



Section I. Arria GX Device Data Sheet

This section provides designers with the data sheet specifications for Arria™ GX devices. They contain feature definitions of the transceivers, internal architecture, configuration, and JTAG boundary-scan testing information, DC operating conditions, AC timing parameters, a reference to power consumption, and ordering information for Arria GX devices.

This section includes the following chapters:

- [Chapter 1, Arria GX Device Family Overview](#)
- [Chapter 2, Arria GX Architecture](#)
- [Chapter 3, Configuration and Testing](#)
- [Chapter 4, DC and Switching Characteristics](#)
- [Chapter 5, Reference and Ordering Information](#)

Revision History

Refer to each chapter for its own specific revision history. For information on when each chapter was updated, refer to the Chapter Revision Dates section, which appears in the full handbook.

Introduction

The Arria™ GX family of devices combines 3.125 gigabits per second (Gbps) serial transceivers with reliable packaging technology and a proven logic array. Arria GX devices include 4 to 12 high-speed transceiver channels, each incorporating clock/data recovery (CDR) technology and embedded SERDES circuitry designed to support PCI-Express, Gigabit Ethernet, SDI, SerialLite II, XAUI, and Serial RapidIO protocols, along with the ability to develop proprietary, serial-based IP using its Basic mode. The transceivers build upon the success of Stratix® II GX family. The Arria GX FPGA technology offers a 1.2-V logic array with the right level of performance and dependability needed to support these mainstream protocols.

Features

The key device features for the Arria GX include:

- Transceiver block features
 - High-speed serial transceiver channels with clock/data recovery support up to 3.125 Gbps.
 - Devices available with 4, 8, or 12 high-speed full-duplex serial transceiver channels
 - Support for the following CDR-based bus standards — PCI Express, Gigabit Ethernet, SDI, SerialLite II, XAUI, and Serial RapidIO, along with the ability to develop proprietary, serial-based IP using its Basic mode
 - Individual transmitter and receiver channel power-down capability for reduced power consumption during non-operation
 - 1.2- and 1.5-V pseudo current mode logic (PCML) support on transmitter output buffers
 - Receiver indicator for loss of signal (available only in PCI Express (PIPE) mode)
 - Hot socketing feature for hot plug-in or hot swap and power sequencing support without the use of external devices
 - Dedicated circuitry that is compliant with PIPE, XAUI, GIGE, SDI, and Serial RapidIO
 - 8B/10B encoder/decoder performs 8-bit to 10-bit encoding and 10-bit to 8-bit decoding
 - Phase compensation FIFO buffer performs clock domain translation between the transceiver block and the logic array
 - Channel aligner compliant with XAUI

- Main device features:
 - TriMatrix memory consisting of three RAM block sizes to implement true dual-port memory and first-in first-out (FIFO) buffers with performance up to 380 MHz
 - Up to 16 global clock networks with up to 32 regional clock networks per device
 - High-speed DSP blocks provide dedicated implementation of multipliers, multiply-accumulate functions, and finite impulse response (FIR) filters
 - Up to four enhanced PLLs per device provide spread spectrum, programmable bandwidth, clock switch-over, and advanced multiplication and phase shifting
 - Support for numerous single-ended and differential I/O standards
 - High-speed source-synchronous differential I/O support on up to 47 channels
 - Support for source-synchronous bus standards, including SPI-4 Phase 2 (POS-PHY Level 4), SFI-4.1, XSBI, UTOPIA IV, NPSI, and CSIX-L1
 - Support for high-speed external memory including double data rate (DDR and DDR2) SDRAM, and single data rate (SDR) SDRAM
 - Support for multiple intellectual property megafunctions from Altera® MegaCore® functions and Altera Megafunction Partners Program (AMPPSM)
 - Support for remote configuration updates

Table 1–1 lists Arria GX device features for FineLine BGA (FBGA) with flip-chip packages.

| Feature | EP1AGX20C | EP1AGX35C/D | | EP1AGX50C/D | | EP1AGX60C/D/E | | | EP1AGX90E |
|-----------------------|------------------------------|------------------------|---------------------|------------------------|-------------------------------|------------------------|---------------------|----------------------|------------------------|
| | C | C | D | C | D | C | D | E | E |
| Package | 484-pin, 780-pin (Flip-chip) | 484-pin (Flip-chip) | 780-pin (Flip-chip) | 484-pin (Flip-chip) | 780-pin, 1152-pin (Flip-chip) | 484-pin (Flip-chip) | 780-pin (Flip-chip) | 1152-pin (Flip-chip) | 1152-pin (Flip-chip) |
| ALMs | 8,632 | 13,408 | | 20,064 | | 24,040 | | | 36,088 |
| Equivalent LEs | 21,580 | 33,520 | | 50,160 | | 60,100 | | | 90,220 |
| Transceiver channels | 4 | 4 | 8 | 4 | 8 | 4 | 8 | 12 | 12 |
| Transceiver data rate | 600 Mbps to 3.125 Gbps | 600 Mbps to 3.125 Gbps | | 600 Mbps to 3.125 Gbps | | 600 Mbps to 3.125 Gbps | | | 600 Mbps to 3.125 Gbps |

Table 1–1. Arria GX Device Features (Part 2 of 2)

| Feature | EP1AGX20C | EP1AGX35C/D | | EP1AGX50C/D | | EP1AGX60C/D/E | | | EP1AGX90E |
|--------------------------------------|-----------|-------------|-----|-------------|----------|---------------|-----|-----|-----------|
| | C | C | D | C | D | C | D | E | E |
| Source-synchronous receive channels | 31 | 31 | 31 | 31 | 31, 42 | 31 | 31 | 42 | 47 |
| Source-synchronous transmit channels | 29 | 29 | 29 | 29 | 29, 42 | 29 | 29 | 42 | 45 |
| M512 RAM blocks (32 × 18 bits) | 166 | 197 | | 313 | | 326 | | | 478 |
| M4K RAM blocks (128 × 36 bits) | 118 | 140 | | 242 | | 252 | | | 400 |
| M-RAM blocks (4096 × 144 bits) | 1 | 1 | | 2 | | 2 | | | 4 |
| Total RAM bits | 1,229,184 | 1,348,416 | | 2,475,072 | | 2,528,640 | | | 4,477,824 |
| Embedded multipliers (18 × 18) | 40 | 56 | | 104 | | 128 | | | 176 |
| DSP blocks | 10 | 14 | | 26 | | 32 | | | 44 |
| PLLs | 4 | 4 | | 4 | 4, 8 | 4 | | 8 | 8 |
| Maximum user I/O pins | 230, 341 | 230 | 341 | 229 | 350, 514 | 229 | 350 | 514 | 538 |

Arria GX devices are available in space-saving FBGA packages (refer to [Table 1–2](#)). All Arria GX devices support vertical migration within the same package. With vertical migration support, designers can migrate to devices whose dedicated pins, configuration pins, and power pins are the same for a given package across device densities. For I/O pin migration

across densities, the designer must cross-reference the available I/O pins using the device pin-outs for all planned densities of a given package type to identify which I/O pins are migratable.

Table 1–2. Arria GX Package Options (Pin Counts and Transceiver Channels)

| Device | Transceiver Channels | Source-Synchronous Channels | | Maximum User I/O Pin Count | | |
|-----------|----------------------|-----------------------------|----------|----------------------------|----------------------|-----------------------|
| | | Receive | Transmit | 484-Pin FBGA (23 mm) | 780-Pin FBGA (29 mm) | 1152-Pin FBGA (35 mm) |
| EP1AGX20C | 4 | 31 | 29 | 230 | 341 | — |
| EP1AGX35C | 4 | 31 | 29 | 230 | — | — |
| EP1AGX50C | 4 | 31 | 29 | 229 | — | — |
| EP1AGX60C | 4 | 31 | 29 | 229 | — | — |
| EP1AGX35D | 8 | 31 | 29 | — | 341 | — |
| EP1AGX50D | 8 | 31, 42 | 29, 42 | — | 350 | 514 |
| EP1AGX60D | 8 | 31 | 29 | — | 350 | — |
| EP1AGX60E | 12 | 42 | 42 | — | — | 514 |
| EP1AGX90E | 12 | 47 | 45 | — | — | 538 |

Table 1–3 lists the Arria GX device package sizes.

Table 1–3. Arria GX FBGA Package Sizes

| Dimension | 484 Pins | 780 Pins | 1152 Pins |
|--------------------------|----------|----------|-----------|
| Pitch (mm) | 1.00 | 1.00 | 1.00 |
| Area (mm ²) | 529 | 841 | 1225 |
| Length × width (mm × mm) | 23 × 23 | 29 × 29 | 35 × 35 |

Document Revision History

Table 1–4 shows the revision history for this chapter.

| Date and Document Version | Changes Made | Summary of Changes |
|----------------------------------|--|---------------------------|
| May 2008, v1.2 | Included support for SDI, SerialLite II, and XAUI. | — |
| June 2007, v1.1 | Included GIGE information. | — |
| May 2007, v1.0 | Initial Release | — |

Transceivers

Arria™ GX devices incorporate up to 12 high-speed serial transceiver channels that build on the success of the Stratix® II GX device family. Arria GX transceivers are structured into full-duplex (transmitter and receiver) four-channel groups called transceiver blocks located on the right side of the device. The transceiver blocks can be configured to support the following serial connectivity protocols (functional modes):

- PCI Express (PIPE)
- Gigabit Ethernet (GIGE)
- XAUI
- Basic (600 Mbps to 3.125 Gbps)
- SDI (HD, 3G)
- Serial RapidIO (1.25 Gbps, 2.5 Gbps, 3.125 Gbps)

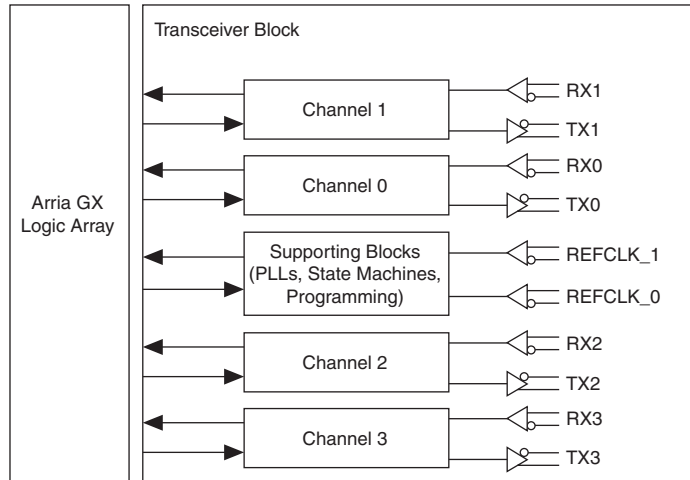
Transceivers within each block are independent and have their own set of dividers. Therefore, each transceiver can operate at different frequencies. Each block can select from two reference clocks to provide two clock domains that each transceiver can select from.

Table 2–1 shows the number of transceiver channels for each member of the Arria GX family.

| <i>Table 2–1. Arria GX Transceiver Channels</i> | |
|---|---------------------------------------|
| Device | Number of Transceiver Channels |
| EP1AGX20C | 4 |
| EP1AGX35C | 4 |
| EP1AGX35D | 8 |
| EP1AGX50C | 4 |
| EP1AGX50D | 8 |
| EP1AGX60C | 4 |
| EP1AGX60D | 8 |
| EP1AGX60E | 12 |
| EP1AGX90E | 12 |

Figure 2–1 shows a high-level diagram of the transceiver block architecture divided into four channels.

Figure 2–1. Transceiver Block

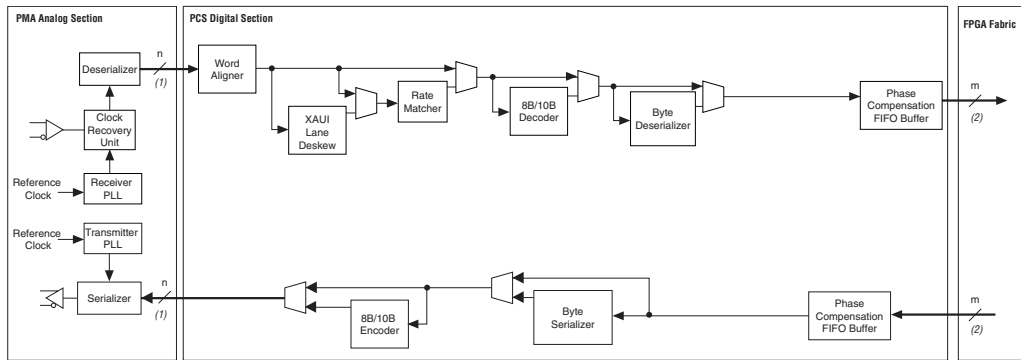


Each transceiver block has:

- Four transceiver channels with dedicated physical coding sublayer (PCS) and physical media attachment (PMA) circuitry
- One transmitter PLL that takes in a reference clock and generates high-speed serial clock depending on the functional mode
- Four receiver PLLs and clock recovery unit (CRU) to recover clock and data from the received serial data stream
- State machines and other logic to implement special features required to support each protocol

Figure 2–2 shows functional blocks that make up a transceiver channel.

Figure 2–2. Arria GX Transceiver Channel Block Diagram



Notes to Figure 2–2:

- (1) “n” represents the number of bits in each word that must be serialized by the transmitter portion of the PMA. n = 8 or 10.
- (2) “m” represents the number of bits in the word that passes between the FPGA logic and the PCS portion of the transceiver. m = 8, 10, 16, or 20.

Each transceiver channel is full-duplex and consists of a transmitter channel and a receiver channel.

The transmitter channel contains the following sub-blocks:

- Transmitter phase compensation first-in first-out (FIFO) buffer
- Byte serializer (optional)
- 8B/10B encoder (optional)
- Serializer (parallel-to-serial converter)
- Transmitter differential output buffer

The receiver channel contains the following:

- Receiver differential input buffer
- Receiver lock detector and run length checker
- Clock recovery unit (CRU)
- Deserializer
- Pattern detector
- Word aligner
- Lane deskew
- Rate matcher (optional)
- 8B/10B decoder (optional)
- Byte deserializer (optional)
- Receiver phase compensation FIFO buffer

You can configure the transceiver channels to the desired functional modes using the ALT2GXB MegaCore instance in the Quartus® II MegaWizard® Plug-in Manager for the Arria GX device family. Depending on the selected functional mode, the Quartus II software automatically configures the transceiver channels to employ a subset of the sub-blocks listed above.

Transmitter Path

This section describes the data path through the Arria GX transmitter. The sub-blocks are described in order from the PLD-transmitter parallel interface to the serial transmitter buffer.

Clock Multiplier Unit

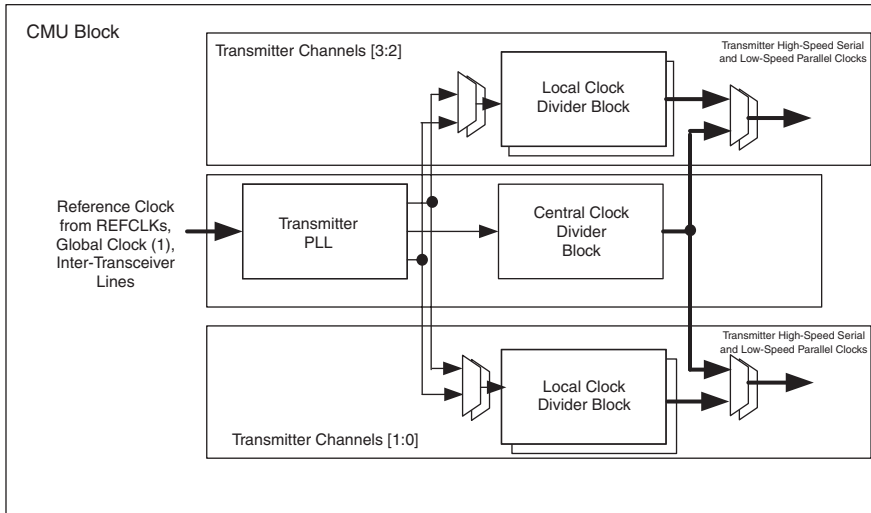
Each transceiver block has a clock multiplier unit (CMU) that takes in a reference clock and synthesizes two clocks: a high-speed serial clock to serialize the data and a low-speed parallel clock to clock the transmitter digital logic (PCS).

The CMU is further divided into three sub-blocks:

- One transmitter PLL
- One central clock divider block
- Four local clock divider blocks (one per channel)

Figure 2–3 shows the block diagram of the clock multiplier unit.

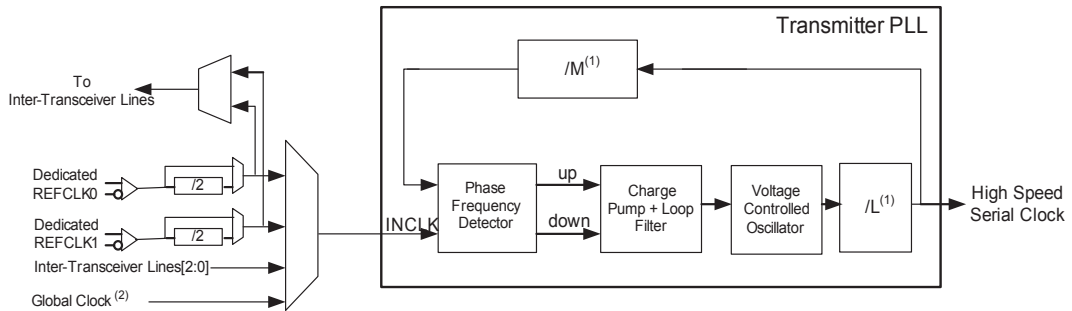
Figure 2–3. Clock Multiplier Unit



The transmitter PLL multiplies the input reference clock to generate the high-speed serial clock required to support the intended protocol. It implements a half-rate voltage controlled oscillator (VCO) that generates a clock at half the frequency of the serial data rate for which it is configured.

Figure 2-4 shows the block diagram of the transmitter PLL.

Figure 2-4. Transmitter PLL



Notes to Figure 2-4:

- (1) You only need to select the protocol and the available input reference clock frequency in the ALTGX MegaWizard Plug-In Manager. Based on your selections, the MegaWizard Plug-In Manager automatically selects the necessary /M and /L dividers (clock multiplication factors).
- (2) The global clock line must be driven from an input pin only.

The reference clock input to the transmitter PLL can be derived from:

- One of two available dedicated reference clock input pins (REFCLK0 or REFCLK1) of the associated transceiver block
- PLD global clock network (must be driven directly from an input clock pin and cannot be driven by user logic or enhanced PLL)
- Inter-transceiver block lines driven by reference clock input pins of other transceiver blocks



Altera® recommends using the dedicated reference clock input pins (REFCLK0 or REFCLK1) to provide reference clock for the transmitter PLL.

Table 2-2 lists the adjustable parameters in the transmitter PLL.

| Table 2-2. Transmitter PLL Specifications | |
|--|------------------------|
| Parameter | Specifications |
| Input reference frequency range | 50 MHz to 622.08 MHz |
| Data rate support | 600 Mbps to 3.125 Gbps |
| Bandwidth | Low, medium, or high |

The transmitter PLL output feeds the central clock divider block and the local clock divider blocks. These clock divider blocks divide the high-speed serial clock to generate the low-speed parallel clock for the transceiver PCS logic and PLD-transceiver interface clock.

Transmitter Phase Compensation FIFO Buffer

A transmitter phase compensation FIFO is located at each transmitter channel’s logic array interface. It compensates for the phase difference between the transmitter PCS clock and the local PLD clock. The transmitter phase compensation FIFO is used in all supported functional modes. The transmitter phase compensation FIFO buffer is eight words deep in PCI Express (PIPE) mode and four words deep in all other modes.



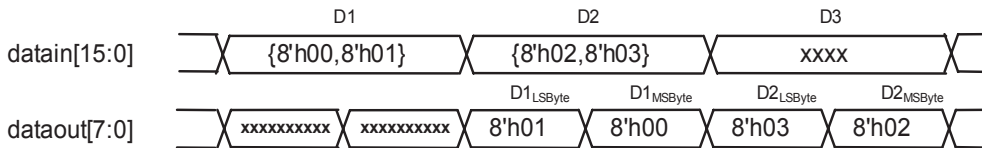
For more details about architecture and clocking, refer to the *Arria GX Transceiver Architecture* chapter in volume 2 of the *Arria GX Device Handbook*.

Byte Serializer

The byte serializer takes in two-byte wide data from the transmitter phase compensation FIFO buffer and serializes it into a one-byte wide data at twice the speed. The transmit data path after the byte serializer is 8 or 10 bits. This allows clocking the PLD-transceiver interface at half the speed as compared to the transmitter PCS logic. The byte serializer is bypassed in GIGE mode. After serialization, the byte serializer transmits the least significant byte (LSByte) first and the most significant byte (MSByte) last.

Figure 2–5 shows byte serializer input and output. `datain [15 : 0]` is the input to the byte serializer from the transmitter phase compensation FIFO; `dataout [7 : 0]` is the output of the byte serializer.

Figure 2–5. Byte Serializer Operation Note (1)



Note to Figure 2–5:

(1) `datain` may be 16 or 20 bits. `dataout` may be 8 or 10 bits.

8B/10B Encoder

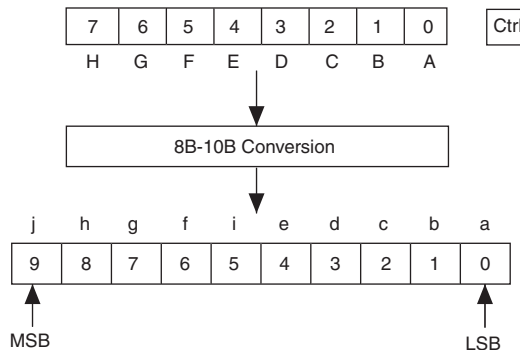
The 8B/10B encoder block is used in all supported functional modes. The 8B/10B encoder block takes in 8-bit data from the byte serializer or the transmitter phase compensation FIFO buffer. It generates a 10-bit code group with proper running disparity from the 8-bit character and a 1-bit control identifier (`tx_ctrlenable`). When `tx_ctrlenable` is low, the 8-bit character is encoded as data code group ($Dx.y$). When `tx_ctrlenable` is high, the 8-bit character is encoded as a control code group ($Kx.y$). The 10-bit code group is fed to the serializer. The 8B/10B encoder conforms to the IEEE 802.3 1998 edition standard.

Figure 2–6 shows the 8B/10B conversion format.



For additional information regarding 8B/10B encoding rules, refer to the *Specifications and Additional Information* chapter in volume 2 of the *Arria GX Device Handbook*.

Figure 2–6. 8B/10B Encoder



During reset (`tx_digitalreset`), the running disparity and data registers are cleared and the 8B/10B encoder outputs a K28.5 pattern from the RD- column continuously. Once out of reset, the 8B/10B encoder starts with a negative disparity (RD-) and transmits three K28.5 code groups for synchronizing before it starts encoding the input data or control character.

Transmit State Machine

The transmit state machine operates in either PCI Express (PIPE) mode, XAUI mode, or GIGE mode, depending on the protocol used.

GIGE Mode

In GIGE mode, the transmit state machine converts all idle ordered sets (/K28.5/, /Dx.y/) to either /I1/ or /I2/ ordered sets. The /I1/ set consists of a negative-ending disparity /K28.5/ (denoted by /K28.5/-), followed by a neutral /D5.6/. The /I2/ set consists of a positive-ending disparity /K28.5/ (denoted by /K28.5/+) and a negative-ending disparity /D16.2/ (denoted by /D16.2/-). The transmit state machines do not convert any of the ordered sets to match /C1/ or /C2/, which are the configuration ordered sets. (/C1/ and /C2/ are defined by [/K28.5/, /D21.5/] and [/K28.5/, /D2.2/], respectively). Both the /I1/ and /I2/ ordered sets guarantee a negative-ending disparity after each ordered set.

XAUI Mode

The transmit state machine translates the XAUI XGMII code group to the XAUI PCS code group. Table 2-3 shows the code conversion.

| XGMII TXC | XGMII TXD | PCS Code-Group | Description |
|-----------|-------------------------------------|-------------------------------------|-------------------------|
| 0 | 00 through FF | Dxx.y | Normal data |
| 1 | 07 | K28.0 or K28.3 or K28.5 | Idle in |
| 1 | 07 | K28.5 | Idle in T |
| 1 | 9C | K28.4 | Sequence |
| 1 | FB | K27.7 | Start |
| 1 | FD | K29.7 | Terminate |
| 1 | FE | K30.7 | Error |
| 1 | See IEEE 802.3 reserved code groups | See IEEE 802.3 reserved code groups | Reserved code groups |
| 1 | Other value | K30.7 | Invalid XGMII character |

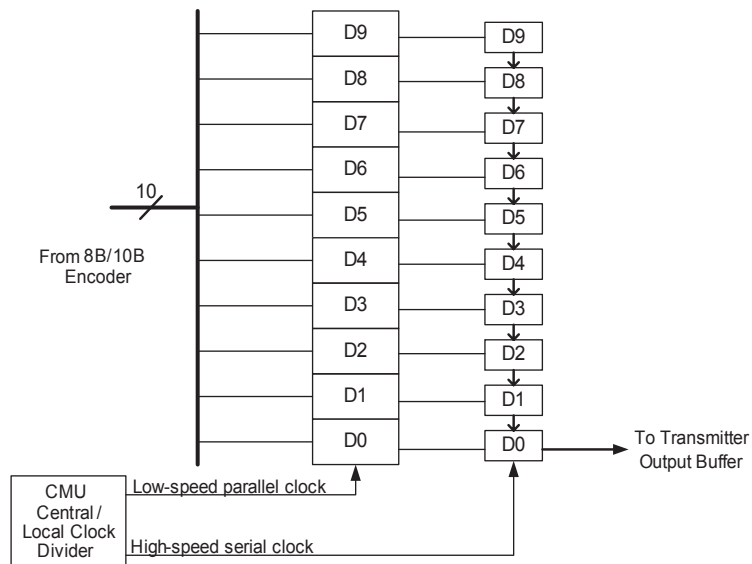
The XAUI PCS idle code groups, /K28.0/ (/R/) and /K28.5/ (/K/), are automatically randomized based on a PRBS7 pattern with an $\times 7 + \times 6 + 1$ polynomial. The /K28.3/ (/A/) code group is automatically generated between 16 and 31 idle code groups. The idle randomization on the /A/, /K/, and /R/ code groups is done automatically by the transmit state machine.

Serializer (Parallel-to-Serial Converter)

The serializer block clocks in 8- or 10-bit encoded data from the 8B/10B encoder using the low-speed parallel clock and clocks out serial data using the high-speed serial clock from the central or local clock divider blocks. The serializer feeds the data LSB to MSB to the transmitter output buffer.

Figure 2-7 shows the serializer block diagram.

Figure 2-7. Serializer



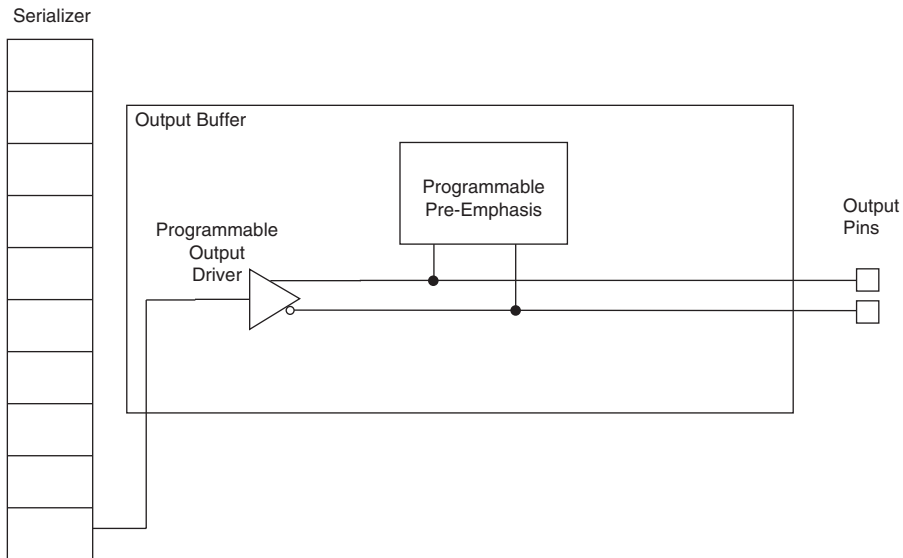
Transmitter Buffer

The Arria GX transceiver buffers support the 1.2- and 1.5-V PCML I/O standard at rates up to 3.125 Gbps. The common mode voltage (V_{CM}) of the output driver may be set to 600 or 700 mV.



Refer to the *Arria GX Transceiver Architecture* chapter in volume 2 of the *Arria GX Device Handbook*.

The output buffer, as shown in Figure 2-8, is directly driven by the high-speed data serializer and consists of a programmable output driver, a programmable pre-emphasis circuit, and OCT circuitry.

Figure 2–8. Output Buffer

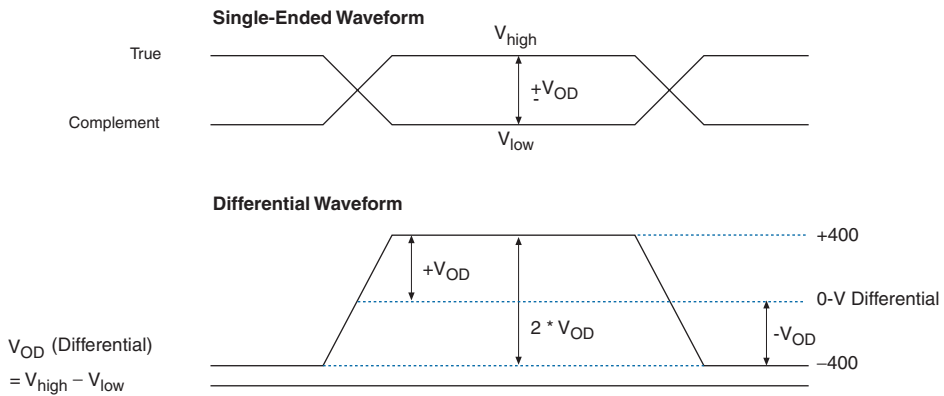
Programmable Output Driver

The programmable output driver can be set to drive out differentially 400 to 1200 mV. The differential output voltage (V_{OD}) can be statically set by using the ALTGXB megafunction.

The output driver may be configured using 100 Ω on-chip termination or external termination.

Differential signaling conventions are shown in [Figure 2–9](#). The differential amplitude represents the value of the voltage between the true and complement signals. Peak-to-peak differential voltage is defined as $2(V_{HIGH} - V_{LOW}) = 2$ single-ended voltage swing. The common mode voltage is the average of V_{HIGH} and V_{LOW} .

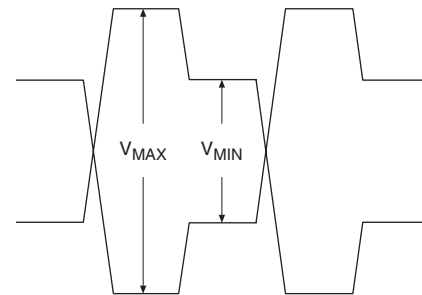
Figure 2–9. Differential Signaling



Programmable Pre-Emphasis

The programmable pre-emphasis module controls the output driver to boost high frequency components and compensate for losses in the transmission medium, as shown in Figure 2–10. Pre-emphasis is set statically using the ALTGXB megafunction.

Figure 2–10. Pre-Emphasis Signaling



$$\text{Pre-Emphasis \%} = \left(\frac{V_{MAX}}{V_{MIN}} - 1 \right) \times 100$$

Pre-emphasis percentage is defined as $(V_{MAX}/V_{MIN} - 1) \times 100$, where V_{MAX} is the differential emphasized voltage (peak-to-peak) and V_{MIN} is the differential steady-state voltage (peak-to-peak).

PCI Express (PIPE) Receiver Detect

The Arria GX transmitter buffer has a built-in receiver detection circuit for use in PCI Express (PIPE) mode. This circuit provides the ability to detect if there is a receiver downstream by sending out a pulse on the channel and monitoring the reflection. This mode requires a tri-stated transmitter buffer (in electrical idle mode).

PCI Express (PIPE) Electric Idles (or Individual Transmitter Tri-State)

The Arria GX transmitter buffer supports PCI Express (PIPE) electrical idles. This feature is only active in PCI Express (PIPE) mode. The `tx_forceelectricidle` port puts the transmitter buffer in electrical idle mode. This port is available in all PCI Express (PIPE) power-down modes and has specific usage in each mode.

Receiver Path

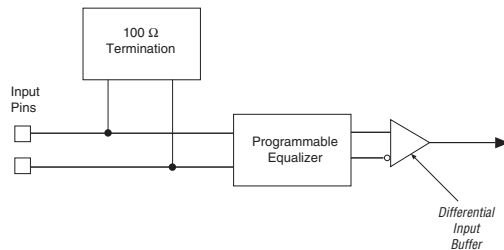
This section describes the data path through the Arria GX receiver. The sub-blocks are described in order from the receiver buffer to the PLD-receiver parallel interface.

Receiver Buffer

The Arria GX receiver input buffer supports the 1.2 V and 1.5 V PCML I/O standard at rates up to 3.125 Gbps. The common mode voltage of the receiver input buffer is programmable between 0.85 V and 1.2 V. You must select the 0.85 V common mode voltage for AC- and DC-coupled PCML links and 1.2 V common mode voltage for DC-coupled LVDS links.

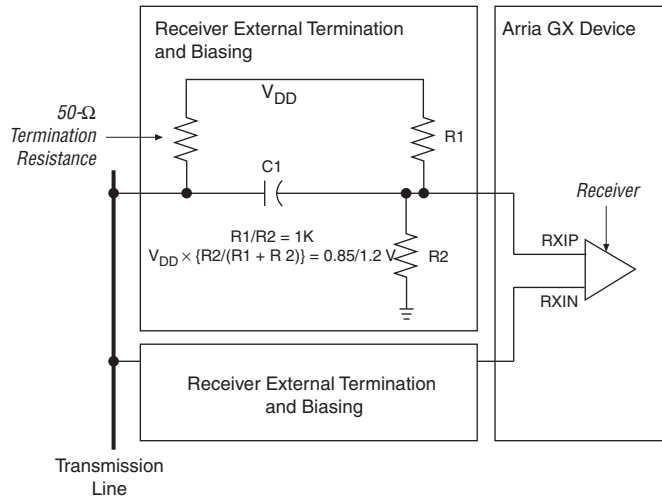
The receiver has on-chip $100\ \Omega$ differential termination for different protocols, as shown in [Figure 2–11](#). The receiver's internal termination can be disabled if external terminations and biasing are provided. The receiver and transmitter differential termination method can be set independently of each other.

Figure 2–11. Receiver Input Buffer



If a design uses external termination, the receiver must be externally terminated and biased to 0.85 V or 1.2 V. Figure 2–12 shows an example of an external termination and biasing circuit.

Figure 2–12. External Termination and Biasing Circuit



Programmable Equalizer

The Arria GX receivers provide a programmable receiver equalization feature to compensate for the effects of channel attenuation for high-speed signaling. PCB traces carrying these high-speed signals have low-pass filter characteristics. Impedance mismatch boundaries can also cause signal degradation. Equalization in the receiver diminishes the loss attenuation effects of the PCB at high frequencies.

The receiver equalization circuit is comprised of a programmable amplifier. Each stage is a peaking equalizer with a different center frequency and programmable gain. This allows varying amounts of gain to be applied, depending on the overall frequency response of the channel loss. Channel loss is defined as the summation of all losses through the PCB traces, vias, connectors, and cables present in the physical link. The Quartus II software allows five equalization settings for Arria GX devices.

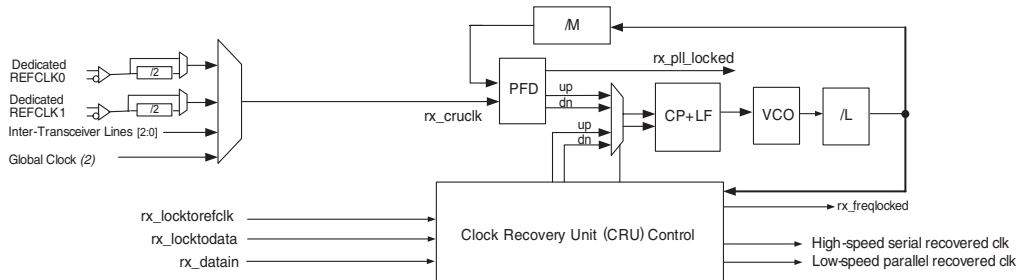
Receiver PLL and Clock Recovery Unit (CRU)

Each transceiver block has four receiver PLLs and CRU units, each of which is dedicated to a receiver channel. The receiver PLL is fed by an input reference clock. The receiver PLL, in conjunction with the CRU,

generates two clocks: a high-speed serial recovered clock that clocks the deserializer and a low-speed parallel recovered clock that clocks the receiver's digital logic.

Figure 2–13 shows a block diagram of the receiver PLL and CRU circuits.

Figure 2–13. Receiver PLL and Clock Recovery Unit



Notes to Figure 2–13:

- (1) You only need to select the protocol and the available input reference clock frequency in the ALTGX MegaWizard Plug-In Manager. Based on your selections, the ALTGX MegaWizard Plug-In Manager automatically selects the necessary /M and /L dividers.
- (2) The global clock line must be driven from an input pin only.

The reference clock input to the receiver PLL can be derived from:

- One of the two available dedicated reference clock input pins (REFCLK0 or REFCLK1) of the associated transceiver block
- PLD global clock network (must be driven directly from an input clock pin and cannot be driven by user logic or enhanced PLL)
- Inter-transceiver block lines driven by reference clock input pins of other transceiver blocks

All the parameters listed are programmable in the Quartus II software. The receiver PLL has the following features:

- Operates from 600 Mbps to 3.125 Gbps.
- Uses a reference clock between 50 MHz and 622.08 MHz.
- Programmable bandwidth settings: low, medium, and high.
- Programmable `rx_locktorefclk` (forces the receiver PLL to lock to reference clock) and `rx_locktodata` (forces the receiver PLL to lock to data).
- The voltage-controlled oscillator (V_{CO}) operates at half rate.
- Programmable frequency multiplication W of 1, 4, 5, 8, 10, 16, 20, and 25. Not all settings are supported for any particular frequency.
- Two lock indication signals are provided. They are found in PFD mode (lock-to-reference clock), and PD (lock-to-data).

The clock recovery unit controls whether the receiver PLL locks to the input reference clock (lock-to-reference mode) or the incoming serial data (lock-to data mode). You can set the CRU to switch between lock-to-data and lock-to-reference modes automatically or manually. In automatic lock mode, the phase detector and dedicated parts per million (PPM) detector within each receiver channel control the switch between lock-to-data and lock-to-reference modes based on some pre-set conditions. In manual lock mode, you control the switch manually using the `rx_locktorefclk` and `rx_locktodata` signals.



For more details, refer to the Clock Recovery Unit section in the *Arria GX Transceiver Protocol Support and Additional Features* chapter in volume 2 of the *Arria GX Device Handbook*.

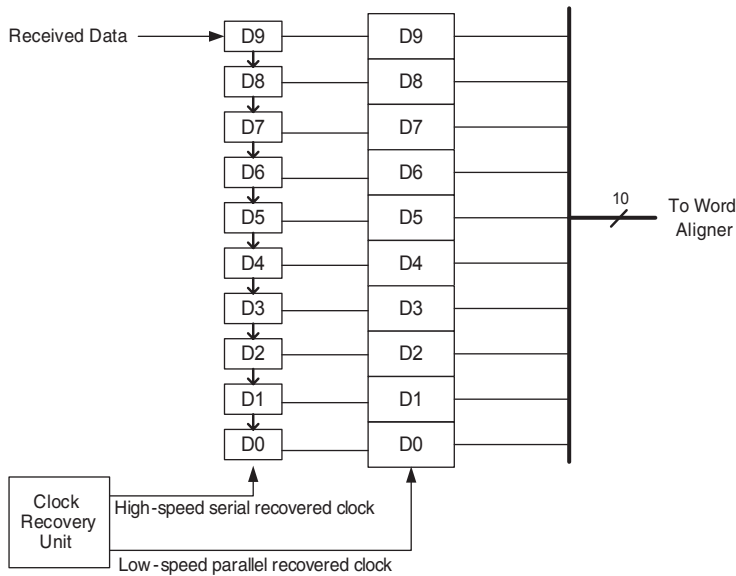
Table 2–4 show the behavior of THE CRU block with respect to the `rx_locktorefclk` and `rx_locktodata` signals.

| <code>rx_locktorefclk</code> | <code>rx_locktodata</code> | CRU Mode |
|------------------------------|----------------------------|-------------------------|
| 1 | 0 | Lock-to-reference clock |
| x | 1 | Lock-to-data |
| 0 | 0 | Automatic |

If the `rx_locktorefclk` and `rx_locktodata` ports are not used, the default is automatic lock mode.

Deserializer

The deserializer block clocks in serial input data from the receiver buffer using the high-speed serial recovered clock and deserializes into 8- or 10-bit parallel data using the low-speed parallel recovered clock. The serial data is assumed to be received with LSB first, followed by MSB. It feeds the deserialized 8- or 10-bit data to the word aligner, as shown in Figure 2–14.

Figure 2–14. Deserializer Note (1)**Note to Figure 2–14:**

(1) This is a 10-bit deserializer. The deserializer can also convert 8 bits of data.

Word Aligner

The deserializer block creates 8- or 10-bit parallel data. The deserializer ignores protocol symbol boundaries when converting this data. Therefore, the boundaries of the transferred words are arbitrary. The word aligner aligns the incoming data based on specific byte or word boundaries. The word alignment module is clocked by the local receiver recovered clock during normal operation. All the data and programmed patterns are defined as “big-endian” (most significant word followed by least significant word). Most-significant-bit-first protocols should reverse the bit order of word align patterns programmed.

This module detects word boundaries for 8B/10B-based protocols. This module is also used to align to specific programmable patterns in PRBS7/23 test mode.

Pattern Detection

The programmable pattern detection logic can be programmed to align word boundaries using a single 7- or 10-bit pattern. The pattern detector can either do an exact match, or match the exact pattern and the

complement of a given pattern. Once the programmed pattern is found, the data stream is aligned to have the pattern on the LSB portion of the data output bus.

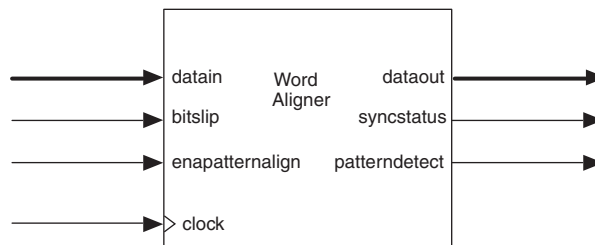
XAUI, GIGE, PCI Express (PIPE), and Serial RapidIO standards have embedded state machines for symbol boundary synchronization. These standards use K28.5 as their 10-bit programmed comma pattern. Each of these standards uses different algorithms before signaling symbol boundary acquisition to the FPGA.

pattern detection logic searches from the LSB to the most significant bit (MSB). If multiple patterns are found within the search window, the pattern in the lower portion of the data stream (corresponding to the pattern received earlier) is aligned and the rest of the matching patterns are ignored.

Once a pattern is detected and the data bus is aligned, the word boundary is locked. The two detection status signals (`rx_syncstatus` and `rx_patterndetect`) indicate that an alignment is complete.

Figure 2-15 is a block diagram of the word aligner.

Figure 2-15. Word Aligner



Control and Status Signals

The `rx_enapatternalign` signal is the FPGA control signal that enables word alignment in non-automatic modes. The `rx_enapatternalign` signal is not used in automatic modes (PCI Express [PIPE], XAUI, GIGE, and Serial RapidIO).

In manual alignment mode, after the `rx_enapatternalign` signal is activated, the `rx_syncstatus` signal goes high for one parallel clock cycle to indicate that the alignment pattern has been detected and the word boundary has been locked. If `rx_enapatternalign` is

deactivated, the `rx_syncstatus` signal acts as a re-synchronization signal to signify that the alignment pattern has been detected but not locked on a different word boundary.

When using the synchronization state machine, the `rx_syncstatus` signal indicates the link status. If the `rx_syncstatus` signal is high, link synchronization is achieved. If the `rx_syncstatus` signal is low, link synchronization has not yet been achieved, or there were enough code group errors to lose synchronization.



For more information about manual alignment modes, refer to the *Arria GX Device Handbook*.

The `rx_patterndetect` signal pulses high during a new alignment and whenever the alignment pattern occurs on the current word boundary.

Programmable Run Length Violation

The word aligner supports a programmable run length violation counter. Whenever the number of the continuous '0' (or '1') exceeds a user programmable value, the `rx_rlv` signal goes high for a minimum pulse width of two recovered clock cycles. The maximum run values supported are 128 UI for 8-bit serialization or 160 UI for 10-bit serialization.

Running Disparity Check

The running disparity error `rx_disperr` and running disparity value `rx_runningdisp` are sent along with aligned data from the 8B/10B decoder to the FPGA. You can ignore or act on the reported running disparity value and running disparity error signals.

Bit-Slip Mode

The word aligner can operate in either pattern detection mode or in bit-slip mode.

The Bit-slip mode provides the option to manually shift the word boundary through the FPGA. This feature is useful for:

- Longer synchronization patterns than the pattern detector can accommodate
- Scrambled data stream
- Input stream consisting of over-sampled data

The word aligner outputs a word boundary as it is received from the analog receiver after reset. You can examine the word and search its boundary in the FPGA. To do so, assert the `rx_bitslip` signal. The `rx_bitslip` signal should be toggled and held constant for at least two FPGA clock cycles.

For every rising edge of the `rx_bitslip` signal, the current word boundary is slipped by one bit. Every time a bit is slipped, the bit received earliest is lost. If bit slipping shifts a complete round of bus width, the word boundary is back to the original boundary.

The `rx_syncstatus` signal is not available in bit-slipping mode.

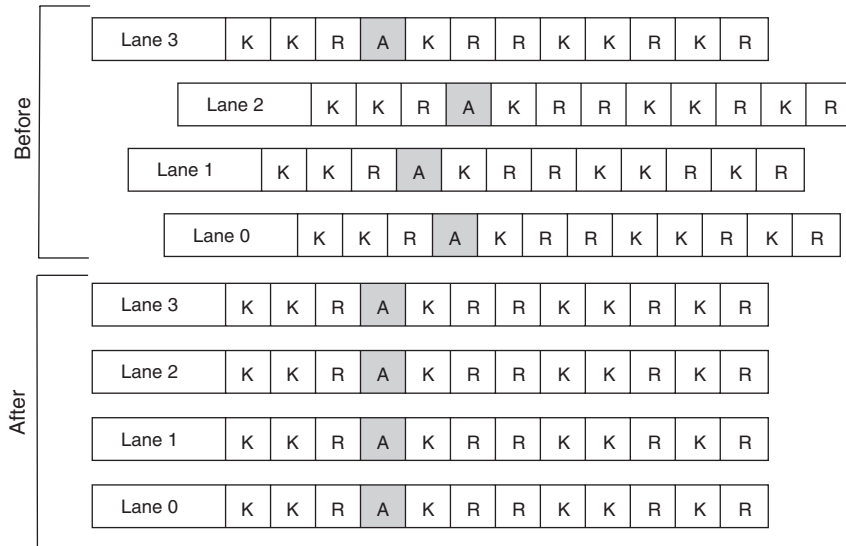
Channel Aligner

The channel aligner is available only in XAUI mode and aligns the signals of all four channels within a transceiver. The channel aligner follows the IEEE 802.3ae, clause 48 specification for channel bonding.

The channel aligner is a 16-word FIFO buffer with a state machine controlling the channel bonding process. The state machine looks for an /A/ (/K28.3/) in each channel and aligns all the /A/ code groups in the transceiver. When four columns of /A/ (denoted by //A//) are detected, the `rx_channelaligned` signal goes high, signifying that all the channels in the transceiver have been aligned. The reception of four consecutive misaligned /A/ code groups restarts the channel alignment sequence and sends the `rx_channelaligned` signal low.

Figure 2–16 shows misaligned channels before the channel aligner and the aligned channels after the channel aligner.

Figure 2–16. Before and After the Channel Aligner



Rate Matcher

In asynchronous systems, the upstream transmitter and local receiver may be clocked with independent reference clock sources. Frequency differences in the order of a few hundred PPM can potentially corrupt the data at the receiver.

The rate matcher compensates for small clock frequency differences between the upstream transmitter and the local receiver clocks by inserting or removing skip characters from the inter packet gap (IPG) or idle streams. It inserts a skip character if the local receiver is running a faster clock than the upstream transmitter. It deletes a skip character if the local receiver is running a slower clock than the upstream transmitter. The Quartus II software automatically configures the appropriate skip character as specified in the IEEE 802.3 for GIGE mode and PCI-Express Base Specification for PCI Express (PIPE) mode. The rate matcher is bypassed in Serial RapidIO and must be implemented in the PLD logic array or external circuits depending on your system design.

Table 2-5 shows the maximum frequency difference that the rate matcher can tolerate in XAUI, PCI Express (PIPE), GIGE, and Basic functional modes.

| Function Mode | PPM |
|----------------------|------------|
| XAUI | ± 100 |
| PCI Express (PIPE) | ± 300 |
| GIGE | ± 100 |
| Basic | ± 300 |

XAUI Mode

In XAUI mode, the rate matcher adheres to clause 48 of the IEEE 802.3ae specification for clock rate compensation. The rate matcher performs clock compensation on columns of $/R/$ ($/K28.0/$), denoted by $//R//$. An $//R//$ is added or deleted automatically based on the number of words in the FIFO buffer.

PCI Express (PIPE) Mode Rate Matcher

In PCI Express (PIPE) mode, the rate matcher can compensate up to ± 300 PPM (600 PPM total) frequency difference between the upstream transmitter and the receiver. The rate matcher logic looks for skip ordered sets (SOS), which contains a $/K28.5/$ comma followed by three $/K28.0/$ skip characters. The rate matcher logic deletes or inserts $/K28.0/$ skip characters as necessary from/to the rate matcher FIFO.

The rate matcher in PCI Express (PIPE) mode has a FIFO buffer overflow and underflow protection. In the event of a FIFO buffer overflow, the rate matcher deletes any data after detecting the overflow condition to prevent FIFO pointer corruption until the rate matcher is not full. In an underflow condition, the rate matcher inserts $9'h1FE$ ($/K30.7/$) until the FIFO buffer is not empty. These measures ensure that the FIFO buffer can gracefully exit the overflow and underflow condition without requiring a FIFO reset. The rate matcher FIFO overflow and underflow condition is indicated on the `pipestatus` port.

You can bypass the rate matcher in PCI Express (PIPE) mode if you have a synchronous system where the upstream transmitter and local receiver derive their reference clocks from the same source.

GIGE Mode Rate Matcher

In GIGE mode, the rate matcher can compensate up to ± 100 PPM (200 PPM total) frequency difference between the upstream transmitter and the receiver. The rate matcher logic inserts or deletes /I2/ idle ordered sets to/from the rate matcher FIFO during the inter-frame or inter-packet gap (IFG or IPG). /I2/ is selected as the rate matching ordered set since it maintains the running disparity, unlike /I1/ that alters the running disparity. Since the /I2/ ordered-set contains two 10-bit code groups (/K28.5/, /D16.2/), 20 bits are inserted or deleted at a time for rate matching.



The rate matcher logic has the capability to insert or delete /C1/ or /C2/ configuration ordered sets when 'GIGE Enhanced' mode is chosen as the sub-protocol in the MegaWizard Plug-In Manager.

If the frequency PPM difference between the upstream transmitter and the local receiver is high, or if the packet size is too large, the rate matcher FIFO buffer can face an overflow or underflow situation.

Basic Mode

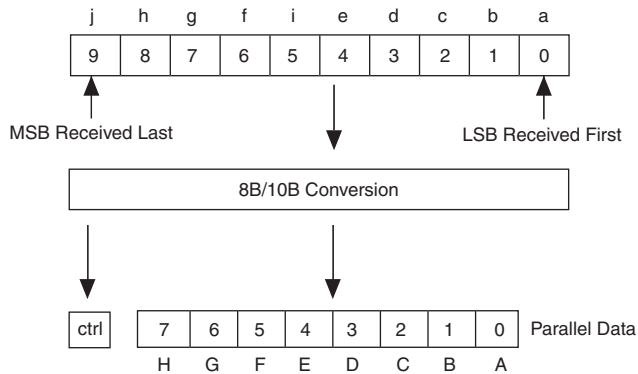
In Basic mode, you can program the skip and control pattern for rate matching. There is no restriction on the deletion of a skip character in a cluster. The rate matcher deletes the skip characters as long as they are available. For insertion, the rate matcher inserts skip characters such that the number of skip characters at the output of rate matcher does not exceed five.

8B/10B Decoder

The 8B/10B decoder is used in all supported functional modes. The 8B/10B decoder takes in 10-bit data from the rate matcher and decodes it into 8-bit data + 1-bit control identifier, thereby restoring the original transmitted data at the receiver. The 8B/10B decoder indicates whether the received 10-bit character is a data or control code through the `rx_ctrldetect` port. If the received 10-bit code group is a control character (Kx.y), the `rx_ctrldetect` signal is driven high and if it is a data character (Dx.y), the `rx_ctrldetect` signal is driven low.

Figure 2–17 shows a 10-bit code group decoded to an 8-bit data and a 1-bit control indicator.

Figure 2–17. 10-Bit to 8-Bit Conversion



If the received 10-bit code is not a part of valid $D_{x.y}$ or $K_{x.y}$ code groups, the 8B/10B decoder block asserts an error flag on the `rx_errdetect` port. If the received 10-bit code is detected with incorrect running disparity, the 8B/10B decoder block asserts an error flag on the `rx_disperr` and `rx_errdetect` ports. The error flag signals (`rx_errdetect` and `rx_disperr`) have the same data path delay from the 8B/10B decoder to the PLD-transceiver interface as the bad code group.

Receiver State Machine

The receiver state machine operates in Basic, GIGE, PCI Express (PIPE), and XAUI modes. In GIGE mode, the receiver state machine replaces invalid code groups with K30.7. In XAUI mode, the receiver state machine translates the XAUI PCS code group to the XAUI XGMII code group.

Byte Deserializer

Byte deserializer takes in one-byte wide data from the 8B/10B decoder and deserializes it into a two-byte wide data at half the speed. This allows clocking the PLD-receiver interface at half the speed as compared to the receiver PCS logic. The byte deserializer is bypassed in GIGE mode.

The byte ordering at the receiver output might be different than what was transmitted. This is a non-deterministic swap, because it depends on PLL lock times and link delay. If required, you must implement byte ordering logic in the PLD to correct this situation.



For more details, refer to the *Arria GX Transceiver Architecture* chapter in volume 2 of *Arria GX Device Handbook*.

Receiver Phase Compensation FIFO Buffer

A receiver phase compensation FIFO buffer is located at each receiver channel's logic array interface. It compensates for the phase difference between the receiver PCS clock and the local PLD receiver clock. The receiver phase compensation FIFO is used in all supported functional modes. The receiver phase compensation FIFO buffer is eight words deep in PCI Express (PIPE) mode and four words deep in all other modes.



For more details about architecture and clocking, refer to the *Arria GX Transceiver Architecture* chapter in volume 2 of *Arria GX Device Handbook*.

Loopback Modes

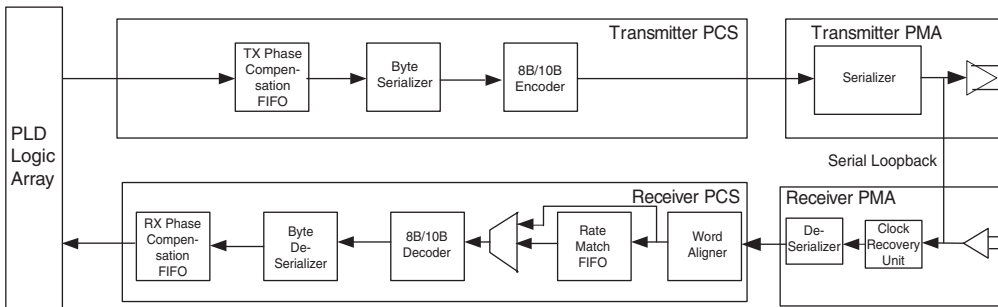
Arria GX transceivers support the following loopback configurations for diagnostic purposes:

- Serial loopback
- Reverse serial loopback
- Reverse serial loopback (pre-CDR)
- PCI Express (PIPE) reverse parallel loopback (available only in [PIPE] mode)

Serial Loopback

Figure 2–18 shows the transceiver data path in serial loopback.

Figure 2–18. Transceiver Data Path in Serial Loopback



In GIGE and Serial RapidIO modes, you can dynamically put each transceiver channel individually in serial loopback by controlling the `rx_serialpbken` port. A high on the `rx_serialpbken` port puts the transceiver into serial loopback and a low takes the transceiver out of serial loopback.

As seen in Figure 2–18, the serial data output from the transmitter serializer is looped back to the receiver CRU in serial loopback. The transmitter data path from the PLD interface to the serializer in serial loopback is the same as in non-loopback mode. The receiver data path from the clock recovery unit to the PLD interface in serial loopback is the same as in non-loopback mode. Since the entire transceiver data path is available in serial loopback, this option is often used to diagnose the data path as a probable cause of link errors.



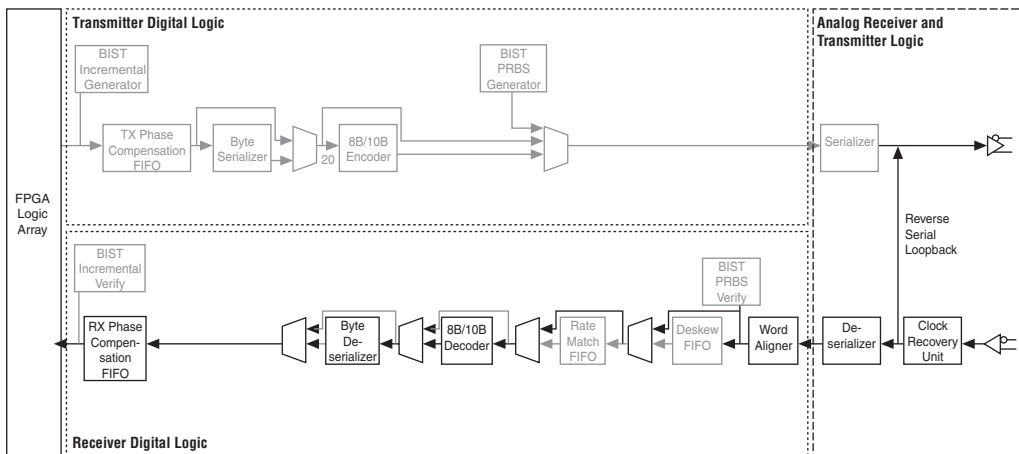
When serial loopback is enabled, the transmitter output buffer is still active and drives the serial data out on the `tx_dataout` port.

Reverse Serial Loopback

Reverse serial loopback mode uses the analog portion of the transceiver. An external source (pattern generator or transceiver) generates the source data. The high-speed serial source data arrives at the high-speed differential receiver input buffer, passes through the CRU unit and the retimed serial data is looped back, and is transmitted through the high-speed differential transmitter output buffer.

Figure 2–19 shows the data path in reverse serial loopback mode.

Figure 2–19. Arria GX Block in Reverse Serial Loopback Mode

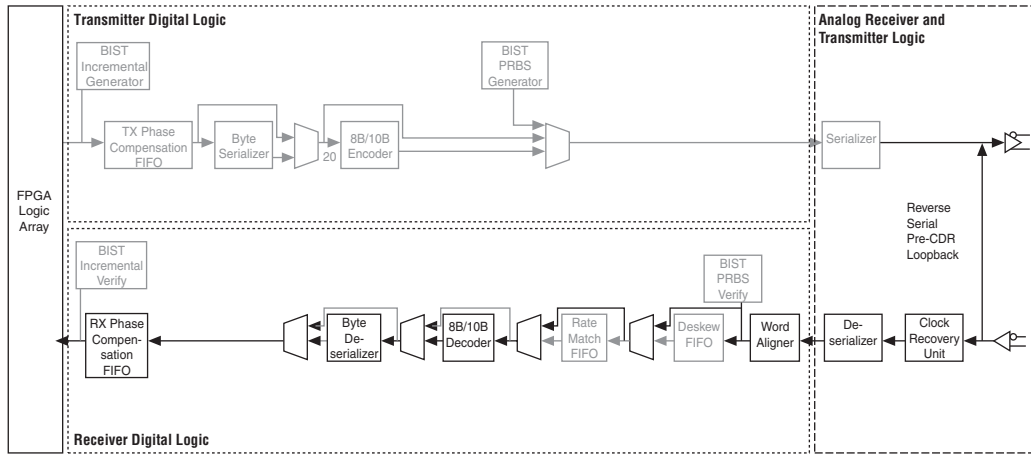


Reverse Serial Pre-CDR Loopback

Reverse serial pre-CDR loopback mode uses the analog portion of the transceiver. An external source (pattern generator or transceiver) generates the source data. The high-speed serial source data arrives at the high-speed differential receiver input buffer, loops back before the CRU unit, and is transmitted through the high-speed differential transmitter output buffer. It is for test or verification use only to verify the signal being received after the gain and equalization improvements of the input buffer. The signal at the output is not exactly what is received since the signal goes through the output buffer and the V_{OD} is changed to the V_{OD} setting level. Pre-emphasis settings have no effect.

Figure 2–20 show the Arria GX block in reverse serial pre-CDR loopback mode.

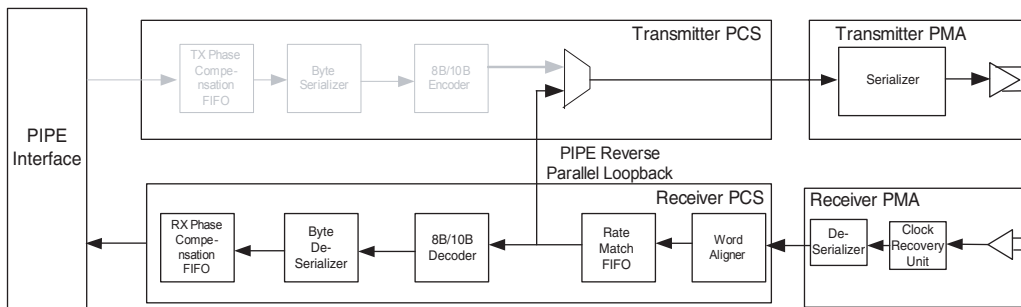
Figure 2–20. Arria GX Block in Reverse Serial Pre-CDR Loopback Mode



PCI Express (PIPE) Reverse Parallel Loopback

Figure 2–21 shows the data path for PCI Express (PIPE) reverse parallel loopback. The reverse parallel loopback configuration is compliant with the PCI Express (PIPE) specification and is available only on PCI Express (PIPE) mode.

Figure 2–21. PCI Express (PIPE) Reverse Parallel Loopback



You can dynamically put the PCI Express (PIPE) mode transceiver in reverse parallel loopback by controlling the tx_detectrxloopback port instantiated in the MegaWizard Plug-In Manager. A high on the

`tx_detectrxloopback` port in P0 power state puts the transceiver in reverse parallel loopback. A high on the `tx_detectrxloopback` port in any other power state does not put the transceiver in reverse parallel loopback.

As seen in [Figure 2–21](#), the serial data received on the `rx_datain` port in reverse parallel loopback goes through the CRU, deserializer, word aligner, and the rate matcher blocks. The parallel data at the output of the receiver rate matcher block is looped back to the input of the transmitter serializer block. The serializer converts the parallel data to serial data and feeds it to the transmitter output buffer that drives the data out on the `tx_dataout` port. The data at the output of the rate matcher also goes through the 8B/10B decoder, byte deserializer, and receiver phase compensation FIFO before being fed to the PLD on the `rx_dataout` port.

Reset and Powerdown

Arria GX transceivers offer a power saving advantage with their ability to shut off functions that are not needed.

The following three reset signals are available per transceiver channel and can be used to individually reset the digital and analog portions within each channel:

- `tx_digitalreset`
- `rx_analogreset`
- `rx_digitalreset`

The following two powerdown signals are available per transceiver block and can be used to shut down an entire transceiver block that is not being used:

- `gxb_powerdown`
- `gxb_enable`

Table 2–6 shows the reset signals available in Arria GX devices and the transceiver circuitry affected by each signal.

Table 2–6. Reset Signal Map to Arria GX Blocks

| Reset Signal | Transmitter Phase Compensation FIFO Module/ Byte Serializer | Transmitter 8B/10B Encoder | Transmitter Serializer | Transmitter Analog Circuits | Transmitter PLL | Transmitter XAUI State Machine | BIST Generators | Receiver Deserializer | Receiver Word Aligner | Receiver Deskew FIFO Module | Receiver Rate Matcher | Receiver 8B/10B Decoder | Receiver Phase Comp FIFO Module/ Byte Deserializer | Receiver PLL / CRU | Receiver XAUI State Machine | BIST Verifiers | Receiver Analog Circuits |
|-----------------|---|----------------------------|------------------------|-----------------------------|-----------------|--------------------------------|-----------------|-----------------------|-----------------------|-----------------------------|-----------------------|-------------------------|--|--------------------|-----------------------------|----------------|--------------------------|
| rx_digitalreset | | | | | | | | | ✓ | | ✓ | ✓ | ✓ | | ✓ | ✓ | |
| rx_analogreset | | | | | | | | ✓ | | | | | | ✓ | | | ✓ |
| tx_digitalreset | ✓ | ✓ | | | | ✓ | ✓ | | | | | | | | | | |
| gxb_powerdown | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| gxb_enable | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |

Calibration Block

Arria GX devices use the calibration block to calibrate on-chip termination for the PLLs and their associated output buffers and the terminating resistors on the transceivers. The calibration block counters the effects of process, voltage, and temperature (PVT). The calibration block references a derived voltage across an external reference resistor to calibrate the on-chip termination resistors on Arria GX devices. The calibration block can be powered down. However, powering down the calibration block during operations may yield transmit and receive data errors.

Transceiver Clocking

This section describes the clock distribution within an Arria GX transceiver channel and the PLD clock resource utilization by the transceiver blocks.

Transceiver Channel Clock Distribution

Each transceiver block has one transmitter PLL and four receiver PLLs.

The transmitter PLL multiplies the input reference clock to generate a high-speed serial clock at a frequency that is half the data rate of the configured functional mode. This high-speed serial clock (or its divide-by-two version if the functional mode uses byte serializer) is fed to the CMU clock divider block. Depending on the configured functional mode, the CMU clock divider block divides the high-speed serial clock to generate the low-speed parallel clock that clocks the transceiver PCS logic in the associated channel. The low-speed parallel clock is also forwarded to the PLD logic array on the `tx_clkout` or `coreclkout` ports.

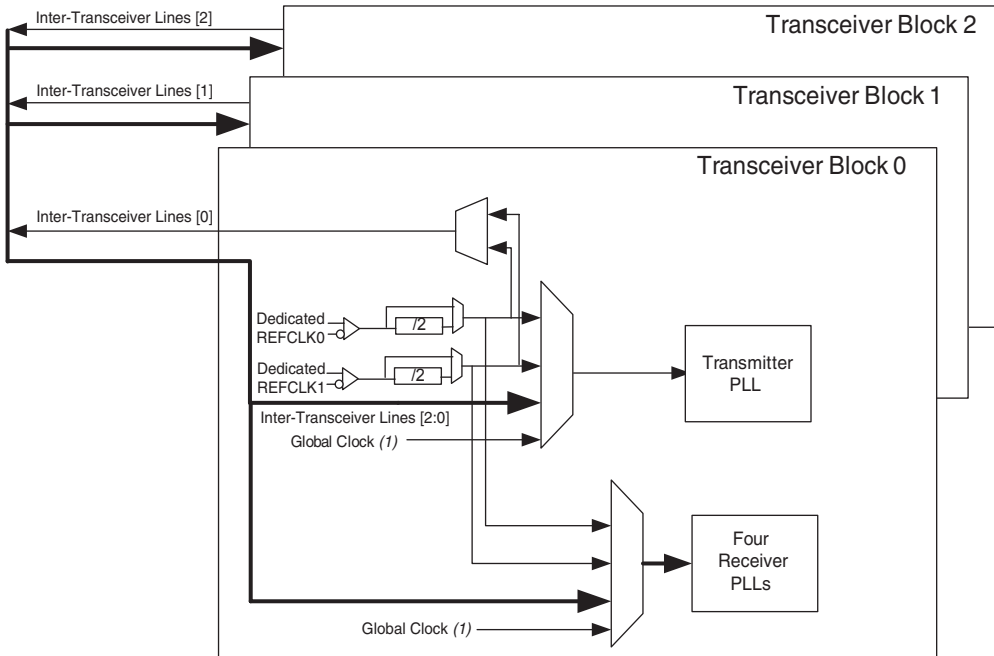
The receiver PLL in each channel is also fed by an input reference clock. The receiver PLL along with the clock recovery unit generates a high-speed serial recovered clock and a low-speed parallel recovered clock. The low-speed parallel recovered clock feeds the receiver PCS logic until the rate matcher. The CMU low-speed parallel clock clocks the rest of the logic from the rate matcher until the receiver phase compensation FIFO. In modes that do not use a rate matcher, the receiver PCS logic is clocked by the recovered clock until the receiver phase compensation FIFO.

The input reference clock to the transmitter and receiver PLLs can be derived from:

- One of two available dedicated reference clock input pins (`REFCLK0` or `REFCLK1`) of the associated transceiver block
- PLD clock network (must be driven directly from an input clock pin and cannot be driven by user logic or enhanced PLL)
- Inter-transceiver block lines driven by reference clock input pins of other transceiver blocks

Figure 2–22 shows the input reference clock sources for the transmitter and receiver PLL.

Figure 2–22. Input Reference Clock Sources



For detailed transceiver clocking in all supported functional modes, refer to the *Arria GX Transceiver Architecture* chapter in volume 2 of the *Arria GX Device Handbook*.

PLD Clock Utilization by Transceiver Blocks

Arria GX devices have up to 16 global clock (GCLK) lines and 16 regional clock (RCLK) lines that are used to route the transceiver clocks. The following transceiver clocks utilize the available global and regional clock resources:

- `p11_inclk` (if driven from an FPGA input pin)
- `rx_crucclk` (if driven from an FPGA input pin)
- `tx_clkout/coreclkout` (CMU low-speed parallel clock forwarded to the PLD)
- Recovered clock from each channel (`rx_clkout`) in non-rate matcher mode

- Calibration clock (`cal_blk_clk`)
- Fixed clock (`fixedclk` used for receiver detect circuitry in PCI Express [PIPE] mode only)

Figures 2–23 and 2–24 show the available global and regional clock resources in Arria GX devices.

Figure 2–23. Global Clock Resources in Arria GX Devices

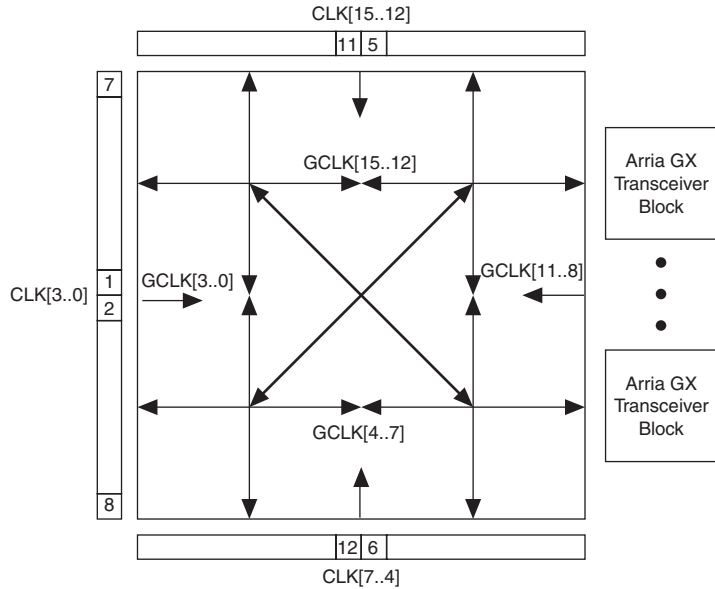
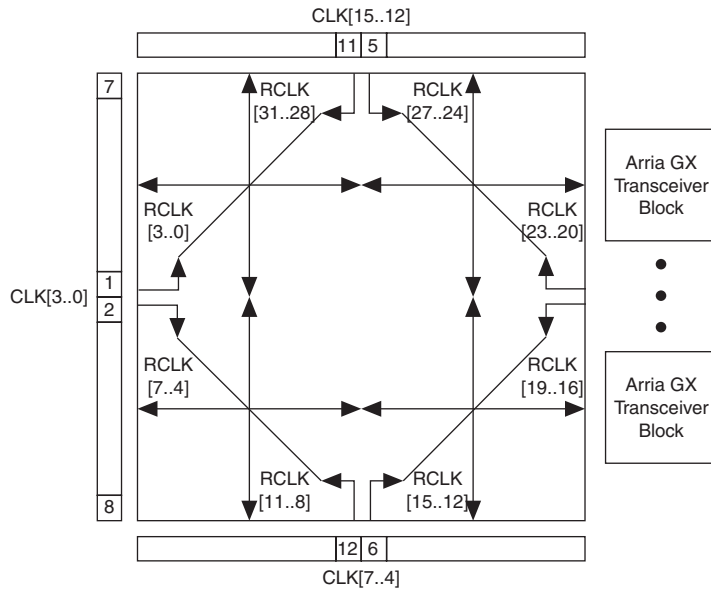


Figure 2–24. Regional Clock Resources in Arria GX Devices



For the regional or global clock network to route into the transceiver, a local route input output (LRIO) channel is required. Each LRIO clock region has up to eight clock paths and each transceiver block has a maximum of eight clock paths for connecting with LRIO clocks. These resources are limited and determine the number of clocks that can be used between the PLD and transceiver blocks. Tables 2–7 and 2–8 give the number of LRIO resources available for Arria GX devices with different number of transceiver blocks.

Table 2–7. Available Clocking Connections for Transceivers in EP1AGX35D, EP1AGX50D, and EP1AGX60D

| Source | Clock Resource | | Transceiver | |
|-------------------------|----------------|----------------|-----------------------|-----------------------|
| | Global Clock | Regional Clock | Bank13 8 Clock I/O | Bank14 8 Clock I/O |
| Region0 8 LRIO clock | ✓ | RCLK 20-27 | ✓ | |
| Region1 8 LRIO clock | ✓ | RCLK 12-19 | | ✓ |

Table 2–8. Available Clocking Connections for Transceivers in EP1AGX60E and EP1AGX90E

| Source | Clock Resource | | Transceiver | | |
|-------------------------|----------------|----------------|-----------------------|-----------------------|-----------------------|
| | Global Clock | Regional Clock | Bank13 8 Clock I/O | Bank14 8 Clock I/O | Bank15 8 Clock I/O |
| Region0 8 LRIO clock | ✓ | RCLK 20-27 | ✓ | | |
| Region1 8 LRIO clock | ✓ | RCLK 20-27 | ✓ | ✓ | |
| Region2 8 LRIO clock | ✓ | RCLK 12-19 | | ✓ | ✓ |
| Region3 8 LRIO clock | ✓ | RCLK 12-19 | | | ✓ |

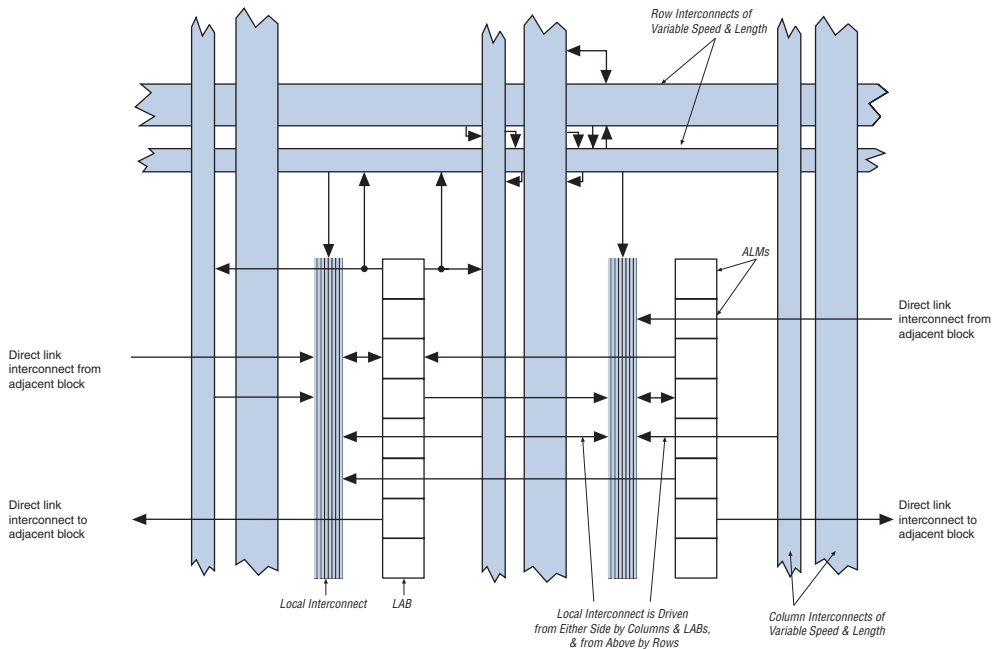
Logic Array Blocks

Each logic array block (LAB) consists of eight adaptive logic modules (ALMs), carry chains, shared arithmetic chains, LAB control signals, local interconnects, and register chain connection lines. The local interconnect transfers signals between ALMs in the same LAB. Register chain connections transfer the output of an ALM register to the adjacent ALM register in a LAB. The Quartus II Compiler places associated logic in a LAB or adjacent LABs, allowing the use of local, shared arithmetic chain, and register chain connections for performance and area efficiency. [Table 2–9](#) shows Arria GX device resources. [Figure 2–25](#) shows the Arria GX LAB structure.

