PSR: Positive Switching Regulators

PSL-Family

No input to output isolation Single output of 12, 15, 24, 36 or 48 V DC/72...288 W Input voltage up to 144 V DC

- High efficiency up to 96%
- Extremely wide input voltage range
- · Very good dynamic properties
- · Input undervoltage cut-out
- · External output voltage adjustment and inhibit
- Two temperature ranges
- · Continuous no-load and short-circuit proof
- · No derating

Safety according to IEC 950







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Type Survey

Table 1: Type survey

| Nominal output voltage | Nominal output current | Input voltage range | Nominal input voltage | Efficiency | Type designation | Options |
|------------------------|------------------------------|------------------------------------|-----------------------------|------------|---------------------|----------------------|
| U _{o nom} | I _{o nom} | <i>U</i> _i ¹ | <i>U</i> i nom | η | | |
| 12 V | 6 A | 18144 V | 60 V | 89% | PSL 126-7R | -9, L, i, P, C, D, A |
| 15 V | | 22144 V | | 90% | PSL 156-7R | |
| 24 V | | 31144 V | | 94% | PSL 246-7R | |
| 36 V | | 44144 V | 80 V | 95% | PSL 366-7R | |
| 48 V | | 58144 V | | 96% | PSL 486-7R | |

¹ Surges up to 156 V for 2 sec. See data $\Delta U_{\rm lo\ min}$ (min. differential voltage $U_{\rm l}-U_{\rm o}$)

Description

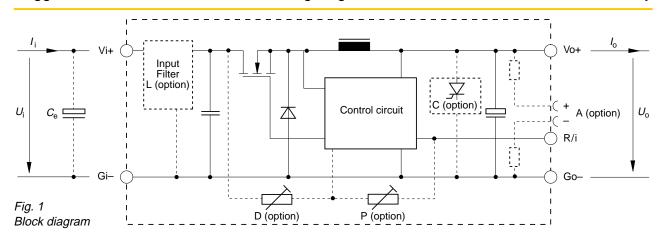
The PSL family of positive swiching regulators is designed as power supply modules for electronic systems. Their major advantages include a high level of efficiency that remains virtually constant over the entire input range, high reliability, low ripple and excellent dynamic response. Modules with input up to 144 V are specially designed for battery driven mobile applications.

Case L04: Aluminium, black finish and self cooling.

External input circuitry

An external capacitor (see "Application Notes") is required in rectifier mode and in DC operation mode only, if the sum of the lengths of the two input lines between source and input (without option L) is greater than approx. 5 m. For long connection lines the use of option L is recommended in order to reduce superimposed interference voltages or currents and to prevent oscillation.





Safety and Installation Instructions

Safety

If the output circuit of a switching regulator is operator-accessible according to the IEC 950 related safety standards, it shall be an SELV circuit (Safety Extra Low Voltage circuit, i.e. a circuit, separated from mains by at least basic insulation, that is so designed and protected that under normal and single fault conditions, the voltage between any two conductors and between any conductor and earth does not exceed 60 V DC).

In the following section an interpretation is provided of the IEC 950 safety standard with respect to the safety status of the output circuit. However, it is the sole responsibility of the

installer or user to assure the compliance with the relevant and applicable safety standards.

If the following table is observed, the output of any switching regulator is considered to be an SELV circuit up to a nominal output voltage of 36 V, or up to 48 V if option C is fitted.

Note: Check for hazardous voltages before altering any connections. Do not open the module. The input and the output circuitry are not separated, i.e. the negative path is internally interconnected!

Table 2: Insulation concept for SELV circuits

| Nominal mains supply voltage (AC) | Minimum required grade of isolation, to be provided by the AC-DC front end, including mains supplied battery charger | Maximum output voltage from the front end | Minimum required safety status of the front end output circuit | Measures to achieve the specified safety status of the output circuit | Resulting safety status of the switching regulator output circuit |
|---|--|---|---|--|---|
| None | Battery supply completely | ≤60 V SELV battery circuit | | None | SELV circuit |
| | separated from mains | ≤144 V | Hazardous voltage battery circuit ² | Input fuse ¹ and unearthed, non operator-accessible case ² | SELV circuit |
| | | | Hazardous voltage battery circuit | Input fuse ¹ and earthed output circuit ³ and earthed ³ or non operator-accessible case | Earthed SELV circuit |
| ≤250 V | Basic | ≤60 V | Earthed SELV circuit | Earthed input circuit 3 | SELV circuit |
| | | | ELV circuit | Input fuse ¹ and earthed output circuit ³ | Earthed SELV circuit |
| | | ≤144 V | Hazardous voltage secondary circuit | Input fuse ¹ and earthed output circuit ³ and earthed ³ or non operator-accessible case | Earthed SELV circuit |
| | Double or reinforced | ≤60 V | SELV circuit | None | SELV circuit |
| | | ≤144 V | Double or reinforced insulated unearthed hazardous voltage secondary circuit ² | Input fuse ¹ and unearthed and non operator-accessible case ² | SELV circuit |

¹ The installer shall provide an approved fuse (slow blow type with lowest rating suitable for the application, max. 12.5 A) in the positive or negative input conductor directly at the input of the switching regulator. For UL's purpose, the fuse needs to be UL-listed. If option C is fitted, a suitable fuse is built-in.

