

SANYO Semiconductors DATA SHEET



CMOSIC 16K-byte FROM and 2048-byte RAM integrated 8-bit 1-chip Microcontroller with USB-host controller

Overview

The LC87F1L16A is an 8-bit microcomputer that, centered around a CPU running at a minimum bus cycle time of 83.3ns, integrates on a single chip a number of hardware features such as 16K-byte flash ROM (onboard programmable), 2048-byte RAM, an on-chip debugger, a sophisticated 16-bit timer/counter (may be divided into 8-bit timers), a 16-bit timer (may be divided into 8-bit timers or PWMs), four 8-bit timers with a prescaler, a base timer serving as a time-of-day clock, a synchronous SIO interface with automatic data transfer capabilities, an asynchronous/synchronous SIO interface, a UART interface (full duplex), 2 channels of full-speed USB interface (host control function), a 12-bit 12-channel AD converter, 2 channels of 12-bit PWM, a system clock frequency divider, and a 39-source 10-vector interrupt feature.

Features

■Flash ROM

- Capable of on-board programming with a wide range of supply voltages: 3.0 to 5.5V
- Block-erasable in 128 byte units
- Writes data in 2-byte units
- 16384 × 8 bits

■RAM

• 2048×9 bits

■Bus Cycle Time

• 83.3ns (When CF=12MHz)

Note: The bus cycle time here refers to the ROM read speed.

* This product is licensed from Silicon Storage Technology, Inc. (USA), and manufactured and sold by SANYO Semiconductor Co., Ltd.

- Any and all SANYO Semiconductor Co.,Ltd. products described or contained herein are, with regard to "standard application", intended for the use as general electronics equipment (home appliances, AV equipment, communication device, office equipment, industrial equipment etc.). The products mentioned herein shall not be intended for use for any "special application" (medical equipment whose purpose is to sustain life, aerospace instrument, nuclear control device, burning appliances, transportation machine, traffic signal system, safety equipment etc.) that shall require extremely high level of reliability and can directly threaten human lives in case of failure or malfunction of the product or may cause harm to human bodies, nor shall they grant any guarantee thereof. If you should intend to use our products for applications outside the standard applications, please consult with us prior to the intended use. If there is no consultation or inquiry before the intended use, our customer shall be solely responsible for the use.
- Specifications of any and all SANYO Semiconductor Co.,Ltd. products described or contained herein stipulate the performance, characteristics, and functions of the described products in the independent state, and are not guarantees of the performance, characteristics, and functions of the described products as mounted in the customer's products or equipment. To verify symptoms and states that cannot be evaluated in an independent device, the customer should always evaluate and test devices mounted in the customer's products or equipment.

SANYO Semiconductor Co., Ltd. http://semicon.sanyo.com/en/network ■Minimum Instruction Cycle Time (tCYC)

• 250ns (When CF=12MHz)

■Ports

• I/O ports

Ports whose I/O direction can be designated in 1-bit units	26 (P10 to P17, P20 to P25, P30 to P34,
	P70 to P73, PWM0, PWM1, XT2)
Ports whose I/O direction can be designated in 4-bit units	8 (P00 to P07)
• USB ports	2 (UHAD+, UHAD-, UHBD+, UHBD-)
 Dedicated oscillator ports 	2 (CF1, CF2)
• Input-only port (also used for oscillation)	1 (XT1)
• Reset pins	$1(\overline{\text{RES}})$
• Power supply pins	6 (V _{SS} 1 to 3, V _{DD} 1 to 3)

- ■Timers
 - Timer 0: 16-bit timer/counter with 2 capture registers.

Mode 0: 8-bit timer with an 8-bit programmable prescaler (with two 8-bit capture registers) × 2 channels Mode 1: 8-bit timer with an 8-bit programmable prescaler (with two 8-bit capture registers) + 8-bit counter (with two 8-bit capture registers)

- Mode 2: 16-bit timer with an 8-bit programmable prescaler (with two 16-bit capture registers)
- Mode 3: 16-bit counter (with two 16-bit capture registers)
- Timer 1: 16-bit timer/counter that supports PWM/toggle outputs

Mode 0: 8-bit timer with an 8-bit prescaler (with toggle outputs) + 8-bit timer/

- counter with an 8-bit prescaler (with toggle outputs)
- Mode 1: 8-bit PWM with an 8-bit prescaler \times 2 channels
- Mode 2: 16-bit timer/counter with an 8-bit prescaler (with toggle outputs)
 - (toggle outputs also possible from lower-order 8 bits)
- Mode 3: 16-bit timer with an 8-bit prescaler (with toggle outputs)
 - (lower-order 8 bits may be used as a PWM output)
- Timer 4: 8-bit timer with a 6-bit prescaler
- Timer 5: 8-bit timer with a 6-bit prescaler
- Timer 6: 8-bit timer with a 6-bit prescaler (with toggle outputs)
- Timer 7: 8-bit timer with a 6-bit prescaler (with toggle outputs)
- Base timer
 - 1) The clock is selectable from the subclock (32.768kHz crystal oscillation), system clock, and timer 0 prescaler output.
 - 2) Interrupts programmable in 5 different time schemes

■SIO

- SIO0: Synchronous serial interface
 - 1) LSB first/MSB first mode selectable
 - 2) Transfer clock cycle: 4/3 to 512/3 tCYC
 - Automatic continuous data transmission (1 to 256 bits, specifiable in 1-bit units) (Suspension and resumption of data transmission possible in 1 byte units)
- SIO1: 8-bit asynchronous/synchronous serial interface
 - Mode 0: Synchronous 8-bit serial I/O (2- or 3-wire configuration, 2 to 512 tCYC transfer clocks)
 - Mode 1: Asynchronous serial I/O (half-duplex, 8 data bits, 1 stop bit, 8 to 2048 tCYC baudrates)
 - Mode 2: Bus mode 1 (start bit, 8 data bits, 2 to 512 tCYC transfer clocks)
 - Mode 3: Bus mode 2 (start detect, 8 data bits, stop detect)

■Full Duplex UART

- 1) Data length: 7/8/9 bits selectable
- 2) Stop bits: 1 bit (2 bits in continuous transmission mode)
- 3) Baud rate: 16/3 to 8192/3 tCYC

AD Converter: 12 bits \times 12 channels

■PWM: Multifrequency 12-bit PWM × 2 channels

USB Interface (host control function) \times 2 channels

- 1) Compliant with full-speed (12M bps) specifications
- 2) Supports 4 transfer types (control transfer, bulk transfer, interrupt transfer, and isochronous transfer).
- ■Watchdog Timer
 - Watchdog timer using external RC circuitry
 - Interrupt and reset signals selectable
- ■Clock Output Function
 - 1) Can output a clock with a clock rate of 1/1, 1/2, 1/4, 1/8, 1/16, 1/32, or 1/64 of the source oscillator clock selected as the system clock.
 - 2) Can output the source oscillation clock for the subclock.

■Interrupts

- 39 sources, 10 vector addresses
 - 1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.
 - 2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address takes precedence.

No.	Vector Address	Level	Interrupt Source		
1	00003H	X or L	INTO		
2	0000BH	X or L	INT1		
3	00013H	H or L	INT2/T0L/INT4/UHC-A bus active/UHC-B bus active		
4	0001BH	H or L	INT3/INT5/Base timer		
5	00023H	H Or L T0H/INT6/UHC-A device connected/UHC-A disconnected/UHC-A res			
6	0002BH	H or L	T1L/T1H/INT7/UHC-B device connected/UHC-B disconnected/UHC-B resume		
7	00033H	H or L	SIO0/UART1 receive complete		
8	0003BH	H or L	SIO1/UART1 buffer empty/UART1 transmit complete		
9	00043H	H or L	ADC/T6/T7/UHC-ACK/UHC-NAK/UHC error/UHC STALL		
10	0004BH	H or L	Port 0/PWM0/PWM1/T4/T5/UHC-SOF		

• Priority levels X > H > L

• Of interrupts of the same level, the one with the smallest vector address takes precedence.

