ t_{11} = \text{DATA SETUP TIME} \\ t_{12} = \text{DATA HOLD TIME} \end{array}$

Figure 5. PS 4:2:2 1× 8-Bit Interleaved at 54 MHz EAV/SAV Input Mode (Input Mode 011)

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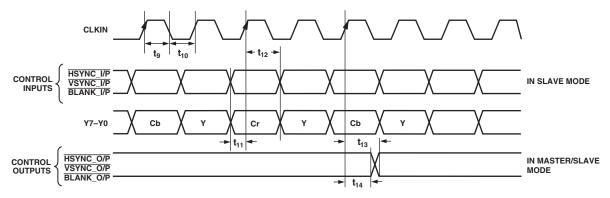


Figure 6. 8-Bit SD Pixel Input Mode (Input Mode 000)

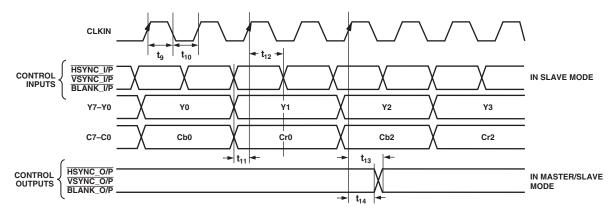


Figure 7. 16-Bit SD Pixel Input Mode (Input Mode 000)

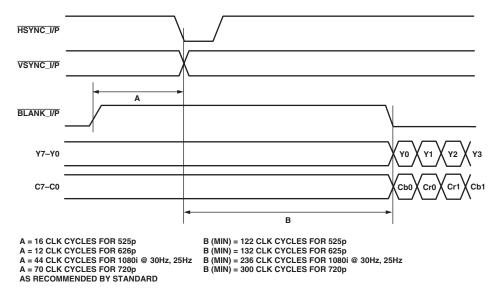


Figure 8. HD 4:2:2 Input Timing Diagram

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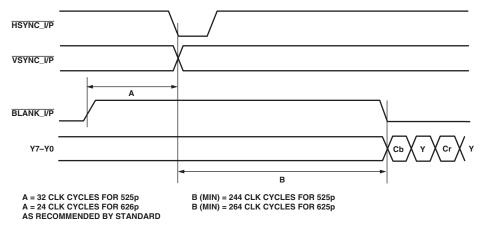


Figure 9. PS 4:2:2, 1×8 -Bit Interleaved Input Timing Diagram

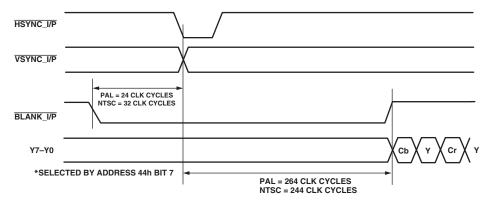


Figure 10. SD Timing Input for Timing Mode 1

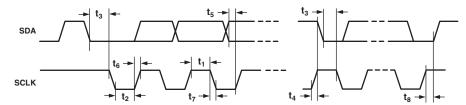


Figure 11. MPU Port Timing Diagram

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ABSOLUTE MAXIMUM RATINGS1, 2

V_{AA} to AGND
V_{DD} to DGND0.3 V to +3.0 V
$V_{DD\ IO}$ to GND_IO
Digital Input Voltage to DGND \dots -0.3 V to $V_{DD IO}$ + 0.3 V
V_{AA} to V_{DD}
AGND to DGND
DGND to GND_IO
AGND to GND_IO0.3 V to +0.3 V
Ambient Operating Temperature (T _A) 0°C to 70°C
Storage Temperature (T_S)65°C to +150°C
Infrared Reflow Soldering (20 secs) 260°C
NOTES

¹ Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those listed in the operational section of this specification is not implied. Exposure to absolute maximum ratings for extended periods may affect device reliability.

THERMAL CHARACTERISTICS

 $\theta_{\rm JC} = 11^{\circ} \rm C/W$

 $\theta_{\rm JA} = 47^{\circ} \rm C/W$

The ADV7330 is a Pb-free, environmentally friendly product. It is manufactured using the most up-to-date materials and processes. The coating on the leads of each device is 100% pure Sn electroplate. The device is suitable for Pb-free applications, and is able to withstand surface-mount soldering at up to 255° C ($\pm 5^{\circ}$ C).

In addition, it is backward compatible with conventional SnPb soldering processes. This means that the electroplated Sn coating can be soldered with Sn/Pb solder pastes at conventional reflow temperatures of 220°C to 235°C.

ORDERING GUIDE

Model	Temperature Range	Package Description	Package Option		
ADV7330KST	0°C to 70°C	Low Profile Quad Flat Package	ST-64-2		

CAUTION _

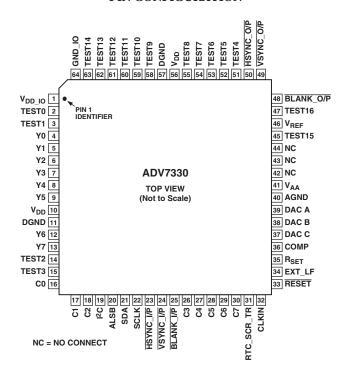
ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the ADV7330 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



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² Analog output short circuit to any power supply or common can be of an indefinite duration.

PIN CONFIGURATION



PIN FUNCTION DESCRIPTIONS

Pin Number	Mnemonic	I/O	Function
11, 57	DGND	G	Digital Ground.
2, 3, 14, 15, 51–55, 58–63	TEST0-TEST14	I	Not used, tie to DGND.
40	AGND	G	Analog Ground.
32	CLKIN	I	Pixel Clock Input for HD (74.25 MHz Only, PS (27 MHz), SD (27 MHz)).
36	COMP	О	Compensation Pin for DACs. Connect 0.1 μF capacitor from COMP pin to V_{AA} .
39	DAC A	О	CVBS/GREEN/Y Analog Output.
38	DAC B	О	Chroma/BLUE/Pb Analog Output.
37	DAC C	О	Luma/RED/Pr Analog Output.
25	BLANK_I/P	I	Video Blanking Control Signal. For HD and PS, this input is active high. For SD input, this input is active low.
23	HSYNC_I/P	I	Video Horizontal Sync Control Signal.
24	VSYNC_I/P	I	Video Vertical Sync Control Signal.
4–9, 12, 13	Y7-Y0	I	SD or Progressive Scan/HDTV Input Port for Y Data. Input port for interleaved progressive scan data. The LSB is set up on Pin Y0.
16-18, 26-30	C7-C0	I	8-Bit SD/Progressive Scan/HDTV Input Port. The LSB is set up on Pin C0.
33	RESET	I	This input resets the on-chip timing generator and sets the ADV7330 into the default register setting. Reset is an active low signal.
35	R _{SET}	I	A 3040 Ω resistor must be connected from this pin to AGND and is used to control the amplitudes of the DAC outputs.
22	SCLK	I	I ² C Port Serial Interface Clock Input.
21	SDA	I/O	I ² C Port Serial Data Input/Output.
20	ALSB	I	TTL Address Input. This signal sets up the LSB of the I^2C address. When this pin is tied low, the I^2C filter is activated, which reduces noise on the I^2C interface.
1	$V_{\mathrm{DD_IO}}$	P	Power Supply for Digital Inputs and Outputs.

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PIN FUNCTION DESCRIPTIONS (continued)

Pin Number	Mnemonic	I/O	Function
10, 56	V_{DD}	P	Digital Power Supply.
41	V_{AA}	P	Analog Power Supply.
45, 47	TEST15, TEST16	О	Not used, do not connect.
34	EXT_LF	I	External Loop Filter for the Internal PLL.
31	RTC_SCR_TR	I	Multifunctional Input: Real-Time Control (RTC) Input, Timing Reset Input, Subcarrier Reset Input.
48	BLANK_O/P	О	Video Blanking Control Signal. For HD and PS, this input is active high. For SD input, this output is active low.
50	HSYNC_O/P	О	Video Horizontal Sync Control Signal.
49	VSYNC_O/P	О	Video Vertical Sync Control Signal.
19	I ² C	I	This input pin must be tied high (V_{DD_IO}) for the ADV7330 to interface over the I^2C port.
64	GND_IO		Digital Input/Output Ground.
42-44	NC		No Connect.
46	$V_{ m REF}$	I/O	Optional External Voltage Reference Input for DACs or Voltage Reference Output (1.235 V).

TERMINOLOGY

SD	Standard definition video, conforming to ITU-R
	BT.601/656.
HD	High definition video, such as progressive scan or HDTV.
PS	Progressive scan video, conforming to SMPTE 293M,
	ITU-R BT.1358, BTA T-1004EDTC2, BTA1362

HDTV High definition television video, conforming to SMPTE 274M or SMPTE 296M.

YCrCb SD, PS, or HD component digital video. YPrPb SD, PS, or HD component analog video.

MPU PORT DESCRIPTION

The ADV7330 supports a 2-wire serial (I²C compatible) microprocessor bus driving multiple peripherals. This bus operates in an Open Drain configuration. Two inputs, serial data (SDA) and serial clock (SCL), carry information between any devices connected to the bus. Each slave device is recognized by a unique address. The ADV7330 has four possible slave addresses for both read and write operations. These are unique addresses for each device and are illustrated in Figure 12. The LSB sets either a read or write operation. Logic 1 corresponds to a read operation, while Logic 0 corresponds to a write operation. A1 is set by setting the ALSB pin of the ADV7330 to Logic 0 or Logic 1. When ALSB is set to 1, there is greater input bandwidth on the I²C lines, which allows high speed data transfers on this bus. When ALSB is set to 0, there is reduced input bandwidth on the I²C lines, which means that pulses of less than 50 ns will not pass into the I²C internal controller. This mode is recommended for noisy systems.

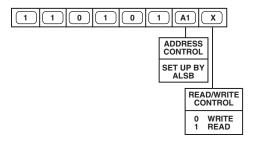


Figure 12. ADV7330 Slave Address = D4h

To control the various devices on the bus, the following protocol must be followed. First the master initiates a data transfer by establishing a start condition, defined by a high-to-low transition on SDA, while SCL remains high. This indicates that an address/data stream will follow. All peripherals respond to the start condition and shift the next eight bits (7-bit address + R/\overline{W} bit). The bits are transferred from MSB down to LSB. The peripheral that recognizes the transmitted address responds by pulling the data line low during the ninth clock pulse. This is known as an acknowledge bit. All other devices withdraw from the bus at this point and maintain an idle condition. The idle condition is when the device monitors the SDA and SCL lines waiting for the start condition and the correct transmitted address. The R/\overline{W} bit determines the direction of the data.

A Logic 0 on the LSB of the first byte means that the master will write information to the peripheral. A Logic 1 on the LSB of the first byte means that the master will read information from the peripheral.

The ADV7330 acts as a standard slave device on the bus. The data on the SDA pin is eight bits long, supporting the 7-bit addresses plus the R/\overline{W} bit. It interprets the first byte as the device address and the second byte as the starting subaddress. There is a subaddress auto-increment facility. This allows data to be written to or read from registers in ascending subaddress sequence, starting at any valid subaddress. A data transfer is always terminated by a stop condition. The user can also access any unique subaddress register on a one-by-one basis without having to update all the registers.

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Stop and start conditions can be detected at any stage during the data transfer. If these conditions are asserted out of sequence with normal read and write operations, they cause an immediate jump to the idle condition. During a given SCL high period, the user should issue only one start condition, one stop condition, or a single stop condition followed by a single start condition. If an invalid subaddress is issued by the user, the ADV7330 will not issue an acknowledge and will return to the idle condition. If in auto-increment mode the user exceeds the highest subaddress, the following action will be taken:

- In read mode, the highest subaddress register contents will continue to be output until the master device issues a no acknowledge. This indicates the end of a read. A no acknowledge condition is when the SDA line is not pulled low on the ninth pulse.
- In write mode, the data for the invalid byte will not be loaded into any subaddress register, a no acknowledge will be issued by the ADV7330, and the part will return to the idle condition.

Before writing to the subcarrier frequency registers, it is a requirement that the ADV7330 reset at least once after power-up.

The four subcarrier frequency registers must be updated starting with subcarrier frequency register 0 through subcarrier frequency register 3. The subcarrier frequency will not update until the

last subcarrier frequency register byte has been received by the ADV7330.

Figure 13 illustrates an example of data transfer for a write sequence and the start and stop conditions. Figure 14 shows bus write and read sequences.

REGISTER ACCESS

The MPU can write to or read from all of the registers of the ADV7330 except the subaddress registers that are write-only registers. The subaddress register determines which register the next read or write operation accesses. All communications with the part go through the bus start with an access to the subaddress register. Then a read/write operation is performed from/to the target address, which then increments to the next address until a stop command on the bus is performed.

Register Programming

The following tables describe the functionality of each register. All registers can be read from as well as written to, unless otherwise stated.

Subaddress Register (SR7-SR0)

The communications register is an 8-bit write-only register. After the part has been accessed over the bus and a read/write operation is selected, the subaddress is set up. The subaddress register determines to/from which register the operation takes place.



Figure 13. Bus Data Transfer

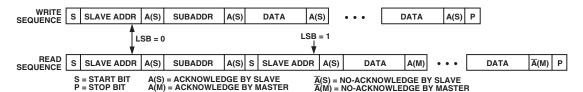


Figure 14. Write and Read Sequence

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SR7- SR0	Register	Bit Description	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register Setting	Register Reset Values (Shaded)	
00h	Power Mode	Sleep Mode. With this control enabled, the current consumption is reduced to μA level. All DACs and the internal PLL cct are disabled. I ² C registers can be read from and written to in sleep mode.								0	Sleep Mode Off	FCh	
										1	Sleep Mode On		
		PLL and Oversampling Control. This control allows the internal PLL cct to be powered down and the oversampling to be switched off.							0		PLL On		
									1		PLL Off		
		DAC C. Power On/Off.						0			DAC C Off		
								1			DAC C On		
		DAC B. Power On/Off. DAC A. Power On/Off.					0				DAC B Off		
							1				DAC B On		
						0					DAC A Off		
						1					DAC A On		
			X	X	X							Reserved	
01h	Input Mode	BTA T-1004 or BT 1362								0	Disabled	Only for PS dual-	
		Compatibility.								1	Enabled	edge clk mode	
		Clock Edge							0		Cb Clocked on Rising Edge	Only for PS interleaved input at	
									1		Y Clocked on Rising Edge	27 MHz	
		Reserved						0					
		Reserved					0						
		Input Mode		0	0	0					SD Input	38h	
				0	0	1					PS Input		
				0	1	0				$ldsymbol{ldsymbol{ldsymbol{eta}}}$	HDTV Input		
				0	1	1	├─	Ь—		\vdash	PS 54 MHz Input		
				1	0	0	├─	Ь—			PS 27 MHz Input		
				1	0	1	<u> </u>	ـــــ			Reserved		
				1	1	0					Reserved		
				1	1	1					Reserved		
1		Reserved	0										

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SR7- SR0	Register	Bit Description	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register Setting	Reset Values
02h	Mode Register 0	Reserved							0	0	Zero must be written to these bits	20h
		Test Pattern Black Bar						0			Disabled	11h, Bit 2 must
								1			Enabled	also be enabled
		RGB Matrix					0				Disable Programmable RGB Matrix	
							1				Enable Programmable RGB Martix	
		Sync on RGB ¹				0					No Sync	
						1					Sync on all RGB Outputs	
		RGB/YUV Output			0						RGB component Outputs YUV component	
					1						YUV component Outputs	
		SD Sync	-	0							No Sync Output	
				1							Output SD Syncs on HSYNC_O/P, VSYNC_O/P,	
		TID C									BLANK_O/P	
		HD Sync	1								No Sync Output Output HD Syncs on HSYNC_O/P,	
											VSYNC_O/P, BLANK_O/P	
03h	RGB Matrix 0		-						x	х	LSB for GY	03h
04h	RGB Matrix 1								х	х	LSB for RV	F0h
							х	х			LSB for BU	
					х	X					LSB for GV	
			X	х							LSB for GU	
05h	RGB Matrix 2		х	х	х	X	х	х	X	х	Bit 9–2 for GY Bit 9–2 for GU	4Eh 0Eh
06h 07h	RGB Matrix 3 RGB Matrix 4		X X	X X	x x	X X	X X	X X	x x	X X	Bit 9–2 for GU Bit 9–2 for GV	24h
08h	RGB Matrix 5		X	X	X	X	X	X	X	X	Bit 9–2 for BU	92h
09h	RGB Matrix 6		x	X	x	X	x	x	X	х	Bit 9–2 for RV	7Ch
0Ah			х	х	х	х	x	х	х	х	Reserved	
0Bh	DAC A,B,C Output Level ²	Positive Gain to DAC Output Voltage	0	0	0	0	0	0	0	0	0%	00h
			0	0	0	0	0	0	0	1	0.018%	
			0	0	0	0	0	0	1	0	0.036%	
			0	0	1	1	1	1	1	1	7.382%	
			0	1	0	0	0	0	0	0	7.5%	
		Negative Gain to DAC Output Voltage	1	1	0	0	0	0	0	0	-7.5%	
			1	1	0	0	0	0	0	1	-7.382%	
			1	0	0	0	0	0	1	0	-7.364%	
									<u> </u>			
			1	1	1	1	1	1	1	1	-0.018%	
0Ch		Reserved										00h
0Dh		Reserved								\perp		00h
0Eh		Reserved										00h
0Fh		Reserved										00h

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NOTES 1 For more detail, refer to Appendix 7. 2 For more detail on the programmable output levels, refer to the Programmable DAC Gain Control section.

