## FXM2IC102

# Dual Supply 2-Bit I ${ }^{2}$ C Interface Voltage Translator with Configurable Voltage Supplies and Signal Levels and Auto Direction Sensing 

## Features

■ Bi-directional interface between any two levels from 1.65 V to 5.5 V

- Buffer isolates capacitance and allows 400pF on each port
- Open-drain inputs/outputs
- Accommodates Standard-mode and Fast-mode $1^{2} \mathrm{C}$-bus devices
■ Fully configurable: Inputs and outputs track $\mathrm{V}_{\mathrm{CC}}$ level
■ Non-preferential power-up; either $\mathrm{V}_{\mathrm{CC}}$ may be powered-up first
- Outputs remain in 3-state until active $\mathrm{V}_{\mathrm{CC}}$ level is reached
- Outputs switch to 3-state if either $\mathrm{V}_{\mathrm{CC}}$ is at GND

■ Power off high impedance

- Active high output enable referenced to $\mathrm{V}_{\mathrm{CCA}}$ voltage
- 5V tolerant output enable
- Packaged in 8-terminal leadless MicroPak ( $1.6 \mathrm{~mm} \times 1.6 \mathrm{~mm}$ )
■ Direction control not needed
- ESD protection exceeds:
- 8kV HBM ESD (per JESD22-A114 \& Mil Std 883e 3015.7)
- 15kV HBM I/O to GND ESD
(per JESD22-A114 \& Mil Std 883e 3015.7)


## General Description

The FXM2IC102 is a configurable dual-voltage-supply translator designed for bi-directional voltage translation over a wide range of input and output voltages levels.
The FXM2IC102 is intended for use as a voltage translator in applications using the $I^{2} \mathrm{C}$ bus interface. Input and output voltage levels are compatible with $I^{2} \mathrm{C}$ device specification voltage levels.

The device is designed so that the A port tracks the $\mathrm{V}_{\text {CCA }}$ level, and the B port tracks the $\mathrm{V}_{\mathrm{CCB}}$ level. This allows for bi-directional voltage translation over the voltage ranges: $1.8 \mathrm{~V}, 2.5 \mathrm{~V}, 3.3 \mathrm{~V}, 5.0 \mathrm{~V}$.

The device remains in 3-state until both $\mathrm{V}_{\mathrm{CC}} \mathrm{S}$ reach active levels allowing either $V_{C C}$ to be powered-up first. Internal power down control circuits place the device in 3-state if either $\mathrm{V}_{\mathrm{CC}}$ is removed.

The two ports of the device have auto-direction sense capability. Either port may sense an input signal and transfer it as an output signal to the other port.

## Ordering Information

| Order <br> Number | Package <br> Number | Product Code <br> Top Mark | Package Description | Supplied As |
| :---: | :---: | :---: | :---: | :---: |
| FXM2IC102L8X | MAC08A | XG | 8-Lead MicroPak, 1.6 mm Wide | 3k Units on Tape and <br> Reel |

All packages are lead free per JEDEC: J-STD-020B standard.

## Connection Diagram


(Top Thru View)

## Pin Description

| Number | Name | Description |
| :---: | :--- | :--- |
| 1 | $\mathrm{~V}_{\mathrm{CCA}}$ | A Side Power Supply |
| 2,3 | $\mathrm{~A}_{0}, \mathrm{~A}_{1}$ | A Side Inputs or 3-State <br> Outputs |
| 4 | GND |  |
| 5 | OE | Output Enable Input |
| 6,7 | $\mathrm{~B}_{1}, \mathrm{~B}_{0}$ | B Side Inputs or 3-State <br> Outputs |
| 8 | $\mathrm{~V}_{\mathrm{CCB}}$ | B Side Power Supply |

## Power-Up/Power-Down Sequencing

FXM translators offer an advantage in that either $\mathrm{V}_{\mathrm{CC}}$ may be powered up first. This benefit derives from the chip design. When either $\mathrm{V}_{\mathrm{CC}}$ is at 0 V , outputs are in a high-impedance state. The control input (OE) is designed to track the $\mathrm{V}_{\mathrm{CCA}}$ supply. A pull-down resistor tying OE to GND should be used to ensure that bus contention, excessive currents, or oscillations do not occur during power-up/power-down. The size of the pull-down resistor is based upon the current-sinking capability of the device driving the OE pin.

