

Analog Semiconductor IC

MRX1533L Series

Low power consumption, 1.5mT High sensitivity CMOS MR Magnetic Sensor Switch

(IMPORTANT: Please check the last page for Genuine Product Labeling)

Rev. E13-01

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Low power consumption, 1.5mT High sensitivity CMOS MR Magnet Sensor Switch

MRX1533L Series

GENERAL DESCRIPTIONS

MRX1533L series are monolithic ICs with built-in MR magnet resistive element and CMOS switch. It becomes the non-contact switch with low current consumption, high sensitivity and reliability which is combined with magnet. HALOGEN RoHS COMPLIANCE

A horizontal magnetic field parallel to the electrode of the package can be detected by an arbitrary polarity. (N pole \Leftrightarrow S pole)

FEATURES

- Detection pulse driving cycle Typ. 50msec with 25µsec width

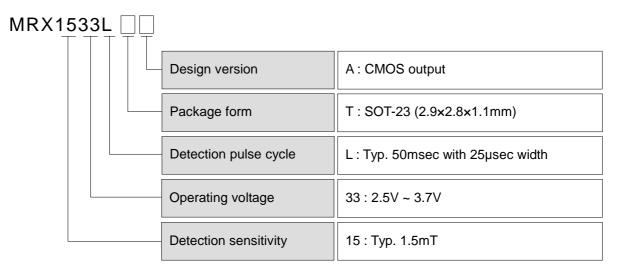
APPLICATIONS

- Detection of opening and closing : Mobile phone, Notebook PC, Microwave oven, Washing machine, Rice cooker, Refrigerator, Electronic dictionary, Digital camera, etc.
- Detection of position : Air cylinder, Antitheft window, Digital door lock, etc.
- Detection of water level : Water purifier, Humidifier, Bidet, etc.
- Detection of rotation : Water meter, Gas meter, Wattmeter, Speed meter, etc.
- Power supply switch : Cordless phone, Electric toothbrush, etc.

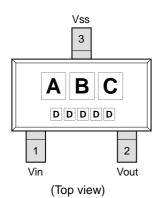
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PRODUCTS NUMBERING GUIDE



PIN CONFIGURATION / MARKING SPECIFICATION



Pin Configuration

No.	Symbol	Descriptions
1	Vin	Voltage input
2	Vout	Output
3	Vss	Power ground

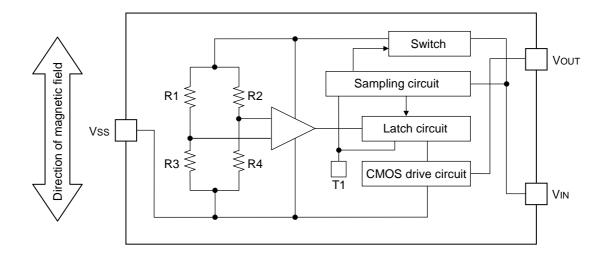
Marking Specification

	Code	Mark	Contents			
-	А	М	Series name			
-	BC	AA	Products specification & version			
-	D	Internal rule	Lot number			



MRX1533L Series

BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS

Items	Symbol	Min.	Тур.	Max.	Conditions	Unit
Operating temperature	TOPR	-40	-	+85		°C
Storage temperature	TSTG	-50	-	+125		°C
Supply voltage	VMAX	VIN-0.3	-	VIN+6.0		V
Assembly temp. condition	TASY	-	255	260	t=max:5sec/Tmax	°C

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ELECTRICAL CHARACTERISTICS

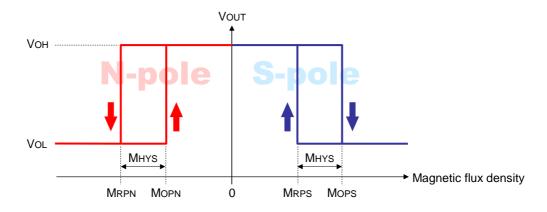
				(Unless otl	nerwise specified, VDD=3.3V, T	a=25°C)
Items	Symbol	Min.	Тур.	Max.	Conditions	Unit
Operating voltage	Vin	2.5	3.3	3.7		V
Current consumption	IAVG	-	3.0	5.0		μA
Detection pulse driving cycle	ts	-	50	90		msec
"H"-level output voltage	Vон	0.9Vin	-	-	IOUT=+1.0mA	V
"L"-level output voltage	Vol	-	-	0.1VIN	IOUT=-1.0mA	V

