

## Low Noise, High-Speed Dual Operational Amplifier

### ■ GENERAL DESCRIPTION

The NJM2719 is a dual high speed voltage feedback operational amplifier specifically optimized for low voltage noise.

A voltage noise specification of  $2.5\text{nV}/\sqrt{\text{Hz}}$  Typ. (at  $f=100\text{kHz}$ ), a unity gain of  $100\text{MHz}$  combine to make the NJM2719 an ideal choice for I/Q baseband amplifier, RFID reader application and other in wireless communication system designs.

The NJM2719 is available in the 8-pin SO package (DMP8) with standard pinouts. For compact layouts, the dual is also available in a tiny dual fine pitch 8-pin package (SSOP8, TVSP8).

### ■ PACKAGE OUTLINE



NJM2719M  
(DMP8)



NJM2719V  
(SSOP8)



NJM2719RB1  
(TVSP8)

### ■ FEATURES

#### ● Low Noise

$V_{ni} = 2.5\text{nV}/\sqrt{\text{Hz}}$  typ. at  $f=100\text{kHz}$

$V_{ni} = 3\text{nV}/\sqrt{\text{Hz}}$  typ. at  $f=10\text{kHz}$

#### ● Unity Gain Bandwidth

$f_T = 100\text{MHz}$  typ. at  $V^+/V^- = \pm 5\text{V}$

$f_T = 90\text{MHz}$  typ. at  $V^+/V^- = \pm 2.5\text{V}$

#### ● Phase Margin

$\Phi_m = 60\text{deg}$  typ.

#### ● Slew Rate

$60\text{V}/\mu\text{s}$  typ. at  $V^+/V^- = \pm 5\text{V}$

$35\text{V}/\mu\text{s}$  typ. at  $V^+/V^- = \pm 2.5\text{V}$

#### ● Output Rail-to-Rail

$V_{OH} \geq +4.7\text{V}$ ,  $V_{OL} \leq -4.8\text{V}$  at  $V^+/V^- = \pm 5\text{V}$

$V_{OH} \geq +2.4\text{V}$ ,  $V_{OL} \leq -2.4\text{V}$  at  $V^+/V^- = \pm 2.5\text{V}$

$\pm 2.5\text{V} \sim \pm 5\text{V}$

#### ● Operating Voltage

#### ● Bipolar Technology

#### ● Package Outline

DMP8 [NJM2719M]

SSOP8 [NJM2719V]

TVSP8 [NJM2719RB1]

### ■ APPLICATION

#### ● Wireless Communication Equipment

#### ● I/Q Baseband Application

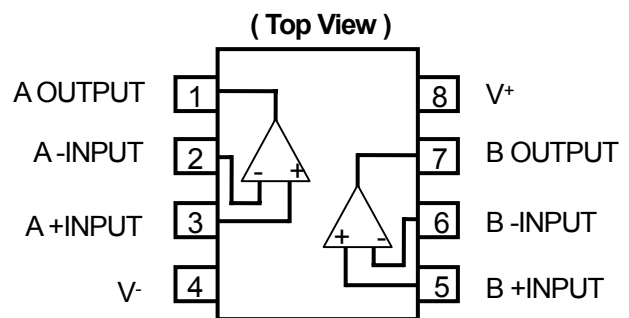
#### ● RFID Reader Application

#### ● Active Filter

#### ● ADC/DAC Buffer

#### ● Ultrasound Amplifier

### ■ PIN CONFIGURATION



DMP8 [NJM2719M]

SSOP8 [NJM2719V]

TVSP8 [NJM2719RB1]

# NJM2719

## ■ ABSOLUTE MAXIMUM RATINGS (Ta=25°C)

PARAMETER	SYMBOL	RATINGS	UNIT
Supply Voltage	V <sup>+</sup>	+5.5	V
Common Mode Input Voltage Range	V <sub>ICM</sub>	±5.5 (Note1)	V
Differential Input Voltage Range	V <sub>ID</sub>	±3	V
Power Dissipation	P <sub>D</sub>	370 [DMP8], 310 [SSOP8], 400 [TVSP8]	mW
		470 [DMP8] (Note2), 410 [SSOP8] (Note2), 510 [TVSP8] (Note2)	mW
Operating Temperature Range	T <sub>opr</sub>	-40 to +85	°C
Storage Temperature Range	T <sub>stg</sub>	-50 to +150	°C

(Note 1) The output voltage of normal operation will be the Output Voltage Swing of electrical characteristics.

(Note 2) On the PCB " EIA/JEDEC (76.2x114.3x1.6mm, two layers, FR-4) "

(Note 3) Do not exceed "Power dissipation: PD" in which power dissipation in IC is shown by the absolute maximum rating.  
Refer to following Figure 1 for a permissible loss when ambient temperature (Ta) is Ta ≥ 25°C.

