## Applications

- SmartReflex ${ }^{\text {TM }}$-Compliant Power Supply
- Split Supply DSPs and $\mu$ P Solutions OMAP ${ }^{\text {TM }}$, XSCALE $^{\text {TM }}$
- Cell Phones, Smart Phones, PDAs, Digital Cameras, and Portable Media Players
- Micro DC-DC Converter Modules
- Handset Graphic Processors (NVIDIA ${ }^{\circledR}$, ATI)
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## Description

The FAN5355 device is a high-frequency, ultra-fast transient response, synchronous step-down DC-DC converter optimized for low-power applications using small, low-cost inductors and capacitors. The FAN5355 supports up to 800 mA or $1 \mathrm{~A}^{(1)}$ load current.
The device is ideal for mobile phones and similar portable applications powered by a single-cell Lithium-Ion battery. With an output voltage range adjustable via $I^{2} C^{T M}$ interface from 0.75 V to 1.975 V , the device supports low-voltage DSPs and processors, core power supplies in smart phones, PDAs, and handheld computers.
The FAN5355 operates at 3 MHz (nominal) fixed switching frequency using either its internal oscillator or external SYNC frequency.
During light-load conditions, the regulator includes a PFM mode to enhance light-load efficiency. The regulator transitions smoothly between PWM and PFM modes with no glitches on Vout. Normal PFM (NPFM) mode offers the lowest quiescent current, at the expense of setpoint accuracy. Enhanced PFM (EPFM) mode features higher accuracy, as well as a 25 kHz minimum PFM frequency, designed to prevent the regulator from operating in the audible range. In shutdown, the current consumption is reduced to less than $2 \mu \mathrm{~A}$, using software shutdown (EN = 1 with EN_DCDC = 0), and less than 200nA in hardware shutdown ( $\mathrm{EN}=0$ ).
The serial interface is compatible with Fast/Standard and High-Speed mode $I^{2} \mathrm{C}$ specifications, allowing transfers up to 3.4 Mbps . This interface is used for dynamic voltage scaling with 12.5 mV voltage steps, for reprogramming the mode of operation (PFM or Forced PWM), or to disable/enable the output voltage.
The chip's advanced protection features include short-circuit protection and current and temperature limits. During a sustained over-current event, the IC shuts down and restarts after a delay to reduce average power dissipation into a fault.
During start-up, the IC controls the output slew rate to minimize input current and output overshoot at the end of softstart. The IC maintains a consistent soft-start ramp, regardless of output load during start-up.
The FAN5355 is available in 10-lead MLP ( $3 \times 3 \mathrm{~mm}$ ) and 12-bump CSP packages.

## Ordering Information

| Order Number ${ }^{(4)}$ | Option | Slave <br> Address LSB |  | V ${ }_{\text {out }}$ Programming |  |  | Power-up Defaults |  | Package ${ }^{(4)}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | A1 | A0 | DAC | MIN. | MAX. | VSELO | VSEL1 |  |
| FAN5355UC00X | 00 | 0 | 0 | 6 | 0.7500 | 1.5375 | 1.05 | 1.35 | WLCSP-12, $2.23 \times 1.46 \mathrm{~mm}$ |
| FAN5355MP00X | 00 | 0 | 0 | 6 | 0.7500 | 1.5375 | 1.05 | 1.35 | MLP-10, 3x3mm |
| FAN5355UC02X | 02 | 1 | 0 | 6 | 0.7500 | $1.4375{ }^{(2)}$ | 1.05 | 1.20 | WLCSP-12, 2.23x1.46mm |
| FAN5355UC03X | 03 | 0 | 0 | 6 | 0.7500 | 1.5375 | 1.00 | 1.20 | WLCSP-12, $2.23 \times 1.46 \mathrm{~mm}$ |
| FAN5355UC06X | $06^{(1)}$ | 0 | 0 | 6 | 1.1875 | 1.9750 | 1.80 | 1.80 | WLCSP-12, $2.23 \times 1.46 \mathrm{~mm}$ |
| FAN5355UC07X | $07^{(1)}$ | 1 | 1 | 7 | $0.7500{ }^{(3)}$ | 1.9750 | 1.05 | 1.35 | WLCSP-12, 2.23x1.46mm |
| FAN5355MP07X | $07^{(1)}$ | 1 | 1 | 7 | $0.7500^{(3)}$ | 1.9750 | 1.05 | 1.35 | MLP-10, 3x3mm |

## Notes:

1. Option 06 and 07 is rated for 1 A output current. All other options are rated for 800 mA output current.
2. Vout is limited to the maximum voltage for all VSEL codes greater than the maximum Vout listed.
3. Vout may be programmed down 100 mV for option 07 . Performance below 0.75 V is not guaranteed.
4. All packages are "green" per JEDEC: J-STD-020B standard. The " $X$ " designator specifies tape and reel packaging.

## Typical Application



Figure 1. Typical Application

| Component | Description | Vendor | Parameter | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| L1 (Lout) | $1 \mu \mathrm{H}$ nominal | Murata LQM31P <br> or FDK MIPSA2520 | $\mathrm{L}^{(5)}$ | 0.7 | 1.0 | 1.2 | $\mu \mathrm{H}$ |
|  |  | DCR (series R) |  | 100 | $\mathrm{~m} \Omega$ |  |  |
| $\mathrm{C}_{\text {out }}$ | $0603(1.6 \times 0.8 \times 0.8)$ <br> $10 \mu \mathrm{~F}$ X5R or better | Murata or equivalent <br> GRM188R60G106ME47D | $\mathrm{C}^{(6)}$ | 5.6 | 10.0 | 12.0 | $\mu \mathrm{~F}$ |
| $\mathrm{C}_{\mathbb{N}}$ | $0603(1.6 \times 0.8 \times 0.8)$ <br> $4.7 \mu \mathrm{~F}$ X5R or better | Murata or equivalent <br> GRM188R60J475KE19D | $\mathrm{C}^{(6)}$ | 3.0 | 4.7 | 5.6 | $\mu \mathrm{~F}$ |

Table 1. Recommended External Components

## Notes:

5. Minimum $L$ incorporates both tolerance, temperature, and partial saturation effects ( $L$ decreases with increasing current).
6. Minimum $C$ is a function of initial tolerance, maximum temperature, and the effective capacitance being reduced due to frequency, dielectric, and voltage bias effects.

## Pin Configuration



Top View


Bottom View

Figure 2. WLCSP- 12, 2.23x1.46mm

Pin Definitions

| Pin \# |  | Name | Description |
| :---: | :---: | :---: | :---: |
| WLCSP | MLP |  |  |
| A1, B1 | 9 | PGND | Power GND. Power return for gate drive and power transistors. Connect to AGND on PCB. The connection from this pin to the bottom of $\mathrm{C}_{\mathbb{N}}$ should be as short as possible. |
| A2 | 10 | SW | Switching Node. Connect to output inductor. |
| A3 | 1 | PVIN | Power Input Voltage. Connect to input power source. The connection from this pin to $\mathrm{C}_{\mathrm{IN}}$ should be as short as possible. |
| B2 | N/A | SYNC | Sync. When toggling and SYNC_EN bit is HIGH, the regulator synchronizes to the frequency on this pin. In PWM mode, when this pin is statically LOW or statically HIGH, or when its frequency is outside of the specified capture range, the regulator's frequency is controlled by its internal 3 MHz clock. |
| B3 | 2 | AVIN | Analog Input Voltage. Connect to input power source as close as possible to the input bypass capacitor. |
| C1 | 8, PAD | AGND | Analog GND. This is the signal ground reference for the IC. All voltage levels are measured with respect to this pin. |
| C2 | 7 | EN | Enable. When this pin is HIGH, the circuit is enabled. When LOW, quiescent current is minimized. This pin should not be left floating. |
| C3 | 3 | SDA | SDA. ${ }^{2} \mathrm{C}$ interface serial data. |
| D1 | 6 | VOUT | Output Voltage Monitor. Tie this pin to the output voltage. This is a signal input pin to the control circuit and does not carry DC current. |
| D2 | 5 | VSEL | Voltage Select. When HIGH, $\mathrm{V}_{\text {OUt }}$ is set by VSEL1. When LOW, $\mathrm{V}_{\text {OUt }}$ is set by VSELO. This behavior can be overridden through $I^{2} \mathrm{C}$ register settings. This pin should not be left floating. |
| D3 | 4 | SCL | SCL. $\mathrm{I}^{2} \mathrm{C}$ interface serial clock. |

## Note:

7. All logic inputs (SDA, SCL, SYNC, EN, and VSEL) are high impedance and should not be left floating. For minimum quiescent power consumption, tie unused logic inputs to AVIN or AGND. If I2C control is unused, tie SDA and SCL to AVIN.

