

## ATT20C497 CMOS RAMDAC

### Features

- Similar functionality and footprint to ATT20C478A/477A/476A/475A
- 110/80/50 MHz operation
- Powers down to 3 mA typical while retaining color RAM updates
- Low power dissipation 0.5 W typical
- 8-bit pseudocolor
- Internal  $V_{REF}$  accuracy better than  $\pm 3\%$
- External  $V_{REF}$  option
- Auto  $V_{REF}$  disable during powerdown
- On-chip output comparators for monitor detection
- Antisparkle circuitry
- VGA accessible control register
- Software identification
- Program DACs to 8 bits or 6 bits
- 256 x 24 (18) color RAM
- 15 x 24 (18) overlay RAM
- Programmable synchronization signal (R, G, B)
- Pin programmable blank pedestal
- RS-343A, RS-170, and  $PS/2^*$  compatible
- Monolithic 0.9  $\mu\text{m}$  CMOS
- 44-pin PLCC industry-standard compatible footprints

### Applications

- Desktop, laptop, and notebook PCs
- Screen resolutions
  - 1280 x 1024, 60 Hz noninterlaced
  - 1024 x 768, 85 Hz noninterlaced

\*  $PS/2$  is a registered trademark of International Business Machines Corporation.

### Application Differences

(From the ATT20C478A/477A/476A/475A)

- When placing an ATT20C497 into ATT20C478A RAMDAC socket, make sure socket pin 1 is not grounded or tied to  $V_{CC}$ . Pin 1 is an active output for the ATT20C497.
- See page 9 for additional details on the differences between the ATT20C47XA family and the ATT20C497.

### Description

The ATT20C497 RAMDAC is designed to increase speed and reduce power in the digital-to-analog conversion of frame buffer images.

This device can replace the ATT20C478A/477A/476A/475A RAMDACs (see Application Differences section). The ATT20C497 adds the ability to access the control register by executing multiple reads to the read mask register. Software can differentiate between ATT20C49X devices using an embedded read operation.

A microprocessor port configures the internal registers and writes and reads the color and overlay RAM. The ATT20C497 powers down to less than or equal to 3 mA total current while retaining palette data and read/write capability. The device has three 8-bit video DACs with antisparkle circuitry. On-chip comparators detect connection to a monitor. An on-chip voltage reference is accurate to better than  $\pm 3\%$ .

The device is offered in the industry-standard 44-pin PLCC package and compatible footprint. It is designed to work with an internal or external voltage reference only.

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Description (continued)

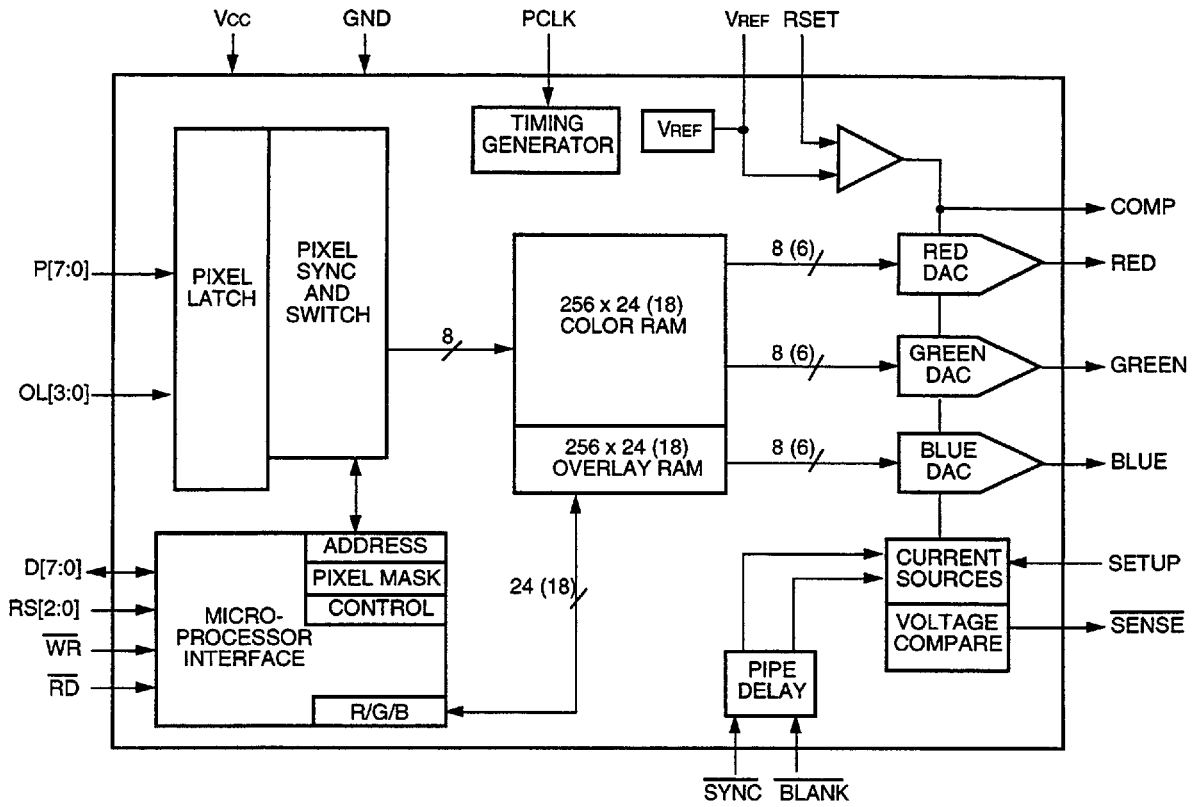
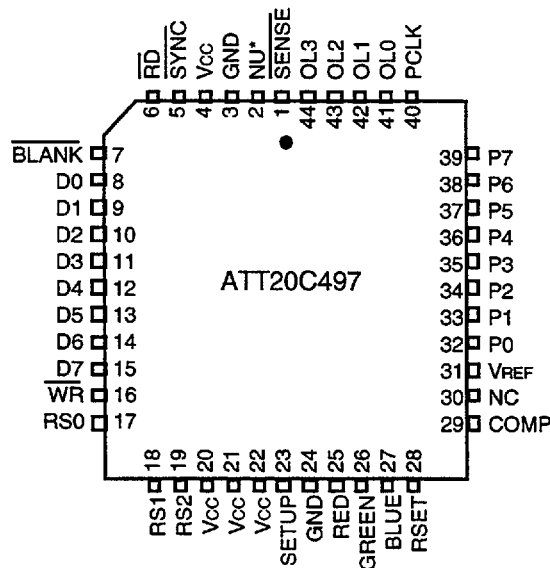


Figure 1. Block Diagram

Pin Information



\* NU = this pin is not used; tie to Vcc or GND.

Figure 2. 44-Pin PLCC Pin Diagram

## Pin Information (continued)

Table 1. Pin Descriptions

ATT20C497 Pin #	Symbol	Type	Name/Function
1	$\overline{\text{SENSE}}$	O	<b><math>\overline{\text{SENSE}}</math> (Active-Low).</b> TTL compatible. Monitor detection signal. $\overline{\text{SENSE}}$ is a logic 0 if one or more of the red, green, or blue outputs have exceeded the internal voltage reference level of 340 mV. $\overline{\text{SENSE}}$ may not be stable while SYNC is toggling.
2	Not Used	I	<b>Not Used.</b> Tie to Vcc or GND. <b>Note:</b> The ATT20C478A/477A devices can use this pin as an input to control switching between 8- and 6-bit modes. This can be accomplished on the ATT20C497 and the ATT20C478A/477A with control register bit CR1.
3, 24	GND	—	<b>Ground.</b>
4, 20—22	Vcc	—	<b>Power.</b>
5	$\overline{\text{SYNC}}$	I	<b><math>\overline{\text{SYNC}}</math> (Active-Low).</b> TTL compatible. Latched on the rising edge of PCLK. $\overline{\text{SYNC}}$ removes a 7.62 mA (RS-343A) current source from each RGB output. For $\overline{\text{SYNC}}$ to operate properly, it should be asserted only during blanking. For systems having a sync signal separate from the RAMDAC, $\overline{\text{SYNC}}$ should be tied low to turn off the sync current source.
6	$\overline{\text{RD}}$	I	<b>Read (Active-Low).</b> TTL compatible. When $\overline{\text{RD}}$ is low, data transfers from the selected internal register to the data bus. RS[2:0] is latched on the falling edge of $\overline{\text{RD}}$ .
7	$\overline{\text{BLANK}}$	I	<b><math>\overline{\text{BLANK}}</math> (Active-Low).</b> TTL compatible. $\overline{\text{BLANK}}$ is latched on the rising edge of PCLK. When $\overline{\text{BLANK}}$ is low, the 1.44 mA current source on the analog outputs will be turned off. The DACs ignore digital input from memory. The RAMDAC and overlay memory can be updated during blanking.
8—15	D[7:0]	I/O	<b>Data Bus.</b> TTL compatible. Data is transferred between the data bus and the internal registers under control of the $\overline{\text{RD}}$ / $\overline{\text{WR}}$ signals. In an MPU write operation, D[7:0] is latched on the rising edge of $\overline{\text{WR}}$ . To read data D[7:0] from the device, $\overline{\text{RD}}$ must be active. The rising edge of the $\overline{\text{RD}}$ signal indicates the end of a read cycle. Following the read cycle, the data bus will go to a high-impedance state. For 6-bit operation, color data is contained in the lower 6 bits of the data bus. D0 is the LSB, and D5 is the MSB. When the MPU writes color data, D6 and D7 are ignored. During MPU read cycles, D6 and D7 are a logic 0.
16	$\overline{\text{WR}}$	I	<b>Write (Active-Low).</b> TTL compatible. $\overline{\text{WR}}$ controls the data transfer from the data bus to the selected internal register. D[7:0] data is latched at the rising edge of $\overline{\text{WR}}$ , and RS[2:0] data is latched at the falling edge of $\overline{\text{WR}}$ .
17—19	RS[2:0]	I	<b>Register Select.</b> TTL compatible. These inputs are sampled on the falling edge of the $\overline{\text{RD}}$ or $\overline{\text{WR}}$ to determine which one of the internal registers is to be accessed. RS2 is not needed to access the control register. See the Control Register section under Internal Registers.