SR7- SR0	Register	Bit Description	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register Setting	Reset Values
10h	HD Mode Register 1	HD Output Standard							0	0	EIA770.2 Output	00h
									0	1	EIA770.1 Output	
									1	0	Output levels for Full Input	
			<u> </u>					-	1	1	Range Reserved	
		HD Input Control Signals	+				0	0	1	1		
		11D input Control Signals									HSYNC, VSYNC, BLANK	
							0	1			EAV/SAV codes	
							1	0			Async Timing Mode	
		TID COS	 				1	1		\vdash	Reserved	
		HD 625p	-			0		-	-	\vdash	525p	
		HD 720p	-		0	1		 	-	\vdash	625p 1080i	
		HD 720p	-		1			-	-	\vdash	720p	
		HD BLANK Polarity	+	0	1	-	_	-	-	\vdash	BLANK Active High	
		TID BEAUTY County		1		 		1	_	\vdash	BLANK Active Low	
		HD Macrovision for 525p/625p	0								Macrovision Off	
										\vdash	Macrovision On	
11h	HD Mode Register 2	HD Pixel Data Valid								0	Pixel Data Valid Off	00h
								1		1	Pixel Data Valid On	
									0	1	Reserved	
		HD Test Pattern Enable	1					0			HD Test Pattern Off	
								1			HD Test Pattern On	
		HD Test Pattern Hatch/Field	1				0				Hatch	
							1				Field/Frame	
		HD VBI Open				0					Disabled	
						1					Enabled	
		HD Undershoot Limiter		0	0						Disabled	
				0	1						-11 IRE	
				1	0						−6 IRE	
				1	1						-1.5 IRE	
		HD Sharpness Filter	0								Disabled	
		_	1					1			Enabled	
			1	1				1	1			

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SR7- SR0	Register	Bit Description	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register Setting	Reset Values
12h	HD Mode Register 3	HD Y Delay with respect to falling						0	0	0	0 Clk Cycle	00h
		edge of HSYNC						0	0	1	1 Clk Cycle	
								0	1	0	2 Clk Cycles	
								0	1	1	3 Clk Cycles	
							_	1	0	0	4 Clk Cycles	
		HD Color Delay with respect to			0	0	0				0 Clk Cycle	
		falling edge of HSYNC			0	0	1				1 Clk Cycle	
					0	1	0				2 Clk Cycles	
					0	1	1				3 Clk Cycles	
		TID COLIG			1	0	0				4 Clk Cycles	
		HD CGMS	-	0							Disabled Enabled	-
		HD CGMS CRC	0	1							Disabled	+
		HD CGIVIS CKC	1								Enabled	+
13h	HD Mode Register 4	HD Cr/Cb Sequence	1							0	Cb after Falling Edge of HSYNC	4Ch
		HD CI/CB Sequence								1	Cr after Falling Edge of HSYNC	
		Reserved	1						0	<u> </u>	0 must be written to this bit.	
		Reserved	1					0	0		0 must be written to this bit.	
		Sinc Filter on DAC A, B, C	1				0	0			Disabled	+
		Sinc Finer on Briefi, B, G					1				Enabled	+
		Reserved	1			0	-				0 must be written to this bit.	
		HD Chroma SSAF	1		0						Disabled	
					1						Enabled	
		Reserved	1	1								
		HD Double Buffering	0								Disabled	
		_	1								Enabled	1
14h	HD Mode Register 5	HD Timing Reset								х	A low-high-low transition resets the internal HD timing counters.	00h
		1000; F B						0	0		30 Hz/2200 Total Samples/Line	_
		1080i Frame Rate						0	1		25 Hz/2640 Total Samples/Line	
		Reserved			0	0	0				0 must be written to these bits.	
		HD Vsync/Field Input		0							Field Input	
				1							Vsync Input	
		Lines/Frame ¹	0								Update Field/Line Counter	_
			1								Field/Line Counter Free Running	1
15h	HD Mode Register 6	Reserved								0	0 must be written to this bit.	00h
		HD RGB Input							0		Disabled	
		I II NOD III II							1		Enabled	1
		HD Sync on PrPb						0			Disabled	
								1			Enabled	1
		HD Color DAC Swap					0				DAC E = Pr; DAC F = Pb	1
							1				DAC E = Pb; DAC F = Pr	
		HD Gamma Curve A/B				0					Gamma Curve A	
		HD Gamma Curve Enable	+		0	1					Gamma Curve B	
		HD Gamma Curve Enable	-	_	1				_		Disabled Enabled	4
		HD Adaptive Filter Mode	+	0	1				-	<u> </u>	Mode A	
		The reaptive I met wiode	H	1							Mode B	+
		HD Adaptive Filter Enable	0	<u> </u>							Disabled	
			1								Enabled	1
	l	1	1								·· · · · · · · · · · · · · · · · · · ·	<u> </u>

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¹When set to 0, the line and field counters automatically wrap around at the end of the field/frame of the standard selected. When set to 1, the field/line counters are free running and wrap around when external sync signals indicate so.

SR7- SR0	Register	Bit Description	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register Setting	Reset Values
16h	HD Y Level ¹		х	х	х	x	х	х	х	х	Y Color Value	A0h
17h	HD Cr Level ¹		х	х	х	x	х	х	х	х	Cr Color Value	80h
18h	HD Cb Level ¹		x	x	х	x	х	X	х	х	Cb Color Value	80h
19h		Reserved										00h
1Ah		Reserved										00h
1Bh		Reserved										00h
1Ch		Reserved										00h
1Dh		Reserved										00h
1Eh		Reserved										00h
1Fh		Reserved										00h
20h	HD Sharpness Filter	HD Sharpness Filter Gain Value A					0	0	0	0	Gain A = 0	00h
	Gain						0	0	0	1	Gain A = +1	
												1
							0	1	1	1	Gain A = +7	Ī
							1	0	0	0	Gain A = -8	İ
												İ
							1	1	1	1	Gain A = -1	İ
		HD Sharpness Filter Gain Value B	0	0	0	0					Gain B = 0	
			0	0	0	1					Gain B = +1	İ
			<u></u>									†
			0	1	1	1					Gain B = +7	İ
			1	0	0	0					Gain B = -8	†
			<u> </u>	_								İ
			1	1	1	1					Gain B = -1	†
21h	HD CGMS Data 0	HD CGMS Data Bits	0	0	0	0	C19	C18	C17	C16	CGMS 19–16	00h
22h	HD CGMS Data 1	HD CGMS Data Bits	C15	C14	C13	C12	C11	C10	C9	C8	CGMS 15–8	00h
23h	HD CGMS Data 2	HD CGMS Data Bits	C7	C6	C5	C4	C3	C2	C1	C0	CGMS 7-0	00h
24h	HD Gamma A	HD Gamma Curve A Data Points	x	x	x	x	x	x	x	x	A0	00h
25h	HD Gamma A	HD Gamma Curve A Data Points	x	x	x	x	x	x	x	x	A1	00h
26h	HD Gamma A	HD Gamma Curve A Data Points	x	x	x	x	x	x	x	x	A2	00h
27h	HD Gamma A	HD Gamma Curve A Data Points	x	x	x	x	x	x	x	x	A3	00h
28h	HD Gamma A	HD Gamma Curve A Data Points	x	х	х	x	х	х	х	х	A4	00h
29h	HD Gamma A	HD Gamma Curve A Data Points	x	x	x	x	x	x	x	x	A5	00h
2Ah	HD Gamma A	HD Gamma Curve A Data Points	x	х	х	x	х	х	х	х	A6	00h
2Bh	HD Gamma A	HD Gamma Curve A Data Points	x	x	x	x	x	x	x	x	A7	00h
2Ch	HD Gamma A	HD Gamma Curve A Data Points	X	x	x	x	x	X	x	X	A8	00h
2Dh	HD Gamma A	HD Gamma Curve A Data Points	x	x	x	x	x	x	x	x	A9	00h
2Eh	HD Gamma B	HD Gamma Curve B Data Points	X	x	x	x	x	X	x	X	B0	00h
2Fh	HD Gamma B	HD Gamma Curve B Data Points	x	x	x	x	x	x	x	x	B1	00h
30h	HD Gamma B	HD Gamma Curve B Data Points	X	x	x	x	X	X	x	X	B2	00h
31h	HD Gamma B	HD Gamma Curve B Data Points	x	x	x	X	X	x	X	x	B3	00h
32h	HD Gamma B	HD Gamma Curve B Data Points	X	X	X	X	X	X	X	X	B4	00h
33h	HD Gamma B	HD Gamma Curve B Data Points	X	X	x	X	x	X	x	X	B5	00h
2211	HD Gamma B	HD Gamma Curve B Data Points	x	X	X	X	X	X	X	X	B6	00h
34h		1 Camma Carve D Data I Ollits	Α	А			_					
34h 35h	HD Gamma B	HD Gamma Curve B Data Points	v	v	v	v	v	v	v	v	l R7	I 00h
34h 35h 36h	HD Gamma B HD Gamma B	HD Gamma Curve B Data Points HD Gamma Curve B Data Points	x x	x x	x x	x x	x x	x x	x x	x x	B7 B8	00h 00h

NOTES ¹For the internal test pattern only.

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SR7- SR0	Register	Bit Description	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register Setting	Reset Values
38h	HD Adaptive Filter	HD Adaptive Filter Gain 1					0	0	0	0	Gain A = 0	00h
	Gain 1	Value A					0	0	0	1	Gain A = +1	
												1
							0	1	1	1	Gain $A = +7$	1
							1	0	0	0	Gain A = -8	1
												1
							1	1	1	1	Gain A = −1	
		HD Adaptive Filter Gain 1	0	0	0	0					Gain B = 0	1
		Value B	0	0	0	1					Gain B = +1	1
]
			0	1	1	1					Gain B = +7	
			1	0	0	0					Gain $B = -8$]
			1	1	1	1					Gain B = −1	
39h	HD Adaptive Filter	HD Adaptive Filter Gain 2					0	0	0	0	Gain A = 0	00h
	Gain 2	Value A					0	0	0	1	Gain $A = +1$	1
												1
							0	1	1	1	Gain $A = +7$	
							1	0	0	0	Gain A = -8]
							1	1	1	1	Gain $A = -1$	
		HD Adaptive Filter Gain 2	0	0	0	0					Gain B = 0	
		Value B	0	0	0	1					Gain B = +1	1
												1
			0	1	1	1					Gain B = +7	1
			1	0	0	0					Gain B = -8	1
												1
			1	1	1	1					Gain B = -1	1
3Ah	HD Adaptive Filter	HD Adaptive Filter Gain 3					0	0	0	0	Gain A = 0	00h
	Gain 3	Value A					0	0	0	1	Gain $A = +1$	
							l					1
							0	1	1	1	Gain A = +7	1
							1	0	0	0	Gain A = -8	1
							l					1
							1	1	1	1	Gain A = -1	1
		HD Adaptive Filter Gain 3	0	0	0	0					Gain B = 0	
		Value B	0	0	0	1					Gain B = +1	1
												1
			0	1	1	1					Gain B = +7	1
			1	0	0	0					Gain B = -8	
												1
			1	1	1	1					Gain B = −1	1
3Bh	HD Adaptive Filter Threshold A	HD Adaptive Filter Threshold A Value	х	х	х	х	х	х	х	х	Threshold A	00h
3Ch	HD Adaptive Filter	HD Adaptive Filter Threshold B	x	х	x	х	х	x	х	х	Threshold B	00h
	Threshold B	Value	F			-	†	<u> </u>				
3Dh	HD Adaptive Filter	HD Adaptive Filter Threshold C	x	х	х	х	х	х	х	х	Threshold C	00h
	Threshold C	Value	T			<u> </u>	<u> </u>		-	<u> </u>		

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SEB	00h 00h
Abb	00h
A	
SD Luma Filter	00h
SD Luma Filter	
SD Luma Filter	\neg
A	
A	
A	
A	
A	
A	
SD Chroma Filter	_
SD Chroma Filter	
SD Chroma Filter	
Althorse	
A	_
O	-
1	-
A	
1	
1	
Althors	
A2h	00h
SD DAC Output 1	08h
SD DAC Output 1	0811
SD DAC Output 2	\longrightarrow
SD DAC Output 2	
SD Pedestal	
SD Pedestal	
SD Square Pixel	
SD Square Pixel	
SD VCR FF/RW Sync	
SD VCR FF/RW Sync	
1	
SD Pixel Data Valid	
1	
SD SAV/EAV Step Edge Control 0	
1	
43h SD Mode Register 2 SD Pedestal YPrPb Output 0 No Pedestal on YPrPb 1 7.5 IRE Pedestal on YPrPb	
1 7.5 IRE Pedestal on YPrPb	
III III III III III III III III III II	00h
CD O word I work V	
SD Output Levels Y 0 Y = 700 mV/300 mV	
1 Y = 714 mV/286 mV	
SD Output Levels PrPb 0 0 0 700 mV p-p (PAL); 1000 mV p-p (NTSO	
0 1 700 mV p-p	
1 0 1000 mV p-p	
1 1 648 mV p-p	
SD VBI Open 0 Disabled	
1 Enabled	
SD CC Field Control 0 0 CC Disabled	
0 1 CC on Odd Field Only	
1 0 CC on Even Field Only	\dashv
1 1 CC on Both Fields	_

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SR7- SR0	Register	Bit Description	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register Setting	Reset Values
44h	SD Mode Register 3	SD VSYNC-3H								0	Disabled	00h
										1	$\overline{\text{VSYNC}}$ = 2.5 Lines (PAL) $\overline{\text{VSYNC}}$ = 3 Lines (NTSC)	
		SD RTC/TR/SCR*						0	0		Genlock Disabled	
								0	1		Subcarrier Reset	
								1	0		Timing Reset	
								1	1		RTC Enabled	
		SD Active Video Length	-				0		_		720 Pixels	_
		SD Chroma				_	1	_		\vdash	710 (NTSC)/702 (PAL)	
		SD Chroma	-	-		0	-	-	_	\vdash	Chroma Enabled Chroma Disabled	_
		SD Burst	+		0	1	-	-	-	\vdash	Enabled	
		SD Burst	-		1					\vdash	Disabled	-
		SD Color Bars	+	0	1					Н	Disabled	
		SD Gold Ball		1							Enabled	
		SD DAC Swap	0								DAC B = Luma	
			0								DAC C = Chroma	
			1								DAC B = Chroma DAC C = Luma	
45h	Reserved		\perp							ш		00h
46h	Reserved											00h
47h	SD Mode Register 4	SD PrPb Scale								0	Disabled	00h
		0D V 0 1	_				-			1	Enabled	
		SD Y Scale	_						0	\vdash	Disabled Enabled	
		SD Huo Adinot	+				_	0	1	\vdash		
		SD Hue Adjust	_				_	1	_	\vdash	Disabled Enabled	-
		SD Brightness	-				0	1	-	\vdash	Disabled	
		3D Brightness					1				Enabled	
		SD Luma SSAF Gain	+			0	1				Disabled	
		SE Edinia SOFIE Sum				1					Enabled	
		Reserved			0	<u> </u>					0 must be written to this bit.	
		Reserved		0							0 must be written to this bit.	
		Reserved	0								0 must be written to this bit.	
48h	SD Mode Register 5	Reserved								0	0 must be written to this bit.	
		Reserved							0		0 must be written to this bit.	
		SD Double Buffering						0			Disabled	
								1			Enabled	
		SD Input Format					0				8-Bit Input	
							1				16-Bit Input	
		Reserved				0					0 must be written to this bit.	
		SD Digital Noise Reduction			0						Disabled	
		07.0	_		1		-			\vdash	Enabled	
		SD Gamma Control	-	0			-	_	_	\vdash	Disabled	_
		SD Gamma Curve	0	1			-	-	-	\vdash	Enabled	
		SD Gainma Curve	1	 		-	\vdash	-	\vdash	$\vdash\vdash$	Gamma Curve A Gamma Curve B	\dashv
49h	SD Mode Register 6	SD Undershoot Limiter	+ 1	-		-	_	-	0	0	Disabled	00h
		52 Olicishoot Limitei	-	 		!	 	 	0	1	-11 IRE	
						l -			1	0	-6 IRE	7
				†		l			1	1	-1.5 IRE	7
		Reserved	+	 		 	\vdash	0	Ė	\vdash	0 must be written to this bit.	1
		SD Black Burst Output on DAC Luma	+	 			0	Ľ		\vdash	Disabled	+
						 	1	\vdash	\vdash	\vdash	Enabled	
		SD Chroma Delay	+		0	0	Ė			\vdash	Disabled	
					0	1				Н	4 Clk Cycles	┪
					1	0				П	8 Clk Cycles	7
					1	1				П	Reserved	7
		Reserved		0							0 must be written to this bit.	
i		Reserved	0								0 must be written to this bit.	
				-								

^{*}See Figure 23, RTC Timing and Connections.

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SR7- SR0	Register	Bit Description	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register Setting	Reset Values
4Ah	SD Timing Register 0	SD Slave/Master Mode								0	Slave Mode	08h
									1	1	Master Mode	
		SD Timing Mode						0	0		Mode 0	
								0	1		Mode 1	
								1	0		Mode 2	
								1	1		Mode 3	
		SD BLANK Input					0				Enabled	
							1				Disabled	1
		SD Luma Delay			0	0			1		No Delay	
					0	1					2 Clk Cycles	
					1	0					4 Clk Cycles	
					1	1					6 Clk Cycles	1
		SD Min. Luma Value		0					1		- 40 IRE	
				1							– 7.5 IRE	
		SD Timing Reset	х	0	0	0	0	0	0	0	A low-high-low transition will reset the internal SD timing counters.	
4Bh	SD Timing Register 1	SD HSYNC Width							0	0	T _A = 1 Clk Cycle	00h
									0	1	T _A = 4 Clk Cycles	
									1	0	T _A = 16 Clk Cycles	
									1	1	T _A = 128 Clk Cycles	
		SD HSYNC to VSYNC Delay					0	0	<u> </u>		T _B = 0 Clk Cycle	
							0	1	i –		T _B = 4 Clk Cycles	1
							1	0			T _B = 8 Clk Cycles	
							1	1			T _B = 18 Clk Cycles	1
		SD HSYNC to VSYNC Rising			х	0			<u> </u>		$T_C = T_R$	
		Edge Delay (Mode 1 Only)			х	1			i –		$T_C = T_B + 32 \mu s$	1
		VSYNC Width (Mode 2 Only)			0	0					1 Clk Cycle	
					0	1					4 Clk Cycles	
					1	0			<u> </u>		16 Clk Cycles	1
					1	1			i –		128 Clk Cycles	1
		HSYNC to Pixel Data Adjust	0	0							0 Clk Cycles	
			0	1							1 Clk Cycle	
			1	0					i –		2 Clk Cycles	1
			1	1							3 Clk Cycles	1
4Ch	SD F _{SC} Register 0		х	х	х	х	х	х	х	х	Subcarrier Frequency Bit 7–0	16h
4Dh	SD F _{SC} Register 1		x	х	х	х	х	х	х	х	Subcarrier Frequency Bit 15–8	7Ch
4Eh	SD F _{SC} Register 2		x	х	х	х	х	х	х	х	Subcarrier Frequency Bit 23–16	F0h
4Fh	SD F _{SC} Register 3		x	х	х	х	х	х	х	х	Subcarrier Frequency Bit 31-24	21h
50h	SD F _{SC} Phase		х	х	х	х	х	х	х	х	Subcarrier Phase Bit 9–2	00h
51h	SD Closed Captioning	Extended Data on Even Fields	x	х	х	х	х	х	х	х	Extended Data Bit 7-0	00h
52h	SD Closed Captioning	Extended Data on Even Fields	x	х	х	х	х	х	х	х	Extended Data Bit 15-8	00h
53h	SD Closed Captioning	Data on Odd Fields	x	х	х	х	х	х	х	х	Data Bit 7–0	00h
54h	SD Closed Captioning	Data on Odd Fields	x	х	х	х	х	х	х	х	Data Bit 15–8	00h
55h	SD Pedestal Register 0	Pedestal on Odd Fields	17	16	15	14	13	12	11	10	Setting any of these bits to 1	00h
56h	SD Pedestal Register 1	Pedestal on Odd Fields	25	24	23	22	21	20	19	18	will disable pedestal on the	00h
57h	SD Pedestal Register 2	Pedestal on Even Fields	17	16	15	14	13	12	11	10	line number indicated by the	00h
58h	SD Pedestal Register 3	Pedestal on Even Fields	25	24	23	22	21	20	19	18	bit settings.	00h