## Absolute Maximum Ratings

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

| Symbol |  | Parameter | Min. | Max. |
| :---: | :--- | :---: | :---: | :---: |
| Units |  |  |  |  |
| $\mathrm{V}_{\mathrm{CC}}$ | AVIN, SW, PVIN Pins | -0.3 | 6.5 | V |
|  | Other Pins | -0.3 | $\mathrm{AVIN}+0.3^{(8)}$ | V |
| ESD | Electrostatic Discharge Protection Level | Human Body Model per JESD22-A114 | 3.5 | KV |
|  |  | 1.5 | KV |  |
| $\mathrm{T}_{\mathrm{J}}$ | Junction Temperature | -40 | +150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {STG }}$ | Storage Temperature | -65 | +150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\mathrm{L}}$ | Lead Soldering Temperature, 10 Seconds |  | +260 | ${ }^{\circ} \mathrm{C}$ |

## Note:

8. Lesser of 6.5 V or $\mathrm{V}_{\mathrm{CC}}+0.3 \mathrm{~V}$.

## Recommended Operating Conditions

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to absolute maximum ratings.

| Symbol | Parameter | Min. | Max. | Units |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{IN}}$ | Supply Voltage | 2.7 | 5.5 | V |
| f | Frequency Range | 2.7 | 3.3 | MHz |
| $\mathrm{V}_{\mathrm{Sw}}$ | SDA and SCL Voltage Swing ${ }^{(9)}$ |  | 2.5 | V |
| $\mathrm{~T}_{\mathrm{A}}$ | Ambient Temperature | -40 | +85 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\mathrm{J}}$ | Junction Temperature | -40 | +125 | ${ }^{\circ} \mathrm{C}$ |

## Note:

9. The $I^{2} C$ interface operates with $t_{H D ; D A T}=0$ as long as the pull-up voltage for SDA and $S C L$ is less than 2.5 V . If voltage swings greater than 2.5 V are required (for example if the $\mathrm{I}^{2} \mathrm{C}$ bus is pulled up to $\mathrm{V}_{\mathrm{IN}}$ ), the minimum $t_{H D ; D A T}$ must be increased to 80 ns . Most $I^{2} \mathrm{C}$ masters change SDA near the midpoint between the falling and rising edges of SCL, which provides ample $t_{\text {hd; DAT }}$.

## Dissipation Ratings ${ }^{(10)}$

| Package | $\mathbf{R} \theta_{\mathbf{J A}}{ }^{(11)}$ | Power Rating at $\mathbf{T}_{\mathbf{A}} \leq \mathbf{2 5}{ }^{\circ} \mathbf{C}$ | Derating Factor $\mathbf{>} \mathbf{T}_{\mathbf{A}}=\mathbf{2 5}{ }^{\circ} \mathbf{C}$ |
| :--- | :---: | :---: | :---: |
| Molded Leadless Package (MLP) | $49^{\circ} \mathrm{C} / \mathrm{W}$ | 2050 mW | $21 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ |
| Wafer-Level Chip-Scale Package (WLCSP) | $110^{\circ} \mathrm{C} / \mathrm{W}$ | 900 mW | $9 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ |

## Notes:

10. Maximum power dissipation is a function of $T_{J(\max )}, \theta_{J A}$, and $T_{A}$. The maximum allowable power dissipation at any allowable ambient temperature is $P_{D}=\left[T_{J(\max )}-T_{A}\right] / \theta_{J A}$.
11. This thermal data is measured with high-K board (four-layer board according to JESD51-7 JEDEC standard).

## Electrical Specifications

$\mathrm{V}_{\mathbb{I N}}=3.6 \mathrm{~V}, \mathrm{EN}=\mathrm{V}_{\mathbb{I N}}, \mathrm{VSEL}=\mathrm{V}_{\mathrm{IN}}, \mathrm{SYNC}=\mathrm{GND}, \mathrm{VSELO}(6)$ bit $=1, \operatorname{CONTROL2[4:3]}=00 . \mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$. Circuit and components according to Figure 1.

| Symbol | Parameter | Conditions | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power Supplies |  |  |  |  |  |  |
| $\mathrm{V}_{\text {IN }}$ | Input Voltage Range |  | 2.7 |  | 5.5 | V |
| $\mathrm{I}_{0}$ | Quiescent Current | $\mathrm{I}_{\mathrm{O}}=0 \mathrm{~mA}$, EPFM Mode, $\mathrm{F}_{\text {PFM }}=25 \mathrm{kHz}$ |  | 110 | 150 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{I}_{0}=0 \mathrm{~mA}$, NPFM Mode |  | 37 | 50 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{I}_{\mathrm{O}}=0 \mathrm{~mA}, 3 \mathrm{MHz}$ PWM Mode |  | 4.8 |  | mA |
| $I_{\text {sD }}$ | Shutdown Supply Current | EN = GND |  | 0.1 | 2.0 | $\mu \mathrm{A}$ |
|  |  | $\begin{aligned} & \mathrm{EN}=\mathrm{V}_{\text {IN }}, \mathrm{EN}=\mathrm{DCDC} \text { bit }=0, \\ & \mathrm{SDA}=\mathrm{SCL}=\mathrm{V}_{\text {IN }} \end{aligned}$ |  | 0.1 | 2.0 |  |
| Vuvio | Under-Voltage Lockout Threshold | $\mathrm{V}_{\text {IN }}$ Rising |  | 2.40 | 2.60 | V |
|  |  | $\mathrm{V}_{\text {IN }}$ Falling | 2.00 | 2.15 | 2.30 | V |
| VUVHYSt | Under-Voltage Lockout Hysteresis |  | 200 | 250 | 300 | mV |
| ENABLE, VSEL, SDA, SCL, SYNC |  |  |  |  |  |  |
| $\mathrm{V}_{\mathrm{IH}}$ | HIGH-Level Input Voltage |  | 1.2 |  |  | V |
| $\mathrm{V}_{\text {IL }}$ | LOW-Level Input Voltage |  |  |  | 0.4 | V |
| 1 N | Input Bias Current | Input tied to GND or $\mathrm{V}_{1 \times}$ |  | 0.01 | 1.00 | $\mu \mathrm{A}$ |
| Power Switch and Protection |  |  |  |  |  |  |
| $\mathrm{R}_{\mathrm{DS} \text { (ON) }}$ | P-channel MOSFET On Resistance | $\mathrm{V}_{\text {IN }}=3.6 \mathrm{~V}$, CSP Package |  | 145 |  | $\mathrm{m} \Omega$ |
|  |  | $\mathrm{V}_{\text {IN }}=3.6 \mathrm{~V}$, MLP Package |  | 165 |  |  |
|  |  | $\mathrm{V}_{\text {IN }}=2.7 \mathrm{~V}$, MLP Package |  | 200 |  |  |
| ILKGP | P-channel Leakage Current | $\mathrm{V}_{\mathrm{DS}}=6 \mathrm{~V}$ |  |  | 1 | $\mu \mathrm{A}$ |
| $\mathrm{R}_{\text {DS(on)N }}$ | N-channel MOSFET On Resistance | $\mathrm{V}_{\text {IN }}=3.6 \mathrm{~V}$, CSP Package |  | 75 |  | $\mathrm{m} \Omega$ |
|  |  | $\mathrm{V}_{\text {IN }}=3.6 \mathrm{~V}$, MLP Package |  | 95 |  |  |
|  |  | $\mathrm{V}_{\text {IN }}=2.7 \mathrm{~V}$, MLP Package |  | 101 |  |  |
| $I_{\text {LKGN }}$ | N -channel Leakage Current | $\mathrm{V}_{\mathrm{DS}}=6 \mathrm{~V}$ |  |  | 1 | $\mu \mathrm{A}$ |
| $\mathrm{R}_{\text {DIS }}$ | Discharge Resistor for Power-down Sequence | Options 03, 06, 07 |  | 15 | 50 | $\Omega$ |
| ILIMPK | P-MOS Current Limit | $2.7 \mathrm{~V} \leq \mathrm{V}_{\mathbb{I N}} \leq 4.2 \mathrm{~V}$, All Options Except 06 and 07 | 1150 | 1350 | 1600 | mA |
|  |  | $2.7 \mathrm{~V} \leq \mathrm{V}_{\mathbb{N}} \leq 5.5 \mathrm{~V}$, All Options Except 06 and 07 | 1050 | 1350 | 1600 |  |
|  |  | $2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 4.2 \mathrm{~V}, 06$ and 07 Option | 1300 | 1550 | 1800 |  |
| TLIMIT | Thermal Shutdown |  |  | 150 |  | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {HYST }}$ | Thermal Shutdown Hysteresis |  |  | 20 |  | ${ }^{\circ} \mathrm{C}$ |
| Frequency Control |  |  |  |  |  |  |
| $\mathrm{f}_{\text {sw }}$ | Oscillator Frequency |  | 2.65 | 3.00 | 3.35 | MHz |
| $\mathrm{f}_{\text {SYNC }}$ | Synchronization Range |  | 2.7 | 3.0 | 3.3 | MHz |
| $\mathrm{D}_{\text {SYNC }}$ | Synchronization Duty Cycle |  | 20 |  | 80 | \% |
| $\mathrm{f}_{\text {SYNCVAL }}$ | SYNC Frequency Rejection |  | 1.6 |  | 4.3 | MHz |
| $\mathrm{f}_{\text {PFM(MIN }}$ | Minimum PFM Frequency | EPFM Mode, $\mathrm{I}_{\text {LOAD }}=0$ |  | 25 |  | kHz |

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## Electrical Specifications (Continued)