Table 2–9. Arria GX Device Resources

| Device | M512 RAM Columns/Blocks | M4K RAM Columns/Blocks | M-RAM Blocks | DSP Block Columns/Blocks |
|----------|----------------------------|---------------------------|-----------------|-----------------------------|
| EP1AGX20 | 166 | 118 | 1 | 10 |
| EP1AGX35 | 197 | 140 | 1 | 14 |
| EP1AGX50 | 313 | 242 | 2 | 26 |
| EP1AGX60 | 326 | 252 | 2 | 32 |
| EP1AGX90 | 478 | 400 | 4 | 44 |

Figure 2–25. Arria GX LAB Structure

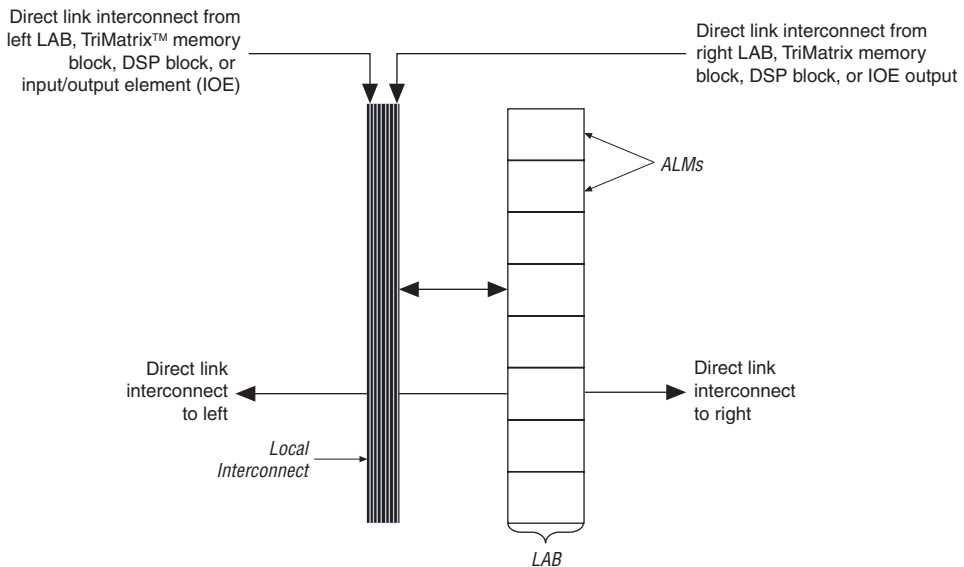


LAB Interconnects

The LAB local interconnect can drive all eight ALMs in the same LAB. It is driven by column and row interconnects and ALM outputs in the same LAB. Neighboring LABs, M512 RAM blocks, M4K RAM blocks, M-RAM blocks, or digital signal processing (DSP) blocks from the left and right can also drive a LAB's local interconnect through the direct link connection. The direct link connection feature minimizes the use of row and column interconnects, providing higher performance and flexibility. Each ALM can drive 24 ALMs through fast local and direct link interconnects.

Figure 2–26 shows the direct link connection.

Figure 2–26. Direct Link Connection



LAB Control Signals

Each LAB contains dedicated logic for driving control signals to its ALMs. The control signals include three clocks, three clock enables, two asynchronous clears, synchronous clear, asynchronous preset/load, and synchronous load control signals, providing a maximum of 11 control signals at a time. Although synchronous load and clear signals are generally used when implementing counters, they can also be used with other functions.

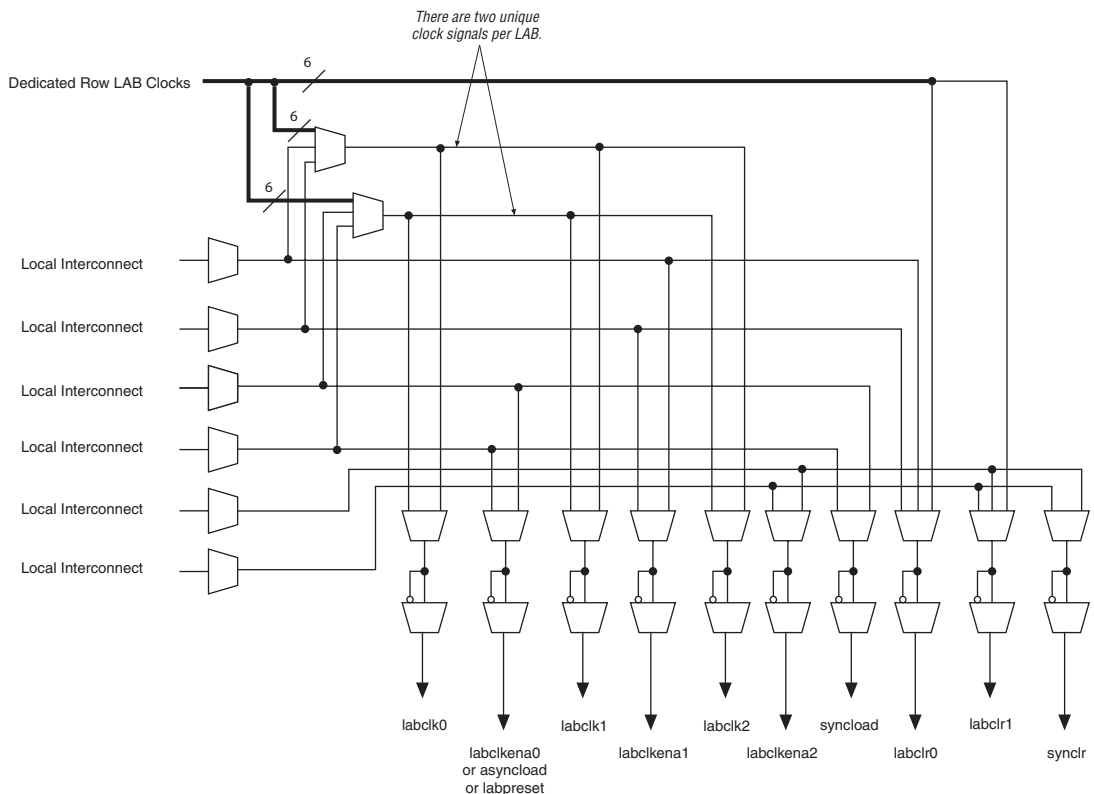
Each LAB can use three clocks and three clock enable signals. However, there can only be up to two unique clocks per LAB, as shown in the LAB control signal generation circuit in Figure 2–27. Each LAB's clock and clock enable signals are linked. For example, any ALM in a particular LAB using the `labclk1` signal also uses `labckena1`. If the LAB uses both the rising and falling edges of a clock, it also uses two LAB-wide clock signals. De-asserting the clock enable signal turns off the corresponding LAB-wide clock. Each LAB can use two asynchronous clear signals and an asynchronous load/preset signal. The asynchronous

load acts as a preset when the asynchronous load data input is tied high. When the asynchronous load/preset signal is used, the `labclkena0` signal is no longer available.

The LAB row clocks [5..0] and LAB local interconnect generate the LAB-wide control signals. The MultiTrack interconnects have inherently low skew. This low skew allows the MultiTrack interconnects to distribute clock and control signals in addition to data.

Figure 2–27 shows the LAB control signal generation circuit.

Figure 2–27. LAB-Wide Control Signals



Adaptive Logic Modules

The basic building block of logic in the Arria GX architecture is the ALM. The ALM provides advanced features with efficient logic utilization. Each ALM contains a variety of look-up table (LUT)-based resources that can be divided between two adaptive LUTs (ALUTs). With up to eight inputs

to the two ALUTs, one ALM can implement various combinations of two functions. This adaptability allows the ALM to be completely backward-compatible with four-input LUT architectures. One ALM can also implement any function of up to six inputs and certain seven-input functions.

In addition to the adaptive LUT-based resources, each ALM contains two programmable registers, two dedicated full adders, a carry chain, a shared arithmetic chain, and a register chain. Through these dedicated resources, the ALM can efficiently implement various arithmetic functions and shift registers. Each ALM drives all types of interconnects: local, row, column, carry chain, shared arithmetic chain, register chain, and direct link interconnects. Figure 2–28 shows a high-level block diagram of the Arria GX ALM while Figure 2–29 shows a detailed view of all the connections in the ALM.

Figure 2–28. High-Level Block Diagram of the Arria GX ALM

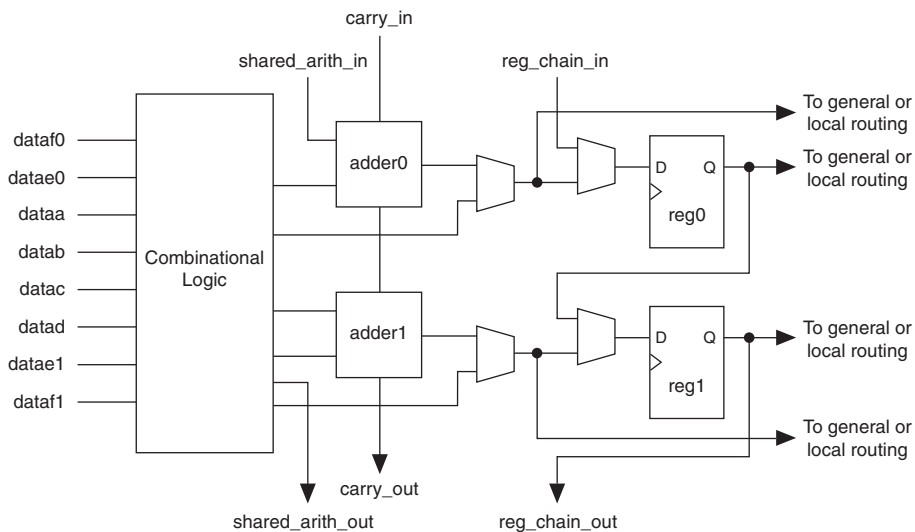
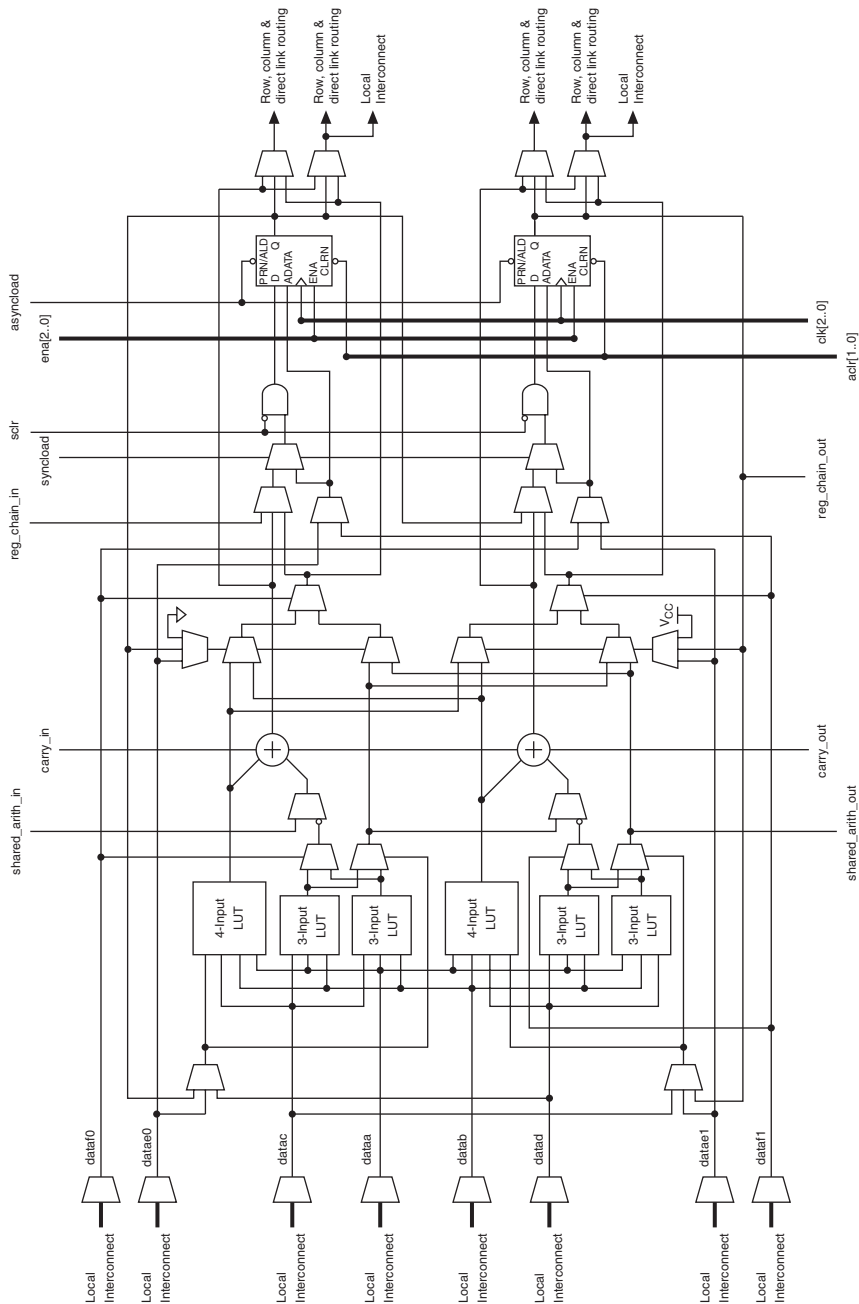


Figure 2–29. Arria GX ALM Details



One ALM contains two programmable registers. Each register has data, clock, clock enable, synchronous and asynchronous clear, asynchronous load data, and synchronous and asynchronous load/preset inputs.

Global signals, general-purpose I/O pins, or any internal logic can drive the register's clock and clear control signals. Either general-purpose I/O pins or internal logic can drive the clock enable, preset, asynchronous load, and asynchronous load data. The asynchronous load data input comes from the `datae` or `dataf` input of the ALM, which are the same inputs that can be used for register packing. For combinational functions, the register is bypassed and the output of the LUT drives directly to the outputs of the ALM.

Each ALM has two sets of outputs that drive the local, row, and column routing resources. The LUT, adder, or register output can drive these output drivers independently (see [Figure 2–29](#)). For each set of output drivers, two ALM outputs can drive column, row, or direct link routing connections. One of these ALM outputs can also drive local interconnect resources. This allows the LUT or adder to drive one output while the register drives another output. This feature, called register packing, improves device utilization because the device can use the register and combinational logic for unrelated functions. Another special packing mode allows the register output to feed back into the LUT of the same ALM so that the register is packed with its own fan-out LUT. This feature provides another mechanism for improved fitting. The ALM can also drive out registered and unregistered versions of the LUT or adder output.

ALM Operating Modes

The Arria GX ALM can operate in one of the following modes:

- Normal mode
- Extended LUT mode
- Arithmetic mode
- Shared arithmetic mode

Each mode uses ALM resources differently. Each mode has 11 available inputs to the ALM (see [Figure 2–28](#))—the eight data inputs from the LAB local interconnect; carry-in from the previous ALM or LAB; the shared arithmetic chain connection from the previous ALM or LAB; and the register chain connection—are directed to different destinations to implement the desired logic function. LAB-wide signals provide clock, asynchronous clear, asynchronous preset/load, synchronous clear, synchronous load, and clock enable control for the register. These

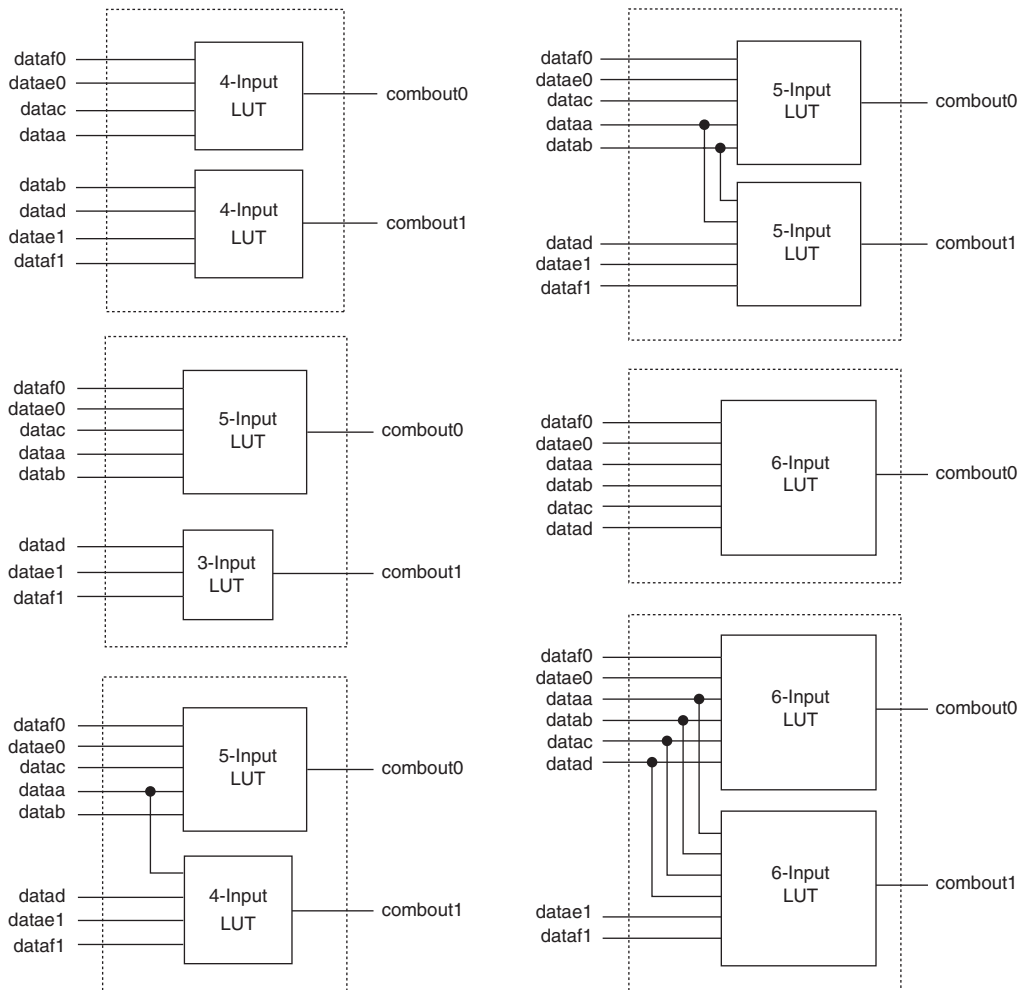
LAB-wide signals are available in all ALM modes. Refer to “[LAB Control Signals](#)” on [page 2–37](#) for more information about LAB-wide control signals.

The Quartus II software and supported third-party synthesis tools, in conjunction with parameterized functions such as library of parameterized modules (LPM) functions, automatically choose the appropriate mode for common functions such as counters, adders, subtractors, and arithmetic functions. If required, you can also create special-purpose functions that specify which ALM operating mode to use for optimal performance.

Normal Mode

Normal mode is suitable for general logic applications and combinational functions. In this mode, up to eight data inputs from the LAB local interconnect are inputs to the combinational logic. Normal mode allows two functions to be implemented in one Arria GX ALM, or an ALM to implement a single function of up to six inputs. The ALM can support certain combinations of completely independent functions and various combinations of functions which have common inputs. [Figure 2–30](#) shows the supported LUT combinations in normal mode.

Figure 2–30. ALM in Normal Mode *Note (1)*



Note to Figure 2–30:

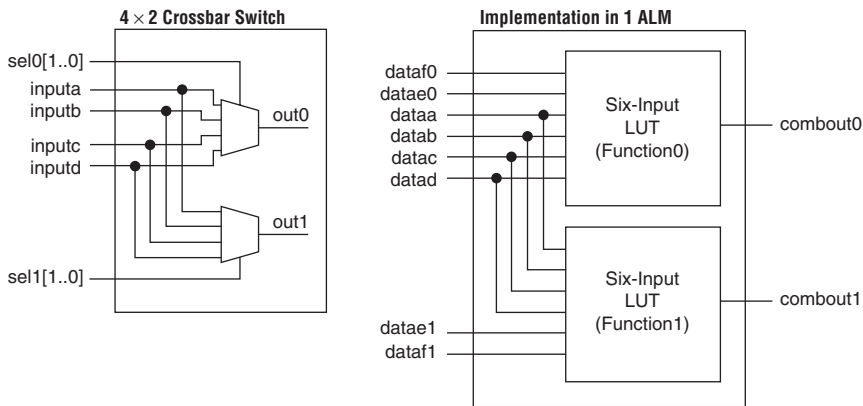
- (1) Combinations of functions with less inputs than those shown are also supported. For example, combinations of functions with the following number of inputs are supported: 4 and 3, 3 and 3, 3 and 2, 5 and 2, etc.

Normal mode provides complete backward compatibility with four-input LUT architectures. Two independent functions of four inputs or less can be implemented in one Arria GX ALM. In addition, a five-input function and an independent three-input function can be implemented without sharing inputs.

To pack two five-input functions into one ALM, the functions must have at least two common inputs. The common inputs are `dataaa` and `datab`. The combination of a four-input function with a five-input function requires one common input (either `dataaa` or `datab`).

To implement two six-input functions in one ALM, four inputs must be shared and the combinational function must be the same. For example, a 4×2 crossbar switch (two 4-to-1 multiplexers with common inputs and unique select lines) can be implemented in one ALM, as shown in [Figure 2–31](#). The shared inputs are `dataaa`, `datab`, `dataac`, and `datad`, while the unique select lines are `datae0` and `dataf0` for `function0`, and `datae1` and `dataf1` for `function1`. This crossbar switch consumes four LUTs in a four-input LUT-based architecture.

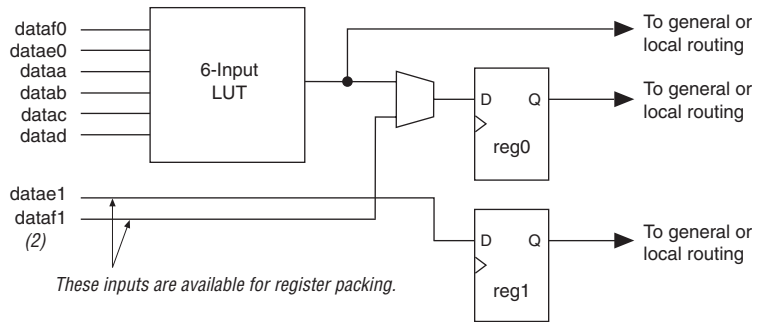
Figure 2–31. 4×2 Crossbar Switch Example



In a sparsely used device, functions that could be placed into one ALM can be implemented in separate ALMs. The Quartus II Compiler spreads a design out to achieve the best possible performance. As a device begins to fill up, the Quartus II software automatically utilizes the full potential of the Arria GX ALM. The Quartus II Compiler automatically searches for functions of common inputs or completely independent functions to be placed into one ALM and to make efficient use of the device resources. In addition, you can manually control resource usage by setting location assignments. Any six-input function can be implemented utilizing inputs `dataaa`, `datab`, `dataac`, `datad`, and either `datae0` and `dataf0` or `datae1` and `dataf1`. If `datae0` and `dataf0` are utilized, the output is driven to `register0`, and/or `register0` is bypassed and the data drives out to the interconnect using the top set of output drivers (see [Figure 2–32](#)). If `datae1` and `dataf1` are utilized, the output drives to `register1` and/or bypasses `register1` and drives to the interconnect

using the bottom set of output drivers. The Quartus II Compiler automatically selects the inputs to the LUT. Asynchronous load data for the register comes from the `dataae` or `dataaf` input of the ALM. ALMs in normal mode support register packing.

Figure 2–32. Six-Input Function in Normal Mode *Notes (1), (2)*

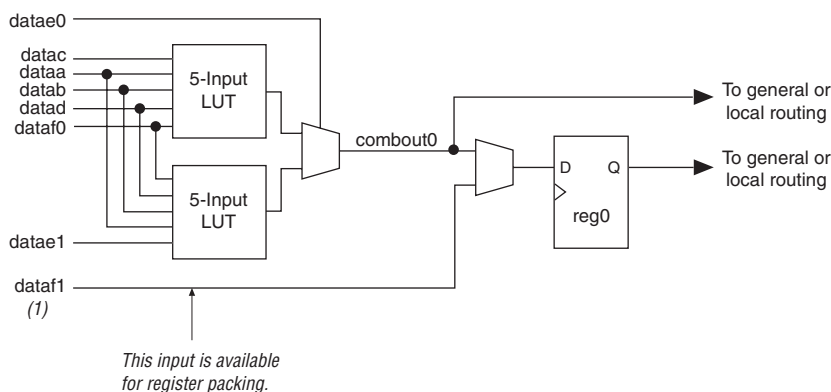


Notes to Figure 2–32:

- (1) If `datae1` and `dataf1` are used as inputs to the six-input function, `datae0` and `dataf0` are available for register packing.
- (2) The `dataf1` input is available for register packing only if the six-input function is un-registered.

Extended LUT Mode

Extended LUT mode is used to implement a specific set of seven-input functions. The set must be a 2-to-1 multiplexer fed by two arbitrary five-input functions sharing four inputs. Figure 2–33 shows the template of supported seven-input functions utilizing extended LUT mode. In this mode, if the seven-input function is unregistered, the unused eighth input is available for register packing. Functions that fit into the template shown in Figure 2–33 occur naturally in designs. These functions often appear in designs as “if-else” statements in Verilog HDL or VHDL code.

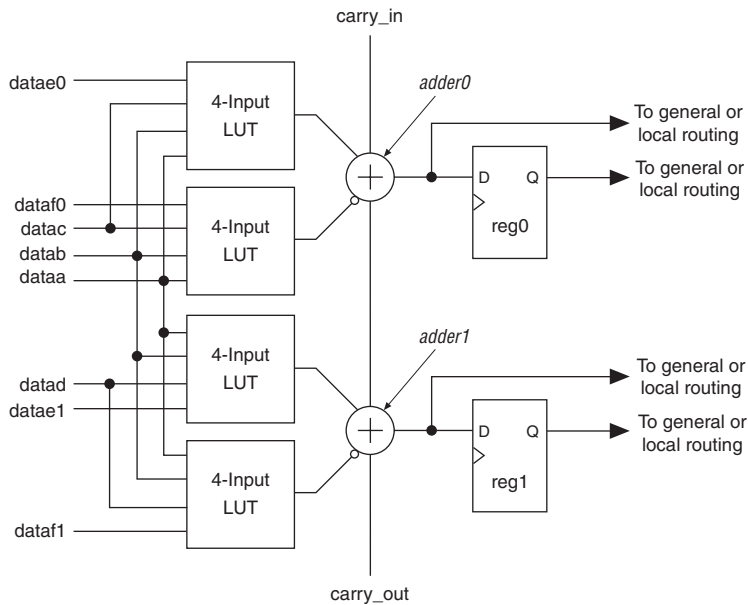
Figure 2–33. Template for Supported Seven-Input Functions in Extended LUT Mode**Note to Figure 2–33:**

- (1) If the seven-input function is unregistered, the unused eighth input is available for register packing. The second register, reg1, is not available.

Arithmetic Mode

Arithmetic mode is ideal for implementing adders, counters, accumulators, wide parity functions, and comparators. An ALM in arithmetic mode uses two sets of 2 four-input LUTs along with two dedicated full adders. The dedicated adders allow the LUTs to be available to perform pre-adder logic; therefore, each adder can add the output of two four-input functions. The four LUTs share the dataa and datab inputs. As shown in Figure 2–34, the carry-in signal feeds to adder0, and the carry-out from adder0 feeds to carry-in of adder1. The carry-out from adder1 drives to adder0 of the next ALM in the LAB. ALMs in arithmetic mode can drive out registered and/or unregistered versions of the adder outputs.

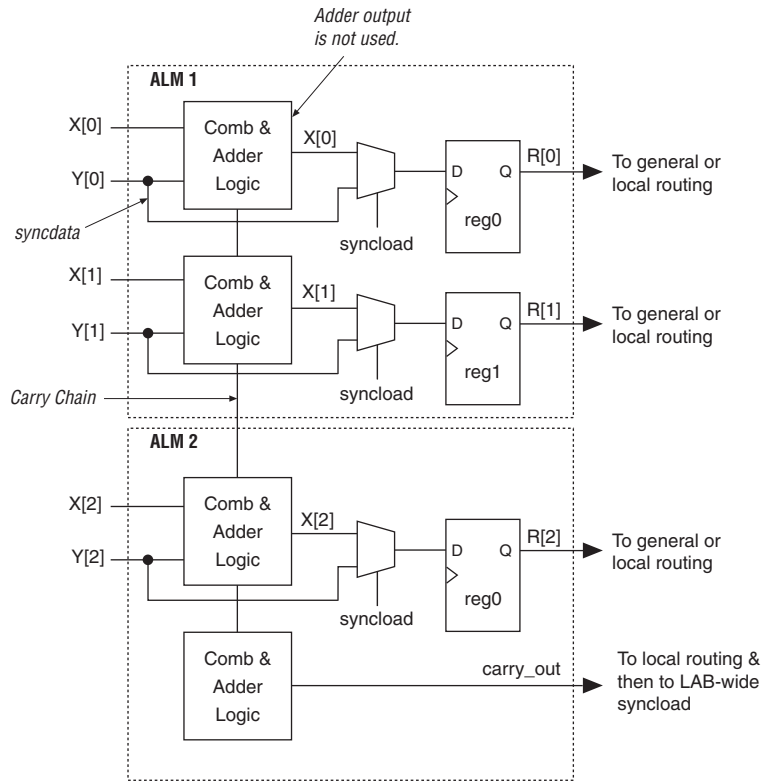
Figure 2–34. ALM in Arithmetic Mode



While operating in arithmetic mode, the ALM can support simultaneous use of the adder's carry output along with combinational logic outputs. In this operation, adder output is ignored. This usage of the adder with the combinational logic output provides resource savings of up to 50% for functions that can use this ability. An example of such functionality is a conditional operation, such as the one shown in Figure 2–35. The equation for this example is:

$$R = (X < Y) ? Y : X$$

To implement this function, the adder is used to subtract 'Y' from 'X.' If 'X' is less than 'Y,' the *carry_out* signal will be '1.' The *carry_out* signal is fed to an adder where it drives out to the LAB local interconnect. It then feeds to the LAB-wide *syncload* signal. When asserted, *syncload* selects the *syncdata* input. In this case, the data 'Y' drives the *syncdata* inputs to the registers. If 'X' is greater than or equal to 'Y,' the *syncload* signal is de-asserted and 'X' drives the data port of the registers.

Figure 2–35. Conditional Operation Example

Arithmetic mode also offers clock enable, counter enable, synchronous up/down control, add/subtract control, synchronous clear, and synchronous load. The LAB local interconnect data inputs generate the clock enable, counter enable, synchronous up/down and add/subtract control signals. These control signals may be used for the inputs that are shared between the four LUTs in the ALM. The synchronous clear and synchronous load options are LAB-wide signals that affect all registers in the LAB. The Quartus II software automatically places any registers that are not used by the counter into other LABs.

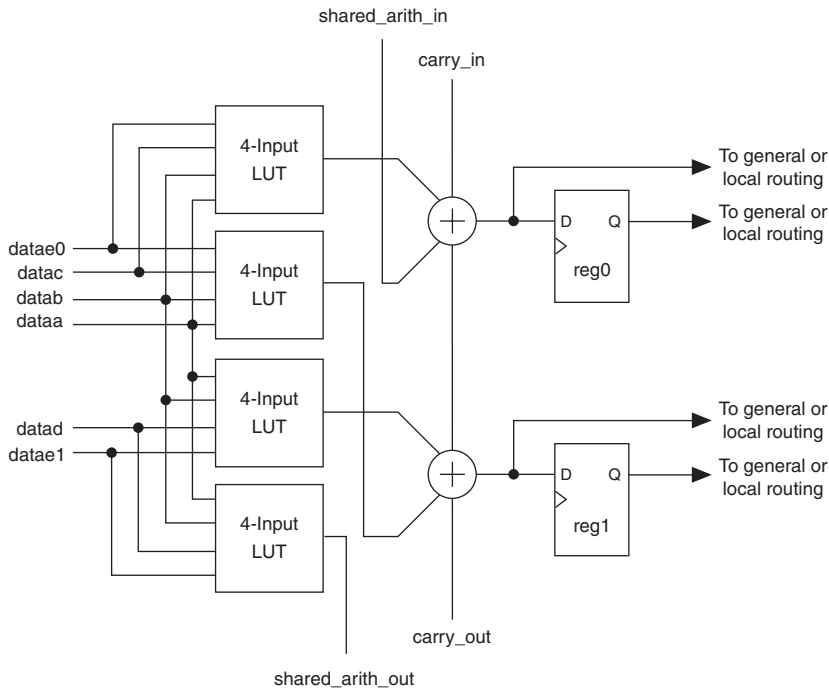
Carry Chain

Carry chain provides a fast carry function between the dedicated adders in arithmetic or shared arithmetic mode. Carry chains can begin in either the first ALM or the fifth ALM in a LAB. The final carry-out signal is routed to an ALM, where it is fed to local, row, or column interconnects.

The Quartus II Compiler automatically creates carry chain logic during compilation, or you can create it manually during design entry. Parameterized functions such as LPM functions automatically take advantage of carry chains for the appropriate functions. The Quartus II Compiler creates carry chains longer than 16 (8 ALMs in arithmetic or shared arithmetic mode) by linking LABs together automatically. For enhanced fitting, a long carry chain runs vertically allowing fast horizontal connections to TriMatrix memory and DSP blocks. A carry chain can continue as far as a full column. To avoid routing congestion in one small area of the device when a high fan-in arithmetic function is implemented, the LAB can support carry chains that only utilize either the top half or bottom half of the LAB before connecting to the next LAB. The other half of the ALMs in the LAB is available for implementing narrower fan-in functions in normal mode. Carry chains that use the top four ALMs in the first LAB carries into the top half of the ALMs in the next LAB within the column. Carry chains that use the bottom four ALMs in the first LAB carries into the bottom half of the ALMs in the next LAB within the column. Every other column of the LABs are top-half bypassable, while the other LAB columns are bottom-half bypassable. Refer to [“MultiTrack Interconnect” on page 2-54](#) for more information about carry chain interconnect.

Shared Arithmetic Mode

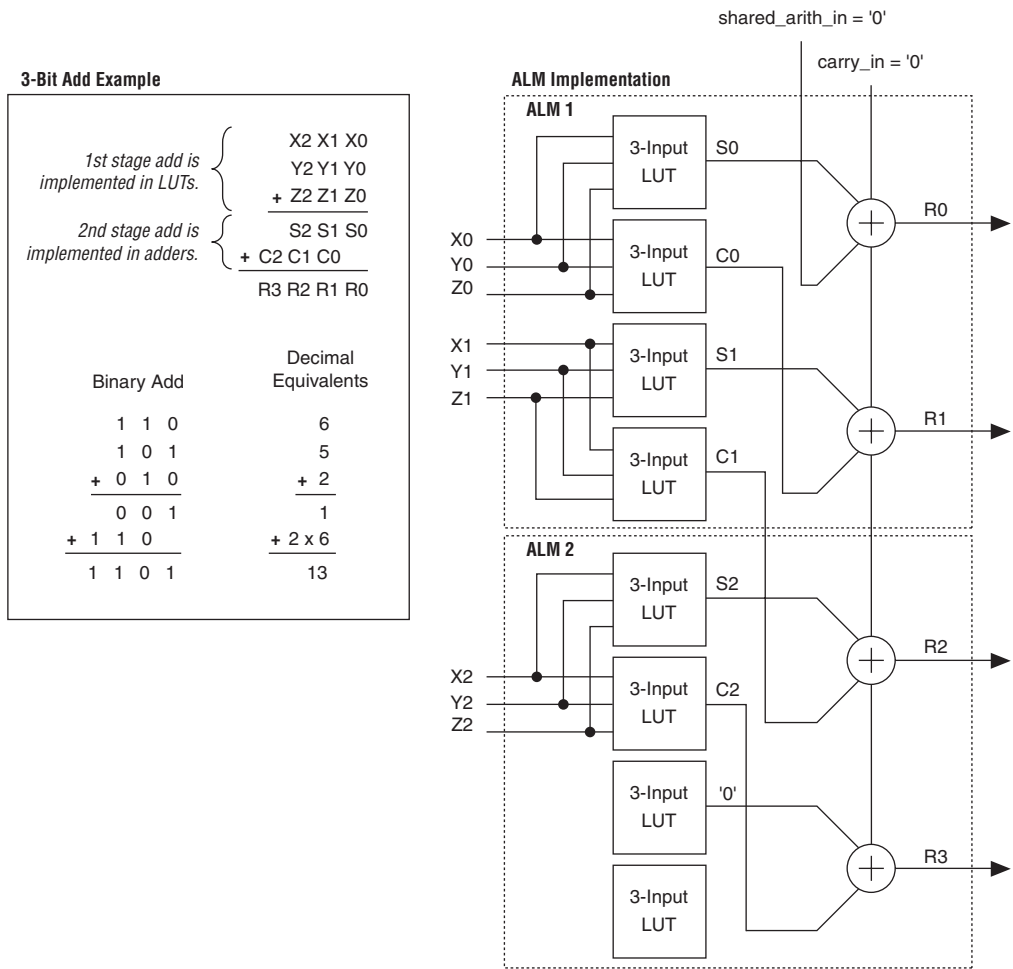
In shared arithmetic mode, the ALM can implement a three-input add. In this mode, the ALM is configured with four 4-input LUTs. Each LUT either computes the sum of three inputs or the carry of three inputs. The output of the carry computation is fed to the next adder (either to `adder1` in the same ALM or to `adder0` of the next ALM in the LAB) using a dedicated connection called the shared arithmetic chain. This shared arithmetic chain can significantly improve the performance of an adder tree by reducing the number of summation stages required to implement an adder tree. [Figure 2-36](#) shows the ALM in shared arithmetic mode.

Figure 2–36. ALM in Shared Arithmetic Mode**Note to Figure 2–36:**

- (1) Inputs dataf0 and dataf1 are available for register packing in shared arithmetic mode.

Adder trees are used in many different applications. For example, the summation of partial products in a logic-based multiplier can be implemented in a tree structure. Another example is a correlator function that can use a large adder tree to sum filtered data samples in a given time frame to recover or to de-spread data which was transmitted utilizing spread spectrum technology. An example of a three-bit add operation utilizing the shared arithmetic mode is shown in Figure 2–37. The partial sum ($S[2..0]$) and the partial carry ($C[2..0]$) is obtained using LUTs, while the result ($R[2..0]$) is computed using dedicated adders.

Figure 2–37. Example of a 3-Bit Add Utilizing Shared Arithmetic Mode



Shared Arithmetic Chain

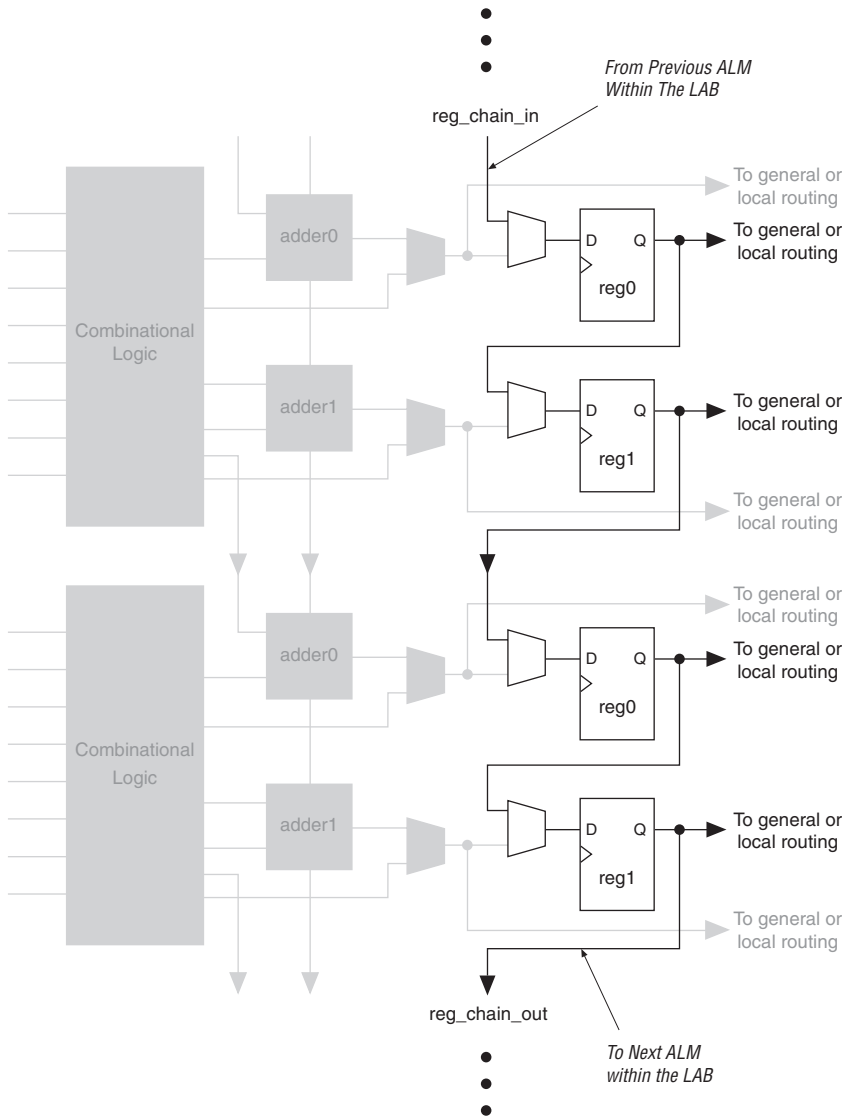
In addition to dedicated carry chain routing, the shared arithmetic chain available in shared arithmetic mode allows the ALM to implement a three-input add, which significantly reduces the resources necessary to implement large adder trees or correlator functions. Shared arithmetic chains can begin in either the first or fifth ALM in a LAB. The Quartus II Compiler automatically links LABs to create shared arithmetic chains longer than 16 (8 ALMs in arithmetic or shared arithmetic mode). For enhanced fitting, a long shared arithmetic chain runs vertically allowing

fast horizontal connections to TriMatrix memory and DSP blocks. A shared arithmetic chain can continue as far as a full column. Similar to carry chains, shared arithmetic chains are also top- or bottom-half bypassable. This capability allows the shared arithmetic chain to cascade through half of the ALMs in a LAB while leaving the other half available for narrower fan-in functionality. Every other LAB column is top-half bypassable, while the other LAB columns are bottom-half bypassable. Refer to [“MultiTrack Interconnect” on page 2-54](#) for more information about shared arithmetic chain interconnect.

Register Chain

In addition to the general routing outputs, the ALMs in a LAB have register chain outputs. Register chain routing allows registers in the same LAB to be cascaded together. The register chain interconnect allows a LAB to use LUTs for a single combinational function and the registers to be used for an unrelated shift register implementation. These resources speed up connections between ALMs while saving local interconnect resources (see [Figure 2-38](#)). The Quartus II Compiler automatically takes advantage of these resources to improve utilization and performance. Refer to [“MultiTrack Interconnect” on page 2-54](#) for more information about register chain interconnect.

Figure 2–38. Register Chain within a LAB Note (1)



Note to Figure 2–38:

(1) The combinational or adder logic can be utilized to implement an unrelated, un-registered function.

Clear and Preset Logic Control

LAB-wide signals control the logic for the register's clear and load/preset signals. The ALM directly supports an asynchronous clear and preset function. The register preset is achieved through the asynchronous load of a logic high. The direct asynchronous preset does not require a NOT gate push-back technique. Arria GX devices support simultaneous asynchronous load/preset and clear signals. An asynchronous clear signal takes precedence if both signals are asserted simultaneously. Each LAB supports up to two clears and one load/preset signal.

In addition to the clear and load/preset ports, Arria GX devices provide a device-wide reset pin (`DEV_CLRn`) that resets all registers in the device. An option set before compilation in the Quartus II software controls this pin. This device-wide reset overrides all other control signals.

MultiTrack Interconnect

In Arria GX architecture, the MultiTrack interconnect structure with DirectDrive technology provides connections between ALMs, TriMatrix memory, DSP blocks, and device I/O pins. The MultiTrack interconnect consists of continuous, performance-optimized routing lines of different lengths and speeds used for inter- and intra-design block connectivity. The Quartus II Compiler automatically places critical design paths on faster interconnects to improve design performance.

DirectDrive technology is a deterministic routing technology that ensures identical routing resource usage for any function regardless of placement in the device. The MultiTrack interconnect and DirectDrive technology simplify the integration stage of block-based designing by eliminating the re-optimization cycles that typically follow design changes and additions.

The MultiTrack interconnect consists of row and column interconnects that span fixed distances. A routing structure with fixed length resources for all devices allows predictable and repeatable performance when migrating through different device densities. Dedicated row interconnects route signals to and from LABs, DSP blocks, and TriMatrix memory in the same row.

These row resources include:

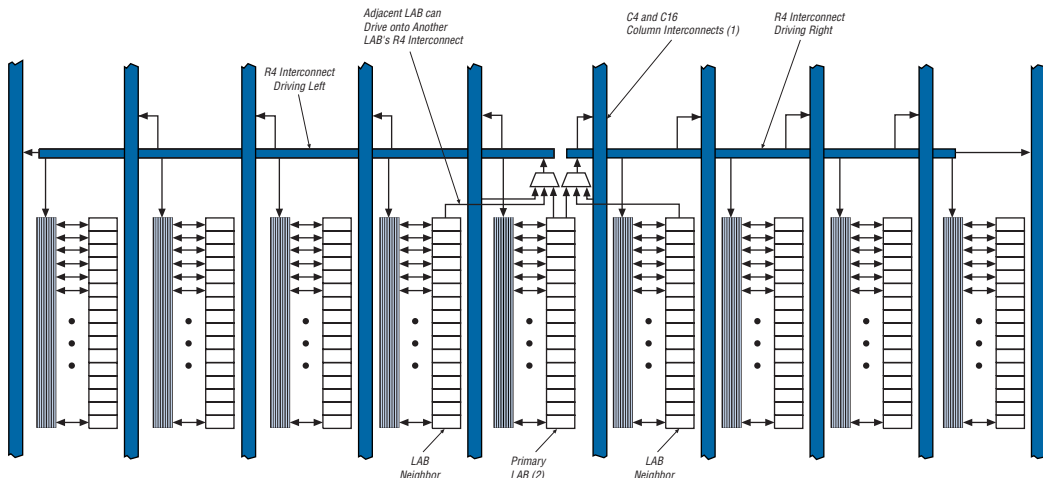
- Direct link interconnects between LABs and adjacent blocks
- R4 interconnects traversing four blocks to the right or left
- R24 row interconnects for high-speed access across the length of the device

The direct link interconnect allows a LAB, DSP block, or TriMatrix memory block to drive into the local interconnect of its left and right neighbors and then back into itself, providing fast communication between adjacent LABs and/or blocks without using row interconnect resources.

The R4 interconnects span four LABs, three LABs and one M512 RAM block, two LABs and one M4K RAM block, or two LABs and one DSP block to the right or left of a source LAB. These resources are used for fast row connections in a four-LAB region. Every LAB has its own set of R4 interconnects to drive either left or right. [Figure 2–39](#) shows R4 interconnect connections from a LAB.

R4 interconnects can drive and be driven by DSP blocks and RAM blocks and row IOEs. For LAB interfacing, a primary LAB or LAB neighbor can drive a given R4 interconnect. For R4 interconnects that drive to the right, the primary LAB and right neighbor can drive onto the interconnect. For R4 interconnects that drive to the left, the primary LAB and its left neighbor can drive onto the interconnect. R4 interconnects can drive other R4 interconnects to extend the range of LABs they can drive. R4 interconnects can also drive C4 and C16 interconnects for connections from one row to another. Additionally, R4 interconnects can drive R24 interconnects.

Figure 2–39. R4 Interconnect Connections *Notes (1), (2), (3)*



Notes to Figure 2–39:

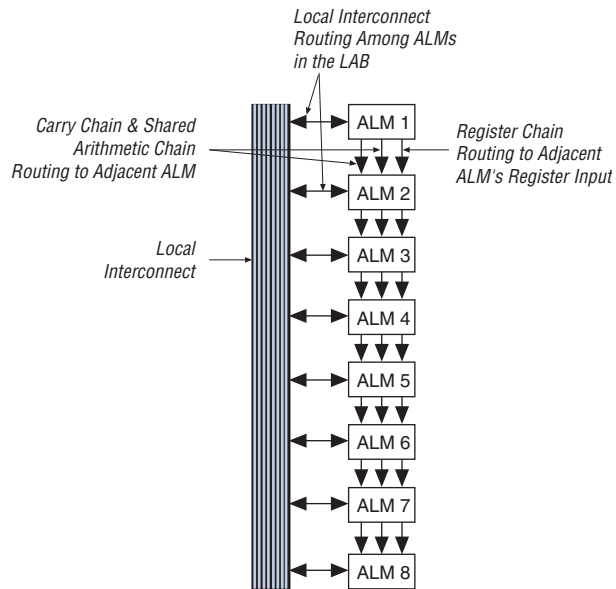
- (1) C4 and C16 interconnects can drive R4 interconnects.
- (2) This pattern is repeated for every LAB in the LAB row.
- (3) The LABs in [Figure 2–39](#) show the 16 possible logical outputs per LAB.

R24 row interconnects span 24 LABs and provide the fastest resource for long row connections between LABs, TriMatrix memory, DSP blocks, and row IOEs. The R24 row interconnects can cross M-RAM blocks. R24 row interconnects drive to other row or column interconnects at every fourth LAB and do not drive directly to LAB local interconnects. R24 row interconnects drive LAB local interconnects via R4 and C4 interconnects. R24 interconnects can drive R24, R4, C16, and C4 interconnects. The column interconnect operates similarly to the row interconnect and vertically routes signals to and from LABs, TriMatrix memory, DSP blocks, and IOEs. Each column of LABs is served by a dedicated column interconnect.

These column resources include:

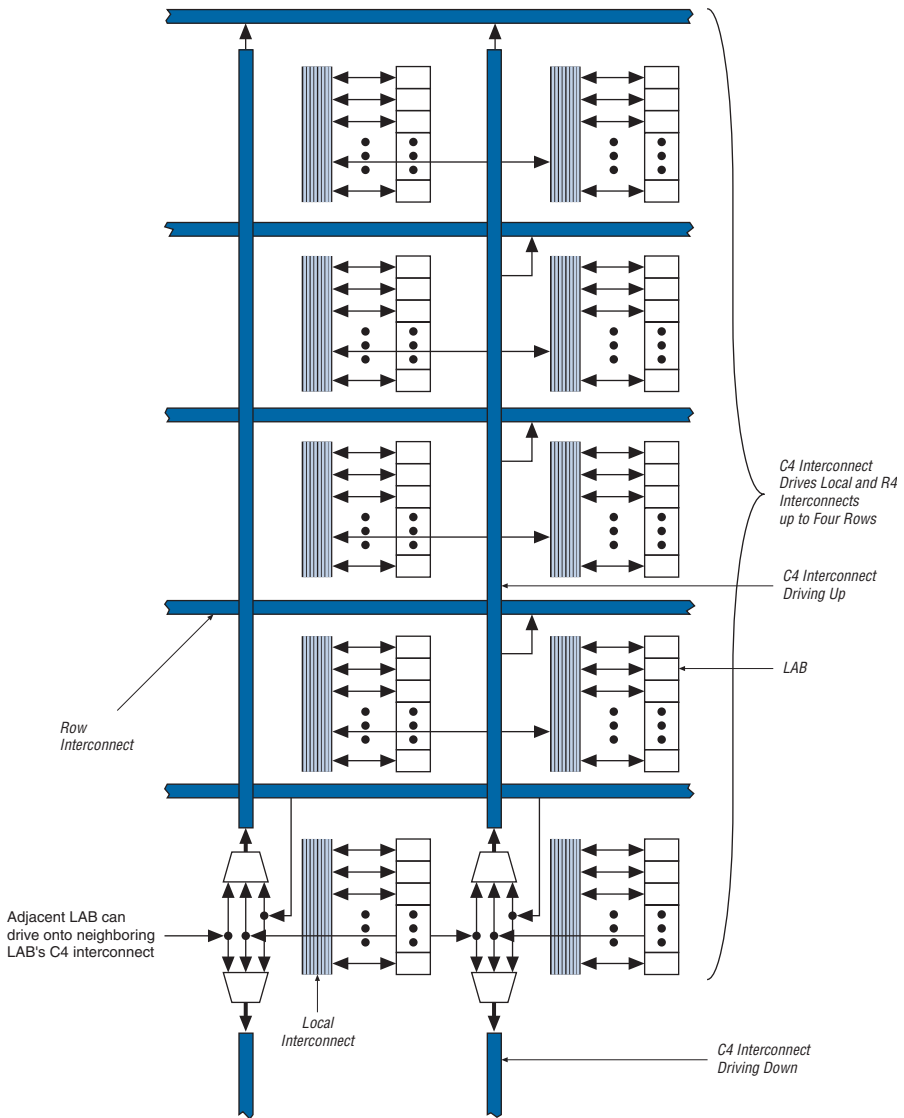
- Shared arithmetic chain interconnects in a LAB
- Carry chain interconnects in a LAB and from LAB to LAB
- Register chain interconnects in a LAB
- C4 interconnects traversing a distance of four blocks in up and down direction
- C16 column interconnects for high-speed vertical routing through the device

Arria GX devices include an enhanced interconnect structure in LABs for routing shared arithmetic chains and carry chains for efficient arithmetic functions. The register chain connection allows the register output of one ALM to connect directly to the register input of the next ALM in the LAB for fast shift registers. These ALM-to-ALM connections bypass the local interconnect. The Quartus II Compiler automatically takes advantage of these resources to improve utilization and performance. [Figure 2-40](#) shows shared arithmetic chain, carry chain, and register chain interconnects.

Figure 2–40. Shared Arithmetic Chain, Carry Chain and Register Chain Interconnects

C4 interconnects span four LABs, M512, or M4K blocks up or down from a source LAB. Every LAB has its own set of C4 interconnects to drive either up or down. [Figure 2–41](#) shows the C4 interconnect connections from a LAB in a column. C4 interconnects can drive and be driven by all types of architecture blocks, including DSP blocks, TriMatrix memory blocks, and column and row IOEs. For LAB interconnection, a primary LAB or its LAB neighbor can drive a given C4 interconnect. C4 interconnects can drive each other to extend their range as well as drive row interconnects for column-to-column connections.

Figure 2-41. C4 Interconnect Connections Note (1)



Note to Figure 2-41:

(1) Each C4 interconnect can drive either up or down four rows.

C16 column interconnects span a length of 16 LABs and provide the fastest resource for long column connections between LABs, TriMatrix memory blocks, DSP blocks, and IOEs. C16 interconnects can cross M-RAM blocks and also drive to row and column interconnects at every fourth LAB. C16 interconnects drive LAB local interconnects via C4 and R4 interconnects and do not drive LAB local interconnects directly. All embedded blocks communicate with the logic array similar to LAB-to-LAB interfaces. Each block (that is, TriMatrix memory and DSP blocks) connects to row and column interconnects and has local interconnect regions driven by row and column interconnects. These blocks also have direct link interconnects for fast connections to and from a neighboring LAB. All blocks are fed by the row LAB clocks, `labclk[5..0]`.

Table 2–10 shows the Arria GX device’s routing scheme.

Table 2–10. Arria GX Device Routing Scheme (Part 1 of 2)

| Source | Destination | | | | | | | | | | | | | | | |
|--------------------------|-------------------------|-------------|----------------|--------------------|--------------------------|-----------------|------------------|-----------------|------------------|-----|----------------|---------------|-------------|------------|------------|---------|
| | Shared Arithmetic Chain | Carry Chain | Register Chain | Local Interconnect | Direct Link Interconnect | R4 Interconnect | R24 Interconnect | C4 Interconnect | C16 Interconnect | ALM | M512 RAM Block | M4K RAM Block | M-RAM Block | DSP Blocks | Column IOE | Row IOE |
| Shared arithmetic chain | | | | | | | | | | ✓ | | | | | | |
| Carry chain | | | | | | | | | | ✓ | | | | | | |
| Register chain | | | | | | | | | | ✓ | | | | | | |
| Local interconnect | | | | | | | | | | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| Direct link interconnect | | | | ✓ | | | | | | | | | | | | |
| R4 interconnect | | | | ✓ | | ✓ | ✓ | ✓ | ✓ | | | | | | | |
| R24 interconnect | | | | | | ✓ | ✓ | ✓ | ✓ | | | | | | | |
| C4 interconnect | | | | ✓ | | ✓ | | ✓ | | | | | | | | |
| C16 interconnect | | | | | | ✓ | ✓ | ✓ | ✓ | | | | | | | |
| ALM | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | | ✓ | | | | | | | | |
| M512 RAM block | | | | ✓ | ✓ | ✓ | | ✓ | | | | | | | | |
| M4K RAM block | | | | ✓ | ✓ | ✓ | | ✓ | | | | | | | | |
| M-RAM block | | | | | ✓ | ✓ | ✓ | ✓ | | | | | | | | |
| DSP blocks | | | | | ✓ | ✓ | | ✓ | | | | | | | | |

Table 2–10. Arria GX Device Routing Scheme (Part 2 of 2)

| Source | Destination | | | | | | | | | | | | | | | |
|------------|-------------------------|-------------|----------------|--------------------|--------------------------|-----------------|------------------|-----------------|------------------|-----|----------------|---------------|-------------|------------|------------|---------|
| | Shared Arithmetic Chain | Carry Chain | Register Chain | Local Interconnect | Direct Link Interconnect | R4 Interconnect | R24 Interconnect | C4 Interconnect | C16 Interconnect | ALM | M512 RAM Block | M4K RAM Block | M-RAM Block | DSP Blocks | Column IOE | Row IOE |
| Column IOE | | | | | ✓ | | | ✓ | ✓ | | | | | | | |
| Row IOE | | | | | ✓ | ✓ | ✓ | ✓ | | | | | | | | |

TriMatrix Memory

TriMatrix memory consists of three types of RAM blocks: M512, M4K, and M-RAM. Although these memory blocks are different, they can all implement various types of memory with or without parity, including true dual-port, simple dual-port, and single-port RAM, ROM, and first-in first-out (FIFO) buffers. Table 2–11 shows the size and features of the different RAM blocks.

Table 2–11. TriMatrix Memory Features (Part 1 of 2)

| Memory Feature | M512 RAM Block (32 × 18 Bits) | M4K RAM Block (128 × 36 Bits) | M-RAM Block (4K × 144 Bits) |
|------------------------------|----------------------------------|----------------------------------|--------------------------------|
| Maximum performance | 345 MHz | 380 MHz | 290 MHz |
| True dual-port memory | | ✓ | ✓ |
| Simple dual-port memory | ✓ | ✓ | ✓ |
| Single-port memory | ✓ | ✓ | ✓ |
| Shift register | ✓ | ✓ | |
| ROM | ✓ | ✓ | |
| FIFO buffer | ✓ | ✓ | ✓ |
| Pack mode | | ✓ | ✓ |
| Byte enable | ✓ | ✓ | ✓ |
| Address clock enable | | ✓ | ✓ |
| Parity bits | ✓ | ✓ | ✓ |
| Mixed clock mode | ✓ | ✓ | ✓ |
| Memory initialization (.mif) | ✓ | ✓ | |

Table 2–11. TriMatrix Memory Features (Part 2 of 2)

| Memory Feature | M512 RAM Block (32 × 18 Bits) | M4K RAM Block (128 × 36 Bits) | M-RAM Block (4K × 144 Bits) |
|---|---|--|--|
| Simple dual-port memory mixed width support | ✓ | ✓ | ✓ |
| True dual-port memory mixed width support | | ✓ | ✓ |
| Power-up conditions | Outputs cleared | Outputs cleared | Outputs unknown |
| Register clears | Output registers | Output registers | Output registers |
| Mixed-port read-during-write | Unknown output/old data | Unknown output/old data | Unknown output |
| Configurations | 512 × 1 256 × 2 128 × 4 64 × 8 64 × 9 32 × 16 32 × 18 | 4K × 1 2K × 2 1K × 4 512 × 8 512 × 9 256 × 16 256 × 18 128 × 32 128 × 36 | 64K × 8 64K × 9 32K × 16 32K × 18 16K × 32 16K × 36 8K × 64 8K × 72 4K × 128 4K × 144 |

TriMatrix memory provides three different memory sizes for efficient application support. The Quartus II software automatically partitions the user-defined memory into the embedded memory blocks using the most efficient size combinations. You can also manually assign the memory to a specific block size or a mixture of block sizes.

M512 RAM Block

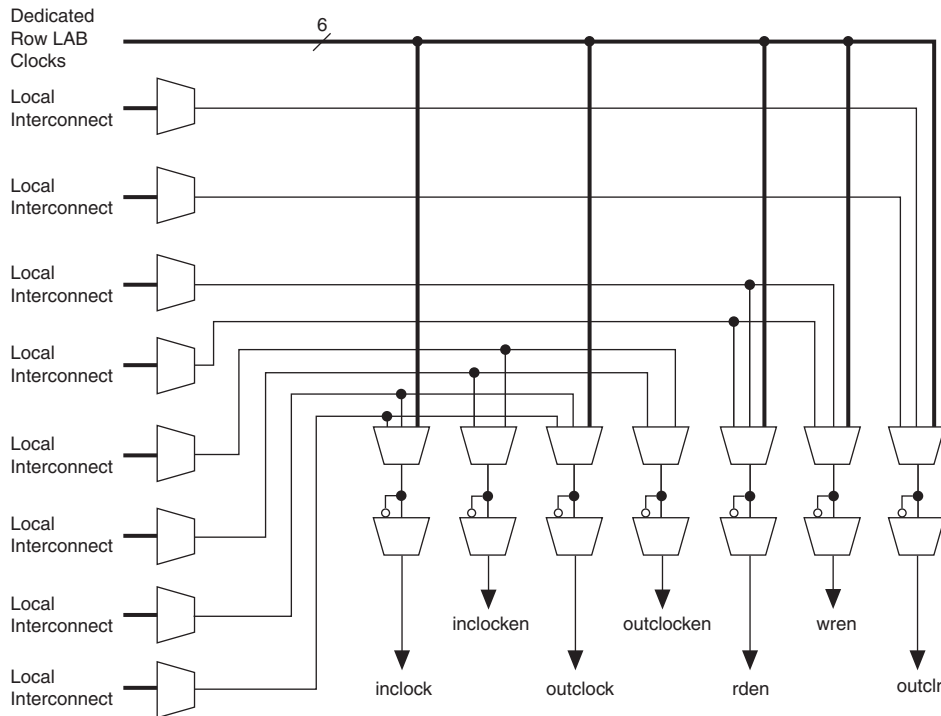
The M512 RAM block is a simple dual-port memory block and is useful for implementing small FIFO buffers, DSP, and clock domain transfer applications. Each block contains 576 RAM bits (including parity bits). M512 RAM blocks can be configured in the following modes:

- Simple dual-port RAM
- Single-port RAM
- FIFO
- ROM
- Shift register

When configured as RAM or ROM, you can use an initialization file to pre-load the memory contents.

M512 RAM blocks can have different clocks on its inputs and outputs. The `wren`, `datain`, and write address registers are all clocked together from one of the two clocks feeding the block. The read address, `rden`, and output registers can be clocked by either of the two clocks driving the block, allowing the RAM block to operate in read and write or input and output clock modes. Only the output register can be bypassed. The six `labclk` signals or local interconnect can drive the `inclock`, `outclock`, `wren`, `rden`, and `outclr` signals. Because of the advanced interconnect between the LAB and M512 RAM blocks, ALMs can also control the `wren` and `rden` signals and the RAM clock, clock enable, and asynchronous clear signals. Figure 2–42 shows the M512 RAM block control signal generation logic.

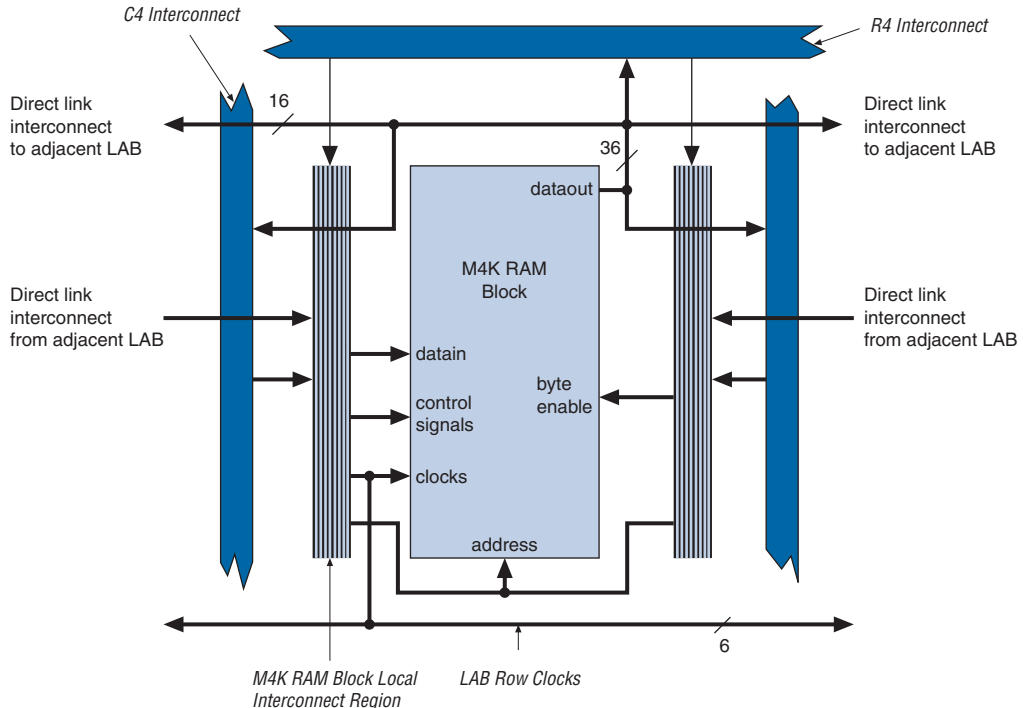
Figure 2–42. M512 RAM Block Control Signals



The RAM blocks in Arria GX devices have local interconnects to allow ALMs and interconnects to drive into RAM blocks. The M512 RAM block local interconnect is driven by the R4, C4, and direct link interconnects from adjacent LABs. The M512 RAM blocks can communicate with LABs on either the left or right side through these row interconnects or with LAB columns on the left or right side with the column interconnects. The

M512 RAM block has up to 16 direct link input connections from the left adjacent LABs and another 16 from the right adjacent LAB. M512 RAM outputs can also connect to left and right LABs through direct link interconnect. The M512 RAM block has equal opportunity for access and performance to and from LABs on either its left or right side. Figure 2–43 shows the M512 RAM block to logic array interface.

Figure 2–43. M512 RAM Block LAB Row Interface



M4K RAM Blocks

The M4K RAM block includes support for true dual-port RAM. The M4K RAM block is used to implement buffers for a wide variety of applications such as storing processor code, implementing lookup schemes, and implementing larger memory applications. Each block contains 4,608 RAM bits (including parity bits). M4K RAM blocks can be configured in the following modes:

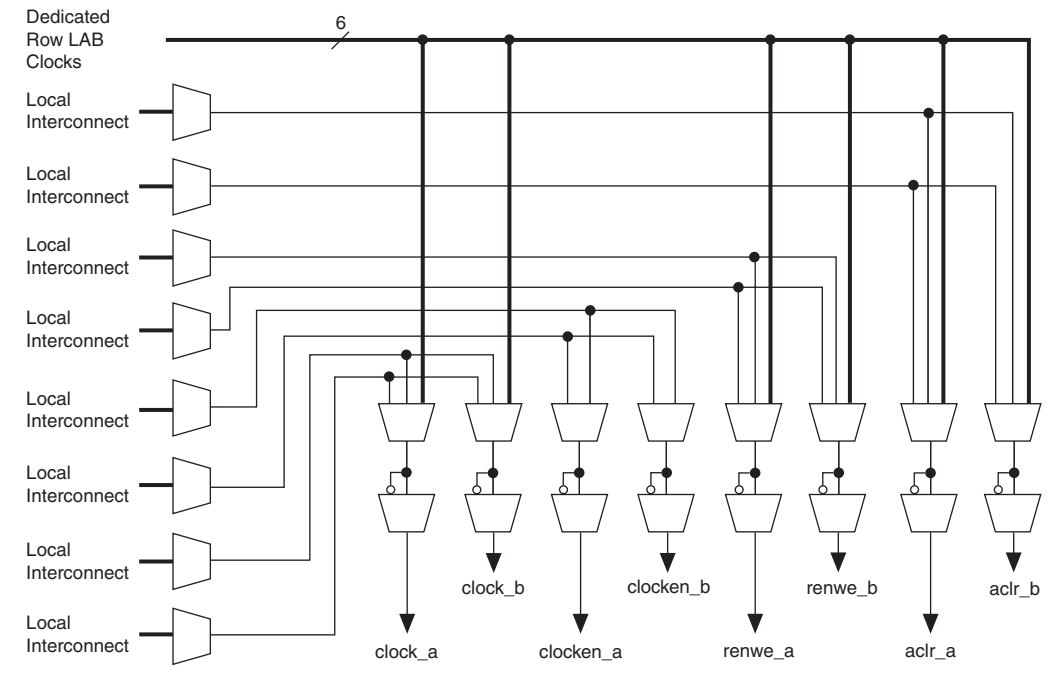
- True dual-port RAM
- Simple dual-port RAM
- Single-port RAM

- FIFO
- ROM
- Shift register

When configured as RAM or ROM, you can use an initialization file to pre-load the memory contents.

M4K RAM blocks allow for different clocks on their inputs and outputs. Either of the two clocks feeding the block can clock M4K RAM block registers (*renwe*, *address*, *byte enable*, *datain*, and output registers). Only the output register can be bypassed. The six *labclk* signals or local interconnects can drive the control signals for the A and B ports of the M4K RAM block. ALMs can also control the *clock_a*, *clock_b*, *renwe_a*, *renwe_b*, *clr_a*, *clr_b*, *clocken_a*, and *clocken_b* signals, as shown in [Figure 2-44](#).

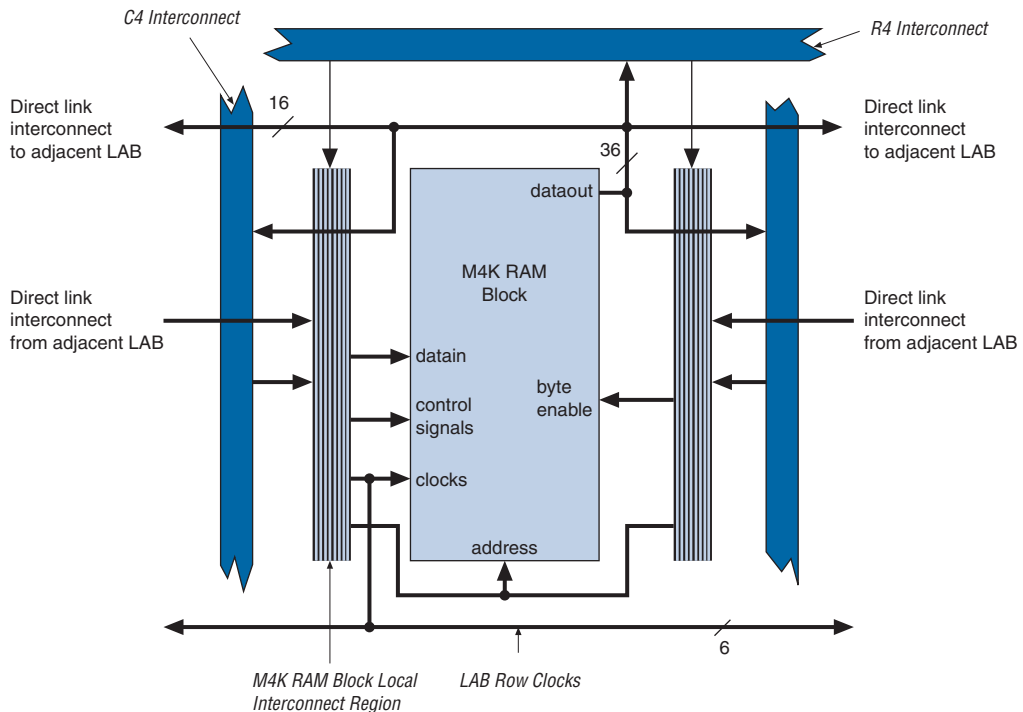
Figure 2-44. M4K RAM Block Control Signals



The R4, C4, and direct link interconnects from adjacent LABs drive the M4K RAM block local interconnect. The M4K RAM blocks can communicate with LABs on either the left or right side through these row resources or with LAB columns on either the right or left with the column

resources. Up to 16 direct link input connections to the M4K RAM block are possible from the left adjacent LABs and another 16 are possible from the right adjacent LAB. M4K RAM block outputs can also connect to left and right LABs through direct link interconnect. Figure 2–45 shows the M4K RAM block to logic array interface.

Figure 2–45. M4K RAM Block LAB Row Interface



M-RAM Block

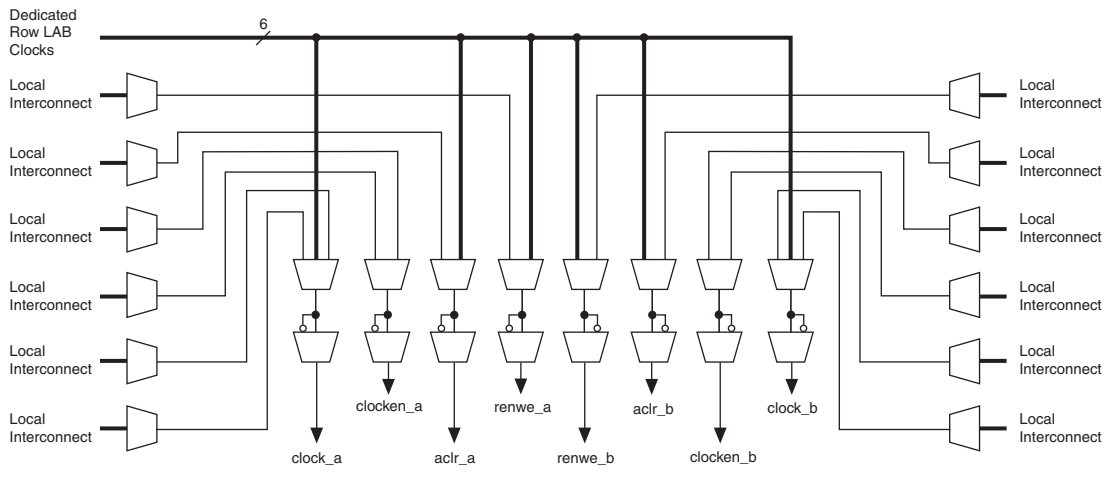
The largest TriMatrix memory block, the M-RAM block, is useful for applications where a large volume of data must be stored on-chip. Each block contains 589,824 RAM bits (including parity bits). The M-RAM block can be configured in the following modes:

- True dual-port RAM
- Simple dual-port RAM
- Single-port RAM
- FIFO

You cannot use an initialization file to initialize the contents of a M-RAM block. All M-RAM block contents power up to an undefined value. Only synchronous operation is supported in the M-RAM block, so all inputs are registered. Output registers can be bypassed.

