

# **PCA9521**

# Fast dual bidirectional bus buffer

Rev. 2 — 19 March 2013

**Product data sheet** 

# 1. General description

The PCA9521 is a monolithic bipolar integrated circuit for bus buffering in applications including I<sup>2</sup>C-bus, SMBus, PMBus, and other systems based on similar principles.

The buffer extends the bus load limit by buffering both the SCL and SDA lines. It supports up to 400 pF loads on each side of the buffer at 400 kHz. Higher capacitance is supported at lower speeds, and lower capacitance at higher speeds up to 1 MHz.

The enable function allows sections of the bus to be isolated. Individual parts of the system can be brought on-line successively. This means a controlled start-up using a diverse range of components, operating speeds and loads is easily achieved. Systems employing removable components on a back-plane (for example, telecommunications racks) can use the enable pin and the high-impedance ports on power-down to safely install and remove components in active systems.

Bus level translation between a very wide range of bus voltages, from 1.8 V to 10 V, is supported. This feature provides enormous flexibility in interfacing systems of different technologies.

The unique operation of the PCA9521 provides one of the fastest response times of such bidirectional buffers, ensuring any glitches (common to other buffers) are kept well within the 50 ns  $I^2C$ -bus specification. Additionally, it does this without the need for 'rise-time accelerators' which, combined with low noise margins, may cause glitches outside of the  $I^2C$ -bus specification.

### 2. Features and benefits

- Dual, bidirectional unity gain buffer
- Fast switching times allow operation in excess of 1 MHz
- Supports I<sup>2</sup>C-bus (Standard-mode and Fast-mode), SMBus (standard and high power mode), PMBus and IPMB
- Enable allows bus segments to be disconnected
- Low standby current when not enabled
- Application/removal of power to IC will not interfere with other bus activity
- 6 mA (static) pull-down capability supports a wide range of bus standards
- Low noise susceptibility
- Low input-output offset voltage
- Threshold and offset parameters allow the connection of several devices in series
- Bus levels independent of supply voltage
- Operating voltages from 2.7 V to 5.5 V
- Wide range of bus voltages from 1.8 V to 10 V



#### Fast dual bidirectional bus buffer

- Level shifting between different bus voltages
- Achieves superior response times without the need for rise time accelerators
- ESD protection exceeds 2 kV HBM per JESD22-A114 and 500 V CDM per JESD22-C101
- Latch-up testing is done to JEDEC Standard JESD78 which exceeds 100 mA

# 3. Applications

- Power management systems
- Telecommunications systems including ATCA
- Desktop and portable computers including RAID
- Building automation
- TV/projector/monitor interconnection
- Game consoles/boxes
- CompactPCI
- Medical systems
- Gaming machine networks
- Backplane management/interconnect

# 4. Ordering information

Table 1. Ordering information

Type number	Topside	Package	Package								
	marking	Name	Description	Version							
PCA9521D	PCA9521	SO8	plastic small outline package; 8 leads; body width 3.9 mm	SOT96-1							
PCA9521DP	9521	TSSOP8	plastic thin shrink small outline package; 8 leads; body width 3 mm	SOT505-1							

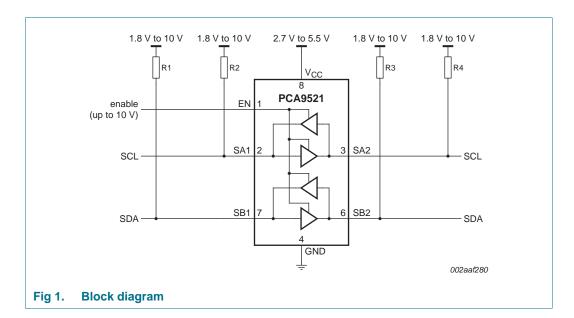
# 4.1 Ordering options

Table 2. Ordering options

Type number	Orderable part number	Package	Packing method	Minimum order quantity	Temperature range
PCA9521D	PCA9521D,118	SO8	Reel 13" Q1/T1 *standard mark SMD	2500	$T_{amb} = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}$
PCA9521DP	PCA9521DP,118	TSSOP8	Reel 13" Q1/T1 *standard mark SMD	2500	$T_{amb} = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}$

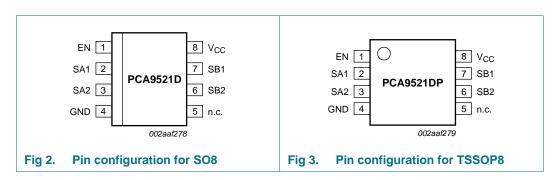
### Fast dual bidirectional bus buffer

# 5. Block diagram



# 6. Pinning information

# 6.1 Pinning



# 6.2 Pin description

Table 3. Pin description

Symbol	Pin	Description
EN	1	enable
SA1	2	buffer A, port 1 (SCL output <sup>[1]</sup> )
SA2	3	buffer A, port 2 (SCL input[1])
GND	4	supply ground
n.c.	5	not connected
SB2	6	buffer B, port 2 (SDA input[1])
SB1	7	buffer B, port 1 (SDA output[1])
$V_{CC}$	8	positive supply

 $<sup>\</sup>begin{tabular}{ll} [1] & Recommended I^2C\mbox{-bus orientation for device family compatibility.} \end{tabular}$ 

Fast dual bidirectional bus buffer

# 7. Functional description

Refer to Figure 1 "Block diagram".

