

AK8778

Hall Effect IC for Pulse Encoders

Overview

The AK8778 is a Hall effect latch which detects both "vertical magnetic field" and "horizontal magnetic field" (perpendicular and parallel to the marking side of the package) at the same time. The pulse output F and direction output D are switched according to the vertical and horizontal magnetic fields applied to the device. The direction is calculated internally and output D is switched at a rising or falling edge of output F. The AK8778 is for use in the incremental pulse encoders or rotational detection systems.

Features

- \Box 4.0 to 24V supply voltage operation
- $\Box \quad Low power consumption : 1.4mA(Typ.)$
- $\square \quad Sensitivity (Vertical, Horizontal) : \pm 2.5 mT(Typ.)$
- $\Box \quad \text{Two outputs}: F (Pulse), D (Direction)$
- □ Small package: SOP-6pin
- □ Halogen free

Block Diagram

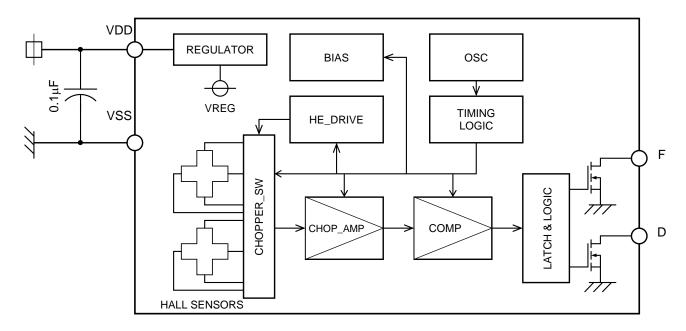


Figure 1. Block diagram

Circuit Configuration

Block	Function
REGULATOR	Generate internal operating voltage.
HALL SENSORS	Two Hall elements fabricated by CMOS process.
CHOPPER_SW	Perform chopping in order to cancel the offset of Hall sensor.
CHOP_AMP	Amplifies two Hall sensor output voltage with summation and subtraction circuit.
COMP	Hysteresis comparator.
BIAS	Generates bias current to internal circuits.
HE_DRIVE	Generates bias current for Hall sensors.
OSC	Generates operating clock.
TIMING LOGIC	Generates timing signal for internal circuits.
LATCH & LOGIC	Logical circuits and open drain driver.

Pin/Function

Table 2. Description of	f pin name and function
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Pin No.	Pin name	I/O	Function	Note
1	VDD		Power supply pin	
2	TAB		(TAB pin)	
3	F	0	Output F (Pulse) pin	Open drain
4	D	0	Output D (Direction) pin	Open drain
5	TAB		(TAB pin)	
6	VSS		Ground pin	

Note) TAB pins should be connected to VSS.

Absolute Maximum Ratings

Table 3. Absolute maximum ratings							
Parameter	Symbol	Min.	Max.	Unit	Note		
Supply voltage	V _{DD}	-0.3	+32	V	VSS=0V		
Output voltage	V _{OUT}	-0.3	+32	V	F,D pin VSS=0V		
Output current	I _{SINK}		20	mA	F,D pin		
Storage temperature	T _{STG}	-55	+150	°C			

Note) Stress beyond these listed values may cause permanent damage to the device.

Recommended Operating Conditions

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Parameter	Symbol	Min.	Тур.	Max.	Unit
Supply voltage	V _{DD}	4.0	12.0	24.0	V
Output current	I _{SINK}			15	mA
Operating temperature	Та	-40		+115	°C

Table 4. Recommended operating conditions

Electrical Characteristics

Table 5. Electrical characteristics at v_{DD} -4.0 to 24.0 v, Ta = -40 to +115 C						
Parameter	Symbol	Min.	Тур.	Max.	Unit	Note
Current consumption	I _{DD}	0.7	1.4	2.5	mA	Average
Output saturation voltage	V _{SAT}			0.4	V	F, D pin, I _{SINK} = 15mA
Output leak current	I _{LEAK}			10	μΑ	F, D=V _{DD}
Pulse drive period	T_{PD1}	24.4	48.8	97.6	μs	
Pulse drive duration time	T _{PD2}	12.2	24.4	48.8	US	

