



Dual Bidirectional Motor Driver

Overview

The LB1650 is a dual bidirectional motor driver that is designed to accept standard TTL input logic levels and drive motors. It provides the functions of bidirectional motor drive, brake that are determined by two inputs and the inhibit function that brings the output to a high impedance state.

Applications

- Multi DC motor driver.
- Bidirectional motor driver.
- Bipolar stepping motor driver.

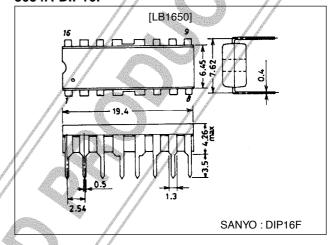
Features

- High output current (1A/ch).
- Wide operating voltage range (4.5 to 36V).
- Inhibit facility.
- Input connectable to TTL, CMOS IC.
- High noise margin.

Package Dimensions

unit:mm

3054A-DIP16F



Specifications

Absolute Maximum Ratings at Ta ≠ 25°C

Parameter	Symbol Conditions	Ratings	Unit
Maximum supply voltage	V _{CC} 1	36	V
Logic supply voltage	Vcc 2	36	V
Input voltage	V _{IN}	7	V
Inhibit voltage	V _{inh}	7	V
Peak output current	I _{OUT} 1ms non-repetitive	2	Α
Allowable power dissipation	Pd max IC only	1.9	W
Operating temperature	Topr	-20 to +80	°C
Storage temperature	Tstg	-40 to +150	°C

Allowable Operating Conditions at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V _{CC} 1		4.5 to 36	V
Logic supply voltage	V _{CC} 2		4.5 to 36	V

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Electrical Characteristics at Ta = 25 $^{\bullet}C,\,V_{CC1}$ =24V, V_{CC2} =5V

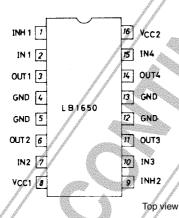
Parameter	Cumbal	Conditions		Ratings		Unit
Parameter	Symbol	Conditions	min	typ	max	Offic
Supply current (per CH)	I _{CC} 1	V _{IN} =L, I _O =0, V _{inh} =H			1.5	mA
		V _{IN} =H, I _O =0, V _{inh} =H	1		6	mA
		V _{inh} =L	1/2	The state of the s	1	mA
Logic supply current	I _{CC} 2	V _{IN} =L, I _O =0, V _{inh} =H	// `	44	60	mA
		V _{IN} =H, I _O =0, V _{inh} =H		2000	22	mA
		V _{inh} =L	1 1		24	mA
Low-level input voltage	V _{IL}		-0.3		1.5	V
High-level input voltage	VIH	V _{CC2} ≤7V	2.3		V _{CC2}	/ V
		V _{CC2} ≤7V	2.3	A	17	V
Low-level input current	I _{IL}	V _{IN} =L			±10	μΑ
High-level input current	lіН	V _{IN} =H-0.3V		30	100	μΑ
Low-levle inhibit voltage	V _{inhL}		-0.3		1.5	V
High-level inhibit voltage	V _{inhH}	V _{CC2} ≤7V	2.3		V _{CC2}	V
		V _{CC2} ≤7V	2.3		7	V
Low-level inhibit current	linhL		-100	/ -30		μΑ
High-level inhibit current	linhH				±10	μΑ
Saturation voltage	V _{CE(sat)} H	I _O =-1A		1.4	1.8	V
	V _{CE(sat)L}	I _O =1A		1.2	1.8	V

Truth Table

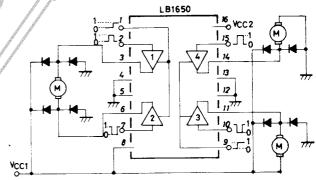
V _{IN} (per CH)	V _{inh}	VO
Н	Н	Н
L	Н	L
Н	L	Open*
L	L	Open*

^{* :} High impedance

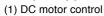
Pin Assignment

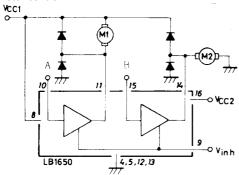


Equivalent Circuit Block Diagram and Peripheral Circuit



Sample Application Circuits

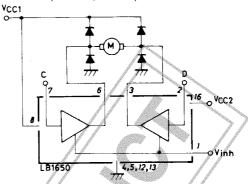




V _{inh}	Α	M1	В	M2	
Н	Н	Brake	Н	Forward	
Н	L	Forward	L	Brake	
L	Х	Open*	Х	Open*	

X : don't care

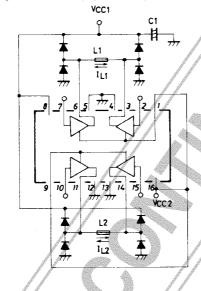
(2) DC motor control (Forward, reverse)

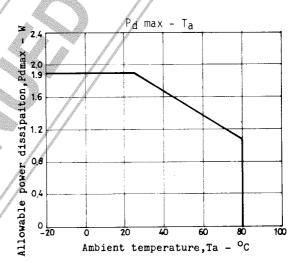


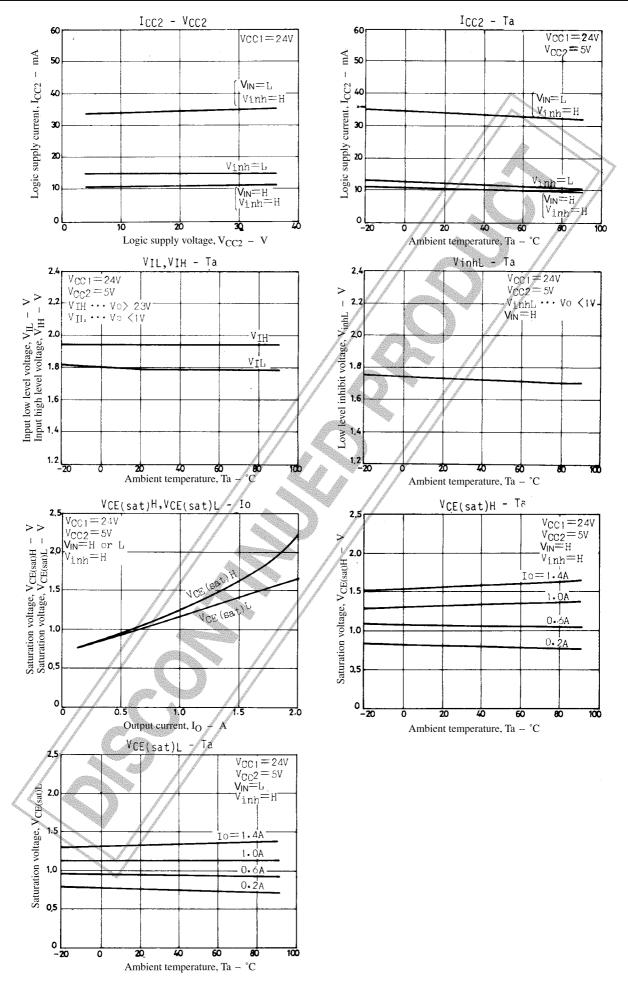
	Input	Function
	C≡H D=L V _{inh} C=L D=H	Forward (right) Reverse (left)
	"""	Brake
200000	V _{inh} =L C=X D≠X	Open*
	2000a. // * ·	High impadance

* : High impedance

(3) Stepping motor control (Bipolar drive)









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