Subroutine Stack Levels: 1024 levels maximum (The stack is allocated in RAM.)

High-speed Multiplication/Division Instructions

- 16 bits \times 8 bits (5 tCYC execution time)
- 24 bits \times 16 bits (12 tCYC execution time)
- 16 bits ÷ 8 bits (8 tCYC execution time)
- 24 bits ÷ 16 bits (12 tCYC execution time)

■Oscillation and PLL Circuits

- RC oscillation circuit (internal): For system clock
- CF oscillation circuit: For system clock
- Crystal oscillation circuit: For system clock, time-of-day clock
- PLL circuit (internal): For USB interface (see Fig.5)

■Standby Function

- HALT mode: Halts instruction execution while allowing the peripheral circuits to continue operation.
 - 1) Oscillation is not halted automatically.
 - 2) There are three ways of resetting the HOLD mode.
 - (1) Setting the reset pin to the lower level
 - (2) System resetting by watchdog timer
 - (3) Occurrence of an interrupt
- HOLD mode: Suspends instruction execution and the operation of the peripheral circuits.
- 1) The PLL base clock generator, CF, RC and crystal oscillators automatically stop operation.
- 2) There are five ways of resetting the HOLD mode.
 - (1) Setting the reset pin to the lower level
 - (2) System resetting by watchdog timer
 - (3) Having an interrupt source established at either INT0, INT1, INT2, INT4 or INT5
 - * INT0 and INT1 HOLD mode reset is available only when level detection is set.
 - (4) Having an interrupt source established at port 0
 - (5) Having an bus active interrupt source established in the USB host controll circuit
- X'tal HOLD mode: Suspends instruction execution and the operation of the peripheral circuits except the base timer.
 - 1) The PLL base clock generator, CF and RC oscillator automatically stop operation.
 - 2) The state of crystal oscillation established when the X'tal HOLD mode is entered is retained.
 - 3) There are six ways of resetting the X'tal HOLD mode.
 - (1) Setting the reset pin to the low level
 - (2) System resetting by watchdog timer
 - (3) Having an interrupt source established at either INT0, INT1, INT2, INT4 or INT5
 - * INT0 and INT1 HOLD mode reset is available only when level detection is set.
 - (4) Having an interrupt source established at port 0
 - (5) Having an interrupt source established in the base timer circuit
 - (6) Having an bus active interrupt source established in the USB host controll circuit

■Package Form

• SQFP48 (7×7): Lead-/Halogen-free type

■Development Tools

• On-chip debugger: TCB87 type-B + LC87F1L16A or TCB87 type-C (three wire cable) + LC87F1L16A

■Flash ROM Programming Boards

Package	Programming Boards
SQFP48(7 × 7)	W87F55256SQ

■Flash Programmer

Maker		Model	Supported version	Device	
Flash Support Group, Inc. (FSG)	Single Programmer	AF9709/AF9709B/AF9709C (Including Ando Electric Co., Ltd. models)	Rev 03.18c or later	LC87F1L16A	
Flash Support Group, Inc. (FSG)	Onboard	AF9101/AF9103 (Main unit) (FSG models)	()	LC87F1L16A	
+ Sanyo (Note 1)	Single/Gang Programmer	SIB87(Inter Face Driver) (Sanyo model)	(Note 2)		
	Single/Gang Programmer	SKK/SKK TypeB (SanyoFWS)	Application Version		
Sanyo	Onboard Single/Gang Programmer	SKK-DBG TypeB (SanyoFWS)	1.04 or later Chip Data Version 2.21 or later	LC87F1L16	

For information about AF-Series:

Flash Support Group, Inc.

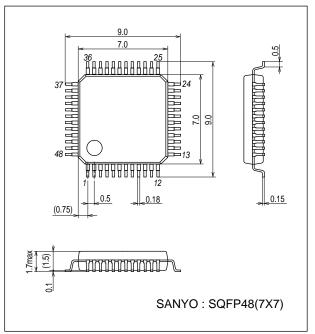
TEL: +81-53-459-1050

E-mail: sales@j-fsg.co.jp

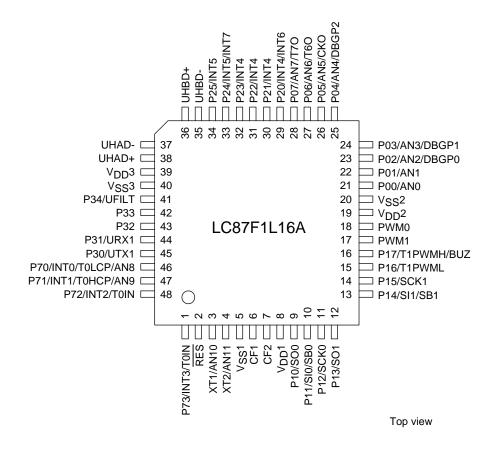
- Note1: On-board-programmer from FSG (AF9101/AF9103) and serial interface driver from SANYO (SIB87) together can give a PC-less, standalone on-board-programming capabilities.
- Note2: It needs a special programming devices and applications depending on the use of programming environment. Please ask FSG or SANYO for the information.

Package Dimensions

unit : mm (typ) 3163B



Pin Assignment

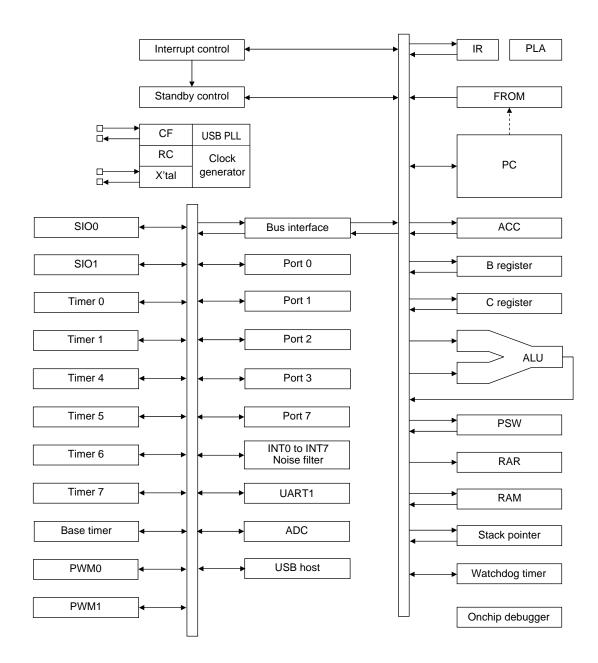


SANYO : SQFP48(7×7) "Lead-/Halogen-free Type"

SQFP48	NAME
1	P73/INT3/T0IN
2	RES
3	XT1/AN10
4	XT2/AN11
5	V _{SS} 1
6	CF1
7	CF2
8	V _{DD} 1
9	P10/SO0
10	P11/SI0/SB0
11	P12/SCK0
12	P13/SO1
13	P14/SI1/SB1
14	P15/SCK1
15	P16/T1PWML
16	P17/T1PWMH/BUZ
17	PWM1
18	PWM0
19	V _{DD} 2
20	V _{SS} 2
21	P00/AN0
22	P01/AN1
23	P02/AN2/DBGP0
24	P03/AN3/DBGP1