³ The earth connection has to be provided by the installer according to the relevant safety standards, e.g. IEC 950.

² Has to be insulated from earth by double or reinforced insulation according to the relevant safety standard, based on the maximum input voltage of the switching regulator (contrary to case marking: "This apparatus must be earthed.").

Standards and Approvals

All Melcher power supplies are subject to manufacturing surveillance in accordance with ISO 9001 standards.

All units are UL recognized as per UL 1950, UL 1012 and CAN/CSA C22.2 No. 234-M90.

Installation Instructions

The connector pin allocation table defines the electrical potentials and the physical pin position on the connector. Pin no. 32 is the protective ground pin and is protruding, i.e. attaching the female connector, this pin provides electrical contact first. The modules should only be wired via the female connector H11 (according to DIN 41612) to ensure requested safety!

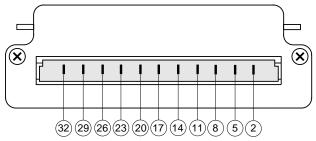


Fig. 2
View of male H11 connector

Protection Degree

The protection degree is defined by IP 30 (equipped with any potentiometer adjustable option: IP 20). The protection degree applies only if the module is plugged-in or the female connector is properly attached to the module.

Table 3: H11 connector pin allocation and designation

| Electrical Determination | Type Pin No. | H11 Design. |
|---|-----------------|----------------|
| R-input (or inhibit input) ¹ | 2 | R (i) |
| Undervoltage monitor (Option D) | 5 | D |
| Output voltage (negative) | 8 | Go- |
| Output voltage (negative) | 11 | Go- |
| Output voltage(positive) | 14 | Vo+ |
| Output voltage (positive) | 17 | Vo+ |
| Input voltage (negative) | 20 | Gi– |
| Input voltage (negative) | 23 | Gi– |
| Input voltage (positive) | 26 | Vi+ |
| Input voltage (positive) | 29 | Vi+ |
| Protective ground (protruding pin) | 32 | |

¹ R-input (output voltage programming) not available with option P (potentiometer) or option i (inhibit)

Immunity to Environmental Conditions

Table 4: Mechanical stress

| Test | Method | Standard | Test Conditions | Status | | |
|------|---|--|--|--|--------------------|--|
| Ca | Damp heat steady state | DIN 40046 part IEC 68-2-3 MIL-STD-810D section 507.2 | Temperature: Relative humidity: Duration: | 40 ±2 °C 93 +2/-3 % 56 days | Unit not operating | |
| Ea | Shock (half-sinusoidal) | DIN 40046 part 7 IEC 68-2-27 MIL-STD-810D section 516.3 | Acceleration amplitude: Bump duration: Number of bumps: | 100 g _n = 981 m/s ² 6 ms 18 (3 each direction) | Unit operating | |
| Eb | Continuous shock (half-sinusoidal) | DIN 40046 part 26 IEC 68-2-29 MIL-STD-810D section 516.3 | Acceleration amplitude: Bump duration: Number of bumps: | $40 g_n = 392 \text{ m/s}^2$ 6 ms 6000 (1000 each direction) | Unit operating | |
| Fc | Vibration (sinusoidal) | DIN 40046 part 8 IEC 68-2-6 MIL-STD-810D section 514.3 | Frequency (1 Oct/min): Max. vibration amplitude: Acceleration amplitude: Test duration: | 102000 Hz 0.35 mm (1060 Hz) 5 g_n = 49 m/s ² (602000 Hz) 7.5 h (2.5 h each axis) | Unit operating | |
| Fda | Random vibration wide band reproducibility high | DIN 40046 part 23 IEC 68-2-35 | Acceleration spectral density: Frequency band: Acceleration magnitude: Test duration: | 0.05 g ² /Hz 20500 Hz 4.9 g _{rms} 3 h (1 h each axis) | Unit not operating | |
| Kb | Salt mist cyclic (sodium chloride NaCl solution) | DIN 40046 part 105 IEC 68-2-52 | Concentration: Duration: Storage: Storage duration: Number of cycles: | 5% (30°C) 2 h per cycle 40°C, 93% rel. humidity 22 h per cycle 3 | Unit not operating | |

