#### Product Preview

# 2.5Gb/s Fiber Optic Post Amplifier

The MC10SX1127 is an integrated limiting amplifier for high frequency fiber optic applications. The device interfaces directly to the trans–impedance amplifier of a typical optical to electrical conversion portion of a fiber optic link. With data rate capabilities in the 2.5Gb/s range, the high gain limiting amplification of the SX1127 is ideal for high speed fiber optic applications like SONET/SDM, ATM, FDDI, Fibre Channel or Serial Hippi. The CAZP and CAZN inputs to the limiting amplifier provide an auto-zero function to effectively cancel any input offset voltage present in the amplifier.

The SX1127 incorporates a programmable level detect function to identify when the input signal has been lost. This information can be fed back to the Disable input of the device to maintain stability under loss of signal conditions. Using the  $V_{\text{Set}}$  pin the sensitivity of the level detect can be adjusted. The  $C_{\text{LD}}$  input is used to filter the level detect input so that random noise spikes are filtered out.

The MC10SX1127 is compatible with MECL10H logic levels.

- Wideband Operation: 50MHz to 1.8GHz
- Programmable Input Signal Level Detection
- Operation with single +3.3V to +5V or standard ECL supply
- Standard 16-lead SOIC Package and 16 TSSOP Package
- Fully Differential Design to Minimize Noise Affects
- 10KH Compatible

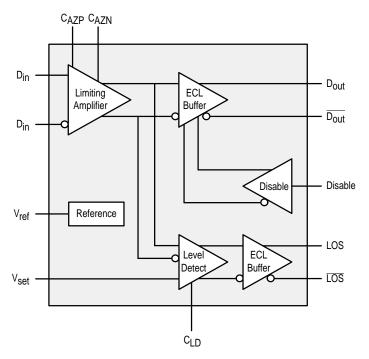
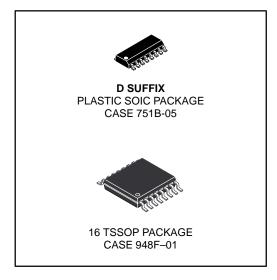


Figure 1. MC10SX1127 Block Diagram

MC10SX1127

# FIBER OPTIC POST AMPLIFIER



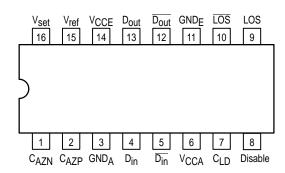


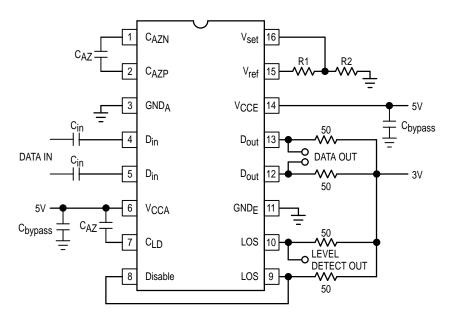
Figure 2. 16-Lead Pinout (Top View)

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#### **FUNCTION TABLE**

Pin	Function
C <sub>AZN</sub>	Auto-zero capacitor pin. A capacitor between this pin and CAZP cancels any offset inherent to the limiting amplifier.
C <sub>AZP</sub>	Auto-zero capacitor pin. A capacitor between this pin and CAZN cancels any offset inherent to the limiting amplifier.
GND <sub>A</sub>	Analog ground pin. Ground for PECL operation or –3.3V to –5V for standard ECL operation. GND <sub>A</sub> and GND <sub>E</sub> must be at the same potential.
D <sub>in</sub> , D <sub>in</sub>	Differential data input.
VCCA	Analog power supply pin. +3.3V to +5V for PECL operation or ground for standard ECL operation. V <sub>CCA</sub> and V <sub>CCE</sub> must be at the same potential.
C <sub>LD</sub>	Filter capacitor for the level detect comparator. Capacitor should be connected to VCCA.
Disable	When asserted LOW, or left open and pulled LOW via the input pulldown resistor, the output buffer will be enabled and will respond to the input stimulus on the D <sub>in</sub> input. Forcing Disable HIGH will force the D <sub>out</sub> output LOW and its complimentary output HIGH.
LOS, LOS	Differential loss of signal. LOS will go HIGH when the input signal falls below (V <sub>Set</sub> /100) mV <sub>P-P</sub> .
GNDE	Digital ground pin. Ground for PECL operation or –3.3V to –5V for standard ECL operation. GND <sub>A</sub> and GND <sub>E</sub> must be at the same potential.
D <sub>out</sub> , D <sub>out</sub>	Differential data outputs.
VCCE	Digital power supply pin. +3.3V to +5V for PECL operation or ground for standard ECL operation. V <sub>CCA</sub> and V <sub>CCE</sub> must be at the same potential.
V <sub>ref</sub>	Reference voltage for threshold level set voltage division network (V <sub>CC</sub> – 1.2V).
V <sub>set</sub>	Input threshold level detect setting input. Input generated from voltage divider between V <sub>ref</sub> and GND <sub>A</sub> .



