# RICHTEK®

## Dual Channel High Efficiency and High Accuracy Average Current Control LED Backlight Buck Controller

### **General Description**

The RT6010 is a dual channel high accuracy average current control LED backlight buck controller for 2 LED strings w/ o LED binning. Dual MOSFET drivers are specifically designed to drive two power N-MOSFETs in an asynchronous buck converter topology. The controller provides variable LED current control by adjusting the CS resistor value for digital and linear dimming. The controller operates with T1/T2 Average Current Control (T<sup>2</sup>C) topology to provide high accuracy ±3%. The controller also provides high efficiency (higher than 95%) under proper setting without LED binning. The controller provides V<sub>IN</sub> from 8V to 450V. It is preferred to operate the controller under a current ripple of < 30% average current and about 85% duty to optimize the performance.

The RT6010 can be easily connected in series by master/ slave synchronization for multiple channel, even for more than 6-CH. The controller provides SPD (Smart Phase Shift Dimming) that is easily implemented to synchronize master and slave ICs. The controller provides both analog and PWM dimming.

The RT6010 automatically detects LED bar open, LED bar short to  $V_{IN}$ , and LED bar short to GND to prevent VOUT from over/under voltage damages. The controller also outputs fault signal with programmable delay to previous power stage, such as ACDC controller.

### **Ordering Information**

RT6010

Package Type S :SOP-16 —Lead Plating System G : Green (Halogen Free and Pb Free)

Note :

Richtek products are :

- RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- Suitable for use in SnPb or Pb-free soldering processes.

### Features

- Fast Average Current Control T<sup>2</sup>C (T1/T2 Average Current Control)
- Dual MOSFET Drives for Asynchronous Buck Topology
- Provide High Efficiency > 95% and High Accuracy ±3% Channel to Channel Variation
- Provide LED w/o Binning
- Programmable PWM Constant Off Time
- Support both PWM and Analog Dimming
- PWM Dimming Duty Down to 1%
- $\bullet$  OVP for Bar Short with  $V_{\text{IN}}$
- UVP for Bar Open/Short to GND with programmable Fault Delay
- Support SPD (Smart Phase Shift Dimming) for Multiple Channel Dimming Solution
- V<sub>IN</sub> POR Detection with EN Pin to Prevent Malfunction
- SOP-16 Package
- RoHS Compliant and Halogen Free

### Applications

- LCD TV, MNT Display Backlight
- DC/DC or ACDC LED Driver Application
- General Purpose Constant Current Source
- LED Signage and Display
- Architectural and Decorative LED Lighting
- LED Street Lighting

## **Pin Configurations**

(TOP VIEW)





### **Marking Information**

RT6010 GSYMDNN RT6010GS : Product Number YMDNN : Date Code

### **Typical Application Circuit**



Figure 1



Figure 2. Synchronization for Multiple Channel\_Digital







### **Functional Pin Description**

Pin No.	Pin Name	Pin Function
1	VCC	Power Supply for PWM Controller.
2	DIM/PWM_IN	Dimming PWM Pulse Input or Analog Voltage Input.
3	RT	Constant off time setting by connecting proper resistor to VSS.
4	D_OSC	For analog dimming, D_OSC should be connected to a capacitor to generate dimming triangle oscillator that is compared with DIM/PWM_IN DC voltage level to generate PWM dimming pulse. For digital dimming, D_OSC should be connected to VSS.
5	F_DELAY	Define FAULT pin output delay by connecting to a proper capacitor to prevent false trigger for UVP and OTP.
6	FAULT	Open drain output fault including UVP, OVP, and OTP (Active Low).
7	NC	No Internal Connection.
8	DPS	Smart Phase Shift Dimming Disable Pin. Pull DPS high to disable function.
9	CS1	Channel 1 Current Sense Input.
10	GATE1	Channel 1 Current Gate Driver Output.
11	GATE2	Channel 2 Current Gate Driver Output.
12	CS2	Channel 2 Current Sense Input.
13	EN	Chip Enable (Active High). Enable PWM system, prefer connect to $V_{IN}$ resistive voltage divider to guarantee $V_{IN}$ power ready to prevent from PWM malfunction.
14	RT_OUT	Output for the next RT6010 RT.
15	PWM_OUT	SPD (Smart Phase Shift Dimming) output for slave to synchronize dimming phase shift.
16	VSS	Ground.



