Suntac ELECTRONIC CORP

STC494 Pulse Width Modulation

Description

The STC494 is a monolithic integrated circuit which includes all the necessary building blocks for the design of pulse width modulate(PWM) switching power supplies, including push-pull, bridge and series configuration. The device can operate at switching frequencies between 1KHz and 300KHz and output voltage up to 40V. The STC494 is specified over an operating temperature range of -40°C to 85°C .

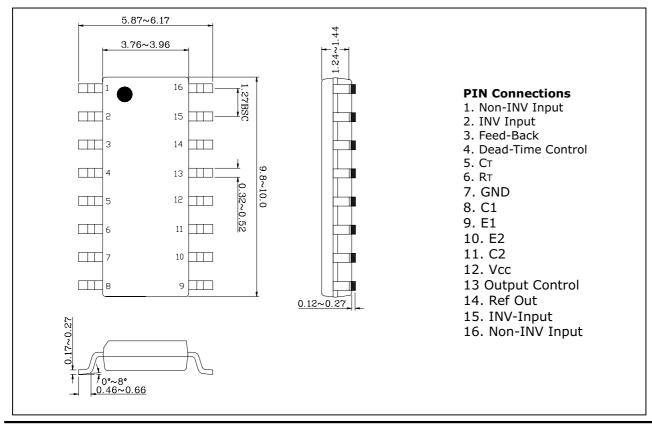
Features

- Uncommitted output transistors capable of 200mA source or sink
- Internal protection from double pulsing of out-puts with narrow pulse widths or with supply voltages bellows specified limits
- Easily synchronized to other circuits
- Dead time control comparator
- Output control selects single-ended or push-pull operation

Ordering Information

| Type NO. | Marking | Package Code | |
|----------|---------|--------------|--|
| STC494 | STC494 | SOP-16 | |

Outline Dimensions



unit : mm

| Absolute Maximum Ratings | | | Ta=25° C |
|---|-----------------------------------|----------------------|-----------------|
| Characteristic | Symbol | Ratings | Unit |
| supply voltage | V _{cc} | 42 | V |
| Voltage From Any Pin to Ground (except pin 8 and pin 11) | V _{IN} | V _{CC} +0.3 | V |
| Output Collector Voltage | V _{C1} , V _{C2} | 42 | V |
| Peak Collector Current | I _{C1} , I _{C2} | 250 | mA |
| Power Dissipation | P _D | 1500 | mW |
| Operating Temperature | T _{opr} | -40 ~ 85 | °C |
| Storage Temperature | T _{stg} | -65 ~ 150 | °C |

Recommended Operating Condition

| Characteristic | Symbol | Min. | Max. | Unit |
|---|-----------------------------------|------|----------------------|------|
| supply voltage | V _{cc} | 7 | 40 | V |
| Voltage on Any Pin Except Pin 8 and 11(Referenced to Ground) | V _{IN} | -0.3 | V _{cc} +0.3 | V |
| Output Voltage | V _{C1} , V _{C2} | -0.3 | 40 | V |
| Output Collector Current | I _{C1} , I _{C2} | - | 200 | mA |
| Timing Capacitor | Ct | 470 | - | PF |
| Timing Capacitor | Ct | - | 10 | μF |
| Timing Resistor | R _t | 1.8 | 500 | kΩ |
| Oscillator Frequency | f _{osc} | 1 | 300 | KHz |

Electrical Characteristics Reference Section

| | | | - | | | |
|-------------------------|-------------------|------------------------|------|------|------|------|
| Characteristic | Symbol | Test Condition | Min. | Тур. | Max. | Unit |
| Reference Voltage | Vref | Iref = 1.0mA | 4.75 | 5.00 | 5.25 | V |
| Line Regulation | V _{LINE} | 7V < Vcc < 40V | - | 2 | 25 | mV |
| Load Regulation | V _{LOAD} | $1mA < I_{REF} < 10mA$ | - | 1 | 15 | mV |
| Temperature Coefficient | - | 0°C < Ta <70°C | - | 0.01 | 0.03 | %/°C |

Oscillator Section

| Characteristic | Symbol | Test Condition | Min. | Тур. | Max. | Unit |
|--|------------------|--|------|------|------|------|
| Oscillator Frequency | f _{osc} | $C_t=0.01 \ \mu F$, $R_t=12 \ k\Omega$ | - | 10 | - | kHz |
| Oscillator Frequency Change Over Operating Temperature Range | Δf_{SOC} | $C_t=0.01 \ \mu\text{F}$, $R_t=12 \ \text{k}\Omega$ | - | - | 2 | % |

Dead Time Control Section

| Character | istic | Symbol | Test Condition | Min. | Тур. | Max. | Unit |
|-----------------------|-----------|---------------------|--|------|------|------|------|
| Input Bias Current (I | Pin4) | $I_{IB(DT)}$ | $Vcc = 15V, 0V < V_4 < 5.25V$ | - | -2 | -10 | μA |
| Max. Duty cycle, Eac | h Output | DC _(Max) | Vcc = 15V, Pin4 = 0V, Output Control Pin = Vref | 43 | - | 45 | % |
| Voltage | Zero Duty | V | _ | - | 3 | 3.3 | v |
| | Max Duty | V _{TH} | | 0 | - | - | |