## Pin Information (continued)

Table 1. Pin Descriptions (continued)

ATT20C497 Pin #	Symbol	Type	Name/Function
23	SETUP	I	<b>Blank Pedestal Setup.</b> TTL compatible. A logic high will cause a blanking pedestal of 1.44 mA on an RS-343A output.
25 26 27	RED GREEN BLUE	O	<b>Color Signals.</b> These pins are analog outputs. These high-impedance current sources are capable of driving a double-terminated 75 $\Omega$ coaxial cable.
28	RSET	I	<b>Reference Resistor.</b> An external resistor (RSET) is connected between the RSET pin and GND to control the magnitude of the full-scale current. Refer to DAC Gain section under Functional Description.
29	COMP	—	<b>Compensation Pin.</b> Bypass this pin with an external 0.1 $\mu$ F capacitor to Vcc.
30	NC	—	<b>No Connect.</b> No internal connection to the chip.
31	VREF	I	<b>Voltage Reference.</b> If an external voltage is used, supply this input with a 1.235 V reference. This node is disabled internally during powerdown.
32—39	P[7:0]	I	<b>Pixel Address.</b> TTL compatible. These pins are latched on the rising edge of PCLK. Pixels are presented as addresses to look up color data in the color RAM. Unused inputs should be connected to GND.
40	PCLK	I	<b>Pixel Clock.</b> TTL compatible. The duty cycle of the clock should be between 40% and 60%. The rising edge of the pixel clock latches the pixel address, BLANK, and SYNC inputs. The pixel clock controls the four-stage video pipelined operation.
41—44	OL[3:0]	I	<b>Overlay Address.</b> TTL compatible. These pins are latched on the rising edge of PCLK. These inputs are used to specify one of the 15 addresses of the color overlays. When the overlay address is non-zero, the pixel address inputs are ignored. Unused inputs should be connected to GND.

## Internal Registers

Table 2. Register Map

The following table shows the locations of the address and control registers and also the pixel and overlay color RAMs.

RS2	RS1	RS0	Addressed by the MPU
0	0	0	Address register (RAM write mode)
0	1	1	Address register (RAM read mode)
0	0	1	Pixel color RAM
0	1	0	Pixel read mask register
1	0	0	Address register (overlay write mode)
1	1	1	Address register (overlay read mode)
1	0	1	Overlay color RAM
1	1	0	Control register*

\* The control register can be accessed by reading the read mask register four times. Refer to Control Register Access Using the RMR section under Internal Registers (page 7).

**Internal Registers** (continued)**Table 3. Control Register**

This register is operational on powerup. It can be read or written to by the MPU at any time and is not initialized. This register may be written using RS[2:0] as address pins or may be written or read by first reading the read mask register as specified in the Control Register Access Using the RMR section (page 7).

Bit	Name/Description
CR[7:5]	<p><b>Software Identification Bits.</b> See the Software Identification section and Figure 3. <b>Note:</b> These bits can be written and read and will not affect the function of the device.</p>
CR[4:2]	<p><b>Sync Enable.</b> Logic 0: Sync disabled. Logic 1: Sync enabled. Bits CR4, CR3, and CR2, respectively, specify whether the blue, green, or red outputs will have sync offset current. A logic 1 specifies sync current. The sync currents enabled by CR4, CR3, and CR2 are controlled by the SYNC pin. For noncomposite sync, tie the SYNC pin to logic 0.</p>
CR1	<p><b>8-/6-bit Select.</b> Logic 0: 6 bit. Logic 1: 8 bit. A logic 1 specifies 8-bit color operation (16M possible colors). A logic 0 specifies 6-bit color operation (256K possible colors).</p>
CR0	<p><b>Sleep Enable.</b> Logic 0: Normal operation. Logic 1: Sleep mode. If this bit is logic 0, the device will be in normal operation. If this bit is logic 1, the DAC is turned off and the palette RAM is powered down. The RAM retains data and will wake up to accept inputs from the MPU port. After accepting MPU data, the RAM returns to the sleep state. After programming the device for normal operation, valid data will appear at the DAC outputs in about one second.</p>

## Internal Registers (continued)

### Pixel Read Mask Register (RMR)

The contents of the pixel read mask register (RMR) may be accessed by the MPU at any time and are not initialized. The RMR bits are logically ANDed with the 8-bit pixels. A logic one stored in a data bit of the RMR leaves the corresponding bit in the pixel unchanged. A logic zero in the RMR sets the pixel bit to zero. Bit D0 of the RMR corresponds to pixel bit P0. By reading the RMR four times, the control register will be accessed on the next read or write to the RMR (see Control Register Access Using the RMR).

### Control Register

The control register may be written to or read by the MPU at any time and is not initialized. CR0 is the least significant bit and corresponds to D0 of the MPU port. Table 3 defines the bits of the control register. Bits CR[7:5] may be written or read at any time and will return the value written. These bits do not affect the functionality of the device. These bits may also be used for software identification (see Software Identification section).

Bits CR[4:2] indicate which analog channels will have sync information present. CR1 controls whether 8 bits or 6 bits of color information are being passed over the D[7:0] port and whether the DACs are 8 bits or 6 bits. A logical one in bit CR0 puts the RAMDAC to sleep. While asleep, the RAMDAC wakes up to accept updates to the color RAM, and then goes back to sleep. Hence, the device tracks color changes to the color look-up table while utilizing minimum power.

### Control Register Access Using the RMR

For graphics systems controllers that do not have a control signal for RS2, the control register may be accessed by using the following sequence of events: A flag will be set when the ADDR is read once, and then the RMR (RS1 = 1, RS0 = 0, also defined as VGA I/O port \$3C6) is read four times consecutively. The next read or write to the RMR will be sent to the control register. Another read of the ADDR should be performed to reset the internal state machine. The count to four results in a single access and has to be repeated for each access to the control register via the RMR. Reading or writing any other register during the count will reset the flag. Hence, any of the control register bits may be programmed by systems and graphics controllers not having an RS2 address pin.

## Functional Description

### Software Identification

The ATT20C497 can be differentiated from other 49X RAMDACs by programming control register bits CR[7:5] with ones and reading the bits using the RMR. If zeros are returned, the device is an ATT20C497. The ATT20C497 may be differentiated from the ATT20C47XA family by trying to read the control register using the RMR. If this cannot be done, the device is from the ATT20C47X family. See Table 4 and Figure 3.

Table 4. Software Identification

Part Number	CR[7:5]	
	Write	Read*
ATT20C497	111	000
ATT20C491	111	111
ATT20C490	011	000
ATT20C47XA	†	†

\* The read must be accomplished through the read mask register.  
 † The ATT20C47XA cannot be accessed in this manner and will identify itself by this characteristic.

Figure 3 illustrates how programmers can identify the ATT20C47X family and ATT20C49X RAMDACs. The RMR is the pixel read mask register; Write CR indicates that the programmer should write to the control register; and Read CR indicates that the programmer should read the control register. Reading the address register resets the internal state machine. (See the Control Register section under Internal Registers).