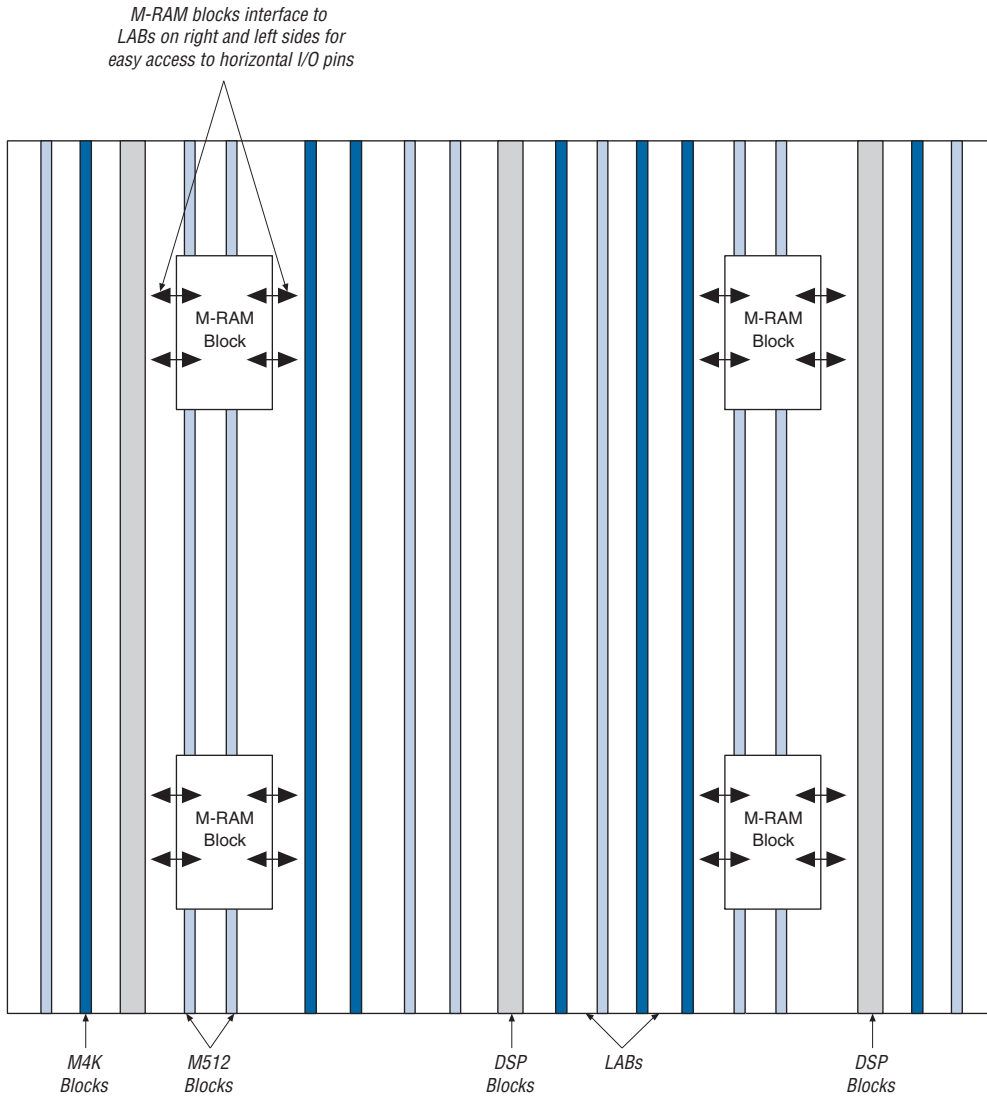
Similar to all RAM blocks, M-RAM blocks can have different clocks on their inputs and outputs. Either of the two clocks feeding the block can clock M-RAM block registers (renwe, address, byte enable, datain, and output registers). The output register can be bypassed. The six labclk signals or local interconnect can drive the control signals for the A and B ports of the M-RAM block. ALMs can also control the clock_a, clock_b, renwe_a, renwe_b, clr_a, clr_b, clocken_a, and clocken_b signals, as shown in Figure 2-46.

Figure 2-46. M-RAM Block Control Signals



The R4, R24, C4, and direct link interconnects from adjacent LABs on either the right or left side drive the M-RAM block local interconnect. Up to 16 direct link input connections to the M-RAM block are possible from the left adjacent LABs and another 16 are possible from the right adjacent LAB. M-RAM block outputs can also connect to left and right LABs through direct link interconnect. Figure 2-47 shows an example floorplan for the EP1AGX90 device and the location of the M-RAM interfaces. Figures 2-48 and 2-49 show the interface between the M-RAM block and the logic array.

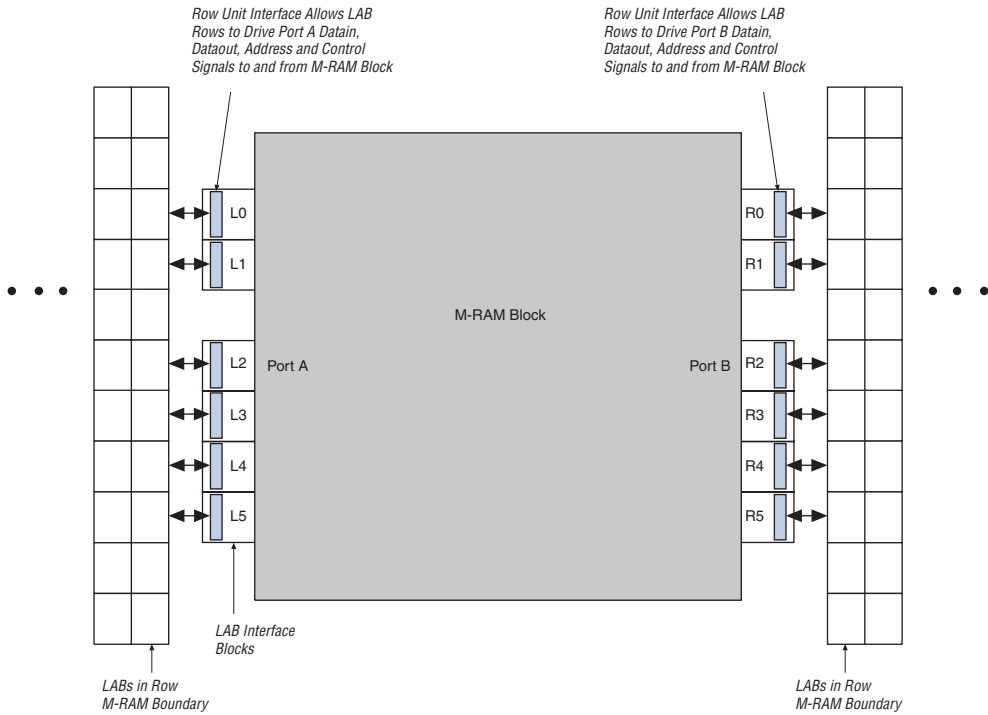
Figure 2–47. EP1AGX90 Device with M-RAM Interface Locations *Note (1)*



Note to Figure 2–47:

(1) The device shown is an EP1AGX90 device. The number and position of M-RAM blocks vary in other devices.

Figure 2-48. M-RAM Block LAB Row Interface *Note (1)*



Note to Figure 2-48:

(1) Only R24 and C16 interconnects cross the M-RAM block boundaries.

Figure 2-49. M-RAM Row Unit Interface to Interconnect

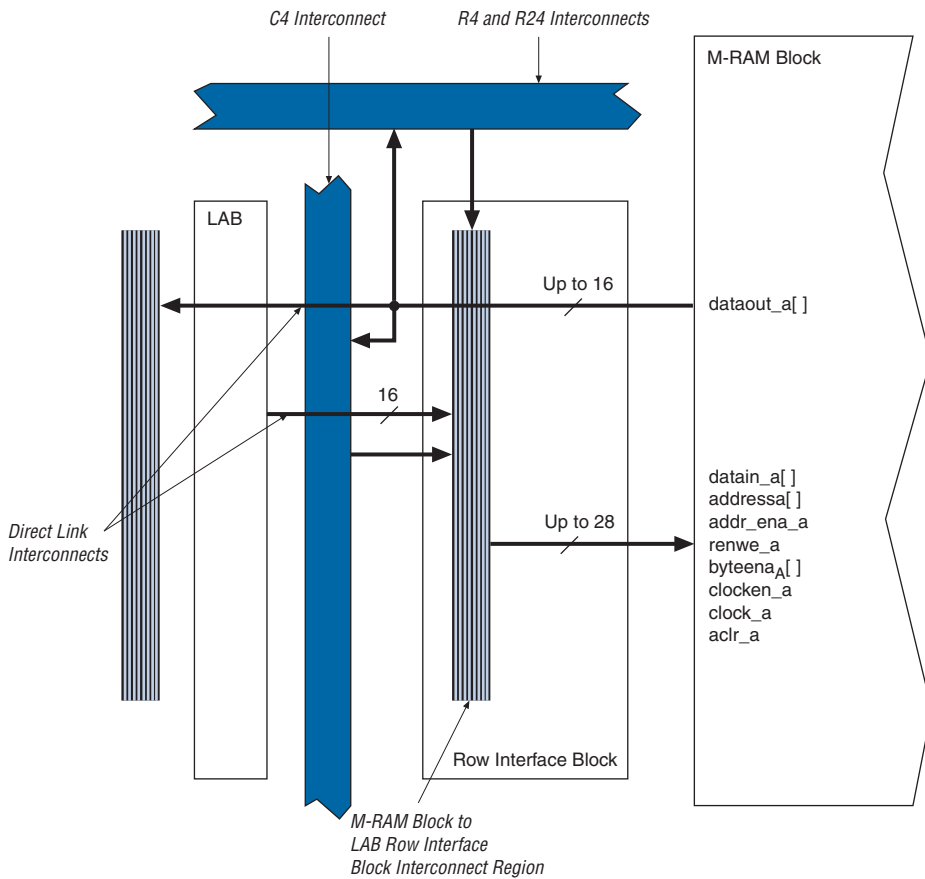


Table 2–12 shows the input and output data signal connections along with the address and control signal input connections to the row unit interfaces (L0 to L5 and R0 to R5).

| Unit Interface Block | Input Signals | Output Signals |
|-----------------------------|---|-----------------------|
| L0 | datain_a[14..0] byteena_a[1..0] | dataout_a[11..0] |
| L1 | datain_a[29..15] byteena_a[3..2] | dataout_a[23..12] |
| L2 | datain_a[35..30] addressa[4..0] addr_ena_a clock_a clocken_a renwe_a aclr_a | dataout_a[35..24] |
| L3 | addressa[15..5] datain_a[41..36] | dataout_a[47..36] |
| L4 | datain_a[56..42] byteena_a[5..4] | dataout_a[59..48] |
| L5 | datain_a[71..57] byteena_a[7..6] | dataout_a[71..60] |
| R0 | datain_b[14..0] byteena_b[1..0] | dataout_b[11..0] |
| R1 | datain_b[29..15] byteena_b[3..2] | dataout_b[23..12] |
| R2 | datain_b[35..30] addressb[4..0] addr_ena_b clock_b clocken_b renwe_b aclr_b | dataout_b[35..24] |
| R3 | addressb[15..5] datain_b[41..36] | dataout_b[47..36] |
| R4 | datain_b[56..42] byteena_b[5..4] | dataout_b[59..48] |
| R5 | datain_b[71..57] byteena_b[7..6] | dataout_b[71..60] |



For more information about TriMatrix memory, refer to the *TriMatrix Embedded Memory Blocks in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

Digital Signal Processing Block

The most commonly used DSP functions are finite impulse response (FIR) filters, complex FIR filters, infinite impulse response (IIR) filters, fast Fourier transform (FFT) functions, direct cosine transform (DCT) functions, and correlators. All of these use the multiplier as the fundamental building block. Additionally, some applications need specialized operations such as multiply-add and multiply-accumulate operations. Arria GX devices provide DSP blocks to meet the arithmetic requirements of these functions.

Each Arria GX device has two to four columns of DSP blocks to efficiently implement DSP functions faster than ALM-based implementations. Each DSP block can be configured to support up to:

- Eight 9×9 -bit multipliers
- Four 18×18 -bit multipliers
- One 36×36 -bit multiplier

As indicated, the Arria GX DSP block can support one 36×36 -bit multiplier in a single DSP block and is true for any combination of signed, unsigned, or mixed sign multiplications.

Figures 2–50 shows one of the columns with surrounding LAB rows.

Figure 2–50. DSP Blocks Arranged in Columns

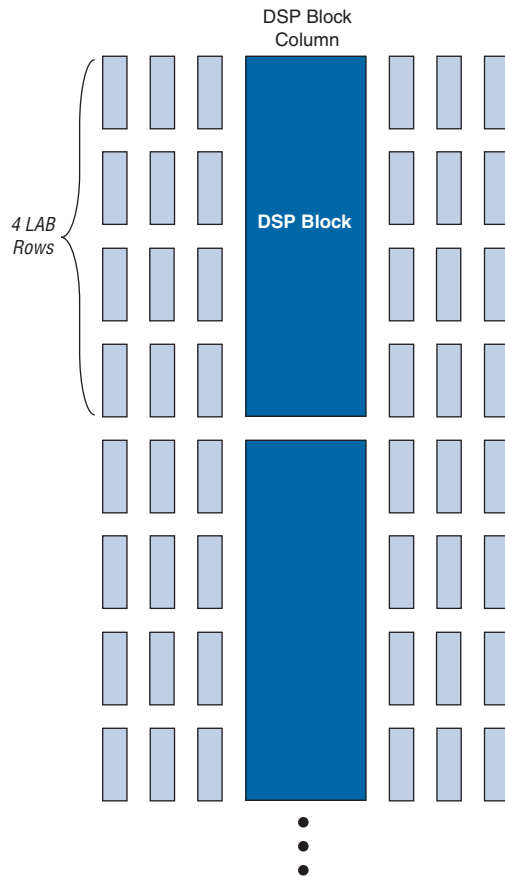


Table 2–13 shows the number of DSP blocks in each Arria GX device. DSP block multipliers can optionally feed an adder/subtractor or accumulator in the block depending on the configuration, which makes routing to ALMs easier, saves ALM routing resources, and increases performance because all connections and blocks are in the DSP block.

Table 2–13. DSP Blocks in Arria GX Devices *Note (1)*

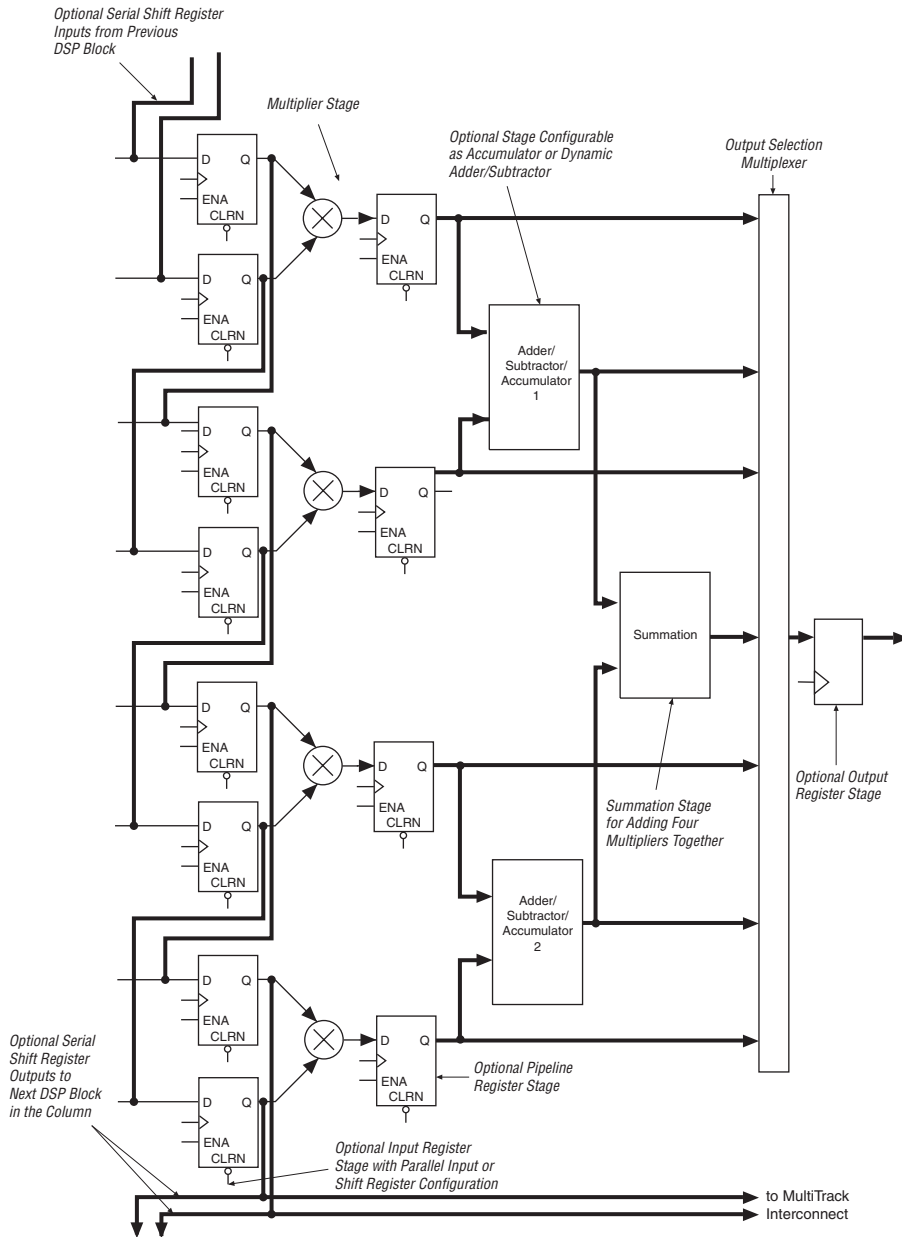
| Device | DSP Blocks | Total 9 × 9 Multipliers | Total 18 × 18 Multipliers | Total 36 × 36 Multipliers |
|----------|------------|-------------------------|---------------------------|---------------------------|
| EP1AGX20 | 10 | 80 | 40 | 10 |
| EP1AGX35 | 14 | 112 | 56 | 14 |
| EP1AGX50 | 26 | 208 | 104 | 26 |
| EP1AGX60 | 32 | 256 | 128 | 32 |
| EP1AGX90 | 44 | 352 | 176 | 44 |

Note to Table 2–13:

- (1) This list only shows functions that can fit into a single DSP block. Multiple DSP blocks can support larger multiplication functions.

Additionally, DSP block input registers can efficiently implement shift registers for FIR filter applications. DSP blocks support Q1.15 format rounding and saturation. Figure 2–51 shows a top-level diagram of the DSP block configured for 18 × 18-bit multiplier mode.

Figure 2–51. DSP Block Diagram for 18 × 18-Bit Configuration



Modes of Operation

The adder, subtractor, and accumulate functions of a DSP block have four modes of operation:

- Simple multiplier
- Multiply-accumulator
- Two-multipliers adder
- Four-multipliers adder

Table 2–14 shows the different number of multipliers possible in each DSP block mode according to size. These modes allow the DSP blocks to implement numerous applications for DSP including FFTs, complex FIR, FIR, 2D FIR filters, equalizers, IIR, correlators, matrix multiplication, and many other functions. DSP blocks also support mixed modes and mixed multiplier sizes in the same block. For example, half of one DSP block can implement one 18×18 -bit multiplier in multiply-accumulator mode, while the other half of the DSP block implements four 9×9 -bit multipliers in simple multiplier mode.

Table 2–14. Multiplier Size and Configurations per DSP Block

| DSP Block Mode | 9×9 | 18×18 | 36×36 |
|------------------------|---|--|--|
| Multiplier | Eight multipliers with eight product outputs | Four multipliers with four product outputs | One multiplier with one product output |
| Multiply-accumulator | — | Two 52-bit multiply-accumulate blocks | — |
| Two-multipliers adder | Four two-multiplier adder (two 9×9 complex multiply) | Two two-multiplier adder (one 18×18 complex multiply) | — |
| Four-multipliers adder | Two four-multiplier adder | One four-multiplier adder | — |

DSP Block Interface

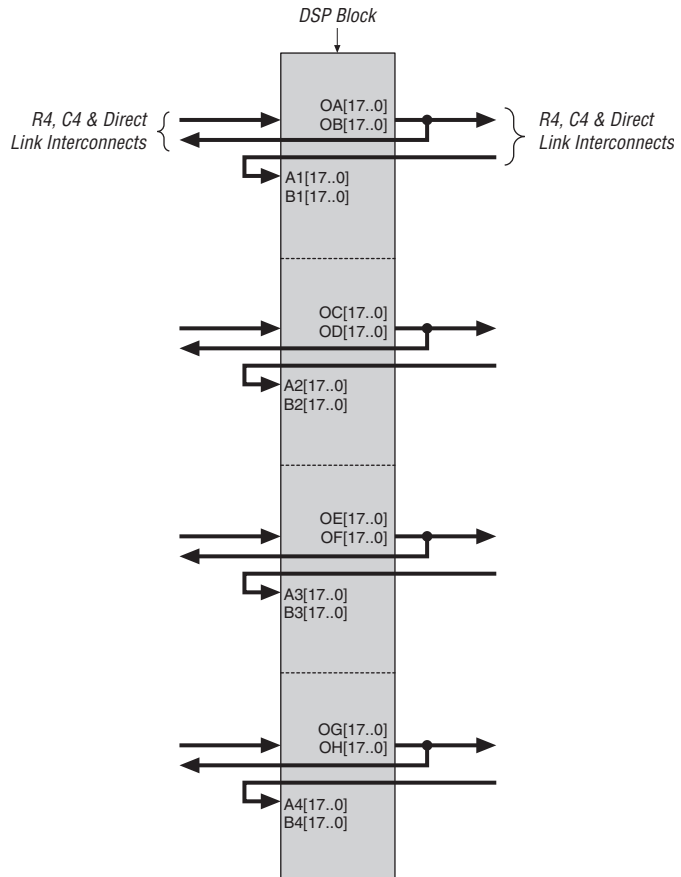
The Arria GX device DSP block input registers can generate a shift register that can cascade down in the same DSP block column. Dedicated connections between DSP blocks provide fast connections between shift register inputs to cascade shift register chains. You can cascade registers within multiple DSP blocks for 9×9 - or 18×18 -bit FIR filters larger than four taps, with additional adder stages implemented in ALMs. If the DSP block is configured as 36×36 bits, the adder, subtractor, or accumulator stages are implemented in ALMs. Each DSP block can route the shift register chain out of the block to cascade multiple columns of DSP blocks.

The DSP block is divided into four block units that interface with four LAB rows on the left and right. Each block unit can be considered one complete 18×18 -bit multiplier with 36 inputs and 36 outputs. A local interconnect region is associated with each DSP block. Like a LAB, this interconnect region can be fed with 16 direct link interconnects from the LAB to the left or right of the DSP block in the same row. R4 and C4 routing resources can access the DSP block's local interconnect region.

The outputs also work similarly to LAB outputs as well. Eighteen outputs from the DSP block can drive to the left LAB through direct link interconnects and 18 can drive to the right LAB through direct link interconnects. All 36 outputs can drive to R4 and C4 routing interconnects. Outputs can drive right- or left-column routing.

Figures 2–52 and 2–53 show the DSP block interfaces to LAB rows.

Figure 2–52. DSP Block Interconnect Interface





For more information about DSP blocks, refer to the *DSP Blocks in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

| Table 2–15. DSP Block Signal Sources and Destinations | | | |
|--|--|--------------------------|--------------------------|
| LAB Row at Interface | Control Signals Generated | Data Inputs | Data Outputs |
| 0 | clock0 aclr0 ena0 mult01_saturate addnsub1_round/ accum_round addnsub1 signa sourcea sourceb | A1 [17..0] B1 [17..0] | OA [17..0] OB [17..0] |
| 1 | clock1 aclr1 ena1 accum_saturate mult01_round accum_sload sourcea sourceb mode0 | A2 [17..0] B2 [17..0] | OC [17..0] OD [17..0] |
| 2 | clock2 aclr2 ena2 mult23_saturate addnsub3_round/ accum_round addnsub3 sign_b sourcea sourceb | A3 [17..0] B3 [17..0] | OE [17..0] OF [17..0] |
| 3 | clock3 aclr3 ena3 accum_saturate mult23_round accum_sload sourcea sourceb mode1 | A4 [17..0] B4 [17..0] | OG [17..0] OH [17..0] |

PLLs and Clock Networks

Arria GX devices provide a hierarchical clock structure and multiple phase-locked loops (PLLs) with advanced features. The large number of clocking resources in combination with the clock synthesis precision provided by enhanced and fast PLLs provides a complete clock management solution.

Global and Hierarchical Clocking

Arria GX devices provide 16 dedicated global clock networks and 32 regional clock networks (eight per device quadrant). These clocks are organized into a hierarchical clock structure that allows for up to 24 clocks per device region with low skew and delay. This hierarchical clocking scheme provides up to 48 unique clock domains in Arria GX devices.

There are 12 dedicated clock pins (CLK [15 . . 12] and CLK [7 . . 0]) to drive either the global or regional clock networks. Four clock pins drive each side of the device except the right side, as shown in [Figures 2-54 and 2-55](#). Internal logic and enhanced and fast PLL outputs can also drive the global and regional clock networks. Each global and regional clock has a clock control block, which controls the selection of the clock source and dynamically enables or disables the clock to reduce power consumption. [Table 2-16](#) shows the global and regional clock features.

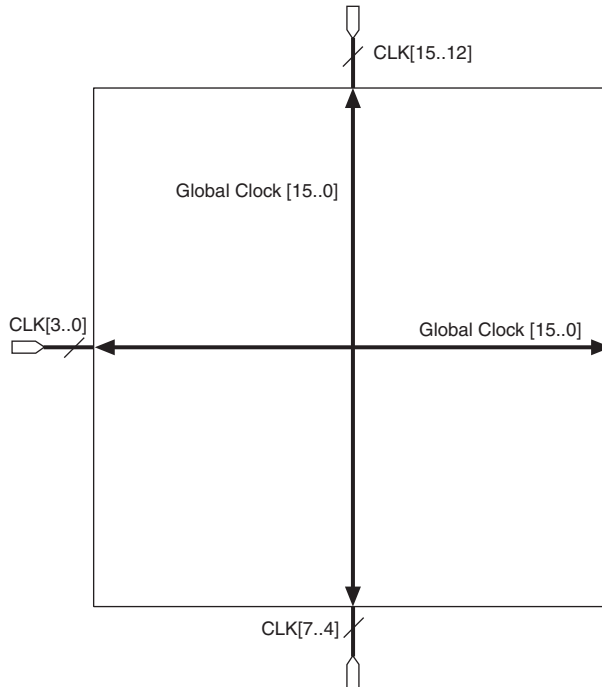
| Table 2-16. Global and Regional Clock Features | | |
|---|--|--|
| Feature | Global Clocks | Regional Clocks |
| Number per device | 16 | 32 |
| Number available per quadrant | 16 | 8 |
| Sources | Clock pins, PLL outputs, core routings, inter-transceiver clocks | Clock pins, PLL outputs, core routings, inter-transceiver clocks |
| Dynamic clock source selection | ✓ | |
| Dynamic enable/disable | ✓ | ✓ |

Global Clock Network

These clocks drive throughout the entire device, feeding all device quadrants. Global clock networks can be used as clock sources for all resources in the device IOEs, ALMs, DSP blocks, and all memory blocks. These resources can also be used for control signals, such as clock enables and synchronous or asynchronous clears fed from the external pin. The global clock networks can also be driven by internal logic for internally

generated global clocks and asynchronous clears, clock enables, or other control signals with large fanout. Figure 2–54 shows the 12 dedicated CLK pins driving global clock networks.

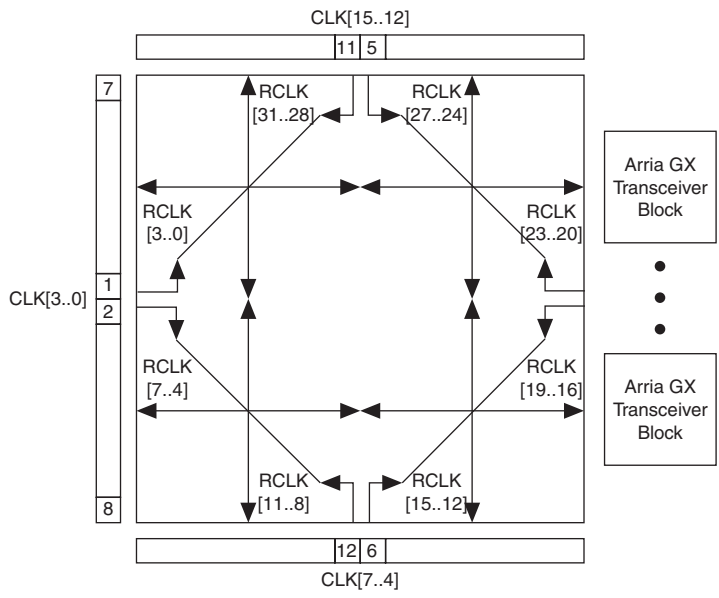
Figure 2–54. Global Clocking



Regional Clock Network

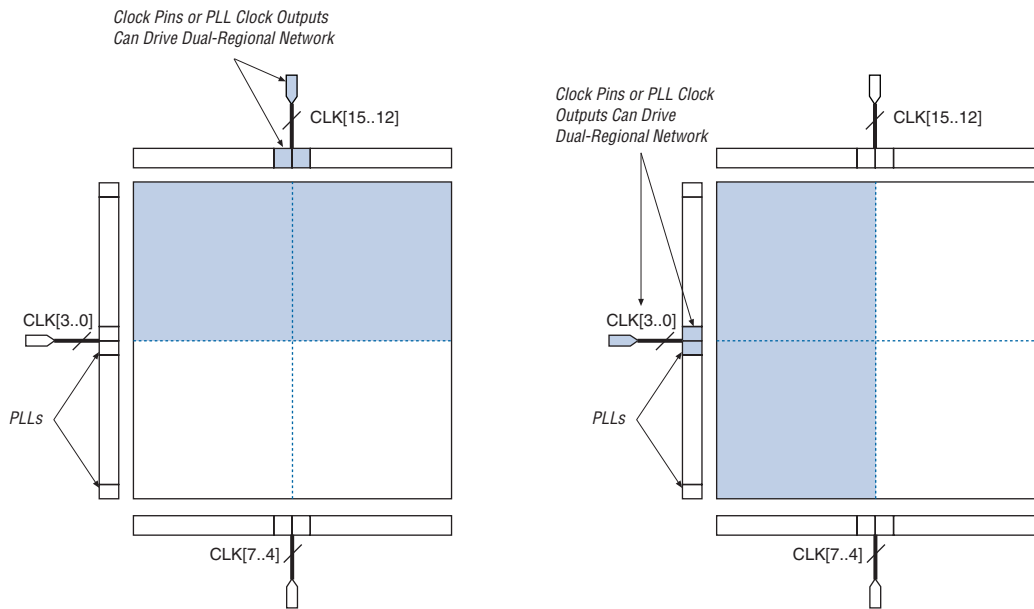
There are eight regional clock networks (RCLK [7 . . 0]) in each quadrant of the Arria GX device that are driven by the dedicated CLK [15 . . 12] and CLK [7 . . 0] input pins, by PLL outputs, or by internal logic. The regional clock networks provide the lowest clock delay and skew for logic contained in a single quadrant. The CLK pins symmetrically drive the RCLK networks in a particular quadrant, as shown in Figure 2–55.

Figure 2–55. Regional Clocks



Dual-Regional Clock Network

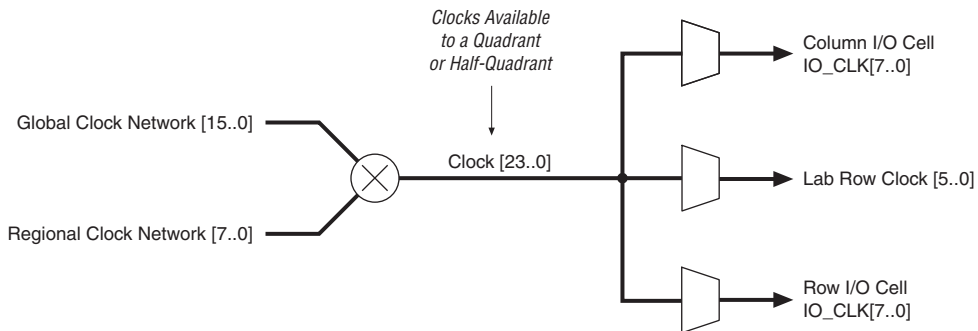
A single source (CLK pin or PLL output) can generate a dual-regional clock by driving two regional clock network lines in adjacent quadrants (one from each quadrant), which allows logic that spans multiple quadrants to utilize the same low skew clock. The routing of this clock signal on an entire side has approximately the same speed but slightly higher clock skew when compared with a clock signal that drives a single quadrant. Internal logic-array routing can also drive a dual-regional clock. Clock pins and enhanced PLL outputs on the top and bottom can drive horizontal dual-regional clocks. Clock pins and fast PLL outputs on the left and right can drive vertical dual-regional clocks, as shown in [Figure 2–56](#). Corner PLLs cannot drive dual-regional clocks.

Figure 2–56. Dual-Regional Clocks

Combined Resources

Within each quadrant, there are 24 distinct dedicated clocking resources consisting of 16 global clock lines and eight regional clock lines. Multiplexers are used with these clocks to form buses to drive LAB row clocks, column IOE clocks, or row IOE clocks. Another multiplexer is used at the LAB level to select three of the six row clocks to feed the ALM registers in the LAB (see [Figure 2–57](#)).

Figure 2–57. Hierarchical Clock Networks Per Quadrant



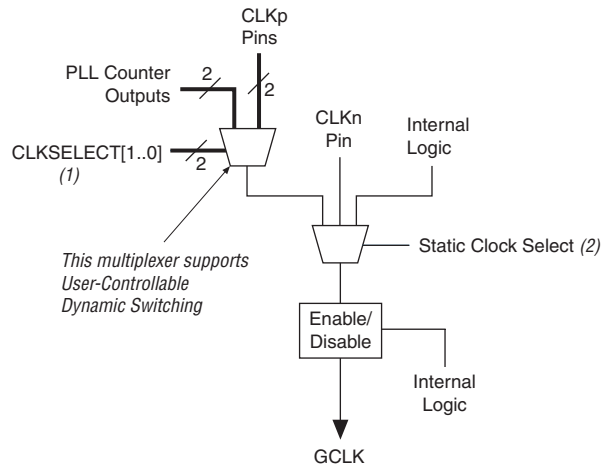
You can use the Quartus II software to control whether a clock input pin drives either a global, regional, or dual-regional clock network. The Quartus II software automatically selects the clocking resources if not specified.

Clock Control Block

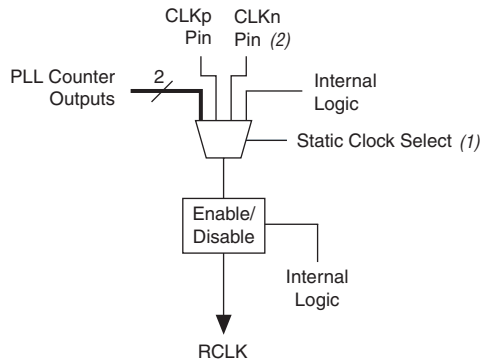
Each global clock, regional clock, and PLL external clock output has its own clock control block. The control block has two functions:

- Clock source selection (dynamic selection for global clocks)
- Clock power-down (dynamic clock enable or disable)

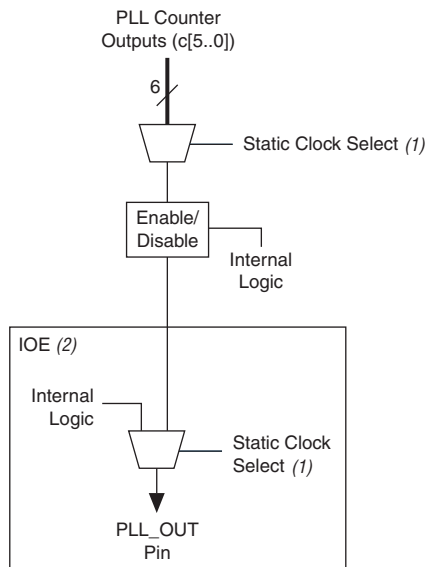
Figures 2–58 through 2–60 show the clock control block for the global clock, regional clock, and PLL external clock output, respectively.

Figure 2–58. Global Clock Control Blocks**Notes to Figure 2–58:**

- (1) These clock select signals can be dynamically controlled through internal logic when the device is operating in user mode.
- (2) These clock select signals can only be set through a configuration file (SRAM Object File [.sof] or Programmer Object File [.pof]) and cannot be dynamically controlled during user mode operation.

Figure 2–59. Regional Clock Control Blocks**Notes to Figure 2–59:**

- (1) These clock select signals can only be set through a configuration file (SOF or POF) and cannot be dynamically controlled during user mode operation.
- (2) Only the CLKn pins on the top and bottom of the device feed to regional clock select.

Figure 2–60. External PLL Output Clock Control Blocks**Notes to Figure 2–60:**

- (1) These clock select signals can only be set through a configuration file (SOF or POF) and cannot be dynamically controlled during user mode operation.
- (2) The clock control block feeds to a multiplexer within the PLL_OUT pin's IOE. The PLL_OUT pin is a dual-purpose pin. Therefore, this multiplexer selects either an internal signal or the output of the clock control block.

For the global clock control block, clock source selection can be controlled either statically or dynamically. You have the option of statically selecting the clock source by using the Quartus II software to set specific configuration bits in the configuration file (SOF or POF) or you can control the selection dynamically by using internal logic to drive the multiplexer select inputs. When selecting statically, the clock source can be set to any of the inputs to the select multiplexer. When selecting the clock source dynamically, you can either select between two PLL outputs (such as the C0 or C1 outputs from one PLL), between two PLLs (such as the C0/C1 clock output of one PLL or the C0/C1 clock output of the other PLL), between two clock pins (such as CLK0 or CLK1), or between a combination of clock pins or PLL outputs.

For the regional and PLL_OUT clock control block, clock source selection can only be controlled statically using configuration bits. Any of the inputs to the clock select multiplexer can be set as the clock source.

Arria GX clock networks can be disabled (powered down) by both static and dynamic approaches. When a clock net is powered down, all the logic fed by the clock net is in an off-state thereby reducing the overall power consumption of the device. Global and regional clock networks can be powered down statically through a setting in the configuration file (SOF or POF). Clock networks that are not used are automatically powered down through configuration bit settings in the configuration file generated by the Quartus II software. The dynamic clock enable or disable feature allows the internal logic to control power up/down synchronously on GCLK and RCLK nets and PLL_OUT pins. This function is independent of the PLL and is applied directly on the clock network or PLL_OUT pin, as shown in [Figures 2-58 through 2-60](#).

Enhanced and Fast PLLs

Arria GX devices provide robust clock management and synthesis using up to four enhanced PLLs and four fast PLLs. These PLLs increase performance and provide advanced clock interfacing and clock frequency synthesis. With features such as clock switchover, spread spectrum clocking, reconfigurable bandwidth, phase control, and reconfigurable phase shifting, the Arria GX device's enhanced PLLs provide you with complete control of your clocks and system timing. The fast PLLs provide general purpose clocking with multiplication and phase shifting as well as high-speed outputs for high-speed differential I/O support. Enhanced and fast PLLs work together with the Arria GX high-speed I/O and advanced clock architecture to provide significant improvements in system performance and bandwidth.

The Quartus II software enables the PLLs and their features without requiring any external devices. Table 2–17 shows the PLLs available for each Arria GX device and their type.

Table 2–17. Arria GX Device PLL Availability *Notes (1), (2)*

| Device | Fast PLLs | | | | | | | | Enhanced PLLs | | | |
|--------------|-----------|---|-------|-------|---|---|-------|--------|---------------|---|----|----|
| | 1 | 2 | 3 (3) | 4 (3) | 7 | 8 | 9 (3) | 10 (3) | 5 | 6 | 11 | 12 |
| EP1AGX20 | ✓ | ✓ | | | | | | | ✓ | ✓ | | |
| EP1AGX35 | ✓ | ✓ | | | | | | | ✓ | ✓ | | |
| EP1AGX50 (4) | ✓ | ✓ | | | ✓ | ✓ | | | ✓ | ✓ | ✓ | ✓ |
| EP1AGX60(5) | ✓ | ✓ | | | ✓ | ✓ | | | ✓ | ✓ | ✓ | ✓ |
| EP1AGX90 | ✓ | ✓ | | | ✓ | ✓ | | | ✓ | ✓ | ✓ | ✓ |

Notes to Table 2–17:

- (1) The global or regional clocks in a fast PLL's transceiver block can drive the fast PLL input. A pin or other PLL must drive the global or regional source. The source cannot be driven by internally generated logic before driving the fast PLL.
- (2) EP1AGX20C, EP1AGX35C/D, EP1AGX50C and EP1AGX60C/D devices only have two fast PLLs (PLLs 1 and 2), but the connectivity from these two PLLs to the global and regional clock networks remains the same as shown in this table.
- (3) PLLs 3, 4, 9, and 10 are not available in Arria GX devices.
- (4) 4 or 8 PLLs are available depending on C or D device and the package option.
- (5) 4 or 8 PLLs are available depending on C, D, or E device option.

Table 2–18 shows the enhanced PLL and fast PLL features in Arria GX devices.

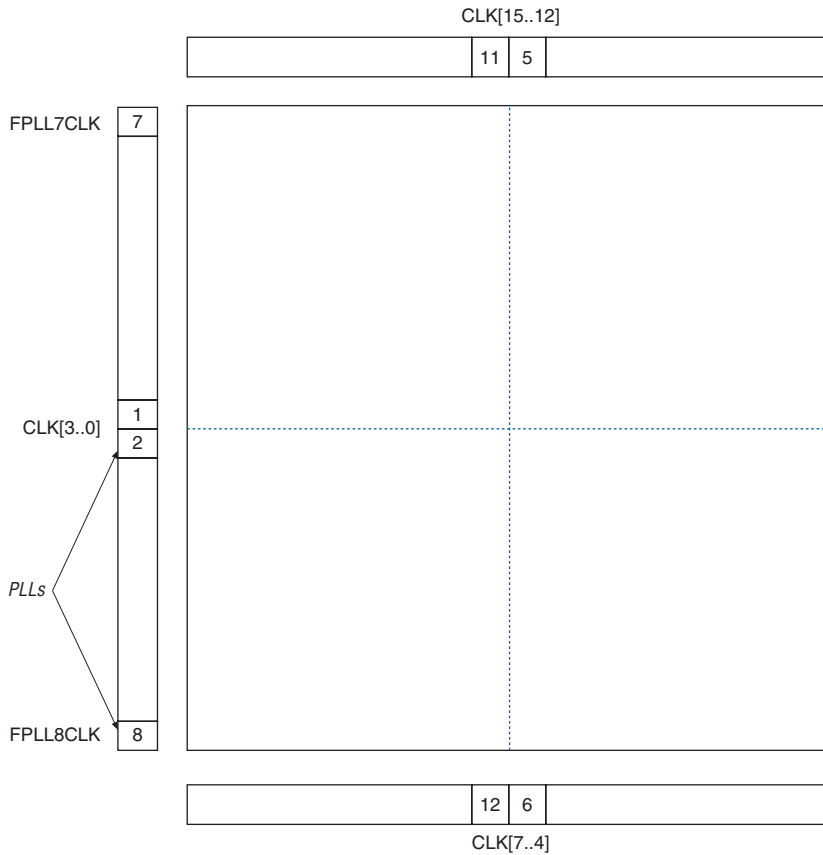
| Feature | Enhanced PLL | Fast PLL |
|-----------------------------------|--|--|
| Clock multiplication and division | $m/(n \times \text{post-scale counter})$ (1) | $m/(n \times \text{post-scale counter})$ (2) |
| Phase shift | Down to 125-ps increments (3), (4) | Down to 125-ps increments (3), (4) |
| Clock switchover | ✓ | ✓ (5) |
| PLL reconfiguration | ✓ | ✓ |
| Reconfigurable bandwidth | ✓ | ✓ |
| Spread spectrum clocking | ✓ | |
| Programmable duty cycle | ✓ | ✓ |
| Number of internal clock outputs | 6 | 4 |
| Number of external clock outputs | Three differential/six single-ended | (6) |
| Number of feedback clock inputs | One single-ended or differential (7), (8) | |

Notes to Table 2–18:

- (1) For enhanced PLLs, m , n range from 1 to 256 and post-scale counters range from 1 to 512 with 50% duty cycle.
- (2) For fast PLLs, m , and post-scale counters range from 1 to 32. The n counter ranges from 1 to 4.
- (3) The smallest phase shift is determined by the voltage controlled oscillator (V_{CO}) period divided by 8.
- (4) For degree increments, Arria GX devices can shift all output frequencies in increments of at least 45. Smaller degree increments are possible depending on the frequency and divide parameters.
- (5) Arria GX fast PLLs only support manual clock switchover.
- (6) Fast PLLs can drive to any I/O pin as an external clock. For high-speed differential I/O pins, the device uses a data channel to generate `txclkout`.
- (7) If the feedback input is used, you will lose one (or two, if f_{BIN} is differential) external clock output pin.
- (8) Every Arria GX device has at least two enhanced PLLs with one single-ended or differential external feedback input per PLL.

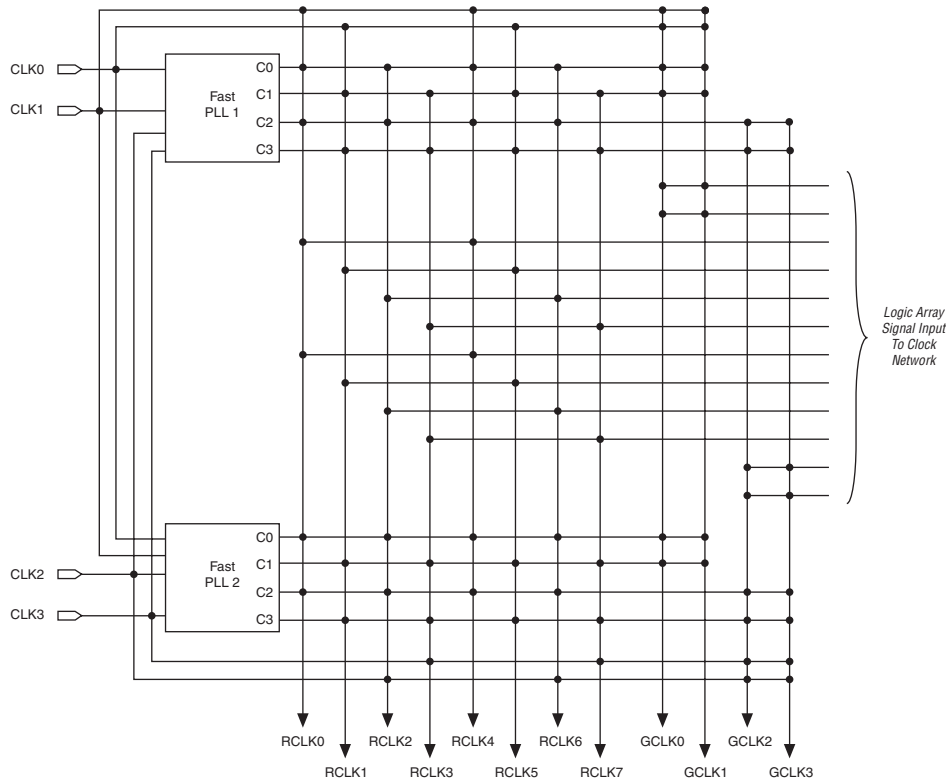
Figure 2–61 shows a top-level diagram of the Arria GX device and PLL floorplan.

Figure 2–61. PLL Locations



Figures 2–62 and 2–63 shows global and regional clocking from the fast PLL outputs and side clock pins. The connections to the global and regional clocks from the fast PLL outputs, internal drivers, and CLK pins on the left side of the device are shown in Table 2–19.

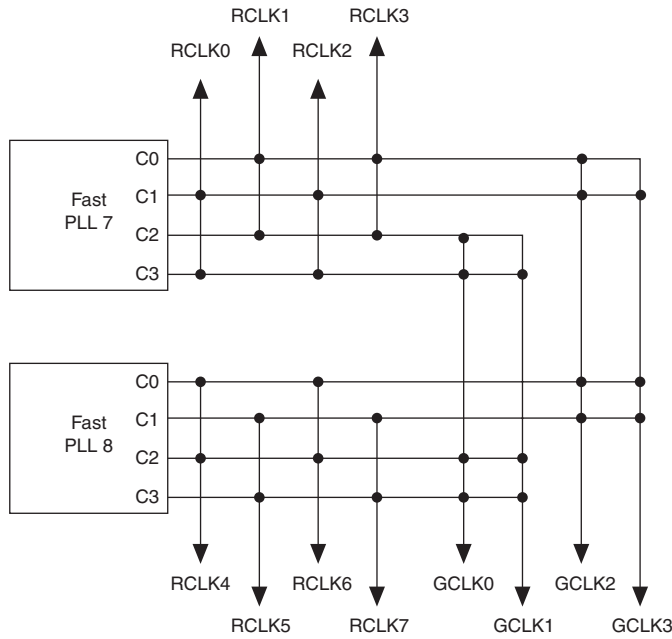
Figure 2–62. Global and Regional Clock Connections from Center Clock Pins and Fast PLL Outputs *Note (1)*



Note to Figure 2–62:

- (1) The global or regional clocks in a fast PLL's quadrant can drive the fast PLL input. A dedicated clock input pin or other PLL must drive the global or regional source. The source cannot be driven by internally generated logic before driving the fast PLL.

Figure 2–63. Global and Regional Clock Connections from Corner Clock Pins and Fast PLL Outputs *Note (1)*



Note to Figure 2–63:

- (1) The global or regional clocks in a fast PLL’s quadrant can drive the fast PLL input. A dedicated clock input pin or other PLL must drive the global or regional source. The source cannot be driven by internally generated logic before driving the fast PLL.

Table 2–19. Global and Regional Clock Connections from Left Side Clock Pins and Fast PLL Outputs (Part 1 of 3)

| Left Side Global & Regional Clock Network Connectivity | CLK0 | CLK1 | CLK2 | CLK3 | RCLK0 | RCLK1 | RCLK2 | RCLK3 | RCLK4 | RCLK5 | RCLK6 | RCLK7 |
|--|------|------|------|------|-------|-------|-------|-------|-------|-------|-------|-------|
| Clock Pins | | | | | | | | | | | | |
| CLK0p | ✓ | ✓ | | | ✓ | | | | ✓ | | | |
| CLK1p | ✓ | ✓ | | | | ✓ | | | | ✓ | | |
| CLK2p | | | ✓ | ✓ | | | ✓ | | | | ✓ | |
| CLK3p | | | ✓ | ✓ | | | | ✓ | | | | ✓ |
| Drivers from Internal Logic | | | | | | | | | | | | |

**Table 2–19. Global and Regional Clock Connections from Left Side Clock Pins and Fast PLL Outputs
(Part 2 of 3)**

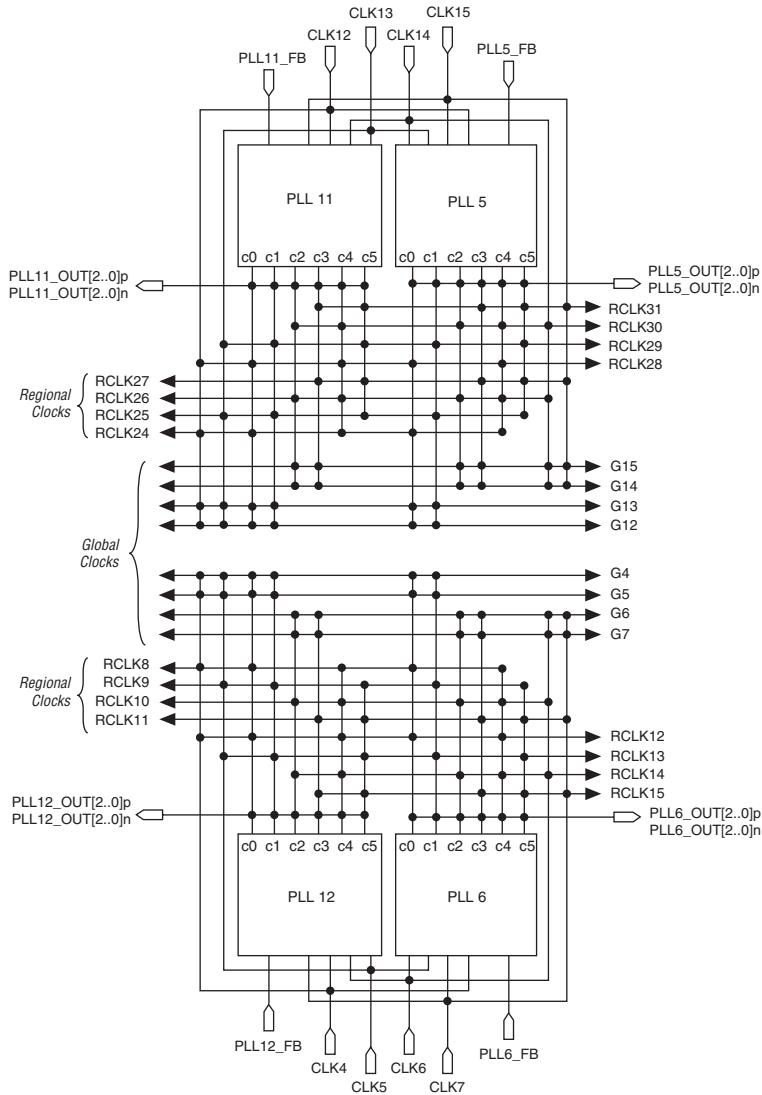
| Left Side Global & Regional Clock Network Connectivity | CLK0 | CLK1 | CLK2 | CLK3 | RCLK0 | RCLK1 | RCLK2 | RCLK3 | RCLK4 | RCLK5 | RCLK6 | RCLK7 |
|--|------|------|------|------|-------|-------|-------|-------|-------|-------|-------|-------|
| GCLKDRV0 | ✓ | ✓ | | | | | | | | | | |
| GCLKDRV1 | ✓ | ✓ | | | | | | | | | | |
| GCLKDRV2 | | | ✓ | ✓ | | | | | | | | |
| GCLKDRV3 | | | ✓ | ✓ | | | | | | | | |
| RCLKDRV0 | | | | | ✓ | | | | ✓ | | | |
| RCLKDRV1 | | | | | | ✓ | | | | ✓ | | |
| RCLKDRV2 | | | | | | | ✓ | | | | ✓ | |
| RCLKDRV3 | | | | | | | | ✓ | | | | ✓ |
| RCLKDRV4 | | | | | ✓ | | | | ✓ | | | |
| RCLKDRV5 | | | | | | ✓ | | | | ✓ | | |
| RCLKDRV6 | | | | | | | ✓ | | | | ✓ | |
| RCLKDRV7 | | | | | | | | ✓ | | | | ✓ |
| PLL 1 Outputs | | | | | | | | | | | | |
| c0 | ✓ | ✓ | | | ✓ | | ✓ | | ✓ | | ✓ | |
| c1 | ✓ | ✓ | | | | ✓ | | ✓ | | ✓ | | ✓ |
| c2 | | | ✓ | ✓ | ✓ | | ✓ | | ✓ | | ✓ | |
| c3 | | | ✓ | ✓ | | ✓ | | ✓ | | ✓ | | ✓ |
| PLL 2 Outputs | | | | | | | | | | | | |
| c0 | ✓ | ✓ | | | | ✓ | | ✓ | | ✓ | | ✓ |
| c1 | ✓ | ✓ | | | ✓ | | ✓ | | ✓ | | ✓ | |
| c2 | | | ✓ | ✓ | | ✓ | | ✓ | | ✓ | | ✓ |
| c3 | | | ✓ | ✓ | ✓ | | ✓ | | ✓ | | ✓ | |
| PLL 7 Outputs | | | | | | | | | | | | |
| c0 | | | ✓ | ✓ | | ✓ | | ✓ | | | | |
| c1 | | | ✓ | ✓ | ✓ | | ✓ | | | | | |
| c2 | ✓ | ✓ | | | | ✓ | | ✓ | | | | |
| c3 | ✓ | ✓ | | | ✓ | | ✓ | | | | | |
| PLL 8 Outputs | | | | | | | | | | | | |

Table 2–19. Global and Regional Clock Connections from Left Side Clock Pins and Fast PLL Outputs (Part 3 of 3)

| Left Side Global & Regional Clock Network Connectivity | CLK0 | CLK1 | CLK2 | CLK3 | RCLK0 | RCLK1 | RCLK2 | RCLK3 | RCLK4 | RCLK5 | RCLK6 | RCLK7 |
|--|------|------|------|------|-------|-------|-------|-------|-------|-------|-------|-------|
| c0 | | | ✓ | ✓ | | | | | ✓ | | ✓ | |
| c1 | | | ✓ | ✓ | | | | | | ✓ | | ✓ |
| c2 | ✓ | ✓ | | | | | | | ✓ | | ✓ | |
| c3 | ✓ | ✓ | | | | | | | | ✓ | | ✓ |

Figure 2–64 shows the global and regional clocking from enhanced PLL outputs and top and bottom CLK pins.

Figure 2–64. Global and Regional Clock Connections from Top and Bottom Clock Pins and Enhanced PLL Outputs *Note (1)*



Note to Figure 2–64:

(1) If the design uses the feedback input, you will lose one (or two if FBIN is differential) external clock output pin.

The connections to the global and regional clocks from the top clock pins and enhanced PLL outputs are shown in Table 2–20. The connections to the clocks from the bottom clock pins are shown in Table 2–21.

Table 2–20. Global and Regional Clock Connections from Top Clock Pins and Enhanced PLL Outputs (Part 1 of 2)

| Top Side Global and Regional Clock Network Connectivity | DLLCLK | CLK12 | CLK13 | CLK14 | CLK15 | RCLK24 | RCLK25 | RCLK26 | RCLK27 | RCLK28 | RCLK29 | RCLK30 | RCLK31 |
|---|--------|-------|-------|-------|-------|--------|--------|--------|--------|--------|--------|--------|--------|
| Clock pins | | | | | | | | | | | | | |
| CLK12p | ✓ | ✓ | ✓ | | | ✓ | | | | ✓ | | | |
| CLK13p | ✓ | ✓ | ✓ | | | | ✓ | | | | ✓ | | |
| CLK14p | ✓ | | | ✓ | ✓ | | | ✓ | | | | ✓ | |
| CLK15p | ✓ | | | ✓ | ✓ | | | | ✓ | | | | ✓ |
| CLK12n | | ✓ | | | | ✓ | | | | ✓ | | | |
| CLK13n | | | ✓ | | | | ✓ | | | | ✓ | | |
| CLK14n | | | | ✓ | | | | ✓ | | | | ✓ | |
| CLK15n | | | | | ✓ | | | | ✓ | | | | ✓ |
| Drivers from internal logic | | | | | | | | | | | | | |
| GCLKDRV0 | | ✓ | | | | | | | | | | | |
| GCLKDRV1 | | | ✓ | | | | | | | | | | |
| GCLKDRV2 | | | | ✓ | | | | | | | | | |
| GCLKDRV3 | | | | | ✓ | | | | | | | | |
| RCLKDRV0 | | | | | | ✓ | | | | ✓ | | | |
| RCLKDRV1 | | | | | | | ✓ | | | | ✓ | | |
| RCLKDRV2 | | | | | | | | ✓ | | | | ✓ | |
| RCLKDRV3 | | | | | | | | | ✓ | | | | ✓ |
| RCLKDRV4 | | | | | | ✓ | | | | ✓ | | | |
| RCLKDRV5 | | | | | | | ✓ | | | | ✓ | | |
| RCLKDRV6 | | | | | | | | ✓ | | | | ✓ | |
| RCLKDRV7 | | | | | | | | | ✓ | | | | ✓ |
| Enhanced PLL5 outputs | | | | | | | | | | | | | |
| c0 | ✓ | ✓ | ✓ | | | ✓ | | | | ✓ | | | |
| c1 | ✓ | ✓ | ✓ | | | | ✓ | | | | ✓ | | |

Table 2–20. Global and Regional Clock Connections from Top Clock Pins and Enhanced PLL Outputs (Part 2 of 2)

| Top Side Global and Regional Clock Network Connectivity | DLLCLK | CLK12 | CLK13 | CLK14 | CLK15 | RCLK24 | RCLK25 | RCLK26 | RCLK27 | RCLK28 | RCLK29 | RCLK30 | RCLK31 |
|---|--------|-------|-------|-------|-------|--------|--------|--------|--------|--------|--------|--------|--------|
| c2 | ✓ | | | ✓ | ✓ | | | ✓ | | | | ✓ | |
| c3 | ✓ | | | ✓ | ✓ | | | | ✓ | | | | ✓ |
| c4 | ✓ | | | | | ✓ | | ✓ | | ✓ | | ✓ | |
| c5 | ✓ | | | | | | ✓ | | ✓ | | ✓ | | ✓ |
| Enhanced PLL 11 outputs | | | | | | | | | | | | | |
| c0 | | ✓ | ✓ | | | ✓ | | | | ✓ | | | |
| c1 | | ✓ | ✓ | | | | ✓ | | | | ✓ | | |
| c2 | | | | ✓ | ✓ | | | ✓ | | | | ✓ | |
| c3 | | | | ✓ | ✓ | | | | ✓ | | | | ✓ |
| c4 | | | | | | ✓ | | ✓ | | ✓ | | ✓ | |
| c5 | | | | | | | ✓ | | ✓ | | ✓ | | ✓ |

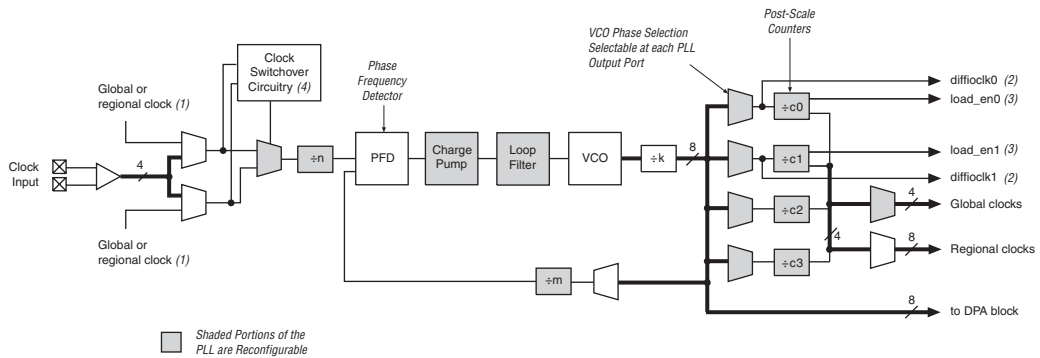
Table 2–21. Global and Regional Clock Connections from Bottom Clock Pins and Enhanced PLL Outputs (Part 1 of 2)

| Bottom Side Global and Regional Clock Network Connectivity | DLLCLK | CLK4 | CLK5 | CLK6 | CLK7 | RCLK8 | RCLK9 | RCLK10 | RCLK11 | RCLK12 | RCLK13 | RCLK14 | RCLK15 |
|--|--------|------|------|------|------|-------|-------|--------|--------|--------|--------|--------|--------|
| Clock pins | | | | | | | | | | | | | |
| CLK4p | ✓ | ✓ | ✓ | | | ✓ | | | | ✓ | | | |
| CLK5p | ✓ | ✓ | ✓ | | | | ✓ | | | | ✓ | | |
| CLK6p | ✓ | | | ✓ | ✓ | | | ✓ | | | | ✓ | |
| CLK7p | ✓ | | | ✓ | ✓ | | | | ✓ | | | | ✓ |
| CLK4n | | ✓ | | | | ✓ | | | | ✓ | | | |
| CLK5n | | | ✓ | | | | ✓ | | | | ✓ | | |
| CLK6n | | | | ✓ | | | | ✓ | | | | ✓ | |
| CLK7n | | | | | ✓ | | | | ✓ | | | | ✓ |
| Drivers from internal logic | | | | | | | | | | | | | |
| GCLKDRV0 | | ✓ | | | | | | | | | | | |
| GCLKDRV1 | | | ✓ | | | | | | | | | | |

Table 2–21. Global and Regional Clock Connections from Bottom Clock Pins and Enhanced PLL Outputs (Part 2 of 2)

| Bottom Side Global and Regional Clock Network Connectivity | DLCLK | CLK4 | CLK5 | CLK6 | CLK7 | RCLK8 | RCLK9 | RCLK10 | RCLK11 | RCLK12 | RCLK13 | RCLK14 | RCLK15 |
|--|-------|------|------|------|------|-------|-------|--------|--------|--------|--------|--------|--------|
| GCLKDRV2 | | | | ✓ | | | | | | | | | |
| GCLKDRV3 | | | | | ✓ | | | | | | | | |
| RCLKDRV0 | | | | | | ✓ | | | | ✓ | | | |
| RCLKDRV1 | | | | | | | ✓ | | | | ✓ | | |
| RCLKDRV2 | | | | | | | | ✓ | | | | ✓ | |
| RCLKDRV3 | | | | | | | | | ✓ | | | | ✓ |
| RCLKDRV4 | | | | | | ✓ | | | | ✓ | | | |
| RCLKDRV5 | | | | | | | ✓ | | | | ✓ | | |
| RCLKDRV6 | | | | | | | | ✓ | | | | ✓ | |
| RCLKDRV7 | | | | | | | | | ✓ | | | | ✓ |
| Enhanced PLL 6 outputs | | | | | | | | | | | | | |
| c0 | ✓ | ✓ | ✓ | | | ✓ | | | | ✓ | | | |
| c1 | ✓ | ✓ | ✓ | | | | ✓ | | | | ✓ | | |
| c2 | ✓ | | | ✓ | ✓ | | | ✓ | | | | ✓ | |
| c3 | ✓ | | | ✓ | ✓ | | | | ✓ | | | | ✓ |
| c4 | ✓ | | | | | ✓ | | ✓ | | ✓ | | ✓ | |
| c5 | ✓ | | | | | | ✓ | | ✓ | | ✓ | | ✓ |
| Enhanced PLL 12 outputs | | | | | | | | | | | | | |
| c0 | | ✓ | ✓ | | | ✓ | | | | ✓ | | | |
| c1 | | ✓ | ✓ | | | | ✓ | | | | ✓ | | |
| c2 | | | | ✓ | ✓ | | | ✓ | | | | ✓ | |
| c3 | | | | ✓ | ✓ | | | | ✓ | | | | ✓ |
| c4 | | | | | | ✓ | | ✓ | | ✓ | | ✓ | |
| c5 | | | | | | | ✓ | | ✓ | | ✓ | | ✓ |

Figure 2–66. Arria GX Device Fast PLL



Notes to Figure 2–66:

- (1) The global or regional clock input can be driven by (1) an output from another PLL, a pin-driven dedicated global or regional clock, or through a clock control block provided the clock control block is fed by an output from another PLL or a pin-driven dedicated global or regional clock. An internally generated global signal cannot drive the PLL.
- (2) In high-speed differential I/O support mode, this high-speed PLL clock feeds the serializer/deserializer (SERDES) circuitry. Arria GX devices only support one rate of data transfer per fast PLL in high-speed differential I/O support mode.
- (3) This signal is a differential I/O SERDES control signal.
- (4) Arria GX fast PLLs only support manual clock switchover.



For more information about enhanced and fast PLLs, refer to the *PLLs in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*. Refer to “[High-Speed Differential I/O with DPA Support](#)” on page 2–124 for more information about high-speed differential I/O support.

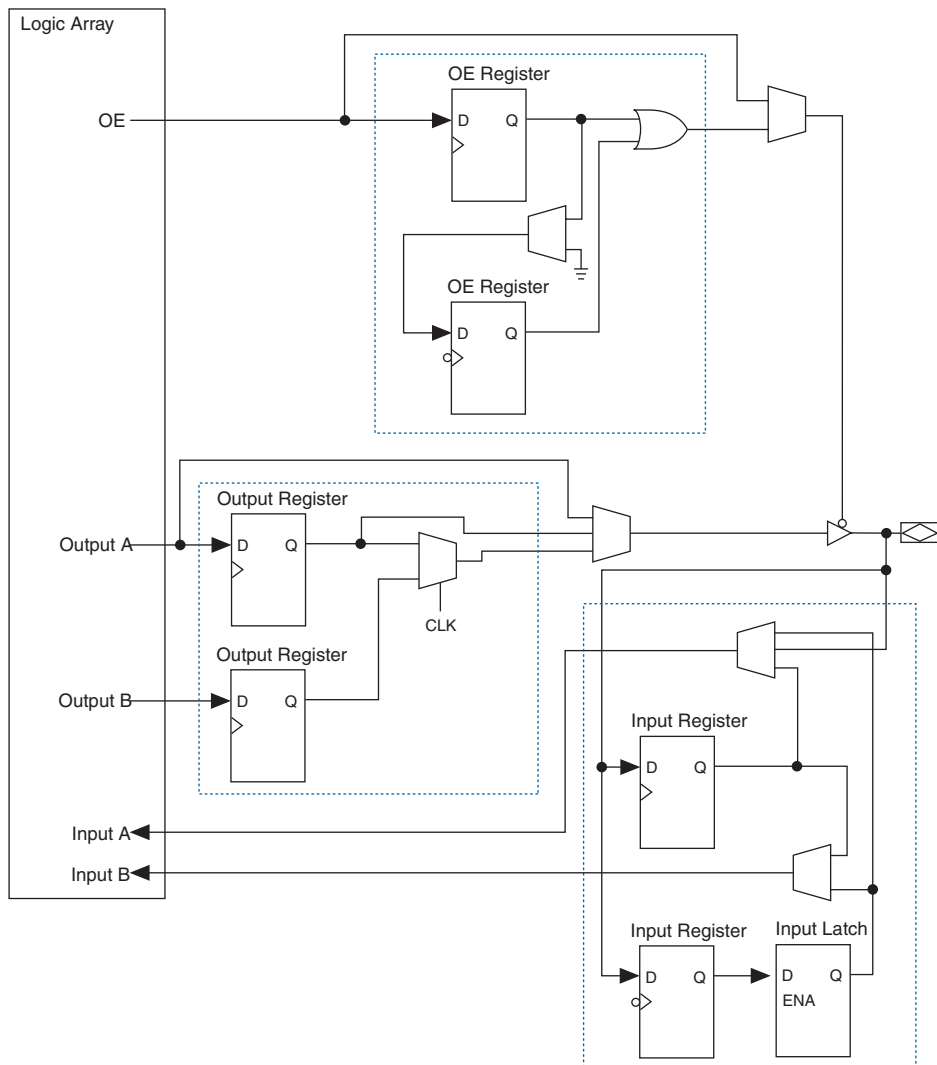
I/O Structure

The Arria GX IOEs provide many features, including:

- Dedicated differential and single-ended I/O buffers
- 3.3-V, 64-bit, 66-MHz PCI compliance
- 3.3-V, 64-bit, 133-MHz PCI-X 1.0 compliance
- Joint Test Action Group (JTAG) boundary-scan test (BST) support
- On-chip driver series termination
- On-chip termination for differential standards
- Programmable pull-up during configuration
- Output drive strength control
- Tri-state buffers
- Bus-hold circuitry
- Programmable pull-up resistors
- Programmable input and output delays
- Open-drain outputs
- DQ and DQS I/O pins
- Double data rate (DDR) registers

The IOE in Arria GX devices contains a bidirectional I/O buffer, six registers, and a latch for a complete embedded bidirectional single data rate or DDR transfer. [Figure 2-67](#) shows the Arria GX IOE structure. The IOE contains two input registers (plus a latch), two output registers, and two output enable registers. The design can use both input registers and the latch to capture DDR input and both output registers to drive DDR outputs. Additionally, the design can use the output enable (OE) register for fast clock-to-output enable timing. The negative edge-clocked OE register is used for DDR SDRAM interfacing. The Quartus II software automatically duplicates a single OE register that controls multiple output or bidirectional pins.

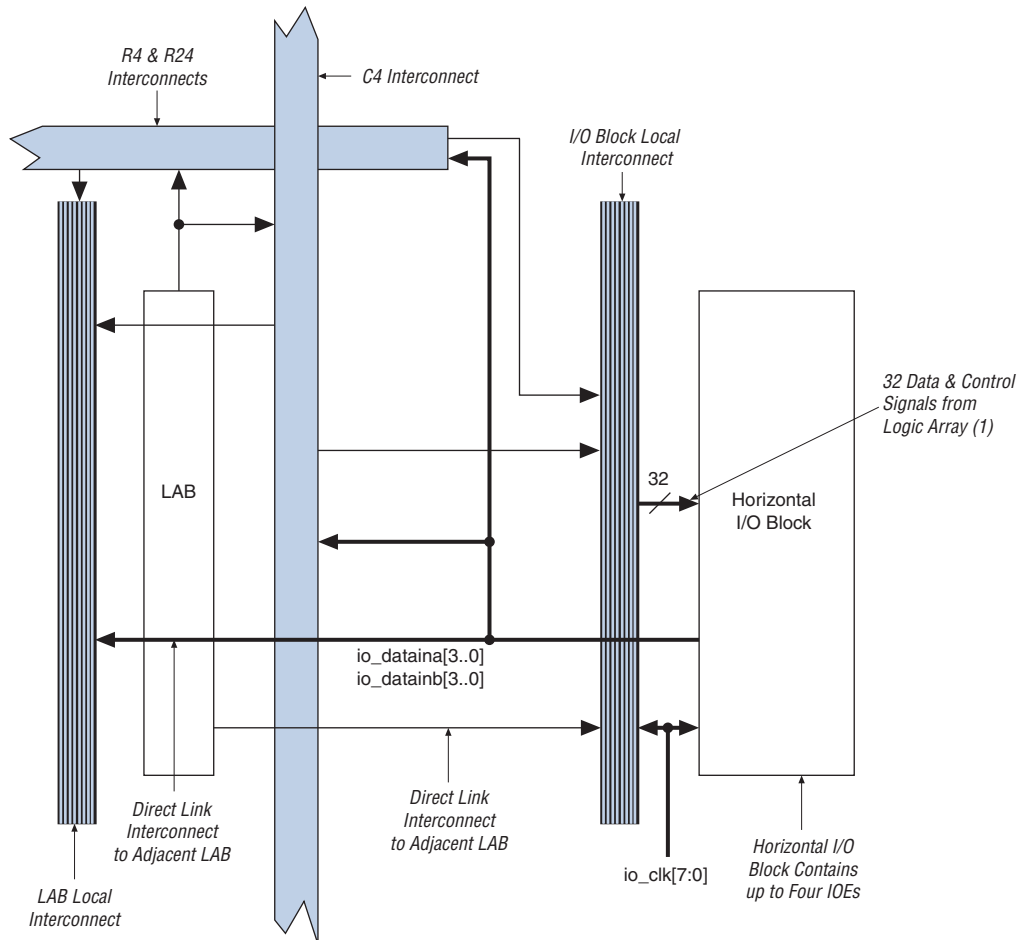
Figure 2-67. Arria GX IOE Structure



The IOEs are located in I/O blocks around the periphery of the Arria GX device. There are up to four IOEs per row I/O block and four IOEs per column I/O block. Row I/O blocks drive row, column, or direct link interconnects. Column I/O blocks drive column interconnects.

Figure 2–68 shows how a row I/O block connects to the logic array.

Figure 2–68. Row I/O Block Connection to the Interconnect

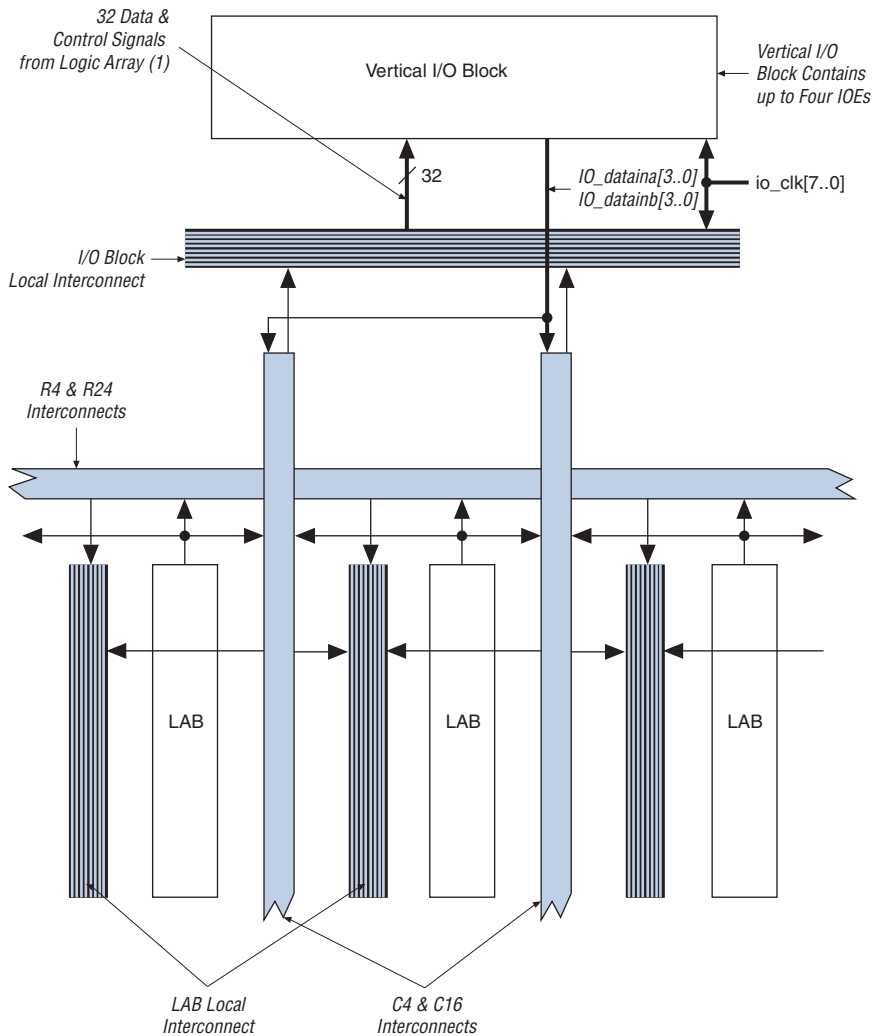


Note to Figure 2–68:

- (1) The 32 data and control signals consist of eight data out lines: four lines each for DDR applications $io_dataouta[3..0]$ and $io_dataoutb[3..0]$, four output enables $io_oe[3..0]$, four input clock enables $io_ce_in[3..0]$, four output clock enables $io_ce_out[3..0]$, four clocks $io_clk[3..0]$, four asynchronous clear and preset signals $io_aclr/apreset[3..0]$, and four synchronous clear and preset signals $io_sclr/spreset[3..0]$.