## **Function Block Diagram**



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## **RT6010**

## Absolute Maximum Ratings (Note 1)

Supply Voltage, V <sub>CC</sub>	- –0.3V to 15V
• D_OSC, PWM_OUT	- –0.3V to 7V
Others Pins	- –0.3V to 15V
• Power Dissipation, $P_D @ T_A = 25^{\circ}C$	
SOP-16	- 1.176W
Package Thermal Resistance (Note 2)	
SOP-16, θ <sub>JA</sub>	- 85°C/W
Lead Temperature (Soldering, 10 sec.)	- 260°C
Junction Temperature	- 150°C
Storage Temperature Range	- –65°C to 150°C
ESD Susceptibility (Note 3)	
HBM (Human Body Mode)	- 2kV
MM (Machine Mode)	- 200V

## Recommended Operating Conditions (Note 4)

Control Input Voltage, V <sub>CC</sub>	- 12V ±10%
Supply Input Voltage, V <sub>IN</sub>	- 8V to 450V
Junction Temperature Range	- –40°C to 125°C
Ambient Temperature Range	- –40°C to 85°C

### **Electrical Characteristics**

 $(T_A = 25^{\circ}C, \text{ unless otherwise specified})$ 

Parameter		Symbol	Test Conditions		Тур	Мах	Unit	
Supply Input								
Supply Current		Ivcc	$V_{BOOT} = 12V, V_{DIM/PWM_IN} = 5V, V_{CSx} = 0.3V$		4		mA	
Shutdown Current		I <sub>SHDN</sub>	Without HV LDO → lower shut down current 1mA			1	mA	
UVLO Threshold		VUVLO		7	8	9	V	
UVLO Hysteresis		$\Delta V_{UVLO}$			1		V	
DIM/PWN_IN	Logic-High	V <sub>IH</sub>		2			v	
Threshold Voltage	Logic-Low	VIL				0.6		
PWM_OUT	Logic-High	V <sub>OH</sub>		2.4			V	
Threshold Voltage	Logic-Low	Vol				0.4	v	
EN Threshold					2		V	
EN Hysteresis					0.2		V	
PWM Controller								
CS V <sub>REF</sub>					500		mV	
On-Time		t <sub>ON</sub>	Recommend		8	20	μS	
Constant Off-Time		t <sub>OFF</sub>	Set up by RT(set 66.6k $\Omega$ )		1	1.2	μS	
Duty			Recommend customer application duty		85	90	%	



Parameter		Symbol	Test Conditions	Min	Тур	Max	Unit	
PWM Frequency			Defined by t <sub>OFF</sub>	50	100	300	kHz	
Channel-to-Channel Accuracy					1.6		%	
Protection								
OVP			LED string short		1		V	
UVP			LED string no connection		100		mV	
F_DELAY Detect Voltage			Bar open, Bar short to GND, Bar short to $V_{IN} \& OTP$	0.9	1	1.1	V	
F_DELAY Curr	ent Source				10		μA	
FAULT Open D	Drain Ability					100	Ω	
UVP/OVP Blar	nking Time				500		ns	
UVP Delay Tin	ne		To gate off		250		ns	
OTP					160		°C	
OTP Hysteresis				-	20		°C	
Dimming								
PWM Dimming Frequency				100		600	Hz	
Min Dimming Pulse				5			μS	
Forced Dimming Delay Time (High)			Force dimming to H when DIM/PWM_IN goes H for too long		25		ms	
D_OSC Input	High-Level	V <sub>IH</sub>	When operating at analog dimming, we recommend DIM below 2.4V	-	2.5		V	
	Low-Level	V <sub>IL</sub>	When operating at analog dimming, we recommend DIM above 1.1V		1			
D_OSC Sourcing Current					10		μA	
D_OSC Sinking Current					10		μA	
Driver Capabi	lity							
Gate Driver So	ource		V <sub>CC</sub> = 12V, V <sub>GATEX</sub> = 9V		80		mA	
Gate Driver Sink			$V_{CC} = 12V$ , $V_{GATEX} = 3V$		200		mA	

- **Note 1.** Stresses beyond those listed "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.
- **Note 2.**  $\theta_{JA}$  is measured at  $T_A = 25^{\circ}C$  on a high effective thermal conductivity four-layer test board per JEDEC 51-7.
- Note 3. Devices are ESD sensitive. Handling precaution is recommended.
- Note 4. The device is not guaranteed to function outside its operating conditions.

## **Typical Operating Characteristics**











Output Voltage (V)





LED Current vs. PWM Duty Cycle



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### **Application Information**

The RT6010 is a dual channel, high accuracy current control LED backlight buck controller. The controller is capable of providing efficiency higher than 95% for LED backlight use.

