

RL78/G13

Serial Array Unit (UART Communication)

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Introduction

This application note explains how to use UART communication through the serial array unit (SAU). ASCII characters transmitted from the device on the opposite side are analyzed to make responses.

Target Device

RL78/G13

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.

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1. Specifications

In this application note, UART communication is performed through the serial array unit (SAU). ASCII characters transmitted from the device on the opposite side are analyzed to make responses.

Table 1.1 shows the peripheral function to be used and its use. Figures 1.1 and 1.2 illustrate UART communication operation.

Table 1.1 Peripheral Function to be Used and its Use

Peripheral Function	Use		
Serial array unit 0	Perform UART communication using the TxD0 pin		
	(transmission) and the RxD0 pin (reception).		

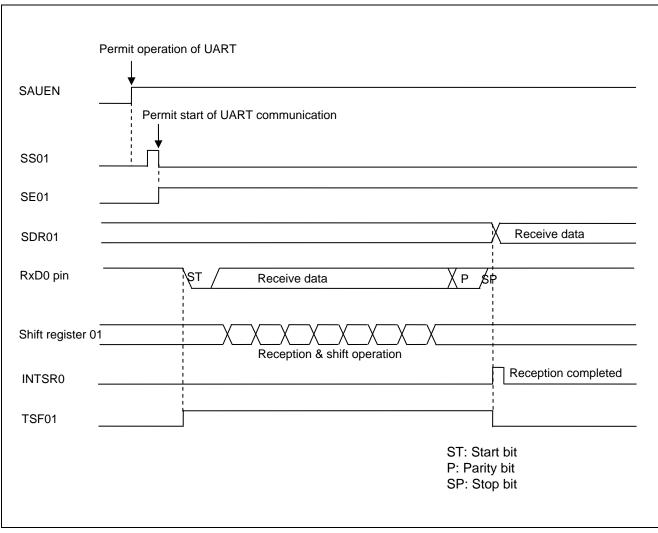


Figure 1.1 UART Reception Timing Chart

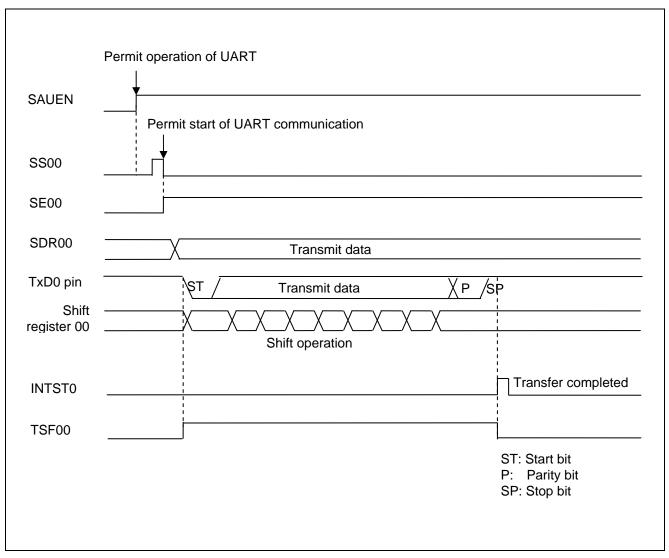


Figure 1.2 UART Transmission Timing Chart

2. Operation Check Conditions

The sample code contained in this application note has been checked under the conditions listed in the table below.

Table 2.1 Operation Check Conditions

Item	Description
Microcontroller used	RL78/G13 (R5F100LEA)
Operating frequency	High-speed on-chip oscillator (HOCO) clock: 32 MHz
	CPU/peripheral hardware clock: 32 MHz
Operating voltage	5.0 V (can run on a voltage range of 2.9 V to 5.5 V.)
	LVD operation (V _{LVI}): Reset mode 2.81 V (2.76 V to 2.87 V)
Integrated development	CubeSuite + V1.00.01
environment (CubeSuite+)	
C compiler (CubeSuite+)	CA78K0R V1.20
Integrated development	e2studio V2.0.1.3
environment (e2studio)	
C compiler (e2studio)	KPIT GNURL78-ELF Toolchain V13.02
Integrated development	IAR Embedded Workbench for Renesas RL78 V1.30.2
environment (IAR)	
C compiler (IAR)	IAR C/C++ Compiler for Renesas RL78 V1.30.2.50607

3. Related Application Note

The application note that is related to this application note is listed below for reference.

RL78/G13 Initialization (R01AN0451EJ0100) Application Note

Description of the Hardware

Hardware Configuration Example 4.1

Figure 4.1 shows an example of hardware configuration that is used for this application note.

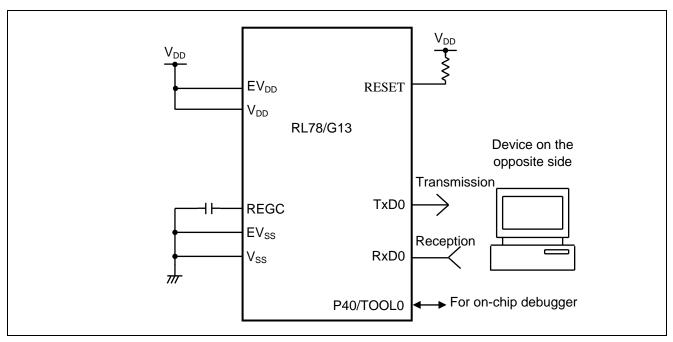


Figure 4.1 **Hardware Configuration**

- Caution: 1. The purpose of this circuit is only to provide the connection outline and the circuit is simplified accordingly. When designing and implementing an actual circuit, provide proper pin treatment and make sure that the hardware's electrical specifications are met (connect the input-only ports separately to V_{DD} or V_{SS} via a resistor).
 - 2. Connect any pins whose name begins with EV_{SS} to V_{SS} and any pins whose name begins with EV_{DD} to V_{DD}, respectively.
 - 3. V_{DD} must be held at not lower than the reset release voltage (V_{LVI}) that is specified as LVD.

4.2 List of Pins to be Used

Table 4.1 lists the pins to be used and their function.