Figure 2–69 shows how a column I/O block connects to the logic array.

Figure 2–69. Column I/O Block Connection to the Interconnect



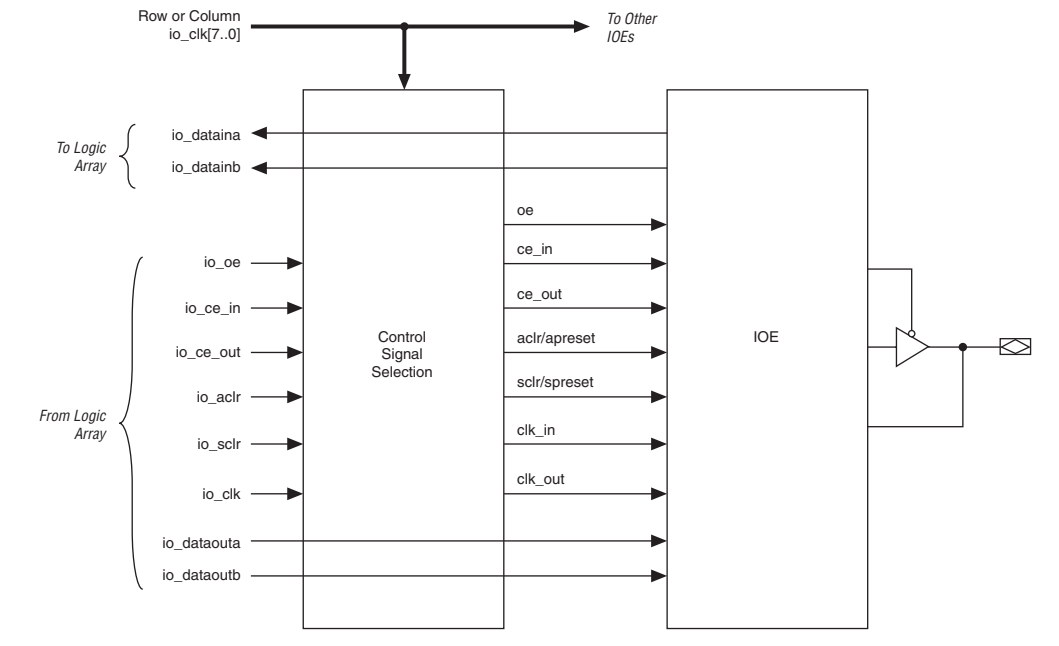
Note to Figure 2–69:

- (1) The 32 data and control signals consist of eight data out lines: four lines each for DDR applications $io_dataouta[3..0]$ and $io_dataoutb[3..0]$, four output enables $io_oe[3..0]$, four input clock enables $io_ce_in[3..0]$, four output clock enables $io_ce_out[3..0]$, four clocks $io_clk[3..0]$, four asynchronous clear and preset signals $io_aclr/apreset[3..0]$, and four synchronous clear and preset signals $io_sclr/spreset[3..0]$.

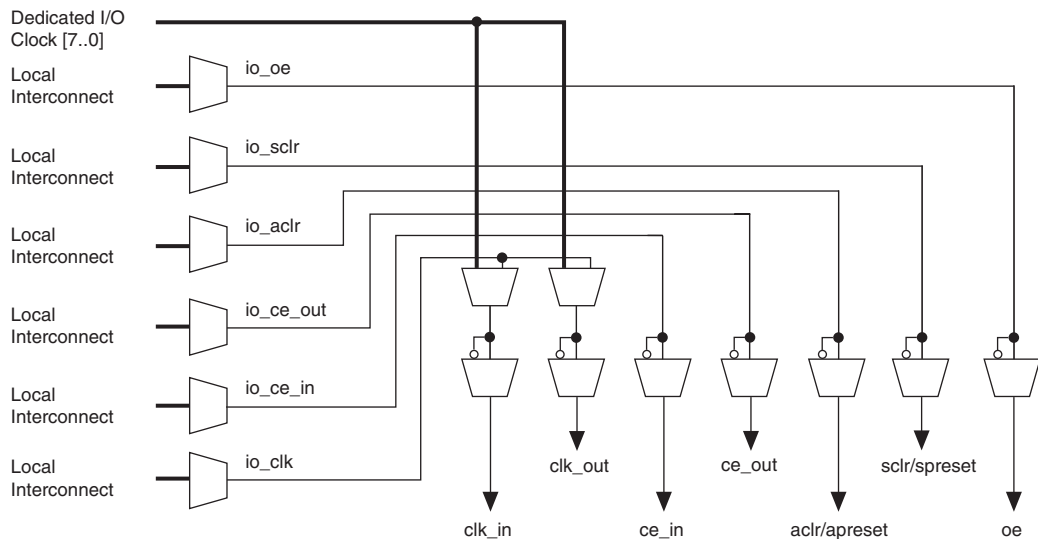
There are 32 control and data signals that feed each row or column I/O block. These control and data signals are driven from the logic array. The row or column IOE clocks, `io_clk[7..0]`, provide a dedicated routing resource for low-skew, high-speed clocks. I/O clocks are generated from global or regional clocks (refer to “PLLs and Clock Networks” on page 2–80).

Figure 2–70 illustrates the signal paths through the I/O block.

Figure 2–70. Signal Path Through the I/O Block



Each IOE contains its own control signal selection for the following control signals: `oe`, `ce_in`, `ce_out`, `aclr/apreset`, `sclr/spreset`, `clk_in`, and `clk_out`. Figure 2–71 illustrates the control signal selection.

Figure 2–71. Control Signal Selection per IOE Note (1)**Notes to Figure 2–71:**

- (1) Control signals `ce_in`, `ce_out`, `aclr/apreset`, `sclr/spreset`, and `oe` can be global signals even though their control selection multiplexers are not directly fed by the `ioe_clk [7..0]` signals. The `ioe_clk` signals can drive the I/O local interconnect, which then drives the control selection multiplexers.

In normal bidirectional operation, you can use the input register for input data requiring fast setup times. The input register can have its own clock input and clock enable separate from the OE and output registers. The output register can be used for data requiring fast clock-to-output performance. You can use the OE register for fast clock-to-output enable timing. The OE and output register share the same clock source and the same clock enable source from the local interconnect in the associated LAB, dedicated I/O clocks, and the column and row interconnects. [Figure 2–72](#) shows the IOE in bidirectional configuration.

A path in which a pin directly drives a register can require the delay to ensure zero hold time, whereas a path in which a pin drives a register through combinational logic may not require the delay. Programmable delays exist for decreasing input-pin-to-logic-array and IOE input register delays. The Quartus II Compiler can program these delays to automatically minimize setup time while providing a zero hold time. Programmable delays can increase the register-to-pin delays for output and/or output enable registers. Programmable delays are no longer required to ensure zero hold times for logic array register-to-IOE register transfers. The Quartus II Compiler can create zero hold time for these transfers. [Table 2–22](#) shows the programmable delays for Arria GX devices.

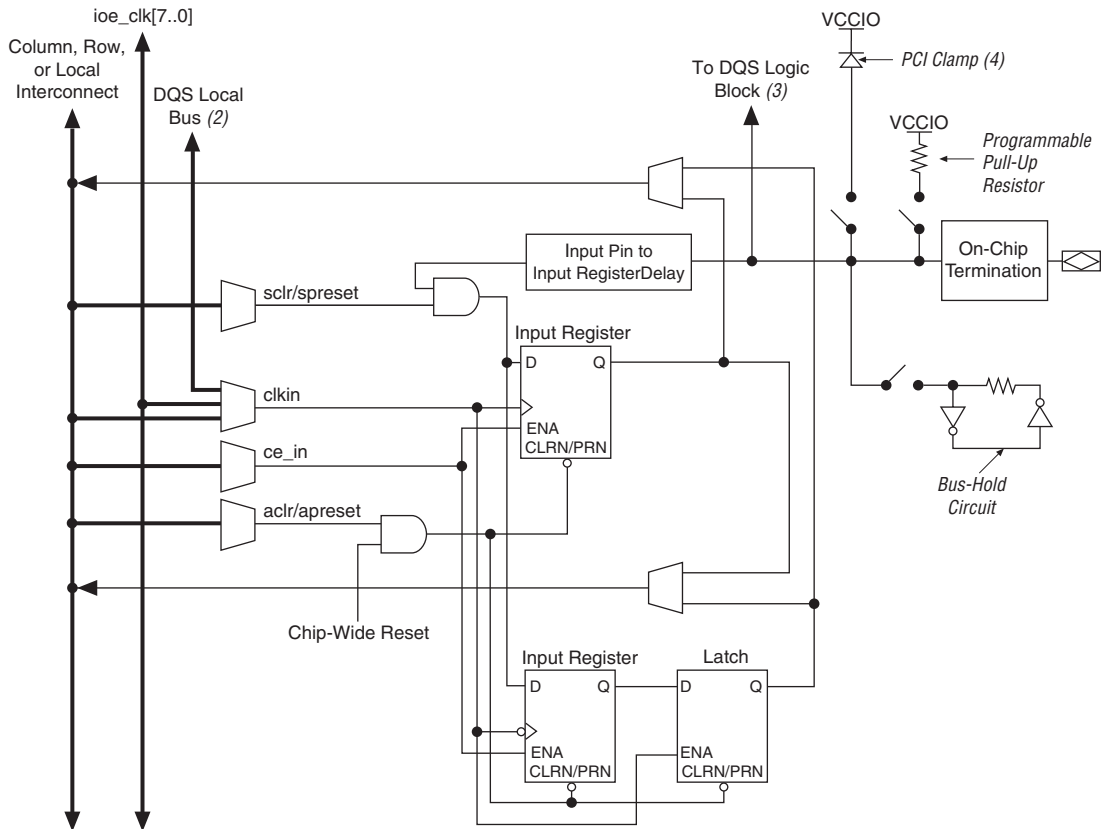
| Programmable Delays | Quartus II Logic Option |
|---------------------------------------|--|
| Input pin to logic array delay | Input delay from pin to internal cells |
| Input pin to input register delay | Input delay from pin to input register |
| Output pin delay | Delay from output register to output pin |
| Output enable register t_{CO} delay | Delay to output enable pin |

IOE registers in Arria GX devices share the same source for clear or preset. You can program preset or clear for each individual IOE. You can also program the registers to power up high or low after configuration is complete. If programmed to power up low, an asynchronous clear can control the registers. If programmed to power up high, an asynchronous preset can control the registers. This feature prevents the inadvertent activation of another device's active-low input upon power-up. If one register in an IOE uses a preset or clear signal, all registers in the IOE must use that same signal if they require preset or clear. Additionally, a synchronous reset signal is available for the IOE registers.

Double Data Rate I/O Pins

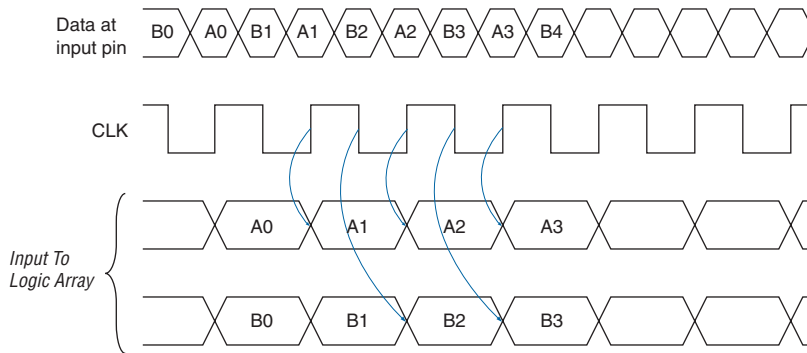
Arria GX devices have six registers in the IOE, which support DDR interfacing by clocking data on both positive and negative clock edges. The IOEs in Arria GX devices support DDR inputs, DDR outputs, and bidirectional DDR modes. When using the IOE for DDR inputs, the two input registers clock double rate input data on alternating edges. An input latch is also used in the IOE for DDR input acquisition. The latch holds the data that is present during the clock high times, allowing both bits of data to be synchronous with the same clock edge (either rising or falling). [Figure 2–73](#) shows an IOE configured for DDR input. [Figure 2–74](#) shows the DDR input timing diagram.

Figure 2-73. Arria GX IOE in DDR Input I/O Configuration *Note (1)*



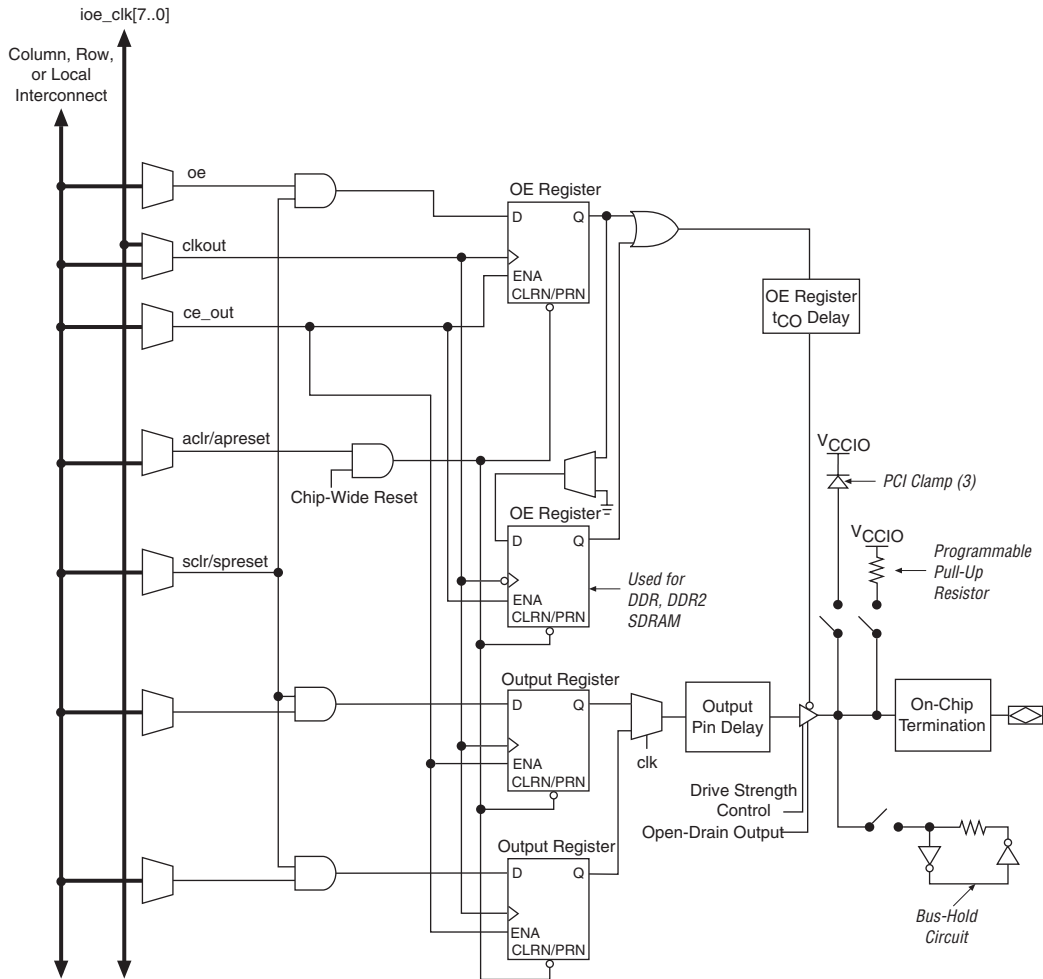
Notes to Figure 2-73:

- (1) All input signals to the IOE can be inverted at the IOE.
- (2) This signal connection is only allowed on dedicated DQ function pins.
- (3) This signal is for dedicated DQS function pins only.
- (4) The optional PCI clamp is only available on column I/O pins.

Figure 2-74. Input Timing Diagram in DDR Mode

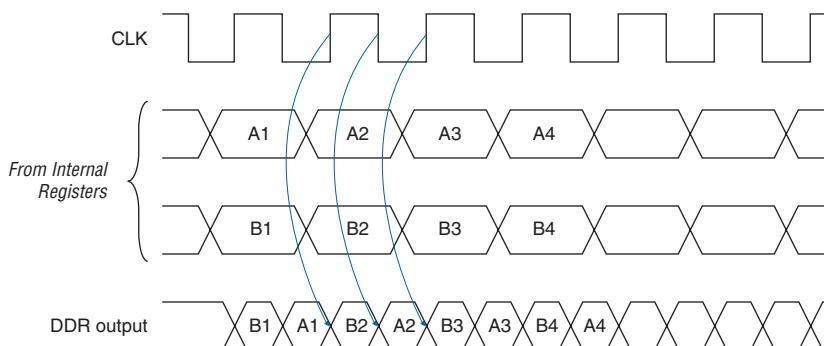
When using the IOE for DDR outputs, the two output registers are configured to clock two data paths from ALMs on rising clock edges. These output registers are multiplexed by the clock to drive the output pin at a $\times 2$ rate. One output register clocks the first bit out on the clock high time, while the other output register clocks the second bit out on the clock low time. [Figure 2-75](#) shows the IOE configured for DDR output. [Figure 2-76](#) shows the DDR output timing diagram.

Figure 2-75. Arria GX IOE in DDR Output I/O Configuration Notes (1), (2)



Notes to Figure 2-75:

- (1) All input signals to the IOE can be inverted at the IOE.
- (2) The tri-state buffer is active low. The DDIO megafunction represents the tri-state buffer as active-high with an inverter at the OE register data port.
- (3) The optional PCI clamp is only available on column I/O pins.

Figure 2–76. Output Timing Diagram in DDR Mode

The Arria GX IOE operates in bidirectional DDR mode by combining the DDR input and DDR output configurations. The negative-edge-clocked OE register holds the OE signal inactive until the falling edge of the clock to meet DDR SDRAM timing requirements.

External RAM Interfacing

In addition to the six I/O registers in each IOE, Arria GX devices also have dedicated phase-shift circuitry for interfacing with external memory interfaces, including DDR, DDR2 SDRAM, and SDR SDRAM. In every Arria GX device, the I/O banks at the top (Banks 3 and 4) and bottom (Banks 7 and 8) of the device support DQ and DQS signals with DQ bus modes of $\times 4$, $\times 8/\times 9$, $\times 16/\times 18$, or $\times 32/\times 36$. Table 2–23 shows the number of DQ and DQS buses that are supported per device.

Table 2–23. DQS and DQ Bus Mode Support (Part 1 of 2) Note (1)

| Device | Package | Number of $\times 4$ Groups | Number of $\times 8/\times 9$ Groups | Number of $\times 16/\times 18$ Groups | Number of $\times 32/\times 36$ Groups |
|-------------|------------------------|-----------------------------|--------------------------------------|--|--|
| EP1AGX20 | 484-pin FineLine BGA | 2 | 0 | 0 | 0 |
| EP1AGX35 | 484-pin FineLine BGA | 2 | 0 | 0 | 0 |
| | 780-pin FineLine BGA | 18 | 8 | 4 | 0 |
| EP1AGX50/60 | 484-pin FineLine BGA | 2 | 0 | 0 | 0 |
| | 780-pin FineLine BGA | 18 | 8 | 4 | 0 |
| | 1,152-pin FineLine BGA | 36 | 18 | 8 | 4 |

Table 2–23. DQS and DQ Bus Mode Support (Part 2 of 2) Note (1)

| Device | Package | Number of ×4 Groups | Number of ×8/×9 Groups | Number of ×16/×18 Groups | Number of ×32/×36 Groups |
|----------|------------------------|------------------------|---------------------------|--------------------------------|--------------------------------|
| EP1AGX90 | 1,152-pin FineLine BGA | 36 | 18 | 8 | 4 |

Note to [Table 2–23](#):

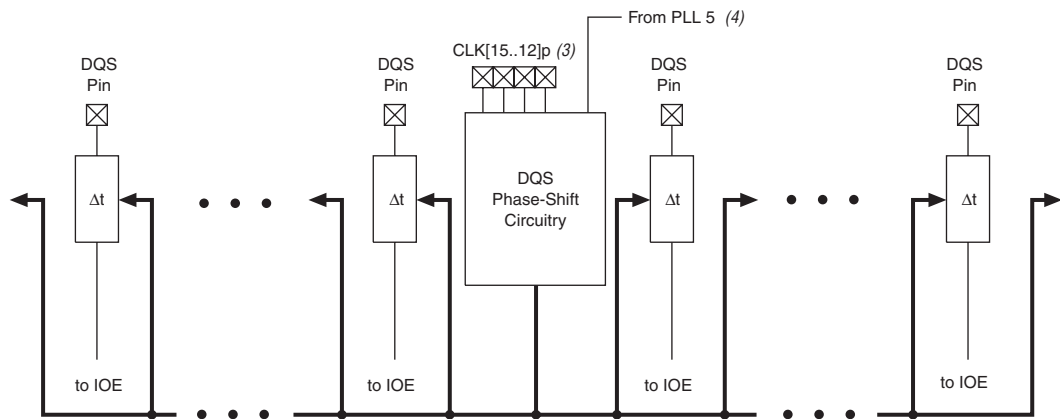
(1) Numbers are preliminary until devices are available.

A compensated delay element on each DQS pin automatically aligns input DQS synchronization signals with the data window of their corresponding DQ data signals. The DQS signals drive a local DQS bus in the top and bottom I/O banks. This DQS bus is an additional resource to the I/O clocks and is used to clock DQ input registers with the DQS signal.

The Arria GX device has two phase-shifting reference circuits, one on the top and one on the bottom of the device. The circuit on the top controls the compensated delay elements for all DQS pins on the top. The circuit on the bottom controls the compensated delay elements for all DQS pins on the bottom.

Each phase-shifting reference circuit is driven by a system reference clock, which must have the same frequency as the DQS signal. Clock pins CLK [15 . . 12] p feed phase circuitry on the top of the device and clock pins CLK [7 . . 4] p feed phase circuitry on the bottom of the device. In addition, PLL clock outputs can also feed the phase-shifting reference circuits. [Figure 2–77](#) shows the phase-shift reference circuit control of each DQS delay shift on the top of the device. This same circuit is duplicated on the bottom of the device.

Figure 2–77. DQS Phase-Shift Circuitry Notes (1), (2)



Notes to Figure 2–77:

- (1) There are up to 18 pairs of DQS pins available on the top or bottom of the Arria GX device. There are up to 10 pairs on the right side and 8 pairs on the left side of the DQS phase-shift circuitry.
- (2) The “t” module represents the DQS logic block.
- (3) Clock pins CLK [15 . . 12] p feed phase-shift circuitry on the top of the device and clock pins CLK [7 . . 4] p feed the phase circuitry on the bottom of the device. You can also use a PLL clock output as a reference clock to phase shift circuitry.
- (4) You can only use PLL 5 to feed the DQS phase-shift circuitry on the top of the device and PLL 6 to feed the DQS phase-shift circuitry on the bottom of the device.

These dedicated circuits combined with enhanced PLL clocking and phase-shift ability provide a complete hardware solution for interfacing to high-speed memory.



For more information about external memory interfaces, refer to the *External Memory Interfaces in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

Programmable Drive Strength

The output buffer for each Arria GX device I/O pin has a programmable drive strength control for certain I/O standards. The LVTTTL, LVCMOS, SSTL, and HSTL standards have several levels of drive strength that you can control. The default setting used in the Quartus II software is the maximum current strength setting that is used to achieve maximum I/O performance. For all I/O standards, the minimum setting is the lowest drive strength that guarantees the I_{OH}/I_{OL} of the standard. Using minimum settings provides signal slew rate control to reduce system noise and signal overshoot.

Table 2–24 shows the possible settings for I/O standards with drive strength control.

| I/O Standard | I _{OH} / I _{OL} Current Strength Setting (mA) for Column I/O Pins | I _{OH} / I _{OL} Current Strength Setting (mA) for Row I/O Pins |
|---------------------|---|--|
| 3.3-V LVTTTL | 24, 20, 16, 12, 8, 4 | 12, 8, 4 |
| 3.3-V LVCMOS | 24, 20, 16, 12, 8, 4 | 8, 4 |
| 2.5-V LVTTTL/LVCMOS | 16, 12, 8, 4 | 12, 8, 4 |
| 1.8-V LVTTTL/LVCMOS | 12, 10, 8, 6, 4, 2 | 8, 6, 4, 2 |
| 1.5-V LVCMOS | 8, 6, 4, 2 | 4, 2 |
| SSTL-2 Class I | 12, 8 | 12, 8 |
| SSTL-2 Class II | 24, 20, 16 | 16 |
| SSTL-18 Class I | 12, 10, 8, 6, 4 | 10, 8, 6, 4 |
| SSTL-18 Class II | 20, 18, 16, 8 | — |
| HSTL-18 Class I | 12, 10, 8, 6, 4 | 12, 10, 8, 6, 4 |
| HSTL-18 Class II | 20, 18, 16 | — |
| HSTL-15 Class I | 12, 10, 8, 6, 4 | 8, 6, 4 |
| HSTL-15 Class II | 20, 18, 16 | — |

Note to Table 2–24:

- (1) The Quartus II software default current setting is the maximum setting for each I/O standard.

Open-Drain Output

Arria GX devices provide an optional open-drain (equivalent to an open collector) output for each I/O pin. This open-drain output enables the device to provide system-level control signals (for example, interrupt and write enable signals) that can be asserted by any of several devices.

Bus Hold

Each Arria GX device I/O pin provides an optional bus-hold feature. Bus-hold circuitry can hold the signal on an I/O pin at its last-driven state. Since the bus-hold feature holds the last-driven state of the pin until the next input signal is present, an external pull-up or pull-down resistor is not needed to hold a signal level when the bus is tri-stated.

Bus-hold circuitry also pulls undriven pins away from the input threshold voltage where noise can cause unintended high-frequency switching. You can select this feature individually for each I/O pin. The bus-hold output drives no higher than V_{CCIO} to prevent overdriving signals. If the bus-hold feature is enabled, the programmable pull-up option cannot be used. Disable the bus-hold feature when the I/O pin has been configured for differential signals.

Bus-hold circuitry uses a resistor with a nominal resistance (RBH) of approximately 7 k Ω to pull the signal level to the last-driven state. This information is provided for each V_{CCIO} voltage level. Bus-hold circuitry is active only after configuration. When going into user mode, the bus-hold circuit captures the value on the pin present at the end of configuration.



For the specific sustaining current driven through this resistor and overdrive current used to identify the next-driven input level, refer to the *DC & Switching Characteristics* chapter in volume 1 of the *Arria GX Device Handbook*.

Programmable Pull-Up Resistor

Each Arria GX device I/O pin provides an optional programmable pull-up resistor during user mode. If you enable this feature for an I/O pin, the pull-up resistor (typically 25 k Ω) holds the output to the V_{CCIO} level of the output pin's bank.

Advanced I/O Standard Support

Arria GX device IOEs support the following I/O standards:

- 3.3-V LVTTTL/LVCMOS
- 2.5-V LVTTTL/LVCMOS
- 1.8-V LVTTTL/LVCMOS
- 1.5-V LVCMOS
- 3.3-V PCI
- 3.3-V PCI-X mode 1
- LVDS
- LVPECL (on input and output clocks only)
- Differential 1.5-V HSTL class I and II
- Differential 1.8-V HSTL class I and II
- Differential SSTL-18 class I and II
- Differential SSTL-2 class I and II
- 1.2-V HSTL class I and II
- 1.5-V HSTL class I and II
- 1.8-V HSTL class I and II
- SSTL-2 class I and II
- SSTL-18 class I and II

Table 2–25 describes the I/O standards supported by Arria GX devices.

| I/O Standard | Type | Input Reference Voltage (V_{REF}) (V) | Output Supply Voltage (V_{CCIO}) (V) | Board Termination Voltage (V_{TT}) (V) |
|--|--------------------|---|--|--|
| LVTTTL | Single-ended | - | 3.3 | - |
| LVCMOS | Single-ended | - | 3.3 | - |
| 2.5 V | Single-ended | - | 2.5 | - |
| 1.8 V | Single-ended | - | 1.8 | - |
| 1.5-V LVCMOS | Single-ended | - | 1.5 | - |
| 3.3-V PCI | Single-ended | - | 3.3 | - |
| 3.3-V PCI-X mode 1 | Single-ended | - | 3.3 | - |
| LVDS | Differential | - | 2.5 (3) | - |
| LVPECL (1) | Differential | - | 3.3 | - |
| HyperTransport technology | Differential | - | 2.5 (3) | - |
| Differential 1.5-V HSTL class I and II (2) | Differential | 0.75 | 1.5 | 0.75 |
| Differential 1.8-V HSTL class I and II (2) | Differential | 0.90 | 1.8 | 0.90 |
| Differential SSTL-18 class I and II (2) | Differential | 0.90 | 1.8 | 0.90 |
| Differential SSTL-2 class I and II (2) | Differential | 1.25 | 2.5 | 1.25 |
| 1.2-V HSTL(4) | Voltage-referenced | 0.6 | 1.2 | 0.6 |
| 1.5-V HSTL class I and II | Voltage-referenced | 0.75 | 1.5 | 0.75 |
| 1.8-V HSTL class I and II | Voltage-referenced | 0.9 | 1.8 | 0.9 |
| SSTL-18 class I and II | Voltage-referenced | 0.90 | 1.8 | 0.90 |
| SSTL-2 class I and II | Voltage-referenced | 1.25 | 2.5 | 1.25 |

Notes to Table 2–25:

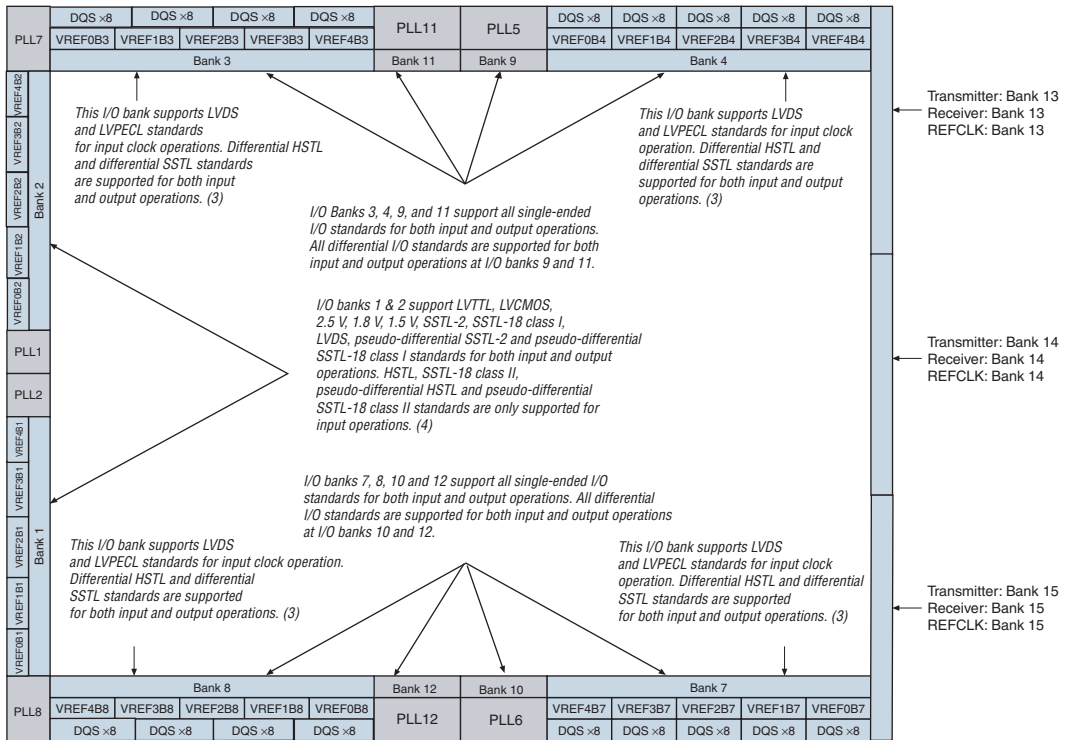
- (1) This I/O standard is only available on input and output column clock pins.
- (2) This I/O standard is only available on input clock pins and DQS pins in I/O banks 3, 4, 7, and 8, and output clock pins in I/O banks 9, 10, 11, and 12.
- (3) V_{CCIO} is 3.3 V when using this I/O standard in input and output column clock pins (in I/O banks 3, 4, 7, 8, 9, 10, 11, and 12).
- (4) 1.2-V HSTL is only supported in I/O banks 4, 7, and 8.



For more information about the I/O standards supported by Arria GX I/O banks, refer to the *Selectable I/O Standards in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

Arria GX devices contain six I/O banks and four enhanced PLL external clock output banks, as shown in Figure 2–78. The two I/O banks on the left of the device contain circuitry to support source-synchronous, high-speed differential I/O for LVDS inputs and outputs. These banks support all Arria GX I/O standards except PCI or PCI-X I/O pins, and SSTL-18 class II and HSTL outputs. The top and bottom I/O banks support all single-ended I/O standards. Additionally, enhanced PLL external clock output banks allow clock output capabilities such as differential support for SSTL and HSTL.

Figure 2–78. Arria GX I/O Banks Notes (1), (2)



Notes to Figure 2–78:

- (1) Figure 2–78 is a top view of the silicon die that corresponds to a reverse view for flip chip packages. It is a graphical representation only.
- (2) Depending on the size of the device, different device members have different numbers of V_{REF} groups. Refer to the pin list and the Quartus II software for exact locations.
- (3) Banks 9 through 12 are enhanced PLL external clock output banks.
- (4) Horizontal I/O banks feature SERDES and DPA circuitry for high-speed differential I/O standards. For more information about differential I/O standards, refer to the *High-Speed Differential I/O Interfaces in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

Each I/O bank has its own V_{CCIO} pins. A single device can support 1.5-, 1.8-, 2.5-, and 3.3-V interfaces; each bank can support a different V_{CCIO} level independently. Each bank also has dedicated V_{REF} pins to support the voltage-referenced standards (such as SSTL-2).

Each I/O bank can support multiple standards with the same V_{CCIO} for input and output pins. Each bank can support one V_{REF} voltage level. For example, when V_{CCIO} is 3.3 V, a bank can support LVTTTL, LVCMOS, and 3.3-V PCI for inputs and outputs.

On-Chip Termination

Arria GX devices provide differential (for the LVDS technology I/O standard) and series on-chip termination to reduce reflections and maintain signal integrity. There is no calibration support for these on-chip termination resistors. On-chip termination simplifies board design by minimizing the number of external termination resistors required. Termination can be placed inside the package, eliminating small stubs that can still lead to reflections.

Arria GX devices provide two types of termination:

- Differential termination (R_D)
- Series termination (R_S)

Table 2–26 shows the Arria GX on-chip termination support per I/O bank.

| On-Chip Termination Support | I/O Standard Support | Top and Bottom Banks (3, 4, 7, 8) | Left Bank (1, 2) |
|------------------------------|---------------------------|--------------------------------------|------------------|
| Series termination | 3.3-V LVTTTL | ✓ | ✓ |
| | 3.3-V LVCMOS | ✓ | ✓ |
| | 2.5-V LVTTTL | ✓ | ✓ |
| | 2.5-V LVCMOS | ✓ | ✓ |
| | 1.8-V LVTTTL | ✓ | ✓ |
| | 1.8-V LVCMOS | ✓ | ✓ |
| | 1.5-V LVTTTL | ✓ | ✓ |
| | 1.5-V LVCMOS | ✓ | ✓ |
| | SSTL-2 class I and II | ✓ | ✓ |
| | SSTL-18 class I | ✓ | ✓ |
| | SSTL-18 class II | ✓ | |
| | 1.8-V HSTL class I | ✓ | ✓ |
| | 1.8-V HSTL class II | ✓ | |
| | 1.5-V HSTL class I | ✓ | ✓ |
| 1.2-V HSTL | ✓ | | |
| Differential termination (1) | LVDS | | ✓ |
| | HyperTransport technology | | ✓ |

Note to Table 2–26:

- (1) Clock pins CLK1 and CLK3, and pins FPLL [7 . . 8] CLK do not support differential on-chip termination. Clock pins CLK0 and CLK2, do support differential on-chip termination. Clock pins in the top and bottom banks (CLK [4 . . 7, 12 . . 15]) do not support differential on-chip termination.

Differential On-Chip Termination

Arria GX devices support internal differential termination with a nominal resistance value of 100 Ω for LVDS input receiver buffers. LVPECL input signals (supported on clock pins only) require an external termination resistor. Differential on-chip termination is supported across the full range of supported differential data rates as shown in the *High-Speed I/O Specifications* section of the *DC & Switching Characteristics* chapter in volume 1 of the *Arria GX Device Handbook*.



For more information about differential on-chip termination, refer to the *High-Speed Differential I/O Interfaces with DPA in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

For more information about tolerance specifications for differential on-chip termination, refer to the *DC & Switching Characteristics* chapter in volume 1 of the *Arria GX Device Handbook*.

On-Chip Series Termination

Arria GX devices support driver impedance matching to provide the I/O driver with controlled output impedance that closely matches the impedance of the transmission line. As a result, reflections can be significantly reduced. Arria GX devices support on-chip series termination for single-ended I/O standards with typical R_S values of 25 and 50 Ω . Once matching impedance is selected, current drive strength is no longer selectable. [Table 2–26](#) shows the list of output standards that support on-chip series termination.



For more information about series on-chip termination supported by Arria GX devices, refer to the *Selectable I/O Standards in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.



For more information about tolerance specifications for on-chip termination without calibration, refer to the *DC & Switching Characteristics* chapter in volume 1 of the *Arria GX Device Handbook*.

MultiVolt I/O Interface

The Arria GX architecture supports the MultiVolt I/O interface feature that allows Arria GX devices in all packages to interface with systems of different supply voltages. Arria GX V_{CCINT} pins must always be connected to a 1.2-V power supply. With a 1.2-V V_{CCINT} level, input pins are 1.2-, 1.5-, 1.8-, 2.5-, and 3.3-V tolerant. The V_{CCIO} pins can be connected to either a 1.2-, 1.5-, 1.8-, 2.5-, or 3.3-V power supply, depending on the output requirements. The output levels are compatible with systems of the same voltage as the power supply (for example, when V_{CCIO} pins are connected to a 1.5-V power supply, the output levels are compatible with 1.5-V systems). Arria GX V_{CCPD} power pins must be connected to a 3.3-V power supply. These power pins are used to supply the pre-driver power to the output buffers, which increases the performance of the output pins. The V_{CCPD} pins also power configuration input pins and JTAG input pins.

Table 2–27 summarizes Arria GX MultiVolt I/O support.

| V_{CCIO} (V) | Input Signal (V) | | | | | Output Signal (V) | | | | | |
|----------------|------------------|-------|-------|-------|-------|-------------------|-------|-------|-------|-----|-----|
| | 1.2 | 1.5 | 1.8 | 2.5 | 3.3 | 1.2 | 1.5 | 1.8 | 2.5 | 3.3 | 5.0 |
| 1.2 | (4) | ✓ (2) | ✓ (2) | ✓ (2) | ✓ (2) | ✓ (4) | | | | | |
| 1.5 | (4) | ✓ | ✓ | ✓ (2) | ✓ (2) | ✓ (3) | ✓ | | | | |
| 1.8 | (4) | ✓ | ✓ | ✓ (2) | ✓ (2) | ✓ (3) | ✓ (3) | ✓ | | | |
| 2.5 | (4) | | | ✓ | ✓ | ✓ (3) | ✓ (3) | ✓ (3) | ✓ | | |
| 3.3 | (4) | | | ✓ | ✓ | ✓ (3) | ✓ (3) | ✓ (3) | ✓ (3) | ✓ | ✓ |

Notes to Table 2–27:

- (1) To drive inputs higher than V_{CCIO} but less than 4.0 V, disable the PCI clamping diode and select the **Allow LVTTTL and LVCMOS input levels to overdrive input buffer** option in the Quartus II software.
- (2) The pin current may be slightly higher than the default value. You must verify that the driving device's V_{OL} maximum and V_{OH} minimum voltages do not violate the applicable Arria GX V_{IL} maximum and V_{IH} minimum voltage specifications.
- (3) Although V_{CCIO} specifies the voltage necessary for the Arria GX device to drive out, a receiving device powered at a different level can still interface with the Arria GX device if it has inputs that tolerate the V_{CCIO} value.
- (4) Arria GX devices support 1.2-V HSTL. They do not support 1.2-V LVTTTL and 1.2-V LVCMOS.

The TDO and nCEO pins are powered by V_{CCIO} of the bank that they reside. TDO is in I/O bank 4 and nCEO is in I/O Bank 7. Ideally, the V_{CC} supplies for the I/O buffers of any two connected pins are at the same voltage level. This may not always be possible depending on the V_{CCIO} level of TDO and nCEO pins on master devices and the configuration voltage level chosen by V_{CCSEL} on slave devices. Master and slave devices can be in any position in the chain. Master indicates that it is driving out TDO or nCEO to a slave device. For multi-device passive configuration schemes, the nCEO pin of the master device will be driving the nCE pin of the slave device. The V_{CCSEL} pin on the slave device selects which input buffer is used for nCE. When V_{CCSEL} is logic high, it selects the 1.8-V/1.5-V buffer powered by V_{CCIO} . When V_{CCSEL} is logic low it selects the 3.3-V/2.5-V input buffer powered by V_{CCPD} . The ideal case is to have the V_{CCIO} of the nCEO bank in a master device match the V_{CCSEL} settings for the nCE input buffer of the slave device it is connected to, but that may not be possible depending on the application.

Table 2–28 contains board design recommendations to ensure that nCEO can successfully drive nCE for all power supply combinations.

| nCE Input Buffer Power in I/O Bank 3 | Arria GX nCEO V_{CCIO} Voltage Level in I/O Bank 7 | | | | |
|--|--|---------------------------|---------------------------|---------------------------|---------------------------|
| | $V_{CCIO} = 3.3\text{ V}$ | $V_{CCIO} = 2.5\text{ V}$ | $V_{CCIO} = 1.8\text{ V}$ | $V_{CCIO} = 1.5\text{ V}$ | $V_{CCIO} = 1.2\text{ V}$ |
| VCCSEL high (V_{CCIO} Bank 3 = 1.5 V) | ✓ (1), (2) | ✓ (3), (4) | ✓ (5) | ✓ | ✓ |
| VCCSEL high (V_{CCIO} Bank 3 = 1.8 V) | ✓ (1), (2) | ✓ (3), (4) | ✓ | ✓ | Level shifter required |
| VCCSEL low (nCE powered by $V_{CCPD} = 3.3\text{ V}$) | ✓ | ✓ (4) | ✓ (6) | Level shifter required | Level shifter required |

Notes to Table 2–28:

- (1) Input buffer is 3.3-V tolerant.
- (2) The nCEO output buffer meets V_{OH} (MIN) = 2.4 V.
- (3) Input buffer is 2.5-V tolerant.
- (4) The nCEO output buffer meets V_{OH} (MIN) = 2.0 V.
- (5) Input buffer is 1.8-V tolerant.
- (6) An external 250- Ω pull-up resistor is not required, but recommended if signal levels on the board are not optimal.

For JTAG chains, the TDO pin of the first device will be driving the TDI pin of the second device in the chain. The V_{CCSEL} input on JTAG input I/O cells (TCK, TMS, TDI, and TRST) is internally hardwired to GND selecting the 3.3-V/2.5-V input buffer powered by V_{CCPD} . The ideal case is to have the V_{CCIO} of the TDO bank from the first device to match the V_{CCSEL} settings for TDI on the second device, but that may not be possible depending on the application. Table 2–29 contains board design recommendations to ensure proper JTAG chain operation.

| Device | TDI Input Buffer Power | Arria GX TDO V_{CCIO} Voltage Level in I/O Bank 4 | | | | |
|----------|---------------------------|---|---------------------------|---------------------------|---------------------------|---------------------------|
| | | $V_{CCIO} = 3.3\text{ V}$ | $V_{CCIO} = 2.5\text{ V}$ | $V_{CCIO} = 1.8\text{ V}$ | $V_{CCIO} = 1.5\text{ V}$ | $V_{CCIO} = 1.2\text{ V}$ |
| Arria GX | Always V_{CCPD} (3.3 V) | ✓ (1) | ✓ (2) | ✓ (3) | Level shifter required | Level shifter required |

Table 2–29. Supported TDO/TDI Voltage Combinations (Part 2 of 2)

| Device | TDI Input Buffer Power | Arria GX TDO V_{CCIO} Voltage Level in I/O Bank 4 | | | | |
|--------------|------------------------|---|---------------------------|---------------------------|---------------------------|---------------------------|
| | | $V_{CCIO} = 3.3\text{ V}$ | $V_{CCIO} = 2.5\text{ V}$ | $V_{CCIO} = 1.8\text{ V}$ | $V_{CCIO} = 1.5\text{ V}$ | $V_{CCIO} = 1.2\text{ V}$ |
| Non-Arria GX | VCC = 3.3 V | ✓ (1) | ✓ (2) | ✓ (3) | Level shifter required | Level shifter required |
| | VCC = 2.5 V | ✓ (1), (4) | ✓ (2) | ✓ (3) | Level shifter required | Level shifter required |
| | VCC = 1.8 V | ✓ (1), (4) | ✓ (2), (5) | ✓ | Level shifter required | Level shifter required |
| | VCC = 1.5 V | ✓ (1), (4) | ✓ (2), (5) | ✓ (6) | ✓ | ✓ |

Notes to Table 2–29:

- (1) The TDO output buffer meets $V_{OH}(\text{MIN}) = 2.4\text{ V}$.
- (2) The TDO output buffer meets $V_{OH}(\text{MIN}) = 2.0\text{ V}$.
- (3) An external 250- Ω pull-up resistor is not required, but recommended if signal levels on the board are not optimal.
- (4) Input buffer must be 3.3-V tolerant.
- (5) Input buffer must be 2.5-V tolerant.
- (6) Input buffer must be 1.8-V tolerant.

High-Speed Differential I/O with DPA Support

Arria GX devices contain dedicated circuitry for supporting differential standards at speeds up to 840 Mbps. LVDS differential I/O standards are supported in the Arria GX device. In addition, the LVPECL I/O standard is supported on input and output clock pins on the top and bottom I/O banks.

The high-speed differential I/O circuitry supports the following high-speed I/O interconnect standards and applications:

- SPI-4 Phase 2 (POS-PHY Level 4)
- SFI-4
- Parallel RapidIO standard

There are two dedicated high-speed PLLs (PLL1 and PLL2) in the EP1AGX20 and EP1AGX35 devices and up to four dedicated high-speed PLLs (PLL1, PLL2, PLL7, and PLL8) in the EP1AGX50, EP1AGX60, and EP1AGX90 devices to multiply reference clocks and drive high-speed differential SERDES channels in I/O banks 1 and 2.

Tables 2–30 through 2–34 show the number of channels that each fast PLL can clock in each of the Arria GX devices. In Tables 2–30 through 2–34 the first row for each transmitter or receiver provides the maximum number of channels that each fast PLL can drive in its adjacent I/O bank (I/O Bank 1 or I/O Bank 2). The second row shows the maximum number of

channels that each fast PLL can drive in both I/O banks (I/O Bank 1 and I/O Bank 2). For example, in the 780-pin FineLine BGA EP1AGX20 device, PLL 1 can drive a maximum of 16 transmitter channels in I/O Bank 2 or a maximum of 29 transmitter channels in I/O Banks 1 and 2. The Quartus II software can also merge receiver and transmitter PLLs when a receiver is driving a transmitter. In this case, one fast PLL can drive both the maximum numbers of receiver and transmitter channels.



For more details, refer to the Differential Pin Placement Guidelines section in the *High-Speed Differential I/O Interfaces with DPA in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

| Package | Transmitter/Receiver | Total Channels | Center Fast PLLs | |
|----------------------|----------------------|----------------|------------------|------|
| | | | PLL1 | PLL2 |
| 484-pin FineLine BGA | Transmitter | 29 | 16 | 13 |
| | | | 13 | 16 |
| | Receiver | 31 | 17 | 14 |
| | | | 14 | 17 |
| 780-pin FineLine GBA | Transmitter | 29 | 16 | 13 |
| | | | 13 | 16 |
| | Receiver | 31 | 17 | 14 |
| | | | 14 | 17 |

Note to Table 2–30:

- (1) The total number of receiver channels includes the four non-dedicated clock channels that can be optionally used as data channels.

| Package | Transmitter/Receiver | Total Channels | Center Fast PLLs | |
|----------------------|----------------------|----------------|------------------|------|
| | | | PLL1 | PLL2 |
| 484-pin FineLine BGA | Transmitter | 29 | 16 | 13 |
| | | | 13 | 16 |
| | Receiver | 31 | 17 | 14 |
| | | | 14 | 17 |

| Package | Transmitter/Receiver | Total Channels | Center Fast PLLs | |
|----------------------|----------------------|----------------|------------------|------|
| | | | PLL1 | PLL2 |
| 780-pin FineLine BGA | Transmitter | 29 | 16 | 13 |
| | | | 13 | 16 |
| | Receiver | 31 | 17 | 14 |
| | | | 14 | 17 |

Note to Table 2–31:

- (1) The total number of receiver channels includes the four non-dedicated clock channels that can be optionally used as data channels.

| Package | Transmitter/Receiver | Total Channels | Center Fast PLLs | | Corner Fast PLLs | |
|------------------------|----------------------|----------------|------------------|------|------------------|------|
| | | | PLL1 | PLL2 | PLL7 | PLL8 |
| 484-pin FineLine BGA | Transmitter | 29 | 16 | 13 | — | — |
| | | | 13 | 16 | — | — |
| | Receiver | 31 | 17 | 14 | — | — |
| | | | 14 | 17 | — | — |
| 780-pin FineLine BGA | Transmitter | 29 | 16 | 13 | — | — |
| | | | 13 | 16 | — | — |
| | Receiver | 31 | 17 | 14 | — | — |
| | | | 14 | 17 | — | — |
| 1,152-pin FineLine BGA | Transmitter | 42 | 21 | 21 | 21 | 21 |
| | | | 21 | 21 | — | — |
| | Receiver | 42 | 21 | 21 | 21 | 21 |
| | | | 21 | 21 | — | — |

Note to Table 2–32:

- (1) The total number of receiver channels includes the four non-dedicated clock channels that can be optionally used as data channels.

Table 2–33. EP1AGX60 Device Differential Channels *Note (1)*

| Package | Transmitter/Receiver | Total Channels | Center Fast PLLs | | Corner Fast PLLs | |
|------------------------|----------------------|----------------|------------------|------|------------------|------|
| | | | PLL1 | PLL2 | PLL7 | PLL8 |
| 484-pin FineLine BGA | Transmitter | 29 | 16 | 13 | — | — |
| | | | 13 | 16 | — | — |
| | Receiver | 31 | 17 | 14 | — | — |
| | | | 14 | 17 | — | — |
| 780-pin FineLine BGA | Transmitter | 29 | 16 | 13 | — | — |
| | | | 13 | 16 | — | — |
| | Receiver | 31 | 17 | 14 | — | — |
| | | | 14 | 17 | — | — |
| 1,152-pin FineLine BGA | Transmitter | 42 | 21 | 21 | 21 | 21 |
| | | | 21 | 21 | — | — |
| | Receiver | 42 | 21 | 21 | 21 | 21 |
| | | | 21 | 21 | — | — |

Note to Table 2–33:

- (1) The total number of receiver channels includes the four non-dedicated clock channels that can be optionally used as data channels.

Table 2–34. EP1AGX90 Device Differential Channels *Note (1)*

| Package | Transmitter/Receiver | Total Channels | Center Fast PLLs | | Corner Fast PLLs | |
|------------------------|----------------------|----------------|------------------|------|------------------|------|
| | | | PLL1 | PLL2 | PLL7 | PLL8 |
| 1,152-pin FineLine BGA | Transmitter | 45 | 23 | 22 | 23 | 22 |
| | | | 22 | 23 | — | — |
| | Receiver | 47 | 23 | 24 | 23 | 24 |
| | | | 24 | 23 | — | — |

Note to Table 2–34:

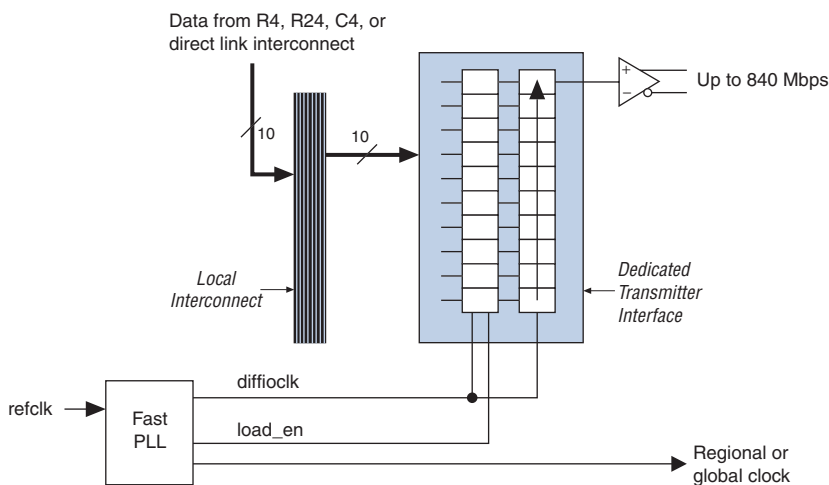
- (1) The total number of receiver channels includes the four non-dedicated clock channels that can be optionally used as data channels.

Dedicated Circuitry with DPA Support

Arria GX devices support source-synchronous interfacing with LVDS signaling at up to 840 Mbps. Arria GX devices can transmit or receive serial channels along with a low-speed or high-speed clock.

The receiving device PLL multiplies the clock by an integer factor $W = 1$ through 32. The SERDES factor J determines the parallel data width to deserialize from receivers or to serialize for transmitters. The SERDES factor J can be set to 4, 5, 6, 7, 8, 9, or 10 and does not have to equal the PLL clock-multiplication W value. A design using the dynamic phase aligner also supports all of these J factor values. For a J factor of 1, the Arria GX device bypasses the SERDES block. For a J factor of 2, the Arria GX device bypasses the SERDES block, and the DDR input and output registers are used in the IOE. Figure 2-79 shows the block diagram of the Arria GX transmitter channel.

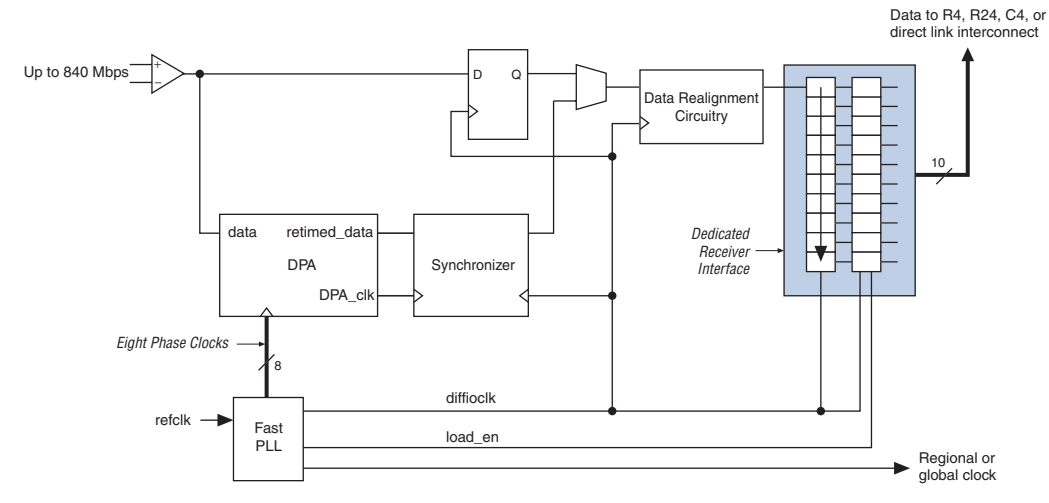
Figure 2-79. Arria GX Transmitter Channel



Each Arria GX receiver channel features a DPA block for phase detection and selection, a SERDES, a synchronizer, and a data realigner circuit. You can bypass the dynamic phase aligner without affecting the basic source-synchronous operation of the channel. In addition, you can dynamically switch between using the DPA block or bypassing the block via a control signal from the logic array.

Figure 2–80 shows the block diagram of the Arria GX receiver channel.

Figure 2–80. GX Receiver Channel



An external pin or global or regional clock can drive the fast PLLs, which can output up to three clocks: two multiplied high-speed clocks to drive the SERDES block and/or external pin, and a low-speed clock to drive the logic array. In addition, eight phase-shifted clocks from the V_{CO} can feed to the DPA circuitry.



For more information about fast PLL, see the *PLLs in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

The eight phase-shifted clocks from the fast PLL feed to the DPA block. The DPA block selects the closest phase to the center of the serial data eye to sample the incoming data. This allows the source-synchronous circuitry to capture incoming data correctly regardless of channel-to-channel or clock-to-channel skew. The DPA block locks to a phase closest to the serial data phase. The phase-aligned DPA clock is used to write the data into the synchronizer.

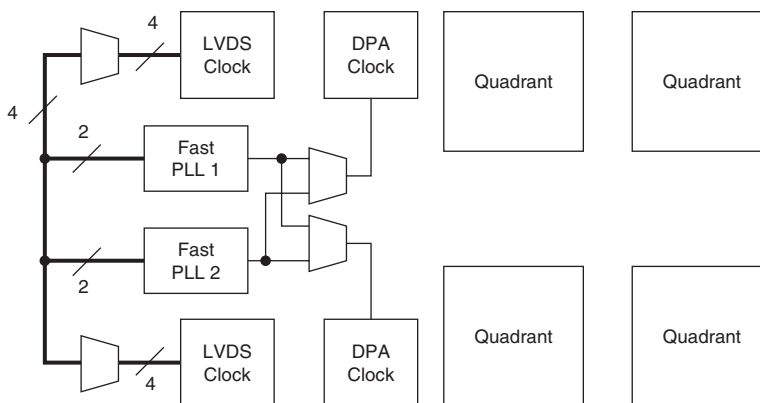
The synchronizer sits between the DPA block and the data realignment and SERDES circuitry. Since every channel utilizing the DPA block can have a different phase selected to sample the data, the synchronizer is needed to synchronize the data to the high-speed clock domain of the data realignment and the SERDES circuitry.

For high-speed source synchronous interfaces such as POS-PHY 4 and the Parallel RapidIO standard, the source synchronous clock rate is not a byte- or SERDES-rate multiple of the data rate. Byte alignment is necessary for these protocols since the source synchronous clock does not provide a byte or word boundary since the clock is one half the data rate, not one eighth. The Arria GX device's high-speed differential I/O circuitry provides dedicated data realignment circuitry for user-controlled byte boundary shifting. This simplifies designs while saving ALM resources. You can use an ALM-based state machine to signal the shift of receiver byte boundaries until a specified pattern is detected to indicate byte alignment.

Fast PLL and Channel Layout

The receiver and transmitter channels are interleaved such that each I/O bank on the left side of the device has one receiver channel and one transmitter channel per LAB row. [Figure 2-81](#) shows the fast PLL and channel layout in the EP1AGX20C, EP1AGX35C/D, EP1AGX50C/D and EP1AGX60C/D devices. [Figure 2-82](#) shows the fast PLL and channel layout in EP1AGX60E and EP1AGX90E devices.

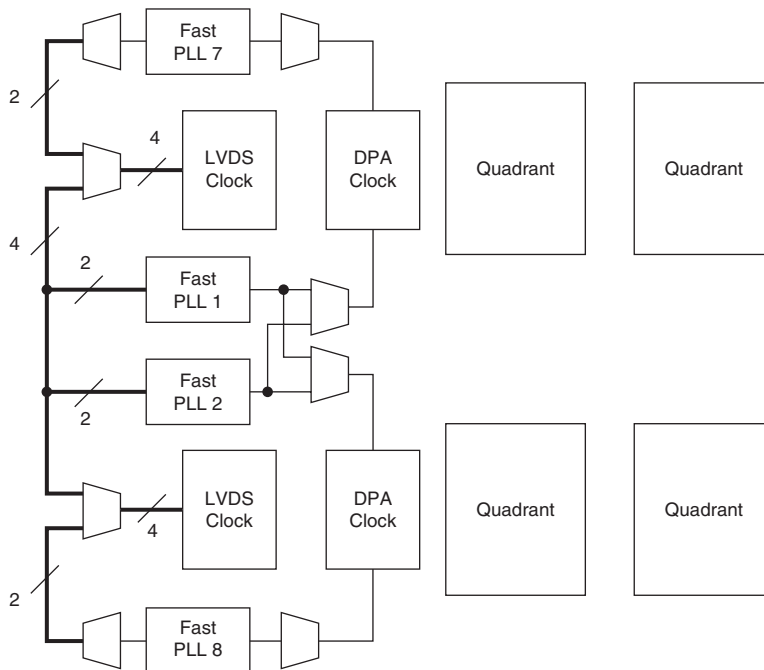
Figure 2-81. Fast PLL and Channel Layout in the EP1AGX20C, EP1AGX35C/D, EP1AGX50C/D, EP1AGX60C/D Devices *Note (1)*



Note to Figure 2-81:

(1) See [Table 2-30](#) for the number of channels each device supports.

Figure 2–82. Fast PLL and Channel Layout in the EP1AGX60E and EP1AGX90E Devices *Note (1)*



Note to Figure 2–82:

(1) See Tables 2–30 through 2–34 for the number of channels each device supports.

Referenced Documents

This chapter references the following documents:

- *Arria GX Transceiver Architecture* chapter in volume 2 of the *Arria GX Device Handbook*
- *Arria GX Transceiver Protocol Support and Additional Features* chapter in volume 2 of the *Arria GX Device Handbook*
- *DC & Switching Characteristics* chapter in volume 1 of the *Arria GX Device Handbook*
- *DSP Blocks in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*
- *External Memory Interfaces in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*
- *High-Speed Differential I/O Interfaces with DPA in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*
- *PLLs in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*

- *Selectable I/O Standards in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*
- *Specifications and Additional Information* chapter in volume 2 of the *Arria GX Device Handbook*
- *TriMatrix Embedded Memory Blocks in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*

Document Revision History

Table 2–35 shows the revision history for this chapter.

| Date and Document Version | Changes Made | Summary of Changes |
|----------------------------------|---|---------------------------|
| May 2008, v1.3 | Added “Reverse Serial Pre-CDR Loopback” and “Calibration Block” sub-sections to “Transmitter Path” section. | — |
| August 2007, v1.2 | Added “Referenced Documents” section. | — |
| June 2007, v1.1 | Added GIGE information. | — |
| May 2007 v1.0 | Initial release. | — |

Introduction

All Arria™ GX devices provide Joint Test Action Group (JTAG) boundary-scan test (BST) circuitry that complies with the IEEE Std. 1149.1. You can perform JTAG boundary-scan testing either before or after, but not during configuration. Arria GX devices can also use the JTAG port for configuration with the Quartus® II software or hardware using either jam files (.jam) or jam byte-code files (.jbc).

This chapter contains the following sections:

- “IEEE Std. 1149.1 JTAG Boundary-Scan Support” on page 3–1
- “SignalTap II Embedded Logic Analyzer” on page 3–4
- “Configuration” on page 3–4
- “Temperature Sensing Diode” on page 3–10
- “Automated Single Event Upset (SEU) Detection” on page 3–12

IEEE Std. 1149.1 JTAG Boundary- Scan Support

Arria GX devices support I/O element (IOE) standard setting reconfiguration through the JTAG BST chain. The JTAG chain can update the I/O standard for all input and output pins any time before or during user-mode through the CONFIG_IO instruction. You can use this capability for JTAG testing before configuration when some of the Arria GX pins drive or receive from other devices on the board using voltage-referenced standards. Because the Arria GX device may not be configured before JTAG testing, the I/O pins may not be configured for appropriate electrical standards for chip-to-chip communication. Programming these I/O standards via JTAG allows you to fully test the I/O connections to other devices.

A device operating in JTAG mode uses four required pins, TDI, TDO, TMS, and TCK, and one optional pin, TRST. The TCK pin has an internal weak pull-down resistor, while the TDI, TMS, and TRST pins have weak internal pull-up resistors. The JTAG input pins are powered by the 3.3-V V_{CCPD} pins. The TDO output pin is powered by the V_{CCIO} power supply in I/O bank 4.

Arria GX devices also use the JTAG port to monitor the logic operation of the device with the SignalTap® II embedded logic analyzer. Arria GX devices support the JTAG instructions shown in Table 3–1.



Arria GX, Stratix®, Stratix II, Stratix GX, Stratix II GX, Cyclone® II, and Cyclone devices must be within the first 17 devices in a JTAG chain. All of these devices have the same JTAG controller. If any of the Stratix, Arria GX, Cyclone, and Cyclone II devices are in the 18th or further position, they will fail configuration. This does not affect the functionality of the SignalTap II embedded logic analyzer.

Table 3–1. Arria GX JTAG Instructions (Part 1 of 2)

| JTAG Instruction | Instruction Code | Description |
|------------------|------------------|---|
| SAMPLE/PRELOAD | 00 0000 0101 | Allows a snapshot of signals at the device pins to be captured and examined during normal device operation and permits an initial data pattern to be output at the device pins. Also used by the SignalTap II embedded logic analyzer. |
| EXTEST (1) | 00 0000 1111 | Allows external circuitry and board-level interconnects to be tested by forcing a test pattern at the output pins and capturing test results at the input pins. |
| BYPASS | 11 1111 1111 | Places the 1-bit bypass register between the TDI and TDO pins, which allows the BST data to pass synchronously through selected devices to adjacent devices during normal device operation. |
| USERCODE | 00 0000 0111 | Selects the 32-bit USERCODE register and places it between the TDI and TDO pins, allowing the USERCODE to be serially shifted out of TDO. |
| IDCODE | 00 0000 0110 | Selects the IDCODE register and places it between TDI and TDO, allowing IDCODE to be serially shifted out of TDO. |
| HIGHZ (1) | 00 0000 1011 | Places the 1-bit bypass register between the TDI and TDO pins, which allows the BST data to pass synchronously through selected devices to adjacent devices during normal device operation, while tri-stating all of the I/O pins. |
| CLAMP (1) | 00 0000 1010 | Places the 1-bit bypass register between the TDI and TDO pins, which allows the BST data to pass synchronously through selected devices to adjacent devices during normal device operation while holding I/O pins to a state defined by the data in the boundary-scan register. |
| ICR instructions | — | Used when configuring an Arria GX device via the JTAG port with a USB-Blaster™, MasterBlaster™, ByteBlasterMV™, or ByteBlaster II download cable, or when using a .jam or .jbc via an embedded processor or JRunner™. |
| PULSE_NCONFIG | 00 0000 0001 | Emulates pulsing the nCONFIG pin low to trigger reconfiguration even though the physical pin is unaffected. |

Table 3–1. Arria GX JTAG Instructions (Part 2 of 2)

| JTAG Instruction | Instruction Code | Description |
|------------------|------------------|--|
| CONFIG_IO (2) | 00 0000 1101 | Allows configuration of I/O standards through the JTAG chain for JTAG testing. Can be executed before, during, or after configuration. Stops configuration if executed during configuration. Once issued, the CONFIG_IO instruction holds nSTATUS low to reset the configuration device. nSTATUS is held low until the IOE configuration register is loaded and the TAP controller state machine transitions to the UPDATE_DR state. |

Notes to Table 3–1:

- (1) Bus hold and weak pull-up resistor features override the high-impedance state of HIGHZ, CLAMP, and EXTEST.
- (2) For more information about using the CONFIG_IO instruction, refer to the *MorphIO: An I/O Reconfiguration Solution for Altera Devices* White Paper.

The Arria GX device instruction register length is 10 bits and the USERCODE register length is 32 bits. Tables 3–2 and 3–3 show the boundary-scan register length and device IDCODE information for Arria GX devices.

Table 3–2. Arria GX Boundary-Scan Register Length

| Device | Boundary-Scan Register Length |
|----------|-------------------------------|
| EP1AGX20 | 1320 |
| EP1AGX35 | 1320 |
| EP1AGX50 | 1668 |
| EP1AGX60 | 1668 |
| EP1AGX90 | 2016 |

Table 3–3. 2-Bit Arria GX Device IDCODE (Part 1 of 2)

| Device | IDCODE (32 Bits) | | | |
|----------|------------------|-----------------------|---------------------------------|-------------|
| | Version (4 Bits) | Part Number (16 Bits) | Manufacturer Identity (11 Bits) | LSB (1 Bit) |
| EP1AGX20 | 0000 | 0010 0001 0010 0001 | 000 0110 1110 | 1 |
| EP1AGX35 | 0000 | 0010 0001 0010 0001 | 000 0110 1110 | 1 |
| EP1AGX50 | 0000 | 0010 0001 0010 0010 | 000 0110 1110 | 1 |

Table 3–3. 2-Bit Arria GX Device IDCODE (Part 2 of 2)

| Device | IDCODE (32 Bits) | | | |
|----------|------------------|-----------------------|---------------------------------|-------------|
| | Version (4 Bits) | Part Number (16 Bits) | Manufacturer Identity (11 Bits) | LSB (1 Bit) |
| EP1AGX60 | 0000 | 0010 0001 0010 0010 | 000 0110 1110 | 1 |
| EP1AGX90 | 0000 | 0010 0001 0010 0011 | 000 0110 1110 | 1 |

SignalTap II Embedded Logic Analyzer

Arria GX devices feature the SignalTap II embedded logic analyzer, which monitors design operation over a period of time through the IEEE Std. 1149.1 (JTAG) circuitry. You can analyze internal logic at speed without bringing internal signals to the I/O pins. This feature is particularly important for advanced packages, such as FineLine BGA (FBGA) packages, because it can be difficult to add a connection to a pin during the debugging process after a board is designed and manufactured.

Configuration

The logic, circuitry, and interconnects in the Arria GX architecture are configured with CMOS SRAM elements. Altera® FPGAs are reconfigurable and every device is tested with a high coverage production test program so you do not have to perform fault testing and can instead focus on simulation and design verification.

Arria GX devices are configured at system power up with data stored in an Altera configuration device or provided by an external controller (for example, a MAX® II device or microprocessor). You can configure Arria GX devices using the fast passive parallel (FPP), active serial (AS), passive serial (PS), passive parallel asynchronous (PPA), and JTAG configuration schemes. Each Arria GX device has an optimized interface that allows microprocessors to configure it serially or in parallel, and synchronously or asynchronously. The interface also enables microprocessors to treat Arria GX devices as memory and configure them by writing to a virtual memory location, making reconfiguration easy.

In addition to the number of configuration methods supported, Arria GX devices also offer decompression and remote system upgrade features. The decompression feature allows Arria GX FPGAs to receive a compressed configuration bitstream and decompress this data in real-time, reducing storage requirements and configuration time. The remote system upgrade feature allows real-time system upgrades from remote locations of Arria GX designs. For more information, refer to [“Configuration Schemes” on page 3–6](#).

Operating Modes

The Arria GX architecture uses SRAM configuration elements that require configuration data to be loaded each time the circuit powers up. The process of physically loading the SRAM data into the device is called configuration. During initialization, which occurs immediately after configuration, the device resets registers, enables I/O pins, and begins to operate as a logic device. The I/O pins are tri-stated during power up, and before and during configuration. Together, the configuration and initialization processes are called command mode. Normal device operation is called user mode.

SRAM configuration elements allows you to reconfigure Arria GX devices in-circuit by loading new configuration data into the device. With real-time reconfiguration, the device is forced into command mode with a device pin. The configuration process loads different configuration data, re-initializes the device, and resumes user-mode operation. You can perform in-field upgrades by distributing new configuration files either within the system or remotely.

PORSEL is a dedicated input pin used to select power-on reset (POR) delay times of 12 ms or 100 ms during power up. When the PORSEL pin is connected to ground, the POR time is 100 ms. When the PORSEL pin is connected to V_{CC} , the POR time is 12 ms.

The nIO_PULLUP pin is a dedicated input that chooses whether the internal pull-up resistors on the user I/O pins and dual-purpose configuration I/O pins (nCSO, ASDO, DATA [7 . . 0], nWS, nRS, RDYnBSY, nCS, CS, RUnLU, PGM [2 . . 0], CLKUSR, INIT_DONE, DEV_OE, DEV_CLR) are on or off before and during configuration. A logic high (1.5, 1.8, 2.5, 3.3 V) turns off the weak internal pull-up resistors, while a logic low turns them on.

Arria GX devices also offer a new power supply, V_{CCPD} , which must be connected to 3.3 V in order to power the 3.3-V/2.5-V buffer available on the configuration input pins and JTAG pins. V_{CCPD} applies to all the JTAG input pins (TCK, TMS, TDI, and TRST) and the following configuration pins: nCONFIG, DCLK (when used as an input), nIO_PULLUP, DATA [7 . . 0], RUnLU, nCE, nWS, nRS, CS, nCS, and CLKUSR. The V_{CCSEL} pin allows the V_{CCIO} setting (of the banks where the configuration inputs reside) to be independent of the voltage required by the configuration inputs. Therefore, when selecting the V_{CCIO} voltage, you do not have to take the VIL and VIH levels driven to the configuration inputs into consideration. The configuration input pins, nCONFIG, DCLK (when used as an input), nIO_PULLUP, RUnLU, nCE, nWS, nRS, CS, nCS, and CLKUSR, have a dual buffer design: a 3.3-V/2.5-V input buffer and a 1.8-V/1.5-V

input buffer. The V_{CCSEL} input pin selects which input buffer is used. The 3.3-V/2.5-V input buffer is powered by V_{CCPD} , while the 1.8-V/1.5-V input buffer is powered by V_{CCIO} .

V_{CCSEL} is sampled during power up. Therefore, the V_{CCSEL} setting cannot change on-the-fly or during a reconfiguration. The V_{CCSEL} input buffer is powered by V_{CCINT} and must be hard-wired to V_{CCPD} or ground. A logic high V_{CCSEL} connection selects the 1.8-V/1.5-V input buffer, and a logic low selects the 3.3-V/2.5-V input buffer. V_{CCSEL} should be set to comply with the logic levels driven out of the configuration device or MAX II microprocessor.

If the design must support configuration input voltages of 3.3 V/2.5 V, set V_{CCSEL} to a logic low. You can set the V_{CCIO} voltage of the I/O bank that contains the configuration inputs to any supported voltage. If the design must support configuration input voltages of 1.8 V/1.5 V, set V_{CCSEL} to a logic high and the V_{CCIO} of the bank that contains the configuration inputs to 1.8 V/1.5 V.



For more information about multi-volt support, including information about using TDO and nCEO in multi-volt systems, refer to the [Arria GX Architecture](#) chapter in volume 1 of the *Arria GX Device Handbook*.

Configuration Schemes

You can load the configuration data for an Arria GX device with one of five configuration schemes (refer to [Table 3–4](#)), chosen on the basis of the target application. You can use a configuration device, intelligent controller, or the JTAG port to configure an Arria GX device. A configuration device can automatically configure an Arria GX device at system power up.

You can configure multiple Arria GX devices in any of the five configuration schemes by connecting the configuration enable (nCE) and configuration enable output ($nCEO$) pins on each device. Arria GX FPGAs offer the following:

- Configuration data decompression to reduce configuration file storage
- Remote system upgrades for remotely updating Arria GX designs

Table 3–4 summarizes which configuration features can be used in each configuration scheme.



