# **Dual PID auto tuning control**

### ■ Features

•Dual PID auto tuning function:

High-speed response of PID control to reach to the desired value fast, low-speed of response of PID control to minimize the overshoot even though response is a little bit slow.

- High display accuracy:±0.3% (by F S value of each input)
- •2-Steps auto tuning control function
- •Multi-input function(13 kinds of multi-input selection function):

Temperature sensor, voltage and current selection function.

- ●Various sub output function: Includes in LBA, SBA, 7kinds of alarm output and 4 kinds of alarm option function, PV transmission output(DC4-20mA), RS485 communication output
- •Display the decimal point for analog input

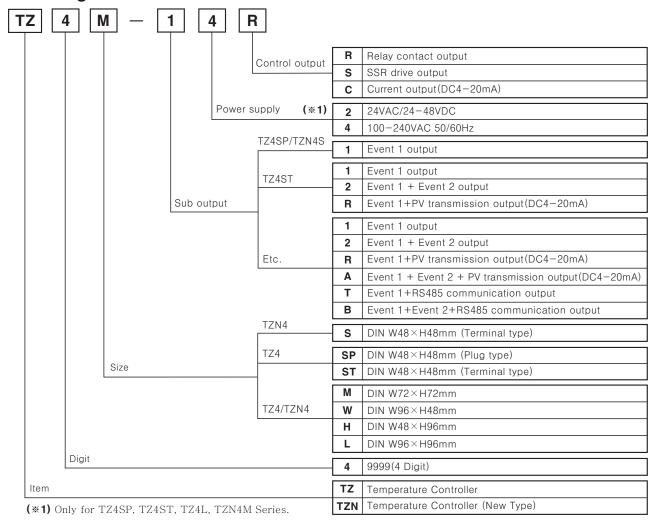




Please read "Caution for your safety" in operation manual before using.



## Ordering information



(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure

(F) Rotary encoder

(G) Connector/

(H) Temp. controller

(I) SSR/ Power controller

> (J) Counter

Timer

(∟)

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

Switching power supply

Stepping motor & Driver & Controller (R) Graphic/

Logic panel (S) Field network

(T) Production stoppage models & replacement

# **■**Specifications

Series		TZ4SP TZN4S	TZ4ST	TZ4M TZN4M	TZ4W TZN4W	TZ4H TZN4H	TZ4L TZN4L			
Power	supply	(★) 100-240VAC 50/60Hz, 24VAC 50/60Hz / 24-48VDC								
Allowal range	ble voltage			90 to 110% of	power supply					
Power c	consumption	Approx	x. 5VA	Approx. 6VA(Lo	w voltage type 🖙	AC:Approx. 8VA	, DC:Approx. 7W)			
Display	/ method	7Segn	nent LED Display	Process value	(PV) : Red, Setti	ng value(SV) : G	reenl			
Character size		<b>TZ4SP</b>	W4.8×H7.8mm	PV:W8×H13mm SV:W5×H9mm	W8×H10mm	<b>TZ4H</b>	PV:W9.8×H14.2mm SV:W8×H10mm			
	Thermocouple	K(CA), J(IC), R(PR), E(CR), T(CC), S(PR), N(NN), W(TT) <tolerance 100ω="" a="" is="" line="" max.="" of="" per="" resistance="" wire=""></tolerance>								
Input	RTD	Pt100Ω, JIS Pt100Ω, 3wire <tolerance 5ω="" a="" is="" line="" max.="" of="" per="" resistance="" wire=""></tolerance>								
	Analog		1-5VDC, 0-10VDC, DC4-20mA							
	Relay			<u> </u>	C 3A 1c					
Control	SSR				30mA Max.					
output	Current		DC	4-20mA (Resisti		),Q,)				
	Transmission				n: DC4-20mA I					
	EVENT 1				C 1A 1a	Zoad IIIax. 000 E				
Sub output	EVENT 2			200 111	250VAC 1A 1a					
	Communi -cation					mission, SV setti	ng)			
Contro	l method			N/OFF control P	DI DU DIDE DI	DS				
	/ accuracy	ON/OFF control P, PI, PD, PIDF, PIDS  F.S ± 0.3% or 3°C (Higher one)								
Setting	-	Front push buttons								
Hystere			Adiustable	1 to 100℃ (0.1 to		/OFF control				
Alarm of hystere	output	Adjustable ON/OFF 1 to 100 (0.1 to 100.0) °C of alarm output								
Propor band(F		0.0 to 100.0%								
Intergra	al time(I)	0 to 3600sec.								
Derivat	tive time(D)	0 to 3600sec.								
Contro	I time(T)	1 to 120sec.								
Sampli	ng period	0.5sec.								
LBA se	etting	1 to 999sec.								
RAMP	setting	Ramp Up, Ramp Down at 1 to 99min.								
Dielect	ric strength			2000VAC 50/	60Hz for 1min.					
Vibratio	on	0.75mm	amplitude at freq	uency of 10 to 55	Hz in each of X.	Y, Z directions fo	or 2 hours			
Relay	Main output									
	e Sub output	Mechanical: Min. 10,000,000 times, Electrical: Min. 100,000 times (250VAC 3A resistive load)  Mechanical: Min. 20,000,000 times, Electrical: Min. 300,000 times (250VAC 1A resistive load)								
	on resistance			Min. 100MΩ (at			•			
Noise		Square shaped noise by noise simulator (pulse width $1\mu$ s) $\pm 2kV$								
Memor	y protection			(When using non			)			
Ambier temper	nt			·10 to 50°C (at no						
Storage temperature		-20 to 60℃ (at non-freezing status)								
	nt humidity				35%RH	/				
Approv	-			€	c <b>FL</b> us					
Unit we		TZ4SP: Approx. 136g TZN4S: Approx. 150g	Approx. 136g	Approx. 270g	TZ4W: Approx. 270g TZN4W: Approx. 259g	Approx. 259g	Approx. 360g			

 $\mbox{\ensuremath{\%}($\star$)}\mbox{Low voltage}$  is only for TZ4SP, TZ4ST, TZ4L, TZN4M series.