## Functional Diagram



Function Table

| Control | Outputs |  |
| :---: | :--- | :---: |
| OE |  |  |
| L | 3-State |  |
| $H$ | Normal Operation |  |

H = HIGH Logic Level
L = LOW Logic Level

The recommended power-up sequence is the following:

1. Apply power to the first $\mathrm{V}_{\mathrm{Cc}}$.
2. Apply power to the second $\mathrm{V}_{\mathrm{CC}}$.
3. Drive the OE input high to enable the device.

The recommended power-down sequence is the following:

1. Drive OE input low to disable the device.
2. Remove power from either $\mathrm{V}_{\mathrm{CC}}$.
3. Remove power from other $\mathrm{V}_{\mathrm{CC}}$.

## Absolute Maximum Ratings

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

| Symbol | Parameter | Rating |
| :---: | :---: | :---: |
| $\mathrm{V}_{\text {CCA }}, \mathrm{V}_{\text {CCB }}$ | Supply Voltage | -0.5 V to +7.0 V |
| $V_{1}$ | DC Input Voltage <br> A Port <br> B Port <br> Control Input (OE) | $\begin{aligned} & -0.5 \mathrm{~V} \text { to }+7.0 \mathrm{~V} \\ & -0.5 \mathrm{~V} \text { to }+7.0 \mathrm{~V} \\ & -0.5 \mathrm{~V} \text { to }+7.0 \mathrm{~V} \end{aligned}$ |
| $\mathrm{V}_{\mathrm{O}}$ | Output Voltage ${ }^{(1)}$ $A_{n}$ Outputs 3-State $\mathrm{B}_{\mathrm{n}}$ Outputs 3-State $A_{n}$ Outputs Active $B_{n}$ Outputs Active | $\begin{array}{r} -0.5 \mathrm{~V} \text { to }+7.0 \mathrm{~V} \\ -0.5 \mathrm{~V} \text { to }+7.0 \mathrm{~V} \\ -0.5 \mathrm{~V} \text { to } \mathrm{V}_{\mathrm{CCA}}+0.5 \mathrm{~V} \\ -0.5 \mathrm{~V} \text { to } \mathrm{V}_{\mathrm{CCB}}+0.5 \mathrm{~V} \end{array}$ |
| $\mathrm{I}_{\text {IK }}$ | DC Input Diode Current @ $\mathrm{V}_{1}<0 \mathrm{~V}$ | -50mA |
| $\mathrm{I}_{\mathrm{OK}}$ | DC Output Diode Current @ $\begin{aligned} & \mathrm{V}_{\mathrm{O}}<0 \mathrm{~V} \\ & \mathrm{~V}_{\mathrm{O}}>\mathrm{V}_{\mathrm{Cc}} \end{aligned}$ | $\begin{aligned} & -50 \mathrm{~mA} \\ & +50 \mathrm{~mA} \end{aligned}$ |
| $\mathrm{IOH} / \mathrm{l}_{\mathrm{OL}}$ | DC Output Source/Sink Current | $-50 \mathrm{~mA} /+50 \mathrm{~mA}$ |
| $\mathrm{I}_{\mathrm{CC}}$ | DC $\mathrm{V}_{\text {CC }}$ or Ground Current per Supply Pin | $\pm 100 \mathrm{~mA}$ |
| $\mathrm{T}_{\text {STG }}$ | Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |

## Note:

1. $\mathrm{I}_{\mathrm{O}}$ Absolute Maximum Rating must be observed.

## Recommended Operating Conditions ${ }^{(2)}$

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to absolute maximum ratings.

| Symbol | Parameter | Rating |
| :---: | :--- | ---: |
| $\mathrm{V}_{\mathrm{CCA}}$ or $\mathrm{V}_{\mathrm{CCB}}$ | Power Supply Operating | 1.65 V to 5.5 V |
| $\mathrm{~V}_{\mathrm{I}}$ | Input Voltage |  |
|  | A Port | 0.0 V to 5.5 V |
|  | B Port | 0.0 V to 5.5 V |
|  | Control Input (OE) | 0.0 V to $\mathrm{V}_{\mathrm{CCA}}$ |
| $\Delta \mathrm{t} / \Delta \mathrm{V}$ | Maximum Input Edge Rate $\mathrm{V}_{\mathrm{CCA}}=1.65 \mathrm{~V}$ to 5.5 V | $200 \mathrm{~ns} / \mathrm{V}$ |
| $\mathrm{T}_{\mathrm{A}}$ | Free Air Operating Temperature | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |

## Note:

2. All unused inputs and I/O pins must be held at $\mathrm{V}_{\mathrm{CCI}}$ or GND .

## FXM2IC102 Application Circuit



## Application Notes

The FXM2IC102 has open-drain outputs and requires pull-up resistors on the four data I/O pins as shown in the above figure. If a pair of data I/O pins $\left(\mathrm{A}_{\mathrm{n}} / \mathrm{B}_{\mathrm{n}}\right)$ are not used, they both should be tied to Gnd (or both to $\mathrm{V}_{\mathrm{C}}$ ). In this case, pull-down or pull-up resistors are not required.
The recommended values for the pull-up resistors $\left(R_{P U}\right)$ are $1 \mathrm{k} \Omega$ minimum to $10 \mathrm{k} \Omega$ maximum. The recommended value for the bypass capacitors ( $C_{B P}$ ) is $1.1 \mu \mathrm{~F}$. The recommended value for the pull-down resistor ( $\mathrm{R}_{\mathrm{PD}}$ ) on OE is $1 \mathrm{k} \Omega$ or higher and may depend upon the current-sinking capability of the device driving the OE pin.

DC Electrical Characteristics ( $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ )

| Symbol | Parameter | $\mathrm{V}_{\mathrm{CCA}}(\mathrm{V})$ | $\mathrm{V}_{\mathrm{CCB}}(\mathrm{V})$ |  | Conditions | Min. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {IHA }}$ | High Level Input Voltage | 1.65-5.5 | 1.65-5.5 | Data Inputs $\mathrm{A}_{n}$ |  | $0.7 \times \mathrm{V}_{\text {CCA }}$ |  | V |
|  |  | 1.65-5.5 | 1.65-5.5 | Control Input OE |  | $0.9 \times \mathrm{V}_{\text {CCA }}$ |  |  |
| $\mathrm{V}_{\text {IHB }}$ |  | 1.65-5.5 | 1.65-5.5 | Data Inputs $B_{n}$ |  | $0.7 \times \mathrm{V}_{\text {CCB }}$ |  | V |
| $\mathrm{V}_{\text {ILA }}$ | Low Level Input Voltage | 1.65-5.5 | 1.65-5.5 | Data Inputs $A_{n}$ |  |  | $0.3 \times \mathrm{V}_{\text {CCA }}$ | V |
|  |  | 1.65-5.5 | 1.65-5.5 | Control Input OE |  |  | $0.1 \times \mathrm{V}_{\text {CCA }}$ |  |
| $\mathrm{V}_{\text {ILB }}$ |  | 1.65-5.5 | 1.65-5.5 | Data Inputs $\mathrm{B}_{\mathrm{n}}$ |  |  | $0.3 \times \mathrm{V}_{\text {ССВ }}$ | V |
| $\mathrm{V}_{\text {OLA }}{ }^{(3)}$ | Low Level Output Voltage | 1.65-2.3 | 1.65-5.5 | APort | $\mathrm{I}_{\mathrm{OL}}=3 \mathrm{~mA}$ |  | $0.1 \times \mathrm{V}_{\text {CCA }}$ | V |
|  |  | 3.0-5.5 | 1.65-5.5 |  | $\mathrm{I}_{\text {OL }}=6 \mathrm{~mA}$ |  | 0.2 |  |
| $\mathrm{V}_{\text {OLB }}{ }^{(3)}$ |  | 1.65-5.5 | 1.65-2.3 | B Port | $\mathrm{I}_{\text {OL }}=3 \mathrm{~mA}$ |  | $0.1 \times \mathrm{V}_{\text {ССВ }}$ | V |
|  |  | 1.65-5.5 | 3.0-5.5 |  | $\mathrm{I}_{\mathrm{OL}}=6 \mathrm{~mA}$ |  | 0.2 |  |
| I | Input Leakage Current | 1.65-5.5 | 1.65-5.5 | Control input OE, $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CCA}}$ or GND |  |  | $\pm 1.0$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {OFF }}$ | Power Off Leakage Current | 0 | 5.5 | $\mathrm{A}_{\mathrm{n}}$ | $\begin{aligned} & V_{1} \text { or } V_{O}=0 \mathrm{~V} \text { to } \\ & 5.5 \mathrm{~V} \end{aligned}$ |  | $\pm 2.0$ | $\mu \mathrm{A}$ |