$\mathrm{V}_{\mathbb{I N}}=3.6 \mathrm{~V}, \mathrm{EN}=\mathrm{V}_{\mathbb{I N}}, \mathrm{VSEL}=\mathrm{V}_{\mathbb{I N}}, S Y N C=G N D, \mathrm{VSELO}(6)$ bit $=1, \operatorname{CONTROL2[4:3]}=00 . \mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$. Circuit and components according to Figure 1

| Symbol | Parameter |  | Conditions | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Output Regulation |  |  |  |  |  |  |  |
| Vout | Vout Accuracy | Option 00 | $\mathrm{Iout}_{(\mathrm{DC})}=0$, Forced PWM, $\mathrm{V}_{\text {Out }}=1.35 \mathrm{~V}$ | -1.5 |  | 1.5 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out }} \text { from } 0.75 \text { to } 1.5375, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 800 \mathrm{~mA} \text {, Forced } \mathrm{PWM} \end{aligned}$ | -2 |  | 2 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out }} \text { from } 0.75 \text { to } 1.5375, \\ & l_{\text {out }(\mathrm{DC})}=0 \text { to } 800 \mathrm{~mA} \text {, NPFM Mode } \end{aligned}$ | -1.5 |  | 3.5 | \% |
|  |  | Option 02 | $\mathrm{I}_{\text {OUT }(\mathrm{DC})}=0$, Forced PWM, $\mathrm{V}_{\text {OUt }}=1.20 \mathrm{~V}$ | -1.5 |  | 1.5 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out for }} 0.75 \text { to } 1.4375, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 800 \mathrm{~mA} \text {, Forced } \mathrm{PWM} \end{aligned}$ | -2 |  | 2 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out }} \text { from } 0.75 \text { to } 1.4375, \\ & \text { lout(DC) })=0 \text { to } 800 \mathrm{~mA} \text {, NPFM Mode } \end{aligned}$ | -1.5 |  | 3.5 | \% |
|  |  | Option 03 | $\mathrm{I}_{\text {OUT(DC) }}=0$, Forced PWM, $\mathrm{V}_{\text {OUt }}=1.20 \mathrm{~V}$ | -1.5 |  | 1.5 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out }} \text { from } 0.75 \text { to } 1.5375, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 800 \mathrm{~mA} \text {, Forced } \mathrm{PWM} \end{aligned}$ | -2 |  | 2 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{IN}} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out }} \text { from } 0.75 \text { to } 1.5375, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 800 \mathrm{~mA} \text {, NPFM Mode } \end{aligned}$ | -1.5 |  | 3.5 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out }} \text { from } 0.75 \text { to } 1.5375, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 800 \mathrm{~mA} \text {, EPFM Mode } \end{aligned}$ | -0.5 |  | 2 | \% |
|  |  | Option 06 | $\mathrm{I}_{\text {OUT( }(\mathrm{CC})}=0$, Forced PWM, $\mathrm{V}_{\text {OUT }}=1.800 \mathrm{~V}$ | -1.5 |  | 1.5 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\mathbb{I N}} \leq 5.5 \mathrm{~V} \text {, } \mathrm{V}_{\text {out }} \text { from } 1.185 \text { to } 1.975 \text {, } \\ & \text { lout }(\mathrm{DC})=0 \text { to } 1 \mathrm{~A} \text {, Forced PWM } \end{aligned}$ | -2 |  | 2 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out fom }} 1.185 \text { to } 1.975, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 1 \mathrm{~A} \text {, NPFM Mode } \end{aligned}$ | -1.5 |  | 3.5 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out }} \text { from } 1.185 \text { to } 1.975, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 1 \mathrm{~A} \text {, EPFM Mode } \end{aligned}$ | -0.5 |  | 2 | \% |
|  |  | Option 07 | $\mathrm{I}_{\text {Out }(\mathrm{DC})}=0$, Forced PWM, $\mathrm{V}_{\text {Out }}=1.35 \mathrm{~V}$ | -1.5 |  | 1.5 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V} \text {, } \mathrm{V}_{\text {out }} \text { from } 0.75 \text { to } 1.6875, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 1 \mathrm{~A} \text {, Forced PWM } \end{aligned}$ | -2 |  | 2 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out }} \text { from } 0.75 \text { to } 1.6875, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 1 \mathrm{~A} \text {, NPFM Mode } \end{aligned}$ | -1.5 |  | 3.5 | \% |
|  |  |  | $\begin{aligned} & 2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{~V}_{\text {out }} \text { from } 0.75 \text { to } 1.6875, \\ & \text { lout }(\mathrm{DC})=0 \text { to } 1 \mathrm{~A} \text {, EPFM Mode } \end{aligned}$ | -0.5 |  | 2 | \% |
| $\frac{\Delta V_{\text {OUT }}}{\Delta I_{\text {LOAD }}}$ | Load Regulation |  | $\mathrm{I}_{\text {OUT }(\mathrm{DC})}=0$ to 800 mA , Forced PWM |  | -0.5 |  | \%/A |
| $\frac{\Delta \mathrm{V}_{\text {OUT }}}{\Delta \mathrm{V}_{\mathrm{IN}}}$ | Line Regulation |  | $2.7 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}, \mathrm{I}_{\text {OUT }(\mathrm{DC})}=300 \mathrm{~mA}$ |  | 0 |  | \%/V |
| $\mathrm{V}_{\text {RIPPLE }}$ | Output Ripple Voltage |  | PWM Mode, $\mathrm{V}_{\text {Out }}=1.35 \mathrm{~V}$ |  | 2.2 |  | mVP-P |
|  |  |  | PFM Mode, $\mathrm{I}_{\text {OUt( }(\mathrm{DC})}=10 \mathrm{~mA}$ |  | 20 |  | mVP-P |

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## Electrical Specifications (Continued)

$\mathrm{V}_{\mathbb{I N}}=3.6 \mathrm{~V}, \mathrm{EN}=\mathrm{V}_{\mathbb{I N}}, \mathrm{VSEL}=\mathrm{V}_{\mathbb{I N}}, S Y N C=G N D, \mathrm{VSELO}(6)$ bit $=1, \operatorname{CONTROL2[4:3]}=00 . \mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$. Circuit and components according to Figure 1.

| Symbol | Parameter |  | Conditions | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DAC |  |  |  |  |  |  |  |
|  | Resolution |  | Option 07 | 7 |  |  | Bits |
|  |  |  | All Other Options | 6 |  |  | Bits |
|  | Differential Nonlinearity |  | Monotonicity Assured by Design |  |  | 0.8 | LSB |
| Timing |  |  |  |  |  |  |  |
| $12 \mathrm{C}_{\text {EN }}$ | EN HIGH to $\mathrm{I}^{2} \mathrm{C}$ Start |  |  | 250 |  |  | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\mathrm{V}(\mathrm{L}-\mathrm{H})}$ | $V_{\text {OUT }}$ LOW to HIGH Settling |  | $R_{\text {LOAD }}=75 \Omega$, Transition from 1.0 to 1.5375 V <br> $V_{\text {out }}$ Settled to within 2\% of Setpoint |  | 7 |  | $\mu \mathrm{S}$ |
| Soft-Start |  |  |  |  |  |  |  |
| $\mathrm{t}_{\text {ss }}$ | Regulator Enable to Regulated Vout | Option 06 | $\mathrm{R}_{\text {LOAD }} \geq 5 \Omega$, to $\mathrm{V}_{\text {OUT }}=1.8000 \mathrm{~V}$ |  | 170 | 210 | $\mu \mathrm{s}$ |
|  |  | All Other Options | $\mathrm{R}_{\text {LOAD }} \geq 5 \Omega$, to $\mathrm{V}_{\text {Out }}=$ Power-up Default |  | 140 | 180 | $\mu \mathrm{S}$ |
| $\mathrm{V}_{\text {SLEW }}$ | Soft-start V ${ }_{\text {out }}$ Slew Rate ${ }^{(12)}$ |  |  |  | 18.75 |  | V/ms |

Note:
12. Option 06 slew rate is $35.5 \mathrm{~V} / \mathrm{ms}$ during the first $16 \mu \mathrm{~s}$ of soft-start.

## $I^{2} C$ Timing Specifications

Guaranteed by design.

