Philips Components

Data sheet				
Preliminary specification				
December 1990				

PC.8582 Family 256 x 8-BIT CMOS EEPROMS with I²C-BUS interface

GENERAL DESCRIPTION

The 2 Kbit (256 x 8-bit) CMOS EEPROMS are floating gate electrically erasable programmable read only memories.

Power consumption is low due to the full CMOS technology used. The programming voltage is generated on-chip using a voltage multiplier.

As data bytes are received and transmitted via the serial I²C-bus, a package using eight pins is sufficient.

Chip select is accomplished by the three address inputs, which also allows up to eight devices to be connected to the I²C-bus.

Features

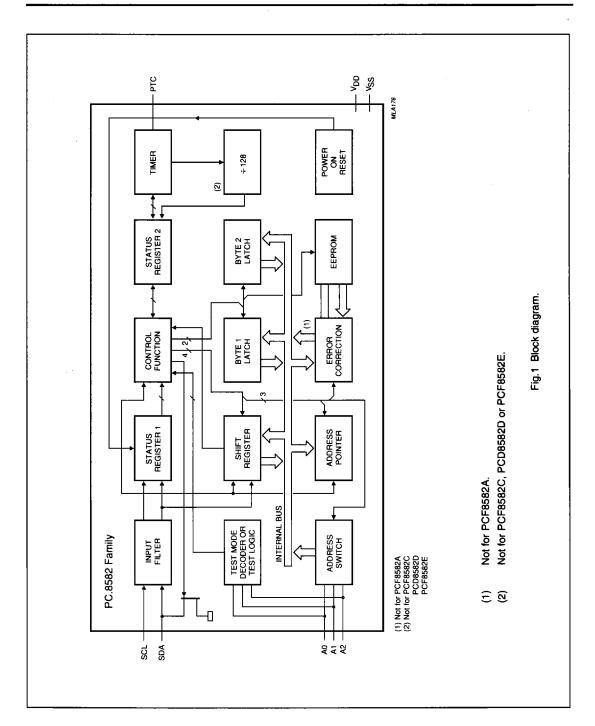
- Non-volatile storage of 2 Kbits organized as 256 x 8-bits
- · Only one power supply required
- · On chip voltage multiplier
- Serial input/output bus (I2C)
- Automatic word address incrementing
- · Low power consumption
- · Power-on reset
- 10 years non-volatile data retention time
- Pin and address compatible to PCF8570, PCF8571, and PCF8581
- Mini-pack package for SMD technology.



QUICK SELECTION GUIDE

TYPE	PCF8582A	PCA8582B	PCF8582C	PCD8582D	PCF8582E
extended temperature range	•	•	•	_	•
extended voltage supply range	-	-	•	•	-
no external RC required	-	-	•	•	•
single bit error correction for extended number of erase/write cycles	_	•	•	•	•

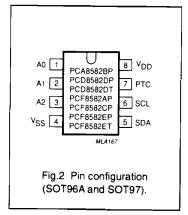
PC.8582 Family



PC.8582 Family

ORDERING INFORMATION

EXTENDED TYPE NUMBER	PACKAGE				
EXTENDED TIPE NUMBER	PINS	PIN POSITION	MATERIAL	CODE	
PCA8582BP	8	DIL	plastic	SOT97	
PCA8582BT	16	SO16L	plastic	SOT162A	
PCD8582DP	8	DIL	plastic	SOT97	
PCD8582DT	8	SO8	plastic	SOT96A	
PCF8582AP	8	DIL	plastic	SOT97	
PCF8582AT	16	SO16L	plastic	SOT162A	
PCF8582CP	8	DIL	plastic	SOT97	
PCF8582CT	16	SO16L	plastic	SOT162A	
PCF8582EP	8	DIL	plastic	SOT97	
PCF8582ET	8	SO8	plastic	SOT96A	



FUNCTIONAL DESCRIPTION Characteristics of the I²C-bus

The I²C-bus is a bidirectional, 2-line communication between different ICs or modules. The two lines are for serial data (SDA) and serial clock (SCL). Both the SDA and the SCL lines must be connected to a positive supply voltage via a pull-up resistor.

