TOSHIBA CMOS Digital Integrated Circuit Silicon Monolithic
TC74VCXH16646FT

Low-Voltage 16-Bit Bus Transceiver/Register with Bushold

The TC74VCXH16646FT is a high-performance CMOS 16-bit bus transceiver/register. Designed for use in $1.8-\mathrm{V}, 2.5-\mathrm{V}$ or $3.3-\mathrm{V}$ systems, it achieves high-speed operation while maintaining the CMOS low power dissipation.

This device is bus transceiver with 3 -state outputs, D-type flip-flops, and control circuitry arranged for multiplexed transmission of data directly from the internal registers.

The A, B data inputs include active bushold circuitry, eliminating the need for external pull-up resistors to hold unused or floating data inputs at a valid logic level.

All inputs are equipped with protection circuits against static


Weight: 0.25 g (typ.) discharge.

## Features (Note)

- Low-voltage operation: $\mathrm{VCC}_{\mathrm{CC}}=1.8$ to 3.6 V
- Bushold on data inputs eliminating the need for external pull-up/pull-down resistors
- High-speed operation : $\mathrm{t}_{\mathrm{pd}}=2.9 \mathrm{~ns}(\max )\left(\mathrm{V}_{\mathrm{CC}}=3.0\right.$ to 3.6 V$)$

$$
\begin{aligned}
& : \mathrm{t}_{\mathrm{pd}}=3.5 \mathrm{~ns}(\max )\left(\mathrm{V}_{\mathrm{CC}}=2.3 \text { to } 2.7 \mathrm{~V}\right) \\
& : \mathrm{t}_{\mathrm{pd}}=7.0 \mathrm{~ns}(\max )(\mathrm{VCC}=1.8 \mathrm{~V})
\end{aligned}
$$

- 3.6-V tolerant control inputs
- Output current: $\mathrm{IOH} / \mathrm{IOL}= \pm 24 \mathrm{~mA}(\mathrm{~min})(\mathrm{VCC}=3.0 \mathrm{~V})$

$$
\begin{aligned}
& : \mathrm{IOH} / \mathrm{IOL}= \pm 18 \mathrm{~mA}(\min )(\mathrm{VCC}=2.3 \mathrm{~V}) \\
& : \mathrm{IOH}_{\mathrm{OH}} / \mathrm{I}_{\mathrm{OL}}= \pm 6 \mathrm{~mA}(\min )(\mathrm{VCC}=1.8 \mathrm{~V})
\end{aligned}
$$

- Latch-up performance: - 300 mA
- ESD performance: Machine model $\geq \pm 200 \mathrm{~V}$

Human body model $\geq \pm 2000 \mathrm{~V}$

- Package: TSSOP

Note: Do not apply a signal to any bus pins when it is in the output mode. Damage may result.

## Pin Assignment (top view)



## IEC Logic Symbol



## Truth Table

| Control Inputs |  |  |  |  |  | Bus |  | Function |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\overline{\mathrm{OE}}$ | DIR | CAB | CBA | SAB | SBA | A | B |  |
| H | X | X* | X* | X | X | Input | Input | The output functions of $A$ and $B$ Busses are disabled. |
|  |  |  |  |  |  | Z | Z |  |
|  |  | $\uparrow$ | $\uparrow$ | X | X | X | X | Both $A$ and $B$ Busses are used as inputs to the internal flip-flops. Data on the Bus will be stored on the rising edge of the Clock. |
| L | H | X* | X* | L | X | Input | Output | The data on the A bus are displayed on the $B$ bus. |
|  |  |  |  |  |  | L | L |  |
|  |  |  |  |  |  | H | H |  |
|  |  | $\uparrow$ | X* | L | X | L | L | The data on the A bus are displayed on the B Bus, and are stored into the A storage flip-flops on the rising edge of CAB. |
|  |  |  |  |  |  | H | H |  |
|  |  | X* | X* | H | X | X | Qn | The data in the A storage flop-flops are displayed on the B Bus. |
|  |  | $\uparrow$ | X* | H | X | L | L | The data on the A Bus are stored into the A storage flip-flops on the rising edge of CAB, and the stored data propagate directly onto the B Bus. |
|  |  |  |  |  |  | H | H |  |
| L | L | X* | X* | X | L | Output | Input | The data on the $B$ Bus are displayed on the A bus. |
|  |  |  |  |  |  | L | L |  |
|  |  |  |  |  |  | H | H |  |
|  |  | X* | $\uparrow$ | X | L | L | L | The data on the $B$ Bus are displayed on the A Bus, and are stored into the B storage flip-flops on the rising edge of CBA. |
|  |  |  |  |  |  | H | H |  |
|  |  | X* | X* | X | H | Qn | X | The data in the B storage flip-flops are displayed on the A Bus. |
|  |  | X* | $\uparrow$ | X | H | L | L | The data on the $B$ Bus are stored into the $B$ storage flip-flops on the rising edge of CBA, and the stored data propagate directly onto the A Bus. |
|  |  |  |  |  |  | H | H |  |

