

DC Brushless Motor Driver IC

# **PT-30DFA** Single- Phase Full-Wave Linear Drive

# APPLICATIONS

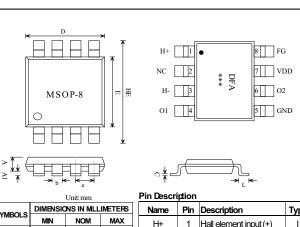
- · Single coils DC brushless motor.
- DC 2.0V~18V.

# FEATURES

- Single-phase full-wave linear driver (BTL linear output driver)
- . Switch noise elimination
- Motor lock protection and automatic restart
- Connectable direct to Hall element
- Built-in hysteresis comparator
- Frequency Generation output
- Low power consumption and high driving efficiency

### **INPUT DEVICES**

 $\cdot$  HALL IC or HALL ELEMENT



**PACKAGE: MSOP8** 

SYMBOLS	DIMENSIONS IN MILLIMETERS			Name	Pin	Description	Туре
STIVIDOLS	MIN	NOM	MAX	H+	1	Hall element input (+)	I
A1	0.00	-	0.20	NO	0	1.()	
А	0.76	0.86	0.97	NC	NC 2 NC		-
b	0.15	0.20	0.30	H-	3	Hall element input (-)	I
С	0.13	0.15	0.23	01	4	First output pin	0
D	2.90	3.0	3.10	GND	5	DC ground	Р
E	2.90	3.0	3.10	02	6	Second output pin	0
HE	4.80	4.90	5.10				-
е	-	0.65	-	VDD	1	DC power supply	Р
L	0.40	0.53	0.66	FG	8	Frequency Generation	0

# SPECIFICATIONS

### Absolute Maximum Ratings (Ta = 25C)

Parameter	Symbol	Conditions	Ratings	Units
Maximum supply voltage	VDD <sup>max</sup>		18	v
Allowable power dissipation	Pd		<b>450</b> <sup>*</sup>	mW
Operating temperature	Та		-30 ~ +100	°C
Storage temperature	Ts		-55 ~ +150	°C
Output current	lout	Continoue	350	mA

#### \*On 50mm x 50mm x 1.6mm glass epoxy board

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# **Electrical Characteristics**

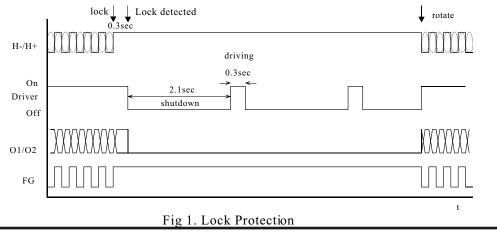
Characteristic	Symbol	Test Condition	Min.	Тур.	Max.	Units
Supply Voltage	V <sub>DD</sub>		2.0		18	V
Output low-level	V <sub>OL</sub>	I <sub>O</sub> =200mA		0.4	0.5	V
Voltage						
Output High-level	V <sub>OH</sub>	I <sub>O</sub> =200mA	V <sub>CC</sub> -0.5	V <sub>cc</sub> -0.4		V
Voltage						
Output Breakdown	$V_{BV}$		18	22	30	V
Voltage						
Input offset	V <sub>OS</sub>		-6		6	mV
voltage						
Supply Current	I <sub>DD</sub>	Output open		3	10	mA
FG flow-in Current	I <sub>FG</sub>	Pull-high resistor is		25		mA
		470ohm@12V				
FG Supply Voltage					30	V
FG Frequency		Same with Hall				
		input signal				
Pre-Amplifier Gain	$V_{G}$			50		dB

# Truth Table

H+	H-	State	01	02	FG	RD
н	L	Rotate	L	Н	L	L
L	Н	Rotate	Н	L	Н	L
н	L	Lock	L	L	Н	Н
L	Н	Lock	L	L	Н	Н

# Lock Protection

In order to protect the motor, the driver IC will be shutdown to drive the coil when the motor is locked over 0.3seconds. Then, it restarts to drive the motor after 2.1seconds. Figure 1 shows the timing diagram between the hall input signal and driver's output state.



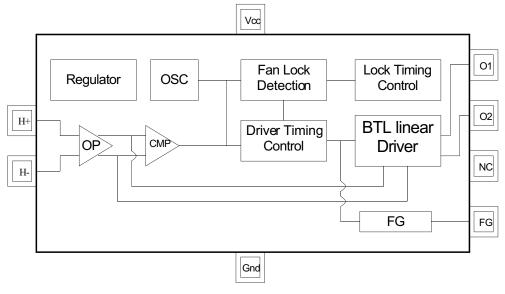




# **Pre-Amplifier**

This driver IC integrates signal amplifier and the hysteresis comparator in this chip. The hysteresis comparator uses the hysteresis characteristic to eliminate noisy oscillations at output of the comparator.

The driver IC architecture block diagram is shown in Fig. 2.





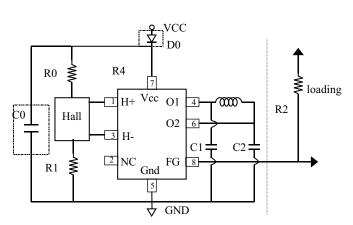
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# **APPLICATION CIRCUITS**/ Single coil

# **\***Hall element input



R0=R1:depend on hall device Spec. R0=R1 is recommended R2: open drain loading C0: optional decoupling capacitor 0.1uF C1,C2: 1uF~2.2uF capacitor

★ Hall IC input