Table 4.1 Pins to be Used and their Functions

Pin Name	I/O	Description
P12/SO00/TxD0/TOOLTxD	Output	Data transmission pin
P11/SI00/RxD0/TOOLRxD/SDA00	Input	Data reception pin

5. Description of the Software

5.1 Operation Outline

This sample code transmits, to the device on the opposite side, the data corresponding to that received from the device. If an error occurs, it transmits to the device the data corresponding to the error. Tables 5.1 and 5.2 show the correspondence between transmit data and receive data.

Table 5.1 Correspondence between Receive Data and Transmit Data

Receive Data	Response (Transmit) Data
T (54H)	O (4FH), K (4BH), "CR" (0DH), "LF" (0AH)
t (74H)	o (6FH), k (6BH), "CR" (0DH), "LF" (0AH)
Other than above	U (55H), C (43H), "CR" (0DH), "LF" (0AH)

Table 5.2 Correspondence between Error and Transmit Data

Error	Response (Transmit) Data
Parity error	P (50H), E (45H), "CR" (0DH), "LF" (0AH)
Framing error	F (46H), E (45H), "CR" (0DH), "LF" (0AH)
Overrun error	O (4FH), E (45H), "CR" (0DH), "LF" (0AH)

(1) Perform initial setting of UART.

<UART Setting Conditions>

- Use SAU0 channels 0 and 1 as UART.
- Use the P12/TxD0 pin and the P11/RxD0 pin for data output and data input, respectively.
- The data length is 8 bits.
- Set the data transfer direction to LSB first.
- Use even parity as the parity setting.
- Set the receive data level to standard.
- Set the transfer rate to 9600 bps.
- Use reception end interrupt (INTSR0), transmission end interrupt (INTST0), and error interrupt (INTSRE0).
- Set the interrupt priority orders of INTSR0, INTST0, and INTSRE0 to low priority.
- (2) After the system is made to enter a UART communication wait state by using the serial channel start register, a HALT instruction is executed. Processing is performed in response to reception end interrupt (INTSR0) and error interrupt (INTSRE0).
- When an INTSR0 occurs, the received data is taken in and the data corresponding to the received data is transmitted. When an INTSRE0 occurs, error handling is performed to transmit the data corresponding to the error.
- After data transmission, a HALT instruction is executed again to wait for reception end interrupt (INTSR0) and error interrupt (INTSRE0).

5.2 List of Option Byte Settings

Table 5.1 summarizes the settings of the option bytes.

Table 5.1 Option Byte Settings

Address	Value	Description	
000C0H/010C0H	01101110B	Disables the watchdog timer.	
		(Stops counting after the release from the reset state.)	
000C1H/010C1H	01111111B	LVD reset mode, 2.81 V (2.76 V to 2.87 V)	
000C2H/010C2H	11101000B	HS mode, HOCO: 32 MHz	
000C3H/010C3H	10000100B	Enables the on-chip debugger.	

5.3 List of Constants

Table 5.2 lists the constants that are used in this sample program.

Table 5.2 Constants for the Sample Program

Constant	Setting	Description
MessageOK[4]	"OK¥r¥n"	Response message to reception of "T".
Messageok[4]	"ok¥r¥n"	Response message to reception of "t".
MessageUC[4]	"UC¥r¥n"	Response message to reception of characters other than "T" or "t".
MessageFE[4]	"FE¥r¥n"	Response message to a framing error.
MessagePE[4]	"PE¥r¥n"	Response message to a parity error.
MessageOE[4]	"OE¥r¥n"	Response message to an overrun error.

5.4 List of Variables

Table 5.3 lists the global variable that is used by this sample program.

Table 5.3 Global Variable

Туре	Variable Name	Contents	Function Used
uint8_t	g_Uart0RxBuf	Receive data buffer	main()
uint8_t	gp_Uart0TxAddress	Transmit data pointer	R_UART0_Send, R_UART0_Interrupt_Send
uint16_t	g_Uart0TxCnt	Transmit data number counter	R_UART0_Send, R_UART0_Interrupt_Send
uint8_t	gp_Uart0RxAddress	Receive data pointer	R_UART0_Receive, R_UART0_Interrupt_Receive, R_UART0_Interrupt_Error
uint16_t	g_Uart0RxCnt	Receive data number counter	R_UART0_Receive, R_UART0_Interrupt_Receive
uint16_t	g_Uart0RxLen	Receive data number	R_UART0_Receive, R_UART0_Interrupt_Receive

5.5 List of Functions

Table 5.4 lists the functions that are used in this sample program.

Table 5.4 Functions

Function Name	Outline
R_UART0_Start	UART0 operation start
R_UART0_Receive	UART0 reception status initialization function
R_UART0_Send	UART0 data transmission function
R_UART0_Interrupt_Receive	UART0 reception end interrupt handling
R_UART0_Callback_ReceiveEnd	UART0 receive data classification function
R_UART0_Interrupt_Error	UART0 error interrupt handling
R_UART0_Callback_Error	UART0 reception error classification function
R_UART0_Interrupt_Send	UART0 transmission end interrupt handling
R_UART0_Callback_SendEnd	UART0 transmission end processing function

5.6 Function Specifications

This section describes the specifications for the functions that are used in this sample program.

[Function Name]R_ UART0_Start

Synopsis UART0 operation start

Header r_cg_macrodriver.h, r_cg_serial.h, and r_cg_userdefine.h

Declaration void R_ UART0_Start(void)

Explanation Starts operation of channel 0 of serial array units 0 and 1 to make the system enter a

communication wait state.

Arguments None
Return value None
Remarks None

[Function Name] R_UART0_Receive

Synopsis UART0 reception status initialization function

Header r_cg_macrodriver.h, r_cg_serial.h, r_cg_userdefine.h

Declaration MD_STATUS R_UART0_Receive(uint8_t *rxbuf, uint16_t rxnum)

Explanation Makes initial setting for UART0 reception.

Arguments uint8_t *rxbuf : [Receive data buffer address]

uint16_t rxnum : [Receive data buffer size]

Return value [MD_OK]: Reception setting is completed

[MD_ARGERROR]: Reception setting failed

Remarks None

[Function Name] R_UART0_Send

Synopsis UART0 data transmission function

Header r_cg_macrodriver.h, r_cg_serial.h, r_cg_userdefine.h

Declaration MD_STATUS R_UART0_Send(uint8_t* txbuf, uint16_t txnum)

Explanation Makes initial setting for UART0 transmission, and starts data transmission.

