# **TOSHIBA**



TLCS-870 Series

TMP87P809NG TMP87P809MG

## **TOSHIBA CORPORATION**

Semiconductor Company

## **Important Notices**

Thank you for your continued patronage of Toshiba microcontrollers.

This page gives you important information on using Toshiba microcontrollers. Please be sure to check each item for proper use of our products.



TOSHIBA Microcontrollers 870 Family

(TMP87C409BN) (TMP87C409BM) (TMP87C809BN) (TMP87C809BM) (TMP87P809)

## Datasheet Modifications: I<sup>2</sup>C Bus Mode Control

The following problem is included in the explanation of the I<sup>2</sup>C bus function of this data sheet. It will guide the correction as follows. Please read it for the explanation of this data sheet as follows.

## Section: "I2C Bus Mode Control"

- In the explanation of the Serial Bus Interface Control Register 1
  - 1. Delete the setting examples where the serial clock frequency exceeds 100 kHz.
  - 2. Add the following note.

SCK	Serial clock selection	( nin)	rite- only
-----	------------------------	--------	---------------

Note: This I<sup>2</sup>C bus circuit does not support the Fast mode. It supports the Standard mode only. Although the I<sup>2</sup>C bus circuit itself allows the setting of a baud rate over 100 kbps, the compliance with the I<sup>2</sup>C specification is not guaranteed in that case.

- In "(3) Serial clock"
  - 1. Add the following sentence about the communication baud rate.
    - a. Clock source

The SCK (bits 2 to 0 in the SBICR1) is used to select a maximum transfer frequency outputed on the SCL pin in the master mode. Set a communication baud rate that meets the I<sup>2</sup>C bus specification, such as the shortest pulse width of t<sub>Low</sub>, based on the equations shown below.

In both master mode and slave mode, a pulse width of at least 4 machine cycles is require for both "H" and "L" levels.

$$t_{LOW} = 2^{n}/f_{C}$$
  

$$t_{HIGH} = 2^{n}/f_{C} + 8/f_{C}$$
  

$$fscl = 1/(t_{LOW} + t_{HIGH})$$

# **Document Change Notification**

The purpose of this notification is to inform customers about the launch of the Pb free version of the device. The introduction of a Pb-free replacement affects the datasheet. Please understand that this notification is intended as a temporary substitute for a revision of the datasheet.

Changes to the datasheet may include the following, though not all of them may apply to this particular device.

1. Part number

Example: TMPxxxxxxFG TMPxxxxxxFG

All references to the previous part number were left unchanged in body text. The new part number is indicated on the prelims pages (cover page and this notification).

2. Package code and package dimensions

Example: LQFP100-P-1414-0.50C

LQFP100-P-1414-0.50F

All references to the previous package code and package dimensions were left unchanged in body text. The new ones are indicated on the prelims pages.

3. Addition of notes on lead solderability

Now that the device is Pb free, notes on lead solderability have been added.

Ι

4. RESTRICTIONS ON PRODUCT USE

The previous (obsolete) provision might be left unchanged on page 1 of body text. A new replacement is included on the next page.

5. Publication date of the datasheet

The publication date at the lower right corner of the prelims pages applies to the new device.

#### 1. Part number

## Package code and dimensions

Previous Part Number (in Body Text)	Previous Package Code (in Body Text)	New Part Number	New Package Code	ОТР
TMP87P809N	P-SDIP28-400-1.78	TMP87P809NG	SDIP28-P-400-1.78	_
TMP87P809M	P-SOP28-450-1.27	TMP87P809MG	SOP28-P-450-1.27B)	_

<sup>\*:</sup> For the dimensions of the new package, see the attached Package Dimensions diagram.

## 3. Addition of notes on lead solderability

The following solderability test is conducted on the new device.

Lead solderability of Pb-free devices (with the G suffix)

Test	Test Conditions	Remark
Solderability	(1) Use of Lead (Pb) -solder bath temperature = 230°C -dipping time = 5 seconds -the number of times = once -use of R-type flux (2) Use of Lead (Pb)-Free -solder bath temperature = 245°C -dipping time = 5 seconds -the number of times = once -use of R-type flux	Leads with over 95% solder coverage till lead forming are acceptable.

## 4. RESTRICTIONS ON PRODUCT USE

The following replaces the "RESTRICTIONS ON PRODUCT USE" on page 1 of body text.