X: Don't care
Z: High impedance
Qn: The data stored into the internal flip-flops by most recent low to high transition of the clock inputs.
*: The clocks are not internally with either OE or DIR.
Therefore, data on the A and/or B busses may be clocked into the storage flip-flops at any time.

## System Diagram



## Timing Chart


: Don't care Z: High impedance

## Absolute Maximum Ratings (Note 1)

| Characteristics |  | Symbol | Rating | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Power supply voltage |  | $\mathrm{V}_{\mathrm{CC}}$ | -0.5 to 4.6 | V |
| DC input voltage | $\begin{gathered} (\mathrm{DIR}, \overline{\mathrm{OE}}, \mathrm{CAB}, \mathrm{CBA}, \\ \mathrm{SAB}, \mathrm{SBA}) \end{gathered}$ | $\mathrm{V}_{\text {IN }}$ | -0.5 to 4.6 | V |
|  | (An, Bn) |  | $-0.5 \text { to } \mathrm{V}_{\mathrm{CC}}+0.5$ <br> (Note 2) |  |
| DC output voltage | (An, Bn) | Vout | $-0.5 \text { to } \mathrm{V}_{\mathrm{CC}}+0.5$ <br> (Note 3) | V |
| Input diode current |  | IIK | -50 | mA |
| Output diode current |  | IOK | $\pm 50$ (Note 4) | mA |
| Output current |  | IOUT | $\pm 50$ | mA |
| Power dissipation |  | $\mathrm{P}_{\mathrm{D}}$ | 400 | mW |
| DC $\mathrm{V}_{\text {CC }} /$ ground current per supply pin |  | $\mathrm{I}_{\text {CC }} / \mathrm{I}_{\text {GND }}$ | $\pm 100$ | mA |
| Storage temperature |  | $\mathrm{T}_{\text {stg }}$ | -65 to 150 | ${ }^{\circ} \mathrm{C}$ |

Note 1: Exceeding any of the absolute maximum ratings, even briefly, lead to deterioration in IC performance or even destruction.
Using continuously under heavy loads (e.g. the application of high temperature/current/voltage and the significant change in temperature, etc.) may cause this product to decrease in the reliability significantly even if the operating conditions (i.e. operating temperature/current/voltage, etc.) are within the absolute maximum ratings and the operating ranges.
Please design the appropriate reliability upon reviewing the Toshiba Semiconductor Reliability Handbook ("Handling Precautions"/"Derating Concept and Methods") and individual reliability data (i.e. reliability test report and estimated failure rate, etc).
Note 2: OFF state
Note 3: High or low state. IOUT absolute maximum rating must be observed.
Note 4: VOUT < GND, VOUT > VCC

