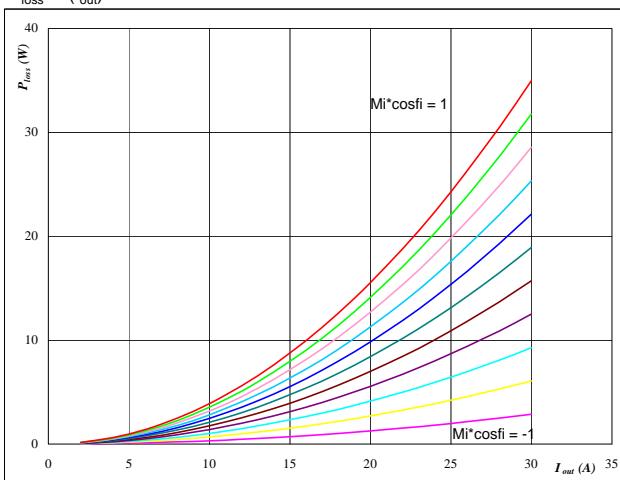


**flowPIM 0**
**Output Inverter Application**
**600V/20A**
**General conditions**
**3phase SPWM**

$V_{G\text{Eon}}$	=	15 V
$V_{G\text{Eoff}}$	=	0 V
$R_{g\text{on}}$	=	16 Ω
$R_{g\text{off}}$	=	8 Ω