#### RESTRICTIONS ON PRODUCT USE

20070701-EN

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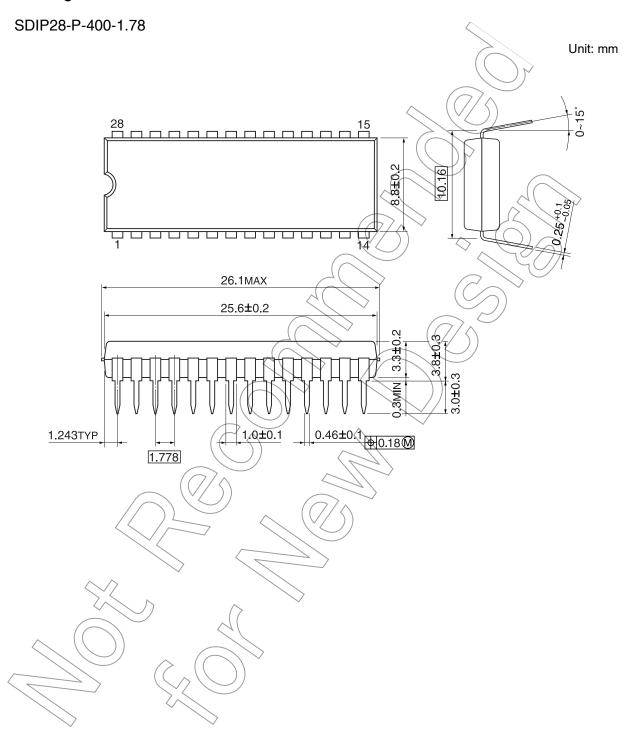
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  as a result of noncompliance with applicable laws and regulations.
- For a discussion of how the reliability of microcontrollers can be predicted, please refer to Section 1.3 of the chapter entitled Quality and Reliability Assurance/Handling Precautions.

#### Publication date of the datasheet

The publication date of this datasheet is printed at the lower right corner of this notification.

(Annex)

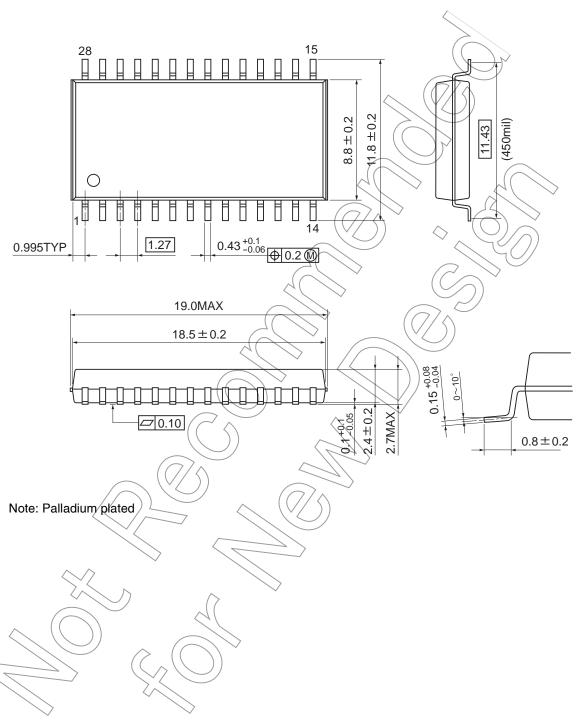
# Package Dimensions



III 2008-03-06

## SOP28-P-450-1.27B

Unit: mm



IV 2008-03-06

#### CMOS 8-bit Microcontroller

## TMP87P809N/M

The TMP87P809 is a high-speed, high-performance 8-bit single chip microcomputer, which has 64-Kbits One-Time PROM. The TMP87P809 is pin compatible with the TMP87C409B/809B. The operations possible with the TMP87C409B/809B can be performed by writing programs to PROM. The TMP87P809 can write and verify in the same way as the TC57256AD using an adapter socket and a general purpose PROM programmer.