Operating Ranges (Note 1) (Note 2)

| Characteristics |  | Symbol | Rating | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Power supply voltage |  | $\mathrm{V}_{\mathrm{CC}}$ | 1.8 to 3.6 | V |
|  |  | 1.2 to 3.6 (Note 3) |  |
| Input voltage | (DIR, $\overline{O E}, C A B, C B A$, SAB, SBA) |  | $V_{\text {IN }}$ | -0.3 to 3.6 | V |
|  | (An, Bn) | 0 to VCC (Note 4) |  |  |  |
| Output voltage | (An, Bn) | V OUT | 0 to $\mathrm{V}_{\text {CC }}$ (Note 5) | V |  |
| Output current |  | $1 \mathrm{OH} / \mathrm{lOL}$ | $\pm 24 \quad$ (Note 6) | mA |  |
|  |  | $\pm 18 \quad$ (Note 7) |  |  |  |
|  |  | $\pm 6 \quad$ (Note 8) |  |  |  |
| Operating temperature |  |  | $\mathrm{T}_{\text {opr }}$ | -40 to 85 | ${ }^{\circ} \mathrm{C}$ |
| Input rise and fall time |  |  | dt/dv | 0 to 10 (Note 9) | $\mathrm{ns} / \mathrm{V}$ |

Note 1: The operating ranges must be maintained to ensure the normal operation of the device. Unused inputs must be tied to either VCC or GND.

Note 2: Floating or unused control inputs must be held high or low.
Note 3: Data retention only
Note 4: OFF state
Note 5: High or low state
Note 6: $\mathrm{V}_{\mathrm{CC}}=3.0$ to 3.6 V
Note 7: $\quad \mathrm{V}_{\mathrm{CC}}=2.3$ to 2.7 V
Note 8: $V_{C C}=1.8 \mathrm{~V}$
Note 9: $\mathrm{V}_{\mathrm{IN}}=0.8$ to $2.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CC}}=3.0 \mathrm{~V}$

## Electrical Characteristics

DC Characteristics ( $\mathrm{Ta}=-40$ to $85^{\circ} \mathrm{C}, 2.7 \mathrm{~V}<\mathrm{V}_{\mathrm{Cc}} \leqq 3.6 \mathrm{~V}$ )

| Characteristics |  | Symbol | Test Condition |  |  | Min | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input voltage | H-level | $\mathrm{V}_{\mathrm{IH}}$ | - |  | 2.7 to 3.6 | 2.0 | - | V |
|  | L-level | $\mathrm{V}_{\text {IL }}$ | - |  | 2.7 to 3.6 | - | 0.8 |  |
| Output voltage | H-level | $\mathrm{V}_{\mathrm{OH}}$ | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{IH}}$ or $\mathrm{V}_{\mathrm{IL}}$ | $\mathrm{l} \mathrm{OH}=-100 \mu \mathrm{~A}$ | 2.7 to 3.6 | $\begin{gathered} V_{\mathrm{CC}} \\ -0.2 \end{gathered}$ | - | V |
|  |  |  |  | $\mathrm{IOH}=-12 \mathrm{~mA}$ | 2.7 | 2.2 | - |  |
|  |  |  |  | $\mathrm{IOH}=-18 \mathrm{~mA}$ | 3.0 | 2.4 | - |  |
|  |  |  |  | $\mathrm{IOH}^{\prime}=-24 \mathrm{~mA}$ | 3.0 | 2.2 | - |  |
|  | L-level | $\mathrm{V}_{\mathrm{OL}}$ | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\text {IH }}$ or $\mathrm{V}_{\text {IL }}$ | $\mathrm{lOL}=100 \mu \mathrm{~A}$ | 2.7 to 3.6 | - | 0.2 |  |
|  |  |  |  | $\mathrm{IOL}=12 \mathrm{~mA}$ | 2.7 | - | 0.4 |  |
|  |  |  |  | $\mathrm{IOL}=18 \mathrm{~mA}$ | 3.0 | - | 0.4 |  |
|  |  |  |  | $\mathrm{l} \mathrm{OL}=24 \mathrm{~mA}$ | 3.0 | - | 0.55 |  |
| Input leakage current (DIR, $\overline{O E}, ~ C A B, ~ C B A, ~ S A B, ~ S B A) ~(~) ~$ |  | IIN | $\mathrm{V}_{\text {IN }}=0$ to 3.6 V |  | 2.7 to 3.6 | - | $\pm 5.0$ | $\mu \mathrm{A}$ |
| Bushold input minimum drive hold current |  | 11 (HOLD) | $\mathrm{V}_{\mathrm{IN}}=0.8 \mathrm{~V}$ |  | 3.0 | 75 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{IN}}=2.0 \mathrm{~V}$ |  | 3.0 | -75 | - |  |
| Bushold input over-drive current to change state |  |  | $11(O D)$ |  | (Note 1) | 3.6 | - | 450 | $\mu \mathrm{A}$ |
|  |  |  |  | (Note 2) | 3.6 | - | -450 |  |  |
| 3-state output OFF state current |  | Ioz | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{IH}} \text { or } \mathrm{V}_{\mathrm{IL}} \\ & \mathrm{~V}_{\mathrm{OUT}}=\mathrm{V}_{\mathrm{CC}} \text { or GND } \end{aligned}$ |  | 2.7 to 3.6 | - | $\pm 10.0$ | $\mu \mathrm{A}$ |  |
| Quiescent supply current |  | ICC | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {CC }}$ or GND |  | 2.7 to 3.6 | - | 20.0 | $\mu \mathrm{A}$ |  |
| Increase in ICC per input |  | $\Delta_{\text {CC }}$ | $\mathrm{V}_{\mathrm{IH}}=\mathrm{V}_{\mathrm{CC}}-0.6 \mathrm{~V}$ |  | 2.7 to 3.6 | - | 750 | $\mu \mathrm{A}$ |  |