SQFP48	NAME
25	P04/AN4/DBGP2
26	P05/AN5/CKO
27	P06/AN6/T6O
28	P07/AN7/T7O
29	P20/INT4/INT6
30	P21/INT4
31	P22/INT4
32	P23/INT4
33	P24/INT5/INT7
34	P25/INT5
35	UHBD-
36	UHBD+
37	UHAD-
38	UHAD+
39	V _{DD} 3
40	V _{SS} 3
41	P34/UFILT
42	P33
43	P32
44	P31/URX1
45	P30/UTX1
46	P70/INT0/T0LCP/AN8
47	P71/INT1/T0HCP/AN9
48	P72/INT2/T0IN

System Block Diagram



Pin Description

Pin Name	I/O			De	scription			Option		
V _{SS} 1,V _{SS} 2,	-	- power supply						No		
V _{SS} 3										
V _{DD} 1, V _{DD} 2	-	+ power supply						No		
V _{DD} 3	-	USB reference	voltage					Yes		
Port 0	I/O	8-bit I/O ports						Yes		
P00 to P07		 I/O specifiable 	e in 4-bit units							
		Pull-up resister	ors can be turne	ed on and off in 4	-bit units.					
		HOLD reset in	nput							
		 Port 0 interrup 	ot input							
		Pin functions								
				0 to AN7(P00 to	-					
				P0 to DBGP2(P0	2 to P04)					
		P05: System								
		P06: Timer 6								
De et 4	1/0	P07: Timer 7								
Port 1	I/O	 8-bit I/O ports I/O specifiable 						Yes		
P10 to P17				ed on and off in 1	bit unite					
		Pin functions	ors can be turne		-bit units.					
		P10: SIO0 dat	ta output	P1	4: SIO1 data inpu	ut/bus input/outp	ut			
			ta input/bus inp		5: SIO1 clock inp					
			ck input/output	-	6: Timer 1 PWMI	•				
		P13: SIO1 dat			7: Timer 1 PWM	•	output			
Port 2	I/O	6-bit I/O ports				· · ·	-	Yes		
P20 to P25		 I/O specifiable 	e in 1-bit units							
		Pull-up resister	ors can be turne	ed on and off in 1	-bit units.					
		Pin functions								
		P20 to P23: IN	P20 to P23: INT4 input/HOLD reset input/timer 1 event input/timer 0L capture input/							
		ti								
			P24 to P27: INT5 input/HOLD reset input/timer 1 event input/timer 0L capture input/							
			mer 0H capture	-						
		P20: INT6 input/timer 0L capture 1 input								
		-	P24: INT7 input/timer 0H capture 1 input							
		Interrupt ackn	owledge types							
			Divi	F	Rising &					
			Rising	Falling	Falling	H level	L level			
		INT4	enable	enable	enable	disable	disable			
		INT5	enable	enable	enable	disable	disable			
		INT6	enable	enable	enable	disable	disable			
		INT7	enable	enable	enable	disable	disable			
			CIIDUC	CIIADIC	enable	uisable	UISADIE			
Port 3	I/O	 5-bit I/O ports 						Yes		
P30 to P34		 I/O specifiable 								
				ed on and off in 1	-bit units.					
		Pin functions								
		P30: UART1 t	ransmit							
		P31: UART1 r	eceive							
		P34: USB inte	erface PLL filter	pin (see Fig. 5.)						

Continued on next page.

LC87F1L16A

Pin Name	I/O		Description						
Port 7	I/O	• 4-bit I/O port						No	
P70 to P73		I/O specifiable in 1-bit units							
		Pull-up resistors can be turned on and off in 1-bit units.							
		Pin functions							
		P70: INT0 input	HOLD reset inp	out/timer 0L cap	ture input/watch	dog timer output			
		P71: INT1 input	HOLD reset inp	out/timer 0H cap	ture input				
		P72: INT2 input	HOLD reset inp	out/timer 0 even	t input/timer 0L o	apture input/			
		high spee	d clock counter i	nput					
			• •	,	event input/timer	0H capture inpu	ut		
			put ports: AN8(F	P70), AN9(P71)					
		Interrupt acknow	wledge types	1	1		1		
			Rising	Falling	Rising & Falling	H level	L level		
		INT0	enable	enable	disable	enable	enable		
		INT1	enable	enable	disable	enable	enable		
		INT2	enable	enable	enable	disable	disable		
		INT3	enable	enable	enable	disable	disable		
PWM0	I/O	PWM0, PWM1 o						No	
PWM1	., 0	General-purpose							
UHAD-	I/O	USB-A port data		purpose I/O por	t			No	
UHAD+				F F	-				
UHBD-	I/O	USB-B port data	I/O pin/general-	purpose I/O por	t			No	
UHBD+								_	
RES	Input	Reset pin						No	
XT1	Input	• 32.768kHz crys	tal oscillator inp	ut				No	
	•	Pin functions							
		General-purpos	General-purpose input port						
		AD converter in	put ports: AN10						
		Must be connec	cted to V _{DD} 1 wh	nen not to be us	ed.				
XT2	I/O	• 32.768kHz crys	tal oscillator out	put				No	
		Pin functions							
		General-purpos	e I/O						
		AD converter in	put port: AN11						
		Must be set for	oscillation and k	ept open if not	to be used.				
CF1	Input	Ceramic/crystal r	esonator input					No	
CF2	Output	Ceramic/crystal r	esonator output					No	

On-chip Debugger Pin Connection Requirements

For the treatment of the on-chip debugger pins, refer to the separately available documents entitled "Rd87 On-chip Debugger Installation Manual"

Port Output Types

The table below lists the types of port outputs and the presence/absence of a pull-up resistor. Data can be read into any input port even if it is in the output mode.

Port Name	Option selected in units of	Option type	Output type	Pull-up resistor
P00 to P07	1 bit	1	CMOS	Programmable (Note 1)
		2	Nch-open drain	No
P10 to P17 1 bit 1 CMOS P20 to P25		CMOS	Programmable	
P20 to P25 P30 to P34		2	Nch-open drain	Programmable
P70	-	No	Nch-open drain	Programmable
P71 to P73	-	No	CMOS	Programmable
PWM0, PWM1	-	No	CMOS	No
UHAD+, UHAD- UHBD+, UHBD-	-	No	CMOS	No
XT1	-	No	Input only	No
XT2	-	No	32.768kHz crystal resonator output (N channel open drain when in general-purpose output mode)	No

Note 1: Programmable pull-up resistors for port 0 are controlled in 4 bit units (P00 to 03, P04 to 07).

User Option Table

Option Name	Option Type	Mask Version *1	Flash Version	Option Selected in Units of	Option Selection
Port output form	P00 to P07				CMOS
		enable	enable	1 bit	Nch-open drain
Port output form Program start address USB Regulator	P10 to P17				CMOS
		enable	enable	1 bit	Nch-open drain
	P20 to P25	enable	enable		CMOS
		enable	enable	1 bit	Nch-open drain
	P30 to P34		enable	4 6 9	CMOS
		enable		1 bit	Nch-open drain
Program start		×	enable		00000h
address	-	*2	enable	-	03E00h
USB Regulator	USB Regulator	enable	enable		USE
		enable	enable	-	NONUSE
	USB Regulator	enable	enable		USE
	(at HOLD mode)	enable	enable	-	NONUSE
	USB Regulator	enable	enable		USE
	(at HALT mode)	enable	endble	-	NONUSE
Main clock 8MHz		enable			ENABLE
selection	-	enable	enable	-	DISABLE

*1: Mask option selection – No change possible after mask is completed.

*2: Program start address of the mask version is 00000h.

USB Reference Power Option

When a voltage 4.5 to 5.5V is supplied to $V_{DD}1$ and the internal USB reference voltage circuit is activated, the reference voltage for USB port output is generated. The active/inactive state of the reference voltage circuit can be switched by option select. The procedure for marking the option selection is described below.

