



#### **General Description**

The MAX11626-MAX11629/MAX11632/MAX11633 are serial 12-bit analog-to-digital converters (ADCs) with an internal reference. These devices feature on-chip FIFO, scan mode, internal clock mode, internal averaging, and AutoShutdown™. The maximum sampling rate is 300ksps using an external clock. The MAX11632/ MAX11633 have 16 input channels; the MAX11628/ MAX11629 have 8 input channels; and the MAX11626/ MAX11627 have 4 input channels. These eight devices operate from either a +3V supply or a +5V supply, and contain a 10MHz SPITM-/QSPITM-/MICROWIRETM-compatible serial port.

The MAX11626-MAX11629 are available in 16-pin QSOP packages. The MAX11632/MAX11633 are available in 24-pin QSOP packages. All eight devices are specified over the extended -40°C to +85°C temperature range.

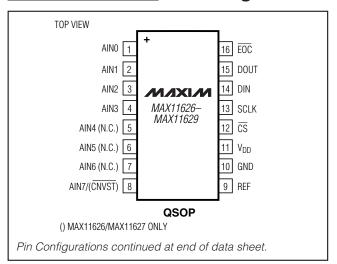
#### **Applications**

System Supervision **Data-Acquisition Systems** Industrial Control Systems Patient Monitoring **Data Logging** Instrumentation

AutoShutdown is a trademark of Maxim Integrated Products, Inc. SPI/QSPI are trademarks of Motorola. Inc.

MICROWIRE is a trademark of National Semiconductor Corp.

#### Pin Configurations



#### **Features**

- ◆ Analog Multiplexer with Track/Hold 16 Channels (MAX11632/MAX11633) 8 Channels (MAX11628/MAX11629) 4 Channels (MAX11626/MAX11627)
- **♦ Single Supply** 2.7V to 3.6V (MAX11627/MAX11629/MAX11633) 4.75V to 5.25V (MAX11626/MAX11628/MAX11632)
- ♦ Internal Reference 2.5V (MAX11627/MAX11629/MAX11633) 4.096V (MAX11626/MAX11628/MAX11632)
- ♦ External Reference: 1V to VDD **♦** 16-Entry First-In/First-Out (FIFO)
- ♦ Scan Mode, Internal Averaging, and Internal Clock
- ♦ Accuracy: ±1 LSB INL, ±1 LSB DNL, No Missing **Codes Over Temperature**
- **♦ 10MHz 3-Wire SPI-/QSPI-/MICROWIRE-Compatible** Interface
- ♦ Small Packages 16-Pin QSOP (MAX11626-MAX11629) 24-Pin QSOP (MAX11632/MAX11633)

#### **Ordering Information**

PART	NUMBER OF INPUTS	SUPPLY VOLTAGE RANGE (V)	PIN PACKAGE
MAX11626EEE+*	4	4.75 to 5.25	16 QSOP
MAX11627EEE+*	4	2.7 to 3.6	16 QSOP
MAX11628EEE+	8	4.75 to 5.25	16 QSOP
MAX11628EEE/V+	8	4.75 to 5.25	16 QSOP
MAX11629EEE+	8	2.7 to 3.6	16 QSOP
MAX11632EEG+	16	4.75 to 5.25	24 QSOP
MAX11633EEG+	16	2.7 to 3.6	24 QSOP

Note: All devices are specified over the -40°C to +85°C operating temperature range.

+Denotes a lead(Pb)-free/RoHS-compliant package.

/V denotes an automotive qualified part.

<sup>\*</sup>Future product—contact for availability.

#### **ABSOLUTE MAXIMUM RATINGS**

V <sub>DD</sub> to GND0.3V to +6V
CS, SCLK, DIN, EOC, DOUT to GND0.3V to (VDD + 0.3V)
AINO-AIN13, AIN_, CNVST/AIN_,
REF to GND0.3V to (V <sub>DD</sub> + 0.3V)
Maximum Current into Any Pin50mA
Continuous Power Dissipation ( $T_A = +70$ °C)
16-Pin QSOP (derate 8.3mW/°C above +70°C)667mW
24-Pin OSOP (derate 9.5mW/ $^{\circ}$ C above +70 $^{\circ}$ C) 762mW

Operating Temperature Range	40°C to +85°C
Storage Temperature Range	60°C to +150°C
Junction Temperature	+150°C
Lead Temperature (soldering, 10s)	+300°C
Soldering Temperature (reflow)	+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $(V_{DD} = +2.7V \ to \ +3.6V \ (MAX11627/MAX11629/MAX11633); \ V_{DD} = +4.75V \ to \ +5.25V \ (MAX11626/MAX11628/MAX11632), \ f_{SAMPLE} = 300kHz, \ f_{SCLK} = 4.8MHz \ (50\% \ duty \ cycle), \ V_{REF} = 2.5V \ (MAX11627//MAX11629/MAX11633); \ V_{REF} = 4.096V \ (MAX11626/MAX11628/MAX11632), \ T_{A} = T_{MIN} \ to \ T_{MAX}, \ unless \ otherwise \ noted. \ Typical \ values \ are \ at \ T_{A} = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
DC ACCURACY (Note 1)	•			•			•
Resolution	RES			12			Bits
Integral Nonlinearity	INL					±1.0	LSB
Differential Nonlinearity	DNL	No missing co	des over temperature			±1.0	LSB
Offset Error					±0.5	±4.0	LSB
Gain Error		(Note 2)			±0.5	±4.0	LSB
Offset Error Temperature Coefficient					±2		ppm/°C FSR
Gain Temperature Coefficient					±0.8		ppm/°C
Channel-to-Channel Offset Matching					±0.1		LSB
DYNAMIC SPECIFICATIONS (30	kHz sine-wav	e input, 2.5V <sub>P-P</sub>	o, 300ksps, f <sub>SCLK</sub> = 4.8MHz)	•			
Signal-to-Noise Plus Distortion	SINAD	MAX11627/MAX11629/MAX11633			71		- dB
Signal-to-Noise Flus Distortion	SINAD	MAX11626/MA	X11628/MAX11632	73			
Total Haussania Diatostian	F	Up to the 5th harmonic	MAX11627/MAX11629/ MAX11633		-80		15
Total Harmonic Distortion	THD		MAX11626/MAX11628/ MAX11632		-88	dB	- ubc
Courier o Free Dunerais Denge	CEDD	MAX11627/MA	X11629/MAX11633		81		dD.
Spurious-Free Dynamic Range	SFDR	MAX11626/MA	X11628/MAX11632	Ì	89		- dBc
Intermodulation Distortion	IMD	fIN1 = 29.9kHz, fIN2 = 30.2kHz			76		dBc
Full-Power Bandwidth		-3dB point			1		MHz
Full-Linear Bandwidth		S/(N + D) > 686	dB		100		kHz

#### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = +2.7 V \text{ to } +3.6 V \text{ (MAX11627/MAX11629/MAX11633)}; V_{DD} = +4.75 V \text{ to } +5.25 V \text{ (MAX11626/MAX11628/MAX11632)}, f_{SAMPLE} = 300 kHz, f_{SCLK} = 4.8 MHz (50\% \text{ duty cycle}), V_{REF} = 2.5 V \text{ (MAX11627//MAX11629/MAX11633)}; V_{REF} = 4.096 V \text{ (MAX11626/MAX11628/MAX11632)}, T_{A} = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_{A} = +25 ^{\circ}\text{C.} )$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
CONVERSION RATE							
Power-Up Time	tou	External reference		0.8		110	
Power-op Time	t <sub>PU</sub>	Internal reference (Note 3)		65		μs	
Acquisition Time	t <sub>ACQ</sub>				0.6	μs	
Conversion Time	toony	Internally clocked		3.5		110	
Conversion Time	tCONV	Externally clocked (Note 4)	2.7			μs	
External Clock Frequency	footiv	Externally clocked conversion	0.1		4.8	MHz	
External Clock Frequency	fsclk	Data I/O			10	IVIITZ	
Aperture Delay				30		ns	
Aperture Jitter				< 50		ps	
ANALOG INPUT							
Input Voltage Range		Unipolar	0		VREF	V	
Input Leakage Current		$V_{IN} = V_{DD}$		±0.01	±1	μΑ	
Input Capacitance		During acquisition time (Note 5)		24		pF	
INTERNAL REFERENCE							
REF Output Voltage		MAX11626/MAX11628/MAX11632	4.024	4.096	4.168	V	
NEF Output Voltage		MAX11627/MAX11629/MAX11633	2.48	2.50	2.52	V	
REF Temperature Coefficient	TO	MAX11626/MAX11628/MAX11632 ±20			nnm/°C		
NEF Temperature Coemicient	TC <sub>REF</sub>	MAX11627/MAX11629/MAX11633		±30		ppm/°C	
Output Resistance				6.5		kΩ	
REF Output Noise				200		μVRMS	
REF Power-Supply Rejection	PSRR			-70		dB	
EXTERNAL REFERENCE INPUT	•						
REF Input Voltage Range	V <sub>REF</sub>		1.0	V	D + 50mV	V	
REF Input Current	IREF	V <sub>REF</sub> = 2.5V (MAX11627/MAX11629/ MAX11633); V <sub>REF</sub> = 4.096V (MAX11626/MAX11628/MAX11632), f <sub>SAMPLE</sub> = 300ksps		40	100	μA	
	IKEF	V <sub>REF</sub> = 2.5V (MAX11627/MAX11629/ MAX11633); V <sub>REF</sub> = 4.096V (MAX11626/MAX11628/MAX11632), f <sub>SAMPLE</sub> = 0		±0.1	±5	μΑ	

#### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = +2.7V \text{ to } +3.6V \text{ (MAX11627/MAX11629/MAX11633)}; V_{DD} = +4.75V \text{ to } +5.25V \text{ (MAX11626/MAX11628/MAX11632)}, f_{SAMPLE} = 300kHz, f_{SCLK} = 4.8MHz (50% duty cycle), V_{REF} = 2.5V (MAX11627/MAX11629/MAX11633); V_{REF} = 4.096V (MAX11626/MAX11628/MAX11632), T_{A} = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_{A} = +25^{\circ}\text{C}.)$ 

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
DIGITAL INPUTS (SCLK, DIN, CS	CNVST)							
Innut Valtaga Laur	\ /	MAX11626/M			0.8	V		
Input Voltage Low	VIL	MAX11627/M	AX11629/MAX11633		V	<sub>DD</sub> x 0.3	V	
lanut Valta ea Lliah		MAX11626/M	AX11628/MAX11632	2.0			V	
Input Voltage High	VIH	MAX11627/M	AX11629/MAX11633	V <sub>DD</sub> x 0.7			V	
Input Hysteresis	VHYST				200		mV	
Input Leakage Current	I <sub>IN</sub>	V <sub>IN</sub> = 0V or V	'DD		±0.01	±1.0	μΑ	
Input Capacitance	CIN				15		рF	
DIGITAL OUTPUTS (DOUT, EOC)								
Output Voltage Low	Vol	Isink = 2mA				0.4	V	
Output voltage Low	VOL	I <sub>SINK</sub> = 4mA				0.8	V	
Output Voltage High	VoH	ISOURCE = 1	.5mA	V <sub>DD</sub> - 0.5			V	
Three-State Leakage Current	ΙL	$\overline{\text{CS}} = V_{\text{DD}}$			±0.05	±1	μΑ	
Three-State Output Capacitance	Cout	$\overline{\text{CS}} = V_{\text{DD}}$			15		рF	
POWER REQUIREMENTS								
Supply Voltage	V <sub>DD</sub>	MAX11626/M	AX11628/MAX11632	4.75		5.25	V	
Supply Voltage	VDD	MAX11627/M	AX11629/MAX11633	2.7		3.6	V	
		Internal reference	f <sub>SAMPLE</sub> = 300ksps		1750	2000	μΑ	
NAAV11007/NAAV11000/NAAV11000			fSAMPLE = 0, REF on		1000	1200		
MAX11627/MAX11629/MAX11633 Supply Current (Note 6)	loo	1010101100	Shutdown		0.2	5		
	I <sub>DD</sub>	External	fsample = 300ksps		1050	1200		
		reference	Shutdown		0.2	5		
		Internal	f <sub>SAMPLE</sub> = 300ksps		2300	2550		
NAAV11000/NAAV11000/NAAV11000		reference	fsample = 0, REF on		1050	1350		
MAX11626/MAX11628/MAX11632 Supply Current (Note 6)	I <sub>DD</sub>	Totoloronoo	Shutdown		0.2	5	μΑ	
		External	fsample = 300ksps		1550	1700		
		reference	Shutdown		0.2	5		
Power-Supply Rejection	PSR	$V_{DD} = 2.7V \text{ to}$	o 3.6V; full-scale input		±0.2	±1	mV	
Tower-oupply Hejection	1 311	$V_{DD} = 4.75V$	to 5.25V; full-scale input		±0.2	±1.2	1110	

- Note 1: MAX11627/MAX11629/MAX11633 tested at V<sub>DD</sub> = +3V. MAX11626/MAX11628/MAX11632 tested at V<sub>DD</sub> = +5V.
- Note 2: Offset nulled.
- Note 3: Time for reference to power up and settle to within 1 LSB.
- Note 4: Conversion time is defined as the number of clock cycles multiplied by the clock period; clock has 50% duty cycle.
- Note 5: See Figure 3 (Equivalent Input Circuit) and the Sampling Error vs. Source Impedance curve in the *Typical Operating Characteristics* section.
- Note 6: Supply current is specified depending on whether an internal or external reference is used for voltage conversions.

