# 18Mb DDRII+ SRAM Specification

## 165 FBGA with Pb & Pb-Free (RoHS compliant)

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## **Document Title**

#### 512Kx36-bit, 1Mx18-bit DDR™ II+ CIO b2 SRAM

#### **Revision History**

Rev. No.	<u>History</u>	Draft Date	<u>Remark</u>
1.0	1. First release	Aug. 28, 2008	Final
1.1	1. Corrected the Timing Diagram of CL2.5 on page.15 2. Corrected Package Dimensions on page.19	Aug. 10, 2010	Final

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## 512Kx36-bit, 1Mx18-bit DDRII CIO b2 SRAM

#### **FEATURES**

- 1.8V+0.1V/-0.1V Power Supply.
- DLL circuitry for wide output data valid window and future freguency scaling.
- I/O Supply Voltage 1.5V+0.1V/-0.1V
- · Pipelined, double-data rate operation.
- · Common data input/output bus .
- HSTL I/O
- Full data coherency, providing most current data.
- · Synchronous pipeline read with self timed late write.
- · Read latency : 2.5 clock cycles
- · Registered address, control and data input/output.
- DDR(Double Data Rate) Interface on read and write ports.
- Fixed 2-bit burst for both read and write operation.
- · Clock-stop supports to reduce current.
- Two input clocks(K and  $\overline{K}$ ) for accurate DDR timing at clock rising edges only.
- Two echo clocks (CQ and  $\overline{CQ}$ ) to enhance output data traceability.
- Data Valid pin(QVLD) supported
- · Single address bus.
- Byte write (x18, x36) function.
- Simple depth expansion with no data contention.
- Programmable output impedance(ZQ).
- JTAG 1149.1 compatible test access port.
- 165FBGA(11x15 ball aray FBGA) with body size of 15x17mm

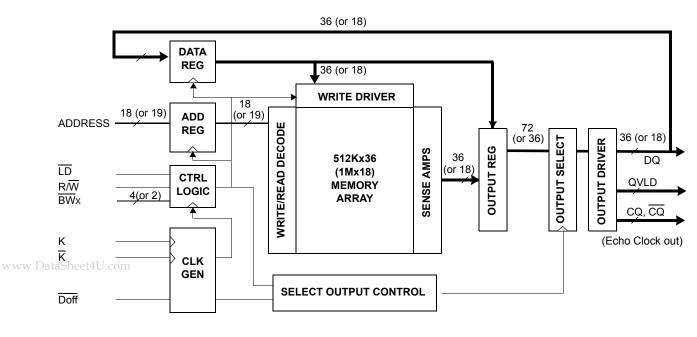
Organiza- tion	Part Number	Cycle Time	Access Time	Unit
	K7K1636U2C-F(E)C(I)45	2.22	0.45	ns
X36	K7K1636U2C-F(E)C(I)40	2.5	0.45	ns
	K7K1636U2C-F(E)C(I)33	3.0	0.45	ns
	K7K1618U2C-F(E)C(I)45	2.22	0.45	ns
X18	K7K1618U2C-F(E)C(I)40	2.5	0.45	ns
	K7K1618U2C-F(E)C(I)33	3.0	0.45	ns

\* -F(E)C(I)

F(E) [Package type] : E-Pb Free, F-Pb

C(I) [Operating Temperature] : C-Commercial, I-Industrial

### FUNCTIONAL BLOCK DIAGRAM



Notes: 1. Numbers in ( ) are for x18 device

DDR SRAM and Double Data Rate comprise a new family of products developed by Cypress, Renesas, IDT, NEC and Samsung technology.



## K7K1636U2C K7K1618U2C

## 512Kx36 & 1Mx18 DDRII+ CIO b2 SRAM

#### PIN CONFIGURATIONS(TOP VIEW) K7K1636T2C(512Kx36)

			-	-		-	-				
	1	2	3	4	5	6	7	8	9	10	11
Α	CQ	NC/SA*	NC/SA*	R/W	BW2	K	BW1	LD	SA	NC/SA*	CQ
В	NC	DQ27	DQ18	SA	BW3	К	BW <sub>0</sub>	SA	NC	NC	DQ8
С	NC	NC	DQ28	Vss	SA	NC	SA	Vss	NC	DQ17	DQ7
D	NC	DQ29	DQ19	Vss	Vss	Vss	Vss	Vss	NC	NC	DQ16
Е	NC	NC	DQ20	Vddq	Vss	Vss	Vss	Vddq	NC	DQ15	DQ6
F	NC	DQ30	DQ21	Vddq	Vdd	Vss	Vdd	Vddq	NC	NC	DQ5
G	NC	DQ31	DQ22	Vddq	Vdd	Vss	Vdd	Vddq	NC	NC	DQ14
н	Doff	VREF	Vddq	Vddq	Vdd	Vss	Vdd	Vddq	Vddq	VREF	ZQ
J	NC	NC	DQ32	Vddq	Vdd	Vss	Vdd	Vddq	NC	DQ13	DQ4
к	NC	NC	DQ23	Vddq	Vdd	Vss	Vdd	Vddq	NC	DQ12	DQ3
L	NC	DQ33	DQ24	Vddq	Vss	Vss	Vss	Vddq	NC	NC	DQ2
М	NC	NC	DQ34	Vss	Vss	Vss	Vss	Vss	NC	DQ11	DQ1
Ν	NC	DQ35	DQ25	Vss	SA	SA	SA	Vss	NC	NC	DQ10
Р	NC	NC	DQ26	SA	SA	QVLD	SA	SA	NC	DQ9	DQ0
R	TDO	TCK	SA	SA	SA	NC	SA	SA	SA	TMS	TDI

Notes: 1. \* Checked No Connect(NC) pins are reserved for higher density address, i.e. 3A for 36Mb, 10A for 72Mb, 2A for 144Mb . 2. BWo controls write to DQ0:DQ8, BW1 controls write to DQ9:DQ17, BW2 controls write to DQ18:DQ26 and BW3 controls write to DQ27:DQ35.