### 7.1 $V_{CC}$ , GND — supply pins

The power supply voltage for the PCA9521 may be any voltage in the range 2.7 V to 5.5 V. The threshold level below which the output will begin to match the input is 33 % of  $V_{CC}$ . Hence, the operating voltage should be chosen with the required bus voltage, switching threshold, and noise margins, in mind.

### 7.2 SA1, SA2, SB1, SB2 — buffer inputs/outputs

The two buffers (SA and SB) are identical and symmetrical. The buffers can be driven from either direction, with the same response. When port 1 of the buffer is being driven LOW (<  $0.3V_{\rm CC}$ ) by another device on the bus, port 2 will be driven LOW by the IC to provide the buffered output.

The 'input' side is determined by the lowest externally driven signal. Therefore if port 1 is externally pulled to  $V_{Sx1} = 250$  mV, and port 2 is externally pulled to  $V_{Sx2} = 500$  mV, the buffer will pull port 2 down further such that it becomes  $V_{Sx2} = V_{Sx1} + V_{offset}$ . Should port 2 subsequently become lower than port 1 by the amount of the offset voltage  $(V_{Sx2} + V_{offset} < V_{Sx1})$  by means of an external device pulling it LOW, control of the buffering operation will switch, and port 2 will become the 'input'. The voltage at port 1 will then become  $V_{Sx1} = V_{Sx2} + V_{offset}$ . When both ports are being held almost equal (less than an offset voltage) the external devices are effectively in control.

### 7.3 EN — enable; activate buffer operations

The enable input, EN, is used to disable the buffer, for the purpose of isolating sections of the bus. The IC should only be disabled when the bus is idle. This prevents truncation of commands which may confuse other devices on the bus.

Enable may also be used to progressively activate sections of the bus during system start-up. Bus sections slow to respond on power-up can be kept isolated from the main system to avoid interference and collisions.

The EN pin may be pulled up higher than the  $V_{CC}$  of the buffer, further enhancing the capability of the PCA9521 in a level shifting role. For example, a microprocessor could drive EN, SA1 and SB1 at 5 V, while the buffer  $V_{CC}$ , SA2 and SB2 ports are at 3.3 V.

Similarly, the threshold level of the EN pin allows a 1.8 V device to disable a PCA9521 with a  $V_{CC}$  of 3.3 V.

The EN pin includes an internal 2  $\mu$ A pull-down current, which will act to disable the device should the pin be left floating.

### Fast dual bidirectional bus buffer

# 8. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC}$	supply voltage		<u>[1]</u> –0.3	+7	V
V <sub>n</sub>	voltage on any other pin	SA1, SA2, SB1, SB2	<u>[1]</u> –0.3	+12	V
$V_{I(EN)}$	input voltage on pin EN		<u>[1]</u> –0.3	+12	V
I <sub>IO</sub>	input/output current	any pin	-	20	mA
P <sub>tot</sub>	total power dissipation		-	300	mW
T <sub>stg</sub>	storage temperature		-55	+125	°C
T <sub>amb</sub>	ambient temperature	operating	-40	+85	°C

<sup>[1]</sup> Voltages are specified with respect to pin 4 (GND).