Table 5: Temperature specifications

| Temperature | | Stand | ard -7 | Opti | | | |
|----------------|---------------------|---------------------------------------|--------|------|-----|-----|------|
| Char | acteristics | Conditions | min | max | min | max | Unit |
| TA | Ambient temperature | U _{i min} U _{i max} | -25 | 71 | -40 | 71 | °C |
| T _C | Case temperature | $I_0 = 0I_{0 \text{ nom}}$ | -25 | 95 | -40 | 95 | |
| Ts | Storage temperature | Not operational | -40 | 100 | -55 | 100 | |



Table 6: MTBF and device hours

| MTBF | Groun | d Fixed | Ground | Device Hours 1 | |
|----------------------------|---|----------|------------------------------|-------------------------------|-------------|
| MTBF acc. to MIL-HDBK-217D | $T_{\rm C} = 40^{\circ}{\rm C}$ $T_{\rm C} = 70^{\circ}{\rm C}$ | | <i>T</i> _C = 40°C | <i>T</i> _C = 70 °C | |
| | 130'000 h | 58'000 h | 36'000 h | 17'000 h | 3'900'000 h |

¹ Statistical values, based on an average of 4300 working hours per year and in general field use

Electromagnetic Compatibility EMC

Immunity

General condition: Case earthed.

Table 7: Immunity type tests

| Phenomenon | Standard | Class Level | Coupling mode ⁴ | Value applied | Waveform | Source Imped. | Test procedure | In oper. | Per- form |
|-------------------------------------|---|----------------|-------------------------------|----------------------------------|---|------------------|---|-------------|--------------|
| Impulse voltage | IEC 255-4 App. E4 ⁵ (1976) | III | i/o, i/c, o/c +i/–i | 5000 V _p | 1.2/50 µs | 500 Ω | 3 pos. and 3 neg. impulses per coupling mode | no | - |
| High frequency | IEC 255-4 | III | i/o, i/c, o/c | 2500 V _p | 400 damped | 200 Ω | 2 s per | yes | 1 |
| disturbance | App. E5 ⁵ (1976) | | +i/–i | 1000 V _p | 1 MHz waves/s | | coupling mode | | |
| Voltage surge | IEC 571-1 | | i/c, +i/-i | 800 V _p | 100 μs | 100 Ω | | yes | 2 |
| | (1990-07) | | | 1500 V _p | 50 μs | | 1 pos. and 1 neg. voltage surge per coupling mode | | |
| | | | | 3000 V _p | 5 μs | | | | |
| | | | | 4000 V _p | 1 μs | | | | |
| | | | | 7000 V _p | 100 ns | | | | |
| Electrostatic discharge | IEC 801-2 (1991-04) | 4 | contact discharge to case | 8000 V _p | 1/50 ns | 330 Ω | 10 positive and 10 negative discharges | yes | 1 3 6 |
| Electric field | IEC 801-3 (1984) | 3 | antenna in 1m distance | 10 V/m | sine wave mod- ulated w. 1 kHz | | 261000 MHz | yes | 1 |
| Fast transient/ burst | IEC 801-4 (1988) | 4 | i/c, +i/–i | 4000 V _p | bursts of 5/50 ns 5 kHz rep. rate transients with 15 ms burst duration and a 300 ms period | 50 Ω | 1 min positive 1 min negative bursts per coupling mode | yes | 1 3 6 |
| Transient | IEC 801-5 | III | i/c | 2000 V _p | 1.2/50 μs | 12 Ω | 5 pos. and 5 neg. | yes | 1 6 |
| | (Draft 1993-01) | | +i/-i | 1000 V _p | | 2 Ω | impulses per coupling mode | | |
| Immunity to conducted disturbancies | IEC 801-6 | 3 | i, o, signal wires | 10 V _{rms} ⁷ | 80% amplitude modulated with 1 kHz | 50 Ω | AM 0.1580 MHz | yes | 1 |

¹ Normal operation, no deviation from specifications

Emission

For emission levels refer to "Electrical Input and Output Data".