Arguments uint8_t *txbuf : [Transmit data buffer address]

uint16_t txnum : [Transmit data buffer size]

Return value [MD_OK]: Transmission setting is completed

[MD_ARGERROR]: Transmission setting failed

Remarks None

[Function Name] R_UART0_Interrupt_Receive

Synopsis UART0 reception end interrupt handling

Header r_cg_macrodriver.h, r_cg_serial.h, and r_cg_userdefine.h

Declaration __interrupt void R_UARTO_Interrupt_Receive(void)

Explanation Makes a response (data transmission) corresponding to received data.

Arguments None
Return value None
Remarks None

[Function Name]R_UART0_Interrupt_Error

Synopsis UART error interrupt function

 $\label{eq:condition} \textit{Header} \qquad \qquad \textit{r_cg_macrodriver.h, r_cg_serial.h, and r_cg_userdefine.h}$

Declaration ___interrupt void R_UART0_Interrupt_Error(void)

Explanation Transmits the data corresponding to a detected error.

Arguments None
Return value None
Remarks None

[Function Name] R_UART0_Callback_ReceiveEnd

Synopsis UART0 receive data classification function

Header r_cg_macrodriver.h, r_cg_serial.h, and r_cg_userdefine.h

Declaration void R_UART0_Callback_ReceiveEnd(void)

Explanation Clears the reception error flag.

Arguments None
Return value None
Remarks None

[Function Name] R_UART0_Callback_Error

Synopsis UARTO reception error classification function

Header r_cg_macrodriver.h, r_cg_serial.h, and r_cg_userdefine.h

Declaration void R_UART0_Callback_Error(uint8_t err_type)

Explanation Makes flag setting for transmission of the data corresponding to an error.

Arguments err_type : Error type

Return value None
Remarks None

[Function Name] R_UART0_Interrupt_Send

Synopsis UART0 transmission end interrupt handling

Header r_cg_macrodriver.h, r_cg_serial.h, and r_cg_userdefine.h

Declaration ___interrupt void R_UART0_Interrupt_Send(void)
Explanation Transmits a specified number of pieces of data.

Arguments None
Return value None
Remarks None

[Function Name] R_UART0_Callback_SendEnd

Synopsis UART0 transmission end processing function

Header r_cg_macrodriver.h, r_cg_serial.h, r_cg_userdefine.h

Declaration void R_UART0_Callback_SendEnd(void)
Explanation Makes transmission end flag setting.

Arguments None
Return value None
Remarks None

5.7 Flowcharts

Figure 5.1 shows the overall flow of the sample program described in this application note.

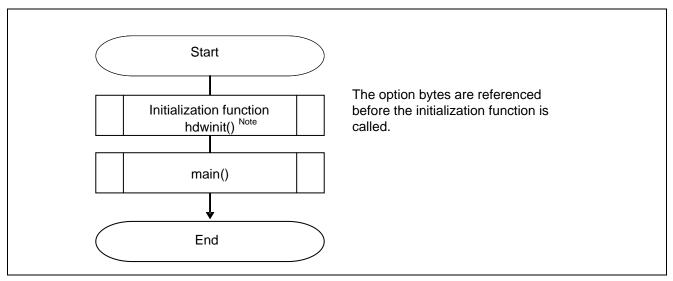


Figure 5.1 Overall Flow

5.7.1 Initialization Function

Figure 5.2 shows the flowchart for the initialization function.

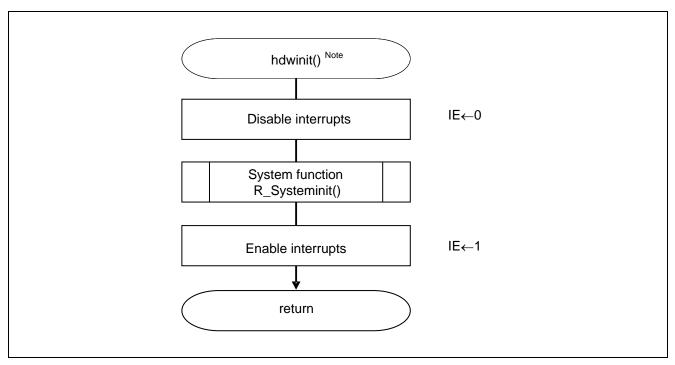


Figure 5.2 Initialization Function

Note: This function is used in the Renesas CubeSuite+ sample code. The function __low_level_init initializes the system in the IAR Workbench IDE-based sample code instead.

5.7.2 System Function

Figure 5.3 shows the flowchart for the system function.

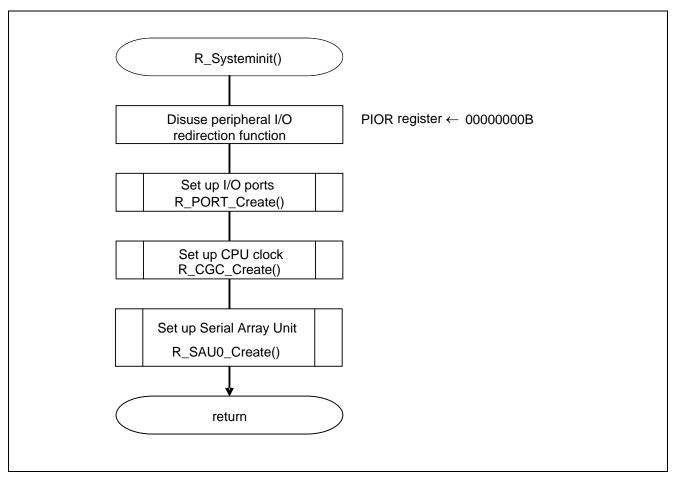


Figure 5.3 System Function

5.7.3 I/O Port Setup

Figure 5.4 shows the flowchart for setting up the I/O ports.