Note 1: An external driver must source at least the specified current to switch from LOW-to-HIGH.
Note 2: An external driver must sink at least the specified current to switch from HIGH-to-LOW.

DC Characteristics ( $\mathrm{Ta}=-40$ to $85^{\circ} \mathrm{C}, 2.3 \mathrm{~V} \leqq \mathrm{~V} \mathrm{CC} \leqq 2.7 \mathrm{~V}$ )

| Characteristics |  | Symbol | Test Condition |  |  | Min | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input voltage | H-level | $\mathrm{V}_{\mathrm{IH}}$ | - |  | 2.3 to 2.7 | 1.6 | - | V |
|  | L-level | $\mathrm{V}_{\text {IL }}$ | - |  | 2.3 to 2.7 | - | 0.7 |  |
| Output voltage | H-level | $\mathrm{V}_{\mathrm{OH}}$ | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{IH}}$ or $\mathrm{V}_{\text {IL }}$ | $\mathrm{I}^{\mathrm{OH}}=-100 \mu \mathrm{~A}$ | 2.3 to 2.7 | $\begin{gathered} V_{C C} \\ -0.2 \end{gathered}$ | - | V |
|  |  |  |  | $\mathrm{IOH}=-6 \mathrm{~mA}$ | 2.3 | 2.0 | - |  |
|  |  |  |  | $\mathrm{IOH}^{\prime}=-12 \mathrm{~mA}$ | 2.3 | 1.8 | - |  |
|  |  |  |  | $\mathrm{IOH}=-18 \mathrm{~mA}$ | 2.3 | 1.7 | - |  |
|  | L-level | Vol | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{IH}}$ or $\mathrm{V}_{\mathrm{IL}}$ | $\mathrm{lOL}=100 \mu \mathrm{~A}$ | 2.3 to 2.7 | - | 0.2 |  |
|  |  |  |  | $\mathrm{l} \mathrm{OL}=12 \mathrm{~mA}$ | 2.3 | - | 0.4 |  |
|  |  |  |  | $\mathrm{lOL}=18 \mathrm{~mA}$ | 2.3 | - | 0.6 |  |
| Input leakage current <br> (DIR, $\overline{O E}, C A B, C B A, S A B, S B A)$ |  | In | $\mathrm{V}_{\mathrm{IN}}=0$ to 3.6 V |  | 2.3 to 2.7 | - | $\pm 5.0$ | $\mu \mathrm{A}$ |
| Bushold input minimum drive hold current |  | $\mathrm{II}_{\text {(HOLD }}$ | $\mathrm{V}_{\text {IN }}=0.7 \mathrm{~V}$ |  | 2.3 | 45 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{IN}}=1.6 \mathrm{~V}$ |  | 2.3 | -45 | - |  |
| Bushold input over-drive current to change state |  |  | $11(O D)$ |  | (Note 1) | 2.7 | - | 300 | $\mu \mathrm{A}$ |
|  |  |  |  | (Note 2) | 2.7 | - | -300 |  |  |
| 3-state output OFF state current |  | loz | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{IH}} \text { or } \mathrm{V}_{\mathrm{IL}} \\ & \mathrm{~V}_{\mathrm{OUT}}=\mathrm{V}_{\mathrm{CC}} \text { or } \mathrm{GND} \end{aligned}$ |  | 2.3 to 2.7 | - | $\pm 10.0$ | $\mu \mathrm{A}$ |  |
| Quiescent supply current |  | Icc | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {CC }}$ or GND |  | 2.3 to 2.7 | - | 20.0 | $\mu \mathrm{A}$ |  |