# 9. Characteristics

Table 5. Characteristics

 $T_{amb} = -40 \, ^{\circ}\text{C}$  to +85  $^{\circ}\text{C}$ ; voltages are specified with respect to ground (GND).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Power su	pply					
$V_{CC}$	supply voltage	operating	2.7	-	5.5	V
I <sub>CC</sub>	supply current	operating; $V_{CC} = V_{I(EN)} = 5.5 \text{ V}$	-	6	-	mA
		standby; $V_{CC} = 5.5 \text{ V}$ ; $V_{I(EN)} = 0 \text{ V}$	-	670	900	μΑ
Buffer po	rts (SA1, SA2, SB1, SB2)					
V <sub>bus</sub>	bus voltage		1.8	-	10	V
$V_{\text{th(IL)}}$	LOW-level input threshold voltage		-	-	0.3V <sub>CC</sub>	V
$V_{th(IH)} \\$	HIGH-level input threshold voltage		0.41V <sub>CC</sub>	-	-	V
I <sub>IL</sub>	LOW-level input current	drive current; V <sub>bus</sub> < V <sub>CC</sub>	-	-6	-20	μΑ
I <sub>O(sink)</sub>	output sink current	LOW-level; $V_{bus(out)} = 0.4 \text{ V}$	6	-	-	mA
V <sub>offset</sub>	offset voltage	input/output; $V_{CC} = 5 \text{ V}$				
		$I_{OL} = 5 \text{ mA}; V_{bus(in)} = 50 \text{ mV}$	-	230	300	mV
		$I_{OL} = 500 \mu A; V_{bus(in)} = 50 \text{ mV}$	-	90	125	mV
		$I_{OL} = 1.2 \text{ mA}; V_{bus(in)} = 200 \text{ mV}$	-	90	125	mV
IL	leakage current	$V_{bus} \ge V_{CC}$	-	-	5	μΑ
C <sub>io</sub>	input/output capacitance		[1] -	-	10	pF
Enable (E	N)					
V <sub>en</sub>	enable voltage	active	1.3	-	-	V
V <sub>dis</sub>	disable voltage	standby	-	-	0.7	V
I <sub>1</sub>	input current	V <sub>en</sub> > 1.2 V	0.7	-	5	μΑ

### Fast dual bidirectional bus buffer

 Table 5.
 Characteristics ...continued

 $T_{amb} = -40$  °C to +85 °C; voltages are specified with respect to ground (GND).

$t_{d(en-act)}$ enable to active delay time EN HIGH to Sxx active - 1.5 -	Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$C_{L(ext)} = 120 \text{ pF}; \frac{\text{Figure 4}}{\text{Figure 4}}$ $t_f \qquad \text{fall time} \qquad \qquad V_{CC} = 5 \text{ V}; \text{ $V_{bus} = 5 \text{ V}; \text{ $R_{pu(bus)} = 1 \text{ k}\Omega$;}} \qquad - \qquad 40 \qquad - \qquad \\ C_{L(ext)} = 120 \text{ pF}; \frac{\text{Figure 4}}{\text{Figure 4}} \qquad \qquad 0 \qquad - \qquad 1000 \text{ constant}$ $t_{d(en-act)} \qquad \text{enable to active delay time} \qquad \text{EN HIGH to Sxx active} \qquad - \qquad 1.5 \qquad - \qquad 0.44 \text{ constant}$	Timing ch	aracteristics[1]					
$C_{L(ext)} = 120 \text{ pF; } \underline{\text{Figure 4}}$ $f_{oper(I2C)} \qquad I^2\text{C operating frequency} \qquad \qquad 0 \qquad - \qquad 1000$ $t_{d(en-act)} \qquad \text{enable to active delay time} \qquad \text{EN HIGH to Sxx active} \qquad - \qquad 1.5 \qquad - \qquad 0.4$	t <sub>d</sub>	delay time		-	45	-	ns
$t_{d(en-act)}$ enable to active delay time EN HIGH to Sxx active - 1.5 -	t <sub>f</sub>	fall time		-	40	-	ns
Section 1. The section of the sectio	f <sub>oper(I2C)</sub>	I <sup>2</sup> C operating frequency		0	-	1000	kHz
t <sub>d(dis-sth)</sub> disable to standby delay time EN LOW to Sxx disabled - 0.4 -	t <sub>d(en-act)</sub>	enable to active delay time	EN HIGH to Sxx active	-	1.5	-	μS
4(4.6-51.5)	t <sub>d(dis-stb)</sub>	disable to standby delay time	EN LOW to Sxx disabled	-	0.4	-	μS

[1] Guaranteed by design (not subject to test).

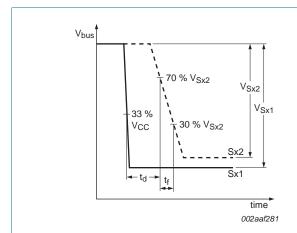


Fig 4. Timing parameters

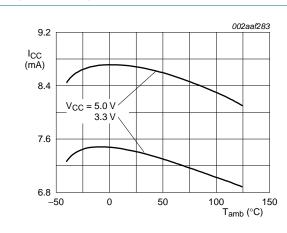
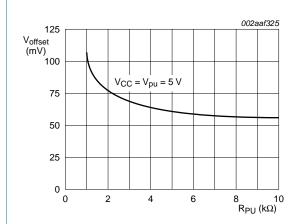
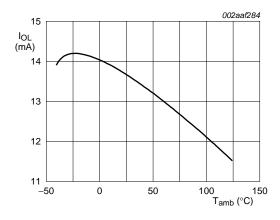


Fig 6. Supply current versus ambient temperature



 $T_{amb} = 25$  °C;  $V_{bus(in)} = 200$  mV.