#### **PIN NAME**

SYMBOL	PIN NUMBERS	DESCRIPTION	NOTE
K, K	6B, 6A	Input Clock	
QVLD	6P	Q Valid output	
CQ, CQ	11A, 1A	Output Echo Clock	
Doff	1H	DLL Disable	
SA	9A,4B,8B,5C,7C,5N-7N,4P,5P,7P,8P,3R-5R,7R-9R	Address Inputs	
DQ0-35	2B,3B,11B,3C,10C,11C,2D,3D,11D,3E,10E,11E,2F,3F 11F,2G,3G,11G,3J,10J,11J,3K,10K,11K,2L,3L,11L 3M,10M,11M,2N,3N,11N,3P,10P,11P	Data Inputs Outputs	
R/W	4A	Read, Write Control Pin, Read active when high	
LD	8A	Synchronous Load Pin, bus Cycle sequence is to be defined when low	
BW0, BW1, BW2, BW3	7B,7A,5A,5B	Block Write Control Pin, active when low	
Vref	2H,10H	Input Reference Voltage	
ZQ	11H	Output Driver Impedance Control Input	1
Vdd	5F,7F,5G,7G,5H,7H,5J,7J,5K,7K	Power Supply (1.8 V)	
Vddq	4E,8E,4F,8F,4G,8G,3H,4H,8H,9H,4J,8J,4K,8K,4L,8L	Output Power Supply (1.5)	
Vss	4C,8C,4D-8D,5E-7E,6F,6G,6H,6J,6K,5L-7L, 4M-8M,4N,8N	Ground	
TMS	10R	JTAG Test Mode Select	
TDI	11R	JTAG Test Data Input	
ТСК	2R	JTAG Test Clock	
TDO	1R	JTAG Test Data Output	
aSheet4U <sub>NC</sub> em	2A,10A,1B,9B,10B,1C,2C,6C,9C,1D,9D,10D,1E,2E,9E, 1F,9F,10F,1G,9G,10G,1J,2J,9J,1K,2K,9K 1L,9L,10L,1M,2M,9M,1N,9N,10N,1P,2P,9P,6R	No Connect	2

Notes:

1. When ZQ pin is directly connected to Vob output impedance is set to minimum value and it cannot be connected to ground or left unconnected.

2. Not connected to chip pad internally.

3. K, K can not be set to VREF voltage.



#### PIN CONFIGURATIONS(TOP VIEW) K7K1618T2C(1Mx18)

	1	2	3	4	5	6	7	8	9	10	11
Α	CQ	NC/SA*	SA	R/W	BW1	ĸ	NC	LD	SA	NC/SA*	CQ
В	NC	DQ9	NC	SA	NC	К	BW <sub>0</sub>	SA	NC	NC	DQ8
С	NC	NC	NC	Vss	SA	NC	SA	Vss	NC	DQ7	NC
D	NC	NC	DQ10	Vss	Vss	Vss	Vss	Vss	NC	NC	NC
Е	NC	NC	DQ11	Vddq	Vss	Vss	Vss	Vddq	NC	NC	DQ6
F	NC	DQ12	NC	Vddq	Vdd	Vss	Vdd	Vddq	NC	NC	DQ5
G	NC	NC	DQ13	Vddq	Vdd	Vss	Vdd	Vddq	NC	NC	NC
н	Doff	VREF	Vddq	Vddq	Vdd	Vss	Vdd	Vddq	Vddq	VREF	ZQ
J	NC	NC	NC	Vddq	Vdd	Vss	Vdd	Vddq	NC	DQ4	NC
к	NC	NC	DQ14	Vddq	Vdd	Vss	Vdd	Vddq	NC	NC	DQ3
L	NC	DQ15	NC	Vddq	Vss	Vss	Vss	Vddq	NC	NC	DQ2
м	NC	NC	NC	Vss	Vss	Vss	Vss	Vss	NC	DQ1	NC
Ν	NC	NC	DQ16	Vss	SA	SA	SA	Vss	NC	NC	NC
Р	NC	NC	DQ17	SA	SA	QVLD	SA	SA	NC	NC	DQ0
R	TDO	TCK	SA	SA	SA	NC	SA	SA	SA	TMS	TDI

Notes: 1. \* Checked No Connect(NC) pins are reserved for higher density address, i.e. 10A for 36Mb and 2A for 72Mb. 2. BWo controls write to DQ0:DQ8 and BW1 controls write to DQ9:DQ17.

#### **PIN NAME**

SYMBOL	PIN NUMBERS	DESCRIPTION	NOTE
<u>к</u> , <del>к</del>	6B, 6A	Input Clock	
QVLD	6P	Q Valid output	
CQ, CQ	11A, 1A	Output Echo Clock	
Doff	1H	DLL Disable	
SA	3A,9A,4B,8B,5C,7C,5N-7N,4P,5P,7P,8P,3R-5R,7R-9R	Address Inputs	
DQ0-17	2B,11B,10C,3D,3E,11E,2F,11F,3G,10J,3K,11K,2L,11L 10M,3N,3P,11P	Data Inputs Outputs	
R/W	4A	Read, Write Control Pin, Read active when high	
LD	8A	Synchronous Load Pin, bus Cycle sequence is to be defined when low	
BW0, BW1	7B, 5A	Block Write Control Pin, active when low	
Vref	2H,10H	Input Reference Voltage	
ZQ	11H	Output Driver Impedance Control Input	1
Vdd	5F,7F,5G,7G,5H,7H,5J,7J,5K,7K	Power Supply (1.8 V)	
Vddq	4E,8E,4F,8F,4G,8G,3H,4H,8H,9H,4J,8J,4K,8K,4L,8L	Output Power Supply ( 1.5V )	
Vss	4C,8C,4D-8D,5E-7E,6F,6G,6H,6J,6K,5L-7L,4M-8M,4N,8N	Ground	
TMS	10R	JTAG Test Mode Select	
TDI	11R	JTAG Test Data Input	
ТСК	2R	JTAG Test Clock	
TDO	1R	JTAG Test Data Output	
NC Sheet4U.com	2A,7A,1B,3B,5B,9B,10B,1C,2C,3C,6C,9C,11C,1D,2D,9D,10D 11D,1E,2E,9E,10E,1F,3F,9F,10F,1G,2G,9G,10G,11G 1J,2J,3J,9J,11J,1K,2K,9K,10K,1L,3L,9L,10L 1M,2M,3M,9M,11M,1N,2N,9N,10N,11N,1P,2P,9P,10P,6R	No Connect	2