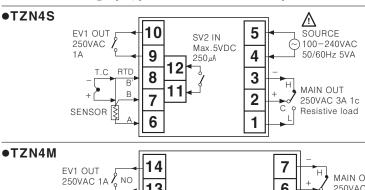
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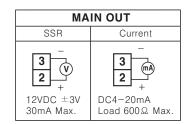
## Connections

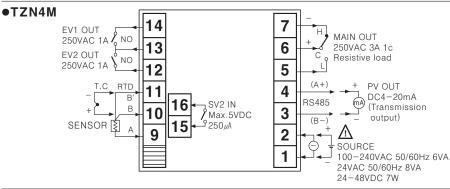
※RTD(Resistance Temperature Detector): DIN Pt 100Ω(3-wire type), JIS Pt 100Ω(3-wire type)

\*T.C(Thermocouple): K, J, R, E, T, S, W, N

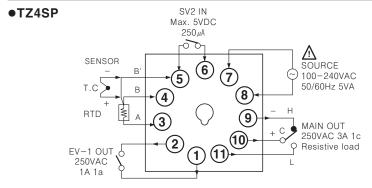
\*In case of Analog input, please use T.C(Thermocouple) terminal and be careful about polarity.



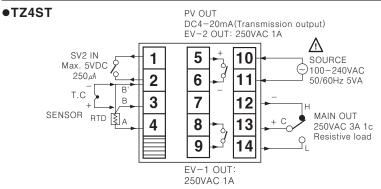




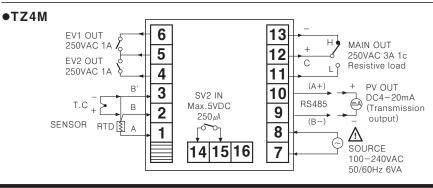
MA	MAIN OUT					
SSR	Current					
7 6 +	7 mA					
12VDC ±3V 30mA Max.	DC4-20mA Load 600Ω Max.					



MAIN OUT					
SSR	Current				
9	9 - 10 +				
12VDC ±3V 30mA Max.	DC4-20mA Load 600Ω Max.				



MA	SUB OUT	
SSR	Current	PV transmission output
12 -	12 13 +	5 mA
12VDC ±3V 30mA Max.	DC4-20mA Load 600Ω Max.	DC4-20mA Load 600Ω Max.



MAIN OUT					
SSR	Current				
13 12 +	13 mA				
12VDC $\pm$ 3V 30mA Max.	DC4-20mA Load 600Ω Max.				

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L)

Panel meter (M) Tacho/

Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

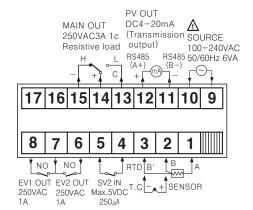
(Q) Stepping motor & Driver & Controller

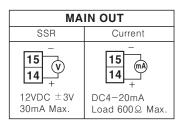
(R) Graphic/ Logic panel

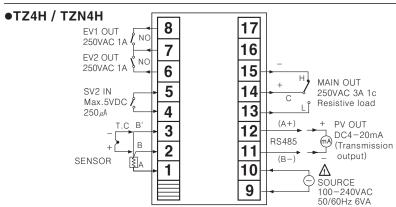
(S) Field network device

(T) Production stoppage models & replacement

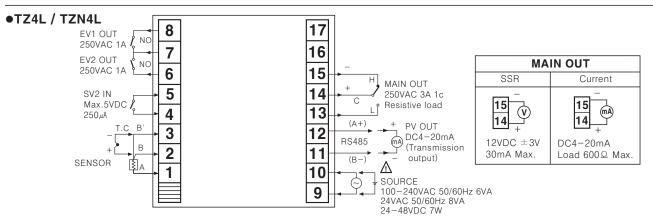






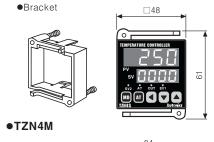


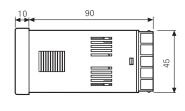
MA	IN OUT
SSR	Current
15 14 +	15 14 +
12VDC $\pm$ 3V 30mA Max.	DC4-20mA Load 600Ω Max.

