

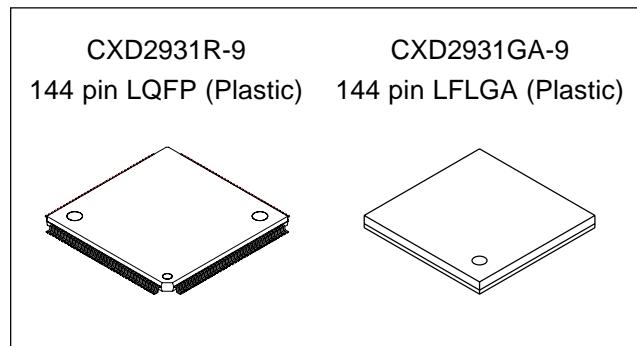
1 chip GPS LSI

Description

The CXD2931R-9/GA-9 is a dedicated LSI for the GPS (Global Positioning System) satellite-based position measurement system.

This LSI contains a 32-bit RISC CPU, 2M-bit MASK ROM, RAM, UART, timer, and others.

This LSI, used together with the RF LSI (CXA1951AQ), enables the configuration of a 2-chip system capable of measuring its position anywhere on the globe.



Features

- 16-channel GPS receiver capable of simultaneously receiving 16 satellites
- Supports differential GPS
 - Conforms to RTCM SC-104 Ver. 2.1
 - Supports DARC
- All-in-view measurement
- 2-satellite measurement
- Timer supporting GPS time
- High performance 32-bit RISC CPU
- 256K-byte program ROM
- 36K-byte RAM
- 3-channel UART
 - Baud rate generator
 - Supports 1.2K, 2.4K, 4.8K, 9.6K, 19.2K and 38.4K baud
 - Supports 1/2/4-byte buffer mode
- 23-bit general-purpose I/O port capable of defining input/output independently for each bit
- 8-bit successive approximation system A/D converter

Structure

Silicon gate CMOS IC

Absolute Maximum Ratings

| | | | |
|-------------------------|------------------|--|----|
| • Supply voltage | V _{DD} | V _{ss} – 0.5 to 4.6 | V |
| • Input voltage | V _I | V _{ss} – 0.5 to V _{DD} + 0.5 | V |
| • Output voltage | V _O | V _{ss} – 0.5 to V _{DD} + 0.5 | V |
| • Operating temperature | | | |
| | Topr | –40 to +85 | °C |
| • Storage temperature | | | |
| | T _{Stg} | –50 to +150 | °C |

Recommended Operating Conditions

| | | | |
|-------------------------|-----------------|------------|----|
| • Supply voltage | V _{DD} | 3.0 to 3.6 | V |
| • Operating temperature | | | |
| | Topr | –40 to +85 | °C |

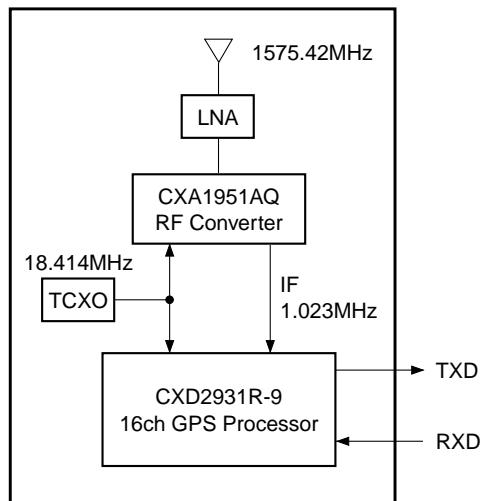
Input/Output Pin Capacitance

| | | | |
|----------------------|------------------|-----------|----|
| • Input capacitance | C _{IN} | 9 (Max.) | pF |
| • Output capacitance | C _{OUT} | 11 (Max.) | pF |
| • I/O capacitance | C _{i/o} | 11 (Max.) | pF |

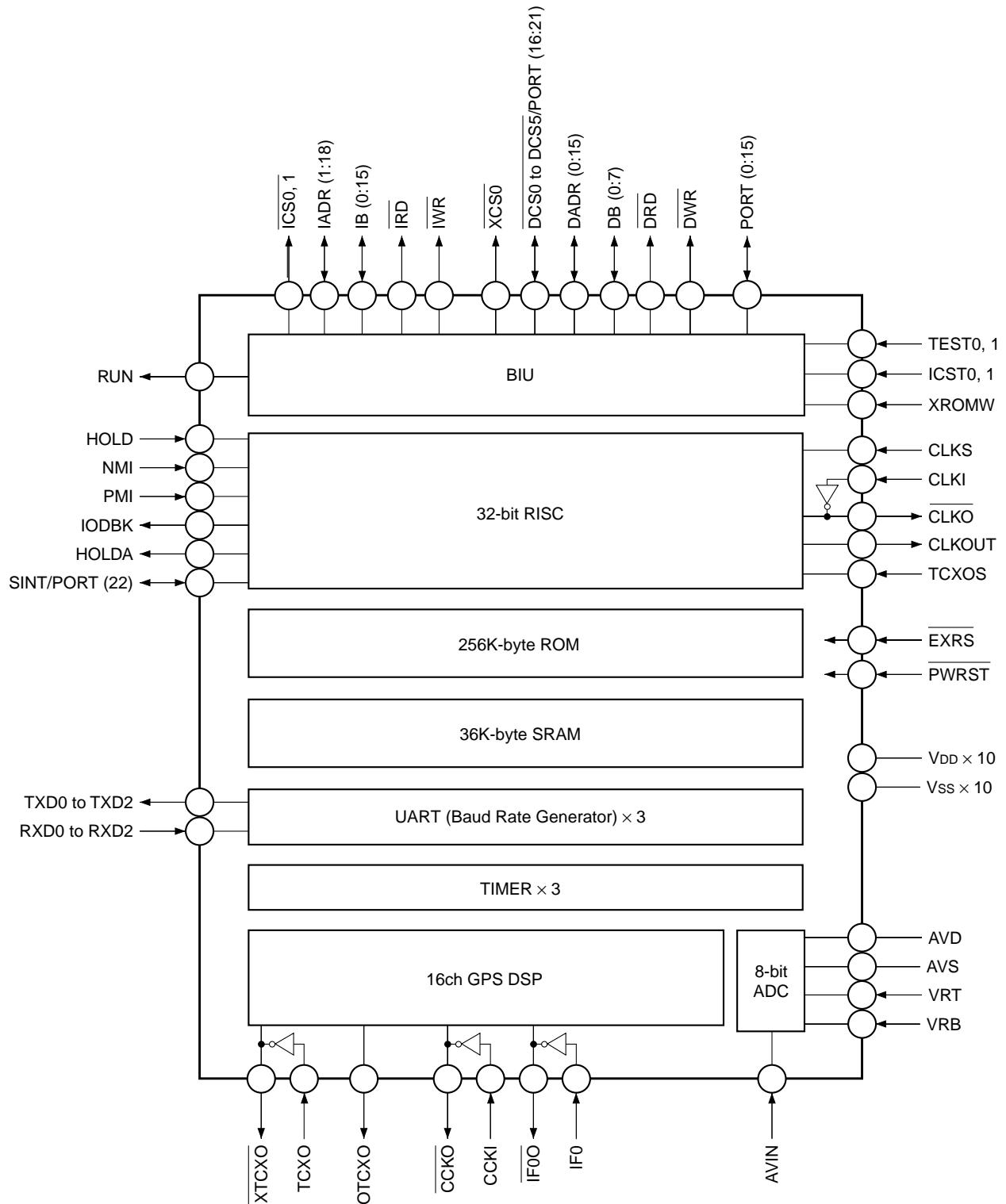
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Performance

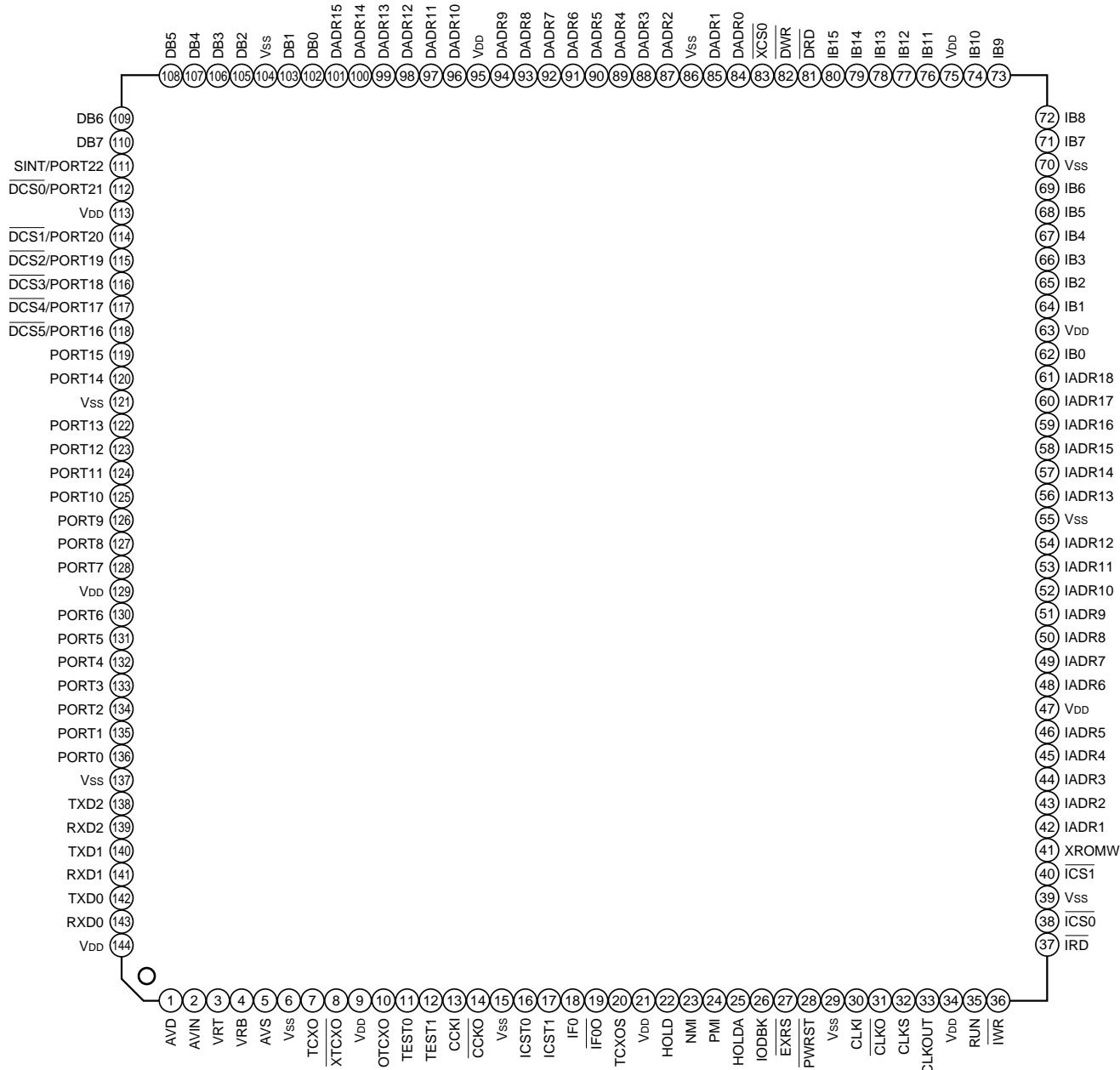
- 16-channel GPS receiver
- High performance 32-bit RISC CPU
- Receiver frequency: 1575.42MHz (L1 band, CA code)
- Reception sensitivity
Tracking sensitivity: -145dBm (typ.) when using the antenna of 25dBi, NF = 2dB and the RF amplifier with the 25dB gain
* Reference data using the Sony's reference board.
This value is not guaranteed, depending on the conditions.
- Time to First Fix (time until initial measurement after power-on)
Cold Start (without both ephemeris and almanac): 27 to 58s
Warm Start (without ephemeris with almanac): 23 to 45s
Hot Start (with both ephemeris and almanac): 6 to 17s
* Reference data with elevation angle of 5° or more and no interception environment on Nov., 2001.
Positioning time with 90% possibility.
These values are not guaranteed, depending on the conditions.
- Positioning accuracy
2DRMS: approx. 12m
* Reference data with elevation angle of 5° or more and no interception environment.
This value is not guaranteed, depending on the conditions.
- Measurement data update time
1s
- Interface format
NMEA0183 (4800bps)
- Communication method
Start-stop synchronization
- All-in-view