#### Notes:

1. When ZQ pin is directly connected to VDD output impedance is set to minimum value and it cannot be connected to ground or left unconnected.

2. Not connected to chip pad internally. 3. K, K can not be set to VREF voltage.



#### **GENERAL DESCRIPTION**

The K7K1636T2C and K7K1618T2C are 18,874,368-bits DDR Common I/O Synchronous Pipelined Burst SRAMs. They are organized as 524,288 words by 36bits for K7K1636T2C and 1,048,576 words by 18 bits for K7K1618T2C . Address, data inputs, and all control signals are synchronized to the input clock ( K or  $\overline{K}$  ). Read data are referenced to echo clock ( CQ or  $\overline{CQ}$  ) outputs. Read address and write address are registered on rising edges of the input K clocks. Common address bus is used to access address both for read and write operations. The internal burst counter is fixed to 2-bit sequential for both read and write operations. Synchronous pipeline read and late write enable high speed operations. Simple depth expansion is accomplished by using  $\overline{LD}$  for port selection. Byte write operation is supported with  $\overline{BWo}$  and  $\overline{BW_1}$  ( $\overline{BW_2}$  and  $\overline{BW_3}$ ) pins for x18 ( x36 ) device. IEEE 1149.1 serial boundary scan (JTAG) simplifies monitoriing package pads attachment status with system. The K7K1636T2C and K7K1618T2C are implemented with SAMSUNG's high performance 6T CMOS technology and is available in 165pin FBGA packages. Multiple power and ground pins minimize ground bounce.

#### **Read Operations**

Read cycles are initiated by initiating  $R\overline{W}$  as high at the rising edge of the positive input clock K. Address is presented and stored in the read address register synchronized with K clock. For 2-bit burst DDR operation, it will access two 36-bit or 18-bit data words with each read command. The first pipelined data is transfered out of the device triggered by K clock rising edge. Next burst data is triggered by the rising edge of following  $\overline{K}$  clock rising edge. Continuous read operations are initated with K clock rising edge. And pipelined data are transferred out of device on every rising edge of both K and  $\overline{K}$  clocks. Initial read data latency is 2.5 clock cycles when DLL is on. When the  $\overline{LD}$  is disabled after a read operation, the K7K1636T2C and K7K1618T2C will first complete burst read operation before entering into deselect mode at the next K clock rising edge. Then output drivers disabled automatically to high impedance state.

#### Write Operations

Write cycles are initiated by activating R/W as low at the rising edge of the positive input clock K. Address is presented and stored in the write address register synchronized with next K clock. For 2-bit burst DDR operation, it will write two 36-bit or 18-bit data words with each write command. The first "late writed" data is transfered and registered in to the device synchronous with next K clock rising edge. Next burst data is transfered and registered synchronous with following K clock rising edge. Continuous write operations are initated with K rising edge.

And "late writed" data is presented to the device on every rising edge of both K and  $\overline{K}$  clocks.

When the  $\overline{\text{LD}}$  is disabled, the K7K1636T2C and K7K1618T2C will enter into deselect mode.

The device disregards input data presented on the same cycle  $\ensuremath{\mathsf{R}}/\ensuremath{\overline{\mathsf{W}}}$  disabled.

The K7K1636T2C and K7K1618T2C support byte write operations.

With activating  $\overline{BW_0}$  or  $\overline{BW_1}$  ( $\overline{BW_2}$  or  $\overline{BW_3}$ ) in write cycle, only one byte of input data is presented. In K7K1618T2C,  $\overline{BW_0}$  controls write operation to D0:D8,  $\overline{BW_1}$  controls write operation to D9:D17. And in K7K1636T2C,  $\overline{BW_2}$  controls write operation to D18:D26,  $\overline{BW_3}$  controls write operation to D27:D35.



#### **Depth Expansion**

Each port can be selected and deselected independently with R/W be shared among all SRAMs and provide a new  $\overline{LD}$  signal for each bank. Before chip deselected, all read and write pending operations are completed.

#### Programmable Impedance Output Buffer Operation

The designer can program the SRAM's output buffer impedance by terminating the ZQ pin to Vss through a precision resistor(RQ). The allowable range of RQ is between  $175\Omega$  and  $350\Omega$ .

The value of RQ (within 15%) is five times the output impedance desired.

For example,  $250\Omega$  resistor will give an output impedance of  $50\Omega$ .

Impedance updates occur early in cycles that do not activate the outputs, such as deselect cycles.

In all cases impedance updates are transparent to the user and do not produce access time "push-outs" or other anomalous behavior in the SRAM.

To guarantee optimum output driver impedance after power up, the SRAM needs 1024 non-read cycles.

#### **Output Valid Pin (QVLD)**

The Q Valid indicates valid output data. QVLD is activated half cycle before the read data for the receiver to be ready for capturing the data. QVLD is edge aligned with CQ and  $\overline{CQ}$ .

#### Echo clock operation

To assure the output tracibility, the SRAM provides the output Echo clock, pair of compliment clock CQ and  $\overline{CQ}$ , which are synchronized with internal data output. Echo clocks run free during normal operation. The Echo clock is triggered by internal output clock signal, and transfered to external through same structures as output driver.