	Poduct No.	ROM	RAM	Package Adapter soc	ket
	TMP87P809N			P-SDIP28-400-1.78 BM11122	2
	TMP87P809M	8 Kbytes	256 bytes	P-SOP28-450-1.27 BM11116	5
		•		7()	
Pin Assignr	<b>nents</b> (Top Vie	ew)		25D1D20 400 4 70	
				P-SDIP28-400-1.78	
SOP28 / SDIP28	3				
			<b>_</b>		402
	DIDS/XOUT <del>≪</del> —□		28 □← VDD (VAR	REF) (VCC	
•	CLOCK/XIN <del>→</del> □		27 □← RESET		
	VPP/TEST─➤□		26		1,1,1,0
OE/	(AIN0) P60 <del>&lt;&gt;</del> □	4 2	25 🗆 😽 P16/A14/A	·	T. 450-750-001
CE/	(AIN1) P61 <del>≪&gt;</del> □	5 2	24 P15/A13/A	A5/D5 (\// ))	TMP87P809N
D0/A0/A8/	(AIN2) P62 <del>≪&gt;</del> □	6 2	23 🗆 🖚 P14/A12/A	A4/D4 P-SOP28-450-1.27	
D1/A1/A9/	(AIN3) P63 <del>≪&gt;</del> □	7 2	22 🔾 🔫 🗢 P13 (DVO)	)/A1/1/A3/D3	
	(AIN4) P64 <del>←→</del> □	8	21 (TC1).	/A10/A2/D2	
	(AIN5) P65 <del>&lt;&gt;&gt;</del> □	9 ((2	20 🖹 🔷 > P11 (INT1)	)	
	(AIN6) P66 <del>&lt;&gt;&gt;</del> □	10	9		THE PARTY OF THE P
(AIN7/\	VAREF) P67 <del>&lt;&gt;</del> □	11 ( \( \lambda \)	8 □ <del>&lt;&gt;</del> P43 (STOP	P/INT5)	All line
(TC3/INT3	3/CLZ0) P50 <del>&lt;&gt;&gt;</del> □	12	7 🗆 🛶 P42 (SDA7	(SO)	
(TC4/PWM/PDO	√CLZ1) P51 <del>&lt;&gt;&gt;</del> □	13	6 □ ←→ P41 (SCL/S	50	T1 4 D0 T D0 0 0 1 4
GND/	(VASS) VSS→□	14( // \) 1	5 □ <del>&lt; &gt; </del> P40 (SCK)	2	TMP87P809M
		$\rightarrow$			

For a discussion of how the reliability of microcontrollers can be predicted, please refer to Section 1.3 of the chapter entitled Quality and Reliability Assurance / Handling Precautions.

Quality and Reliability Assurance / Handling Precautions.

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2008-02-08 3-09-89

## **Pin Function**

The TMP87P809 has two modes: MCU and PROM.

(1) MCU mode

In this mode, the TMP87P809 is pin compatible with the TMP87C409B/809B (fix the TEST pin at "L" level).

(2) PROM mode

Pin Name (PROM mode)	Input / Output	Functions	Pin name (MCU mode)
A14 to A8	la annua		P17 to P12, P63, P62
A7 to A0	Input	Program memory address input	P17 to P12, P63, P62
D7 to D0	I/O	Program memory data imput/output	P17 to P12, P63, P62
CE		Chip enable signal input	P61
ŌĒ	Input	Output enable signal input	P60
VPP		+ 12.5 V / 5 V (Program supply voltage)	TEST
vcc	Power supply	+5V	VDD
GND		ov (	vss
P11 to P10			
P43 to P40	110		
P51 to P50	1/0	RROM mode setting pins. Be fixed at "L" level.	
P67 to P64			
RESET	Input		
XIN	Input	Inputs a clock externally. (CLOCK)	XIN
хоит	Input	PROM mode control signal (DIDS) input	хоит

#### **Operational Description**

The configuration and function of the TMP87P809 are the same as those of the TMP87C409B/809B, except in that a one-time PROM is used instead of an on-chip mask ROM.

## 1. Operating Mode

The TMP87P809 has two modes: MCU and PROM.

#### 1.1 MCU Mode

The MCU mode is activated by fixing the TEST/VPP pin at "L" level.

In the MCU mode, operation is the same as with the TMP87C409B/809B (TEST/VPP pin cannot be used open because it has no built in pull-down resistance.)

#### 1.1.1 Program memory

The TMP87P809 has a 8 Kbyte (addresses E000 to FFFF<sub>H</sub> in the MCU mode, addresses 6000 to 7FFF<sub>H</sub> in the PROM mode) one-time PROM.

To use the TMP87P809 as the system evaluation for the TMP87C409B/809B, the program should be written to the program memory area as shown in Figure 1-1.

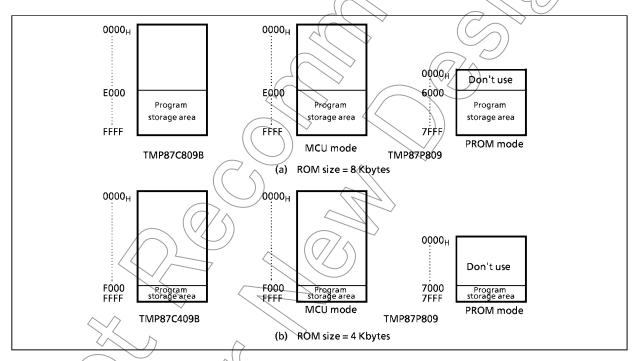


Figure 1-1. Program memory area

Note: Either write the data FFH to the unused area or set the general-purpose PROM programmer to access only the program storage area

#### 1.1.2 Data memory

The TMP87P809 has an 256 bytes data memory (static RAM).