#### **Current Setting**

Current flow through the inductor during charging period is detected by a sensing resistor,  $R_{CS}$ . The RT6010 provides average current mode by dynamically adjusting  $V_{REF}$ . The LED average current can be set as :

 $I_{OUT} = \frac{500 \text{mV}}{\text{Rcs}}$ 

#### **Constant Off-Time Setting**

The RT6010 is a constant off-time control IC. The off-time can be set via the external RT pin resistance,  $R_{RT}$ . The switching frequency is usually designed to be between 50kHz to 300kHz, so the constant off-time must also meet the following condition :

$$\begin{split} & 50k \leq \frac{V_{IN} - V_{LED}}{t_{OFF} \ x \ V_{IN}} \leq 300k \\ & t_{OFF} = 15p \ x \ R_{RT} \end{split}$$

where  $t_{\mathsf{OFF}}$  is the constant off-time

#### **Smart Phase Shift Dimming**

The RT6010 provides dimming function selection via the DPS pin. If the pin is connected to VCC, the two dimming signals will be in sync for those two channels. On the other hand, if the pin is connected to GND, the two dimming signals will be separated. See Figure below.



Figure 4. Smart Phase Shift Dimming Via the DPS Pin

#### **Analog Dimming Frequency Setting**

The RT6010 not only provides digital dimming, but also analog dimming as well. The analog dimming frequency is set via the D\_OSC pin. Note that the minimum dimming duty is 6.667%. The dimming frequency is set according to the following equation :

 $f_{PWM} = 10 \mu A / (C_D \text{ OSC} \times 3V)$ 

where  $C_{\text{D}\_\text{OSC}}$  is the capacitor connected from the D\_OSC pin to GND.

#### **Protection Functions**

The RT6010 provides various protection features to prevent damage to the IC during abnormal situations. The features include over voltage protection, under voltage protection, and over temperature protection. The protection flow chart is shown below.

#### **FLT Blanking Delay**

An FLT blanking delay function is available for setting the fault delay time to prevent false triggers for UVP and OTP. The delay time is set via the external capacitor connected from the F\_DELAY pin to ground. The blanking delay time can be set according to below equation :

$$t = C_{F_{DELAY}} \times \frac{1V}{10\mu A}$$

where  $C_{F_DELAY}$  is the capacitor connected from the F\_DELAY pin to GND. After  $V_{F_DELAY} > 1V$ , a fault signal will be sent to the FAULT pin.

#### **Over Voltage Protection**

The RT6010 provides Over Voltage Protection (OVP) when the LED cathode becomes shorted to VIN. The OVP threshold voltage of the CSx pin is approximately 1V. If OVP is triggered during gate-on period, the controller will turn off the MOSFET for 400 $\mu$ s. If OVP occurs consecutively for more than 14 times, the RT6010 will send a fault signal to the FAULT.

#### **Under Voltage Protection**

For situations where the LED cathode becomes open or shorted to GND, the RT6010 provides Under Voltage Protection (UVP). The threshold voltage of UVP is approximately 0.1V. If UVP occurs during gate-on period, the RT6010 will send a fault signal to the FAULT pin after the fault delay time.





Figure 5. Protection Flow Chart for the RT6010

#### **Over Temperature Protection**

To prevent excessive power dissipation from damaging the device, the RT6010 includes an over temperature protection feature. When the temperature rises above OTP temperature, a fault signal will be sent to disable the channel after the fault delay time. After the die temperature falls below OTP hysteresis temperature, the channel will be enabled again.

#### **Inductor Selection**

The inductor current ripple is usually designed below 30% of its average current. Hence, the recommended inductor value can be calculated as :

$$L > \frac{V_{LED}}{0.3 \times I_{OUT}} \times t_{OFF}$$

where  $V_{\text{LED}}$  is the LED series voltage drop,  $t_{\text{OFF}}$  is the PWM off-time, and  $I_{\text{OUT}}$  is the LED average current.

#### **MOSFET Selection**

For operating at high input or output voltages, the power N-MOSFET switch is typically chosen according to the drain voltage,  $V_{DS}$ , rating and low gate charge. Consideration of switch on-resistance,  $R_{DS(ON)}$ , is usually secondary because switching losses dominate power loss. The gate driving voltage follows the V<sub>CC</sub> voltage range, which is 12V for normal operation. The N-MOSFET must meet this specification.

#### **Capacitor Selection**

Selecting a suitable capacitor can reduce LED current ripple and increase LED life-time. Moreover, if the capacitor has good current sense linearity, it will also ensure that the current matching is accurate. Note that having too large of a capacitance will cause the LED current to respond slowly. The typical value of the capacitor is  $0.22\mu$ F.

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#### **Diode Selection**

Ultra-fast diodes are chosen for their low forward voltage drop and fast switching speed. When selecting ultra-fast diodes, important parameters such as power dissipation, reverse voltage rating, and pulsating peak current should all be taken into consideration. A suitable ultra-fast diode's reverse voltage rating must be greater than the input voltage and its average current rating must exceed the LED average current.