Functional Description (continued)

Software Identification (continued)

■ Procedure to write CR

1. Read address register (VGA \$3C8)
2. Read RMR four times (VGA \$3C6)
3. Write RMR with value for CR
4. Read address register

■ Procedure to read CR

1. Read address register (VGA \$3C8)
2. Read RMR five times (VGA \$3C6)
3. Results in CR contents
4. Read address register

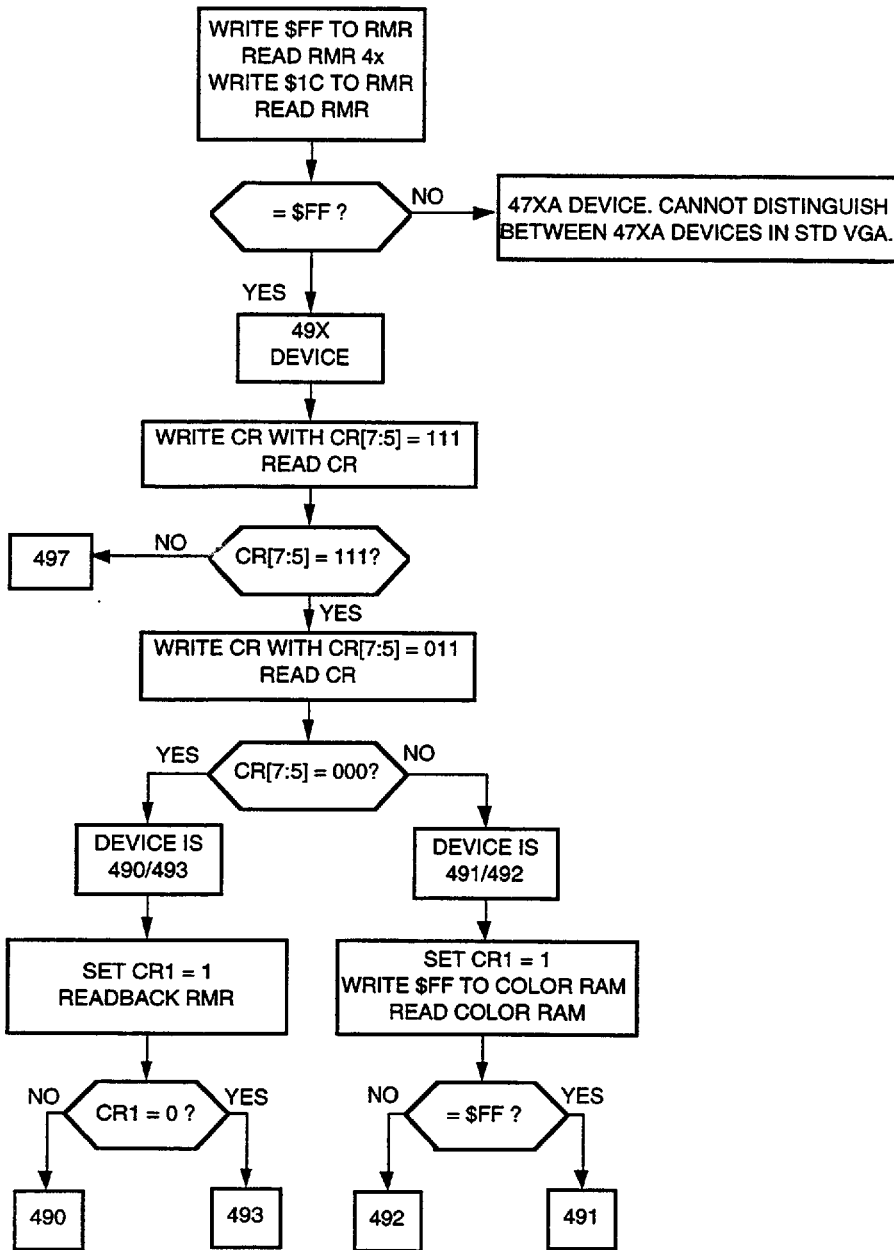


Figure 3. Software Identification Flow Chart



## Functional Description (continued)

### Functional Differences from 47X Family

This device can replace the ATT20C478A/477A/476A/475A RAMDACs. The ATT20C497 adds the ability to access the control register by executing multiple reads to the RMR. Software can differentiate between ATT20C49X devices by reading CR[7:5] through the RMR. **Note:** See page 1 for application differences.

**Table 5. Differences Between ATT20C497 and ATT20C47X Family of RAMDACs**

Feature	ATT20C497	ATT20C478A
<ul style="list-style-type: none"> <li>▪ Pin 1 ( SENSE )</li> <li>▪ MODE (pin 2) 8-/6-bit operation</li> <li>▪ Control register</li> <li>▪ Identification</li> </ul>	<ul style="list-style-type: none"> <li>▪ SENSE pin (for monitor detect).</li> <li>▪ Pin 2 is not used and should be tied to Vcc or GND. 8-/6-bit operation controlled by CR1 bit only.</li> <li>▪ Addressable via software through pixel read mask register or RS2 pin.</li> <li>▪ By checking CR[7:5].</li> </ul>	<ul style="list-style-type: none"> <li>▪ Pin 1 has no internal connection.</li> <li>▪ ATT20C478A MODE pin controls 8-/6-bit operation*.</li> <li>▪ No control register.</li> <li>▪ Identification by trying to read control register through the RMR.</li> </ul>
Feature	ATT20C497	ATT20C477A
<ul style="list-style-type: none"> <li>▪ MODE (pin 2) 8-/6-bit operation</li> <li>▪ Control register</li> <li>▪ Blank pedestal</li> <li>▪ Identification</li> </ul>	<ul style="list-style-type: none"> <li>▪ Pin 2 is not used and should be tied to Vcc or GND. 8-/6-bit operation controlled by CR1 bit only.</li> <li>▪ Addressable via software through pixel read mask register or RS2 pin.</li> <li>▪ Pin programmable.</li> <li>▪ By checking CR[7:5].</li> </ul>	<ul style="list-style-type: none"> <li>▪ 477A MODE pin controls 8-/6-bit operation and gates CR1 (8/ 6 ) bit.*</li> <li>▪ Must use RS2 pin to address control register.</li> <li>▪ Pin and bit programmable*.</li> <li>▪ Identification by trying to read control register through the RMR.</li> </ul>
Feature	ATT20C497	ATT20C476A
<ul style="list-style-type: none"> <li>▪ MODE (pin 2) 8-/6-bit operation</li> <li>▪ Control register</li> <li>▪ Identification</li> </ul>	<ul style="list-style-type: none"> <li>▪ Pin 2 is not used and should be tied to Vcc or GND. 8-/6-bit operation controlled by CR1 bit only.</li> <li>▪ Addressable via software through pixel read mask register or RS2 pin.</li> <li>▪ By checking CR[7:5].</li> </ul>	<ul style="list-style-type: none"> <li>▪ NC. No internal connection.</li> <li>▪ No control register.</li> <li>▪ Identification by trying to read control register through the RMR.</li> </ul>
Feature	ATT20C497	ATT20C475A
<ul style="list-style-type: none"> <li>▪ MODE (pin 2) 8-/6-bit operation</li> <li>▪ Control register</li> <li>▪ Blank pedestal</li> <li>▪ Identification</li> </ul>	<ul style="list-style-type: none"> <li>▪ Pin 2 is not used and should be tied to Vcc or GND. 8-/6-bit operation controlled by CR1 bit only.</li> <li>▪ Addressable via software through pixel read mask register or RS2 pin.</li> <li>▪ Pin programmable.</li> <li>▪ By checking CR[7:5].</li> </ul>	<ul style="list-style-type: none"> <li>▪ 475A mode pin controls access to the control register. This is a 6-bit device.</li> <li>▪ Must use RS2 pin to address control register.</li> <li>▪ Pin and bit programmable*.</li> <li>▪ Identification by trying to read control register through the RMR.</li> </ul>

\* For more details on operation, refer to the ATT20C478A/477A/475A CMOS RAMDACs Data Sheet and ATT20C476A CMOS RAMDAC Data Sheet.

## Functional Description (continued)

### MPU Interface

The ATT20C497 supports a standard MPU interface, allowing the MPU direct access to the RAMDAC RAM, overlay color registers, or control register (see Figure 1). As outlined in Table 2, the RS[2:0] select inputs indicate whether the MPU is accessing the address register, RAMDAC RAM, overlay registers, read mask register, or control register. To eliminate the requirement for external address multiplexers, the 8-bit address register is used to address the RAMDAC RAM and overlay registers. ADDR0 corresponds to D0, the least significant bit.

### Writing the RAMDAC Color RAM

The MPU writes the address register (RAM write mode) with the address of the RAMDAC RAM location to be modified. Using RS[2:0] to select the RAMDAC RAM, the MPU completes three continuous write cycles (6 bits or 8 bits each of red, green, and blue). Following the blue write cycle, the 3 bytes of color information are concatenated into an 18- or 24-bit word and written to the location specified by the address register. The address register advances to the next location, which the MPU can modify by simply writing another sequence of red, green, and blue data. A block of color values in successive locations can be written to by writing the start address and performing continuous R, G, and B write cycles until the entire block has been written.

### Reading the RAMDAC Color RAM

The MPU loads the address register (RAM read mode) with the address of the RAMDAC RAM location to be read. The contents of the RAMDAC RAM at the specified address are copied into the RGB register, and the address register advances to the next RAM location. Using RS[2:0] to select the RAMDAC RAM, the MPU completes three continuous read cycles (6 bits or 8 bits each of red, green, and blue). After the blue read cycle, the contents of the RAMDAC RAM at the address specified by the address register are copied into the RGB registers, and the address register advances to the next address. A block of color values in successive locations can be read by writing the start address and performing continuous R, G, and B read cycles until the entire block has been read.

## Writing the Overlay Registers

The MPU writes the address register (overlay write mode) with the address of the overlay location to be modified. Using RS[2:0] to select the overlay registers, the MPU completes three continuous write cycles (6 bits or 8 bits each of red, green, and blue). Following the blue write cycle, the 3 bytes of color information are concatenated into an 18- or 24-bit word and written to the overlay location specified by the address register. The address register then advances to the next location, which the MPU can modify by simply writing another sequence of red, green, and blue data. A block of color values in successive locations can be written to by writing the start address and performing continuous R, G, and B write cycles until the entire block has been written.