Figure1A: Power Dissipation – Ambient Temperature

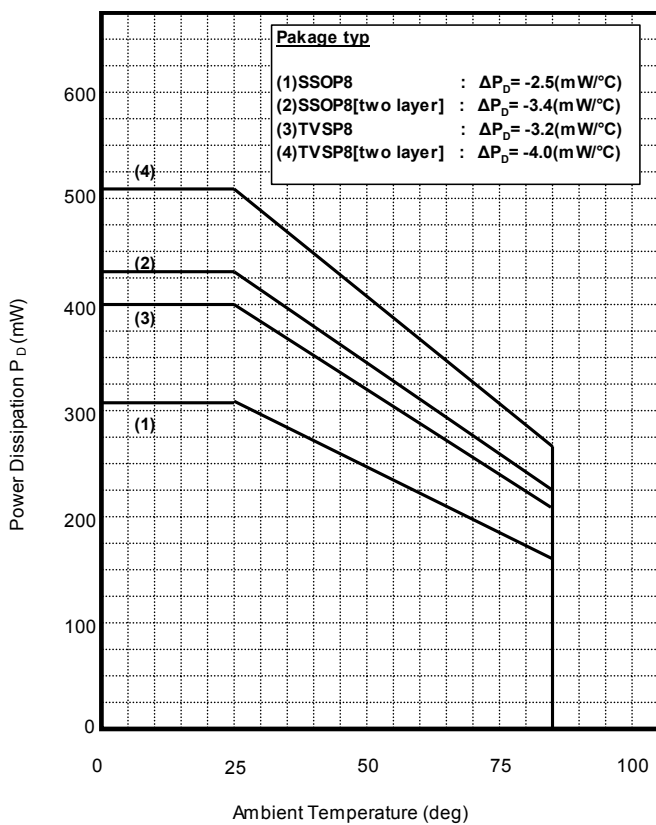
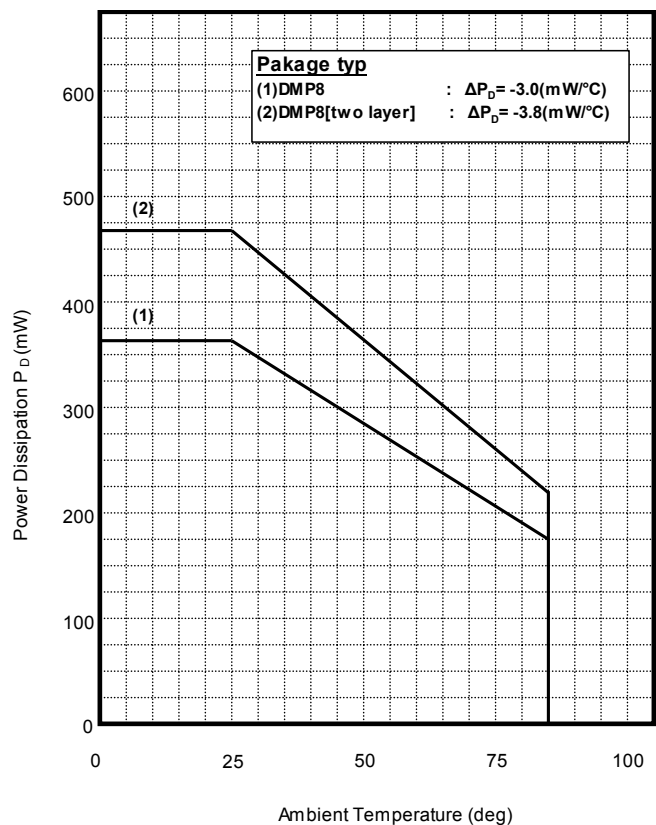


Figure1B: Power Dissipation – Ambient Temperature



## ■ OPERATING VOLTAGE (Ta=25°C)

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Supply Voltage	V <sup>+</sup> /V <sup>-</sup>	(Note3)	±2.25	-	±5.5	V

## ■ ELECTRICAL CHARACTERISTICS

### ●DC CHARACTERISTICS (V<sup>+</sup>/V<sup>-</sup>=±2.5V, Ta=25°C)

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Supply Current	I <sub>CC</sub>	No Signal	-	11	14	mA
Input Offset Voltage	V <sub>IO</sub>	Rs=50Ω	-	1	9	mV
Input Offset Voltage Drift	ΔV <sub>IO</sub> /ΔT	Rs=50Ω	-	10	-	μV/deg
Input Bias Current	I <sub>B</sub>		-	2.9	25	μA
Input Offset Current	I <sub>IO</sub>		-	0.2	2	μA
Voltage Gain	A <sub>V</sub>	R <sub>L</sub> = 1kΩ to 0V, V <sub>o</sub> = ±1V	68	91	-	dB
Common Mode Rejection Ratio	CMR	-2V ≤ V <sub>CM</sub> ≤ +1.2V	82	92	-	dB
Supply Voltage Rejection Ratio	SVR	±2.25V ≤ V <sup>+</sup> /V <sup>-</sup> ≤ ±5V	84	97	-	dB
Maximum Output Voltage 1	V <sub>OH1</sub>	R <sub>L</sub> = 1kΩ to 0V	+2.3	+2.4	-	V
	V <sub>OL1</sub>		-	-2.4	-2.3	
Maximum Output Voltage 2	V <sub>OH2</sub>	I <sub>source</sub> =4mA, +Input =+0.1V, -Input =-0.1V	+2.2	+2.3	-	V
	V <sub>OL2</sub>	I <sub>sink</sub> =4mA, +Input =-0.1V, -Input =+0.1V	-	-2.3	-2.2	
Common Mode Input Voltage Range	V <sub>ICM+</sub>	CMR≥82dB	+1.2	-	-	V
	V <sub>ICM-</sub>		-	-	-2	