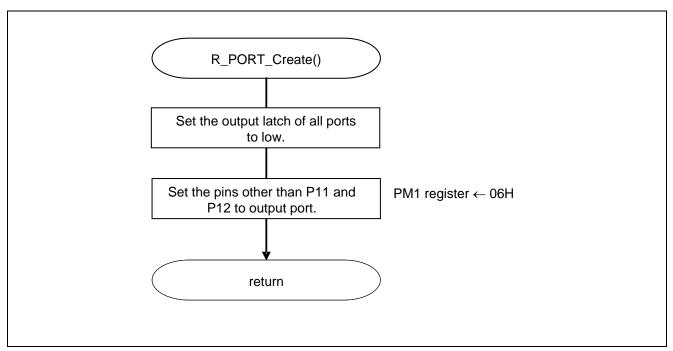


Figure 5.4 I/O Port Setup

Note: Refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN0451EJ0100) for the configuration of the unused ports.

Caution: Provide proper treatment for unused pins so that their electrical specifications are observed. Connect each of any unused input-only ports to V_{DD} or V_{SS} via a separate resistor.

5.7.4 CPU Clock Setup

Figure 5.5 shows the flowchart for setting up the CPU clock.

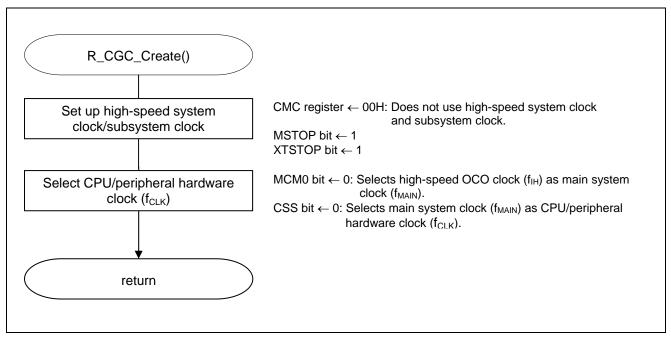


Figure 5.5 CPU Clock Setup

Caution: For details on the procedure for setting up the CPU clock (R_CGC_Create ()), refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN0451EJ0100).

5.7.5 Serial Array Unit Setup

Figure 5.6 shows the flowchart for setting up the serial array unit.

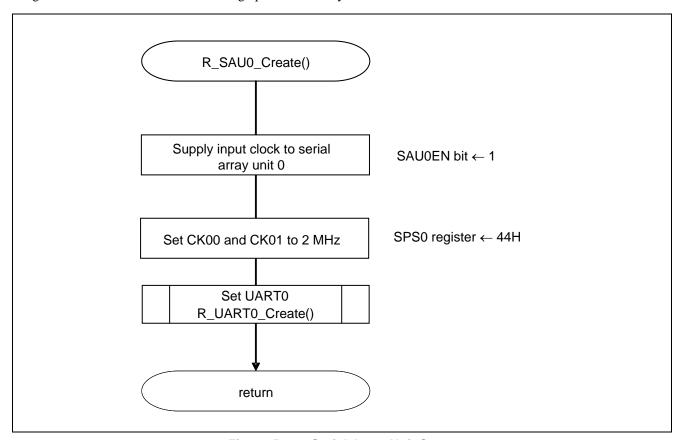


Figure 5.6 Serial Array Unit Setup

Start supplying clock to the SAU

• Peripheral enable register 0 (PER0) Clock supply

Symbol: PER0

7	6	5	4	3	2	1	0
RTCEN	IICA1EN	ADCEN	IICA0EN	SAU1EN	SAU0EN	TAU1EN	TAU0EN
Х	0	Х	Х	Х	1	0	Х

Bit 2

SAU0EN	Input clock control for serial array unit 0			
0	Stops supply of input clock.			
1	Starts supply of input clock.			

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

Select serial clock

• Serial clock select register 0 (SPS0) Operation clock setting

Symbol: SPS0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
I	0	0	0	0	0	0	0	_	PRS							
	U	U	U	U	0	U	U	U	013	012	011	010	003	002	001	000
I	0	0	0	0	0	0	0	0	0	1	0	0	0	1	0	0

Bits 7 to 0

PRS	PRS	PRS	PRS		Operati	ion clock (Cl	K00) selection	on (n = 0, 1)		
0n3	0n2	0n1	0n0		f _{CLK} = 2 MHz	f _{CLK} = 5 MHz	f _{CLK} = 10 MHz	f _{CLK} = 20 MHz	f _{CLK} = 32 MHz	
0	0	0	0	f _{CLK}	2 MHz	5 MHz	10 MHz	20 MHz	32 MHz	
0	0	0	1	f _{CLK} /2	1 MHz	2.5 MHz	5 MHz	10 MHz	16 MHz	
0	0	1	0	f _{CLK} /2 ²	500 kHz	1.25 MHz	2.5 MHz	5 MHz	8 MHz	
0	0	1	1	f _{CLK} /2 ³	250 kHz	625 kHz	1.25 MHz	2.5 MHz	4 MHz	
0	1	0	0	f _{CLK} /2 ⁴	125 kHz	312.5 kHz	625 kHz	1.25 MHz	2 MHz	
0	1	0	1	f _{CLK} /2 ⁵	62.5 kHz	156.2 kHz	312.5 kHz	625 kHz	1 MHz	
0	1	1	0	f _{CLK} /2 ⁶	31.25 kHz	78.1 kHz	156.2 kHz	312.5 kHz	500 kHz	
0	1	1	1	f _{CLK} /2 ⁷	15.62 kHz	39.1 kHz	78.1 kHz	156.2 kHz	250 kHz	
1	0	0	0	f _{CLK} /2 ⁸	7.81 kHz	19.5 kHz	39.1 kHz	78.1 kHz	125 kHz	
1	0	0	1	f _{CLK} /2 ⁹	3.91 kHz	9.76 kHz	19.5 kHz	39.1 kHz	62.5 kHz	
1	0	1	0	f _{CLK} /2 ¹⁰	1.95 kHz	4.88 kHz	9.76 kHz	19.5 kHz	31.25 kHz	
1	0	1	1	f _{CLK} /2 ¹¹	977 Hz	2.44 kHz	4.88 kHz	9.76 kHz	15.6 kHz	
Ot	her tha	an abov	/e.	Setting prohibited.						

5.7.6 UART0 Setup

Figures 5.7, 5.8, and 5.9 show the flowcharts for setting up UARTO.

