



# 20mA Air-Core Tachometer Drive Circuit

## Description

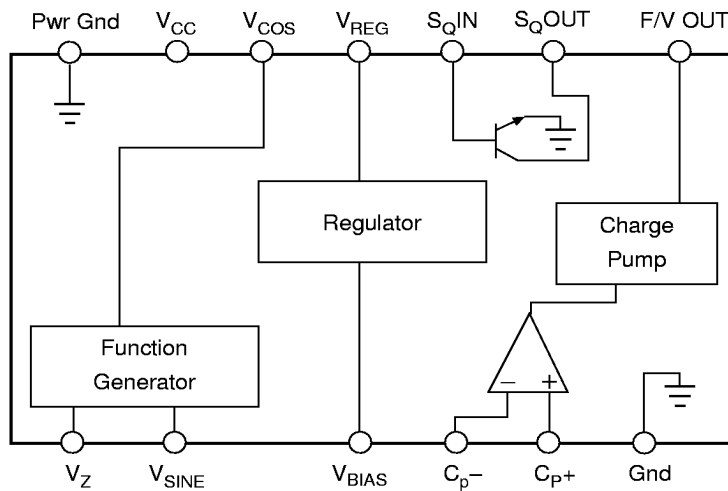
The CS-289 is specifically designed for use with air-core meter movements. The IC has charge pump circuitry for frequency-to-voltage conversion, a shunt regulator for stable operation, a func-

tion generator, and sine and cosine amplifiers. The buffered sine and cosine outputs will typically sink or source 20mA.

## Absolute Maximum Ratings

Supply Voltage ( $V_{CC}$ ) .....20V  
 Operating Temperature.....-40°C to +100°C  
 Junction Temperature .....-40°C to 150°C  
 Storage Temperature .....-65°C to +150°C  
 Lead Temperature Soldering  
 Wave Solder (through hole styles only).....10 sec. max, 260°C peak  
 Reflow (SMD styles only).....60 sec. max above 183°C, 230°C peak

## Block Diagram

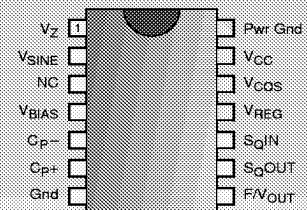


## Features

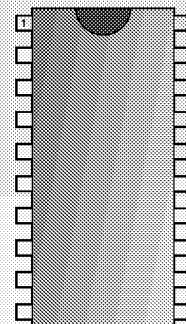
- Single Supply Operation
- On-Chip Regulation
- 20mA Output Drive Capability

## Package Options

### 14L PDIP



### 20L SOIC Wide Batwing



Rev. 2/19/98

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A CHERRY Company

Electrical Characteristics: ( $V_{CC} = 13.1V$ ,  $-40^{\circ}C \leq T_A \leq 85^{\circ}C$ )

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Supply Current (note 2)	$V_{CC} = 15.0V$		54		mA
Regulated Voltage	$I_{REG} = 4.3mA$		8.5		V
Regulation	$I_{REG} = 0$ to $5mA$		0.10		V
Signal Input Current			2.0		mA
Saturation Voltage	$I_{SQ OUT} = 5mA$ , $V_{SQ IN}$		0.20		V
Leakage Current	$I_{SQ OUT} = 16V$ , $V_{SQ IN} = 0V$				$\mu A$
Input Current	Zero input to $C_{P+}$		1		nA
F to V Output	$V_{SQ IN} = 0$ (zero input), $\phi = 0^{\circ}$		2.1		V
	$V_{COS} = 0$ (note 1), $\phi = 270^{\circ}$		7.1		
Linearity	$E_O$ vs. Frequency				%
	$V_{COS} = 0$ (note 1), $\phi = 270^{\circ}$				
$V_{sine}$ at $\phi = 0^{\circ}$	$V_{SQ IN} = 0$ (zero input), $\phi = 0^{\circ}$		0.00		V
MAX $V_{sine+}$	$V_{COS} = 0$ (note 1), $\phi = 90^{\circ}$		4.5		V
MAX $V_{sine-}$	$V_{COS} = 0$ (note 1), $\phi = 270^{\circ}$		-4.5		V
Coil Drive Current	$V_{COS} = 0$ (note 1), $\phi = 90^{\circ}$		20		mA
	$V_{COS} = 0$ (note 1), $\phi = 270^{\circ}$		20		mA
MAX $V_{COS+}$	$V_{SQ IN} = 0$ (zero input), $\phi = 0^{\circ}$		4.5		V
MAX $V_{COS-}$	$V_{sine} = 0$ (note 1), $\phi = 180^{\circ}$		-4.5		V
Coil Drive Current	$V_{SQ IN} = 0$ (zero input), $\phi = 0^{\circ}$		20		mA
	$V_{sine} = 0$ (note 1), $\phi = 180^{\circ}$		20		mA
External Voltage Ref.			5.40		V