## 1.1.3 Input / Output circuits

## (1) Control pins

The control pins of the TMP87P809 are the same as those of the TMP87C409B/809B except that the TEST pin has no built-in pull-down resistance.

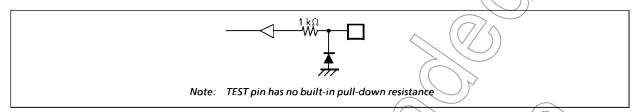


Figure 1-2. TEST Pin

#### (2) I/O port

The I/O circuits of TMP87P809 ports are the same as the TMP87C409B/809B.

#### 1.2 PROM Mode

The PROM mode is used to write and verify programs with a general-purpose PROM programmer.

Note: Please set the high-speed programming mode according to each manual of PROM programmer.

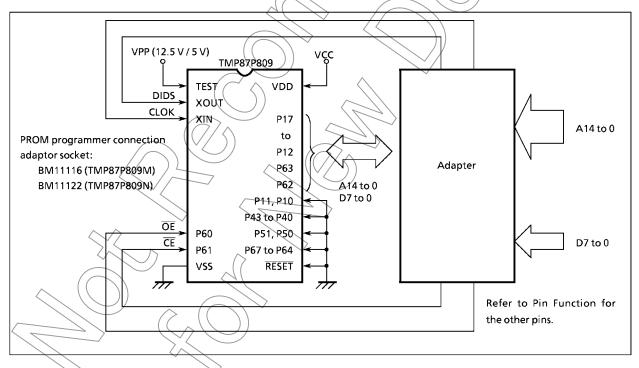


Figure 1-3. Setting for PROM mode

## 1.2.1 Programming flowchart (High-speed Programming Mode-I)

The high-speed programming mode is achieved by applying the program voltage (  $\pm$  12.5 V) to the Vpp pin when Vcc = 6 V. After the address and input data are stable, the data is programmed by applying a single 1ms program pulse to the  $\overline{\text{CE}}$  input. The programmed data is verified. If incorrect, another 1ms program pulse is applied and then the programmed data is verified. This process should be repeated (up to 25 times) until the program operates correctly. Programming for one address is ended by applying additional program pulse with width 3 times that needed for initial programming (number of programmed times  $\times$  1 ms). After that, change the address and input data, and program as before. When programming has been completed, the data in all addresses should be verified with Vcc = Vpp = 5 V.

Start  $V_{CC} = 6 V$  $V_{PP} = 12.5 \text{ V}$ Start address set Data = FF? √V)ò N = 0Single 1 ms program pulse N = N + 1Y es N = 253ИÒ Error Verify òκ Overwriting 1 ms pulse 3N times of 3Nms pulse 1 time Error Verify Address = Next Address OK. Nο Last Address? Yes  $V_{CC} = 5 V$  $V_{PP} = 5 V$ Error Read all NG address OK Pass

Figure 1-4. Flowchart of high-speed programming mode -  $\,\mathrm{I}$ 

## 1.2.2 Programming flowchart (High-speed Programming Mode-II)

The high-speed programming mode is achieved by applying the program voltage (  $\pm$  12.75 V) to the Vpp pin when Vcc = 6.25 V. After the address and input data are stable, the data is programmed by applying a single 0.1ms program pulse to the  $\overline{\text{CE}}$  input. The programmed data is verified. If incorrect, another 0.1ms program pulse is applied and then the programmed data is verified. This process should be repeated (up to 25 times) until the program operates correctly. After that, change the address and input data, and program as before. When programming has been completed, the data in all addresses should be verified with Vcc = Vpp = 5 V.