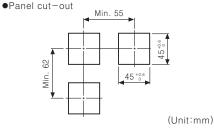


## Dimensions

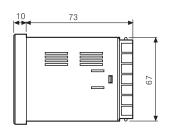


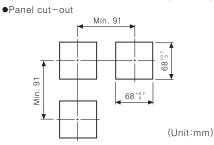




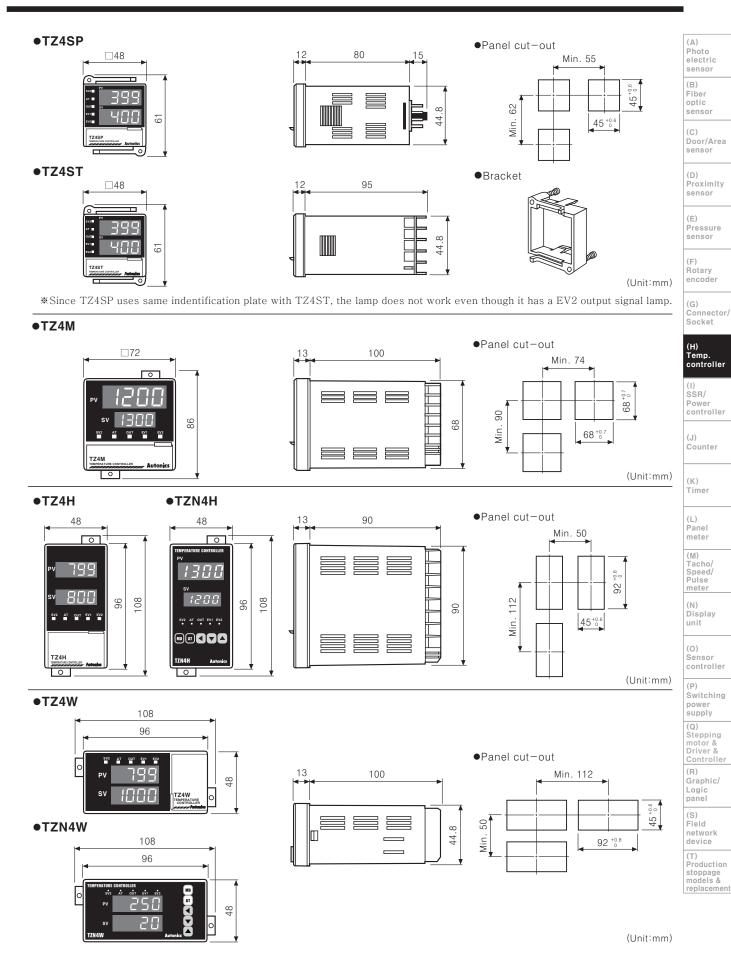






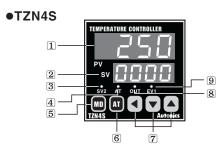


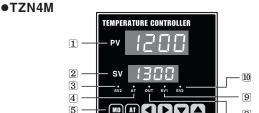
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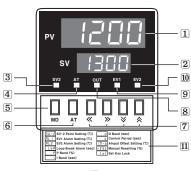
# Panel cut—out Panel cut—out | Panel cut—out

# ■ Front panel identification





●TZ4M



1 : Display Processing value(Red)

2 : Display Setting value(Green)

3 : Indicate SV2 operation

4: Indicate Autotuning operation

5 : Mode key

6 : Autotuning operation key

 ${f 7}$  : Setting keys

8: Indicate control output operation

9: Indicate EVENT 1 output

10: Indicate EVENT 2 output

11 : Procedure of setting key

\*\*Since TZ4SP uses same identification plate with TZ4ST, the lamp does not work even though it has a EV2 output signal lamp.

\*\*There are no(𝐎, ▶) Key in TZ4SP/TZ4ST/TZ4H/TZ4W and TZN4S/TZN4H/TZN4W.

\*\*Control output indicator(OUT) does not work when it is used as current output type.

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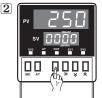
# ■How to set and change the setting value(SV)



In case of changing the setting value at status of RUN, push («) key.

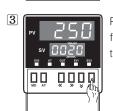
10° digit will flash at SV.





Push  $\P(\ll)$  key, and then the flash will be shifted step by step.





Push ▼ (♥), ▲ (♠) at the flash digit, and then change the setting value.



Push MD key when the setting is completed. It will stop flashing, then return to **RUN** mode.

\*\*Above explanations are the example of TZ4M. In case of TZ series. Use the Key in brackets for setting (changing). There are no (>>, ) Key in TZN4S, TZ4SP and TZ4ST. It is not used for setting or changing the setting value.

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#### ■Flow chart for setting group 1 If press MD key for 3sec. This mode changes to first flow chart. RUN MD Set SV-2 value within input range for each sensor. (Setting value 2) MD Event 1 Setting value 10 Set alarm temperature in EV-1 within the rated using range of each sensor. MD **RL2** Event 2 Setting value Ш Set alarm temperature in EV-2 within the rated using range of each sensor. MD **LbR** Loop Break Alarm 999 Set monitoring time of loop break alarm within 0 to 999sec. MD Set Interval between ON and OFF for alarm output from 1 to 100℃ Alarm output hysteresis 2 (Decimal type : 0.1 to $100.0^{\circ}$ ). It is only displayed for temperature alarm output. MD Proportional Set Proportional band from 0.0 to 100.0%. ρ band If setting value P as 0.0, it will be ON/OFF control. MD Set Integral time from 0 to 3600 sec. Integral time If setting value I as 0 sec. This function will be OFF. It is not displayed when P is 0.0. (ON/OFF control) MD Set Derivative time from 0 to 3600 sec. **d** Derivative time If setting value D as 0 sec. This function will be OFF. It is not displayed when P is 0.0. (ON/OFF control) MD Set control period cycle from 1 to 120 sec. 201 Control time In case of SSR output, this value should be small. (Ex: 2sec.) MD When the ON/OFF control function used. **HY5** Hysteresis 2 Set Hysteresis from 1 to 100 ℃ (Decimal type: 0.1 to 100.0 ℃)

(Decimal type: -50.0 to 50.0℃) Set Manual reset value from 0.0 to 100.0% This is for P control only, not for PID.

Set Ramp rising-time from 1 to 99 min. RAMP falling
RAMP-down time

It is displayed when selecting Ramp function at setting group 2.

off Cancel the Lock function for OFF. **†** ¥ **☆** This function is for locking the setting value. on l (Available to operate AT key)

**↑**♥ ↓ 🌣 Select ON1, changing setting value in the setting group 1 and AT key in the front panel cannot be changed.

Set Ramp falling-time from 1 to 99 min.

Correct the error in input sensor from -49 to 50°C

by (♠), ▼ (♦) keys. After that if pressing MD key the DATA will be changed then display next mode.

XIt returns to RUN status in case of pressing MD key for 3sec. after setting all mode to change.

\*If no key touched for 60sec., it will return to RUN mode automatically.

XIf not to set related mode in setting group 2, AL I, ALZ, LbA, I, d, E, HYS, rESE, rAPU, rAPd mode will disappear and then jump to next mode.

# Factory defaults(Setting group 1)

MD

MD

MD

MD

MD

MD

οĹ

RAMP rising

Lock

Input bias

Manual reset

RAMP-up time

10-6

Mode	Setting value	Mode	Setting value	Mode	Setting value	Mode	Setting value
50-2	0	AHY5	5	Ł	50	rAPU	10
ALI	10	ρ	3,0	H Y 5	5	rRPd	10
BL5	10	1	0	1 n-b	0	LoC	oFF
LBR	<i>500</i>	d	0	r E S Ł	0.0		