² Normal operation, temporary deviation from specs possible

³ With option C: manual reset

⁴ i = input, o = output, c = case

⁵ In correspondance with DIN 57435 part 303 and VDE 0435 part 303 (1984-09)

⁶ Option L neccessary

⁷ Open circuit

Electrical Input and Output Data

General Conditions

- $T_A = 25$ °C, unless T_C is specified.
- With R or option P, output voltage $U_0 = U_0$ nom at I_0 nom

Table 8a: Input and output data

| Charac | eteristics | Conditions | P | SL 12 | 6 | PSL 156 | | PSL 246 | | Unit | | |
|---------------------------|---|--|-------|-------|-------------|---------|------|-------------|-------|------|-------|------------------|
| | | | min | typ | max | min | typ | max | min | typ | max | |
| Output | <u>t</u> | | | | | | | | | | | |
| U _{o nom} | Output voltage | U _{i nom} , I _{o nom} | 11.92 | | 12.07 | 14.91 | | 15.09 | 23.85 | | 24.14 | V |
| I _{o nom} | Output current | U _{i min} U _{i max} | | 6.0 | | | 6.0 | | | 6.0 | | Α |
| <i>I</i> _{oL} | Output current limitation response | T _{C min} T _{C max} | 6.0 | | 7.8 | 6.0 | | 7.8 | 6.0 | | 7.8 | |
| u _o | Ripple at output (BW = 20 MHz) | U _{i nom} I _{o nom} | | 55 | 75 | | 80 | 100 | | 80 | 120 | mV _{pp} |
| Δ <i>U</i> _{o U} | Static control deviation versus input voltage U_i | U _{i min} U _{i max} | | 25 | 40 | | 25 | 40 | | 80 | 100 | mV |
| Δ <i>U</i> ₀₁ | Static control deviation versus output current I_0 | $U_{i \text{ nom}}$ $I_{o} = 0I_{o \text{ nom}}$ | | 30 | 50 | | 30 | 50 | | 60 | 100 | |
| u _{o d} | Dynamic control deviation ¹ | $I_{\text{o nom}} \leftrightarrow 1/3 I_{\text{o nom}}$ | | 100 | | | 100 | | | 120 | | |
| t _r | Dynamic load transient time recovery ¹ | | | 60 | | | 60 | | | 80 | | μs |
| α_{uo} | Temperature coefficient $\Delta U_{\rm o}/\Delta T_{\rm C}$ | $U_{\text{i min}}U_{\text{i max}}$ $T_{\text{C min}}T_{\text{C max}}$ $I_{\text{0}} = 0I_{\text{0 nom}}$ | | | ±2 ±0.02 | | | ±3 ±0.02 | | | ±5 | mV/k |
| Input | | I ₀ = 0I ₀ nom | | | ±0.02 | | | ±0.02 | | | ±0.02 | 70/K |
| U _i | Input voltage 5 | $I_0 = 0I_{0 \text{ nom}}$ $T_{C \text{ min}}T_{C \text{ max}}$ | 18 | | 144 | 22 | | 144 | 31 | | 144 | V DC |
| $\Delta U_{io\;min}$ | Minimum differential voltage U_i - U_0^2 | | | 6 | | | 7 | | | 7 | | V |
| U _{i o} | Undervoltage cut-out | | | 12 | | | 15 | | | 19 | | _ |
| ľю | No load input current | $I_0 = 0$ $U_{i \text{ min}}U_{i \text{ max}}$ | | 35 | | | 35 | | | 35 | | mA |
| <i>I</i> _{i m} | Peak value of inrush current ³ | U _{i nom} | | 250 | | | 250 | | | 250 | | А |
| t _{is} | Rise time ³ | | | 5 | | | 5 | | | 5 | | μs |
| t _{i r} | Tail half value time ³ | [| | 40 | | | 40 | | | 40 | | 7 |
| l _{i m} | Peak value of inrush current ³ | U _{i nom} with option L | | 350 | | | 350 | | | 350 | | А |
| t _{is} | Rise time ³ | | | 25 | | | 25 | | | 25 | | μs |
| t _{ir} | Tail half value time ³ | | | 125 | | | 125 | | | 125 | | |
| u i rfi | RFI level at input, ⁴ 0.0130 MHz | VDE 0871 (6.78) <i>U</i> _{i minmax} , <i>I</i> _{o nom} | | | В | | | В | | | В | dB (μV) |
| Efficie | ncy | | | | | | | | | | | |
| η | Efficiency | U _{i nom} , I _{o nom} | | 89 | | | 90 | | | 94 | | % |
| Isolatio | on | | | | | | | | | | | |
| Uis | Isolation test voltage electronics to case | Inputs/outputs interconnected | | 1500 | | | 1500 | | | 1500 | | V DC |

¹ See "Dynamic characteristics"



² The minimum differential voltage $\Delta U_{\text{io min}}$ between input and output increases linearly from 0 to 1 V at T_{A} = 46°C and 71°C (T_{C} = 70°C and 95°C)

³ Definitions according to VDE 0433, part 3

⁴ With option L and additional external input capacitor C_e = 470 μF/200 V, e.g. Chemicon, KME-series or equivalent

⁵ Surges up to 156 V for 2 sec. (complying to LES-DB standard for $U_{\rm N}$ = 110 V)