GPS receiver system block diagram using the CXD2931R-9

Block Diagram

Pin Configuration (CXD2931R-9)



Pin Configuration (CXD2931GA-9)

| | | | | | | | | | | | | | | | |
|--------|-----------------|-----------------|-----------------|-----------------|-----------------|--------|--------|-------|-------|-------|-------|--------|-------|-------|---|
| (70) | (67) | (64) | (62) | (59) | (58) | (55) | (54) | (51) | (50) | (47) | (45) | (42) | (39) | (34) | R |
| Vss | IB4 | IB1 | IB0 | IADR16 | IADR15 | Vss | IADR12 | IADR9 | IADR8 | Vdd | IADR4 | IADR1 | Vss | Vdd | P |
| (75) | (71) | (68) | (66) | (63) | (60) | (56) | (53) | (49) | (46) | (43) | (41) | (38) | (35) | (31) | N |
| VDD | IB7 | IB5 | IB3 | Vdd | IADR17 | IADR13 | IADR11 | IADR7 | IADR5 | IADR2 | XROMW | ICS0 | RUN | CLKO | M |
| (78) | (74) | (72) | (69) | (65) | (61) | (57) | (52) | (48) | (44) | (40) | (37) | (36) | (32) | (28) | L |
| IB13 | IB10 | IB8 | IB6 | IB2 | IADR18 | IADR14 | IADR10 | IADR6 | IADR3 | ICS1 | IRD | IWR | CLKS | PWRST | K |
| (81) | (77) | (73) | | | | | | | | | | (33) | (30) | (26) | H |
| DRD | IB12 | IB9 | | | | | | | | | | CLKOUT | CLKI | IODBK | G |
| (83) | (79) | (76) | | | | | | | | | | (29) | (27) | (23) | F |
| XCS0 | IB14 | IB11 | | | | | | | | | | Vss | EXRS | NMI | C |
| (86) | (82) | (80) | | | | | | | | | | (25) | (24) | (22) | B |
| Vss | DWR | IB15 | | | | | | | | | | HOLDA | PMI | HOLD | A |
| (87) | (85) | (84) | | | | | | | | | | (21) | (20) | (19) | E |
| DADR2 | DADR1 | DADR0 | | | | | | | | | | Vdd | TCXOS | IFOO | D |
| (90) | (89) | (88) | | | | | | | | | | (16) | (17) | (18) | C |
| DADR5 | DADR4 | DADR3 | | | | | | | | | | ICST0 | ICST1 | IF0 | B |
| (91) | (92) | (93) | | | | | | | | | | (12) | (13) | (15) | A |
| DADR6 | DADR7 | DADR8 | | | | | | | | | | TEST1 | CCKI | Vss | E |
| (94) | (96) | (97) | | | | | | | | | | (8) | (10) | (14) | D |
| DADR9 | DADR10 | DADR11 | | | | | | | | | | XTCXO | OTCXO | CCKO | C |
| (95) | (99) | (101) | | | | | | | | | | (4) | (7) | (11) | B |
| VDD | DADR13 | DADR15 | | | | | | | | | | VRB | TCXO | TEST0 | A |
| (98) | (102) | (105) | | | | | | | | | | (1) | (5) | (9) | E |
| DADR12 | DB0 | DB2 | | | | | | | | | | AVD | AVS | Vdd | D |
| (100) | (104) | (108) | (109) | (112) | (116) | (120) | (124) | (129) | (133) | (137) | (141) | (144) | (2) | (6) | C |
| DADR14 | Vss | DB5 | DB6 | DCS0/ PORT21 | DCS3/ PORT18 | PORT14 | PORT11 | Vdd | PORT3 | Vss | RXD1 | Vdd | AVIN | Vss | B |
| (103) | (107) | (110) | (113) | (115) | (118) | (121) | (125) | (128) | (132) | (135) | (138) | (140) | (143) | (3) | A |
| DB1 | DB4 | DB7 | Vdd | DCS2/ PORT19 | DCS5/ PORT16 | PORT10 | PORT7 | PORT4 | PORT1 | PORT2 | TXD2 | TXD1 | RXD0 | VRT | E |
| (106) | (111) | (114) | (117) | (119) | (122) | (123) | (126) | (127) | (130) | (131) | (134) | (136) | (139) | (142) | F |
| DB3 | SINT/ PORT22 | DCS1/ PORT20 | DCS4/ PORT17 | PORT15 | PORT13 | PORT12 | PORT9 | PORT8 | PORT6 | PORT5 | PORT2 | PORT0 | RXD2 | TXD0 | G |

15 14 13 12 11 10 9 8 7 6 5 4 3 2 1

Pin Configuration

| Pin No. | Symbol | I/O | Description |
|---------|--------|-----|---|
| 1 | AVD | — | A/D converter power supply. |
| 2 | AVIN | I | Analog input. |
| 3 | VRT | I | |
| 4 | VRB | I | Reference input. |
| 5 | AVS | — | A/D converter GND. |
| 6 | Vss | — | GND |
| 7 | TCXO | I | |
| 8 | XTCXO | O | TCXO binary conversion circuit/crystal oscillator. |
| 9 | VDD | — | Power supply. |
| 10 | OTCXO | O | TCXO clock output. |
| 11 | TEST0 | I | |
| 12 | TEST1 | I | Test. (Low level fixed) |
| 13 | CCKI | I | |
| 14 | CCKO | O | Timer oscillation. (32.768kHz ± 100ppm) |
| 15 | Vss | — | GND |
| 16 | ICST0 | I | |
| 17 | ICST1 | I | Test. (Low level fixed) |
| 18 | IF0 | I | |
| 19 | IF0O | O | IF signal binary conversion circuit. |
| 20 | TCXOS | I | TCXO select. (Low: TCXO/2, High: TCXO through) |
| 21 | VDD | — | Power supply. |
| 22 | HOLD | I | Hold input signal. (High: Hold) |
| 23 | NMI | I | Non maskable interrupt. |
| 24 | PMI | I | Program maskable interrupt. |
| 25 | HOLDA | O | Hold acknowledge signal. |
| 26 | IODBK | O | Break signal for debugging. |
| 27 | EXRS | I | Reset input signal. |
| 28 | PWRST | I | Connect to main power supply. Leave open during backup. |
| 29 | Vss | — | GND |
| 30 | CLKI | I | |
| 31 | CLKO | O | CPU clock oscillation circuit. |
| 32 | CLKS | I | CPU clock select signal. (Low: TCXO, High: CLKI) |
| 33 | CLKOUT | O | CPU clock output. |
| 34 | VDD | — | Power supply. |
| 35 | RUN | O | Signal indicating CPU operating status. |
| 36 | IWR | O | Write signal for external expansion memory. |
| 37 | IRD | O | Read signal for external expansion memory. |

| Pin No. | Symbol | I/O | Description |
|---------|-----------------|-----|---|
| 38 | ICS0 | O | Chip select 0 for external expansion memory. |
| 39 | Vss | — | GND |
| 40 | ICS1 | O | Chip select 1 for external expansion memory. |
| 41 | XROMW | I | Wait signal for external expansion memory. (High: Wait) |
| 42 | IADR1 | I/O | (LSB) |
| 43 | IADR2 | I/O | Address signal for external expansion memory. |
| 44 | IADR3 | I/O | |
| 45 | IADR4 | I/O | |
| 46 | IADR5 | I/O | |
| 47 | V _{DD} | — | Power supply. |
| 48 | IADR6 | I/O | |
| 49 | IADR7 | I/O | |
| 50 | IADR8 | I/O | |
| 51 | IADR9 | I/O | |
| 52 | IADR10 | I/O | |
| 53 | IADR11 | I/O | |
| 54 | IADR12 | I/O | |
| 55 | Vss | — | GND |
| 56 | IADR13 | I/O | |
| 57 | IADR14 | I/O | |
| 58 | IADR15 | I/O | |
| 59 | IADR16 | I/O | |
| 60 | IADR17 | I/O | |
| 61 | IADR18 | I/O | (MSB) |
| 62 | IB0 | I/O | (LSB) Data bus I/O for external expansion memory. |
| 63 | V _{DD} | — | Power supply. |
| 64 | IB1 | I/O | |
| 65 | IB2 | I/O | |
| 66 | IB3 | I/O | |
| 67 | IB4 | I/O | |
| 68 | IB5 | I/O | |
| 69 | IB6 | I/O | |
| 70 | Vss | — | GND |
| 71 | IB7 | I/O | |
| 72 | IB8 | I/O | |
| 73 | IB9 | I/O | |
| 74 | IB10 | I/O | |

| Pin No. | Symbol | I/O | Description |
|---------|-----------------|-----|--|
| 75 | V _{DD} | — | Power supply. |
| 76 | IB11 | I/O | |
| 77 | IB12 | I/O | |
| 78 | IB13 | I/O | Data bus I/O for external expansion memory. |
| 79 | IB14 | I/O | |
| 80 | IB15 | I/O | (MSB) |
| 81 | DRD | O | Read signal for external expansion data memory. |
| 82 | DWR | O | Write signal for external expansion data memory. |
| 83 | XCS0 | O | Chip select signal for external expansion data memory. |
| 84 | DADR0 | I/O | (LSB) |
| 85 | DADR1 | I/O | Address signal for external expansion data memory. |
| 86 | V _{ss} | — | GND |
| 87 | DADR2 | I/O | |
| 88 | DADR3 | I/O | |
| 89 | DADR4 | I/O | |
| 90 | DADR5 | I/O | |
| 91 | DADR6 | I/O | |
| 92 | DADR7 | I/O | |
| 93 | DADR8 | I/O | |
| 94 | DADR9 | I/O | |
| 95 | V _{DD} | — | Power supply. |
| 96 | DADR10 | I/O | |
| 97 | DADR11 | I/O | |
| 98 | DADR12 | I/O | |
| 99 | DADR13 | I/O | |
| 100 | DADR14 | I/O | |
| 101 | DADR15 | I/O | (MSB) |
| 102 | DB0 | I/O | (LSB) |
| 103 | DB1 | I/O | Data bus I/O for external expansion data memory. |
| 104 | V _{ss} | — | GND |
| 105 | DB2 | I/O | |
| 106 | DB3 | I/O | |
| 107 | DB4 | I/O | |
| 108 | DB5 | I/O | |
| 109 | DB6 | I/O | |
| 110 | DB7 | I/O | (MSB) |