MAGNETIC CHARACTERISTICS

	(Ur	nless otherw	ise specified	, Vdd=3.3V, ⁻	Ta=25°C)
Items	Symbol	Min.	Тур.	Max.	Unit
Magnetic flux density at operating point (H \rightarrow L)	Mops	1.0 [*]	1.5	2.5	mT
Magnetic flux density at operating point ($\square \rightarrow L$)	Mopn	-2.5	-1.5	-1.0 [*]	
Magnetic flux density at release point (L \rightarrow H)	Mrps	0.7	1.2	2.2*	mT
Magnetic flux density at release point (L \rightarrow \square)	Mrpn	-2.2 [*]	-1.2	-0.8	
Width of hysteresis	MHYS	0.1 [*]	0.3	0.8 [*]	mT

Note : The values with [*] marks are guaranteed by design, not tested in production.

MAGNETIC-ELECTRIC CONVERSION CHARACTERISTIC



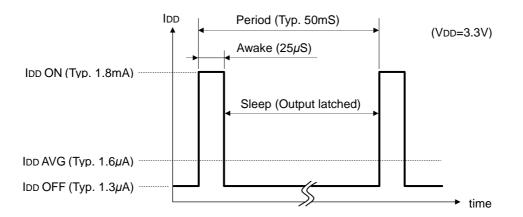
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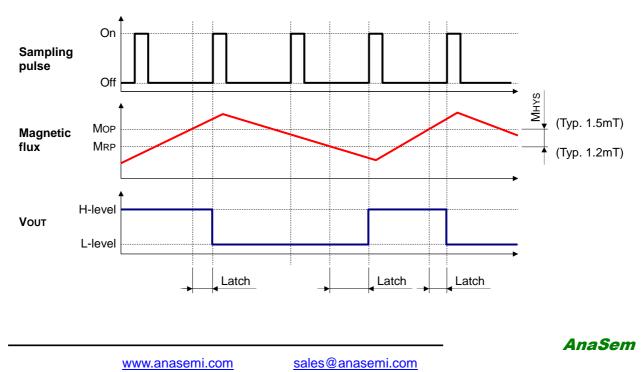
MAGNETIC FLUX DENSITY AND OUTPUT VOLTAGE LEVEL

Condition	Output loval	
Magnet & Power	Magnet flux density	Output level
Magnet = OFF / Power = ON	M = 0mT	High-level
Magnet = ON / Power = ON	$M \ge 2.5 mT$	Low-level
Magnet = OFF / Power = ON	$M \leq 0.7 mT$	High-level

DETECTION PULSE DRIVING CYCLE (SAMPLING CYCLE)

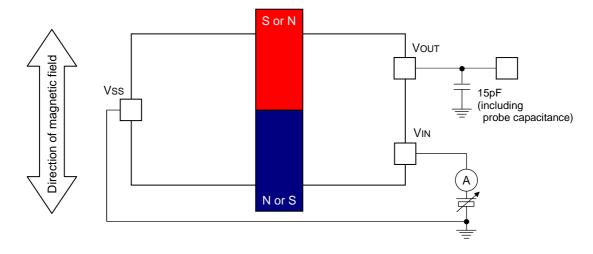


OUTPUT SWITCHING TIMING CHART

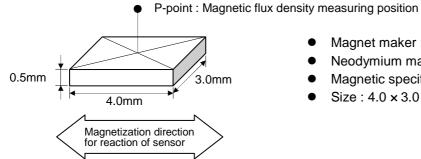


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TEST CIRCUIT



STANDARD MAGNET SPECIFICATIONS



- Magnet maker : TDK Corp. / Japan
 - Neodymium magnet
 - Magnetic specification : NE047BW
 - Size : 4.0 × 3.0 × 0.5mm

DETECTION DISTANCE SIMULATION (with standard magnet)