Table 8b: Input and output data

| Charac | eteristics | Conditions | PSL 366 | | | PSL 486 | | 6 | Unit |
|---------------------------|---|--|---------|------|-------------|---------|------|-------|------------------|
| | | | min | typ | max | min | typ | max | |
| Output | 1 | | | | | | | | |
| U _{o nom} | Output voltage | U _{i nom} , I _{o nom} | 35.78 | | 36.22 | 47.70 | | 48.29 | V |
| I _{o nom} | Output current | U _{i min} U _{i max} | | 6.0 | | | 6.0 | | Α |
| I _{oL} | Output current limitation response | $T_{\text{C min}}T_{\text{C max}}$ | 6.0 | | 7.8 | 6.0 | | 7.8 | |
| u _o | Ripple at output (BW = 20 MHz) | U _{i nom} I _{o nom} | | 80 | 150 | | 100 | 200 | mV _{pp} |
| Δ U _{o U} | Static control deviation versus input voltage U_i | $U_{\text{i min}}U_{\text{i max}}$ $I_{\text{o nom}}$ | | 200 | 300 | | 100 | 200 | mV |
| Δ <i>U</i> ₀ ι | Static control deviation versus output current I_0 | $U_{\text{i nom}}$ $I_{\text{o}} = 0I_{\text{o nom}}$ | | 120 | 200 | | 180 | 250 | |
| u _{o d} | Dynamic control deviation ¹ | $U_{\text{i nom}}$ $I_{\text{o nom}} \leftrightarrow^{1/3} I_{\text{o nom}}$ | | 140 | | | 150 | | |
| t _r | Dynamic load transient time recovery ¹ | | | 100 | | | 100 | | μs |
| α_{uo} | Temperature coefficient $\Delta U_{\rm o}/\Delta T_{\rm C}$ | $U_{i \text{ min}}U_{i \text{ max}}$ $T_{C \text{ min}}T_{C \text{ max}}$ $I_{0} = 0I_{0 \text{ nom}}$ | | | ±8 ±0.02 | | | ±10 | mV/K |
| Input | | 10 01110110111 | | | | 1 | | | 1 |
| U _i | Input voltage 5 | $I_0 = 0I_{0 \text{ nom}}$ $T_{C \text{ min}}T_{C \text{ max}}$ | 44 | | 144 | 58 | | 144 | V DC |
| $\Delta U_{io\;min}$ | Minimum differential voltage U_i - U_0^2 | - | | 8 | | | 10 | | V |
| U _{i o} | Undervoltage cut-out | | | 29 | | | 40 | | |
| ħο | No load input current | $I_0 = 0$ $U_{i \text{ min}}U_{i \text{ max}}$ | | 40 | | | 45 | | mA |
| l _{i m} | Peak value of inrush current ³ | U _{i nom} | | 250 | | | 250 | | Α |
| t _{is} | Rise time ³ | | | 5 | | | 5 | | μs |
| t _{ir} | Tail half value time ³ | | | 40 | | | 40 | | |
| <i>l</i> i m | Peak value of inrush current ³ | U _{i nom} with option L | | 350 | | | 350 | | А |
| t _{is} | Rise time ³ | | | 25 | | | 25 | | μs |
| t _{ir} | Tail half value time ³ | | | 125 | | | 125 | | |
| U i rfi | RFI level at input, ⁴ 0.0130 MHz | VDE 0871 (6.78) <i>U</i> _{i nom} , <i>I</i> _{o nom} | | | В | | | В | dB (μV) |
| Efficie | ncy | | | | | | | | |
| η | Efficiency | U _{i minmax} , I _{o nom} | | 95 | | | 96 | | % |
| Isolatio | on | | | | | | | | |
| Uis | Isolation test voltage electronics to case | Inputs/outputs interconnected | | 1500 | | | 1500 | | V DC |

¹ See "Dynamic characteristics"

² The minimum differential voltage $\Delta U_{\text{io min}}$ between input and output increases linearly from 0 to 1 V at T_A = 46°C and 71°C $(T_C = 70$ °C and 95 °C)

³ Definitions according to VDE 0433, part 3

⁴ With option L and additional external input capacitor C_e = 470 μF/200 V, e.g. Chemicon, KME-series or equivalent ⁵ Surges up to 156 V for 2 sec. (complying to LES-DB standard for U_N = 110 V)

Characteristics and Definitions

Output Protection

A voltage suppressor diode protects the output against an internally generated overvoltage, which could occur due to a failure of the control circuit, which in worst case conditions fails into a short circuit. The suppressor diode is not designed to withstand externally applied overvoltages. The user should ensure that systems with Melcher power supplies, in the event of a failure, do not result in an unsafe condition (fail-safe).