Photo electric sensor

(B) sensor

Door/Area

(D) Proximity sensor

Pressure

encoder

Connector/ Socket

#### (H) Temp.

SSR/ Power controller

> (L) Counter

(K) Timer

(L) meter

Tacho/ Speed/ Pulse meter

(N) Display unit

Sensor controller

Switching power supply

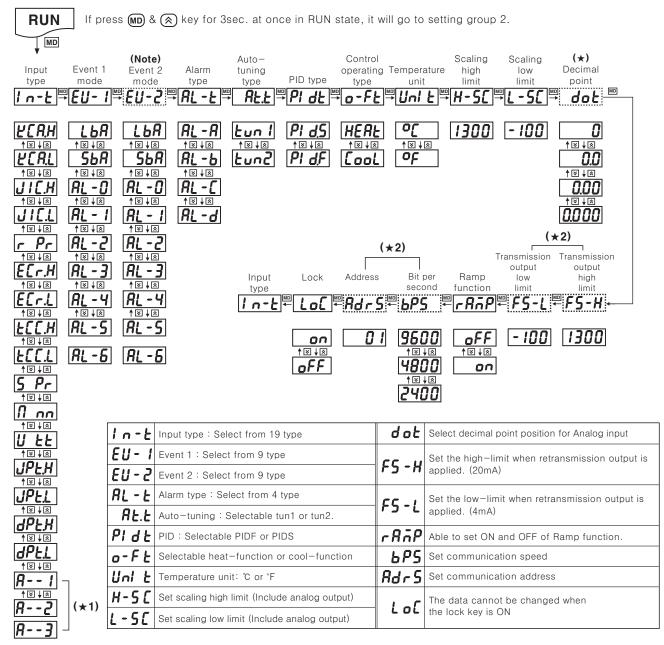
(Q) Stepping motor & Driver & Controlle

(R) Graphic/ Logic panel

(S) Field network device

Production stoppage models & replacement

# ■Flow chart for setting group 2



 $<sup>\</sup>Re$  It will start to flash by pressing  $\boxed{(\&)}$  key then select each mode by  $\boxed{(\&)}$ ,  $\boxed{(♥)}$  keys.

After that if press [MD] key, the DATA will be changed then display next mode.

# ■ Factory defaults (Setting group 2)

Mode	Setting value	Mode	Setting value	Mode	Setting value	Mode	Setting value
1 n - E	F.C. B.H	AL-F	AL-A	PI dE	P1 d.5	H-5[	1300
EU-1	AL-1	A F.F	tun!	o-Ft	HERE	L-5[	- 100
EU-2	BL-2	rRiP	off	Unle	٥٤	LoC	of F

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<sup>\*</sup>It returns to RUN status in case of pressing MD key for 3 sec. after setting all mode to change.

<sup>₩</sup>If no key is touched for 60sec. in each mode, it will return to RUN mode automatically.

<sup>\*\*</sup>ALI, ALZ, LbA, I, d, E, HY5, rE5E, rAPU, rAPd modes are not displayed depending on the result of setting group 1.2 and then jump to next mode.

<sup>※&</sup>quot;(★1)" is displayed only when input Sensor/Voltage/Current switch is voltage or current.

 $<sup>\</sup>mbox{\em $\tt \#$}"(\mbox{\em $\tt \#$}2)"$  is displayed only for model with High/Low-limit of transmission output.

# **■Input range for the sensor**

	Input se	ensor	Display	Selectable temperature range(°C)	Selectable temperature range(°F)
		K(CA) H	FC BH	−100 to 1300°C	−148 to 2372°F
		K(CA) L	FCUL	−100.0 to 999.9°C	This mode cannot be used as °F
		J(IC) H	J 15.H	0 to 800℃	32 to 1472°F
Thermocouple		J(IC) L	J IEL	0.0 to 800.0°C	This mode cannot be used as °F
		R(PR)	ר 6ר	0 to 1700℃	32 to 3092°F
		E(CR) H	EEr.H	0 to 800℃	32 to 1472°F
		E(CR) L	E C r.L	0.0 to 800.0℃	This mode cannot be used as °F
		T(CC) H	E C C.H	-200 to 400℃	−328 to 752°F
		T(CC) L	F C C.L	−199.9 to 400.0°C	This mode cannot be used as °F
		S(PR)	5 Pr	0 to 1700℃	32 to 3092°F
		N(NN)	N nn	0 to 1300℃	32 to 2372°F
		W(TT)	U FF	0 to 2300℃	32 to 4172°F
	JIS	JPt H	JPE.H	0 to 500℃	32 to 932°F
RTD	standard	JPt L	JPEL	−199.9 to 199.9°C	−199.9 to 391.8°F
טוא	DIN	DPt H	48F.H	0 to 500℃	32 to 932°F
	standard	DPt L	dPŁ.L	−199.9 to 199.9°C	−199.9 to 391.8°F
		0-10VDC	A!	−1999 to 9999°C	−1999 to 9999°F
Ana	log input	1-5VDC	A 5	-1999 to 9999℃	−1999 to 9999°F
		DC4-20mA	A 3	−1999 to 9999°C	−1999 to 9999°F

# ■ Selection switch for Input sensor/Voltage/Current

			, S(PR), N(NN), W(TT), DPt $100\Omega$ , JPt	
S/W1		顶	S/W2	
S/W1:1	1 1	mA V	S/W2:V	
<b>B)</b> In case of voltage inp	ut <1-5VDC, 0-10\	VDC>		
S/W1		1,1111	S/W2	
		m / \/	S/W2:V	
S/W1:2	2 2	mA V	0/ ** 2 . *	
S/W1:2		IIIA V	0/**2.*	
<b>C)</b> In case of current inp		IIIA V		
		IIIA V	S/W2	

\*\*Factory specification of Input sensor/Voltage/Current conversion switch: Temperature sensor input.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure

(F) Rotary encoder

(G) Connector/ Socket

#### (H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(∟)

Panel meter (M) Tacho/ Speed/ Pulse meter

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(R) Graphic/ Logic panel

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(T) Production stoppage models & replacement

 $<sup>\</sup>Re$  Please select **B)** or **C)** according to input specification when it is voltage or current.

## ■Alarm output function

This unit has output for control and sub(alarm) output. Sub output is optional. (This alarm output is relay contact(1a) and operates regardless of output for control.) Alarm output operates when the temperature of target is getting higher or lower than setting value.

- •1 alarm mode can be selected among 7 kinds of alarm mode at **EV-1(EV-2)** in the setting group 2.
- •Since **EV-1** and **EV-2** operate separately, both **EV-1** and **EV-2** can be used as a high or low 2nd alarm operation.
- ●When selecting LbA or 5bA function in EV-1(EV-2) of EV-1, alarm cannot be operated.
- •Please note below "Operation chart for alarm output" & "Option of alarm output" for detailed operation and optional operation.