- Vertical direction (VD) Horizontal direction (HD) (HD = 0mm) Standard magnet Detection point of sensor Magnetic flux density (mT) Magnetic flux density (mT) ----- 1.5mT 14 16 Vertical distance (mm)
 - (VD = 3mm) Standard magnet Detection point of sensor

 Horizontal distance (mm)



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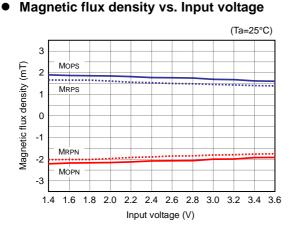
1.5mT

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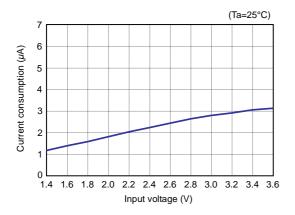
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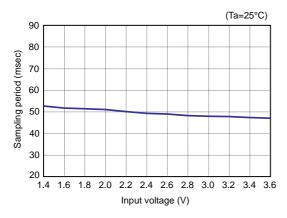
TYPICAL ELECTRIC CHARACTERISTICS



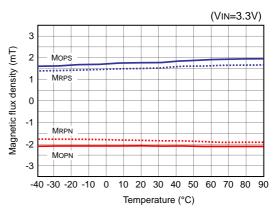
• Current consumption vs. Input voltage





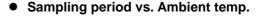


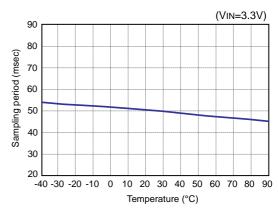
• Magnetic flux density vs. Ambient temp.



(VIN=3.3V) 7 6 5 4 3 2 1 0 -40 -30 -20 -10 0 10 20 30 40 50 60 70 80 90 Temperature (°C)

• Current consumption vs. Ambient temp.







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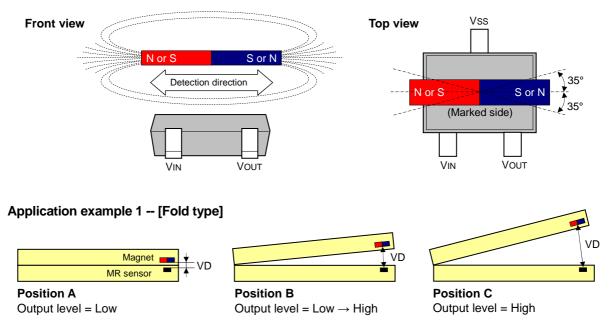
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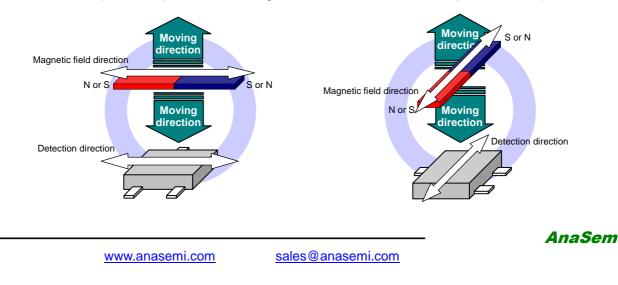
APPLICATION INFORMATIONS

• Detection of magnetic field

To operate output switch, the magnetic field should be applied to the sensor with sufficient magnetic flux density and correct direction. MR series are designed to be ON-state (L-level output) when the horizontal direction magnetic field is applied in parallel to the marked side of sensor, with sufficient magnetic flux (MOPS or MOPN value) regardless of polarity of magnet. Because MR series detect the horizontal direction magnetic field, it has not influence of the reverse-magnetic field. And also, MR series detect the vertical direction magnetic field according to the level of magnetic flux, so that it is possible to apply to not only slide type but also fold type.