Table 5. Electrical characteristics at V_{DD} =4.0 to 24.0V, Ta=-40 to +115°C

Magnetic Characteristics

Table 6. Magnetic characteristics at V_{DD} =4.0 to 24.0V, Ta= -40 to +115°C

Parameter	Symbol	Min.	Тур.	Max.	Unit	Note
Operating point of vertical magnetic field	BopV	0.1	2.5	6.0	mT	(*1)
Releasing point of vertical magnetic field	BrpV	-6.0	-2.5	-0.1	mT	(*1)
Operating point of horizontal magnetic field	BopH	0.1	2.5	6.0	mT	(*2)
Operating point of horizontal magnetic field	BrpH	-6.0	-2.5	-0.1	mT	(*2)
Hysteresis	BhV, BhH		5.0		mT	(*1), (*2)

(*1) Horizontal magnetic flux density is zero.

(*2) Vertical magnetic flux density is zero.

Operational Characteristics

The internal signal A switches 'Low' state when the magnetic field perpendicular to the marking side of the package exceeds BopV. When the magnetic field is reduced below BrpV, the internal signal A goes 'High' state. Otherwise; that is, in case of the magnetic field strength is greater than BrpV and smaller than BopV; the internal signal A keeps its status.

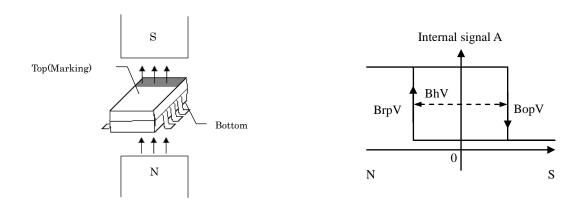


Figure 2. Switching behavior of the internal signal A when vertical magnetic field is applied

The internal signal B switches 'Low' state when the magnetic field parallel to the marking side of the package exceeds BopH. When the magnetic field is reduced below BrpH, the internal signal B goes 'High' state. Otherwise; that is, in case of the magnetic field strength is greater than BrpH and smaller than BopH; the internal signal B keeps its status.

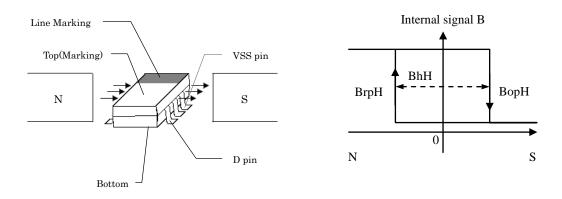
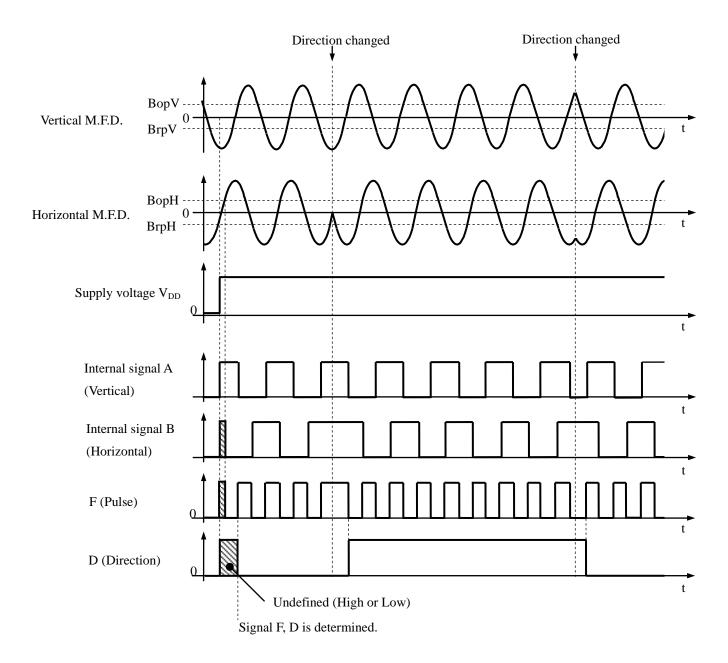
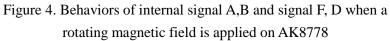