The following protocol has been defined:

PINNING

SYMBOL	PIN	DESCRIPTION		
A0	1	address input		
A1	2	address input		
A2	3	address input		
V _{ss}	4	ground		
SDA	5	serial data		
SCL	6	serial clock		
PTC	7	can be connected to V _{DD} or left open-circuit		
V _{DD}	8	positive supply voltage		

- data transfer may be initiated only when the bus is not busy.
- during data transfer, the data line must remain stable whenever the clock line is HIGH. Changes in the data line while the clock line is HIGH will be interpreted as control signals.

The following bus conditions have been defined:

Bus not busy: both data and clock lines remain HIGH.

Start data transfer: a change in the state of the data line, from HIGH-to-LOW, while the clock is HIGH defines the start condition.

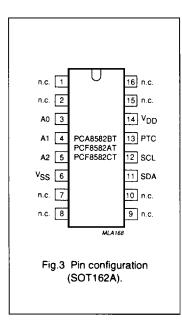
Stop data transfer: a change in the state of the data line, from

LOW-to-HIGH, while the clock is HIGH, defines the stop condition.

Data valid: the state of the data line represents valid data when, after a start condition, the data line is stable for the duration of the HIGH period of the clock signal. There is one clock pulse per bit of data.

Each data transfer is initiated with a start condition and terminated with a stop condition; the number of the data bytes, transferred between the start and stop conditions is limited to two bytes in the ERASE/WRITE mode and unlimited in the READ mode. The information is transmitted in bytes and each receiver acknowledges with a ninth bit.

PC.8582 Family



PINNING

SYMBOL	PIN	DESCRIPTION
n.c.	1	not connected
n.c.	2	not connected
A 0	3	address input
A1	4	address input
A2	5	address input
V _{ss}	6	ground
n.c.	7	not connected
n.c.	8	not connected
n.c.	9	not connected
n.c.	10	not connected
SDA	11	serial data
SCL	12	serial clock
PTC	13	can be connected to V _{DD} or left open-circuit
V _{DD}	14	positive supply voltage
n.c.	15	not connected
n.c.	16	not connected

By definition a device that sends a signal is called a "transmitter" and the device which receives the signal is called a "receiver". The device which controls the signals is called the "master". The devices that are controlled by the master are called "slaves".

Each byte of eight bits is followed by one acknowledge bit. This acknowledge bit is a HIGH level put on the bus by the transmitter. The master generates an extra acknowledge related clock pulse.

The slave receiver which is addressed is obliged to generate an acknowledge after the reception of each byte.

The master receiver must generate an acknowledge after the reception

of each byte that has been clocked out of the slave transmitter.

The device that acknowledges has to pull down the SDA line during the acknowledge clock pulse in such a way that the SDA line is stable LOW during the HIGH period of the acknowledge related clock pulse.

Set up and hold times must be taken into account. A master receiver must signal an end of data to the slave transmitter by not generating an acknowledge on the last byte that has been clocked out of the slave. In this event the transmitter must leave the data line HIGH to enable the master generation of the stop condition.

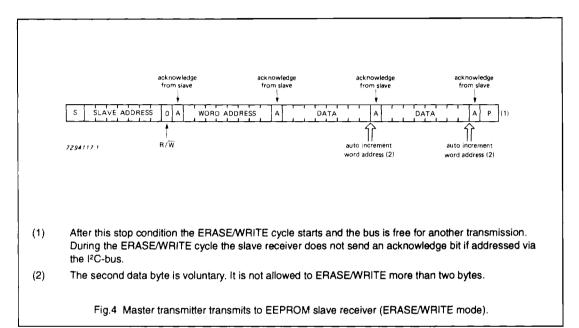
(1)

⁽¹⁾ Detailed specifications of the I2C-bus are available on request.

PC.8582 Family

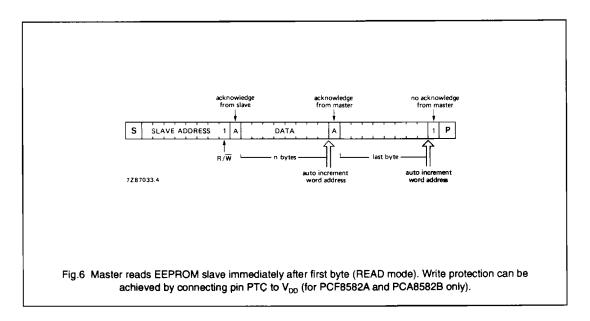
I2C-bus protocol

The I2C-bus configuration for different READ and WRITE cycles of the EEPROM are shown in Figures 4, 5 and 6.