| Symbol | Parameter | Conditions | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{f}_{\mathrm{SCL}}$ | SCL Clock Frequency | Standard mode |  |  | 100 | kHz |
|  |  | Fast mode |  |  | 400 | kHz |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  |  | 3400 | kHz |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  |  | 1700 | kHz |
| $\mathrm{t}_{\text {buF }}$ | Bus-free Time between STOP and START Conditions | Standard mode |  | 4.7 |  | $\mu \mathrm{s}$ |
|  |  | Fast mode |  | 1.3 |  | $\mu \mathrm{S}$ |
| thdista | START or Repeated START Hold Time | Standard mode |  | 4 |  | $\mu \mathrm{s}$ |
|  |  | Fast mode |  | 600 |  | ns |
|  |  | High-Speed mode |  | 160 |  | ns |
| tow | SCL LOW Period | Standard mode |  | 4.7 |  | $\mu \mathrm{s}$ |
|  |  | Fast mode |  | 1.3 |  | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 160 |  | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 320 |  | ns |
| $\mathrm{tHIGH}^{\text {l }}$ | SCL HIGH Period | Standard mode |  | 4 |  | $\mu \mathrm{s}$ |
|  |  | Fast mode |  | 600 |  | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 60 |  | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 120 |  | ns |
| tsu;sta | Repeated START Setup Time | Standard mode |  | 4.7 |  | $\mu \mathrm{s}$ |
|  |  | Fast mode |  | 600 |  | ns |
|  |  | High-Speed mode |  | 160 |  | ns |
| $\mathrm{tsu}_{\text {jat }}$ | Data Setup Time | Standard mode |  | 250 |  | ns |
|  |  | Fast mode |  | 100 |  | ns |
|  |  | High-Speed mode |  | 10 |  | ns |
| $\mathrm{t}_{\mathrm{HD} ; \mathrm{DAT}}$ | Data Hold Time ${ }^{(9)}$ | Standard mode | 0 |  | 3.45 | $\mu \mathrm{s}$ |
|  |  | Fast mode | 0 |  | 900 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ | 0 |  | 70 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ | 0 |  | 150 | ns |
| $\mathrm{t}_{\mathrm{RCL}}$ | SCL Rise Time | Standard mode | 20+0 |  | 1000 | ns |
|  |  | Fast mode | 20+0. |  | 300 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 10 | 80 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 20 | 160 | ns |
| $\mathrm{t}_{\text {FCL }}$ | SCL Fall Time | Standard mode | 20+0 |  | 300 | ns |
|  |  | Fast mode | 20+0 |  | 300 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 10 | 40 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 20 | 80 | ns |
| $t_{\text {RDA }}$ <br> $\mathrm{t}_{\mathrm{RCL}}$ | SDA Rise Time <br> Rise Time of SCL After a Repeated START Condition and After ACK Bit | Standard mode | 20+0 |  | 1000 | ns |
|  |  | Fast mode | 20+0 |  | 300 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 10 | 80 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 20 | 160 | ns |
| $t_{\text {fDA }}$ | SDA Fall Time | Standard mode | 20+0 |  | 300 | ns |
|  |  | Fast mode | 20+0 |  | 300 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 10 | 80 | ns |
|  |  | High-Speed mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 20 | 160 | ns |
| $\mathrm{t}_{\text {su; }}$ STo | Stop Condition Setup Time | Standard mode |  | 4 |  | $\mu \mathrm{s}$ |
|  |  | Fast mode |  | 600 |  | ns |
|  |  | High-Speed mode |  | 160 |  | ns |
| $\mathrm{C}_{\mathrm{B}}$ | Capacitive Load for SDA and SCL |  |  |  | 400 | pF |



Figure 5. $\quad I^{2} C$ Interface Timing for Fast and Slow Modes


Note A: First rising edge of SCLH after Repeated Start and after each ACK bit.
Figure 6. $I^{2} \mathrm{C}$ Interface Timing for High-Speed Mode

## Typical Performance Characteristics

Unless otherwise specified, Auto-PWM/NPFM, $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, and recommended components as specified in Table 1.

## Efficiency



Figure 7. Efficiency vs. Load at $\mathrm{V}_{\text {out }}=1.05 \mathrm{~V}$


Figure 9. Efficiency vs. Load at $\mathrm{V}_{\text {OUt }}=1.50 \mathrm{~V}$


Figure 8. Efficiency vs. Load at $\mathrm{V}_{\text {OUT }}=1.35 \mathrm{~V}$

## Typical Performance Characteristics

Unless otherwise specified, Auto-PWM/NPFM, $\mathrm{V}_{\mathbb{I N}}=3.6 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, and recommended components as specified in Table 1.


Figure 10. Load Regulation at $\mathrm{V}_{\text {OUT }}=1.05 \mathrm{~V}$


Figure 12. Quiescent Current, $\mathrm{I}_{\text {LOAD }}=0, \mathrm{EN}=1.8 \mathrm{~V}$


Figure 14. \% Vout Shift vs. Temperature (Normalized)


Figure 11. Load Regulation at $\mathrm{V}_{\text {out }}=1.35 \mathrm{~V}$


Figure 13. Shutdown Current, $\mathrm{I}_{\text {LOAD }}=0, \mathrm{EN}=0$


Figure 15. Output Stage $\mathbf{R}_{\mathrm{DS}(\mathrm{ON})}$ vs. $\mathbf{V}_{\mathrm{IN}}$

## Typical Performance Characteristics (Continued)

Unless otherwise specified, $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=1.35 \mathrm{~V}$, and load step $\mathrm{t}_{\mathrm{R}}=\mathrm{t}_{\mathrm{F}}<100 \mathrm{~ns}$.

## Load Transient Response



Figure 16. $\mathbf{5 0} \mathrm{mA}$ to $\mathbf{4 0 0 \mathrm { mA }}$ to $\mathbf{5 0 m A}$, Forced PWM


Figure 18. 400 mA to $\mathbf{7 5 0 m A}$ to 400 mA , Auto PWM/NPFM


Figure 17. 50 mA to 400 mA to 50 mA , Auto PWM/NPFM


Figure 19. 0 mA to 125 mA to 0 mA , Auto PWM/NPFM

Typical Performance Characteristics (Continued)
Unless otherwise specified, $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}$.
VSEL Transitions


Figure 20. Single-Step, $\mathrm{R}_{\text {LOAD }}=6.2 \Omega$


Figure 22. Single-Step, $\mathrm{R}_{\text {LOAD }}=50 \Omega$


Figure 21. Single-Step, R LOAD $=6.2 \Omega$


Figure 23. Single-Step, $\mathrm{R}_{\text {LOAD }}=50 \Omega$

Typical Performance Characteristics (Continued)
Unless otherwise specified, $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}$.
VSEL Transitions


Figure 24. Single-Step from Forced PWM (MODE1=0), $R_{\text {LOAD }}=50 \Omega$


Figure 26. Single-Step from Auto PWM/PFM (MODE1=1), $R_{\text {LOAD }}=50 \Omega$


Figure 25. Single Step, R LOAD $=6.2 \Omega$

Typical Performance Characteristics (Continued)
$R_{\text {LOAD }}$ is switched with N -channel MOSFET from VOUT to $G N D$. $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}$, initial $\mathrm{V}_{\text {OUT }}=1.35 \mathrm{~V}$, initial I LOAD $=0 \mathrm{~mA}$.
Short Circuit and Over-Current Fault Response


Figure 27. Metallic Short Applied at VOUT


Figure 29. R $_{\text {LOAD }}=660 \mathrm{~m} \Omega$


Figure 28. Metallic Short Applied at VOUT


Figure 30. R $_{\text {LOAD }}=660 \mathrm{~m} \Omega$

Typical Performance Characteristics (Continued)
Unless otherwise specified, $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}$.


Figure 31. SW-Node Jitter (Infinite Persistence), $I_{\text {LOAD }}=200 \mathrm{~mA}$


Figure 33. Soft-Start, R $_{\text {LOAD }}=50 \Omega$


Figure 32. SW-Node Jitter, External Synchronization (Infinite Persistence), ILOAD $=200 \mathrm{~mA}$


Figure 34. $\mathrm{V}_{\mathrm{IN}}$ Ripple Rejection (PSRR)

## Circuit Description

## Overview

The FAN5355 is a synchronous buck regulator that typically operates at 3 MHz with moderate to heavy load currents. At light load currents, the converter operates in power-saving PFM mode. The regulator automatically transitions between fixed-frequency PWM and variable-frequency PFM mode to maintain the highest possible efficiency over the full range of load current.

The FAN5355 uses a very fast non-linear control architecture to achieve excellent transient response with minimum-sized external components.

The FAN5355 integrates an $I^{2} \mathrm{C}$-compatible interface, allowing transfers up to 3.4 Mbps . This communication interface can be used to:

1. Dynamically re-program the output voltage in 12.5 mV increments.
2. Reprogram the mode of operation to enable or disable PFM mode.
3. Control voltage transition slew rate.
4. Control the frequency of operation by synchronizing to an external clock.
5. Enable / disable the regulator.

For more details, refer to the $I^{2} C$ Interface and Register Description sections.

## Output Voltage Programming

| Option | V OUT Equation |  |
| :---: | :--- | :---: |
| 00,02, <br> 03 | $\mathrm{~V}_{\text {OUT }}=0.75+\mathrm{N}_{\text {VSEL }} \bullet 12.5 \mathrm{mV}$ | (1) |
| 07 | $\mathrm{V}_{\text {OUT }}=0.100+\mathrm{N}_{\text {VSEL }} \bullet 25 \mathrm{mV}$ <br> for $\mathrm{N}_{\text {VSEL }}=0$ to 23 <br> $\mathrm{~V}_{\text {OUT }}=0.675+\left(\mathrm{N}_{\text {VSEL }}-23\right) \bullet 12.5 \mathrm{mV}$ <br> for $\mathrm{N}_{\text {VSEL }}>23$ | (2) |
| 06 | $\mathrm{~V}_{\text {OUT }}=1.1875+\mathrm{N}_{\text {VSEL }} \bullet 12.5 \mathrm{mV}$ | (3) |

where $\mathrm{N}_{\text {vSEL }}$ is the decimal value of the setting of the VSEL register that controls Vout.

## Note:

13. Option 02 maximum voltage is 1.4375 V (see Table 3).

## Power-up, EN, and Soft-start

All internal circuits remain de-biased and the IC is in a very low quiescent current state until the following are true:

1. $\mathrm{V}_{\mathrm{IN}}$ is above its rising UVLO threshold, and
2. EN is HIGH .

At that point, the IC begins a soft-start cycle, its $I^{2} \mathrm{C}$ interface is enabled, and its registers loaded with their default values.

During the initial soft-start, Vout ramps linearly to the setpoint programmed in the VSEL register selected by the VSEL pin. The soft start features a fixed output voltage slew rate of $18.75 \mathrm{~V} / \mathrm{ms}$, and achieves regulation approximately $90 \mu \mathrm{~s}$ after EN rises. PFM mode is enabled during soft-start until the output is in regulation, regardless of the MODE bit settings. This allows the regulator to start into a partially charged output without discharging it; in other words, the regulator does not allow current to flow from the load back to the battery.

