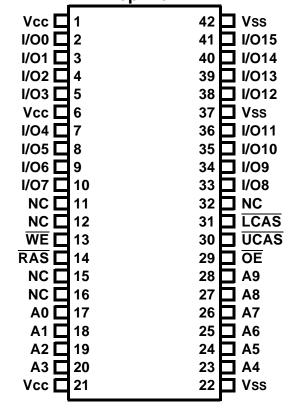
ACT-PD1M16 Fast Page Mode 16 Megabit Plastic Monolithic DRAM

Pin Configuration Top View





Features

- Fast Access Time (tRAC): 70ns
- Power Supply: 5.0V ± 0.5V
- Packaging
 - 42 Lead Plastic Surface-Mount SOJ (L4)
- Industrial and Military Temperature Ranges
- **■** Three-State Unlatched Output
- Fast Page Mode
- RAS-Only Refresh
- xCAS Before RAS Refresh
- Hidden Refresh
- 1024 Cycle Refresh in 16ms
- **Low Power Dissipation**
- **Long Refresh Period Option**

Pin Description

A 0–9	Address Inputs
I/O ₀₋₁₅	Data Input / Output
WE	Read/Write Enable
OE	Output Enable
RAS	Row Address Strobe
UCAS	Upper Byte Control / Column Address Strobe
LCAS	Lower Byte Control / Column Address Strobe
Vcc	+5.0V Power Supply
Vss	Ground
NC	Not Connected



Absolute Maximum Ratings

Symbol	Parameter	MINIMUM	MAXIMUM	Units
T _C	Case Operating Temp.	-55	+125	°C
T _{STG}	Storage Temperature	-55	+150	°C
I _{os}	Short Circuit Output Current	-	50	mA
P _T	Power Dissipated	-	1	W
V _{CC}	Supply Voltage Range	-1.0	+7.0	V
V_{T}	Voltage Range on any Pin*	-1.0	+7.0	V

Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum rated conditions for extended periods may affect device reliability.

Recommended Operating Conditions

Symbol	Parameter	Minimum	Maximum	Units
V _{CC}	Power Supply Voltage	+4.5	+5.5	V
V_{IH}	Input High Voltage	+2.4	-	V
V_{IL}	Input Low Voltage	-	+0.8	V
T _{CM}	Operating Temp. (Mil)	-55	+125	°C
T _{CI}	Operating Temp. (Ind.)	-40	+85	°C

Symbol	Parameter	Maximum	Units
$C_{I(A)}$	A ₀₋₉ Input Capacitance	10	pF
C _{I(RC)}	RAS and CAS Input Capacitance	10	pF
C _{I(OE)}	OE Input Capacitance	10	pF
C _{I(WE)}	WE Input Capacitance	10	pF
Co	Output Capacitance	15	pF

These parameters are guaranteed by design but not tested.

DC Characteristics

(VCC = 5.0V, VSS = 0V, TCI or TCM)

Parameter	Sym	Conditions	Min	Max	Units
Output Low Voltage	V _{OL}	I _{OL} = 4.2 mA	-	0.4	V
Output High Voltage	V _{OH}	I _{OH} = -5 mA	2.4		V
Input Leakage Current	ΙL	$V_I = 0$ to +6.5V, All others 0V to V_{CC}	-10	+10	μΑ
Output Leakage Current	Io	$V_O = 0$ to V_{CC} , \overline{CAS} high	-10	+10	μΑ
Read or Write Cycle Current 1,2	I _{CC1}	V _{CC} = 5.5V, minimum cycle		190	mA

^{*} All voltage values are with respect to Vss.