For more information about configuration schemes in Arria GX devices, refer to the *Configuring Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

| Configuration Scheme | Configuration Method | Decompression | Remote System Upgrade |
|----------------------|--|---------------|-----------------------|
| FPP | MAX II device or microprocessor and flash device | ✓(1) | ✓ |
| | Enhanced configuration device | ✓(2) | ✓ |
| AS | Serial configuration device | ✓ | ✓(3) |
| PS | MAX II device or microprocessor and flash device | ✓ | ✓ |
| | Enhanced configuration device | ✓ | ✓ |
| | Download cable (4) | ✓ | — |
| PPA | MAX II device or microprocessor and flash device | — | ✓ |
| JTAG | Download cable (4) | — | — |
| | MAX II device or microprocessor and flash device | — | — |

Notes for Table 3–4:

- (1) In these modes, the host system must send a DCLK that is 4× the data rate.
- (2) The enhanced configuration device decompression feature is available, while the Arria GX decompression feature is not available.
- (3) Only remote update mode is supported when using the AS configuration scheme. Local update mode is not supported.
- (4) The supported download cables include the Altera USB-Blaster universal serial bus (USB) port download cable, MasterBlaster serial/USB communications cable, ByteBlaster II parallel port download cable, and the ByteBlasterMV parallel port download cable.

Device Configuration Data Decompression

Arria GX FPGAs support decompression of configuration data, which saves configuration memory space and time. This feature allows you to store compressed configuration data in configuration devices or other memory and transmit this compressed bitstream to Arria GX FPGAs. During configuration, the Arria GX FPGA decompresses the bitstream in real time and programs its SRAM cells. Arria GX FPGAs support decompression in the FPP (when using a MAX II device or

microprocessor and flash memory), AS, and PS configuration schemes. Decompression is not supported in the PPA configuration scheme nor in JTAG-based configuration.

Remote System Upgrades

Shortened design cycles, evolving standards, and system deployments in remote locations are difficult challenges faced by system designers. Arria GX devices can help effectively deal with these challenges with their inherent reprogrammability and dedicated circuitry to perform remote system updates. Remote system updates help deliver feature enhancements and bug fixes without costly recalls, reduce time to market, and extend product life.

Arria GX FPGAs feature dedicated remote system upgrade circuitry to facilitate remote system updates. Soft logic (Nios® processor or user logic) implemented in the Arria GX device can download a new configuration image from a remote location, store it in configuration memory, and direct the dedicated remote system upgrade circuitry to initiate a reconfiguration cycle. The dedicated circuitry performs error detection during and after the configuration process, recovers from any error condition by reverting back to a safe configuration image, and provides error status information. This dedicated remote system upgrade circuitry avoids system downtime and is the critical component for successful remote system upgrades.

Remote system configuration is supported in the following Arria GX configuration schemes: FPP, AS, PS, and PPA. You can also implement remote system configuration in conjunction with Arria GX features such as real-time decompression of configuration data for efficient field upgrades.



For more information about remote configuration in Arria GX devices, refer to the *Remote System Upgrades with Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

Configuring Arria GX FPGAs with JRunner

The JRunner software driver configures Altera FPGAs, including Arria GX FPGAs, through the ByteBlaster II or ByteBlasterMV cables in JTAG mode. The programming input file supported is in Raw Binary File (.rbf) format. JRunner also requires a Chain Description File (.cdf) generated by the Quartus II software. JRunner is targeted for embedded JTAG configuration. The source code is developed for the Windows NT operating system (OS), but can be customized to run on other platforms.



For more information about the JRunner software driver, refer to the *AN414: JRunner Software Driver: An Embedded Solution for PLD JTAG Configuration* and the source files on the Altera web site (www.altera.com).

Programming Serial Configuration Devices with SRunner

You can program a serial configuration device in-system by an external microprocessor using SRunner™. SRunner is a software driver developed for embedded serial configuration device programming that can be easily customized to fit into different embedded systems. SRunner reads a raw programming data file (.rpd) and writes to serial configuration devices. The serial configuration device programming time using SRunner is comparable to the programming time when using the Quartus II software.



For more information about SRunner, refer to the *AN418: SRunner: An Embedded Solution for Serial Configuration Device Programming* and the source code on the Altera web site.



For more information about programming serial configuration devices, refer to the *Serial Configuration Devices (EPCS1, EPCS4, EPCS64, and EPCS128) Data Sheet* in the *Configuration Handbook*.

Configuring Arria GX FPGAs with the MicroBlaster Driver

The MicroBlaster™ software driver supports a raw binary file (RBF) programming input file and is ideal for embedded FPP or PS configuration. The source code is developed for the Windows NT operating system, although it can be customized to run on other operating systems.



For more information about the MicroBlaster software driver, refer to the *Configuring the MicroBlaster Fast Passive Parallel Software Driver White Paper* or the *AN423: Configuring the MicroBlaster Passive Serial Software Driver* on the Altera web site.

PLL Reconfiguration

The phase-locked loops (PLLs) in the Arria GX device family support reconfiguration of their multiply, divide, VCO-phase selection, and bandwidth selection settings without reconfiguring the entire device. You can use either serial data from the logic array or regular I/O pins to program the PLL's counter settings in a serial chain. This option provides

considerable flexibility for frequency synthesis, allowing real-time variation of the PLL frequency and delay. The rest of the device is functional while reconfiguring the PLL.



For more information about Arria GX PLLs, refer to the *PLLs in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

Temperature Sensing Diode

Arria GX devices include a diode-connected transistor for use as a temperature sensor in power management. This diode is used with an external digital thermometer device such as a MAX1617A or MAX1619 from MAXIM Integrated Products. These devices steer bias current through the Arria GX diode, measuring forward voltage and converting this reading to temperature in the form of an eight-bit signed number (seven bits plus one sign bit). The external device's output represents the junction temperature of the Arria GX device and can be used for intelligent power management.

The diode requires two pins (`tempdiodep` and `tempdioden`) on the Arria GX device to connect to the external temperature-sensing device, as shown in [Figure 3-1](#). The temperature sensing diode is a passive element and therefore can be used before the Arria GX device is powered.

Figure 3-1. External Temperature-Sensing Diode

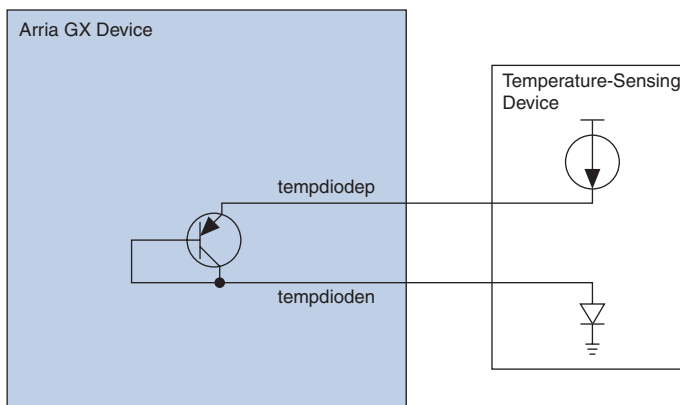
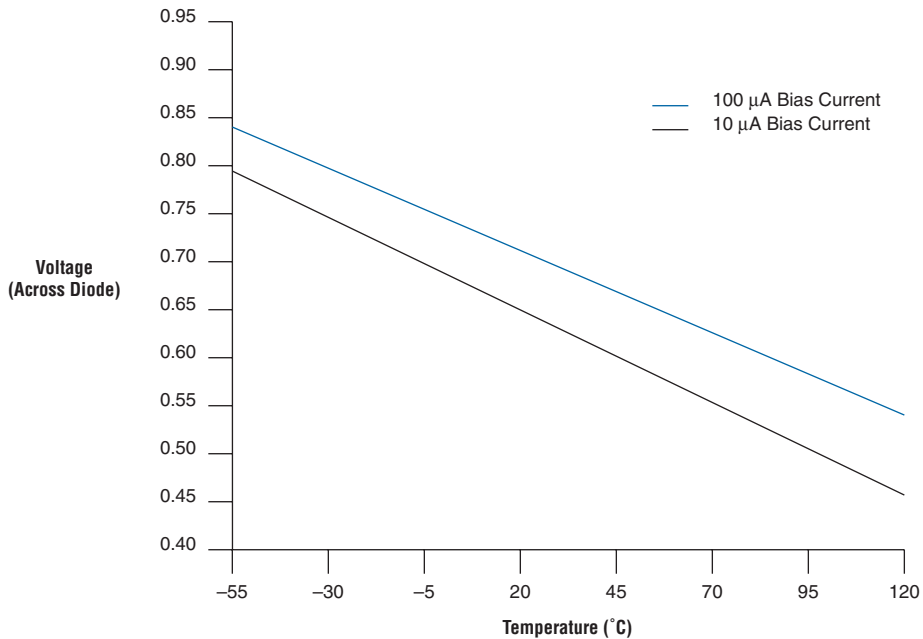


Table 3-5 shows the specifications for bias voltage and current of the Arria GX temperature sensing diode.

| Parameter | Minimum | Typical | Maximum | Unit |
|-------------------|---------|---------|---------|---------------|
| IBIAS high | 80 | 100 | 120 | μA |
| IBIAS low | 8 | 10 | 12 | μA |
| VBP - VBN | 0.3 | — | 0.9 | V |
| VBN | — | 0.7 | — | V |
| Series resistance | — | — | 3 | Ω |

The temperature-sensing diode works for the entire operating range, as shown in Figure 3-2.

Figure 3-2. Temperature vs. Temperature-Sensing Diode Voltage



Automated Single Event Upset (SEU) Detection

Arria GX devices offer on-chip circuitry for automated checking of single event upset (SEU) detection. Some applications that require the device to operate error free at high elevations or in close proximity to Earth's North or South Pole will require periodic checks to ensure continued data integrity. The error detection cyclic redundancy check (CRC) feature controlled by the **Device and Pin Options** dialog box in the Quartus II software uses a 32-bit CRC circuit to ensure data reliability and is one of the best options for mitigating SEU.

You can implement the error detection CRC feature with existing circuitry in Arria GX devices, eliminating the need for external logic. Arria GX devices compute CRC during configuration. The Arria GX device checks the computed-CRC against an automatically computed CRC during normal operation. The `CRC_ERROR` pin reports a soft error when configuration SRAM data is corrupted, triggering device reconfiguration.

Custom-Built Circuitry

Dedicated circuitry is built into Arria GX devices to automatically perform error detection. This circuitry constantly checks for errors in the configuration SRAM cells while the device is in user mode. You can monitor one external pin for the error and use it to trigger a reconfiguration cycle. You can select the desired time between checks by adjusting a built-in clock divider.

Software Interface

Beginning with version 7.1 of the Quartus II software, you can turn on the automated error detection CRC feature in the **Device and Pin Options** dialog box. This dialog box allows you to enable the feature and set the internal frequency of the CRC between 400 kHz to 50 MHz. This controls the rate that the CRC circuitry verifies the internal configuration SRAM bits in the Arria GX FPGA.



For more information about CRC, refer to [AN 357: Error Detection Using CRC in Altera FPGAs](#).

Referenced Documents

This chapter references the following documents:

- [AN 357: Error Detection Using CRC in Altera FPGAs](#)
- [AN414: JRunner Software Driver: An Embedded Solution for PLD JTAG Configuration](#)
- [AN418: SRunner: An Embedded Solution for Serial Configuration Device Programming](#)
- [AN423: Configuring the MicroBlaster Passive Serial Software Driver](#)

- *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*
- *Configuring Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*
- *Configuring the MicroBlaster Fast Passive Parallel Software Driver* White Paper
- *MorphIO: An I/O Reconfiguration Solution for Altera Devices* White Paper
- *PLLs in Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*
- *Remote System Upgrades with Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*
- *Serial Configuration Devices (EPCS1, EPCS4, EPCS64, and EPCS128) Data Sheet* in the *Configuration Handbook*

Document Revision History

Table 3–6 shows the revision history for this chapter.

| <i>Table 3–6. Document Revision History</i> | | |
|---|---|---------------------------|
| Date and Document Version | Changes Made | Summary of Changes |
| May 2008 v1.3 | Updated note in “ Introduction ” section. | — |
| | Minor text edits. | — |
| August 2007 v1.2 | Added the “Referenced Documents” section. | — |
| June 2007 v1.1 | Deleted Signal Tap II information from Table 3–1. | — |
| May 2007 v1.0 | Initial Release | — |

Operating Conditions

Arria™ GX devices are offered in both commercial and industrial grades. Both commercial and industrial devices are offered in -6 speed grade only.

This chapter contains the following sections:

- “Operating Conditions” on page 4–1
- “Power Consumption” on page 4–34
- “I/O Timing Model” on page 4–34
- “Typical Design Performance” on page 4–43
- “Block Performance” on page 4–110
- “IOE Programmable Delay” on page 4–113
- “Maximum Input and Output Clock Toggle Rate” on page 4–114
- “Duty Cycle Distortion” on page 4–125
- “High-Speed I/O Specifications” on page 4–131
- “PLL Timing Specifications” on page 4–133
- “External Memory Interface Specifications” on page 4–135
- “JTAG Timing Specifications” on page 4–137

Tables 4–1 through 4–42 provide information on absolute maximum ratings, recommended operating conditions, DC electrical characteristics, and other specifications for Arria GX devices.

Absolute Maximum Ratings

Table 4–1 contains the absolute maximum ratings for the Arria GX device family.

Table 4–1. Arria GX Device Absolute Maximum Ratings *Notes (1), (2), (3)*

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|--------------------|----------------------------|------------------------|---------|---------|------|
| V _{CCINT} | Supply voltage | With respect to ground | –0.5 | 1.8 | V |
| V _{CCIO} | Supply voltage | With respect to ground | –0.5 | 4.6 | V |
| V _{CCPD} | Supply voltage | With respect to ground | –0.5 | 4.6 | V |
| V _I | DC input voltage (4) | | –0.5 | 4.6 | V |
| I _{OUT} | DC output current, per pin | | –25 | 40 | mA |
| T _{STG} | Storage temperature | No bias | –65 | 150 | C |

Table 4–1. Arria GX Device Absolute Maximum Ratings Notes (1), (2), (3)

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|--------|----------------------|-------------------------|---------|---------|------|
| T_J | Junction temperature | BGA packages under bias | –55 | 125 | C |

Notes to Table 4–1:

- (1) See the operating requirements for Altera® devices in the *Arria GX Device Family Data Sheet* in volume 1 of the *Arria GX Device Handbook* for more information.
- (2) Conditions beyond those listed in Table 4–1 may cause permanent damage to a device. Additionally, device operation at the absolute maximum ratings for extended periods of time may have adverse effects on the device.
- (3) Supply voltage specifications apply to voltage readings taken at the device pins, not at the power supply.
- (4) During transitions, the inputs may overshoot to the voltage shown in Table 4–2 based upon the input duty cycle. The DC case is equivalent to 100% duty cycle. During transitions, the inputs may undershoot to –2.0 V for input currents less than 100 mA and periods shorter than 20 ns.

Table 4–2. Maximum Duty Cycles in Voltage Transitions Note (1)

| Symbol | Parameter | Condition | Maximum Duty Cycles (%) |
|--------|--|----------------------|-------------------------|
| V_I | Maximum duty cycles in voltage transitions | $V_I = 4.0\text{ V}$ | 100 |
| | | $V_I = 4.1\text{ V}$ | 90 |
| | | $V_I = 4.2\text{ V}$ | 50 |
| | | $V_I = 4.3\text{ V}$ | 30 |
| | | $V_I = 4.4\text{ V}$ | 17 |
| | | $V_I = 4.5\text{ V}$ | 10 |

Note to Table 4–2:

- (1) During transition, the inputs may overshoot to the voltages shown based on the input duty cycle. The DC case is equivalent to 100% duty cycle.

Recommended Operating Conditions

Table 4–3 contains the Arria GX device family recommended operating conditions.

Table 4–3. Arria GX Device Recommended Operating Conditions (Part 1 of 2) Note (1)

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|-------------|---|------------------------------------|---------|---------|------|
| V_{CCINT} | Supply voltage for internal logic and input buffers | Rise time $\leq 100\text{ ms}$ (3) | 1.15 | 1.25 | V |

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|------------|---|---|-----------------|-----------------|------|
| V_{CCIO} | Supply voltage for output buffers, 3.3-V operation | Rise time ≤ 100 ms (3), (6) | 3.135 (3.00) | 3.465 (3.60) | V |
| | Supply voltage for output buffers, 2.5-V operation | Rise time ≤ 100 ms (3) | 2.375 | 2.625 | V |
| | Supply voltage for output buffers, 1.8-V operation | Rise time ≤ 100 ms (3) | 1.71 | 1.89 | V |
| | Supply voltage for output buffers, 1.5-V operation | Rise time ≤ 100 ms (3) | 1.425 | 1.575 | V |
| | Supply voltage for output buffers, 1.2-V operation | Rise time ≤ 100 ms (3) | 1.15 | 1.25 | V |
| V_{CCPD} | Supply voltage for pre-drivers as well as configuration and JTAG I/O buffers. | $100 \mu\text{s} \leq \text{rise time} \leq 100$ ms (4) | 3.135 | 3.465 | V |
| V_I | Input voltage (see Table 4–2) | (2), (5) | –0.5 | 4.0 | V |
| V_O | Output voltage | | 0 | V_{CCIO} | V |
| T_J | Operating junction temperature | For commercial use | 0 | 85 | C |
| | | For industrial use | –40 | 100 | C |

Notes to Table 4–3:

- (1) Supply voltage specifications apply to voltage readings taken at the device pins, not at the power supply.
- (2) During transitions, the inputs may overshoot to the voltage shown in Table 4–2 based upon the input duty cycle. The DC case is equivalent to 100% duty cycle. During transitions, the inputs may undershoot to –2.0 V for input currents less than 100 mA and periods shorter than 20 ns.
- (3) Maximum V_{CC} rise time is 100 ms, and V_{CC} must rise monotonically from ground to V_{CC} .
- (4) V_{CCPD} must ramp-up from 0 V to 3.3 V within 100 μs to 100 ms. If V_{CCPD} is not ramped up within this specified time, the Arria GX device will not configure successfully. If the system does not allow for a V_{CCPD} ramp-up time of 100 ms or less, hold $nCONFIG$ low until all power supplies are reliable.
- (5) All pins, including dedicated inputs, clock, I/O, and JTAG pins, may be driven before V_{CCINT} , V_{CCPD} , and V_{CCIO} are powered.
- (6) V_{CCIO} maximum and minimum conditions for PCI and PCI-X are shown in parentheses.

Transceiver Block Characteristics

Tables 4–4 through 4–6 contain transceiver block specifications.

| Symbol | Parameter | Conditions | Minimum | Maximum | Units |
|-----------|----------------------------------|---------------------------|---------|---------|-------|
| V_{CCA} | Transceiver block supply voltage | Commercial and industrial | –0.5 | 4.6 | V |
| V_{CCP} | Transceiver block supply voltage | Commercial and industrial | –0.5 | 1.8 | V |

Table 4–4. Arria GX Transceiver Block Absolute Maximum Ratings (Part 2 of 2) *Note (1)*

| Symbol | Parameter | Conditions | Minimum | Maximum | Units |
|--------------|----------------------------------|---------------------------|---------|---------|-------|
| V_{CCR} | Transceiver block supply Voltage | Commercial and industrial | –0.5 | 1.8 | V |
| V_{CCT_B} | Transceiver block supply voltage | Commercial and industrial | –0.5 | 1.8 | V |
| V_{CCL_B} | Transceiver block supply voltage | Commercial and industrial | –0.5 | 1.8 | V |
| V_{CCH_B} | Transceiver block supply voltage | Commercial and industrial | –0.5 | 2.4 | V |

Note to Tables 4–4:

- (1) The device can tolerate prolonged operation at this absolute maximum, as long as the maximum specification is not violated.

Table 4–5. Arria GX Transceiver Block Operating Conditions

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Units |
|----------------|----------------------------------|---------------------------|---------|---------|---------|----------|
| V_{CCA} | Transceiver block supply voltage | Commercial and industrial | 3.135 | 3.3 | 3.465 | V |
| V_{CCP} | Transceiver block supply voltage | Commercial and industrial | 1.15 | 1.2 | 1.25 | V |
| V_{CCR} | Transceiver block supply voltage | Commercial and industrial | 1.15 | 1.2 | 1.25 | V |
| V_{CCT_B} | Transceiver block supply voltage | Commercial and industrial | 1.15 | 1.2 | 1.25 | V |
| V_{CCL_B} | Transceiver block supply voltage | Commercial and industrial | 1.15 | 1.2 | 1.25 | V |
| V_{CCH_B} | Transceiver block supply voltage | Commercial and industrial | 1.15 | 1.2 | 1.25 | V |
| | | | 1.425 | 1.5 | 1.575 | V |
| R_{REFB} (1) | Reference resistor | Commercial and industrial | 2K –1% | 2K | 2K +1% | Ω |

Notes to Table 4–5:

- (1) The DC signal on this pin must be as clean as possible. Ensure that no noise is coupled to this pin.

Table 4–6. Arria GX Transceiver Block AC Specification (Part 1 of 4)

| Symbol / Description | Conditions | -6 Speed Grade Commercial and Industrial | | | Unit |
|---|-------------------------|--|-----|--------|------|
| | | Min | Typ | Max | |
| Reference clock | | | | | |
| Input reference clock frequency | | 50 | — | 622.08 | MHz |
| Absolute V_{MAX} for a REFCLK Pin | | — | — | 3.3 | V |
| Absolute V_{MIN} for a REFCLK Pin | | -0.3 | — | — | V |
| Rise/Fall time | | — | 0.2 | — | UI |
| Duty cycle | | 45 | — | 55 | % |
| Peak to peak differential input voltage V_{id} (diff p-p) | | 200 | — | 2000 | mV |
| Spread spectrum clocking (1) | 0 to -0.5% | 30 | — | 33 | kHz |
| On-chip termination resistors | | 115 ± 20% | | | Ω |
| V_{ICM} (AC coupled) | | 1200 ± 5% | | | mV |
| V_{ICM} (DC coupled) (2) | PCI Express (PIPE) mode | 0.25 | — | 0.55 | V |
| | | | | | |
| RREFB | | 2000 +/-1% | | | Ω |
| | | | | | |
| Transceiver Clocks | | | | | |
| Calibration block clock frequency | | 10 | - | 125 | MHz |
| Calibration block minimum power-down pulse width | | 30 | - | - | ns |
| $fixedclk$ clock frequency (3) | | 125 ± 10% | | | MHz |
| $reconfig$ clock frequency | SDI mode | 2.5 | | 50 | MHz |
| Transceiver block minimum power-down pulse width | | 100 | - | - | ns |

Table 4–6. Arria GX Transceiver Block AC Specification (Part 2 of 4)

| Symbol / Description | Conditions | -6 Speed Grade Commercial and Industrial | | | Unit |
|---|----------------------------------|--|------------|------------|------|
| | | Min | Typ | Max | |
| Receiver | | | | | |
| Data rate | | 600 | - | 3125 | Mbps |
| Absolute V_{MAX} for a receiver pin (4) | | - | - | 2.0 | V |
| Absolute V_{MIN} for a receiver pin | | -0.4 | - | - | V |
| Maximum peak-to-peak differential input voltage V_{ID} (diff p-p) | Vicm = 0.85 V | - | - | 3.3 | V |
| Minimum peak-to-peak differential input voltage V_{ID} (diff p-p) | DC Gain = 3 dB | 160 | - | - | mV |
| On-chip termination resistors | | 100±15% | | | Ω |
| V_{ICM} (15) | Vicm = 0.85 V setting | 850 ± 10% | 850 ± 10% | 850 ± 10% | mV |
| | Vicm = 1.2 V setting | 1200 ± 10% | 1200 ± 10% | 1200 ± 10% | mV |
| Bandwidth at 3.125 Gbps | BW = Low | | 30 | - | MHz |
| | BW = Med | | 40 | | |
| | BW = High | | 50 | | |
| Bandwidth at 2.5 Gbps | BW = Low | | 35 | - | MHz |
| | BW = Med | | 50 | | |
| | BW = High | | 60 | | |
| Return loss differential mode | 50 MHz to 1.25 GHz (PCI Express) | -10 | | | dB |
| | 100 MHz to 2.5 GHz (XAUI) | | | | |
| Return loss common mode | 50 MHz to 1.25 GHz (PCI Express) | -6 | | | dB |
| | 100 MHz to 2.5 GHz (XAUI) | | | | |
| Programmable PPM detector (5) | | ± 62.5, 100, 125, 200, 250, 300, 500, 1000 | | | PPM |
| Run length (6) | | 80 | | | UI |
| Programmable equalization | | | | 5 | dB |
| Signal detect/loss threshold (7) | | 65 | - | 175 | mV |

Table 4–6. Arria GX Transceiver Block AC Specification (Part 3 of 4)

| Symbol / Description | Conditions | -6 Speed Grade Commercial and Industrial | | | Unit |
|---|----------------------------------|--|-----|--------|------|
| | | Min | Typ | Max | |
| CDR LTR Time (8), (9) | | - | - | 75 | us |
| CDR Minimum T1b (9), (10) | | 15 | - | - | us |
| LTD lock time (9), (11) | | 0 | 100 | 4000 | ns |
| Data lock time from rx_freqlocked (9), (12) | | - | - | 4 | us |
| Programmable DC gain | | 0, 3, 6 | | | dB |
| Transmitter Buffer | | | | | |
| Output Common Mode voltage (Vocm) | Vocm = 0.6 V setting | 580 ± 10% | | | mV |
| | Vocm = 0.7 V setting | 680 ± 10% | | | mV |
| On-chip termination resistors | | 108±10% | | | Ω |
| Return loss differential mode | 50 MHz to 1.25 GHz (PCI Express) | -10 | | | dB |
| | 312 MHz to 625 MHz (XAUI) | | | | |
| Return loss common mode | 50 MHz to 1.25 GHz (PCI Express) | -6 | | | dB |
| Rise time | | 35 | - | 65 | ps |
| Fall time | | 35 | - | 65 | ps |
| Intra differential pair skew | V _{OD} = 800 mV | - | - | 15 | ps |
| Intra-transceiver block skew (x4) (13) | | - | - | 100 | ps |
| Transmitter PLL | | | | | |
| VCO frequency range | | 500 | - | 1562.5 | MHz |
| Bandwidth at 3.125 Gbps | BW = Low | | 3 | - | MHz |
| | BW = Med | | 5 | | |
| | BW = High | | 9 | | |
| Bandwidth at 2.5 Gbps | BW = Low | | 1 | - | MHz |
| | BW = Med | | 2 | | |
| | BW = High | | 4 | | |
| TX PLL lock time from gxb_powerdown deassertion (9), (14) | | - | - | 100 | us |

Table 4–6. Arria GX Transceiver Block AC Specification (Part 4 of 4)

| Symbol / Description | Conditions | -6 Speed Grade Commercial and Industrial | | | Unit |
|---------------------------|------------|--|-----|--------|------|
| | | Min | Typ | Max | |
| PCS | | | | | |
| Interface speed per mode | | 25 | | 156.25 | MHz |
| Digital Reset Pulse Width | | Minimum is 2 parallel clock cycles | | | |

Note to Table 4–6:

- (1) Spread spectrum clocking is allowed only in PCI Express (PIPE) mode if the upstream transmitter and the receiver share the same clock source.
- (2) The reference clock DC coupling option is only available in PCI Express (PIPE) mode for the HCSL I/O standard.
- (3) The `fixedclk` is used in PIPE mode receiver detect circuitry.
- (4) The device cannot tolerate prolonged operation at this absolute maximum.
- (5) The rate matcher supports only up to ± 300 PPM for PIPE mode and ± 100 PPM for GIGE mode.
- (6) This parameter is measured by embedding the run length data in a PRBS sequence.
- (7) Signal detect threshold detector circuitry is available only in PCI Express (PIPE mode).
- (8) Time taken for `rx_pll_locked` to go high from `rx_analogreset` deassertion. Refer to [Figure 4–1](#).
- (9) Refer to protocol characterization documents for lock times specific to the protocols.
- (10) Time for which the CDR needs to stay in LTR mode after `rx_pll_locked` is asserted and before `rx_locktodata` is asserted in manual mode. Refer to [Figure 4–1](#).
- (11) Time taken to recover valid data from GXB after the `rx_locktodata` signal is asserted in manual mode. Measurement results are based on PRBS31, for native data rates only. Refer to [Figure 4–1](#).
- (12) Time taken to recover valid data from GXB after the `rx_freqlocked` signal goes high in automatic mode. Measurement results are based on PRBS31, for native data rates only. Refer to [Figure 4–2](#).
- (13) This is applicable only to PCI Express (PIPE) $\times 4$ and XAUI $\times 4$ mode.
- (14) Time taken to lock TX PLL from `gxb_powerdown` deassertion.
- (15) The 1.2 V RX VICM settings is intended for DC-coupled LVDS links.

[Figure 4–1](#) shows the lock time parameters in manual mode. [Figure 4–2](#) shows the lock time parameters in automatic mode.



LTD = Lock to data

LTR = Lock to reference clock

Figure 4–1. Lock Time Parameters for Manual Mode

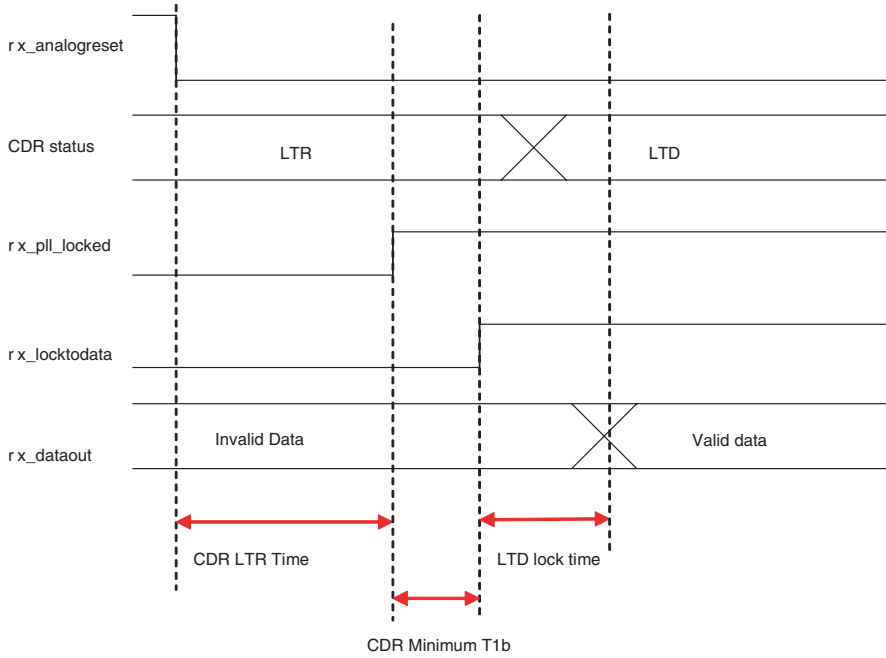


Figure 4–2. Lock Time Parameters for Automatic Mode

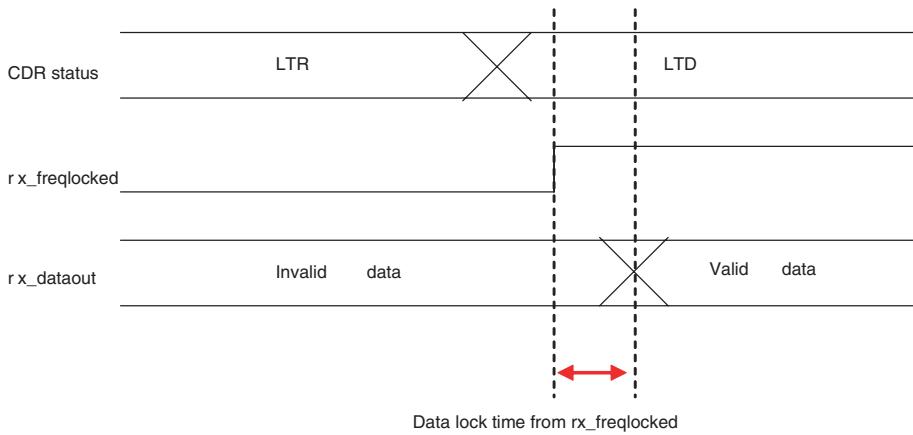


Figure 4-3 and Figure 4-4 show differential receiver input and transmitter output waveforms, respectively.

Figure 4-3. Receiver Input Waveform

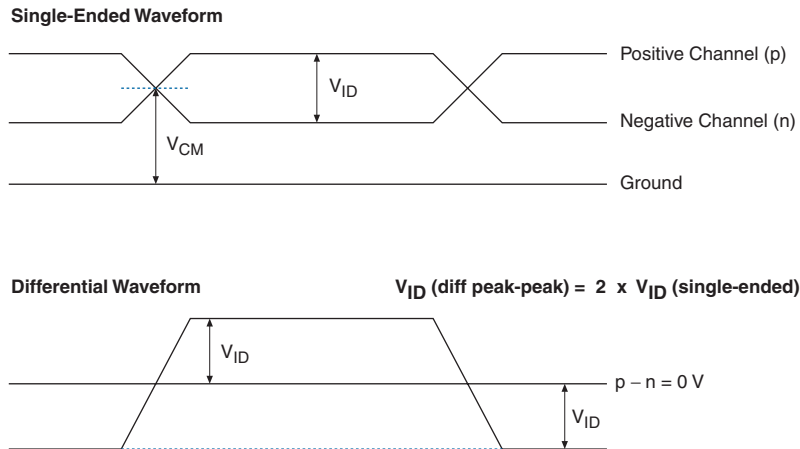


Figure 4-4. Transmitter Output Waveform

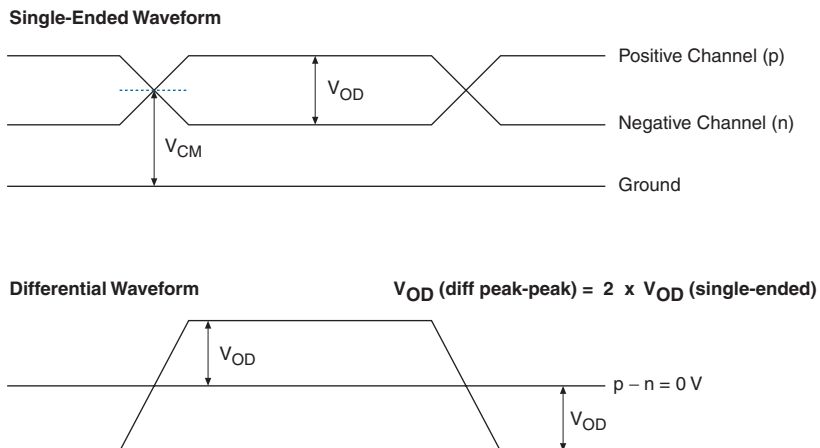


Table 4–7 shows the Arria GX transceiver block AC specification.

| Table 4–7. Arria GX Transceiver Block AC Specification Notes (1), (2), (3) (Part 1 of 3) | | | |
|---|--|---|-------------|
| Description | Condition | -6 Speed Grade Commercial & Industrial | Unit |
| XAUI Transmit Jitter Generation (4) | | | |
| Total jitter at 3.125 Gbps | REFCLK = 156.25 MHz Pattern = CJPAT V _{OD} = 1200 mV No Pre-emphasis | 0.3 | UI |
| Deterministic jitter at 3.125 Gbps | REFCLK = 156.25 MHz Pattern = CJPAT V _{OD} = 1200 mV No Pre-emphasis | 0.17 | UI |
| XAUI Receiver Jitter Tolerance (4) | | | |
| Total jitter | | > 0.65 | UI |
| Deterministic jitter | | > 0.37 | UI |
| Peak-to-peak jitter | Jitter frequency = 22.1 KHz | > 8.5 | UI |
| Peak-to-peak jitter | Jitter frequency = 1.875 MHz | > 0.1 | UI |
| Peak-to-peak jitter | Jitter frequency = 20 MHz | > 0.1 | UI |
| PCI Express (PIPE) Transmitter Jitter Generation (5) | | | |
| Total Transmitter Jitter Generation | Compliance Pattern; V _{OD} = 800 mV; Pre-emphasis = 49% | < 0.25 | UI p-p |
| PCI Express (PIPE) Receiver Jitter Tolerance (5) | | | |
| Total Receiver Jitter Tolerance | Compliance Pattern; DC Gain = 3 db | > 0.6 | UI p-p |
| Gigabit Ethernet (GIGE) Transmitter Jitter Generation (7) | | | |
| Total Transmitter Jitter Generation (TJ) | CRPAT; V _{OD} = 800 mV; Pre-emphasis = 0% | < 0.279 | UI p-p |
| Deterministic Transmitter Jitter Generation (DJ) | CRPAT; V _{OD} = 800 mV; Pre-emphasis = 0% | < 0.14 | UI p-p |
| Gigabit Ethernet (GIGE) Receiver Jitter Tolerance | | | |
| Total Jitter Tolerance | CJPAT Compliance Pattern; DC Gain = 0 dB | > 0.66 | UI p-p |
| Deterministic Jitter Tolerance | CJPAT Compliance Pattern; DC Gain = 0 dB | > 0.4 | UI p-p |

| Table 4–7. Arria GX Transceiver Block AC Specification Notes (1), (2), (3) (Part 2 of 3) | | | |
|---|--|---|-------------|
| Description | Condition | -6 Speed Grade Commercial & Industrial | Unit |
| Serial RapidIO (1.25 Gbps, 2.5 Gbps, and 3.125 Gbps) Transmitter Jitter Generation (6) | | | |
| Total Transmitter Jitter Generation (TJ) | CJPAT Compliance Pattern; V _{OD} = 800 mV; Pre-emphasis = 0% | < 0.35 | UI p-p |
| Deterministic Transmitter Jitter Generation (DJ) | CJPAT Compliance Pattern; V _{OD} = 800 mV; Pre-emphasis = 0% | < 0.17 | UI p-p |
| Serial RapidIO (1.25 Gbps, 2.5 Gbps, and 3.125 Gbps) Receiver Jitter Tolerance (6) | | | |
| Total Jitter Tolerance | CJPAT Compliance Pattern; DC Gain = 0 dB | > 0.65 | UI p-p |
| Combined Deterministic and Random Jitter Tolerance (J _{DR}) | CJPAT Compliance Pattern; DC Gain = 0 dB | > 0.55 | UI p-p |
| Deterministic Jitter Tolerance (J _D) | CJPAT Compliance Pattern; DC Gain = 0 dB | > 0.37 | UI p-p |
| Sinusoidal Jitter Tolerance | Jitter Frequency = 22.1 KHz | > 8.5 | UI p-p |
| | Jitter Frequency = 200 KHz | > 1.0 | UI p-p |
| | Jitter Frequency = 1.875 MHz | > 0.1 | UI p-p |
| | Jitter Frequency = 20 MHz | > 0.1 | UI p-p |
| SDI Transmitter Jitter Generation (8) | | | |
| Alignment Jitter (peak-to-peak) | Data Rate = 1.485 Gbps (HD) REFCLK = 74.25 MHz Pattern = Color Bar V _{od} = 800 mV No Pre-emphasis Low-Frequency Roll-Off = 100 KHz | 0.2 | UI |
| | Data Rate = 2.97 Gbps (3G) REFCLK = 148.5 MHz Pattern = Color Bar V _{od} = 800 mV No Pre-emphasis Low-Frequency Roll-Off = 100 KHz | 0.3 | UI |

| Table 4–7. Arria GX Transceiver Block AC Specification Notes (1), (2), (3) (Part 3 of 3) | | | |
|---|--|---|-------------|
| Description | Condition | -6 Speed Grade Commercial & Industrial | Unit |
| SDI Receiver Jitter Tolerance (8) | | | |
| Sinusoidal Jitter Tolerance (peak-to-peak) | Jitter Frequency = 15 KHz Data Rate = 2.97 Gbps (3G) REFCLK = 148.5 MHz Pattern = Single Line Scramble Color Bar No Equalization DC Gain = 0 dB | > 2 | UI |
| | Jitter Frequency = 100 KHz Data Rate = 2.97 Gbps (3G) REFCLK = 148.5 MHz Pattern = Single Line Scramble Color Bar No Equalization DC Gain = 0 dB | > 0.3 | UI |
| | Jitter Frequency = 148.5 MHz Data Rate = 2.97 Gbps (3G) REFCLK = 148.5 MHz Pattern = Single Line Scramble Color Bar No Equalization DC Gain = 0 dB | > 0.3 | UI |
| Sinusoidal Jitter Tolerance (peak-to-peak) | Jitter Frequency = 20 KHz Data Rate = 1.485 Gbps (HD) REFCLK = 74.25 MHz Pattern = 75% Color Bar No Equalization DC Gain = 0 dB | > 1 | UI |
| | Jitter Frequency = 100 KHz Data Rate = 1.485 Gbps (HD) REFCLK = 74.25 MHz Pattern = 75% Color Bar No Equalization DC Gain = 0 dB | > 0.2 | UI |

Notes to Table 4–7:

- (1) Dedicated REFCLK pins were used to drive the input reference clocks.
- (2) Jitter numbers specified are valid for the stated conditions only.
- (3) Refer to the protocol characterization documents for detailed information.
- (4) The jitter numbers for XAUI are compliant to the IEEE802.3ae-2002 Specification.
- (5) The jitter numbers for PCI Express are compliant to the PCIe Base Specification 2.0.
- (6) The jitter numbers for Serial RapidIO are compliant to the RapidIO Specification 1.3.
- (7) The jitter numbers for GIGE are compliant to the IEEE802.3-2002 Specification.
- (8) The HD-SDI and 3G-SDI jitter numbers are compliant to the SMPTE292M and SMPTE424M specifications.

Tables 4–8 and 4–9 show the transmitter and receiver PCS latency for each mode, respectively.

Table 4–8. PCS Latency *Note (1)*

| Functional Mode | Configuration | Transmitter PCS Latency | | | | | |
|--------------------|---------------------------------------|-------------------------|--------------------|-----------------|------------------|----------------|---------|
| | | TX PIPE | TX Phase Comp FIFO | Byte Serializer | TX State Machine | 8B/10B Encoder | Sum (2) |
| XAUI | | - | 2-3 | 1 | 0.5 | 0.5 | 4-5 |
| PIPE | ×1, ×4, ×8 8-bit channel width | 1 | 3-4 | 1 | - | 1 | 6-7 |
| | ×1, ×4, ×8 16-bit channel width | 1 | 3-4 | 1 | - | 0.5 | 6-7 |
| GIGE | | - | 2-3 | 1 | - | 1 | 4-5 |
| Serial RapidIO | 1.25 Gbps, 2.5 Gbps, 3.125 Gbps | - | 2-3 | 1 | - | 0.5 | 4-5 |
| SDI | HD 10-bit channel width | - | 2-3 | 1 | - | 1 | 4-5 |
| | HD, 3G 20-bit channel width | - | 2-3 | 1 | - | 0.5 | 4-5 |
| BASIC Single Width | 8-bit/10-bit channel width | - | 2-3 | 1 | - | 1 | 4-5 |
| | 16-bit/20-bit channel width | - | 2-3 | 1 | - | 0.5 | 4-5 |

Notes to Tables 4–8:

- (1) The latency numbers are with respect to the PLD-transceiver interface clock cycles.
- (2) The total latency number is rounded off in the Sum column.

Table 4–9. PCS Latency (Part 1 of 2) Note (1)

| Functional Mode | Configuration | Receiver PCS Latency | | | | | | | | | |
|-----------------|---------------------------------------|----------------------|-------------|------------------|----------------|------------------------|--------------------|------------|--------------------------|---------------|---------|
| | | Word Aligner | Deskew FIFO | Rate Matcher (3) | 8B/10B Decoder | Receiver State Machine | Byte De-serializer | Byte Order | Receiver Phase Comp FIFO | Receiver PIPE | Sum (2) |
| XAUI | | 2-2.5 | 2-2.5 | 5.5-6.5 | 0.5 | 1 | 1 | 1 | 1-2 | - | 14-17 |
| PIPE | ×1, ×4 8-bit channel width | 4-5 | - | 11-13 | 1 | - | 1 | 1 | 2-3 | 1 | 21-25 |
| | ×1, ×4 16-bit channel width | 2-2.5 | - | 5.5-6.5 | 0.5 | - | 1 | 1 | 2-3 | 1 | 13-16 |
| GIGE | | 4-5 | - | 11-13 | 1 | - | 1 | 1 | 1-2 | - | 19-23 |
| Serial RapidIO | 1.25 Gbps, 2.5 Gbps, 3.125 Gbps | 2-2.5 | - | - | 0.5 | - | 1 | 1 | 1-2 | - | 6-7 |
| SDI | HD 10-bit channel width | 5 | - | - | 1 | - | 1 | 1 | 1-2 | - | 9-10 |
| | HD, 3G 20-bit channel width | 2.5 | - | - | 0.5 | - | 1 | 1 | 1-2 | - | 6-7 |

Table 4–9. PCS Latency (Part 2 of 2) Note (1)

| Functional Mode | Configuration | Receiver PCS Latency | | | | | | | | | |
|--------------------|---|----------------------|-------------|------------------|----------------|------------------------|--------------------|------------|--------------------------|---------------|---------|
| | | Word Aligner | Deskew FIFO | Rate Matcher (3) | 8B/10B Decoder | Receiver State Machine | Byte De-serializer | Byte Order | Receiver Phase Comp FIFO | Receiver PIPE | Sum (2) |
| BASIC Single Width | 8/10-bit channel width; with Rate Matcher | 4-5 | - | 11-13 | 1 | - | 1 | 1 | 1-2 | 1 | 19-23 |
| | 8/10-bit channel width; without Rate Matcher | 4-5 | - | - | 1 | - | 1 | 1 | 1-2 | - | 8-10 |
| | 16/20-bit channel width; with Rate Matcher | 2-2.5 | - | 5.5-6.5 | 0.5 | - | 1 | 1 | 1-2 | - | 11-14 |
| | 16/20-bit channel width; without Rate Matcher | 2-2.5 | - | - | 0.5 | - | 1 | 1 | 1-2 | - | 6-7 |

Notes to Tables 4–9:

- (1) The latency numbers are with respect to the PLD-transceiver interface clock cycles.
- (2) The total latency number is rounded off in the Sum column.
- (3) The rate matcher latency shown is the steady state latency. Actual latency may vary depending on the skip ordered set gap allowed by the protocol, actual PPM difference between the reference clocks, and so forth.

Tables 4–10 to Tables 4–13 show the typical V_{OD} for data rates from 600 Mbps to 3.125 Gbps. The specification is for measurement at the package ball.

Table 4–10. Typical V_{OD} Setting, TX Term = 100 Ω

| $V_{ccHTX} = 1.5\text{ V}$ | V_{OD} Setting (mV) | | | | |
|----------------------------|-----------------------|-----|-----|------|------|
| | 400 | 600 | 800 | 1000 | 1200 |
| V_{OD} Typical (mV) | 430 | 625 | 830 | 1020 | 1200 |

Table 4–11. Typical V_{OD} Setting, TX Term = 100 Ω

| $V_{ccHTX} = 1.2\text{ V}$ | V_{OD} Setting (mV) | | | | |
|----------------------------|-----------------------|-----|-----|-----|-----|
| | 320 | 480 | 640 | 800 | 960 |
| V_{OD} Typical (mV) | 344 | 500 | 664 | 816 | 960 |

Table 4–12. Typical Pre-Emphasis (First Post-Tap), Note (1)

| $V_{ccHTX} = 1.5\text{ V}$ | First Post Tap Pre-Emphasis Level | | | | |
|----------------------------|-----------------------------------|-----|------|------|------|
| V_{OD} Setting (mV) | 1 | 2 | 3 | 4 | 5 |
| | TX Term = 100 Ω | | | | |
| 400 | 24% | 62% | 112% | 184% | |
| 600 | | 31% | 56% | 86% | 122% |
| 800 | | 20% | 35% | 53% | 73% |
| 1000 | | | 23% | 36% | 49% |
| 1200 | | | 17% | 25% | 35% |

Note to Table 4–12:

- (1) Applicable to data rates from 600 Mbps to 3.125 Gbps. Specification is for measurement at the package ball.

Table 4–13. Typical Pre-Emphasis (First Post-Tap), Note (1)

| V _{CC} HTX = 1.2 V | First Post Tap Pre-Emphasis Level | | | | |
|--------------------------------|-----------------------------------|-----|------|-----|------|
| | V _{OD} Setting (mV) | 1 | 2 | 3 | 4 |
| TX Term = 100 Ω | | | | | |
| 320 | 24% | 61% | 114% | | |
| 480 | | 31% | 55% | 86% | 121% |
| 640 | | 20% | 35% | 54% | 72% |
| 800 | | | 23% | 36% | 49% |
| 960 | | | 18% | 25% | 35% |

Note to Table 4–13:

- (1) Applicable to data rates from 600 Mbps to 3.125 Gbps. Specification is for measurement at the package ball.

DC Electrical Characteristics

Table 4–14 shows the Arria GX device family DC electrical characteristics.

Table 4–14. Arria GX Device DC Operating Conditions (Part 1 of 2) Note (1)

| Symbol | Parameter | Conditions | Device | Minimum | Typical | Maximum | Unit |
|---------------------|---|---|-------------|---------|---------|---------|------|
| I _I | Input pin leakage current | V _I = V _{CCIOmax} to 0 V (2) | All | –10 | | 10 | μA |
| I _{OZ} | Tri-stated I/O pin leakage current | V _O = V _{CCIOmax} to 0 V (2) | All | –10 | | 10 | μA |
| I _{CCINT0} | V _{CCINT} supply current (standby) | V _I = ground, no load, no toggling inputs T _J = 25 °C | EP1AGX20/35 | | 0.30 | (3) | A |
| | | | EP1AGX50/60 | | 0.50 | (3) | A |
| | | | EP1AGX90 | | 0.62 | (3) | A |
| I _{CCPD0} | V _{CCPD} supply current (standby) | V _I = ground, no load, no toggling inputs T _J = 25 °C, V _{CCPD} = 3.3V | EP1AGX20/35 | | 2.7 | (3) | mA |
| | | | EP1AGX50/60 | | 3.6 | (3) | mA |
| | | | EP1AGX90 | | 4.3 | (3) | mA |
| I _{CCIO0} | V _{CCIO} supply current (standby) | V _I = ground, no load, no toggling inputs T _J = 25 °C | EP1AGX20/35 | | 4.0 | (3) | mA |
| | | | EP1AGX50/60 | | 4.0 | (3) | mA |
| | | | EP1AGX90 | | 4.0 | (3) | mA |

| Symbol | Parameter | Conditions | Device | Minimum | Typical | Maximum | Unit |
|-------------------|--|------------------------------------|--------|---------|---------|---------|-----------|
| R_{CONF} (4) | Value of I/O pin pull-up resistor before and during configuration | $V_i = 0, V_{CCIO} = 3.3\text{ V}$ | | 10 | 25 | 50 | $k\Omega$ |
| | | $V_i = 0, V_{CCIO} = 2.5\text{ V}$ | | 15 | 35 | 70 | $k\Omega$ |
| | | $V_i = 0, V_{CCIO} = 1.8\text{ V}$ | | 30 | 50 | 100 | $k\Omega$ |
| | | $V_i = 0, V_{CCIO} = 1.5\text{ V}$ | | 40 | 75 | 150 | $k\Omega$ |
| | | $V_i = 0, V_{CCIO} = 1.2\text{ V}$ | | 50 | 90 | 170 | $k\Omega$ |
| | Recommended value of I/O pin external pull-down resistor before and during configuration | | | | | 1 | 2 |

Notes to Table 4–14:

- (1) Typical values are for $T_A = 25\text{ }^\circ\text{C}$, $V_{CCINT} = 1.2\text{ V}$, and $V_{CCIO} = 1.2\text{ V}, 1.5\text{ V}, 1.8\text{ V}, 2.5\text{ V}$, and 3.3 V .
- (2) This value is specified for normal device operation. The value may vary during power-up. This applies for all V_{CCIO} settings (3.3, 2.5, 1.8, 1.5, and 1.2 V).
- (3) Maximum values depend on the actual T_J and design utilization. See the Excel-based PowerPlay Early Power Estimator (available at www.altera.com) or the Quartus® II PowerPlay Power Analyzer feature for maximum values. See the section “Power Consumption” on page 4–34 for more information.
- (4) Pin pull-up resistance values will be lower if an external source drives the pin higher than V_{CCIO} .

I/O Standard Specifications

Tables 4–15 through 4–38 show the Arria GX device family I/O standard specifications.

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|----------------|---------------------------|-----------------------------|---------|---------|------|
| V_{CCIO} (1) | Output supply voltage | | 3.135 | 3.465 | V |
| V_{IH} | High-level input voltage | | 1.7 | 4.0 | V |
| V_{IL} | Low-level input voltage | | –0.3 | 0.8 | V |
| V_{OH} | High-level output voltage | $I_{OH} = -4\text{ mA}$ (2) | 2.4 | | V |

Table 4–15. LVTTL Specifications

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|----------|--------------------------|-----------------------------|---------|---------|------|
| V_{OL} | Low-level output voltage | $I_{OL} = 4 \text{ mA}$ (2) | | 0.45 | V |

Notes to Table 4–15:

- (1) Arria GX devices comply to the narrow range for the supply voltage as specified in the EIA/JEDEC Standard, JESD8-B.
- (2) This specification is supported across all the programmable drive strength settings available for this I/O standard.

Table 4–16. LVCMOS Specifications

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|---------------|---------------------------|--|------------------|---------|------|
| $V_{CCIO}(1)$ | Output supply voltage | | 3.135 | 3.465 | V |
| V_{IH} | High-level input voltage | | 1.7 | 4.0 | V |
| V_{IL} | Low-level input voltage | | –0.3 | 0.8 | V |
| V_{OH} | High-level output voltage | $V_{CCIO} = 3.0, I_{OH} = -0.1 \text{ mA}$ (2) | $V_{CCIO} - 0.2$ | | V |
| V_{OL} | Low-level output voltage | $V_{CCIO} = 3.0, I_{OL} = 0.1 \text{ mA}$ (2) | | 0.2 | V |

Notes to Table 4–16:

- (1) Arria GX devices comply to the narrow range for the supply voltage as specified in the EIA/JEDEC Standard, JESD8-B.
- (2) This specification is supported across all the programmable drive strength available for this I/O standard.

Table 4–17. 2.5-V I/O Specifications

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|----------------|---------------------------|------------------------------|---------|---------|------|
| V_{CCIO} (1) | Output supply voltage | | 2.375 | 2.625 | V |
| V_{IH} | High-level input voltage | | 1.7 | 4.0 | V |
| V_{IL} | Low-level input voltage | | –0.3 | 0.7 | V |
| V_{OH} | High-level output voltage | $I_{OH} = -1 \text{ mA}$ (2) | 2.0 | | V |
| V_{OL} | Low-level output voltage | $I_{OL} = 1 \text{ mA}$ (2) | | 0.4 | V |

Notes to Table 4–17:

- (1) The Arria GX device V_{CCIO} voltage level support of 2.5 to 5% is narrower than defined in the normal range of the EIA/JEDEC standard.
- (2) This specification is supported across all the programmable drive settings available for this I/O standard.

Table 4–18. 1.8-V I/O Specifications

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|----------------|---------------------------|------------------------------|------------------------|------------------------|------|
| V_{CCIO} (1) | Output supply voltage | | 1.71 | 1.89 | V |
| V_{IH} | High-level input voltage | | $0.65 \times V_{CCIO}$ | 2.25 | V |
| V_{IL} | Low-level input voltage | | –0.3 | $0.35 \times V_{CCIO}$ | V |
| V_{OH} | High-level output voltage | $I_{OH} = -2 \text{ mA}$ (2) | $V_{CCIO} - 0.45$ | | V |
| V_{OL} | Low-level output voltage | $I_{OL} = 2 \text{ mA}$ (2) | | 0.45 | V |

Notes to Table 4–18:

- (1) The Arria GX device V_{CCIO} voltage level support of 1.8 to 5% is narrower than defined in the normal range of the EIA/JEDEC standard.
- (2) This specification is supported across all the programmable drive settings available for this I/O standard as shown in *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–19. 1.5-V I/O Specifications

| Symbol | Parameter | Conditions | Minimum | Maximum | Unit |
|----------------|---------------------------|------------------------------|-----------------|------------------|------|
| V_{CCIO} (1) | Output supply voltage | | 1.425 | 1.575 | V |
| V_{IH} | High-level input voltage | | $0.65 V_{CCIO}$ | $V_{CCIO} + 0.3$ | V |
| V_{IL} | Low-level input voltage | | -0.3 | $0.35 V_{CCIO}$ | V |
| V_{OH} | High-level output voltage | $I_{OH} = -2 \text{ mA}$ (2) | $0.75 V_{CCIO}$ | | V |
| V_{OL} | Low-level output voltage | $I_{OL} = 2 \text{ mA}$ (2) | | $0.25 V_{CCIO}$ | V |

Notes to Table 4–19:

- (1) The Arria GX device V_{CCIO} voltage level support of 1.5 to 5% is narrower than defined in the normal range of the EIA/JEDEC standard.
- (2) This specification is supported across all the programmable drive settings available for this I/O standard as shown in *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Figures 4–5 and 4–6 show receiver input and transmitter output waveforms, respectively, for all differential I/O standards (LVDS and LVPECL).

Figure 4–5. Receiver Input Waveforms for Differential I/O Standards

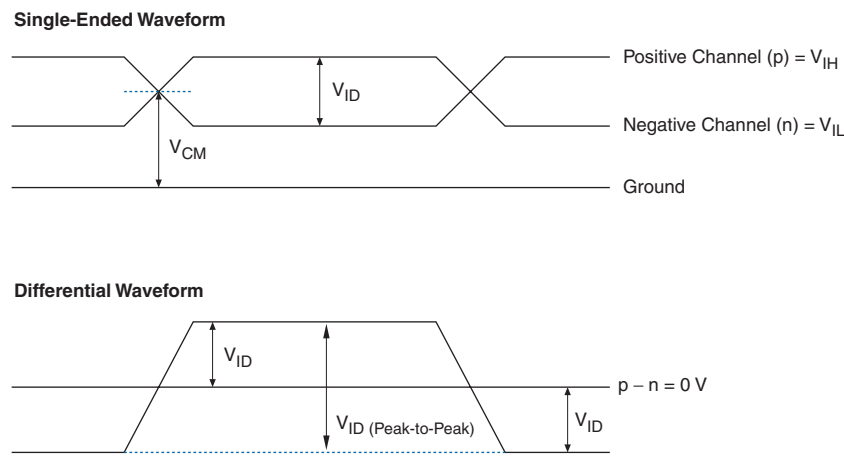


Figure 4–6. Transmitter Output Waveforms for Differential I/O Standards

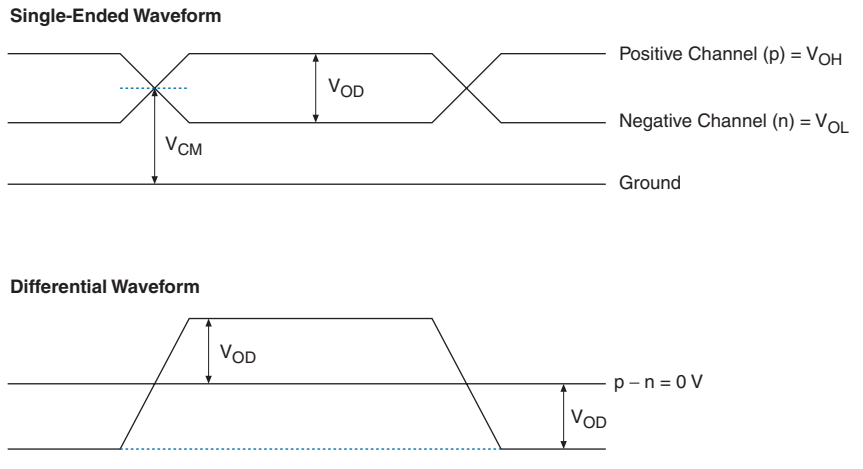


Table 4–20. 2.5-V LVDS I/O Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|------------|--|---------------------|---------|---------|---------|----------|
| V_{CCIO} | I/O supply voltage for left and right I/O banks (1, 2, 5, and 6) | | 2.375 | 2.5 | 2.625 | V |
| V_{ID} | Input differential voltage swing (single-ended) | | 100 | 350 | 900 | mV |
| V_{ICM} | Input common mode voltage | | 200 | 1,250 | 1,800 | mV |
| V_{OD} | Output differential voltage (single-ended) | $R_L = 100\ \Omega$ | 250 | | 450 | mV |
| V_{OCM} | Output common mode voltage | $R_L = 100\ \Omega$ | 1.125 | | 1.375 | V |
| R_L | Receiver differential input discrete resistor (external to Arria GX devices) | | 90 | 100 | 110 | Ω |

Table 4–21. 3.3-V LVDS I/O Specifications (Part 1 of 2)

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|----------------|---|------------|---------|---------|---------|------|
| $V_{CCIO} (1)$ | I/O supply voltage for top and bottom PLL banks (9, 10, 11, and 12) | | 3.135 | 3.3 | 3.465 | V |
| V_{ID} | Input differential voltage swing (single-ended) | | 100 | 350 | 900 | mV |

Table 4–21. 3.3-V LVDS I/O Specifications (Part 2 of 2)

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|-----------|--|--------------------|---------|---------|---------|----------|
| V_{ICM} | Input common mode voltage | | 200 | 1,250 | 1,800 | mV |
| V_{OD} | Output differential voltage (single-ended) | $R_L = 100 \Omega$ | 250 | | 710 | mV |
| V_{OCM} | Output common mode voltage | $R_L = 100 \Omega$ | 840 | | 1,570 | mV |
| R_L | Receiver differential input discrete resistor (external to Arria GX devices) | | 90 | 100 | 110 | Ω |

Note to Table 4–21:

- (1) The top and bottom clock input differential buffers in I/O banks 3, 4, 7, and 8 are powered by V_{CCINT} , not V_{CCIO} . The PLL clock output/feedback differential buffers are powered by VCC_PLL_OUT . For differential clock output/feedback operation, connect VCC_PLL_OUT to 3.3 V.

Table 4–22. 3.3-V PCML Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Units |
|------------------|---|------------|---------|------------|---------|----------|
| V_{CCIO} | I/O supply voltage | | 3.135 | 3.3 | 3.465 | V |
| V_{ID} | Input differential voltage swing (single-ended) | | 300 | | 600 | mV |
| V_{ICM} | Input common mode voltage | | 1.5 | | 3.465 | V |
| V_{OD} | Output differential voltage (single-ended) | | 300 | 370 | 500 | mV |
| ΔV_{OD} | Change in V_{OD} between high and low | | | | 50 | mV |
| V_{OCM} | Output common mode voltage | | 2.5 | 2.85 | 3.3 | V |
| ΔV_{OCM} | Change in V_{OCM} between high and low | | | | 50 | mV |
| V_T | Output termination voltage | | | V_{CCIO} | | V |
| R_1 | Output external pull-up resistors | | 45 | 50 | 55 | Ω |
| R_2 | Output external pull-up resistors | | 45 | 50 | 55 | Ω |

Table 4–23. LVPECL Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|----------------|---|--------------------|---------|---------|---------|----------|
| V_{CCIO} (1) | I/O supply voltage | | 3.135 | 3.3 | 3.465 | V |
| V_{ID} | Input differential voltage swing (single-ended) | | 300 | 600 | 1,000 | mV |
| V_{ICM} | Input common mode voltage | | 1.0 | | 2.5 | V |
| V_{OD} | Output differential voltage (single-ended) | $R_L = 100 \Omega$ | 525 | | 970 | mV |
| V_{OCM} | Output common mode voltage | $R_L = 100 \Omega$ | 1,650 | | 2,250 | mV |
| R_L | Receiver differential input resistor | | 90 | 100 | 110 | Ω |

Note to Table 4–23:

- (1) The top and bottom clock input differential buffers in I/O banks 3, 4, 7, and 8 are powered by V_{CCINT} , not V_{CCIO} . The PLL clock output/feedback differential buffers are powered by VCC_PLL_OUT . For differential clock output/feedback operation, connect VCC_PLL_OUT to 3.3 V.

Table 4–24. 3.3-V PCI Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|------------|---------------------------|-------------------------|----------------|---------|------------------|------|
| V_{CCIO} | Output supply voltage | | 3.0 | 3.3 | 3.6 | V |
| V_{IH} | High-level input voltage | | $0.5 V_{CCIO}$ | | $V_{CCIO} + 0.5$ | V |
| V_{IL} | Low-level input voltage | | -0.3 | | $0.3 V_{CCIO}$ | V |
| V_{OH} | High-level output voltage | $I_{OUT} = -500 \mu A$ | $0.9 V_{CCIO}$ | | | V |
| V_{OL} | Low-level output voltage | $I_{OUT} = 1,500 \mu A$ | | | $0.1 V_{CCIO}$ | V |

Table 4–25. PCI-X Mode 1 Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|------------|---------------------------|-------------------------|----------------|---------|------------------|------|
| V_{CCIO} | Output supply voltage | | 3.0 | | 3.6 | V |
| V_{IH} | High-level input voltage | | $0.5 V_{CCIO}$ | | $V_{CCIO} + 0.5$ | V |
| V_{IL} | Low-level input voltage | | -0.3 | | $0.35 V_{CCIO}$ | V |
| V_{IPU} | Input pull-up voltage | | $0.7 V_{CCIO}$ | | | V |
| V_{OH} | High-level output voltage | $I_{OUT} = -500 \mu A$ | $0.9 V_{CCIO}$ | | | V |
| V_{OL} | Low-level output voltage | $I_{OUT} = 1,500 \mu A$ | | | $0.1 V_{CCIO}$ | V |

Table 4–26. SSTL-18 Class I Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|---------------|-----------------------------|--------------------------------|-------------------|-----------|-------------------|------|
| V_{CCIO} | Output supply voltage | | 1.71 | 1.8 | 1.89 | V |
| V_{REF} | Reference voltage | | 0.855 | 0.9 | 0.945 | V |
| V_{TT} | Termination voltage | | $V_{REF} - 0.04$ | V_{REF} | $V_{REF} + 0.04$ | V |
| $V_{IH} (DC)$ | High-level DC input voltage | | $V_{REF} + 0.125$ | | | V |
| $V_{IL} (DC)$ | Low-level DC input voltage | | | | $V_{REF} - 0.125$ | V |
| $V_{IH} (AC)$ | High-level AC input voltage | | $V_{REF} + 0.25$ | | | V |
| $V_{IL} (AC)$ | Low-level AC input voltage | | | | $V_{REF} - 0.25$ | V |
| V_{OH} | High-level output voltage | $I_{OH} = -6.7 \text{ mA}$ (1) | $V_{TT} + 0.475$ | | | V |
| V_{OL} | Low-level output voltage | $I_{OL} = 6.7 \text{ mA}$ (1) | | | $V_{TT} - 0.475$ | V |

Note to Table 4–26:

- (1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–27. SSTL-18 Class II Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|---------------|-----------------------------|---------------------------------|-------------------|-----------|-------------------|------|
| V_{CCIO} | Output supply voltage | | 1.71 | 1.8 | 1.89 | V |
| V_{REF} | Reference voltage | | 0.855 | 0.9 | 0.945 | V |
| V_{TT} | Termination voltage | | $V_{REF} - 0.04$ | V_{REF} | $V_{REF} + 0.04$ | V |
| $V_{IH} (DC)$ | High-level DC input voltage | | $V_{REF} + 0.125$ | | | V |
| $V_{IL} (DC)$ | Low-level DC input voltage | | | | $V_{REF} - 0.125$ | V |
| $V_{IH} (AC)$ | High-level AC input voltage | | $V_{REF} + 0.25$ | | | V |
| $V_{IL} (AC)$ | Low-level AC input voltage | | | | $V_{REF} - 0.25$ | V |
| V_{OH} | High-level output voltage | $I_{OH} = -13.4 \text{ mA}$ (1) | $V_{CCIO} - 0.28$ | | | V |
| V_{OL} | Low-level output voltage | $I_{OL} = 13.4 \text{ mA}$ (1) | | | 0.28 | V |

Note to Table 4–27:

- (1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–28. SSTL-18 Class I & II Differential Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|------------------|---|------------|------------------------|----------------|------------------------|------|
| V_{CCIO} | Output supply voltage | | 1.71 | 1.8 | 1.89 | V |
| V_{SWING} (DC) | DC differential input voltage | | 0.25 | | | V |
| V_X (AC) | AC differential input cross point voltage | | $(V_{CCIO}/2) - 0.175$ | | $(V_{CCIO}/2) + 0.175$ | V |
| V_{SWING} (AC) | AC differential input voltage | | 0.5 | | | V |
| V_{ISO} | Input clock signal offset voltage | | | $0.5 V_{CCIO}$ | | V |
| ΔV_{ISO} | Input clock signal offset voltage variation | | | 200 | | mV |
| V_{OX} (AC) | AC differential cross point voltage | | $(V_{CCIO}/2) - 0.125$ | | $(V_{CCIO}/2) + 0.125$ | V |

Table 4–29. SSTL-2 Class I Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|---------------|-----------------------------|--------------------------------|------------------|-----------|------------------|------|
| V_{CCIO} | Output supply voltage | | 2.375 | 2.5 | 2.625 | V |
| V_{TT} | Termination voltage | | $V_{REF} - 0.04$ | V_{REF} | $V_{REF} + 0.04$ | V |
| V_{REF} | Reference voltage | | 1.188 | 1.25 | 1.313 | V |
| V_{IH} (DC) | High-level DC input voltage | | $V_{REF} + 0.18$ | | 3.0 | V |
| V_{IL} (DC) | Low-level DC input voltage | | -0.3 | | $V_{REF} - 0.18$ | V |
| V_{IH} (AC) | High-level AC input voltage | | $V_{REF} + 0.35$ | | | V |
| V_{IL} (AC) | Low-level AC input voltage | | | | $V_{REF} - 0.35$ | V |
| V_{OH} | High-level output voltage | $I_{OH} = -8.1 \text{ mA}$ (1) | $V_{TT} + 0.57$ | | | V |
| V_{OL} | Low-level output voltage | $I_{OL} = 8.1 \text{ mA}$ (1) | | | $V_{TT} - 0.57$ | V |

Note to Table 4–29:

- (1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–30. SSTL-2 Class II Specifications (Part 1 of 2)

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|------------|-----------------------|------------|------------------|-----------|------------------|------|
| V_{CCIO} | Output supply voltage | | 2.375 | 2.5 | 2.625 | V |
| V_{TT} | Termination voltage | | $V_{REF} - 0.04$ | V_{REF} | $V_{REF} + 0.04$ | V |
| V_{REF} | Reference voltage | | 1.188 | 1.25 | 1.313 | V |

Table 4–30. SSTL-2 Class II Specifications (Part 2 of 2)

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|----------------------|-----------------------------|--------------------------------|-------------------------|---------|-------------------------|------|
| V _{IH} (DC) | High-level DC input voltage | | V _{REF} + 0.18 | | V _{CCIO} + 0.3 | V |
| V _{IL} (DC) | Low-level DC input voltage | | –0.3 | | V _{REF} – 0.18 | V |
| V _{IH} (AC) | High-level AC input voltage | | V _{REF} + 0.35 | | | V |
| V _{IL} (AC) | Low-level AC input voltage | | | | V _{REF} – 0.35 | V |
| V _{OH} | High-level output voltage | I _{OH} = –16.4 mA (1) | V _{TT} + 0.76 | | | V |
| V _{OL} | Low-level output voltage | I _{OL} = 16.4 mA (1) | | | V _{TT} – 0.76 | V |

Note to Table 4–30:

- (1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–31. SSTL-2 Class I & II Differential Specifications Note (1)

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|-------------------------|---|------------|------------------------------|-----------------------|------------------------------|------|
| V _{CCIO} | Output supply voltage | | 2.375 | 2.5 | 2.625 | V |
| V _{SWING} (DC) | DC differential input voltage | | 0.36 | | | V |
| V _X (AC) | AC differential input cross point voltage | | (V _{CCIO} /2) – 0.2 | | (V _{CCIO} /2) + 0.2 | V |
| V _{SWING} (AC) | AC differential input voltage | | 0.7 | | | V |
| V _{ISO} | Input clock signal offset voltage | | | 0.5 V _{CCIO} | | V |
| ΔV _{ISO} | Input clock signal offset voltage variation | | | 200 | | mV |
| V _{OX} (AC) | AC differential output cross point voltage | | (V _{CCIO} /2) – 0.2 | | (V _{CCIO} /2) + 0.2 | V |

Note to Table 4–31:

- (1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–32. 1.2-V HSTL Specifications (Part 1 of 2)

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|----------------------|-----------------------------|------------|-------------------------|-----------------------|--------------------------|------|
| V _{CCIO} | Output supply voltage | | 1.14 | 1.2 | 1.26 | V |
| V _{REF} | Reference voltage | | 0.48 V _{CCIO} | 0.5 V _{CCIO} | 0.52 V _{CCIO} | V |
| V _{IH} (DC) | High-level DC input voltage | | V _{REF} + 0.08 | | V _{CCIO} + 0.15 | V |
| V _{IL} (DC) | Low-level DC input voltage | | –0.15 | | V _{REF} – 0.08 | V |
| V _{IH} (AC) | High-level AC input voltage | | V _{REF} + 0.15 | | V _{CCIO} + 0.24 | V |

Table 4–32. 1.2-V HSTL Specifications (Part 2 of 2)

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|----------------------|----------------------------|-------------------------|-------------------------|---------|--------------------------|------|
| V _{IL} (AC) | Low-level AC input voltage | | –0.24 | | V _{REF} – 0.15 | V |
| V _{OH} | High-level output voltage | I _{OH} = 8 mA | V _{REF} + 0.15 | | V _{CCIO} + 0.15 | V |
| V _{OL} | Low-level output voltage | I _{OH} = –8 mA | –0.15 | | V _{REF} – 0.15 | V |

Table 4–33. 1.5-V HSTL Class I Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|----------------------|-----------------------------|-----------------------------|-------------------------|---------|------------------------|------|
| V _{CCIO} | Output supply voltage | | 1.425 | 1.5 | 1.575 | V |
| V _{REF} | Input reference voltage | | 0.713 | 0.75 | 0.788 | V |
| V _{TT} | Termination voltage | | 0.713 | 0.75 | 0.788 | V |
| V _{IH} (DC) | DC high-level input voltage | | V _{REF} + 0.1 | | | V |
| V _{IL} (DC) | DC low-level input voltage | | –0.3 | | V _{REF} – 0.1 | V |
| V _{IH} (AC) | AC high-level input voltage | | V _{REF} + 0.2 | | | V |
| V _{IL} (AC) | AC low-level input voltage | | | | V _{REF} – 0.2 | V |
| V _{OH} | High-level output voltage | I _{OH} = 8 mA (1) | V _{CCIO} – 0.4 | | | V |
| V _{OL} | Low-level output voltage | I _{OH} = –8 mA (1) | | | 0.4 | V |

Note to Table 4–33:

- (1) This specification is supported across all the programmable drive settings available for this I/O standard as shown in the *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–34. 1.5-V HSTL Class II Specifications (Part 1 of 2)

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|----------------------|-----------------------------|-----------------------------|-------------------------|---------|------------------------|------|
| V _{CCIO} | Output supply voltage | | 1.425 | 1.50 | 1.575 | V |
| V _{REF} | Input reference voltage | | 0.713 | 0.75 | 0.788 | V |
| V _{TT} | Termination voltage | | 0.713 | 0.75 | 0.788 | V |
| V _{IH} (DC) | DC high-level input voltage | | V _{REF} + 0.1 | | | V |
| V _{IL} (DC) | DC low-level input voltage | | –0.3 | | V _{REF} – 0.1 | V |
| V _{IH} (AC) | AC high-level input voltage | | V _{REF} + 0.2 | | | V |
| V _{IL} (AC) | AC low-level input voltage | | | | V _{REF} – 0.2 | V |
| V _{OH} | High-level output voltage | I _{OH} = 16 mA (1) | V _{CCIO} – 0.4 | | | V |

Table 4–34. 1.5-V HSTL Class II Specifications (Part 2 of 2)

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|-----------------|--------------------------|------------------------------|---------|---------|---------|------|
| V _{OL} | Low-level output voltage | I _{OH} = –16 mA (1) | | | 0.4 | V |

Note to Table 4–34:

- (1) This specification is supported across all the programmable drive settings available for this I/O standard, as shown in the *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–35. 1.5-V HSTL Class I & II Differential Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|-----------------------|-------------------------------------|------------|---------|---------|---------|------|
| V _{CCIO} | I/O supply voltage | | 1.425 | 1.5 | 1.575 | V |
| V _{DIF} (DC) | DC input differential voltage | | 0.2 | | | V |
| V _{CM} (DC) | DC common mode input voltage | | 0.68 | | 0.9 | V |
| V _{DIF} (AC) | AC differential input voltage | | 0.4 | | | V |
| V _{OX} (AC) | AC differential cross point voltage | | 0.68 | | 0.9 | V |

Table 4–36. 1.8-V HSTL Class I Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|----------------------|-----------------------------|-----------------------------|-------------------------|---------|------------------------|------|
| V _{CCIO} | Output supply voltage | | 1.71 | 1.80 | 1.89 | V |
| V _{REF} | Input reference voltage | | 0.85 | 0.90 | 0.95 | V |
| V _{TT} | Termination voltage | | 0.85 | 0.90 | 0.95 | V |
| V _{IH} (DC) | DC high-level input voltage | | V _{REF} + 0.1 | | | V |
| V _{IL} (DC) | DC low-level input voltage | | –0.3 | | V _{REF} – 0.1 | V |
| V _{IH} (AC) | AC high-level input voltage | | V _{REF} + 0.2 | | | V |
| V _{IL} (AC) | AC low-level input voltage | | | | V _{REF} – 0.2 | V |
| V _{OH} | High-level output voltage | I _{OH} = 8 mA (1) | V _{CCIO} – 0.4 | | | V |
| V _{OL} | Low-level output voltage | I _{OH} = –8 mA (1) | | | 0.4 | V |

Note to Table 4–36:

- (1) This specification is supported across all the programmable drive settings available for this I/O standard, as shown in the *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–37. 1.8-V HSTL Class II Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|---------------|-----------------------------|-------------------------------|------------------|---------|-----------------|------|
| V_{CCIO} | Output supply voltage | | 1.71 | 1.80 | 1.89 | V |
| V_{REF} | Input reference voltage | | 0.85 | 0.90 | 0.95 | V |
| V_{TT} | Termination voltage | | 0.85 | 0.90 | 0.95 | V |
| V_{IH} (DC) | DC high-level input voltage | | $V_{REF} + 0.1$ | | | V |
| V_{IL} (DC) | DC low-level input voltage | | -0.3 | | $V_{REF} - 0.1$ | V |
| V_{IH} (AC) | AC high-level input voltage | | $V_{REF} + 0.2$ | | | V |
| V_{IL} (AC) | AC low-level input voltage | | | | $V_{REF} - 0.2$ | V |
| V_{OH} | High-level output voltage | $I_{OH} = 16 \text{ mA}$ (1) | $V_{CCIO} - 0.4$ | | | V |
| V_{OL} | Low-level output voltage | $I_{OH} = -16 \text{ mA}$ (1) | | | 0.4 | V |

Note to Table 4–37:

- (1) This specification is supported across all the programmable drive settings available for this I/O standard, as shown in the *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*.

