mofaic

31,072 x 8 bit CMOS EEPROM

Semiconductor Inc.

Mosaic

Features

Fast Access Time of 120/150/200 ns.

Operating Power 275 mW max.

Standby Power 2.75mW max.

Software Data Protection.

Data Polling/Toggle bit.

Byte or Page Write Cycle: 5ms typical.

JEDEC Pinout.

High Density VIL™ Package.

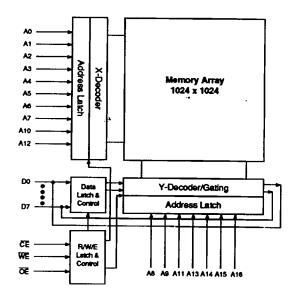
Data Retention > 10 years.

Endurance > 104 Write Cycles.

May be Processed In Accordance with

MIL-STD-883, Method 5004.

Block Diagram

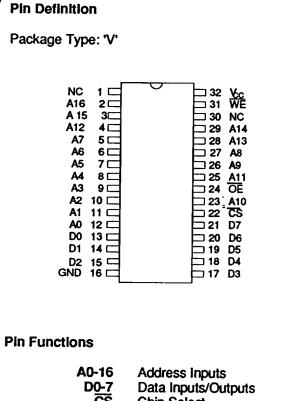


128K x 8 EEPROM

MEM8128-12/15/20

Issue 1.1: March 1993

ADVANCE PRODUCT INFORMATION



D0-7 Data Inputs/Output:

CS Chip Select
OE Output Enable
WE Write Enable
NC No Connect
V
COND Ground

Package Details (See package details section for details)

Pin Count Description Package Type Material Pin Out
32 100 mil Vertical-In-Line VIL™ Ceramic JEDEC

VIL is a Trademark of Mosaic Semiconductor Inc. US patent number D316251

Absolute Maximum Ratings

Voltage on any pin relative to GND	V_{τ}	-1.0 to +7.0	V
Power Dissipation	P <u>,</u>	1	W
Storage Temperature	T _{STG}	-65 to +150	∘ C
Temperature Under Bias	TRIAS	-65 to +135	℃

Notes: (1) Stresses above those listed may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

(2) V, can be -3.5V pulse of less than 20ns.

Recommended Operating Conditions

		min	typ	max	
Supply Voltage	V_{∞}	4.5	5.0	5.5	V
Input High Voltage	V _H	2.0	-	V _∞ +1	V
Input Low Voltage	V _{II}	-0.1	-	0.8	V
Operating Temperature	T _A	0	-	70	℃
	T _{AL}	-40	-	85	°C (MEM832I)
	TAM	-55	-	125	°C (MEM832M,MB)

DC Electrical Characteristics

Parameter	Symbol	Test Condition	min	max	Unit
Input Leakage Current		V _№ =GND to V _{CC}	-	10	μА
Output Leakage Current	الم	$\overline{\text{CS}}=V_{\text{HI}}, V_{\text{IO}}=\overline{\text{GND}}$ to V_{CC}	. •	10	μΑ
Average Current	l _{cc1}	I _{IO} =0mA, CS = OE =V _{IL} , WE =V _{IH} , f=5MHz	-	50	mA
Standby Current TTL	I ₅₈	CS=V _H , OE=V _K , I _{vo} =0mA	-	3	mA
Standby Current CMOS	l _{se1}	$\overline{CE} = V_{\infty} - 0.3V$, $\overline{OE} = V_{iL}$, $I_{iO} = 0$ mA	-	500	μА
Output Voltage	VoL	I _{oL} =2.1mA	-	0.4	٧
	V _{OH}	I _{OH} =-400 μA	2.4	-	V

Capacitance ($V_{\infty}=5V\pm10\%$, $T_{\bullet}=25$	°C.	. t=1MHz)	į
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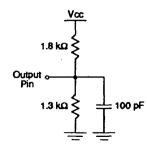
Parameter	Symbol	Test Condition	typ	max	Unit
Input Capacitance	C _{IN}	V _{IN} = 0V	-	10	pF
I/O Capacitance	C ^{ko}	$V_{WO}^{"}=0V$	-	10	pF

Note: This parameter is periodically sampled and not 100% tested.

