

PAW3501UI USB OPTICAL MOUSE SENSOR SINGLE CHIP

General Description

PAW3501UI is a CMOS process optical mouse sensor single chip with USB interface that serves as a non-mechanical motion estimation engine for implementing a computer mouse.

Feat	tures	Key Specification	
	USB interface	Dames C	Wide operating supply range
	Single 5.0 volt power supply	Power Supply	4.25V ~ 5.5V
	Compatible with Microsoft $^{\! \oplus}$ Windows 2000 $^{\! \oplus}$ and 5-button Wheel Mouse	Interface	USB
	Optical motion estimation technology	Optical Lens	1:1
	Complete 2-D motion sensor	System Clock	18.000 MHz
	Accurate motion estimation over a wide range of surfaces	Speed	28 inches/sec
	High speed motion detection up to 28 inches/sec	Acceleration	20g
	High resolution up to 800 CPI	Resolution	400/600/800 CPI
	Power saving mode during times of no movement	Frame Rate	3000 frames/sec
	Supports five buttons (R, M, L, B4, B5) and three axes (X, Y, Z) output	Operating Current	12 mA @Mouse moving (Normal) 8 mA @Mouse not moving (Sleep)
	Z-axis can support two kinds of scroller		480 uA @USB suspend (Suspend)
	input (Opto-mechanical and mechanical).	Package	Shrunk DIP24
	Complete Universal Serial Bus® spec V1.1 compatibility		
	Complete USB HID spec V1.1 compatibility		
	Integrated USB transceiver and 1.5 Mbps USB serial interface engine		

Ordering Information

Part Number	CPI	Sensor Rotate	Device Type	Z-axis Type
PAW3501UI	400/600/800	0°/+90°/-90°	2D2B/3D3B/3D5B	Mechanical (Z/2)
PAW3501UI-P2	400/600/800	0°/+90°/-90°	2D2B/3D3B/3D5B	Optical (Z/2)
PAW3501UI-P4	400/600/800	0°/+90°/-90°	2D2B/3D3B/3D5B	Optical (Z/4)

1. Pin Configuration

1.1 Pin Assignment

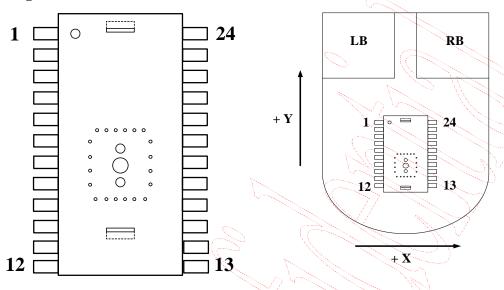


Figure 1. Top View Pinout

Figure 2. Top View of Mouse

1.2 Pin Description

Pin#	Name	Type	Definition
1	Z1	IN	Z axis, support two kinds of scroller input, opto-mechanical and mechanical
2	Z2	IN	Z axis, support two kinds of scroller input, opto-mechanical and mechanical
3	SR	IN	Sensor rotate $(0, 1, floating) => (-90^\circ, +90^\circ, 0^\circ), 3$ -states input
4	IRCTL	OUT	IR LED control
5	BM	IN	Button middle key input, normal pull-high (50k), press connect to low
6	BL	IN \nearrow	Button left key input, normal pull-high (50k), press connect to low
7	DT	IN ,	Device type (0, 1, floating) => (3D3B, 2D2B, 3D5B), 3-states input
8	B4	IN \	Button 4 key input, normal pull-high (50k), press connect to low
9	B5	IN	Button 5 key input, normal pull-high (50k), press connect to low
10	CPI	IN	CPI select to (0, 1, floating) => (800, 600, 400), 3-states input
11	VSSLED	GND	LED ground
12	LED	I/O	LED control
13 _	VREFB <	BYPASS	Analog voltage reference
14	VREFA /	BYPASS	Analog voltage reference
15	VDD5V	PWR	Chip power VDD, 5.0V
/16	VSS	GND \	Chip ground
47	VDDQ	BYPASS	IO voltage reference
18	OSCIN	IN	Oscillator input, connect to 18.000MHz crystal or resonator
19	OSCOUT	OUT	Oscillator output, connect to 18.000MHz crystal or resonator
20	D+	I/O	USB D+
21	D-	I/O	USB D-
22	BR	IN \	Button right key input, normal pull-high (50k), press connect to low
23	RFU	IN /	Reserve for future use, PAW3501UP used the pin to switch USB or PS/2
24	TEST	IN	Test pin. It is needed to connect to GND in normal operation mode