### ●AC CHARACTERISTICS (V<sup>+</sup>/V<sup>-</sup>=±2.5V, Ta=25°C)

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Unity Gain	f <sub>T</sub>	A <sub>V</sub> =+40dB,	-	90	-	MHz
Phase Margin	φ <sub>m</sub>	R <sub>f</sub> =1.98kΩ, R <sub>g</sub> =20Ω,	-	60	-	deg
Gain Margin	G <sub>m</sub>	R <sub>L</sub> =1kΩ to 0V, C <sub>L</sub> =5pF	-	10	-	dB
Equivalent Input Noise Voltage	V <sub>NI1</sub>	f=100kHz	-	2.5	-	nV/√Hz
	V <sub>NI2</sub>	f=10kHz	-	3	-	
Equivalent Input Noise Current	I <sub>NI</sub>	f=100kHz	-	3	-	pA/√Hz
Channel Separation	CS	f=1MHz, V <sub>in</sub> =0.2Vpp, A <sub>V</sub> =+1, R <sub>L</sub> =1kΩ to 0V, C <sub>L</sub> =5pF	-	70	-	dB

### ●TRANSIENT CHARACTERISTICS (V<sup>+</sup>/V<sup>-</sup>=±2.5V, Ta=25°C)

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Slew Rate 1	+SR1	A <sub>V</sub> =0dB, R <sub>L</sub> =1kΩ to 0V, C <sub>L</sub> =5pF, V <sub>out</sub> =2Vpp	-	35	-	V/μs
	-SR1		-	35	-	
Slew Rate 2	+SR2	A <sub>V</sub> =+6dB, R <sub>L</sub> =1kΩ to 0V, C <sub>L</sub> =5pF, V <sub>out</sub> =2Vpp	-	30	-	V/μs
	-SR2		-	30	-	
Rise Time	t <sub>r</sub>	A <sub>V</sub> =+6dB, R <sub>L</sub> =1kΩ to 0V, C <sub>L</sub> =5pF, V <sub>out</sub> =0.2Vpp, 10% to 90%	-	8.3	-	ns
Fall Time	t <sub>f</sub>		-	8.3	-	ns
Power Band Width	PBW	A <sub>V</sub> =+6dB, R <sub>L</sub> =1kΩ to 0V, C <sub>L</sub> =5pF, V <sub>out</sub> =2Vpp, HD2 ≤40dB, HD3 ≤40dB	-	3	-	MHz
Total Harmonic Distortion	THD	A <sub>V</sub> =+6dB, R <sub>L</sub> =1kΩ to 0V, C <sub>L</sub> =5pF, f=10kHz, V <sub>out</sub> =2Vpp	-	0.1	-	%
Second Harmonic	HD2	A <sub>V</sub> =+6dB, R <sub>L</sub> =1kΩ to 0V, C <sub>L</sub> =5pF, f=1MHz, V <sub>out</sub> =2Vpp	-	-50	-	dBc
Third Harmonic	HD3		-	-50	-	dBc
Settling time (1%)	ts1	A <sub>V</sub> =+6dB, R <sub>L</sub> =1kΩ to 0V, C <sub>L</sub> =5pF, V <sub>out</sub> =2Vpp	-	100	-	ns
Settling time (0.1%)	ts2		-	110	-	ns

## ●DC CHARACTERISTICS ( $V^+V^- = \pm 5V$ , $T_a = 25^\circ C$ )

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Supply Current	$I_{CC}$	No Signal	-	14	17	mA
Input Offset Voltage	$V_{IO}$	$R_s = 50\Omega$	-	1	9	mV
Input Offset Voltage Drift	$\Delta V_{IO}/\Delta T$	$R_s = 50\Omega$	-	10	-	$\mu V/deg$
Input Bias Current	$I_B$		-	2.9	25	$\mu A$
Input Offset Current	$I_{IO}$		-	0.2	2	$\mu A$
Voltage Gain	$A_v$	$R_L = 1k\Omega$ to 0V, $V_o = \pm 1V$	70	91	-	dB
Common Mode Rejection Ratio	CMR	$-4.5V \leq V_{CM} \leq +3.7V$	82	92	-	dB
Supply Voltage Rejection Ratio	SVR	$\pm 2.25V \leq V^+V^- \leq \pm 5V$	84	97	-	dB
Maximum Output Voltage 1	$V_{OH1}$	$R_L = 1k\Omega$ to 0V	+4.6	+4.7	-	V
	$V_{OL1}$		-	-4.8	-4.7	
Maximum Output Voltage 2	$V_{OH2}$	Isource =5mA, +Input =+0.1V, -Input =-0.1V	+4.5	+4.6	-	V
	$V_{OL2}$		Isink =5mA, +Input =-0.1V, -Input =+0.1V	-	-4.7	-4.6
Common Mode Input Voltage Range	$V_{ICM+}$	CMR $\geq$ 82dB	+3.7	-	-	V
	$V_{ICM-}$		-	-	-4.5	