# ■Operation chart for alarm output

AL -D		No alarm output.
AL - I	OFF b ON  A A SV PV  100°C 110°C  **When set 10°C in AL 1(AL 2) as deviation temperature	■Deviation High-limit alarm  If deviation between PV and SV is occurring higher than deviation of temperature setting value, the output will be ON. The deviation temperature is set in AL-1 or AL-2 of setting group 1.
AL-2	ON b OFF  A A A  PV SV  90°C 100°C  **When set 10°C in AL 1(AL 2) as deviation temperature	■Deviation Low-limit alarm  If deviation between PV and SV is occurring lower than deviation of temperature setting value, the output will be ON. The deviation temperature is set in AL-1 or AL-2 of setting group 1.
AL - 3	ON b OFF b ON  PV SV PV  90°C 100°C 110°C  **When set 10°C in AL 1(AL 2) as deviation temperature	■ Deviation High/Low-limit alarm  If deviation between PV and SV is higher or lower than deviation of temperature setting value, the output will be ON. The deviation temperature is set in AL-1 or AL-2 of setting group 1.
AL-4	OFF b ON b OFF  A A A A  PV SV PV  90°C 100°C 110°C  **When set 10°C in AL 1(AL 2) as deviation temperature	■ Deviation High/Low-limit reverse alarm If deviation between PV and SV is higher or lower than deviation of temperature setting value, the output will be OFF. The deviation temperature is set in AL-1 or AL-2 of setting group 1.
AL-5	OFF b ON  SV PV  100°C 110°C  **When set 110°C in AL 1(AL 2) as alarm temperature	■The absolute value High-limit alarm  If PV is equal or higher than alarm temperature setting value, the output will be ON.  The alarm temperature is set in AL-1 or AL-2 of setting group 1.
AL - 6	ON b OFF  PV SV 90°C 100°C  **When set 90°C in AL 1(AL 2) as alarm temperature	■The absolute value Low-limit alarm If PV is equal or lower than alarm temperature setting value, the output will be ON. The alarm temperature is set in AL-1 or AL-2 of setting group 1.

<sup>\*&</sup>quot;b" is interval between ON and OFF the setting range is 1 to 100% (0.1 to 100.0%) and can be set at "ЯНУ5" made in setting group 1.

## ■Alarm type setting [ AL - L ]

Symbol	Operation name	Function
AL-A	Standard alarm	Standard alarm output without option.
AL-P	Alarm latch	When alarm output turns on once, the output will be ON continuously.
AL -E	Standby sequence	It doesn't output at first operation. (When it reaches to first target value)
AL-9	Alarm latch and standby sequence	It operates alarm latch and standby sequence together.

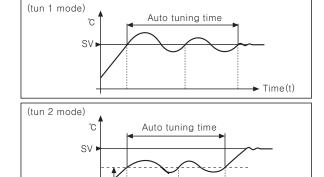
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## **■**Functions

### Auto tuning operation

PID auto tuning function automatically measures the thermal characteristics and response of the control system and then executes its value under high response & stability after calculating the time constant of PID required to control optimum temperature.

- •Execute the auto tuning function at initial time after connecting the controller & the sensor.
- •Execution of auto tuning is started when pressing AT key for 3sec. or more.
- •When the auto tuning is started, AT lamp will flash, and when the lamp is OFF, this operation will stop.
- •While the auto tuning function is executing, it is stopped by pressing AT key for 5sec. or more.
- •When the power turns off or the stop signal is applied while auto tuning function is executing, time constant of PID is not changed and it remembers the value before power turns off.
- Time constant of PID selected by auto tuning function can be changed in setting group 1.
- ●It has two kinds of auto tuning mode. auto tuning operation is executed at setting value(SV) in *EUn!* mode which is factory default. Auto tuning operation in *EUn?* mode is executed in 70% of setting value (SV). Mode change is available in setting group 2.



•Execute the auto tuning function again periodically, because the thermal characteristics for the control object can be changed when the controller is used continuously for a long time.

70% of SV

### OSub output(Event) function

Sub output can execute as main control output and sub function as well. There is one sub output in this unit.

- •This sub output is relay "1a" contact output.
- •1 mode can be selected among 7 kinds of alarm mode or LBA operated when the heater line is cut, SBA operated when the sensor line is cut.
- The Sub output can be latched ON or automatically reset depending on the alarm option mode selected.
- •When the sensor line or the heater line is cut, SBA or LBA output turns on. This "Output on" status must be reset by turning the power off.

#### OSensor Break Alarm(SBA) function

This function causes the sub output to turn on when the sensor line is cut or open.

It is easier to check that whether the sensor line is cut or not through buzzer or etc by exterior sub output (relay contact).

•Set SBA mode at Event1 or Event2 mode in setting group 2.

## **○Loop Break Alarm(LBA) function**

Ex) When setting value (SV) is 300°C, process value (PV) is 50°C, this unit controls 100%.

In this time if there is no change of system temperature, it recognizes Heater is cut off then

temperature, it recognizes Heater is c LBA output will be ON.

- •LBA output can be selected at EV1 of the setting group 2.
- •If LBA output is not selected at event output, it will not be displayed in setting group 1.
- •Setting range of LBA output is 1 to 999sec.
- •If thermal response of the control system is slow, LBA value should be set to a high value.
- •LBA output operates when the manipulated value of the controller is 0% and 100%.
- •In case the LBA output is ON, please check the following;
  - ①Short-circuit or cutting of the temp. sensor.
- ②Abnormal condition of the equipment (Magnet, sub -relay, etc.)
- ③Abnormal condition of the load (Heater, cooler)④Wrong-wiring or cutting of the other cables.
- •Once SBA is ON due to broken sensor, it will not reset, although sensor is connected. In this case, turn off the power then turn on again.

#### **©Error display**

➤ Time(t)

If error is occurred while the controller is operating, it will be displayed as follow.

- •"LLLL" is flashing when measured input temperature is lower than input range of the sensor.
- •"HHHH" is flashing when measured input temperature is higher than input range of the sensor.
- •"pPEn" is flashing when the input sensor is not connected or its wire is cut.

