# **1.0 A Output Current, Dual Power Operational Amplifiers**

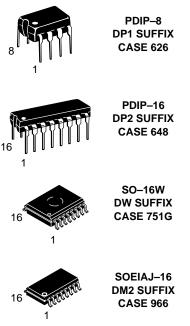
The TCA0372 is a monolithic circuit intended for use as a power operational amplifier in a wide range of applications, including servo amplifiers and power supplies. No deadband crossover distortion provides better performance for driving coils.

- Output Current to 1.0 A
- Slew Rate of 1.3 V/µs
- Wide Bandwidth of 1.1 MHz
- Internal Thermal Shutdown
- Single or Split Supply Operation
- Excellent Gain and Phase Margins
- Common Mode Input Includes Ground
- Zero Deadband Crossover Distortion



### **ON Semiconductor®**

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#### ORDERING INFORMATION

Device	Package	Shipping
TCA0372DW	SO-16W	47 Units/Rail
TCA0372DWR2	SO-16W	1000 Tape & Reel
TCA0372DP1	PDIP-8	50 Units/Rail
TCA0372BDP1	PDIP-8	50 Units/Rail
TCA0372DP2	PDIP-16	25 Units/Rail
TCA0372DM2EL	SOEIAJ-16	2500 Tape & Reel

#### **DEVICE MARKING INFORMATION**

See general marking information in the device marking section on page 6 of this data sheet.

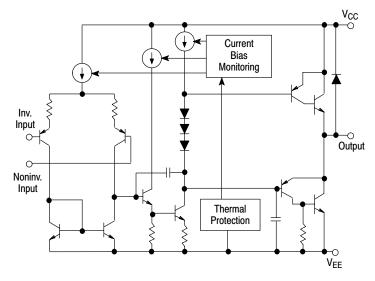
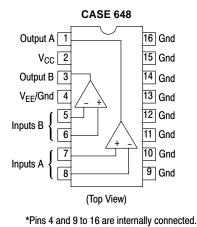
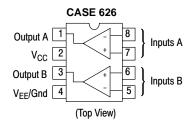
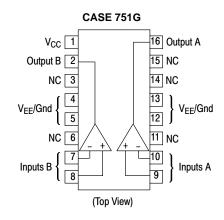


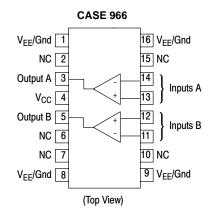
Figure 1. Representative Block Diagram

#### **PIN CONNECTIONS**









#### MAXIMUM RATINGS

Rating	Symbol	Value	Unit
Supply Voltage (from V <sub>CC</sub> to V <sub>EE</sub> )	V <sub>S</sub>	40	V
Input Differential Voltage Range	V <sub>IDR</sub>	Note 1	V
Input Voltage Range	V <sub>IR</sub>	Note 1	V
Junction Temperature (Note 2)	TJ	+150	°C
Operating Temperature Range	T <sub>A</sub>	-40 to +125	°C
Storage Temperature Range	T <sub>stg</sub>	-55 to +150	°C
DC Output Current	I <sub>O</sub>	1.0	А
Peak Output Current (Nonrepetitive)	l <sub>(max)</sub>	1.5	А
Thermal Resistance, Junction–to–Air Case 626 Case 648 Case 751G	R <sub>θJA</sub>	137 72 80	°C/W
Thermal Resistance, Junction–to–Case Case 626 Case 648 Case 751G	R <sub>θJC</sub>	23 10 12	°C/W

Either or both input voltages should not exceed the magnitude of V<sub>CC</sub> or V<sub>EE</sub>.
 Power dissipation must be considered to ensure maximum junction temperature (T<sub>J</sub>) is not exceeded.