#### Power-Up/Power-Down Supply Voltage Sequencing

The following power-up supply voltage application is recommended: Vss, VDD, VDDQ, VREF, then VIN. VDD and VDDQ can be applied simultaneously, as long as VDDQ does not exceed VDD by more than 0.5V during power-up. The following power-down supply voltage removal sequence is recommended: VIN, VREF, VDDQ, VDD, VSs. VDD and VDDQ can be removed simultaneously, as long as VDDQ does not exceed VDD by more than 0.5V during power-down.



#### **Detail Specification of Power-Up Sequence in DDRII+ SRAM**

DDRII+ SRAMs must be powered up and initialized in a predefined manner to prevent undefined operations.

#### • Power-Up Sequence

- 1. Apply power and keep  $\overline{\text{Doff}}$  at low state (All other inputs may be undefined)
  - Apply VDD before VDDQ
  - Apply VDDQ before VREF or the same time with VREF
- 2. Just after the stable power and  $clock(K,\overline{K})$ , take Doff to be high.
- 3. The additional 2048 cycles of clock input is required to lock the DLL after enabling DLL

\* **Notes**: If you want to tie up the  $\overline{\text{Doff}}$  pin to High with unstable clock, then you must stop the clock for a few seconds (Min. 30ns) to reset the DLL after it become a stable clock status.

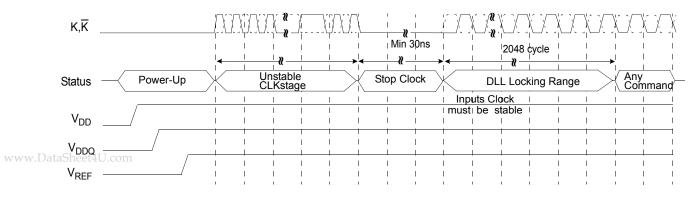
#### DLL Constraints

- 1. DLL uses K clock as its synchronizing input, the input should have low phase jitter which is specified as TK var.
- 2. The lower end of the frequency at which the DLL can operate is 120MHz.
- If the incoming clock is unstable and the DLL is enabled, then the DLL may lock onto a wrong frequency and this may cause the failure in the initial stage.

K,K		**************************************	2048 cycle	
Status	Power-Up	table Kstage	DLL Locking Range	Any Command
V <sub>DD</sub>		Ir mu	puts Clock	
V <sub>DDQ</sub>				
V <sub>DDQ</sub> V <sub>REF</sub>				
Doff		/		

#### Power up & Initialization Sequence (Doff pin controlled)

#### Power up & Initialization Sequence (Doff pin Fixed high, Clock controlled)



\* Notes: When the operating frequency is changed, DLL reset should be required again. After DLL reset again, the minimum 2048 cycles of clock input is needed to lock the DLL.



#### **TRUTH TABLES**

#### SYNCHRONOUS TRUTH TABLE

K	LD	R/W		OPERATION	
n	LD	FC/ ¥¥	DQ(A1)		
Stopped	Х	Х	Previous state	Previous state	Clock Stop
$\uparrow$	Н	Х	High-Z	High-Z High-Z I	
1	L	Н	Qout at K(t+2)	QOUT at K(t+2)	Read
1	L	L	Din at K(t+1)	Din at $\overline{K}(t+1)$	Write

Notes: 1. X means "Don't Care".

2. The rising edge of clock is symbolized by (  $\uparrow$  ).

3. Before enter into clock stop status, all pending read and write operations will be completed.

#### WRITE TRUTH TABLE(x18)

К	К	BW <sub>0</sub>	BW1	OPERATION
$\uparrow$		L	L	WRITE ALL BYTEs ( $K^{\uparrow}$ )
	$\uparrow$	L	L	WRITE ALL BYTES ( $\overline{K}\uparrow$ )
$\uparrow$		L	Н	WRITE BYTE 0 ( K↑ )
	$\uparrow$	L	Н	WRITE BYTE 0 ( $\overline{\mathbf{K}}$ )
$\uparrow$		Н	L	WRITE BYTE 1 ( K↑ )
	$\uparrow$	Н	L	WRITE BYTE 1 ( $\overline{\mathbf{K}}$ )
$\uparrow$		Н	Н	WRITE NOTHING ( K↑ )
	$\uparrow$	Н	Н	WRITE NOTHING ( $\overline{\mathbf{K}}$ )

Notes: 1. X means "Don't Care".

2. All inputs in this table must meet setup and hold time around the rising edge of input clock K or  $\overline{K}$  (  $\uparrow$  ).

3. Assumes a WRITE cycle was initiated.

4. This table illustates operation for x18 devices.

#### WRITE TRUTH TABLE(x36)

к	к	BW <sub>0</sub>	BW1	BW <sub>2</sub>	BW3	OPERATION
$\uparrow$		L	L	L	L	WRITE ALL BYTEs ( $K^{\uparrow}$ )
	$\uparrow$	L	L	L	L	WRITE ALL BYTES ( $\overline{K}^{\uparrow}$ )
$\uparrow$		L	Н	Н	Н	WRITE BYTE 0 ( K <sup>↑</sup> )
	$\uparrow$	L	Н	Н	Н	WRITE BYTE 0 ( $\overline{\mathbf{K}}$ )
$\uparrow$		Н	L	Н	Н	WRITE BYTE 1 ( K <sup>↑</sup> )
	$\uparrow$	Н	L	Н	Н	WRITE BYTE 1 ( $\overline{\mathbf{K}}$ )
$\uparrow$		Н	Н	L	L	WRITE BYTE 2 and BYTE 3 ( K $\uparrow$ )
	$\uparrow$	Н	Н	L	L	WRITE BYTE 2 and BYTE 3 ( $\overline{\mathbf{K}}$ )
$\uparrow$		Н	Н	Н	Н	WRITE NOTHING ( K <sup>↑</sup> )
	$\uparrow$	Н	Н	Н	Н	WRITE NOTHING ( $\overline{\mathbf{K}}$ )

Notes: 1. X means "Don't Care".