|  |  | 5.5 | 0 | $\mathrm{B}_{\mathrm{n}}$ | $\begin{aligned} & V_{1} \text { or } V_{O}=0 \mathrm{~V} \text { to } \\ & 5.5 \mathrm{~V} \end{aligned}$ |  | $\pm 2.0$ |  |
| $\mathrm{I}_{\mathrm{Oz}}{ }^{(4)}$ | 3-State Output Leakage | 5.5 | 5.5 | $A_{n}, B_{n}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{O}}=0 \mathrm{~V} \text { to } 5.5 \mathrm{~V}, \\ & \mathrm{OE}=\mathrm{V}_{\mathrm{IL}} \end{aligned}$ |  | $\pm 2.0$ | $\mu \mathrm{A}$ |
|  |  | 5.5 | 0 | $\mathrm{A}_{n}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{O}}=0 \mathrm{~V} \text { to } 5.5 \mathrm{~V}, \\ & \mathrm{OE}=\text { Don't Care } \end{aligned}$ |  | $\pm 2.0$ |  |
|  |  | 0 | 5.5 | $\mathrm{B}_{\mathrm{n}}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{O}}=0 \mathrm{~V} \text { to } 5.5 \mathrm{~V}, \\ & \mathrm{OE}=\text { Don't Care } \end{aligned}$ |  | $\pm 2.0$ |  |
| $\mathrm{I}_{\text {CCA/B }}{ }^{(5)(6)}$ | Quiescent Supply Current | 1.65-5.5 | 1.65-5.5 | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CCI}}$ or GND, $\mathrm{I}_{\mathrm{O}}=0$ |  |  | 5.0 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\mathrm{Ccz}}{ }^{(5)}$ | Quiescent Supply Current | 1.65-5.5 | 1.65-5.5 | $\begin{aligned} & \mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CCI}} \text { or } \mathrm{GND}, \mathrm{I}_{\mathrm{O}}=0, \mathrm{OE} \\ & =\mathrm{V}_{\mathrm{IL}} \end{aligned}$ |  |  | 5.0 | $\mu \mathrm{A}$ |
| $I_{\text {CCA }}$ | Quiescent Supply Current | 0 | 1.65-5.5 | $\begin{aligned} & \mathrm{V}_{1}=5.5 \mathrm{~V} \text { or } \mathrm{GND}, \mathrm{I}_{\mathrm{O}}=0, \\ & \mathrm{OE}=\text { Don't Care, } \mathrm{B}_{\mathrm{n}} \text { to } \mathrm{A}_{n} \end{aligned}$ |  |  | -2.0 | $\mu \mathrm{A}$ |
|  |  | 1.65-5.5 | 0 |  |  |  | 2.0 |  |
| $I_{\text {ccB }}$ | Quiescent Supply Current | 1.65-5.5 | 0 | $\begin{aligned} & \mathrm{V}_{1}=5.5 \mathrm{~V} \text { or } \mathrm{GND}, \mathrm{I}_{\mathrm{O}}=0, \\ & \mathrm{OE}=\text { Don't Care, } \mathrm{A}_{\mathrm{n}} \text { to } \mathrm{B}_{\mathrm{n}} \end{aligned}$ |  |  | -2.0 | $\mu \mathrm{A}$ |
|  |  | 0 | 1.65-5.5 |  |  |  | 2.0 |  |

## Notes:

3. This is the output voltage for static conditions. Dynamic drive specifications are given in "Dynamic Output Electrical Characteristics."
4. "Don't Care" indicates any valid logic level.
5. $\mathrm{V}_{\mathrm{CCI}}$ is the $\mathrm{V}_{\mathrm{CC}}$ associated with the input side.
6. Reflects current per supply, $\mathrm{V}_{\mathrm{CCA}}$ or $\mathrm{V}_{\mathrm{CCB}}$.