## Reading the Overlay Registers

The MPU loads the address register (overlay read mode) with the address of the overlay location to be read. The contents of the overlay register at the specified address are copied into the RGB register, and the address register advances to the next overlay location. Using RS[2:0] to select the overlay registers, the MPU completes three continuous read cycles (6 bits or 8 bits each of red, green, and blue). After the blue read cycle, the contents of the overlay location at the address specified by the address register are copied into the RGB registers, and the address register advances to the next address. A block of color values in successive locations can be read by writing the start address and performing continuous R, G, and B read cycles until the entire block has been read.

## Additional Information

Following a blue read or write cycle to RAM location \$FF, the address register resets to \$00. The four most significant bits of the address register ADDR[7:4] are ignored while accessing the overlay color registers.

## Functional Description (continued)

### Additional Information (continued)

Operation of the MPU interface occurs asynchronously to the pixel clock. Internal logic synchronizes data transfers between the RAMDAC color/overlay RAM and the R, G, B color subregister. As a result, the WR and RD signals must maintain a logic high for several clock cycles. See Table 15 for RD and WR high time for further information. To eliminate sparkling on the CRT screen during MPU access to the RAMDAC RAMs, internal logic maintains the previous output color data on the analog outputs, while the transfer between look-up table RAMs and the RGB registers occurs.

To monitor the red, green, and blue read/write cycles, the address register has two additional bits (ADa, ADb) that count modulo three, as shown in Table 6. They are reset to 0 when the MPU writes to the address register, and are not reset to 0 when the MPU reads the address register. The MPU does not have access to these bits.

The other 8 bits of the address register ADDR[7:0], incremented following a blue read or write cycle, are accessible to the MPU and are used to address RAMDAC color and overlay RAMs, as outlined in Table 7.

The MPU can read the address register at any time without modifying its contents or the existing read/write mode. Note that the pixel clock must be active for MPU accesses to the RAMDAC color or overlay RAM.

**Table 6. Modulo 3 Counter Operation**

AD[b:a]	Addressed by MPU
00	red color RAM byte
01	green color RAM byte
10	blue color RAM byte

**Table 7. Address Register (ADDR) Operation**

RS2	RS1	RS0	ADDR [7:0]	Addressed by MPU
0	0	1	\$00—\$FF	RAMDAC RAM
1	0	1	\$X0	reserved
1	0	1	\$X1	overlay color 1
:	:	:	:	:
1	0	1	\$XF	overlay color 15

## 8-/6 -Bit Color Resolution

The  $\overline{8/6}$  bit in the control register (CR1) determines whether the MPU port reads and writes 8 bits or 6 bits of color data to the color look-up table RAM. In 6-bit mode, color data is on the lower 6 bits of the data bus, with D0 being the LSB and D5, the MSB of color data. When writing color data, D6 and D7 are ignored. During color read cycles, D6 and D7 will be logic 0. Note that in the 6-bit mode, the full-scale output current will be about 1.5% lower than when in the 8-bit mode. This is a result of the two LSBs of each 8-bit DAC always being a logic 0 in the 6-bit mode. In the 8-bit color mode, bit D0 is the color data LSB and bit D7 is the MSB.

## Pixel and Overlay Pins

Table 8 outlines how the OL[3:0] and P[7:0] inputs address the RAMDAC RAM and overlay registers. The contents of the pixel read mask register can be accessed by the MPU at any time and are bit-wise logically ANDed with the P[7:0] inputs (LUT modes when TRCTL is high). Bit D0 of the pixel read mask register corresponds to pixel input P0. The address pointed to by the pixel data provides 18 bits of color information to the three DACs in the 6-bit mode and 24 bits in the 8-bit mode.

To maintain synchronization with color data, the rising edge of the clock latches the SYNC and BLANK inputs. SYNC and BLANK add appropriately weighted currents to the analog outputs to produce the SYNC and BLANK pedestal currents as shown in Figures 4 and 5 and Tables 10 and 11.

The analog outputs are capable of directly driving a 37.5  $\Omega$  load, such as a doubly terminated 75  $\Omega$  coaxial cable.

**Table 8. Pixel and Overlay Address Map**

OL[3:0]	P[7:0]	Addressed by Frame Buffer
\$0	\$00	RAMDAC RAM location \$00
\$0	\$01	RAMDAC RAM location \$01
:	:	:
\$0	\$FF	RAMDAC RAM location \$FF
\$1	\$XX	overlay color 1
:	\$XX	:
\$F	\$XX	overlay color 15

**Functional Description** (continued)

**Powerdown**

The SLEEP control bit, CR0, controls the powerdown. The device operates normally while the sleep bit is a logic 0. A logic 1 in the control register SLEEP bit turns off power to the RAM and the DACs. The RAM still retains the data and can still be read or written to while sleeping, as long as the pixel clock is running. The RAM automatically powers up during MPU read/write cycles and shuts down when the MPU access is completed.

During powerdown, all references both internal and external to the device are disabled, preventing current from flowing out of the device. The internal reference disable circuitry eliminates the need for external disable logic and allows minimum power dissipation during sleep mode, regardless of the referencing scheme used.

**SENSE Output**

SENSE is a logic 0 if one or more of the red, green, or blue outputs have exceeded the internal voltage reference level (340 mV). This output is used to determine the presence of a CRT monitor, and, via diagnostic code, the difference between a loaded or unloaded RGB line can be discerned. The range is 280 mV to 380 mV with nominal value of 340 mV. Note that SYNC should be a logic 0 for SENSE to be stable. When using the ATT20C497 in a socket of an earlier, compatible device, make sure that the SENSE pin is not tied to power or ground.

**DAC Gain**

The device gain from the voltage reference to the DAC output current is shown below. To set the full-scale white current on the DACs while using an internal or external voltage reference, use the formula below.

VREF is the voltage reference in volts, K is the gain constant from Table 9, and RSET is the resistor connected between the RSET pin and ground. Find the recommended RSET in Table 9.

$$I_{OUT} \text{ (mA)} = [V_{REF} \text{ (V)} * 1,000 * K] / RSET \text{ (}\Omega\text{)}$$

In this case, a voltage reference of 1.235 V with RSET = 147 Ω and a K factor of 3.17 results in Iout = 26.63 mA. A 6-bit DAC with no sync or blank results in a K factor of 2.1 and Iout = 17.64 mA.

As shown in Table 9, the recommended RSET for RS-343A compatibility applications (doubly terminated 75 Ω) is 147 Ω. The recommended RSET for PS/2 applications (50 Ω) is 182 Ω.

**Table 9. Iout Current**

Output Waveform Level	RS-343A	PS/2	K Factor
Black to White (6 bit)	17.6 mA	14.25 mA	2.1
Black to White (8 bit)	17.6 mA	14.25 mA	2.125
Black to BLANK	1.4 mA	—	0.1667
BLANK to SYNC	7.6 mA	6.1 mA	0.9
Recommended RSET	147 Ω	182 Ω	—

**Functional Description** (continued)

**DAC Gain** (continued)

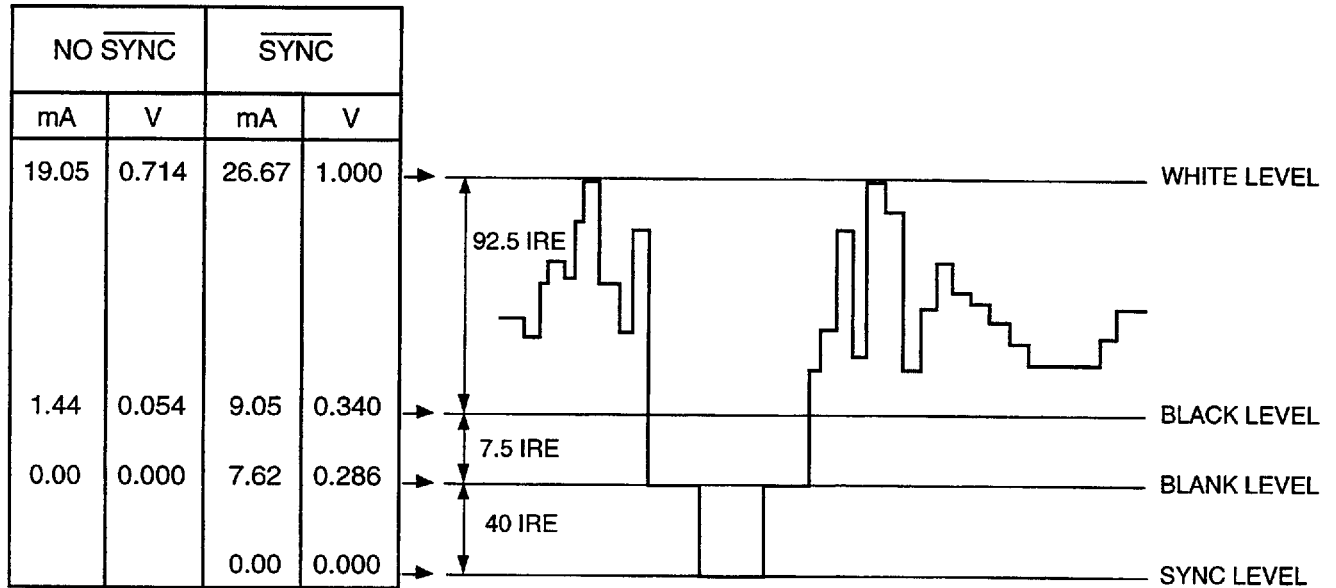


Figure 4. RS-343A Composite Video Output Waveforms

Table 10. RS-343A Video Output Truth Table (Blank Offset Current to Equal 7.5 IRE)

DAC Input Data	SYNC	BLANK	Output Level	I <sub>out</sub> (mA)	
				SYNC Disabled	SYNC Enabled
\$FF	1	1	WHITE	19.05	26.67
data	1	1	DATA	data + 1.44	data + 9.05
data	0	1	DATA- SYNC	data + 1.44	data + 1.44
\$00	1	1	BLACK	1.44	9.05
\$00	0	1	BLACK- SYNC	1.44	1.44
\$XX	1	0	BLANK	0	7.62
\$XX	0	0	SYNC	0	0

Note: 75 Ω doubly terminated load, SETUP = 7.5 IRE. V<sub>REF</sub> = 1.235 V, RSET = 147 Ω.