Note 1:  $V_{sine}$  measured  $V_{sine}$  to  $V_Z$ .  $V_{COS}$  measured  $V_{COS}$  to  $V_Z$ . All other voltages specified are measured to ground.

Note 2: Max PWR dissipation  $\leq V_{CC} \times I_{CC} - (V_2 I_{sine} + V_{I2} I_{COS})$ .

## Package Pin Description

PACKAGE PIN #		PIN SYMBOL	FUNCTION
20L SO	14L PDIP		
1	1	$V_Z$	External Zener reference.
2	2	$V_{sine}$	Sine output signal.
3	4	$V_{BIAS}$	Test pin or "0" calibration pin.
4, 5, 6, 7, 14, 15, 16, 17	7	Gnd	Analog Ground connection.
8	5	$C_{P-}$	Negative input to charge pump.
9	6	$C_{P+}$	Positive input to charge pump.
10	3	NC	No Connection
11	8	F/ $V_{OUT}$	Output voltage proportional to input signal frequency.

## Package Pin Description: continued

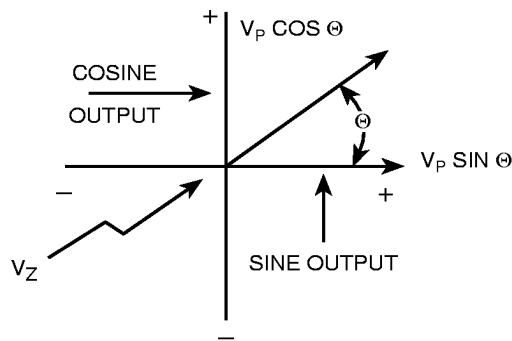
PACKAGE PIN #	PIN SYMBOL	FUNCTION
<b>20L SO</b>	<b>14L PDIP</b>	
12	9	S <sub>Q</sub> OUT Buffered square wave output signal.
13	10	S <sub>Q</sub> IN Speed or RPM input signal.
18	11	V <sub>REG</sub> Voltage regulator output.
19	12	V <sub>COS</sub> Cosine output signal.
20	13	V <sub>CC</sub> Supply voltage.
	14	Pwr Gnd Power Ground connection.

Note 1: V<sub>sine</sub> measured V<sub>sine</sub> to V<sub>Z</sub>. V<sub>cos</sub> measured V<sub>cos</sub> to V<sub>Z</sub>. All other voltages specified are measured to ground.

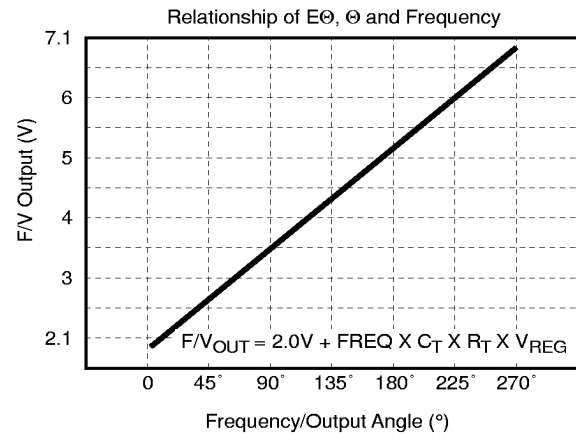
Note 2: Max PWR dissipation  $\leq V_{CC} \times I_{CC} - (V_2 I_{sine} + V_{12} I_{cos})$ .