As soon as the output has reached its setpoint, the control forces PWM mode for about $85 \mu$ s to allow all internal control circuits to calibrate.

| Symbol | Description |  | Value ( $\mu \mathrm{s}$ ) |
| :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\text {SSLLY }}$ | Time from EN to start of soft-start ramp |  | 25 |
| $\mathrm{t}_{\text {REG }}$ | $V_{\text {out }}$ ramp start to regulation | Opt 06 | 16 +(VSEL-0.7) X 53 |
|  |  | Others | (VSEL-0.1) X 53 |
| tpok | PWROK (CONTROL2[5]) rising from $t_{\text {REG }}$ |  | 11 |
| $\mathrm{t}_{\text {cal }}$ | Regulator stays in PWM mode during this time |  | 10 |

Table 2. Soft-Start Timing (see Figure 35)


Figure 35. Soft-start Timing

| VSEL Value |  |  | VOUT |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec | Binary | Hex | 00, 03 | 02 | 06 |
| 0 | 000000 | 00 | 0.7500 | 0.7500 | 1.1875 |
| 1 | 000001 | 01 | 0.7625 | 0.7625 | 1.2000 |
| 2 | 000010 | 02 | 0.7750 | 0.7750 | 1.2125 |
| 3 | 000011 | 03 | 0.7875 | 0.7875 | 1.2250 |
| 4 | 000100 | 04 | 0.8000 | 0.8000 | 1.2375 |
| 5 | 000101 | 05 | 0.8125 | 0.8125 | 1.2500 |
| 6 | 000110 | 06 | 0.8250 | 0.8250 | 1.2625 |
| 7 | 000111 | 07 | 0.8375 | 0.8375 | 1.2750 |
| 8 | 001000 | 08 | 0.8500 | 0.8500 | 1.2875 |
| 9 | 001001 | 09 | 0.8625 | 0.8625 | 1.3000 |
| 10 | 001010 | OA | 0.8750 | 0.8750 | 1.3125 |
| 11 | 001011 | 0B | 0.8875 | 0.8875 | 1.3250 |
| 12 | 001100 | OC | 0.9000 | 0.9000 | 1.3375 |
| 13 | 001101 | OD | 0.9125 | 0.9125 | 1.3500 |
| 14 | 001110 | 0E | 0.9250 | 0.9250 | 1.3625 |
| 15 | 001111 | 0F | 0.9375 | 0.9375 | 1.3750 |
| 16 | 010000 | 10 | 0.9500 | 0.9500 | 1.3875 |
| 17 | 010001 | 11 | 0.9625 | 0.9625 | 1.4000 |
| 18 | 010010 | 12 | 0.9750 | 0.9750 | 1.4125 |
| 19 | 010011 | 13 | 0.9875 | 0.9875 | 1.4250 |
| 20 | 010100 | 14 | 1.0000 | 1.0000 | 1.4375 |
| 21 | 010101 | 15 | 1.0125 | 1.0125 | 1.4500 |
| 22 | 010110 | 16 | 1.0250 | 1.0250 | 1.4625 |
| 23 | 010111 | 17 | 1.0375 | 1.0375 | 1.4750 |
| 24 | 011000 | 18 | 1.0500 | 1.0500 | 1.4875 |
| 25 | 011001 | 19 | 1.0625 | 1.0625 | 1.5000 |
| 26 | 011010 | 1A | 1.0750 | 1.0750 | 1.5125 |
| 27 | 011011 | 1B | 1.0875 | 1.0875 | 1.5250 |
| 28 | 011100 | 1C | 1.1000 | 1.1000 | 1.5375 |
| 29 | 011101 | 1D | 1.1125 | 1.1125 | 1.5500 |
| 30 | 011110 | 1E | 1.1250 | 1.1250 | 1.5625 |
| 31 | 011111 | 1F | 1.1375 | 1.1375 | 1.5750 |
| 32 | 100000 | 20 | 1.1500 | 1.1500 | 1.5875 |
| 33 | 100001 | 21 | 1.1625 | 1.1625 | 1.6000 |
| 34 | 100010 | 22 | 1.1750 | 1.1750 | 1.6125 |
| 35 | 100011 | 23 | 1.1875 | 1.1875 | 1.6250 |
| 36 | 100100 | 24 | 1.2000 | 1.2000 | 1.6375 |
| 37 | 100101 | 25 | 1.2125 | 1.2125 | 1.6500 |
| 38 | 100110 | 26 | 1.2250 | 1.2250 | 1.6625 |
| 39 | 100111 | 27 | 1.2375 | 1.2375 | 1.6750 |
| 40 | 101000 | 28 | 1.2500 | 1.2500 | 1.6875 |
| 41 | 101001 | 29 | 1.2625 | 1.2625 | 1.7000 |
| 42 | 101010 | 2A | 1.2750 | 1.2750 | 1.7125 |
| 43 | 101011 | 2B | 1.2875 | 1.2875 | 1.7250 |
| 44 | 101100 | 2C | 1.3000 | 1.3000 | 1.7375 |
| 45 | 101101 | 2D | 1.3125 | 1.3125 | 1.7500 |
| 46 | 101110 | 2E | 1.3250 | 1.3250 | 1.7625 |
| 47 | 101111 | 2F | 1.3375 | 1.3375 | 1.7750 |
| 48 | 110000 | 30 | 1.3500 | 1.3500 | 1.7875 |
| 49 | 110001 | 31 | 1.3625 | 1.3625 | 1.8000 |
| 50 | 110010 | 32 | 1.3750 | 1.3750 | 1.8125 |
| 51 | 110011 | 33 | 1.3875 | 1.3875 | 1.8250 |
| 52 | 110100 | 34 | 1.4000 | 1.4000 | 1.8375 |
| 53 | 110101 | 35 | 1.4125 | 1.4125 | 1.8500 |
| 54 | 110110 | 36 | 1.4250 | 1.4250 | 1.8625 |
| 55 | 110111 | 37 | 1.4375 | 1.4375 | 1.8750 |
| 56 | 111000 | 38 | 1.4500 | 1.4375 | 1.8875 |
| 57 | 111001 | 39 | 1.4625 | 1.4375 | 1.9000 |
| 58 | 111010 | 3A | 1.4750 | 1.4375 | 1.9125 |
| 59 | 111011 | 3B | 1.4875 | 1.4375 | 1.9250 |
| 60 | 111100 | 3C | 1.5000 | 1.4375 | 1.9375 |
| 61 | 111101 | 3D | 1.5125 | 1.4375 | 1.9500 |
| 62 | 111110 | 3E | 1.5250 | 1.4375 | 1.9625 |
| 63 | 111111 | 3F | 1.5375 | 1.4375 | 1.9750 |