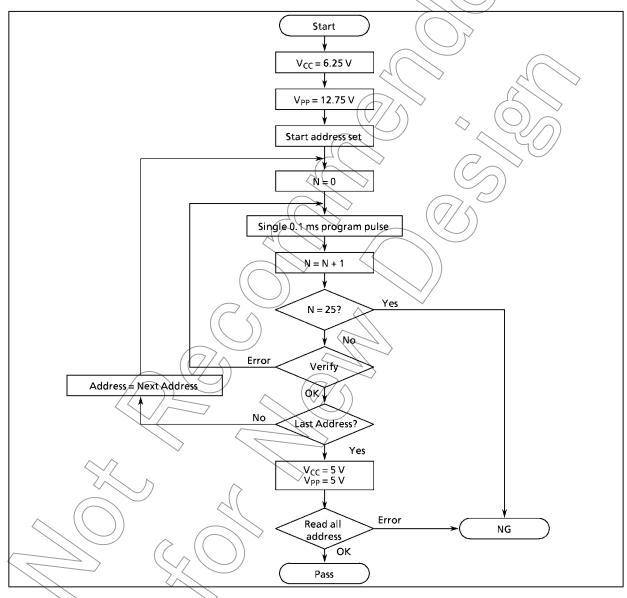


Figure 1-5. Flowchart of high-speed programming mode - II

## 1.2.3 Writing method for general-purpose PROM program

(1) Adapters

BM11116: TMP87P809M BM11122: TMP87P809N

(2) Adapter setting Switch (SW1) is set to side N.

(3) PROM programmer specifying

i) PROM type is specified to TC57256AD.

Writing voltage: 12.5 V (high-speed program | mode)

12.75 V (high-speed program II/mode)

ii) Data transfer (copy) (note 1)

In TMP87P809, EPROM is within the addresses 6000 to 7FFF<sub>H</sub>. Data is required to be transferred (copied) to the addresses where it is possible to write. The program area in MCU mode and PROM mode is referred to "Program memory area" in Figure 1-1.

Ex. In the block transfer (copy) mode, executed as below.

ROM capacity of 4KB: transferred addresses F000 to FFFF<sub>H</sub> to addresses 7000 to 7FFF<sub>H</sub> ROM capacity of 8KB: transferred addresses E000 to FFFF<sub>H</sub> to addresses 6000 to 7FFF<sub>H</sub>

iii) Writing address is specified. (note 1)

Start address: 7000H (ROM 8 KB: 6000H)

End address: 7FFF<sub>H</sub>

(4) Writing

Writing/Verifying is required to be executed in accordance with PROM programmer operating procedure.

- Note 1: The specifying method is referred to the PROM programmer description. The data in addresses 0000 to 5FFF<sub>H</sub> must be specified to FF<sub>H</sub>.
- Note 2: When MCU is set to an adapter or the adapter is set to PROM programmer, a position of pin 1 must be adjusted. If the setting is reversed, MCU, the adapter and PROM program is damaged.
- Note 3: TMP87P809 does not support the electric signature mode (hereinafter referred to as "signature"). If the signature is used in PROM program, a device is damaged due to applying  $12 \text{ V} \pm 0.5 \text{ V}$  to the address pin 9 (A9). The signature must not be used.

### **Electrical Characteristics**

**Absolute Maximum Ratings** 

 $(V_{SS} = 0 V)$ 

Param	eter	Symbol	Condition	Ratings	Unit
Supply Voltage		$V_{DD}$		-0.3 to 6.5	V
Program Voltage		V <sub>PP</sub>	TEST/V <sub>PP</sub> pin	0.3 to 13.0	V
Input Voltage		V <sub>IN</sub>		0.3 to V <sub>DD</sub> + 0.3	٧
Outrout Valtage		V <sub>OUT1</sub>	Ports P1, P5, P6, XOUT	- 0.3 to V <sub>DD</sub> + 0.3	
Output Voltage		V <sub>OUT2</sub>	Port P4	- 0.3 to 5.5	V
Output Current	IOL	l <sub>OUT1</sub>	Ports P1, P6	3.2	
Output Current		I <sub>OUT2</sub>	Ports P4, P5	30	mA
(Per 1 pin)	ЮН	I <sub>OUT3</sub>	Ports P1, P5, P6	-1.8	>
0.15.16	IOL	Σ l <sub>OUT1</sub>	Ports P1, P6	30	
Output Current		Σ I <sub>OUT2</sub>	Ports P4, P5	(80)	mA
(Total)	ЮН	Σ l <sub>OUT3</sub>	Ports P1, P5, P6	30//)	
Danier Dissipation 13	70961	PD	SDIP	300	>4/
Power Dissipation [Topr = 70°C]			SOP	180	mW
Soldering Temperature (time)		Tsld		260 (10 s)	°C
Storage Temperature		Tstg		55 to 125	°C
Operating Tempera	ture	Topr		- 30 to 70	°C

Note: The absolute maximum ratings are rated values which must not be exceeded during operation, even for an instant.