| Pin No. | Symbol | I/O | Description |
|---------|-----------------|-----|---|
| 111 | SINT/PORT22 | I/O | External interrupt input signal/general-purpose I/O port. This pin can be used as a general-purpose I/O port according to the internal registers. |
| 112 | DCS0/PORT21 | I/O | Chip select for external expansion data memory/general-purpose I/O port. This pin can be used as a general-purpose I/O port according to the internal registers. |
| 113 | V _{DD} | — | Power supply. |
| 114 | DCS1/PORT20 | I/O | Chip select for external expansion data memory/general-purpose I/O port. These pins can be used as a general-purpose I/O port according to the internal registers. |
| 115 | DCS2/PORT19 | I/O | |
| 116 | DCS3/PORT18 | I/O | |
| 117 | DCS4/PORT17 | I/O | |
| 118 | DCS5/PORT16 | I/O | |
| 119 | PORT15 | I/O | |
| 120 | PORT14 | I/O | General-purpose I/O port. |
| 121 | V _{ss} | — | GND |
| 122 | PORT13 | I/O | General-purpose I/O port. |
| 123 | PORT12 | I/O | |
| 124 | PORT11 | I/O | |
| 125 | PORT10 | I/O | |
| 126 | PORT9 | I/O | |
| 127 | PORT8 | I/O | |
| 128 | PORT7 | I/O | |
| 129 | V _{DD} | — | Power supply. |
| 130 | PORT6 | I/O | General-purpose I/O port. |
| 131 | PORT5 | I/O | |
| 132 | PORT4 | I/O | |
| 133 | PORT3 | I/O | |
| 134 | PORT2 | I/O | |
| 135 | PORT1 | I/O | |
| 136 | PORT0 | I/O | |
| 137 | V _{ss} | — | GND |
| 138 | TXD2 | O | UART transmission data output. (channel 2) |
| 139 | RXD2 | I | UART reception data input. (channel 2) |
| 140 | TXD1 | O | UART transmission data output. (channel 1) |
| 141 | RXD1 | I | UART reception data input. (channel 1) |
| 142 | TXD0 | O | UART transmission data output. (channel 0) |
| 143 | RXD0 | I | UART reception data input. (channel 0) |
| 144 | V _{DD} | — | Power supply. |

A/D Converter Characteristics

(0 < VRB < VIN < VRT < AVD = 3.0 to 3.6V, Topr = -40 to +85°C)

| Item | Pin | Condition | Min. | Typ. | Max. | Unit |
|------------------------------------|-----|---------------|------|------|------|------|
| Resolution | | | | | 8 | Bit |
| Differential linearity error (DLE) | | AVD = 3.0V | -0.5 | | +0.5 | LSB |
| Integral linearity error (ILE) | | | -2.5 | | +2.5 | LSB |
| Sampling time | | f = 18.414MHz | 648 | | | ns |
| Conversion time | | | 864 | | | ns |
| Current consumption | | AVD = 3.0V | | 2.0 | | mA |

Electrical Characteristics**DC Characteristics**(V_{DD} = 3.0 to 3.6V, Topr = -40 to +85°C)

| Item | Symbol | Condition | Min. | Typ. | Max. | Unit | Applicable Pins |
|--|---------------------|--------------------------|------------------------|------|-----------------------|------|-----------------|
| Input voltage (1) (CMOS level) | V _{IH} (1) | | 0.7 × V _{DD} | | V _{DD} | V | *1 |
| | V _{IL} (1) | | | | 0.2 × V _{DD} | V | |
| Input voltage (2) (5V interface) | V _{IH} (2) | | 0.7 × V _{DD} | | 5.5 | V | *2 |
| | V _{IL} (2) | | | | 0.2 × V _{DD} | V | |
| Output voltage (1) | V _{OH} (1) | I _{OH} = -4.0mA | V _{DD} - 0.4 | | | V | *3 |
| | V _{OL} (1) | I _{OL} = 4.0mA | | | 0.4 | V | |
| Output voltage (2) | V _{OH} (2) | I _{OH} = -2.0mA | V _{DD} - 0.8 | | | V | *4 |
| | V _{OL} (2) | I _{OL} = 4.0mA | | | 0.4 | V | |
| Output voltage (3) | V _{OH} (3) | I _{OH} = -2.0mA | V _{DD} - 0.8 | | | V | *5 |
| | V _{OL} (3) | I _{OL} = 8.0mA | | | 0.4 | V | |
| Current consumption in standby mode (Using external timer, +85°C) | | ISTB | V _{DD} = 3.0V | | 20 | 70 | μA |
| | | | V _{DD} = 1.8V | | 4 | 50 | |
| Supply current | I _{DD} | f = 18.414MHz | | 55 | | mA | — |

Applicable pins

*1 Pins 11, 12, 16, 17, 20, 28, 32, 41

*2 Pins 22 to 24, 27, 62, 64 to 69, 71 to 74, 76 to 80, 84, 85, 87 to 94, 96 to 103, 105 to 112, 114 to 120, 122, 128, 130 to 136, 139, 141, 143

*3 Pins 10, 25, 26, 33, 35

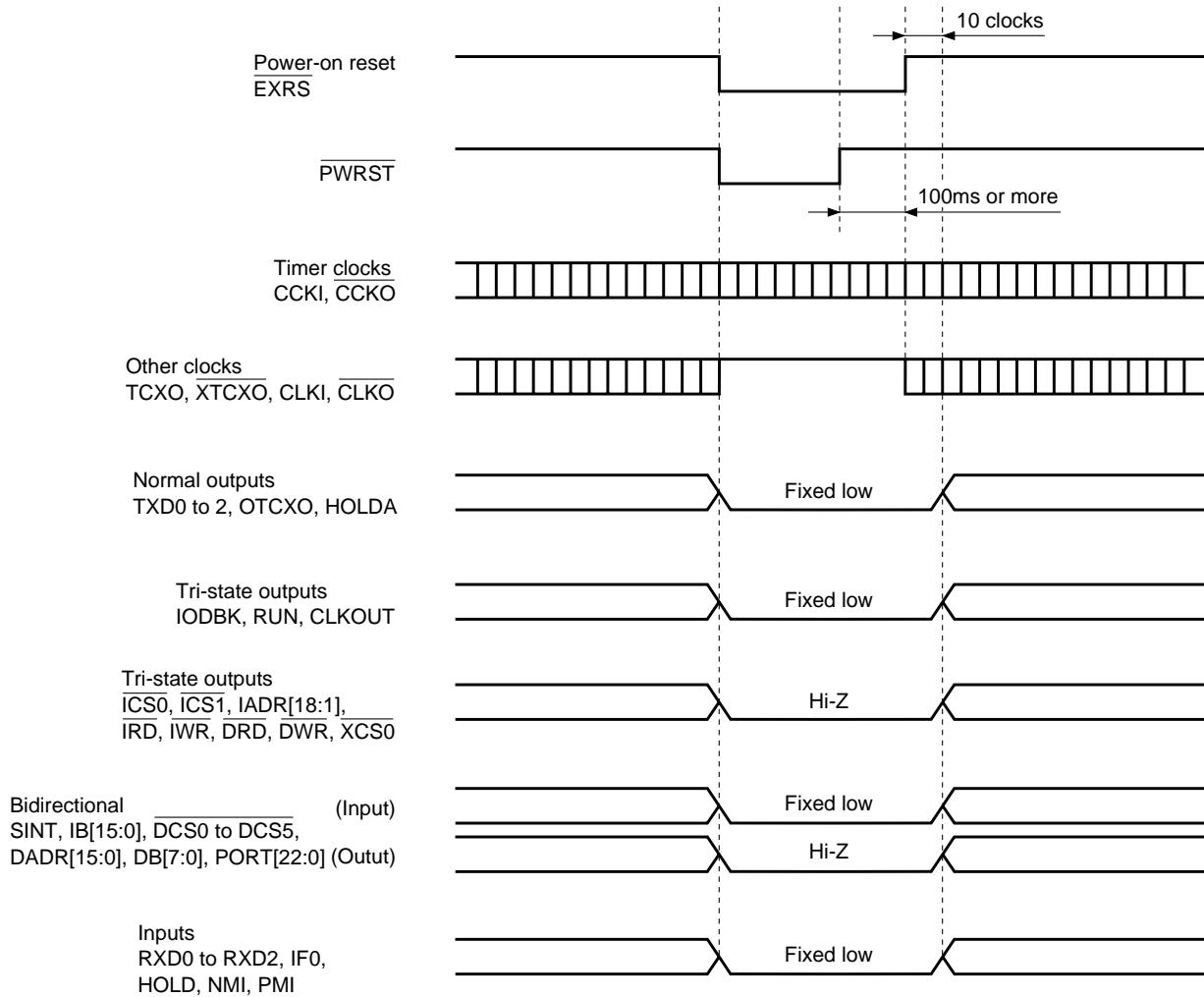
*4 Pins 38, 40, 82, 83, 138, 140, 142

*5 Pins 36, 37, 42 to 46, 48 to 54, 56 to 62, 64 to 69, 71 to 74, 76 to 81, 84, 85, 87 to 94, 96 to 103, 105 to 112, 114 to 120, 122 to 128, 130 to 136

Battery Backup Mode

The battery backup mode is activated when the power for the GPS receiver is turned off and power-on reset goes to low level. The timer clock continues to operate even when power-on reset goes low, but all other clock are fixed high and the LSI is set to the low power consumption mode. At this time, the RAM data is held and the registers are initialized.

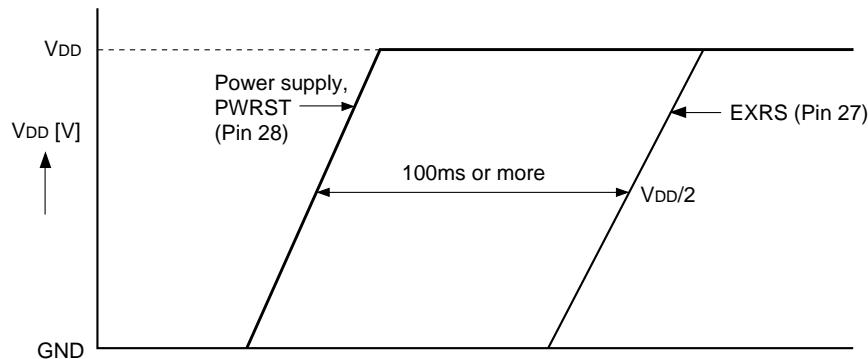
Battery backup mode is canceled by setting power-on reset to high.