Functional Description (continued)

DAC Gain (continued)

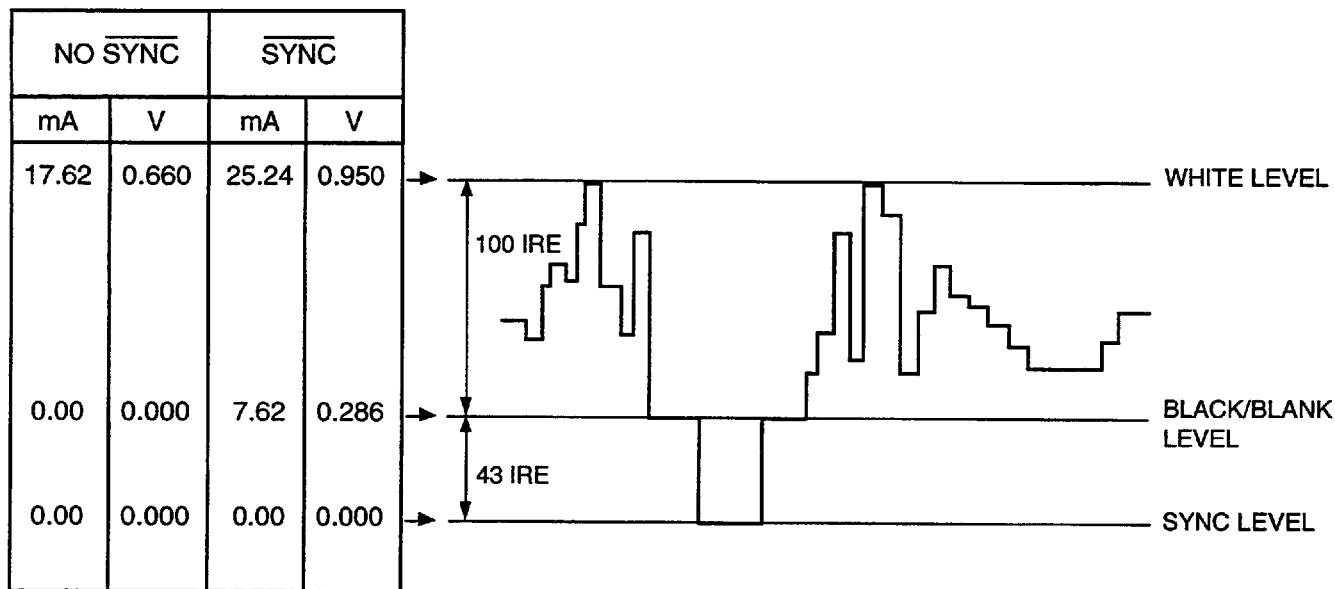


Figure 5. RS-343A Composite Video Output Waveforms

Table 11. RS-343A Video Output Truth Table (No Blank Offset Current)

DAC Input Data	SYNC	BLANK	Output Level	I <sub>OUT</sub> (mA)	
				SYNC Disabled	SYNC Enabled
\$FF	1	1	WHITE	17.62	25.24
data	1	1	DATA	data	data + 7.62
data	0	1	DATA- SYNC	data	data
\$00	1	1	BLACK	0	7.62
\$00	0	1	BLACK- SYNC	0	0
\$XX	1	0	BLANK	0	7.62
\$XX	0	0	SYNC	0	0

Note: 75 Ω doubly terminated load, SETUP = 0 IRE. V<sub>REF</sub> = 1.235 V, RSET = 147 Ω.

## Application Information

### Board Layout

Careful configuration and placement of supply planes, components, and signal traces ensure a low-noise board. This also helps ensure proper functionality and low signal emissions in restricted frequency bands as mandated by regulatory agencies.

A four-layer PC board with separate power and ground planes will likely result in a board with quieter signals and supplies as well as less spectral content in emitted frequency bands. The board should have signal layers 1 and 4 (outside layers) and supply layers 2 and 3 (inside layers). Use a solid ground plane for frequencies up to 100 MHz.

The ATT20C497 should be placed close to the video output connector and between the video output connector and the edge card connector. This will keep the high-speed DAC output traces short and minimize the amount of circuitry between the RAMDAC and the supply pins on the edge card connector.

### Power Distribution

Separate the power plane into digital and analog areas. Place all digital components over the digital plane and all analog components over the analog plane. The analog components include the RAMDAC, reference circuitry, comparators, all mixed signal chips (such as a clock synthesizer), and any passive support components for analog circuits.

The analog and digital power plane should be connected with at least one ferrite bead across the separation, as illustrated in Figures 6 and 7. This bead provides resistance to high-frequency currents. Select a ferrite bead with an impedance curve suitable for your design. The ferrite should have a resistance at a higher frequency than the maximum signal frequency on the board, but lower than the second harmonic (2x) of that frequency. The following beads provide resistances of approximately 75  $\Omega$  at 100 MHz: Ferroxcube VK20019-4B, Fair-Rite 2743001111, or Philips 431202036690.

### Decoupling Capacitors

All decoupling capacitors should be located within 0.25 in. of the device to be decoupled. Chip capacitors are recommended, but radial and axial leads will work. Keep lead lengths as short as possible to reduce inductance and EMI. For leaded capacitors, use devices with a self-resonance above the pixel clock frequency.

For the ATT20C497, decouple Vcc pin 4 to ground with a 0.1  $\mu$ F and Vcc pins 20, 21, and 22 to ground with 0.1  $\mu$ F. For higher-frequency pixel clocks (>80 MHz), use a 0.01  $\mu$ F capacitor in parallel with the 0.1  $\mu$ F capacitor to shunt the higher-frequency noise to ground. Power supply noise should be less than 200 mV for a good design. About 10% of any noise below 1 MHz will be coupled onto the DAC outputs. As illustrated in Figures 6 and 7, the COMP pin should also be decoupled with a 0.1  $\mu$ F capacitor. For designs showing ghosting or smearing, add a parallel COMP capacitance of 2.2  $\mu$ F.

### Digital Signals

The digital inputs should not travel over the analog power plane if possible. The RAMDAC should be located over the analog plane close to the digital/analog supply separation. The RAMDAC may also be placed over the supply separation so the digital pixel inputs are over the digital supply plane. The digital inputs, especially the P[7:0] high-speed inputs, should be isolated from the analog outputs. Placing the digital inputs over the digital supply reduces coupling into the analog supply plane. High-speed signals (both analog and digital) should not be routed under the RAMDAC.

Avoid high slew rate edges since they can contribute to undershoot, overshoot, ringing, EMI, and noise feedthrough. Wherever possible, use slower edge rate (3 ns—5 ns) logic such as 74S or 74ALS devices. If this is not possible, edges can be slowed down by using series termination (75  $\Omega$  to 150  $\Omega$ ). Edge noise will result if the digital signal propagates from an impedance mismatch while the signal rises. The reflection noise is particularly troublesome in the TTL threshold region. For a 2 ns edge, the trace length must be less than 4 in.

## Application Information (continued)

### Digital Signals (continued)

The clock signal trace should be as short as possible and should not run parallel to any high-speed signals. To ensure a quality clock signal without high-frequency noise components, decouple the supply pins on the clock driver. If necessary, transmission line techniques should be used on the clock by providing controlled-impedance striplines and parallel termination.

### Analog Signals

The load resistor should be as close as possible to the DAC outputs. The resistor should equal the destination termination, which is usually a 75  $\Omega$  monitor. Unused analog outputs should be connected to ground. The DAC output traces should be as short as possible to minimize any impedance mismatch in the trace or video connector.

Series ferrite beads can be added to the analog video signal to reduce high-frequency signals coupled onto the DAC outputs or reflected from the monitor.

To reduce the interaction of the analog video return current with board components, a separate video ground return trace can be added to the ground plane or signal layer. This trace connects directly to the ground of the edge card connector.

### DAC Outputs

The ATT20C497 analog outputs should be protected against high-energy discharges, such as those from monitor arc-over or from hot-switching ac-coupled monitors.