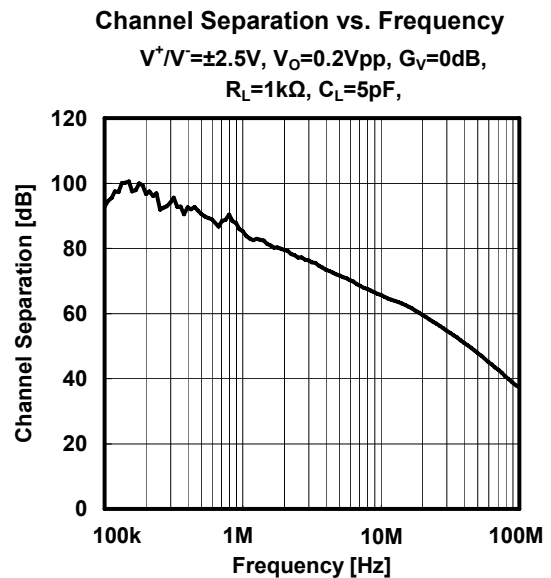
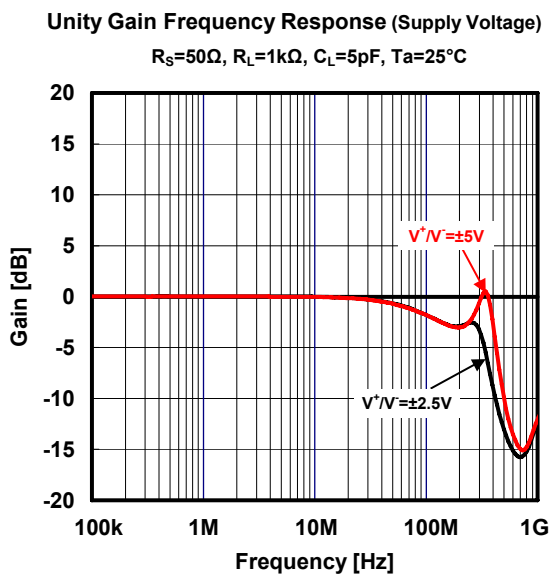
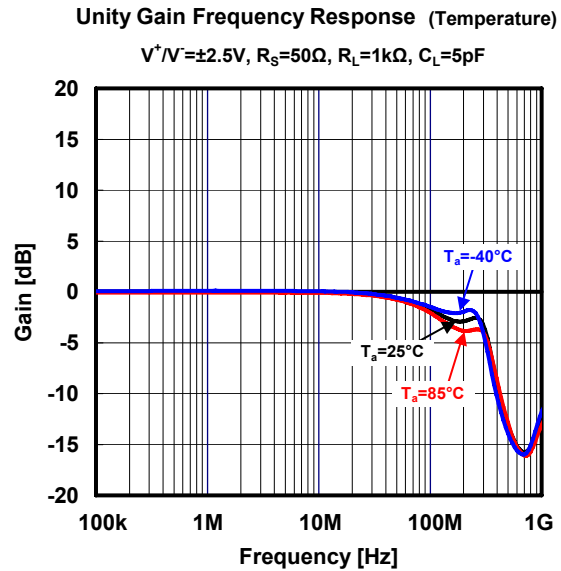
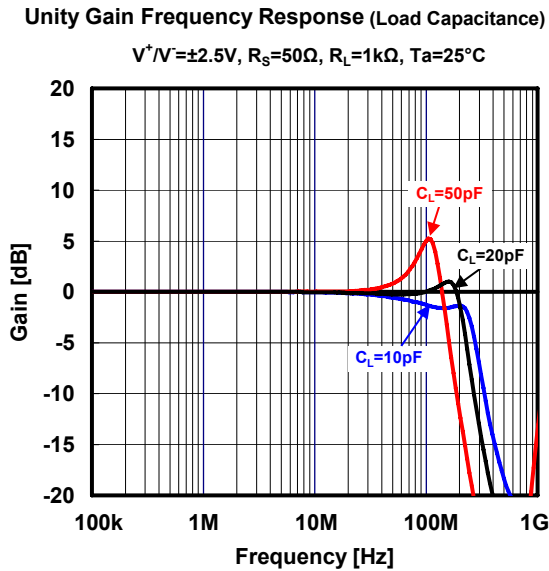
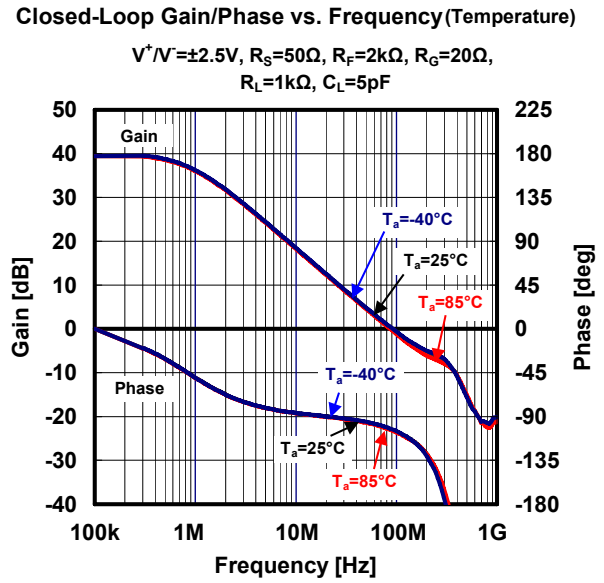
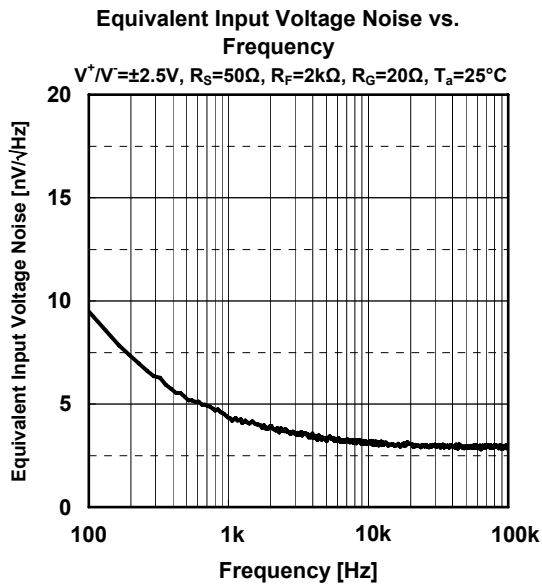
## ●AC CHARACTERISTICS ( $V^+V^- = \pm 5V$ , $T_a = 25^\circ C$ )