CXD2931R-9/GA-9 Initialization

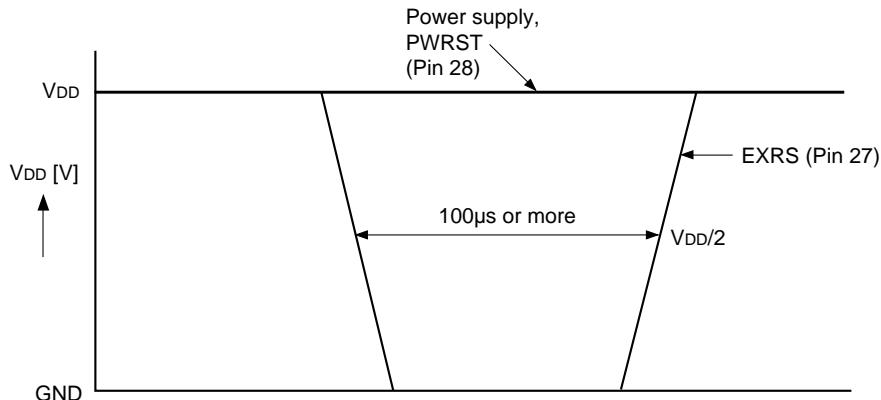
CXD2931R-9/GA-9 initialization is started by setting the reset input signal EXRS (Pin 27) to low level. The timing should satisfy the conditions noted below.

1. During power-on (power-on reset) ($V_{DD} = 3.0$ to $3.6V$, $T_{opr} = -40$ to $+85^{\circ}C$)



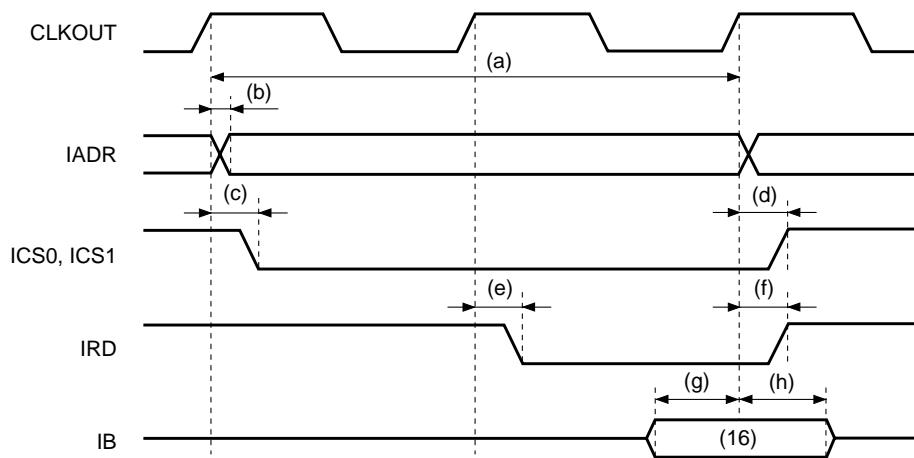
The PWRST (Pin 28) signal should rise simultaneously with the power supply. The EXRS (Pin 27) signal should rise 100ms or more after the power supply and the PWRST signal have risen. Note that the PWRST signal should be left open during battery backup.

2. Initialization during operation ($V_{DD} = 3.0$ to $3.6V$, $T_{opr} = -40$ to $+85^{\circ}C$)



The internal registers can be initialized during operation by setting the EXRS (Pin 27) signal to low level for 100μs or more. Keep the PWRST (Pin 28) signal at high level at this time.

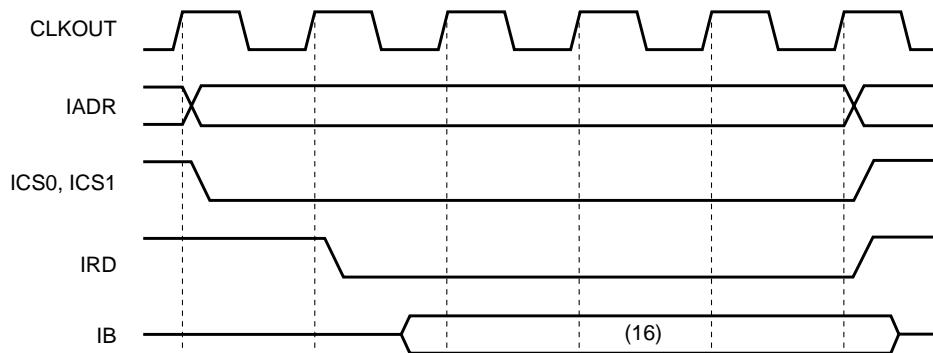
• External Command Fetch Timing (XROMW = 0)



| No. | Item | Min. | Typ. | Max. | Unit |
|-----|-------------------------------|------|------|------|------|
| (a) | Read cycle time (Fex: @20MHz) | — | 100 | — | ns |
| (b) | Address delay time | — | — | 12 | ns |
| (c) | Chip select fall delay time | 2 | — | 10 | ns |
| (d) | Chip select rise delay time | 2 | — | 10 | ns |
| (e) | Read signal fall delay time | 0 | — | 3 | ns |
| (f) | Read signal rise delay time | 0 | — | 5 | ns |
| (g) | Read data setup time | 11 | — | — | ns |
| (h) | Read data hold time | 0 | — | — | ns |

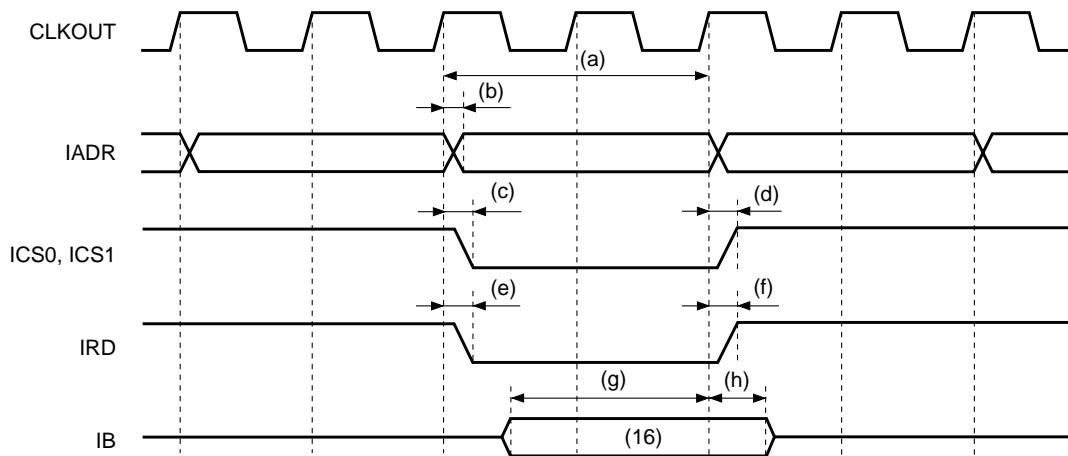
* The load capacitance = 30pF.

• External Command Fetch Timing (XROMW = 1)

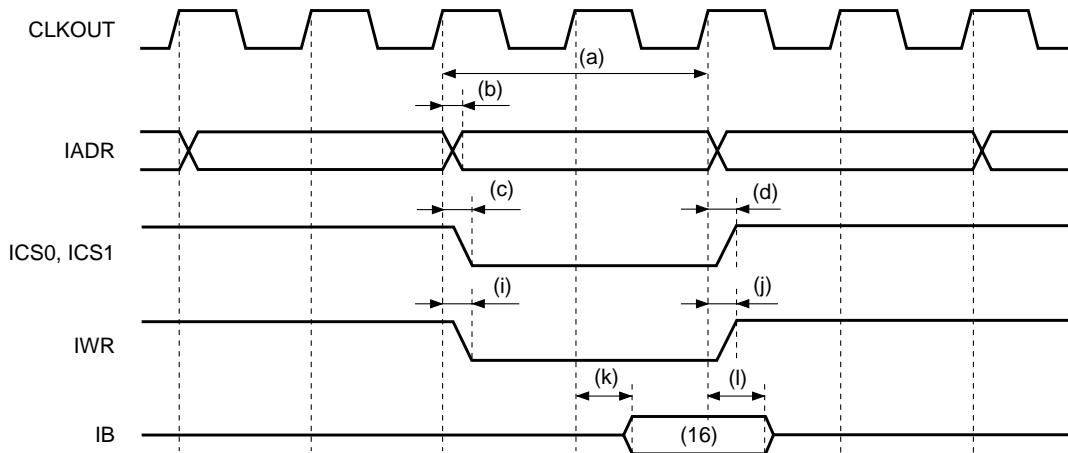


• External Data Access Timing (ICS0, ICS1/XROMW = 0)

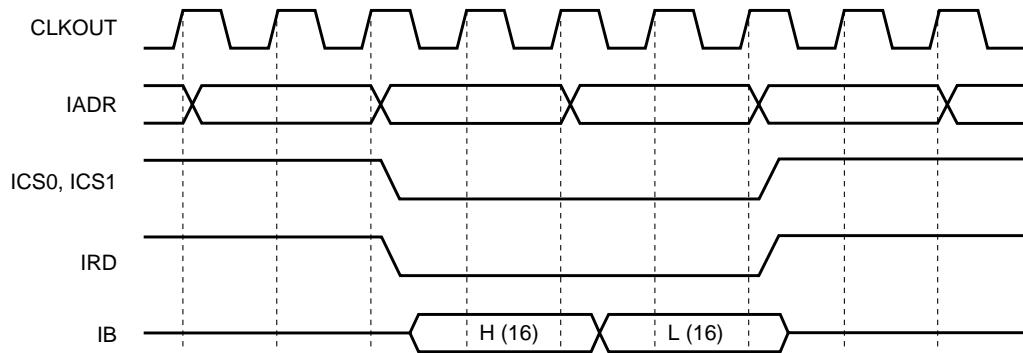
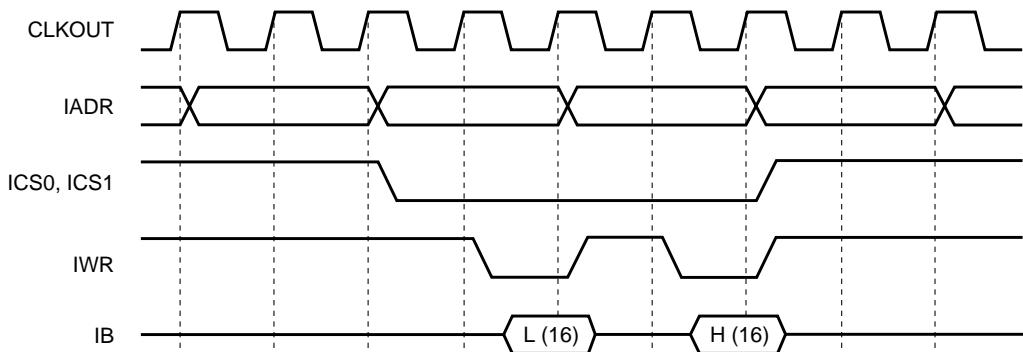
(1) Read (half-word access/XROMW = 0)



(2) Write (half-word access/XROMW = 0)