Dynamic Characteristics

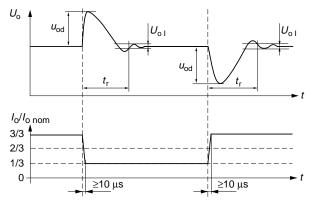


Fig. 3
Behaviour and characteristics under varying load conditions.

Temperature

When a converter is located in free, quasi-stationary air at a temperature $T_A = 71$ °C and is operated at its nominal output power, the case temperature T_C will be about 95°C after the warm-up phase measured at the measuring point of case temperature T_C (see "Mechanical Data").

Under practical operating conditions, the ambient temperature T_A may exceed 71°C, provided additional measures are taken to ensure that the case temperature T_C does not exceed its maximum value of 95°C (heat sink, fan, etc.).

Example: Sufficient forced cooling allows $T_{\rm A\ max} = 85\,^{\circ}{\rm C}$. A simple check of the case temperature $T_{\rm C}$ ($T_{\rm C} \le 95\,^{\circ}{\rm C}$) at full load ensures correct operation of the system

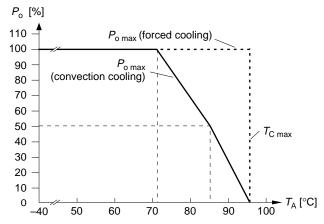


Fig. 4
Output power derating versus ambient temperature

Parallel and Series Connection

Outputs of equal nominal voltages can be parallel-connected. However, the use of a single unit with higher output power, because of its power dissipation, is always a better solution.

In parallel-connected operation, one or several outputs may operate continuously at their current limit knee-point which will cause an increase of the case temperature. Consequently, the max. ambient temperature value should be reduced by 10 K.

Outputs can be series-connected with any other module. In series-connection the maximum output current is limited by the lowest current limitation. Galvanically separated source voltages are needed for each module!

Short circuit behaviour

A constant current limitation circuit holds the output current almost constant whenever an overload or a short circuit is applied to the regulator's output. It acts self-protecting and recovers - in contrary to the fold back method - automatically after removal of the overload or short circuit condition.

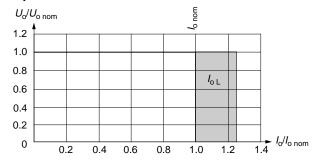


Fig. 5
Overload, short-circuit behaviour U₀ versus I₀

Standard Features

R External Output Voltage Adjustment

Note: With open R input, $U_0 = U_{0 \text{ nom}}$.

R-input together with option i or option P cannot be

supported simultaneously.

The output voltage U_0 can either be adjusted with an external resistor (R_1 or R_2) or with an external voltage (U_{ex}). The adjustment range is 0...1.08 of Uo nom. The minimal differential voltage $\Delta U_{\text{io min}}$ between input and output should be maintained (see data). Min. input = Undervoltage cut-out.

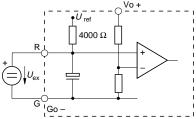


Fig. 6 Voltage adjustment with Uex [V] between R and G (Go-):

a)
$$U_0 \approx U_{\text{ex}} \bullet \frac{U_{\text{o nom}}}{U_{\text{ref}}}$$

$$(U_{\text{ref}} = 2.5 \text{ V } \pm 4\%)$$

Caution: To prevent damage U_{ex} should not exceed 2.7 V, nor be negative.

Voltage adjustment with external resistor R_1 or $R_2[\Omega]$

4000 Ω

b) $U_0 = 0...100 \% U_{0 \text{ nom}}$, using R_1 between R and G (Go-):

$$U_0 \approx U_{0 \text{ nom}} \bullet \frac{R_1}{R_1 + 4000}$$

$$R_1 \approx \frac{4000 \cdot U_0}{U_{0 \text{ nom}} - U_0}$$

c) $U_0 = U_{0 \text{ nom}}...U_{0 \text{ max}}$, using R_2 between R and Vo+: $U_{\text{o max}} = U_{\text{o nom}} + 8\%$

$$U_0 \approx U_{\text{ref}} \cdot \frac{R_2}{\text{k} \cdot (R_2 + 4000) - 4000}$$

$$k = \frac{U_{ref}}{U_{e norm}}$$

$$R_2 \approx 4000 \bullet \frac{U_0 \bullet (1-k)}{k \bullet U_0 - U_{ref}}$$

$$(U_{\text{ref}} = 2.5 \text{ V} \pm 4\%)$$

All formulae give approximate values only.

Description of Options

Option i Inhibit

Note: With open i-input, output is enabled ($U_0 = on$) Inhibit excludes R function.

The inhibit input allows the switching regulators to be disabled via a control signal. In systems with several units, this feature can be used, for example, to control the activation sequence of the regulators by a logic signal (TTL, C-MOS, etc.).