DC Characteristics (continued)

(VCC = 5.0V, VSS = 0V, TCI or TCM)

Parameter	Sym Conditions		Min	Max	Units
Standby Current		VIH = 2.4V (TTL), After 1 memory cycle, \overline{RAS} and \overline{CAS} high	1	2	mA
Standby Current	I _{CC3}	$\label{eq:VIH} \begin{split} \text{VIH} &= \text{Vcc - 0.05V (CMOS), After 1 memory} \\ &\text{cycle, } \overline{\text{RAS}} \text{ and } \overline{\text{CAS}} \text{ high} \end{split}$	ı	1	mA
Average Page Current ²	I _{CC4}	RAS low, CAS cycling	1	100	mA

- 1. Measured with a maximum of one address change while $\overline{RAS} = VIL$.
- 2. Measured with a maximum of one address change while $\overline{\text{CAS}} = \text{VIH}$.

AC Characteristics*

 $(VCC = 5.0V \pm 10\%, VSS = 0V, TCI \text{ or TCM})$

Parameter	Sy	/m	Min	Max	Units
Access Time from Column-Address	t#	λA	-	35	ns
CAS Low Access Time from CAS	tc	AC	-	20	ns
Column Access Time from CAS Precharge	tc	PA	-	40	ns
Access Time from RAS	tR	AC	-	70	ns
OE Access Time	to	EA	-	20	ns
Output Buffer Turn-off Delay ¹	tc	FF	0	15	ns
Output Buffer Turn-off Delay Time from $\overline{\text{OE}}^1$	to	EZ	0	15	ns

^{*} Valid data is presented at the outputs after all access times are satisfied but can go from the high-impedance state to an invalid-data state prior to the specified access times as the outputs are driven when \overline{CAS} goes low.

1. toff and toez are specified when the outputs are no longer driven. The outputs are disabled by bringing either \overline{OE} or \overline{CAS} high.

AC Characteristics

(VCC = 5.0V, VSS = 0V, TCI or TCM)

Parameter	Sym	Min	Max	Units
Cycle Time, Read or Write Random ¹	tRC	130	-	ns
Cycle Time, Fast Page Mode Read or Write 1,2	tPC	45	-	ns
Cycle Time, Fast Page Mode Read-Modify-Write ¹	tPRWC	90	-	ns
Pulse Duration, RAS Low Fast Page Mode ³	tRASP	70	200,000	ns
Pulse Duration, RAS Low Nonpage Mode ³	tras	70	10,000	ns
Pulse Duration, CAS Low 4	tCAS	20	10,000	ns
Pulse Duration, CAS High Precharge Time	tCP	10	-	ns
Pulse Duration, RAS High Precharge Time	tRP	50	-	ns
Pulse Duration, WE Low	tWP	15	-	ns
Setup Time, Column Address before CAS Low	tASC	0	-	ns
Setup Time, Row Address before RAS Low	tasr	0	-	ns
Setup Time, Data ⁵	tDS	0	-	ns
Setup Time, WE High before CAS Low	tRCS	0	-	ns
Setup Time, WE Low before CAS High	tCWL	20	-	ns
Setup Time, WE Low before RAS High	tRWL	20	-	ns

AC Characteristics (continued)

(VCC = 5.0V, VSS = 0V, TCI or TCM)

Parameter	Sym	Min	Max	Units
Setup Time, WE Low before CAS Low (early-write operation only)	twcs	0	-	ns
Hold Time, Column Address after CAS Low	tCAH	15	-	ns
Hold Time, Data ⁵	tDH	15	-	ns
Hold Time, Row Address after RAS Low	trah	10	-	ns
Hold Time, WE High after CAS High ⁶	tRCH	0	-	ns
Hold Time, WE High after RAS High ⁶	trrh	0	-	ns

- 1. All cycle times assume tT= 5ns, reference to VIH (min) and VIL (max).
- 2. To assume tPC min, tASC should be \geq tCP.
- 3. In read-write cycle, tRWD and tRWL must be observed.
- 4. In read-write cycle, tCWD and tCWL must be observed.
- 5. Referenced to the later of \overline{xCAS} or \overline{WE} in write operations.
- 6. Either tRRH or tRCH must be satisfied for a read cycle.