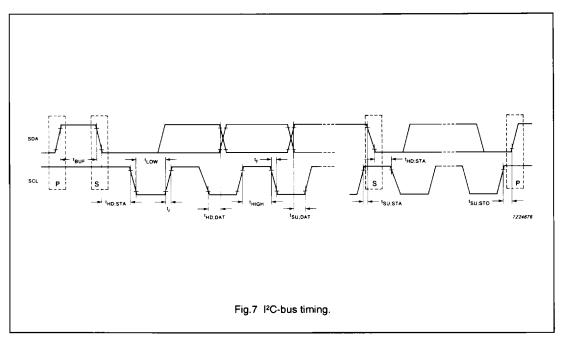
ack nowledge acknowledge acknowledge acknowledge from slave from slave from master s SLAVE ADDRESS 0 Α WORD ADDRESS Α s SLAVE ADDRESS 1 DATA А R/W R/W n bytes transmitter becomes master receiver and auto increment word address EEPROM slave receiver becomes slave transmitter 7296672.2 no acknowledge from master DATA Р last byte auto increment word address Fig.5 Master reads EEPROM slave after setting word address (write word address; READ data).

PC.8582 Family

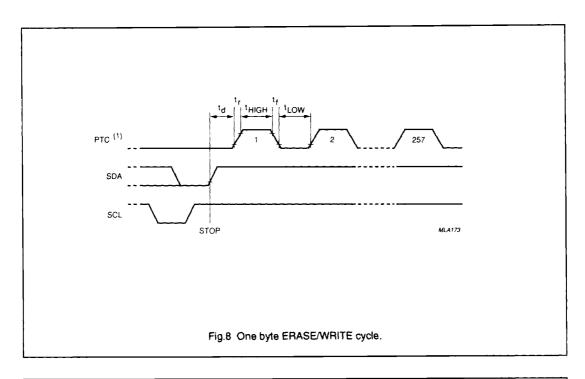


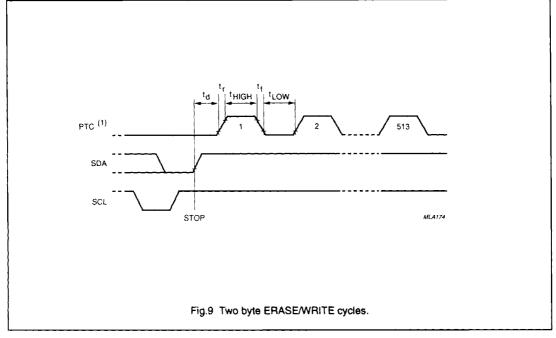
The slave address is defined in accordance with the I2C-bus specification as:



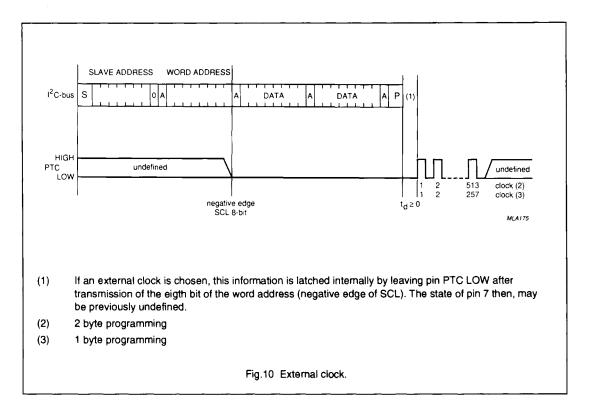


PC.8582 Family





PC.8582 Family



LIMITING VALUES

In accordance with the Absolute Maximum System (IEC 134)

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V _{DD}	supply voltage		-0.3	+7.0	V
V _I	voltage on any input	Z _i > 500 Ω	V _{ss} -0.8	V _{DD} + 0.8	V
I,	current on any input pin		-	1	mA
lo	output current		-	10	mA
T _{stg}	storage temperature range		-65	+150	°C
T _{amb}	operating ambient temperature range PCF8582A/C/E PCA8582B PCD8582D		40 40 25	+85 +125 +70	င့် င့်