2. All inputs in this table must meet setup and hold time around the rising edge of input clock K or  $\overline{\mathsf{K}}$  (  $\uparrow$  ).

www.DataSheet3UAssumes a WRITE cycle was initiated.



#### ABSOLUTE MAXIMUM RATINGS

PARAMETE	SYMBOL	RATING	UNIT	
Voltage on VDD Supply Relative to Vss		Vdd	-0.5 to 2.9	V
Voltage on VDDQ Supply Relative to Vss		Vddq	-0.5 to VDD	V
Voltage on Input Pin Relative to Vss		VIN	-0.5 to VDD+0.3	V
Storage Temperature		Тѕтс	-65 to 150	°C
Operating Temperature	Commercial / Industrial	Topr	0 to 70 / -40 to 85	°C
Storage Temperature Range Under Bias				°C

Note: 1. Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

#### **OPERATING CONDITIONS** ( $0^{\circ}C \le TA \le 70^{\circ}C$ )

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
Supply Voltage	Vdd	1.7	1.8	1.9	V
Supply Voltage	Vddq	1.4	1.5	1.6	V
Reference Voltage	VREF	0.7	0.75	0.8	V
Input Low Voltage(DC) 2,3)	VIL(DC)	-0.3	-	VREF-0.1	V
Input High Voltage(DC) 2,4)	VIH(DC)	VREF+0.1	-	VDDQ+0.3	V
Input High Voltage(AC) 6,7)	VIL(AC)	VREF + 0.2	-	-	V
Input Low Voltage(AC) 6,7)	VIH(AC)	-	-	VREF - 0.2	V

Note: 1. VDDQ must not exceed VDD during normal operation.

- 2. These are DC test criteria. DC design criteria is VREF±50mV. The AC VIH/VIL levels are defined separately for measuring timing parameters.
- 3. VIL (Min)DC=-0.3V, VIL (Min)AC=-1.5V(pulse width  $\leq$  3ns).
- 4. VIH (Max)DC=VDDQ+0.3V, VIH (Max)AC=VDDQ+0.85V(pulse width  $\leq$  3ns).
- 5. Overshoot : VIH (AC)  $\leq$  VDDQ+0.5V for t  $\leq$  50% tKHKH(MIN).
- Undershoot : VIL (AC)  $\leq$  VSS-0.5V for t  $\leq$  50% tKHKH(MIN).
- 6. This condition is for AC function test only, not for AC parameter test.
- 7. To maintain a valid level, the transitioning edge of the input must : a) Sustain a constant slew rate from the current AC level through the target AC level, VIL(AC) or VIH(AC)
- b) Reach at least the target AC level
- c) After the AC target level is reached, continue to maintain at least the target DC level, VIL(DC) or VIH(DC)



#### DC ELECTRICAL CHARACTERISTICS (VDD=1.8V ±0.1V, TA=0°C to +70°C)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN	MAX	UNIT	NOTES
Input Leakage Current	lı∟	VDD=Max ; VIN=Vss to VDDQ		-2	+2	μA	
Output Leakage Current	Iol	Output Disabled,		-2	+2	μA	
			-45	-	950		
Operating Current (x36): QDR	Icc	Vpp=Max , louт=0mA Cycle Time ≥ tкнкн Min	-40	-	900	mA	1,4
			-33	-	800		
Operating Current (x18): QDR	Icc		-45	-	850	mA	
		Voo=Max , louт=0mA Cycle Time ≥ tкнкн Min	-40	-	800		1,4
			-33	-	700		
		Device deselected,	-45	-	400		
Standby Current(NOP): QDR	ISB1	IOUT=0mA, f=Max,	-40	-	350	mA	1,5
		All Inputs≤0.2V or ≥ VDD-0.2V	-33	-	300		
Output High Voltage	Voh1			VDDQ/2-0.12	VDDQ/2+0.12	V	2,6
Output Low Voltage	Vol1			VDDQ/2-0.12	VDDQ/2+0.12	V	2,6
Output High Voltage	Voh2	Іон=-1.0mA		VDDQ-0.2	Vddq	V	3
Output Low Voltage	Vol2	IoL=1.0mA		Vss	0.2	V	3

Notes: 1. Minimum cycle. IOUT=0mA.

 $2. \ |\text{Ioh}| = (\text{VDDQ}/2)/(\text{RQ}/5) \pm 15\% \ \text{ for } 175\Omega \leq \text{RQ} \leq 350\Omega. \ |\text{Ioh}| = (\text{VDDQ}/2)/(\text{RQ}/5) \pm 15\% \ \text{ for } 175\Omega \leq \text{RQ} \leq 350\Omega.$ 

3. Minimum Impedance Mode when ZQ pin is connected to VDD.

Operating current is calculated with 100% read cycles or 100% write cycles.
 Standby Current is only after all pending read and write burst opeactions are completed.
 Programmable Impedance Mode.