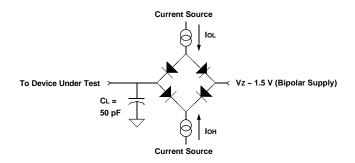
AC Characteristics

(VCC = 5.0V, VSS = 0V, TCI or TCM)

Parameter	Sym	Min	Max	Units
WE Low before CAS Low Hold Time (early-write operation only)	tWCH	15	-	ns
OE Command Hold Time	tOEH	15	-	ns
RAS Referenced to OE Hold Time	tROH	10	-	ns
RAS from CAS Precharge (Fast Page Mode)	tRHCP	40	-	ns
Column Address to WE Low Delay Time (read-write operation only)	tawd	60	-	ns
RAS Low to CAS High Delay Time (CBR refresh only)	tCHR	15	-	ns
CAS High to RAS Low Delay Time (CAS to RAS Precharge Time)	tCRP	5	-	ns
RAS Low to CAS High Delay Time (CAS Hold Time)	tCSH	70	-	ns
CAS Low to RAS Low Delay Time (CAS Set-up Time)	tCSR	5	-	ns
CAS Low to WE Low Delay Time (read-write operation only)	tcwD	45	-	ns
OE to Data Delay Time	tOED	15	-	ns
RAS Low to Column Address Delay Time ¹	tRAD	15	35	ns
Column Address to RAS High Delay Time	tRAL	35	-	ns
RAS Low to CAS Low Delay Time ¹	tRCD	20	50	ns
RAS High to CAS Low Precharge Time	tRPC	5	-	ns
CAS Low to RAS High Delay Time (RAS Hold Time)	tRSH	20	-	ns
RAS Low to WE Low Delay Time (read-write operation only)	tRWD	95	-	ns
WE Low after CAS Precharge Delay Time (read-write operation only)	tCWD	65	-	ns
Refresh Time Interval	tREF		16	ms
Transition time ²	tτ	3	50	ns

- 1. The maximum value is specified only to assure access time
- 2. Transition times (rise and fall) for \overline{RAS} and \overline{xCAS} are to be a minimum of 3ns and a maximum of 30ns.

AC Test Circuit



Parameter	Typical	Units
Input Pulse Level	0 – 3.0	٧
Input Rise and Fall	5	ns
Input and Output Reference Level	1.5	٧
Output Timing Reference Level	1.5	V

Notes: 1) Vz is programmable from -2V to +7V.

- 2) IOL and IOH programmable from 0 to 16 mA.
- 3) Tester Impedance Zo = 75Ω .
- 4) Vz is typically the midpoint of VOH and VoL.
- 5) IOL and IOH are adjusted to simulate a typical resistance load circuit.
- 6) ATE Tester includes jig capacitance.

OPERATIONS

DUAL CAS

Two $\overline{\text{CAS}}$ pins ($\overline{\text{LCAS}}$ and $\overline{\text{UCAS}}$) are provided to give independent control of the 16 data-I/O pins (I/O0-15),with **LCAS** corresponding to I/O0-7 and **UCAS** corresponding to I/O8-15. For read or write cycles, the column address is latched on the first xCAS falling edge. Each xCAS going low enables its corresponding I/Ox pin with data associated with the column address latched on the first falling \overline{xCAS} edge. All address setup and hold parameters are referenced to the first falling \overline{xCAS} edge. The delay time from xCAS low to valid data out (see parameter tCAC) is measured form each individual \overline{xCAS} to its corresponding I/Ox pin.

In order to latch in a new column address, both \overline{xCAS} pins must be brought high. The column-precharge time (see parameter tCP) is measured from the last \overline{xCAS} rising edge to the first \overline{xCAS} falling edge of the new cycle. Keeping a column address valid while toggling \overline{xCAS} requires a minimum setup time, tCLCH. During tCLCH at least one \overline{xCAS} must be brought low before the other \overline{xCAS} is taken high.