(A) Photo electric

(B) Fiber optic sensor

> (C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

#### (H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

meter
(M)
Tacho/
Speed/
Pulse

meter
(N)
Display

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

#### **ON/OFF** control

ON/OFF control is called two position control because the output turns on when PV falls lower than SV and the output turns off when PV is higher than SV.

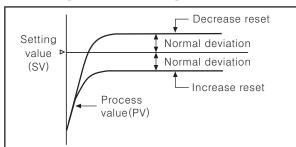
This control method is not only for controlling temperature, but also it is basic control method for sequence control.

- •If you set value P as "**QQ**" in setting group 1, ON/OFF control will operate.
- ●There is a programmable temperature difference between ON and OFF in ON/OFF control, if difference is too small, then hunting (chattering) can occur. Temperature difference can be set in Hy5 mode of setting group 1. Setting range is 1 to 100(or 0.1 to 100.0).
- •H**y5** mode is displayed when P value is "**QQ**", but **Hy5** will not be displayed, and then jump if P value is not "**QQ**".
- •This ON/OFF control should not be applied when equipment (Cooling compressor) to be controlled can be damaged by frequent ON and OFF.
- •Even if ON/OFF control is stable status, the hunting can be occurred by setting value in **HY5** or capacity of the heater or response characteristic of the equipment to be controlled or installing position of the sensor. Please consider above points to minimize the hunting when designing the system.

#### 

Proportional control has deviation because rising time is not same as falling time, even if the unit operates normally. Manual reset function is used at proportional control mode only.

- •If set **rE5k** function in setting group 1, the manual reset will run.
- •When PV and SV is equal, **rESt** value is 50.0% and when control is stable, if the temperature is lower than SV, **rESt** value should be higher and on the other hand, **rESt** value should be smaller.
- •rE5£ setting method according to result of control.



#### ODual PID control function

When controlling temperature, two types of control characteristic are available as below.

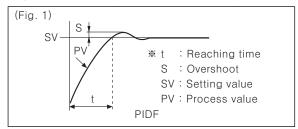
One is when you need to minimize the time which PV reaches to SV as like (Fig. 1). The other is when you need to minimize overshoot even though the reaching time (PV to SV) is slow (Fig. 2).

- •There are high-speed response type and lowspeed response type built in this unit.
  - Therefore user can select each function according to their application.
- •You can select dual PID control function in setting group 2. It is selectable **PI dF** or **PI d5** in **PI dE** mode.
- •PI dF (High-speed response type)

This mode is applied to machines or systems which require high-speed response.

Ex) Machines which must be applied preliminary heat before it operates

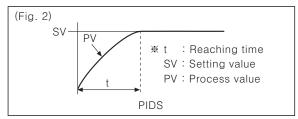
\*Injection machine, an electric furnace, etc.



#### ●PI d5(Low-speed response type)

It is PID Slow, used to minimize overshoot even though the response is slow.

For control temperature of oil, plating machine have a possibility of fire with overshoot, **Pl d5**(Limit over) should be used.



Factory default setting is PI d5.

Please select mode according to control system.

#### **○RS485** communication function

It is used on the purpose that transmitting PV to an external equipment, setting SV at the external equipment.

- •It can be set at **bP5**, **Adr5** in second setting group
- •Start bit(1bit, Fixed), Stop bit(1bit, Fixed), Parity bit(None)
- •**Adr5** setting: 1 to 99
- ●If the external equipment is a PC(Personal Computer) using RS232C to RS485 converter(SCM-38I) sold separately.

## ○Decimal point(dot) setting function

Decimal point is displayed as "dot" in second setting group when the input is analog only.

(0-10VDC, 1-5VDC, DC4-20mA)

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#### ○Cool/Heat function

Generally there are two ways to control temperature, one (Heat-function) is to heat when PV is getting down (Heater). The other (Cool-function) is to cool when PV is getting higher (Freezer).

These functions are operating oppositely when it is ON/OFF control or proportional control.

But in this case PID time constant will be different due to PID time constant will be decided according to control system when it is PID control.

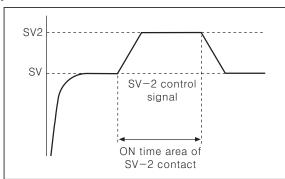
- •Cool-function and heat-function can be set at "Setting group 2".
- •Cool-function and heat-function must be set correctly according to the application, if set as opposite function, it may cause a fire.

(If set cool-function at heater, even if temperature is getting high, it will be maintained ON and it may cause a fire.)

- Avoid changing heat—function to cool—function or cool—function to heat—function on the unit is operating.
- •It is impossible to operate both function at once in this unit. Therefore, only one function should be selected only.
- Factory default setting is heat-function.

#### **OSV-2** function

If using SV-2 function, it changes the temperature of control system to the second setting value by external relay contact signal. It can change the setting value as sequentially by relay contact without key operation.



- ●It can set SV-2 at required time and particular area as like the above chart.
- $\bullet$ SV-2 is in setting group 1.
- Application :

The control system, which has to maintain constant temperature such as oven. If you open the door, temperature will go down.

In this case, if you set the second setting value higher than setting value, temperature will rise fast. Therefore, after installing a micro-switch in order to detect the door Open/Close and connect it to SV-2(the second setting value should be higher than SV) then it controls temperature of oven efficiently.

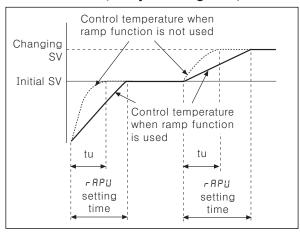
#### **ORamp function**

Ramp function is to delay the rising time or falling time of temperature. If you change setting value at stable state of control, it forces to rise or fall the temperature of control system during setting time at rAPU, rAPd in setting group 1.

If **rAnP** is not ON in setting group 2, **rAPU**, **rAPd** will not be displayed in setting group 1.

- •Set RAP is ON in setting group 2 for using ramp function.
- •Set the rising time and falling time at **rRPU** mode and **rRPd** mode of setting group 1.
- •Ramp function will be operating when changing the set value at stable control status or supply the power again after the power was removed.
- •The setting range of rising and falling time is 1 to 99 minute.