## Dynamic Output Electrical Characteristics

Output Rise/Fall Time and Dynamic Output Current ${ }^{(7)}$
Output Load: $\mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega$

| Symbol ${ }^{(8)}$ | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCO}}=$ |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 4.5 V to 5.5 V |  | 3.0 V to 3.6 V |  | 2.3V to 2.7V |  | 1.65 V to 1.95 V |  |  |
|  |  | Typ. | Max. | Typ. | Max. | Typ. | Max. | Typ. | Max. |  |
| $\mathrm{t}_{\text {rise }}{ }^{(9)}$ | Output Rise Time, A Port, B Port |  | 4.0 |  | 5.0 |  | 6.0 |  | 8.0 | ns |
| $t_{\text {fall }}{ }^{(10)}$ | Output Fall Time, A Port, B Port |  | 4.0 |  | 5.0 |  | 6.0 |  | 8.0 | ns |
| $\mathrm{IOHD}^{(9)}$ | Dynamic Output Current HIGH | -45 |  | -24 |  | -15 |  | -8.0 |  | mA |
| $\mathrm{I}_{\text {OLD }}{ }^{(10)}$ | Dynamic Output Current LOW | +45 |  | +24 |  | +15 |  | +8.0 |  | mA |

## Maximum Data Rate ${ }^{(11)}$

Output Load: $\mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega$

| $\mathrm{V}_{\mathrm{CCA}}=$ | $\mathrm{T}_{\mathbf{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 4.5 V to 5.5 V | 3.0 V to 3.6 V | $\mathbf{2 . 3 V}$ to 2.7 V | 1.65 V to 1.95 V |  |
|  | Min. | Min. | Min. | Min. | Units |
| 4.5V to 5.5 V | 40 | 35 | 30 | 20 | MHz |
| 3.0V to 3.6 V | 35 | 35 | 30 | 20 | MHz |
| 2.3V to 2.7 V | 30 | 30 | 25 | 20 | MHz |
| 1.65 V to 1.95 V | 20 | 20 | 20 | 20 | MHz |

## Notes:

7. Dynamic output characteristics are guaranteed but not tested.
8. $\mathrm{V}_{\mathrm{CCO}}$ is the $\mathrm{V}_{\mathrm{CC}}$ associated with the output side.
9. See Figure 5.
10. See Figure 6.
11. Maximum data rate is guaranteed but not tested.

AC Characteristics (Output Load: $C_{L}=50 p F, R_{L}=1 \mathrm{k} \Omega$ )
$\mathrm{V}_{\mathrm{CCA}}=4.5 \mathrm{~V}$ to 5.5 V

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 4.5V to 5.5 V |  | 3.0 V to 3.6 V |  | 2.3V to 2.7V |  | 1.65 V to 1.95 V |  |  |
|  |  | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. |  |
| $t_{\text {PLH }}$ | A to B | 1.0 | 4.5 | 1.5 | 5.5 | 2.0 | 7.0 | 3.0 | 11.5 | ns |
|  | $B$ to A | 1.0 | 4.5 | 1.5 | 5.5 | 1.5 | 6.5 | 2.5 | 9.5 |  |
| $\mathrm{t}_{\text {PHL }}$ | A to B | 2.0 | 6.0 | 2.5 | 6.5 | 3.0 | 8.0 | 4.0 | 12.5 | ns |
|  | $B$ to $A$ | 2.0 | 6.0 | 2.5 | 7.0 | 3.0 | 8.0 | 3.5 | 12.0 |  |
| $t_{\text {PZL }}$ | OE to A |  | 9.5 |  | 10.0 |  | 11.5 |  | 18.0 | ns |
|  | OE to B |  | 9.0 |  | 11.0 |  | 13.5 |  | 22.0 |  |
| $t_{\text {PLZ }}$ | OE to A |  | 26.5 |  | 26.5 |  | 26.5 |  | 26.5 | ns |
|  | OE to B |  | 26.0 |  | 26.5 |  | 20.5 |  | 15.5 |  |
| $\mathrm{t}_{\text {skew }}{ }^{(12)}$ | A Port, B Port |  | 0.5 |  | 0.5 |  | 0.5 |  | 0.5 | ns |