The diode protection circuit shown in Figures 6 and 7 can prevent latch-up under severe discharge conditions without adversely degrading analog transition times. The 1N4148/9 are low-capacitance, fast-switching diodes.



Application Information (continued)

DAC Outputs (continued)

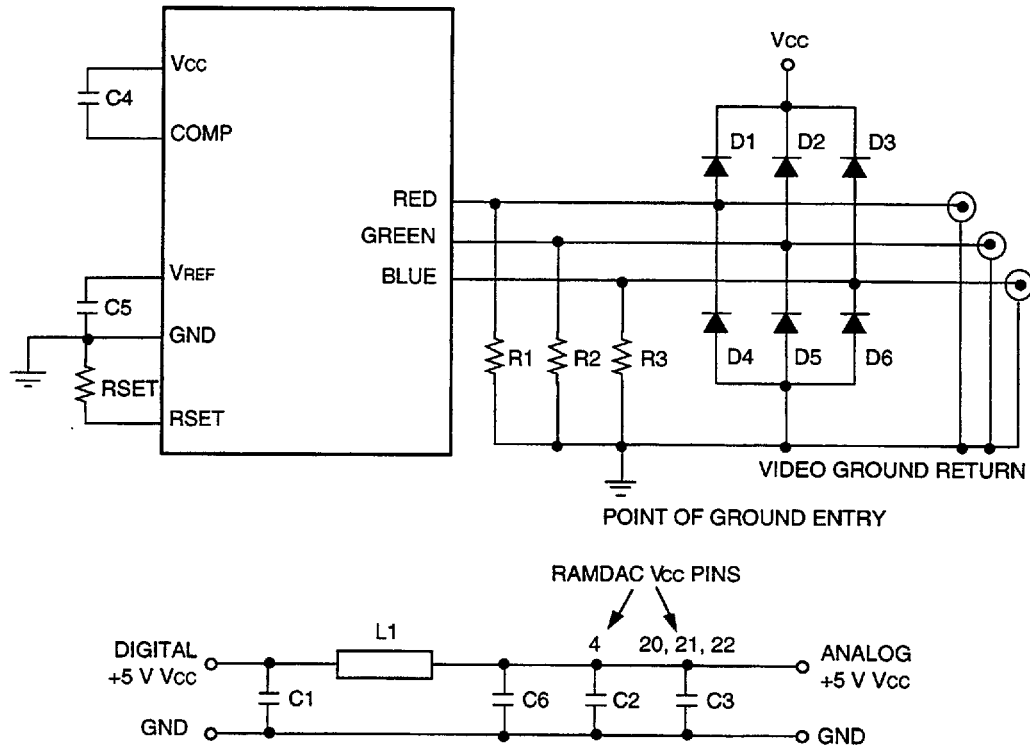


Figure 6. Typical Connection Diagram Using the Internal Voltage Reference

Table 12. Internal Voltage Reference Parts List

Location	Description	Vendor Part Number
C1—C5	0.1 $\mu$ F ceramic capacitor	Erie RPE112Z5U104M50V
C6	10 $\mu$ F capacitor	Mallory CSR13G106KM
L1	Ferrite bead	Fair-Rite 2743001111
R1—R3	75 $\Omega$ , 1% metal film resistor	Dale CMF-55C
RSET	147 $\Omega$ , 1% metal film resistor	Dale CMF-55C
D1—D6	Fast-switching diodes	National 1N4148/49

Note: The above vendor numbers are listed only as a guide. Substitution of devices with similar characteristics will not affect the performance of the ATT20C497.

Application Information (continued)

DAC Outputs (continued)

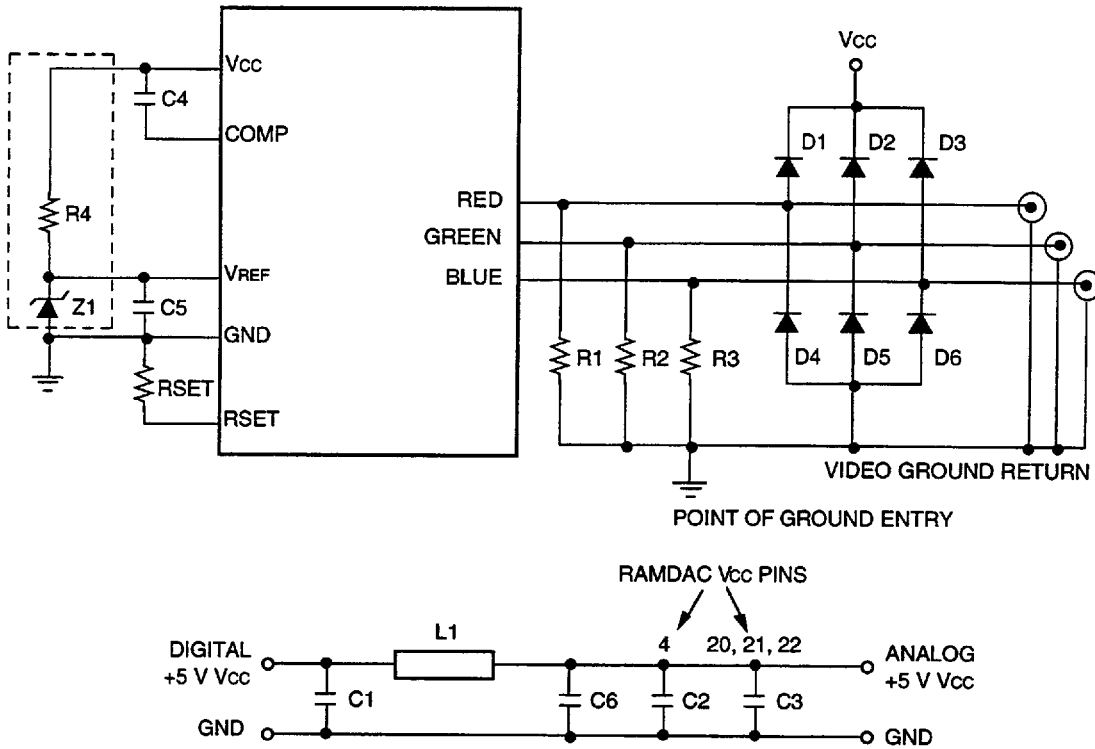


Figure 7. Typical Connection Diagram Using an External Voltage Reference

Table 13. External Voltage Reference Parts List

Location	Description	Vendor Part Number
C1—C5	0.1 $\mu$ F ceramic capacitor	Erie RPE112Z5U104M50V
C6	10 $\mu$ F capacitor	Mallory CSR13G106KM
L1	Ferrite bead	Fair-Rite 2743001111
R1—R3	75 $\Omega$ , 1% metal film resistor	Dale CMF-55C
R4	1 k $\Omega$ , 5% resistor	—
RSET	147 $\Omega$ , 1% metal film resistor	Dale CMF-55C
Z1	1.2 voltage reference	National Semiconductor LM385BZ-1.2
D1—D6	Fast-switching diodes	National 1N4148/49

Note: The above vendor numbers are listed only as a guide. Substitution of devices with similar characteristics will not affect the performance of the ATT20C497.

## Absolute Maximum Ratings

Stresses in excess of the Absolute Maximum Ratings can cause permanent damage to the device. These are absolute stress ratings only. Functional operation of the device is not implied at these or any other conditions in excess of those given in the operational sections of the data sheet. Exposure to Absolute Maximum Ratings for extended periods can adversely affect device reliability.

Parameter	Symbol	Min	Typ	Max	Unit
V <sub>CC</sub> (measured to GND)	—	—	—	7.0	V
Voltage on Any Digital Pin	—	GND – 0.5	—	V <sub>CC</sub> + 0.5	V
Analog Output Short Circuit: Duration to Any Power Supply or Common	ISC	—	Indefinite	—	—
Ambient Operating Temperature	T <sub>A</sub>	–55	—	125	°C
Storage Temperature	T <sub>stg</sub>	–65	—	150	°C
Junction Temperature	T <sub>J</sub>	—	—	150	°C
Vapor Phase Soldering (60 s)	TV <sub>SOL</sub>	—	—	220	°C

## Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Power Supply	V <sub>CC</sub>	4.75	5.00	5.25	V
Ambient Operating Temperature	T <sub>A</sub>	0	—	70	°C
Output Load	R <sub>L</sub>	—	37.5	—	Ω
Reference Voltage	V <sub>REF</sub>	1.2	1.235	1.27	V

## Electrical Characteristics

**Table 14. dc Characteristics**

Test conditions generate RS-343A video signals unless otherwise specified. The recommended operating condition for generating test signals is RSET = 147 Ω, V<sub>REF</sub> = 1.235 V, SETUP = 7.5 IRE. The parameters below are applicable over full voltage and temperature ranges as shown in the Recommended Operating Conditions table.