		(1)	(2)	(3)	(4)
Option settings	USB regulator	USE	USE	USE	NONUSE
	USB regulator at HOLD mode	USE	NONUSE	NONUSE	NONUSE
	USB regulator at HALT mode	USE	NONUSE	USE	NONUSE
Reference voltage circuit state	Normal mode	active	active	active	inactive
	HOLD mode	active	inactive	inactive	inactive
	HALT mode	active	inactive	active	inactive

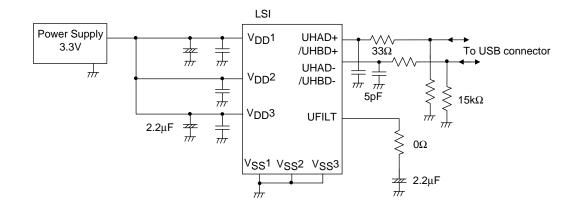
• When the USB reference voltage circuit is made inactive, the level of the reference voltage for USB port output is equal to V_{DD}1.

• Selection (2) or (3) can be used to set the reference voltage circuit inactive in HOLD or HALT mode.

• When the reference voltage circuit is activated, the current drain increases by approximately 100µA compared with when the reference voltage circuit is inactive.

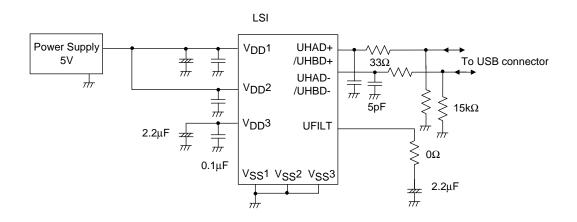
Example 1: VDD1=VDD2=3.3V

- Inactivating the reference voltage circuit (selection (4)).
- Connecting VDD3 to VDD1 and VDD2.



Example 2: VDD1=VDD2=5.0V

- Activating the reference voltage circuit (selection (1)).
- Isolating VDD3 from VDD1 and VDD2, and connecting capacitor between VDD3 and VSS.



Note: Do not apply the voltage of more than 3.6V to UHAD+, UHAD-, UHBD+ and UHBD- when the reference voltage circuit is active.

Absolute Maximum Ratings at $Ta = 25^{\circ}C$, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

	Parameter	Symbol	Pin/Remarks	Conditions	ł		-	ication	
	- arameter	Cymbol			V _{DD} [V]	min	typ m		uni
	aximum supply Itage	V _{DD} max	V_{DD} 1, V_{DD} 2, V_{DD} 3	$V_{DD}1 = V_{DD}2 = V_{DD}3$		-0.3		+6.5	
np	out voltage	V _I (1)	XT1, CF1, RES			-0.3		V _{DD} +0.3	v
Input/output voltage Peak output		V _{IO} (1)	Ports 0, 1, 2, 3, 7 PWM0, PWM1 XT2			-0.3		V _{DD} +0.3	v
	Peak output current	IOPH(1)	Ports 0, 1, 2	When CMOS output type is selected		-10			
		IOPH(2)	PWM0, PWM1	Per 1 applicable pin Per 1 applicable pin		-20			
		IOPH(3)	Port 3 P71 to P73	When CMOS output type is selected		-5			
	Average output current	•	Ports 0, 1, 2	Per 1 applicable pin When CMOS output type is selected Per 1 applicable pin		-7.5			
curr	(Note 1-1)	IOMH(2)	PWM0, PWM1	Per 1 applicable pin		-15			
evel output	IOMH(3) Port 3 • Wh P71 to P73 • Wh • Per • Per • Total output ΣIOAH(1) Ports 0, 2	When CMOS output type is selected Per 1 applicable pin		-3					
High		ΣIOAH(1)	Ports 0, 2	Total current of all applicable pins		-25			
		ΣIOAH(2)	Port 1 PWM0, PWM1	Total current of all applicable pins		-25			
		ΣΙΟΑΗ(3)	Ports 0, 1, 2	Total current of all		-45			
		ΣΙΟΑΗ(4)	PWM0, PWM1 Port 3	applicable pins Total current of all		-10			
		ΣIOAH(5)	P71 to P73 UHAD+, UHAD- UHBD+, UHBD-	applicable pins Total current of all applicable pins		-50			m
	Peak output current	IOPL(1)	P02 to P07 Ports 1, 2 PWM0, PWM1	Per 1 applicable pin				20	
		IOPL(2)	P00, P01	Per 1 applicable pin				30	
		IOPL(3)	Ports 3, 7 XT2	Per 1 applicable pin				10	
ent	Average output current (Note 1-1)	IOML(1)	P02 to P07 Ports 1, 2 PWM0, PWM1	Per 1 applicable pin				15	
curr		IOML(2)	P00, P01	Per 1 applicable pin				20	
l output		IOML(3)	Ports 3, 7 XT2	Per 1 applicable pin				7.5	
Low level output current	Total output current	ΣIOAL(1)	Ports 0, 2	Total current of all applicable pins				45	
		ΣIOAL(2)	Port 1 PWM0, PWM1	Total current of all applicable pins				45	
		ΣIOAL(3)	Ports 0, 1, 2 PWM0, PWM1	Total current of all applicable pins				80	
		ΣIOAL(4)	Ports 3, 7 XT2	Total current of all applicable pins				15	
		ΣIOAL(5)	UHAD+, UHAD- UHBD+, UHBD-	Total current of all applicable pins				50	
	owable power	Pd max	SQFP48(7×7)	Ta=-40 to +85°C				140	m\
Ор	perating ambient	Topr				-40		+85	
	orage ambient	Tstg				-55		+125)ە

Note 1-1: The average output current is an average of current values measured over 100ms intervals.

LC87F1L16A

Paramotor	Symbol	Pin/Remarks	Conditions			Specific	cation	
Parameter	Symbol	Pin/Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
Operating	V _{DD} (1)	V _{DD} 1=V _{DD} 2=V _{DD} 3	$0.245 \mu s \leq tCYC \leq 200 \mu s$		3.0		5.5	
supply voltage			$0.245 \mu s \leq tCYC \leq 0.383 \mu s$		3.0		5.5	
(Note 2-1)			USB circuit active		0.0		0.0	-
			$0.490\mu s \le tCYC \le 200\mu s$ Except		2.7		5.5	
Mamoni	VHD	\/	in onboard programming mode					-
Memory sustaining supply voltage	VHD	VDD1=VDD2=VDD3	RAM and register contents sustained in HOLD mode.		2.0		5.5	
High level	V _{IH} (1)	Port 0, 1, 2, 3						
input voltage		P71 to P73			0.3V _{DD}			
		P70 port input/		2.7 to 5.5	+0.7		V _{DD}	
		interrupt side PWM0, PWM1						
	V _{IH} (2)	Port 70 watchdog						
	. 10/-/	timer side		2.7 to 5.5	0.9V _{DD}		VDD	V
	V _{IH} (3)	XT1, XT2, CF1, RES		2.7 to 5.5	0.75V _{DD}		VDD	
Low level	V _{IL} (1)	Port 1, 2, 3					0.1V _{DD}	
input voltage		P71 to P73		4.0 to 5.5	V _{SS}		+0.4	-
_	V _{IL} (2)	P70 port input/ interrupt side		2.7 to 4.0	VSS		0.2V _{DD}	
	V _{IL} (3)	Port 0 PWM0, PWM1		4.0 to 5.5	V _{SS}		0.15V _{DD} +0.4	
	∨ _{IL} (4)			2.7 to 4.0	VSS		0.2V _{DD}	
	V _{IL} (5)	Port 70 watchdog timer side		2.7 to 5.5	V _{SS}		0.8V _{DD} -1.0	
	V _{IL} (6)	XT1, XT2, CF1, RES		2.7 to 5.5	V _{SS}		0.25V _{DD}	
Instruction	tCYC			3.0 to 5.5	0.245		200	
cycle time			USB circuit active	3.0 to 5.5	0.245		0.383	
(Note 2-2)			Except for onboard programming mode	2.7 to 5.5	0.490		200	μs
External system clock frequency	FEXCF(1)	CF1	 CF2 pin open System clock frequency division ratio=1/1 External system clock duty =50±5% 	3.0 to 5.5	0.1		12	
			 CF2 pin open System clock frequency division ratio=1/1 External system clock duty =50±5% 	2.7 to 5.5	0.1		6	MHz
Oscillation frequency	FmCF	CF1, CF2	When 12MHz ceramic oscillation See Fig. 1.	3.0 to 5.5		12		MHz
range	FmRC		Internal RC oscillation	2.7 to 5.5	0.3	1.0	2.0	
(Note 2-3)	FsX'tal	XT1, XT2	32.768kHz crystal oscillation See Fig. 2.	2.7 to 5.5		32.768		kHz
			· · ·					