$\mathrm{V}_{\mathrm{CCA}}=3.0 \mathrm{~V}$ to 3.6 V

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 4.5 V to 5.5 V |  | 3.0 V to 3.6 V |  | 2.3V to 2.7 V |  | 1.65 V to 1.95 V |  |  |
|  |  | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. |  |
| $\mathrm{t}_{\text {PLH }}$ | A to B | 1.5 | 5.5 | 1.5 | 6.5 | 2.0 | 8.0 | 3.0 | 12.0 | ns |
|  | B to A | 1.5 | 5.5 | 1.5 | 6.5 | 2.0 | 7.5 | 2.5 | 10.5 |  |
| $t_{\text {PHL }}$ | $A$ to $B$ | 2.5 | 7.0 | 2.5 | 7.5 | 3.0 | 9.0 | 4.0 | 13.0 | ns |
|  | B to A | 2.5 | 6.5 | 2.5 | 7.5 | 3.0 | 9.5 | 4.0 | 13.0 |  |
| $t_{\text {PZL }}$ | OE to A |  | 12.5 |  | 13.0 |  | 15.5 |  | 21.0 | ns |
|  | OE to B |  | 10.0 |  | 12.5 |  | 14.5 |  | 22.5 |  |
| $\mathrm{t}_{\text {PLZ }}$ | OE to A |  | 27.5 |  | 28.0 |  | 28.0 |  | 28.0 | ns |
|  | OE to B |  | 27.5 |  | 28.0 |  | 28.5 |  | 22.5 |  |
| $\mathrm{t}_{\text {skew }}{ }^{(12)}$ | A Port, B Port |  | 0.5 |  | 0.5 |  | 0.5 |  | 0.5 | ns |

$\mathrm{V}_{\mathrm{CCA}}=2.3 \mathrm{~V}$ to 2.7 V

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 4.5V to 5.5V |  | 3.0 V to 3.6 V |  | 2.3V to 2.7 V |  | 1.65 V to 1.95 V |  |  |
|  |  | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. |  |
| $t_{\text {PLH }}$ | A to B | 1.5 | 6.5 | 2.0 | 7.5 | 2.5 | 8.5 | 3.5 | 12.5 | ns |
|  | B to A | 2.0 | 7.5 | 2.0 | 8.0 | 2.5 | 8.5 | 3.0 | 11.5 |  |
| $\mathrm{t}_{\text {PHL }}$ | A to B | 3.0 | 8.5 | 3.0 | 9.5 | 3.0 | 10.0 | 4.0 | 13.5 | ns |
|  | B to A | 3.0 | 8.0 | 3.0 | 9.0 | 3.0 | 10.0 | 4.5 | 14.0 |  |
| $\mathrm{t}_{\text {PZL }}$ | OE to A |  | 16.0 |  | 16.5 |  | 18.0 |  | 23.5 | ns |
|  | OE to B |  | 11.0 |  | 14.0 |  | 15.5 |  | 23.5 |  |
| $t_{\text {PLZ }}$ | OE to A |  | 29.0 |  | 29.0 |  | 29.5 |  | 29.5 | ns |
|  | OE to B |  | 29.0 |  | 29.0 |  | 29.5 |  | 29.5 |  |
| $\mathrm{t}_{\text {skew }}{ }^{(12)}$ | A Port, B Port |  | 0.5 |  | 0.5 |  | 0.5 |  | 0.5 | ns |

AC Characteristics (Continued) (Output Load: $C_{L}=50 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega$ )
$\mathrm{V}_{\mathrm{CCA}}=1.65 \mathrm{~V}$ to 1.95 V

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 4.5V to 5.5V |  | 3.0 V to 3.6 V |  | 2.3V to 2.7 V |  | 1.65 V to 1.95 V |  |  |
|  |  | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. |  |
| $t_{\text {PLH }}$ | A to B | 2.5 | 9.5 | 2.5 | 10.5 | 3.0 | 11.5 | 4.0 | 15.0 | ns |
|  | B to A | 3.0 | 11.5 | 3.0 | 12.0 | 3.5 | 12.5 | 4.0 | 15.0 |  |
| $\mathrm{t}_{\text {PHL }}$ | A to B | 3.5 | 11.5 | 4.0 | 12.5 | 4.5 | 14.0 | 5.0 | 15.5 | ns |
|  | B to A | 4.0 | 12.5 | 4.0 | 13.0 | 4.0 | 13.5 | 5.0 | 15.5 |  |
| $t_{\text {PZL }}$ | OE to A |  | 27.0 |  | 27.0 |  | 27.0 |  | 30.0 | ns |
|  | OE to B |  | 18.0 |  | 19.5 |  | 22.5 |  | 29.0 |  |
| $t_{\text {PLZ }}$ | OE to A |  | 34.0 |  | 34.0 |  | 34.5 |  | 35.0 | ns |
|  | OE to B |  | 31.5 |  | 32.5 |  | 33.5 |  | 36.5 |  |
| $\mathrm{t}_{\text {skew }}{ }^{(12)}$ | A Port, B Port |  | 0.5 |  | 0.5 |  | 0.5 |  | 0.5 | ns |

