iC149

PROGRAMMABLE ns-PULSE GENERATOR



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FEATURES

Pulse width 1 bis 64 ns in steps of 0.25 ns Fixed frequency of 1 MHz LVDS und TTL outputs Compatible with HG1D, NZN1D, NZP1D **APPLICATIONS**

Pulse generator for fast laser diode drivers

BLOCK DIAGRAM





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DESCRIPTION

Pulse generator iC149 produces pulses with a small duty cycle in the range of ca. 1 ns up to 64 ns max. in steps of 0.25 ns at a pulse frequency of 1 MHz. The pulse width is set by means of two hexadecimal coding switches in coarse and fine steps. The pulses are output both as LVDS and TTL signals.

This module can easily be used with the evaluation boards HG1D, NZN1D ans NZP1D.

ELECTRICAL CHARACTERISTICS

Test Conditions: Vs = ± 15 V, Ta = 25 °C, System Impedace 50 Ω

| Item | Symbol | Parameter | Conditions | | | | Unit |
|--------------|-------------------|-------------------|--|------|----------------|------|----------------|
| No. | | | | Min. | Тур. | Max. | |
| Power Supply | | | | | | | |
| 101 | V5 | Power Supply | | 4.75 | 5 | 5.25 | V |
| 102 | I(V5) | Supply Current | V5 = 5 V, S1 = OFF V5 = 5 V, S1 = ON, TRIGGER open V5 = 5 V, S1 = ON, TRIGGER 50 Ω vs. Ground | | 45 50 75 | | mA mA mA |
| Pulse Width | | | | | | | |
| 201 | Tp _{max} | Maximum Pulsweite | V5 = 5 V, Ta = 27 °C, <i>coarse</i> = "F", <i>fine</i> = "F" | | 63.75 | | ns |
| 202 | Tp _{min} | Minimum Pulsweite | V5 = 5 V, Ta = 27 °C, <i>coarse</i> = "0", <i>fine</i> = "C" | | 1 | | ns |

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SETTING THE PULSE WIDTH

Typical pulse widths as follows (measured values in parentheses):

```
m = 15 | \Delta T = 15 * 4 ns = 60 ns (60.2 ns)
m = 14 | \Delta T = 14 * 4 ns = 56 ns (56.4 ns)
m = 13
           \Delta T = 13 * 4 \text{ ns} = 52 \text{ ns} (52.3 ns)
m = 12 | \Delta T = 12 * 4 ns = 48 ns (48.7 ns)
m = 11
           \Delta T = 11 * 4 \text{ ns} = 44 \text{ ns} (44.7 ns)
m = 10
           \Delta T = 10 * 4 \text{ ns} = 40 \text{ ns} (40.9 ns)
m = 9
           \Delta T = 9 * 4 \text{ ns} = 36 \text{ ns} (36.7 ns)
           \Delta T = 8 * 4 \text{ ns} = 32 \text{ ns} (32.6 ns)
m = 8
m = 7
           \Delta T = 7 * 4 \text{ ns} = 28 \text{ ns} (28.7 ns)
           \Delta T = 6 * 4 \text{ ns} = 24 \text{ ns} (24.7 ns)
m = 6
m = 5
           \Delta T = 5 * 4 \text{ ns} = 20 \text{ ns} (20.2 ns)
           \Delta T = 4 * 4 \text{ ns} = 16 \text{ ns} (15.7 ns)
m = 4
m = 3 | \Delta T = 3 * 4 ns = 12 ns (12.4 ns)
m = 2 | \Delta T = 2 * 4 ns = 8 ns
                                             (7.5 ns)
m = 1 | \Delta T = 1 * 4 ns = 4 ns
                                             (3.0 ns)
```