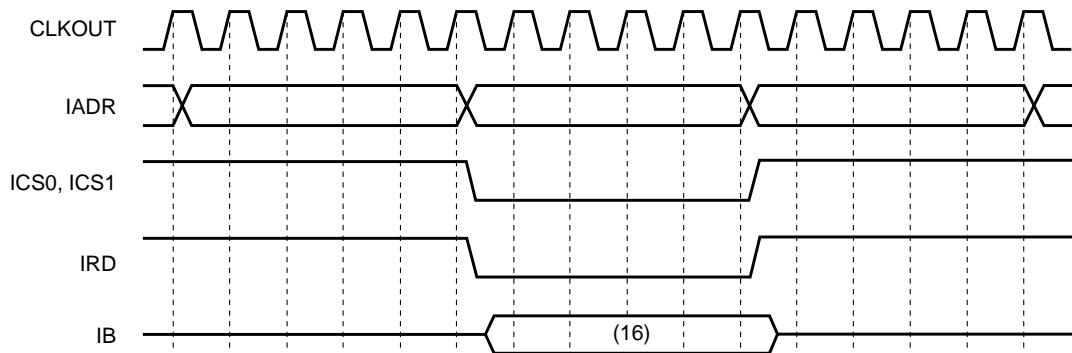


| No. | Item | Min. | Typ. | Max. | Unit |
|-----|-------------------------------------|------|------|------|------|
| (a) | Read/write cycle time (Fex: @20MHz) | — | 100 | — | ns |
| (b) | Address delay time | — | — | 12 | ns |
| (c) | Chip select fall delay time | 2 | — | 10 | ns |
| (d) | Chip select rise delay time | 2 | — | 10 | ns |
| (e) | Read signal fall delay time | 0 | — | 3 | ns |
| (f) | Read signal rise delay time | 0 | — | 5 | ns |
| (g) | Read data setup time | 11 | — | — | ns |
| (h) | Read data hold time | 0 | — | — | ns |
| (i) | Write signal fall delay time | 0 | — | 1 | ns |
| (j) | Write signal rise delay time | 0 | — | 2 | ns |
| (k) | Write data established time | — | — | 5 | ns |
| (l) | Write data hold time | 5 | — | — | ns |

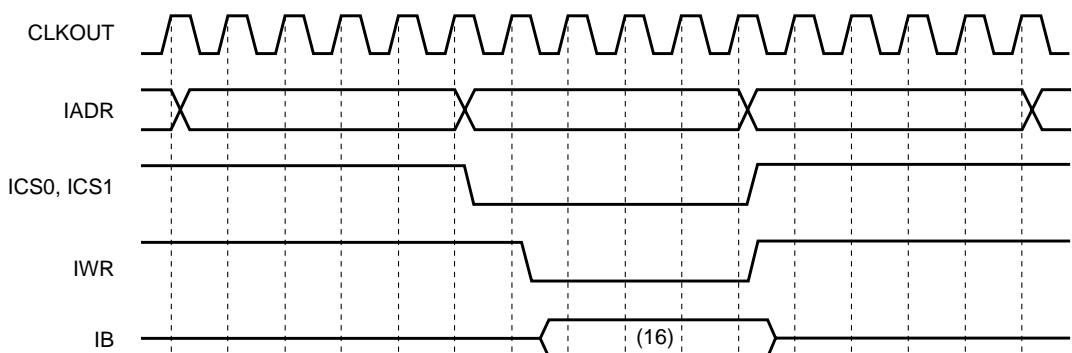
(3) Read (word access/XROMW = 0)**(4) Write (word access/XROMW = 0)**

- External Data Access Timing (ICS0, ICS1/XROMW = 1)

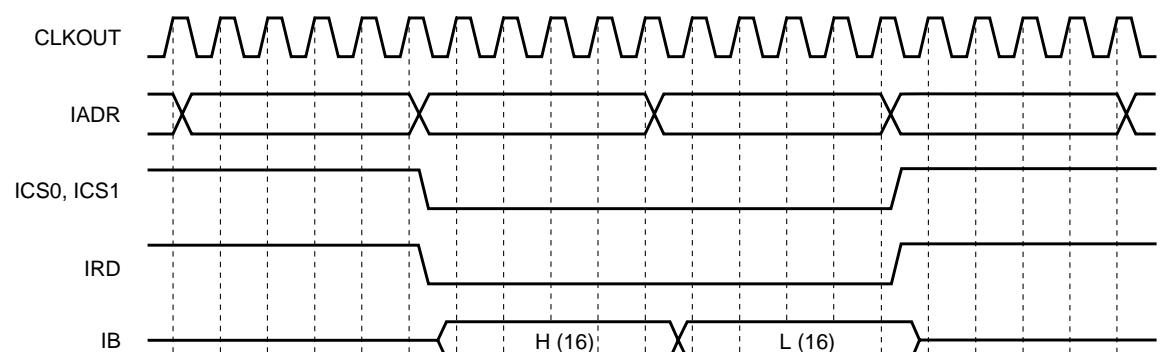
(1) Read (half-word access/XROMW = 1)



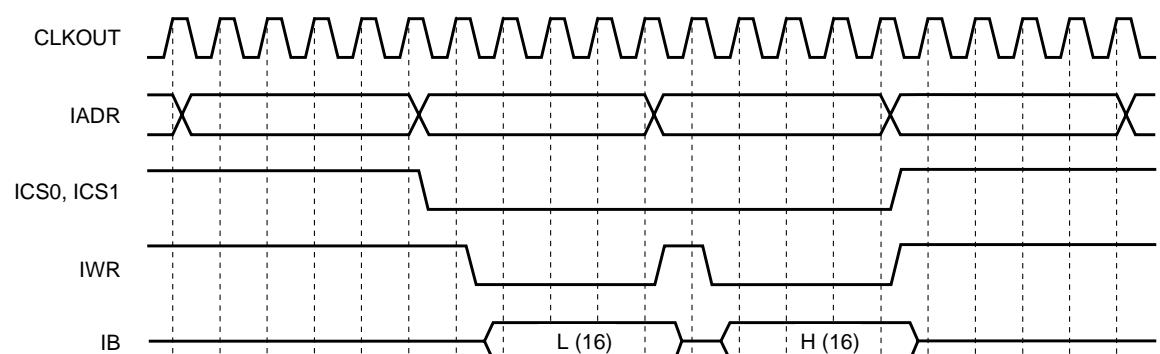
(2) Write (half-word access/XROMW = 1)



(3) Read (word access/XROMW = 1)

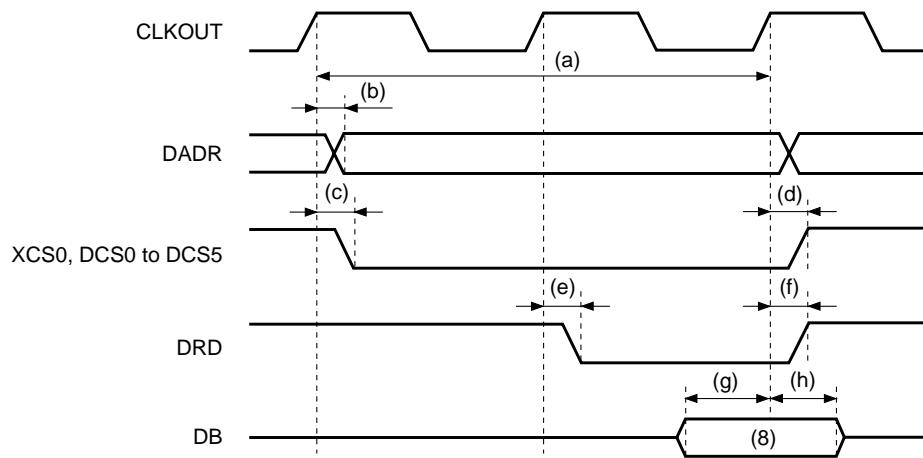


(4) Write (word access/XROMW = 1)

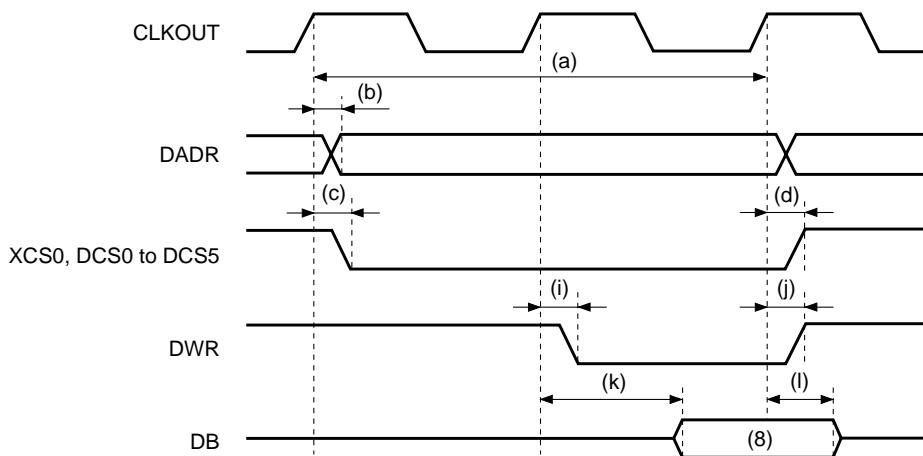


• External Data Access Timing (XCS0, DCS0 to DCS5/no data wait)