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Unity Gain	fT	$A_v = +40dB$ ,	-	100	-	MHz
Phase Margin	$\phi_m$	$R_f = 1.98k\Omega$ , $R_g = 20\Omega$ ,	-	60	-	deg
Gain Margin	Gm	$R_L = 1k\Omega$ to 0V, $C_L = 5pF$	-	10	-	dB
Equivalent Input Noise Voltage	$V_{NI1}$	f =100kHz	-	2.5	-	$nV/\sqrt{Hz}$
	$V_{NI2}$		f =10kHz	-	3	-
Equivalent Input Noise Current	$I_{NI}$	f =100kHz	-	3	-	$pA/\sqrt{Hz}$
Channel Separation	CS	f =1MHz, $V_{in} = 0.2V_{pp}$ , $A_v = +1$ , $R_L = 1k\Omega$ to 0V, $C_L = 5pF$	-	70	-	dB

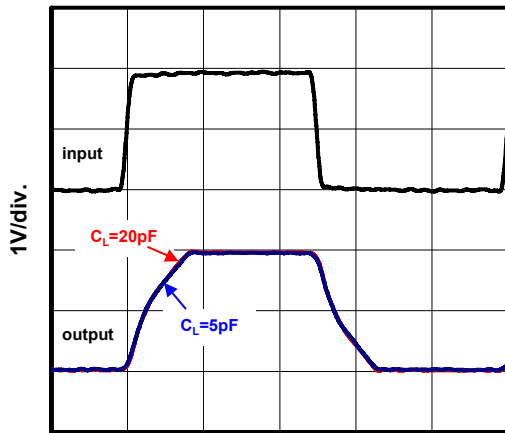
## ●TRANSIENT CHARACTERISTICS ( $V^+V^- = \pm 5V$ , $T_a = 25^\circ C$ )

PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Slew Rate 1	+SR1	$A_v = 0dB$ , $R_L = 1k\Omega$ to 0V, $C_L = 5pF$ , $V_{out} = 5V_{pp}$	-	60	-	$V/\mu s$
	-SR1		-	60	-	
Slew Rate 2	+SR2	$A_v = +6dB$ , $R_L = 1k\Omega$ to 0V, $C_L = 5pF$ , $V_{out} = 5V_{pp}$	-	55	-	$V/\mu s$
	-SR2		-	55	-	
Rise Time	$t_r$	$A_v = +6dB$ , $R_L = 1k\Omega$ to 0V, $C_L = 5pF$ , $V_{out} = 0.2V_{pp}$ , 10% to 90%	-	8	-	ns
Fall Time	$t_f$		-	8	-	
Power Band Width	PBW	$A_v = +6dB$ , $R_L = 1k\Omega$ to 0V, $C_L = 5pF$ , $V_{out} = 2V_{pp}$ , HD2 $\leq$ 40dB, HD3 $\leq$ 40dB	-	4	-	MHz
Total Harmonic Distortion	THD	$A_v = +6dB$ , $R_L = 1k\Omega$ to 0V, $C_L = 5pF$ , f =10kHz, $V_{out} = 2V_{pp}$	-	0.1	-	%
Second Harmonic	HD2	$A_v = +6dB$ , $R_L = 1k\Omega$ to 0V, $C_L = 5pF$ ,	-	-50	-	dBc
Third Harmonic	HD3	f =1MHz, $V_{out} = 2V_{pp}$	-	-50	-	
Settling time (1%)	$t_{s1}$	$A_v = +6dB$ , $R_L = 1k\Omega$ to 0V, $C_L = 5pF$ ,	-	90	-	ns
Settling time (0.1%)	$t_{s2}$	$V_{out} = 2V_{pp}$	-	110	-	

## ■ TYPICAL CHARACTERISTICS

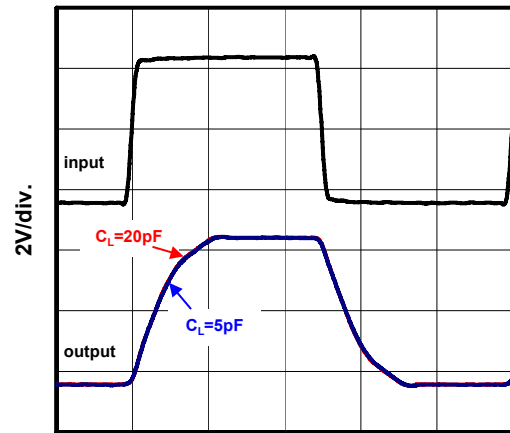


**Transient Response (Load Capacitance)**  
 $V^+/V^-=\pm 2.5V, f=4MHz, V_O=2V_{PP}, G_V=1, R_T=50\Omega,$   
 $R_L=1k\Omega, T_a=25^\circ C$



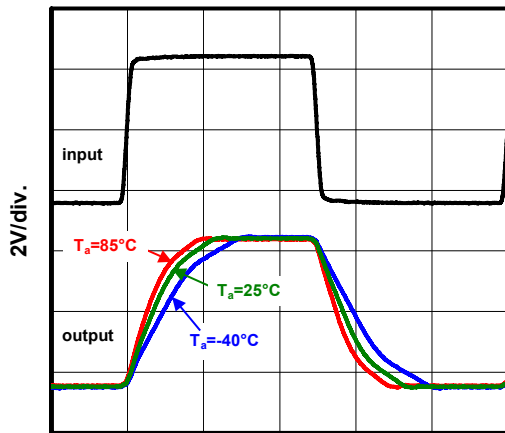
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**Transient Response (Load Capacitance)**  
 $V^+/V^-=\pm 5V, f=4MHz, V_O=5V_{PP}, G_V=1, R_T=50\Omega,$   
 $R_L=1k\Omega, T_a=25^\circ C$