Note 1: An external driver must source at least the specified current to switch from LOW-to-HIGH.
Note 2: An external driver must sink at least the specified current to switch from HIGH-to-LOW.

DC Characteristics ( $\mathrm{Ta}=-40$ to $85^{\circ} \mathrm{C}, 1.8 \mathrm{~V} \leqq \mathrm{~V} \mathrm{CC}<2.3 \mathrm{~V}$ )

| Characteristics | Symbol | Test Condition |  |  | Min | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input voltage | $\mathrm{V}_{\mathrm{IH}}$ |  |  | 1.8 to 2.3 | $\begin{aligned} & 0.7 \times \\ & \mathrm{V}_{\mathrm{CC}} \end{aligned}$ | - | V |
|  | VIL |  |  | 1.8 to 2.3 | - | $\begin{aligned} & 0.2 \times \\ & \mathrm{V}_{\mathrm{CC}} \end{aligned}$ |  |
| Output voltage | V OH | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\text {IH }}$ or $\mathrm{V}_{\text {IL }}$ | $\mathrm{IOH}=-100 \mu \mathrm{~A}$ | 1.8 | $\begin{aligned} & \hline \mathrm{V}_{\mathrm{CC}} \\ & -0.2 \end{aligned}$ | - | V |
|  |  |  | $\mathrm{IOH}=-6 \mathrm{~mA}$ | 1.8 | 1.4 | - |  |
|  | VoL | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{IH}}$ or $\mathrm{V}_{\mathrm{IL}}$ | $\mathrm{lOL}=100 \mu \mathrm{~A}$ | 1.8 | - | 0.2 |  |
|  |  |  | $\mathrm{IOL}=6 \mathrm{~mA}$ | 1.8 | - | 0.3 |  |
| Input leakage current <br> (DIR, $\overline{O E}, ~ C A B, ~ C B A, ~ S A B, ~ S B A) ~$ | In | $\mathrm{V}_{\mathrm{IN}}=0$ to 3.6 V |  | 1.8 | - | $\pm 5.0$ | $\mu \mathrm{A}$ |
| Bushold input minimum drive hold current | $\mathrm{II}_{\text {(HOLD }}$ | $\mathrm{V}_{\text {IN }}=0.36 \mathrm{~V}$ |  | 1.8 | 25 | - | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{IN}}=1.26 \mathrm{~V}$ |  | 1.8 | -25 | - |  |
| Bushold input over-drive current to change state | 11 (OD) |  | (Note 1) | 1.8 | - | 200 | $\mu \mathrm{A}$ |
|  |  |  | (Note 2) | 1.8 | - | -200 |  |
| 3-state output OFF state current | Ioz | $\begin{aligned} & V_{\text {IN }}=V_{\text {IH }} \text { or } V_{\text {IL }} \\ & V_{\text {OUT }}=V_{\text {CC }} \text { or } G N \end{aligned}$ |  | 1.8 | - | $\pm 10.0$ | $\mu \mathrm{A}$ |
| Quiescent supply current | Icc | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\text {CC }}$ or GND |  | 1.8 | - | 20.0 | $\mu \mathrm{A}$ |

Note 1: An external driver must source at least the specified current to switch from LOW-to-HIGH.
Note 2: An external driver must sink at least the specified current to switch from HIGH-to-LOW.