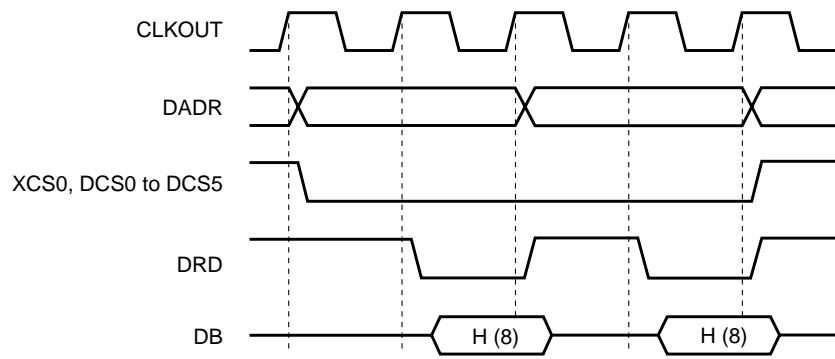
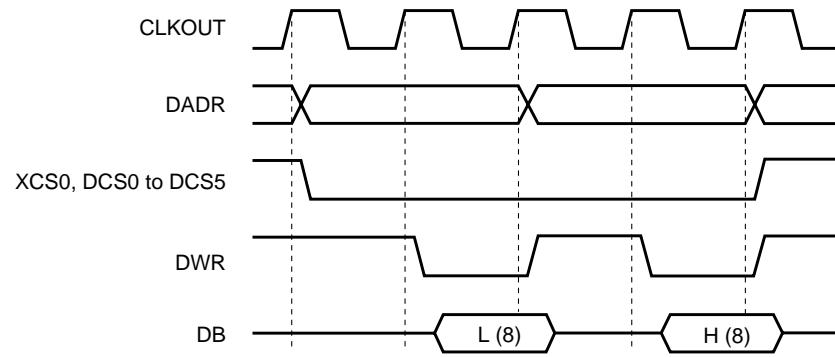
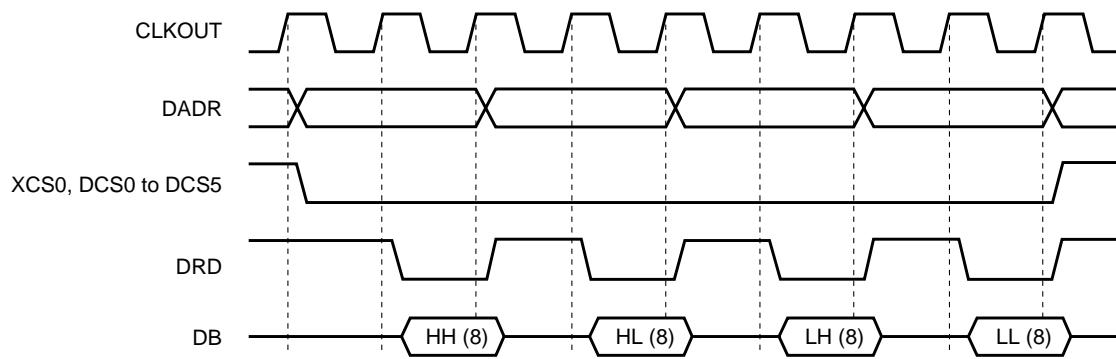
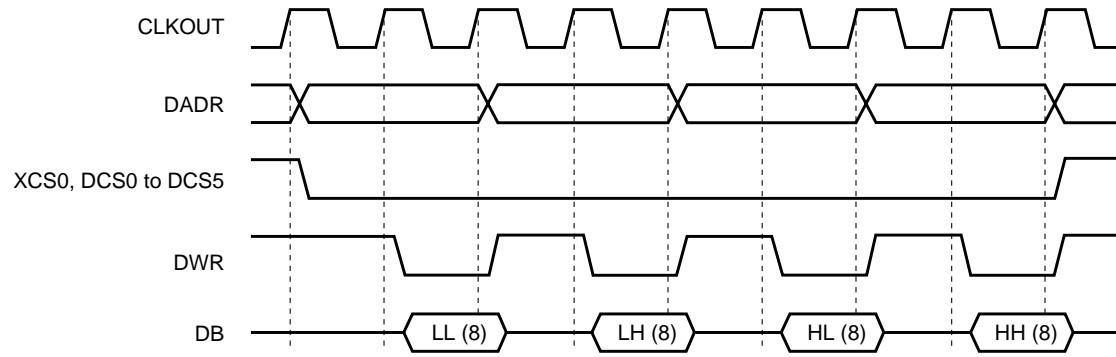
(1) Read (byte access/no data wait)



(2) Write (byte access/no data wait)

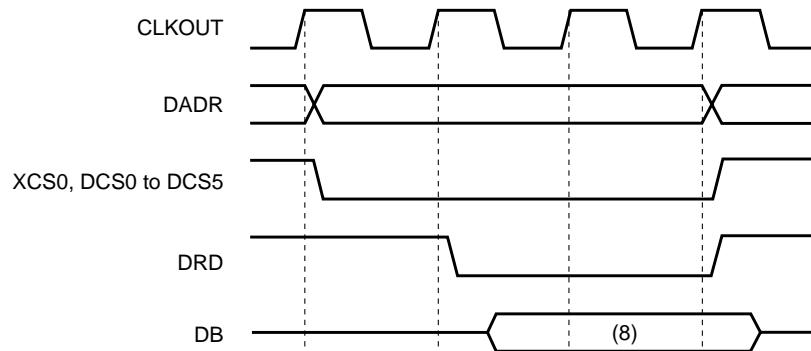


| No. | Item | Min. | Typ. | Max. | Unit |
|-----|-------------------------------------|------|------|------|------|
| (a) | Read/write cycle time (Fex: @20MHz) | — | 100 | — | ns |
| (b) | Address delay time | — | — | 12 | ns |
| (c) | Chip select fall delay time | 3 | — | 13 | ns |
| (d) | Chip select rise delay time | 3 | — | 13 | ns |
| (e) | Read signal fall delay time | 2 | — | 8 | ns |
| (f) | Read signal rise delay time | 2 | — | 10 | ns |
| (g) | Read data setup time | 16 | — | — | ns |
| (h) | Read data hold time | 0 | — | — | ns |
| (i) | Write signal fall delay time | 0 | — | 2 | ns |
| (j) | Write signal rise delay time | 0 | — | 3 | ns |
| (k) | Write data established time | — | — | 12 | ns |
| (l) | Write data hold time | 5 | — | — | ns |

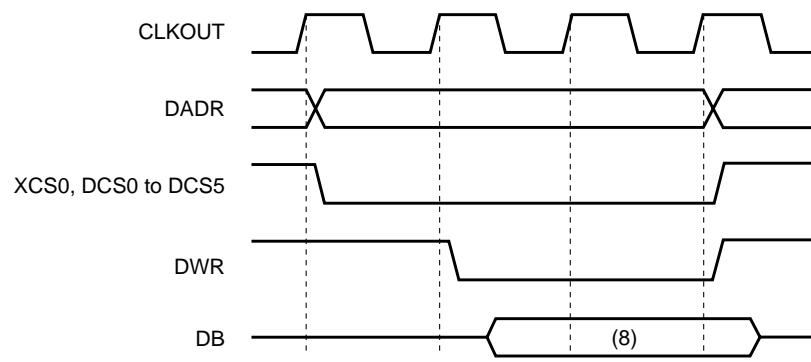
(3) Read (half-word access/no data wait)**(4) Write (half-word access/no data wait)****(5) Read (word access/no data wait)****(6) Write (word access/no data wait)**

• External Data Access Timing (XCS0, DCS0 to DCS5/data wait = 1)

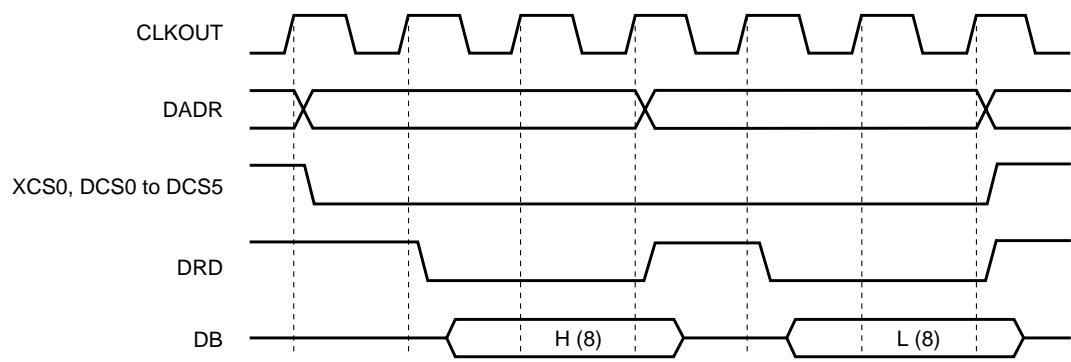
(1) Read (byte access/data wait = 1)



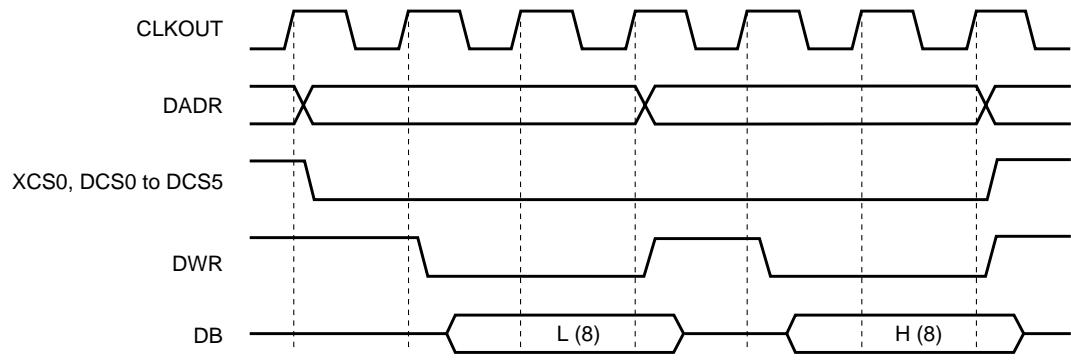
(2) Write (byte access/data wait = 1)

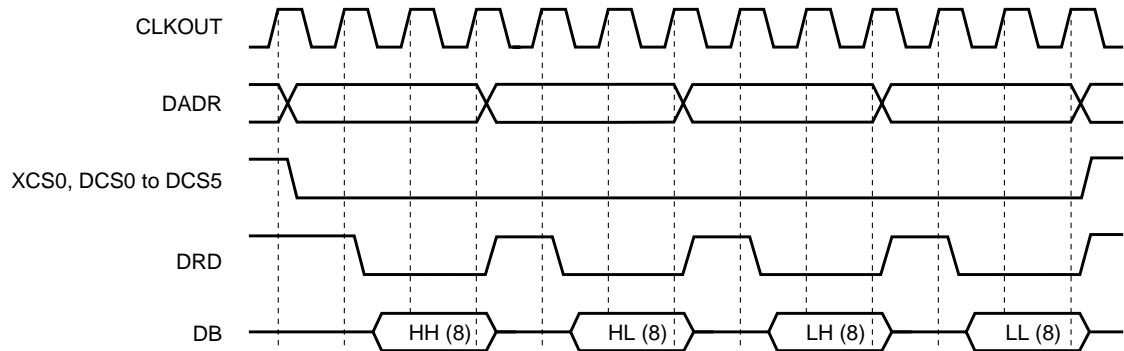
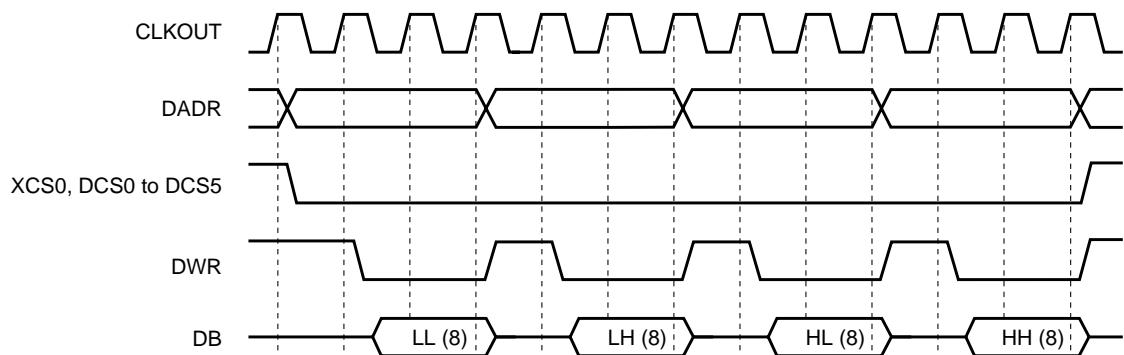


(3) Read (half-word access/data wait = 1)