Allowable Operating Conditions at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Note 2-1: V_{DD} must be held greater than or equal to 3.0V in the flash ROM onboard programming mode.

Note 2-2: Relationship between tCYC and oscillation frequency is 3/FmCF at a division ratio of 1/1 and 6/FmCF at a division ratio of 1/2.

Note 2-3: See Tables 1 and 2 for the oscillation constants.

LC87F1L16A

Parameter	Symbol	Pin/Remarks	Conditions			Specifica	ition	
Falameter	Symbol	Fill/Remaiks	Conditions	V _{DD} [V]	min	typ	max	unit
High level input current	I _{IH} (1)	Ports 0, 1, 2, 3 Port 7 RES PWM0, PWM1	Output disabled Pull-up resistor off VIN=VDD (Including output Tr's off leakage current)	2.7 to 5.5			1	
	I _{IH} (2)	XT1, XT2	Input port configuration VIN ^{=V} DD	2.7 to 5.5			1	
	I _{IH} (3)	CF1	V _{IN} =V _{DD}	2.7 to 5.5			15	
Low level input current	I <u>IL</u> (1)	Ports 0, 1, 2, 3 Port 7 RES PWM0, PWM1	Output disabled Pull-up resistor off VIN=VSS (Including output Tr's off leakage current)	2.7 to 5.5	-1			μA
	I _{IL} (2)	XT1, XT2	Input port configuration VIN ^{=V} SS	2.7 to 5.5	-1			
	I _{IL} (3)	CF1	VIN=VSS	2.7 to 5.5	-15			
High level output	V _{OH} (1)	Ports 0, 1, 2, 3	I _{OH} =-1mA	4.5 to 5.5	V _{DD} -1			
voltage	V _{OH} (2)	P71 to P73	I _{OH} =-0.4mA	3.0 to 5.5	V _{DD} -0.4			
	V _{OH} (3)		I _{OH} =-0.2mA	2.7 to 5.5	V _{DD} -0.4			
	V _{OH} (4)	PWM0, WM1	I _{OH} =-10mA	4.5 to 5.5	V _{DD} -1.5			
	V _{OH} (5)	P05 (CKO when using system clock	I _{OH} =-1.6mA	3.0 to 5.5	V _{DD} -0.4			
	V _{OH} (6)	output function)	I _{OH} =-1mA	2.7 to 5.5	V _{DD} -0.4			
Low level output	V _{OL} (1)	P00, P01	I _{OL} =30mA	4.5 to 5.5			1.5	v
voltage	V _{OL} (2)		I _{OL} =5mA	3.0 to 5.5			0.4	Ň
	V _{OL} (3)		I _{OL} =2.5mA	2.7 to 5.5			0.4	
	V _{OL} (4)	Ports 0, 1, 2	I _{OL} =10mA	4.5 to 5.5			1.5	
	V _{OL} (5)	PWM0, PWM1	I _{OL} =1.6mA	3.0 to 5.5			0.4	
	V _{OL} (6)	XT2	I _{OL} =1mA	2.7 to 5.5			0.4	
	V _{OL} (7)	Ports 3, 7	I _{OL} =1.6mA	3.0 to 5.5			0.4	
	V _{OL} (8)		I _{OL} =1mA	2.7 to 5.5			0.4	
Pull-up resistance	Rpu(1)	Ports 0, 1, 2, 3	V _{OH} =0.9V _{DD}	4.5 to 5.5	15	35	80	kΩ
	Rpu(2)	Port 7		2.7 to 5.5	18	50	150	N32
Hysteresis voltage	VHYS	RES Port 1, 2, 3, 7		2.7 to 5.5		0.1V _{DD}		V
Pin capacitance	CP	All pins	For pins other than that under test: VIN ^{=V} SS f=1MHz Ta=25°C	2.7 to 5.5		10		pF

Electrical Characteristics at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Serial I/O Characteristics at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$ 1. SIO0 Serial I/O Characteristics (Note 4-1-1)

	F	Parameter	Symbol	Pin/	Conditions	r		Spec	ification	1
		arameter	-	Remarks		V _{DD} [V]	min	typ	max	unit
		Frequency	tSCK(1)	SCK0(P12)	See Fig. 8.		2			
		Low level pulse width	tSCKL(1)				1			
		High level pulse width	tSCKH(1)				1			
	Input clock		tSCKHA(1a)	*	 Continuous data transmission/ reception mode USB not used at the same time. See Fig. 8. (Note 4-1-2) 	2.7 to 5.5	4			tCYC
S			tSCKHA(1b)		 Continuous data transmission/ reception mode USB used at the same time. See Fig. 8. (Note 4-1-2) 		7			
Serial clock		Frequency	tSCK(2)	SCK0(P12)	When CMOS output type is selected		4/3			
Se		Low level pulse width	tSCKL(2)		• See Fig. 8.			1/2		10.014
	Output clock	High level pulse width	tSCKH(2)					1/2		tSCK
			tSCKHA(2a)	*	 Continuous data transmission/ reception mode USB not used at the same time. When CMOS output type is selected See Fig. 8. 	2.7 to 5.5	tSCKH(2) +2tCYC		tSCKH(2) +(10/3) tCYC	
			tSCKHA(2b)	*	 Continuous data transmission/ reception mode USB used at the same time. When CMOS output type is selected. See Fig. 8. 		tSCKH(2) +2tCYC		tSCKH(2) +(19/3) tCYC	tCYC
Serial input	Da	ta setup time	tsDI(1)	SB0(P11), SI0(P11)	 Must be specified with respect to rising edge of SIOCLK. See Fig. 8. 	2.7 to 5.5	0.03			
Serial	Da	ta hold time	thDI(1)			2.7 10 5.5	0.03			
	clock	Output delay time	tdD0(1)	SO0(P10), SB0(P11)	Continuous data transmission/ reception mode (Note 4-1-3)				(1/3)tCYC +0.05	μs
Serial output	Output clock Input clock	tdD0(2)	Synchronous 8-bit mode(Note 4-1-3)	2.7 to 5.5			1tCYC +0.05			
Seria			tdD0(3)		(Note 4-1-3)				(1/3)tCYC +0.05	

Note 4-1-1: These specifications are theoretical values. Margins must be allowed according to the actual operating conditions.

Note 4-1-2: In an application where the serial clock input is to be used in the continuous data transfer mode, the time from SIORUN being set when serial clock is high to the falling edge of the first serial clock must be longer than tSCKHA.