#### AC TIMING CHARACTERISTICS (VDD=1.8V±0.1V, TA=0°C to +70°C)

DADAMETED		-4	45	-4	40	-33			NOTE
PARAMETER	SYMBOL	MIN	MAX	MIN	MAX	MIN	MAX		NOTE
Clock					•				
Clock Cycle Time (K, K)	tкнкн	2.22	8.4	2.5	8.4	3.0	8.4	ns	
Clock Phase Jitter (K, K)	tK var		0.20		0.20		0.20	ns	4
Clock High Time (K, K)	<b>t</b> KHKL	0.4		0.4		0.4		ns	
Clock Low Time (K, K)	tкікн	0.4		0.4		0.4		ns	
Clock to $\overline{\text{Clock}}$ (K $\uparrow \rightarrow \overline{\text{K}}\uparrow$ )	tкн <del>к</del> н	0.95		1.06		1.3		ns	
DLL Lock Time (K)	tK lock	2048		2048		2048		cycle	5
K Static to DLL reset	tK reset	30		30		30		ns	
Output Times									
K, K High to Output Valid	<b>t</b> KHQV		0.45		0.45		0.45	ns	
K, K High to Output Hold	tкнqх	-0.45		-0.45		-0.45		ns	
K, K High to Echo Clock Valid	tкнсqv		0.45		0.45		0.45	ns	
K, $\overline{K}$ High to Echo Clock Hold	tкнсqх	-0.45		-0.45		-0.45		ns	
CQ, CQ High to Output Valid	tcqнqv		0.2		0.2		0.2	ns	
CQ, CQ High to Output Hold	tсанах	-0.2		-0.2		-0.2		ns	
CQ High to CQ High	tcqн <del>сq</del> н	0.75		0.86		1.1		ns	6
K, K High to Output High-Z	tкнz		0.45		0.45		0.45	ns	
K, K High to Output Low-Z	tкız	-0.45		-0.45		-0.45		ns	
CQ, CQ High to QVLD Valid	tqvld	-0.2	0.2	-0.2	0.2	-0.2	0.2	ns	
Setup Times									
Address valid to K rising edge	tavkh	0.40		0.40		0.40		ns	
Control inputs valid to K rising edge	tıvкн	0.40		0.40		0.40		ns	2
Data-in valid to K, K rising edge	tdvkh	0.28		0.28		0.28		ns	
Hold Times									
K rising edge to address hold	tкнах	0.40		0.40		0.40		ns	
K rising edge to control inputs hold	tкніх	0.40		0.40		0.40		ns	
K, $\overline{K}$ rising edge to data-in hold	<b>t</b> KHDX	0.28	T	0.28		0.28		ns	

Notes: 1. All address inputs must meet the specified setup and hold times for all latching clock edges.
2. Control signals are R/ W and LD. However BWx does not apply to this parameters. BWx signals obey the data setup and hold times.
3. To avoid bus contention, at a given voltage and temperature tKLZ is bigger than tKHZ. The specs as shown do not imply bus contention because tKLZ is a MIN parameter that is worst case at totally different test conditions (0°C, 1.9V) than tKHZ, which is a MAX parameter(worst case at 70°C, 1.7V) It is not possible for two SRAMs on the same board to be at such different voltage and temperature.
4. Clock phase jitter is the variance from clock rising edge to the next expected clock rising edge.
5. Vidd slew rate must be less than 0.1V DC per 50. ps for DL lock retention. DL lock time begins once V/dd and input clock are stable.

5. Vdd slew rate must be less than 0.1V DC per 50 ns for DLL lock retention. DLL lock time begins once Vdd and input clock are stable.

6. This parameter is extrapolated from the input timing parameters (tKHKH - 200ps where 200ps is the internal jitter.) This parameter is only guaranteed by design and not tested in production.



#### THERMAL RESISTANCE

PRMETER	SYMBOL	ТҮР	Unit	NOTES
Junction to Ambient	ALθ	20.8	°C/W	
Junction to Case	θJC	2.3	°C/W	
Junction to Pins	θјв	4.3	°C/W	

Note: Junction temperature is a function of on-chip power dissipation, package thermal impedance, mounting site temperature and mounting site thermal impedance. TJ=TA + PD x θJA

#### **PIN CAPACITANCE**

PRMETER	SYMBOL	TESTCONDITION	TYP	MAX	Unit	NOTES
Address Control Input Capacitance	CIN	VIN=0V	3.5	4	pF	
Input and Output Capacitance	Соит	Vout=0V	4	5	pF	
Clock Capacitance	CCLK	-	3	4	pF	

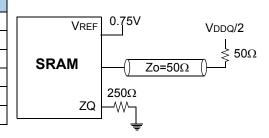
Note: 1. Parameters are tested with RQ=250 $\Omega$  and VDDQ=1.5V.

2. Periodically sampled and not 100% tested.

#### AC TEST CONDITIONS

Parameter	Symbol	Value	Unit
Core Power Supply Voltage	Vdd	1.7~1.9	V
Output Power Supply Voltage	Vddq	1.4~1.6	V
Input High/Low Level	VIH/VIL	1.25/0.25	V
Input Reference Level	VREF	0.75	V
Input Rise/Fall Time	Tr/Tf	0.3/0.3	ns
Output Timing Reference Level		Vddq/2	V