## Typical Performance Characteristics

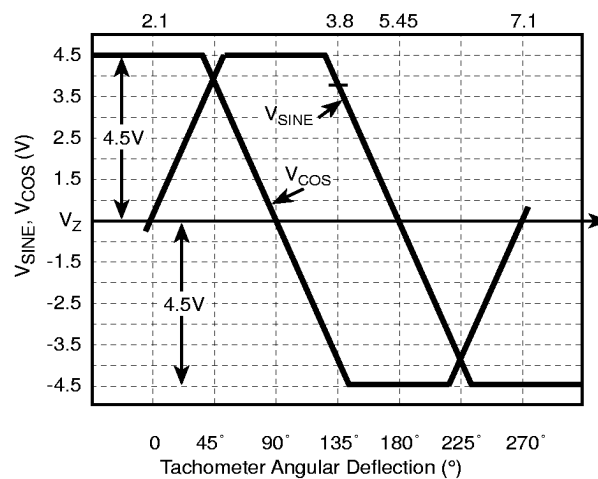
Output Angle in Polar Form



Charge Pump Output Voltage



Function Generator Output Voltage



## Charge Pump

The input frequency is buffered through a transistor, then applied to the charge pump for frequency-to-voltage conversion (Figure 1). The charge pump output voltage,  $E_{\phi}$ , will range from 2.1V with no input ( $\phi = 0^\circ$ ) to 7.1V at  $\phi = 270^\circ$ . The charge that appears on  $C_T$  is reflected to  $C_{OUT}$  through a Norton amplifier. The frequency applied at  $S_{QIN}$  charges and discharges  $C_T$  through  $R_1$  and  $R_2$ .  $C_{OUT}$  reflects the charge as a voltage across resistor  $R_T$ .

## Function Generator/Sine and Cosine Amplifiers

The output waveforms of the sine and cosine amplifiers are derived by On-Chip Amplifier/Comparator circuitry. The various trip points for the circuit (i.e.  $90^\circ$ ,  $180^\circ$ ,  $270^\circ$ ) are determined by an internal resistor divider connected to the voltage regulator. The voltage  $E_{\phi}$  is compared to the divider network by the function generator circuitry. Use of an external zener reference at  $V_Z$  allows both sine and cosine amplifiers to swing positive and negative with respect to this reference. The output magnitudes and directions have the relationship as shown in Typical Characteristics diagrams.

Note: Pin connections referenced are for the 14L DIP.

Function Generator Output ( $\phi$ ):  $V_{CC}=13.1V$ ,  $T_A=25^\circ C$

$\phi = \text{ArcTan} \left( \frac{V_{\text{sine}}}{V_{\text{cos}}} \right)$  (Measured angle after calibration at  $180^\circ C$ )

For  $\phi_A = 45^\circ, 90^\circ, 135^\circ, 180^\circ, 225^\circ, 270^\circ$ , (Desired angle)  
 $(\phi_A - \phi_M) \leq 4.0^\circ$

Temperature Sensitivity:  $V_{CC}=13.1V$

$\Delta\phi_{MT} = \phi_M (T=25^\circ C) - \phi_M (-20^\circ C \leq T \leq +85^\circ C)$