**Figure 3. Typical Operating Circuit** 

#### **Coupling Capacitors**

The SX1127 inputs must be AC coupled to allow proper operation of the offset correction function. The coupling capacitors, C<sub>in</sub>, must be large enough to pass the lowest input frequency of interest.

$$C_{in} = \frac{1}{2\pi \ (R_{in}) \ (f_{low})}$$

where

 $R_{in}$  = input resistance =  $5000\Omega$ 

 $f_{IOW}$  = lowest frequency.

#### **Auto-zero Capacitors**

A feedback amplifier is used to cancel the offset voltage of the forward signal path, so the input to the internal ECL comparator is at its toggle point in the absence of any input signal. The time constant of the cancelling circuitry is set by an external capacitor (CAZ) connected between Pins 1 and 2. The formula for the calculation of the auto–zero capacitor is:

$$C_{AZ} = \frac{150}{2\pi \text{ (RAZ) (flow)}}$$

where

 $R_{AZ}$  = internal driving impedance =  $290k\Omega$ 

flow = lowest frequency.

#### **Input Signal Level Detector**

The SX1127 allows for user programmable input signal level-detection and can automatically disable the switching of its ECL data output if the input level is below a set threshold. This prevents the outputs from reacting to noise in the absence of a valid input signal, and ensures that data will only be transmitted when the signal-to-noise ratio is sufficient for low bit-error-rate system operation. Complimentary ECL flags (LOS and LOSB) indicate whether the input signal is above or below the desired threshold level. In the level detect system, the input signal is amplified and rectified before being compared to a programmable reference. A filter is included to prevent noise spikes from triggering the level-detector. The filter has a nominal 1µs time constant, and additional filtering can be achieved by using an external capacitor (CLD) from Pin 7 to VCCA (the internal driving impedance is nominally 28k). The formula for the calculation of the CLD capacitor is:

$$C_{LD} = \frac{t}{Rz}$$

where

 $R_Z$  = internal driving impedance =  $28k\Omega$  t = LOS filter time constant.

#### DC CHARACTERISTICS (GND<sub>A</sub> = GND<sub>E</sub> = Ground; V<sub>CCA</sub> = V<sub>CCE</sub> = 4.5V to 5.5V)

Symbol	Characteristic	Min	Тур	Max	Unit	Condition
VIN	Input Signal Voltage (Din) Single-Ended	TBD		1.5	V <sub>P-P</sub>	Note 1.
Vos	Input Offset Voltage			50	μV	
V <sub>N</sub>	Input RMS Noise			225	μV	
VTH	Input Level Detect Programmability	8.0		20	mVp₋p	
VHYS	Level Detect Hysteresis	1.5	2.5	7.0	dB	Note 2.
lн	Input HIGH Current Disable			150	μΑ	
Icc	Power Supply Current		33	45	mA	

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- 1. This device functions with  $V_{in}min = 6mV_{P-P}$ , but with increased BER (See BER data).
- 2. This device has an anomoly in V<sub>HYS</sub> when 0.65 < V<sub>SET</sub> < 0.75V. Operation in this region is not recommended. (See Figure 5)

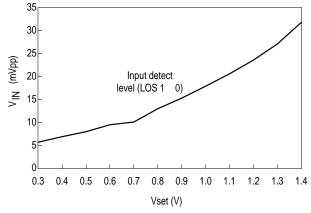


Figure 4. LOS versus Vset  $(T_A = 25^{\circ}C)$ 

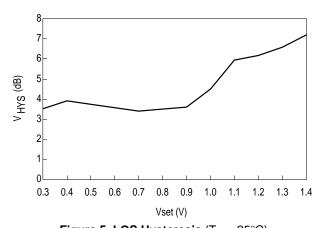


Figure 5. LOS Hysteresis  $(T_A = 25^{\circ}C)$ 

#### I/O DC CHARACTERISTICS (Note 3.)

		-40	)°C	<b>0</b> °	C	25	°C	85	°C	
Symbol	Characteristic	Min	Max	Min	Max	Min	Max	Min	Max	Unit
VOH	Output HIGH Voltage $V_{CC} = -4.5 \text{ to } -5.5 \text{V}$ $V_{CC} = 5.0 \text{V (Note 4.)}$	1080 3920	-890 4110	1020 3980	-840 4160	-980 4020	-810 4190	-910 4090	-720 4280	mV
VOL	Output LOW Voltage $V_{CC} = -4.5 \text{ to } -5.5 \text{V}$ $V_{CC} = 5.0 \text{V (Note 4.)}$	-1950 3050	-1650 3350	-1950 3050	-1630 3370	-1950 3050	-1630 3370	-1950 3050	-1595 3405	mV
VIH	Input HIGH Voltage (Note 5.) $V_{CC} = -4.5 \text{ to } -5.5 \text{V}$ $V_{CC} = 5.0 \text{V (Note 4.)}$	-1230 3770	-890 4110	-1170 3830	-840 4160	-1130 3870	-810 4190	-1060 3940	-720 4280	mV
V <sub>IL</sub>	Input LOW Voltage (Note 5.) $V_{CC} = -4.5 \text{ to } -5.5 \text{V}$ $V_{CC} = 5.0 \text{V (Note 4.)}$	-1950 3050	-1500 3500	-1950 3050	-1480 3520	-1950 3050	-1480 3520	-1950 3050	-1445 3555	mV
IIL	Input LOW Current (Note 5.)	0.5		0.5		0.5		0.3		μΑ