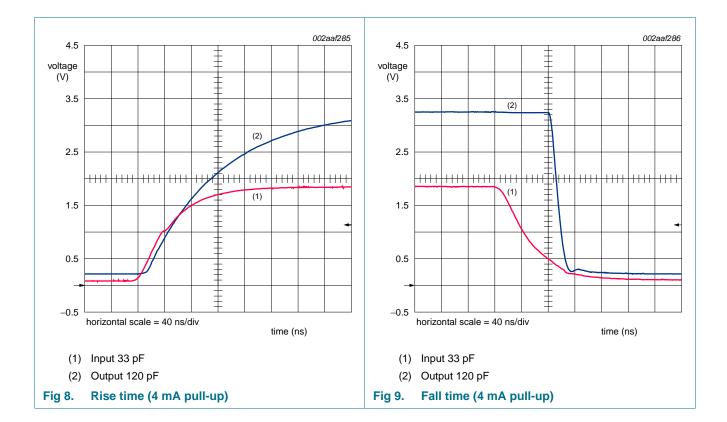
Fig 5. Offset voltage,  $V_O - V_I$ 



 $V_{bus(out)} = 500 \text{ mV}; V_{CC} = 2.7 \text{ V}.$ 

Fig 7. LOW-level output current versus ambient temperature

### Fast dual bidirectional bus buffer

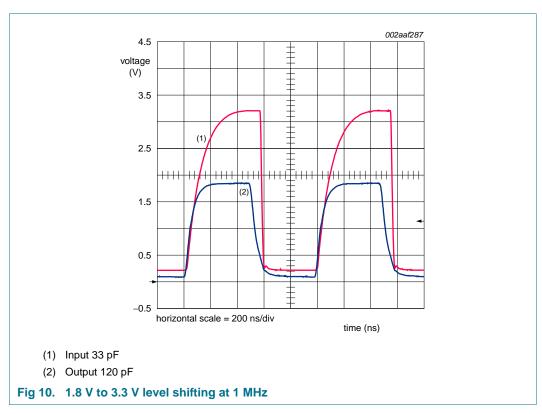


Fast dual bidirectional bus buffer

# 10. Application information

## 10.1 Design considerations

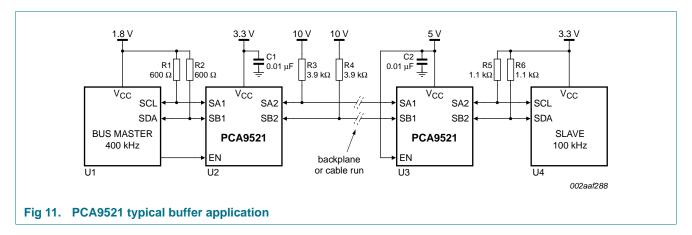
<u>Figure 10</u> shows the PCA9521 level shifting signals from 1.8 V to 3.3 V at 1 MHz clock speed. The PCA9521 has excellent application to extending loads and providing interfaces to connectors on high-speed microprocessor cards, well in excess of the Fast-mode 400 kHz I<sup>2</sup>C-bus specification. Rise times are determined simply by the side of the buffer with the slowest RC time constant.



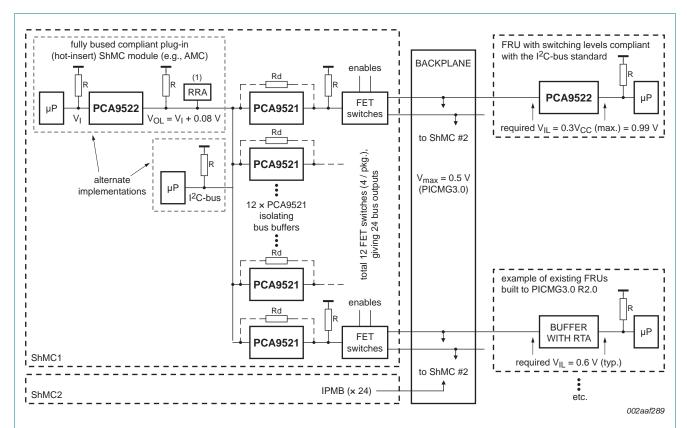
<u>Figure 11</u> shows a typical application for the PCA9521. The IC can level shift between different bus voltages without the need for external components. Higher bus voltages and currents outside the range of the Standard-mode I<sup>2</sup>C-bus specification can be catered for, providing a longer range capability and higher noise immunity.

The enable pin (EN) can be used to interface buses of different operating frequencies. When certain bus sections are enabled, the system frequency may be limited by a bus section having a slave device specified only to 100 kHz. When that bus section is disabled, the slow slave is isolated and the remaining bus can be run at 400 kHz. The timing performance and current sinking capability will allow the PCA9521 to run well in excess of the 400 kHz maximum limit of the Fast-mode I<sup>2</sup>C-bus.