Any one of the ratings must not be exceeded. If any absolute maximum rating is exceeded, a device may break down or its performance may be degraded, causing it to catch fire or explode resulting in injury to the user. Thus, when designing products which include this device, ensure that no absolute maximum rating value will ever be exceeded.

Recommended Operating Conditions

 $(V_{SS} = 0 \text{ V}, \text{ Topr} = -30 \text{ to } 70^{\circ}\text{C})$ 

Parameter	Symbol	Pins	1	Sonditions	Min	Max	Unit		
			fc=8MHz	NORMAL mode	4.5				
Supply Voltage	VpD		fc =	NORMAL mode	2.2	5.5	V		
			4.2 MHz	IDLE mode	2.2				
				STOP mode	2.0				
	V <sub>IH1</sub> Except hysteresis input		V > 4.5.4		ept hysteresis input $V_{DD} \times 0.70$		V <sub>DD</sub> <b>x</b> 0.70		
Input High Voltage	y <sub>IH2</sub>	y <sub>IH2</sub> Hysteresis input		$V_{DD} \ge 4.5 V$		V <sub>DD</sub>	V		
	V <sub>IH3</sub>	4	V <sub>DD</sub> < 4.5 V		V <sub>DD</sub> × 0.90				
	V <sub>IL1</sub>	Except hysteresis input		. > 45.1		V <sub>DD</sub> × 0.30			
Input Low Voltage	V <sub>L2</sub>	Hysteresis input	$V_{DD} \ge 4.5 \text{ V}$ $V_{DD} < 4.5 \text{ V}$		0	$V_{DD} \times 0.25$	V		
	V <sub>IL3</sub>					V <sub>DD</sub> × 0.10			
		VIII VOLIT	VDD	0 = 4.5 to 5.5 V	1.0	8.0			
Clock Frequency	fc	XIN, XOUT	V <sub>DD</sub> :	V <sub>DD</sub> = 2.2 V to 5.5 V		4.2	MHz		

Note1: The recommended operating conditions for a device are operating conditions under which it can be guaranteed that the device will operate as specified. If the device is used under operating conditions other than the recommended operating conditions (supply voltage, operating temperature range, specified AC/DC values etc.), malfunction may occur. Thus, when designing products which include this device, ensure that the recommended operating conditions for the device are always adhered to.

Note2: Clock frequency fc: Supply voltage range is specified in NORMAL mode and IDLE mode.

#### DC Characteristics

 $(V_{SS} = 0 \text{ V}, \text{ Topr} = -30 \text{ to } 70^{\circ}\text{C})$ 

Parameter	Symbol	Pins	Conditions	Min	Тур.	Max	Unit
Hysteresis Voltage	$V_{HS}$	Hysteresis input		(-	0,9	-	٧
	I <sub>IN1</sub>	TEST	V <sub>DD</sub> = 5.5 V		/)~		
Input Current	I <sub>IN2</sub>	Tri-state ports	$V_{\rm IN} = 5.5  \text{V/OV}$	> <del>-</del>	_	± 2	μA
	I <sub>IN3</sub>	RESET, STOP					
Input Resistance	R <sub>IN2</sub>	RESET	7/6	100	220	450	kΩ
Output Leakage		Tri-state ports	$V_{DD} = 5.5 \text{ V}, V_{OUT} = 5.5 \text{ V} \times 0 \text{ V}$	- 2		2	
Current	ILO			- 2	1	2	μΑ
Output High Voltage	V <sub>OH2</sub>	Tri-state ports	$V_{DD} = 4.5 \text{ V}, I_{OH} = -0.7 \text{ mA}$	4.1		1	v
Output Low Voltage	V <sub>OL1</sub>	Except XOUT, P4 and P5	$V_{DD} = 4.5 \text{ V}, V_{QL} = 1.6 \text{ mA}$	ı	7	<del>(</del>	V
Output Low current	I <sub>OL3</sub>	P4, P5	$V_{DD} = 4.5 \text{ V}, V_{OL} = 1.0 \text{ V}$	-	20	\ 	mA
Supply Current in			V <sub>DD</sub> = 5.5 V		8	14	
NORMAL modes			fc = 8\MHz )		) <b>)</b>	14	mA
Supply Current in			V <sub>JN</sub> =5.3 V / 0.2 V			6	mA
IDLE modes			4( \>		)	0	
Supply Current in	1 .	$\langle \langle \langle \rangle \rangle \rangle$	$V_{DQ} = 3.0 \text{ V}$		2.5	3.5	
NORAML mode	DD		fc = 4.2 MHz		2.5	3.5	mA
Supply Current in			V <sub>IN</sub> = 2.8 V / 0.2 V		1.5	2.0	'''A
IDLE mode					1.5	2.0	
Supply Current in			V <sub>DD</sub> = 5.5 V		0.5	10	
STOP mode			V <sub>IN</sub> = 5.3 V / 0.2 V		0.5	10	μΑ

Note 1: Typical values show those at Topr =  $25^{\circ}$ C,  $V_{DD} = 5 V$ .