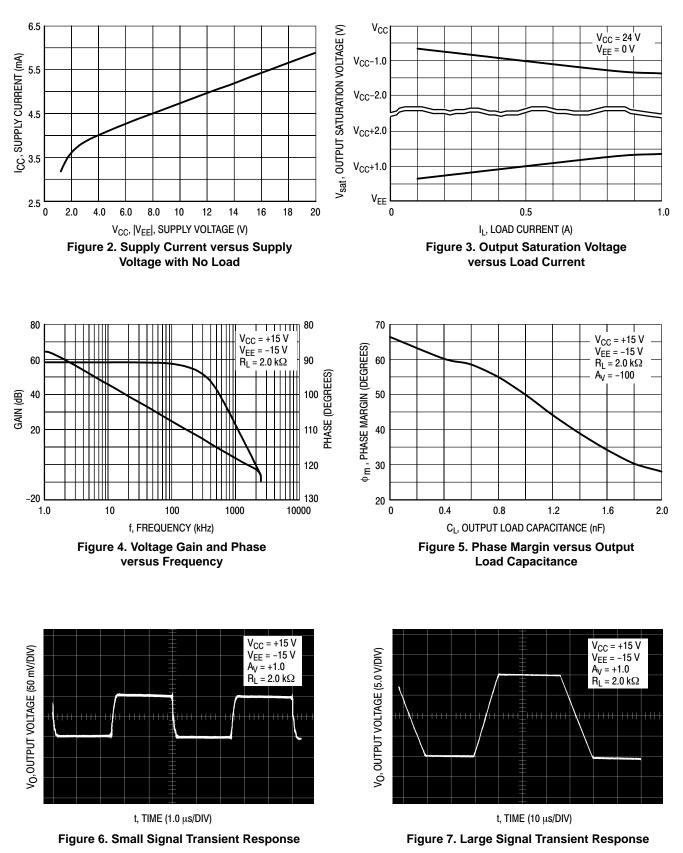
Characteristics	Symbol	Min	Тур	Max	Unit
Input Offset Voltage (V <sub>CM</sub> = 0) $T_A = +25^{\circ}C$ $T_A$ , $T_{low}$ to $T_{high}$	V <sub>IO</sub>		1.0 _	15 20	mV
Average Temperature Coefficient of Offset Voltage	$\Delta V_{IO} / \Delta T$	-	20	-	μV/°C
Input Bias Current (V <sub>CM</sub> = 0)	I <sub>IB</sub>	—	100	500	nA
Input Offset Current (V <sub>CM</sub> = 0)	I <sub>IO</sub>	-	10	50	nA
Large Signal Voltage Gain $V_O = \pm 10 \text{ V}, \text{ R}_L = 2.0 \text{ k}$	A <sub>VOL</sub>	30	100	-	V/mV
Output Voltage Swing ( $I_L = 100 \text{ mA}$ ) $T_A = +25^{\circ}\text{C}$ $T_A = T_{low}$ to $T_{high}$ $T_A = +25^{\circ}\text{C}$ $T_A = T_{low}$ to $T_{high}$	V <sub>OH</sub> V <sub>OL</sub>	14.0 13.9 –	14.2 _ _14.2 _	- - -14.0 -13.9	V
Output Voltage Swing ( $I_L = 1.0 \text{ A}$ ) $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = +25^{\circ}\text{C}$ $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = T_{low} \text{ to } T_{high}$ $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = +25^{\circ}\text{C}$ $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = T_{low} \text{ to } T_{high}$	V <sub>OH</sub> V <sub>OL</sub>	22.5 22.5 –	22.7 - 1.3 -	- - 1.5 1.5	V
Input Common Mode Voltage Range $T_A = +25^{\circ}C$ $T_A = T_{low}$ to $T_{high}$	V <sub>ICR</sub>	V <sub>EE</sub> to (V <sub>CC</sub> –1.0) V <sub>EE</sub> to (V <sub>CC</sub> –1.3)		V	
Common Mode Rejection Ratio (R <sub>S</sub> = 10 k)	CMRR	70	90	-	dB
Power Supply Rejection Ratio ( $R_S = 100 \Omega$ )	PSRR	70	90	-	dB
Power Supply Current $T_A = +25^{\circ}C$ TCA0372TCA0372BTCA0372B $T_A = T_{low}$ to $T_{high}$ TCA0372TCA0372BTCA0372B	Ι <sub>D</sub>		5.0 8.0 –	10 10 14 14	mA

DC ELECTRICAL CHARACTERISTICS (V <sub>CC</sub> = +15 V, V <sub>EE</sub> = -15 V, R <sub>I</sub>	connected to ground, $T_A = -40^\circ$ to +125°C.)
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AC ELECTRICAL CHARACTERISTICS ( $V_{CC}$  = +15 V,  $V_{EE}$  = -15 V,  $R_L$  connected to ground,  $T_A$  = +25°C, unless otherwise noted.)