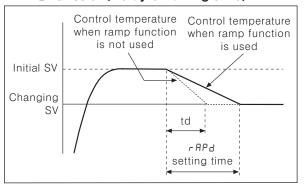
#### ※←APU function(Delay of rising time)



It makes delay rising temperature when change the set value at stable control status or delay the initial rising temperature as like above picture.

Note) rapu time cannot be shorter than rising time (tu) of temperature when Ramp function is not used.

#### ※r APd function(Delay of falling time)



It controls falling temperature as like above.

Note) rRPd time cannot be shorter than falling time

(td) of temperature when Ramp function is not used.

(A) Photo electric

(B) Fiber optic sensor

> (C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

#### (H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(∟)

meter
(M)
Tacho/

Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

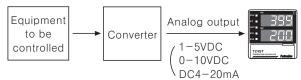
#### OInput bias(/ n-b) function

Input correction is to correct deviation occurred from temperature sensor such as thermocouples, RTD, Analog sensor etc. If you check the deviation of every temperature sensor precisely, it can measure temperature accurately.

- •Input revise can be set at "In-b" mode in setting group 1.
- •Use this mode after measuring deviation occurred from temperature sensor exactly.
- Because if measured deviation value is not corrected, displayed temperature may be too high or too low.
- •Setting range of input revise is -49 to  $50^{\circ}$  (-50.0 to  $50.0^{\circ}$ )
- •When you set the Input revise value, you may need to record it, because it will be useful when performing maintenance.

#### ○Analog input(A-1, A-2, A-3 mode)

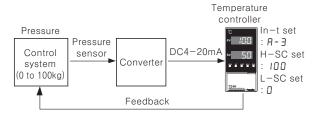
•In case of measuring or controlling humidity & pressure, flux, etc, it uses the proper converter which is converting the measuring value to DC4−20mA or 1−5VDC or 0−10VDC.



•In order to use the analog output of the converter as the controller input, select the input sensor, voltage/current converter switch built in the controller to be a same condition with analog output.

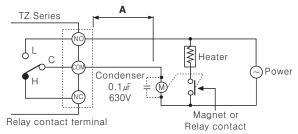
(This should be operated in power-off status.)

- •This unit has the mode for the converter built—in. Please select **R-** 1(0−10VDC) or **R-2**(1−5VDC) or **R-3**(DC4−20mA) in selection mode of input in setting group 2.
- •Set the input value by High scale (**H-5£**) and Low scale (**L-5£**) mode.
- •Please connect the analog output of the converter to the temperature sensor terminal of the controller. Please be cautious of the polarity.
- After the procedure, it is controlled same with temperature control.
- •Ex) After the procedure, it is controlled same with temperature control.



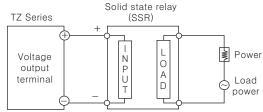
#### **Output** connections

Application of relay output type

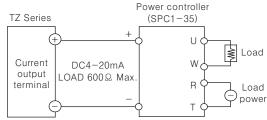


Keep power relay as far away as possible from TZ/TZN series. If wires length of **A** is short, electromotive force occurred from a coil of magnet switch & power relay may flow in power line of the unit, it may cause malfunction. If wires length of **A** is short, please connect a mylar condenser 104(630V) across coil of the power relay "\mathbb{\empty}" to protect electromotive force.

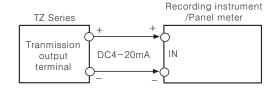
Application of SSR output type



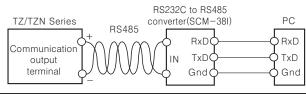
- \*\*SSR should be selected by the capacity of load, otherwise, it may short-circuit and result in a fire. Indirect heated should be used with SSR for efficient working.
- \*Please use a cooling plate or it may cause the capability deterioration, breakdown of SSR for a long usage.
- Application of current output(DC4-20mA)



- \*It is important to select SCR unit after checking the capacity of the load.
- \*If the capacity is exceeded, it may cause a fire.
- Application of transmission output(DC4-20mA)



Application of communication output (RS485)



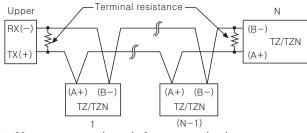
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# ■Communication output

#### OInterface

Standard	EIA RS485
Number of connections	Max. 31 units. It is available to set address 01 to 99.
Communication method	2 wire half duplex
Synchronous method	Asynchronous type
Communication distance	Within 1.2km
Communication speed	2400, 4800, 9600(Available to set)
Start bit	1bit(Fixed)
Stop bit	1bit(Fixed)
Parity bit	None
Data bit	8bit(Fixed)
Protocol	BCC

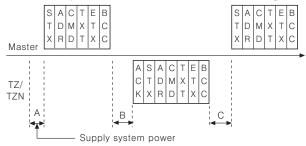
#### **OSystem ordering**



\*Use a proper twist pair for communication.

#### Communication control ordering

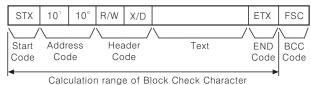
- 1. The communication control ordering of TZ/TZN series is exclusive protocol.
- 2. After 4sec. being supplied the power into master system, then able to start communicating.
- 3. Initial communication will be started by master system. When Command signal comes out from master system then TZ/TZN series will respond.



 $*A \rightarrow Over min. 4sec, B \rightarrow Within max. 300ms, C \rightarrow Over min. 20ms$ 

## **©Communication Command and Block**

Format of Command and Response



DStart code

It indicates the first of Block STX  $\rightarrow$  [02H], in case of response, ACK will be added.

②Address code

This code is master system can discern TZ/TZN series and able to set within range of 01 to 99. (BCD ASCII)

#### ③Header code :

It indicates command as 2 alphabets as below. RX(Read request)  $\rightarrow$  R[52H], X[58H] RD(Read response)  $\rightarrow$  R[52H], D[44H] WX(Write request)  $\rightarrow$  W[57H], R[58H] WD(Write response)  $\rightarrow$  W[57H], D[44H]

Text: It indicates the detail contents of Command/ Response. (See command)

⑤END code: It indicates the end of Block. ETX→[03H] ⑥BCC: It indicates XOR operating value from the first to ETX of the protocol as abbreviation of TZ/TZN.