#### Fast dual bidirectional bus buffer



<u>Figure 12</u> shows the PCA9521 used in a radial (star) configuration on an AdvancedTCA Shelf Management Controller board (ShMC). The PCA9521 is highly suited to this and other backplane applications, providing excellent noise margins and I<sup>2</sup>C-bus compliant switching levels.



The system shown here uses FET switches, however a valid alternative is to simply use  $24 \times PCA9521$ 's without FET switches. Long track runs on the ShMC board and backplane can sometimes result in high frequency tuned circuits on either side of the PCA9521. If your layout is prone to forming such tuned circuits, it is perfectly acceptable to use a 'traditional' damping resistor (Rd) across the PCA9521.

(1) RRA = Rise Rate Accelerator.

Fig 12. AdvancedTCA style backplane application using PCA9521 in a radial Shelf Manager configuration

#### Fast dual bidirectional bus buffer

Peripheral cards (or FRU (Field Replaceable Units)) and backplanes operating at a range of voltages can be interfaced together using a minimum of components. The PCA9521 can be teamed with the PCA9522 to achieve substantial noise margin gains across a system.

Multiplexers such as the PCA9544A are simple analog switches which provide no capacitive load isolation between connected branches. <u>Figure 14</u> shows the PCA9521 enhancing an I<sup>2</sup>C-bus multiplexer application, by isolating the load capacitance of each branch. <u>Figure 15</u> and <u>Figure 16</u> show alternate forms of bus multiplexing.

Similarly, the P82B715  $I^2C$ -bus extender, which is commonly used for line driver applications, provides a '10× impedance transformation' but does not isolate either side of the buffer. Figure 13 shows the PCA9521 used to isolate the bus loading due to the P82B715. This greatly simplifies calculation of the pull-ups, increases the total system loading capability in extender applications, will meet the Fast-mode release requirement (when PCA9521 and P82B715  $V_{CC}$ 's share a common supply), and ensures the 300 ns rise time requirement can easily be met even if the cable bus rise is relatively slow.

Buffers are intended to extend total system capacitance above 400 pF, so anticipate high capacitance on each side. When loading on one side is small, adding 47 pF is suggested to avoid any waveform ripple, should it occur.

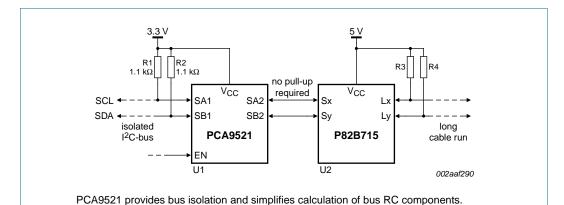


Fig 13. PCA9521 isolating the Standard-mode I<sup>2</sup>C-bus from a P82B715 used as a

line driver

#### Fast dual bidirectional bus buffer

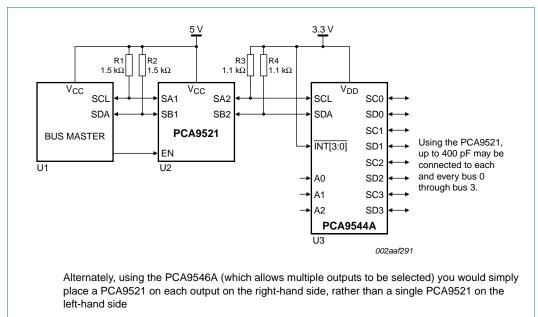
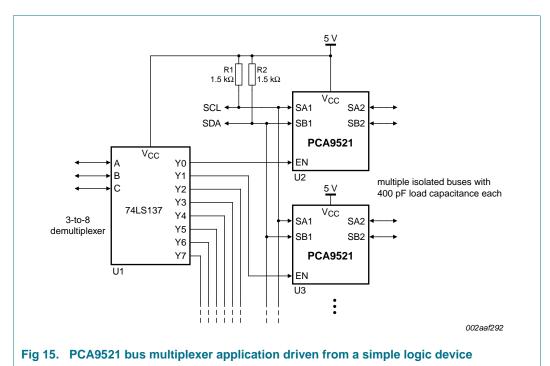
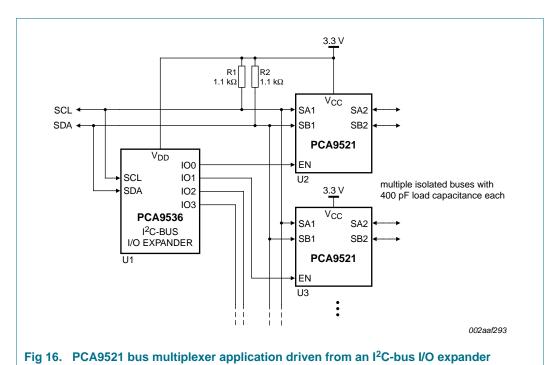