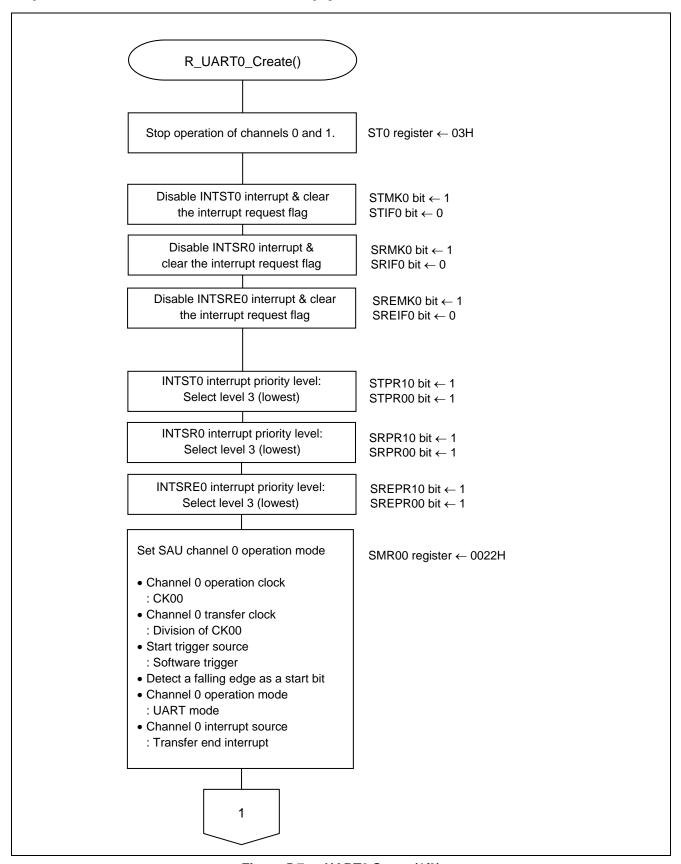


Figure 5.7 UART0 Setup (1/3)

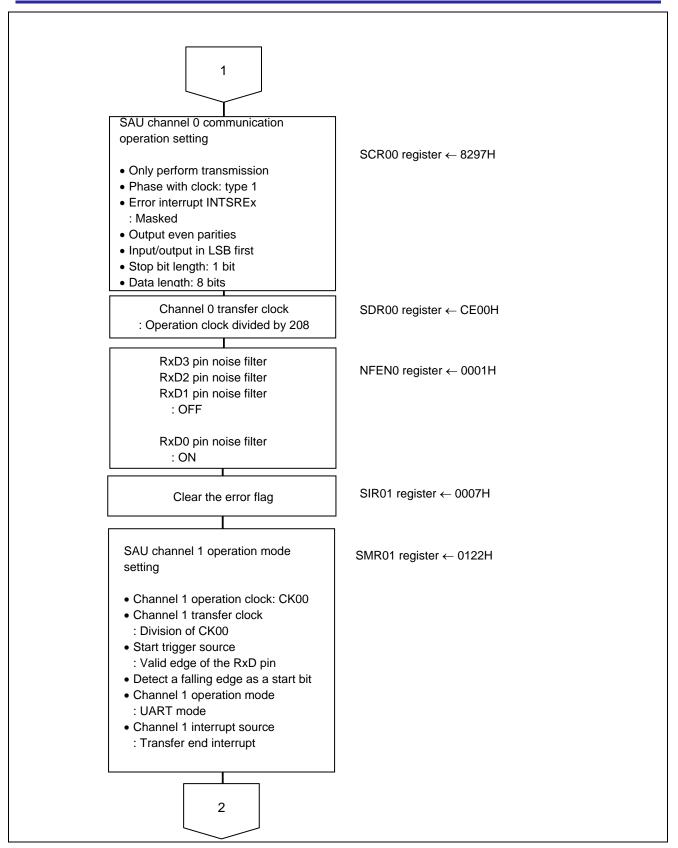


Figure 5.8 UART0 Setup (2/3)

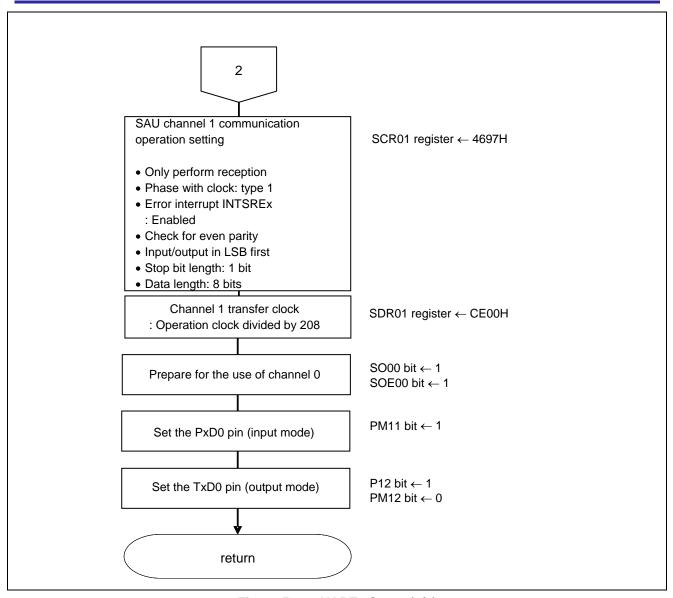


Figure 5.9 UART0 Setup (3/3)

Transmission channel operation mode setting

• Serial mode register 00 (SMR00) Interrupt source Operation mode Transfer clock selection f_{MCK} selection

Symbol: SMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS 00	CCS 00	0	0	0	0	0	0	0	0	1	0	0	MD 002	MD 001	MD 000
0	0	0	0	0	0	0	0	0	0	1	0	0	0	1	0

Bit 15

CKS00	Channel 0 operation clock (f _{MCK}) selection
0	Prescaler output clock CK00 configured by the SPS0 register
1	Prescaler output clock CK01 configured by the SPS0 register

Bit 14

CCS00	Channel 0 transfer clock (TCLK) selection
0	Clock obtained by dividing the operation clock f _{MCK} specified by the CKS00 bit.
1	Clock input from the SCK pin.