#### **TIMING CHARACTERISTICS (Figure 1)**

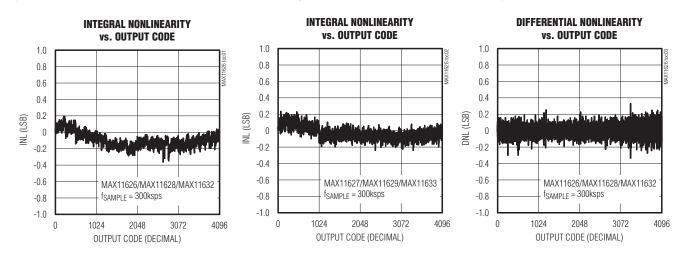
 $(V_{DD} = +2.7V \text{ to } +3.6V \text{ (MAX11627/MAX11629/MAX11633)}; V_{DD} = +4.75V \text{ to } +5.25V \text{ (MAX11626/MAX11628/MAX11632)}, f_{SAMPLE} = 300kHz, f_{SCLK} = 4.8MHz \text{ (50\% duty cycle)}, V_{REF} = 2.5V \text{ (MAX11627//MAX11629/MAX11633)}; V_{REF} = 4.096V \text{ (MAX11626/MAX11632)}, T_{A} = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.} Typical values are at T_{A} = +25°C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
CCL I/ Cloudy Davie d	+	Externally clocked conversion	208			
SCLK Clock Period	tCP	Data I/O	100			ns
SCLK Pulse Width High	tсн		40			ns
SCLK Pulse Width Low	tCL		40			ns
SCLK Fall to DOUT Transition	tDOT	C <sub>LOAD</sub> = 30pF			40	ns
CS Rise to DOUT Disable	tDOD	C <sub>LOAD</sub> = 30pF			40	ns
CS Fall to DOUT Enable	tDOE	C <sub>LOAD</sub> = 30pF			40	ns
DIN to SCLK Rise Setup	t <sub>DS</sub>		40			ns
SCLK Rise to DIN Hold	tDH		0			ns
CS Low to SCLK Setup	tcsso		40			ns
CS High to SCLK Setup	tCSS1		40			ns
CS High After SCLK Hold	tCSH1		0			ns
CS Low After SCLK Hold	tCSH0		0		4	μs
CNVST Pulse Width Low	tcspw	CKSEL = 00	40			ns
CINVST Pulse Width Low		CKSEL = 01	1.4			μs
CS or CNVST Rise to EOC		Voltage conversion			7	
Low (Note 7)		Reference power-up			65	· µs

Note 7: This time is defined as the number of clock cycles needed for conversion multiplied by the clock period. If the internal reference needs to be powered up, the total time is additive.

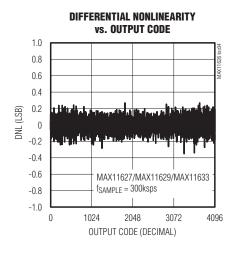
#### **Typical Operating Characteristics**

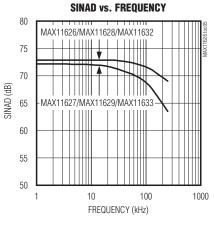
(VDD = +3V, VREF = +2.5V, fSCLK = 4.8MHz, CLOAD = 30pF, TA = +25°C, unless otherwise noted.)

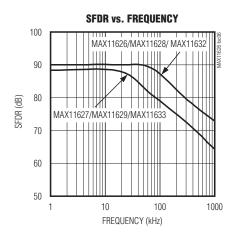


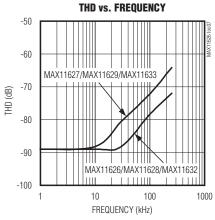
#### Typical Operating Characteristics (continued)

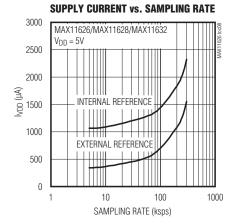
 $(V_{DD} = +3V, V_{REF} = +2.5V, f_{SCLK} = 4.8MHz, C_{LOAD} = 30pF, T_{A} = +25^{\circ}C, unless otherwise noted.)$ 

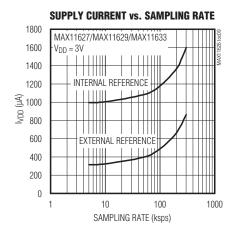


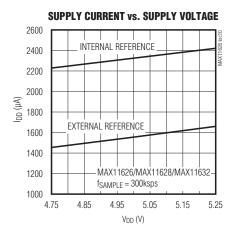








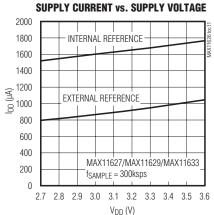


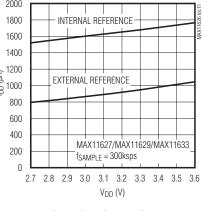


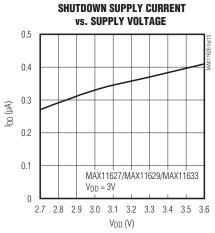
## 12-Bit 300ksps ADCs with FIFO, Temp Sensor, Internal Reference

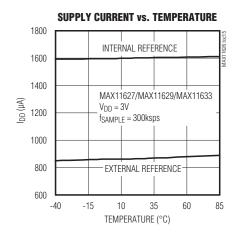
#### **Typical Operating Characteristics (continued)**

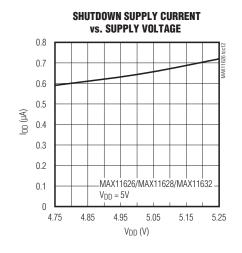
 $(V_{DD} = +3V, V_{REF} = +2.5V, f_{SCLK} = 4.8MHz, C_{LOAD} = 30pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 