Note 4-1-3: Must be specified with respect to falling edge of SIOCLK.

Must be specified as the time to the beginning of output state change in open drain output mode. See Fig. 8.

2. SIO1 Serial I/O Characteristics (Note 4-2-1)

		Parameter	Cumbol	Pin/	Conditions			Spec	ification	
		Parameter	Symbol	Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
	¥	Frequency	tSCK(3)	SCK1(P15)	See Fig. 8.		2			
	Input clock	Low level pulse width	tSCKL(3)			2.7 to 5.5	1			
clock	ľ	High level pulse width	tSCKH(3)				1			tCYC
Serial clock	ş	Frequency	tSCK(4)	SCK1(P15)	When CMOS output type is selected		2			
	Output clock	Low level pulse width	tSCKL(4)		• See Fig. 8.	2.7 to 5.5		1/2		10.01/
		High level pulse width	tSCKH(4)					1/2		tSCK
input	Da	ata setup time	tsDI(2)	SB1(P14), SI1(P14)	 Must be specified with respect to rising edge of SIOCLK. See Fig. 8. 		0.03			
Serial input	Da	ata hold time	thDI(2)			2.7 to 5.5	0.03			
Serial output	O	utput delay time	tdD0(4)	SO1(P13), SB1(P14)	 Must be specified with respect to falling edge of SIOCLK. Must be specified as the time to the beginning of output state change in open drain output mode. See Fig. 8. 	2.7 to 5.5			(1/3)tCYC +0.05	μs

Note 4-2-1: These specifications are theoretical values. Margins must be allowed according to the actual operating conditions.

Pulse Input Conditions at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Parameter	Symbol	Pin/Remarks	Conditions			Speci	fication	
Parameter	Symbol	Pin/Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
High/low level pulse width	tP1H(1) tP1L(1)	INT0(P70), INT1(P71), INT2(P72), INT4(P20 to P23), INT5(P24 to P25), INT6(P20), INT7(P24)	 Interrupt source flag can be set. Event inputs for timer 0 or 1 are enabled. 	2.7 to 5.5	1			
	tPIH(2) tPIL(2)	INT3(P73) when noise filter time constant is 1/1	 Interrupt source flag can be set. Event inputs for timer 0 are enabled. 	2.7 to 5.5	2			tCYC
	tPIH(3) tPIL(3)	INT3(P73) when noise filter time constant is 1/32	 Interrupt source flag can be set. Event inputs for timer 0 are nabled. 	2.7 to 5.5	64			
	tPIH(4) tPIL(4)	INT3(P73) when noise filter time constant is 1/128	 Interrupt source flag can be set. Event inputs for timer 0 are enabled. 	2.7 to 5.5	256			
	tPIL(5)	RES	Resetting is enabled.	2.7 to 5.5	200			μs

AD Converter Characteristics at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

<12-bits AD Converter Mode>

Parameter	Symbol	Pin/Remarks	Conditions		Specification			
Parameter	Symbol	T III/Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
Resolution	Ν	AN0(P00) to		3.0 to 5.5		12		bit
Absolute accuracy	ET	AN7(P07), AN8(P70),	(Note 6-1)	3.0 to 5.5			±16	LSB
Conversion time	TCAD	AN9(P71),	See conversion time calculation	4.5 to 5.5	32		115	
		AN10(XT1), AN11(XT2)	formulas. (Note 6-2)	3.0 to 5.5	64		115	μs
Analog input voltage range	VAIN	ANTI(X12)		3.0 to 5.5	V _{SS}		V _{DD}	V
Analog port	IAINH	1	VAIN=V _{DD}	3.0 to 5.5			1	
input current	IAINL	1	VAIN=V _{SS}	3.0 to 5.5	-1			μA

<8-bits AD Converter Mode>

Parameter	Cumbal	Pin/Remarks	Conditions	_		Specifi	cation	
Parameter	Symbol	Pin/Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
Resolution	Ν	AN0(P00) to		3.0 to 5.5		8		bit
Absolute accuracy	ET	AN7(P07), AN8(P70),	(Note 6-1)	3.0 to 5.5			±1.5	LSB
Conversion time	TCAD	AN9(P71),	See conversion time calculation	4.5 to 5.5	20		90	
		AN10(XT1), AN11(XT2)	formulas. (Note 6-2)	3.0 to 5.5	40		90	μs
Analog input voltage range	VAIN	ANTI(X12)		3.0 to 5.5	V _{SS}		V _{DD}	V
Analog port	IAINH		VAIN=V _{DD}	3.0 to 5.5			1	
input current	input current IAINL		VAIN=V _{SS}	3.0 to 5.5	-1			μA

Conversion time calculation formulas :

12-bits AD Converter Mode : TCAD (Conversion time) = $((52/(AD \text{ division ratio}))+2) \times (1/3) \times tCYC$ 8-bits AD Converter Mode : TCAD (Conversion time) = $((32/(AD \text{ division ratio}))+2) \times (1/3) \times tCYC$

<Recommended Operating Conditions>

External	Supply Voltage	System Clock	Cycle Time	AD Frequency	Conversion Time (TCAD)[µs]		
oscillator FmCF[MHz]	Range V _{DD} [V]	Division (SYSDIV)	tCYC [ns]	Division Ratio (ADDIV)	12-bit AD	8-bit AD	
40	4.0 to 5.5	1/1	250	1/8	34.8	21.5	
12	3.0 to 5.5	1/1	250	1/16	69.5	42.8	

Note 6-1: The quantization error (±1/2LSB) must be excluded from the absolute accuracy. The absolute accuracy must be measured in the microcontroller's state in which no I/O operations occur at the pins adjacent to the analog input channel.

Note 6-2: The conversion time refers to the period from the time an instruction for starting a conversion process till the time the conversion results register(s) are loaded with a complete digital conversion value corresponding to the analog input value.

The conversion time is 2 times the normal-time conversion time when:

- The first AD conversion is performed in the 12-bit AD conversion mode after a system reset.
- The first AD conversion is performed after the AD conversion mode is switched from 8-bit to 12-bit conversion mode.