## Note:

12. Skew is the variation of propagation delay between output signals and applies only to output signals on the same port (An or Bn) and switching with the same polarity (LOW-to-HIGH or HIGH-to-LOW). See Figure 8. Skew is guaranteed but not tested

Capacitance

| Symbol | Parameter | Conditions | $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ | Units |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Typical |  |
| Cin | Input Capacitance Control pin (OE) | $\mathrm{V}_{\mathrm{CCA}}=\mathrm{V}_{\mathrm{CCB}}=\mathrm{GND}$ | 4 | pF |
| $\mathrm{Ci} / \mathrm{o}$ | Input/Output Capacitance, $\mathrm{A}_{\mathrm{n}}$, $\mathrm{B}_{\mathrm{n}}$ | $\mathrm{V}_{\text {CCA }}=\mathrm{V}_{\text {CCB }}=5.0 \mathrm{~V}$, OE $=\mathrm{V}_{\text {CCA }}$ | 6 | pF |
| Cpd | Power Dissipation Capacitance | $\begin{aligned} & V_{\mathrm{CCA}}=\mathrm{V}_{\mathrm{CCB}}=5.0 \mathrm{~V}, \\ & \mathrm{~V}_{\mathrm{I}}=0 \mathrm{~V} \text { or } \mathrm{V}_{\mathrm{CC}}, \mathrm{f}=10 \mathrm{MHz} \end{aligned}$ | 40 | pF |



| Test | Input Signal | Output Enable <br> Control | S1 Position |
| :---: | :---: | :---: | :---: |
| $\mathrm{t}_{\mathrm{PLH}}, \mathrm{t}_{\mathrm{PHL}}$ | Data Pulses | $\mathrm{V}_{\mathrm{CCA}}$ | Open |
| $\mathrm{t}_{\text {PZL }}\left(\mathrm{OE}\right.$ to $\left.\mathrm{A}_{\mathrm{n}}, \mathrm{B}_{\mathrm{n}}\right)$ | 0 V | LOW to HIGH Switch | $2 \times \mathrm{V}_{\mathrm{CCO}}$ |
| $\mathrm{t}_{\text {PLZ }}\left(\mathrm{OE}\right.$ to $\left.\mathrm{A}_{\mathrm{n}}, \mathrm{B}_{\mathrm{n}}\right)$ | 0 V | HIGH to LOW Switch | $2 \times \mathrm{V}_{\mathrm{CCO}}$ |

AC Load Table

| $\mathbf{V}_{\mathbf{C C O}}$ | $\mathbf{C l}$ | $\mathbf{R I}$ |
| :---: | :---: | :---: |
| $1.8 \mathrm{~V} \pm 0.15 \mathrm{~V}$ | 50 pF | $1 \mathrm{k} \Omega$ |
| $2.5 \mathrm{~V} \pm 0.2 \mathrm{~V}$ | 50 pF | $1 \mathrm{k} \Omega$ |
| $3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}$ | 50 pF | $1 \mathrm{k} \Omega$ |
| $5.0 \mathrm{~V} \pm 0.5 \mathrm{~V}$ | 50 pF | $1 \mathrm{k} \Omega$ |

Figure 1. AC Test Circuit and AC Load Table


Input $t_{R}=t_{F}=2.0 \mathrm{~ns}, 10 \%$ to $90 \%$ @ $\mathrm{V}_{\mathrm{I}}=1.65 \mathrm{~V}$ to 1.95 V
Input $t_{R}=t_{F}=2.0 n s, 10 \%$ to $90 \%$ @ $V_{I}=2.3$ to 2.7 V
Input $t_{R}=t_{F}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%$, @ $V_{I}=3.0 \mathrm{~V}$ to 3.6 V only Input $t_{R}=t_{F}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%$, @ $V_{I}=4.5 \mathrm{~V}$ to 5.5 only

Figure 2. Waveform for Inverting and Non-inverting Functions

OUTPUT
CONTROL

DATA
OUT


Input $t_{R}=t_{F}=2.0 n s, 10 \%$ to $90 \% @ V_{1}=1.65 \mathrm{~V}$ to 1.95 V
Input $t_{R}=t_{F}=2.0$ ns, $10 \%$ to $90 \% @ V_{I}=2.3$ to 2.7 V
Input $\mathrm{t}_{\mathrm{R}}=\mathrm{t}_{\mathrm{F}}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%$, @ $\mathrm{V}_{\mathrm{I}}=3.0 \mathrm{~V}$ to 3.6 V only
Input $t_{R}=t_{F}=2.5 n s, 10 \%$ to $90 \%, @ V_{1}=4.5 \mathrm{~V}$ to 5.5 only
Figure 4. 3-STATE Output High Enable Time