AC Test Conditions

Output Test Load

- * Input pulse levels: 0V to 3.0V
- * Input rise and fall times: 10ns
- * Input and Output timing reference levels: 1.5V
- * Output load: 1 TTL gate + 100pF
- * V_{cc}=5V±10%



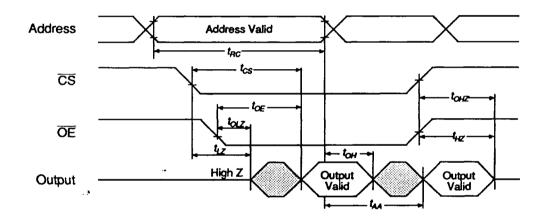
AC READ CHARACTERISTICS

Read	Cycle
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		-	12	-	15	-2	0		
Parameter	Symbol	min	max	min	max	min	max	Unit	Notes
Read Cycle Time	t _{RC}	120	-	150	-	200	-	ns	
Address Access Time	t _M	-	120	-	150	-	200	ns	
CS Access Time	tcs	-	120	-	150	-	200	ns	
OE Access Time	t _{oe}	0	50	0	50	0	50	ns	
CS, OE High to High Z Output	t _{HZ} ,t _{OHZ}	0	50	0	50	0	50	ns	(1)
CS, OE Low to Active Output	t _{ız} ,t _{oız}	0	-	0	-	0	-	ns	(1)
Output Hold from Address Change	t _{oH}	0	-	0	-	0	-	ns	, ,

Notes: (1) t_{tZ} max. and t_{otZ} max. are measured with CL = 5pF, from the point when CS or OE return high (whichever occurs first) to the time when the outputs are no longer driven. t_{tZ} and t_{otZ} are shown for reference only: they are characterized and not tested.

Read Cycle Timing Waveform

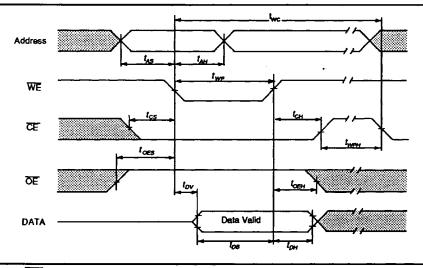


AC WRITE CHARACTERISTICS

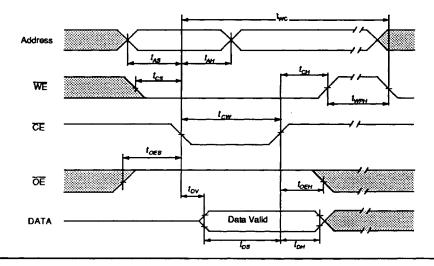
Write Cycle

Parameter	Symbol	min	typ	max	Unit
Write Cycle Time	t _{wc}	-	-	10	ms
Address Set-up Time	t _{AS}	0	-	-	ns
Address Hold Time	t _{AH}	50	-	-	ns
OE Set-up Time	t _{oes}	10	-	-	ns
OE Hold Time	t _{oeH}	10	-	-	ns
Chip Select Set-up Time	t _{cs}	0	-	-	ns
Chip Select Hold Time	t _{cH}	0	-	-	ns
Chip Select Pulse Width	tcw	100	-	-	ns
Write Pulse Width	t _{wp}	100	-	-	ns
WE High Recovery	t _{wpH}	100	-	-	ns
Data Set-up Time	t _{DS}	50	-	-	ns
Data Hold Time	t _{DH}	10	-	-	ns
Data Valid	t _{ov}	•	-	1	μs
Delay to Next Write	t _{ow}	10	-	-	μs
Byte Load Cycle	t _{BLC}	0.2	-	100	μs

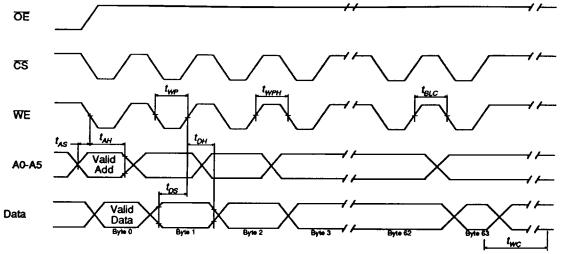
AC Write Waveform - WE Controlled



AC Write Waveform - CS Controlled

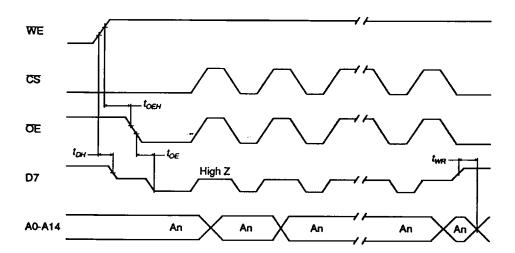


Page Mode Write Waveform

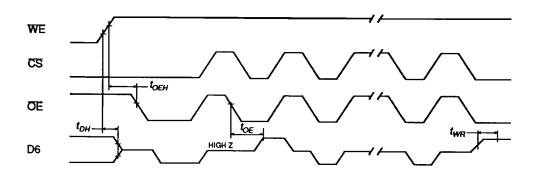


Note: A6 through A14 must specify the page address during each high to low transition of WE (or CE). OE must be high only when WE and CE are both low.

DATA Polling Waveform



Toggle Bit Waveform



Device Operation

Read

The MEM8128 read operations are initiated by both \overline{OE} and \overline{CS} LOW. The read operation is terminated by either \overline{CS} or \overline{OE} returning HIGH. This 2-line control architecture elimanates bus connection in a system environment. The data bus will be in a high impendence state when either \overline{OE} or \overline{CS} is HIGH.