AC Characteristics ( $\mathbf{T a}=-40$ to $85^{\circ} \mathrm{C}$, input: $\mathrm{t}_{\mathrm{r}}=\mathrm{t}_{\mathrm{f}}=\mathbf{2 . 0} \mathrm{ns}, \mathrm{C}_{\mathrm{L}}=\mathbf{3 0} \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=500 \Omega$ ) (Note 1)

| Characteristics | Symbol | Test Condition |  | Min | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\mathrm{V}_{\mathrm{CC}}(\mathrm{V})$ |  |  |  |
| Maximum clock frequency | $f_{\text {max }}$ | Figure 1, Figure 3 | 1.8 | 100 | - | MHz |
|  |  |  | $2.5 \pm 0.2$ | 200 | - |  |
|  |  |  | $3.3 \pm 0.3$ | 250 | - |  |
| Propagation delay time(An, Bn-Bn, An) | $\begin{aligned} & \mathrm{t}_{\mathrm{pLH}} \\ & \mathrm{t}_{\mathrm{pHL}} \end{aligned}$ | Figure 1, Figure 2 | 1.8 | 1.5 | 7.0 | ns |
|  |  |  | $2.5 \pm 0.2$ | 0.8 | 3.5 |  |
|  |  |  | $3.3 \pm 0.3$ | 0.6 | 2.9 |  |
| Propagation delay time <br> (CAB, CBA-Bn, An) | $\begin{aligned} & \mathrm{t}_{\mathrm{pLH}} \\ & \mathrm{t}_{\mathrm{pHL}} \end{aligned}$ | Figure 1, Figure 3 | 1.8 | 1.5 | 8.8 | ns |
|  |  |  | $2.5 \pm 0.2$ | 0.8 | 4.4 |  |
|  |  |  | $3.3 \pm 0.3$ | 0.6 | 3.2 |  |
| Propagation delay time <br> (SAB, SBA-Bn, An) | $\begin{aligned} & \mathrm{t}_{\mathrm{pLH}} \\ & \mathrm{t}_{\mathrm{pHL}} \end{aligned}$ | Figure 1, Figure 2 | 1.8 | 1.5 | 8.8 | ns |
|  |  |  | $2.5 \pm 0.2$ | 0.8 | 4.4 |  |
|  |  |  | $3.3 \pm 0.3$ | 0.6 | 3.5 |  |
| Output enable time$(\overline{\mathrm{OE}}, \mathrm{DIR}-\mathrm{An}, \mathrm{Bn})$ | $\begin{aligned} & \mathrm{t}_{\mathrm{pzL}} \\ & \mathrm{t}_{\mathrm{pzH}} \end{aligned}$ | Figure 1, Figure 4, Figure 5 | 1.8 | 1.5 | 9.8 | ns |
|  |  |  | $2.5 \pm 0.2$ | 0.8 | 4.9 |  |
|  |  |  | $3.3 \pm 0.3$ | 0.6 | 3.8 |  |
| Output disable time$(\overline{\mathrm{OE}}, \mathrm{DIR}-\mathrm{An}, \mathrm{Bn})$ | $\begin{aligned} & \mathrm{t}_{\mathrm{pLLZ}} \\ & \mathrm{t}_{\mathrm{pHZ}} \end{aligned}$ | Figure 1, Figure 4, Figure 5 | 1.8 | 1.5 | 7.6 | ns |
|  |  |  | $2.5 \pm 0.2$ | 0.8 | 4.2 |  |
|  |  |  | $3.3 \pm 0.3$ | 0.6 | 3.7 |  |
| Minimum pulse width | $\begin{aligned} & \mathrm{t}_{\mathrm{w}}(\mathrm{H}) \\ & \mathrm{t}_{\mathrm{w}(\mathrm{~L})} \end{aligned}$ | Figure 1, Figure 3 | 1.8 | 4.0 | - | ns |
|  |  |  | $2.5 \pm 0.2$ | 1.5 | - |  |
|  |  |  | $3.3 \pm 0.3$ | 1.5 | - |  |
| Minimum setup time | $\mathrm{t}_{\text {s }}$ | Figure 1, Figure 3 | 1.8 | 2.5 | - | ns |
|  |  |  | $2.5 \pm 0.2$ | 1.5 | - |  |
|  |  |  | $3.3 \pm 0.3$ | 1.5 | - |  |
| Minimum hold time | $t_{n}$ | Figure 1, Figure 3 | 1.8 | 1.0 | - | ns |
|  |  |  | $2.5 \pm 0.2$ | 1.0 | - |  |
|  |  |  | $3.3 \pm 0.3$ | 1.0 | - |  |
| Output to output skew | $\mathrm{t}_{\mathrm{os} \text { LH }}$ <br> $\mathrm{t}_{\mathrm{osHL}}$ |  | 1.8 | - | 0.5 | ns |
|  |  |  | $2.5 \pm 0.2$ | - | 0.5 |  |
|  |  |  | $3.3 \pm 0.3$ | - | 0.5 |  |