Fig 14. PCA9521 multiplexer isolation application



#### Fast dual bidirectional bus buffer



# 10.2 Input to output offset voltage calculation

The offset voltage between the side acting as the output (Sxx(out)) and the side acting as the input (Sxx(in)) of the PCA9521 can be calculated using the relationship given in Equation 1:

$$V_{offset} = V_i + 50 \ mV + \left(\frac{V_{BUS}}{R}\right) \times 11 \tag{1}$$

This calculation is valid for  $V_{bus(in)} \ge 200$  mV, as below this point the saturation voltage of the open-collector output drive transistor will begin to affect the characteristic. Input and output voltages are shown in millivolts,  $V_{BUS}$  (the supply voltage to the bus) is in volts, and R is in ohms.

An example calculation for  $V_{BUS} = 3.3 \text{ V}$ ,  $V_{SA1} = 200 \text{ mV}$ , the resistance R pulling up SA2 is 2 k $\Omega$ , then the voltage on SA2 is typically:

$$V_{SA2} = 200 \ mV + 50 \ mV + \left(\frac{3.3}{2000}\right) \times 11 = 268 \ mV$$
 (2)

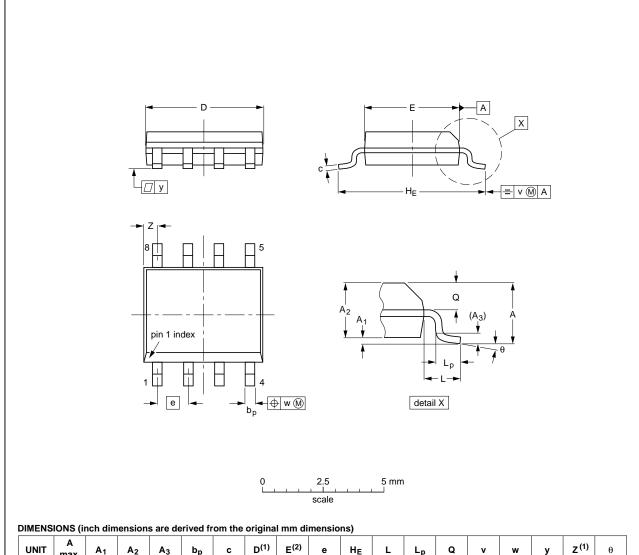
This can be compared with the offset characteristic shown in Figure 5.

### Fast dual bidirectional bus buffer

# 11. Package outline

### SO8: plastic small outline package; 8 leads; body width 3.9 mm

SOT96-1



UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	<b>A</b> <sub>3</sub>	bp	С	D <sup>(1)</sup>	E <sup>(2)</sup>	е	HE	L	Lp	Q	٧	w	у	z <sup>(1)</sup>	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	5.0 4.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
inches	0.069	0.010 0.004	0.057 0.049	0.01		0.0100 0.0075	0.20 0.19	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016		0.01	0.01	0.004	0.028 0.012	0°

#### Notes

- 1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.
- 2. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

OUTLINE		REFER	RENCES	EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE
SOT96-1	076E03	MS-012			<del>99-12-27</del> 03-02-18
001001	070200	100012			(

Fig 17. Package outline SOT96-1 (SO8)

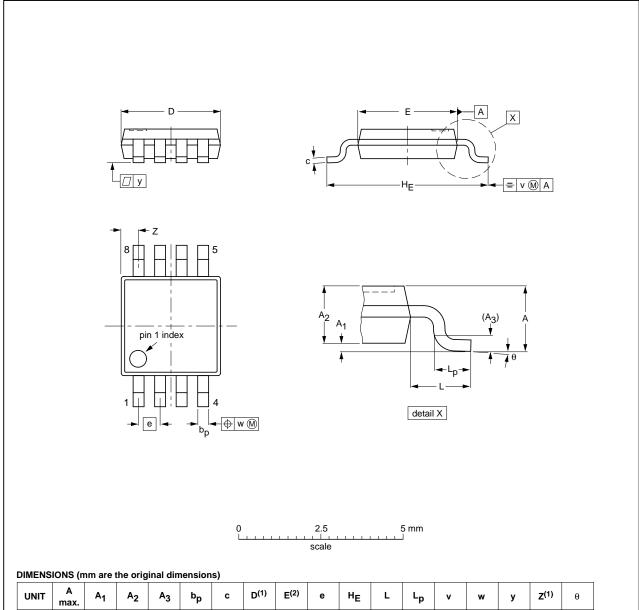
CA9521

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### TSSOP8: plastic thin shrink small outline package; 8 leads; body width 3 mm

SOT505-1



UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	bр	С	D <sup>(1)</sup>	E <sup>(2)</sup>	е	HE	L	Lp	v	w	у	Z <sup>(1)</sup>	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.45 0.25	0.28 0.15	3.1 2.9	3.1 2.9	0.65	5.1 4.7	0.94	0.7 0.4	0.1	0.1	0.1	0.70 0.35	6° 0°

#### Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	ENCES		EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	JEITA		PROJECTION	1330E DATE
SOT505-1						<del>-99-04-09</del> 03-02-18
	•	•		•		

Fig 18. Package outline SOT505-1 (TSSOP8)

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Fast dual bidirectional bus buffer

# 12. Handling information

#### **CAUTION**



This device is sensitive to ElectroStatic Discharge (ESD). Observe precautions for handling electrostatic sensitive devices.