**Figure 1**
**IGBT**
**Typical average static loss as a function of output current**

$$P_{\text{loss}} = f(I_{\text{out}})$$

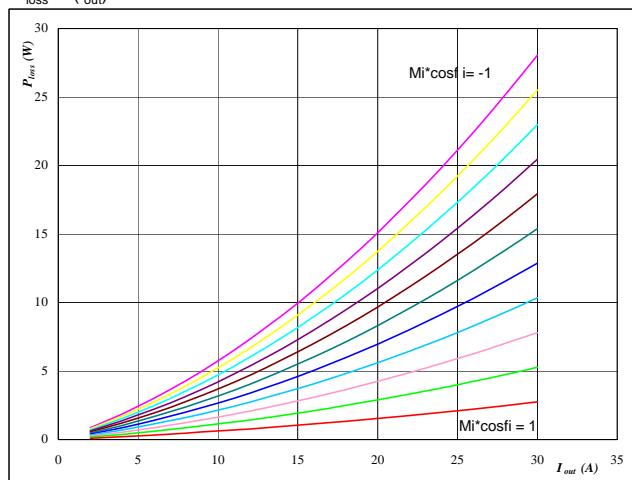

**At**

$$T_j = 125 \quad ^\circ\text{C}$$

 $Mi \cdot \cos\phi$  from -1 to 1 in steps of 0,2

**Figure 2**
**FWD**
**Typical average static loss as a function of output current**

$$P_{\text{loss}} = f(I_{\text{out}})$$

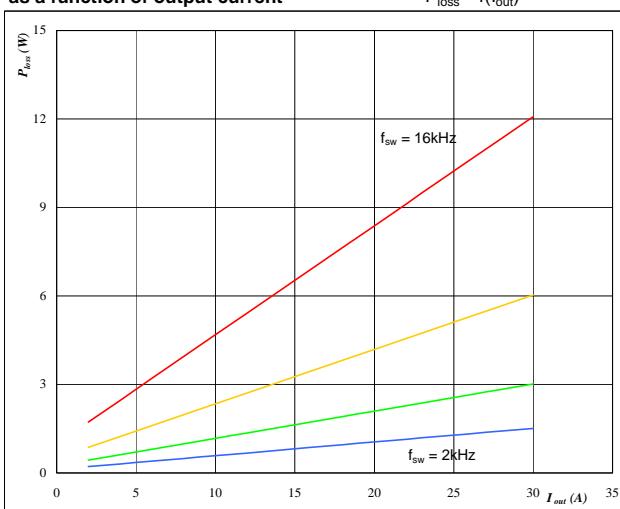

**At**

$$T_j = 125 \quad ^\circ\text{C}$$

 $Mi \cdot \cos\phi$  from -1 to 1 in steps of 0,2

**Figure 3**
**IGBT**
**Typical average switching loss as a function of output current**

$$P_{\text{loss}} = f(I_{\text{out}})$$


**At**

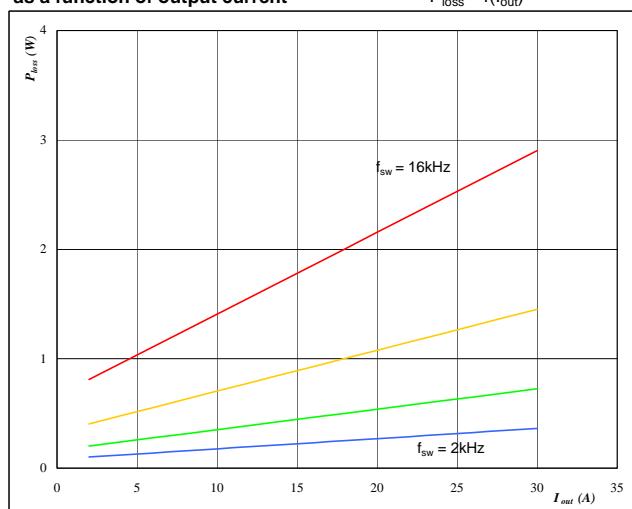
$$T_j = 125 \quad ^\circ\text{C}$$

$$\text{DC link} = 320 \quad \text{V}$$

 $f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 4**
**FWD**
**Typical average switching loss as a function of output current**

$$P_{\text{loss}} = f(I_{\text{out}})$$


**At**

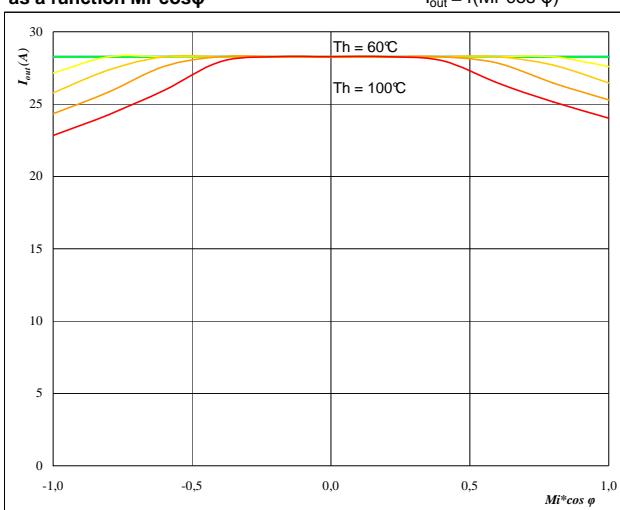
$$T_j = 125 \quad ^\circ\text{C}$$

$$\text{DC link} = 320 \quad \text{V}$$

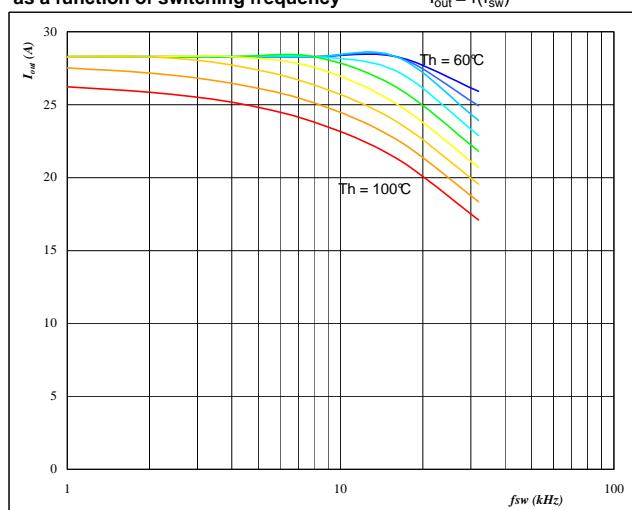
 $f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

**flowPIM 0**
**Output Inverter Application**
**600V/20A**
**Figure 5**
**Typical available 50Hz output current  
as a function  $M_i \cos \varphi$** 