Figure 3. Switching behavior of the internal signal B when horizontal magnetic field is applied

Behaviors of internal signal A,B and output signal F, D when a rotating magnetic field is applied on AK8778

F signal (Pulse) is correspond to the result of EX-OR operation of internal signal A and B. And signal D (Direction) is calculated by the state of internal signal A and B.





*M.F.D. is Magnetic Flux Density.

Note) Signal D is determined after one signal F pulse is sent out. The indeterminate output state appears only in the powering up of this device.

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Functional Timing

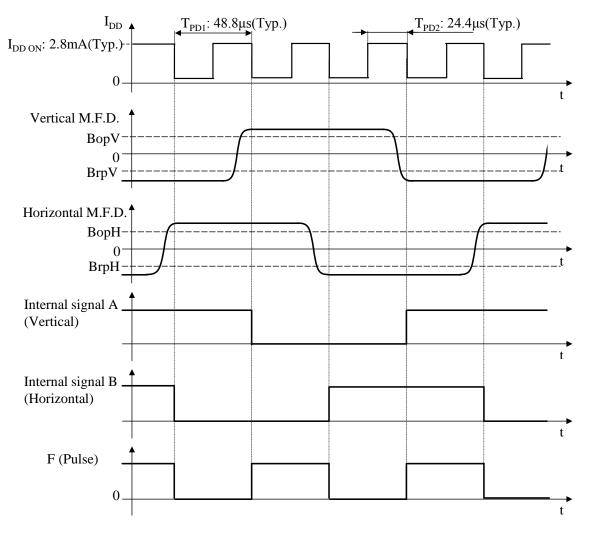


Figure 5. Timing diagram

*M.F.D. is Magnetic Flux Density.

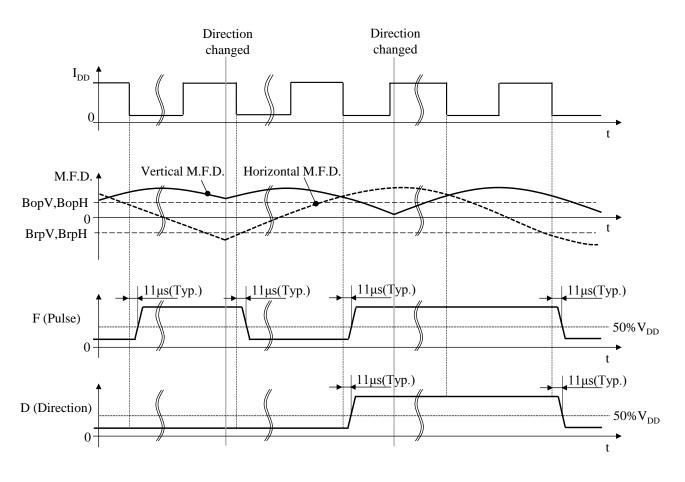
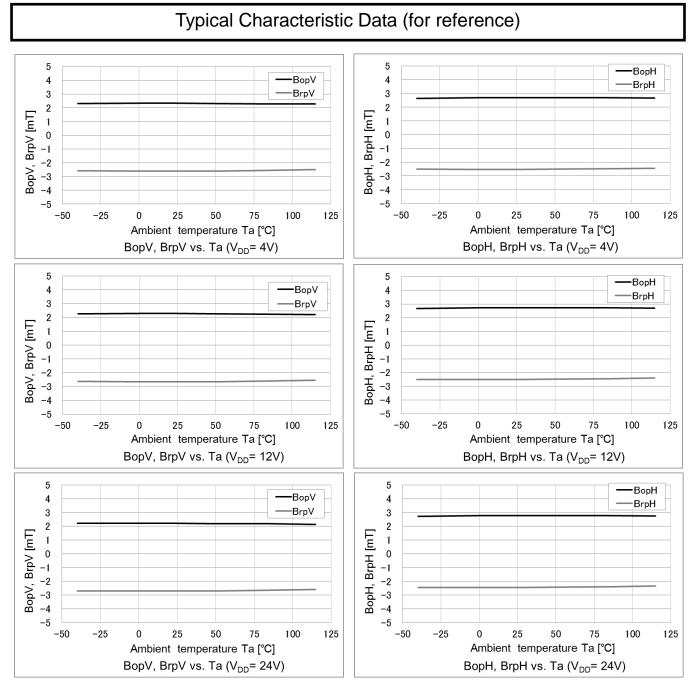