2. Block Diagram and Operation

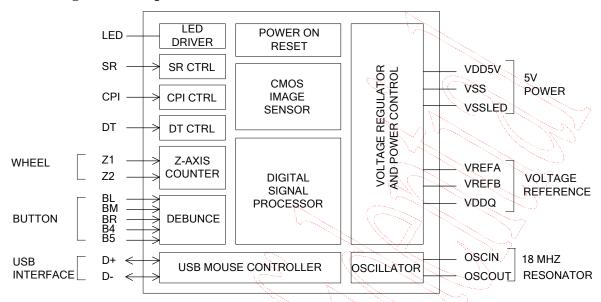
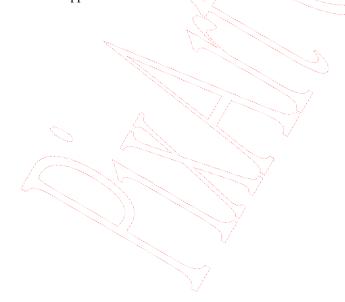


Figure 3. Block Diagram

PAW3501UI supports X, Y, Z three axes, and L, R, M, B4, B5 five buttons under USB mode. It is a CMOS process optical mouse sensor single chip with USB interface that serves as a non-mechanical motion estimation engine for implementing a computer mouse.

PAW3501UI is in a 24-pin optical package and comes with the resolution of 400/600/800 counts per inch (cpi) and the rate of motion up to 28 inches per second. It includes USB interface so that no mouse controller is needed to interface through USB. PAW3501UI can receive command and echo status or data format, both complete Universal Serial Bus® spec V1.1 and USB HID spec V1.1 compatibility. It is also a cost effective solution to support USB Mouse.



PAW3501UI

3. Specifications

3.1 Absolute Maximum Ratings

Exposure to absolute maximum rating may affect device reliability.

Symbol	Parameter	Min.	Max.	Unit	Notes
T_{STG}	Storage Temperature	-40	85	°C	
TA	Operating Temperature	-15	55	°C	
	Lead Solder Temp		260	°C	For 10 seconds, 1.6 mm below seating plane.
ESD			2	kV	All pins, human body model MIL 883 Method 3015
V_{DC}	DC Supply Voltage	-0.5	5.5	V	
V_{IN}	DC Input Voltage	-0.5	5.5	V	All I/O pin

3.2 Recommend Operating Condition

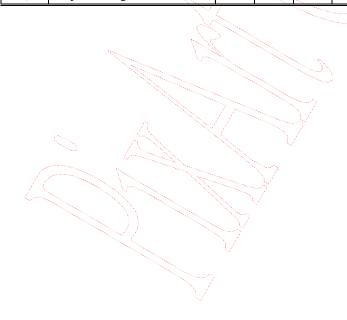
Symbol	Parameter	Min.	Тур.	Max.	Unit	Notes
T_A	Operating Temperature	0		40	°C	7
V_{DD}	Power Supply Voltage	4.25	5.0	5.5	V	\searrow
V_N	Supply Noise			100	mV	Peak to peak within 0 - 100 MHz
Z	Distance from Lens Reference Plane to Surface	2.3	2.4	2.5	mm	Refer to Figure 4.
R	Resolution	400	600	800	CPI	
A	Acceleration			20	g	
F_{CLK}	Clock Frequency	2	18.000		MHz	
FR	Frame Rate		3000		frames/sec	
S	Speed	0		28	inches/sec	

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3.3 DC Electrical Characteristics

Electrical characteristics over recommended operating conditions. Typical values at 25 °C, V_{DD} = 5.0 V