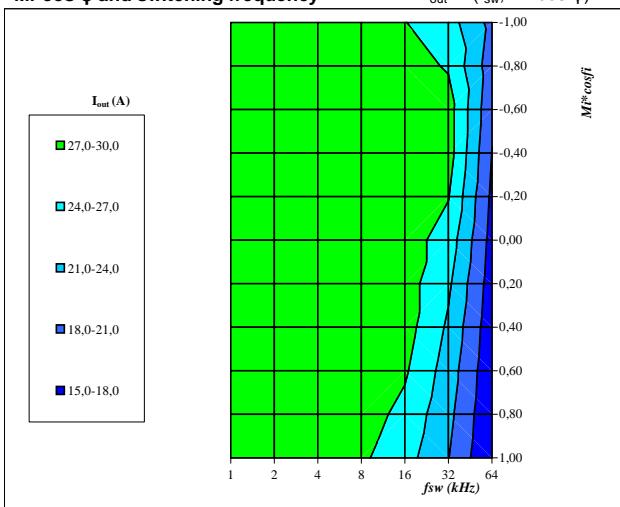
$$I_{out} = f(M_i \cos \varphi)$$


**At**
 $T_j = 125 \quad ^\circ\text{C}$ 
 $\text{DC link} = 320 \quad \text{V}$ 
 $f_{sw} = 4 \quad \text{kHz}$ 
 $T_h \text{ from } 60 \text{ }^\circ\text{C} \text{ to } 100 \text{ }^\circ\text{C} \text{ in steps of } 5 \text{ }^\circ\text{C}$ 
**Figure 6**
**Typical available 50Hz output current  
as a function of switching frequency**

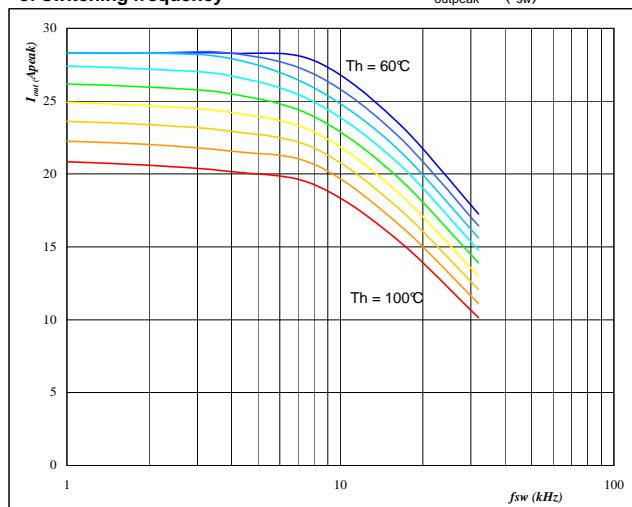
$$I_{out} = f(f_{sw})$$


**At**
 $T_j = 125 \quad ^\circ\text{C}$ 
 $\text{DC link} = 320 \quad \text{V}$ 
 $M_i \cos \varphi = 0,8$ 
 $T_h \text{ from } 60 \text{ }^\circ\text{C} \text{ to } 100 \text{ }^\circ\text{C} \text{ in steps of } 5 \text{ }^\circ\text{C}$ 
**Figure 7**
**Typical available 50Hz output current as a function of  
 $M_i \cos \varphi$  and switching frequency**

$$I_{out} = f(f_{sw}, M_i \cos \varphi)$$


**At**
 $T_j = 125 \quad ^\circ\text{C}$ 
 $\text{DC link} = 320 \quad \text{V}$ 
 $T_h = 80 \quad ^\circ\text{C}$ 
**Figure 8**
**Typical available 0Hz output current as a function  
of switching frequency**