PC.8582 Family

CHARACTERISTICS

PCF8582A; $V_{DD} = 4.5$ to 5.5 V; $V_{SS} = 0$ V; $T_{amb} = -40$ to +85 °C PCA8582B; $V_{DD} = 4.5$ to 5.5 V; $V_{SS} = 0$ V; $T_{amb} = -40$ to +125 °C PCF8582C; $V_{DD} = 2.5$ to 6 V; $V_{SS} = 0$ V; $T_{amb} = -40$ to +85 °C PCD8582D; $V_{DD} = 3$ to 6 V; $V_{SS} = 0$ V; $T_{amb} = -25$ to +70 °C PCF8582E; $V_{DD} = 4.5$ to 5.5 V; $V_{SS} = 0$ V; $T_{amb} = -40$ to +85 °C

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V _{DD}	supply voltage					
	PCF8582A/E, PCA8582B		4.5	-	5.5	V
	PCF8582C		2.5	-	6.0	٧
	PCD8582D		3	<u>-</u>	6	٧
IDOR	supply current READ	f _{SCL} = 100 kHz	ļ			
	PCF8582A	V _{DD(max)}	-	-	0.4	mA
	PCA8582B	V _{DD(max)}	-	-	0.8	mA
	PCF8582C/PCD8582D	$V_{DD} = 3 V$	-	-	0.25	mA
		$V_{DD} = 6 V$	-	-	1.6	mA
	PCF8582E	V _{DD(max)}	-	<u> </u>	1.6	mA
I _{DDE/W}	supply current ERASE/WRITE	f _{SCL} = 100 kHz				į
	PCF8582A/PCA8582B	V _{DD(max)}	[-	-	2	mA
	PCF8582C/PCD8582D	$V_{DD} = 3 V$	-	-	0.35	mA
		$V_{DD} = 6 V$	-] —	2.5	mA
	PCF8582E	V _{DD(max)}	-	-	2.5	mA
l _{stb}	supply current STANDBY					
	PCF8582A	V _{DD(max)}	-] -	10	μА
	PCA8582B	V _{DD(max)}	-	-	20	μA
	PCF8582C/PCD8582D	$V_{DD} = 3 V$	-	(-	3.5	μА
		$V_{DD} = 6 V$	-	-	10	μA
	PCF8582E	V _{DD(max)}	-]	10	μA
PTC input	(PCF8582A/PCA8582B)					
V _{IH}	input voltage HIGH		V _{DD} -0.3		V _{DD} + 0.8	V
V _{IL}	input voltage LOW		-0.8	-	V _{ss} + 0.3	V
PTC input	(PCF8582C/PCD8582D/PCF8582E)					
V _H	input voltage HIGH		0.9 V _{DD}	-	V _{DD} + 0.8	V
V _{IL}	input voltage LOW	1	-0.8	-	0.1 V _{DD}	V
SCL input						
V _H	input voltage HIGH					
	PCF8582A/PCA8582B		3	-	$V_{DD} + 0.8$	V
	PCF8582C/PCD8582D/PCF8582E		0.7 V _{DD}	-	$V_{DD} + 0.8$	V

PC.8582 Family

SYMBOL	PARAMETER	CONDITIONS	MiN.	TYP.	MAX.	UNIT
SDA input/	output	•			<u> </u>	
V _{IL}	input voltage LOW PCF8582A/PCA8582B PCF8582C/PCD8582D/PCF8582E		-0.3 -0.8 V _{DD}	_ _	1.5 0.3 V _{DD}	V
Val	output voltage LOW PCF8582A/PCA8582B PCF8582C PCD8582D PCF8582E	$I_{OL} = 3 \text{ mA}$ $V_{DD} = 4.5 \text{ V}$ $V_{DD} = 2.5 \text{ V}$ $V_{DD} = 3 \text{ V}$ $V_{DD(min)}$	- - -	 - -	0.4 0.4 0.4 0.4	> > >
I _{LO}	output leakage current	V _{OH} = V _{DD}	-	_	1	μА
lu	input leakage current	$V_1 = V_{DD}$ or V_{SS}	_	_	1	μА
Data retent	tion time		•			
t _s	data retention time	T _{amb} = 55 °C	10	-	-	yrs