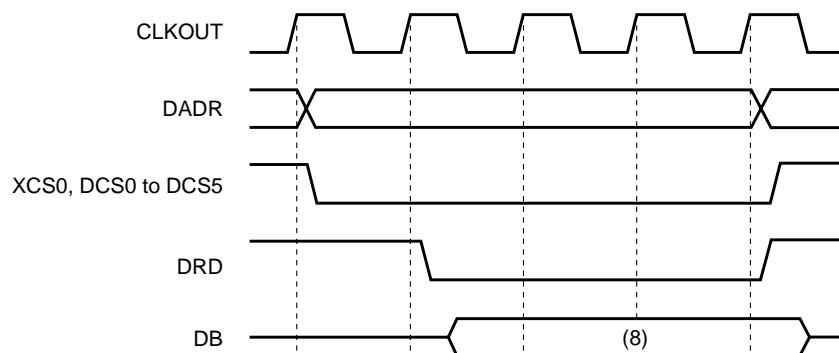
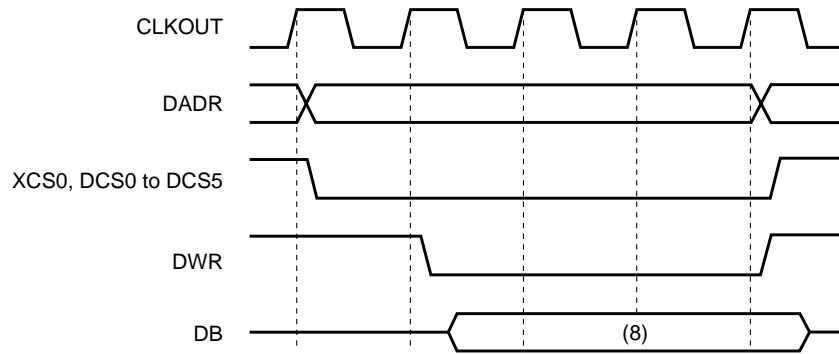


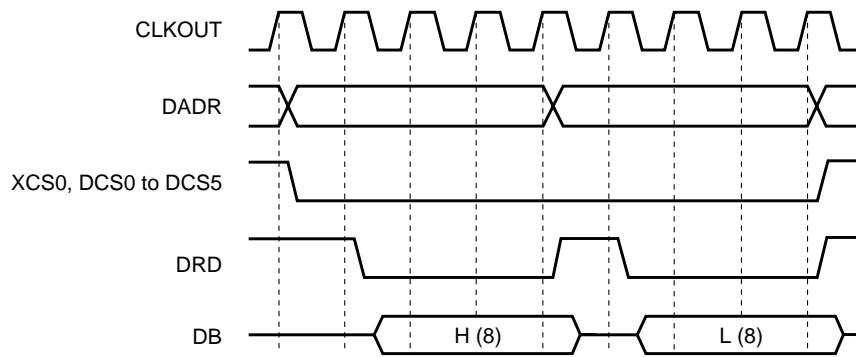
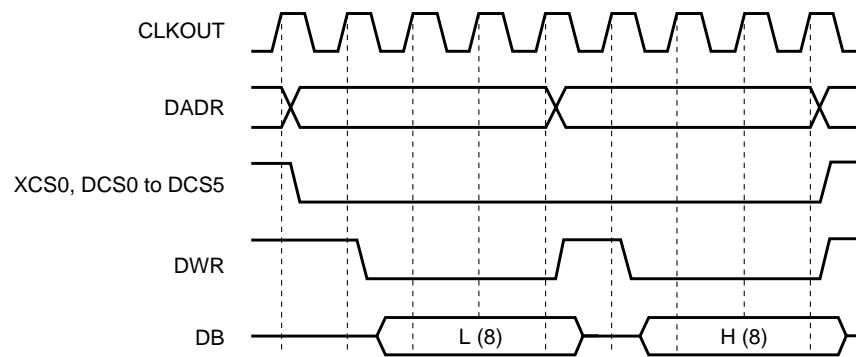
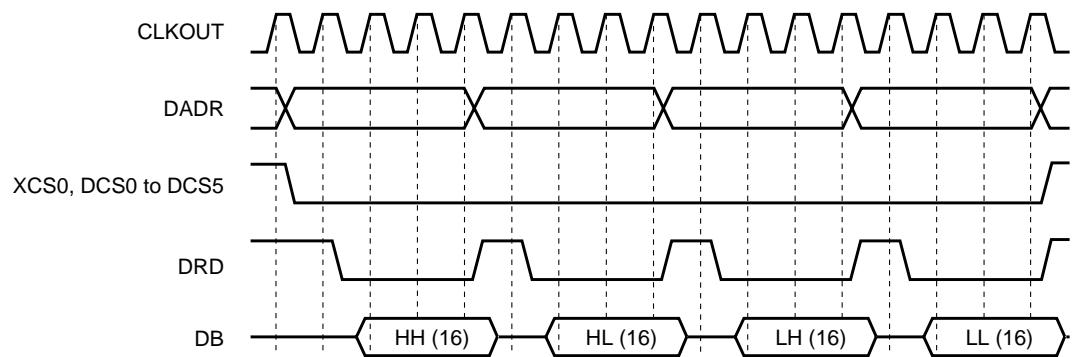
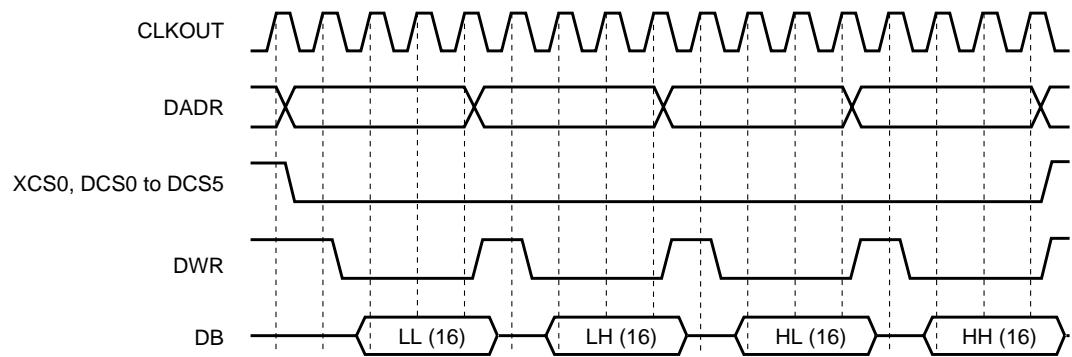
(4) Write (half-word access/data wait = 1)



(5) Read (word access/data wait = 1)**(6) Write (word access/data wait = 1)**

- External Data Access Timing (XCS0, DCS0 to DCS5/data wait = 2)

(1) Read (byte access/data wait = 2)**(2) Write (byte access/data wait = 2)**

(3) Read (half-word access/data wait = 2)**(4) Write (half-word access/data wait = 2)****(5) Read (word access/data wait = 2)****(6) Write (word access/data wait = 2)**

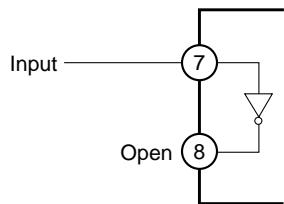
Application Notes

The constants shown in the circuits below are the examples, and do not guarantee the circuit operation.

1. TCXO input

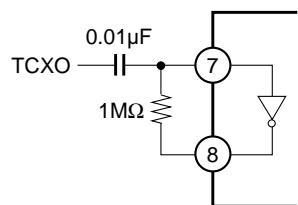
- (1) When inputting the binary-converted signal

The TCXO (Pin 7) input signal should be $18.414\text{MHz} \pm 3\text{ppm}$.



- (2) When performing the self-oscillation with the TCXO and XTCXO pins (Pins 7 and 8)

The TCXO (Pin 7) input signal should be $18.414\text{MHz} \pm 3\text{ppm}$.



2. CPU clock generation

Pin 32 is used to select that TCXO is used or that the self-oscillation is performed with the MCKI and MCKO pins (Pins 30 and 31).

- (1) TCXO solution (TCXO is used for CPU clock)

Set Pin 32 to low.

Pin 30: Low

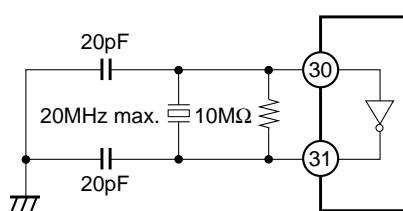
Pin 31: Open

- (2) When performing the self-oscillation with the MCKI and MCKO pins (Pins 30 and 31)

Set Pin 32 to high.

The crystal frequency should be less than 20MHz.

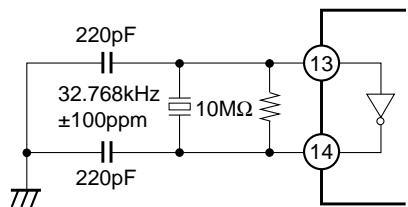
The following circuit is just a reference, and is not guaranteed.



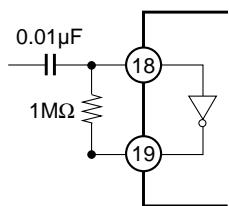
(3) Using internal clock

Set PORT5 (Pin 131) to high.

Connect the external parts as follows when performing the self-oscillation with the CCKI and CCKO pins (Pins 13 and 14).



(4) Input IF signal



Description of Application Circuit

See the Application Circuit when using the CXD2931R-9/GA-9 to configure a GPS receiver.

Points for caution are as follows.

1. Unused pins

Software processing is performed to prevent undesired current from flowing to unused pins in the circuit diagram, so leave these pins open.

2. TCXO input

The TCXO frequency is $18.414\text{MHz} \pm 3\text{ppm}$. Signals that have not been binary-converted should be input via a DC filter capacitor (C19 in the circuit diagram). Input binary-converted signals directly to Pin 7 (TCXO) without passing through C19 or R1 in the circuit diagram.

Make sure the input level at this time satisfies the Electrical Characteristics.

3. IF input

The CXD2931R-9/GA-9 interface is 1.023MHz , and does not accept other frequencies. Signals that have not been binary-converted should be input via a DC filter capacitor (C20). Input binary-converted signals directly to Pin 18 (IF0) without passing through C20 or R3 in the circuit diagram.

Make sure the input level at this time satisfies the Electrical Characteristics.

4. TXD (SIO output)

The TXD amplitude low level is 0.4V or less, and the high level is $\text{V}_{\text{DD}} - 0.4\text{V}$ ($\text{V}_{\text{DD}} = 3.0$ to 3.6V) or more. When the LSI, etc., connected to TXD operates at 5V and has a CMOS input level, perform 3 to 5V conversion before inputting the signal.