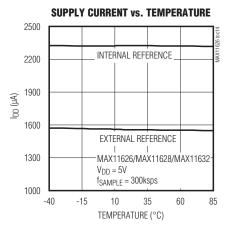


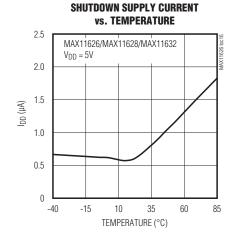






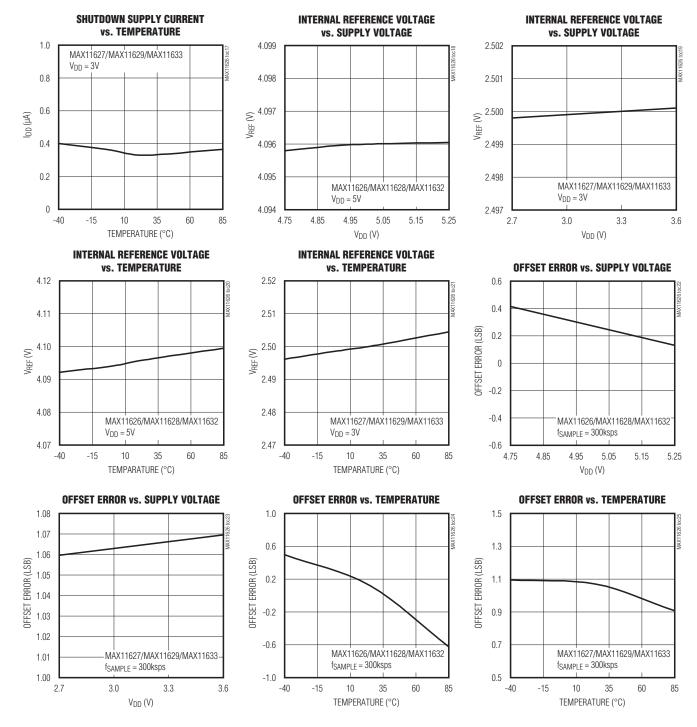






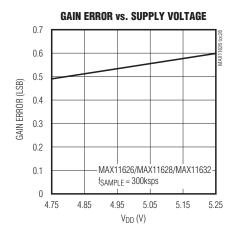
#### **Typical Operating Characteristics (continued)**

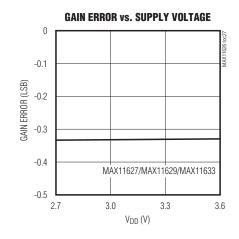
 $(V_{DD} = +3V, V_{REF} = +2.5V, f_{SCLK} = 4.8MHz, C_{LOAD} = 30pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 

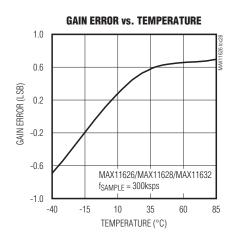


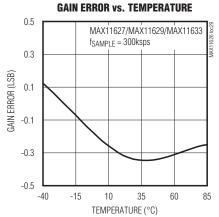
#### **Typical Operating Characteristics (continued)**

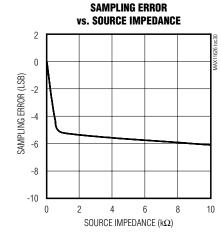
 $(V_{DD} = +3V, V_{REF} = +2.5V, f_{SCLK} = 4.8MHz, C_{LOAD} = 30pF, T_{A} = +25^{\circ}C, unless otherwise noted.)$ 











#### **Pin Description**

MAX11626 MAX11627 (4 CHANNELS)	MAX11628 MAX11629 (8 CHANNELS)	MAX11632 MAX11633 (16 CHANNELS)	NAME	FUNCTION
5, 6, 7	_	_	N.C.	No Connection. Not internally connected.
_	_	1–15	AIN0-AIN14	Analog Inputs
_	1–7	_	AIN0-AIN6	Analog Inputs
1–4	_		AIN0-AIN3	Analog Inputs
_	_	16	CNVST/AIN15	Active-Low Conversion Start Input/Analog Input 15. See Table 3 for details on programming the setup register.
_	8	_	CNVST/AIN7	Active-Low Conversion Start Input/Analog Input 7. See Table 3 for details on programming the setup register.
8	_	_	CNVST	Active-Low Conversion Start Input. See Table 3 for details on programming the setup register.
9	9	17	REF	Reference Input. Bypass to GND with a 0.1µF capacitor.
10	10	18	GND	Ground
11	11	19	$V_{DD}$	Power Input. Bypass to GND with a 0.1µF capacitor.
12	12	20	<del>C</del> S	Active-Low Chip-Select Input. When $\overline{CS}$ is low, the serial interface is enabled. When $\overline{CS}$ is high, DOUT is high impedance.
13	13	21	SCLK	Serial Clock Input. Clocks data in and out of the serial interface. (Duty cycle must be 40% to 60%.) See Table 3 for details on programming the clock mode.
14	14	22	DIN	Serial Data Input. DIN data is latched into the serial interface on the rising edge of SCLK.
15	15	23	DOUT	Serial Data Output. Data is clocked out on the falling edge of SCLK. High impedance when $\overline{\text{CS}}$ is connected to $V_{DD}$ .
16	16	24	EOC	End of Conversion Output. Data is valid after EOC pulls low.

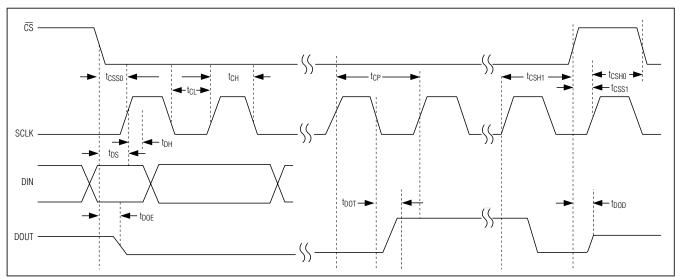


Figure 1. Detailed Serial-Interface Timing Diagram

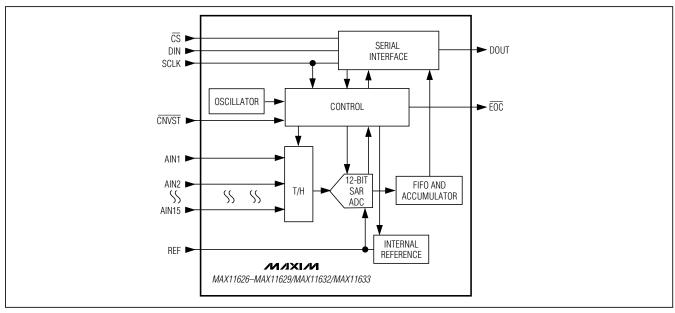


Figure 2. Functional Diagram

#### **Detailed Description**

The MAX11626–MAX11629/MAX11632/MAX11633 are low-power, serial-output, multichannel ADCs with FIFO capability for system monitoring, process-control, and instrumentation applications. These 12-bit ADCs have internal track and hold (T/H) circuitry supporting single-ended inputs. Data is converted from analog voltage sources in a variety of channel and data-acquisition configurations. Microprocessor (µP) control is made easy

through a 3-wire SPI-/QSPI-/MICROWIRE-compatible serial interface.

Figure 2 shows a simplified functional diagram of the MAX11626–MAX11629/MAX11632/MAX11633 internal architecture. The MAX11632/MAX11633 have 16 single-ended analog input channels. The MAX11628/MAX11629 have 8 single-ended analog input channels. The MAX11626/MAX11627 have 4 single-ended analog input channels.

#### **Converter Operation**

The MAX11626–MAX11629/MAX11632/MAX11633 ADCs use a successive-approximation register (SAR) conversion technique and an on-chip T/H block to convert voltage signals into a 12-bit digital result. This single-ended configuration supports unipolar signal ranges.

#### Input Bandwidth

The ADC's input-tracking circuitry has a 1MHz small-signal bandwidth, so it is possible to digitize high-speed transient events and measure periodic signals with bandwidths exceeding the ADC's sampling rate by using undersampling techniques. Anti-alias prefiltering of the input signals is necessary to avoid high-frequency signals aliasing into the frequency band of interest.