Table 4–38. 1.8-V HSTL Class I & II Differential Specifications

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|----------------|-------------------------------------|------------|---------|---------|---------|------|
| V_{CCIO} | I/O supply voltage | | 1.71 | 1.80 | 1.89 | V |
| V_{DIF} (DC) | DC input differential voltage | | 0.2 | | | V |
| V_{CM} (DC) | DC common mode input voltage | | 0.78 | | 1.12 | V |
| V_{DIF} (AC) | AC differential input voltage | | 0.4 | | | V |
| V_{OX} (AC) | AC differential cross point voltage | | 0.68 | | 0.9 | V |

Bus Hold Specifications

Table 4–39 shows the Arria GX device family bus hold specifications.

Table 4–39. Bus Hold Parameters

| Parameter | Conditions | V_{CCIO} Level | | | | | | | | | | Unit |
|-------------------------|----------------------------------|------------------|------|-------|------|-------|------|-------|------|-------|------|---------------|
| | | 1.2 V | | 1.5 V | | 1.8 V | | 2.5 V | | 3.3 V | | |
| | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| Low sustaining current | $V_{IN} > V_{IL}$ (maximum) | 22.5 | | 25 | | 30 | | 50 | | 70 | | μA |
| High sustaining current | $V_{IN} < V_{IH}$ (minimum) | -22.5 | | -25 | | -30 | | -50 | | -70 | | μA |
| Low overdrive current | $0\text{ V} < V_{IN} < V_{CCIO}$ | | 120 | | 160 | | 200 | | 300 | | 500 | μA |
| High overdrive current | $0\text{ V} < V_{IN} < V_{CCIO}$ | | -120 | | -160 | | -200 | | -300 | | -500 | μA |
| Bus-hold trip point | | 0.45 | 0.95 | 0.5 | 1.0 | 0.68 | 1.07 | 0.7 | 1.7 | 0.8 | 2.0 | V |

On-Chip Termination Specifications

Tables 4–40 and 4–41 define the specification for internal termination resistance tolerance when using series or differential on-chip termination.

Table 4–40. Series On-Chip Termination Specification for Top and Bottom I/O Banks (Part 1 of 2)

| Symbol | Description | Conditions | Resistance Tolerance | | |
|-----------------------------------|--|------------------------------|----------------------|----------------|------|
| | | | Commercial Max | Industrial Max | Unit |
| $25\text{-}\Omega R_S$ 3.3/2.5 | Internal series termination without calibration (25- Ω setting) | $V_{CCIO} = 3.3/2.5\text{V}$ | ± 30 | ± 30 | % |
| $50\text{-}\Omega R_S$ 3.3/2.5 | Internal series termination without calibration (50- Ω setting) | $V_{CCIO} = 3.3/2.5\text{V}$ | ± 30 | ± 30 | % |
| $25\text{-}\Omega R_S$ 1.8 | Internal series termination without calibration (25- Ω setting) | $V_{CCIO} = 1.8\text{V}$ | ± 30 | ± 30 | % |
| $50\text{-}\Omega R_S$ 1.8 | Internal series termination without calibration (50- Ω setting) | $V_{CCIO} = 1.8\text{V}$ | ± 30 | ± 30 | % |

Table 4–40. Series On-Chip Termination Specification for Top and Bottom I/O Banks (Part 2 of 2)

| Symbol | Description | Conditions | Resistance Tolerance | | |
|----------------------------|--|--------------------------|----------------------|----------------|------|
| | | | Commercial Max | Industrial Max | Unit |
| 50-Ω R _S 1.5 | Internal series termination without calibration (50-Ω setting) | V _{CCIO} = 1.5V | ±36 | ±36 | % |
| 50-Ω R _S 1.2 | Internal series termination without calibration (50-Ω setting) | V _{CCIO} = 1.2V | ±50 | ±50 | % |

Table 4–41. Series On-Chip Termination Specification for Left I/O Banks

| Symbol | Description | Conditions | Resistance Tolerance | | |
|------------------------------------|--|----------------------------------|----------------------|----------------|------|
| | | | Commercial Max | Industrial Max | Unit |
| 25-Ω R _S 3.3/2.5 | Internal series termination without calibration (25-Ω setting) | V _{CCIO} = 3.3/2.5V | ±30 | ±30 | % |
| 50-Ω R _S 3.3/2.5/1.8 | Internal series termination without calibration (50-Ω setting) | V _{CCIO} = 3.3/2.5/1.8V | ±30 | ±30 | % |
| 50-Ω R _S 1.5 | Internal series termination without calibration (50-Ω setting) | V _{CCIO} = 1.5V | ±36 | ±36 | % |
| R _D | Internal differential termination for LVDS (100-Ω setting) | V _{CCIO} = 3.3 V | ±20 | ±25 | % |

Pin Capacitance

Table 4–42 shows the Arria GX device family pin capacitance.

Table 4–42. Arria GX Device Capacitance Note (1) (Part 1 of 2)

| Symbol | Parameter | Typical | Unit |
|--------------------|--|---------|------|
| C _{IOTB} | Input capacitance on I/O pins in I/O banks 3, 4, 7, and 8. | 5.0 | pF |
| C _{IOL} | Input capacitance on I/O pins in I/O banks 1 and 2, including high-speed differential receiver and transmitter pins. | 6.1 | pF |
| C _{CLKTB} | Input capacitance on top/bottom clock input pins: CLK [4 . . 7] and CLK [12 . . 15]. | 6.0 | pF |
| C _{CLKL} | Input capacitance on left clock inputs: CLK0 and CLK2. | 6.1 | pF |
| C _{CLKL+} | Input capacitance on left clock inputs: CLK1 and CLK3. | 3.3 | pF |

Table 4–42. Arria GX Device Capacitance Note (1) (Part 2 of 2)

| Symbol | Parameter | Typical | Unit |
|--------------------|--|---------|------|
| C _{OUTFB} | Input capacitance on dual-purpose clock output/feedback pins in PLL banks 11 and 12. | 6.7 | pF |

Note to Table 4–42:

- (1) Capacitance is sample-tested only. Capacitance is measured using time-domain reflections (TDR). Measurement accuracy is within ± 0.5 pF.

Power Consumption

Altera offers two ways to calculate power for a design: the Excel-based PowerPlay early power estimator power calculator and the Quartus II PowerPlay power analyzer feature.

The interactive Excel-based PowerPlay Early Power Estimator is typically used prior to designing the FPGA in order to get an estimate of device power. The Quartus II PowerPlay Power Analyzer provides better quality estimates based on the specifics of the design after place-and-route is complete. The power analyzer can apply a combination of user-entered, simulation-derived and estimated signal activities which, combined with detailed circuit models, can yield very accurate power estimates.

In both cases, these calculations should only be used as an estimation of power, not as a specification.



For more information on PowerPlay tools, refer to the *PowerPlay Early Power Estimator and PowerPlay Power Analyzer* paper and the *PowerPlay Power Analysis* chapter in volume 3 of the *Quartus II Handbook*.

The PowerPlay early power estimator is available on the Altera web site at www.altera.com. See [Table 4–14 on page 18](#) for typical I_{CC} standby specifications.

I/O Timing Model

The DirectDrive technology and MultiTrack interconnect ensures predictable performance, accurate simulation, and accurate timing analysis across all Arria GX device densities and speed grades. This section describes and specifies the performance of I/Os.

All specifications are representative of worst-case supply voltage and junction temperature conditions.



The timing numbers listed in the tables of this section are extracted from the Quartus II software, version 7.1.

Preliminary, Correlated, and Final Timing

Timing models can have either preliminary, correlated, or final status. The Quartus II software issues an informational message during design compilation if the timing models are preliminary. [Table 4-43](#) shows the status of the Arria GX device timing models.

- **Preliminary** status means the timing model is subject to change. Initially, timing numbers are created using simulation results, process data, and other known parameters. These tests are used to make the preliminary numbers as close to the actual timing parameters as possible.
- **Correlated** numbers are based on actual device operation and testing. These numbers reflect the actual performance of the device under worst-case voltage and junction temperature conditions.
- **Final timing** numbers are based on complete correlation to actual devices and addressing any minor deviations from the correlated timing model. When the timing models are final, all or most of the Arria GX family devices have been completely characterized and no further changes to the timing model are expected.

Table 4-43. Arria GX Device Timing Model Status

| Device | Preliminary | Correlated | Final |
|----------|-------------|------------|-------|
| EP1AGX20 | | | ✓ |
| EP1AGX35 | | | ✓ |
| EP1AGX50 | | | ✓ |
| EP1AGX60 | | | ✓ |
| EP1AGX90 | | | ✓ |

I/O Timing Measurement Methodology

Different I/O standards require different baseline loading techniques for reporting timing delays. Altera characterizes timing delays with the required termination for each I/O standard and with 0 pF (except for PCI and PCI-X which use 10 pF) loading and the timing is specified up to the output pin of the FPGA device. The Quartus II software calculates the I/O timing for each I/O standard with a default baseline loading as specified by the I/O standards.

The following measurements are made during device characterization. Altera measures clock-to-output delays (t_{CO}) at worst-case process, minimum voltage, and maximum temperature (PVT) for default loading conditions shown in [Table 4-44](#).

Use the following equations to calculate clock pin to output pin timing for Arria GX devices:

t_{CO} from clock pin to I/O pin = delay from clock pad to I/O output register + IOE output register clock-to-output delay + delay from output register to output pin + I/O output delay

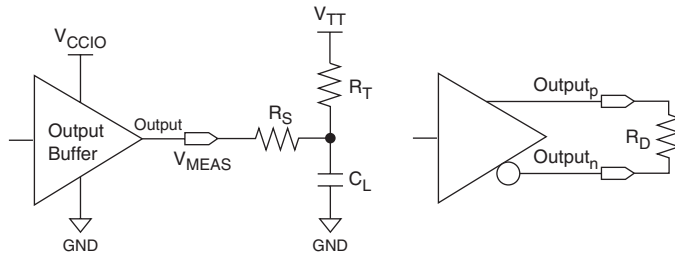
t_{xz}/t_{zx} from clock pin to I/O pin = delay from clock pad to I/O output register + IOE output register clock-to-output delay + delay from output register to output pin + I/O output delay + output enable pin delay

Simulation using IBIS models is required to determine the delays on the PCB traces in addition to the output pin delay timing reported by the Quartus II software and the timing model in the device handbook.

1. Simulate the output driver of choice into the generalized test setup, using values from [Table 4-44](#).
2. Record the time to V_{MEAS} .
3. Simulate the output driver of choice into the actual PCB trace and load, using the appropriate IBIS model or capacitance value to represent the load.
4. Record the time to V_{MEAS} .
5. Compare the results of steps 2 and 4. The increase or decrease in delay should be added to or subtracted from the I/O Standard Output Adder delays to yield the actual worst-case propagation delay (clock-to-output) of the PCB trace.

The Quartus II software reports the timing with the conditions shown in [Table 4-44](#) using the above equation. [Figure 4-7](#) shows the model of the circuit that is represented by the output timing of the Quartus II software.

Figure 4–7. Output Delay Timing Reporting Setup Modeled by Quartus II



Notes to Figure 4–7:

- (1) Output pin timing is reported at the output pin of the FPGA device. Additional delays for loading and board trace delay need to be accounted for with IBIS model simulations.
- (2) V_{CCPD} is 3.085 V unless otherwise specified.
- (3) V_{CCINT} is 1.12 V unless otherwise specified.

Table 4–44. Output Timing Measurement Methodology for Output Pins Notes (1), (2), (3) (Part 1 of 2)

| I/O Standard | Loading and Termination | | | | | | Measurement Point |
|-----------------------------|-------------------------|--------------------|--------------------|----------------|--------------|------------|-------------------|
| | R_S (Ω) | R_D (Ω) | R_T (Ω) | V_{CCIO} (V) | V_{TT} (V) | C_L (pF) | V_{MEAS} (V) |
| LVTTTL (4) | | | | 3.135 | | 0 | 1.5675 |
| LVC MOS (4) | | | | 3.135 | | 0 | 1.5675 |
| 2.5 V (4) | | | | 2.375 | | 0 | 1.1875 |
| 1.8 V (4) | | | | 1.710 | | 0 | 0.855 |
| 1.5 V (4) | | | | 1.425 | | 0 | 0.7125 |
| PCI (5) | | | | 2.970 | | 10 | 1.485 |
| PCI-X (5) | | | | 2.970 | | 10 | 1.485 |
| SSTL-2 Class I | 25 | | 50 | 2.325 | 1.123 | 0 | 1.1625 |
| SSTL-2 Class II | 25 | | 25 | 2.325 | 1.123 | 0 | 1.1625 |
| SSTL-18 Class I | 25 | | 50 | 1.660 | 0.790 | 0 | 0.83 |
| SSTL-18 Class II | 25 | | 25 | 1.660 | 0.790 | 0 | 0.83 |
| 1.8-V HSTL Class I | | | 50 | 1.660 | 0.790 | 0 | 0.83 |
| 1.8-V HSTL Class II | | | 25 | 1.660 | 0.790 | 0 | 0.83 |
| 1.5-V HSTL Class I | | | 50 | 1.375 | 0.648 | 0 | 0.6875 |
| 1.5-V HSTL Class II | | | 25 | 1.375 | 0.648 | 0 | 0.6875 |
| 1.2-V HSTL with OCT | | | | 1.140 | | 0 | 0.570 |
| Differential SSTL-2 Class I | 25 | | 50 | 2.325 | 1.123 | 0 | 1.1625 |

Table 4–44. Output Timing Measurement Methodology for Output Pins Notes (1), (2), (3) (Part 2 of 2)

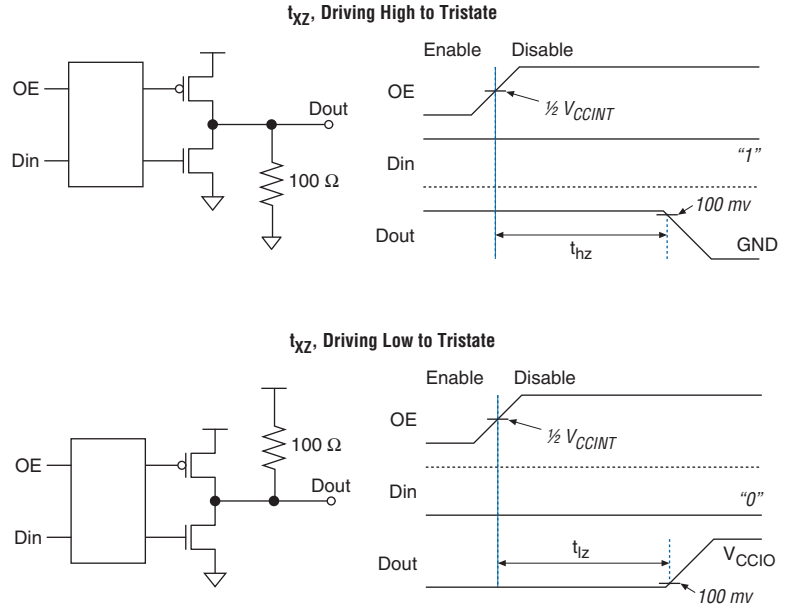
| I/O Standard | Loading and Termination | | | | | | Measurement Point |
|----------------------------------|-------------------------|--------------------|--------------------|----------------|--------------|------------|-------------------|
| | R_S (Ω) | R_D (Ω) | R_T (Ω) | V_{CCIO} (V) | V_{TT} (V) | C_L (pF) | V_{MEAS} (V) |
| Differential SSTL-2 Class II | 25 | | 25 | 2.325 | 1.123 | 0 | 1.1625 |
| Differential SSTL-18 Class I | 50 | | 50 | 1.660 | 0.790 | 0 | 0.83 |
| Differential SSTL-18 Class II | 25 | | 25 | 1.660 | 0.790 | 0 | 0.83 |
| 1.5-V differential HSTL Class I | | | 50 | 1.375 | 0.648 | 0 | 0.6875 |
| 1.5-V differential HSTL Class II | | | 25 | 1.375 | 0.648 | 0 | 0.6875 |
| 1.8-V differential HSTL Class I | | | 50 | 1.660 | 0.790 | 0 | 0.83 |
| 1.8-V differential HSTL Class II | | | 25 | 1.660 | 0.790 | 0 | 0.83 |
| LVDS | | 100 | | 2.325 | | 0 | 1.1625 |
| LVPECL | | 100 | | 3.135 | | 0 | 1.5675 |

Notes to Table 4–44:

- (1) Input measurement point at internal node is $0.5 V_{CCINT}$.
- (2) Output measuring point for V_{MEAS} at buffer output is $0.5 V_{CCIO}$.
- (3) Input stimulus edge rate is 0 to V_{CC} in 0.2 ns (internal signal) from the driver preceding the I/O buffer.
- (4) Less than 50-mV ripple on V_{CCIO} and V_{CCPD} , $V_{CCINT} = 1.15$ V with less than 30-mV ripple.
- (5) $V_{CCPD} = 2.97$ V, less than 50-mV ripple on V_{CCIO} and V_{CCPD} , $V_{CCINT} = 1.15$ V.

Figures 4–8 and 4–9 show the measurement setup for output disable and output enable timing.

Figure 4–8. Measurement Setup for t_{xz} Note (1)



Note to Figure 4–8:

(1) V_{CCINT} is 1.12 V for this measurement.

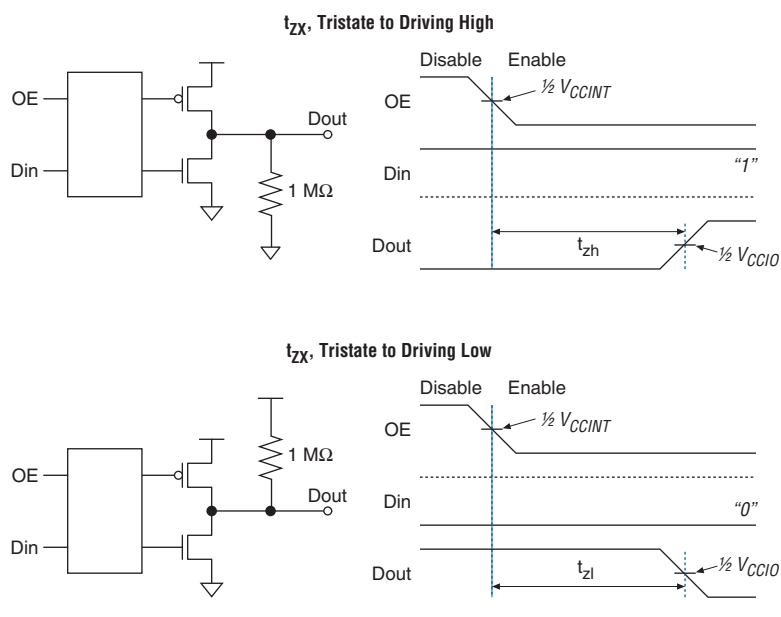
Figure 4–9. Measurement Setup for t_{zx} 

Table 4–45 specifies the input timing measurement setup.

| I/O Standard | Measurement Conditions | | | Measurement Point |
|--------------------|------------------------|---------------|----------------|-------------------|
| | V_{CCIO} (V) | V_{REF} (V) | Edge Rate (ns) | VMEAS (V) |
| LVTTTL (5) | 3.135 | | 3.135 | 1.5675 |
| LVC MOS (5) | 3.135 | | 3.135 | 1.5675 |
| 2.5 V (5) | 2.375 | | 2.375 | 1.1875 |
| 1.8 V (5) | 1.710 | | 1.710 | 0.855 |
| 1.5 V (5) | 1.425 | | 1.425 | 0.7125 |
| PCI (6) | 2.970 | | 2.970 | 1.485 |
| PCI-X (6) | 2.970 | | 2.970 | 1.485 |
| SSTL-2 Class I | 2.325 | 1.163 | 2.325 | 1.1625 |
| SSTL-2 Class II | 2.325 | 1.163 | 2.325 | 1.1625 |
| SSTL-18 Class I | 1.660 | 0.830 | 1.660 | 0.83 |
| SSTL-18 Class II | 1.660 | 0.830 | 1.660 | 0.83 |
| 1.8-V HSTL Class I | 1.660 | 0.830 | 1.660 | 0.83 |

Table 4–45. Timing Measurement Methodology for Input Pins Notes (1), (2), (3), (4) (Part 2 of 2)

| I/O Standard | Measurement Conditions | | | Measurement Point |
|----------------------------------|------------------------|----------------------|----------------|-------------------|
| | V _{CCIO} (V) | V _{REF} (V) | Edge Rate (ns) | VMEAS (V) |
| 1.8-V HSTL Class II | 1.660 | 0.830 | 1.660 | 0.83 |
| 1.5-V HSTL Class I | 1.375 | 0.688 | 1.375 | 0.6875 |
| 1.5-V HSTL Class II | 1.375 | 0.688 | 1.375 | 0.6875 |
| 1.2-V HSTL with OCT | 1.140 | 0.570 | 1.140 | 0.570 |
| Differential SSTL-2 Class I | 2.325 | 1.163 | 2.325 | 1.1625 |
| Differential SSTL-2 Class II | 2.325 | 1.163 | 2.325 | 1.1625 |
| Differential SSTL-18 Class I | 1.660 | 0.830 | 1.660 | 0.83 |
| Differential SSTL-18 Class II | 1.660 | 0.830 | 1.660 | 0.83 |
| 1.5-V differential HSTL Class I | 1.375 | 0.688 | 1.375 | 0.6875 |
| 1.5-V differential HSTL Class II | 1.375 | 0.688 | 1.375 | 0.6875 |
| 1.8-V differential HSTL Class I | 1.660 | 0.830 | 1.660 | 0.83 |
| 1.8-V differential HSTL Class II | 1.660 | 0.830 | 1.660 | 0.83 |
| LVDS | 2.325 | | 0.100 | 1.1625 |
| LVPECL | 3.135 | | 0.100 | 1.5675 |

Notes to Table 4–45:

- (1) Input buffer sees no load at buffer input.
- (2) Input measuring point at buffer input is 0.5 V_{CCIO}.
- (3) Output measuring point is 0.5 V_{CC} at internal node.
- (4) Input edge rate is 1 V/ns.
- (5) Less than 50-mV ripple on V_{CCIO} and V_{CCPD}, V_{CCINT} = 1.15 V with less than 30-mV ripple.
- (6) V_{CCPD} = 2.97 V, less than 50-mV ripple on V_{CCIO} and V_{CCPD}, V_{CCINT} = 1.15 V.

Clock Network Skew Adders

The Quartus II software models skew within dedicated clock networks such as global and regional clocks. Therefore, the intra-clock network skew adder is not specified. Table 4–46 specifies the clock skew between any two clock networks driving registers in the I/O element (IOE).

Table 4–46. Clock Network Specifications (Part 1 of 2)

| Name | Description | Min | Typ | Max | Unit |
|-------------------------------------|----------------------------------|-----|-----|-------|------|
| Clock skew adder EP1AGX20/35 (1) | Inter-clock network, same side | | | ± 50 | ps |
| | Inter-clock network, entire chip | | | ± 100 | ps |
| Clock skew adder EP1AGX50/60 (1) | Inter-clock network, same side | | | ± 50 | ps |
| | Inter-clock network, entire chip | | | ± 100 | ps |

Table 4–46. Clock Network Specifications (Part 2 of 2)

| Name | Description | Min | Typ | Max | Unit |
|----------------------------------|----------------------------------|-----|-----|-------|------|
| Clock skew adder EP1AGX90 (1) | Inter-clock network, same side | | | ± 55 | ps |
| | Inter-clock network, entire chip | | | ± 110 | ps |

Notes to Table 4–46:

- (1) This is in addition to intra-clock network skew, which is modeled in the Quartus II software.

Default Capacitive Loading of Different I/O Standards

See Table 4–47 for default capacitive loading of different I/O standards.

Table 4–47. Default Loading of Different I/O Standards for Arria GX Devices (Part 1 of 2)

| I/O Standard | Capacitive Load | Unit |
|----------------------------------|-----------------|------|
| LVTTTL | 0 | pF |
| LVC MOS | 0 | pF |
| 2.5 V | 0 | pF |
| 1.8 V | 0 | pF |
| 1.5 V | 0 | pF |
| PCI | 10 | pF |
| PCI-X | 10 | pF |
| SSTL-2 Class I | 0 | pF |
| SSTL-2 Class II | 0 | pF |
| SSTL-18 Class I | 0 | pF |
| SSTL-18 Class II | 0 | pF |
| 1.5-V HSTL Class I | 0 | pF |
| 1.5-V HSTL Class II | 0 | pF |
| 1.8-V HSTL Class I | 0 | pF |
| 1.8-V HSTL Class II | 0 | pF |
| Differential SSTL-2 Class I | 0 | pF |
| Differential SSTL-2 Class II | 0 | pF |
| Differential SSTL-18 Class I | 0 | pF |
| Differential SSTL-18 Class II | 0 | pF |
| 1.5-V differential HSTL Class I | 0 | pF |
| 1.5-V differential HSTL Class II | 0 | pF |
| 1.8-V differential HSTL Class I | 0 | pF |

Table 4–47. Default Loading of Different I/O Standards for Arria GX Devices (Part 2 of 2)

| I/O Standard | Capacitive Load | Unit |
|----------------------------------|-----------------|------|
| 1.8-V differential HSTL Class II | 0 | pF |
| LVDS | 0 | pF |

Typical Design Performance

The following section describes the typical design performance for the Arria GX device family.

User I/O Pin Timing

Tables 4–48 to 4–77 show user I/O pin timing for Arria GX devices. I/O buffer t_{SU} , t_H , and t_{CO} are reported for the cases when I/O clock is driven by a non-PLL global clock (GCLK) and a PLL driven global clock (GCLK-PLL). For t_{SU} , t_H , and t_{CO} using regional clock, add the value from the adder tables listed for each device to the GCLK/GCLK-PLL values for the device.

EP1AGX20 I/O Timing Parameters

Tables 4–48 through 4–51 show the maximum I/O timing parameters for EP1AGX20 devices for I/O standards which support general purpose I/O pins.

Table 4–48 describes the row pin delay adders when using the regional clock in Arria GX devices.

Table 4–48. EP1AGX20 Row Pin Delay Adders for Regional Clock

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.117 | 0.117 | 0.273 | ns |
| RCLK PLL input adder | 0.011 | 0.011 | 0.019 | ns |
| RCLK output adder | -0.117 | -0.117 | -0.273 | ns |
| RCLK PLL output adder | -0.011 | -0.011 | -0.019 | ns |

Table 4–49 describes I/O timing specifications.

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 3.3-V LVTTL | GCLK | t_{SU} | 1.251 | 1.251 | 2.915 | ns |
| | | t_H | -1.146 | -1.146 | -2.638 | ns |
| | GCLK PLL | t_{SU} | 2.693 | 2.693 | 6.021 | ns |
| | | t_H | -2.588 | -2.588 | -5.744 | ns |
| 3.3-V LVCMOS | GCLK | t_{SU} | 1.251 | 1.251 | 2.915 | ns |
| | | t_H | -1.146 | -1.146 | -2.638 | ns |
| | GCLK PLL | t_{SU} | 2.693 | 2.693 | 6.021 | ns |
| | | t_H | -2.588 | -2.588 | -5.744 | ns |
| 2.5 V | GCLK | t_{SU} | 1.261 | 1.261 | 2.897 | ns |
| | | t_H | -1.156 | -1.156 | -2.620 | ns |
| | GCLK PLL | t_{SU} | 2.703 | 2.703 | 6.003 | ns |
| | | t_H | -2.598 | -2.598 | -5.726 | ns |
| 1.8 V | GCLK | t_{SU} | 1.327 | 1.327 | 3.107 | ns |
| | | t_H | -1.222 | -1.222 | -2.830 | ns |
| | GCLK PLL | t_{SU} | 2.769 | 2.769 | 6.213 | ns |
| | | t_H | -2.664 | -2.664 | -5.936 | ns |
| 1.5 V | GCLK | t_{SU} | 1.330 | 1.330 | 3.200 | ns |
| | | t_H | -1.225 | -1.225 | -2.923 | ns |
| | GCLK PLL | t_{SU} | 2.772 | 2.772 | 6.306 | ns |
| | | t_H | -2.667 | -2.667 | -6.029 | ns |
| SSTL-2 CLASS I | GCLK | t_{SU} | 1.075 | 1.075 | 2.372 | ns |
| | | t_H | -0.970 | -0.970 | -2.095 | ns |
| | GCLK PLL | t_{SU} | 2.517 | 2.517 | 5.480 | ns |
| | | t_H | -2.412 | -2.412 | -5.203 | ns |
| SSTL-2 CLASS II | GCLK | t_{SU} | 1.075 | 1.075 | 2.372 | ns |
| | | t_H | -0.970 | -0.970 | -2.095 | ns |
| | GCLK PLL | t_{SU} | 2.517 | 2.517 | 5.480 | ns |
| | | t_H | -2.412 | -2.412 | -5.203 | ns |

Table 4–49. EP1AGX20 Column Pins Input Timing Parameters (Part 2 of 3)

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | GCLK | t_{SU} | 1.113 | 1.113 | 2.479 | ns |
| | | t_H | -1.008 | -1.008 | -2.202 | ns |
| | GCLK PLL | t_{SU} | 2.555 | 2.555 | 5.585 | ns |
| | | t_H | -2.450 | -2.450 | -5.308 | ns |
| SSTL-18 CLASS II | GCLK | t_{SU} | 1.114 | 1.114 | 2.479 | ns |
| | | t_H | -1.009 | -1.009 | -2.202 | ns |
| | GCLK PLL | t_{SU} | 2.556 | 2.556 | 5.587 | ns |
| | | t_H | -2.451 | -2.451 | -5.310 | ns |
| 1.8-V HSTL CLASS I | GCLK | t_{SU} | 1.113 | 1.113 | 2.479 | ns |
| | | t_H | -1.008 | -1.008 | -2.202 | ns |
| | GCLK PLL | t_{SU} | 2.555 | 2.555 | 5.585 | ns |
| | | t_H | -2.450 | -2.450 | -5.308 | ns |
| 1.8-V HSTL CLASS II | GCLK | t_{SU} | 1.114 | 1.114 | 2.479 | ns |
| | | t_H | -1.009 | -1.009 | -2.202 | ns |
| | GCLK PLL | t_{SU} | 2.556 | 2.556 | 5.587 | ns |
| | | t_H | -2.451 | -2.451 | -5.310 | ns |
| 1.5-V HSTL CLASS I | GCLK | t_{SU} | 1.131 | 1.131 | 2.607 | ns |
| | | t_H | -1.026 | -1.026 | -2.330 | ns |
| | GCLK PLL | t_{SU} | 2.573 | 2.573 | 5.713 | ns |
| | | t_H | -2.468 | -2.468 | -5.436 | ns |
| 1.5-V HSTL CLASS II | GCLK | t_{SU} | 1.132 | 1.132 | 2.607 | ns |
| | | t_H | -1.027 | -1.027 | -2.330 | ns |
| | GCLK PLL | t_{SU} | 2.574 | 2.574 | 5.715 | ns |
| | | t_H | -2.469 | -2.469 | -5.438 | ns |
| 3.3-V PCI | GCLK | t_{SU} | 1.256 | 1.256 | 2.903 | ns |
| | | t_H | -1.151 | -1.151 | -2.626 | ns |
| | GCLK PLL | t_{SU} | 2.698 | 2.698 | 6.009 | ns |
| | | t_H | -2.593 | -2.593 | -5.732 | ns |

Table 4–49. EP1AGX20 Column Pins Input Timing Parameters (Part 3 of 3)

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 3.3-V PCI-X | GCLK | t_{SU} | 1.256 | 1.256 | 2.903 | ns |
| | | t_H | -1.151 | -1.151 | -2.626 | ns |
| | GCLK PLL | t_{SU} | 2.698 | 2.698 | 6.009 | ns |
| | | t_H | -2.593 | -2.593 | -5.732 | ns |
| LVDS | GCLK | t_{SU} | 1.106 | 1.106 | 2.489 | ns |
| | | t_H | -1.001 | -1.001 | -2.212 | ns |
| | GCLK PLL | t_{SU} | 2.530 | 2.530 | 5.564 | ns |
| | | t_H | -2.425 | -2.425 | -5.287 | ns |

Table 4–50 describes I/O timing specifications.

Table 4–50. EP1AGX20 Row Pins output Timing Parameters (Part 1 of 3)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 4 mA | GCLK | t_{CO} | 2.904 | 2.904 | 6.699 | ns |
| | | GCLK PLL | t_{CO} | 1.485 | 1.485 | 3.627 | ns |
| 3.3-V LVTTTL | 8 mA | GCLK | t_{CO} | 2.776 | 2.776 | 6.059 | ns |
| | | GCLK PLL | t_{CO} | 1.357 | 1.357 | 2.987 | ns |
| 3.3-V LVTTTL | 12 mA | GCLK | t_{CO} | 2.720 | 2.720 | 6.022 | ns |
| | | GCLK PLL | t_{CO} | 1.301 | 1.301 | 2.950 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 2.776 | 2.776 | 6.059 | ns |
| | | GCLK PLL | t_{CO} | 1.357 | 1.357 | 2.987 | ns |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.670 | 2.670 | 5.753 | ns |
| | | GCLK PLL | t_{CO} | 1.251 | 1.251 | 2.681 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 2.759 | 2.759 | 6.033 | ns |
| | | GCLK PLL | t_{CO} | 1.340 | 1.340 | 2.961 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.656 | 2.656 | 5.775 | ns |
| | | GCLK PLL | t_{CO} | 1.237 | 1.237 | 2.703 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.637 | 2.637 | 5.661 | ns |
| | | GCLK PLL | t_{CO} | 1.218 | 1.218 | 2.589 | ns |

Table 4–50. EP1AGX20 Row Pins output Timing Parameters (Part 2 of 3)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8 V | 2 mA | GCLK | t_{CO} | 2.829 | 2.829 | 7.052 | ns |
| | | GCLK PLL | t_{CO} | 1.410 | 1.410 | 3.980 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 2.818 | 2.818 | 6.273 | ns |
| | | GCLK PLL | t_{CO} | 1.399 | 1.399 | 3.201 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.707 | 2.707 | 5.972 | ns |
| | | GCLK PLL | t_{CO} | 1.288 | 1.288 | 2.900 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.676 | 2.676 | 5.858 | ns |
| | | GCLK PLL | t_{CO} | 1.257 | 1.257 | 2.786 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 2.789 | 2.789 | 6.551 | ns |
| | | GCLK PLL | t_{CO} | 1.370 | 1.370 | 3.479 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.682 | 2.682 | 5.950 | ns |
| | | GCLK PLL | t_{CO} | 1.263 | 1.263 | 2.878 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.626 | 2.626 | 5.614 | ns |
| | | GCLK PLL | t_{CO} | 1.207 | 1.207 | 2.542 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.602 | 2.602 | 5.538 | ns |
| | | GCLK PLL | t_{CO} | 1.183 | 1.183 | 2.466 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.568 | 2.568 | 5.407 | ns |
| | | GCLK PLL | t_{CO} | 1.149 | 1.149 | 2.335 | ns |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.614 | 2.614 | 5.556 | ns |
| | | GCLK PLL | t_{CO} | 1.195 | 1.195 | 2.484 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.618 | 2.618 | 5.485 | ns |
| | | GCLK PLL | t_{CO} | 1.199 | 1.199 | 2.413 | ns |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.594 | 2.594 | 5.468 | ns |
| | | GCLK PLL | t_{CO} | 1.175 | 1.175 | 2.396 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.597 | 2.597 | 5.447 | ns |
| | | GCLK PLL | t_{CO} | 1.178 | 1.178 | 2.375 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.595 | 2.595 | 5.466 | ns |
| | | GCLK PLL | t_{CO} | 1.176 | 1.176 | 2.394 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.598 | 2.598 | 5.430 | ns |
| | | GCLK PLL | t_{CO} | 1.179 | 1.179 | 2.358 | ns |

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.580 | 2.580 | 5.426 | ns |
| | | GCLK PLL | t_{CO} | 1.161 | 1.161 | 2.354 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.584 | 2.584 | 5.415 | ns |
| | | GCLK PLL | t_{CO} | 1.165 | 1.165 | 2.343 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.575 | 2.575 | 5.414 | ns |
| | | GCLK PLL | t_{CO} | 1.156 | 1.156 | 2.342 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.594 | 2.594 | 5.443 | ns |
| | | GCLK PLL | t_{CO} | 1.175 | 1.175 | 2.371 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.597 | 2.597 | 5.429 | ns |
| | | GCLK PLL | t_{CO} | 1.178 | 1.178 | 2.357 | ns |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.582 | 2.582 | 5.421 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.349 | ns |
| LVDS | - | GCLK | t_{CO} | 2.654 | 2.654 | 5.613 | ns |
| | | GCLK PLL | t_{CO} | 1.226 | 1.226 | 2.530 | ns |

Table 4–51 describes I/O timing specifications.

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTL | 4 mA | GCLK | t_{CO} | 2.909 | 2.909 | 6.541 | ns |
| | | GCLK PLL | t_{CO} | 1.467 | 1.467 | 3.435 | ns |
| 3.3-V LVTTL | 8 mA | GCLK | t_{CO} | 2.764 | 2.764 | 6.169 | ns |
| | | GCLK PLL | t_{CO} | 1.322 | 1.322 | 3.063 | ns |
| 3.3-V LVTTL | 12 mA | GCLK | t_{CO} | 2.697 | 2.697 | 6.169 | ns |
| | | GCLK PLL | t_{CO} | 1.255 | 1.255 | 3.063 | ns |
| 3.3-V LVTTL | 16 mA | GCLK | t_{CO} | 2.671 | 2.671 | 6.000 | ns |
| | | GCLK PLL | t_{CO} | 1.229 | 1.229 | 2.894 | ns |
| 3.3-V LVTTL | 20 mA | GCLK | t_{CO} | 2.649 | 2.649 | 5.875 | ns |
| | | GCLK PLL | t_{CO} | 1.207 | 1.207 | 2.769 | ns |

Table 4–51. EP1AGX20 Column Pins Output Timing Parameters (Part 2 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 24 mA | GCLK | t_{CO} | 2.642 | 2.642 | 5.877 | ns |
| | | GCLK PLL | t_{CO} | 1.200 | 1.200 | 2.771 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 2.764 | 2.764 | 6.169 | ns |
| | | GCLK PLL | t_{CO} | 1.322 | 1.322 | 3.063 | ns |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.672 | 2.672 | 5.874 | ns |
| | | GCLK PLL | t_{CO} | 1.230 | 1.230 | 2.768 | ns |
| 3.3-V LVCMOS | 12 mA | GCLK | t_{CO} | 2.644 | 2.644 | 5.796 | ns |
| | | GCLK PLL | t_{CO} | 1.202 | 1.202 | 2.690 | ns |
| 3.3-V LVCMOS | 16 mA | GCLK | t_{CO} | 2.651 | 2.651 | 5.764 | ns |
| | | GCLK PLL | t_{CO} | 1.209 | 1.209 | 2.658 | ns |
| 3.3-V LVCMOS | 20 mA | GCLK | t_{CO} | 2.638 | 2.638 | 5.746 | ns |
| | | GCLK PLL | t_{CO} | 1.196 | 1.196 | 2.640 | ns |
| 3.3-V LVCMOS | 24 mA | GCLK | t_{CO} | 2.627 | 2.627 | 5.724 | ns |
| | | GCLK PLL | t_{CO} | 1.185 | 1.185 | 2.618 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 2.726 | 2.726 | 6.201 | ns |
| | | GCLK PLL | t_{CO} | 1.284 | 1.284 | 3.095 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.674 | 2.674 | 5.939 | ns |
| | | GCLK PLL | t_{CO} | 1.232 | 1.232 | 2.833 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.653 | 2.653 | 5.822 | ns |
| | | GCLK PLL | t_{CO} | 1.211 | 1.211 | 2.716 | ns |
| 2.5 V | 16 mA | GCLK | t_{CO} | 2.635 | 2.635 | 5.748 | ns |
| | | GCLK PLL | t_{CO} | 1.193 | 1.193 | 2.642 | ns |
| 1.8 V | 2 mA | GCLK | t_{CO} | 2.766 | 2.766 | 7.193 | ns |
| | | GCLK PLL | t_{CO} | 1.324 | 1.324 | 4.087 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 2.771 | 2.771 | 6.419 | ns |
| | | GCLK PLL | t_{CO} | 1.329 | 1.329 | 3.313 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.695 | 2.695 | 6.155 | ns |
| | | GCLK PLL | t_{CO} | 1.253 | 1.253 | 3.049 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.697 | 2.697 | 6.064 | ns |
| | | GCLK PLL | t_{CO} | 1.255 | 1.255 | 2.958 | ns |

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8 V | 10 mA | GCLK | t_{CO} | 2.651 | 2.651 | 5.987 | ns |
| | | GCLK PLL | t_{CO} | 1.209 | 1.209 | 2.881 | ns |
| 1.8 V | 12 mA | GCLK | t_{CO} | 2.652 | 2.652 | 5.930 | ns |
| | | GCLK PLL | t_{CO} | 1.210 | 1.210 | 2.824 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 2.746 | 2.746 | 6.723 | ns |
| | | GCLK PLL | t_{CO} | 1.304 | 1.304 | 3.617 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.682 | 2.682 | 6.154 | ns |
| | | GCLK PLL | t_{CO} | 1.240 | 1.240 | 3.048 | ns |
| 1.5 V | 6 mA | GCLK | t_{CO} | 2.685 | 2.685 | 6.036 | ns |
| | | GCLK PLL | t_{CO} | 1.243 | 1.243 | 2.930 | ns |
| 1.5 V | 8 mA | GCLK | t_{CO} | 2.644 | 2.644 | 5.983 | ns |
| | | GCLK PLL | t_{CO} | 1.202 | 1.202 | 2.877 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.629 | 2.629 | 5.762 | ns |
| | | GCLK PLL | t_{CO} | 1.184 | 1.184 | 2.650 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.612 | 2.612 | 5.712 | ns |
| | | GCLK PLL | t_{CO} | 1.167 | 1.167 | 2.600 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.590 | 2.590 | 5.639 | ns |
| | | GCLK PLL | t_{CO} | 1.145 | 1.145 | 2.527 | ns |
| SSTL-2 CLASS II | 20 mA | GCLK | t_{CO} | 2.591 | 2.591 | 5.626 | ns |
| | | GCLK PLL | t_{CO} | 1.146 | 1.146 | 2.514 | ns |
| SSTL-2 CLASS II | 24 mA | GCLK | t_{CO} | 2.587 | 2.587 | 5.624 | ns |
| | | GCLK PLL | t_{CO} | 1.142 | 1.142 | 2.512 | ns |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.626 | 2.626 | 5.733 | ns |
| | | GCLK PLL | t_{CO} | 1.184 | 1.184 | 2.627 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.630 | 2.630 | 5.694 | ns |
| | | GCLK PLL | t_{CO} | 1.185 | 1.185 | 2.582 | ns |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.609 | 2.609 | 5.675 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.563 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.614 | 2.614 | 5.673 | ns |
| | | GCLK PLL | t_{CO} | 1.169 | 1.169 | 2.561 | ns |

Table 4–51. EP1AGX20 Column Pins Output Timing Parameters (Part 4 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | 12 mA | GCLK | t_{CO} | 2.608 | 2.608 | 5.659 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.547 | ns |
| SSTL-18 CLASS II | 8 mA | GCLK | t_{CO} | 2.597 | 2.597 | 5.625 | ns |
| | | GCLK PLL | t_{CO} | 1.152 | 1.152 | 2.513 | ns |
| SSTL-18 CLASS II | 16 mA | GCLK | t_{CO} | 2.609 | 2.609 | 5.603 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.491 | ns |
| SSTL-18 CLASS II | 18 mA | GCLK | t_{CO} | 2.605 | 2.605 | 5.611 | ns |
| | | GCLK PLL | t_{CO} | 1.160 | 1.160 | 2.499 | ns |
| SSTL-18 CLASS II | 20 mA | GCLK | t_{CO} | 2.605 | 2.605 | 5.609 | ns |
| | | GCLK PLL | t_{CO} | 1.160 | 1.160 | 2.497 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.629 | 2.629 | 5.664 | ns |
| | | GCLK PLL | t_{CO} | 1.187 | 1.187 | 2.558 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.634 | 2.634 | 5.649 | ns |
| | | GCLK PLL | t_{CO} | 1.189 | 1.189 | 2.537 | ns |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.612 | 2.612 | 5.638 | ns |
| | | GCLK PLL | t_{CO} | 1.167 | 1.167 | 2.526 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.616 | 2.616 | 5.644 | ns |
| | | GCLK PLL | t_{CO} | 1.171 | 1.171 | 2.532 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.608 | 2.608 | 5.637 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.525 | ns |
| 1.8-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.591 | 2.591 | 5.401 | ns |
| | | GCLK PLL | t_{CO} | 1.146 | 1.146 | 2.289 | ns |
| 1.8-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.593 | 2.593 | 5.412 | ns |
| | | GCLK PLL | t_{CO} | 1.148 | 1.148 | 2.300 | ns |
| 1.8-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.593 | 2.593 | 5.421 | ns |
| | | GCLK PLL | t_{CO} | 1.148 | 1.148 | 2.309 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.629 | 2.629 | 5.663 | ns |
| | | GCLK PLL | t_{CO} | 1.187 | 1.187 | 2.557 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.633 | 2.633 | 5.641 | ns |
| | | GCLK PLL | t_{CO} | 1.188 | 1.188 | 2.529 | ns |

Table 4–51. EP1AGX20 Column Pins Output Timing Parameters (Part 5 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.615 | 2.615 | 5.643 | ns |
| | | GCLK PLL | t_{CO} | 1.170 | 1.170 | 2.531 | ns |
| 1.5-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.615 | 2.615 | 5.645 | ns |
| | | GCLK PLL | t_{CO} | 1.170 | 1.170 | 2.533 | ns |
| 1.5-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.609 | 2.609 | 5.643 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.531 | ns |
| 1.5-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.596 | 2.596 | 5.455 | ns |
| | | GCLK PLL | t_{CO} | 1.151 | 1.151 | 2.343 | ns |
| 1.5-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.599 | 2.599 | 5.465 | ns |
| | | GCLK PLL | t_{CO} | 1.154 | 1.154 | 2.353 | ns |
| 1.5-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.601 | 2.601 | 5.478 | ns |
| | | GCLK PLL | t_{CO} | 1.156 | 1.156 | 2.366 | ns |
| 3.3-V PCI | - | GCLK | t_{CO} | 2.755 | 2.755 | 5.791 | ns |
| | | GCLK PLL | t_{CO} | 1.313 | 1.313 | 2.685 | ns |
| 3.3-V PCI-X | - | GCLK | t_{CO} | 2.755 | 2.755 | 5.791 | ns |
| | | GCLK PLL | t_{CO} | 1.313 | 1.313 | 2.685 | ns |
| LVDS | - | GCLK | t_{CO} | 3.621 | 3.621 | 6.969 | ns |
| | | GCLK PLL | t_{CO} | 2.190 | 2.190 | 3.880 | ns |

Tables 4–52 through 4–53 shows EP1AGX20 regional clock (RCLK) adder values that should be added to GCLK values. These adder values are used to determine I/O timing when the I/O pin is driven using the regional clock. This applies for all I/O standards supported by Arria GX with general purpose I/O pins.

Table 4–52 describes row pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.117 | 0.117 | 0.273 | ns |
| RCLK PLL input adder | 0.011 | 0.011 | 0.019 | ns |
| RCLK output adder | -0.117 | -0.117 | -0.273 | ns |
| RCLK PLL output adder | -0.011 | -0.011 | -0.019 | ns |

Table 4–53 describes column pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.081 | 0.081 | 0.223 | ns |
| RCLK PLL input adder | -0.012 | -0.012 | -0.008 | ns |
| RCLK output adder | -0.081 | -0.081 | -0.224 | ns |
| RCLK PLL output adder | 1.11 | 1.11 | 2.658 | ns |

EP1AGX35 I/O Timing Parameters

Tables 4–54 through 4–57 show the maximum I/O timing parameters for EP1AGX35 devices for I/O standards which support general purpose I/O pins.

Table 4–54 describes I/O timing specifications.

| Table 4–54. EP1AGX35 Row Pins Input Timing Parameters (Part 1 of 3) | | | | | | |
|--|----------|-----------|------------|------------|----------------|-------|
| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
| | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | GCLK | t_{SU} | 1.561 | 1.561 | 3.556 | ns |
| | | t_H | -1.456 | -1.456 | -3.279 | ns |
| | GCLK PLL | t_{SU} | 2.980 | 2.980 | 6.628 | ns |
| | | t_H | -2.875 | -2.875 | -6.351 | ns |
| 3.3-V LVCMOS | GCLK | t_{SU} | 1.561 | 1.561 | 3.556 | ns |
| | | t_H | -1.456 | -1.456 | -3.279 | ns |
| | GCLK PLL | t_{SU} | 2.980 | 2.980 | 6.628 | ns |
| | | t_H | -2.875 | -2.875 | -6.351 | ns |
| 2.5 V | GCLK | t_{SU} | 1.573 | 1.573 | 3.537 | ns |
| | | t_H | -1.468 | -1.468 | -3.260 | ns |
| | GCLK PLL | t_{SU} | 2.992 | 2.992 | 6.609 | ns |
| | | t_H | -2.887 | -2.887 | -6.332 | ns |
| 1.8 V | GCLK | t_{SU} | 1.639 | 1.639 | 3.744 | ns |
| | | t_H | -1.534 | -1.534 | -3.467 | ns |
| | GCLK PLL | t_{SU} | 3.058 | 3.058 | 6.816 | ns |
| | | t_H | -2.953 | -2.953 | -6.539 | ns |
| 1.5 V | GCLK | t_{SU} | 1.642 | 1.642 | 3.839 | ns |
| | | t_H | -1.537 | -1.537 | -3.562 | ns |
| | GCLK PLL | t_{SU} | 3.061 | 3.061 | 6.911 | ns |
| | | t_H | -2.956 | -2.956 | -6.634 | ns |
| SSTL-2 CLASS I | GCLK | t_{SU} | 1.385 | 1.385 | 3.009 | ns |
| | | t_H | -1.280 | -1.280 | -2.732 | ns |
| | GCLK PLL | t_{SU} | 2.804 | 2.804 | 6.081 | ns |
| | | t_H | -2.699 | -2.699 | -5.804 | ns |

Table 4–54. EP1AGX35 Row Pins Input Timing Parameters (Part 2 of 3)

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|---------------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| SSTL-2 CLASS II | GCLK | t_{SU} | 1.385 | 1.385 | 3.009 | ns |
| | | t_H | -1.280 | -1.280 | -2.732 | ns |
| | GCLK PLL | t_{SU} | 2.804 | 2.804 | 6.081 | ns |
| | | t_H | -2.699 | -2.699 | -5.804 | ns |
| SSTL-18 CLASS I | GCLK | t_{SU} | 1.417 | 1.417 | 3.118 | ns |
| | | t_H | -1.312 | -1.312 | -2.841 | ns |
| | GCLK PLL | t_{SU} | 2.836 | 2.836 | 6.190 | ns |
| | | t_H | -2.731 | -2.731 | -5.913 | ns |
| SSTL-18 CLASS II | GCLK | t_{SU} | 1.417 | 1.417 | 3.118 | ns |
| | | t_H | -1.312 | -1.312 | -2.841 | ns |
| | GCLK PLL | t_{SU} | 2.836 | 2.836 | 6.190 | ns |
| | | t_H | -2.731 | -2.731 | -5.913 | ns |
| 1.8-V HSTL CLASS I | GCLK | t_{SU} | 1.417 | 1.417 | 3.118 | ns |
| | | t_H | -1.312 | -1.312 | -2.841 | ns |
| | GCLK PLL | t_{SU} | 2.836 | 2.836 | 6.190 | ns |
| | | t_H | -2.731 | -2.731 | -5.913 | ns |
| 1.8-V HSTL CLASS II | GCLK | t_{SU} | 1.417 | 1.417 | 3.118 | ns |
| | | t_H | -1.312 | -1.312 | -2.841 | ns |
| | GCLK PLL | t_{SU} | 2.836 | 2.836 | 6.190 | ns |
| | | t_H | -2.731 | -2.731 | -5.913 | ns |
| 1.5-V HSTL CLASS I | GCLK | t_{SU} | 1.443 | 1.443 | 3.246 | ns |
| | | t_H | -1.338 | -1.338 | -2.969 | ns |
| | GCLK PLL | t_{SU} | 2.862 | 2.862 | 6.318 | ns |
| | | t_H | -2.757 | -2.757 | -6.041 | ns |
| 1.5-V HSTL CLASS II | GCLK | t_{SU} | 1.443 | 1.443 | 3.246 | ns |
| | | t_H | -1.338 | -1.338 | -2.969 | ns |
| | GCLK PLL | t_{SU} | 2.862 | 2.862 | 6.318 | ns |
| | | t_H | -2.757 | -2.757 | -6.041 | ns |

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| LVDS | GCLK | t_{SU} | 1.341 | 1.341 | 3.088 | ns |
| | | t_H | -1.236 | -1.236 | -2.811 | ns |
| | GCLK PLL | t_{SU} | 2.769 | 2.769 | 6.171 | ns |
| | | t_H | -2.664 | -2.664 | -5.894 | ns |

Table 4–55 describes I/O timing specifications.

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | GCLK | t_{SU} | 1.251 | 1.251 | 2.915 | ns |
| | | t_H | -1.146 | -1.146 | -2.638 | ns |
| | GCLK PLL | t_{SU} | 2.693 | 2.693 | 6.021 | ns |
| | | t_H | -2.588 | -2.588 | -5.744 | ns |
| 3.3-V LVCMOS | GCLK | t_{SU} | 1.251 | 1.251 | 2.915 | ns |
| | | t_H | -1.146 | -1.146 | -2.638 | ns |
| | GCLK PLL | t_{SU} | 2.693 | 2.693 | 6.021 | ns |
| | | t_H | -2.588 | -2.588 | -5.744 | ns |
| 2.5 V | GCLK | t_{SU} | 1.261 | 1.261 | 2.897 | ns |
| | | t_H | -1.156 | -1.156 | -2.620 | ns |
| | GCLK PLL | t_{SU} | 2.703 | 2.703 | 6.003 | ns |
| | | t_H | -2.598 | -2.598 | -5.726 | ns |
| 1.8 V | GCLK | t_{SU} | 1.327 | 1.327 | 3.107 | ns |
| | | t_H | -1.222 | -1.222 | -2.830 | ns |
| | GCLK PLL | t_{SU} | 2.769 | 2.769 | 6.213 | ns |
| | | t_H | -2.664 | -2.664 | -5.936 | ns |
| 1.5 V | GCLK | t_{SU} | 1.330 | 1.330 | 3.200 | ns |
| | | t_H | -1.225 | -1.225 | -2.923 | ns |
| | GCLK PLL | t_{SU} | 2.772 | 2.772 | 6.306 | ns |
| | | t_H | -2.667 | -2.667 | -6.029 | ns |

Table 4–55. EP1AGX35 Column Pins Input Timing Parameters (Part 2 of 3)

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| SSTL-2 CLASS I | GCLK | t_{SU} | 1.075 | 1.075 | 2.372 | ns |
| | | t_H | -0.970 | -0.970 | -2.095 | ns |
| | GCLK PLL | t_{SU} | 2.517 | 2.517 | 5.480 | ns |
| | | t_H | -2.412 | -2.412 | -5.203 | ns |
| SSTL-2 CLASS II | GCLK | t_{SU} | 1.075 | 1.075 | 2.372 | ns |
| | | t_H | -0.970 | -0.970 | -2.095 | ns |
| | GCLK PLL | t_{SU} | 2.517 | 2.517 | 5.480 | ns |
| | | t_H | -2.412 | -2.412 | -5.203 | ns |
| SSTL-18 CLASS I | GCLK | t_{SU} | 1.113 | 1.113 | 2.479 | ns |
| | | t_H | -1.008 | -1.008 | -2.202 | ns |
| | GCLK PLL | t_{SU} | 2.555 | 2.555 | 5.585 | ns |
| | | t_H | -2.450 | -2.450 | -5.308 | ns |
| SSTL-18 CLASS II | GCLK | t_{SU} | 1.114 | 1.114 | 2.479 | ns |
| | | t_H | -1.009 | -1.009 | -2.202 | ns |
| | GCLK PLL | t_{SU} | 2.556 | 2.556 | 5.587 | ns |
| | | t_H | -2.451 | -2.451 | -5.310 | ns |
| 1.8-V HSTL CLASS I | GCLK | t_{SU} | 1.113 | 1.113 | 2.479 | ns |
| | | t_H | -1.008 | -1.008 | -2.202 | ns |
| | GCLK PLL | t_{SU} | 2.555 | 2.555 | 5.585 | ns |
| | | t_H | -2.450 | -2.450 | -5.308 | ns |
| 1.8-V HSTL CLASS II | GCLK | t_{SU} | 1.114 | 1.114 | 2.479 | ns |
| | | t_H | -1.009 | -1.009 | -2.202 | ns |
| | GCLK PLL | t_{SU} | 2.556 | 2.556 | 5.587 | ns |
| | | t_H | -2.451 | -2.451 | -5.310 | ns |
| 1.5-V HSTL CLASS I | GCLK | t_{SU} | 1.131 | 1.131 | 2.607 | ns |
| | | t_H | -1.026 | -1.026 | -2.330 | ns |
| | GCLK PLL | t_{SU} | 2.573 | 2.573 | 5.713 | ns |
| | | t_H | -2.468 | -2.468 | -5.436 | ns |

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 1.5-V HSTL CLASS II | GCLK | t_{SU} | 1.132 | 1.132 | 2.607 | ns |
| | | t_H | -1.027 | -1.027 | -2.330 | ns |
| | GCLK PLL | t_{SU} | 2.574 | 2.574 | 5.715 | ns |
| | | t_H | -2.469 | -2.469 | -5.438 | ns |
| 3.3-V PCI | GCLK | t_{SU} | 1.256 | 1.256 | 2.903 | ns |
| | | t_H | -1.151 | -1.151 | -2.626 | ns |
| | GCLK PLL | t_{SU} | 2.698 | 2.698 | 6.009 | ns |
| | | t_H | -2.593 | -2.593 | -5.732 | ns |
| 3.3-V PCI-X | GCLK | t_{SU} | 1.256 | 1.256 | 2.903 | ns |
| | | t_H | -1.151 | -1.151 | -2.626 | ns |
| | GCLK PLL | t_{SU} | 2.698 | 2.698 | 6.009 | ns |
| | | t_H | -2.593 | -2.593 | -5.732 | ns |
| LVDS | GCLK | t_{SU} | 1.106 | 1.106 | 2.489 | ns |
| | | t_H | -1.001 | -1.001 | -2.212 | ns |
| | GCLK PLL | t_{SU} | 2.530 | 2.530 | 5.564 | ns |
| | | t_H | -2.425 | -2.425 | -5.287 | ns |

Table 4–56 describes I/O timing specifications.

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 4 mA | GCLK | t_{CO} | 2.904 | 2.904 | 6.699 | ns |
| | | GCLK PLL | t_{CO} | 1.485 | 1.485 | 3.627 | ns |
| 3.3-V LVTTTL | 8 mA | GCLK | t_{CO} | 2.776 | 2.776 | 6.059 | ns |
| | | GCLK PLL | t_{CO} | 1.357 | 1.357 | 2.987 | ns |
| 3.3-V LVTTTL | 12 mA | GCLK | t_{CO} | 2.720 | 2.720 | 6.022 | ns |
| | | GCLK PLL | t_{CO} | 1.301 | 1.301 | 2.950 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 2.776 | 2.776 | 6.059 | ns |
| | | GCLK PLL | t_{CO} | 1.357 | 1.357 | 2.987 | ns |

Table 4–56. EP1AGX35 Row Pins Output Timing Parameters (Part 2 of 3)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|-----------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.670 | 2.670 | 5.753 | ns |
| | | GCLK PLL | t_{CO} | 1.251 | 1.251 | 2.681 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 2.759 | 2.759 | 6.033 | ns |
| | | GCLK PLL | t_{CO} | 1.340 | 1.340 | 2.961 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.656 | 2.656 | 5.775 | ns |
| | | GCLK PLL | t_{CO} | 1.237 | 1.237 | 2.703 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.637 | 2.637 | 5.661 | ns |
| | | GCLK PLL | t_{CO} | 1.218 | 1.218 | 2.589 | ns |
| 1.8 V | 2 mA | GCLK | t_{CO} | 2.829 | 2.829 | 7.052 | ns |
| | | GCLK PLL | t_{CO} | 1.410 | 1.410 | 3.980 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 2.818 | 2.818 | 6.273 | ns |
| | | GCLK PLL | t_{CO} | 1.399 | 1.399 | 3.201 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.707 | 2.707 | 5.972 | ns |
| | | GCLK PLL | t_{CO} | 1.288 | 1.288 | 2.900 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.676 | 2.676 | 5.858 | ns |
| | | GCLK PLL | t_{CO} | 1.257 | 1.257 | 2.786 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 2.789 | 2.789 | 6.551 | ns |
| | | GCLK PLL | t_{CO} | 1.370 | 1.370 | 3.479 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.682 | 2.682 | 5.950 | ns |
| | | GCLK PLL | t_{CO} | 1.263 | 1.263 | 2.878 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.626 | 2.626 | 5.614 | ns |
| | | GCLK PLL | t_{CO} | 1.207 | 1.207 | 2.542 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.602 | 2.602 | 5.538 | ns |
| | | GCLK PLL | t_{CO} | 1.183 | 1.183 | 2.466 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.568 | 2.568 | 5.407 | ns |
| | | GCLK PLL | t_{CO} | 1.149 | 1.149 | 2.335 | ns |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.614 | 2.614 | 5.556 | ns |
| | | GCLK PLL | t_{CO} | 1.195 | 1.195 | 2.484 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.618 | 2.618 | 5.485 | ns |
| | | GCLK PLL | t_{CO} | 1.199 | 1.199 | 2.413 | ns |

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.594 | 2.594 | 5.468 | ns |
| | | GCLK PLL | t_{CO} | 1.175 | 1.175 | 2.396 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.597 | 2.597 | 5.447 | ns |
| | | GCLK PLL | t_{CO} | 1.178 | 1.178 | 2.375 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.595 | 2.595 | 5.466 | ns |
| | | GCLK PLL | t_{CO} | 1.176 | 1.176 | 2.394 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.598 | 2.598 | 5.430 | ns |
| | | GCLK PLL | t_{CO} | 1.179 | 1.179 | 2.358 | ns |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.580 | 2.580 | 5.426 | ns |
| | | GCLK PLL | t_{CO} | 1.161 | 1.161 | 2.354 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.584 | 2.584 | 5.415 | ns |
| | | GCLK PLL | t_{CO} | 1.165 | 1.165 | 2.343 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.575 | 2.575 | 5.414 | ns |
| | | GCLK PLL | t_{CO} | 1.156 | 1.156 | 2.342 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.594 | 2.594 | 5.443 | ns |
| | | GCLK PLL | t_{CO} | 1.175 | 1.175 | 2.371 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.597 | 2.597 | 5.429 | ns |
| | | GCLK PLL | t_{CO} | 1.178 | 1.178 | 2.357 | ns |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.582 | 2.582 | 5.421 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.349 | ns |
| LVDS | - | GCLK | t_{CO} | 2.654 | 2.654 | 5.613 | ns |
| | | GCLK PLL | t_{CO} | 1.226 | 1.226 | 2.530 | ns |

Table 4–57 describes I/O timing specifications.

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 4 mA | GCLK | t_{CO} | 2.909 | 2.909 | 6.541 | ns |
| | | GCLK PLL | t_{CO} | 1.467 | 1.467 | 3.435 | ns |

Table 4–57. EP1AGX35 Column Pins Output Timing Parameters (Part 2 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 8 mA | GCLK | t_{CO} | 2.764 | 2.764 | 6.169 | ns |
| | | GCLK PLL | t_{CO} | 1.322 | 1.322 | 3.063 | ns |
| 3.3-V LVTTTL | 12 mA | GCLK | t_{CO} | 2.697 | 2.697 | 6.169 | ns |
| | | GCLK PLL | t_{CO} | 1.255 | 1.255 | 3.063 | ns |
| 3.3-V LVTTTL | 16 mA | GCLK | t_{CO} | 2.671 | 2.671 | 6.000 | ns |
| | | GCLK PLL | t_{CO} | 1.229 | 1.229 | 2.894 | ns |
| 3.3-V LVTTTL | 20 mA | GCLK | t_{CO} | 2.649 | 2.649 | 5.875 | ns |
| | | GCLK PLL | t_{CO} | 1.207 | 1.207 | 2.769 | ns |
| 3.3-V LVTTTL | 24 mA | GCLK | t_{CO} | 2.642 | 2.642 | 5.877 | ns |
| | | GCLK PLL | t_{CO} | 1.200 | 1.200 | 2.771 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 2.764 | 2.764 | 6.169 | ns |
| | | GCLK PLL | t_{CO} | 1.322 | 1.322 | 3.063 | ns |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.672 | 2.672 | 5.874 | ns |
| | | GCLK PLL | t_{CO} | 1.230 | 1.230 | 2.768 | ns |
| 3.3-V LVCMOS | 12 mA | GCLK | t_{CO} | 2.644 | 2.644 | 5.796 | ns |
| | | GCLK PLL | t_{CO} | 1.202 | 1.202 | 2.690 | ns |
| 3.3-V LVCMOS | 16 mA | GCLK | t_{CO} | 2.651 | 2.651 | 5.764 | ns |
| | | GCLK PLL | t_{CO} | 1.209 | 1.209 | 2.658 | ns |
| 3.3-V LVCMOS | 20 mA | GCLK | t_{CO} | 2.638 | 2.638 | 5.746 | ns |
| | | GCLK PLL | t_{CO} | 1.196 | 1.196 | 2.640 | ns |
| 3.3-V LVCMOS | 24 mA | GCLK | t_{CO} | 2.627 | 2.627 | 5.724 | ns |
| | | GCLK PLL | t_{CO} | 1.185 | 1.185 | 2.618 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 2.726 | 2.726 | 6.201 | ns |
| | | GCLK PLL | t_{CO} | 1.284 | 1.284 | 3.095 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.674 | 2.674 | 5.939 | ns |
| | | GCLK PLL | t_{CO} | 1.232 | 1.232 | 2.833 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.653 | 2.653 | 5.822 | ns |
| | | GCLK PLL | t_{CO} | 1.211 | 1.211 | 2.716 | ns |
| 2.5 V | 16 mA | GCLK | t_{CO} | 2.635 | 2.635 | 5.748 | ns |
| | | GCLK PLL | t_{CO} | 1.193 | 1.193 | 2.642 | ns |

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8 V | 2 mA | GCLK | t_{CO} | 2.766 | 2.766 | 7.193 | ns |
| | | GCLK PLL | t_{CO} | 1.324 | 1.324 | 4.087 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 2.771 | 2.771 | 6.419 | ns |
| | | GCLK PLL | t_{CO} | 1.329 | 1.329 | 3.313 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.695 | 2.695 | 6.155 | ns |
| | | GCLK PLL | t_{CO} | 1.253 | 1.253 | 3.049 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.697 | 2.697 | 6.064 | ns |
| | | GCLK PLL | t_{CO} | 1.255 | 1.255 | 2.958 | ns |
| 1.8 V | 10 mA | GCLK | t_{CO} | 2.651 | 2.651 | 5.987 | ns |
| | | GCLK PLL | t_{CO} | 1.209 | 1.209 | 2.881 | ns |
| 1.8 V | 12 mA | GCLK | t_{CO} | 2.652 | 2.652 | 5.930 | ns |
| | | GCLK PLL | t_{CO} | 1.210 | 1.210 | 2.824 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 2.746 | 2.746 | 6.723 | ns |
| | | GCLK PLL | t_{CO} | 1.304 | 1.304 | 3.617 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.682 | 2.682 | 6.154 | ns |
| | | GCLK PLL | t_{CO} | 1.240 | 1.240 | 3.048 | ns |
| 1.5 V | 6 mA | GCLK | t_{CO} | 2.685 | 2.685 | 6.036 | ns |
| | | GCLK PLL | t_{CO} | 1.243 | 1.243 | 2.930 | ns |
| 1.5 V | 8 mA | GCLK | t_{CO} | 2.644 | 2.644 | 5.983 | ns |
| | | GCLK PLL | t_{CO} | 1.202 | 1.202 | 2.877 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.629 | 2.629 | 5.762 | ns |
| | | GCLK PLL | t_{CO} | 1.184 | 1.184 | 2.650 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.612 | 2.612 | 5.712 | ns |
| | | GCLK PLL | t_{CO} | 1.167 | 1.167 | 2.600 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.590 | 2.590 | 5.639 | ns |
| | | GCLK PLL | t_{CO} | 1.145 | 1.145 | 2.527 | ns |
| SSTL-2 CLASS II | 20 mA | GCLK | t_{CO} | 2.591 | 2.591 | 5.626 | ns |
| | | GCLK PLL | t_{CO} | 1.146 | 1.146 | 2.514 | ns |
| SSTL-2 CLASS II | 24 mA | GCLK | t_{CO} | 2.587 | 2.587 | 5.624 | ns |
| | | GCLK PLL | t_{CO} | 1.142 | 1.142 | 2.512 | ns |

Table 4–57. EP1AGX35 Column Pins Output Timing Parameters (Part 4 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.626 | 2.626 | 5.733 | ns |
| | | GCLK PLL | t_{CO} | 1.184 | 1.184 | 2.627 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.630 | 2.630 | 5.694 | ns |
| | | GCLK PLL | t_{CO} | 1.185 | 1.185 | 2.582 | ns |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.609 | 2.609 | 5.675 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.563 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.614 | 2.614 | 5.673 | ns |
| | | GCLK PLL | t_{CO} | 1.169 | 1.169 | 2.561 | ns |
| SSTL-18 CLASS I | 12 mA | GCLK | t_{CO} | 2.608 | 2.608 | 5.659 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.547 | ns |
| SSTL-18 CLASS II | 8 mA | GCLK | t_{CO} | 2.597 | 2.597 | 5.625 | ns |
| | | GCLK PLL | t_{CO} | 1.152 | 1.152 | 2.513 | ns |
| SSTL-18 CLASS II | 16 mA | GCLK | t_{CO} | 2.609 | 2.609 | 5.603 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.491 | ns |
| SSTL-18 CLASS II | 18 mA | GCLK | t_{CO} | 2.605 | 2.605 | 5.611 | ns |
| | | GCLK PLL | t_{CO} | 1.160 | 1.160 | 2.499 | ns |
| SSTL-18 CLASS II | 20 mA | GCLK | t_{CO} | 2.605 | 2.605 | 5.609 | ns |
| | | GCLK PLL | t_{CO} | 1.160 | 1.160 | 2.497 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.629 | 2.629 | 5.664 | ns |
| | | GCLK PLL | t_{CO} | 1.187 | 1.187 | 2.558 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.634 | 2.634 | 5.649 | ns |
| | | GCLK PLL | t_{CO} | 1.189 | 1.189 | 2.537 | ns |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.612 | 2.612 | 5.638 | ns |
| | | GCLK PLL | t_{CO} | 1.167 | 1.167 | 2.526 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.616 | 2.616 | 5.644 | ns |
| | | GCLK PLL | t_{CO} | 1.171 | 1.171 | 2.532 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.608 | 2.608 | 5.637 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.525 | ns |
| 1.8-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.591 | 2.591 | 5.401 | ns |
| | | GCLK PLL | t_{CO} | 1.146 | 1.146 | 2.289 | ns |

Table 4–57. EP1AGX35 Column Pins Output Timing Parameters (Part 5 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.593 | 2.593 | 5.412 | ns |
| | | GCLK PLL | t_{CO} | 1.148 | 1.148 | 2.300 | ns |
| 1.8-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.593 | 2.593 | 5.421 | ns |
| | | GCLK PLL | t_{CO} | 1.148 | 1.148 | 2.309 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.629 | 2.629 | 5.663 | ns |
| | | GCLK PLL | t_{CO} | 1.187 | 1.187 | 2.557 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.633 | 2.633 | 5.641 | ns |
| | | GCLK PLL | t_{CO} | 1.188 | 1.188 | 2.529 | ns |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.615 | 2.615 | 5.643 | ns |
| | | GCLK PLL | t_{CO} | 1.170 | 1.170 | 2.531 | ns |
| 1.5-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.615 | 2.615 | 5.645 | ns |
| | | GCLK PLL | t_{CO} | 1.170 | 1.170 | 2.533 | ns |
| 1.5-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.609 | 2.609 | 5.643 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.531 | ns |
| 1.5-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.596 | 2.596 | 5.455 | ns |
| | | GCLK PLL | t_{CO} | 1.151 | 1.151 | 2.343 | ns |
| 1.5-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.599 | 2.599 | 5.465 | ns |
| | | GCLK PLL | t_{CO} | 1.154 | 1.154 | 2.353 | ns |
| 1.5-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.601 | 2.601 | 5.478 | ns |
| | | GCLK PLL | t_{CO} | 1.156 | 1.156 | 2.366 | ns |
| 3.3-V PCI | - | GCLK | t_{CO} | 2.755 | 2.755 | 5.791 | ns |
| | | GCLK PLL | t_{CO} | 1.313 | 1.313 | 2.685 | ns |
| 3.3-V PCI-X | - | GCLK | t_{CO} | 2.755 | 2.755 | 5.791 | ns |
| | | GCLK PLL | t_{CO} | 1.313 | 1.313 | 2.685 | ns |
| LVDS | - | GCLK | t_{CO} | 3.621 | 3.621 | 6.969 | ns |
| | | GCLK PLL | t_{CO} | 2.190 | 2.190 | 3.880 | ns |

Tables 4–58 through 4–59 shows EP1AGX35 regional clock (RCLK) adder values that should be added to GCLK values. These adder values are used to determine I/O timing when the I/O pin is driven using the regional clock. This applies for all I/O standards supported by Arria GX with general purpose I/O pins.

Table 4–58 describes row pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.126 | 0.126 | 0.281 | ns |
| RCLK PLL input adder | 0.011 | 0.011 | 0.018 | ns |
| RCLK output adder | -0.126 | -0.126 | -0.281 | ns |
| RCLK PLL output adder | -0.011 | -0.011 | -0.018 | ns |

Table 4–59 describes column pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.099 | 0.099 | 0.254 | ns |
| RCLK PLL input adder | -0.012 | -0.012 | -0.01 | ns |
| RCLK output adder | -0.086 | -0.086 | -0.244 | ns |
| RCLK PLL output adder | 1.253 | 1.253 | 3.133 | ns |

EP1AGX50 I/O Timing Parameters

Tables 4–60 through 4–63 show the maximum I/O timing parameters for EP1AGX50 devices for I/O standards which support general purpose I/O pins.