Table 2: m = 1...15 (*coarse*), n = 0 (*fine*)

```
n = 15 | \Delta T = 4 ns + 15 * 0.25 ns = 7.75 ns (7.2 ns)
n = 14
           \Delta T = 4 \text{ ns} + 14 \text{ * } 0.25 \text{ ns} = 7.50 \text{ ns} (6.8 ns)
n = 13 | \Delta T = 4 ns + 13 * 0.25 ns = 7.25 ns (6.5 ns)
n = 12
           \Delta T = 4 \text{ ns} + 12 * 0.25 \text{ ns} = 7.00 \text{ ns} (6.2 ns)
n = 11
           \Delta T = 4 \text{ ns} + 11 * 0.25 \text{ ns} = 6.75 \text{ ns} (6.0 ns)
           \Delta T = 4 \text{ ns} + 10 * 0.25 \text{ ns} = 6.50 \text{ ns} (5.8 ns)
n = 10
n = 9
           \Delta T = 4 \text{ ns} + 9 * 0.25 \text{ ns} = 6.25 \text{ ns} (5.5 ns)
n = 8
           \Delta T = 4 \text{ ns} + 8 * 0.25 \text{ ns} = 6.00 \text{ ns} (4.9 ns)
n = 7
           \Delta T = 4 \text{ ns} + 7 * 0.25 \text{ ns} = 5.75 \text{ ns} (4.5 ns)
n = 6
           \Delta T = 4 \text{ ns} + 6 * 0.25 \text{ ns} = 5.50 \text{ ns} (4.4 ns)
n = 5
           \Delta T = 4 \text{ ns} + 5 * 0.25 \text{ ns} = 5.25 \text{ ns} (4.3 ns)
           \Delta T = 4 \text{ ns} + 4 * 0.25 \text{ ns} = 5.00 \text{ ns} (4.1 ns)
n = 4
n = 3
           \Delta T = 4 \text{ ns} + 3 * 0.25 \text{ ns} = 4.75 \text{ ns} (3.9 ns)
n = 2 | \Delta T = 4 ns + 2 * 0.25 ns = 4.50 ns (3.5 ns)
           \Delta T = 4 \text{ ns} + 1 * 0.25 \text{ ns} = 4.25 \text{ ns} (3.2 ns)
n = 1
n = 0 | \Delta T = 4 ns + 0 * 0.25 ns = 4.00 ns (3.0 ns)
```

Table 3: m = 1 (*coarse*), n = 1...15 (*fine*)

 $\begin{array}{ll} n = 15 & \Delta T = 2.8 \, \text{ns} \pm 0.4 \text{ns} & (2.8 \, \text{ns}) \\ n = 14 & \Delta T = 2.5 \, \text{ns} \pm 0.4 \text{ns} & (2.6 \, \text{ns}) \\ n = 13 & \Delta T = 2.2 \, \text{ns} \pm 0.4 \text{ns} & (2.1 \, \text{ns}) \\ n = 12 & \Delta T = 1.0 \, \text{ns} \pm 0.4 \text{ns} & (1.1 \, \text{ns}) \\ n < 12 & \Delta T = 0.0 \, \text{ns} \\ \end{array}$

Table 4: m = 0 (*coarse*) und $n \ge 12$ (*fine*)

Formula to calculate the pulse width:

 $\Delta T = (m * 4 ns + n * 0.25 ns) \pm 2 ns$

 $\begin{array}{l} 1 \leq m \; (coarse) \leq 15, \\ 0 \leq n \; (fine)) \leq 15, \\ m = 0 \; s. \; Tab. \; 4 \end{array}$

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PIN CONFIGURATION



Figure 1: The populated PCB



Figure 2: Pin configuration J1

- J1 16 pole pin header for power supply and signal outputs
- J2 RJ45 connector for output signals with LVDS or TTL/CMOS levels
- J3 TRIGGER: SMA connector for trigger output, Rout = 50Ω
- JP1 Jumper at position 1-2 selects TTL/CMOS signals for J2
- S1 Oscillator ON/OFF
- S2 Selector switch: programmable pulse or symmetrical 1 MHz signal
- S3 Coding switch *fine*
- S4 Coding switch *coarse*
- TP1 LVDS signal at J1 (must be terminated with 100Ω for measurement purpose)
- TP2 LVDS signal at J1
- TP3 TTL/CMOS signal at J1
- TP4 LVDS signal at J2
- GND GND
- V5 V5
- 3V3 3.3V

Table 5: Connectors on the PCB

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SAMPLE PULSES



Figure 3: Maximum pulse width



Figure 4: Minimum pulse width



Figure 5: Trigger and LVDS pulse



Figure 6: Trigger and 1 MHz LVDS signal

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BLOCK DIAGRAM



Figure 7: Block diagram of the iC149

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