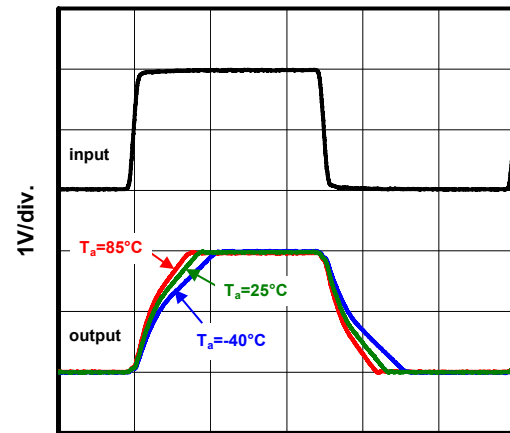
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**Transient Response (Temperature)**  
 $V^+/V^-=\pm 5V, f=4MHz, V_O=5V_{PP}, G_V=1, R_T=50\Omega,$   
 $R_L=1k\Omega, C_L=5pF$



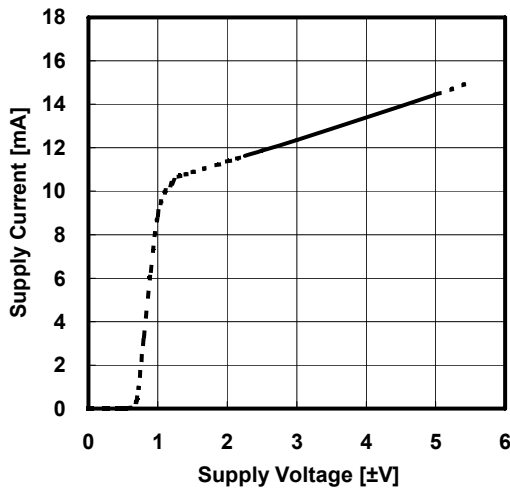
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**Transient Response (Temperature)**  
 $V^+/V^-=\pm 2.5V, f=4MHz, V_O=2V_{PP}, G_V=1, R_T=50\Omega,$   
 $R_L=1k\Omega, C_L=5pF$