#### **Analog Input Protection**

Internal ESD protection diodes clamp all pins to  $V_{DD}$  and GND, allowing the inputs to swing from (GND - 0.3V) to ( $V_{DD}$  + 0.3V) without damage. However, for accurate conversions near full scale, the inputs must not exceed  $V_{DD}$  by more than 50mV or be lower than GND by 50mV. If an off-channel analog input voltage exceeds the supplies, limit the input current to 2mA.

#### **3-Wire Serial Interface**

The MAX11626–MAX11629/MAX11632/MAX11633 feature a serial interface compatible with SPI/QSPI and MICROWIRE devices. For SPI/QSPI, ensure the CPU serial interface runs in master mode so it generates the serial clock signal. Select the SCLK frequency of 10MHz or less, and set clock polarity (CPOL) and phase (CPHA) in the  $\mu P$  control registers to the same value. The MAX11626–MAX11629/MAX11632/MAX11633 operate with SCLK idling high or low, and thus operate with CPOL = CPHA = 0 or CPOL = CPHA = 1. Set  $\overline{CS}$  low to latch input data at DIN on the rising edge of SCLK. Output data at DOUT is updated on the falling edge of SCLK. Results are output in binary format.

Serial communication always begins with an 8-bit input data byte (MSB first) loaded from DIN. A high-to-low transition on  $\overline{CS}$  initiates the data input operation. The input data byte and the subsequent data bytes are clocked from DIN into the serial interface on the rising edge of SCLK. Tables 1–5 detail the register descriptions. Bits 5 and 4, CKSEL1 and CKSEL0, respectively, control the clock modes in the setup register (see Table 3). Choose between four different clock modes for various ways to start a conversion and determine whether the acquisitions are internally or externally timed. Select clock mode 00 to configure  $\overline{CNVST}/AIN_{-}$  to act as a conversion start and use it to request the programmed, internally timed conversions without tying up the serial

bus. In clock mode 01, use  $\overline{\text{CNVST}}$  to request conversions one channel at a time, controlling the sampling speed without tying up the serial bus. Request and start internally timed conversions through the serial interface by writing to the conversion register in the default clock mode 10. Use clock mode 11 with SCLK up to 4.8MHz for externally timed acquisitions to achieve sampling rates up to 300ksps. Clock mode 11 disables scanning and averaging. See Figures 4–7 for timing specifications and how to begin a conversion.

These devices feature an active-low, end-of-conversion output. EOC goes low when the ADC completes the last requested operation and is waiting for the next input data byte (for clock modes 00 and 10). In clock mode 01, EOC goes low after the ADC completes each requested operation. EOC goes high when CS or CNVST goes low. EOC is always high in clock mode 11.

#### Single-Ended Inputs

The single-ended analog input conversion modes can be configured by writing to the setup register (see Table 3). Single-ended conversions are internally referenced to GND (see Figure 3).

AINO-AIN3 are available on the MAX11626-MAX11629/ MAX11632/MAX11633. AIN4-AIN7 are only available on the MAX11628-MAX11633. AIN8-AIN15 are only available on the MAX11632/MAX11633. See Tables 2-5 for more details on configuring the inputs. For the inputs that can be configured as CNVST or an analog input, only one can be used at a time.

#### Unipolai

The MAX11626–MAX11629/MAX11632/MAX11633 always operate in unipolar mode. The analog inputs are internally referenced to GND with a full-scale input range from 0 to VREF.

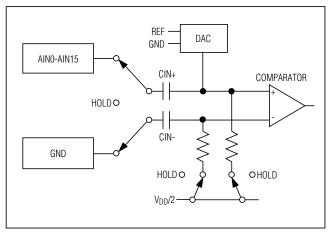


Figure 3. Equivalent Input Circuit

#### True Differential Analog Input T/H

The equivalent circuit of Figure 3 shows the MAX11626–MAX11629/MAX11632/MAX11633's input architecture. In track mode, a positive input capacitor is connected to AIN0–AIN15. A negative input capacitor is connected to GND. For external T/H timing, use clock mode 01. After the T/H enters hold mode, the difference between the sampled positive and negative input voltages is converted. The time required for the T/H to acquire an input signal is determined by how quickly its input capacitance is charged. If the input signal's source impedance is high, the required acquisition time lengthens. The acquisition time, tACQ, is the maximum time needed for a signal to be acquired, plus the power-up time. It is calculated by the following equation:

$$t_{ACQ} = 9 \times (R_S + R_{IN}) \times 24pF + t_{PWR}$$

where  $R_{IN}=1.5k\Omega,\,R_S$  is the source impedance of the input signal, and  $t_{PWR}=1\mu s$ , the power-up time of the device. The varying power-up times are detailed in the explanation of the clock mode conversions.  $t_{ACQ}$  is never less than 1.4µs, and any source impedance below  $300\Omega$  does not significantly affect the ADC's AC performance. A high-impedance source can be accommodated either by lengthening  $t_{ACQ}$  or by placing a  $1\mu F$  capacitor between the positive and negative analog inputs.

#### Internal FIFO

The MAX11626–MAX11629/MAX11632/MAX11633 contain a FIFO buffer that can hold up to 16 ADC results. This allows the ADC to handle multiple internally clocked conversions, without tying up the serial bus. If the FIFO is filled and further conversions are requested without reading from the FIFO, the oldest ADC results are overwritten by the new ADC results. Each result contains 2 bytes, with the MSB preceded by four leading zeros. After each falling edge of  $\overline{CS}$ , the oldest available byte of data is available at DOUT, MSB first. When the FIFO is empty, DOUT is zero.

#### **Internal Clock**

The MAX11626–MAX11629/MAX11632/MAX11633 operate from an internal oscillator, which is accurate within 10% of the 4.4MHz nominal clock rate. The internal

oscillator is active in clock modes 00, 01, and 10. Read out the data at clock speeds up to 10MHz. See Figures 4–7 for details on timing specifications and starting a conversion.

#### Applications Information

#### **Register Descriptions**

The MAX11626–MAX11629/MAX11632/MAX11633 communicate between the internal registers and the external circuitry through the SPI-/QSPI-compatible serial interface. Table 1 details the registers and the bit names. Tables 2–5 show the various functions within the conversion register, setup register, averaging register, and reset register.

#### **Conversion Time Calculations**

The conversion time for each scan is based on a number of different factors: conversion time per sample, samples per result, results per scan, and if the external reference is in use.

Use the following formula to calculate the total conversion time for an internally timed conversion in clock modes 00 and 10 (see the *Electrical Characteristics* section as applicable):

Total Conversion Time = t<sub>CNV</sub> x n<sub>AVG</sub> x n<sub>RESULT</sub> + t<sub>RP</sub> where

 $t_{CNV} = t_{ACQ} (max) + t_{CONV} (max).$ 

navg = samples per result (amount of averaging).

nresult = number of FIFO results requested; determined by the number of channels being scanned or by NSCAN1, NSCAN0.