Table 3. VSEL vs. VOUT for Options 00, 02, 03, 06

| VSEL |  | VOUT | VSEL |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec | Hex |  | Dec | Hex | VOUT |
| 0 | 00 | 0.1000 | 64 | 00 | 1.1875 |
| 1 | 01 | 0.1250 | 65 | 01 | 1.2000 |
| 2 | 02 | 0.1500 | 66 | 02 | 1.2125 |
| 3 | 03 | 0.1750 | 67 | 03 | 1.2250 |
| 4 | 04 | 0.2000 | 68 | 04 | 1.2375 |
| 5 | 05 | 0.2250 | 69 | 05 | 1.2500 |
| 6 | 06 | 0.2500 | 70 | 06 | 1.2625 |
| 7 | 07 | 0.2750 | 71 | 07 | 1.2750 |
| 8 | 08 | 0.3000 | 72 | 08 | 1.2875 |
| 9 | 09 | 0.3250 | 73 | 09 | 1.3000 |
| 10 | 0A | 0.3500 | 74 | 0A | 1.3125 |
| 11 | 0B | 0.3750 | 75 | 0B | 1.3250 |
| 12 | OC | 0.4000 | 76 | OC | 1.3375 |
| 13 | 0D | 0.4250 | 77 | OD | 1.3500 |
| 14 | 0E | 0.4500 | 78 | 0E | 1.3625 |
| 15 | 0F | 0.4750 | 79 | 0F | 1.3750 |
| 16 | 10 | 0.5000 | 80 | 10 | 1.3875 |
| 17 | 11 | 0.5250 | 81 | 11 | 1.4000 |
| 18 | 12 | 0.5500 | 82 | 12 | 1.4125 |
| 19 | 13 | 0.5750 | 83 | 13 | 1.4250 |
| 20 | 14 | 0.6000 | 84 | 14 | 1.4375 |
| 21 | 15 | 0.6250 | 85 | 15 | 1.4500 |
| 22 | 16 | 0.6500 | 86 | 16 | 1.4625 |
| 23 | 17 | 0.6750 | 87 | 17 | 1.4750 |
| 24 | 18 | 0.6875 | 88 | 18 | 1.4875 |
| 25 | 19 | 0.7000 | 89 | 19 | 1.5000 |
| 26 | 1A | 0.7125 | 90 | 1A | 1.5125 |
| 27 | 1B | 0.7250 | 91 | 1B | 1.5250 |
| 28 | 1C | 0.7375 | 92 | 1C | 1.5375 |
| 29 | 1D | 0.7500 | 93 | 1D | 1.5500 |
| 30 | 1E | 0.7625 | 94 | 1E | 1.5625 |
| 31 | 1F | 0.7750 | 95 | 1F | 1.5750 |
| 32 | 20 | 0.7875 | 96 | 20 | 1.5875 |
| 33 | 21 | 0.8000 | 97 | 21 | 1.6000 |
| 34 | 22 | 0.8125 | 98 | 22 | 1.6125 |
| 35 | 23 | 0.8250 | 99 | 23 | 1.6250 |
| 36 | 24 | 0.8375 | 100 | 24 | 1.6375 |
| 37 | 25 | 0.8500 | 101 | 25 | 1.6500 |
| 38 | 26 | 0.8625 | 102 | 26 | 1.6625 |
| 39 | 27 | 0.8750 | 103 | 27 | 1.6750 |
| 40 | 28 | 0.8875 | 104 | 28 | 1.6875 |
| 41 | 29 | 0.9000 | 105 | 29 | 1.7000 |
| 42 | 2A | 0.9125 | 106 | 2A | 1.7125 |
| 43 | 2B | 0.9250 | 107 | 2B | 1.7250 |
| 44 | 2C | 0.9375 | 108 | 2C | 1.7375 |
| 45 | 2D | 0.9500 | 109 | 2D | 1.7500 |
| 46 | 2E | 0.9625 | 110 | 2E | 1.7625 |
| 47 | 2F | 0.9750 | 111 | 2F | 1.7750 |
| 48 | 30 | 0.9875 | 112 | 30 | 1.7875 |
| 49 | 31 | 1.0000 | 113 | 31 | 1.8000 |
| 50 | 32 | 1.0125 | 114 | 32 | 1.8125 |
| 51 | 33 | 1.0250 | 115 | 33 | 1.8250 |
| 52 | 34 | 1.0375 | 116 | 34 | 1.8375 |
| 53 | 35 | 1.0500 | 117 | 35 | 1.8500 |
| 54 | 36 | 1.0625 | 118 | 36 | 1.8625 |
| 55 | 37 | 1.0750 | 119 | 37 | 1.8750 |
| 56 | 38 | 1.0875 | 120 | 38 | 1.8875 |
| 57 | 39 | 1.1000 | 121 | 39 | 1.9000 |
| 58 | 3A | 1.1125 | 122 | 3A | 1.9125 |
| 59 | 3B | 1.1250 | 123 | 3B | 1.9250 |
| 60 | 3C | 1.1375 | 124 | 3C | 1.9375 |
| 61 | 3D | 1.1500 | 125 | 3D | 1.9500 |
| 62 | 3E | 1.1625 | 126 | 3E | 1.9625 |
| 63 | 3F | 1.1750 | 127 | 3F | 1.9750 |

Table 4. VSEL vs. VOUT for Option 07

## Software Enable

The EN_DCDC bit, VSELx[7] can be used to enable the regulator in conjunction with the EN pin. Setting EN_DCDC with EN HIGH begins the soft-start sequence described above.

| EN_DCDC Bit | EN Pin | $\mathbf{I}^{\mathbf{2}} \mathbf{C}$ | REGULATOR |
| :---: | :---: | :---: | :---: |
| 0 | 0 | OFF | OFF |
| 1 | 1 | ON | ON |
| 1 | 0 | OFF | OFF |
| 0 | 1 | ON | OFF |

Table 5. EN_DCDC Behavior

## Light-Load (PFM) Operation

The FAN5355 offers both a Normal PFM (NPFM) and Enhanced PFM (EPFM) mode. NPFM is normally used when the load current is very low and when quiescent current must be minimized. EPFM provides more accurate DC regulation and limits the minimum frequency to 25 kHz typical to prevent operation in the audio band.
$V_{\text {out }}$ ripple is identical in both modes (less than 20 mV ), and both modes feature very fast response to load transients.

The FAN5355 incorporates a single-pulse, light-load modulation that ensures:

- Smooth transitions between PFM and PWM modes
- Minimum frequency, of 25 kHz typical, to avoid audible noise (EPFM only)
- Single-pulse operation for low ripple
- Predictable PFM entry and exit currents.

PFM begins after the inductor current has become discontinuous, crossing zero during the PWM cycle in 32 consecutive cycles. PFM exit occurs when discontinuous current mode (DCM) operation cannot supply sufficient current to maintain regulation. During PFM mode, the inductor current ripple is about $40 \%$ higher than in PWM mode. The load current required to exit PFM mode is thereby about $20 \%$ higher than the load current required to enter PFM mode, providing sufficient hysteresis to prevent "mode chatter."

While PWM ripple voltage is typically less than $4 \mathrm{mVP}-\mathrm{P}$, PFM ripple voltage can be up to $30 \mathrm{mVP}-\mathrm{P}$ during very light load. To prevent significant undershoot when a load transient occurs, the initial DC setpoint for the regulator in PFM mode is set 10 mV higher than in PWM mode. This offset decays to about 5 mV after the regulator has been in PFM mode for $\sim 100 \mu \mathrm{~s}$. The maximum instantaneous voltage in PFM is 30 mV above the setpoint.
In Enhanced PFM (EPFM) mode, the regulator maintains a minimum frequency of 25 kHz (typical) to prevent audible noise being generated by the external components. To achieve this, the regulator turns on the low-side MOSFET to
"create demand" for a pulse if no pulse had been required for $40 \mu \mathrm{~s}$. The minimum frequency limit circuit takes effect with load currents below about 3.5 mA . Above that load point, the natural PFM period is less than $40 \mu \mathrm{~s}$. This circuit only activates when I LOAD is greater than $\sim 3.5 \mathrm{~mA}$. If the load remains above 3.5 mA , there is no quiescent current penalty for EPFM mode and there is some accuracy advantage.

NPFM allows the switching frequency ( $\mathrm{f}_{\mathrm{sw}}$ ) to go as low as required to support the load current. This achieves a lower quiescent current than EPFM, but sacrifices up to $\pm 15 \mathrm{mV}$ of DC accuracy when compared to EPFM or PWM modes. As shown in Table 6, EPFM and NPFM modes have the same frequency when the load is above 4 mA . If the load is above 4 mA , EPFM is the preferred mode, since it has tighter DC regulation with the same efficiency.
EPFM can only be enabled by setting the MODE_CTRL bits to 11. In versions with MODE_CTRL disabled (see Table 12), the PFM mode is NPFM.

| Mode | EPFM | NPFM |
| :--- | :---: | :---: |
| $I_{\text {QUIESCENT }}$ typical at $\mathrm{I}_{\text {LOAD }}=0$ | $110 \mu \mathrm{~A}$ | $38 \mu \mathrm{~A}$ |
| DC Accuracy | Better | Good |
| $\mathrm{f}_{\text {Sw }}$ at $\mathrm{I}_{\text {LOAD }}=0$ | 25 kHz | to 0 Hz |
| $\mathrm{f}_{\text {Sw }}$ at $\mathrm{I}_{\text {LOAD }}>3.5 \mathrm{~mA}$ | $>33 \mathrm{kHz}$ | $>33 \mathrm{kHz}$ |

Table 6. PFM Modes Comparison
PFM mode can be disabled by writing to the mode control bits: CONTROL1[3:0] (see Table 12 for details).

## Switching Frequency Control and Synchronization

The nominal internal oscillator frequency is 3 MHz . The regulator runs at its internal clock frequency until these conditions are met:

1. EN_SYNC bit, CONTROL1[5], is set; and
2. A valid frequency appears on the SYNC pin.

| CONTROL2 |  | Fsync Valid |  |  |
| :---: | :---: | :---: | :---: | :---: |
| PLL_MULT | fsYNc Divider | Min. | Typ. | Max. |
| 00 | 1 | 2.25 | 3.00 | 4.00 |
| 01 | 2 | 1.13 | 1.50 | 2.00 |
| 10 | 3 | 0.75 | 1.00 | 1.33 |
| 11 | 4 | 0.56 | 0.75 | 1.00 |

Table 7.SYNC Frequency Validation for fosc(INTERNAL) $=3.0 \mathrm{MHz}$
If the EN_SYNC is set and SYNC fails validation, the regulator continues to run at its internal oscillator frequency. The regulator is functional if $\mathrm{f}_{\mathrm{SYNC}}$ is valid, as defined in Table 7, but its performance is compromised if fyYNC is outside the $\mathrm{f}_{\mathrm{SYNC}}$ window in the Electrical Specifications.
When CONTROL1[3:2] = 00 and the VSEL line is LOW, the converter operates according to the MODEO bit, CONTROL1[0], with synchronization disabled regardless of the state of the EN_SYNC and HW_nSW bits.

## Output Voltage Transitions

The IC regulates $V_{\text {OUt }}$ to one of two setpoint voltages, as determined by the VSEL pin and the HW_nSW bit.

| VSEL Pin | HW_nSW Bit | V $_{\text {out }}$ Setpoint ${ }^{(14)}$ | PFM |
| :---: | :---: | :---: | :---: |
| 0 | 1 | VSEL0 | Allowed |
| 1 | 1 | VSEL1 | Per MODE1 |
| x | 0 | VSEL1 | Per MODE1 |

Table 8. Vout Setpoint and Mode Control MODE_CTRL, CONTROL1[3:2] = 00

## Note:

14. Option 07 uses VSELx[6:0] to set $\mathrm{V}_{\text {Out }}$, while all other options use VSELx[5:0].

If HW_nSW $=0$, $V_{\text {out }}$ transitions are initiated through the following sequence:

1. Write the new setpoint in VSEL1.
2. Write desired transition rate in DEFSLEW, CONTROL2[2:0], and set the GO bit in CONTROL2[7].