$(\Delta\phi_{MT}) \leq 3.5^\circ C, -20^\circ C \leq T \leq +85^\circ C$

Voltage Sensitivity:  $T_A=25^\circ C$

$\Delta\phi_{MV} = \phi_M (V_{CC}=13.1V) - \phi_M (11.3V \leq V_{CC} \leq 15V)$

$(\Delta\phi_{MV}) \leq 2^\circ, 11.3V \leq V_{CC} \leq 15V$

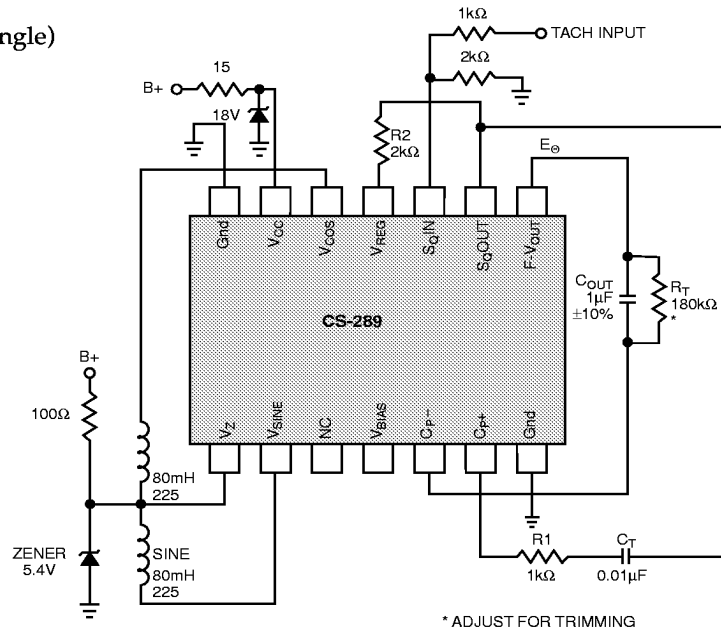


Figure 1. Functional Diagram of CS-289 Circuit.

## Tachometer Application

$$\frac{\text{RPM}}{60} \times \frac{\# \text{ OF CYL.}}{2} = \text{Frequency}$$

$$V_{F/V_{OUT}} = 2.1 + \text{Frequency} \times C_T \times R_T (V_{REG} - 0.7)$$

The above equations were used in calculating the following values, where  $V_{F/V_{OUT}} = 7.1\text{V}$  at  $\approx 270^\circ$  and  $C_T = 0.01\text{ F}$ .

4 cylinder: Freq = 200Hz,  $R_T = 320\text{k}\Omega$

6 cylinder: Freq = 300Hz,  $R_T = 220\text{k}\Omega$

8 cylinder: Freq = 400Hz,  $R_T = 150\text{k}\Omega$

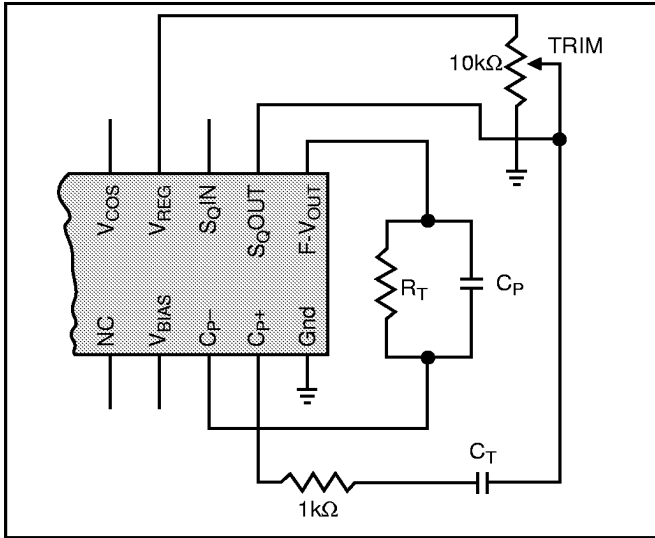


Figure 2: Alternate Trimming Method

Typical values shown above apply to a nominal value of  $V_{REG}$  of 8.5 volts. It must be realized that trimming of  $R_T$  will be necessary to compensate for variations in regulator voltage from one unit to another.

An alternative to this adjustment is to replace  $R_2$  with a potentiometer, as shown in Figure 2.

Partial schematic shown in Figure 3 represents one method for use with DC applications instead of frequency.