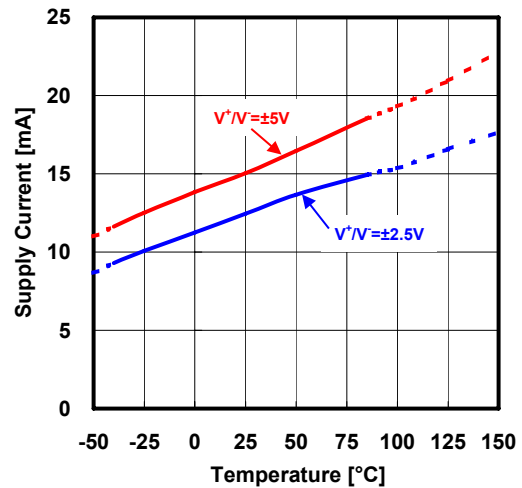


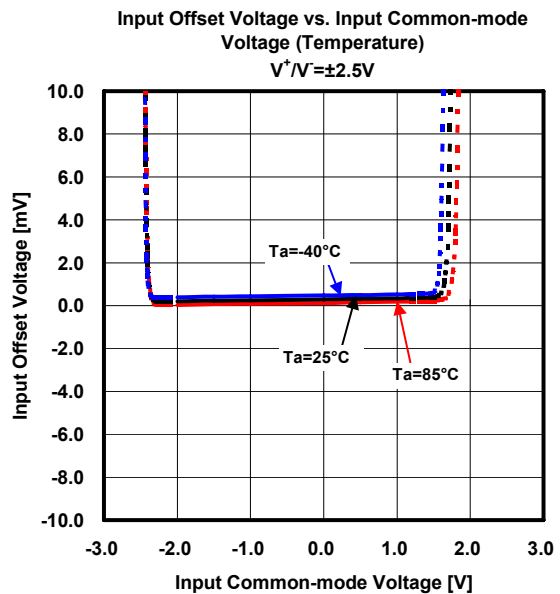
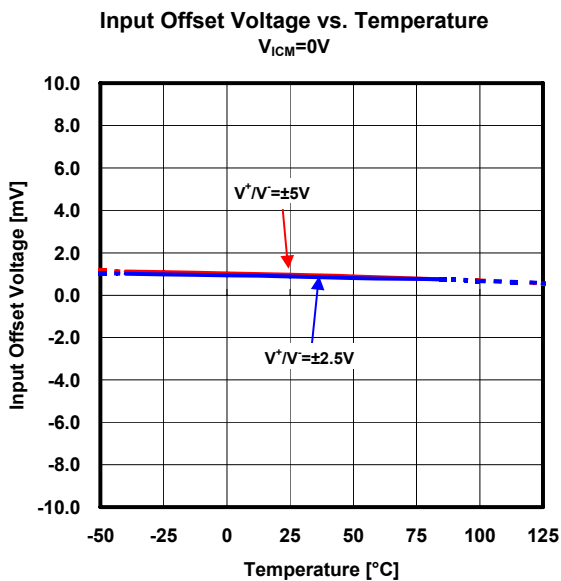
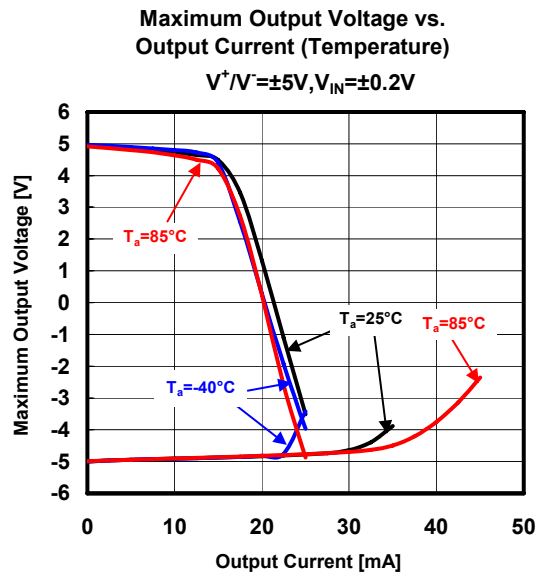
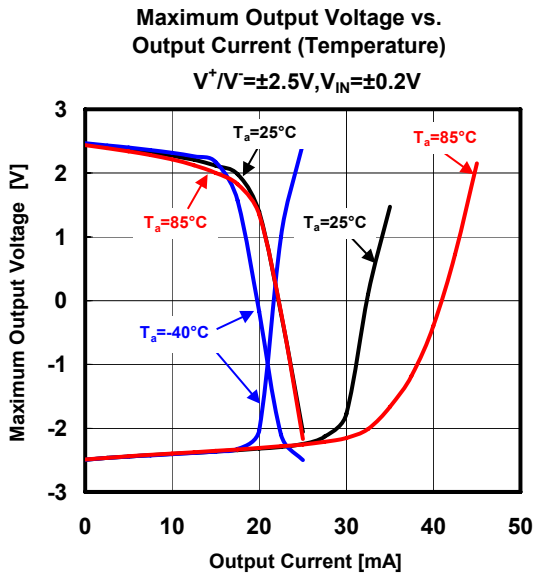
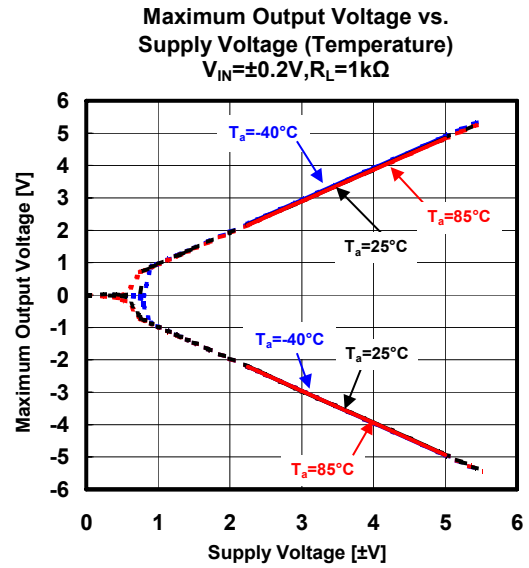
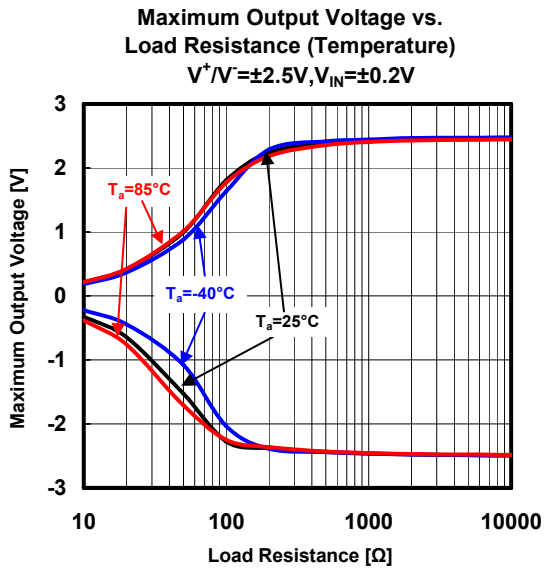
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**Supply Current vs. Supply Voltage**  
 $G_V=0dB, T_a=25^\circ C$