Bits 2 and 1

MD002	MD001	Channel 0 operation mode setting
0	0	CSI mode
0	1	UART mode
1	0	Simplified I ² C mode
1	1	Setting prohibited

Bit 0

MD000	Channel 0 interrupt source selection
0	Transfer end interrupt
1	Buffer empty interrupt

Transmission channel communication operation setting

• Serial communication operation setting register 00 (SCR00)

Data length setting, data transfer order, error interrupt signal mask availability, and operation mode

Symbol: SCR00

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Ī	TXE	RXE	DAP	CKP	0	EOC	PTC	PTC	DIR	0	SLC	SLC	0	4	DLS	DLS
	00	00	00	00	U	00	001	000	00	U	001	000	U	ı	001	000
Ī	1	0	0	0	0	0	1	0	1	0	0	1	0	1	1	1

Bits 15 and 14

TXE00	RXE00	Channel 0 operation mode setting					
0	0	Communication prohibited					
0	1	ception Only					
1	0	Transmission only					
1	1	Both transmission and reception					

Bit 10

EOC00	Error interrupt signal (INTSREx $(x = 0, 1)$) mask availability selection
0	Error interrupt INTSREx is masked
1	Generation of error interrupt INTSREx is enabled

Bits 9 and 8

DTC004	DTCOOO	Parity bit setting in UART mode							
PICOUI	PTC000	Transmission	Reception						
0	0	No parity bit is output	Data is received without parity						
0	1	0 parity is output	No parity check is made						
1	0	Even parity is output	Check is made for even parity						
1	1	Odd parity is output	Check is made for odd parity						

Bit 7

DIR0	00	Selection of data transfer order in CSI and UART modes
0		Input and output in MSB first
1		Input and output in LSB first

Bits 5 and 4

SLC001	SLC000	Stop bit setting in UART mode
0	0	No stop bit
0	1	Stop bit length = 1 bit
1	0	Stop bit length = 2 bits
1	1	Setting prohibited

Symbol: SCR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TXE	RXE	DAP	CKP	0	EOC	PTC	PTC	DIR	0	SLC	SLC	0	4	DLS	DLS
00	00	00	00	U	00	001	000	00	0	001	000	O	ı	001	000
1	0	0	0	0	0	1	0	1	0	0	1	0	1	1	1

Bits 1 and 0

DLS001	DLS000	Data length setting in CSI mode					
0	1	9-bit data length					
1	0	it data length					
1	1	8-bit data length					
Others		Setting prohibited					

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

Transmission channel transfer clock setting

• Serial data register 00 (SDR00) Transfer clock frequency: $f_{MCK}/208$ (≈ 9600 Hz)

Symbol: SDR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	1	0	0	1	1	1	0	Х	Х	Х	Х	Х	Х	Х	Х

Bits 15 to 9

		SDF	R00[1	5:9]			Transfer clock setting by dividing operation clock (f _{MCK})
0	0	0	0	0	0	0	f _{MCK} /2
0	0	0	0	0	0	1	f _{MCK} /4
0	0	0	0	0	1	0	f _{MCK} /6
0	0	0	0	0	1	1	f _{MCK} /8
		٠				٠	•
1	1	0	0	1	1	1	f _{MCK} /208
		٠				٠	•
1	1	1	1	1	1	0	f _{MCK} /254
1	1	1	1	1	1	1	f _{MCK} /256

Reception channel operation mode setting

• Serial mode register 01 (SMR01)

Interrupt source

Operation mode

Transfer clock selection

 f_{MCK} selection

Symbol: SMR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS 01	CCS 01	0	0	0	0	0	STS 01	0	SIS 010	1	0	0	MD 012	MD 011	MD 010
0	0	0	0	0	0	0	1	0	0	1	0	0	0	1	0

Bit 15

CKS01	Channel 1 operation clock (f _{MCK}) selection
0	Prescaler output clock CK00 configured by the SPS0 register
1	Prescaler output clock CK01 configured by the SPS0 register

Bit 14

CCS01	Channel 1 transfer clock (TCLK) selection
0	Clock obtained by dividing the operation clock f _{MCK} specified by the CKS01 bit
1	Clock input from the SCK pin

Bit 8

STS01	Start trigger source selection
0	Only software trigger is valid
1	Valid edge of the RxD pin (selected during UART reception)

Bit 6

SIS010	Control of receive data level inversion on channel 1 in UART mode
0	Falling edge is detected as a start bit
1	Rising edge is detected as a start bit

Bits 2 and 1

MD012	MD011	Channel 1 operation mode setting
0	0	CSI mode
0	1	UART mode
1	0	Simplified I ² C mode
1	1	Setting prohibited

Bit 0

MD010	Channel 1 interrupt source selection
0	Transfer end interrupt
1	Buffer empty interrupt

Reception channel communication operation setting

• Serial communication operation setting register 01 (SCR01)

Data length setting, data transfer order, error interrupt signal mask availability, and operation mode

Symbol: SCR01

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	TXE	RXE	DAP	CKP	0	EOC	PTC	PTC	DIR	0	SLC	SLC	_	4	DLS	DLS
	01	01	01	01	U	01	011	010	01	U	011	010	U	'	011	010
Ī	0	1	0	0	0	1	1	0	1	0	0	1	0	1	1	1

Bits 15 and 14

TXE01	RXE01	Channel 1 operation mode setting
0	0	Communication prohibited
0	1	Reception only
1	0	Transmission only
1	1	Both transmission and reception

For UART reception, wait for 4 f_{CLK} clock cycles or more before setting SS01 to 1, after setting the RXE01 bit of the SCR01 register to 1.