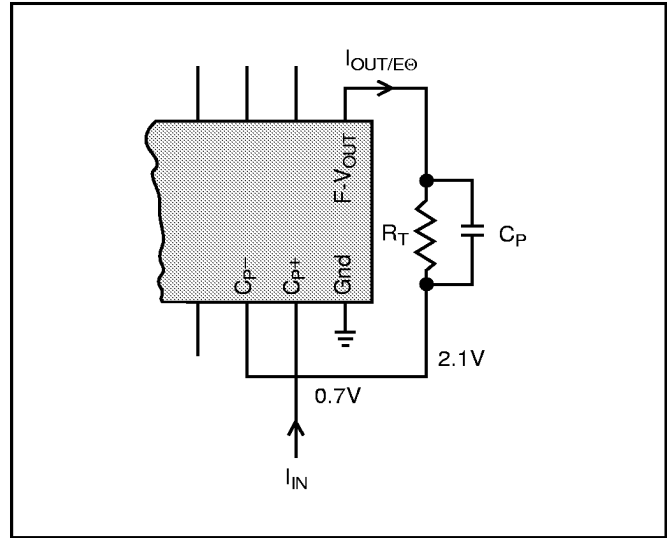


Figure 3: DC Application

# Package Specification

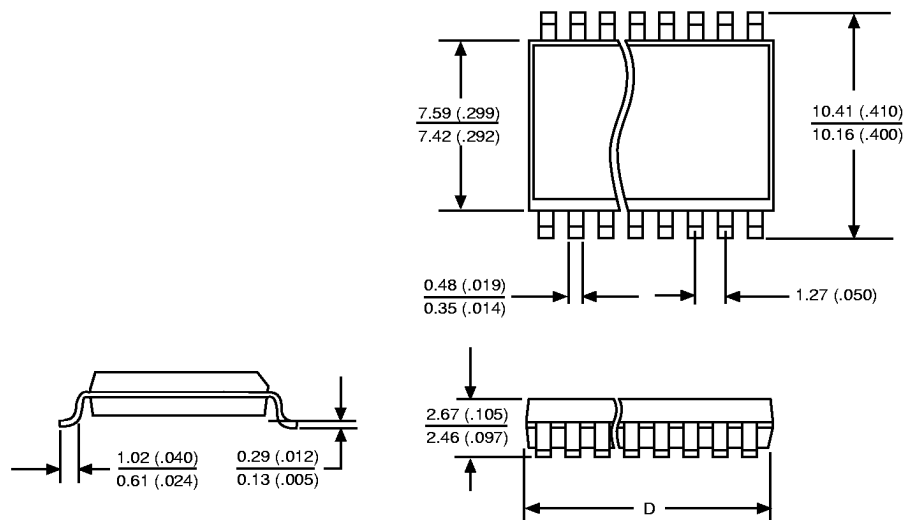
## PACKAGE DIMENSIONS IN mm (INCHES)

Lead Count	D			
	Metric		English	
	Max	Min	Max	Min
14L PDIP	19.18	18.92	.755	.745
20L SO Wide Batwing	12.95	12.70	.510	.500

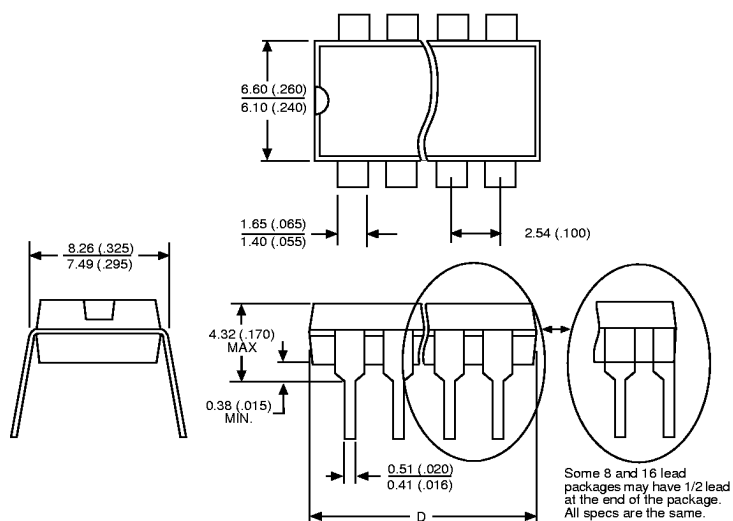
## PACKAGE THERMAL DATA

Thermal Data		14L PDIP	20L SOIC Wide Batwing	
R <sub>θJC</sub>	typ	48	17	°C/W
R <sub>θJA</sub>	typ	85	90	°C/W

### 20L SO Wide Batwing



### 14L PDIP



## Ordering Information

Part Number	Description
CS-289DW20	20 Lead SO Wide Batwing
CS-289N14	14 Lead PDIP

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