Characteristics	Symbol	Min	Тур	Max	Unit
Slew Rate (V <sub>in</sub> = -10 V to +10 V, R <sub>L</sub> = 2.0 k, C <sub>L</sub> = 100 pF) A <sub>V</sub> = -1.0, T <sub>A</sub> = T <sub>low</sub> to T <sub>high</sub>	SR	1.0	1.4	-	V/μs
Gain Bandwidth Product (f = 100 kHz, C <sub>L</sub> = 100 pF, R <sub>L</sub> = 2.0 k) T <sub>A</sub> = 25°C T <sub>A</sub> = T <sub>low</sub> to T <sub>high</sub>	GBW	0.9 0.7	1.4 —		MHz
Phase Margin $T_J = T_{low}$ to $T_{high}$ $R_L = 2.0 \text{ k}, C_L = 100 \text{ pF}$	φm	-	65	-	Degrees
Gain Margin $R_L = 2.0 \text{ k}, C_L = 100 \text{ pF}$	A <sub>m</sub>	-	15	-	dB
Equivalent Input Noise Voltage $R_S = 100 \ \Omega$ , f = 1.0 to 100 kHz	e <sub>n</sub>	_	22	_	nV/√Hz
Total Harmonic Distortion $A_V = -1.0$ , $R_L = 50 \Omega$ , $V_O = 0.5$ VRMS, f = 1.0 kHz	THD	-	0.02	-	%

NOTE: In case V<sub>EE</sub> is disconnected before V<sub>CC</sub>, a diode between V<sub>EE</sub> and Ground is recommended to avoid damaging the device.



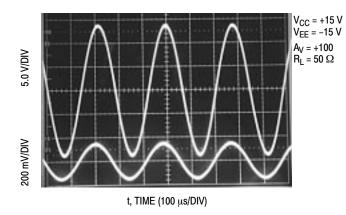
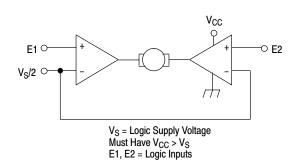
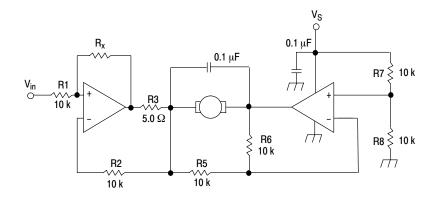


Figure 8. Sine Wave Response



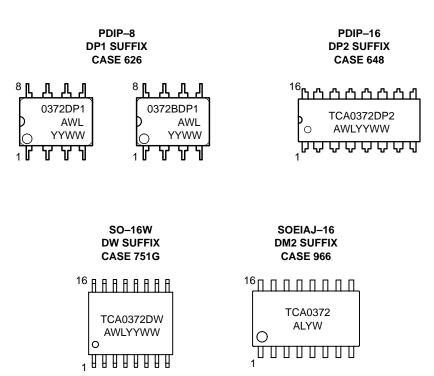
#### Figure 9. Bidirectional DC Motor Control with Microprocessor–Compatible Inputs

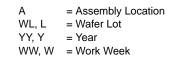


For circuit stability, ensure that  $R_x > \frac{2R3 \cdot R1}{R_M}$  where,  $R_M$  = internal resistance of motor. The voltage available at the terminals of the motor is:  $V_M = 2(V_1 - \frac{V_S}{2}) + |R_0| \cdot I_M$ where,  $|R_0| = \frac{2R3 \cdot R1}{R_X}$  and  $I_M$  is the motor current.

#### Figure 10. Bidirectional Speed Control of DC Motors

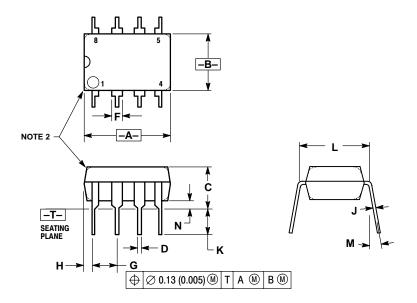
#### MARKING DIAGRAMS





#### PACKAGE DIMENSIONS

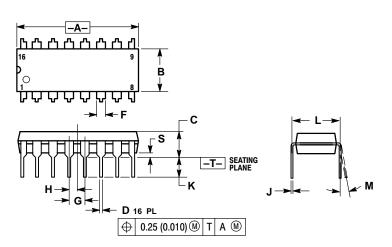
PDIP-8 **DP1 SUFFIX** CASE 626-05 **ISSUE L** 



- NOTES: 1. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL. 2. PACKAGE CONTOUR OPTIONAL (ROUND OR SQUARE CONTERS). 3. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

	MILLIMETERS		INCHES		
DIM	MIN	MAX	MIN	MAX	
Α	9.40	10.16	0.370	0.400	
В	6.10	6.60	0.240	0.260	
С	3.94	4.45	0.155	0.175	
D	0.38	0.51	0.015	0.020	
F	1.02	1.78	0.040	0.070	
G	2.54	2.54 BSC		0.100 BSC	
Н	0.76	1.27	0.030	0.050	
J	0.20	0.30	0.008	0.012	
K	2.92	3.43	0.115	0.135	
L	7.62	BSC	0.300	BSC	
Μ		10°		10°	
N	0.76	1.01	0.030	0.040	