An output voltage overshoot will not occur when the units are switched on or off.

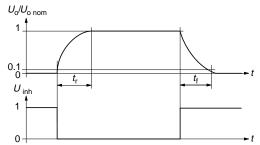


Fig. 9 Output response as a function of inhibit signal

Data

Table 9: Inhibit characteristics

| <i>U</i> _o / <i>U</i> _{o nom} 1 | | |
|---|----------------|------------------|
| | | |
| 0.1 <i>U</i> _{inh} | t _r | t _f - |
| 1 - | 1 | |
| 0 + | | <u></u> t |

2.4 4 `i E 3 2 U_{o} on U_{o} off 1

20 10

Fig. 10 Inhibit current I_{inh} versus inhibit voltage U_{inh}

-20 -10

| Charac | teristics | Conditions | min t | ур тах | Unit | |
|--------------------|--|------------------------------|---|--------|------|------|
| U _{inh} | Inhibit input voltage to keep $U_0 = on$ | | U _{i min} U _{i max} | -50 | +0.8 | V DC |
| | regulator output voltage | U _o = off | = off $T_{\text{C min}}T_{\text{C max}}$ | | +50 | |
| t _r | Switch-on time after inhibit co | ommand | U _i = U _{i nom} | | 5 | ms |
| t _f | Switch-off time after inhibit co | ommand | $R_{\rm L} = U_{\rm o \ nom} / I_{\rm o \ nom}$ | | 10 | |
| I _{i off} | Input current when inhibited | Input current when inhibited | | | 10 | mA |

Fig. 8

I inh [mA]

-50 -40

5

Definition of I_{inh} and U_{inh}

Option -9 Extended Temperature Range

The operational ambient temperature range is extended to $T_A = -40...71$ °C.

Option L Input filter

Option L is recommended to reduce superimposed interference voltages, and to prevent oscillations, if input lines exceed approx. 5 m in total length. The fundamental wave (approx. 120 kHz) of the reduced interference voltage between Vi+ and Gi– has, with an input line inductance of 5 μ H a maximum magnitude of 4 mV_{rms}.

The input impedance of the switching regulator at 120 kHz is about 50 m Ω . The harmonics are small in comparison with the fundamental wave. See also data: RFI.

With option L, the maximum permissible additionally superimposed ripple u_i of the input voltage (rectifier mode) at a specified input frequency f_i has the following values:

 $u_{i \text{ max}} = 10 \text{ V}_{pp} \text{ at } 100 \text{ Hz or V}_{pp} = 1000 \text{ Hz}/f_i \bullet 1 \text{ V}$

Option P Potentiometer

Option P and the R-function cannot be supported simultaneously. The output voltage $U_{\rm 0}$ can be adjusted with a screwdriver in the range from 0.92...1.08 of the nominal output voltage $U_{\rm 0\ nom}$.

However, the minimum differential voltage $\Delta \textit{U}_{\text{i o min}}$ between input and output voltages as specified in "Electrical Input and Output Data" should be maintained.

Option U Ambient Temp. Range acc. UL Recognition

Underwriters Laboratories (UL) have approved the PSL family as recognized components up to an ambient temperature of $T_{\rm A\ max}-10$ K given by the upper temperature limit of the standard PCB material. If the full maximum ambient temperature $T_{\rm A\ max}$ is required with UL approval, option U should be requested. It consists of an alternative PCB material with a higher maximum temperature specification.

The European approval boards have in contrast to UL accepted the standard PCB material to be operated up to $T_{\rm A\ max}$ = 71°C without any further precautions.

Option C Thyristor Crowbar

This option is recommended to protect the load against power supply malfunction, but it is not designed to sink external currents.

A fixed-value monitoring circuit checks the output voltage $U_{\rm o}$. When the trigger voltage $U_{\rm oc}$ is reached, the thyristor crowbar triggers and disables the output. It may be deactivated by removal of the input voltage. In case of a switching transistor defect, an internal fuse prevents excessive current.

Note: As a central overvoltage protection device, the crowbar is usually connected to the external load via distributed inductance of the lines. For this reason, the overvoltage at the load can temporarily exceed the trigger voltage $U_{\rm o\,c}$. Depending on the application, further decentralized overvoltage protection elements may have to be used additionally.