Note 2: Input Current IIN1, IIN3,: The current through resistor is not included, when the input resistor (pull-up or pull-down) is contained.

## AD Conversion Characteristics

 $(V_{SS} = 0V, V_{DD} = 2.2 \text{ to } 5.5V, Topr = -30 \text{ to } 70^{\circ}\text{C})$ 

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
Analas Reference Valtere	V <sub>AREF</sub>		2.2	_	V <sub>DD</sub>	V
Analog Reference Voltage	V <sub>ASS</sub>		V <sub>S</sub>	s		
Analog Input Voltage range	V <sub>AIN</sub> /	>	$V_{ASS}$	_	V <sub>AREF</sub>	V
Analog Reference Current	I <sub>REE</sub>	$V_{AREF} = 5.5 \text{ V}, V_{ASS} (V_{SS}) = 0.0 \text{ V}$	-	0.5	1.0	mA
Nonlinearity Error		V <sub>DD</sub> = 5.0 V V <sub>AREF</sub> = 5.000 V V <sub>ASS</sub> (V <sub>SS</sub> ) = 0.000 V	ı	_	± 2	
Zero Point Error		V <sub>ASS</sub> (V <sub>SS</sub> ) = 0.000 V or	_	_	± 2	1.65
Full Scale Error		$V_{DD} = 2.2 \text{ V}$	_	_	± 2	LSB
Total Error		V <sub>AREF</sub> = 2.200 V V <sub>ASS</sub> (V <sub>SS</sub> ) = 0.000 V	_	_	± 4	

Note: Quantizing error is not contained in those errors.

**Oscillation Stop Detector Characteristics** 

 $(V_{SS} = 0 \text{ V}, \text{ Topr} = -30 \text{ to } 70^{\circ}\text{C})$ 

Parameter	SYMBOL	Conditions	Min	Тур.	Max	Unit
Detection time	_	VDD = 2.2 V to 5.5V (fc = 2 MHz to 4.2 MHz)	, (	20	400	
Detection time	CLZ	VDD = 4.5 V to 5.5 (fc = 8 MHz)	2	20)	400	μS

AC Characteristics

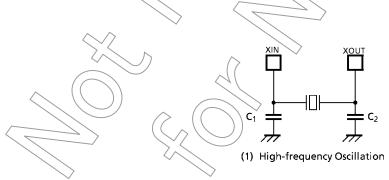
 $(V_{SS} = 0 \text{ V}, V_{DD} = 4.5 \text{ to } 5.5 \text{ V}, \text{ Topr} = -30 \text{ to } 70^{\circ}\text{C})$ 

Parameter	Symbol	Conditions	Min	Typ. Max	Unit
		In NORMAL mode		5	
Machine Cycle Time	tcy	In IDLE mode	0.5	4	μS
High Level Clock Pulse Width	t <sub>WCH</sub>	For external clock operation			
Low Level Clock Pulse Width	t <sub>WCL</sub>	fc = 8 MHz	50		ns

**Recommended Oscillating Conditions** 

 $(V_{SS} = 0 \text{ V}, V_{DD} = 2.2 \text{ to } 5.5 \text{ V}, \text{ Topr} = -30 \text{ to } 70^{\circ}\text{C})$ 

Parameter	Oscillator Oscillation Frequency		Recommended Oscillator	Recommended Constant		
Farameter			Kecomm	ended Oscillator	<b>C</b> <sub>1</sub>	C <sub>2</sub>
		8 MHz	MURATA	CST8.00MTW		_
High-frequency	(7/1)	(4.5 V to 5.5 V)	MURATA	CSA8.00MTZ	30 pF	30 pF
Oscillation	Y/		MURATA	CST4.00MGWU		_
<			MURATA	CSA4.00MGU	30 pF	30 pF



- Note 1: When used in high electric field such as a picture tube, the package is recommended to be electrically shielded to maintain a regular operation.
- Note 2: The product numbers and specifications of the resonators by Murata Manufacturing Co., Ltd. are subject to change. For up-to-date information, please refer to the following