Such precautions are described in the ANSI/ESD S20.20, IEC/ST 61340-5, JESD625-A or equivalent standards.

# 13. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365* "Surface mount reflow soldering description".

### 13.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

### 13.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- · Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

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#### Fast dual bidirectional bus buffer

### 13.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

### 13.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see <u>Figure 19</u>) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with <a href="Table 6">Table 6</a> and <a href="Table 6">Ta

Table 6. SnPb eutectic process (from J-STD-020D)

Package thickness (mm)	Package reflow temperature (°C)  Volume (mm³)					
	< 350	≥ 350				
< 2.5	235	220				
≥ 2.5	220	220				

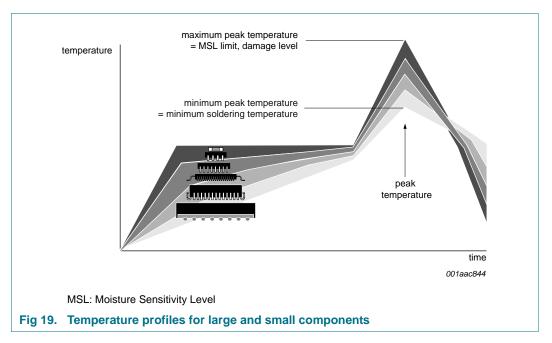
Table 7. Lead-free process (from J-STD-020D)

Package thickness (mm)	Package reflow temperature (°C)  Volume (mm³)							
	< 350	350 to 2000	> 2000					
< 1.6	260	260	260					
1.6 to 2.5	260	250	245					
> 2.5	250	245	245					

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

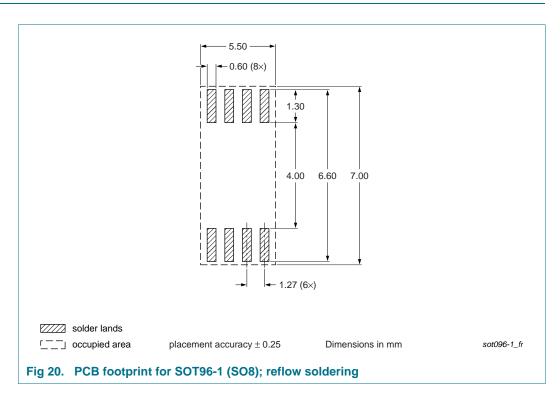
Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 19.

#### Fast dual bidirectional bus buffer

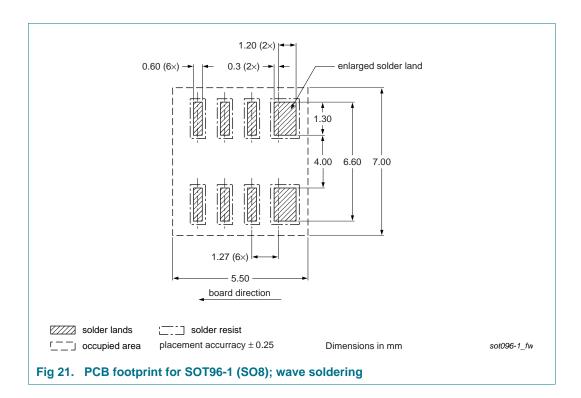


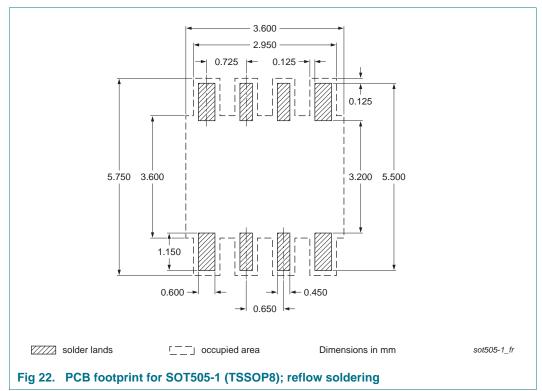
For further information on temperature profiles, refer to Application Note *AN10365* "Surface mount reflow soldering description".