Table 10: Crowbar trigger levels

| Characteristics | | Conditions | 12 V | | 15 V | | 24 V | | 36 V | | 48 V | | Unit |
|------------------|-----------------|---|------|-----|------|-----|------|-----|------|------|------|-----|------|
| | | | min | max | min | max | min | max | min | max | min | max | |
| U _{o c} | Trigger voltage | U _{i min} U _{i max} | 13.5 | 16 | 16.5 | 19 | 27 | 31 | 40 | 45.5 | 55 | 60 | V |
| ts | Delay time | $I_{o} = 0I_{o \text{ nom}}$ $T_{C \text{ min}}T_{C \text{ max}}$ | | 1.5 | | 1.5 | | 1.5 | | 1.5 | | 1.5 | μs |

Option D "Save Data", input undervoltage monitor

Note: Output instead of input undervoltage monitor is available on request (option D1).

If the input voltage U_i is below the adjustable threshold voltage U_t , the control circuit for terminal D has low impedance. Terminal D and Go– are connected to a self-conducting field effect transistor (FET). A 0.5 W Zener diode provides protection against overvoltages.

 V_{t} V_{t

Fig. 11 Test circuit with definition of voltage U_D and current I_D on Terminal D.

The voltage U_t can be externally adjusted with a trim potentiometer by means of a screwdriver. The hysteresis U_H of U_t is <2%. Terminal D stays low for a minimum time $t_{low\ min}$, in order to prevent any oscillation. U_t can be set to a value between $U_{i\ min}$ and $U_{i\ max}$ according to fig. 10. It is important to note that the FET can become conductive again when $U_D > U_i - 3V$.

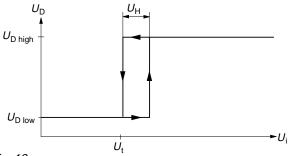


Fig. 12 Definition of U_t and U_H

Data

Table 11: Option D data

| Characteristics | | Conditions | PSL | | | Unit |
|---------------------|--|---|------|-----|-----|------|
| | | | min | typ | max | |
| U _{D low} | Voltage - Terminal D at low impedance | $U_{\rm i} < U_{\rm t}, \ I_{\rm D} \le 2.5 \ {\rm mA}$ | | | 0.8 | V |
| U _{D high} | Voltage - Terminal D at high impedance | $U_{\rm i} > U_{\rm t} + U_{\rm H}, I_{\rm D} > 25 \ \mu {\rm A}$ | 4.75 | | | |
| tow min | Minimum duration $U_{\text{D low}}$ | | | 30 | | ms |
| t _{D f} | Response time to $U_{\rm D\ low}$ | | | 1 | | μs |
| I _{D max} | Maximum current - Terminal D | | | | 20 | mA |

Application examples

- a) The signal U_D can be utilized in battery powered systems to provide a warning in case of **low batteries**.
- b) In case of power failure, the signal can serve to initiate data save routines.

Option A Test sockets

Test sockets (pin $\emptyset=2$ mm) for measuring the output voltage are located at the front panel of the module. The output voltage is measured internally directly at the connector pins.

Mechanical Data

Dimensions in mm. Tolerances ± 0.3 mm unless otherwise indicated.



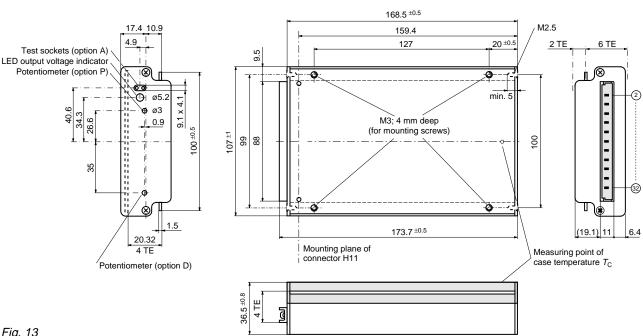


Fig. 13 Case L04 (weight 550 g)

Type Key and Product Marking

Type Key

| | PSL 126-7LiRPCDA |
|--|------------------|
| Positive switching regulator in case L04 PSL Blank | |
| Nominal output voltage in volt | |
| Nominal output current in ampere6 | |
| Ambient temperature range $T_{\rm A} = -2571^{\circ}{\rm C}$ | |
| Input filterL | |
| Inhibit inputi | |
| External output voltage adjustmentR | |
| PotentiometerP | |
| Thyristor-Crowbar C | |
| "Save Data" undervoltage monitor D | |
| Test sockets A | |

Example:PSL 126-7LiPC = A positive switching regulator with a 12 V, 6 A output, ambient temperature range of -25...71°C, input filter, inhibit input, potentiometer and thyristor-crowbar.

Produkt Marking

Main face: Family designation, applicable safety approval and recognition marks, warnings, pin allocation, Melcher patent nos. and company logo.

Front plate: Identification of LED, optional test sockets and potentiometers.

Back plate: Specific type designation, input voltage range, nominal output voltage and current, pin allocation of options and auxiliary functions and degree of protection.

Rear side: Label with batch no., serial no. and data code comprising production site, modification status of the main PCB and production date.