Symbol	Parameter	Min.	Тур.	Max.	Unit	Notes		
Type: U	SB Mouse PWR							
I_{DD}	Supply Current Mouse Moving (Normal)		12		mA			
I_{DD}	Supply Current Mouse Not Moving (Sleep1)		8		mA			
I_{DD}	Supply Current Suspend Current (Suspend)			480	uA			
Type: B	L, BM, BR, B4, B5							
R_{PH}	Internal Pull-up Resistance		50	1	Kohm			
Type: Z	1, Z2			5				
R _{PD}	Internal Pull-down Resistance		50	2		PAW3501UI built-in internal pull-down resistance. PAW3501UI-PX needs external pull-down resistance.		
Type: B	L, BM, BR, B4, B5, Z1, Z2		177		1			
V _{IH}	Input High Voltage	2.0			V	30		
V _{IL}	Input Low Voltage			0.8	V			
Type: U	ISB DP, DN			5				
R _{PH}	Internal Pull-up Resistance		1.5	13	Kohm			
V _{OL}	Output Low Voltage		(0.3	V			
Type: OSCIN								
V_{IH}	Input High Voltage	2.0	,		V	When driving from an external source		
$V_{\rm IL}$	Input Low Voltage			0.5	V	When driving from an external source		
Type: L	ED				N			
V _{OL}	Output Voltage LOW			360	mV	$I_{OL} = 25 \text{ mA}$		



4. Z and 2D Assembly Z and

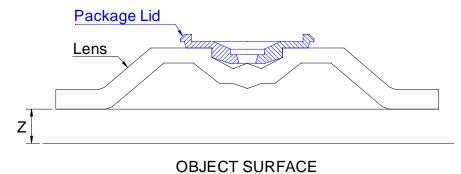


Figure 4. Distance from Lens Reference Plane to Surface

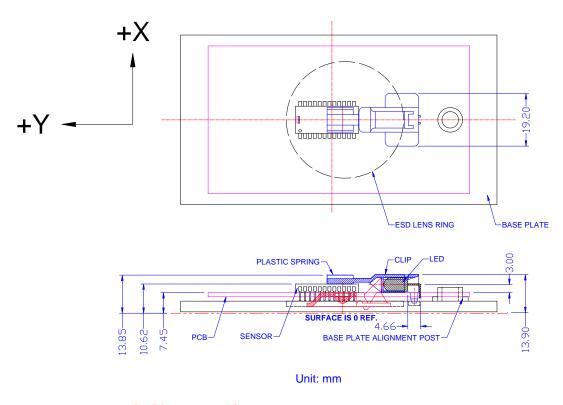


Figure 5. 2D Assembly

5. USB Interface

5.1 USB Command Set Description (USB Descriptor)

The USB HOST detects USB mouse device plug-in and assigns a new unique address to the USB mouse device, then asking USB mouse device for information about the device description, configuration description, and assigning a configuration value for USB mouse device during enumeration period. After enumeration, the USB mouse device is able to transfer motion and button value to the USB host.

Descriptor Type	Byte	Byte	Byte	Byte	Byte	Byte	Byte	Byte
	12	01	10	01	/00	00	00	08
Device Descriptor (18 bytes)	3A	09	00	25	00	01	01	02
	00	01		(
Configuration Descriptor (9 bytes)	09	02	22	00	01	01	04	A0
Configuration Descriptor (9 bytes)	32							
	09	04	00	00	01	03	01	02
Interface Descriptor (9 bytes)	00	V*			77 - `		V	
Human Interface Device Descriptor	09	21	10	01	00	01	/ 22	48
(9 bytes)	00	\sim		,			<i>y</i>	
Endpoint Descriptor (7 bytes)	07	05	81	03	04	-00	0A	
	05	01	09	02	A1	01	05	09
	19	01	⁷ (29	03	15	00	25	01
	95	03	75	01	81	- 02	95	01
Human Interface Device Report	75	05	81	03	05	01	09	01
Descriptor (72 bytes, 3D3B)	A1	00	09	30	09	31	15	81
Descriptor (72 bytes, 3D3B)	25	7F	75	08	95	02	81	06
	C0	09	38	95	01	81	06	09
	3C	15	00	25	/ 01	75	01	95
\\	01	B1	22	95	07	B1	01	C0

5.2 USB Data Report Format

The USB report has two data formats, depending on boot or report protocol is selected. One kind of data format is the boot protocol used in legacy environment as 4.2.1. The other kind of data format is USB report protocol format which includes Z-wheel movement data in the fourth byte as 4.2.2. The Z-wheel is moved forward the fourth byte data is 01H, the Z-wheel is moved backward the fourth byte data is FFH, and the Z-wheel is idle the fourth byte data is 00H.

5.2.1 USB Boot Protocol for Legacy Operation

Byt	te	Bit	Symbol	Description
1		0	BL	1 = Left button pressed
			BR	1 = Right button pressed
		2~7	NC	Reserved
2	0	0-7	X0~X7	X data (D0 - D7). A positive value indicates motion to the right; a negative value
				indicates motion to the left. Bit $0 = LSB$.
3		0 - 7		Y data (D0 - D7). A positive value indicates device motion upward; a negative
				value indicates motion downward. Bit 0 = LSB.