For early-write cycles, the data is latched on the first xCAS falling edge. Only the I/Os that have the corresponding xCAS low are written into. Each xCAS must meet tCAS minimum in order to ensure writing into the storage cell. To latch a new address and new data, all xCAS pins must be high and meet tCP.

PAGE MODE

Page-mode operation allows faster memory access by keeping the same row address while selecting random column addresses. The time for row-address setup and hold and address multiplex is eliminated. The maximum number of columns that can be accessed is determined by the maximum

RAS low time and the xCAS page-mode cycle time used. With minimum xCAS page-cycle time, all columns can be accessed without intervening RAS cycles.

Unlike conventional page-mode DRAMs, the column address buff-ers in this device are activated on the falling edge of RAS. The buffers act as transparent or flow-through latches while \overline{xCAS} is high. The falling edge of the first \overline{xCAS} latches the column addresses. This feature allows the devices to operate at a higher data bandwidth than conventional page-mode parts because data retrieval begins as soon as the column address is valid rather than when \overline{xCAS} transitions low. This performance improvement is referred to as enhanced page mode. A valid column address may be presented immediately after trah (row-address hold time) has been satisfied, usually well in advance of the falling edge of \overline{xCAS} . In this case, data is obtained after tCAC maximum (access time from \overline{xCAS} low) if tAA maximum (access time from column address) has been satisfied. In the event that column addresses for the next page cycle are valid at the time \overline{xCAS} goes high, minimum access time for the next cycle is determined by tCPA (access time from rising edge of the last \overline{xCAS}).

ADDRESS: A0-9

Twenty address bits are required to decode 1 of 1048576 storage cell locations. For the ACTPD1M16, 10 row-address bits are set up on A0 through A9 and latched onto the chip by RAS. Ten, column-address bits are set up on A0 through A9 and latched onto the chip by the first xCAS. All addresses must be stable on or before the falling edge of RAS and xCAS. RAS is similar to a chip enable in that it activates the sense amplifiers as well as the row decoder. xCAS is used as a chip select, activating its correspond-ing output buffer and latching the address bits into the column-address buffers.

WRITE ENABLE (WE)

The read or write mode is selected through \overline{WE} . A logic high on \overline{WE} selects the read mode and a logic low selects the write mode. The data inputs are disabled when the read mode is selected. When \overline{WE} goes low prior to \overline{xCAS} (early write), data out remains in the high-impedance state for the entire cycle, permitting a write operation with \overline{OE} grounded.

DATA IN (I/O0-15)

Data written during write is а or read-modify-write cycle. Depending on the mode of operation, the falling edge of \overline{xCAS} or WE strobes data into the on-chip data latch. In an early-write cycle, WE is brought low prior to \overline{xCAS} and the data is strobed in by the first occurring xCAS with setup and hold times referenced to this signal. In a delayed-write or read-modify-write cycle, \overline{xCAS} is already low and the data is strobed in by WE with setup and hold times referenced to this signal. In a delayed-write or read-modify-write cycle. OE must be high to bring the output buffers to the high-impedance state prior to impressing data on the I/O lines.

DATA OUT (I/O0-15)

Data out is the same polarity as data in. The output is in the high-impedance (floating) state until xCAS and OE are brought low. In a read cycle, the output becomes valid after the access time interval tCAC (which begins with the negative transition of xCAS) as long as tRAC and tAA are satisfied.

OUTPUT ENABLE (OE)*

OE controls the impedance of the output buffers. When \overline{OE} is high, the buffers remain in the high-impedance state. Bringing \overline{OE} low during a normal cycle activates the output buffers, putting them in the low-impedance state. It is necessary for both \overline{RAS} and \overline{xCAS} to be brought low for the output butters to go into the low-impedance state, and they remain

in the low-impedance state until either \overline{OE} or \overline{xCAS} is brought high.

*Output Enable can be held low during write cycles.