Table 4–60 describes I/O timing specifications.

| Table 4–60. EP1AGX50 Row Pins Input Timing Parameters (Part 1 of 3) | | | | | | |
|--|----------|-----------|------------|------------|----------------|-------|
| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
| | | | Industrial | Commercial | | |
| 3.3-V LVTTL | GCLK | t_{SU} | 1.550 | 1.550 | 3.542 | ns |
| | | t_H | -1.445 | -1.445 | -3.265 | ns |
| | GCLK PLL | t_{SU} | 2.978 | 2.978 | 6.626 | ns |
| | | t_H | -2.873 | -2.873 | -6.349 | ns |
| 3.3-V LVCMOS | GCLK | t_{SU} | 1.550 | 1.550 | 3.542 | ns |
| | | t_H | -1.445 | -1.445 | -3.265 | ns |
| | GCLK PLL | t_{SU} | 2.978 | 2.978 | 6.626 | ns |
| | | t_H | -2.873 | -2.873 | -6.349 | ns |
| 2.5 V | GCLK | t_{SU} | 1.562 | 1.562 | 3.523 | ns |
| | | t_H | -1.457 | -1.457 | -3.246 | ns |
| | GCLK PLL | t_{SU} | 2.990 | 2.990 | 6.607 | ns |
| | | t_H | -2.885 | -2.885 | -6.330 | ns |
| 1.8 V | GCLK | t_{SU} | 1.628 | 1.628 | 3.730 | ns |
| | | t_H | -1.523 | -1.523 | -3.453 | ns |
| | GCLK PLL | t_{SU} | 3.056 | 3.056 | 6.814 | ns |
| | | t_H | -2.951 | -2.951 | -6.537 | ns |
| 1.5 V | GCLK | t_{SU} | 1.631 | 1.631 | 3.825 | ns |
| | | t_H | -1.526 | -1.526 | -3.548 | ns |
| | GCLK PLL | t_{SU} | 3.059 | 3.059 | 6.909 | ns |
| | | t_H | -2.954 | -2.954 | -6.632 | ns |
| SSTL-2 CLASS I | GCLK | t_{SU} | 1.375 | 1.375 | 2.997 | ns |
| | | t_H | -1.270 | -1.270 | -2.720 | ns |
| | GCLK PLL | t_{SU} | 2.802 | 2.802 | 6.079 | ns |
| | | t_H | -2.697 | -2.697 | -5.802 | ns |

Table 4–60. EP1AGX50 Row Pins Input Timing Parameters (Part 2 of 3)

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|------------------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| SSTL-2 CLASS II | GCLK | t_{SU} | 1.375 | 1.375 | 2.997 | ns |
| | | t_H | -1.270 | -1.270 | -2.720 | ns |
| | GCLK PLL | t_{SU} | 2.802 | 2.802 | 6.079 | ns |
| | | t_H | -2.697 | -2.697 | -5.802 | ns |
| SSTL-18 CLASS I | GCLK | t_{SU} | 1.406 | 1.406 | 3.104 | ns |
| | | t_H | -1.301 | -1.301 | -2.827 | ns |
| | GCLK PLL | t_{SU} | 2.834 | 2.834 | 6.188 | ns |
| | | t_H | -2.729 | -2.729 | -5.911 | ns |
| SSTL-18 CLASS II | GCLK | t_{SU} | 1.407 | 1.407 | 3.106 | ns |
| | | t_H | -1.302 | -1.302 | -2.829 | ns |
| | GCLK PLL | t_{SU} | 2.834 | 2.834 | 6.188 | ns |
| | | t_H | -2.729 | -2.729 | -5.911 | ns |
| 1.8-V HSTL CLASS I | GCLK | t_{SU} | 1.406 | 1.406 | 3.104 | ns |
| | | t_H | -1.301 | -1.301 | -2.827 | ns |
| | GCLK PLL | t_{SU} | 2.834 | 2.834 | 6.188 | ns |
| | | t_H | -2.729 | -2.729 | -5.911 | ns |
| 1.8-V HSTL CLASS II | GCLK | t_{SU} | 1.407 | 1.407 | 3.106 | ns |
| | | t_H | -1.302 | -1.302 | -2.829 | ns |
| | GCLK PLL | t_{SU} | 2.834 | 2.834 | 6.188 | ns |
| | | t_H | -2.729 | -2.729 | -5.911 | ns |
| 1.5-V HSTL CLASS I | GCLK | t_{SU} | 1.432 | 1.432 | 3.232 | ns |
| | | t_H | -1.327 | -1.327 | -2.955 | ns |
| | GCLK PLL | t_{SU} | 2.860 | 2.860 | 6.316 | ns |
| | | t_H | -2.755 | -2.755 | -6.039 | ns |
| 1.5-V HSTL CLASS II | GCLK | t_{SU} | 1.433 | 1.433 | 3.234 | ns |
| | | t_H | -1.328 | -1.328 | -2.957 | ns |
| | GCLK PLL | t_{SU} | 2.860 | 2.860 | 6.316 | ns |
| | | t_H | -2.755 | -2.755 | -6.039 | ns |

Table 4–60. EP1AGX50 Row Pins Input Timing Parameters (Part 3 of 3)

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| LVDS | GCLK | t_{SU} | 1.341 | 1.341 | 3.088 | ns |
| | | t_H | -1.236 | -1.236 | -2.811 | ns |
| | GCLK PLL | t_{SU} | 2.769 | 2.769 | 6.171 | ns |
| | | t_H | -2.664 | -2.664 | -5.894 | ns |

Table 4–61 describes I/O timing specifications.

Table 4–61. EP1AGX50 Column Pins Input Timing Parameters (Part 1 of 3)

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 3.3-V LVTTL | GCLK | t_{SU} | 1.242 | 1.242 | 2.902 | ns |
| | | t_H | -1.137 | -1.137 | -2.625 | ns |
| | GCLK PLL | t_{SU} | 2.684 | 2.684 | 6.009 | ns |
| | | t_H | -2.579 | -2.579 | -5.732 | ns |
| 3.3-V LVCMOS | GCLK | t_{SU} | 1.242 | 1.242 | 2.902 | ns |
| | | t_H | -1.137 | -1.137 | -2.625 | ns |
| | GCLK PLL | t_{SU} | 2.684 | 2.684 | 6.009 | ns |
| | | t_H | -2.579 | -2.579 | -5.732 | ns |
| 2.5 V | GCLK | t_{SU} | 1.252 | 1.252 | 2.884 | ns |
| | | t_H | -1.147 | -1.147 | -2.607 | ns |
| | GCLK PLL | t_{SU} | 2.694 | 2.694 | 5.991 | ns |
| | | t_H | -2.589 | -2.589 | -5.714 | ns |
| 1.8 V | GCLK | t_{SU} | 1.318 | 1.318 | 3.094 | ns |
| | | t_H | -1.213 | -1.213 | -2.817 | ns |
| | GCLK PLL | t_{SU} | 2.760 | 2.760 | 6.201 | ns |
| | | t_H | -2.655 | -2.655 | -5.924 | ns |
| 1.5 V | GCLK | t_{SU} | 1.321 | 1.321 | 3.187 | ns |
| | | t_H | -1.216 | -1.216 | -2.910 | ns |
| | GCLK PLL | t_{SU} | 2.763 | 2.763 | 6.294 | ns |
| | | t_H | -2.658 | -2.658 | -6.017 | ns |

Table 4–61. EP1AGX50 Column Pins Input Timing Parameters (Part 2 of 3)

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| SSTL-2 CLASS I | GCLK | t_{SU} | 1.034 | 1.034 | 2.314 | ns |
| | | t_H | -0.929 | -0.929 | -2.037 | ns |
| | GCLK PLL | t_{SU} | 2.500 | 2.500 | 5.457 | ns |
| | | t_H | -2.395 | -2.395 | -5.180 | ns |
| SSTL-2 CLASS II | GCLK | t_{SU} | 1.034 | 1.034 | 2.314 | ns |
| | | t_H | -0.929 | -0.929 | -2.037 | ns |
| | GCLK PLL | t_{SU} | 2.500 | 2.500 | 5.457 | ns |
| | | t_H | -2.395 | -2.395 | -5.180 | ns |
| SSTL-18 CLASS I | GCLK | t_{SU} | 1.104 | 1.104 | 2.466 | ns |
| | | t_H | -0.999 | -0.999 | -2.189 | ns |
| | GCLK PLL | t_{SU} | 2.546 | 2.546 | 5.573 | ns |
| | | t_H | -2.441 | -2.441 | -5.296 | ns |
| SSTL-18 CLASS II | GCLK | t_{SU} | 1.074 | 1.074 | 2.424 | ns |
| | | t_H | -0.969 | -0.969 | -2.147 | ns |
| | GCLK PLL | t_{SU} | 2.539 | 2.539 | 5.564 | ns |
| | | t_H | -2.434 | -2.434 | -5.287 | ns |
| 1.8-V HSTL CLASS I | GCLK | t_{SU} | 1.104 | 1.104 | 2.466 | ns |
| | | t_H | -0.999 | -0.999 | -2.189 | ns |
| | GCLK PLL | t_{SU} | 2.546 | 2.546 | 5.573 | ns |
| | | t_H | -2.441 | -2.441 | -5.296 | ns |
| 1.8-V HSTL CLASS II | GCLK | t_{SU} | 1.074 | 1.074 | 2.424 | ns |
| | | t_H | -0.969 | -0.969 | -2.147 | ns |
| | GCLK PLL | t_{SU} | 2.539 | 2.539 | 5.564 | ns |
| | | t_H | -2.434 | -2.434 | -5.287 | ns |
| 1.5-V HSTL CLASS I | GCLK | t_{SU} | 1.122 | 1.122 | 2.594 | ns |
| | | t_H | -1.017 | -1.017 | -2.317 | ns |
| | GCLK PLL | t_{SU} | 2.564 | 2.564 | 5.701 | ns |
| | | t_H | -2.459 | -2.459 | -5.424 | ns |

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 1.5-V HSTL CLASS II | GCLK | t_{SU} | 1.094 | 1.094 | 2.557 | ns |
| | | t_H | -0.989 | -0.989 | -2.280 | ns |
| | GCLK PLL | t_{SU} | 2.557 | 2.557 | 5.692 | ns |
| | | t_H | -2.452 | -2.452 | -5.415 | ns |
| 3.3-V PCI | GCLK | t_{SU} | 1.247 | 1.247 | 2.890 | ns |
| | | t_H | -1.142 | -1.142 | -2.613 | ns |
| | GCLK PLL | t_{SU} | 2.689 | 2.689 | 5.997 | ns |
| | | t_H | -2.584 | -2.584 | -5.720 | ns |
| 3.3-V PCI-X | GCLK | t_{SU} | 1.247 | 1.247 | 2.890 | ns |
| | | t_H | -1.142 | -1.142 | -2.613 | ns |
| | GCLK PLL | t_{SU} | 2.689 | 2.689 | 5.997 | ns |
| | | t_H | -2.584 | -2.584 | -5.720 | ns |
| LVDS | GCLK | t_{SU} | 1.106 | 1.106 | 2.489 | ns |
| | | t_H | -1.001 | -1.001 | -2.212 | ns |
| | GCLK PLL | t_{SU} | 2.530 | 2.530 | 5.564 | ns |
| | | t_H | -2.425 | -2.425 | -5.287 | ns |

Table 4–62 describes I/O timing specifications.

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 4 mA | GCLK | t_{CO} | 2.915 | 2.915 | 6.713 | ns |
| | | GCLK PLL | t_{CO} | 1.487 | 1.487 | 3.629 | ns |
| 3.3-V LVTTTL | 8 mA | GCLK | t_{CO} | 2.787 | 2.787 | 6.073 | ns |
| | | GCLK PLL | t_{CO} | 1.359 | 1.359 | 2.989 | ns |
| 3.3-V LVTTTL | 12 mA | GCLK | t_{CO} | 2.731 | 2.731 | 6.036 | ns |
| | | GCLK PLL | t_{CO} | 1.303 | 1.303 | 2.952 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 2.787 | 2.787 | 6.073 | ns |
| | | GCLK PLL | t_{CO} | 1.359 | 1.359 | 2.989 | ns |

Table 4–62. EP1AGX50 Row Pins Output Timing Parameters (Part 2 of 3)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|-----------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.681 | 2.681 | 5.767 | ns |
| | | GCLK PLL | t_{CO} | 1.253 | 1.253 | 2.683 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 2.770 | 2.770 | 6.047 | ns |
| | | GCLK PLL | t_{CO} | 1.342 | 1.342 | 2.963 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.667 | 2.667 | 5.789 | ns |
| | | GCLK PLL | t_{CO} | 1.239 | 1.239 | 2.705 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.648 | 2.648 | 5.675 | ns |
| | | GCLK PLL | t_{CO} | 1.220 | 1.220 | 2.591 | ns |
| 1.8 V | 2 mA | GCLK | t_{CO} | 2.840 | 2.840 | 7.066 | ns |
| | | GCLK PLL | t_{CO} | 1.412 | 1.412 | 3.982 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 2.829 | 2.829 | 6.287 | ns |
| | | GCLK PLL | t_{CO} | 1.401 | 1.401 | 3.203 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.718 | 2.718 | 5.986 | ns |
| | | GCLK PLL | t_{CO} | 1.290 | 1.290 | 2.902 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.687 | 2.687 | 5.872 | ns |
| | | GCLK PLL | t_{CO} | 1.259 | 1.259 | 2.788 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 2.800 | 2.800 | 6.565 | ns |
| | | GCLK PLL | t_{CO} | 1.372 | 1.372 | 3.481 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.693 | 2.693 | 5.964 | ns |
| | | GCLK PLL | t_{CO} | 1.265 | 1.265 | 2.880 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.636 | 2.636 | 5.626 | ns |
| | | GCLK PLL | t_{CO} | 1.209 | 1.209 | 2.544 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.612 | 2.612 | 5.550 | ns |
| | | GCLK PLL | t_{CO} | 1.185 | 1.185 | 2.468 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.578 | 2.578 | 5.419 | ns |
| | | GCLK PLL | t_{CO} | 1.151 | 1.151 | 2.337 | ns |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.625 | 2.625 | 5.570 | ns |
| | | GCLK PLL | t_{CO} | 1.197 | 1.197 | 2.486 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.628 | 2.628 | 5.497 | ns |
| | | GCLK PLL | t_{CO} | 1.201 | 1.201 | 2.415 | ns |

Table 4–62. EP1AGX50 Row Pins Output Timing Parameters (Part 3 of 3)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.604 | 2.604 | 5.480 | ns |
| | | GCLK PLL | t_{CO} | 1.177 | 1.177 | 2.398 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.607 | 2.607 | 5.459 | ns |
| | | GCLK PLL | t_{CO} | 1.180 | 1.180 | 2.377 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.606 | 2.606 | 5.480 | ns |
| | | GCLK PLL | t_{CO} | 1.178 | 1.178 | 2.396 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.608 | 2.608 | 5.442 | ns |
| | | GCLK PLL | t_{CO} | 1.181 | 1.181 | 2.360 | ns |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.590 | 2.590 | 5.438 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.356 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.594 | 2.594 | 5.427 | ns |
| | | GCLK PLL | t_{CO} | 1.167 | 1.167 | 2.345 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.585 | 2.585 | 5.426 | ns |
| | | GCLK PLL | t_{CO} | 1.158 | 1.158 | 2.344 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.605 | 2.605 | 5.457 | ns |
| | | GCLK PLL | t_{CO} | 1.177 | 1.177 | 2.373 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.607 | 2.607 | 5.441 | ns |
| | | GCLK PLL | t_{CO} | 1.180 | 1.180 | 2.359 | ns |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.592 | 2.592 | 5.433 | ns |
| | | GCLK PLL | t_{CO} | 1.165 | 1.165 | 2.351 | ns |
| LVDS | - | GCLK | t_{CO} | 2.654 | 2.654 | 5.613 | ns |
| | | GCLK PLL | t_{CO} | 1.226 | 1.226 | 2.530 | ns |

Table 4–63 describes I/O timing specifications.

Table 4–63. EP1AGX50 Column Pins Output Timing Parameters (Part 1 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 4 mA | GCLK | t_{CO} | 2.948 | 2.948 | 6.608 | ns |
| | | GCLK PLL | t_{CO} | 1.476 | 1.476 | 3.447 | ns |

Table 4–63. EP1AGX50 Column Pins Output Timing Parameters (Part 2 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 8 mA | GCLK | t_{CO} | 2.797 | 2.797 | 6.203 | ns |
| | | GCLK PLL | t_{CO} | 1.331 | 1.331 | 3.075 | ns |
| 3.3-V LVTTTL | 12 mA | GCLK | t_{CO} | 2.722 | 2.722 | 6.204 | ns |
| | | GCLK PLL | t_{CO} | 1.264 | 1.264 | 3.075 | ns |
| 3.3-V LVTTTL | 16 mA | GCLK | t_{CO} | 2.694 | 2.694 | 6.024 | ns |
| | | GCLK PLL | t_{CO} | 1.238 | 1.238 | 2.906 | ns |
| 3.3-V LVTTTL | 20 mA | GCLK | t_{CO} | 2.670 | 2.670 | 5.896 | ns |
| | | GCLK PLL | t_{CO} | 1.216 | 1.216 | 2.781 | ns |
| 3.3-V LVTTTL | 24 mA | GCLK | t_{CO} | 2.660 | 2.660 | 5.895 | ns |
| | | GCLK PLL | t_{CO} | 1.209 | 1.209 | 2.783 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 2.797 | 2.797 | 6.203 | ns |
| | | GCLK PLL | t_{CO} | 1.331 | 1.331 | 3.075 | ns |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.695 | 2.695 | 5.893 | ns |
| | | GCLK PLL | t_{CO} | 1.239 | 1.239 | 2.780 | ns |
| 3.3-V LVCMOS | 12 mA | GCLK | t_{CO} | 2.663 | 2.663 | 5.809 | ns |
| | | GCLK PLL | t_{CO} | 1.211 | 1.211 | 2.702 | ns |
| 3.3-V LVCMOS | 16 mA | GCLK | t_{CO} | 2.666 | 2.666 | 5.776 | ns |
| | | GCLK PLL | t_{CO} | 1.218 | 1.218 | 2.670 | ns |
| 3.3-V LVCMOS | 20 mA | GCLK | t_{CO} | 2.651 | 2.651 | 5.758 | ns |
| | | GCLK PLL | t_{CO} | 1.205 | 1.205 | 2.652 | ns |
| 3.3-V LVCMOS | 24 mA | GCLK | t_{CO} | 2.638 | 2.638 | 5.736 | ns |
| | | GCLK PLL | t_{CO} | 1.194 | 1.194 | 2.630 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 2.754 | 2.754 | 6.240 | ns |
| | | GCLK PLL | t_{CO} | 1.293 | 1.293 | 3.107 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.697 | 2.697 | 5.963 | ns |
| | | GCLK PLL | t_{CO} | 1.241 | 1.241 | 2.845 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.672 | 2.672 | 5.837 | ns |
| | | GCLK PLL | t_{CO} | 1.220 | 1.220 | 2.728 | ns |
| 2.5 V | 16 mA | GCLK | t_{CO} | 2.654 | 2.654 | 5.760 | ns |
| | | GCLK PLL | t_{CO} | 1.202 | 1.202 | 2.654 | ns |

Table 4–63. EP1AGX50 Column Pins Output Timing Parameters (Part 3 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8 V | 2 mA | GCLK | t_{CO} | 2.804 | 2.804 | 7.295 | ns |
| | | GCLK PLL | t_{CO} | 1.333 | 1.333 | 4.099 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 2.808 | 2.808 | 6.479 | ns |
| | | GCLK PLL | t_{CO} | 1.338 | 1.338 | 3.325 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.717 | 2.717 | 6.195 | ns |
| | | GCLK PLL | t_{CO} | 1.262 | 1.262 | 3.061 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.719 | 2.719 | 6.098 | ns |
| | | GCLK PLL | t_{CO} | 1.264 | 1.264 | 2.970 | ns |
| 1.8 V | 10 mA | GCLK | t_{CO} | 2.671 | 2.671 | 6.012 | ns |
| | | GCLK PLL | t_{CO} | 1.218 | 1.218 | 2.893 | ns |
| 1.8 V | 12 mA | GCLK | t_{CO} | 2.671 | 2.671 | 5.953 | ns |
| | | GCLK PLL | t_{CO} | 1.219 | 1.219 | 2.836 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 2.779 | 2.779 | 6.815 | ns |
| | | GCLK PLL | t_{CO} | 1.313 | 1.313 | 3.629 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.703 | 2.703 | 6.210 | ns |
| | | GCLK PLL | t_{CO} | 1.249 | 1.249 | 3.060 | ns |
| 1.5 V | 6 mA | GCLK | t_{CO} | 2.705 | 2.705 | 6.118 | ns |
| | | GCLK PLL | t_{CO} | 1.252 | 1.252 | 2.942 | ns |
| 1.5 V | 8 mA | GCLK | t_{CO} | 2.660 | 2.660 | 6.014 | ns |
| | | GCLK PLL | t_{CO} | 1.211 | 1.211 | 2.889 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.648 | 2.648 | 5.777 | ns |
| | | GCLK PLL | t_{CO} | 1.202 | 1.202 | 2.675 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.628 | 2.628 | 5.722 | ns |
| | | GCLK PLL | t_{CO} | 1.185 | 1.185 | 2.625 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.606 | 2.606 | 5.649 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.552 | ns |
| SSTL-2 CLASS II | 20 mA | GCLK | t_{CO} | 2.606 | 2.606 | 5.636 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.539 | ns |
| SSTL-2 CLASS II | 24 mA | GCLK | t_{CO} | 2.601 | 2.601 | 5.634 | ns |
| | | GCLK PLL | t_{CO} | 1.160 | 1.160 | 2.537 | ns |

Table 4–63. EP1AGX50 Column Pins Output Timing Parameters (Part 4 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.643 | 2.643 | 5.749 | ns |
| | | GCLK PLL | t_{CO} | 1.193 | 1.193 | 2.639 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.649 | 2.649 | 5.708 | ns |
| | | GCLK PLL | t_{CO} | 1.203 | 1.203 | 2.607 | ns |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.626 | 2.626 | 5.686 | ns |
| | | GCLK PLL | t_{CO} | 1.182 | 1.182 | 2.588 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.630 | 2.630 | 5.685 | ns |
| | | GCLK PLL | t_{CO} | 1.187 | 1.187 | 2.586 | ns |
| SSTL-18 CLASS I | 12 mA | GCLK | t_{CO} | 2.625 | 2.625 | 5.669 | ns |
| | | GCLK PLL | t_{CO} | 1.181 | 1.181 | 2.572 | ns |
| SSTL-18 CLASS II | 8 mA | GCLK | t_{CO} | 2.614 | 2.614 | 5.635 | ns |
| | | GCLK PLL | t_{CO} | 1.170 | 1.170 | 2.538 | ns |
| SSTL-18 CLASS II | 16 mA | GCLK | t_{CO} | 2.623 | 2.623 | 5.613 | ns |
| | | GCLK PLL | t_{CO} | 1.182 | 1.182 | 2.516 | ns |
| SSTL-18 CLASS II | 18 mA | GCLK | t_{CO} | 2.616 | 2.616 | 5.621 | ns |
| | | GCLK PLL | t_{CO} | 1.178 | 1.178 | 2.524 | ns |
| SSTL-18 CLASS II | 20 mA | GCLK | t_{CO} | 2.616 | 2.616 | 5.619 | ns |
| | | GCLK PLL | t_{CO} | 1.178 | 1.178 | 2.522 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.637 | 2.637 | 5.676 | ns |
| | | GCLK PLL | t_{CO} | 1.196 | 1.196 | 2.570 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.645 | 2.645 | 5.659 | ns |
| | | GCLK PLL | t_{CO} | 1.207 | 1.207 | 2.562 | ns |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.623 | 2.623 | 5.648 | ns |
| | | GCLK PLL | t_{CO} | 1.185 | 1.185 | 2.551 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.627 | 2.627 | 5.654 | ns |
| | | GCLK PLL | t_{CO} | 1.189 | 1.189 | 2.557 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.619 | 2.619 | 5.647 | ns |
| | | GCLK PLL | t_{CO} | 1.181 | 1.181 | 2.550 | ns |
| 1.8-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.602 | 2.602 | 5.574 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.314 | ns |

Table 4–63. EP1AGX50 Column Pins Output Timing Parameters (Part 5 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.604 | 2.604 | 5.578 | ns |
| | | GCLK PLL | t_{CO} | 1.166 | 1.166 | 2.325 | ns |
| 1.8-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.604 | 2.604 | 5.577 | ns |
| | | GCLK PLL | t_{CO} | 1.166 | 1.166 | 2.334 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.637 | 2.637 | 5.675 | ns |
| | | GCLK PLL | t_{CO} | 1.196 | 1.196 | 2.569 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.644 | 2.644 | 5.651 | ns |
| | | GCLK PLL | t_{CO} | 1.206 | 1.206 | 2.554 | ns |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.626 | 2.626 | 5.653 | ns |
| | | GCLK PLL | t_{CO} | 1.188 | 1.188 | 2.556 | ns |
| 1.5-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.626 | 2.626 | 5.655 | ns |
| | | GCLK PLL | t_{CO} | 1.188 | 1.188 | 2.558 | ns |
| 1.5-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.620 | 2.620 | 5.653 | ns |
| | | GCLK PLL | t_{CO} | 1.182 | 1.182 | 2.556 | ns |
| 1.5-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.607 | 2.607 | 5.573 | ns |
| | | GCLK PLL | t_{CO} | 1.169 | 1.169 | 2.368 | ns |
| 1.5-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.610 | 2.610 | 5.571 | ns |
| | | GCLK PLL | t_{CO} | 1.172 | 1.172 | 2.378 | ns |
| 1.5-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.612 | 2.612 | 5.581 | ns |
| | | GCLK PLL | t_{CO} | 1.174 | 1.174 | 2.391 | ns |
| 3.3-V PCI | - | GCLK | t_{CO} | 2.786 | 2.786 | 5.803 | ns |
| | | GCLK PLL | t_{CO} | 1.322 | 1.322 | 2.697 | ns |
| 3.3-V PCI-X | - | GCLK | t_{CO} | 2.786 | 2.786 | 5.803 | ns |
| | | GCLK PLL | t_{CO} | 1.322 | 1.322 | 2.697 | ns |
| LVDS | - | GCLK | t_{CO} | 3.621 | 3.621 | 6.969 | ns |
| | | GCLK PLL | t_{CO} | 2.190 | 2.190 | 3.880 | ns |

Tables 4–64 through 4–65 shows EP1AGX50 regional clock (RCLK) adder values that should be added to the GCLK values. These adder values are used to determine I/O timing when the I/O pin is driven using the regional clock. This applies for all I/O standards supported by Arria GX with general purpose I/O pins.

Table 4–64 describes row pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.151 | 0.151 | 0.329 | ns |
| RCLK PLL input adder | 0.011 | 0.011 | 0.016 | ns |
| RCLK output adder | -0.151 | -0.151 | -0.329 | ns |
| RCLK PLL output adder | -0.011 | -0.011 | -0.016 | ns |

Table 4–65 describes column pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.146 | 0.146 | 0.334 | ns |
| RCLK PLL input adder | -1.713 | -1.713 | -3.645 | ns |
| RCLK output adder | -0.146 | -0.146 | -0.336 | ns |
| RCLK PLL output adder | 1.716 | 1.716 | 4.488 | ns |

EP1AGX60 I/O Timing Parameters

Tables 4–66 through 4–69 show the maximum I/O timing parameters for EP1AGX60 devices for I/O standards which support general purpose I/O pins.

Table 4–66 describes I/O timing specifications.

Table 4–66. EP1AGX60 Row Pins Input Timing Parameters (Part 1 of 3)

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 3.3-V LVTTL | GCLK | t_{SU} | 1.413 | 1.413 | 3.113 | ns |
| | | t_H | -1.308 | -1.308 | -2.836 | ns |
| | GCLK PLL | t_{SU} | 2.975 | 2.975 | 6.536 | ns |
| | | t_H | -2.870 | -2.870 | -6.259 | ns |
| 3.3-V LVCMOS | GCLK | t_{SU} | 1.413 | 1.413 | 3.113 | ns |
| | | t_H | -1.308 | -1.308 | -2.836 | ns |
| | GCLK PLL | t_{SU} | 2.975 | 2.975 | 6.536 | ns |
| | | t_H | -2.870 | -2.870 | -6.259 | ns |
| 2.5 V | GCLK | t_{SU} | 1.425 | 1.425 | 3.094 | ns |
| | | t_H | -1.320 | -1.320 | -2.817 | ns |
| | GCLK PLL | t_{SU} | 2.987 | 2.987 | 6.517 | ns |
| | | t_H | -2.882 | -2.882 | -6.240 | ns |
| 1.8 V | GCLK | t_{SU} | 1.477 | 1.477 | 3.275 | ns |
| | | t_H | -1.372 | -1.372 | -2.998 | ns |
| | GCLK PLL | t_{SU} | 3.049 | 3.049 | 6.718 | ns |
| | | t_H | -2.944 | -2.944 | -6.441 | ns |
| 1.5 V | GCLK | t_{SU} | 1.480 | 1.480 | 3.370 | ns |
| | | t_H | -1.375 | -1.375 | -3.093 | ns |
| | GCLK PLL | t_{SU} | 3.052 | 3.052 | 6.813 | ns |
| | | t_H | -2.947 | -2.947 | -6.536 | ns |
| SSTL-2 CLASS I | GCLK | t_{SU} | 1.237 | 1.237 | 2.566 | ns |
| | | t_H | -1.132 | -1.132 | -2.289 | ns |
| | GCLK PLL | t_{SU} | 2.800 | 2.800 | 5.990 | ns |
| | | t_H | -2.695 | -2.695 | -5.713 | ns |

Table 4–66. EP1AGX60 Row Pins Input Timing Parameters (Part 2 of 3)

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|---------------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| SSTL-2 CLASS II | GCLK | t_{SU} | 1.237 | 1.237 | 2.566 | ns |
| | | t_H | -1.132 | -1.132 | -2.289 | ns |
| | GCLK PLL | t_{SU} | 2.800 | 2.800 | 5.990 | ns |
| | | t_H | -2.695 | -2.695 | -5.713 | ns |
| SSTL-18 CLASS I | GCLK | t_{SU} | 1.255 | 1.255 | 2.649 | ns |
| | | t_H | -1.150 | -1.150 | -2.372 | ns |
| | GCLK PLL | t_{SU} | 2.827 | 2.827 | 6.092 | ns |
| | | t_H | -2.722 | -2.722 | -5.815 | ns |
| SSTL-18 CLASS II | GCLK | t_{SU} | 1.255 | 1.255 | 2.649 | ns |
| | | t_H | -1.150 | -1.150 | -2.372 | ns |
| | GCLK PLL | t_{SU} | 2.827 | 2.827 | 6.092 | ns |
| | | t_H | -2.722 | -2.722 | -5.815 | ns |
| 1.8-V HSTL CLASS I | GCLK | t_{SU} | 1.255 | 1.255 | 2.649 | ns |
| | | t_H | -1.150 | -1.150 | -2.372 | ns |
| | GCLK PLL | t_{SU} | 2.827 | 2.827 | 6.092 | ns |
| | | t_H | -2.722 | -2.722 | -5.815 | ns |
| 1.8-V HSTL CLASS II | GCLK | t_{SU} | 1.255 | 1.255 | 2.649 | ns |
| | | t_H | -1.150 | -1.150 | -2.372 | ns |
| | GCLK PLL | t_{SU} | 2.827 | 2.827 | 6.092 | ns |
| | | t_H | -2.722 | -2.722 | -5.815 | ns |
| 1.5-V HSTL CLASS I | GCLK | t_{SU} | 1.281 | 1.281 | 2.777 | ns |
| | | t_H | -1.176 | -1.176 | -2.500 | ns |
| | GCLK PLL | t_{SU} | 2.853 | 2.853 | 6.220 | ns |
| | | t_H | -2.748 | -2.748 | -5.943 | ns |
| 1.5-V HSTL CLASS II | GCLK | t_{SU} | 1.281 | 1.281 | 2.777 | ns |
| | | t_H | -1.176 | -1.176 | -2.500 | ns |
| | GCLK PLL | t_{SU} | 2.853 | 2.853 | 6.220 | ns |
| | | t_H | -2.748 | -2.748 | -5.943 | ns |

Table 4–66. EP1AGX60 Row Pins Input Timing Parameters (Part 3 of 3)

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| LVDS | GCLK | t_{SU} | 1.208 | 1.208 | 2.664 | ns |
| | | t_H | -1.103 | -1.103 | -2.387 | ns |
| | GCLK PLL | t_{SU} | 2.767 | 2.767 | 6.083 | ns |
| | | t_H | -2.662 | -2.662 | -5.806 | ns |

Table 4–67 describes I/O timing specifications.

Table 4–67. EP1AGX60 Column Pins Input Timing Parameters (Part 1 of 3)

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 3.3-V LVTTL | GCLK | t_{SU} | 1.124 | 1.124 | 2.493 | ns |
| | | t_H | -1.019 | -1.019 | -2.216 | ns |
| | GCLK PLL | t_{SU} | 2.694 | 2.694 | 5.928 | ns |
| | | t_H | -2.589 | -2.589 | -5.651 | ns |
| 3.3-V LVCMOS | GCLK | t_{SU} | 1.124 | 1.124 | 2.493 | ns |
| | | t_H | -1.019 | -1.019 | -2.216 | ns |
| | GCLK PLL | t_{SU} | 2.694 | 2.694 | 5.928 | ns |
| | | t_H | -2.589 | -2.589 | -5.651 | ns |
| 2.5 V | GCLK | t_{SU} | 1.134 | 1.134 | 2.475 | ns |
| | | t_H | -1.029 | -1.029 | -2.198 | ns |
| | GCLK PLL | t_{SU} | 2.704 | 2.704 | 5.910 | ns |
| | | t_H | -2.599 | -2.599 | -5.633 | ns |
| 1.8 V | GCLK | t_{SU} | 1.200 | 1.200 | 2.685 | ns |
| | | t_H | -1.095 | -1.095 | -2.408 | ns |
| | GCLK PLL | t_{SU} | 2.770 | 2.770 | 6.120 | ns |
| | | t_H | -2.665 | -2.665 | -5.843 | ns |
| 1.5 V | GCLK | t_{SU} | 1.203 | 1.203 | 2.778 | ns |
| | | t_H | -1.098 | -1.098 | -2.501 | ns |
| | GCLK PLL | t_{SU} | 2.773 | 2.773 | 6.213 | ns |
| | | t_H | -2.668 | -2.668 | -5.936 | ns |

Table 4–67. EP1AGX60 Column Pins Input Timing Parameters (Part 2 of 3)

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| SSTL-2 CLASS I | GCLK | t_{SU} | 0.948 | 0.948 | 1.951 | ns |
| | | t_H | -0.843 | -0.843 | -1.674 | ns |
| | GCLK PLL | t_{SU} | 2.519 | 2.519 | 5.388 | ns |
| | | t_H | -2.414 | -2.414 | -5.111 | ns |
| SSTL-2 CLASS II | GCLK | t_{SU} | 0.948 | 0.948 | 1.951 | ns |
| | | t_H | -0.843 | -0.843 | -1.674 | ns |
| | GCLK PLL | t_{SU} | 2.519 | 2.519 | 5.388 | ns |
| | | t_H | -2.414 | -2.414 | -5.111 | ns |
| SSTL-18 CLASS I | GCLK | t_{SU} | 0.986 | 0.986 | 2.057 | ns |
| | | t_H | -0.881 | -0.881 | -1.780 | ns |
| | GCLK PLL | t_{SU} | 2.556 | 2.556 | 5.492 | ns |
| | | t_H | -2.451 | -2.451 | -5.215 | ns |
| SSTL-18 CLASS II | GCLK | t_{SU} | 0.987 | 0.987 | 2.058 | ns |
| | | t_H | -0.882 | -0.882 | -1.781 | ns |
| | GCLK PLL | t_{SU} | 2.558 | 2.558 | 5.495 | ns |
| | | t_H | -2.453 | -2.453 | -5.218 | ns |
| 1.8-V HSTL CLASS I | GCLK | t_{SU} | 0.986 | 0.986 | 2.057 | ns |
| | | t_H | -0.881 | -0.881 | -1.780 | ns |
| | GCLK PLL | t_{SU} | 2.556 | 2.556 | 5.492 | ns |
| | | t_H | -2.451 | -2.451 | -5.215 | ns |
| 1.8-V HSTL CLASS II | GCLK | t_{SU} | 0.987 | 0.987 | 2.058 | ns |
| | | t_H | -0.882 | -0.882 | -1.781 | ns |
| | GCLK PLL | t_{SU} | 2.558 | 2.558 | 5.495 | ns |
| | | t_H | -2.453 | -2.453 | -5.218 | ns |
| 1.5-V HSTL CLASS I | GCLK | t_{SU} | 1.004 | 1.004 | 2.185 | ns |
| | | t_H | -0.899 | -0.899 | -1.908 | ns |
| | GCLK PLL | t_{SU} | 2.574 | 2.574 | 5.620 | ns |
| | | t_H | -2.469 | -2.469 | -5.343 | ns |

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 1.5-V HSTL CLASS II | GCLK | t_{SU} | 1.005 | 1.005 | 2.186 | ns |
| | | t_H | -0.900 | -0.900 | -1.909 | ns |
| | GCLK PLL | t_{SU} | 2.576 | 2.576 | 5.623 | ns |
| | | t_H | -2.471 | -2.471 | -5.346 | ns |
| 3.3-V PCI | GCLK | t_{SU} | 1.129 | 1.129 | 2.481 | ns |
| | | t_H | -1.024 | -1.024 | -2.204 | ns |
| | GCLK PLL | t_{SU} | 2.699 | 2.699 | 5.916 | ns |
| | | t_H | -2.594 | -2.594 | -5.639 | ns |
| 3.3-V PCI-X | GCLK | t_{SU} | 1.129 | 1.129 | 2.481 | ns |
| | | t_H | -1.024 | -1.024 | -2.204 | ns |
| | GCLK PLL | t_{SU} | 2.699 | 2.699 | 5.916 | ns |
| | | t_H | -2.594 | -2.594 | -5.639 | ns |
| LVDS | GCLK | t_{SU} | 0.980 | 0.980 | 2.062 | ns |
| | | t_H | -0.875 | -0.875 | -1.785 | ns |
| | GCLK PLL | t_{SU} | 2.557 | 2.557 | 5.512 | ns |
| | | t_H | -2.452 | -2.452 | -5.235 | ns |

Table 4–68 describes I/O timing specifications.

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 4 mA | GCLK | t_{CO} | 3.052 | 3.052 | 7.142 | ns |
| | | GCLK PLL | t_{CO} | 1.490 | 1.490 | 3.719 | ns |
| 3.3-V LVTTTL | 8 mA | GCLK | t_{CO} | 2.924 | 2.924 | 6.502 | ns |
| | | GCLK PLL | t_{CO} | 1.362 | 1.362 | 3.079 | ns |
| 3.3-V LVTTTL | 12 mA | GCLK | t_{CO} | 2.868 | 2.868 | 6.465 | ns |
| | | GCLK PLL | t_{CO} | 1.306 | 1.306 | 3.042 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 2.924 | 2.924 | 6.502 | ns |
| | | GCLK PLL | t_{CO} | 1.362 | 1.362 | 3.079 | ns |

Table 4–68. EP1AGX60 Row Pins Output Timing Parameters (Part 2 of 3)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|-----------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.818 | 2.818 | 6.196 | ns |
| | | GCLK PLL | t_{CO} | 1.256 | 1.256 | 2.773 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 2.907 | 2.907 | 6.476 | ns |
| | | GCLK PLL | t_{CO} | 1.345 | 1.345 | 3.053 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.804 | 2.804 | 6.218 | ns |
| | | GCLK PLL | t_{CO} | 1.242 | 1.242 | 2.795 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.785 | 2.785 | 6.104 | ns |
| | | GCLK PLL | t_{CO} | 1.223 | 1.223 | 2.681 | ns |
| 1.8 V | 2 mA | GCLK | t_{CO} | 2.991 | 2.991 | 7.521 | ns |
| | | GCLK PLL | t_{CO} | 1.419 | 1.419 | 4.078 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 2.980 | 2.980 | 6.742 | ns |
| | | GCLK PLL | t_{CO} | 1.408 | 1.408 | 3.299 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.869 | 2.869 | 6.441 | ns |
| | | GCLK PLL | t_{CO} | 1.297 | 1.297 | 2.998 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.838 | 2.838 | 6.327 | ns |
| | | GCLK PLL | t_{CO} | 1.266 | 1.266 | 2.884 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 2.951 | 2.951 | 7.020 | ns |
| | | GCLK PLL | t_{CO} | 1.379 | 1.379 | 3.577 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.844 | 2.844 | 6.419 | ns |
| | | GCLK PLL | t_{CO} | 1.272 | 1.272 | 2.976 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.774 | 2.774 | 6.057 | ns |
| | | GCLK PLL | t_{CO} | 1.211 | 1.211 | 2.633 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.750 | 2.750 | 5.981 | ns |
| | | GCLK PLL | t_{CO} | 1.187 | 1.187 | 2.557 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.716 | 2.716 | 5.850 | ns |
| | | GCLK PLL | t_{CO} | 1.153 | 1.153 | 2.426 | ns |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.776 | 2.776 | 6.025 | ns |
| | | GCLK PLL | t_{CO} | 1.204 | 1.204 | 2.582 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.780 | 2.780 | 5.954 | ns |
| | | GCLK PLL | t_{CO} | 1.208 | 1.208 | 2.511 | ns |

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.756 | 2.756 | 5.937 | ns |
| | | GCLK PLL | t_{CO} | 1.184 | 1.184 | 2.494 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.759 | 2.759 | 5.916 | ns |
| | | GCLK PLL | t_{CO} | 1.187 | 1.187 | 2.473 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.757 | 2.757 | 5.935 | ns |
| | | GCLK PLL | t_{CO} | 1.185 | 1.185 | 2.492 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.760 | 2.760 | 5.899 | ns |
| | | GCLK PLL | t_{CO} | 1.188 | 1.188 | 2.456 | ns |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.742 | 2.742 | 5.895 | ns |
| | | GCLK PLL | t_{CO} | 1.170 | 1.170 | 2.452 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.746 | 2.746 | 5.884 | ns |
| | | GCLK PLL | t_{CO} | 1.174 | 1.174 | 2.441 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.737 | 2.737 | 5.883 | ns |
| | | GCLK PLL | t_{CO} | 1.165 | 1.165 | 2.440 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.756 | 2.756 | 5.912 | ns |
| | | GCLK PLL | t_{CO} | 1.184 | 1.184 | 2.469 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.759 | 2.759 | 5.898 | ns |
| | | GCLK PLL | t_{CO} | 1.187 | 1.187 | 2.455 | ns |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.744 | 2.744 | 5.890 | ns |
| | | GCLK PLL | t_{CO} | 1.172 | 1.172 | 2.447 | ns |
| LVDS | - | GCLK | t_{CO} | 2.787 | 2.787 | 6.037 | ns |
| | | GCLK PLL | t_{CO} | 1.228 | 1.228 | 2.618 | ns |

Table 4–69 describes I/O timing specifications.

| IO Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 4 mA | GCLK | t_{CO} | 3.036 | 3.036 | 6.963 | ns |
| | | GCLK PLL | t_{CO} | 1.466 | 1.466 | 3.528 | ns |

Table 4–69. EP1AGX60 Column Pins Output Timing Parameters (Part 2 of 5)

| IO Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 8 mA | GCLK | t_{CO} | 2.891 | 2.891 | 6.591 | ns |
| | | GCLK PLL | t_{CO} | 1.321 | 1.321 | 3.156 | ns |
| 3.3-V LVTTTL | 12 mA | GCLK | t_{CO} | 2.824 | 2.824 | 6.591 | ns |
| | | GCLK PLL | t_{CO} | 1.254 | 1.254 | 3.156 | ns |
| 3.3-V LVTTTL | 16 mA | GCLK | t_{CO} | 2.798 | 2.798 | 6.422 | ns |
| | | GCLK PLL | t_{CO} | 1.228 | 1.228 | 2.987 | ns |
| 3.3-V LVTTTL | 20 mA | GCLK | t_{CO} | 2.776 | 2.776 | 6.297 | ns |
| | | GCLK PLL | t_{CO} | 1.206 | 1.206 | 2.862 | ns |
| 3.3-V LVTTTL | 24 mA | GCLK | t_{CO} | 2.769 | 2.769 | 6.299 | ns |
| | | GCLK PLL | t_{CO} | 1.199 | 1.199 | 2.864 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 2.891 | 2.891 | 6.591 | ns |
| | | GCLK PLL | t_{CO} | 1.321 | 1.321 | 3.156 | ns |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.799 | 2.799 | 6.296 | ns |
| | | GCLK PLL | t_{CO} | 1.229 | 1.229 | 2.861 | ns |
| 3.3-V LVCMOS | 12 mA | GCLK | t_{CO} | 2.771 | 2.771 | 6.218 | ns |
| | | GCLK PLL | t_{CO} | 1.201 | 1.201 | 2.783 | ns |
| 3.3-V LVCMOS | 16 mA | GCLK | t_{CO} | 2.778 | 2.778 | 6.186 | ns |
| | | GCLK PLL | t_{CO} | 1.208 | 1.208 | 2.751 | ns |
| 3.3-V LVCMOS | 20 mA | GCLK | t_{CO} | 2.765 | 2.765 | 6.168 | ns |
| | | GCLK PLL | t_{CO} | 1.195 | 1.195 | 2.733 | ns |
| 3.3-V LVCMOS | 24 mA | GCLK | t_{CO} | 2.754 | 2.754 | 6.146 | ns |
| | | GCLK PLL | t_{CO} | 1.184 | 1.184 | 2.711 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 2.853 | 2.853 | 6.623 | ns |
| | | GCLK PLL | t_{CO} | 1.283 | 1.283 | 3.188 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.801 | 2.801 | 6.361 | ns |
| | | GCLK PLL | t_{CO} | 1.231 | 1.231 | 2.926 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.780 | 2.780 | 6.244 | ns |
| | | GCLK PLL | t_{CO} | 1.210 | 1.210 | 2.809 | ns |
| 2.5 V | 16 mA | GCLK | t_{CO} | 2.762 | 2.762 | 6.170 | ns |
| | | GCLK PLL | t_{CO} | 1.192 | 1.192 | 2.735 | ns |

| IO Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8 V | 2 mA | GCLK | t_{CO} | 2.893 | 2.893 | 7.615 | ns |
| | | GCLK PLL | t_{CO} | 1.323 | 1.323 | 4.180 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 2.898 | 2.898 | 6.841 | ns |
| | | GCLK PLL | t_{CO} | 1.328 | 1.328 | 3.406 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.822 | 2.822 | 6.577 | ns |
| | | GCLK PLL | t_{CO} | 1.252 | 1.252 | 3.142 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.824 | 2.824 | 6.486 | ns |
| | | GCLK PLL | t_{CO} | 1.254 | 1.254 | 3.051 | ns |
| 1.8 V | 10 mA | GCLK | t_{CO} | 2.778 | 2.778 | 6.409 | ns |
| | | GCLK PLL | t_{CO} | 1.208 | 1.208 | 2.974 | ns |
| 1.8 V | 12 mA | GCLK | t_{CO} | 2.779 | 2.779 | 6.352 | ns |
| | | GCLK PLL | t_{CO} | 1.209 | 1.209 | 2.917 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 2.873 | 2.873 | 7.145 | ns |
| | | GCLK PLL | t_{CO} | 1.303 | 1.303 | 3.710 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.809 | 2.809 | 6.576 | ns |
| | | GCLK PLL | t_{CO} | 1.239 | 1.239 | 3.141 | ns |
| 1.5 V | 6 mA | GCLK | t_{CO} | 2.812 | 2.812 | 6.458 | ns |
| | | GCLK PLL | t_{CO} | 1.242 | 1.242 | 3.023 | ns |
| 1.5 V | 8 mA | GCLK | t_{CO} | 2.771 | 2.771 | 6.405 | ns |
| | | GCLK PLL | t_{CO} | 1.201 | 1.201 | 2.970 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.757 | 2.757 | 6.184 | ns |
| | | GCLK PLL | t_{CO} | 1.184 | 1.184 | 2.744 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.740 | 2.740 | 6.134 | ns |
| | | GCLK PLL | t_{CO} | 1.167 | 1.167 | 2.694 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.718 | 2.718 | 6.061 | ns |
| | | GCLK PLL | t_{CO} | 1.145 | 1.145 | 2.621 | ns |
| SSTL-2 CLASS II | 20 mA | GCLK | t_{CO} | 2.719 | 2.719 | 6.048 | ns |
| | | GCLK PLL | t_{CO} | 1.146 | 1.146 | 2.608 | ns |
| SSTL-2 CLASS II | 24 mA | GCLK | t_{CO} | 2.715 | 2.715 | 6.046 | ns |
| | | GCLK PLL | t_{CO} | 1.142 | 1.142 | 2.606 | ns |

Table 4–69. EP1AGX60 Column Pins Output Timing Parameters (Part 4 of 5)

| IO Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.753 | 2.753 | 6.155 | ns |
| | | GCLK PLL | t_{CO} | 1.183 | 1.183 | 2.720 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.758 | 2.758 | 6.116 | ns |
| | | GCLK PLL | t_{CO} | 1.185 | 1.185 | 2.676 | ns |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.737 | 2.737 | 6.097 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.657 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.742 | 2.742 | 6.095 | ns |
| | | GCLK PLL | t_{CO} | 1.169 | 1.169 | 2.655 | ns |
| SSTL-18 CLASS I | 12 mA | GCLK | t_{CO} | 2.736 | 2.736 | 6.081 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.641 | ns |
| SSTL-18 CLASS II | 8 mA | GCLK | t_{CO} | 2.725 | 2.725 | 6.047 | ns |
| | | GCLK PLL | t_{CO} | 1.152 | 1.152 | 2.607 | ns |
| SSTL-18 CLASS II | 16 mA | GCLK | t_{CO} | 2.737 | 2.737 | 6.025 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.585 | ns |
| SSTL-18 CLASS II | 18 mA | GCLK | t_{CO} | 2.733 | 2.733 | 6.033 | ns |
| | | GCLK PLL | t_{CO} | 1.160 | 1.160 | 2.593 | ns |
| SSTL-18 CLASS II | 20 mA | GCLK | t_{CO} | 2.733 | 2.733 | 6.031 | ns |
| | | GCLK PLL | t_{CO} | 1.160 | 1.160 | 2.591 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.756 | 2.756 | 6.086 | ns |
| | | GCLK PLL | t_{CO} | 1.186 | 1.186 | 2.651 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.762 | 2.762 | 6.071 | ns |
| | | GCLK PLL | t_{CO} | 1.189 | 1.189 | 2.631 | ns |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.740 | 2.740 | 6.060 | ns |
| | | GCLK PLL | t_{CO} | 1.167 | 1.167 | 2.620 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.744 | 2.744 | 6.066 | ns |
| | | GCLK PLL | t_{CO} | 1.171 | 1.171 | 2.626 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.736 | 2.736 | 6.059 | ns |
| | | GCLK PLL | t_{CO} | 1.163 | 1.163 | 2.619 | ns |
| 1.8-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.719 | 2.719 | 5.823 | ns |
| | | GCLK PLL | t_{CO} | 1.146 | 1.146 | 2.383 | ns |

| IO Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.721 | 2.721 | 5.834 | ns |
| | | GCLK PLL | t_{CO} | 1.148 | 1.148 | 2.394 | ns |
| 1.8-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.721 | 2.721 | 5.843 | ns |
| | | GCLK PLL | t_{CO} | 1.148 | 1.148 | 2.403 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.756 | 2.756 | 6.085 | ns |
| | | GCLK PLL | t_{CO} | 1.186 | 1.186 | 2.650 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.761 | 2.761 | 6.063 | ns |
| | | GCLK PLL | t_{CO} | 1.188 | 1.188 | 2.623 | ns |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.743 | 2.743 | 6.065 | ns |
| | | GCLK PLL | t_{CO} | 1.170 | 1.170 | 2.625 | ns |
| 1.5-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.743 | 2.743 | 6.067 | ns |
| | | GCLK PLL | t_{CO} | 1.170 | 1.170 | 2.627 | ns |
| 1.5-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.737 | 2.737 | 6.065 | ns |
| | | GCLK PLL | t_{CO} | 1.164 | 1.164 | 2.625 | ns |
| 1.5-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.724 | 2.724 | 5.877 | ns |
| | | GCLK PLL | t_{CO} | 1.151 | 1.151 | 2.437 | ns |
| 1.5-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.727 | 2.727 | 5.887 | ns |
| | | GCLK PLL | t_{CO} | 1.154 | 1.154 | 2.447 | ns |
| 1.5-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.729 | 2.729 | 5.900 | ns |
| | | GCLK PLL | t_{CO} | 1.156 | 1.156 | 2.460 | ns |
| 3.3-V PCI | - | GCLK | t_{CO} | 2.882 | 2.882 | 6.213 | ns |
| | | GCLK PLL | t_{CO} | 1.312 | 1.312 | 2.778 | ns |
| 3.3-V PCI-X | - | GCLK | t_{CO} | 2.882 | 2.882 | 6.213 | ns |
| | | GCLK PLL | t_{CO} | 1.312 | 1.312 | 2.778 | ns |
| LVDS | - | GCLK | t_{CO} | 3.746 | 3.746 | 7.396 | ns |
| | | GCLK PLL | t_{CO} | 2.185 | 2.185 | 3.973 | ns |

Tables 4–70 through 4–71 show EP1AGX60 regional clock (RCLK) adder values that should be added to the GCLK values. These adder values are used to determine I/O timing when the I/O pin is driven using the regional clock. This applies for all I/O standards supported by Arria GX with general purpose I/O pins.

Table 4-70 describes row pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.138 | 0.138 | 0.311 | ns |
| RCLK PLL input adder | -0.003 | -0.003 | -0.006 | ns |
| RCLK output adder | -0.138 | -0.138 | -0.311 | ns |
| RCLK PLL output adder | 0.003 | 0.003 | 0.006 | ns |

Table 4-71 describes column pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.153 | 0.153 | 0.344 | ns |
| RCLK PLL input adder | -1.066 | -1.066 | -2.338 | ns |
| RCLK output adder | -0.153 | -0.153 | -0.343 | ns |
| RCLK PLL output adder | 1.721 | 1.721 | 4.486 | ns |

EP1AGX90 I/O Timing Parameters

Tables 4–72 through 4–75 show the maximum I/O timing parameters for EP1AGX90 devices for I/O standards which support general purpose I/O pins.

Table 4–72 describes I/O timing specifications.

Table 4–72. EP1AGX90 Row Pins Input Timing Parameters (Part 1 of 3)

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 3.3-V LVTTL | GCLK | t_{SU} | 1.295 | 1.295 | 2.873 | ns |
| | | t_H | -1.190 | -1.190 | -2.596 | ns |
| | GCLK PLL | t_{SU} | 3.366 | 3.366 | 7.017 | ns |
| | | t_H | -3.261 | -3.261 | -6.740 | ns |
| 3.3-V LVCMOS | GCLK | t_{SU} | 1.295 | 1.295 | 2.873 | ns |
| | | t_H | -1.190 | -1.190 | -2.596 | ns |
| | GCLK PLL | t_{SU} | 3.366 | 3.366 | 7.017 | ns |
| | | t_H | -3.261 | -3.261 | -6.740 | ns |
| 2.5 V | GCLK | t_{SU} | 1.307 | 1.307 | 2.854 | ns |
| | | t_H | -1.202 | -1.202 | -2.577 | ns |
| | GCLK PLL | t_{SU} | 3.378 | 3.378 | 6.998 | ns |
| | | t_H | -3.273 | -3.273 | -6.721 | ns |
| 1.8 V | GCLK | t_{SU} | 1.381 | 1.381 | 3.073 | ns |
| | | t_H | -1.276 | -1.276 | -2.796 | ns |
| | GCLK PLL | t_{SU} | 3.434 | 3.434 | 7.191 | ns |
| | | t_H | -3.329 | -3.329 | -6.914 | ns |
| 1.5 V | GCLK | t_{SU} | 1.384 | 1.384 | 3.168 | ns |
| | | t_H | -1.279 | -1.279 | -2.891 | ns |
| | GCLK PLL | t_{SU} | 3.437 | 3.437 | 7.286 | ns |
| | | t_H | -3.332 | -3.332 | -7.009 | ns |
| SSTL-2 CLASS I | GCLK | t_{SU} | 1.121 | 1.121 | 2.329 | ns |
| | | t_H | -1.016 | -1.016 | -2.052 | ns |
| | GCLK PLL | t_{SU} | 3.187 | 3.187 | 6.466 | ns |
| | | t_H | -3.082 | -3.082 | -6.189 | ns |

Table 4–72. EP1AGX90 Row Pins Input Timing Parameters (Part 2 of 3)

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|------------------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| SSTL-2 CLASS II | GCLK | t_{SU} | 1.121 | 1.121 | 2.329 | ns |
| | | t_H | -1.016 | -1.016 | -2.052 | ns |
| | GCLK PLL | t_{SU} | 3.187 | 3.187 | 6.466 | ns |
| | | t_H | -3.082 | -3.082 | -6.189 | ns |
| SSTL-18 CLASS I | GCLK | t_{SU} | 1.159 | 1.159 | 2.447 | ns |
| | | t_H | -1.054 | -1.054 | -2.170 | ns |
| | GCLK PLL | t_{SU} | 3.212 | 3.212 | 6.565 | ns |
| | | t_H | -3.107 | -3.107 | -6.288 | ns |
| SSTL-18 CLASS II | GCLK | t_{SU} | 1.157 | 1.157 | 2.441 | ns |
| | | t_H | -1.052 | -1.052 | -2.164 | ns |
| | GCLK PLL | t_{SU} | 3.235 | 3.235 | 6.597 | ns |
| | | t_H | -3.130 | -3.130 | -6.320 | ns |
| 1.8-V HSTL CLASS I | GCLK | t_{SU} | 1.159 | 1.159 | 2.447 | ns |
| | | t_H | -1.054 | -1.054 | -2.170 | ns |
| | GCLK PLL | t_{SU} | 3.212 | 3.212 | 6.565 | ns |
| | | t_H | -3.107 | -3.107 | -6.288 | ns |
| 1.8-V HSTL CLASS II | GCLK | t_{SU} | 1.157 | 1.157 | 2.441 | ns |
| | | t_H | -1.052 | -1.052 | -2.164 | ns |
| | GCLK PLL | t_{SU} | 3.235 | 3.235 | 6.597 | ns |
| | | t_H | -3.130 | -3.130 | -6.320 | ns |
| 1.5-V HSTL CLASS I | GCLK | t_{SU} | 1.185 | 1.185 | 2.575 | ns |
| | | t_H | -1.080 | -1.080 | -2.298 | ns |
| | GCLK PLL | t_{SU} | 3.238 | 3.238 | 6.693 | ns |
| | | t_H | -3.133 | -3.133 | -6.416 | ns |
| 1.5-V HSTL CLASS II | GCLK | t_{SU} | 1.183 | 1.183 | 2.569 | ns |
| | | t_H | -1.078 | -1.078 | -2.292 | ns |
| | GCLK PLL | t_{SU} | 3.261 | 3.261 | 6.725 | ns |
| | | t_H | -3.156 | -3.156 | -6.448 | ns |

Table 4–72. EP1AGX90 Row Pins Input Timing Parameters (Part 3 of 3)

| I/O Standard | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------|----------|-----------|------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| LVDS | GCLK | t_{SU} | 1.098 | 1.098 | 2.439 | ns |
| | | t_H | -0.993 | -0.993 | -2.162 | ns |
| | GCLK PLL | t_{SU} | 3.160 | 3.160 | 6.566 | ns |
| | | t_H | -3.055 | -3.055 | -6.289 | ns |

Table 4–73 describes I/O timing specifications.

Table 4–73. EP1AGX90 Column Pins Input Timing Parameters (Part 1 of 3)

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 3.3-V LVTTL | GCLK | t_{SU} | 1.018 | 1.018 | 2.290 | ns |
| | | t_H | -0.913 | -0.913 | -2.013 | ns |
| | GCLK PLL | t_{SU} | 3.082 | 3.082 | 6.425 | ns |
| | | t_H | -2.977 | -2.977 | -6.148 | ns |
| 3.3-V LVCMOS | GCLK | t_{SU} | 1.018 | 1.018 | 2.290 | ns |
| | | t_H | -0.913 | -0.913 | -2.013 | ns |
| | GCLK PLL | t_{SU} | 3.082 | 3.082 | 6.425 | ns |
| | | t_H | -2.977 | -2.977 | -6.148 | ns |
| 2.5 V | GCLK | t_{SU} | 1.028 | 1.028 | 2.272 | ns |
| | | t_H | -0.923 | -0.923 | -1.995 | ns |
| | GCLK PLL | t_{SU} | 3.092 | 3.092 | 6.407 | ns |
| | | t_H | -2.987 | -2.987 | -6.130 | ns |
| 1.8 V | GCLK | t_{SU} | 1.094 | 1.094 | 2.482 | ns |
| | | t_H | -0.989 | -0.989 | -2.205 | ns |
| | GCLK PLL | t_{SU} | 3.158 | 3.158 | 6.617 | ns |
| | | t_H | -3.053 | -3.053 | -6.340 | ns |
| 1.5 V | GCLK | t_{SU} | 1.097 | 1.097 | 2.575 | ns |
| | | t_H | -0.992 | -0.992 | -2.298 | ns |
| | GCLK PLL | t_{SU} | 3.161 | 3.161 | 6.710 | ns |
| | | t_H | -3.056 | -3.056 | -6.433 | ns |

Table 4–73. EP1AGX90 Column Pins Input Timing Parameters (Part 2 of 3)

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| SSTL-2 CLASS I | GCLK | t_{SU} | 0.844 | 0.844 | 1.751 | ns |
| | | t_H | -0.739 | -0.739 | -1.474 | ns |
| | GCLK PLL | t_{SU} | 2.908 | 2.908 | 5.886 | ns |
| | | t_H | -2.803 | -2.803 | -5.609 | ns |
| SSTL-2 CLASS II | GCLK | t_{SU} | 0.844 | 0.844 | 1.751 | ns |
| | | t_H | -0.739 | -0.739 | -1.474 | ns |
| | GCLK PLL | t_{SU} | 2.908 | 2.908 | 5.886 | ns |
| | | t_H | -2.803 | -2.803 | -5.609 | ns |
| SSTL-18 CLASS I | GCLK | t_{SU} | 0.880 | 0.880 | 1.854 | ns |
| | | t_H | -0.775 | -0.775 | -1.577 | ns |
| | GCLK PLL | t_{SU} | 2.944 | 2.944 | 5.989 | ns |
| | | t_H | -2.839 | -2.839 | -5.712 | ns |
| SSTL-18 CLASS II | GCLK | t_{SU} | 0.883 | 0.883 | 1.858 | ns |
| | | t_H | -0.778 | -0.778 | -1.581 | ns |
| | GCLK PLL | t_{SU} | 2.947 | 2.947 | 5.993 | ns |
| | | t_H | -2.842 | -2.842 | -5.716 | ns |
| 1.8-V HSTL CLASS I | GCLK | t_{SU} | 0.880 | 0.880 | 1.854 | ns |
| | | t_H | -0.775 | -0.775 | -1.577 | ns |
| | GCLK PLL | t_{SU} | 2.944 | 2.944 | 5.989 | ns |
| | | t_H | -2.839 | -2.839 | -5.712 | ns |
| 1.8-V HSTL CLASS II | GCLK | t_{SU} | 0.883 | 0.883 | 1.858 | ns |
| | | t_H | -0.778 | -0.778 | -1.581 | ns |
| | GCLK PLL | t_{SU} | 2.947 | 2.947 | 5.993 | ns |
| | | t_H | -2.842 | -2.842 | -5.716 | ns |
| 1.5-V HSTL CLASS I | GCLK | t_{SU} | 0.898 | 0.898 | 1.982 | ns |
| | | t_H | -0.793 | -0.793 | -1.705 | ns |
| | GCLK PLL | t_{SU} | 2.962 | 2.962 | 6.117 | ns |
| | | t_H | -2.857 | -2.857 | -5.840 | ns |

| I/O Standard | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------|-----------|-------------|------------|----------------|-------|
| | | | Industrial | Commercial | | |
| 1.5-V HSTL CLASS II | GCLK | t_{SU} | 0.901 | 0.901 | 1.986 | ns |
| | | t_H | -0.796 | -0.796 | -1.709 | ns |
| | GCLK PLL | t_{SU} | 2.965 | 2.965 | 6.121 | ns |
| | | t_H | -2.860 | -2.860 | -5.844 | ns |
| 3.3-V PCI | GCLK | t_{SU} | 1.023 | 1.023 | 2.278 | ns |
| | | t_H | -0.918 | -0.918 | -2.001 | ns |
| | GCLK PLL | t_{SU} | 3.087 | 3.087 | 6.413 | ns |
| | | t_H | -2.982 | -2.982 | -6.136 | ns |
| 3.3-V PCI-X | GCLK | t_{SU} | 1.023 | 1.023 | 2.278 | ns |
| | | t_H | -0.918 | -0.918 | -2.001 | ns |
| | GCLK PLL | t_{SU} | 3.087 | 3.087 | 6.413 | ns |
| | | t_H | -2.982 | -2.982 | -6.136 | ns |
| LVDS | GCLK | t_{SU} | 0.891 | 0.891 | 1.920 | ns |
| | | t_H | -0.786 | -0.786 | -1.643 | ns |
| | GCLK PLL | t_{SU} | 2.963 | 2.963 | 6.066 | ns |
| | | t_H | -2.858 | -2.858 | -5.789 | ns |

Table 4–74 describes I/O timing specifications.

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 4 mA | GCLK | t_{CO} | 3.170 | 3.170 | 7.382 | ns |
| | | GCLK PLL | t_{CO} | 1.099 | 1.099 | 3.238 | ns |
| 3.3-V LVTTTL | 8 mA | GCLK | t_{CO} | 3.042 | 3.042 | 6.742 | ns |
| | | GCLK PLL | t_{CO} | 0.971 | 0.971 | 2.598 | ns |
| 3.3-V LVTTTL | 12 mA | GCLK | t_{CO} | 2.986 | 2.986 | 6.705 | ns |
| | | GCLK PLL | t_{CO} | 0.915 | 0.915 | 2.561 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 3.042 | 3.042 | 6.742 | ns |
| | | GCLK PLL | t_{CO} | 0.971 | 0.971 | 2.598 | ns |

Table 4–74. EP1AGX90 Row Pins Output Timing Parameters (Part 2 of 3)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|-----------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.936 | 2.936 | 6.436 | ns |
| | | GCLK PLL | t_{CO} | 0.865 | 0.865 | 2.292 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 3.025 | 3.025 | 6.716 | ns |
| | | GCLK PLL | t_{CO} | 0.954 | 0.954 | 2.572 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.922 | 2.922 | 6.458 | ns |
| | | GCLK PLL | t_{CO} | 0.851 | 0.851 | 2.314 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.903 | 2.903 | 6.344 | ns |
| | | GCLK PLL | t_{CO} | 0.832 | 0.832 | 2.200 | ns |
| 1.8 V | 2 mA | GCLK | t_{CO} | 3.087 | 3.087 | 7.723 | ns |
| | | GCLK PLL | t_{CO} | 1.034 | 1.034 | 3.605 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 3.076 | 3.076 | 6.944 | ns |
| | | GCLK PLL | t_{CO} | 1.023 | 1.023 | 2.826 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.965 | 2.965 | 6.643 | ns |
| | | GCLK PLL | t_{CO} | 0.912 | 0.912 | 2.525 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.934 | 2.934 | 6.529 | ns |
| | | GCLK PLL | t_{CO} | 0.881 | 0.881 | 2.411 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 3.047 | 3.047 | 7.222 | ns |
| | | GCLK PLL | t_{CO} | 0.994 | 0.994 | 3.104 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.940 | 2.940 | 6.621 | ns |
| | | GCLK PLL | t_{CO} | 0.887 | 0.887 | 2.503 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.890 | 2.890 | 6.294 | ns |
| | | GCLK PLL | t_{CO} | 0.824 | 0.824 | 2.157 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.866 | 2.866 | 6.218 | ns |
| | | GCLK PLL | t_{CO} | 0.800 | 0.800 | 2.081 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.832 | 2.832 | 6.087 | ns |
| | | GCLK PLL | t_{CO} | 0.766 | 0.766 | 1.950 | ns |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.872 | 2.872 | 6.227 | ns |
| | | GCLK PLL | t_{CO} | 0.819 | 0.819 | 2.109 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.878 | 2.878 | 6.162 | ns |
| | | GCLK PLL | t_{CO} | 0.800 | 0.800 | 2.006 | ns |

Table 4–74. EP1AGX90 Row Pins Output Timing Parameters (Part 3 of 3)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Model | | -6 Speed Grade | Units |
|--------------------|----------------|----------|-----------|------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.854 | 2.854 | 6.145 | ns |
| | | GCLK PLL | t_{CO} | 0.776 | 0.776 | 1.989 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.857 | 2.857 | 6.124 | ns |
| | | GCLK PLL | t_{CO} | 0.779 | 0.779 | 1.968 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.853 | 2.853 | 6.137 | ns |
| | | GCLK PLL | t_{CO} | 0.800 | 0.800 | 2.019 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.858 | 2.858 | 6.107 | ns |
| | | GCLK PLL | t_{CO} | 0.780 | 0.780 | 1.951 | ns |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.840 | 2.840 | 6.103 | ns |
| | | GCLK PLL | t_{CO} | 0.762 | 0.762 | 1.947 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.844 | 2.844 | 6.092 | ns |
| | | GCLK PLL | t_{CO} | 0.766 | 0.766 | 1.936 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.835 | 2.835 | 6.091 | ns |
| | | GCLK PLL | t_{CO} | 0.757 | 0.757 | 1.935 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.852 | 2.852 | 6.114 | ns |
| | | GCLK PLL | t_{CO} | 0.799 | 0.799 | 1.996 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.857 | 2.857 | 6.106 | ns |
| | | GCLK PLL | t_{CO} | 0.779 | 0.779 | 1.950 | ns |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.842 | 2.842 | 6.098 | ns |
| | | GCLK PLL | t_{CO} | 0.764 | 0.764 | 1.942 | ns |
| LVDS | - | GCLK | t_{CO} | 2.898 | 2.898 | 6.265 | ns |
| | | GCLK PLL | t_{CO} | 0.831 | 0.831 | 2.129 | ns |

Table 4–75 describes I/O timing specifications.