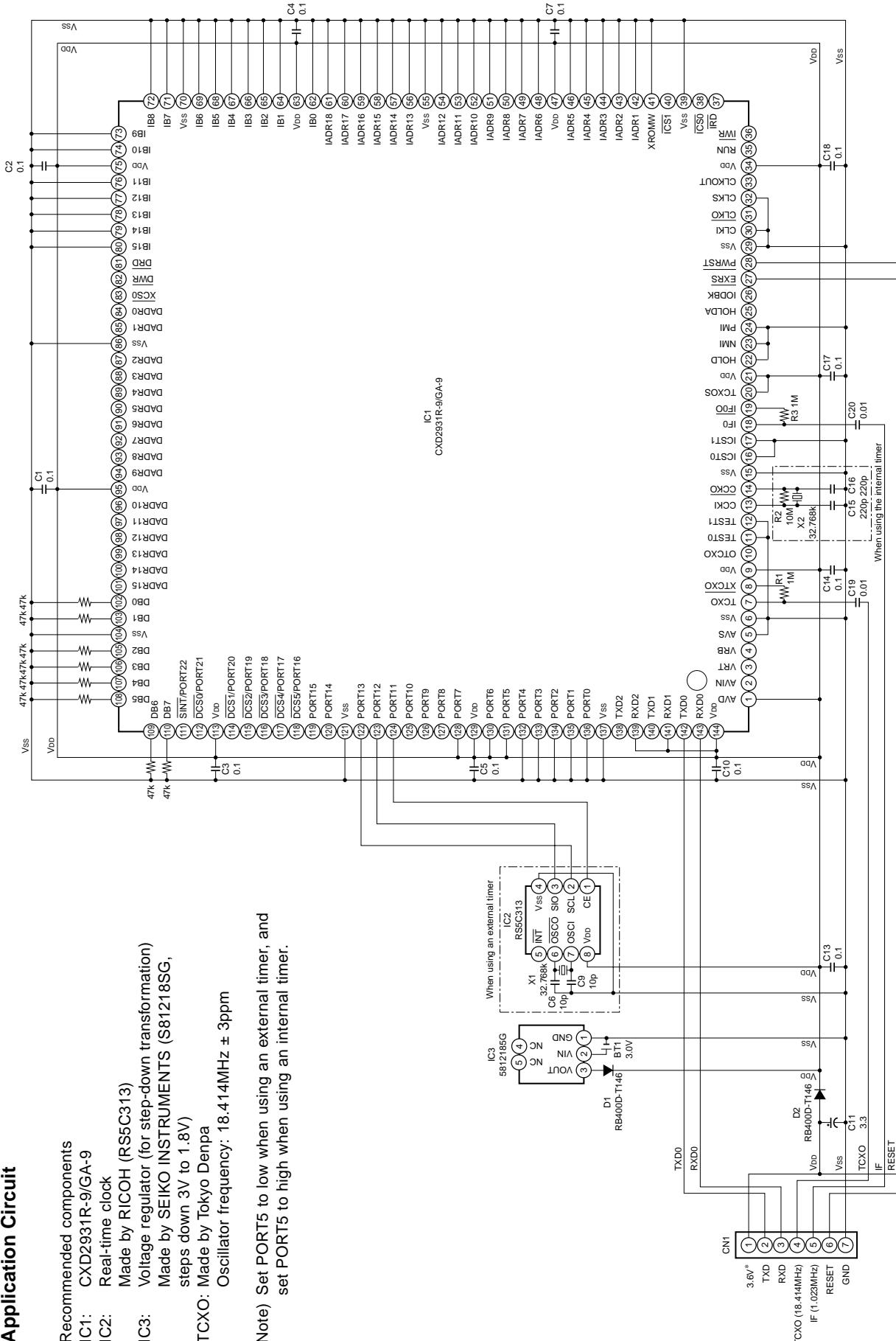
5. Real-time clock

The current software version uses an external real-time clock. Consult your Sony representative beforehand when using the internal real-time clock. When using an external real-time clock, connect Pin 13 (CCKI) to GND.

Application Circuit

| | |
|------------------------|---|
| Recommended components | |
| C1: | CXD2931R-9/GA-9 |
| C2: | Real-time clock |
| C3: | Made by RICOH (RS5C313) Voltage regulator (for step-down transformation) Made by SEIKO INSTRUMENTS (S81218SG, steps down 3V to 1.8V) |
| TCXO: | Made by Tokyo Denpa Oscillator frequency: $18.4114\text{MHz} \pm 3\text{ppm}$ |

Note) Set PORT5 to low when using an external timer, and set PORT5 to high when using an internal timer.



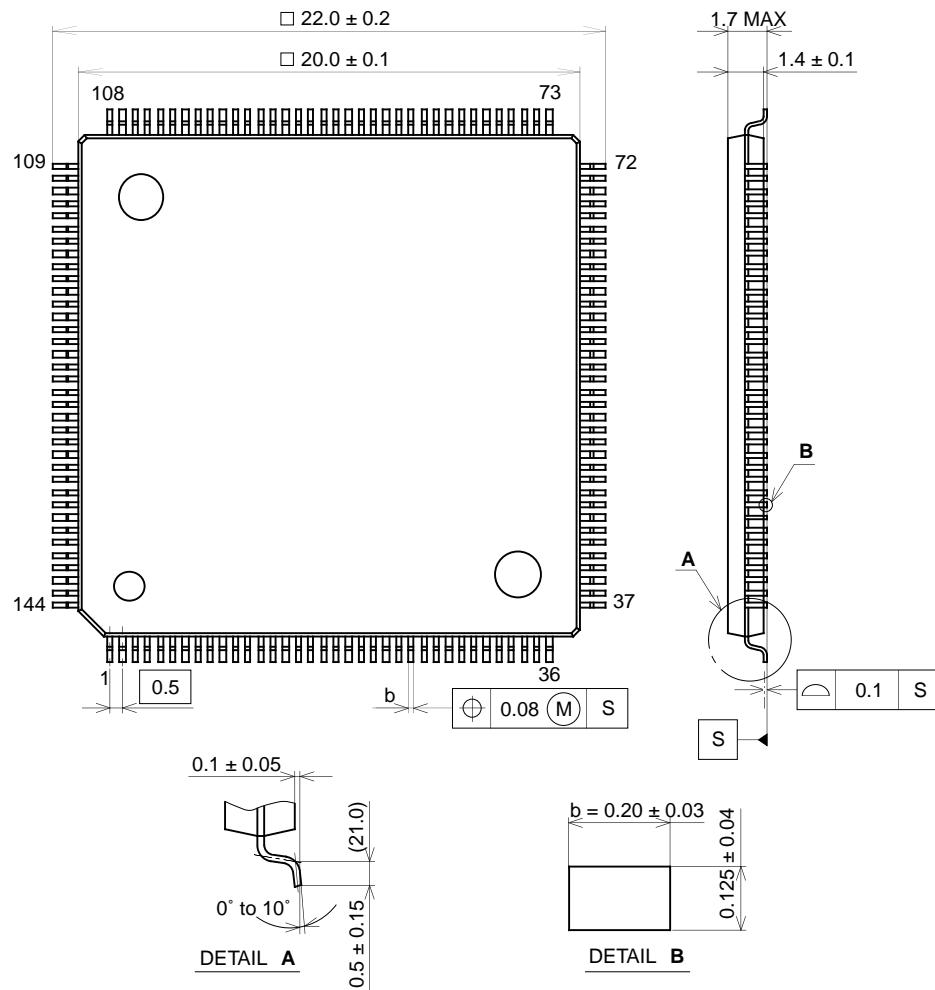
* Input 3.6V in consideration of voltage step-down by diode (D2)

Application circuits shown are typical examples illustrating the operation of the devices. Sony cannot assume responsibility for any problems arising out of the use of these circuits or for any infringement of third party patent and other right due to same.

Package Outline

Unit: mm

CXD2931R-9

144PIN LQFP (PLASTIC)**PACKAGE STRUCTURE**

| | |
|------------|----------------|
| SONY CODE | LQFP-144P-L01 |
| EIAJ CODE | LQFP144-P-2020 |
| JEDEC CODE | _____ |

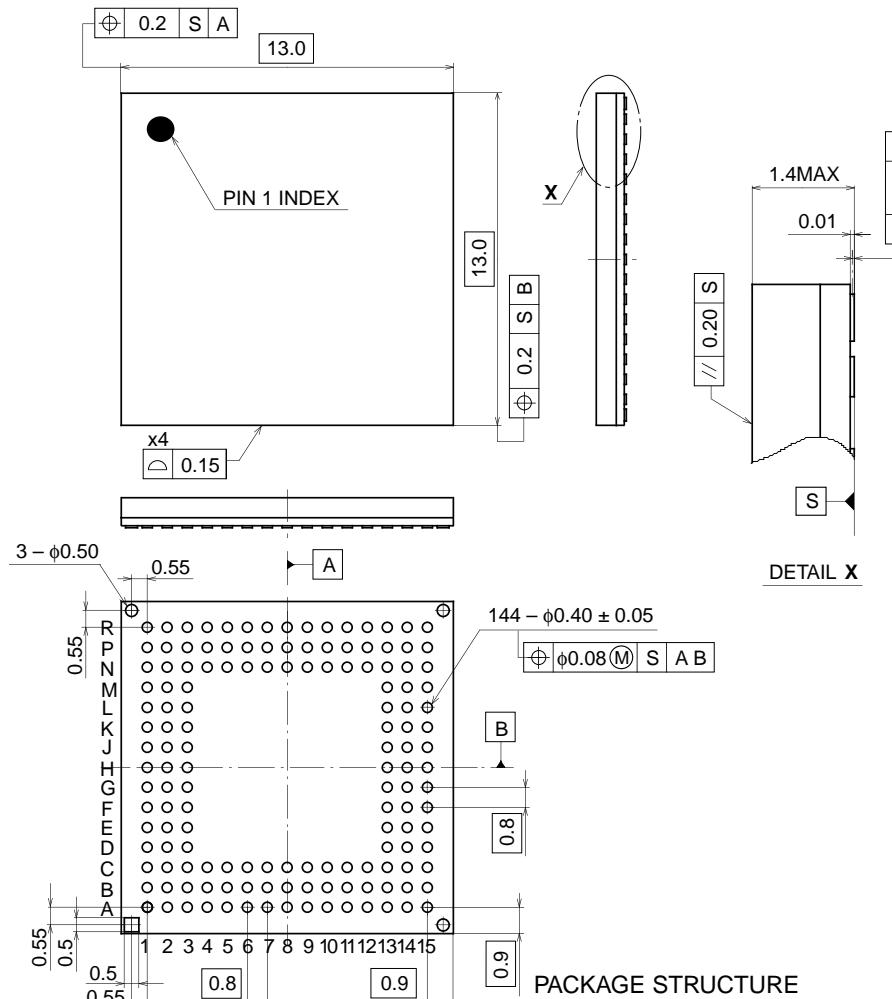
| | |
|------------------|-------------------|
| PACKAGE MATERIAL | EPOXY RESIN |
| LEAD TREATMENT | PALLADIUM PLATING |
| LEAD MATERIAL | COPPER ALLOY |
| PACKAGE MASS | 1.3 g |

Package Outline

Unit: mm

CXD2931GA-9

144PIN LFLGA



| | |
|------------|----------------------|
| SONY CODE | LFLGA-144P-01 |
| EIAJ CODE | P-LFLGA144-13x13-0.8 |
| JEDEC CODE | _____ |

| PACKAGE MATERIAL | ORGANIC SUBSTRATE |
|--------------------|-----------------------|
| TERMINAL TREATMENT | NICKEL & GOLD PLATING |
| TERMINAL MATERIAL | COPPER |
| PACKAGE MASS | 0.5g |