Figure 15. Timing Register 1 in PAL Mode

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SR7- SR0	Register	Bit Description	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register Setting	Reset Values
59h	SD CGMS/WSS 0	SD CGMS Data					19	18	17	16	CGMS data bits C19-C16	00h
		SD CGMS CRC		1		0		1			Disabled	
				1		1	1	1			Enabled	1
		SD CGMS on Odd Fields			0			1	1		Disabled	
				1	1			1			Enabled	1
		SD CGMS on Even Fields		0	1	1	1	1	1		Disabled	
				1	1	1		1	1		Enabled	1
		SD WSS	0	1	1	1	1	1	1		Disabled	
			1	l l							Enabled	
5Ah	SD CGMS/WSS 1	SD CGMS/WSS Data			13	12	11	10	9	8	CGMS Data Bits C13–C8 or WSS Data Bits C13–C8	00h
			15	14							CGMS Data Bits C15-C14	00h
5Bh	SD CGMS/WSS 2	SD CGMS/WSS Data	7	6	5	4	3	2	1	0	CGMS/WSS Data Bits C7-C0	00h
5Ch	SD LSB Register	SD LSB for Y Scale Value							x	x	SD Y Scale Bit 1-0	
l		SD LSB for U Scale Value					x	x			SD U Scale Bit 1-0	
İ		SD LSB for V Scale Value			X	х					SD V Scale Bit 1-0	
		SD LSB for F _{SC} Phase	х	x							Subcarrier Phase Bits 1-0	
5Dh	SD Y Scale	SD Y Scale Value	х	x	х	x	x	x	x	x	SD Y Scale Bit 7-2	00h
5Eh	SD V Scale	SD V Scale Value	x	x	x	x	x	x	x	x	SD V Scale Bit 7-2	00h
5Fh	SD U Scale	SD U Scale Value	х	х	x	х	x	x	x	x	SD U Scale Bit 7–2	00h
60h	SD Hue Register	SD Hue Adjust Value	X	х	х	х	x	x	x	x	SD Hue Adjust Bit 7–0	00h
61h	SD Brightness/	SD Brightness Value		x	x	x	x	x	x	x	SD Brightness Bit 6-0	00h
	WSS	SD Blank WSS Data	0								Disabled	Line 23
			1								Enabled	
62h	SD Luma SSAF	SD Luma SSAF Gain/Attenuation	0	0	0	0	0	0	0	0	-4 dB	00h
			0	0	0	0	0	1	1	0	0 dB	
			0	0	0	0	1	1	0	0	4 dB	
63h	SD DNR 0	Coring Gain Border					0	0	0	0	No Gain	00h
							0	0	0	1	+1/16 (-1/8)	In DNR
							0	0	1	0	+2/16 (-2/8)	modes the
							0	0	1	1	+3/16 (-3/8)	values in the
							0	1	0	0	+4/16 (-4/8)	parentheses apply.
							0	1	0	1	+5/16 (-5/8)	
							0	1	1	0	+6/16 (-6/8)	
							0	1	1	1	+7/16 (-7/8)	
							1	0	0	0	+8/16 (-1)	
		Coring Gain Data	0	0	0	0					No Gain	
			0	0	0	1					+1/16 (-1/8)	
			0	0	1	0					+2/16 (-2/8)	
			0	0	1	1					+3/16 (-3/8)	
			0	1	0	0					+4/16 (-4/8)]
			0	1	0	1					+5/16 (-5/8)	
			0	1	1	0					+6/16 (-6/8)	
			0	1	1	1					+7/16 (-7/8)	
			1	0	0	0					+8/16 (-1)	
64h	SD DNR 1	DNR Threshold			0	0	0	0	0	0	0	00h
				↓	0	0	0	0	0	1	1	4
				+				1		0	62	4
			-	+	1	1	1	_	1		63	4
		Border Area		0	1	1	1	1	1	1	2 Pixels	
	1	20140111104	-	1	1	1	1	1	1	1	4 Pixels	†
		Block Size Control	0								8 Pixels	
	1	I	1	1	1	_	1	1		1	16 Pixels	7

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SR7-	Register	Bit Description	Bit	Bit	Bit	Bit	Bit	Bit	Bit	Bit	Register Setting	Reset
SR0	110810101	Die 2 Goerapaan	7	6	5	4	3	2	1	0	riogister setting	Values
65h	SD DNR 2	DNR Input Select						0	0	1	Filter A	00h
								0	1	0	Filter B	
								0	1	1	Filter C	1
								1	0	0	Filter D	1
		DNR Mode				0					DNR Mode	
						1					DNR Sharpness Mode	1
		DNR Block Offset	0	0	0	0					0 Pixel Offset	
			0	0	0	1					1 Pixel Offset	
												1
			1	1	1	0					14 Pixel Offset]
			1	1	1	1					15 Pixel Offset	
66h	SD Gamma A	SD Gamma Curve A Data Points	x	x	х	X	x	X	x	X	A0	00h
67h	SD Gamma A	SD Gamma Curve A Data Points	x	x	x	х	x	х	x	X	A1	00h
68h	SD Gamma A	SD Gamma Curve A Data Points	x	x	x	х	x	х	x	X	A2	00h
69h	SD Gamma A	SD Gamma Curve A Data Points	x	x	х	х	x	X	x	X	A3	00h
6Ah	SD Gamma A	SD Gamma Curve A Data Points	x	x	x	х	x	X	x	X	A4	00h
6Bh	SD Gamma A	SD Gamma Curve A Data Points	X	х	х	х	x	х	х	Х	A5	00h
6Ch	SD Gamma A	SD Gamma Curve A Data Points	x	x	х	х	x	х	x	X	A6	00h
6Dh	SD Gamma A	SD Gamma Curve A Data Points	x	x	х	х	x	х	x	х	A7	00h
6Eh	SD Gamma A	SD Gamma Curve A Data Points	x	x	х	х	x	х	x	Х	A8	00h
6Fh	SD Gamma A	SD Gamma Curve A Data Points	x	x	х	х	x	х	x	Х	A9	00h
70h	SD Gamma B	SD Gamma Curve B Data Points	x	x	x	x	x	x	x	X	B0	00h
71h	SD Gamma B	SD Gamma Curve B Data Points	x	x	х	х	x	X	x	X	B1	00h
72h	SD Gamma B	SD Gamma Curve B Data Points	x	x	х	х	x	X	x	X	B2	00h
73h	SD Gamma B	SD Gamma Curve B Data Points	X	x	х	х	x	х	x	X	B3	00h
74h	SD Gamma B	SD Gamma Curve B Data Points	X	x	х	х	x	х	x	X	B4	00h
75h	SD Gamma B	SD Gamma Curve B Data Points	X	х	x	x	x	x	x	x	B5	00h
76h	SD Gamma B	SD Gamma Curve B Data Points	x	x	x	х	x	х	x	х	B6	00h
77h	SD Gamma B	SD Gamma Curve B Data Points	x	x	x	х	x	х	x	х	B7	00h
78h	SD Gamma B	SD Gamma Curve B Data Points	x	x	х	х	x	х	x	х	B8	00h
79h	SD Gamma B	SD Gamma Curve B Data Points	x	x	х	х	x	х	x	х	B9	00h
7Ah	SD Brightness Detect	SD Brightness Value	x	x	x	x	x	x	x	x	Read-Only	
7Bh	Field Count Register	Field Count						x	x	х	Read-Only	
		Reserved					0				0 must be written to this bit.	
		Reserved				0					0 must be written to this bit.	
		Reserved			0						0 must be written to this bit.	
		Revision Code	х	х							Read-Only	
7C	Reserved											00h

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SR7-	Register	Bit Description	Bit	Bit	Bit	Bit	Bit	Bit	Bit	Bit	Register Setting	Reset
SR0			7	6	5	4	3	2	1	0		Values
7Dh	Reserved											
7Eh	Reserved											
7Fh	Reserved											
80h	Macrovision	MV Control Bits	х	x	х	x	х	х	Х	х		00h
81h	Macrovision	MV Control Bits	х	x	x	x	x	x	x	x		00h
82h	Macrovision	MV Control Bits	x	x	x	x	x	x	x	x		00h
83h	Macrovision	MV Control Bits	x	x	х	x	х	х	х	х		00h
84h	Macrovision	MV Control Bits	x	x	x	x	x	х	х	x		00h
85h	Macrovision	MV Control Bits	x	x	х	x	х	X	X	X		00h
86h	Macrovision	MV Control Bits	x	x	х	x	х	X	X	X		00h
87h	Macrovision	MV Control Bits	x	X	x	x	x	x	x	x		00h
88h	Macrovision	MV Control Bits	x	x	х	x	X	X	Х	х		00h
89h	Macrovision	MV Control Bits	x	x	x	x	x	x	x	x		00h
8Ah	Macrovision	MV Control Bits	x	x	x	x	x	x	x	x		00h
8Bh	Macrovision	MV Control Bits	x	x	x	x	x	x	x	x		00h
8Ch	Macrovision	MV Control Bits	x	x	х	x	х	х	х	х		00h
8Dh	Macrovision	MV Control Bits	x	x	х	x	х	х	х	х		00h
8Eh	Macrovision	MV Control Bits	x	x	x	x	x	x	x	x		00h
8Fh	Macrovision	MV Control Bits	x	x	х	x	х	х	X	х		00h
90h	Macrovision	MV Control Bits	x	x	х	x	х	х	X	х		00h
91h	Macrovision	MV Control Bits								X		00h
			0	0	0	0	0	0	0		0 must be written to these bits.	

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INPUT CONFIGURATION

Note that the ADV7330 defaults to progressive scan 54 MHz mode on power-up. Address(01h): Input Mode = 011

Standard Definition

Address(01h): Input Mode = 000

The 8-bit multiplexed input data is input on Pins Y7–Y0, with Y0 being the LSB. Input standards supported are ITU-R BT.601/656.

In 16-bit input mode the Y pixel data is input on Pins Y7–Y0 and CrCb data on Pins C7–C0.

Input sync signals are optional and are input on the $\overline{VSYNC_I/P}$, $\overline{HSYNC_I/P}$, and $\overline{BLANK_I/P}$ pins.

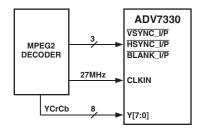


Figure 16. SD Input Mode

Progressive Scan or HDTV Mode

Address (01h): Input Mode 001 or 010, Respectively

YCrCb progressive scan, HDTV, or any other HD YCrCb data can be input in 4:2:2. In 4:2:2 input mode, the Y data is input on Pins Y7–Y0 and the CrCb data on Pins C7–C0.

If the YCrCb data does not conform to SMPTE 293M (525p), ITU-R BT.1358M (625p), SMPTE 274M (1080i), SMPTE 296M (720p), or BTA T-1004/1362, the async timing mode must be used.

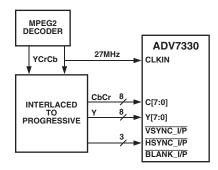


Figure 17. Progressive Scan Input Mode

Progressive Scan at 27 MHz (Dual Edge) or 54 MHz Address (01h): Input Mode 100 or 111, Respectively

YCrCb progressive scan data can be input at 27 MHz or 54 MHz. The input data is interleaved onto a single 8-bit bus and is input on Pins Y7–Y0. When a 27 MHz clock is supplied, the data is clocked in on the rising and falling edge of the input clock and CLOCK EDGE [Address 01h, Bit 1] must be set accordingly.

The following figures show the possible conditions.

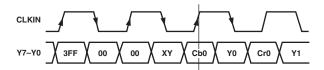


Figure 18a. Cb Data on Rising Edge—Clock Edge Address 01h Bit 1 Should be Set to 0

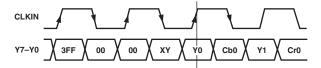


Figure 18b. Y Data on Rising Edge—Clock Edge Address 01h Bit 1 Should be Set to 1

With a 54 MHz clock, the data is latched on every rising edge.

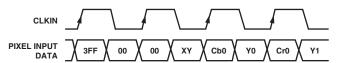


Figure 18c. Input Sequence in PS Bit Interleaved Mode (EAV/SAV)

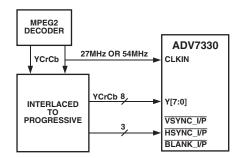


Figure 19. 1× 8-Bit PS at 27 MHz or 54 MHz

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Table I provides an overview of possible input configurations.

Table I. Input Configurations

Input Format	Total Bits		Input Video	Input Pins	Subaddress	Register Setting
ITU-R BT.656	8	4:2:2	YCrCb	Y7-Y0	01h 48h	00h 00h
	16	4:2:2	Y YCrCb	Y7-Y0 C7-C0	01h 48h	00h 08h
PS	8 (27 MHz clock)	4:2:2	YCrCb	Y7-Y0	10h 13h	40h 40h
	8 (54 MHz clock)	4:2:2	YCrCb	Y7-Y0	10h 13h	30h 40h
	16	4:2:2	Y CrCb	Y7-Y0 C7-C0	01h 13h	10h 40h
HDTV	16	4:2:2	Y CrCb	Y7-Y0 C7-C0	01h 13h	20h 40h

OUTPUT CONFIGURATION

Tables II and III show which output signals are assigned to the DACs when according control bits are set.

Table II. Output Configuration in SD Mode

RGB/YPrPb Output 02h, Bit 5	SD DAC Output 1 42h, Bit 2	SD DAC Output 1 42h, Bit 1	SD DAC Swap 44h, Bit 7	DAC A	DAC B	DAC C
0	0	0	0	G	В	R
0	0	0	1	G	В	R
0	0	1	0	CVBS	Luma	Chroma
0	0	1	1	CVBS	Chroma	Luma
0	1	0	0	CVBS	В	R
0	1	0	1	CVBS	В	R
0	1	1	0	G	Luma	Chroma
0	1	1	1	G	Chroma	Luma
1	0	0	0	Y	Pb	Pr
1	0	0	1	Y	Pb	Pr
1	0	1	0	CVBS	Luma	Chroma
1	0	1	1	CVBS	Chroma	Luma
1	1	0	0	CVBS	Pb	Pr
1	1	0	1	CVBS	Pb	Pr
1	1	1	0	Y	Luma	Chroma
1	1	1	1	Y	Chroma	Luma

Table III. Output Configuration in HD/PS Mode

HD Input Format	RGB/YPrPb Output 02h, Bit 5	HD Color Swap 15h, Bit 3	DAC A	DAC B	DAC C
YCrCb 4:2:2	1	0	Y	Pb	Pr
YCrCb 4:2:2	1	1	Y	Pr	Pb
YCrCb 4:2:2	0	0	G	В	R
YCrCb 4:2:2	0	1	G	R	В

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TIMING MODES HD Async Timing Mode [Subaddress 10h, Bit 3,2]

For any input data that does not conform to the standards selectable in input mode, Subaddress 10h, asynchronous timing mode can be used to interface to the ADV7330. Timing control signals for Hsync, Vsync, and Blank have to be programmed by the user. Macrovision and programmable oversampling rates are not available in async timing mode. In async mode, the PLL must be turned off [Subaddress 01h, Bit 1 = 1].

Figures 20a and 20b show an example of how to program the ADV7330 to accept a different high definition standard other than SMPTE 293M, SMPTE 274M, SMPTE 296M, or ITU-R BT.1358.

The following truth table must be followed when programming the control signals in async timing mode.

For standards that do not require a tri-sync level, <u>BLANK_I/P</u> must be tied low at all times.

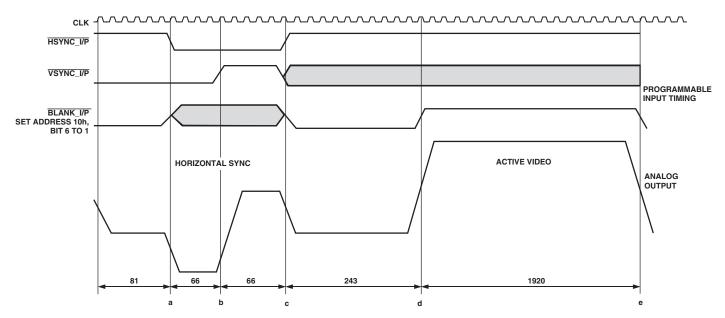


Figure 20a. Async Timing Mode—Programming Input Control Signals for SMPTE 295M Compatibility

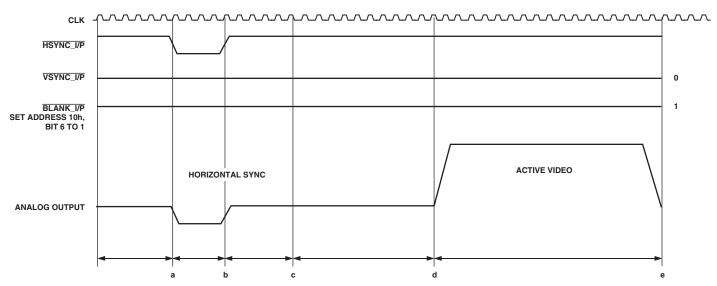


Figure 20b. Async Timing Mode—Programming Input Control Signals for Bilevel Sync Signals

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Table IV. Async Timing Mode Truth Table

HSYNC_I/P	VSYNC_I/P	BLANK_I/P*		Reference in Figures 20a and 20b
$1 \rightarrow 0$	0	0 or 1	50% point of falling edge of tri-level horizontal sync signal	a
0	$0 \rightarrow 1$	0 or 1	25% point of rising edge of tri-level horizontal sync signal	b
$0 \rightarrow 1$	0 or 1	0	50% point of falling edge of tri-level horizontal sync signal	c
1	0 or 1	$0 \rightarrow 1$	50% start of active video	d
1	0 or 1	$1 \rightarrow 0$	50% end of active video	e

^{*}When async timing mode is enabled, $\overline{BLANK_I/P}$ (Pin 25) becomes an active high input. $\overline{BLANK_I/P}$ is set to active low at Address 10h, Bit 6.

HD Timing Reset

[Address 14h, Bit 0]

A timing reset is achieved in setting the HD timing reset control bit at Address 14h from 0 to 1. In this state, the horizontal and vertical counters will remain reset. When this bit is set back to 0, the internal counters will commence counting again. PLL must be powered off by this mode.

The minimum time the pin has to be held high is one clock cycle, otherwise this reset signal might not be recognized. This timing reset applies to the HD timing counters only.

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SD Real-Time Control, Subcarrier Reset, Timing Reset [Subaddress 44h, Bit 2,1]

Together with the RTC_SCR_TR pin and SD Mode Register 3 [Address 44h, Bit 1,2], the ADV7330 can be used in timing reset mode, subcarrier phase reset mode, or RTC mode.

A timing reset is achieved in a low-to-high transition on the RTC_SCR_TR pin (Pin 31). In this state, the horizontal and vertical counters will remain reset. On releasing this pin (set to low), the internal counters will commence counting again, the field count will start on Field 1, and the subcarrier phase will also be reset.

The minimum time the pin has to be held high is one clock cycle; otherwise, this reset signal might not be recognized. This timing reset applies to the SD timing counters only.

In subcarrier phase reset, a low-to-high transition on the RTC_SCR_TR pin (Pin 31) will reset the subcarrier phase to zero on the field following the subcarrier phase reset when the SD RTC/TR/SCR control bits at Address 44h are set to 01.