Bit 10

EOC01	Error interrupt signal (INTSRE1) mask availability selection
0	Error interrupt INTSRE1 is masked
1	Generation of error interrupt INTSRE1 is enabled

Bits 9 and 8

DTC011	PTC010	Parity bit setting in UART mode									
FICUII	F10010	Transmission	Reception								
0	0	No parity bit is output	Data is received without parity								
0	1	0 parity is output	No parity check is made								
1	0	Even parity is output	Check is made for even parity								
1	1	Odd parity is output	Check is made for odd parity								

Bit 7

DIR01	Selection of data transfer order in CSI and UART modes									
0	nput and output in MSB first									
1	Input and output in LSB first									

Bits 5 and 4

SLC011	SLC010	Stop bit setting in UART mode
0	0	No stop bit
0	1	Stop bit length = 1 bit
1	0	Stop bit length = 2 bits
1	1	Setting prohibited

Symbol: SCR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TXE	RXE	DAP	CKP	0	EOC	PTC	PTC	DIR	0	SLC	SLC	0	4	DLS	DLS
01	01	01	01	U	01	011	010	01	U	011	010	U	I	011	010
0	1	0	0	0	1	1	0	1	0	0	1	0	1	1	1

Bits 1 and 0

DLS011	DLS010	Data length setting in CSI mode
0	1	9-bit data length
1	0	7-bit data length
1	1	8-bit data length
others		Setting prohibited

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

Reception transfer clock setting

• Serial data register 01 (SDR01) Transfer clock frequency: $f_{MCK}/208$ ($\approx 9600 \text{ Hz}$)

Symbol: SDR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	1	0	0	1	1	1	0								

Bits 15 to 9

		SDF	R01[1	5:9]			Transfer clock setting by dividing operation clock (f _{MCK})
0	0	0	0	0	0	0	f _{MCK} /2
0	0	0	0	0	0	1	f _{MCK} /4
0	0	0	0	0	1	0	f _{MCK} /6
0	0	0	0	0	1	1	f _{MCK} /8
1	1	0	0	1	1	1	f _{MCK} /208
1	1	1	1	1	1	0	f _{MCK} /254
1	1	1	1	1	1	1	f _{MCK} /256

Initial output level setting

• Serial output register 0 (SO0) Initial output: 1

Symbol: SO0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Ī	0	0	0	0	СКО	СКО	СКО	СКО	0	0	0	0	SO	SO	SO	SO
L	U	O	U	U	03	02	01	00	U	U	U	U	03	02	01	00
	0	0	0	0	Х	Х	Х	Х	0	0	0	0	Х	Х	Х	1

Bit 0

SO00	Channel 0 serial data output
0	Serial data output value is "0"
1	Serial data output value is "1"

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

Enabling of data output on target channel

• Serial output enable register 0 (SOE0) Output enable

Symbol: SOE0

_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0	0	0	0	0	0	0	0	0	0	SOE 03	SOE 02	SOE 01	SOE 00
	0	0	0	0	0	0	0	0	0	0	0	0	Х	Х	Х	1

Bit 0

SOE00	Channel 0 serial output enable/stop				
0	Serial communication output is stopped				
1	Serial communication output is enabled				

Port setting

- Port register 1 (P1)
- Port mode register 1 (PM1)
 Port setting for each of transmit data and receive data.

Symbol: P1

7	6	5	4	3	2	1	0
P17	P16	P15	P14	P13	P12	P11	P10
Х	Х	Х	Х	Х	1	Х	Х

Bit 2

P12	Output data control (in output mode)						
0	0 is output						
1	1 is output						

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

Symbol: PM1

7	6	5	4	3	2	1	0
PM17	PM16	PM15	PM14	PM13	PM12	PM11	PM10
Х	Х	Х	Х	Х	0	1	Х

Bit 2

PM12	P12 I/O mode selection				
0	Output mode (output buffer is on)				
1	Input mode (output buffer is off)				

Bit 1

PM11	P11 I/O mode selection
0	Output mode (output buffer is on)
1	Input mode (output buffer is off)

5.7.7 Main Function

Figures 5.10 and 5.11 show the flowchart for the main function.

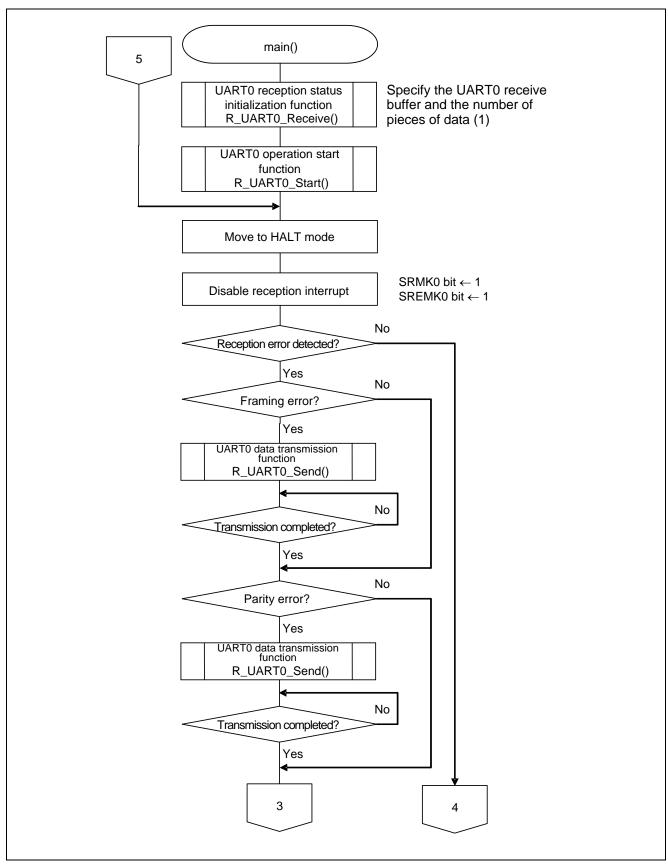


Figure 5.10 Main Function (1/2)