Input $t_{R}=t_{F}=2.0 n s, 10 \%$ to $90 \% @ V_{1}=1.65 \mathrm{~V}$ to 1.95 V Input $t_{R}=t_{F}=2.0$ ns, $10 \%$ to $90 \% @ V_{1}=2.3$ to 2.7 V Input $t_{R}=t_{\mathrm{F}}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%$, @ $\mathrm{V}_{\mathrm{I}}=3.0 \mathrm{~V}$ to 3.6 V only Input $t_{R}=t_{F}=2.5$ ns, $10 \%$ to $90 \%$, @ $V_{I}=4.5 \mathrm{~V}$ to 5.5 only

Figure 3. 3-STATE Output Low Enable Time

| Symbol | Vcc |
| :---: | :---: |
| $\mathrm{Vmi}^{(13)}$ | $\mathrm{V}_{\mathrm{CCI}} / 2$ |
| Vmo | $\mathrm{V}_{\mathrm{CcO}} / 2$ |
| $\mathrm{~V}_{\mathrm{X}}$ | $0.5 \times \mathrm{V}_{\mathrm{Cco}}$ |
| $\mathrm{V}_{\mathrm{Y}}$ | $0.1 \times \mathrm{V}_{\mathrm{CCO}}$ |

## Note:

13. $\mathrm{V}_{\mathrm{CCI}}=\mathrm{V}_{\mathrm{CCA}}$ for control pin OE or $\mathrm{Vmi}=\left(\mathrm{V}_{\mathrm{CCA}} / 2\right)$.


Figure 5. Active Output Rise Time and Dynamic Output Current High


Figure 7. Maximum Data Rate (or F-toggle) in MHz

loLD $\approx\left(C_{L}+C_{/ / O}\right) \times \frac{\Delta V_{\text {OUT }}}{\Delta t}=\left(C_{L}+C_{/ / O}\right) \times \frac{(80 \%-20 \%) \times V_{C C O}}{t_{\text {FALL }}}$

Figure 6. Active Output Fall Time and Dynamic Output Current Low

$t_{\text {skew }}=\left(\mathrm{t}_{\text {pHLmax }}-\mathrm{t}_{\mathrm{p} H L \min }\right)$ or $\left(\mathrm{t}_{\mathrm{pLH}} \max -\mathrm{t}_{\mathrm{pLH}}\right.$ min $)$
Figure 8. Output Skew Time

Tape and Reel Specification
Tape Format for MicroPak

| Package Designator | Tape Section | Number of Cavities | Cavity Status | Cover Tape Status |
| :---: | :---: | :---: | :---: | :---: |
| L8X | Leader (Start End) | 125 (typ.) | Empty | Sealed |
|  | Carrier | 3000 | Filled | Sealed |
|  | Trailer (Hub End) | 75 (typ.) | Empty | Sealed |

Tape Dimensions inches (millimeters)


Reel Dimensions inches (millimeters)


| Tape Size | A | $\mathbf{B}$ | $\mathbf{C}$ | $\mathbf{D}$ | $\mathbf{N}$ | W1 | W2 | W3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8 mm | 7.0 | 0.059 | 0.512 | 0.795 | 2.165 | $0.331+0.059 /-0.000$ | 0.567 | W1 +0.078/-0.039 |
|  | $(177.8)$ | $(1.50)$ | $(13.00)$ | $(20.20)$ | $(55.00)$ | $(8.40+1.50 /-0.00)$ | $(14.40)$ | $(\mathrm{W} 1+2.00 /-1.00)$ |

## Physical Dimensions



Figure 9. 8-Lead MicroPak, 1.6 mm Wide
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| EfficentMax ${ }^{\text {™ }}$ | ISOPLANAR ${ }^{\text {™ }}$ | Saving our world, 1 mW at a time ${ }^{\text {TM }}$ | TinyPWM ${ }^{\text {™ }}$ |
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| $\Gamma^{\circledR}$ | MicroFET ${ }^{\text {TM }}$ | $\text { SPM }^{\circledast}$ | W |
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