This reset signal will have to be held high for a minimum of one clock cycle.

Since the field counter is not reset, it is recommended that the reset signal be applied in Field 7 [PAL] or Field 3 [NTSC]. The reset of the phase will then occur on the next field, i.e., Field 1 being lined up correctly with the internal counters. The field count register at Address 7Bh can be used to identify the number of the active field.

In RTC mode, the ADV7330 can be used to lock to an external video source. The real-time control mode allows the ADV7330 to automatically alter the subcarrier frequency to compensate for line length variations. When the part is connected to a device that outputs a digital data stream in the RTC format (such as an ADV7183A video decoder, see Figure 23), the part will automatically change to the compensated subcarrier frequency on a line by line basis. This digital data stream is 67 bits wide and the subcarrier is contained in Bits 0 to 21. Each bit is two clock cycles long. 00h should be written into all four subcarrier frequency registers when this mode is used.

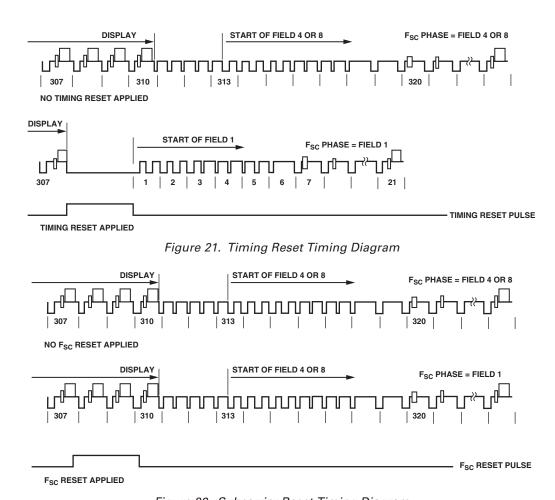


Figure 22. Subcarrier Reset Timing Diagram

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Reset Sequence

A reset is activated with a high-to-low transition on the \overline{RESET} pin (Pin 33) according to the Timing Specifications. The ADV7330 will revert to the default output configuration.

Figure 24 illustrates the RESET sequence timing.

SD VCR FF/RW Sync

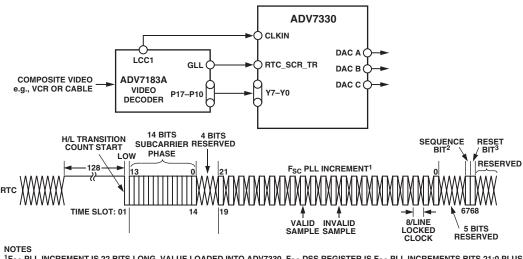
[Subaddress 42h, Bit 5]

In DVD record applications where the encoder is used with a decoder, the VCR FF/RW sync control bit can be used for nonstandard input video, i.e., in fast forward or rewind modes.

In fast forward mode, the sync information at the start of a new field in the incoming video usually occurs before the correct number of lines/fields are reached. In rewind mode, this sync signal usually occurs after the total number of lines/fields are reached. Conventionally this means that the output video will have corrupted field signals, one generated by the incoming video and one generated when the internal lines/field counters reach the end of a field.

When the VCR FF/RW sync control is enabled [Subaddress 42h, Bit 5], the lines/field counters are updated according to the incoming vsync signal, and the analog output matches the incoming vsync signal.

This control is available in all slave timing modes except Slave Mode 0.



 $^{1}F_{SC}$ PLL INCREMENT IS 22 BITS LONG, VALUE LOADED INTO ADV7330, F_{SC} DSS REGISTER IS F_{SC} PLL INCREMENTS BITS 21:0 PLUS BITS 0:9 OF SUBCARRIER FREQUENCY REGISTERS. ALL ZEROS SHOULD BE WRITTEN TO THE SUBCARRIER FREQUENCY REGISTERS OF THE ADV7330.

²SEQUENCE BIT.

PAL: 0 = LINE NORMAL, 1 = LINE INVERTED.

NTSC: 0 = NO CHANGE.

3RESET BIT. RESET ADV7330 DSS.

Figure 23. RTC Timing and Connections

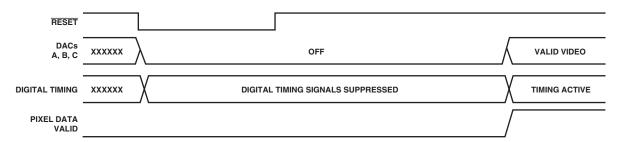


Figure 24. RESET Timing Sequence

Vertical Blanking Interval

The ADV7330 accepts input data that contains VBI data (such as CGMS, WSS, VITS) in SD and HD modes.

For SMPTE 293M (525p) standards, VBI data can be inserted on Lines 13 to 42 of each frame, or Lines 6 to 43 for the ITU-R BT.1358 [625p] standard.

For SD NTSC, this data can be present on Lines 10 to 20; in PAL, on Lines 7 to 22.

If VBI is disabled [Address 11h, Bit 4 for HD; Address 43h, Bit 4 for SD], VBI data is not present at the output and the entire VBI is blanked. These control bits are valid in all master and slave modes.

In Slave Mode 0, if VBI is enabled, the blanking bit in the EAV/SAV code is overwritten; it is possible to use VBI in this timing mode as well.

In Slave Mode 1 or 2, the BLANK control bit must be set to enabled [Address 4Ah, Bit 3] to allow VBI data to pass through the ADV7330; otherwise, the ADV7330 automatically blanks the VBI to standard.

If CGMS is enabled and VBI disabled, the CGMS data will nevertheless be available at the output.

SD Subcarrier Frequency Registers [Subaddress 4Ch-4Fh]

Four 8-bit wide registers are used to set up the subcarrier frequency. The value of these registers is calculated using the following equation:

Subcarrier Frequency Register =
$$\frac{\#Subcarrier Frequency Value in one video line}{\#27 \,MHz \, clk \, cycles in one video line} \times 2^{32}$$

For example, NTSC mode,

Subcarrier Frequency Value =
$$\left(\frac{227.5}{1716}\right) \times 2^{32} = 569408542$$

Subcarrier Register Value = 21F07C1Eh

SD F_{SC} Register 0: 1Eh SD F_{SC} Register 1: 7Ch SD F_{SC} Register 2: F0h SD F_{SC} Register 3: 21h

Refer to the MPU Port Description section for details on how to access the subcarrier frequency registers.

Square Pixel Timing [Register 42h, Bit 4]

In square pixel mode, the timing diagrams in Figures 25 and 26 apply.

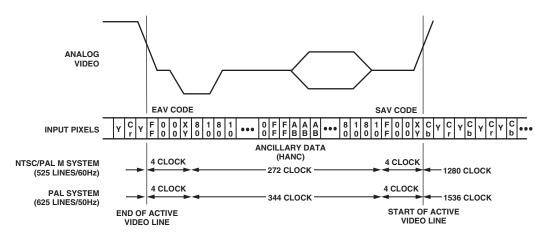


Figure 25. EAV/SAV Embedded Timing

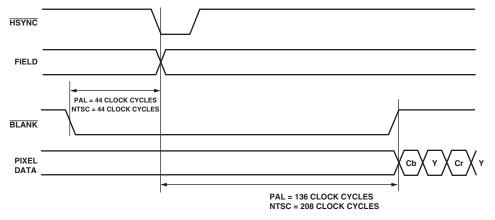


Figure 26. Active Pixel Timing

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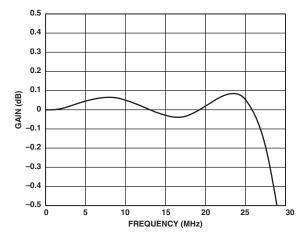
FILTER SECTION

Table V shows an overview of the programmable filters available on the ADV7330.

Table V. Selectable Filters of the ADV7330

Filter	Subaddress		
SD Luma LPF NTSC	40h		
SD Luma LPF PAL	40h		
SD Luma Notch NTSC	40h		
SD Luma Notch PAL	40h		
SD Luma SSAF	40h		
SD Luma CIF	40h		
SD Luma QCIF	40h		
SD Chroma 0.65 MHz	40h		
SD Chroma 1.0 MHz	40h		
SD Chroma 1.3 MHz	40h		
SD Chroma 2.0 MHz	40h		
SD Chroma 3.0 MHz	40h		
SD Chroma CIF	40h		
SD Chroma QCIF	40h		
SD UV SSAF	42h		
HD Chroma Input	13h		
HD Sinc Filter	13h		
HD Chroma SSAF	13h		

HD Sinc Filter



Filter 27. HD Sinc Filter Enabled

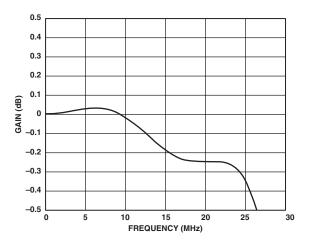


Figure 28. HD Sinc Filter Disabled

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SD Internal Filter Response [Subaddress 40h; Subaddress 42, Bit 0]

The Y filter supports several different frequency responses including two low-pass responses, two notch responses, an extended (SSAF) response with or without gain boost/attenuation, a CIF response, and a QCIF response. The UV filter supports several different frequency responses including six low-pass responses, a CIF response, and a QCIF response, as can be seen in the typical performance characteristics graphs on the following pages.

If SD SSAF gain is enabled, there is the option of 12 responses in the range of –4 dB to +4 dB [Subaddress 47, Bit 4]. The desired response can be chosen by the user by programming the correct value via the I²C [Subaddress 62h]. The variation of frequency responses can be seen in the typical performance characteristics graphs on the following pages.

In addition to the chroma filters listed in Table VI, the ADV7330 contains an SSAF filter specifically designed for and applicable to the color difference component outputs, U and V.

This filter has a cutoff frequency of about 2.7 MHz and -40 dB at 3.8 MHz, as can be seen in Figure 29. This filter can be controlled with Address 42h, Bit 0.

If this filter is disabled, the selectable chroma filters shown in Table VI can be used for the CVBS or chroma signal.

Table VI. Internal Filter Specifications

Filter	Pass-Band Ripple (dB) ¹	3 dB Bandwidth (MHz) ²
Luma LPF NTSC	0.16	4.24
Luma LPF PAL	0.1	4.81
Luma Notch NTSC	0.09	2.3/4.9/6.6
Luma Notch PAL	0.1	3.1/5.6/6.4
Luma SSAF	0.04	6.45
Luma CIF	0.127	3.02
Luma QCIF	Monotonic	1.5
Chroma 0.65 MHz	Monotonic	0.65
Chroma 1.0 MHz	Monotonic	1
Chroma 1.3 MHz	0.09	1.395
Chroma 2.0 MHz	0.048	2.2
Chroma 3.0 MHz	Monotonic	3.2
Chroma CIF	Monotonic	0.65
Chroma QCIF	Monotonic	0.5

NOTES

¹Pass-band ripple refers to the maximum fluctuations from the 0 dB response in the pass band, measured in (dB). The pass band is defined to have 0 (Hz) to fc (Hz) frequency limits for a low-pass filter, 0 (Hz) to f1 (Hz) and f2 (Hz) to infinity for a notch filter, where fc, f1, f2 are the −3 dB points.

 2 3 dB bandwidth refers to the -3 dB cutoff frequency.

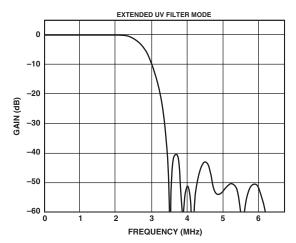
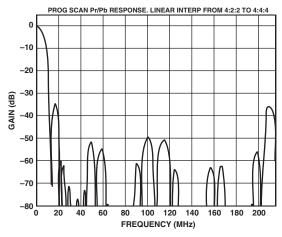


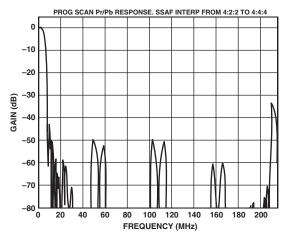
Figure 29. UV SSAF Filter

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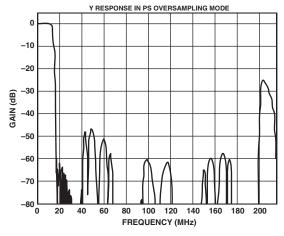
ADV7330-Typical Performance Characteristics



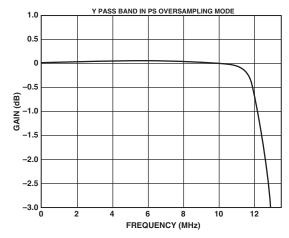
TPC 1. PS-UV (8× Oversampling Filter (Linear))



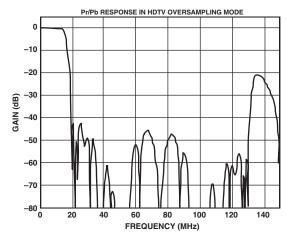
TPC 2. PS-UV (8× Oversampling Filter (SSAF))



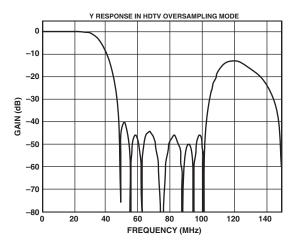
TPC 3. PS-Y (8× Oversampling Filter)



TPC 4. PS-Y (8× Oversampling Filter (Pass Band))

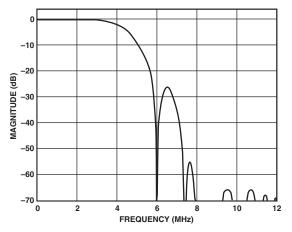


TPC 5. HDTV—UV (2× Oversampling Filter)

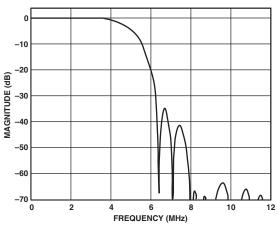


TPC 6. HDTV-Y (2× Oversampling Filter)

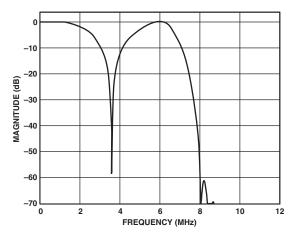
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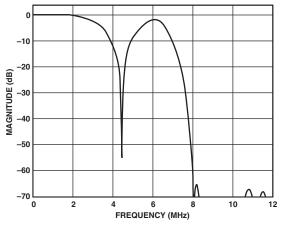
TPC 7. Luma NTSC Low-Pass Filter



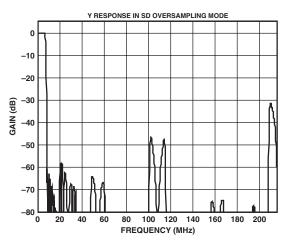
TPC 8. Luma PAL Low-Pass Filter



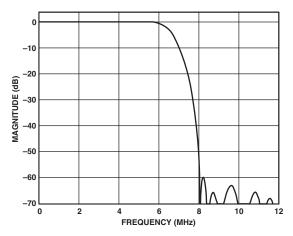
TPC 9. Luma NTSC Notch Filter



TPC 10. Luma PAL Notch Filter

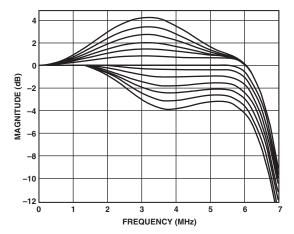


TPC 11. Y-16× Oversampling Filter

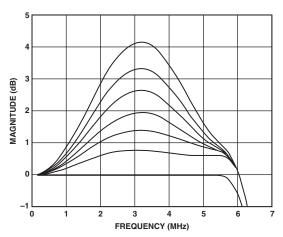


TPC 12. Luma SSAF Filter up to 12 MHz

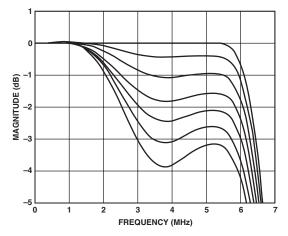
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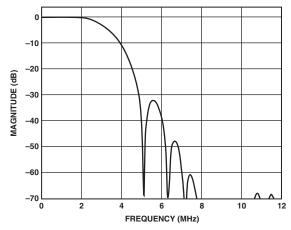
TPC 13. Luma SSAF Filter—Programmable Responses



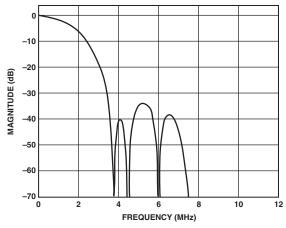
TPC 14. Luma SSAF Filter—Programmable Gain



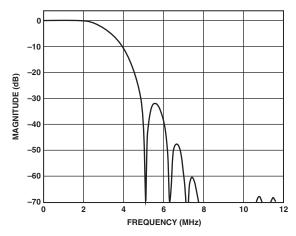
TPC 15. Luma SSAF Filter—Programmable Attenuation



TPC 16. Luma CIF LP Filter

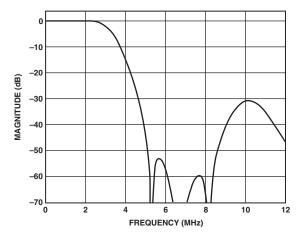


TPC 17. Luma QCIF LP Filter

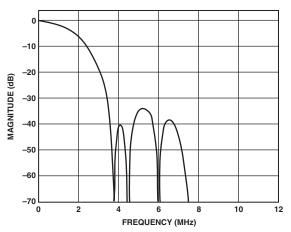


TPC 18. Chroma 3.0 MHz LP Filter

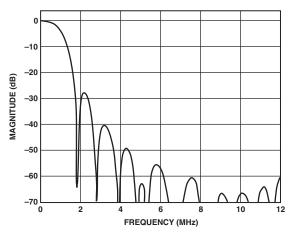
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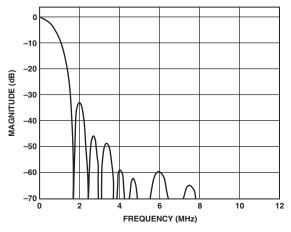
TPC 19. Chroma 2.0 MHz LP Filter



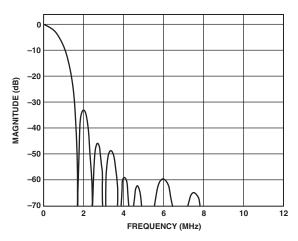
TPC 20. Chroma 1.3 MHz LP Filter



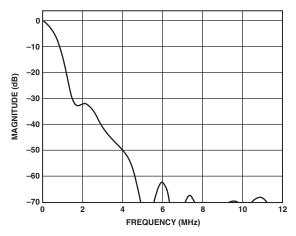
TPC 21. Chroma 1.0 MHz LP Filter



TPC 22. Chroma 0.65 MHz LP Filter



TPC 23. Chroma CIF LP Filter



TPC 24. Chroma QCIF LP Filter

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COLOR CONTROLS AND RGB MATRIX

HD Y Level, Cr Level, Cb Level [Subaddress 16h-18h]

Three 8-bit wide registers at Addresses 16h, 17h, 18h are used to program the output color of the internal HD test pattern generator, whether it is the lines of the cross hatch pattern or the uniform field test pattern. They are not functional as color controls on external pixel data input. For this purpose, the RGB matrix is used.