Write

Write operations are initated when both \overline{CS} and \overline{WE} are LOW and \overline{OE} is HIGH. The MEM8128 supports both a \overline{CS} and \overline{WE} controlled write cycle. That is, the address is latched by the falling edge of either \overline{CS} or \overline{WE} , whichever occurs last. Similarly, the data is latched internally by the rising edge of either \overline{CS} or \overline{WE} , whichever occurs first. A byte write operation, once initiated, will automatically continue to completion, typically within 5 ms.

Page Mode Write

The page write feature of the MEM8128 allows the entire memory to be written in 5 seconds. Page Write allows 256 bytes of data to be written prior to the internal programming cycle. The host can fetch data from another location within the system during a page write operation (change the source address), but the page address (A6 through A16) for each subsequent valid write cycle to the part during this operation must be the same as the initial page address.

The page write mode can be initiated during any write operation. Following the initial byte write cycle, the host can write up to 256 bytes in the same manner as the first byte written. Each successive byte load cycle, started by the $\overline{\text{WE}}$ HIGH to LOW transition, must begin within 100 μ s of the falling edge of the preceding $\overline{\text{WE}}$. If a subsequent $\overline{\text{WE}}$ HIGH to LOW transition is not detected within 100 μ s, the internal automatic programming cycle will commence.

DATA Polling

The MEM8128 features DATA Polling to indicate if the write cycle is completed. During the internal programming cycle, any attempt to read the last byte written will produce the compliment of that data on D7. Once the programming is complete, D7 will refect the true data. Note: If the the MEM8128 is in a protected state and an illegal write operation is attempted DATA Polling will not operate.

TOGGLE bit

In addition to DATA polling, another method is provided to determine the end of a Write Cycle. During a write operation successive attempts to read data will result in D6 toggling between 1 and 0. Once a write is complete, this toggling will stop and valid data will be read.

Hardware Data Protection

The MEM8128 provides three harware features to protect nonvololitile data from inadvertent writes.

- Noise Protection A WE pulse less than 10 ns will not indicate a write cycle.
- * Default V_{∞} Sence All functions are inhabited when V_{∞} is \leq 3.6 V.
- Write Inhibit Holding either OE LOW, WE HIGH or CS HIGH will prevent an inadvertent write cycle during power-on power-off, maintaining data integrity.

Software Data Protection

The MEM8128 can be automatically protected during power-up and power-down without the need for external circuits by employing the software data protect feature. The internal software data protection circuit is enabled after the first write operation utilizing the software algorithm. This circuit is nonvolatile and will remain set for the life of the device unless the reset command is issued.

Once the software protection is enabled, the MEM8128 is also protected against inadvertent and accidental writes in that, the software algorithm must be issued prior to writing additional data to the device.

Software Algorithms

Selecting the software data protection mode requires the host system to precede datawrite operations by a series of three write operations to three specific addresses. The three byte sequence opens the page write window enabling the host to write from from 1 to 256 bytes of data. Once the page load cycle has been completed, the device will automatically be returned to the data protected state

Software Data Protection Algorithm

Regardless of wheather the device has been protected or not, once the software data protected aglorithm is used and the data is written, the MEM8128 will automatically disable further writes unless another command is issued to cancel it. If no further commands are issued the MEM8128 will be write protected during power-down and any subsequent power-up.



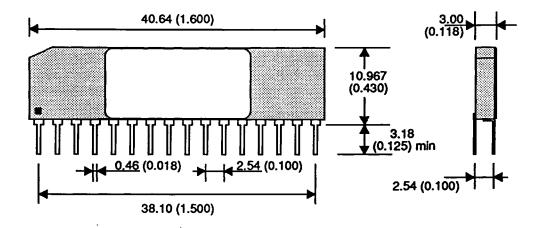
Software Data Protect Disable

In the event the user wants to deactivate the software data protection feature for testing or reprogramming in an E²PROM programmer. The following six step algorithm will reset the internal protection circuit. After $t_{\rm wc}$, the MEM8128 will be in standard operating mode.



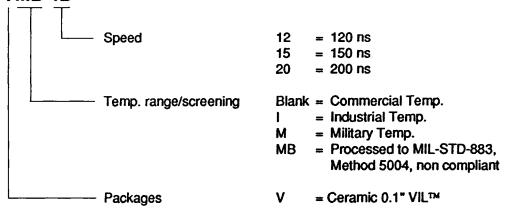
Package Details All dimensions in mm (inches). Tolerance on all dimensions +/- 0.254 (0.010).

32 Pin 0.1" Vertical-in Line (VIL™) "V"- Package



Ordering Information





Note: For more information regarding screening levels, contact Mosaic Semiconductor Inc. for a 'Screening Level Applications Note.'

The policy of the company is one of continuous development and while the information presented in this data sheet is believed to be accurate, no liability is assumed for any data contained within. The company reserves the right to make changes without notice at any time.



Semiconductor

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