5.2.2 USB Report Protocol

Byte	Bit	Symbol	Description				
1	0	BL	1 = Left button pressed				
	1	BR	1 = Right button pressed				
	2	BM	1 = Middle button pressed				
	3	B4	1 = B4 button pressed				
	4	B5	1 = B5 button pressed				
	5 ~ 7	NC	Reserved				
2	0 - 7	X0 ~ X7	X data (D0 - D7). A positive value indicates motion to the right; a negative value				
			indicates motion to the left. Bit 0 = LSB.				
3	0 - 7	Y0 ~ Y7	Y data (D0 - D7). A positive value indicates device motion upward; a negative				
			value indicates motion downward. Bit 0 = LSB.				
4	0 - 7	Z0 ~ Z7	Z-wheel motion data (D0 - D7). A positive value indicates device motion				
			downward; a negative value indicates motion upward. The Z0 - Z7 limit value is				
			\pm 7. Bit 0 = LSB.				



6. Referencing Application Circuit

6.1 Typical Application for PAW3501UI with Mechanical Encoder

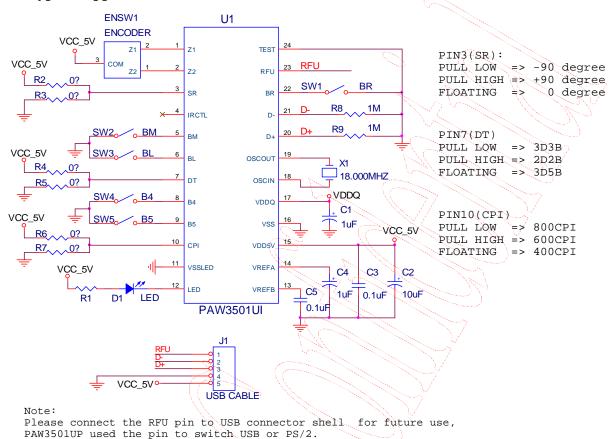
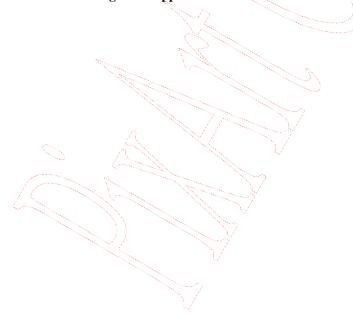
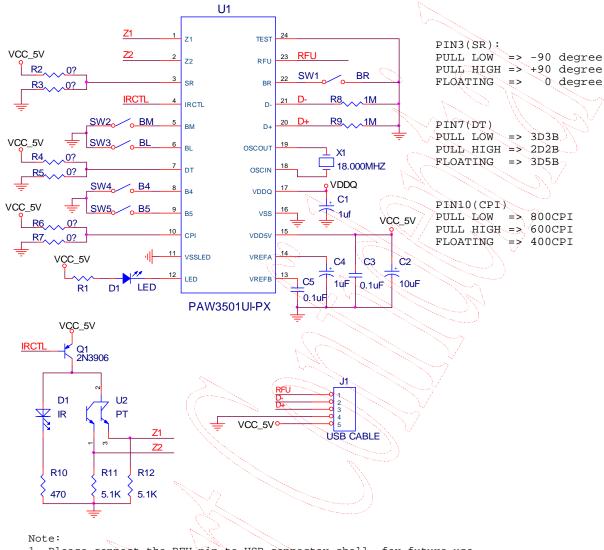


Figure 6. Application Circuit for PAW3501UI (Mechanical Encoder)

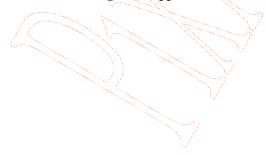


6.2 Typical Application for PAW3501UI-PX with Optical Encoder



- 1. Please connect the RFU pin to USB connector shell for future use, PAW3501UP used the pin to switch USB or PS/2.
- For resistor value selection, refer to high or low input level of Z1 and Z2 in the D.C. Electrical Characteristics table The recommended value for R10 is 4700hm.
 The recommended value for R11/R12 is 5.1Kohm.