The standard used for the values for Y and the color difference signals to obtain white, black, and the saturated primary and complementary colors conforms to the ITU-R BT.601-4 standard.

Table VII shows sample color values to be programmed into the color registers when output standard selection is set to EIA 770.2.

Table VII. Sample Color Values for EIA770.2 Output Standard Selection

Sample			
Color	Y Value	CR Value	CB Value
White	235 (EB)	128 (80)	128 (80)
Black	16 (10)	128(80)	128 (80)
Red	81 (51)	240 (F0)	90 (5A)
Green	145 (91)	34 (22)	54 (36)
Blue	41 (29)	110 (6E)	240 (F0)
Yellow	210 (D2)	146 (92)	16 (10)
Cyan	170 (AA)	16 (10)	166 (A6)
Magenta	106 (6A)	222 (DE)	202 (CA)

HD RGB Matrix

[Subaddress 03h-09h]

When the programmable RGB matrix is disabled [Address 02h, Bit 3], the internal RGB matrix takes care of all YCrCb to YPrPb or RGB scaling according to the input standard programmed into the device.

When the programmable RGB matrix is enabled, the color components are converted according to the 1080i standard [SMPTE 274M]:

$$Y' = 0.2126R' + 0.7152G' + 0.0722B'$$

 $CB' = [0.5 / (1 - 0.0722)](B' - Y')$
 $CR' = [0.5 / (1 - 0.2126)](R' - Y')$

This is reflected in the preprogrammed values for GY = 138Bh, GU = 93h, GV = 3B, BU = 248h, RV = 1F0.

If another input standard is used, the scale values for GY, GU, GV, BU, and RV have to be adjusted according to this input standard. The user must consider that the color component conversion might use different scale values. For example, SMPTE 293M uses the following conversion:

$$Y' = 0.299 R' + 0.587 G' + 0.114 B'$$

 $CB' = [0.5 / (1 - 0.114)] (B' - Y')$
 $CR' = [0.5 / (1 - 0.299)] (R' - Y')$

The programmable RGB matrix can be used to control the HD output levels in cases where the video output does not confirm to standards due to altering the DAC output stages such as termination resistors. The programmable RGB matrix is used for external HD data and is not functional when the HD test pattern is enabled.

Programming the RGB Matrix

The RGB matrix should be enabled [Address 02h, Bit 3], the output should be set to RGB [Address 02h, Bit 5], Sync on PrPb should be disabled [Address 15h, Bit 2], and Sync on RGB is optional [Address 02h, Bit 4].

GY at addresses 03h and 05h controls the output levels on the green signal, BU at 04h and 08h the blue signal output levels, and RV at 04h and 09h the red output levels. To control YPrPb output levels, YPrPb output should be enabled [Address 02h, Bit 5]. In this case, GY [Address 05h; Address 03, Bit 0–1] is used for the Y output, RV [Address 09h; Address 04, Bit 0–1] is used for the Pr output, and BU [Address 08h; Address 04h, Bit 2–3] is used for the Pb output.

If RGB output is selected, the RGB matrix scaler uses the following equations:

$$G = GY \times Y + GU \times Pb + GV \times Pr$$

$$B = GY \times Y + BU \times Pb$$

$$R = GY \times Y + RV \times Pr$$

If YPrPb output is selected, the following equations are used:

$$Y = GY \times Y$$

$$U = BU \times Pb$$

$$V = RV \times Pr$$

On power-up, the RGB matrix is programmed with default values.

Table VIII. RGB Matrix Default Values

Address	Default
03h	03h
04h	F0h
05h	4Eh
06h	0Eh
07h	24h
08h	92h
09h	7Ch

When the programmable RGB matrix is not enabled, the ADV7330 automatically scales YCrCb inputs to all standards supported by this part.

SD Luma and Color Control [Subaddresses 5Ch, 5Dh, 5Eh, 5Fh]

SD Y SCALE, SD Cr SCALE, and SD Cb SCALE are 10-bit wide control registers to scale the Y, U, and V output levels.

Each of these registers represents the value required to scale the U or V level from 0.0 to 2.0, and the Y level from 0.0 to 1.5 of its initial level. The value of these 10 bits is calculated using the following equation:

$$Y$$
, U , or V Scalar Value = Scale Factor \times 512

For example:

Scale factor = 1.18

Y, U, or V Scalar Value = $1.18 \times 512 = 665.6$ Y, U, or V Scalar Value = 665 (rounded to the nearest integer)

1, 0, or v Scalar value – 005 (rounded to the neurest the

Y, U, or V Scalar Value = 1010 0110 01b

Address 5Ch, SD LSB Register = 15h

Address 5Dh, SD Y Scale Register = A6h

Address 5Eh, SD V Scale Register = A6h

Address 5Fh, SD U Scale Register = A6h

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SD Hue Adjust Value [Subaddress 60h]

The hue adjust value is used to adjust the hue on the composite and chroma outputs.

These eight bits represent the value required to vary the hue of the video data, i.e., the variance in phase of the subcarrier during active video with respect to the phase of the subcarrier during the colorburst. The ADV7330 provides a range of $\pm 22.5^{\circ}$ increments of 0.17578125° . For normal operation (zero adjustment), this register is set to 80h. FFh and 00h represent the upper and lower limits (respectively) of adjustment attainable.

(Hue Adjust) [°] = $0.17578125^{\circ} \times (HCRd-128)$, for positive hue adjust value.

For example, to adjust the hue by $+4^{\circ}$, write 97h to the hue adjust value register:

$$\left(\frac{4}{0.17578125}\right) + 128 = 105d^* = 97h$$

*rounded to the nearest integer

To adjust the hue by -4° , write 69h to the hue adjust value register:

$$\left(\frac{-4}{0.17578125}\right) + 128 = 105d^* = 69h$$

*rounded to the nearest integer

SD Brightness Control [Subaddress 61h]

The brightness is controlled by adding a programmable setup level onto the scaled Y data. This brightness level may be added onto the scaled Y data. For NTSC with pedestal, the setup can vary from 0 IRE to 22.5 IRE. For NTSC without pedestal and PAL, the setup can vary from -7.5 IRE to +15 IRE.

The brightness control register is an 8-bit wide register. Seven bits of this 8-bit register are used to control the brightness level. This brightness level can be a positive or negative value.

For example:

Standard: NTSC with pedestal.

To add +20 IRE brightness level, write 28h to Address 61h, SD brightness.

[SD Brightness Value]H = $[IRE Value \times 2.015631]H =$ $[20 \times 2.015631]H = [40.31262]H = 28H$ Standard: PAL.

To add -7 IRE brightness level, write 72h to Address 61h, SD brightness.

$$[|IREValue| \times 2.015631] =$$

 $[7 \times 2.015631] = [14.109417] = 0001110b$
 $[0001110] into twos complement = [1110010]B = 72h$

Table IX. Brightness Control Values*

Setup Level in NTSC with Pedestal	Setup Level in NTSC No Pedestal	Setup Level in PAL	SD Brightness
22.5 IRE	15 IRE	15 IRE	1Eh
15 IRE	7.5 IRE	7.5 IRE	0Fh
7.5 IRE	0 IRE	0 IRE	00h
0 IRE	–7.5 IRE	-7.5 IRE	71h

^{*}Values in the range of 3Fh to 44h might result in an invalid output signal.

SD Brightness Detect

[Subaddress 7Ah]

The ADV7330 allows monitoring of the brightness level of the incoming video data. Brightness detect is a read-only register.

Double Buffering

[Subaddress 13h, Bit 7; Subaddress 48h, Bit 2]

Double-buffered registers are updated once per field on the falling edge of the VSYNC signal. Double buffering improves the overall performance since modifications to register settings will not be made during active video, but take effect on the start of the active video.

Double buffering can be activated on the following HD registers: HD Gamma A and Gamma B curves, and HD CGMS registers. Double buffering can be activated on the following SD registers: SD Gamma A and Gamma B curves, SD Y scale, SD U scale, SD V scale, SD brightness, SD closed captioning, and SD Macrovision Bits 5–0.

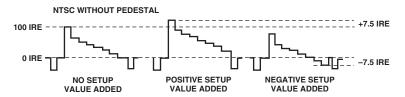


Figure 30. Examples of Brightness Control Values

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PROGRAMMABLE DAC GAIN CONTROL

DACs A, B, and C are controlled by Reg 0B. The I²C control registers will adjust the output signal gain up or down from its absolute level.

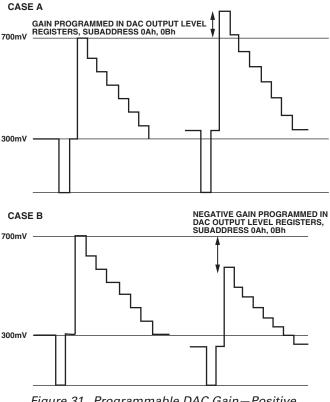


Figure 31. Programmable DAC Gain—Positive and Negative Gain

In Case A, the video output signal is gained. The absolute level of the sync tip and blanking level both increase with respect to the reference video output signal. The overall gain of the signal is increased from the reference signal.

In Case B, the video output signal is reduced. The absolute level of the sync tip and blanking level both decrease with respect to the reference video output signal. The overall gain of the signal is reduced from the reference signal.

The range of this feature is specified for $\pm 7.5\%$ of the nominal output from the DACs. For example, if the output current of the DAC is 4.33 mA, the DAC tune feature can change this output current from 4.008 mA (-7.5%) to 4.658 mA (+7.5%).

The reset value of the vid_out_ctrl registers is $00h \rightarrow$ nominal DAC output current. Table X is an example of how the output current of the DACs varies for a nominal 4.33 mA output current.

Table X.

Register 0Ah or 0Bh	DAC Current (mA)	% Gain	
0100 0000 (40h)	4.658	7.5000	
0011 1111 (3Fh)	4.653	7.3820	
0011 1110 (3Eh)	4.648	7.3640	
•••			
	•••		
0000 0010 (02h)	4.43	0.0360	
0000 0001 (01h)	4.38	0.0180	
0000 0000 (00h)	4.33	0.0000	(I ² C Reset Value,
, ,			Nominal)
1111 1111 (FFh)	4.25	-0.0180	
1111 1110 (FEh)	4.23	-0.0360	
	•••		
•••			
1100 0010 (C2h)	4.018	-7.3640	
1100 0001 (C1h)	4.013	-7.3820	
1100 0000 (C0h)	4.008	-7.5000	

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Gamma Correction

[Subaddress 24h-37h for HD, Subaddress 66h-79h for SD]

Gamma correction is available for SD and HD video. For each standard there are 20 8-bit wide registers. They are used to program the gamma correction curves A and B. HD gamma curve A is programmed at Addresses 24h–2Dh, HD gamma curve B at 2Eh–37h. SD gamma curve A is programmed at Addresses 66h–6Fh, SD gamma curve B at Addresses 70h–79h.

Generally, gamma correction is applied to compensate for the nonlinear relationship between signal input and brightness level output (as perceived on the CRT). It can also be applied wherever nonlinear processing is used.

Gamma correction uses the function

$$Signal_{OUT} = (Signal_{IN})^{\gamma}$$

where γ = gamma power factor.

Gamma correction is performed on the luma data only. The user has the choice to use two different curves, curve A or curve B. At any one time, only one of these curves can be used. The response of the curve is programmed at 10 predefined locations. In changing the values at these locations, the gamma curve can be modified. Between these points, linear interpolation is used to generate intermediate values. Considering the curve to have a total length of 256 points, the 10 locations are at 24, 32, 48, 64, 80, 96, 128, 160, 192, 224. Locations 0, 16, 240, and 255 are fixed and cannot be changed.

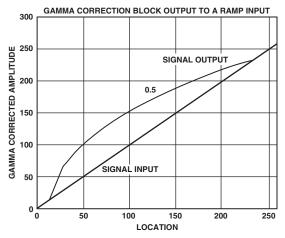


Figure 32. Signal Input (Ramp) and Signal Output for Gamma 0.5

For the length of 16 to 240, the gamma correction curve has to be calculated as follows:

$$v = x^{\gamma}$$

where:

y = gamma corrected output

x = linear input signal

 γ = gamma power factor

To program the gamma correction registers, the seven values for *y* have to be calculated using the following formula:

$$y_n = \left[\frac{x_{(n-16)}}{(240-16)}\right] \gamma \times (240-16) + 16$$

where:

 $x_{(n-16)}$ = Value for x along x-axis at points

n = 24, 32, 48, 64, 80, 96, 128, 160, 192 or 224

 y_n = Value for y along the y-axis, which has to be written into the gamma correction register

For example:

$$\begin{array}{l} y_{24} = [(8 \ / \ 224)^{0.5} \times 224] + 16 = 58^* \\ y_{32} = [16 \ / \ 224)^{0.5} \times 224] + 16 = 76^* \\ y_{48} = [(32 \ / \ 224)^{0.5} \times 224] + 16 = 101^* \\ y_{64} = [(48 \ / \ 224)^{0.5} \times 224] + 16 = 120^* \\ y_{80} = [(64 \ / \ 224)^{0.5} \times 224] + 16 = 136^* \\ y_{96} = [(80 \ / \ 224)^{0.5} \times 224] + 16 = 150^* \\ y_{128} = [(112 \ / \ 224)^{0.5} \times 224] + 16 = 174^* \\ y_{160} = [(144 \ / \ 224)^{0.5} \times 224] + 16 = 195^* \\ y_{192} = [(176 \ / \ 224)^{0.5} \times 224] + 16 = 214^* \\ y_{224} = [(208 \ / \ 224)^{0.5} \times 224] + 16 = 232^* \end{array}$$

*rounded to the nearest integer

The gamma curves in Figure 32 and 33 are examples only; any user defined curve is acceptable in the range of 16–240.

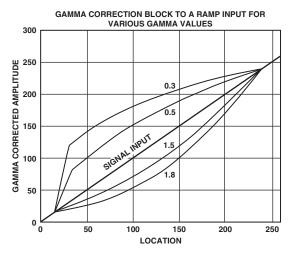


Figure 33. Signal Input (Ramp) and Selectable Gamma Output Curves

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HD SHARPNESS FILTER CONTROL AND ADAPTIVE FILTER CONTROL

[Subaddress 20h, 38h-3Dh]

There are three filter modes available on the ADV7330: sharpness filter mode and two adaptive filter modes.

HD Sharpness Filter Mode

To enhance or attenuate the Y signal in the frequency ranges shown in the figures below, the following register settings must be used: HD sharpness filter must be enabled and HD adaptive filter enable must be set to disabled.

To select one of the 256 individual responses, the according gain values for each filter, which range from -8 to +7, must be programmed into the HD sharpness filter gain register at Address 20h.

HD Adaptive Filter Mode

The HD adaptive filter threshold A, B, C registers, the HD adaptive filter gain 1, 2, 3 registers, and the HD sharpness filter gain register are used in Adaptive Filter mode. To activate the adaptive filter control, HD sharpness filter must be enabled and HD adaptive filter gain must be enabled.

The derivative of the incoming signal is compared to the three programmable threshold values: HD adaptive filter threshold A, B, C. The recommended threshold range is from 16–235, although any value in the range of 0–255 can be used.

The edges can then be attenuated with the settings in HD adaptive filter gain 1, 2, 3 registers and HD sharpness filter gain register. According to the settings of the HD adaptive filter mode control, there are two Adaptive Filter modes available:

- 1. Mode A is used when adaptive filter mode is set to 0. In this case, Filter B (LPF) will be used in the adaptive filter block. Also, only the programmed values for Gain B in the HD sharpness filter gain, HD adaptive filter gain 1, 2, 3 are applied when needed. The Gain A values are fixed and cannot be changed.
- 2. Mode B is used when adaptive filter gain is set to 1. In this mode a cascade of Filter A and Filter B is used. Both settings for Gain A and Gain B in the HD sharpness filter gain, HD adaptive filter gain 1, 2, 3 become active when needed.

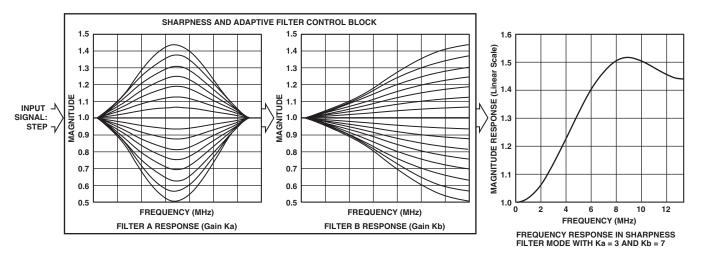


Figure 34. Sharpness and Adaptive Filter Control Block

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HD Sharpness Filter and Adaptive Filter Application Examples HD Sharpness Filter Application

The HD sharpness filter can be used to enhance or attenuate the Y video output signal. The following register settings were used to achieve the results shown in the figures below. Input data was generated by an external signal source.

Table XI.

Address	Register Setting	Reference in Figure 35
00h	FCh	
01h	10h	
02h	20h	
10h	00h	
11h	81h	
20h	00h	a
20h	08h	ь
20h	04h	С
20h	40h	d
20h	80h	e
20h	22h	f

The effect of the sharpness filter can also be seen when using the internally generated cross hatch pattern.

Table XII.

Address	Register Setting		
00h	FCh		
01h	10h		
02h	20h		
10h	00h		
11h	85h		
20h	99h		

In toggling the sharpness filter enable bit [Address 11h, Bit 8], it can be seen that the line contours of the crosshatch pattern change their sharpness.

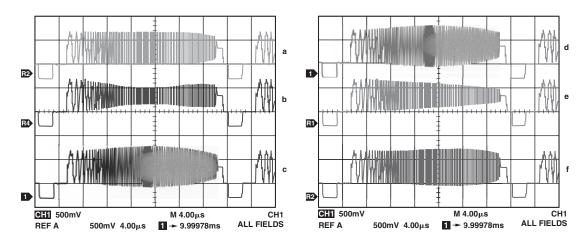


Figure 35. HD Sharpness Filter Control with Different Gain Settings for HS Sharpness Filter Gain Value

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ADAPTIVE FILTER CONTROL APPLICATION

Figures 36 and 37 show a typical signal to be processed by the adaptive filter control block.

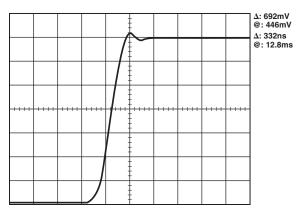


Figure 36. Input Signal to Adaptive Filter Control

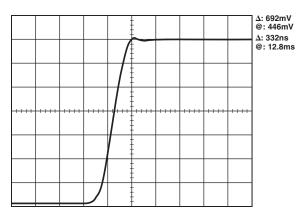


Figure 37. Output Signal After Adaptive Filter Control

The following register settings were used to obtain the results shown in Figure 37, i.e., to remove the ringing on the Y signal.

Input data was generated by an external signal source.

Table XIII.