LC87F1L16A

Consumption Current Characteristics at Ta = -40°C to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Parameter	Symbol	Pin/	Conditions		Specification			
raidiiielei	Symbol	Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
Normal mode consumption current	IDDOP(1)	V _{DD} 1 =V _{DD} 2 =V _{DD} 3	FmCF=12MHz ceramic oscillation mode FsX'tal=32.768kHz crystal oscillation mode System clock set to 12MHz side	4.5 to 5.5		7.8	15	
(Note 7-1)	IDDOP(2)		 Internal PLL oscillation stopped Internal RC oscillation stopped USB circuit stopped 1/1 frequency division ratio 	3.0 to 3.6		4.6	8.4	
	IDDOP(3)		FmCF=12MHz ceramic oscillation mode FsX'tal=32.768kHz crystal oscillation mode System clock set to 12MHz side	4.5 to 5.5		14	25	
	IDDOP(4)		 Internal PLL oscillation mode active Internal RC oscillation stopped USB circuit active 1/1 frequency division ratio 	3.0 to 3.6		7.1	14	mA
	IDDOP(5)		FmCF=12MHz ceramic oscillation mode	4.5 to 5.5		5.2	8.7	
	IDDOP(6)		 FsX'tal=32.768kHz crystal oscillation mode System clock set to 6MHz side 	3.0 to 3.6		3.4	5.6	
	IDDOP(7)		 Internal RC oscillation stopped 1/2 frequency division ratio 	2.7 to 3.0		2.8	4.6	
	IDDOP(8)		FmCF=0Hz (Oscillation stopped)	4.5 to 5.5		0.63	2.3	
	IDDOP(9)		 FsX'tal=32.768kHz crystal oscillation mode System clock set to internal RC oscillation. 	3.0 to 3.6		0.37	1.3	
	IDDOP(10)		System clock set to internal NC oscillation: 1/2 frequency division ratio FmCF=0Hz (Oscillation stopped) FsX'tal=32.768kHz crystal oscillation mode System clock set to crystal oscillation. (32.768kHz)	2.7 to 3.0		0.32	1.0	
ID	IDDOP(11)			4.5 to 5.5		43	123	
	IDDOP(12)			3.0 to 3.6		17	52	μA
	IDDOP(13)		Internal RC oscillation stopped1/2 frequency division ratio	2.7 to 3.0		13	38	
HALT mode consumption current (Note7-1)	IDDHALT(1)		 HALT mode FmCF=12MHz ceramic oscillation mode FsX'tal=32.768kHz crystal oscillation mode System clock set to 12MHz side 	4.5 to 5.5		3.3	5.9	
	IDDHALT(2)		 Internal PLL oscillation stopped Internal RC oscillation stopped USB circuit stopped 1/1 frequency division ratio 	3.0 to 3.6		1.7	3.1	
	IDDHALT(3)		HALT mode FmCF=12MHz ceramic oscillation mode FsX'tal=32.768kHz crystal oscillation mode System clock set to 12MHz side	4.5 to 5.5		9.2	17	
	IDDHALT(4)		 Internal PLL oscillation mode active Internal RC oscillation stopped USB circuit active 1/1 frequency division ratio 	3.0 to 3.6		4.3	8.3	mA
	IDDHALT(5)]	HALT mode FmCF=12MHz ceramic oscillation mode	4.5 to 5.5		2.2	4.0	
	IDDHALT(6)	-	 FsX'tal=32.768kHz crystal oscillation mode System clock set to 6MHz side 	3.0 to 3.6		1.1	2.0	
	IDDHALT(7)	1	 Internal RC oscillation stopped 1/2 frequency division ratio 	2.7 to 3.0		0.88	1.5	
	IDDHALT(8)	• 1/2 frequency division ratio • HALT mode		4.5 to 5.5		0.36	1.3	
	IDDHALT(9)	1	FmCF=0Hz (Oscillation stopped) FsX'tal=32.768kHz crystal oscillation mode	3.0 to 3.6		0.18	0.62	1
	IDDHALT(10)		System clock set to internal RC oscillation.	2.7 to 3.0		0.14	0.45	

Note 7-1: The consumption current value includes none of the currents that flow into the output Tr and internal pull-up resistors.

Continued on next page.

Parameter	Symbol	Pin/	Conditions		Specification			
Falameter	Symbol	Remarks	Conditions	V _{DD} [V]	min	typ	max	unit
HALT mode consumption current (Note 7-1)	IDDHALT(11)	V _{DD} 1 =V _{DD} 2	HALT mode FmCF=0MHz (Oscillation stopped)	4.5 to 5.5		31	99	
	IDDHALT(12)	=V _{DD} 3	 FsX'tal=32.768kHz crystal oscillation mode System clock set to crystal oscillation. 	3.0 to 3.6		8.2	36	
	IDDHALT(13)		 (32.768kHz) Internal RC oscillation stopped 1/2 frequency division ratio 	2.7 to 3.0		5.5	25	
HOLD mode	IDDHOLD(1)	V _{DD} 1	HOLD mode	4.5 to 5.5		0.10	24	μΑ
consumption	IDDHOLD(2)		 CF1=V_{DD} or open (External clock mode) 	3.0 to 3.6		0.04	13	
current	IDDHOLD(3)			2.7 to 3.0		0.03	11	
Timer HOLD mode - consumption - current	IDDHOLD(4)		Timer HOLD mode	4.5 to 5.5		28	92	
	IDDHOLD(5)		CF1=V _{DD} or open (External clock mode) FsX'tal=32.768kHz crystal oscillation mode	3.0 to 3.6		6.6	32	
	IDDHOLD(6)		FSA tal=32.768KHz crystal oscillation mode			4.1	22	

Note 7-1: The consumption current value includes none of the currents that flow into the output Tr and internal pull-up resistors

USB Characteristics and Timing at $Ta = -40^{\circ}C$ to $+85^{\circ}C$, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Deremeter	Sumbol	Conditions		Specifi	cation	
Parameter	Symbol	Conditions	min	typ	max	unit
High level output	VOH(USB)	• 15kΩ±5% to GND	2.8		3.6	V
Low level output	VOL(USB)	• 1.5kΩ±5% to 3.6V	0.0		0.3	V
Output signal crossover voltage	VCRS		1.3		2.0	V
Differential input sensitivity	V _{DI}	• (UHAD+)-(UHAD-) • (UHBD+)-(UHBD-)	0.2			V
Differential input common mode range	VCM		0.8		2.5	V
High level input	VIH(USB)		2.0		3.6	V
Low level input	V _{IL(USB)}		0.0		0.8	V
USB data rise time	^t R	• R _S =33Ω, C _L =50pF	4		20	ns
USB data fall time	tF	• R _S =33Ω, C _L =50pF	4		20	ns

F-ROM Programming Characteristics at $Ta = +10^{\circ}C$ to $+55^{\circ}C$, VSS1 = 0V

Parameter	Cumbol	Pin/	Conditions	Specification				
Parameter	Symbol	Symbol Conditions Remarks	V _{DD} [V]	min	typ	max	unit	
Onboard programming current	IDDFW(1)	V _{DD} 1	 Excluding power dissipation in the microcontroller block 	3.0 to 5.5		5	10	mA
Programming time	tFW(1)		Erase operation	0.045.5.5		20	30	ms
	tFW(2) • Write o		Write operation	3.0 to 5.5		40	60	μs

Characteristics of a Sample Main System Clock Oscillation Circuit

Given below are the characteristics of a sample main system clock oscillation circuit that are measured using a SANYO-designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 1 shows the characteristics of a oscillation circuit when USB host function is not used.

If USB host function is to be used, it is absolutely recommended to use an oscillator that satisfies the precision and stability according to the USB standards.

Table 1	Characteristics of a Sa	mple Main System	n Clock Oscillator	· Circuit with a Cerami	c Oscillator
raoie i	characteristics of a st	imple main bysten	i cioen obeinator	Chedit with a Cerain	e obeimator

Nominal Frequency	Nominal	Vendor		Circuit Constant			Operating Voltage	Oscillation Stabilization Time		
	Name	Oscillator Name	C1 [pF]	C2 [pF]	Rd1 [Ω]	Range [V]	typ [ms]	max [ms]	Remarks	
	12MHz	MURATA	CSTCE12M0GH5L**-R0	(33)	(33)	470	3.0 to 5.5	0.1	0.5	C1 and C2 integrated SMD type

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized in the following cases (see Figure 4):

- Till the oscillation gets stabilized after VDD goes above the operating voltage lower limit.
- Till the oscillation gets stabilized after the instruction for starting the main clock oscillation circuit is executed
- Till the oscillation gets stabilized after the HOLD mode is reset.
- Till the oscillation gets stabilized after the X'tal HOLD mode is reset with CFSTOP (OCR register, bit 0) set to 0

Characteristics of a Sample Subsystem Clock Oscillator Circuit

Given below are the characteristics of a sample subsystem clock oscillation circuit that are measured using a SANYOdesignated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 2 Characteristics of a Sample Subsystem Clock Oscillator Circuit with a Crystal Oscillator

Nominal Frequency	Vendor Name	Oscillator Name	Circuit Constant			Operating Voltage	Oscillation Stabilization Time			
			C3	C4	Rf	Rd2	Range	typ	max	Remarks
			[pF]	[pF]	[Ω]	[Ω]	[V]	[s]	[s]	
32.768kHz	EPSON TOYOCOM	MC-306	18	18	OPEN	560k	2.7 to 5.5	1.1	3.0	Applicable CL value=12.5pF SMD type

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized in the following cases (see Figure 4):

- Till the oscillation gets stabilized after the instruction for starting the subclock oscillation circuit is executed
- Till the oscillation gets stabilized after the HOLD mode is reset with EXTOSC (OCR register, bit 6) set to 1
- Note: The components that are involved in oscillation should be placed as close to the IC and to one another as possible because they are vulnerable to the influences of the circuit pattern.