### **OCommunication Command**

## ●Read[RX] of measurement/setting value : Address 01, Command RX

1. Command (Master)

(1)Command

;	STX	0	1	R X		Р	0	ETX	FSC
3	Start	Add	ress	Comr he:		P:Process S:Setting		End	всс

STX	0	1	R	Х	Р	0	ETX	FSC
02	30	31	52	58	50	30	03	всс

## Write[WX] of setting value : Address 01, Command WX

1. Command (Master)

①Command

STX	0	1	W	Χ	S	0	Symbol	10³	10 <sup>2</sup>	10¹	10°	ETX	FSC
Start	Add	Iress	Comr he	mand ad	S:Se val	tting ue	Space/-	10³	10²	10¹	10°	End	всс

②Application: In case of writing Address(01), Heading Coad(WX), Setting value(S) +123.

STX	0	1	W	Х	S	0	Symbol	10³	10²	10¹	10°	ETX	FSC
02	30	31	57	58	53	30	20	30	31	32	33	03	всс

#### **○Response**

#### Read of process/Setting value

1. In case of receiving normal process value: The data is transmitted adding ACK[60H]. (In case process value is ±123.4)

	(11)		400	- P	100			arac i		1 -	0.1	/				
A C K	S T X	0	1	R	D	Р	0	Symbol	10³	10²	10¹	10°	Decimal point	E T X	F S C	N U L L
A C K	S T X							Space			3	4	1	E T X	B C C	N U L L
06	06 02 30 31 52 44 50 30 20 31 32 33 34 31 03 C 00														00	
2.	2. In case process value is -100															

A C K	S T X	0	1	R	D	Р	0	_	0	1	0	0	0	E T X	B C C	N U L L
06	02	30	31	52	44	50	30	2D	30	31	30	30	30	03	ВСС	00

<sup>\*</sup>It is responded with 1 byte sized NULL(00H) at the end of response frame (next BCC 16).

(A) Photo electric

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

SSR/ Power controller

Counter

Timer (L)

(K)

(M) Tacho/ Speed/ Pulse meter

(N) Display

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

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(T) Production stoppage models & replacement

#### Write of setting value

In case setting value is -100

A C K	S T X	0	1	W	D	S	0	Symbol	10³	10²	10¹	10°	E T X	F S C
A C K	S T X	0	1	W	D	S	0	_	0	1	0	0	E T X	B C C
06	02	30	31	57	44	53	30	2D	30	31	30	30	03	ВСС

- Others: In case of no response of ACK
- ①When the address is not the same after receiving STX.
- 2When receiving buffer overflow is occurred.
- ③When the baud rate or others communication setting value are not the same.
- •When there are no ACK response
  - ①Check the status of lines
  - 2 Check the communication condition (Setting value)
  - When assuming the problem is due to noise, try to operate communication 3 times more until recovery.
  - When occurred communication failure frequently, please adjust the communicating speed.

## Proper usage

## **OSimple** "error" diagnosis

- ●In case, the load (Heater etc.) is not operated, please check operation of the out lamp located in front panel of the unit. If lamp does not operate, please check the parameter of all programmed mode. If lamp is operating, please check the output (Relay, Driving voltage of SSR, DC4−20mA current) after separating output line from the unit.
- But, the out lamp is not operated for DC4-20mA current output.
- ●When it displays "**PEn**" during operation.
- This is a warning that external sensor is cut off. Please turn off power and check the state of sensor. If sensor is not cut off, disconnect sensor line from terminal block and +, together. When you turn on power it can check room temperature.
- If this unit cannot indicate room temperature, this unit itself is faulty. Please remove this unit from equipment and service or replace.
- (When the input mode is thermocouple, it is available to indicate room temperature.)
- ●In case of indicating "Error" in display
  This Error message is indicated in case of damaging inner chip program data by outer strong noise.
  In this case, please send the unit to our after service center after removing the unit from system.
  Noise protection is designed in this unit, but it does not stand up strong noise continuously.
  If bigger noise than specified(Max. 2kV) flows in

the unit, it can be damaged.

## ■ Caution for using

- •Please use the terminal (M3.5, Max. 7.2mm) when connecting the AC power source.
- •"\(\Lambda\)" mark indicated on the diagram of this unit means caution—refer to accompanying documents.
- •In case of cleaning the unit, please keep as following Cautions:
- DClean dust with a dry tissue.
- ②Be sure to use alcohol to clean the unit, do not use acid, chromic acid, solvent, etc.
- ③Be sure to clean the unit after turning off the power and then turn on the power after passing 30minute after cleaning.
- •If this unit is used in a manner not to be specified by the manufacture, it can be injury to a person or damage to property.
- •Be sure that metal dust and wire-dregs do not flow in the unit, because of malfunction damage of the unit or the cause of a fire.
- •Service life for the relay of the unit is indicated in this manual, life cycle is different according to the load capacity and switching times, therfore please use the unit after checking the load capacity and switching times
- •Connect wires correctly after checking polarity of terminals.
- •Do not use this unit as following place.
- ①A place where dust, corrosive gas, oil, moisture are occurred.
- ②A place where there are high humidity or freezing place.
- 3A place where sunshine, radiant heat is occurred.
- A place where vibration, shock is occurred.
- •If the equipment is used in a manner not specified by the manufacture the protection provided by the equipment may be impaired.
- •Please install power switch or circuit-breaker in order to cut power supply off.
- •A switch or circuit-breaker meeting the relevant requirements of IEC947-1 and IEC947-3 shall be included in equipment when the temperature controller.
- •The switch or circuit—breaker should be installed near by users.
- Do not use this product as Volt-meter or Amperemeter, this is a temperature controller.
- •Installation environment
- ①It shall be used indoor
- ②Altitude Max. 2000m
- ③Pollution Degree 2
- ④Installation Category II.
- •If you want to change the input sensor, reset switches (SW1, SW2) according to each input specification after powe off. Turn on power and then set sensor mode by front keys at second flow chart.
- This SSR and current of this controller are insulate from internal power.
- •Do not connect power line to sensor connecting part. The inner circuit may be damaged.

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