<sup>3. 10</sup>SX circuits are designed to meet the DC specifications shown in the table after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse airflow greater than 500lfpm is maintained. Outputs are terminated through a  $50\Omega$  resistor to -2.0 volts except where otherwise specified on the individual data sheets.

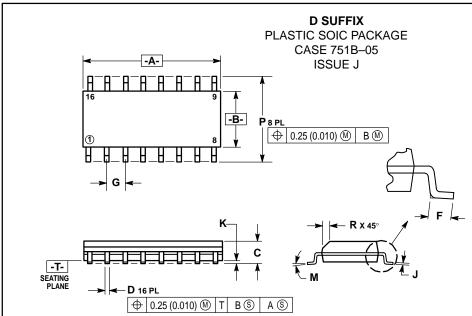
#### AC CHARACTERISTICS (V<sub>CCA</sub> = V<sub>CCE</sub> = 4.5V to 5.5V)

Symbol	Characteristic	Min	Тур	Max	Unit	Condition
BW <sub>min</sub>	Lower –3dB Bandwidth			50	MHz	
BW <sub>max</sub>	Upper –3dB Bandwidth	1.8			GHz	
tPWD	Pulse Width Distortion			70	ps	
t <sub>r</sub> , t <sub>f</sub>	Rise/Fall Times	150	250	650	ps	20% – 80%
R <sub>AZ</sub>	Auto-Zero Output Resistance	200	325	450	kΩ	
R <sub>F</sub>	Level Detect Filter Resistance	14	25	41	kΩ	
t <sub>LD</sub>	Level Detect Time Constant	0.5		4.0	μs	
<sup>t</sup> jitter	Total Jitter		TBD		ps	

<sup>4.</sup> Limits hold for  $V_{CC} = 5.0V$  only. Parametric values will vary 1:1 with any variation of  $V_{CC}$ .

5. Parametric values for the Disable input only.

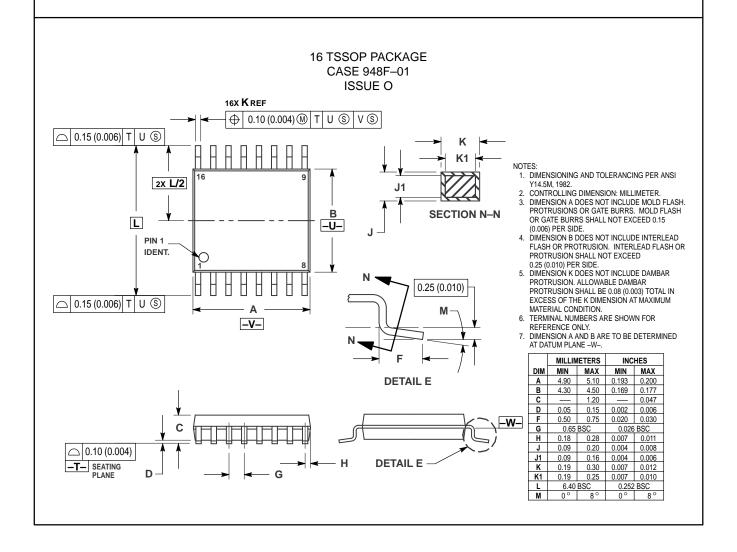
#### **OUTLINE DIMENSIONS**



#### NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: MILLIMETER.
  DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
  MAXIMUM MOLD PROTRUSION 0.15 (0.006)
- DIMENSION D DOES NOT INCLUDE DAMBAR DIMENSION D DUES NOT INCLUDE DAMBAR
  PROTRUSION. ALLOWABLE DAMBAR
  PROTRUSION SHALL BE 0.127 (0.005) TOTAL
  IN EXCESS OF THE D DIMENSION AT
  MAXIMUM MATERIAL CONDITION.

	MILLIM	ETERS	INCHES			
DIM	MIN	MAX	MIN	MAX		
Α	9.80	10.00	0.386	0.393		
В	3.80	4.00	0.150	0.157		
С	1.35	1.75	0.054	0.068		
D	0.35	0.49	0.014	0.019		
F	0.40	1.25	0.016	0.049		
G	1.27 BSC		0.050 BSC			
J	0.19	0.25	0.008	0.009		
K	0.10	0.25	0.004	0.009		
М	0°	7°	0°	7°		
Р	5.80	6.20	0.229	0.244		
R	0.25	0.50	0.010	0.019		



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## **NOTES**

## **NOTES**

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