Error Amplifier Section

| Characteristic | Symbol | Test Condition | Min. | Тур. | Max. | Unit |
|---|------------------|-----------------------------|------|------|-----------------|------|
| Input Offset Voltage | V _{IOS} | V ₃ = 2.5V | - | 2 | 10 | mV |
| Input Offset Current | I _{IOS} | V ₃ = 2.5V | - | 25 | 250 | nA |
| Input Bias Current | I _{IB} | V ₃ = 2.5V | - | 0.2 | 1 | μA |
| Input Common Mode voltage Range | V_{ICR} | $7V \le V_{CC} \le 40V$ | -0.3 | - | V _{cc} | V |
| Large Signal Open Loop Voltage Range | G _{vo} | $0.5V \leq V_3 \ \leq 3.5V$ | 60 | 74 | - | dB |
| Unity Gain Band width | f _C | - | - | 650 | - | kHz |

PWM Comparator Section (Pin3)

| Characteristic | Symbol | Test Condition | Min. | Тур. | Max. | Unit |
|---------------------------|-----------------|------------------------------|------|------|------|------|
| Inhibit Threshold Voltage | V_{THI} | Zero duty cycle | - | 4 | 4.5 | V |
| Output Source Current | Io ⁺ | 0.5V < V ₃ < 3.5V | 2 | - | - | mA |
| Output Sink Current | Io⁻ | 0.5V< V ₃ < 3.5V | -0.2 | -0.6 | - | mA |

Output Section

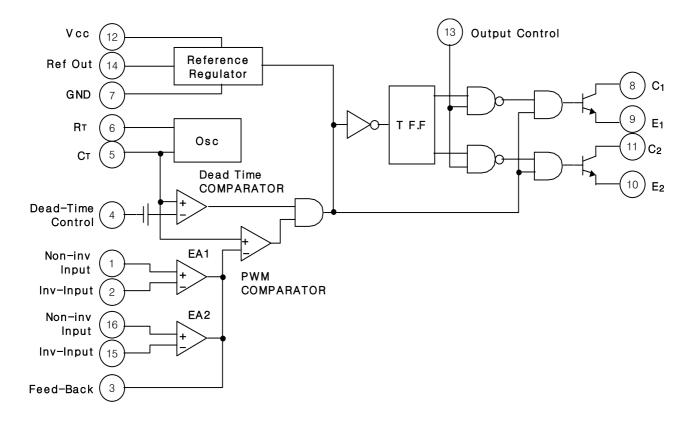
| Chara | acteristic | Symbol | Test Condition | Min. | Тур. | Max. | Unit |
|--|------------------|----------------------|-----------------------------------|------|------|------|------|
| Output Satur- | Common-Emitter | V | V_{E} = 15V, I_{C} = 200mA | - | 1.1 | 1.3 | v |
| ation Voltage | Emitter-Follower | V _{CE(SAT)} | $V_{C} = 15V, I_{E} = 200mA$ | - | 1.5 | 2.5 | v |
| Collector off-sta | ate Current | $I_{C(off)}$ | $V_{CC} = V_{C} = 40V, V_{E} = 0$ | - | 2 | 100 | μA |
| Emitter off-stat | e Current | $I_{E(off)}$ | $V_{CC} = V_{C} = 40V, V_{E} = 0$ | - | - | -100 | μΑ |
| Output Control(Pin 13) | | | | | | | |
| Output Control Required for si Parallel Output | ingle-Ended or | V _{OCL} | - | - | - | 0.4 | V |
| Output Control uired for Push-p | 5 | V _{OCH} | - | 2.4 | - | - | V |
| Total Device | | | | | | | |
| Standby power Current | Supply | I _{CC} | - | - | 6 | 10 | mA |

: These limits apply when the voltage measured at Pin 3 is with in the range specified.

Output AC Characteristic

| Chara | acteristic | Symbol | Test Condition | Min. | Тур. | Max. | Unit |
|-----------|------------------|----------------|----------------|------|------|------|------|
| Rise Time | Common Emitter | ÷ | | - | 100 | 200 | |
| Rise Time | Emitter Follower | ۲ | - | - | 100 | 200 | nc |
| Fall Time | Common Emitter | | | - | 25 | 100 | ns |
| | Emitter Follower | t _f | - | - | 40 | 100 | |

Block Diagram

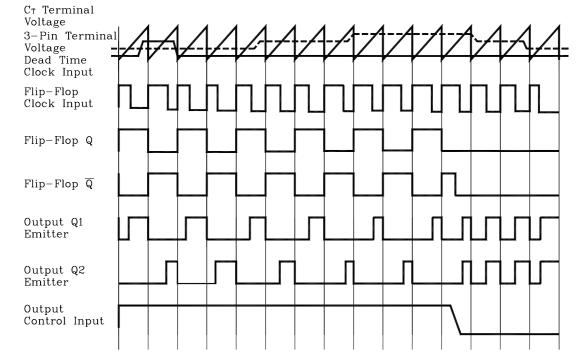


INFORMATION

The basic oscillator(switching)frequency is controlled by an external resistor (Rt) and capacitor(Ct). The relationship between the values of Rt Ct and frequency is shown in.