 $t_{RP}$  = internal reference wake-up; set to zero if internal reference is already powered up or external reference is being used .

In clock mode 01, the total conversion time depends on how long  $\overline{\text{CNVST}}$  is held low or high, including any time required to turn on the internal reference. Conversion time in externally clocked mode (CKSEL1, CKSEL0 = 11) depends on the SCLK period and how long  $\overline{\text{CS}}$  is held high between each set of eight SCLK cycles. In clock mode 01, the total conversion time does not include the time required to turn on the internal reference.

**Table 1. Input Data Byte (MSB First)** 

			-					
REGISTER NAME	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
Conversion	1	CHSEL3	CHSEL2	CHSEL1	CHSEL0	SCAN1	SCAN0	Χ
Setup	0	1	CKSEL1	CKSEL0	REFSEL1	REFSEL0	Χ	Χ
Averaging	0	0	1	AVGON	NAVG1	NAVG0	NSCAN1	NSCAN0
Reset	0	0	0	1	RESET	Χ	X	Χ

X = Don't care.

#### **Conversion Register**

Select active analog input channels per scan and scan modes by writing to the conversion register. Table 2 details channel selection and the four scan modes. Request a scan by writing to the conversion register when in clock mode 10 or 11, or by applying a low pulse to the CNVST pin when in clock mode 00 or 01.

A conversion is not performed if it is requested on a channel that has been configured as CNVST. Do not request conversions on channels 8-15 on the MAX11626-MAX11629. Set CHSEL3:CHSEL0 to the lower channel's binary values.

Select scan mode 00 or 01 to return one result per single-ended channel within the requested range. Select scan mode 10 to scan a single input channel numerous times, depending on NSCAN1 and NSCAN0 in the averaging register (Table 4). Select scan mode 11 to return only one result from a single channel.

#### Setup Register

Write a byte to the setup register to configure the clock, reference, and power-down modes. Table 3 details the bits in the setup register. Bits 5 and 4 (CKSEL1 and CKSEL0) control the clock mode, acquisition and sampling, and the conversion start. Bits 3 and 2 (REFSEL1 and REFSEL0) control internal or external reference use.

#### Averaging Register

Write to the averaging register to configure the ADC to average up to 32 samples for each requested result, and to independently control the number of results requested for single-channel scans.

Table 2 details the four scan modes available in the conversion register. All four scan modes allow averaging as long as the AVGON bit, bit 4 in the averaging register, is set to 1. Select scan mode 10 to scan the same channel multiple times. Clock mode 11 disables averaging.

#### Reset Register

Write to the reset register (as shown in Table 5) to clear the FIFO or to reset all registers to their default states. Set the RESET bit to 1 to reset the FIFO. Set the reset bit to zero to return the MAX11626–MAX11629/MAX11632/MAX11633 to the default power-up state.

Table 2. Conversion Register\*

BIT NAME	BIT	FUNCTION
_	7 (MSB)	Set to 1 to select conversion register.
CHSEL3	6	Analog input channel select.
CHSEL2	5	Analog input channel select.
CHSEL1	4	Analog input channel select.
CHSEL0	3	Analog input channel select.
SCAN1	2	Scan mode select.
SCAN0	1	Scan mode select.
	0 (LSB)	Don't care.

<sup>\*</sup>See below for bit details.

CHSEL3	CHSEL2	CHSEL1	CHSEL0	SELECTED CHANNEL (N)
0	0	0	0	AIN0
0	0	0	1	AIN1
0	0	1	0	AIN2
0	0	1	1	AIN3
0	1	0	0	AIN4
0	1	0	1	AIN5
0	1	1	0	AIN6
0	1	1	1	AIN7
1	0	0	0	AIN8
1	0	0	1	AIN9
1	0	1	0	AIN10
1	0	1	1	AIN11
1	1	0	0	AIN12
1	1	0	1	AIN13
1	1	1	0	AIN14
1	1	1	1	AIN15

SCAN1	SCAN0	SCAN MODE (CHANNEL N IS SELECTED BY BITS CHSEL3-CHSEL0)
0	0 Scans channels 0 through N.	
0	1	Scans channels N through the highest numbered channel.
1	0	Scans channel N repeatedly. The averaging register sets the number of results.
1	1	No scan. Converts channel N once only.

Table 3. Setup Register\*

BIT NAME	BIT	FUNCTION		
_	7 (MSB)	Set to 0 to select setup register.		
_	6	Set to 1 to select setup register.		
CKSEL1	5	Clock mode and CNVST configuration. Resets to 1 at power-up.		
CKSEL0	4	Clock mode and CNVST configuration.		
REFSEL1	3	Reference mode configuration.		
REFSEL0	2	Reference mode configuration.		
_	1	Don't care.		
_	0 (LSB)	Don't care.		

<sup>\*</sup>See below for bit details.

CKSEL1	CKSEL0	CONVERSION CLOCK	ACQUISITION/SAMPLING	CNVST CONFIGURATION
0	0	Internal	Internally timed	CNVST
0	1	Internal	Externally timed through CNVST	CNVST
1	0	Internal	Internally timed	AIN15/AIN11/AIN7*
1	1	External (4.8MHz max)	Externally timed through SCLK	AIN15/AIN11/AIN7*

<sup>\*</sup>For the MAX11626/MAX11627, CNVST has its own dedicated pin.

REFSEL1 REFSEL0		VOLTAGE REFERENCE	AutoShutdown	
0	0	Internal	Reference off after scan; need wake-up delay.	
0	1	External	Reference off; no wake-up delay.	
1	0 Internal		Reference always on; no wake-up delay.	
1	1	Reserved	Reserved. Do not use.	

#### Table 4. Averaging Register\*

BIT NAME	BIT	FUNCTION	
_	7 (MSB)	Set to 0 to select averaging register.	
_	6	Set to 0 to select averaging register.	
_	5	Set to 1 to select averaging register.	
AVGON	4	Set to 1 to turn averaging on. Set to 0 to turn averaging off.	
NAVG1	3	Configures the number of conversions for single-channel scans.	
NAVG0	2	Configures the number of conversions for single-channel scans.	
NSCAN1	1	Single-channel scan count. (Scan mode 10 only.)	
NSCAN0	0 (LSB)	Single-channel scan count. (Scan mode 10 only.)	

<sup>\*</sup>See below for bit details.

AVGON	NAVG1	NAVG0	FUNCTION	
0	X	Х	Performs one conversion for each requested result.	
1	0	0	Performs four conversions and returns the average for each requested result.	
1	0	1	Performs eight conversions and returns the average for each requested result.	
1	1	0	Performs 16 conversions and returns the average for each requested result.	
1	1	1	Performs 32 conversions and returns the average for each requested result.	