If HW_nSW =1, Vout transitions are initiated either by changing the state of the VSEL pin or by writing to the VSEL register selected by the VSEL pin.

## Positive Transitions

When transitioning to a higher $\mathrm{V}_{\text {out, }}$ the regulator can perform the transition using multi-step or single-step mode.

## Multi-step Mode:

The internal DAC is stepped at a rate defined by DEFSLEW, CONTROL2[2:0], ranging from 000 to 110. This mode minimizes the current required to charge Cout and thereby minimizes the current drain from the battery when transitioning. The PWROK bit, CONTROL2[5], remains LOW until about $1.5 \mu \mathrm{~s}$ after the DAC completes its ramp.


Figure 36. Multi-step Vout Transition

## Single-step Mode:

Used if DEFSLEW, CONTROL2[2:0] = 111. The internal DAC is immediately set to the higher voltage and the regulator performs the transition as quickly as its current limit circuit allows, while avoiding excessive overshoot.

Figure 37 shows single-step transition timing. $\mathrm{t}_{\mathrm{V}(\mathrm{L}-\mathrm{H})}$ is the time it takes the regulator to settle to within $2 \%$ of the new
setpoint and is typically $7 \mu \mathrm{~s}$ for a full-range transition (from 00000 to 11111 for 6-bit DAC options). The PWROK bit, CONTROL2[5], goes LOW until the transition is complete and Vout settled. This typically occurs $\sim 2 \mu \mathrm{~s}$ after $\mathrm{t}_{\mathrm{V}(\mathrm{L}(\mathrm{H}) \text {. }}$

It is good practice to reduce the load current before making positive VSEL transitions. This reduces the time required to make positive load transitions and avoids current-limitinduced overshoot.


Figure 37. Single-Step Vout Transition
All positive $\mathrm{V}_{\text {Out }}$ transitions inhibit PFM until the transition is complete, which occurs at the end of tpok(L-H).

## Negative Transitions

When moving from VSEL=1 to VSEL=0, the regulator enters PFM mode, regardless of the condition of the SYNC pin or MODE bits, and remains in PFM until the transition is completed. Reverse current through the inductor is blocked, and the PFM minimum frequency control inhibited, until the new setpoint is reached, at which time the regulator resumes control using the mode established by MODE_CTRL. The transition time from $\mathrm{V}_{\text {High }}$ to $\mathrm{V}_{\text {Low }}$ is controlled by the load current and output capacitance as:


Figure 38. Negative Vout Transition

## Protection Features

## Current Limit / Auto-Restart

The regulator includes cycle-by-cycle current limiting, which prevents the instantaneous inductor current from exceeding ~1350mA.

The IC enters "fault" mode after sustained over-current. If current limit is asserted for more than 32 consecutive cycles (about $20 \mu \mathrm{~s}$ ), the IC returns to shutdown state and remains in that condition for $\sim 80 \mu \mathrm{~s}$. After that time, the regulator attempts to restart with a normal soft-start cycle. If the fault has not cleared, it shuts down $\sim 10 \mu \mathrm{~s}$ later.

If the fault is a short circuit, the initial current limit is $\sim 30 \%$ of the normal current limit, which produces a very small drain on the system power source.

## Thermal Protection

When the junction temperature of the IC exceeds $150^{\circ} \mathrm{C}$, the device turns off all output MOSFETs and remains in a low quiescent current state until the die cools to $130^{\circ} \mathrm{C}$ before commencing a normal soft-start cycle.

## Under-Voltage Lockout (UVLO)

The IC turns off all MOSFETs and remains in a very low quiescent current state until $\mathrm{V}_{\text {IN }}$ rises above the UVLO threshold.

## $I^{2} \mathrm{C}$ Interface

The FAN5355's serial interface is compatible with standard, fast, and HS mode ${ }^{2} \mathrm{C}$ bus specifications. The FAN5355's SCL line is an input and its SDA line is a bi-directional opendrain output; it can only pull down the bus when active. The SDA line only pulls LOW during data reads and when signaling ACK. All data is shifted in MSB (bit 7) first.

SDA and SCL are normally pulled up to a system I/O power supply (VCCIO), as shown in Figure 1. If the $I^{2} \mathrm{C}$ interface is not used, SDA and SCL should be tied to AVIN to minimize quiescent current consumption.

## Addressing

FAN5355 has four user-accessible registers:

|  | Address |  |  |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |  |
| VSELO | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| VSEL1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |  |
| CONTROL1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |  |
| CONTROL2 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |  |

Table 9. ${ }^{2}{ }^{2} \mathrm{C}$ Register Addresses

## Slave Address

In Table 10, A1 and A0 are according to the Ordering Information table on page 2.

| $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0 | 0 | $\mathbf{1}$ | 0 | A 1 | A 0 | $\mathrm{R} / \overline{\mathrm{W}}$ |

Table 10. $I^{2} \mathrm{C}$ Slave Address

## Bus Timing

As shown in Figure 39, data is normally transferred when SCL is LOW. Data is clocked in on the rising edge of SCL. Typically, data transitions shortly at or after the falling edge of SCL to allow ample time for the data to set up before the next SCL rising edge.


Figure 39. Data Transfer Timing
Each bus transaction begins and ends with SDA and SCL HIGH. A transaction begins with a "START" condition, which is defined as SDA transitioning from 1 to 0 with SCL HIGH, as shown in Figure 40.


Figure 40. Start Bit
A transaction ends with a "STOP" condition, which is defined as SDA transitioning from 0 to 1 with SCL HIGH, as shown in Figure 41.


Figure 41. Stop Bit
During a read from the FAN5355 (Figure 44), the master issues a "Repeated Start" after sending the register address, and before resending the slave address. The "Repeated Start" is a 1 to 0 transition on SDA while SCL is HIGH, as shown in Figure 42.

## High-Speed (HS) Mode

The protocols for High-Speed (HS), Low-Speed (LS), and Fast-Speed (FS) modes are identical, except the bus speed for HS mode is 3.4 MHz . HS mode is entered when the bus master sends the HS master code 00001XXX after a start condition. The master code is sent in FS mode (less than 400 kHz clock) and slaves do not ACK this transmission.
The master then generates a repeated start condition (Figure 42) that causes all slaves on the bus to switch to HS mode. The master then sends $I^{2} \mathrm{C}$ packets, as described above, using the HS mode clock rate and timing.

The bus remains in HS mode until a stop bit (Figure 41) is sent by the master. While in HS mode, packets are separated by repeated start conditions (Figure 42).


Figure 42. Repeated Start Timing

## Read and Write Transactions

The following figures outline the sequences for data read and write. Bus control is signified by the shading of the packet,


Slave Drives Bus
All addresses and data are MSB first.

| Symbol | Definition |
| :---: | :--- |
| S | START, see Figure 40. |
| A | ACK. The slave drives SDA to 0 to acknowledge the <br> preceding packet. |
| $\bar{A}$ | NACK. The slave sends a 1 to NACK the preceding <br> packet. |
| R | Repeated START, see Figure 42. |
| P | STOP, see Figure 41. |

Table 11. $I^{2} C$ Bit Definitions for Figure 43 - Figure 44


Figure 43. Write Transaction


Figure 44. Read Transaction

## Register Descriptions

## Default Values

Each option of the FAN5355 (see Ordering Information on page 2) has different default values for the some of the register bits. Table 12 defines both the default values and the bit's type (as defined in Table 13) for each available option.

VSELO

| Option | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ | $\mathbf{V}_{\text {out }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 1 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 1.05 |
| 02 | 1 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 1.05 |
| 03 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1.00 |
| 07 | 1 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 1.05 |
| 06 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 1.80 |

CONTROL1

| Option | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00,02 | 1 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |
| 03 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |
| 06,07 | 1 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |

VSEL1

| Option | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ | $\mathbf{V}_{\text {out }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 1.35 |
| 02 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 1.20 |
| 03 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 1.20 |
| 07 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 1.35 |
| 06 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 1.80 |

CONTROL2

| Option | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00,02 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 |
| 03 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 |
| 06,07 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 |

Table 12. Default Values and Bit Types for VSEL and CONTROL Registers

| $\#$ | Active bit. | Changing this bit changes the behavior of the converter, as described below. |
| :--- | :--- | :--- |
| $\#$ | Disabled. | Converter logic ignores changes made to this bit. Bit can be written to and read-back. |
| $\#$ | Read-only. | Writing to this bit through $I^{2} \mathrm{C}$ does not change the read-back value, nor does it change converter behavior. |

Table 13. Bit Type Definitions for Table 12.