Note 1: For $C_{L}=50 \mathrm{pF}$, add approximately 300 ps to the AC maximum specification.
Note 2: Parameter guaranteed by design.
( $\left.\mathrm{t}_{\mathrm{osLH}}=\left|\mathrm{t}_{\mathrm{pLHm}}-\mathrm{t}_{\mathrm{pLHn}}\right|, \mathrm{t}_{\mathrm{os} H L}=\left|\mathrm{t}_{\mathrm{pHLm}}-\mathrm{t}_{\mathrm{pHLn}}\right|\right)$

## Dynamic Switching Characteristics

( $\mathrm{Ta}=\mathbf{2 5}{ }^{\circ} \mathrm{C}$, input: $\mathrm{t}_{\mathrm{r}}=\mathrm{t}_{\mathrm{f}}=\mathbf{2 . 0} \mathrm{ns}, \mathrm{C}_{\mathrm{L}}=\mathbf{3 0} \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=500 \Omega$ )

| Characteristics | Symbol | Test Condition |  |  | Typ. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\mathrm{V}_{\mathrm{Cc}}(\mathrm{V})$ |  |  |
| Quiet output maximum dynamic $\mathrm{V}_{\mathrm{OL}}$ | V OLP | $\mathrm{V}_{\mathrm{IH}}=1.8 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | (Note) | 1.8 | 0.25 | V |
|  |  | $\mathrm{V}_{\mathrm{IH}}=2.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | (Note) | 2.5 | 0.6 |  |
|  |  | $\mathrm{V}_{\mathrm{IH}}=3.3 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | (Note) | 3.3 | 0.8 |  |
| Quiet output minimum dynamic $\mathrm{V}_{\mathrm{OL}}$ | Volv | $\mathrm{V}_{\mathrm{IH}}=1.8 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | (Note) | 1.8 | -0.25 | V |
|  |  | $\mathrm{V}_{\mathrm{IH}}=2.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | (Note) | 2.5 | -0.6 |  |
|  |  | $\mathrm{V}_{\mathrm{IH}}=3.3 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | (Note) | 3.3 | -0.8 |  |
| Quiet output minimum dynamic $\mathrm{V}_{\mathrm{OH}}$ | V ${ }_{\text {OHV }}$ | $\mathrm{V}_{\mathrm{IH}}=1.8 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | (Note) | 1.8 | 1.5 | V |
|  |  | $\mathrm{V}_{\mathrm{IH}}=2.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | (Note) | 2.5 | 1.9 |  |
|  |  | $\mathrm{V}_{\mathrm{IH}}=3.3 \mathrm{~V}, \mathrm{~V}_{\mathrm{IL}}=0 \mathrm{~V}$ | (Note) | 3.3 | 2.2 |  |