WRITE CYCLE LIMITS

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
t _{EW}	ERASE/WRITE cycle time				
	PCF8582A/PCA8582B		5	40	ms
	PCF8582C/PCD8582D/PCF8582E		5	25	ms
Enduranc	e				
N _{EW}	ERASE/WRITE cycles per byte				
	PCF8582A		-	10000	
	PCA8582B	T _{amb} = 125 °C;			
		t _{EW} = 5 to 40 ms	_	50000	
		T _{amb} = 85 °C;			
		t _{EW} = 5 to 40 ms	-	100000	
		T _{amb} = 33 °C;	1		
		t _{EW} = 10 ms	-	500000	
	PCF8582C	T _{amb} = 85 °C;			
		$t_{EW} = 5$ to 25 ms	-	100000	
		T _{amb} = 33 °C;			1
		t _{EW} = 10 ms	-	500000	1
	PCD8582D	$T_{amb} = -25 \text{ to } +70 \text{ °C};$			1
		t _{Ew} = 5 to 25 ms	-	10000	
		$T_{amb} = 0 \text{ to } +40 ^{\circ}\text{C};$			
		t _{EW} = 10 ms	-	100000	1
	PCF8582E	$T_{amb} = -40 \text{ to } +85 \text{ °C};$			
		t _{EW} = 5 to 25 ms	-	100000	

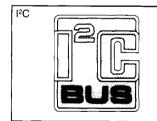
PC.8582 Family

I²C-BUS CHARACTERISTICS

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP,	MAX.	UNIT
f _{SCL}	clock frequency		0		100	kHz
Cı	input capacitance (SDA; SCL)	V _i = V _{SS}	-	-	7	pF
t _{BUF}	time the bus must be free before new transmission can start		4.7	-	-	μs
t _{HD:STA}	start condition hold time after which first clock pulse is generated		4		-	μs
t _{LOW}	clock period LOW		4.7	-	-	μs
t _{HIGH}	clock period HIGH		4	-	i	μS
t _{su:sta}	set up time for start condition	repeated start	4.7	-	-	μs
t _{HD:DAT}	data hold time for bus compatible masters		5		-	μѕ
t _{HD:DAT}	data hold time for bus devices	note 1	0	-	-	ns
t _{SU.DAT}	data set up time		250	-		ns
ţ	SDA and SCL rise time				1	μs
ţ,	SDA and SCL fall time		-	-	300	ns
t _{su.sto}	set up time for stop condition		4.7		-	μs

Note

 The hold time required to bridge the undefined region of the falling edge of SCL must be internally provided by a transmitter. It is not greater than 300 ns.



Purchase of Philips' I²C components conveys a license under the Philips' I²C patent to use the components in the I²C-system provided the system conforms to the I²C specification defined by Philips.

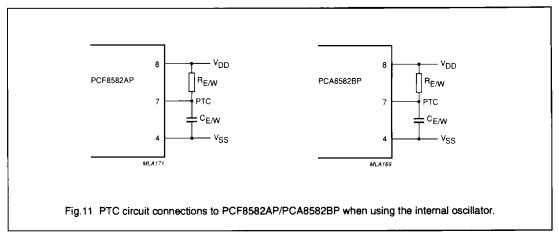
PC.8582 Family

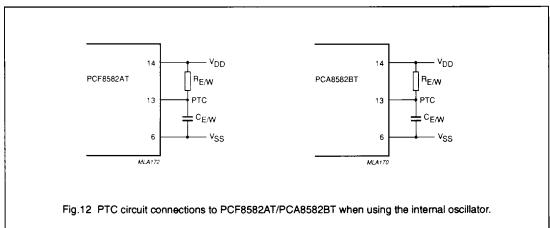
E/W programming time control

Using external resistor R_{EW} and capacitor C_{EW} (see Table 1).

Table 1 Recommended R_{EW} and C_{EW} combinations (PCF8582A/PCA8582B only).

R _{EW}	C _{EW}	T _{EW} (typ.)
(kΩ)	(nF)	(ms)
56	3.3	34
56	2.2	21
22	3.3	13
22	2.2	7.5





PC.8582 Family

Using external clock (see Table 2 and Figs 8, 9 and 10).

Table 2 E/W programming time control using an external clock.

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
CLK	frequency	10	50	kHz
_OW	clock period LOW	10	-	μs
HIGH	clock period HIGH	10	-	μѕ
,	rise time	-	300	ns
!	fall time	-	300	ns
	delay time	0	t _{low}	μs

USING AN INTERNAL OSCILLATOR

When using an internal oscillator t_{EW} has a minimum value of 5 ms and a maximum value of 25 ms; a typical value is 10 ms.

1	