  URL;http://www.murata.com/

## (1) READ OPERATION ( $T_{opr} = 0 \text{ to } 70^{\circ}\text{C}$ )

DC Characteristics, AC Characteristics

 $(V_{SS} = 0 V)$ 

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
Input High Voltage	V <sub>IH4</sub>		V <sub>CC</sub> × 0.67		V <sub>CC</sub>	V
Input Low Voltage	$V_{IL4}$		0 <	((/- {)	$V_{CC} \times 0.3$	V
Supply Voltage	V <sub>CC</sub>		4.75	5.00	5.25	.,
Program Supply Voltage	$V_{PP}$		V <sub>CC</sub> - 0.6	Усс	V <sub>CC+0.6</sub>	\ \
Address Set-up Time	t <sub>ASU</sub>		400	J) -	_	ns
Address Access Time	t <sub>ACC</sub>	$V_{CC} = 5.0 \pm 0.25 \text{ V}$		5tcyc	<u>-</u>	ns
		Note: tcyc = 400 ns				

XOUT
A0 to A14
10 to 17

CE

OE

Tassu

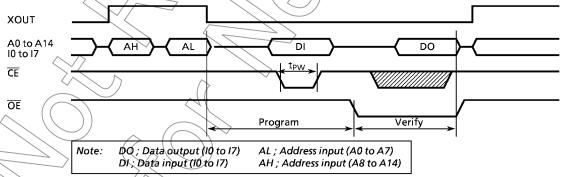
Tassu

Tassu

Tassu

## (2) Program Operation (High speed write mode $\sim I$ ) (Topr = 25 $\pm$ 5°C)

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
Input High Voltage	V <sub>IH</sub> 4		$V_{CC} \times 0.7$	-	V <sub>CC</sub>	٧
Input Low Voltage	VILA		0	-	V <sub>CC</sub> × 0.12	<
Supply Voltage	Vcc		5.75	6.0	6.25	V
Program Supply Voltage	(V <sub>PP</sub> )		12.0	12.5	13.0	٧
Initial Program Pulse Width	t <sub>PW</sub>	$V_{CC} = 6.0 \text{ V} \pm 0.25 \text{ V},$ $V_{PP} = 12.5 \text{ V} \pm 0.25 \text{ V}$	0.95	1.0	1.05	ms



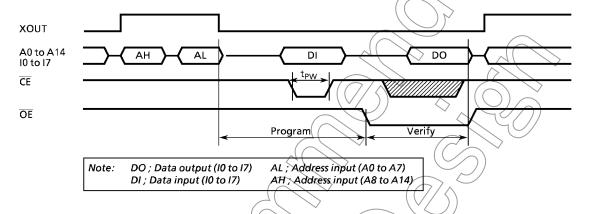
Note1: When  $V_{cc}$  power supply is turned on or after,  $V_{pp}$  must be increased. When  $V_{cc}$  power supply is turned off or before,  $V_{pp}$  must be decreased.

Note2: The device must not be set to the EPROM programmer or picked up from it under applying the program voltage (12.5 V  $\pm$  0.5 V) to the  $V_{pp}$  pin as the device is damaged.

Note3: Be sure to execute the recommended programing mode with the recommended programing adaptor. If a mode or an adaptor except the above, the misoperation sometimes occurs.

#### (3) Program Operation (High speed write mode -II) (Topr = $25 \pm 5^{\circ}$ C)

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
Input High Voltage	V <sub>IH4</sub>		$V_{CC} \times 0.7$	<del>(</del>	Vcc	V
Input Low Voltage	$V_{IL4}$		0	+	V <sub>CC</sub> × 0.12	V
Supply Voltage	V <sub>CC</sub>		6.00	6.25	6.50	٧
Program Supply Voltage	$V_{PP}$		12.50	(1/2/75\	13.0	V
Initial Program Pulse Width	t <sub>PW</sub>	$V_{CC} = 6.25 \text{ V} \pm 0.25 \text{ V},$ $V_{PP} = 12.75 \text{ V} \pm 0.25 \text{ V}$	0.095	0.1	0.105	ms



Note1: When  $V_{cc}$  power supply is turned on or after,  $V_{pp}$  must be increased. When  $V_{cc}$  power supply is turned off or before,  $V_{pp}$  must be decreased.

Note2: The device must not be set to the EPROM programmer or picked up from it under applying the program voltage (12.5  $V \pm 0.5 V$ ) to the  $V_{pp}$  pin as the device is damaged.

Note3: Be sure to execute the recommended programing mode with the recommended programing adaptor. If a mode or an adaptor except the above, the misoperation sometimes occurs.