Note: Parameter guaranteed by design.
Capacitive Characteristics ( $\mathrm{Ta}=\mathbf{2 5}{ }^{\circ} \mathrm{C}$ )

| Characteristics | Symbol | Test Condition |  | $\mathrm{V}_{\mathrm{Cc}}(\mathrm{V})$ | Typ. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input capacitance | $\mathrm{C}_{\text {IN }}$ |  |  | 1.8, 2.5, 3.3 | 6 | pF |
| Bus I/O capacitance | $\mathrm{Cl}_{1 / \mathrm{O}}$ | - - |  | 1.8, 2.5, 3.3 | 7 | pF |
| Power dissipation capacitance | CPD | $\mathrm{f} / \mathrm{N}=10 \mathrm{MHz}$ | (Note) | 1.8, 2.5, 3.3 | 20 | pF |

Note: CPD is defined as the value of the internal equivalent capacitance which is calculated from the operating current consumption without load.
Average operating current can be obtained by the equation:

$$
\mathrm{I}_{\mathrm{CC}}(\mathrm{opr})=\mathrm{CPD} \cdot \mathrm{~V}_{\mathrm{CC}} \cdot \mathrm{fI}_{\mathrm{I}}+\mathrm{I}_{\mathrm{CC}} / 16 \text { (per bit) }
$$

AC Test Circuit


| Parameter | Switch |  |
| :---: | :---: | :---: |
| $\mathrm{tpLH}, \mathrm{t}_{\mathrm{pHL}}$ | Open |  |
| $\mathrm{t}_{\mathrm{pLZ}}$, tpZL | $\begin{aligned} & 6.0 \mathrm{~V} \\ & \mathrm{~V}_{\mathrm{CC}} \times 2 \end{aligned}$ | $@ \mathrm{~V}$ cc $=3.3 \pm 0.3 \mathrm{~V}$ <br> $@ V_{c c}=2.5 \pm 0.2 \mathrm{~V}$ <br> $@ V_{C C}=1.8 \mathrm{~V}$ |
| $\mathrm{t}_{\mathrm{pHz}}, \mathrm{t}_{\mathrm{p} Z \mathrm{H}}$ |  | GND |

Figure 1

## AC Waveform

Input
(An, Bn, SAB, SBA)

Output (Bn, An)


Figure $2 \mathbf{t}_{\mathrm{pLH}}, \mathrm{t}_{\mathrm{pHL}}$


Figure $3 \mathbf{t}_{\mathbf{p L H}}, \mathrm{t}_{\mathrm{pHL}}, \mathrm{t}_{\mathbf{w}}, \mathrm{t}_{\mathbf{s}}, \mathrm{t}_{\mathbf{h}}$


Figure $4 \quad t_{p L Z}, t_{p H}, t_{p z}, t_{p z H}$


Figure $5 \quad t_{p L Z}, t_{p H}, t_{p z}, t_{p z H}$

| Symbol | $\mathrm{V}_{\mathrm{CC}}$ |  |  |
| :---: | :---: | :---: | :---: |
|  | $3.3 \pm 0.3 \mathrm{~V}$ | $2.5 \pm 0.2 \mathrm{~V}$ | 1.8 V |
| $\mathrm{~V}_{\mathrm{IH}}$ | 2.7 V | $\mathrm{~V}_{\mathrm{CC}}$ | $\mathrm{V}_{\mathrm{CC}}$ |
| $\mathrm{V}_{\mathrm{M}}$ | 1.5 V | $\mathrm{~V}_{\mathrm{CC}} / 2$ | $\mathrm{~V}_{\mathrm{CC}} / 2$ |
| $\mathrm{~V}_{\mathrm{X}}$ | $\mathrm{V}_{\mathrm{OL}}+0.3 \mathrm{~V}$ | $\mathrm{~V}_{\mathrm{OL}}+0.15 \mathrm{~V}$ | $\mathrm{~V}_{\mathrm{OL}}+0.15 \mathrm{~V}$ |
| $\mathrm{~V}_{\mathrm{Y}}$ | $\mathrm{V}_{\mathrm{OH}}-0.3 \mathrm{~V}$ | $\mathrm{~V}_{\mathrm{OH}}-0.15 \mathrm{~V}$ | $\mathrm{~V}_{\mathrm{OH}}-0.15 \mathrm{~V}$ |

## Package Dimensions



Weight: 0.25 g (typ.)

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