Table 4–75. EP1AGX90 Column Pins Output Timing Parameters (Part 1 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 4 mA | GCLK | t_{CO} | 3.141 | 3.141 | 7.164 | ns |
| | | GCLK PLL | t_{CO} | 1.077 | 1.077 | 3.029 | ns |

Table 4–75. EP1AGX90 Column Pins Output Timing Parameters (Part 2 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|--------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 3.3-V LVTTTL | 8 mA | GCLK | t_{CO} | 2.996 | 2.996 | 6.792 | ns |
| | | GCLK PLL | t_{CO} | 0.932 | 0.932 | 2.657 | ns |
| 3.3-V LVTTTL | 12 mA | GCLK | t_{CO} | 2.929 | 2.929 | 6.792 | ns |
| | | GCLK PLL | t_{CO} | 0.865 | 0.865 | 2.657 | ns |
| 3.3-V LVTTTL | 16 mA | GCLK | t_{CO} | 2.903 | 2.903 | 6.623 | ns |
| | | GCLK PLL | t_{CO} | 0.839 | 0.839 | 2.488 | ns |
| 3.3-V LVTTTL | 20 mA | GCLK | t_{CO} | 2.881 | 2.881 | 6.498 | ns |
| | | GCLK PLL | t_{CO} | 0.817 | 0.817 | 2.363 | ns |
| 3.3-V LVTTTL | 24 mA | GCLK | t_{CO} | 2.874 | 2.874 | 6.500 | ns |
| | | GCLK PLL | t_{CO} | 0.810 | 0.810 | 2.365 | ns |
| 3.3-V LVCMOS | 4 mA | GCLK | t_{CO} | 2.996 | 2.996 | 6.792 | ns |
| | | GCLK PLL | t_{CO} | 0.932 | 0.932 | 2.657 | ns |
| 3.3-V LVCMOS | 8 mA | GCLK | t_{CO} | 2.904 | 2.904 | 6.497 | ns |
| | | GCLK PLL | t_{CO} | 0.840 | 0.840 | 2.362 | ns |
| 3.3-V LVCMOS | 12 mA | GCLK | t_{CO} | 2.876 | 2.876 | 6.419 | ns |
| | | GCLK PLL | t_{CO} | 0.812 | 0.812 | 2.284 | ns |
| 3.3-V LVCMOS | 16 mA | GCLK | t_{CO} | 2.883 | 2.883 | 6.387 | ns |
| | | GCLK PLL | t_{CO} | 0.819 | 0.819 | 2.252 | ns |
| 3.3-V LVCMOS | 20 mA | GCLK | t_{CO} | 2.870 | 2.870 | 6.369 | ns |
| | | GCLK PLL | t_{CO} | 0.806 | 0.806 | 2.234 | ns |
| 3.3-V LVCMOS | 24 mA | GCLK | t_{CO} | 2.859 | 2.859 | 6.347 | ns |
| | | GCLK PLL | t_{CO} | 0.795 | 0.795 | 2.212 | ns |
| 2.5 V | 4 mA | GCLK | t_{CO} | 2.958 | 2.958 | 6.824 | ns |
| | | GCLK PLL | t_{CO} | 0.894 | 0.894 | 2.689 | ns |
| 2.5 V | 8 mA | GCLK | t_{CO} | 2.906 | 2.906 | 6.562 | ns |
| | | GCLK PLL | t_{CO} | 0.842 | 0.842 | 2.427 | ns |
| 2.5 V | 12 mA | GCLK | t_{CO} | 2.885 | 2.885 | 6.445 | ns |
| | | GCLK PLL | t_{CO} | 0.821 | 0.821 | 2.310 | ns |
| 2.5 V | 16 mA | GCLK | t_{CO} | 2.867 | 2.867 | 6.371 | ns |
| | | GCLK PLL | t_{CO} | 0.803 | 0.803 | 2.236 | ns |

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8 V | 2 mA | GCLK | t_{CO} | 2.998 | 2.998 | 7.816 | ns |
| | | GCLK PLL | t_{CO} | 0.934 | 0.934 | 3.681 | ns |
| 1.8 V | 4 mA | GCLK | t_{CO} | 3.003 | 3.003 | 7.042 | ns |
| | | GCLK PLL | t_{CO} | 0.939 | 0.939 | 2.907 | ns |
| 1.8 V | 6 mA | GCLK | t_{CO} | 2.927 | 2.927 | 6.778 | ns |
| | | GCLK PLL | t_{CO} | 0.863 | 0.863 | 2.643 | ns |
| 1.8 V | 8 mA | GCLK | t_{CO} | 2.929 | 2.929 | 6.687 | ns |
| | | GCLK PLL | t_{CO} | 0.865 | 0.865 | 2.552 | ns |
| 1.8 V | 10 mA | GCLK | t_{CO} | 2.883 | 2.883 | 6.610 | ns |
| | | GCLK PLL | t_{CO} | 0.819 | 0.819 | 2.475 | ns |
| 1.8 V | 12 mA | GCLK | t_{CO} | 2.884 | 2.884 | 6.553 | ns |
| | | GCLK PLL | t_{CO} | 0.820 | 0.820 | 2.418 | ns |
| 1.5 V | 2 mA | GCLK | t_{CO} | 2.978 | 2.978 | 7.346 | ns |
| | | GCLK PLL | t_{CO} | 0.914 | 0.914 | 3.211 | ns |
| 1.5 V | 4 mA | GCLK | t_{CO} | 2.914 | 2.914 | 6.777 | ns |
| | | GCLK PLL | t_{CO} | 0.850 | 0.850 | 2.642 | ns |
| 1.5 V | 6 mA | GCLK | t_{CO} | 2.917 | 2.917 | 6.659 | ns |
| | | GCLK PLL | t_{CO} | 0.853 | 0.853 | 2.524 | ns |
| 1.5 V | 8 mA | GCLK | t_{CO} | 2.876 | 2.876 | 6.606 | ns |
| | | GCLK PLL | t_{CO} | 0.812 | 0.812 | 2.471 | ns |
| SSTL-2 CLASS I | 8 mA | GCLK | t_{CO} | 2.859 | 2.859 | 6.381 | ns |
| | | GCLK PLL | t_{CO} | 0.797 | 0.797 | 2.250 | ns |
| SSTL-2 CLASS I | 12 mA | GCLK | t_{CO} | 2.842 | 2.842 | 6.331 | ns |
| | | GCLK PLL | t_{CO} | 0.780 | 0.780 | 2.200 | ns |
| SSTL-2 CLASS II | 16 mA | GCLK | t_{CO} | 2.820 | 2.820 | 6.258 | ns |
| | | GCLK PLL | t_{CO} | 0.758 | 0.758 | 2.127 | ns |
| SSTL-2 CLASS II | 20 mA | GCLK | t_{CO} | 2.821 | 2.821 | 6.245 | ns |
| | | GCLK PLL | t_{CO} | 0.759 | 0.759 | 2.114 | ns |
| SSTL-2 CLASS II | 24 mA | GCLK | t_{CO} | 2.817 | 2.817 | 6.243 | ns |
| | | GCLK PLL | t_{CO} | 0.755 | 0.755 | 2.112 | ns |

Table 4–75. EP1AGX90 Column Pins Output Timing Parameters (Part 4 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| SSTL-18 CLASS I | 4 mA | GCLK | t_{CO} | 2.858 | 2.858 | 6.356 | ns |
| | | GCLK PLL | t_{CO} | 0.794 | 0.794 | 2.221 | ns |
| SSTL-18 CLASS I | 6 mA | GCLK | t_{CO} | 2.860 | 2.860 | 6.313 | ns |
| | | GCLK PLL | t_{CO} | 0.798 | 0.798 | 2.182 | ns |
| SSTL-18 CLASS I | 8 mA | GCLK | t_{CO} | 2.839 | 2.839 | 6.294 | ns |
| | | GCLK PLL | t_{CO} | 0.777 | 0.777 | 2.163 | ns |
| SSTL-18 CLASS I | 10 mA | GCLK | t_{CO} | 2.844 | 2.844 | 6.292 | ns |
| | | GCLK PLL | t_{CO} | 0.782 | 0.782 | 2.161 | ns |
| SSTL-18 CLASS I | 12 mA | GCLK | t_{CO} | 2.838 | 2.838 | 6.278 | ns |
| | | GCLK PLL | t_{CO} | 0.776 | 0.776 | 2.147 | ns |
| SSTL-18 CLASS II | 8 mA | GCLK | t_{CO} | 2.827 | 2.827 | 6.244 | ns |
| | | GCLK PLL | t_{CO} | 0.765 | 0.765 | 2.113 | ns |
| SSTL-18 CLASS II | 16 mA | GCLK | t_{CO} | 2.839 | 2.839 | 6.222 | ns |
| | | GCLK PLL | t_{CO} | 0.777 | 0.777 | 2.091 | ns |
| SSTL-18 CLASS II | 18 mA | GCLK | t_{CO} | 2.835 | 2.835 | 6.230 | ns |
| | | GCLK PLL | t_{CO} | 0.773 | 0.773 | 2.099 | ns |
| SSTL-18 CLASS II | 20 mA | GCLK | t_{CO} | 2.835 | 2.835 | 6.228 | ns |
| | | GCLK PLL | t_{CO} | 0.773 | 0.773 | 2.097 | ns |
| 1.8-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.861 | 2.861 | 6.287 | ns |
| | | GCLK PLL | t_{CO} | 0.797 | 0.797 | 2.152 | ns |
| 1.8-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.864 | 2.864 | 6.268 | ns |
| | | GCLK PLL | t_{CO} | 0.802 | 0.802 | 2.137 | ns |
| 1.8-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.842 | 2.842 | 6.257 | ns |
| | | GCLK PLL | t_{CO} | 0.780 | 0.780 | 2.126 | ns |
| 1.8-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.846 | 2.846 | 6.263 | ns |
| | | GCLK PLL | t_{CO} | 0.784 | 0.784 | 2.132 | ns |
| 1.8-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.838 | 2.838 | 6.256 | ns |
| | | GCLK PLL | t_{CO} | 0.776 | 0.776 | 2.125 | ns |
| 1.8-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.821 | 2.821 | 6.020 | ns |
| | | GCLK PLL | t_{CO} | 0.759 | 0.759 | 1.889 | ns |

Table 4–75. EP1AGX90 Column Pins Output Timing Parameters (Part 5 of 5)

| I/O Standard | Drive Strength | Clock | Parameter | Fast Corner | | -6 Speed Grade | Units |
|---------------------|----------------|----------|-----------|-------------|------------|----------------|-------|
| | | | | Industrial | Commercial | | |
| 1.8-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.823 | 2.823 | 6.031 | ns |
| | | GCLK PLL | t_{CO} | 0.761 | 0.761 | 1.900 | ns |
| 1.8-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.823 | 2.823 | 6.040 | ns |
| | | GCLK PLL | t_{CO} | 0.761 | 0.761 | 1.909 | ns |
| 1.5-V HSTL CLASS I | 4 mA | GCLK | t_{CO} | 2.861 | 2.861 | 6.286 | ns |
| | | GCLK PLL | t_{CO} | 0.797 | 0.797 | 2.151 | ns |
| 1.5-V HSTL CLASS I | 6 mA | GCLK | t_{CO} | 2.863 | 2.863 | 6.260 | ns |
| | | GCLK PLL | t_{CO} | 0.801 | 0.801 | 2.129 | ns |
| 1.5-V HSTL CLASS I | 8 mA | GCLK | t_{CO} | 2.845 | 2.845 | 6.262 | ns |
| | | GCLK PLL | t_{CO} | 0.783 | 0.783 | 2.131 | ns |
| 1.5-V HSTL CLASS I | 10 mA | GCLK | t_{CO} | 2.845 | 2.845 | 6.264 | ns |
| | | GCLK PLL | t_{CO} | 0.783 | 0.783 | 2.133 | ns |
| 1.5-V HSTL CLASS I | 12 mA | GCLK | t_{CO} | 2.839 | 2.839 | 6.262 | ns |
| | | GCLK PLL | t_{CO} | 0.777 | 0.777 | 2.131 | ns |
| 1.5-V HSTL CLASS II | 16 mA | GCLK | t_{CO} | 2.826 | 2.826 | 6.074 | ns |
| | | GCLK PLL | t_{CO} | 0.764 | 0.764 | 1.943 | ns |
| 1.5-V HSTL CLASS II | 18 mA | GCLK | t_{CO} | 2.829 | 2.829 | 6.084 | ns |
| | | GCLK PLL | t_{CO} | 0.767 | 0.767 | 1.953 | ns |
| 1.5-V HSTL CLASS II | 20 mA | GCLK | t_{CO} | 2.831 | 2.831 | 6.097 | ns |
| | | GCLK PLL | t_{CO} | 0.769 | 0.769 | 1.966 | ns |
| 3.3-V PCI | - | GCLK | t_{CO} | 2.987 | 2.987 | 6.414 | ns |
| | | GCLK PLL | t_{CO} | 0.923 | 0.923 | 2.279 | ns |
| 3.3-V PCI-X | - | GCLK | t_{CO} | 2.987 | 2.987 | 6.414 | ns |
| | | GCLK PLL | t_{CO} | 0.923 | 0.923 | 2.279 | ns |
| LVDS | - | GCLK | t_{CO} | 3.835 | 3.835 | 7.541 | ns |
| | | GCLK PLL | t_{CO} | 1.769 | 1.769 | 3.404 | ns |

Tables 4–76 through 4–77 show the EP1AGX90 regional clock (RCLK) adder values that should be added to the GCLK values. These adder values are used to determine I/O timing when the I/O pin is driven using the regional clock. This applies for all I/O standards supported by Arria GX with general purpose I/O pins.

Table 4-76 describes row pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.175 | 0.175 | 0.418 | ns |
| RCLK PLL input adder | 0.007 | 0.007 | 0.015 | ns |
| RCLK output adder | -0.175 | -0.175 | -0.418 | ns |
| RCLK PLL output adder | -0.007 | -0.007 | -0.015 | ns |

Table 4-77 describes column pin delay adders when using the regional clock in Arria GX devices.

| Parameter | Fast Corner | | -6 Speed Grade | Units |
|-----------------------|-------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| RCLK input adder | 0.138 | 0.138 | 0.354 | ns |
| RCLK PLL input adder | -1.697 | -1.697 | -3.607 | ns |
| RCLK output adder | -0.138 | -0.138 | -0.353 | ns |
| RCLK PLL output adder | 1.966 | 1.966 | 5.188 | ns |

Dedicated Clock Pin Timing

Tables 4–79 to 4–98 show clock pin timing for Arria GX devices when the clock is driven by the global clock, regional clock, periphery clock, and a PLL.

Tables 4–78 describes Arria GX clock timing parameters.

| Table 4–78. Arria GX Clock Timing Parameters | |
|---|---|
| Symbol | Parameter |
| t_{CIN} | Delay from clock pad to I/O input register |
| t_{COUT} | Delay from clock pad to I/O output register |
| t_{PLLCIN} | Delay from PLL inclk pad to I/O input register |
| $t_{PLLCOUT}$ | Delay from PLL inclk pad to I/O output register |

EP1AGX20 Clock Timing Parameters

Tables 4–79 through 4–80 show the GCLK clock timing parameters for EP1AGX20 devices.

Table 4–79 describes clock timing specifications.

| Table 4–79. EP1AGX20 Row Pins Global Clock Timing Parameters | | | | |
|---|-------------------|-------------------|-----------------------|--------------|
| Parameter | Fast Model | | -6 Speed Grade | Units |
| | Industrial | Commercial | | |
| t_{cin} | 1.394 | 1.394 | 3.161 | ns |
| t_{cout} | 1.399 | 1.399 | 3.155 | ns |
| t_{pllcin} | -0.027 | -0.027 | 0.091 | ns |
| $t_{pllcout}$ | -0.022 | -0.022 | 0.085 | ns |

Table 4–80 describes clock timing specifications.

| Table 4–80. EP1AGX20 Row Pins Global Clock Timing Parameters (Part 1) | | | | |
|--|-------------------|-------------------|-----------------------|--------------|
| Parameter | Fast Model | | -6 Speed Grade | Units |
| | Industrial | Commercial | | |
| t_{CIN} | 1.655 | 1.655 | 3.726 | ns |
| t_{COUT} | 1.655 | 1.655 | 3.726 | ns |

Table 4–80. EP1AGX20 Row Pins Global Clock Timing Parameters (Part 2)

| Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{PLLCIN} | 0.236 | 0.236 | 0.655 | ns |
| t_{PLLCOUT} | 0.236 | 0.236 | 0.655 | ns |

Tables 4–81 through 4–82 show the RCLK clock timing parameters for EP1AGX20 devices.

Table 4–81 describes clock timing specifications.

Table 4–81. EP1AGX20 Row Pins Regional Clock Timing Parameters

| Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.283 | 1.283 | 2.901 | ns |
| t_{COUT} | 1.288 | 1.288 | 2.895 | ns |
| t_{PLLCIN} | -0.034 | -0.034 | 0.077 | ns |
| t_{PLLCOUT} | -0.029 | -0.029 | 0.071 | ns |

Table 4–82 describes clock timing specifications.

Table 4–82. EP1AGX20 Row Pins Regional Clock Timing Parameters

| Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.569 | 1.569 | 3.487 | ns |
| t_{COUT} | 1.569 | 1.569 | 3.487 | ns |
| t_{PLLCIN} | 0.278 | 0.278 | 0.706 | ns |
| t_{PLLCOUT} | 0.278 | 0.278 | 0.706 | ns |

EP1AGX35 Clock Timing Parameters

Tables 4–83 through 4–84 show the GCLK clock timing parameters for EP1AGX35 devices.

Table 4–83 describes clock timing specifications.

| Parameter | Fast Model | | -6 Speed Grade | Units |
|---------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.394 | 1.394 | 3.161 | ns |
| t_{COUT} | 1.399 | 1.399 | 3.155 | ns |
| t_{PLLCIN} | -0.027 | -0.027 | 0.091 | ns |
| $t_{PLLCOUT}$ | -0.022 | -0.022 | 0.085 | ns |

Table 4–84 describes clock timing specifications.

| Parameter | Fast Model | | -6 Speed Grade | Units |
|---------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.655 | 1.655 | 3.726 | ns |
| t_{COUT} | 1.655 | 1.655 | 3.726 | ns |
| t_{PLLCIN} | 0.236 | 0.236 | 0.655 | ns |
| $t_{PLLCOUT}$ | 0.236 | 0.236 | 0.655 | ns |

Tables 4–85 through 4–86 show the RCLK clock timing parameters for EP1AGX35 devices.

Table 4–85 describes clock timing specifications.

| Parameter | Fast Model | | -6 Speed Grade | Units |
|------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.283 | 1.283 | 2.901 | ns |
| t_{COUT} | 1.288 | 1.288 | 2.895 | ns |

Table 4–85. EP1AGX35 Row Pins Regional Clock Timing Parameters (Part)

| Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{PLLCIN} | -0.034 | -0.034 | 0.077 | ns |
| t_{PLLCOUT} | -0.029 | -0.029 | 0.071 | ns |

Table 4–86 describes clock timing specifications.

Table 4–86. EP1AGX35 Row Pins Regional Clock Timing Parameters

| Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.569 | 1.569 | 3.487 | ns |
| t_{COUT} | 1.569 | 1.569 | 3.487 | ns |
| t_{PLLCIN} | 0.278 | 0.278 | 0.706 | ns |
| t_{PLLCOUT} | 0.278 | 0.278 | 0.706 | ns |

EP1AGX50 Clock Timing Parameters

Tables 4–87 through 4–88 show the GCLK clock timing parameters for EP1AGX50 devices.

Table 4–87 describes clock timing specifications.

Table 4–87. EP1AGX50 Row Pins Global Clock Timing Parameters

| Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.529 | 1.529 | 3.587 | ns |
| t_{COUT} | 1.534 | 1.534 | 3.581 | ns |
| t_{PLLCIN} | -0.024 | -0.024 | 0.181 | ns |
| t_{PLLCOUT} | -0.019 | -0.019 | 0.175 | ns |

Table 4–88 describes clock timing specifications.

| Table 4–88. EP1AGX50 Row Pins Global Clock Timing Parameters | | | | |
|---|-------------------|-------------------|-----------------------|--------------|
| Parameter | Fast Model | | -6 Speed Grade | Units |
| | Industrial | Commercial | | |
| t_{CIN} | 1.793 | 1.793 | 4.165 | ns |
| t_{COUT} | 1.793 | 1.793 | 4.165 | ns |
| t_{PLLCIN} | 0.238 | 0.238 | 0.758 | ns |
| $t_{PLLCOUT}$ | 0.238 | 0.238 | 0.758 | ns |

Tables 4–89 through 4–90 show the RCLK clock timing parameters for EP1AGX50 devices.

Table 4–89 describes clock timing specifications.

| Table 4–89. EP1AGX50 Row Pins Regional Clock Timing Parameters | | | | |
|---|-------------------|-------------------|-----------------------|--------------|
| Parameter | Fast Model | | -6 Speed Grade | Units |
| | Industrial | Commercial | | |
| t_{CIN} | 1.396 | 1.396 | 3.287 | ns |
| t_{COUT} | 1.401 | 1.401 | 3.281 | ns |
| t_{PLLCIN} | -0.017 | -0.017 | 0.195 | ns |
| $t_{PLLCOUT}$ | -0.012 | -0.012 | 0.189 | ns |

Table 4–90 describes clock timing specifications.

| Table 4–90. EP1AGX50 Row Pins Regional Clock Timing Parameters | | | | |
|---|-------------------|-------------------|-----------------------|--------------|
| Parameter | Fast Model | | -6 Speed Grade | Units |
| | Industrial | Commercial | | |
| t_{CIN} | 1.653 | 1.653 | 3.841 | ns |
| t_{COUT} | 1.651 | 1.651 | 3.839 | ns |
| t_{PLLCIN} | 0.245 | 0.245 | 0.755 | ns |
| $t_{PLLCOUT}$ | 0.245 | 0.245 | 0.755 | ns |

EP1AGX60 Clock Timing Parameters

Tables 4–91 through 4–92 show the GCLK clock timing parameters for EP1AGX60 devices.

Table 4–91 describes clock timing specifications.

| Parameter | Fast Model | | -6 Speed Grade | Units |
|---------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.531 | 1.531 | 3.593 | ns |
| t_{COUT} | 1.536 | 1.536 | 3.587 | ns |
| t_{PLLCIN} | -0.023 | -0.023 | 0.188 | ns |
| $t_{PLLCOUT}$ | -0.018 | -0.018 | 0.182 | ns |

Table 4–92 describes clock timing specifications.

| Parameter | Fast Model | | -6 Speed Grade | Units |
|---------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.792 | 1.792 | 4.165 | ns |
| t_{COUT} | 1.792 | 1.792 | 4.165 | ns |
| t_{PLLCIN} | 0.238 | 0.238 | 0.758 | ns |
| $t_{PLLCOUT}$ | 0.238 | 0.238 | 0.758 | ns |

Tables 4–93 through 4–94 show the RCLK clock timing parameters for EP1AGX60 devices.

Table 4–93 describes clock timing specifications.

| Parameter | Fast Model | | -6 Speed Grade | Units |
|------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.382 | 1.382 | 3.268 | ns |
| t_{COUT} | 1.387 | 1.387 | 3.262 | ns |

Table 4–93. EP1AGX60 Row Pins Regional Clock Timing Parameters (Part)

| Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{PLLCIN} | -0.031 | -0.031 | 0.174 | ns |
| t_{PLLCOUT} | -0.026 | -0.026 | 0.168 | ns |

Table 4–94 describes clock timing specifications.

Table 4–94. EP1AGX60 Row Pins Regional Clock Timing Parameters

| Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.649 | 1.649 | 3.835 | ns |
| t_{COUT} | 1.651 | 1.651 | 3.839 | ns |
| t_{PLLCIN} | 0.245 | 0.245 | 0.755 | ns |
| t_{PLLCOUT} | 0.245 | 0.245 | 0.755 | ns |

EP1AGX90 Clock Timing Parameters

Tables 4–95 through 4–96 show the GCLK clock timing parameters for EP1AGX90 devices.

Table 4–95 describes clock timing specifications.

Table 4–95. EP1AGX90 Row Pins Global Clock Timing Parameters

| Parameter | Fast Model | | -6 Speed Grade | Units |
|----------------------|------------|------------|----------------|-------|
| | Industrial | Commercial | | |
| t_{CIN} | 1.630 | 1.630 | 3.799 | ns |
| t_{COUT} | 1.635 | 1.635 | 3.793 | ns |
| t_{PLLCIN} | -0.422 | -0.422 | -0.310 | ns |
| t_{PLLCOUT} | -0.417 | -0.417 | -0.316 | ns |

Table 4–96 describes clock timing specifications.

| Table 4–96. EP1AGX90 Row Pins Global Clock Timing Parameters | | | | |
|---|-------------------|-------------------|-----------------------|--------------|
| Parameter | Fast Model | | -6 Speed Grade | Units |
| | Industrial | Commercial | | |
| t_{CIN} | 1.904 | 1.904 | 4.376 | ns |
| t_{COUT} | 1.904 | 1.904 | 4.376 | ns |
| t_{PLLCIN} | -0.153 | -0.153 | 0.254 | ns |
| $t_{PLLCOUT}$ | -0.153 | -0.153 | 0.254 | ns |

Tables 4–97 through 4–98 show the RCLK clock timing parameters for EP1AGX90 devices.

Table 4–97 describes clock timing specifications.

| Table 4–97. EP1AGX90 Row Pins Regional Clock Timing Parameters | | | | |
|---|-------------------|-------------------|-----------------------|--------------|
| Parameter | Fast Model | | -6 Speed Grade | Units |
| | Industrial | Commercial | | |
| t_{CIN} | 1.462 | 1.462 | 3.407 | ns |
| t_{COUT} | 1.467 | 1.467 | 3.401 | ns |
| t_{PLLCIN} | -0.430 | -0.430 | -0.322 | ns |
| $t_{PLLCOUT}$ | -0.425 | -0.425 | -0.328 | ns |

Table 4–98 describes clock timing specifications.

| Table 4–98. EP1AGX90 Row Pins Regional Clock Timing Parameters | | | | |
|---|-------------------|-------------------|-----------------------|--------------|
| Parameter | Fast Model | | -6 Speed Grade | Units |
| | Industrial | Commercial | | |
| t_{CIN} | 1.760 | 1.760 | 4.011 | ns |
| t_{COUT} | 1.760 | 1.760 | 4.011 | ns |
| t_{PLLCIN} | -0.118 | -0.118 | 0.303 | ns |
| $t_{PLLCOUT}$ | -0.118 | -0.118 | 0.303 | ns |

Block Performance

Table 4–99 shows the Arria GX performance for some common designs. All performance values were obtained with the Quartus II software compilation of library of parameterized modules (LPM) or MegaCore functions for finite impulse response (FIR) and fast Fourier transform (FFT) designs.

Table 4–99 describes performance notes.

| Applications | | Resources Used | | | Performance |
|-----------------------------|-----------------------------------|----------------|-------------------------|------------|----------------|
| | | ALUTs | TriMatrix Memory Blocks | DSP Blocks | -6 Speed Grade |
| LE | 16-to-1 multiplexer | 5 | 0 | 0 | 168.41 |
| | 32-to-1 multiplexer | 11 | 0 | 0 | 334.11 |
| | 16-bit counter | 16 | 0 | 0 | 374.0 |
| | 64-bit counter | 64 | 0 | 0 | 168.41 |
| TriMatrix Memory M512 block | Simple dual-port RAM 32 x 18 bit | 0 | 1 | 0 | 348.0 |
| | FIFO 32 x 18 bit | 0 | 1 | 0 | 333.22 |
| TriMatrix Memory M4K block | Simple dual-port RAM 128 x 36 bit | 0 | 1 | 0 | 344.71 |
| | True dual-port RAM 128 x 18 bit | 0 | 1 | 0 | 348.0 |

Table 4–99. Arria GX Performance Notes (Part 2 of 3)

| Applications | | Resources Used | | | Performance |
|--------------------------------|-----------------------------------|----------------|-------------------------|------------|----------------|
| | | ALUTs | TriMatrix Memory Blocks | DSP Blocks | -6 Speed Grade |
| TriMatrix Memory MegaRAM block | Single port RAM 4K x 144 bit | 0 | 2 | 0 | 244.0 |
| | Simple dual-port RAM 4K x 144 bit | 0 | 1 | 0 | 292.0 |
| | True dual-port RAM 4K x 144 bit | 0 | 2 | 0 | 244.0 |
| | Single port RAM 8K x 72 bit | 0 | 1 | 0 | 247.0 |
| | Simple dual-port RAM 8K x 72 bit | 0 | 1 | 0 | 292.0 |
| | Single port RAM 16K x 36 bit | 0 | 1 | 0 | 254.0 |
| | Simple dual-port RAM 16K x 36 bit | 0 | 1 | 0 | 292.0 |
| | True dual-port RAM 16K x 36 bit | 0 | 1 | 0 | 251.0 |
| | Single port RAM 32K x 18 bit | 0 | 1 | 0 | 317.36 |
| | Simple dual-port RAM 32K x 18 bit | 0 | 1 | 0 | 292.0 |
| | True dual-port RAM 32K x 18 bit | 0 | 1 | 0 | 251.0 |
| | Single port RAM 64K x 9 bit | 0 | 1 | 0 | 254.0 |
| | Simple dual-port RAM 64K x 9 bit | 0 | 1 | 0 | 292.0 |
| | True dual-port RAM 64K x 9 bit | 0 | 1 | 0 | 251.0 |

Table 4–99. Arria GX Performance Notes (Part 3 of 3)

| Applications | | Resources Used | | | Performance |
|----------------|----------------------------------|----------------|-------------------------|------------|----------------|
| | | ALUTs | TriMatrix Memory Blocks | DSP Blocks | -6 Speed Grade |
| DSP block | 9 x 9-bit multiplier | 0 | 0 | 1 | 335.35 |
| | 18 x 18-bit multiplier | 0 | 0 | 2 | 285.0 |
| | 18 x 18-bit multiplier | 0 | 0 | 4 | 335.35 |
| | 36 x 36-bit multiplier | 0 | 0 | 8 | 174.4 |
| | 36 x 36-bit multiplier | 0 | 0 | 8 | 285.0 |
| | 18-bit 4-tap FIR filter | 0 | 0 | 8 | 163.0 |
| Larger Designs | 8-bit 16-tap parallel FIR filter | 0 | 0 | 4 | 163.0 |

IOE Programmable Delay

Refer to [Tables 4–100 to 4–101](#) for IOE programmable delay.

[Table 4–100](#) describes IOE programmable delays.

Table 4–100. Arria GX IOE Programmable Delay on Row Pins (Part 1 of 2)

| Parameter | Paths Affected | Available Settings | Fast Model | | | | -6 Speed Grade | | Units |
|--|----------------------------|--------------------|------------|------------|------------|------------|----------------|------------|-------|
| | | | Industrial | | Commercial | | Min Offset | Max Offset | |
| | | | Min Offset | Max Offset | Min Offset | Max Offset | | | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 8 | 0 | 1.782 | 0 | 1.782 | 0 | 4.124 | ns |
| Input delay from pin to input register | Pad to I/O input register | 64 | 0 | 2.054 | 0 | 2.054 | 0 | 4.689 | ns |

Table 4–100. Arria GX IOE Programmable Delay on Row Pins (Part 2 of 2)

| Parameter | Paths Affected | Available Settings | Fast Model | | | | -6 Speed Grade | | Units |
|--|----------------------------|--------------------|------------|------------|------------|------------|----------------|------------|-------|
| | | | Industrial | | Commercial | | Min Offset | Max Offset | |
| | | | Min Offset | Max Offset | Min Offset | Max Offset | | | |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.332 | 0 | 0.332 | 0 | 0.717 | ns |
| Output enable pin delay | txz/tzx | 2 | 0 | 0.32 | 0 | 0.32 | 0 | 0.693 | ns |

Table 4–101 describes IOE programmable delays.

Table 4–101. Arria GX IOE Programmable Delay on Column Pins

| Parameter | Paths Affected | Available Settings | Fast Model | | | | -6 Speed Grade | | Units |
|--|----------------------------|--------------------|------------|------------|------------|------------|----------------|------------|-------|
| | | | Industrial | | Commercial | | Min Offset | Max Offset | |
| | | | Min Offset | Max Offset | Min Offset | Max Offset | | | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 8 | 0 | 1.781 | 0 | 1.781 | 0 | 4.132 | ns |
| Input delay from pin to input register | Pad to I/O input register | 64 | 0 | 2.053 | 0 | 2.053 | 0 | 4.697 | ns |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.332 | 0 | 0.332 | 0 | 0.717 | ns |
| Output enable pin delay | txz/tzx | 2 | 0 | 0.32 | 0 | 0.32 | 0 | 0.693 | ns |

Maximum Input and Output Clock Toggle Rate

Maximum clock toggle rate is defined as the maximum frequency achievable for a clock type signal at an I/O pin. The I/O pin can be a regular I/O pin or a dedicated clock I/O pin.

The maximum clock toggle rate is different from the maximum data bit rate. If the maximum clock toggle rate on a regular I/O pin is 300 MHz, the maximum data bit rate for dual data rate (DDR) could be potentially as high as 600 Mbps on the same I/O pin.

To calculate the output toggle rate for a non 0 pF load, use this formula:

The toggle rate for a non 0 pF load

$$= 1,000 / (1,000 / \text{toggle rate at 0 pF load} + \text{derating factor} \times \text{load value in pF} / 1,000)$$

For example, the output toggle rate at 0 pF load for SSTL-18 Class II 20 mA I/O standard is 550 MHz on a -3 device clock output pin. The derating factor is 94 ps/pF. For a 10 pF load the toggle rate is calculated as:

$$1,000 / (1,000 / 550 + 94 \times 10 / 1,000) = 363 \text{ (MHz)}$$

Table 4–102 shows the maximum input clock toggle rates for Arria GX device column I/O pins.

| I/O Standards | -6 Speed Grade | Units |
|----------------------|-----------------------|--------------|
| 3.3-V LVTTTL | 420 | MHz |
| 3.3-V LVCMOS | 420 | MHz |
| 2.5 V | 420 | MHz |
| 1.8 V | 420 | MHz |
| 1.5 V | 420 | MHz |
| SSTL-2 CLASS I | 467 | MHz |
| SSTL-2 CLASS II | 467 | MHz |
| SSTL-18 CLASS I | 467 | MHz |
| SSTL-18 CLASS II | 467 | MHz |
| 1.8-V HSTL CLASS I | 467 | MHz |
| 1.8-V HSTL CLASS II | 467 | MHz |
| 1.5-V HSTL CLASS I | 467 | MHz |
| 1.5-V HSTL CLASS II | 467 | MHz |
| 3.3-V PCI | 420 | MHz |
| 3.3-V PCI-X | 420 | MHz |

Table 4–103 shows the maximum input clock toggle rates for Arria GX device row I/O pins.

| I/O Standards | -6 Speed Grade | Units |
|----------------------|-----------------------|--------------|
| 3.3-V LVTTTL | 420 | MHz |
| 3.3-V LVCMOS | 420 | MHz |
| 2.5 V | 420 | MHz |
| 1.8 V | 420 | MHz |
| 1.5 V | 420 | MHz |
| SSTL-2 CLASS I | 467 | MHz |
| SSTL-2 CLASS II | 467 | MHz |
| SSTL-18 CLASS I | 467 | MHz |
| SSTL-18 CLASS II | 467 | MHz |
| 1.8-V HSTL CLASS I | 467 | MHz |
| 1.8-V HSTL CLASS II | 467 | MHz |
| 1.5-V HSTL CLASS I | 467 | MHz |
| 1.5-V HSTL CLASS II | 467 | MHz |
| LVDS | 392 | MHz |

Table 4–104 shows the maximum input clock toggle rates for Arria GX device dedicated clock pins.

| I/O Standards | -6 Speed Grade | Units |
|----------------------|-----------------------|--------------|
| 3.3-V LVTTTL | 373 | MHz |
| 3.3-V LVCMOS | 373 | MHz |
| 2.5 V | 373 | MHz |
| 1.8 V | 373 | MHz |
| 1.5 V | 373 | MHz |
| SSTL-2 CLASS I | 467 | MHz |
| SSTL-2 CLASS II | 467 | MHz |
| 3.3-V PCI | 373 | MHz |
| 3.3-V PCI-X | 373 | MHz |
| SSTL-18 CLASS I | 467 | MHz |

Table 4–104. Arria GX Maximum Input Clock Rate for Dedicated Clock Pins (Part 2 of 2)

| I/O Standards | -6 Speed Grade | Units |
|----------------------------------|----------------|-------|
| SSTL-18 CLASS II | 467 | MHz |
| 1.8-V HSTL CLASS I | 467 | MHz |
| 1.8-V HSTL CLASS II | 467 | MHz |
| 1.5-V HSTL CLASS I | 467 | MHz |
| 1.5-V HSTL CLASS II | 467 | MHz |
| 1.2-V HSTL | 233 | MHz |
| DIFFERENTIAL SSTL-2 | 467 | MHz |
| DIFFERENTIAL 2.5-V SSTL CLASS II | 467 | MHz |
| DIFFERENTIAL 1.8-V SSTL CLASS I | 467 | MHz |
| DIFFERENTIAL 1.8-V SSTL CLASS II | 467 | MHz |
| DIFFERENTIAL 1.8-V HSTL CLASS I | 467 | MHz |
| DIFFERENTIAL 1.8-V HSTL CLASS II | 467 | MHz |
| DIFFERENTIAL 1.5-V HSTL CLASS I | 467 | MHz |
| DIFFERENTIAL 1.5-V HSTL CLASS II | 467 | MHz |
| DIFFERENTIAL 1.2-V HSTL | 233 | MHz |
| LVDS | 598 | MHz |
| LVDS (1) | 373 | MHz |

Note to Table 4–104:

- (1) This set of numbers refers to the VIO dedicated input clock pins.

Table 4–105 shows the maximum output clock toggle rates for Arria GX device column I/O pins.

Table 4–105. Arria GX Maximum Output Toggle Rate for Column I/O Pins (Part 1 of 2)

| I/O Standards | Drive Strength | -6 Speed Grade | Units |
|-----------------|----------------|----------------|-------|
| 3.3-V LVTTTL | 4 mA | 196 | MHz |
| | 8 mA | 303 | MHz |
| | 12 mA | 393 | MHz |
| | 16 mA | 486 | MHz |
| | 20 mA | 570 | MHz |
| | 24 mA | 626 | MHz |
| 3.3-V LVCMOS | 4 mA | 215 | MHz |
| | 8 mA | 411 | MHz |
| | 12 mA | 626 | MHz |
| | 16 mA | 819 | MHz |
| | 20 mA | 874 | MHz |
| | 24 mA | 934 | MHz |
| 2.5 V | 4 mA | 168 | MHz |
| | 8 mA | 355 | MHz |
| | 12 mA | 514 | MHz |
| | 16 mA | 766 | MHz |
| 1.8 V | 2 mA | 97 | MHz |
| | 4 mA | 215 | MHz |
| | 6 mA | 336 | MHz |
| | 8 mA | 486 | MHz |
| | 10 mA | 706 | MHz |
| | 12 mA | 925 | MHz |
| 1.5 V | 2 mA | 168 | MHz |
| | 4 mA | 303 | MHz |
| | 6 mA | 350 | MHz |
| | 8 mA | 392 | MHz |
| SSTL-2 CLASS I | 8 mA | 280 | MHz |
| | 12 mA | 327 | MHz |
| SSTL-2 CLASS II | 16 mA | 280 | MHz |
| | 20 mA | 327 | MHz |
| | 24 mA | 327 | MHz |

Table 4–105. Arria GX Maximum Output Toggle Rate for Column I/O Pins (Part 2 of 2)

| I/O Standards | Drive Strength | -6 Speed Grade | Units |
|---------------------|----------------|----------------|-------|
| SSTL-18 CLASS I | 4 mA | 140 | MHz |
| | 6 mA | 186 | MHz |
| | 8 mA | 280 | MHz |
| | 10 mA | 373 | MHz |
| | 12 mA | 373 | MHz |
| SSTL-18 CLASS II | 8 mA | 140 | MHz |
| | 16 mA | 327 | MHz |
| | 18 mA | 373 | MHz |
| | 20 mA | 420 | MHz |
| 1.8-V HSTL CLASS I | 4 mA | 280 | MHz |
| | 6 mA | 420 | MHz |
| | 8 mA | 561 | MHz |
| | 10 mA | 561 | MHz |
| | 12 mA | 607 | MHz |
| 1.8-V HSTL CLASS II | 16 mA | 420 | MHz |
| | 18 mA | 467 | MHz |
| | 20 mA | 514 | MHz |
| 1.5-V HSTL CLASS I | 4 mA | 280 | MHz |
| | 6 mA | 420 | MHz |
| | 8 mA | 561 | MHz |
| | 10 mA | 607 | MHz |
| | 12 mA | 654 | MHz |
| 1.5-V HSTL CLASS II | 16 mA | 514 | MHz |
| | 18 mA | 561 | MHz |
| | 20 mA | 561 | MHz |
| 3.3-V PCI | mA | 626 | MHz |
| 3.3-V PCI-X | mA | 626 | MHz |

Table 4–106 shows the maximum output clock toggle rates for Arria GX device row I/O pins.

| Table 4–106. Arria GX Maximum Output Toggle Rate for Row I/O Pins | | | |
|--|-----------------------|-----------------------|--------------|
| I/O Standards | Drive Strength | -6 Speed Grade | Units |
| 3.3-V LVTTTL | 4 mA | 196 | MHz |
| | 8 mA | 303 | MHz |
| | 12 mA | 393 | MHz |
| 3.3-V LVCMOS | 4 mA | 215 | MHz |
| | 8 mA | 411 | MHz |
| 2.5 V | 4 mA | 168 | MHz |
| | 8 mA | 355 | MHz |
| | 12 mA | 514 | MHz |
| 1.8 V | 2 mA | 97 | MHz |
| | 4 mA | 215 | MHz |
| | 6 mA | 336 | MHz |
| | 8 mA | 486 | MHz |
| 1.5 V | 2 mA | 168 | MHz |
| | 4 mA | 303 | MHz |
| SSTL-2 CLASS I | 8 mA | 280 | MHz |
| | 12 mA | 327 | MHz |
| SSTL-2 CLASS II | 16 mA | 280 | MHz |
| SSTL-18 CLASS I | 4 mA | 140 | MHz |
| | 6 mA | 186 | MHz |
| | 8 mA | 280 | MHz |
| | 10 mA | 373 | MHz |
| 1.8-V HSTL CLASS I | 4 mA | 280 | MHz |
| | 6 mA | 420 | MHz |
| | 8 mA | 561 | MHz |
| | 10 mA | 561 | MHz |
| | 12 mA | 607 | MHz |
| 1.5-V HSTL CLASS I | 4 mA | 280 | MHz |
| | 6 mA | 420 | MHz |
| | 8 mA | 561 | MHz |
| LVDS | mA | 598 | MHz |

Table 4–107 describes maximum output clock rate for dedicated clock pins.

Table 4–107. Arria GX Maximum Output Clock Rate for Dedicated Clock Pins (Part 1 of 4)

| I/O Standards | Drive Strength | -6 Speed Grade | Units |
|----------------|----------------|----------------|-------|
| 3.3-V LVTTTL | 4 mA | 196 | MHz |
| | 8 mA | 303 | MHz |
| | 12 mA | 393 | MHz |
| | 16 mA | 486 | MHz |
| | 20 mA | 570 | MHz |
| | 24 mA | 626 | MHz |
| 3.3-V LVCMOS | 4 mA | 215 | MHz |
| | 8 mA | 411 | MHz |
| | 12 mA | 626 | MHz |
| | 16 mA | 819 | MHz |
| | 20 mA | 874 | MHz |
| | 24 mA | 934 | MHz |
| 2.5 V | 4 mA | 168 | MHz |
| | 8 mA | 355 | MHz |
| | 12 mA | 514 | MHz |
| | 16 mA | 766 | MHz |
| 1.8 V | 2 mA | 97 | MHz |
| | 4 mA | 215 | MHz |
| | 6 mA | 336 | MHz |
| | 8 mA | 486 | MHz |
| | 10 mA | 706 | MHz |
| | 12 mA | 925 | MHz |
| 1.5 V | 2 mA | 168 | MHz |
| | 4 mA | 303 | MHz |
| | 6 mA | 350 | MHz |
| | 8 mA | 392 | MHz |
| SSTL-2 CLASS I | 8 mA | 280 | MHz |
| | 12 mA | 327 | MHz |

Table 4–107. Arria GX Maximum Output Clock Rate for Dedicated Clock Pins (Part 2 of 4)

| I/O Standards | Drive Strength | -6 Speed Grade | Units |
|---------------------|----------------|----------------|-------|
| SSTL-2 CLASS II | 16 mA | 280 | MHz |
| | 20 mA | 327 | MHz |
| | 24 mA | 327 | MHz |
| SSTL-18 CLASS I | 4 mA | 140 | MHz |
| | 6 mA | 186 | MHz |
| | 8 mA | 280 | MHz |
| | 10 mA | 373 | MHz |
| | 12 mA | 373 | MHz |
| SSTL-18 CLASS II | 8 mA | 140 | MHz |
| | 16 mA | 327 | MHz |
| | 18 mA | 373 | MHz |
| | 20 mA | 420 | MHz |
| 1.8-V HSTL CLASS I | 4 mA | 280 | MHz |
| | 6 mA | 420 | MHz |
| | 8 mA | 561 | MHz |
| | 10 mA | 561 | MHz |
| | 12 mA | 607 | MHz |
| 1.8-V HSTL CLASS II | 16 mA | 420 | MHz |
| | 18 mA | 467 | MHz |
| | 20 mA | 514 | MHz |
| 1.5-V HSTL CLASS I | 4 mA | 280 | MHz |
| | 6 mA | 420 | MHz |
| | 8 mA | 561 | MHz |
| | 10mA | 607 | MHz |
| | 12 mA | 654 | MHz |
| 1.5-V HSTL CLASS II | 16 mA | 514 | MHz |
| | 18 mA | 561 | MHz |
| | 20 mA | 561 | MHz |
| | 24 mA | 278 | MHz |
| DIFFERENTIAL SSTL-2 | 8 mA | 280 | MHz |
| | 12 mA | 327 | MHz |

Table 4–107. Arria GX Maximum Output Clock Rate for Dedicated Clock Pins (Part 3 of 4)

| I/O Standards | Drive Strength | -6 Speed Grade | Units |
|----------------------------------|----------------|----------------|-------|
| DIFFERENTIAL 2.5-V SSTL CLASS II | 16 mA | 280 | MHz |
| | 20 mA | 327 | MHz |
| | 24 mA | 327 | MHz |
| DIFFERENTIAL 1.8-V SSTL CLASS I | 4 mA | 140 | MHz |
| | 6 mA | 186 | MHz |
| | 8 mA | 280 | MHz |
| | 10 mA | 373 | MHz |
| | 12 mA | 373 | MHz |
| DIFFERENTIAL 1.8-V SSTL CLASS II | 8 mA | 140 | MHz |
| | 16 mA | 327 | MHz |
| | 18 mA | 373 | MHz |
| | 20 mA | 420 | MHz |
| DIFFERENTIAL 1.8-V HSTL CLASS I | 4 mA | 280 | MHz |
| | 6 mA | 420 | MHz |
| | 8 mA | 561 | MHz |
| | 10 mA | 561 | MHz |
| | 12 mA | 607 | MHz |
| DIFFERENTIAL 1.8-V HSTL CLASS II | 16 mA | 420 | MHz |
| | 18 mA | 467 | MHz |
| | 20 mA | 514 | MHz |
| DIFFERENTIAL 1.5-V HSTL CLASS I | 4 mA | 280 | MHz |
| | 6 mA | 420 | MHz |
| | 8 mA | 561 | MHz |
| | 10 mA | 607 | MHz |
| | 12 mA | 654 | MHz |
| DIFFERENTIAL 1.5-V HSTL CLASS II | 16 mA | 514 | MHz |
| | 18 mA | 561 | MHz |
| | 20 mA | 561 | MHz |
| | 24 mA | 278 | MHz |
| 3.3-V PCI | - | 626 | MHz |
| 3.3-V PCI-X | - | 626 | MHz |
| LVDS | - | 280 | MHz |
| HYPERTRANSPORT | - | 116 | MHz |

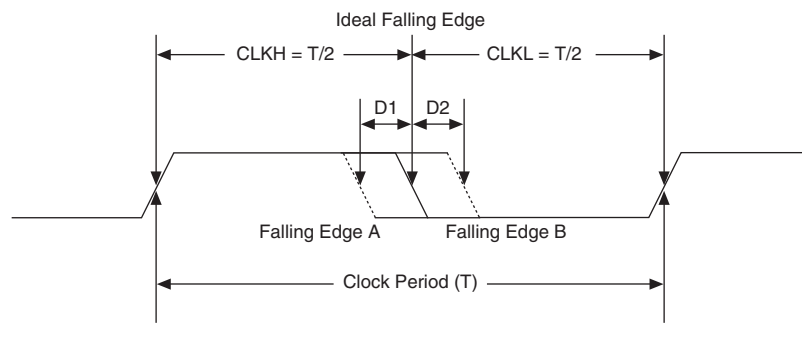
Table 4–107. Arria GX Maximum Output Clock Rate for Dedicated Clock Pins (Part 4 of 4)

| I/O Standards | Drive Strength | -6 Speed Grade | Units |
|----------------------------------|----------------|----------------|-------|
| LVPECL | - | 280 | MHz |
| 3.3-V LVTTTL | SERIES_25_OHMS | 327 | MHz |
| | SERIES_50_OHMS | 327 | MHz |
| 3.3-V LVCMOS | SERIES_25_OHMS | 280 | MHz |
| | SERIES_50_OHMS | 280 | MHz |
| 2.5 V | SERIES_25_OHMS | 280 | MHz |
| | SERIES_50_OHMS | 280 | MHz |
| 1.8 V | SERIES_25_OHMS | 420 | MHz |
| | SERIES_50_OHMS | 420 | MHz |
| 1.5 V | SERIES_50_OHMS | 373 | MHz |
| SSTL-2 CLASS I | SERIES_50_OHMS | 467 | MHz |
| SSTL-2 CLASS II | SERIES_25_OHMS | 467 | MHz |
| SSTL-18 CLASS I | SERIES_50_OHMS | 327 | MHz |
| SSTL-18 CLASS II | SERIES_25_OHMS | 420 | MHz |
| 1.8-V HSTL CLASS I | SERIES_50_OHMS | 561 | MHz |
| 1.8-V HSTL CLASS II | SERIES_25_OHMS | 420 | MHz |
| 1.5-V HSTL CLASS I | SERIES_50_OHMS | 467 | MHz |
| 1.2-V HSTL | SERIES_50_OHMS | 233 | MHz |
| DIFFERENTIAL SSTL-2 | SERIES_50_OHMS | 467 | MHz |
| DIFFERENTIAL 2.5-V SSTL CLASS II | SERIES_25_OHMS | 467 | MHz |
| DIFFERENTIAL 1.8-V SSTL CLASS I | SERIES_50_OHMS | 327 | MHz |
| DIFFERENTIAL 1.8-V SSTL CLASS II | SERIES_25_OHMS | 420 | MHz |
| DIFFERENTIAL 1.8-V HSTL CLASS I | SERIES_50_OHMS | 561 | MHz |
| DIFFERENTIAL 1.8-V HSTL CLASS II | SERIES_25_OHMS | 420 | MHz |
| DIFFERENTIAL 1.5-V HSTL CLASS I | SERIES_50_OHMS | 467 | MHz |
| DIFFERENTIAL 1.2-V HSTL | SERIES_50_OHMS | 233 | MHz |

Duty Cycle Distortion

Duty cycle distortion (DCD) describes how much the falling edge of a clock is off from its ideal position. The ideal position is when both the clock high time (CLKH) and the clock low time (CLKL) equal half of the clock period (T), as shown in [Figure 4–10](#). DCD is the deviation of the non-ideal falling edge from the ideal falling edge, such as D1 for the falling edge A and D2 for the falling edge B (see [Figure 4–10](#)). The maximum DCD for a clock is the larger value of D1 and D2.

Figure 4–10. Duty Cycle Distortion



DCD expressed in absolute derivation, for example, D1 or D2 in [Figure 4–10](#), is clock-period independent. DCD can also be expressed as a percentage, and the percentage number is clock-period dependent. DCD as a percentage is defined as:

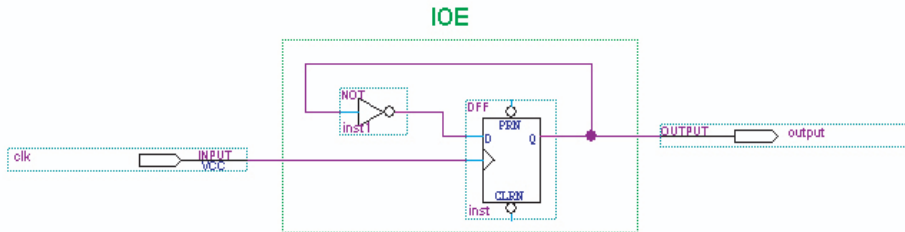
$$(T/2 - D1) / T \text{ (the low percentage boundary)}$$

$$(T/2 + D2) / T \text{ (the high percentage boundary)}$$

DCD Measurement Techniques

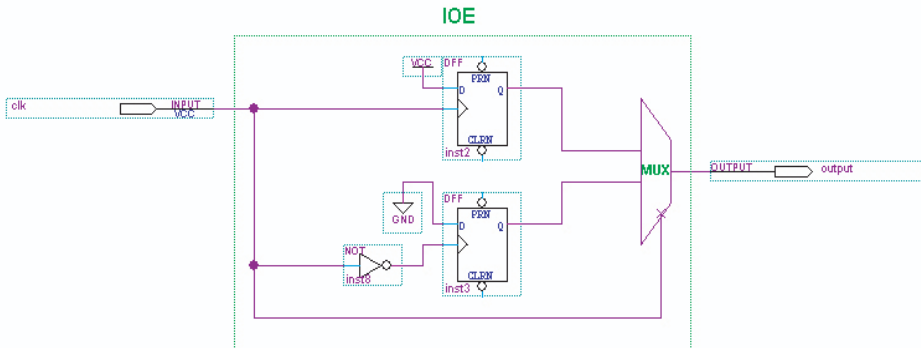
DCD is measured at an FPGA output pin driven by registers inside the corresponding I/O element (IOE) block. When the output is a single data rate signal (non-DDIO), only one edge of the register input clock (positive or negative) triggers output transitions ([Figure 4–11](#)). Therefore, any DCD present on the input clock signal or caused by the clock input buffer or different input I/O standard does not transfer to the output signal.

Figure 4–11. DCD Measurement Technique for Non-DDIO (Single-Data Rate) Outputs



However, when the output is a double data rate input/output (DDIO) signal, both edges of the input clock signal (positive and negative) trigger output transitions (Figure 4–12). Therefore, any distortion on the input clock and the input clock buffer affect the output DCD.

Figure 4–12. DCD Measurement Technique for DDIO (Double-Data Rate) Outputs



When an FPGA PLL generates the internal clock, the PLL output clocks the IOE block. As the PLL only monitors the positive edge of the reference clock input and internally re-creates the output clock signal, any DCD present on the reference clock is filtered out. Therefore, the DCD for a DDIO output with PLL in the clock path is better than the DCD for a DDIO output without PLL in the clock path.

Tables 4–108 through 4–113 show the maximum DCD in absolute derivation for different I/O standards on Arria GX devices. Examples are also provided that show how to calculate DCD as a percentage.

| Row I/O Output Standard | Maximum DCD (ps) for Non-DDIO Output | |
|-------------------------|--------------------------------------|------|
| | -6 Speed Grade | Unit |
| 3.3-V LVTTTL | 275 | ps |
| 3.3-V LVCMOS | 155 | ps |
| 2.5 V | 135 | ps |
| 1.8 V | 180 | ps |
| 1.5-V LVCMOS | 195 | ps |
| SSTL-2 Class I | 145 | ps |
| SSTL-2 Class II | 125 | ps |
| SSTL-18 Class I | 85 | ps |
| 1.8-V HSTL Class I | 100 | ps |
| 1.5-V HSTL Class I | 115 | ps |
| LVDS | 80 | ps |

Here is an example for calculating the DCD as a percentage for a non-DDIO output on a row I/O:

If the non-DDIO output I/O standard is SSTL-2 Class II, the maximum DCD is 125 ps (see Table 4–109). If the clock frequency is 267 MHz, the clock period T is:

$$T = 1 / f = 1 / 267 \text{ MHz} = 3.745 \text{ ns} = 3,745 \text{ ps}$$

To calculate the DCD as a percentage:

$$(T/2 - \text{DCD}) / T = (3,745 \text{ ps}/2 - 125 \text{ ps}) / 3,745 \text{ ps} = 46.66\% \text{ (for low boundary)}$$

$$(T/2 + \text{DCD}) / T = (3,745 \text{ ps}/2 + 125 \text{ ps}) / 3,745 \text{ ps} = 53.33\% \text{ (for high boundary)}$$

Therefore, the DCD percentage for the output clock at 267 MHz is from 46.66% to 53.33%.

Table 4–109. Maximum DCD for Non-DDIO Output on Column I/O Pins

| Column I/O Output Standard I/O Standard | Maximum DCD (ps) for Non-DDIO Output | Unit |
|--|---|------|
| | -6 Speed Grade | |
| 3.3-V LVTTTL | 220 | ps |
| 3.3-V LVCMOS | 175 | ps |
| 2.5 V | 155 | ps |
| 1.8 V | 110 | ps |
| 1.5-V LVCMOS | 215 | ps |
| SSTL-2 Class I | 135 | ps |
| SSTL-2 Class II | 130 | ps |
| SSTL-18 Class I | 115 | ps |
| SSTL-18 Class II | 100 | ps |
| 1.8-V HSTL Class I | 110 | ps |
| 1.8-V HSTL Class II | 110 | ps |
| 1.5-V HSTL Class I | 115 | ps |
| 1.5-V HSTL Class II | 80 | ps |
| 1.2-V HSTL-12 | 200 | ps |
| LVPECL | 80 | ps |

Table 4–110. Maximum DCD for DDIO Output on Row I/O Pins Without PLL in the Clock Path (Part 1 of 2)
Note (1)

| Maximum DCD (ps) for Row DDIO Output I/O Standard | Input I/O Standard (No PLL in the Clock Path) | | | | | Unit |
|---|---|----------|--------|-----------|------|------|
| | TTL/CMOS | | SSTL-2 | SSTL/HSTL | LVDS | |
| | 3.3/2.5V | 1.8/1.5V | 2.5V | 1.8/1.5V | 3.3V | |
| 3.3-V LVTTTL | 440 | 495 | 170 | 160 | 105 | ps |
| 3.3-V LVCMOS | 390 | 450 | 120 | 110 | 75 | ps |
| 2.5 V | 375 | 430 | 105 | 95 | 90 | ps |
| 1.8 V | 325 | 385 | 90 | 100 | 135 | ps |
| 1.5-V LVCMOS | 430 | 490 | 160 | 155 | 100 | ps |
| SSTL-2 Class I | 355 | 410 | 85 | 75 | 85 | ps |

Table 4–110. Maximum DCD for DDIO Output on Row I/O Pins Without PLL in the Clock Path (Part 2 of 2)
Note (1)

| Maximum DCD (ps) for Row DDIO Output I/O Standard | Input I/O Standard (No PLL in the Clock Path) | | | | | Unit |
|---|---|----------|--------|-----------|------|------|
| | TTL/CMOS | | SSTL-2 | SSTL/HSTL | LVDS | |
| | 3.3/2.5V | 1.8/1.5V | 2.5V | 1.8/1.5V | 3.3V | |
| SSTL-2 Class II | 350 | 405 | 80 | 70 | 90 | ps |
| SSTL-18 Class I | 335 | 390 | 65 | 65 | 105 | ps |
| 1.8-V HSTL Class I | 330 | 385 | 60 | 70 | 110 | ps |
| 1.5-V HSTL Class I | 330 | 390 | 60 | 70 | 105 | ps |
| LVDS | 180 | 180 | 180 | 180 | 180 | ps |

Note to Table 4–110:

- (1) Table 4–110 assumes the input clock has zero DCD.

Table 4–111. Maximum DCD for DDIO Output on Column I/O Pins Without PLL in the Clock Path *Note (1)*

| Maximum DCD (ps) for DDIO Column Output I/O Standard | Input IO Standard (No PLL in the Clock Path) | | | | Unit |
|--|--|----------|--------|-----------|------|
| | TTL/CMOS | | SSTL-2 | SSTL/HSTL | |
| | 3.3/2.5V | 1.8/1.5V | 2.5V | 1.8/1.5V | |
| 3.3-V LVTTTL | 440 | 495 | 170 | 160 | ps |
| 3.3-V LVCMOS | 390 | 450 | 120 | 110 | ps |
| 2.5 V | 375 | 430 | 105 | 95 | ps |
| 1.8 V | 325 | 385 | 90 | 100 | ps |
| 1.5-V LVCMOS | 430 | 490 | 160 | 155 | ps |
| SSTL-2 Class I | 355 | 410 | 85 | 75 | ps |
| SSTL-2 Class II | 350 | 405 | 80 | 70 | ps |
| SSTL-18 Class I | 335 | 390 | 65 | 65 | ps |
| SSTL-18 Class II | 320 | 375 | 70 | 80 | ps |
| 1.8-V HSTL Class I | 330 | 385 | 60 | 70 | ps |
| 1.8-V HSTL Class II | 330 | 385 | 60 | 70 | ps |
| 1.5-V HSTL Class I | 330 | 390 | 60 | 70 | ps |
| 1.5-V HSTL Class II | 330 | 360 | 90 | 100 | ps |
| LVPECL | 180 | 180 | 180 | 180 | ps |

Note to Table 4–111:

- (1) Table 4–111 assumes the input clock has zero DCD.

Table 4–112. Maximum DCD for DDIO Output on Row I/O Pins With PLL in the Clock Path

| Maximum DCD (ps) for Row DDIO Output I/O Standard | Arria GX Devices (PLL Output Feeding DDIO) | Unit |
|---|--|------|
| | -6 Speed Grade | |
| 3.3-V LVTTTL | 105 | ps |
| 3.3-V LVCMOS | 75 | ps |
| 2.5V | 90 | ps |
| 1.8V | 100 | ps |
| 1.5-V LVCMOS | 100 | ps |
| SSTL-2 Class I | 75 | ps |
| SSTL-2 Class II | 70 | ps |
| SSTL-18 Class I | 65 | ps |
| 1.8-V HSTL Class I | 70 | ps |
| 1.5-V HSTL Class I | 70 | ps |
| LVDS | 180 | ps |

Table 4–113. Maximum DCD for DDIO Output on Column I/O Pins With PLL in the Clock Path (Part 1 of 2)

| Maximum DCD (ps) for Column DDIO Output I/O Standard | Arria GX Devices (PLL Output Feeding DDIO) | Unit |
|--|--|------|
| | -6 Speed Grade | |
| 3.3-V LVTTTL | 160 | ps |
| 3.3-V LVCMOS | 110 | ps |
| 2.5V | 95 | ps |
| 1.8V | 100 | ps |
| 1.5-V LVCMOS | 155 | ps |
| SSTL-2 Class I | 75 | ps |
| SSTL-2 Class II | 70 | ps |
| SSTL-18 Class I | 65 | ps |
| SSTL-18 Class II | 80 | ps |
| 1.8-V HSTL Class I | 70 | ps |
| 1.8-V HSTL Class II | 70 | ps |
| 1.5-V HSTL Class I | 70 | ps |
| 1.5-V HSTL Class II | 100 | ps |

Table 4–113. Maximum DCD for DDIO Output on Column I/O Pins With PLL in the Clock Path (Part 2 of 2)

| Maximum DCD (ps) for Column DDIO Output I/O Standard | Arria GX Devices (PLL Output Feeding DDIO) | Unit |
|--|--|------|
| | -6 Speed Grade | |
| 1.2-V HSTL | 155 | ps |
| LVPECL | 180 | ps |

High-Speed I/O Specifications

Table 4–114 provides high-speed timing specifications definitions.

Table 4–114. High-Speed Timing Specifications and Definitions

| High-Speed Timing Specifications | Definitions |
|----------------------------------|---|
| t_C | High-speed receiver/transmitter input and output clock period. |
| f_{HSCLK} | High-speed receiver/transmitter input and output clock frequency. |
| J | Deserialization factor (width of parallel data bus). |
| W | PLL multiplication factor. |
| t_{RISE} | Low-to-high transmission time. |
| t_{FALL} | High-to-low transmission time. |
| Timing unit interval (TUI) | The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = 1/(Receiver Input Clock Frequency × Multiplication Factor) = t_C/w). |
| f_{HSDR} | Maximum/minimum LVDS data transfer rate ($f_{HSDR} = 1/TUI$), non-DPA. |
| $f_{HSDRDPA}$ | Maximum/minimum LVDS data transfer rate ($f_{HSDRDPA} = 1/TUI$), DPA. |
| Channel-to-channel skew (TCCS) | The timing difference between the fastest and slowest output edges, including t_{CO} variation and clock skew. The clock is included in the TCCS measurement. |
| Sampling window (SW) | The period of time during which the data must be valid in order to capture it correctly. The setup and hold times determine the ideal strobe position within the sampling window. |
| Input jitter | Peak-to-peak input jitter on high-speed PLLs. |
| Output jitter | Peak-to-peak output jitter on high-speed PLLs. |
| t_{DUTY} | Duty cycle on high-speed transmitter output clock. |
| t_{LOCK} | Lock time for high-speed transmitter and receiver PLLs. |

Table 4–115 shows the high-speed I/O timing specifications.

| Symbol | Conditions | -6 Speed Grade | | | Unit | |
|--|--|-------------------------|---------------------------|-------|------|-----------------------|
| | | Min | Typ | Max | | |
| f_{HSCLK} (clock frequency) $f_{\text{HSCLK}} = f_{\text{HSDR}} / W$ | W = 2 to 32 (LVDS, HyperTransport technology) (3) | 16 | | 420 | MHz | |
| | W = 1 (SERDES bypass, LVDS only) | 16 | | 500 | MHz | |
| | W = 1 (SERDES used, LVDS only) | 150 | | 640 | MHz | |
| f_{HSDR} (data rate) | J = 4 to 10 (LVDS, HyperTransport technology) | 150 | | 840 | Mbps | |
| | J = 2 (LVDS, HyperTransport technology) | (4) | | 700 | Mbps | |
| | J = 1 (LVDS only) | (4) | | 500 | Mbps | |
| f_{HSDRDPA} (DPA data rate) | J = 4 to 10 (LVDS, HyperTransport technology) | 150 | | 840 | Mbps | |
| TCCS | All differential I/O standards | - | | 200 | ps | |
| SW | All differential I/O standards | 440 | | - | ps | |
| Output jitter | | | | 190 | ps | |
| Output t_{RISE} | All differential I/O standards | | | 290 | ps | |
| Output t_{FALL} | All differential I/O standards | | | 290 | ps | |
| t_{DUTY} | | 45 | 50 | 55 | % | |
| DPA run length | | | | 6,400 | UI | |
| DPA jitter tolerance | Data channel peak-to-peak jitter | 0.44 | | | UI | |
| DPA lock time | Standard | Training Pattern | Transition Density | | | Number of repetitions |
| | SPI-4 | 000000000 111111111 | 10% | 256 | | |
| | Parallel Rapid I/O | 00001111 | 25% | 256 | | |
| | | 10010000 | 50% | 256 | | |
| | Miscellaneous | 10101010 | 100% | 256 | | |
| 01010101 | | | 256 | | | |

Notes to Table 4–115:

- (1) When J = 4 to 10, the SERDES block is used.
- (2) When J = 1 or 2, the SERDES block is bypassed.
- (3) The input clock frequency and the W factor must satisfy the following fast PLL VCO specification: $150 \leq \text{input clock frequency} \times W \leq 1,040$.
- (4) The minimum specification is dependent on the clock source (fast PLL, enhanced PLL, clock pin, and so on) and the clock routing resource (global, regional, or local) utilized. The I/O differential buffer and input register do not have a minimum toggle rate.

PLL Timing Specifications

Tables 4–116 and 4–117 describe the Arria GX PLL specifications when operating in both the commercial junction temperature range (0 to 85 C) and the industrial junction temperature range (–40 to 100 C), except for the clock switchover and phase-shift stepping features. These two features are only supported from the 0 to 100 C junction temperature range.

Table 4–116. Enhanced PLL Specifications (Part 1 of 2)

| Name | Description | Min | Typ | Max | Unit |
|------------------|--|---------|-------------------|------|-------------------|
| f_{IN} | Input clock frequency | 2 | | 500 | MHz |
| f_{INPFD} | Input frequency to the PFD | 2 | | 420 | MHz |
| f_{INDUTY} | Input clock duty cycle | 40 | | 60 | % |
| f_{ENDUTY} | External feedback input clock duty cycle | 40 | | 60 | % |
| $t_{INJITTER}$ | Input or external feedback clock input jitter tolerance in terms of period jitter. Bandwidth ≤ 0.85 MHz | | 0.5 | | ns (peak-to-peak) |
| | Input or external feedback clock input jitter tolerance in terms of period jitter. Bandwidth > 0.85 MHz | | 1.0 | | ns (peak-to-peak) |
| $t_{OUTJITTER}$ | Dedicated clock output period jitter | | | (3) | ps or mUI (p-p) |
| t_{FCOMP} | External feedback compensation time | | | 10 | ns |
| f_{OUT} | Output frequency for internal global or regional clock | 1.5 (2) | | 550 | MHz |
| $f_{SCANCLK}$ | Scanclk frequency | | | 100 | MHz |
| $t_{CONFIGEPLL}$ | Time required to reconfigure scan chains for EPLLs | | $174/f_{SCANCLK}$ | | ns |
| f_{OUT_EXT} | PLL external clock output frequency | 1.5 (2) | | (1) | MHz |
| $f_{OUTDUTY}$ | Duty cycle for external clock output | 45 | 50 | 55 | % |
| t_{LOCK} | Time required for the PLL to lock from the time it is enabled or the end of device configuration | | 0.03 | 1 | ms |
| t_{DLOCK} | Time required for the PLL to lock dynamically after automatic clock switchover between two identical clock frequencies | | | 1 | ms |
| $f_{SWITCHOVER}$ | Frequency range where the clock switchover performs properly | 1.5 | 1 | 500 | MHz |
| f_{CLBW} | PLL closed-loop bandwidth | 0.13 | 1.2 | 16.9 | MHz |
| f_{VCO} | PLL VCO operating range | 300 | | 840 | MHz |
| f_{SS} | Spread-spectrum modulation frequency | 100 | | 500 | kHz |

Table 4–116. Enhanced PLL Specifications (Part 2 of 2)

| Name | Description | Min | Typ | Max | Unit |
|------------------------|--|-----|-----|----------|------|
| % spread | Percent down spread for a given clock frequency | 0.4 | 0.5 | 0.6 | % |
| t_{PLL_PSERR} | Accuracy of PLL phase shift | | | ± 30 | ps |
| t_{ARESET} | Minimum pulse width on <code>areset</code> signal. | 10 | | | ns |
| $t_{ARESET_RECONFIG}$ | Minimum pulse width on the <code>areset</code> signal when using PLL reconfiguration. Reset the PLL after <code>scandone</code> goes high. | 500 | | | ns |
| $t_{RECONFIGWAIT}$ | The time required for the wait after the reconfiguration is done and the <code>areset</code> is applied. | | | 2 | us |

Notes to Table 4–116:

- (1) This is limited by the I/O f_{MAX} .
- (2) If the counter cascading feature of the PLL is utilized, there is no minimum output clock frequency.
- (3) 250 ps for ≥ 100 MHz `outclk`. 25 mUI for <100 MHz `outclk`.

Table 4–117. Fast PLL Specifications (Part 1 of 2)

| Name | Description | Min | Typ | Max | Unit |
|------------------|--|--------|------------------|----------|----------|
| f_{IN} | Input clock frequency | 16.08 | | 640 | MHz |
| f_{INPFD} | Input frequency to the PFD | 16.08 | | 500 | MHz |
| f_{INDUTY} | Input clock duty cycle | 40 | | 60 | % |
| $t_{INJITTER}$ | Input clock jitter tolerance in terms of period jitter. Bandwidth ≤ 2 MHz | | 0.5 | | ns (p-p) |
| | Input clock jitter tolerance in terms of period jitter. Bandwidth > 0.2 MHz | | 1.0 | | ns (p-p) |
| f_{VCO} | Upper VCO frequency range | 300 | | 840 | MHz |
| | Lower VCO frequency range | 150 | | 420 | MHz |
| f_{OUT} | PLL output frequency to <code>GCLK</code> or <code>RCLK</code> | 4.6875 | | 550 | MHz |
| | PLL output frequency to <code>LVDS</code> or <code>DPA</code> clock | 150 | | 840 | MHz |
| f_{OUT_EXT} | PLL clock output frequency to regular I/O | 4.6875 | | (1) | MHz |
| $t_{CONFIGPLL}$ | Time required to reconfigure scan chains for fast PLLs | | $75/f_{SCANCLK}$ | | ns |
| f_{CLBW} | PLL closed-loop bandwidth | 1.16 | 5 | 28 | MHz |
| t_{LOCK} | Time required for the PLL to lock from the time it is enabled or the end of the device configuration | | 0.03 | 1 | ms |
| t_{PLL_PSERR} | Accuracy of PLL phase shift | | | ± 30 | ps |

Table 4–117. Fast PLL Specifications (Part 2 of 2)

| Name | Description | Min | Typ | Max | Unit |
|-------------------------------|--|-----|-----|-----|------|
| t_{ARESET} | Minimum pulse width on areset signal. | 10 | | | ns |
| $t_{\text{ARESET_RECONFIG}}$ | Minimum pulse width on the areset signal when using PLL reconfiguration. Reset the PLL after scandone goes high. | 500 | | | ns |

Note to [Table 4–117](#):

- (1) This is limited by the I/O f_{MAX} .

External Memory Interface Specifications

[Tables 4–118 through 4–122](#) contain Arria GX device specifications for the dedicated circuitry used for interfacing with external memory devices.

Table 4–118. DLL Frequency Range Specifications

| Frequency Mode | Frequency Range (MHz) |
|----------------|-----------------------|
| 0 | 100 to 175 |
| 1 | 150 to 230 |
| 2 | 200 to 310 |

**Table 4–119. DQS Jitter Specifications for DLL-Delayed Clock ($t_{\text{DQS_JITTER}}$),
Note (1)**

| Number of DQS Delay Buffer Stages (2) | Commercial (ps) | Industrial (ps) |
|--|-----------------|-----------------|
| 1 | 80 | 110 |
| 2 | 110 | 130 |
| 3 | 130 | 180 |
| 4 | 160 | 210 |

Notes to [Table 4–119](#):

- (1) Peak-to-peak period jitter on the phase-shifted DQS clock. For example, jitter on two delay stages under commercial conditions is 200 ps peak-to-peak or 100 ps.
- (2) Delay stages used for requested DQS phase shift are reported in a project's Compilation Report in the Quartus II software.

Table 4–120. DQS Phase-Shift Error Specifications for DLL-Delayed Clock (t_{DQS_PSERR})

| Number of DQS Delay Buffer Stages | –6 Speed Grade (ps) |
|-----------------------------------|---------------------|
| 1 | 35 |
| 2 | 70 |
| 3 | 105 |
| 4 | 140 |

Table 4–121. DQS Bus Clock Skew Adder Specifications ($t_{DQS_CLOCK_SKEW_ADDER}$)

| Mode | DQS Clock Skew Adder (ps) |
|---------------|---------------------------|
| 4 DQ per DQS | 40 |
| 9 DQ per DQS | 70 |
| 18 DQ per DQS | 75 |
| 36 DQ per DQS | 95 |

Table 4–122. DQS Phase Offset Delay Per Stage (ps) Notes (1), (2), (3)

| Speed Grade | Positive Offset | | Negative Offset | |
|-------------|-----------------|-----|-----------------|-----|
| | Min | Max | Min | Max |
| –6 | 10 | 16 | 8 | 12 |

Notes to Table 4–122:

- (1) The delay settings are linear.
- (2) The valid settings for phase offset are -32 to +31.
- (3) The typical value equals the average of the minimum and maximum values.

JTAG Timing Specifications

Figure 4–13 shows the timing requirements for the JTAG signals

Figure 4–13. Arria GX JTAG Waveforms.

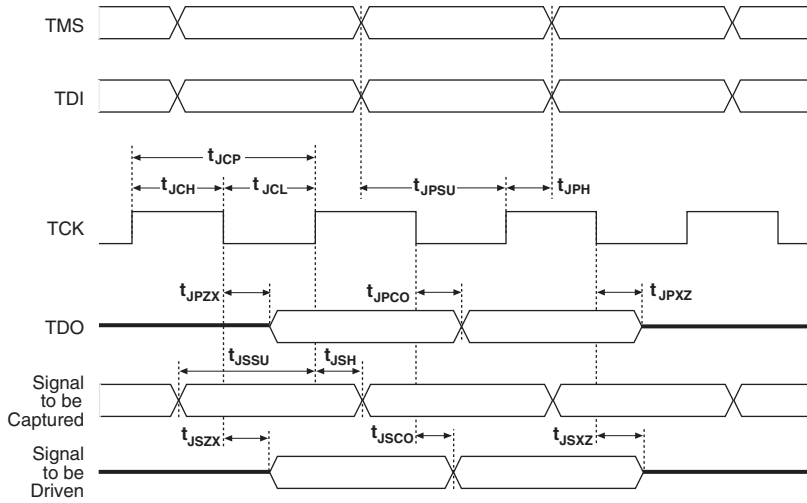


Table 4–123 shows the JTAG timing parameters and values for Arria GX devices.

| Symbol | Parameter | Min | Max | Unit |
|------------|--|-----|-----|------|
| t_{JCP} | TCK clock period | 30 | | ns |
| t_{JCH} | TCK clock high time | 12 | | ns |
| t_{JCL} | TCK clock low time | 12 | | ns |
| t_{JPSU} | JTAG port setup time | 4 | | ns |
| t_{JPH} | JTAG port hold time | 5 | | ns |
| t_{JPCO} | JTAG port clock to output | | 9 | ns |
| t_{JPZX} | JTAG port high impedance to valid output | | 9 | ns |
| t_{JPXZ} | JTAG port valid output to high impedance | | 9 | ns |
| t_{JSSU} | Capture register setup time | 4 | | ns |
| t_{JSH} | Capture register hold time | 5 | | ns |
| t_{JSCO} | Update register clock to output | | 12 | ns |
| t_{JSZX} | Update register high impedance to valid output | | 12 | ns |
| t_{JSXZ} | Update register valid output to high impedance | | 12 | ns |

Referenced Documents

This chapter references the following documents:

- *Arria GX Architecture* chapter in volume 1 of the *Arria GX Device Handbook*
- *Arria GX Device Family Data Sheet* in volume 1 of the *Arria GX Device Handbook*
- *PowerPlay Early Power Estimator and PowerPlay Power Analyzer*
- *PowerPlay Power Analysis* chapter in volume 3 of the *Quartus II Handbook*

Document Revision History

Table 4–124 shows the revision history for this chapter.

| Date and Document Version | Changes Made | Summary of Changes |
|----------------------------------|--|---------------------------|
| May 2008 v1.3 | Updated: <ul style="list-style-type: none"> ● Table 4–5 ● Table 4–7 ● Table 4–8 ● Table 4–9 ● Table 4–10 ● Table 4–11 ● Table 4–12 ● Table 4–13 ● Table 4–14 ● Table 4–15 ● Table 4–16 ● Table 4–17 ● Table 4–43 ● Table 4–116 ● Table 4–117 | — |
| | Updated: <ul style="list-style-type: none"> ● Figure 4–4 | — |
| | Minor text edits. | — |
| August 2007 v1.2 | Removed “Preliminary” from each page. | — |
| | Removed “Preliminary” note from Tables 4–44, 4–45, and 4–47. | — |
| | Added “Referenced Documents” section. | — |
| June 2007 v1.1 | Updated Table 4–99. | — |
| | Added GIGE information. | — |
| May 2007 v1.0 | Initial release. | — |

Software

Arria™ GX devices are supported by the Altera® Quartus® II design software, which provides a comprehensive environment for system-on-a-programmable-chip (SOPC) design. The Quartus II software includes HDL and schematic design entry, compilation and logic synthesis, full simulation and advanced timing analysis, SignalTap® II logic analyzer, and device configuration.



Refer to the *Quartus II Development Software Handbook* for more information on the Quartus II software features.

The Quartus II software supports the Windows XP/2000/NT, Sun Solaris 8/9, Linux Red Hat v7.3, Linux Red Hat Enterprise 3, and HP-UX operating systems. It also supports seamless integration with industry-leading EDA tools through the NativeLink interface.

Device Pin-Outs



Arria GX device pin-outs are available on the Altera web site at www.altera.com.

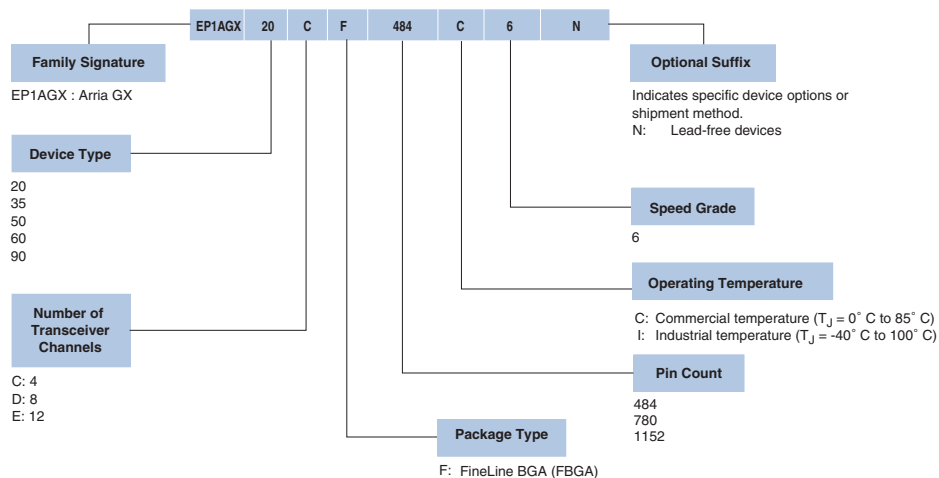
Ordering Information

Figure 5–1 describes the ordering codes for Arria GX devices.



For more information on a specific package, refer to the *Package Information for Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*.

Figure 5–1. Arria GX Device Packaging Ordering Information



Referenced Documents

This chapter references the following documents:

- *Package Information for Arria GX Devices* chapter in volume 2 of the *Arria GX Device Handbook*
- *Quartus II Development Software Handbook*

Document Revision History

Table 5–1 shows the revision history for this chapter.

| Date and Document Version | Changes Made | Summary of Changes |
|----------------------------------|---|---------------------------|
| August 2007, v1.1 | Added the “Referenced Documents” section. | — |
| May 2007, v1.0 | Initial Release. | — |