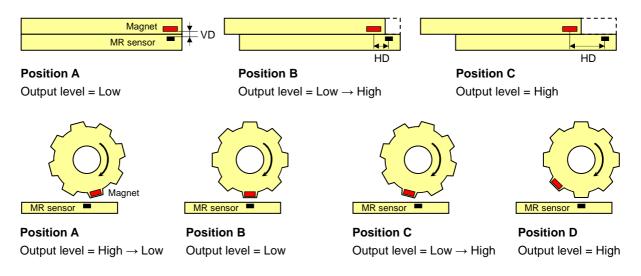


In case MR series is used for fold type cellular phone, IC sense the conditions of opening and shutting of the cover by detection of the magnetic flux according to the distance between IC and magnet. In position A, output is L-level (ON-state) because the detected magnetic flux is sufficient. The magnetic flux decrease according to the magnet is moved from IC (Position $A \rightarrow B$). Then the IC is turned H-level (OFF-state) because the magnetic flux become MRP or less (Position $B \rightarrow C$).



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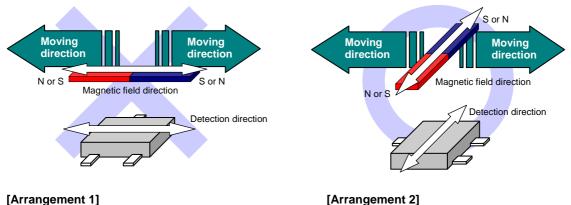
• Application example 2 -- [Slide type & Rotary type]



In the detection of the slide type, there are two ways of arrangement of magnetic field detecting direction against moving direction. One is parallel and another is cross with moving direction.

In case of parallel positioning of magnetic field with moving direction [arrangement 1], the output of IC might be L-level (ON-state) \rightarrow H-level (OFF-state) \rightarrow L-level (ON-state) \rightarrow H-level (OFF-state) due to reverse-magnetic field.

To prevent from this malfunction, it is recommended to arrange the detection direction of sensor and magnetic field to be crossed with moving direction of cover [arrangement 2].



Parallel the direction of detection magnetic field with the moving direction

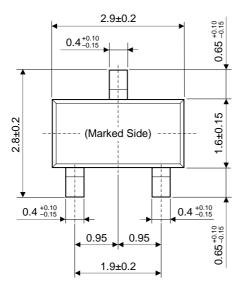
[Arrangement 2] Cross the direction of detection magnetic field with the moving direction

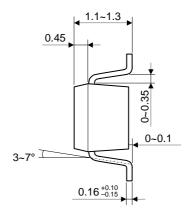
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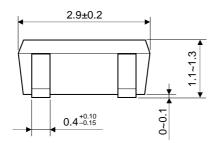
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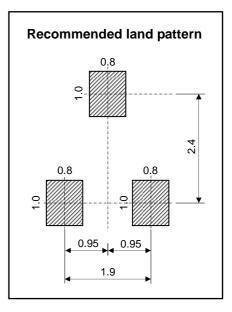
PACKAGE DIMENSIONS (SOT-23)







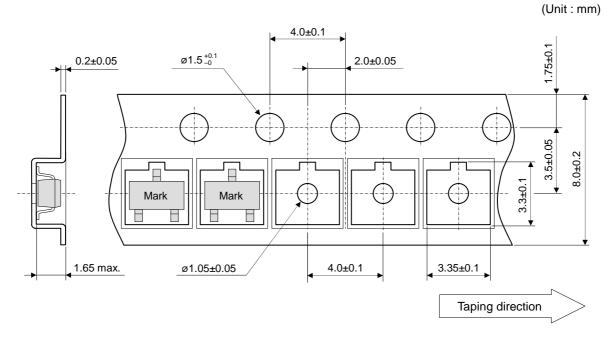




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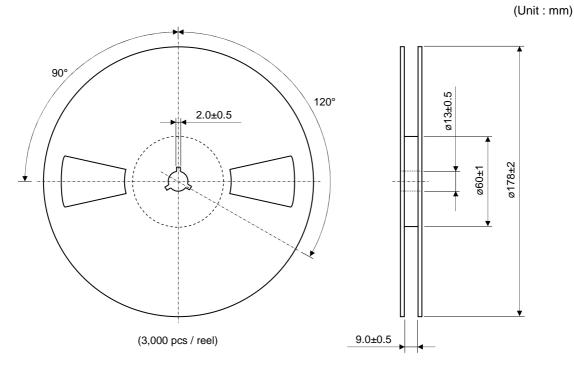
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TAPING AND LOADING SPECIFICATIONS (SOT-23)



REEL DIMENSIONS (SOT-23)

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