#### AC TEST OUTPUT LOAD

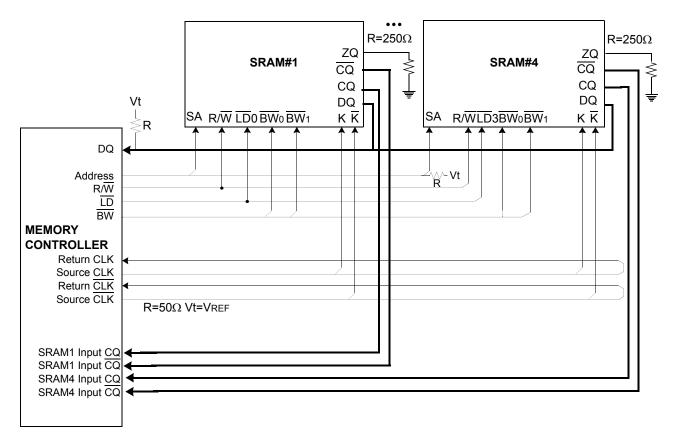


Note: Parameters are tested with RQ=250 $\Omega$ 



## K7K1636U2C K7K1618U2C

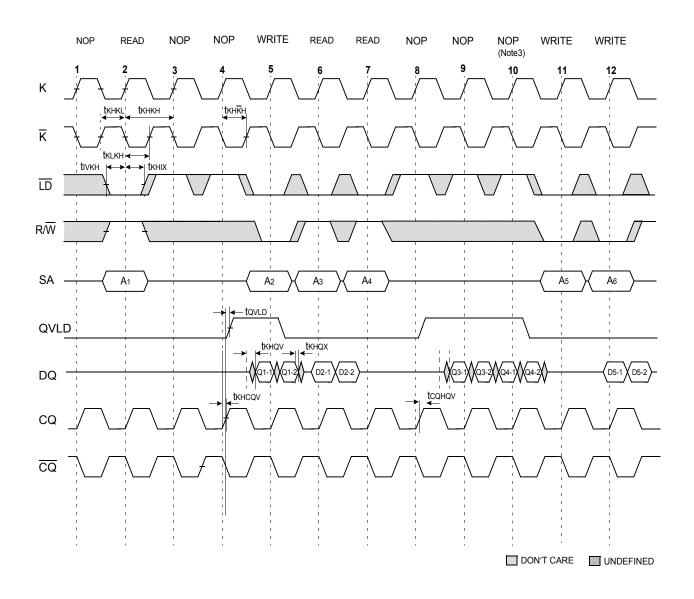
#### **APPLICATION INRORMATION**





## K7K1636U2C K7K1618U2C

#### TIMING WAVE FORMS OF READ, WRITE AND NOP



#### NOTE

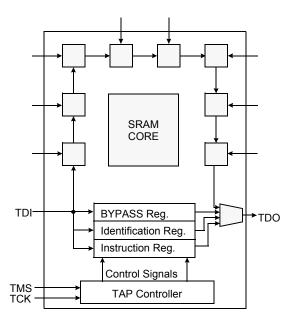
- 1. Q1-1 refers to output from address A1. Q1-2 refers to output from the next internal burst address following A, etc.
- 2. Outputs are disabled(High-Z) two clock cycle after a NOP .
- Two NOP cycle is the mandatory and 3<sup>rd</sup> NOP cycle is not necessary for correct DDRII+ READ/WRITE operation.
   However at high clock frequencies, considering the delay of real system board condition, it may be required to prevent bus contention.



#### IEEE 1149.1 TEST ACCESS PORT AND BOUNDARY SCAN-JTAG

This part contains an IEEE standard 1149.1 Compatible Test Access Port(TAP). The package pads are monitored by the Serial Scan circuitry when in test mode. This is to support connectivity testing during manufacturing and system diagnostics. Internal data is not driven out of the SRAM under JTAG control. In conformance with IEEE 1149.1, the SRAM contains a TAP controller, Instruction Register, Bypass Register and ID register. The TAP controller has a standard 16-state machine that resets internally upon power-up, therefore, TRST signal is not required. It is possible to use this device without utilizing the TAP. To disable the TAP controller without interfacing with normal operation of the SRAM, TCK must be tied to Vss to preclude mid level input. TMS and TDI are designed so an undriven input will produce a response identical to the application of a logic 1, and may be left unconnected. But they may also be tied to VbD through a resistor. TDO should be left unconnected.

#### JTAG Block Diagram



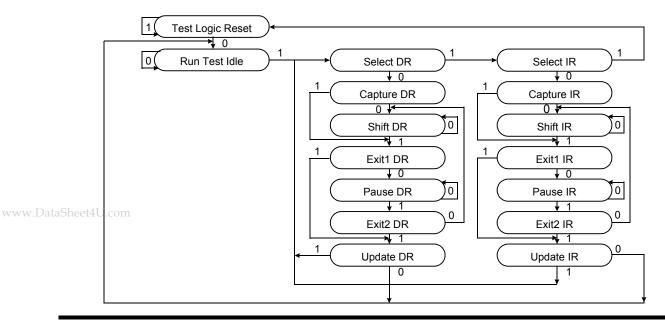
**TAP Controller State Diagram** 

#### **JTAG Instruction Coding**

5								
IR2	IR1	IR0	Instruction	TDO Output	Notes			
0	0	0	EXTEST	Boundary Scan Register	1			
0	0	1	IDCODE	Identification Register	3			
0	1	0	SAMPLE-Z	Boundary Scan Register	2			
0	1	1	RESERVED	Do Not Use	6			
1	0	0	SAMPLE	Boundary Scan Register	5			
1	0	1	RESERVED	Do Not Use	6			
1	1	0	RESERVED	Do Not Use	6			
1	1	1	BYPASS	Bypass Register	4			

NOTE :

- 1. Places DQs in Hi-Z in order to sample all input data regardless of other SRAM inputs. This instruction is not IEEE 1149.1 compliant.
- 2. Places DQs in Hi-Z in order to sample all input data regardless of other SRAM inputs.
- 3. TDI is sampled as an input to the first ID register to allow for the serial shift of the external TDI data.
- Bypass register is initiated to Vss when BYPASS instruction is invoked. The Bypass Register also holds serially loaded TDI when exiting the Shift DR states.
- 5. SAMPLE instruction dose not places DQs in Hi-Z.
- 6. This instruction is reserved for future use.