$$I_{out,peak} = f(f_{sw})$$

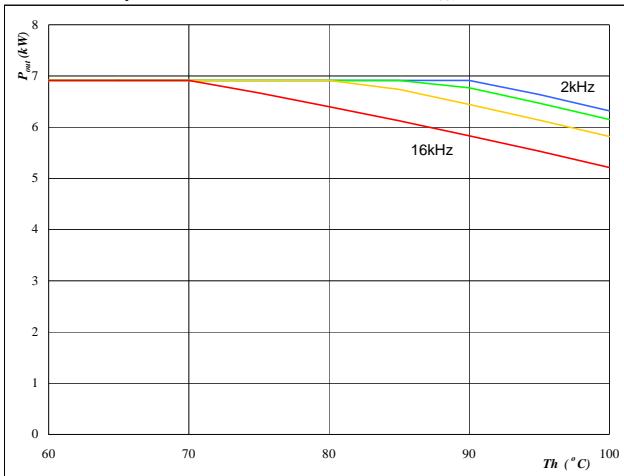

**At**
 $T_j = 125 \quad ^\circ\text{C}$ 
 $\text{DC link} = 320 \quad \text{V}$ 
 $T_h \text{ from } 60 \text{ }^\circ\text{C} \text{ to } 100 \text{ }^\circ\text{C} \text{ in steps of } 5 \text{ }^\circ\text{C}$ 
 $Mi = 0$

flowPIM 0

## Output Inverter Application

600V/20A

Figure 9

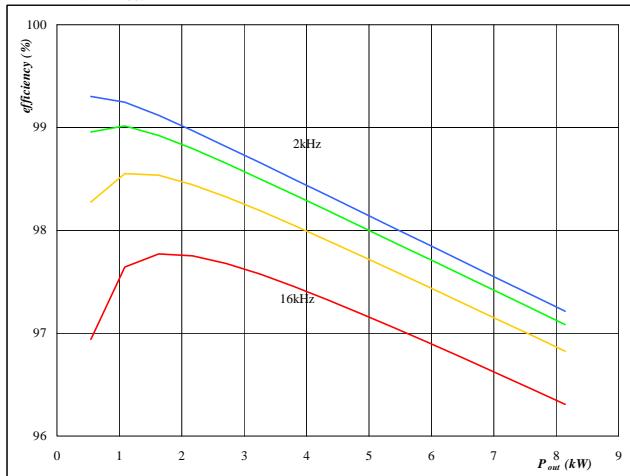
Typical available peak output power as a function of heatsink temperature  
 $P_{out}=f(T_h)$ 


At

T<sub>j</sub> = 125 °C  
DC link = 320 V  
Mi = 1  
cos φ = 0,80  
f<sub>sw</sub> from 2 kHz to 16 kHz in steps of factor 2

Inverter

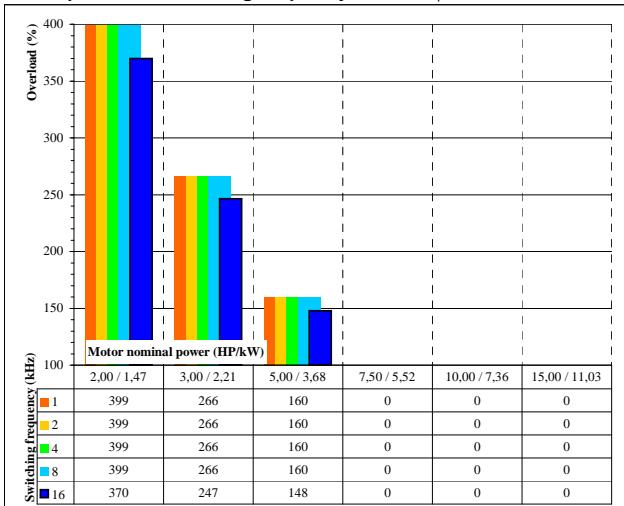
Figure 10

Typical efficiency as a function of output power  
efficiency=f(P<sub>out</sub>)


At

T<sub>j</sub> = 125 °C  
DC link = 320 V  
Mi = 1  
cos φ = 0,80  
f<sub>sw</sub> from 2 kHz to 16 kHz in steps of factor 2

Figure 11

Typical available overload factor as a function of motor power and switching frequency  
 $P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$ 


At

T<sub>j</sub> = 125 °C  
DC link = 320 V  
Mi = 1  
cos φ = 0,8  
f<sub>sw</sub> from 1 kHz to 16kHz in steps of factor 2  
T<sub>h</sub> = 80 °C  
Motor eff = 0,85