Figure 7. Application Circuit for PAW3501UI-PX (Optical Encoder)



PAW3501UI

6.3 PCB Layout Consideration

- Caps for pins 13, 14, 17 must have trace lengths less than **5mm**.
- The trace lengths of OSCOUT, OSCIN must less than **6mm**.

6.4 Recommended Value for R1

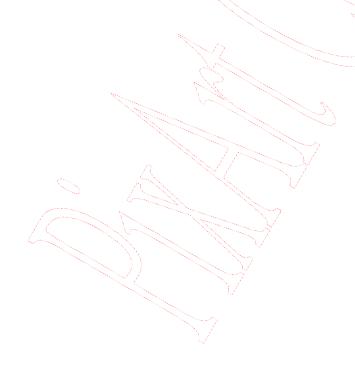
Radiometric intensity of LED
Bin limits (mW/Sr at 20 mA)

LED Bin Grade	Min.	Тур.	Max.
N	14.7		17.7
P	17.7	< (F	21.2
Q	21.2	1	25.4

Note: Tolerance for each bin will be $\pm 15\%$

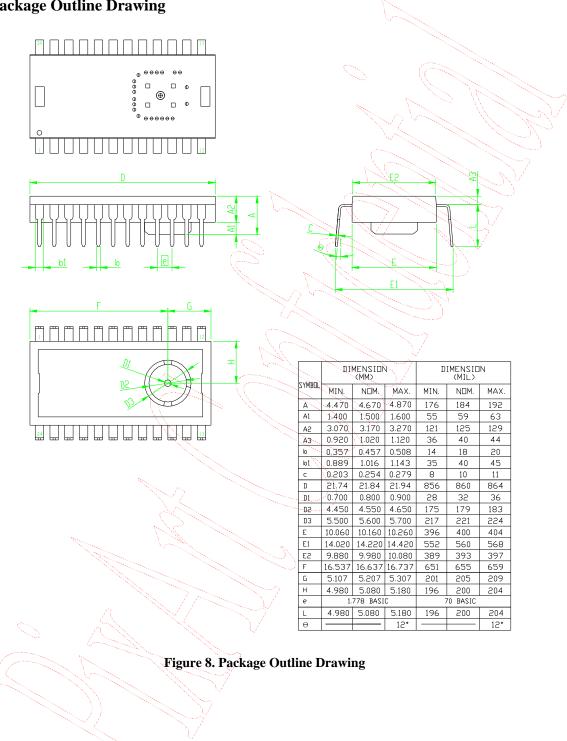
• R1 value (ohm), VDD = 5.0V

LED Bin Grade	Min.	Тур.	Max.
N	51	100	
P	51	100	
Q	51	100	



7. Package Information

7.1 Package Outline Drawing



7.2 Recommended PCB Mechanical Cutouts and Spacing

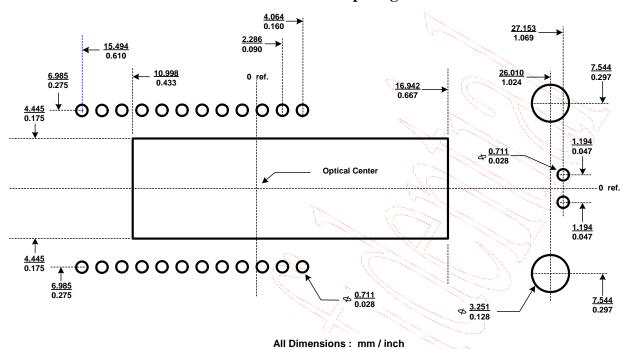


Figure 9. Recommended PCB Mechanical Cutouts and Spacing



8. NSTL Compatibility Test

PAW3501UI has passed the NSTL Compatibility Test Program, which conducts an objective quality assurance test suite to verify correct operation, functionality, and compatibility of system products. "The NSTL standard testing methodologies assessed the compatibility of PAW3501UI at the NSTL/ALLION Labs testing facility. And, it shows that it is getting along great and operated correctly with various software applications and add-on devices under a variety of Operating Systems." cited from the NTSL Test Report. Accordingly, PAW3501UI fully meets NTSL Compatibility Test Standard and is able to carry the NTSL Seal.

9. Update History

Version	Update	Date
V1.0	Creation, Preliminary 1 st version	08/18/2006
V2.0	Modify Application Circuit for PAW3501UI-PX with Optical Encoder (Figure 7.)	07/18/2007
V2.1	Content revise	04/18/2008
		V



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