## Bit Definitions

The following table defines the operation of each register bit. Superscript characters define the default state for each option. Superscripts ${ }^{0,2,3,6,7}$ signify the default values for options $00,02,03,06$, and 07 , respectively. ${ }^{\text {A }}$ signifies the default for all options.

| Bit | Name | Value | Description |
| :---: | :---: | :---: | :---: |
| VSELO |  |  | Register Address: 00 |
| 7 | EN_DCDC | 0 | Device in shutdown regardless of the state of the EN pin. This bit is mirrored in VSEL1. A write to bit 7 in either register establishes the EN DCDC value. |
|  |  | $1^{\text {A }}$ | Device enabled when EN pin is HIGH, disabled when EN is LOW. |
| 6 | $\begin{gathered} \text { Reserved }^{0,2,3,6} \\ \text { or DAC6 } \end{gathered}$ | $\begin{gathered} \text { Table } \\ 12 \end{gathered}$ | Has no effect in options $00,02,03,06$, and defaults to 1 . In option 07 , it is the MSB of the 7 -bit DAC value to set Vout. |
| 5:0 | DAC[5:0] |  | 6-bit DAC value to set $\mathrm{V}_{\text {out. }}$. The six LSBs of the 7-bit value for option 07. |
| VSEL1 |  |  | Register Address: 01 |
| 7 | EN_DCDC | 0 | Device in shutdown regardless of the state of the EN pin. This bit is mirrored in VSELO. A write to bit 7 in either register establishes the EN DCDC value. |
|  |  | $1{ }^{\text {A }}$ | Device enabled when EN pin is HIGH, disabled when EN is LOW. |
| 6 | $\begin{gathered} \text { Reserved }^{0,2,2,6} \\ \text { or DAC6 } \end{gathered}$ | $\begin{gathered} \text { Table } \\ 12 \end{gathered}$ | Has no effect in options $00,02,03,06$, and defaults to 1 . In option 07 , it is the MSB of the 7 -bit DAC value to set Vout. |
| 5:0 | DAC[5:0] |  | 6-bit DAC value to set $\mathrm{V}_{\text {out }}$. The six LSBs of the 7-bit value for option 07. |
| CONTROL1 |  |  | Register Address: 02 |
| 7:6 | Reserved | $\begin{gathered} 10^{0,2,2,6,6} \\ 00^{3} \end{gathered}$ | Vendor ID bits. Writing to these bits has no effect on regulator operation. These bits can be used to distinguish between vendors via $I^{2} \mathrm{C}$. |
| 5 | EN_SYNC | $0^{\text {A }}$ | Disables external signal on SYNC from affecting the regulator. |
|  |  | 1 | When a valid frequency is detected on SYNC, the regulator synchronizes to it and PFM is disabled, except when MODE $=00$, VSEL pin $=$ LOW, and HW nSW $=1$. |
| 4 | HW_nSW | 0 | $V_{\text {Out }}$ is controlled by VSEL1. Voltage transitions occur by writing to the VSEL1, then setting the GO bit. |
|  |  | $1^{\text {A }}$ | $\mathrm{V}_{\text {Out }}$ is programmed by the VSEL pin. $\mathrm{V}_{\text {OUt }}=$ VSEL1 when VSEL is HIGH, and VSELO when VSEL is LOW. |
| 3:2 | MODE_CTRL | $00^{\text {A }}$ | Operation follows MODE0, MODE1. |
|  |  | 01 | NPFM with automatically transitions to PWM, regardless of VSEL. |
|  |  | 10 | PFM disabled (forced PWM), regardless of VSEL. |
|  |  | 11 | EPFM ( $\mathrm{Fsw}_{\text {SWIM }}$ ) $=25 \mathrm{kHz}$ ) with automatically transitions to PWM, regardless of VSEL. |
| 1 | MODE1 | $0^{\text {A }}$ | PFM disabled (forced PWM) when regulator output is controlled by VSEL1. |
|  |  | 1 | NPFM with automatic transitions to PWM when regulator output is controlled by VSEL1. |
| 0 | MODE0 | $0^{\text {A }}$ | NPFM with automatic transitions to PWM when VSEL is LOW. Changing this bit has no effect on the operation of the regulator. |
|  |  | 1 |  |
| CONTROL2 |  |  | Register Address: 03 |
| 7 | GO | $0^{\text {A }}$ | This bit has no effect when HW_nSW = 1. At the end of a $\mathrm{V}_{\text {Out }}$ transition, this bit is reset to 0 . |
|  |  | 1 | Starts a $\mathrm{V}_{\text {Out }}$ transition if HW_nSW $=0$. |
| 6 | $\begin{aligned} & \text { OUTPUT- } \\ & \text { DISCHARG } \end{aligned}$ | $0^{\text {A }}$ | When the regulator is disabled, $\mathrm{V}_{\text {OUT }}$ is not discharged. |
|  |  | 1 | When the regulator is disabled, $\mathrm{V}_{\text {Out }}$ discharges through an internal pull-down. |
| 5 | PWROK (read only) | 0 | $\mathrm{V}_{\text {out }}$ is not in regulation or is in current limit. |
|  |  | 1 | $\mathrm{V}_{\text {Out }}$ is in regulation. |
| 4:3 | PLL_MULT | $00^{\text {A }}$ | $\mathrm{f}_{\text {SW }}=\mathrm{f}_{\text {SYNC }}$ when synchronization is enabled. |
|  |  | 01 | $\mathrm{f}_{\text {SW }}=2 \mathrm{X} \mathrm{f}_{\text {SYNC }}$ when synchronization is enabled. |
|  |  | 10 | $\mathrm{f}_{\mathrm{SW}}=3 \mathrm{X} \mathrm{f}_{\text {SYNC }}$ when synchronization is enabled. |
|  |  | 11 | $\mathrm{f}_{\mathrm{SW}}=4 \mathrm{X} \mathrm{f}_{\mathrm{SYNC}}$ when synchronization is enabled. |
| 2:0 | DEFSLEW | 000 | $\mathrm{V}_{\text {Out }}$ slews at $0.15 \mathrm{mV} / \mu \mathrm{s}$ during positive $\mathrm{V}_{\text {Out }}$ transitions. |
|  |  | 001 | $\mathrm{V}_{\text {Out }}$ slews at $0.30 \mathrm{mV} / \mu \mathrm{s}$ during positive $\mathrm{V}_{\text {Out }}$ transitions. |
|  |  | 010 | $\mathrm{V}_{\text {Out }}$ slews at $0.60 \mathrm{mV} / \mu \mathrm{s}$ during positive $\mathrm{V}_{\text {Out }}$ transitions. |
|  |  | 011 | $\mathrm{V}_{\text {Out }}$ slews at $1.20 \mathrm{mV} / \mu \mathrm{s}$ during positive $\mathrm{V}_{\text {Out }}$ transitions. |
|  |  | 100 | $\mathrm{V}_{\text {Out }}$ slews at $2.40 \mathrm{mV} / \mu \mathrm{s}$ during positive $\mathrm{V}_{\text {Out }}$ transitions. |
|  |  | 101 | $\mathrm{V}_{\text {Out }}$ slews at $4.80 \mathrm{mV} / \mu \mathrm{s}$ during positive $\mathrm{V}_{\text {OUt }}$ transitions. |
|  |  | 110 | $\mathrm{V}_{\text {Out }}$ slews at $9.60 \mathrm{mV} / \mu \mathrm{s}$ during positive $\mathrm{V}_{\text {Out }}$ transitions. |
|  |  | $111^{\text {A }}$ | Positive $\mathrm{V}_{\text {Out }}$ transitions use single-step mode (see Figure 37). |

## Physical Dimensions



Figure 45. 12-Bump WLCSP, 0.5 mm Pitch

## Product-Specific Dimensions

| Product | $\mathbf{D}$ | $\mathbf{E}$ | $\mathbf{X}$ | $\mathbf{Y}$ |
| :---: | :---: | :---: | :---: | :---: |
| FAN5355UC | $2.230+/-0.030$ | $1.460+/-0.030$ | 0.230 | 0.365 |

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## Physical Dimensions



Figure 46. 10-pin, 3x3mm Molded Leadless Package (MLP)
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| EfficentMax ${ }^{\text {TM }}$ | ISOPLANAR ${ }^{\text {TM }}$ | Saving our world, 1 mW at a time ${ }^{\text {Tm }}$ | TinyPWM ${ }^{\text {™ }}$ |
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| E7 $]^{\text {im }}$ | MICROCOUPLER ${ }^{\text {TM }}$ | SMART START ${ }^{\text {TM }}$ | $\mu$ SerDes $^{\text {TM }}$ |
| $5^{\text {B }}$ | MicroFET ${ }^{\text {TM }}$ | SPM $^{(3)}$ | M |
|  | MicroPak ${ }^{\text {™ }}$ | STEALTH ${ }^{\text {TM }}$ | SerDes |
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FAIRCHILD'S PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS WITHOUT THE EXPRESS WRITTEN APPROVAL OF FAIRCHILD SEMICONDUCTOR CORPORATION

As used herein:

1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body or (b) support or sustain life, and (c) whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury of the user.
2. A critical component in any component of a life support, device, or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness

## PRODUCT STATUS DEFINITIONS

Definition of Terms

| Datasheet Identification | Product Status | $\quad$ Definition |
| :--- | :--- | :--- |
| Advance Information | Formative / In Design | This datasheet contains the design specifications for product development. <br> Specifications may change in any manner without notice. |
| Preliminary | First Production | This datasheet contains preliminary data; supplementary data will be published <br> at a later date. Fairchild Semiconductor reserves the right to make changes at <br> any time without notice to improve design. |
| No Identification Needed | Full Production | This datasheet contains final specifications. Fairchild Semiconductor reserves <br> the right to make changes at any time without notice to improve the design. |
| Obsolete | Not In Production | This datasheet contains specifications on a product that is discontinued by <br> Fairchild Semiconductor. The datasheet is for reference information only. |