Address	Register Setting
00h	FCh
01h	10h
02h	20h
10h	00h
11h	81h
15h	80h
20h	00h
38h	ACh
39h	9Ah
3Ah	88h
3Bh	28h
3Ch	3Fh
3Dh	64h

All other registers are set as normal.

When changing the adaptive filter mode to Mode B [Address 15h, Bit 6], the following output can be obtained:

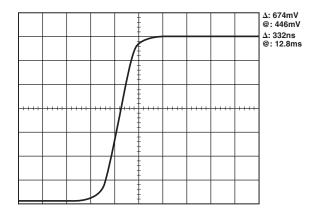


Figure 38. Output Signal from Adaptive Filter Control

The adaptive filter control can also be demonstrated using the internally generated crosshatch test pattern and toggling the adaptive filter control bit [Address 15h, Bit 7].

Table XIV.

Address	Register Setting
00h	FCh
01h	10h
02h	20h
10h	00h
11h	85h
15h	80h
20h	00h
38h	ACh
39h	9Ah
3Ah	88h
3Bh	28h
3Ch	3Fh
3Dh	64h

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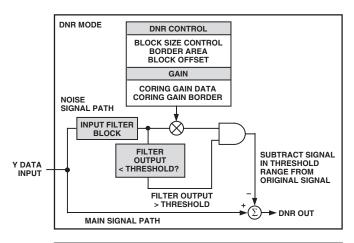
SD Digital Noise Reduction [Subaddress 63h, 64h, 65h]

DNR is applied to the Y data only. A filter block selects the high frequency, low amplitude components of the incoming signal [DNR input select]. The absolute value of the filter output is compared to a programmable threshold value ['DNR threshold control]. There are two DNR modes available: DNR mode and DNR sharpness mode.

In DNR mode, if the absolute value of the filter output is smaller than the threshold, it is assumed to be noise. A programmable amount [coring gain border, coring gain data] of this noise signal will be subtracted from the original signal.

In DNR sharpness mode, if the absolute value of the filter output is less than the programmed threshold, it is assumed to be noise, as before. Otherwise, if the level exceeds the threshold now being identified as a valid signal, a fraction of the signal [coring gain border, coring gain data] will be added to the original signal in order to boost high frequency components and to sharpen the video image.

In MPEG systems, it is common to process the video information in blocks of 8 pixels \times 8 pixels for MPEG2 systems, or 16 pixels \times 16 pixels for MPEG1 systems [block size control]. DNR can be applied to the resulting block transition areas, which are known to contain noise. Generally, the block transition area contains two pixels. It is possible to define this area to contain four pixels [border area].



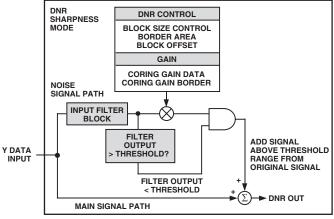


Figure 39. DNR Block Diagram

It is also possible to compensate for variable block positioning or differences in YCrCb pixel timing with the use of the DNR block offset.

The digital noise reduction registers are three 8-bit wide registers. They are used to control the DNR processing.

Coring Gain Border [Address 63h, Bits 3-0]

These four bits are assigned to the gain factor applied to border areas.

In DNR mode, the range of gain values is 0 to 1 in increments of 1/8. This factor is applied to the DNR filter output, which lies below the set threshold range. The result is then subtracted from the original signal.

In DNR sharpness mode, the range of gain values is 0 to 0.5 in increments of 1/16. This factor is applied to the DNR filter output, which lies above the threshold range. The result is added to the original signal.

Coring Gain Data [Address 63h, Bits 7-4]

These four bits are assigned to the gain factor applied to the luma data inside the MPEG pixel block.

In DNR mode, the range of gain values is 0 to 1 in increments of 1/8. This factor is applied to the DNR filter output, which lies below the set threshold range. The result is then subtracted from the original signal.

In DNR sharpness mode, the range of gain values is 0 to 0.5 in increments of 1/16. This factor is applied to the DNR filter output, which lies above the threshold range. The result is added to the original signal.

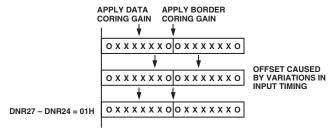


Figure 40. DNR Block Offset Control

DNR Threshold [Address 64h, Bits 5-0]

These six bits are used to define the threshold value in the range of 0 to 63. The range is an absolute value.

Border Area [Address 64h, Bit 6]

In setting this bit to a Logic 1, the block transition area can be defined to consist of four pixels. If this bit is set to a Logic 0, the border transition area consists of two pixels, where one pixel refers to two clock cycles at 27 MHz.

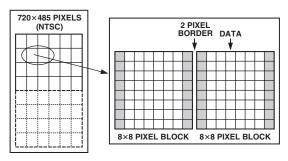


Figure 41. DNR Border Area

Block Size Control [Address 64h, Bit 7]

This bit is used to select the size of the data blocks to be processed. Setting the block size control function to a Logic 1 defines a $16 \text{ pixel} \times 16 \text{ pixel}$ data block and a Logic 0 defines an $8 \text{ pixel} \times 8 \text{ pixel}$ data block, where one pixel refers to two clock cycles at 27 MHz.

DNR Input Select Control [Address 65h, Bit 2-0]

Three bits are assigned to select the filter that is applied to the incoming Y data. The signal that lies in the pass band of the selected filter is the signal that will be DNR processed. Figure 42 shows the filter responses selectable with this control.

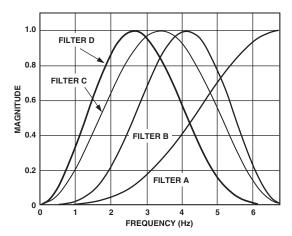


Figure 42. DNR Input Select

DNR Mode Control [Address 65h, Bit 4]

This bit controls the DNR mode selected. A Logic 0 selects DNR mode, a Logic 1 selects DNR sharpness mode.

DNR works on the principle of defining low amplitude, high frequency signals as probable noise and subtracting this noise from the original signal. In DNR mode, it is possible to subtract a fraction of the signal that lies below the set threshold, assumed to be noise, from the original signal. The threshold is set in DNR Register 1.

When DNR sharpness mode is enabled, it is possible to add a fraction of the signal that lies above the set threshold to the original signal, since this data is assumed to be valid data and not noise. The overall effect is that the signal will be boosted (similar to using Extended SSAF filter).

Block Offset Control [Address 65h, Bits 7-4]

Four bits are assigned to this control, which allows a shift of the data block of 15 pixels maximum. Consider the coring gain positions fixed. The block offset shifts the data in steps of one pixel such that the border coring gain factors can be applied at the same position regardless of variations in input timing of the data.

SD ACTIVE VIDEO EDGE

[Subaddress 42h, Bit 7]

When the active video edge is enabled, the first three pixels and the last three pixels of the active video on the luma channel are scaled in such a way that maximum transitions on these pixels are not possible. The scaling factors are $\times 1/8$, $\times 1/2$, and $\times 7/8$. All other active video passes through unprocessed.

SAV/EAV STEP EDGE CONTROL

The ADV7330 has the capability of controlling fast rising and falling signals at the start and end of active video to minimize ringing.

An algorithm monitors SAV and EAV and governs when the edges are too fast. The result will be reduced ringing at the start and end of active video for fast transitions.

Subaddress 42h, Bit 7 = 1 enables this feature.

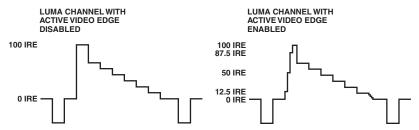


Figure 43. Example for Active Video Edge Functionality

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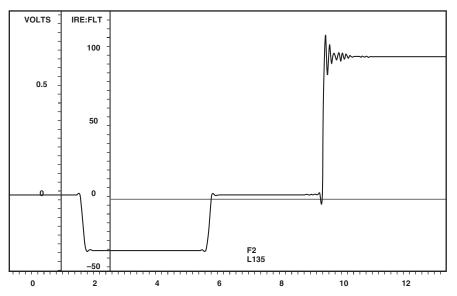


Figure 44. Address 42h, Bit 7 = 0

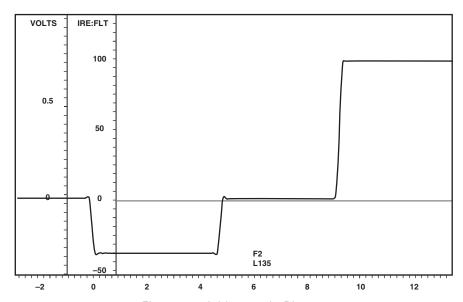


Figure 45. Address 42h, Bit 7 = 1

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BOARD DESIGN AND LAYOUT CONSIDERATIONS DAC Termination and Layout Considerations

The ADV7330 contains an on-board voltage reference. The V_{REF} pin is normally terminated to V_{AA} through a 0.1 μF capacitor when the internal V_{REF} is used. Alternatively, the ADV7330 can be used with an external V_{REF} (AD1580).

The RSET resistors connected between the R_{SET} pin and AGND are used to control the full-scale output current and therefore the DAC voltage output levels. For full-scale output, R_{SET} must have a value of 3040 $\Omega.$ The R_{SET} values should not be changed. R_{LOAD} has a value of 300 Ω for full-scale output.

VIDEO OUTPUT BUFFER AND OPTIONAL OUTPUT FILTER

Output buffering on all three DACs is necessary in order to drive output devices, such as SD or HD monitors.

Analog Devices produces a range of suitable op amps for this application, such as the AD8061. More information on line driver buffering circuits is given in the relevant op amp data sheets.

An optional analog reconstruction low-pass filter (LPF) may be required as an anti-imaging filter if the ADV7330 is connected to a device that requires this filtering.

The filter specifications vary with the application.

Table XV. External Filter Requirements

Application	Oversampling	Cutoff Frequency (MHz)	Attenuation -50 dB @ (MHz)
SD	2×	>6.5	20.5
SD	16×	>6.5	209.5
PS	1×	>12.5	14.5
PS	8×	>12.5	203.5
HDTV	1×	>30	44.25
HDTV	2×	>30	118.5

Table XVI shows possible output rates from the ADV7330.

Table XVI.

Input Mode Address 01h, Bit 6-4	PLL Address 00h, Bit 1	Output Rate	
SD	Off On	27 MHz (2×) 216 MHz (16×)	
PS	Off On	27 MHz (1×) 216 MHz (8×)	
HDTV	Off On	74.25 MHz (1×) 148.5 MHz (2×)	

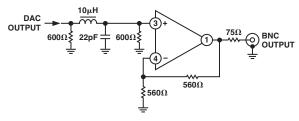


Figure 46. Example for Output Filter for SD, 16 × Oversampling

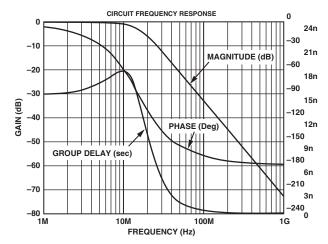


Figure 47. Filter Plot for Output Filter for SD, 16× Oversampling

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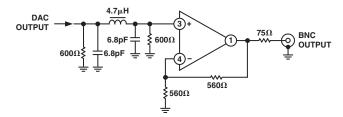


Figure 48. Example Output Filter for PS, 8× Oversampling

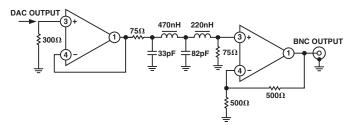


Figure 49. Example Output Filter for HDTV, 2× Oversampling

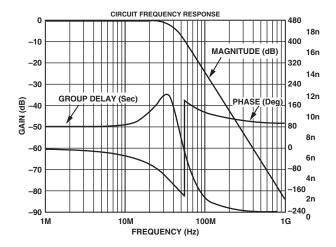


Figure 50. Filter Plot for Output Filter for PS, 8× Oversampling

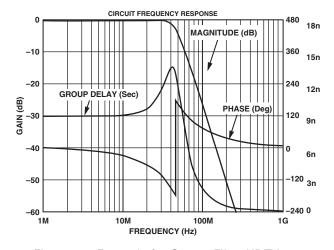


Figure 51. Example for Output Filter HDTV, 2× Oversampling

PC BOARD LAYOUT CONSIDERATIONS

The ADV7330 is optimally designed for low noise performance, both radiated and conducted noise. To complement the excellent noise performance of the ADV7330, it is imperative that great care be given to the PC board layout.

The layout should be optimized for lowest noise on the ADV7330 power and ground lines. This can be achieved by shielding the digital inputs and providing good decoupling. The lead length between groups of V_{AA} and AGND, V_{DD} and DGND, and V_{DD_IO} and GND_IO pins should be kept as short as possible to minimized inductive ringing.

It is recommended that a 4-layer printed circuit board is used with power and ground planes separating the layer of the signal carrying traces of the components and solder-side layer. Component placement should be carefully considered in order to separate noisy circuits, such as crystal clocks, high speed logic circuitry, and analog circuitry.

There should be a separate analog ground plane and a separate digital ground plane.

Power planes should encompass a digital power plane and an analog power plane. The analog power plane should contain the DACs and all associated circuitry, V_{REF} circuitry. The digital power plane should contain all logic circuitry.

The analog and digital power planes should be individually connected to the common power plane at one single point through a suitable filtering device, such as a ferrite bead.

DAC output traces on a PCB should be treated as transmission lines. It is recommended that the DACs be placed as close as possible to the output connector, with the analog output traces being as short as possible (less than 3 inches). The DAC termination resistors should be placed as close as possible to the DAC outputs and should overlay the PCB's ground plane. As well as minimizing reflections, short analog output traces will reduce noise pickup due to neighboring digital circuitry.

To avoid crosstalk between the DAC outputs, it is recommended to leave as much space as possible between the tracks of the individual DAC output pins. The addition of ground tracks between outputs is also recommended.

Supply Decoupling

Noise on the analog power plane can be further reduced by the use of decoupling capacitors.

Optimum performance is achieved by the use of 10 nF and 0.1 μF ceramic capacitors. Each group of $V_{AA},\,V_{DD},$ or V_{DD_IO} pins should be individually decoupled to ground. This should be done by placing the capacitors as close as possible to the device with the capacitor leads as short as possible, thus minimizing lead inductance.

A 1 μ F tantalum capacitor is recommended across the V_{AA} supply in addition to 10 nF ceramic capacitor. See Figure 52.

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Digital Signal Interconnect

The digital signal lines should be isolated as much as possible from the analog outputs and other analog circuitry. Digital signal lines should not overlay the analog power plane.

Due to the high clock rates used, long clock lines to the ADV7330 should be avoided to minimize noise pickup.

Any active pull-up termination resistors for the digital inputs should be connected to the digital power plane and not the analog power plane.

Analog Signal Interconnect

The ADV7330 should be located as close as possible to the output connectors, thus minimizing noise pickup and reflections due to impedance mismatch.

For optimum performance, the analog outputs should each be source and load terminated, as shown in Figure 52. The termination resistors should be as close as possible to the ADV7330 to minimize reflections.

For optimum performance, it is recommended that all decoupling and external components relating to ADV7330 be located on the same side of the PCB and as close as possible to the ADV7330.

Any unused inputs should be tied to ground.

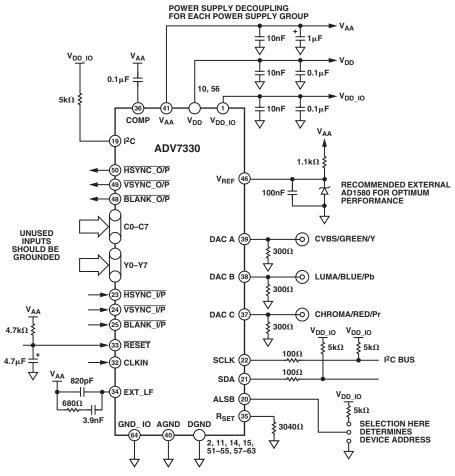


Figure 52. ADV7330 Circuit Layout

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APPENDIX 1—COPY GENERATION MANAGEMENT SYSTEM HD CGMS Data Registers 2-0

[Subaddress 21h, 22h, 23h]

HD CGMS is available in 525p mode only, conforming to 'CGMS-A EIA-J CPR1204-1, Transfer Method of Video ID Information Using Vertical Blanking Interval (525p system), March 1998', and IEC61880, 1998, Video systems (525/60) — video and accompanied data using the vertical blanking intervalanalog interface.

When HD CGMS is enabled [Subaddress 12h, Bit 6 = 1], CGMS data is inserted on Line 41. The HD CGMS data registers are to be found at address 21h, 22h, 23h.

SD CGMS Data Registers 2-0 [Subaddress 59h, 5Ah, 5Bh]

The ADV7330 supports copy generation management system (CGMS) conforming to the standard. CGMS data is transmitted on Line 20 of the odd fields and Line 283 of even fields. Bits C/W05 and C/W06 control whether or not CGMS data is output on odd and even fields. CGMS data can be transmitted only when the ADV7330 is configured in NTSC mode. The CGMS data is 20 bits long; the function of each of these bits is as shown below. The CGMS data is preceded by a reference pulse of the same amplitude and duration as a CGMS bit; see Figure 54.

HD CGMS Data Registers [Subaddress 12h, Bit 6]

The ADV7330 supports copy generation management system (CGMS) in HDTV mode (720p and 1080i) in accordance to EIAJ CPR-1204-2. The HD CGMS data registers are to be found at Addresses 21h, 22h, and 23h.

720p System

CGMS data is applied to Line 24 of the luminance vertical blanking interval.

1080i System

CGMS data is applied to Line 19 and also on Line 582 of the luminance vertical blanking interval.

CGMS CRC Functionality

If SD CGMS CRC [Address 59h, Bit 4] or PS/HD CGMS CRC [Subaddress 12h, Bit 7] is set to Logic 1, the last six bits, C19–C14, which comprise the 6-bit CRC check sequence, are calculated automatically on the ADV7330 based on the lower 14 bits (C0–C13) of the data in the data registers and output with the remaining 14 bits to form the complete 20 bits of the CGMS data. The calculation of the CRC sequence is based on the polynomial $x^6 + x + 1$ with a preset value of 111111. If SD CGMS CRC [Address 59h, Bit 4] or PS/HD CGMS CRC [Subaddress 12h, Bit 7] is set to Logic 0, all 20 bits (C0–C19) are output directly from the CGMS registers (no CRC calculated, must be calculated by the user).

Function of CGMS Bits

Word 0-6 bits; Word 1-4 bits; Word 2-6 bits; CRC 6 bits; CRC polynomial = $x^6 + x + 1$ (preset to 111111).

Table XVII.