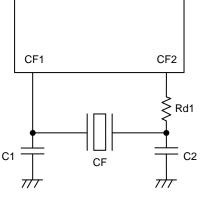


Figure 1 CF Oscillator Circuit

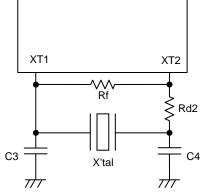


Figure 2 Crystal Oscillator Circuit

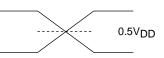
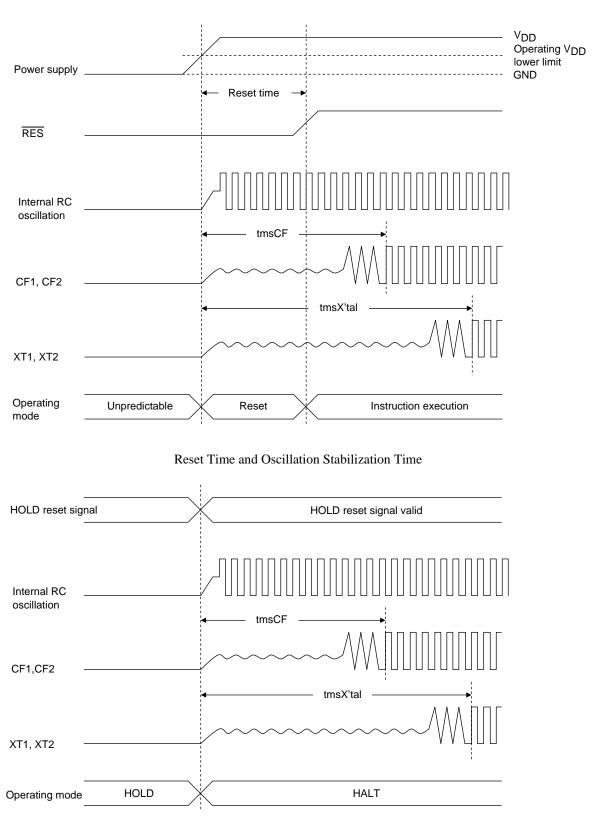
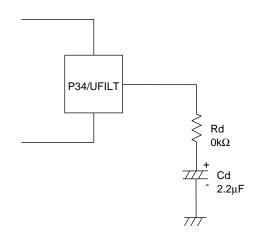


Figure 3 AC Timing Measurement Point

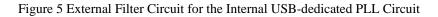


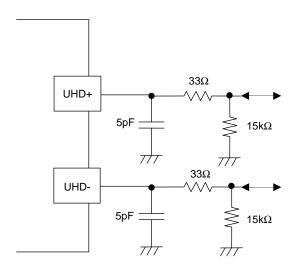
HOLD Reset Signal and Oscillation Stabilization Time

Figure 4 Oscillation Stabilization Time



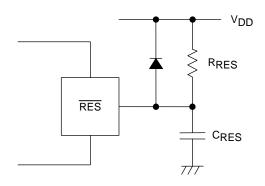
When using the internal PLL circuit to generate the 48MHz clock for USB, it is necessary to connect a filter circuit such to as that shown the left to the P34/UFILT pin.





It's necessary to adjust the Circuit Constant of the USB Port Peripheral Circuit for each mounting board.

Figure 6 USB Port Peripheral Circuit



Note:

Determine the value of C_{RES} and R_{RES} so that the reset signal is present for a period of 200µs after the supply voltage goes beyond the lower limit of the IC's operating voltage.



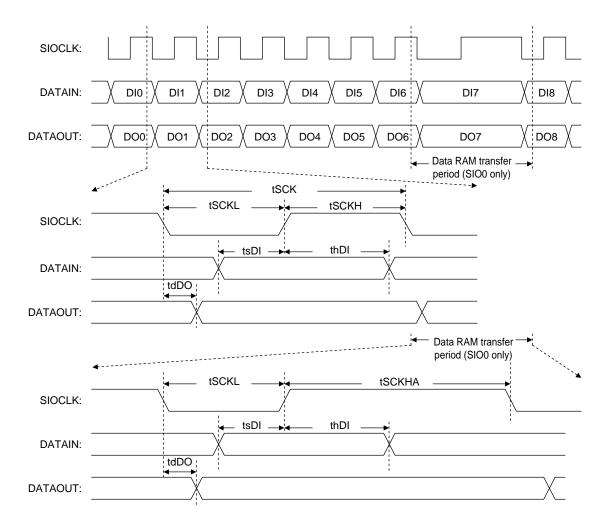


Figure 8 Serial Input/Output Waveform

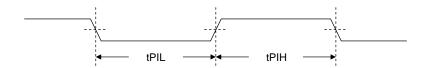


Figure 9 Pulse Input Timing Signal Waveform

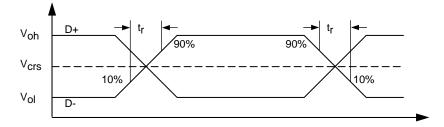


Figure 10 USB Data Signal Timing and Voltage Level

- SANYO Semiconductor Co.,Ltd. assumes no responsibility for equipment failures that result from using products at values that exceed, even momentarily, rated values (such as maximum ratings, operating condition ranges, or other parameters) listed in products specifications of any and all SANYO Semiconductor Co.,Ltd. products described or contained herein.
- SANYO Semiconductor Co.,Ltd. strives to supply high-quality high-reliability products, however, any and all semiconductor products fail or malfunction with some probability. It is possible that these probabilistic failures or malfunction could give rise to accidents or events that could endanger human lives, trouble that could give rise to smoke or fire, or accidents that could cause damage to other property. When designing equipment, adopt safety measures so that these kinds of accidents or events cannot occur. Such measures include but are not limited to protective circuits and error prevention circuits for safe design, redundant design, and structural design.
- In the event that any or all SANYO Semiconductor Co.,Ltd. products described or contained herein are controlled under any of applicable local export control laws and regulations, such products may require the export license from the authorities concerned in accordance with the above law.
- No part of this publication may be reproduced or transmitted in any form or by any means, electronic or mechanical, including photocopying and recording, or any information storage or retrieval system, or otherwise, without the prior written consent of SANYO Semiconductor Co.,Ltd.
- Any and all information described or contained herein are subject to change without notice due to product/technology improvement, etc. When designing equipment, refer to the "Delivery Specification" for the SANYO Semiconductor Co.,Ltd. product that you intend to use.
- Information (including circuit diagrams and circuit parameters) herein is for example only; it is not guaranteed for volume production.
- Upon using the technical information or products described herein, neither warranty nor license shall be granted with regard to intellectual property rights or any other rights of SANYO Semiconductor Co.,Ltd. or any third party. SANYO Semiconductor Co.,Ltd. shall not be liable for any claim or suits with regard to a third party's intellectual property rights which has resulted from the use of the technical information and products mentioned above.

This catalog provides information as of September, 2010. Specifications and information herein are subject to change without notice.