## Rev. 1.1 August 2010

#### SCAN REGISTER DEFINITION

Part	Instruction Register	ruction Register Bypass Register ID Register		Boundary Scan
512Kx36	3 bits	1 bit	32 bits	107 bits
1Mx18	3 bits	1 bit	32 bits	107 bits

#### **ID REGISTER DEFINITION**

Part	Revision Number (31:29)	Part Configuration (28:12)	Samsung JEDEC Code (11: 1)	Start Bit(0)
512Kx36	000	00def0wx0t0q0b0s0	00011001110	1
1Mx18	000	00def0wx0t0q0b0s0	00011001110	1

Note : Part Configuration

/def=001 for 18Mb, /wx=11 for x36, 10 for x18

/t=1 for DLL Ver., 0 for non-DLL Ver. /q=1 for QDR, 0 for DDR /b=1 for 4Bit Burst, 0 for 2Bit Burst /s=1 for Separate I/O, 0 for Common I/O

ORDER	PIN ID	ORDER	PIN ID	ORDER
1	6R	37	10D	73
2	6P	38	9E	74
3	6N	39	10C	75
4	7P	40	11D	76
5	7N	41	9C	77
6	7R	42	9D	78
7	8R	43	11B	79
8	8P	44	11C	80
9	9R	45	9B	81
10	11P	46	10B	82
11	10P	47	11A	83
12	10N	48	10A	84
13	9P	49	9A	85
14	10M	50	8B	86
15	11N	51	7C	87
16	9M	52	6C	88
17	9N	53	8A	89
18	11L	54	7A	90
19	11M	55	7B	91
20	9L	56	6B	92
21	10L	57	6A	93
22	11K	58	5B	94
23	10K	59	5A	95
24	9J	60	4A	96
25	9K	61	5C	97
26	10J	62	4B	98
27	11J	63	3A	99
28	11H	64	2A	100
29	10G	65	1A	101
30	9G	66	2B	102
Sheet41 <mark>31</mark> com	11F	67	3B	103
32	11G	68	1C	104
33	9F	69	1B	105
34	10F	70	3D	106
35	11E	71	3C	107
36	10E	72	1D	108
		L	•	109

#### **BOUNDARY SCAN EXIT ORDER**

www.Data

Note: 1. NC pins are read as "X" ( i.e	. don't care.)
----------------------------------------	----------------



Internal

109

**PIN ID** 2C 3E 2D 2E 1E 2F 3F 1G 1F 3G 2G 1H 1J 2J 3K ЗJ 2K 1K 2L 3L 1M 1L 3N 3M 1N 2M 3P 2N 2P 1P 3R 4R 4P 5P 5N 5R

#### JTAG DC OPERATING CONDITIONS

Parameter	Symbol	Min	Тур	Мах	Unit	Note
Power Supply Voltage	Vdd	1.7	1.8	1.9	V	
Input High Level	Vін	1.3	-	VDD+0.3	V	
Input Low Level	VIL	-0.3	-	0.5	V	
Output High Voltage(Iон=-2mA)	Vон	1.4	-	Vdd	V	
Output Low Voltage(IoL=2mA)	Vol	Vss	-	0.4	V	

Note: 1. The input level of SRAM pin is to follow the SRAM DC specification.

#### JTAG AC TEST CONDITIONS

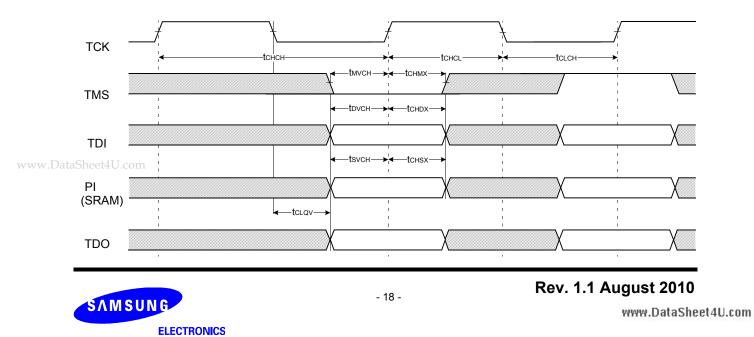
Parameter	Symbol	Min	Unit	Note
Input High/Low Level	VIH/VIL	1.8/0.0	V	
Input Rise/Fall Time	TR/TF	1.0/1.0	ns	
Input and Output Timing Reference Level		0.9	V	1

Note: 1. See SRAM AC test output load on page 11.

#### **JTAG AC Characteristics**

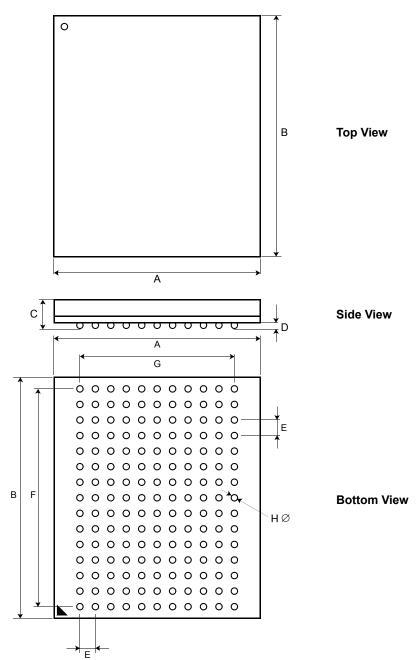
Parameter	Symbol	Min	Мах	Unit	Note
TCK Cycle Time	tснсн	50	-	ns	
TCK High Pulse Width	<b>t</b> CHCL	20	-	ns	
TCK Low Pulse Width	<b>t</b> CLCH	20	-	ns	
TMS Input Setup Time	tмvсн	5	-	ns	
TMS Input Hold Time	tснмх	5	-	ns	
TDI Input Setup Time	tdvcн	5	-	ns	
TDI Input Hold Time	tснох	5	-	ns	
SRAM Input Setup Time	tsvcн	5	-	ns	
SRAM Input Hold Time	tcнsx	5	-	ns	
Clock Low to Output Valid	tCLQV	0	10	ns	

#### JTAG TIMING DIAGRAM



#### **165 FBGA PACKAGE DIMENSIONS**

15mm x 17mm Body, 1.0mm Bump Pitch, 11x15 Ball Array



	Symbol	Value	Units	Note	Symbol	Value	Units	Note
www.Data	Sheet <mark>4</mark> U.com	$15\pm0.1$	mm		E	1.0	mm	
	В	$17\pm0.1$	mm		F	14.0	mm	
	С	$1.3\pm0.1$	mm		G	10.0	mm	
	D	$0.35\pm0.05$	mm		н	$0.5\pm0.05$	mm	