Bit	Function		
WORD0		1	0
B1	Aspect ratio	16:9	4:3
B2	Display format	Letterbox	Normal
B3	Undefined		
WORD0			
B4, B5, B6	Identification information about video and other signals (e.g., audio)		
WORD1			
B7, B8, B9, B10	Identification sign	nal incidental 1	o Word 0
WORD2			
B11, B12, B13, B14	Identification sig		nation

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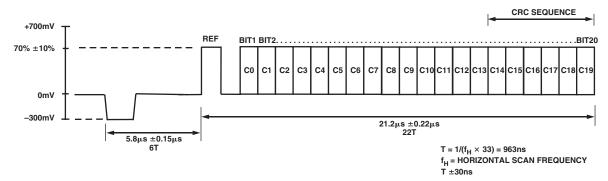


Figure 53. PS CGMS Waveform

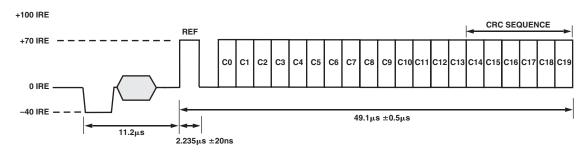


Figure 54. SD CGMS Waveform

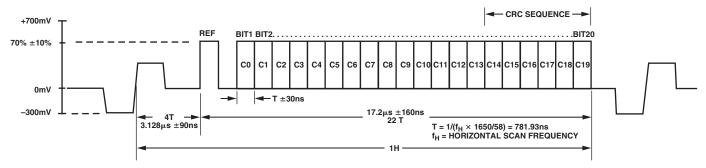


Figure 55. HDTV 720p CGMS Waveform

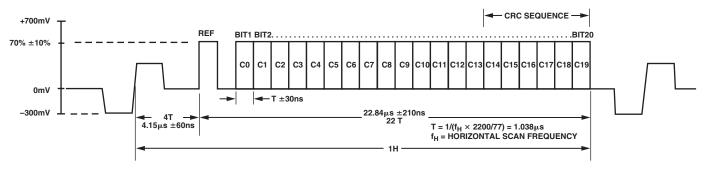


Figure 56. HDTV 1080i CGMS Waveform

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APPENDIX 2—SD WIDE SCREEN SIGNALING [Subaddress 59h, 5Ah, 5Bh]

The ADV7330 supports wide screen signaling (WSS) conforming to the standard. WSS data is transmitted on Line 23. WSS data can be transmitted only when the ADV7330 is configured in PAL mode. The WSS data is 14 bits long, and the function of each of these bits is shown in Table XVII. The WSS data is

preceded by a run-in sequence and a start code (see Figure 57). If SD WSS [Address 59h, Bit 7] is set to Logic 1, it enables the WSS data to be transmitted on Line 23. The latter portion of Line 23 (42.5 μs from the falling edge of \overline{HSYNC}) is available for the insertion of video.

It is possible to blank the WSS portion of Line 23 with Subaddress 61h, Bit 7.

Table V	VIII	Function	of WSS	Rite
I able A	V 111.	runction	01 11 33	o Dito

Bit				Description			Bit	Description
Bit 0–Bit 2				Aspect Ratio/Format/Position		B6		
Bit 3 B0, B1, B2 B3		Odd Parity Check of Bit 0 to Bit 2 Aspect Ratio Format Position		0 1 B7	No Helper Modulated Helper Reserved			
0 1 0 1 0 1 0	0 0 1 1 0 0 1 1	0 0 0 1 1 1 1	1 0 0 1 1 1 0	4:3 14:9 14:9 16:9 16:9 >16:9 14:9 16:9	Full Format Letterbox Letterbox Letterbox Letterbox Letterbox Full Format N/A	N/A Center Top Center Top Center Center Center N/A	B9 B10 0 0 1 0 0 1 1 1 B11	No Open Subtitles Subtitles in Active Image Area Subtitles out of Active Image Area Reserved No Surround Sound Information Surround Sound Mode
B4 0 1 B5 0 1				Camera Mod Film Mode Standard Coo Motion Adap		,	B12 B13	Reserved Reserved

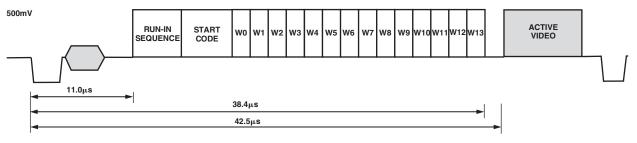


Figure 57. WSS Waveform Diagram

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APPENDIX 3—SD CLOSED CAPTIONING [Subaddress 51h-54h]

The ADV7330 supports closed captioning conforming to the standard television synchronizing waveform for color transmission. Closed captioning is transmitted during the blanked active line time of Line 21 of the odd fields and Line 284 of even fields.

Closed captioning consists of a 7-cycle sinusoidal burst that is frequency and phase locked to the caption data. After the clock run-in signal, the blanking level is held for two data bits and is followed by a Logic 1 start bit. Sixteen bits of data follow the start bit. These consist of two 8-bit bytes, seven data bits and one odd parity bit. The data for these bytes is stored in the SD closed captioning registers (Address 53h–54h).

The ADV7330 also supports the extended closed captioning operation, which is active during even fields and is encoded on Scan Line 284. The data for this operation is stored in the SD closed captioning registers (Address 51h–52h).

All clock run-in signals and timing to support closed captioning on Lines 21 and 284 are generated automatically by the ADV7330. All pixel inputs are ignored during Lines 21 and 284 if closed captioning is enabled.

FCC Code of Federal Regulations (CFR) 47 section 15.119 and EIA608 describe the closed captioning information for Lines 21 and 284.

The ADV7330 uses a single buffering method. This means that the closed captioning buffer is only one byte deep; therefore there will be no frame delay in outputting the closed captioning data unlike other 2-byte deep buffering systems. The data must be loaded one line before (Line 20 or Line 283) it is output on Lines 21 and 284. A typical implementation of this method is to use \$\overline{VSYNC}\$ to interrupt a microprocessor, which in turn will load the new data (two bytes) every field. If no new data is required for transmission, 0s must be inserted in both data registers; this is called *nulling*. It is also important to load control codes, all of which are double bytes on Line 21 or a TV will not recognize them. If there is a message like "Hello World" that has an odd number of characters, it is important to pad it out to even in order to get "end of caption" 2-byte control code to land in the same field.

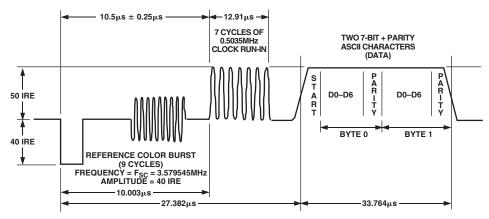


Figure 58. Closed Captioning Waveform, NTSC

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APPENDIX 4—TEST PATTERNS

The ADV7330 can generate SD and HD test patterns.

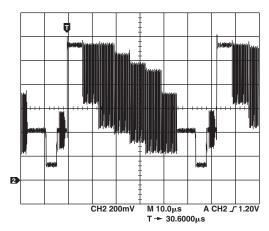


Figure 59. NTSC Color Bars

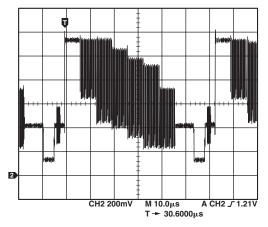


Figure 60. PA0L Color Bars

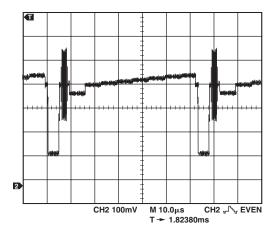


Figure 61. NTSC Black Bar (-21 mV, 0 mV, +3.5 mV, +7 mV, +10.5 mV, +14 mV, +18 mV, +23 mV)

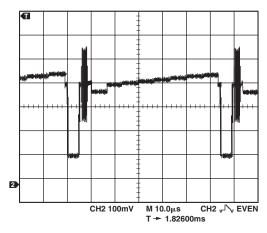


Figure 62. PAL Black Bar (-21 mV, 0 mV, +3.5 mV, +7 mV, +10.5 mV, +14 mV, +18 mV, +23 mV)

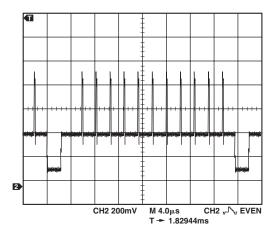


Figure 63. 525p Hatch Pattern

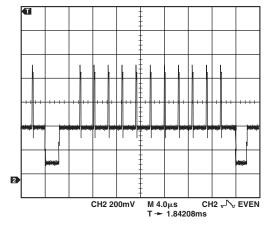


Figure 64. 625p Hatch Pattern

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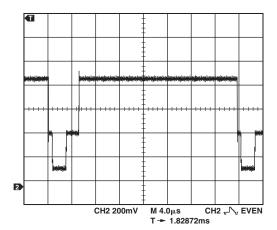


Figure 65. 525p Field Pattern

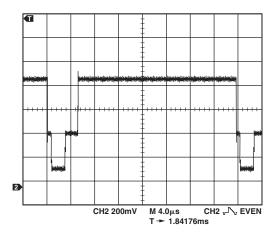


Figure 66. 625p Field Pattern

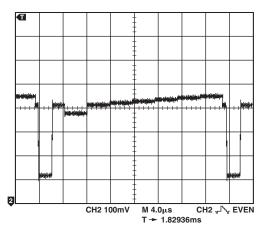


Figure 67. 525p Black Bar (–35 mV, 0 mV, +7 mV, +14 mV, +21 mV, +28 mV, +35 mV)

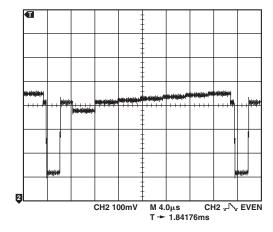


Figure 68. 625p Black Bar (-35 mV, 0 mV, +7 mV, +14 mV, +21 mV, +28 mV, +35 mV)

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The following register settings are used to generate a SD NTSC CVBS output on DAC A:

Subaddress	Register Setting
00h	10h
40h	10h
42h	40h
44h	40h
4Ah	08h

All other registers are set to normal/default.

For PAL CVBS output on DAC A, the same settings are used except that subaddress = 40h and register setting = 11h.

The following register settings are used to generate an SD NTSC black bar pattern output on DAC A:

Subaddress	Register Setting
00h	10h
02h	04h
40h	10h
42h	40h
44h	40h
4Ah	08h

All other registers are set to normal/default.

For PAL black bar pattern output on DAC A, the same settings are used except that subaddress = 40h and register setting = 11h.

The following register settings are used to generate a 525p hatch pattern on DAC A:

Subaddress	Register Setting
00h	10h
01h	10h
10h	40h
11h	05h
16h	A0h
17h	80h
18h	80h

All other registers are set to normal/default.

For 625p hatch pattern on DAC A, the same register settings are used except that subaddress = 10h and register setting = 50h.

For a 525p black bar pattern output on DAC A, the same settings are used as above except that subaddress = 02h and register setting = 24h.

For 625p black bar pattern output on DAC A, the same settings are used as above except that subaddress = 02h and register setting = 24h; and subaddress = 10h and register setting = 50h.

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APPENDIX 5—SD TIMING MODES [Subaddress 4Ah]

Mode 0 (CCIR-656)—Slave Option (Timing Register 0 TR0 = X X X X X 0 0 0)

The ADV7330 is controlled by the SAV (start active video) and EAV (end active video) time codes in the pixel data. All timing information is transmitted using a 4-byte synchronization pattern. A synchronization pattern is sent immediately before and after each line during active picture and retrace. VSYNC_O/P, HSYNC_O/P, and BLANK_O/P (if not used) pins should be tied high during this mode. Blank output is available.

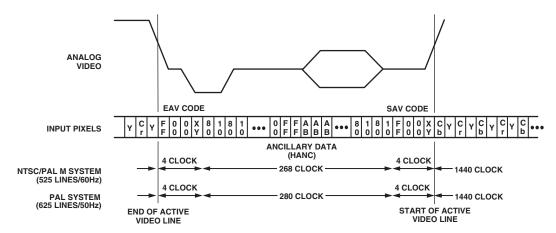
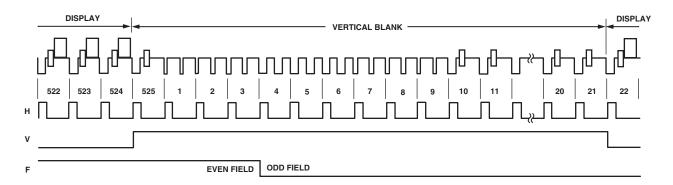


Figure 69. SD Slave Mode 0

Mode 0 (CCIR-656)—Master Option

(Timing Register 0 TR0 = X X X X X 0 0 1)

The ADV7330 generates H, V, and F signals required for the SAV (start active video) and EAV (end active video) time codes in the CCIR656 standard. The H bit is output on $\overline{HSYNC_O/P}$, the V bit is output on $\overline{BLANK_O/P}$, and the F bit is output on $\overline{VSYNC_O/P}$ pin.



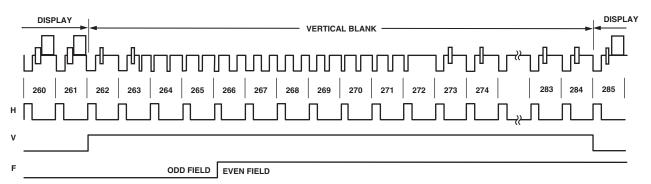
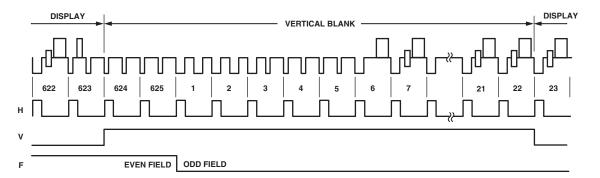


Figure 70. SD Master Mode 0 (NTSC)



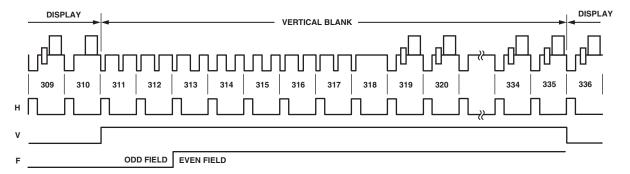


Figure 71. SD Master Mode 0 (PAL)

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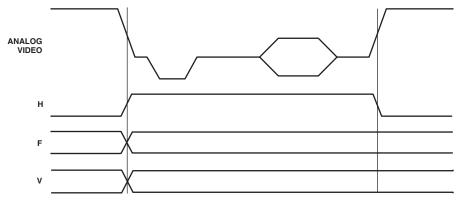


Figure 72. SD Master Mode 0, Data Transitions

Mode 1—Slave Option

(Timing Register 0 TR0 = X X X X X 0 1 0)

In this mode, the ADV7330 accepts horizontal SYNC and odd/even field signals. A transition of the field input when HSYNC_I/P is low indicates a new frame i.e., vertical retrace. The BLANK_I/P signal is optional. When the BLANK_I/P input is disabled, the ADV7330 automatically blanks all normally blank lines as per CCIR-624. HSYNC is applied to the HSYNC_I/P pin, BLANK to the BLANK_I/P pin, and Field to the VSYNC_I/P pin.

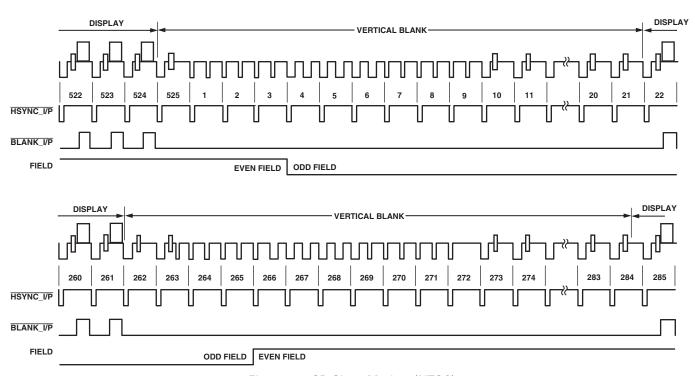


Figure 73. SD Slave Mode 1 (NTSC)

Mode 1-Master Option

(Timing Register 0 TR0 = X X X X X 0 1 1)

In this mode, the ADV7330 can generate horizontal sync and odd/even field signals. A transition of the field output when $\overline{HSYNC_O/P}$ is low indicates a new frame i.e., vertical retrace. The blank signal is optional. Pixel data is latched on the rising clock edge following the timing signal transitions. \overline{HSYNC} is output on the $\overline{HSYNC_O/P}$ pin, \overline{BLANK} on the $\overline{BLANK_O/P}$ pin, and Field on the $\overline{VSYNC_O/P}$ pin.

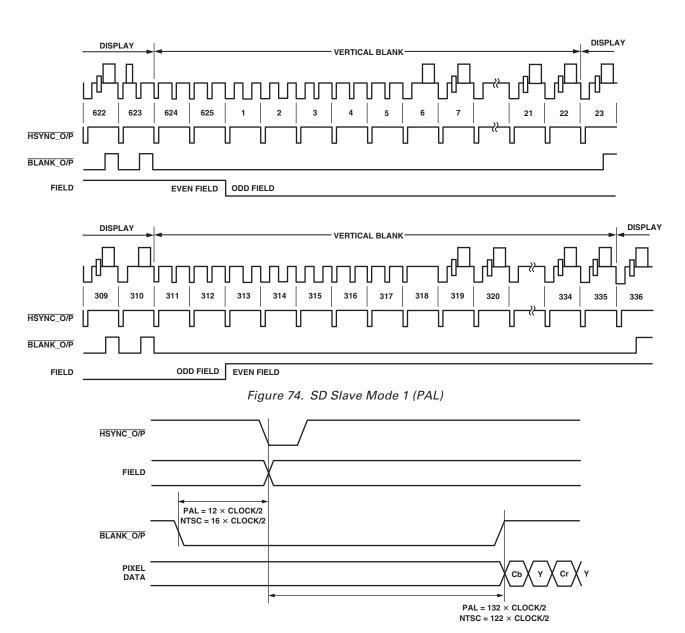


Figure 75. SD Timing Mode 1—Odd/Even Field Transitions Master/Slave

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Mode 2—Slave Option

(Timing Register 0 TR0 = X X X X X 1 0 0)

In this mode, the ADV7330 accepts horizontal and vertical sync signals. A coincident low transition of both $\overline{HSYNC_I/P}$ and $\overline{VSYNC_I/P}$ inputs indicates the start of an odd field. A $\overline{VSYNC_I/P}$ low transition when $\overline{HSYNC_I/P}$ is high indicates the start of an even field. The blank signal is optional. When the blank input is disabled, the ADV7330 automatically blanks all normally blank lines as per CCIR-624. \overline{HSYNC} is input on the $\overline{HSYNC_I/P}$ pin, \overline{BLANK} on the $\overline{BLANK_I/P}$ pin, and \overline{VSYNC} on the $\overline{VSYNC_I/P}$ pin.