PDIP-16 **DP2 SUFFIX** CASE 648-08 ISSUE R

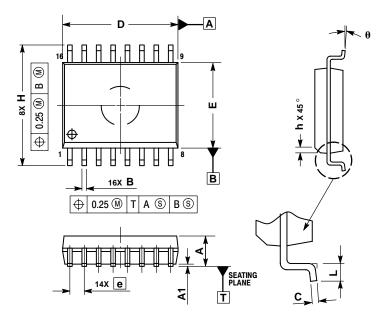


- NOTES: 1. DIMENSIONING AND TOLERANCING PER ANSI
- Y14.5M, 1982. CONTROLLING DIMENSION: INCH. 2.
- 3.
- CUNTRULLING DIMENSION: INCH. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL. DIMENSION B DOES NOT INCLUDE MOLD FLASH. ROUNDED CORNERS OPTIONAL. 4. 5.

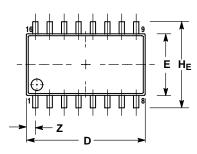
	INCHES		MILLIN	IETERS	
DIM	MIN	MAX	MIN	MAX	
Α	0.740	0.770	18.80	19.55	
В	0.250	0.270	6.35	6.85	
C	0.145	0.175	3.69	4.44	
D	0.015	0.021	0.39	0.53	
F	0.040	0.70	1.02	1.77	
G	0.100	0.100 BSC		2.54 BSC	
Н	0.050	BSC	1.27	BSC	
ſ	0.008	0.015	0.21	0.38	
Κ	0.110	0.130	2.80	3.30	
L	0.295	0.305	7.50	7.74	
М	0°	10 °	0 °	10 °	
S	0.020	0.040	0.51	1.01	

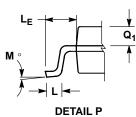
### PACKAGE DIMENSIONS

SO-16W **DW SUFFIX** CASE 751G-03 ISSUE B

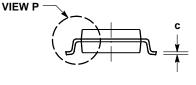


SOEIAJ-16 **DM2 SUFFIX** CASE 966-01 ISSUE O





е Α A<sub>1</sub> -b  $\Box$ 0.10 (0.004) ⊕ 0.13 (0.005) M



- NOTES: 1. DIMENSIONS ARE IN MILLIMETERS.
- INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5M, 1994.
  DIMENSIONS D AND E DO NOT INLCUDE MOLD
- PROTRUSION. 4. MAXIMUM MOLD PROTRUSION 0.15 PER SIDE.
- DIMENSION B DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR 5.
  - PROTRUSION SHALL BE 0.13 TOTAL IN EXCESS OF THE B DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIMETERS				
DIM	MIN MAX				
Α	2.35	2.65			
A1	0.10	0.25			
В	0.35	0.49			
C	0.23	0.32			
D	10.15	10.45			
E	7.40	7.60			
e	1.27	BSC			
Н	10.05	10.55			
h	0.25	0.75			
L	0.50	0.90			
θ	0 °	7 °			

NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  CONTROLLING DIMENSION: MILLIMETER.
  DIMENSIONS D AND E DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS AND ARE MEASURED AT THE PARTING LINE. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.15 (0.006) DED SUDE
- PER SIDE. 4. TERMINAL NUMBERS ARE SHOWN FOR REFERENCE ONLY. 5. THE LEAD WIDTH DIMENSION (b) DOES NOT

INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 (0.003) TOTAL IN EXCESS OF THE LEAD WIDTH DIMENSION AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSIONS AND ADJACENT LEAD TO BE 0.46 (0.018).

	MILLIMETERS		INC	HES
DIM	MIN	MAX	MIN	MAX
Α		2.05		0.081
A <sub>1</sub>	0.05	0.20	0.002	0.008
b	0.35	0.50	0.014	0.020
C	0.18	0.27	0.007	0.011
D	9.90	10.50	0.390	0.413
Ε	5.10	5.45	0.201	0.215
е	1.27 BSC		0.050 BSC	
HE	7.40	8.20	0.291	0.323
L	0.50	0.85	0.020	0.033
LE	1.10	1.50	0.043	0.059
М	0 °	10 °	0 °	10 °
Q <sub>1</sub>	0.70	0.90	0.028	0.035
Z		0.78		0.031

# <u>Notes</u>

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# <u>Notes</u>

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