NSCAN1	NSCAN0	FUNCTION (APPLIES ONLY IF SCAN MODE 10 IS SELECTED)	
0	O Scans channel N and returns four results.		
0	1	Scans channel N and returns eight results.	
1	0	Scans channel N and returns 12 results.	
1	1	Scans channel N and returns 16 results.	

#### **Table 5. Reset Register**

BIT NAME	BIT	FUNCTION		
_	7 (MSB)	Set to 0 to select reset register.		
_	6	Set to 0 to select reset register.		
_	5	Set to 0 to select reset register.		
_	4	Set to 1 to select reset register.		
RESET	3	Set to 0 to reset all registers. Set to 1 to clear the FIFO only.		
Х	2	Reserved. Don't care.		
Х	1	Reserved. Don't care.  SB) Reserved. Don't care.		
Х	0 (LSB)			

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#### **Power-Up Default State**

The MAX11626–MAX11629/MAX11632/MAX11633 power up with all blocks in shutdown, including the reference. All registers power up in state 00000000, except for the setup register, which powers up in clock mode 10 (CKSEL1 = 1)

#### **Output Data Format**

Figures 4–7 illustrate the conversion timing for the MAX11626–MAX11629/MAX11632/MAX11633. The 12-bit conversion result is output in MSB-first format with four leading zeros. DIN data is latched into the serial interface on the rising edge of SCLK. Data on DOUT transitions on the falling edge of SCLK. Conversions in clock modes 00 and 01 are initiated by CNVST. Conversions in clock modes 10 and 11 are initiated by writing an input data byte to the conversion register. Data output is binary.

## Internally Timed Acquisitions and Conversions Using CNVST

#### Performing Conversions in Clock Mode 00

In clock mode 00, the wake-up, acquisition, conversion, and shutdown sequences are initiated through CNVST and performed automatically using the internal oscillator. Results are added to the internal FIFO to be read out later. See Figure 4 for clock mode 00 timing.

Initiate a scan by setting CNVST low for at least 40ns before pulling it high again. The MAX11626–MAX11629/MAX11632/MAX11633 then wake up, scan all requested channels, store the results in the FIFO, and shut down. After the scan is complete, EOC is pulled low and the results are available in the FIFO. Wait until EOC

goes low before pulling  $\overline{\text{CS}}$  low to communicate with the serial interface.  $\overline{\text{EOC}}$  stays low until  $\overline{\text{CS}}$  or  $\overline{\text{CNVST}}$  is pulled low again.

Do not initiate a second  $\overline{\text{CNVST}}$  before  $\overline{\text{EOC}}$  goes low; otherwise, the FIFO can become corrupted.

## Externally Timed Acquisitions and Internally Timed Conversions with CNVST

#### Performing Conversions in Clock Mode 01

In clock mode 01, conversions are requested one at a time using  $\overline{\text{CNVST}}$  and performed automatically using the internal oscillator. See Figure 5 for clock mode 01 timing.

Setting CNVST low begins an acquisition, wakes up the ADC, and places it in track mode. Hold CNVST low for at least 1.4µs to complete the acquisition. If the internal reference needs to wake up, an additional 65µs is required for the internal reference to power up.

Set  $\overline{\text{CNVST}}$  high to begin a conversion. After the conversion is complete, the ADC shuts down and pulls  $\overline{\text{EOC}}$  low.  $\overline{\text{EOC}}$  stays low until  $\overline{\text{CS}}$  or  $\overline{\text{CNVST}}$  is pulled low again. Wait until  $\overline{\text{EOC}}$  goes low before pulling  $\overline{\text{CS}}$  or  $\overline{\text{CNVST}}$  low.

If averaging is turned on, multiple  $\overline{\text{CNVST}}$  pulses need to be performed before a result is written to the FIFO. Once the proper number of conversions has been performed to generate an averaged FIFO result, as specified by the averaging register, the scan logic automatically switches the analog input multiplexer to the next-requested channel. The result is available on DOUT once  $\overline{\text{EOC}}$  has been pulled low.

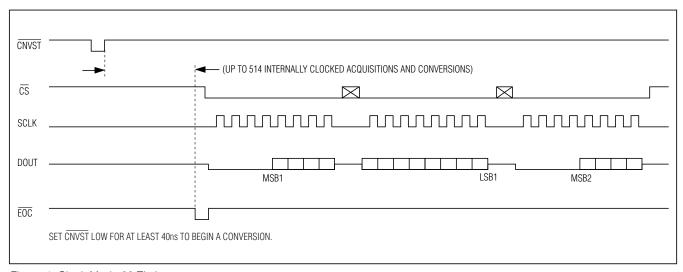


Figure 4. Clock Mode 00 Timing

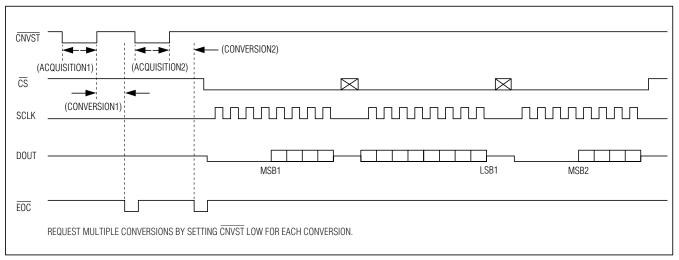


Figure 5. Clock Mode 01 Timing

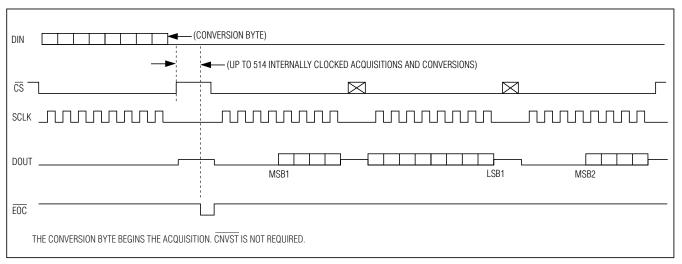


Figure 6. Clock Mode 10 Timing

## Internally Timed Acquisitions and Conversions Using the Serial Interface

#### Performing Conversions in Clock Mode 10

In clock mode 10, the wake-up, acquisition, conversion, and shutdown sequences are initiated by writing an input data byte to the conversion register, and are performed automatically using the internal oscillator. This is the default clock mode upon power-up. See Figure 6 for clock mode 10 timing.

Initiate a scan by writing a byte to the conversion register. The MAX11626–MAX11629/MAX11632/MAX11633 then power up, scan all requested channels, store the results in the FIFO, and shut down. After the scan is

complete,  $\overline{EOC}$  is pulled low and the results are available in the FIFO.  $\overline{EOC}$  stays low until  $\overline{CS}$  is pulled low again.

## **Externally Clocked Acquisitions and Conversions Using the Serial Interface**

#### Performing Conversions in Clock Mode 11

In clock mode 11, acquisitions and conversions are initiated by writing to the conversion register and are performed one at a time using the SCLK as the conversion clock. Scanning and averaging are disabled, and the conversion result is available at DOUT during the conversion. See Figure 7 for clock mode 11 timing.