#### Power On

For power on sequence, it is recommended to connect EN to a resistive voltage divider placed between  $V_{IN}$  and GND to prevent UVP malfunction, as shown below.



Figure 6. Circuit for Proper Power On Via EN Pin





If  $V_{CC}$  and  $V_{EN}$  power on before  $V_{IN}$  powers on, UVP fault will be triggered.

Figure 7. (b) UVP Malfunction without  $R_{\text{EN1}},\,R_{\text{EN2}}$  Resistors

Figure 7. Timing Diagram for Power On Sequence

#### **Thermal Considerations**

For continuous operation, do not exceed absolute maximum junction temperature. The maximum power dissipation depends on the thermal resistance of the IC package, PCB layout, rate of surrounding airflow, and difference between junction and ambient temperature. The maximum power dissipation can be calculated by the following formula :

$$\mathsf{P}_{\mathsf{D}(\mathsf{MAX})} = (\mathsf{T}_{\mathsf{J}(\mathsf{MAX})} - \mathsf{T}_{\mathsf{A}}) / \theta_{\mathsf{J}\mathsf{A}}$$

where  $T_{J(MAX)}$  is the maximum junction temperature,  $T_A$  is the ambient temperature, and  $\theta_{JA}$  is the junction to ambient thermal resistance.

For recommended operating condition specifications, the maximum junction temperature is 125°C. The junction to ambient thermal resistance,  $\theta_{JA}$ , is layout dependent. For SOP-16 package, the thermal resistance,  $\theta_{JA}$ , is 85°C/W on a standard JEDEC 51-7 four-layer thermal test board. The maximum power dissipation at  $T_A = 25$ °C can be calculated by the following formula :

 $P_{D(MAX)} = (125^{\circ}C - 25^{\circ}C) / (85^{\circ}C/W) = 1.176W$  for SOP-16 package

Figure 7. (a) Proper Start Up with R<sub>EN1</sub>, R<sub>EN2</sub> Resistors



The maximum power dissipation depends on the operating ambient temperature for fixed  $T_{J(MAX)}$  and thermal resistance,  $\theta_{JA}$ . The derating curve in Figure 8 allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.



Figure 8. Derating Curve of Maximum Power Dissipation

#### Layout Considerations

PCB layout plays an important role for the RT6010. Careful layout can decrease switching noise for stable operation and improve performance. For best performance of the RT6010, the following layout guidelines should be strictly followed.

- Current sense feedback resistors, D\_OSC capacitor, F\_DELAY capacitor, RT resistor and capacitors for VIN and VCC should be placed as close to the controller as possible.
- Keep the power loops as short as possible to prevent voltage spikes caused by current transition from one device to another at high speed as a result of parasitic components on the circuit board. Therefore, all current switching loops should be kept as short as possible with wide traces to minimize the parasitic components.
- Minimize the trace length between the MOSFET and the controller. Since the drivers are integrated in the controller, the driving path should be short and wide to reduce the parasitic inductance and resistance.
- The CS1 and CS2 current sense feedback trace should be kept away from the switching node. Keep the feedback trace close to the CS1 and CS2 pins. Allow large area for VIN inductor trace, FET trace, R<sub>CS1</sub> and R<sub>CS2</sub> trace, and GND pad.

GND VCC I ⊐ VSS 16 . Q1 DIM/PWM\_IN E PWM OUT 2 15 GN RT C 14 □ RT\_OUT 3 13 ⊐ EN D\_OSC E 4 CS2 F DELAY D 12 5 FAULT 6 11 GATE2 Г NC E 10 7 GATE1 DPS 8 9 ] CS1 GND Current sense feedback resistors, D OSC Place the power components The current sense node capacitor, F DELAY capacitor, RT resistor as close to the IC as possible. must be near the CS pin. and capacitors for VIN and VCC should be placed as close to the controller as possible.

The GND traces should be wide and short.





### **Outline Dimension**



Complete L	Dimensions	n Millimeters	<b>Dimensions In Inches</b>		
Symbol	Min	Max	Min	Мах	
А	9.804	10.008	0.386	0.394	
В	3.810	3.988	0.150	0.157	
С	1.346	1.753	0.053	0.069	
D	0.330	0.508	0.013	0.020	
F	1.194	1.346	0.047	0.053	
Н	0.178	0.254	0.007	0.010	
I	0.102	0.254	0.004	0.010	
J	5.791	6.198	0.228	0.244	
М	0.406	1.270	0.016	0.050	

16-Lead SOP Plastic Package

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