RAS-ONLY REFRESH

A refresh operation must be performed at least once every 16ms (128ms for long refresh periods) to retain data. This can be achieved by strobing each of the 1024 rows (A0-9). A normal read or write cycle refreshes all bits in each row that is selected. A RAS-only operation can be used by holding both xCAS at the high (inactive) level, conserving power as the output buffers high-impedance remain in the state. Externally generated addresses must be used for a RAS-only refresh.

HIDDEN REFRESH

Hidden refresh can be performed while maintaining valid data at the output pin. This is accomplished by holding \overline{xCAS} at VIL after a read operation and cycling \overline{RAS} after a specified precharge period, similar to a \overline{RAS} -only refresh cycle. The external address is ignored and the refresh address is generated internally.

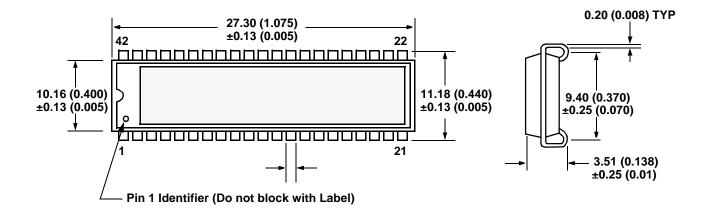
XCAS-BEFORE-RAS (XCBR) REFRESH

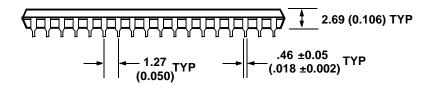
xCBR refresh is utilized by bringing at least one xCAS low earlier than RAS (see parameter tcsr) and holding it low after RAS fails (see parameter tchr). For succesive xCBR refresh cycles, xCAS can remain low while cycling RAS. The external address is ignored and the refresh address is generated internally.

POWER UP

To achieve proper device operation, an initial pause of 200µs followed by a minimum of eight initialization cycles is required after power up to full Vcc level. These eight initialization cycles must include at least one refresh (RAS-only or xCBR) cycle.

Package Outline "L4" — SOJ Package, 42 Leads





All dimensions in millimeters

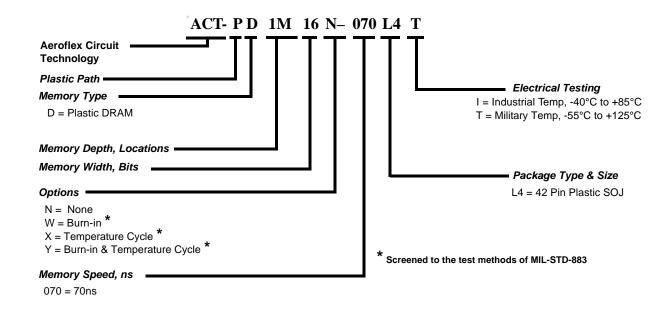
Dimensions in millimeters mm Dimensions in inches ()



Ordering Information (Typical)

Model Number	Options	Speed	Package
ACT-PD1M16N-070L4I	None	70ns	42 Lead SOJ
ACT-PD1M16W-070L4I	Burn-in	70ns	42 Lead SOJ
ACT-PD1M16X-070L4I	Temp Cycle	70ns	42 Lead SOJ
ACT-PD1M16Y-070L4I	Temp Cycle & Burn-in	70ns	42 Lead SOJ
ACT-PD1M16N-070L4T	None	70ns	42 Lead SOJ
ACT-PD1M16W-070L4T	Burn-in	70ns	42 Lead SOJ
ACT-PD1M16X-070L4T	Temp Cycle	70ns	42 Lead SOJ
ACT-PD1M16Y-070L4T	Temp Cycle & Burn-in	70ns	42 Lead SOJ

Part Number Breakdown



Aeroflex Circuit Technology 35 South Service Road Plainview New York 11830 Telephone: (516) 694-6700 FAX: (516) 694-6715

Toll Free Inquiries: 1-(800) 843-1553