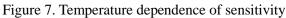
Figure 6. Timing diagram (in detail)

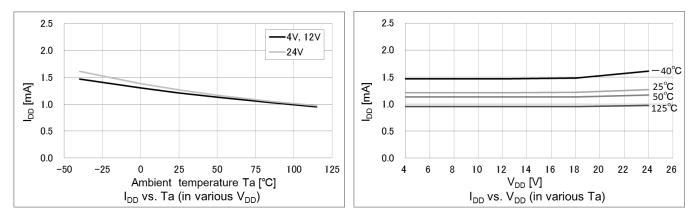
*M.F.D. is Magnetic Flux Density.

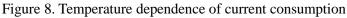
Note 1) V_{DD} =12.0V , R_L =10k Ω , C_L =20pF

Note 2) Signal F and D are changed at the same time.









Package

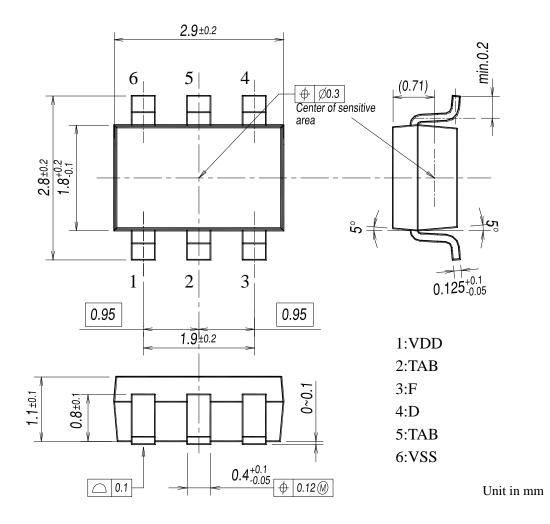


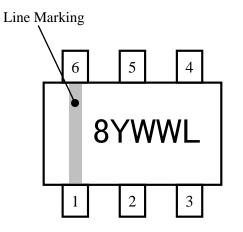
Figure 9. Package dimensions

Note 1) The center of the sensitive area is located within the $\phi 0.3$ mm circle.

Note 2) Coplanarity: The differences between standoff of terminals are max. 0.1mm.

Note 3) The sensor part is located 0.71mm(Typ.) from marking surface.

Material of terminals: Cu alloy Material of plating for terminals: Sn 100% Thickness of plating for terminals:10µm (Typ.) Marking



Marking is performed by laser Product name : 8 (AK8778) Date code : YWWL Y : Manufactured year WW : Manufactured week L : Lot

Figure 10. Marking



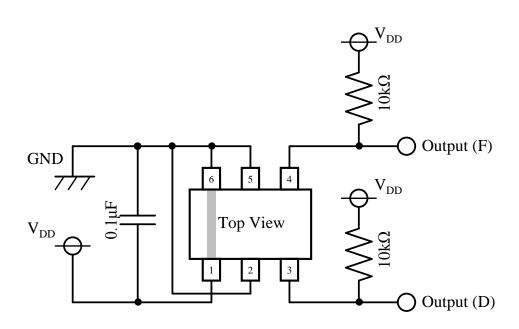


Figure 11. Recommended external circuit

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