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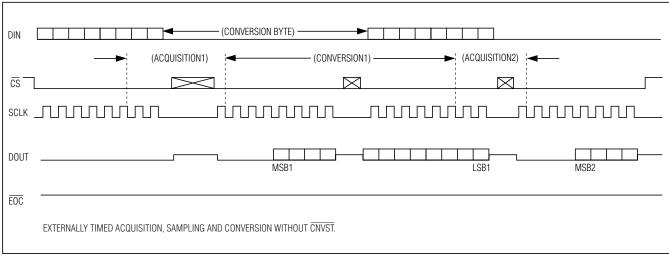


Figure 7. Clock Mode 11 Timing

Initiate a conversion by writing a byte to the conversion register followed by 16 SCLK cycles. If  $\overline{\text{CS}}$  is pulsed high between the eight and ninth cycles, the pulse width must be less than 100 $\mu$ s. To continuously convert at 16 cycles per conversion, alternate 1 byte of zeros between each conversion byte.

If reference mode 00 is requested, wait  $65\mu s$  with  $\overline{CS}$  high after writing the conversion byte to extend the acquisition and allow the internal reference to power up.

#### **Partial Reads and Partial Writes**

If the first byte of an entry in the FIFO is partially read (CS is pulled high after fewer than eight SCLK cycles), the second byte of data that is read out contains the next 8 bits (not b7-b0). The remaining bits are lost for that entry. If the first byte of an entry in the FIFO is read out fully, but the second byte is read out partially, the rest of the entry is lost. The remaining data in the FIFO is uncorrupted and can be read out normally after taking CS low again, as long as the 4 leading bits (normally zeros) are ignored. Internal registers that are written partially through the SPI contain new values, starting at the MSB up to the point that the partial write is stopped. The part of the register that is not written contains previously written values. If  $\overline{\text{CS}}$  is pulled low before  $\overline{\text{EOC}}$ goes low, a conversion cannot be completed and the FIFO is corrupted.

#### **Transfer Function**

Figure 8 shows the unipolar transfer function. Code transitions occur halfway between successive-integer LSB values. Output coding is binary, with 1 LSB = V<sub>REF</sub>/2.5V (MAX11627/MAX11629/MAX11633) and 1 LSB = V<sub>REF</sub>/4.096V (MAX11626/MAX11628/MAX11632).

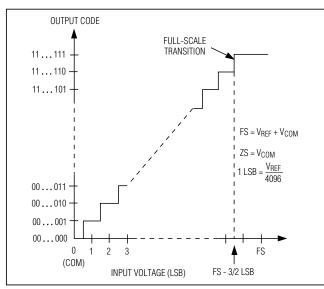


Figure 8. Unipolar Transfer Function, Full Scale (FS) = VREF

#### Layout, Grounding, and Bypassing

For best performance, use PCBs. Do not use wire wrap boards. Board layout should ensure that digital and analog signal lines are separated from each other. Do not run analog and digital (especially clock) signals parallel to one another or run digital lines underneath the MAX11626–MAX11629/MAX11632/MAX11633 package. High-frequency noise in the VDD power supply can affect performance. Bypass the VDD supply with a 0.1  $\mu$ C capacitor to GND, close to the VDD pin. Minimize capacitor lead lengths for best supply-noise rejection. If the power supply is very noisy, connect a  $10\Omega$  resistor in series with the supply to improve power-supply filtering.

#### **Definitions**

#### **Integral Nonlinearity**

Integral nonlinearity (INL) is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit or a line drawn between the end points of the transfer function, once offset and gain errors have been nullified. INL for the MAX11626–MAX11629/MAX11632/MAX11633 is measured using the end-point method.

#### **Differential Nonlinearity**

Differential nonlinearity (DNL) is the difference between an actual step width and the ideal value of 1 LSB. A DNL error specification of less than 1 LSB guarantees no missing codes and a monotonic transfer function.

#### **Aperture Jitter**

Aperture jitter  $(t_{AJ})$  is the sample-to-sample variation in the time between the samples.

#### **Aperture Delay**

Aperture delay (t<sub>AD</sub>) is the time between the rising edge of the sampling clock and the instant when an actual sample is taken.

#### Signal-to-Noise Ratio

For a waveform perfectly reconstructed from digital samples, signal-to-noise ratio (SNR) is the ratio of the full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADC's resolution (N bits):

$$SNR = (6.02 \times N + 1.76)dB$$

In reality, there are other noise sources besides quantization noise, including thermal noise, reference noise, clock jitter, etc. Therefore, SNR is calculated by taking the ratio of the RMS signal to the RMS noise, which includes all spectral components minus the fundamental, the first five harmonics, and the DC offset.

#### Signal-to-Noise Plus Distortion

Signal-to-noise plus distortion (SINAD) is the ratio of the fundamental input frequency's RMS amplitude to the RMS equivalent of all other ADC output signals:

SINAD (dB) = 20 x log (Signal<sub>RMS</sub>/Noise<sub>RMS</sub>)

#### **Effective Number of Bits**

Effective number of bits (ENOB) indicates the global accuracy of an ADC at a specific input frequency and sampling rate. An ideal ADC error consists of quantization noise only. With an input range equal to the full-scale range of the ADC, calculate the effective number of bits as follows:

$$ENOB = (SINAD - 1.76)/6.02$$

#### **Total Harmonic Distortion**

Total harmonic distortion (THD) is the ratio of the RMS sum of the first five harmonics of the input signal to the fundamental itself. This is expressed as:

THD = 
$$20 \times \log \left( \sqrt{(V_2^2 + V_3^2 + V_4^2 + V_5^2)} / V_1 \right)$$

where V1 is the fundamental amplitude, and V2–V5 are the amplitudes of the first five harmonics.

#### **Spurious-Free Dynamic Range**

Spurious-free dynamic range (SFDR) is the ratio of the RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next-largest distortion component.

# MAX11626-MAX11629/MAX11632/MAX11633

# 12-Bit, 300ksps ADCs with FIFO and Internal Reference

#### Pin Configurations (continued)

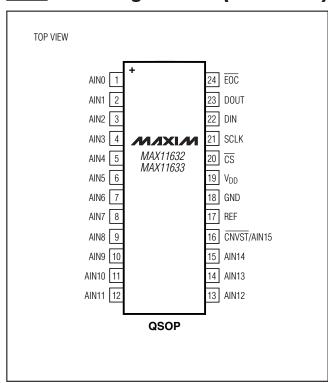


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## \_Package Information

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.	
16 QSOP	E16+5	21-0055	<u>91-0168</u>	
24 QSOP	E24+1	21-0055	91-0168	



#### **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	6/10	Initial release	_
1	8/10	Initial release of MAX11628/MAX11629 and changed internal reference voltage	1
2	3/11	Added MAX11628 automotive qualified part to data sheet	1

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