# 14. Soldering: PCB footprints



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# 15. Abbreviations

Table 8. Abbreviations

Acronym	Description
ATCA	Advanced Telecommunications Computing Architecture
CDM	Charged-Device Model
cPCI	compact Peripheral Component Interconnect
ESD	ElectroStatic Discharge
HBM	Human Body Model
I <sup>2</sup> C-bus	Inter-Integrated Circuit bus
IC	Integrated Circuit
IPMB	Intelligent Platform Management Bus
PICMG	PCI Industrial Computer Manufacturers Group
PMBus	Power Management Bus
RAID	Redundant Array of Independent Discs
SMBus	System Management Bus

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# 16. Revision history

### Table 9. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes			
PCA9521 v.2	20130319	Product data sheet	-	PCA9521 v.1			
Modifications:	<ul> <li>Added <u>Secti</u></li> </ul>	on 4.1 "Ordering options"					
	• Table 5 "Cha	<ul> <li><u>Table 5 "Characteristics"</u>, sub-section "Power supply":</li> </ul>					
	<ul> <li>I<sub>CC</sub> Typ v</li> </ul>	<ul> <li>I<sub>CC</sub> Typ value (operating) changed from "9 mA" to "6 mA"</li> </ul>					
	<ul> <li>I<sub>CC</sub> Typ v</li> </ul>	<ul> <li>I<sub>CC</sub> Typ value (standby) changed from "295 μA" to "670 μA"</li> </ul>					
	– $I_{CC}$ Max value (standby) changed from "350 $\mu$ A" to "900 $\mu$ A"						
	<ul> <li><u>Table 5 "Characteristics"</u>, sub-section "Buffer ports (SA1, SA2, SB1, SB2)":</li> </ul>						
	<ul> <li>V<sub>Sxx</sub> Min value changed from "-" to "1.8 V"</li> </ul>						
	<ul> <li>I<sub>IL</sub> Typ va</li> </ul>	– $I_{IL}$ Typ value changed from "–12 $\mu A$ " to "–6 $\mu A$ "					
	<ul> <li>I<sub>IL</sub> Max va</li> </ul>	– $I_{IL}$ Max value changed from "–30 $\mu$ A" to "–20 $\mu$ A"					
	<ul> <li>V<sub>offset</sub> Co</li> </ul>	<ul> <li>V<sub>offset</sub> Condition changed from "V<sub>CC</sub> = 3.3 V" to "V<sub>CC</sub> = 5 V"</li> </ul>					
	<ul> <li>V<sub>offset</sub> (su</li> </ul>	<ul> <li>V<sub>offset</sub> (sub) Condition changed from "I<sub>OL</sub> = 4 mA" to "I<sub>OL</sub> = 5 mA"</li> </ul>					
		<ul> <li>V<sub>offset</sub> (Condition I<sub>OL</sub> = 5 mA): Typ value changed from "165 mV" to "230 mV"; Max value changed from "200 mV" to "300 mV"</li> </ul>					
		<ul> <li>V<sub>offset</sub> (Condition I<sub>OL</sub> = 500 μA): Typ value changed from "55 mV" to "90 mV";</li> <li>Max value changed from "100 mV" to "125 mV"</li> </ul>					
	<ul> <li>V<sub>offset</sub> (Condition I<sub>OL</sub> = 1.2 mA): Typ value changed from "60 mV" to "90 mV"; Max value changed from "100 mV" to "125 mV"</li> </ul>						
	Table 5 "Characteristics", sub-section "Enable (EN)":						
	<ul> <li>V<sub>en</sub> Min v</li> </ul>	<ul><li>V<sub>en</sub> Min value changed from "1.2 V" to "1.3 V"</li></ul>					
	<ul> <li>I<sub>I</sub> Min value changed from "1" to "0.7 μA"</li> </ul>						
	<ul> <li><u>Table 5 "Characteristics"</u>, sub-section "Timing characteristics":</li> </ul>						
	<ul> <li>t<sub>d</sub> Typ value changed from "30 ns" to "45 ns"</li> </ul>						
	<ul> <li>t<sub>f</sub> Typ value changed from "15 ns" to "40 ns"</li> </ul>						
	– $t_{d(en-act)}$ Typ value changed from "1 $\mu s$ " to "1.5 $\mu s$ "						
	– $t_{d(dis\text{-stb})}$ Typ value changed from "1.1 $\mu s$ " to "0.4 $\mu s$ "						
	<ul> <li>f<sub>oper(I2C)</sub> Max value changed from "400 kHz" to "1000 kHz"</li> </ul>						
	<ul> <li>deleted f<sub>oper(max)</sub> characteristic</li> </ul>						
	<ul> <li>Added <u>Secti</u></li> </ul>	on 14 "Soldering: PCB footp	rints"				
PCA9521 v.1	20110822	Product data sheet	-	-			

#### Fast dual bidirectional bus buffer

# 17. Legal information

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Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
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- [2] The term 'short data sheet' is explained in section "Definitions"
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