Parameter	Symbol	Min	Typ	Max	Unit
Resolution (each DAC):	—	6	6	8	bits
Accuracy (each DAC):					
Integral Linearity Error:	IL				
(each DAC, 6-bit mode)	—	—	—	±1/4	LSB
(each DAC, 8-bit mode)	—	—	—	±1	LSB
Differential Linearity Error:	DL				
(each DAC, 6-bit mode)	—	—	—	±1/4	LSB
(each DAC, 8-bit mode)	—	—	—	±1	LSB
Gain Error	—	—	—	±5	%
Monotonicity	—	—	Guaranteed	—	Scale
Coding	—	—	—	—	Binary

**Electrical Characteristics** (continued)**Table 14. dc Characteristics** (continued)

Test conditions generate RS-343A video signals unless otherwise specified. The recommended operating condition for generating test signals is RSET = 147  $\Omega$ , VREF = 1.235 V, SETUP = 7.5 IRE. The parameters below are applicable over full voltage and temperature ranges as shown in the Recommended Operating Conditions table.

Parameter	Symbol	Min	Typ	Max	Unit
<b>Digital Inputs:</b>					
Input Voltage:					
Low	V <sub>IL</sub>	GND - 0.5	—	0.8	V
High	V <sub>IH</sub>	2.0	—	V <sub>CC</sub> + 0.5	V
Input Current:					
Low (V <sub>IN</sub> = 0.4 V)	I <sub>IL</sub>	—	—	-1	$\mu$ A
High (V <sub>IN</sub> = 2.4 V)	I <sub>IH</sub>	—	—	1	$\mu$ A
Capacitance (f = 1 MHz, V <sub>IN</sub> = 2.4 V)	C <sub>IN</sub>	—	—	7	pF
<b>Digital Outputs:</b>					
Output Voltage:					
Low (I <sub>OL</sub> = 3.2 mA)	V <sub>OL</sub>	—	—	0.4	V
High (I <sub>OH</sub> = -400 $\mu$ A)	V <sub>OH</sub>	2.4	—	—	V
3-State Current	I <sub>oz</sub>	—	—	50	$\mu$ A
Capacitance	C <sub>Dout</sub>	—	—	7	pF
<b>Analog Outputs:</b>					
Gray Scale Current Range	I <sub>gray</sub>	—	—	20	mA
Output Current:					
White Level Relative to Black	I <sub>wb</sub>	16.74	17.62	18.5	mA
Black Level Relative to Blank:	I <sub>bb</sub>	—	—	—	—
Blank Pedestal	—	0.95	1.44	1.90	mA
No Blank Pedestal	—	0	5	50	$\mu$ A
Blank Level:					
Sync Enabled	—	6.29	7.62	8.96	mA
Sync Disabled	—	0	5	50	$\mu$ A
Sync Level	I <sub>sync</sub>	0	5	50	$\mu$ A
LSB Size:					
6-bit	—	—	69.1	—	$\mu$ A
8-bit	—	—	279.68	—	$\mu$ A
DAC to DAC Matching	—	—	2	5	%
Output Compliance	V <sub>oc</sub>	-0.5	—	1.5	V
Output Impedance	R <sub>Aout</sub>	—	10	—	k $\Omega$
Output Capacitance (f = 1 MHz, I <sub>out</sub> = 0 mA)	C <sub>Aout</sub>	—	—	30	pF
Internal Reference Output ( $\pm 3\%$ )	V <sub>REF</sub>	1.2	1.235	1.27	V
SENSE Trip Level	V <sub>SEN</sub>	—	340	—	mV
Power Supply Rejection Ratio:					
(COMP = 0.1 F, f = 1 kHz)	PSRR	—	—	0.5	%/% $\Delta$ V <sub>CC</sub>
	—	—	—	-6	dB

## Electrical Characteristics (continued)

**Table 15. ac Characteristics**

Test conditions generate RS-343 video signals unless otherwise specified. The recommended operating condition for generating test signals is RSET = 147  $\Omega$ , VREF = 1.235 V, SETUP = 7.5 IRE. TTL level input values are 0 V to 3 V, with input rise/fall times of  $\leq 3$  ns, measured from 10% to 90% points. Timing reference points are 50% for both inputs and outputs. The analog output load is  $\leq 10$  pF; SENSE and D[7:0] output loads are  $\leq 50$  pF. The parameters are applicable over the full voltage and temperature range as shown in the Recommended Operating Conditions table.

Parameter	Symbol	110 MHz Devices			80 MHz Devices			Unit
		Min	Typ	Max	Min	Typ	Max	
Clock Rate	fmax	—	—	100	—	—	80	MHz
RS[2:0] Setup Time	1	10	—	—	10	—	—	ns
RS[2:0] Hold Time	2	10	—	—	10	—	—	ns
$\overline{\text{RD}}$ Asserted to Data Bus Driven	3	5	—	—	5	—	—	ns
$\overline{\text{RD}}$ Asserted to Data Valid	4	—	—	40	—	—	40	ns
$\overline{\text{RD}}$ Negated to Data Bus 3-States	5	—	—	20	—	—	20	ns
Read Data Hold Time	6	5	—	—	5	—	—	ns
Write Data Setup Time	7	10	—	—	10	—	—	ns
Write Data Hold Time	8	10	—	—	10	—	—	ns
$\overline{\text{RD}}$ , $\overline{\text{WR}}$ Pulse Width Low	9	50	—	—	50	—	—	ns
$\overline{\text{RD}}$ , $\overline{\text{WR}}$ Pulse Width High	10, 11	6	—	—	6	—	—	PCLK
Pixel and Control Setup Time	12	2	—	—	3	—	—	ns
Pixel and Control Hold Time	13	2	—	—	3	—	—	ns
Clock Cycle Time (PCLK)	14	9.1	—	—	12.5	—	—	ns
Clock Pulse Width High Time	15	3.6	—	—	5	—	—	ns
Clock Pulse Width Low Time	16	3.6	—	—	5	—	—	ns
Analog Output Delay	17	—	—	30	—	—	30	ns
Analog Output Rise/Fall Time	—	—	3	—	—	3	—	ns
Analog Output Settling Time*	—	—	20	—	—	20	—	ns
Clock and Data Feedthrough*	—	—	-30	—	—	-30	—	dB
Glitch Impulse*	—	—	75	—	—	75	—	pV-s
DAC to DAC Crosstalk	—	—	-23	—	—	-23	—	dB
Analog Output Skew	—	—	—	2	—	—	2	ns
SENSE Output Delay	—	—	1	—	—	1	—	$\mu$ s
Pipeline Delay	—	4	4	4	4	4	4	Clocks
Vcc Supply Current <sup>†</sup> Normal Operation	Icc	—	130	190	—	120	180	mA
Sleep Mode <sup>‡</sup> PCLK = 1 MHz	ISLP	—	—	3	—	—	3	mA
PCLK = 35 MHz	—	—	—	5	—	—	5	mA

\* Clock and data feedthrough are functions of the amount of edge rates, overshoot, and undershoot on the digital inputs. For this test, the digital inputs have a 1 k $\Omega$  resistor to ground and are driven by 74 HC logic. Settling time does not include clock and data feedthrough. Glitch impulse includes clock and data feedthrough. -3 dB test bandwidth = 2 x clock rate.

<sup>†</sup> At fmax, Icc (typ) at Vcc = 5.0 V Icc (max) at Vcc (max).

<sup>‡</sup> External current or voltage reference automatically disabled during sleep mode. Test conditions: 25  $^{\circ}$ C to 70  $^{\circ}$ C. Pixel and data ports at 0.4 V.

## Electrical Characteristics (continued)

Table 15. ac Characteristics (continued)

Test conditions generate RS-343 video signals unless otherwise specified. The recommended operating condition for generating test signals is  $R_{SET} = 147 \Omega$ ,  $V_{REF} = 1.235 V$ ,  $SETUP = 7.5 IRE$ . TTL level input values are 0 V to 3 V, with input rise/fall times of  $\leq 3$  ns, measured from 10% to 90% points. Timing reference points are 50% for both inputs and outputs. The analog output load is  $\leq 10$  pF; SENSE and D[7:0] output loads are  $\leq 50$  pF. The parameters are applicable over the full voltage and temperature range as shown in the Recommended Operating Conditions table.

Parameter	Symbol	50 MHz Devices			Unit
		Min	Typ	Max	
Clock Rate	fmax	—	—	50	MHz
RS[2:0] Setup Time	1	10	—	—	ns
RS[2:0] Hold Time	2	10	—	—	ns
$\overline{RD}$ Asserted to Data Bus Driven	3	5	—	—	ns
$\overline{RD}$ Asserted to Data Valid	4	—	—	40	ns
$\overline{RD}$ Negated to Data Bus 3-States	5	—	—	20	ns
Read Data Hold Time	6	5	—	—	ns
Write Data Setup Time	7	10	—	—	ns
Write Data Hold Time	8	10	—	—	ns
$\overline{RD}$ , $\overline{WR}$ Pulse Width Low	9	50	—	—	ns
$\overline{RD}$ , $\overline{WR}$ Pulse Width High	10, 11	6	—	—	PCLK
Pixel and Control Setup Time	12	3	—	—	ns
Pixel and Control Hold Time	13	3	—	—	ns
Clock Cycle Time (PCLK)	14	20	—	—	ns
Clock Pulse Width High Time	15	8	—	—	ns
Clock Pulse Width Low Time	16	8	—	—	ns
Analog Output Delay	17	—	—	30	ns
Analog Output Rise/Fall Time	—	—	3	—	ns
Analog Output Settling Time*	—	—	20	—	ns
Clock and Data Feedthrough*	—	—	-30	—	dB
Glitch Impulse*	—	—	75	—	pV-s
DAC to DAC Crosstalk	—	—	-23	—	dB
Analog Output Skew	—	—	—	2	ns
$\overline{SENSE}$ Output Delay	—	—	1	—	$\mu$ s
Pipeline Delay	—	4	4	4	Clocks
Vcc Supply Current† Normal Operation	Icc	—	100	160	mA
Sleep Mode‡	ISLP	—	—	—	—
PCLK = 1 MHz	—	—	3	—	mA
PCLK = 35 MHz	—	—	5	—	mA

\* Clock and data feedthrough are functions of the amount of edge rates, overshoot, and undershoot on the digital inputs. For this test, the digital inputs have a 1 k $\Omega$  resistor to ground and are driven by 74 HC logic. Settling time does not include clock and data feedthrough. Glitch impulse includes clock and data feedthrough. -3 dB test bandwidth = 2 x clock rate.