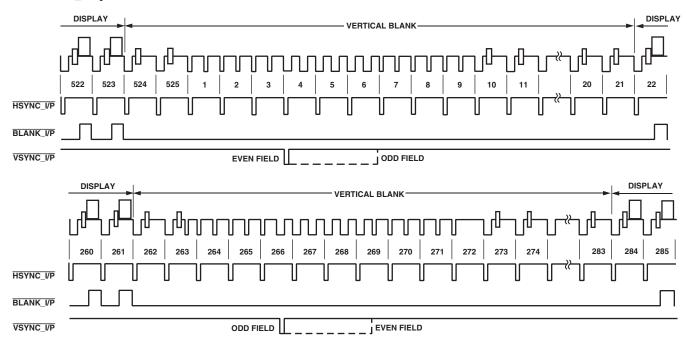


Figure 76. SD Slave Mode 2 (NTSC)

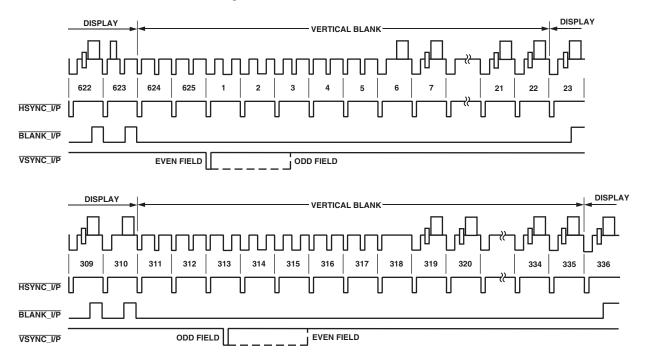


Figure 77. SD Slave Mode 2 (PAL)

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Mode 2-Master Option

(Timing Register 0 TR0 = X X X X X 1 0 1)

In this mode, the ADV7330 can generate horizontal and vertical sync signals. A coincident low transition of both $\overline{HSYNC_O/P}$ and $\overline{VSYNC_O/P}$ outputs indicates the start of an odd field. A $\overline{VSYNC_O/P}$ low transition when $\overline{HSYNC_O/P}$ is high indicates the start of an even field. \overline{HSYNC} is output on the $\overline{HSYNC_O/P}$ pin, \overline{BLANK} on the $\overline{BLANK_O/P}$ pin, and \overline{VSYNC} on the $\overline{VSYNC_O/P}$ pin.

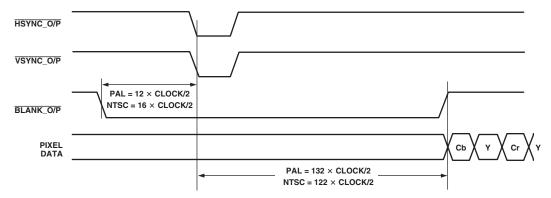


Figure 78. SD Timing Mode 2—Even to Odd Field Transition Master/Slave

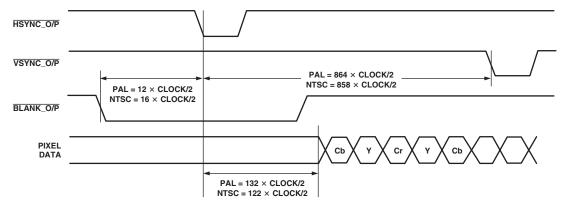


Figure 79. SD Timing Mode 2—Odd to Even Field Transition Master/Slave

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Mode 3—Master/Slave Option

(Timing Register 0 TR0 = X X X X X 1 1 0 or X X X X X 1 1 1)

In this mode, the ADV7330 accepts or generates horizontal sync and odd/even field signals. A transition of the field input when HSYNC_I/P is high indicates a new frame, i.e., vertical retrace. The BLANK_I/P signal is optional. When the BLANK_I/P input is disabled, the ADV7330 automatically blanks all normally blank lines as per CCIR-624. HSYNC is interfaced on HSYNC_I/P, BLANK on BLANK_I/P, VSYNC on VSYNC_I/P.

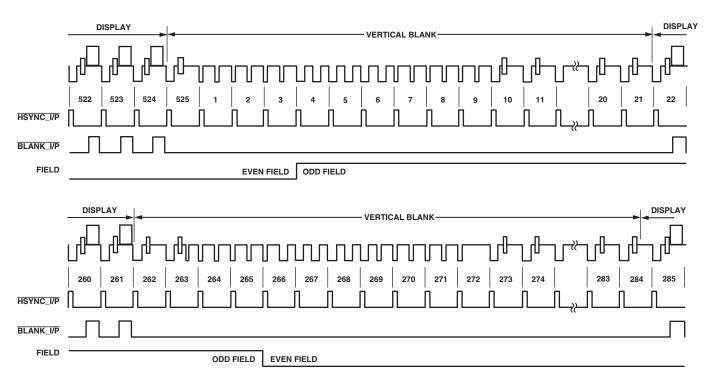


Figure 80. SD Timing Mode 3 (NTSC)

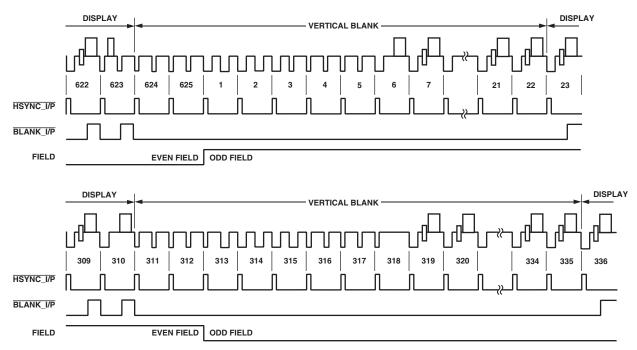
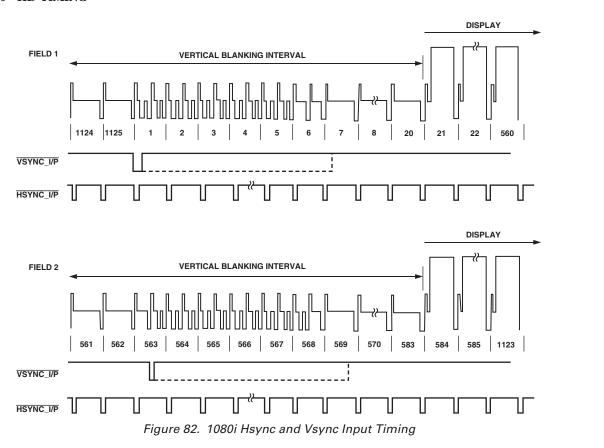


Figure 81. SD Timing Mode 3 (PAL)

APPENDIX 6—HD TIMING



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APPENDIX 7—VIDEO OUTPUT LEVELS

HD YPrPb Output Levels

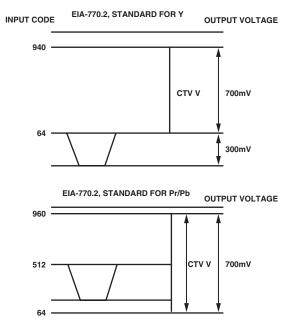


Figure 83. EIA 770.2 Standard Output Signals (525p/625p)

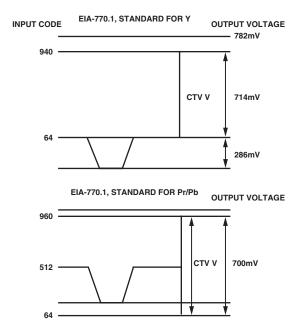


Figure 84. EIA 770.1 Standard Output Signals (525p/625p)

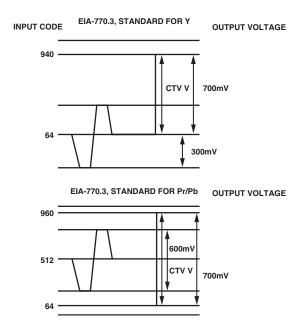
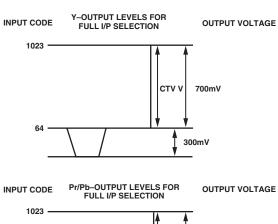


Figure 85. EIA 770.3 Standard Output Signals (1080i, 720p)



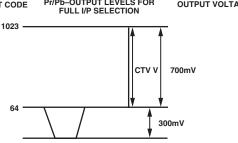


Figure 86. Output Levels for Full I/P Selection

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RGB Output Levels

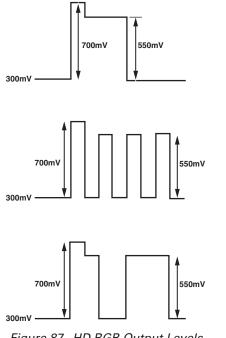


Figure 87. HD RGB Output Levels

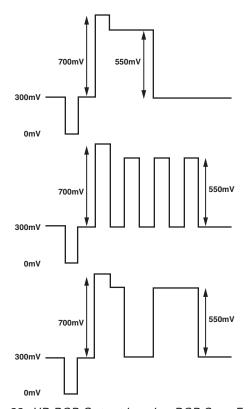


Figure 88. HD RGB Output Levels—RGB Sync Enabled

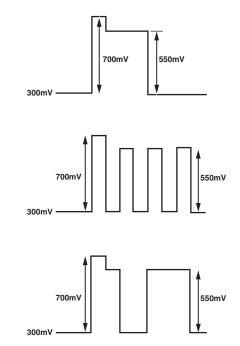


Figure 89. SD RGB Output Levels—RGB Sync Disabled

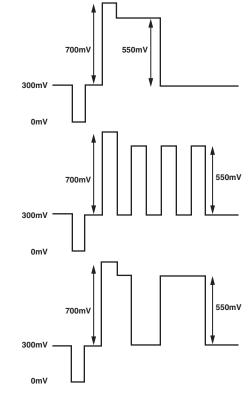


Figure 90. SD RGB Output Levels—RGB Sync Enabled

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YPrPb Output Levels

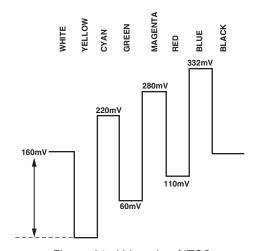


Figure 91. U Levels—NTSC

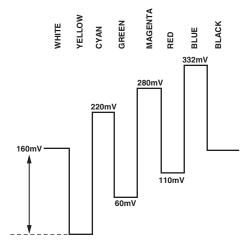


Figure 92. U Levels-PAL

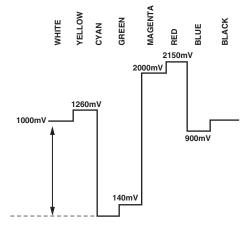


Figure 93. U Levels—NTSC

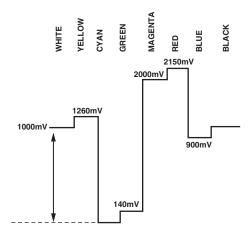


Figure 94. U Levels—PAL

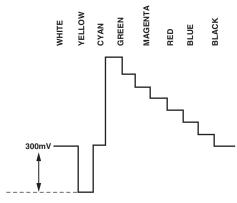


Figure 95. Y Levels—NTSC

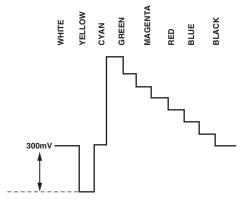


Figure 96. Y Levels—PAL

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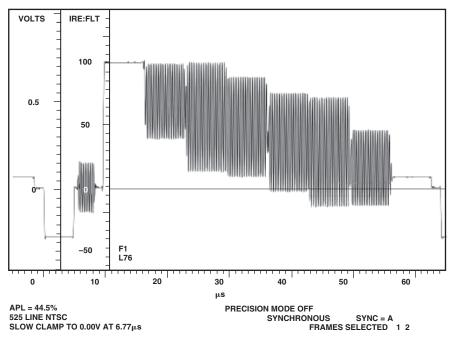


Figure 97. NTSC Color Bars 75%

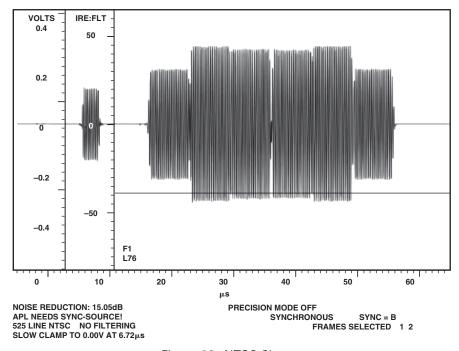


Figure 98. NTSC Chroma

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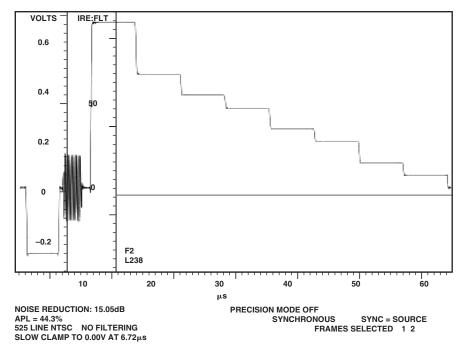


Figure 99. NTSC Luma

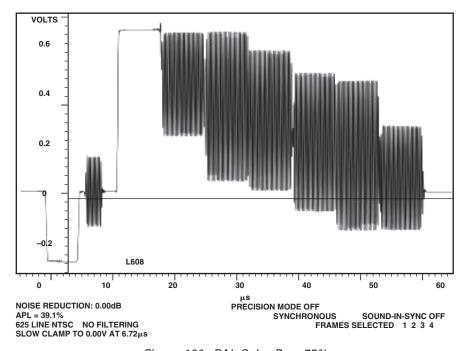


Figure 100. PAL Color Bars 75%

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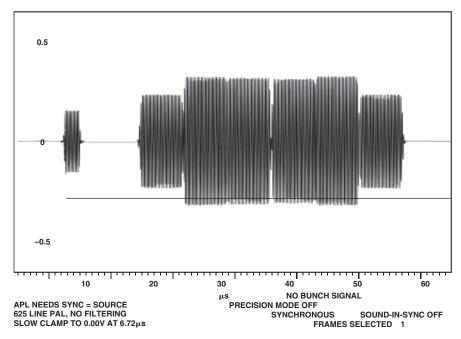


Figure 101. PAL Chroma

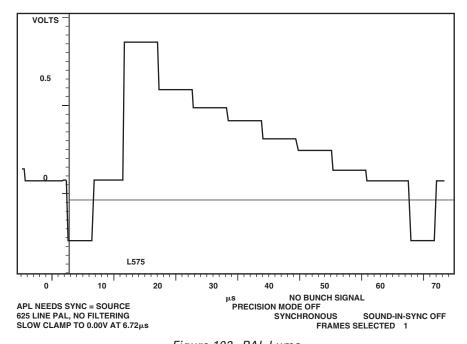
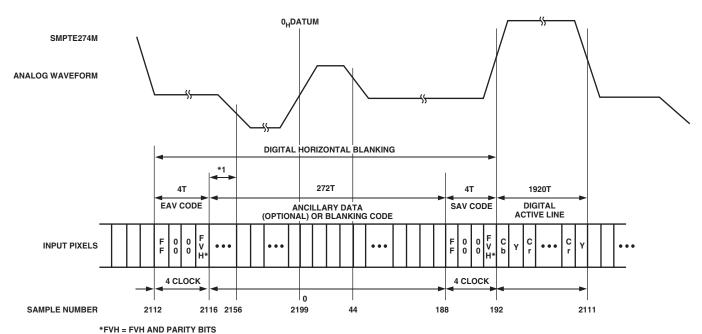


Figure 102. PAL Luma

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APPENDIX 8—VIDEO STANDARDS

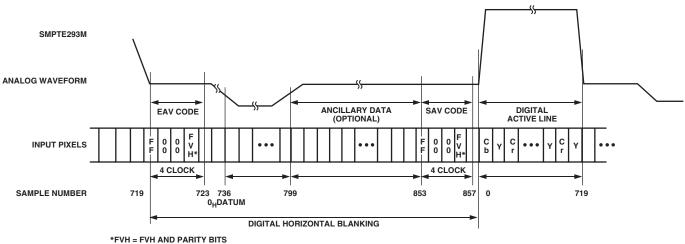


*FVH = FVH AND PARITY BITS SAV/EAV: LINE 1–562: F = 0 SAV/EAV: LINE 563–1125: F = 1

SAV/EAV: LINE 1-20; 561-583; 1124-1125: V = 1 SAV/EAV: LINE 21-560; 584-1123: V = 0

FOR A FIELD RATE OF 30Hz: 40 SAMPLES FOR A FIELD RATE OF 25Hz: 480 SAMPLES

Figure 103. EAV/SAV Input Data Timing Diagram—SMPTE 274M



*FVH = FVH AND PARITY BIT: SAV: LINE 43–525 = 200H SAV: LINE 1–42 = 2AC EAV: LINE 43–525 = 274H EAV: LINE 1–42 = 2D8

Figure 104. EAV/SAV Input Data Timing Diagram-SMPTE 293M

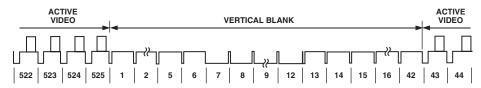


Figure 105. SMPTE 293M (525p)

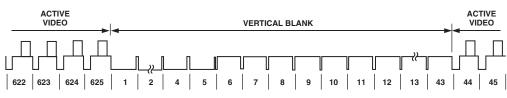


Figure 106. ITU-R BT.1358 (625p)

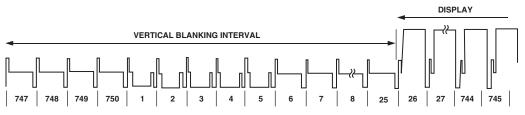
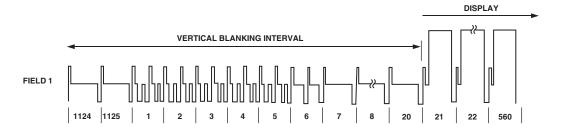


Figure 107. SMPTE 296M (720p)



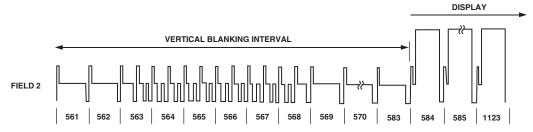


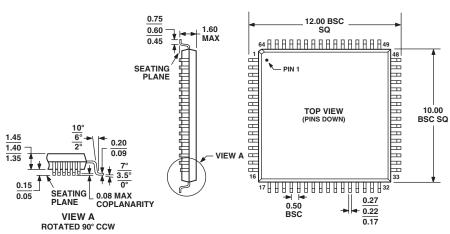
Figure 108. SMPTE 274M (1080i)

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OUTLINE DIMENSIONS

64-Lead Low Profile Quad Flat Package [LQFP] (ST-64-2)

Dimensions shown in millimeters



COMPLIANT TO JEDEC STANDARDS MS-026BCD

Revision History

Location	Page
7/04—Data sheet changed from REV. A to REV. B.	
Changes to ABSOLUTE MAXIMUM RATINGS	
Changes to PIN CONFIGURATION	
Changes to PIN FUNCTION DESCRIPTIONS	
5/04—Data sheet changed from REV. 0 to REV. A.	
Changes to Absolute Maximum Ratings	
Change to Mode Register 0, SD Sync and HD Sync	
Removed Footnote 2	
Change to HD Mode Register 5, Bit 6	
Removed Footnote 2	
Change to Register 43h, Bit 7	
Change to Figure 23	32
Change to Equations	33
Changes to Figures 105 and 106	

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www.datasheetcatalog.com

Datasheets for electronics components.