The level of the sawtooth wave form is compared with an error voltage by the pulse width modulated comparator. The output of the PWM Comparator directs the pulse steering flip flop and the output control logic.

The error voltage is generated by the error amplifier. The error amplifier boosts the voltage difference between the output and the 5V internal reference. See Figure7 for error amp sensing techniques. The second error amp is typically used to implement current limiting. The output control logic (Pin13) selects either push-pull or single-ended operation of the output transistors (see Figure6). The dead time control prevents on-state overlap of the output transistors as can be seen is Figure5. The dead time is approximately 3 to 5% of the total period if the dead time control(pin4) is grounded. This dead time can be increased by connecting the dead time control to a voltage up to 5 V. The frequency response of the error amps can be modified by using external resistors and capacitors. These components are typically connected between the compensation terminal (pin3) and the inverting input of the error amps(pin2 or pin15). The switching frequency of two or more S494 circuits can be synchronized. The timing capacitor, Ct is connected as shown in Figure8. Charging current is provided by the master circuit. Discharging is through all the circuits slaved to the master. Rt is required only for the master circuit.



Operating Waveform

Test Circuit

Fig.1Error Amplifier Test Circuit

Fig.2 Current Limit sense Amplifier Test Circuit

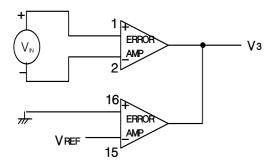
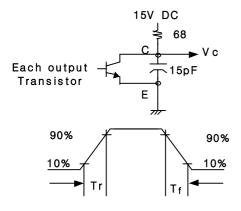
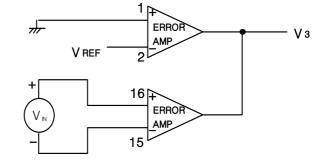
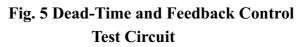


Fig. 3 Common-Emitter Configuration Test circuit and Waveform







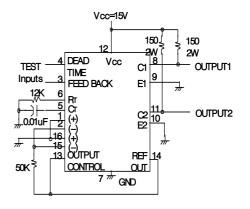


Fig. 4 Emitter-Follower Configuration Test circuit and waveform Voltage waveform



APPLICATION CIRCUIT

Fig. 6 Output Connections for Single-Ended and Push-Pull Configurations

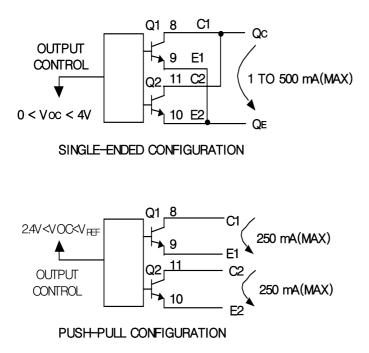


Fig. 7 Error Amplifier Sensing Techniques

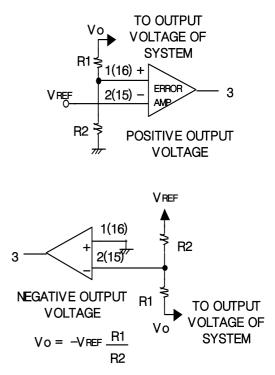
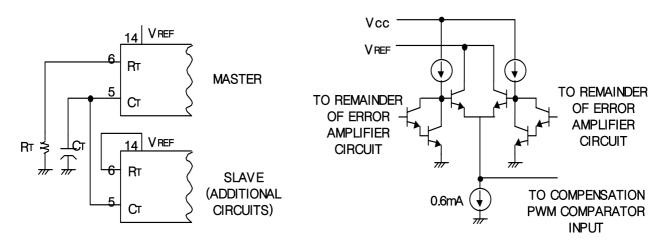


Fig. 8 Slaving Tow or More Control Circuits

Fig. 9Error Amplifier and Current Limit Sense Amplifier Output Circuits



Electrical Characteristic Curves

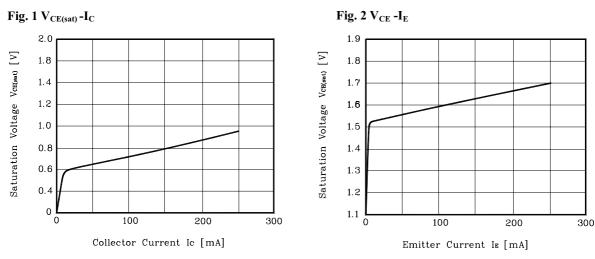


Fig. 3 tosc - R_T