† At fmax, Icc (typ) at Vcc = 5.0 V Icc (max) at Vcc (max).

‡ External current or voltage reference automatically disabled during sleep mode. Test conditions: 25 °C to 70 °C. Pixel and data ports at 0.4 V.

## Timing Characteristics

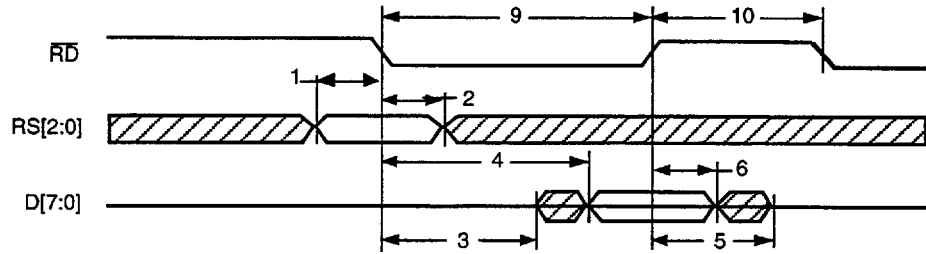


Figure 8. Basic Read-Cycle Timing Diagram

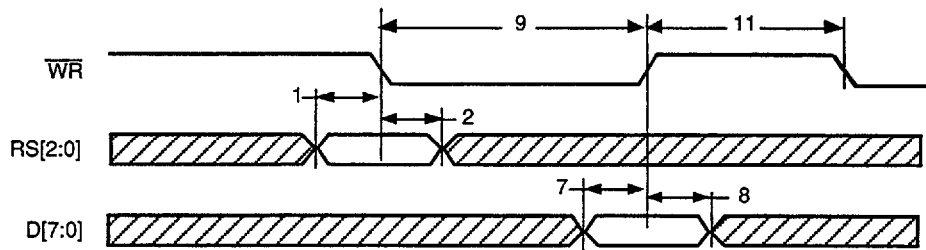


Figure 9. Basic Write-Cycle Timing Diagram

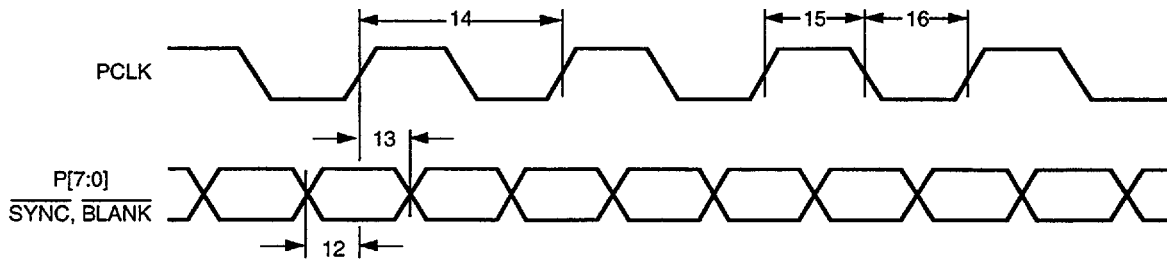


Figure 10. Pixel Timing

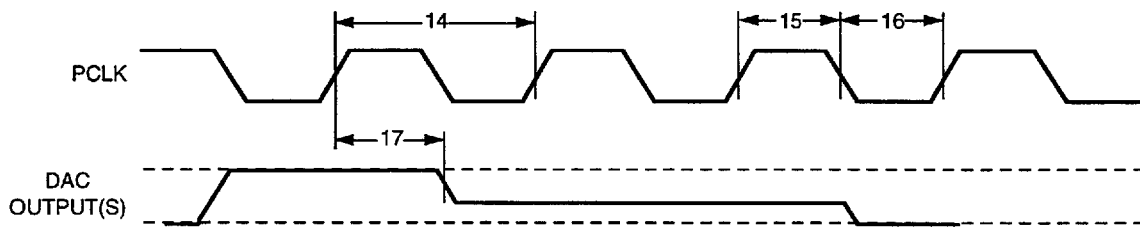
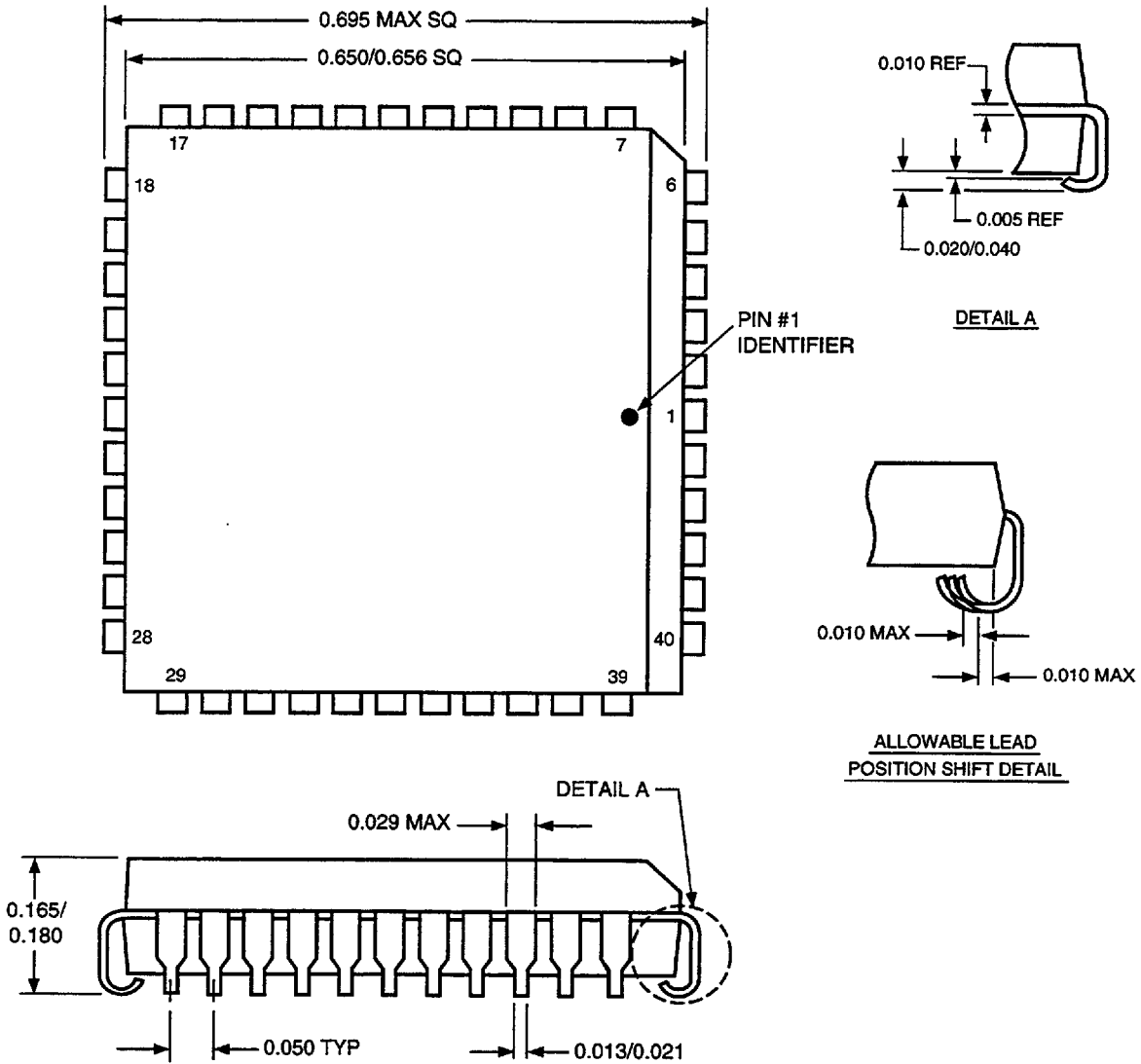


Figure 11. Video Timing

# Outline Diagram

## 44-Pin PLCC Package

Dimensions are in inches.





## Ordering Information

Device*	Speed	Package Type
ATT20C497-XXM44	110/80/50 MHz	44-Pin PLCC

\* XX refers to speed grade:  
11 = 110 MHz, 80 = 80 MHz, and 50 = 50 MHz.