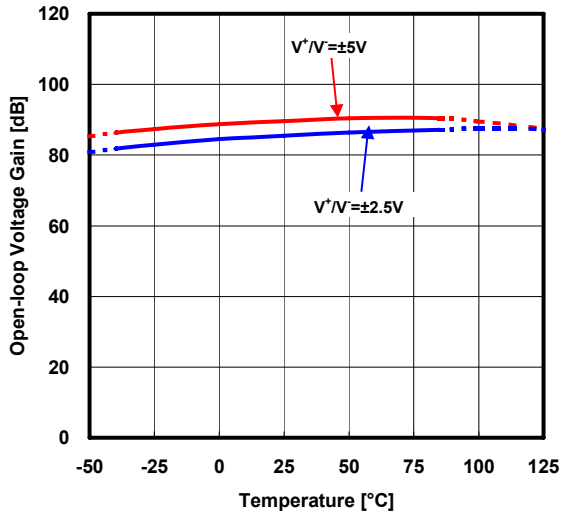


**Supply Current vs. Temperature**  
 $G_V=0dB, V_{ICM}=0V$

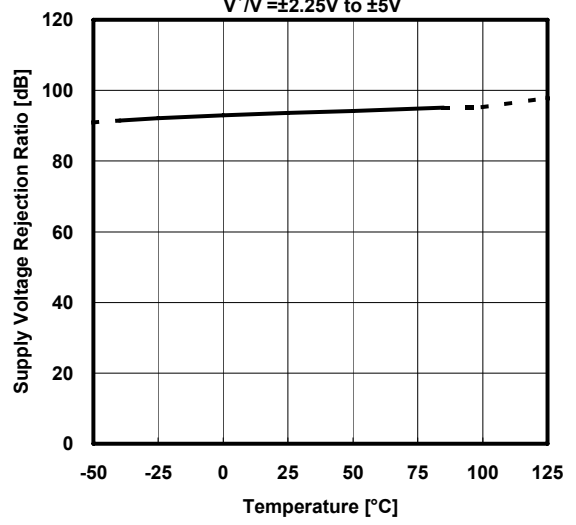




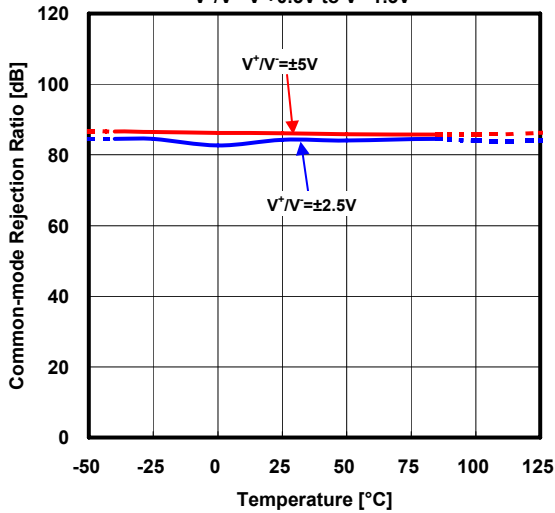
**Open-loop Voltage Gain vs. Temperature**  
 $V_{OUT} = -1V$  to  $+1V$ ,  $R_L = 1k\Omega$



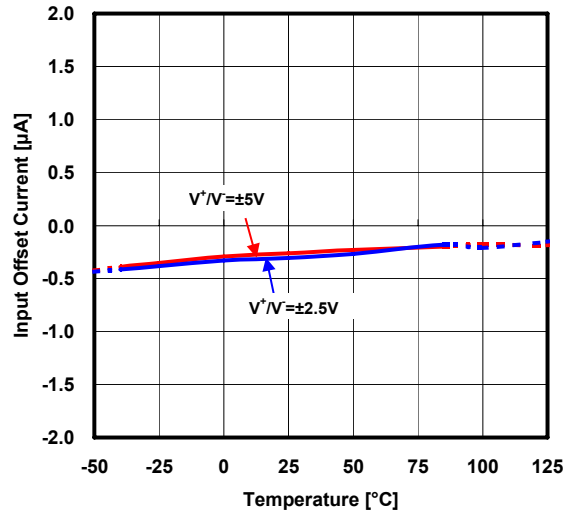
**Supply Voltage Rejection Ratio vs. Temperature**  
 $V^+/V^- = \pm 2.25V$  to  $\pm 5V$



**Common-mode Rejection Ratio vs. Temperature**  
 $V^+/V^- = V^+ + 0.5V$  to  $V^+ - 1.3V$



**Input Offset Voltage vs. Temperature**  
 $V_{ICM} = 0V$





## APPLICATION

### Stability

Generally, when driving a large capacitive load in low closed-loop gain or unity-gain configurations, circuit stability is reduced. In the case of using the NJM2719 for these configurations, it is necessary to care about unwanted oscillation.

An effective way to improve stability and to avoid oscillation is to add an isolation resistor as shown in Figure 1.

Figure 2 shows required resistor values ( $R_{ISO}$ ) for stability versus load capacitances ( $C_L$ ) in the unity-gain configuration (Figure 1). To ensure the stability, add a larger isolation resistor in Figure 2. (Resistor values in Figure 2 are reference values when parasitic capacitance of an evaluation board is minimized.)

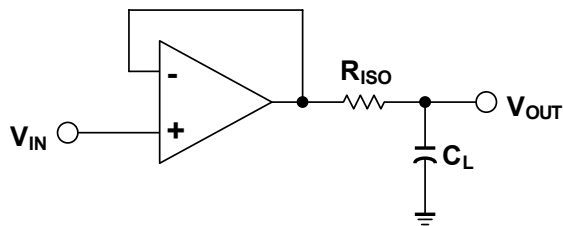


Figure 1.

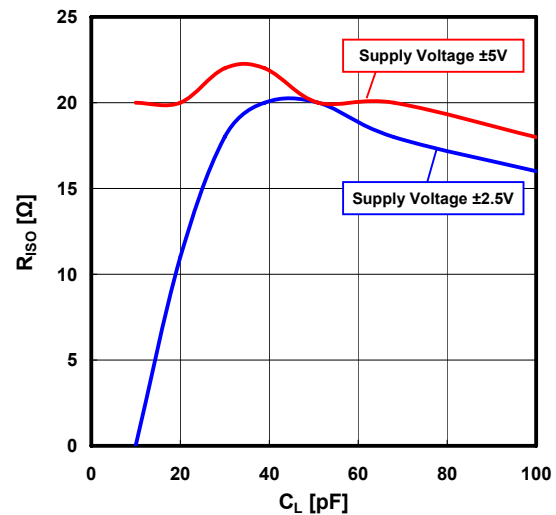


Figure 2. Required Isolation Resistor values for stability,  $R_{ISO}[\Omega]$ , versus Capacitive Loads,  $C_L[\text{pF}]$ . ( $G_V=0\text{dB}$ )

## ■ NOTE

[CAUTION]

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