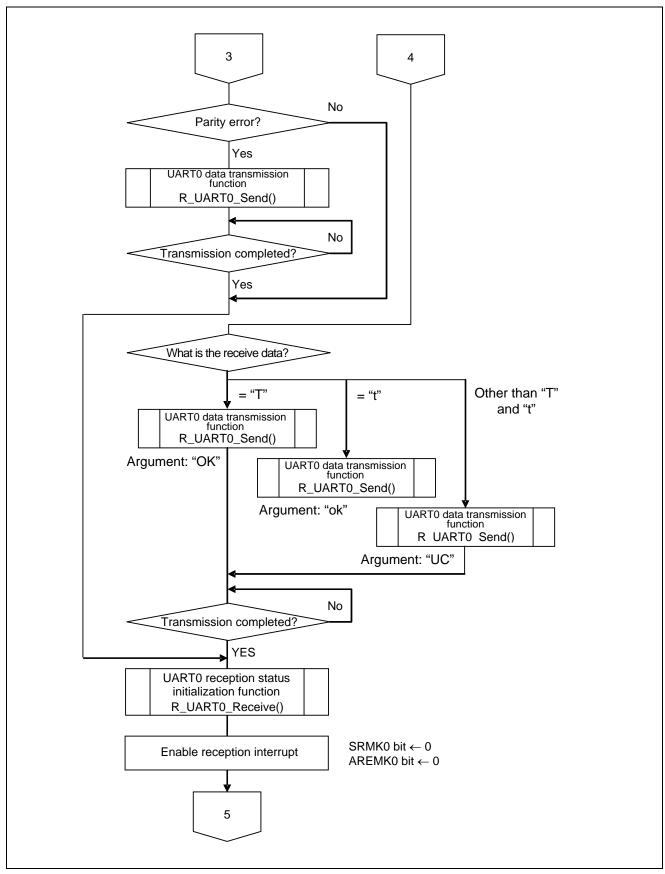


Figure 5.11 Main Function (2/2)

5.7.8 UARTO Reception Status Initialization Function

Figure 5.12 shows the flowchart for the UART0 reception status initialization function.

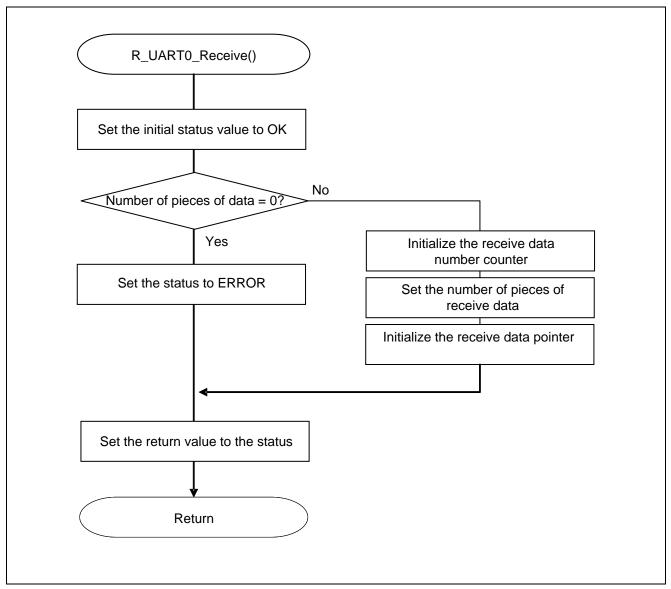


Figure 5.12 UARTO Reception Status Initialization Function

5.7.9 UARTO Operation Start Function

Figure 5.13 shows the flowchart for the UARTO operation start function.

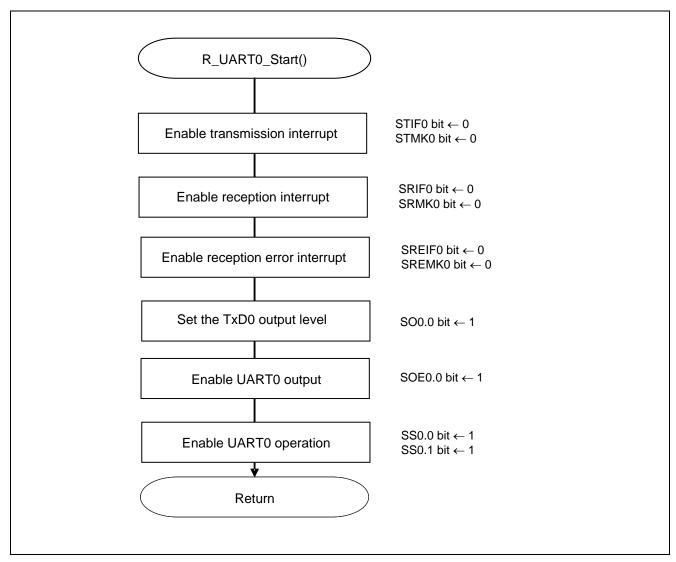


Figure 5.13 UART0 Operation Start Function

Interrupt setting

- Interrupt request flag register (IF0H) Clear the interrupt request flag
- Interrupt mask flag register (MK0H) Cancel interrupt mask

Symbol: IF0H

7	6	5	4	3	2	1	0
SREIF0 TMIF01H	SRIF0 CSIIF01 IICIF01	STIF0 CSIIF00 IICIF00	DMAIF1	DMAIF0	SREIF2 TMIF11H		STIF2 CSIIF20 IICIF20
0	0	0	X	X	X	X	X

Bit 7

SREIF0	Interrupt request flag				
0	No interrupt request signal is generated				
1	Interrupt request is generated, interrupt request status				

Bit 6

SRIF0	Interrupt request flag				
0	No interrupt request signal is generated				
1	Interrupt request is generated, interrupt request status				

Bit 5

STIF0	Interrupt request flag					
0	No interrupt request signal is generated					
1	Interrupt request is generated, interrupt request status					

Symbol: MK0H

7	6	5	4	3	2	1	0
SREMK0	SRMK0	STMK0		1 DMAMK0	SREMK2 TMMK11H	SRMK2	
SKEIVIKU	CSIMK01	CSIMK00	DMAMK1			CSIMK21	CSIMK20
TIVIIVIKUTH	IICMK01	IICMK00			TIVIIVIKTIT	IICMK21	IICMK20
0	0	0	X	X	X	X	X

Bit 7

SREMK0	Interrupt processing control					
0	Enables interrupt processing.					
1	Disables interrupt processing.					

Bit 6

SRMK0	Interrupt processing control					
0	Enables interrupt processing.					
1	Disables interrupt processing.					

Bit 5

STMK0	Interrupt processing control					
0	Enables interrupt processing.					
1	Disables interrupt processing.					

Transition to communication wait state

• Serial channel start register 0 (SS0) Operation start

Symbol: SS0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
I	0	0	0	0	0	0	0	0	0	0	0	0	SS03	SS02	SS01	SS00
ſ	0	0	0	0	0	0	0	0	0	0	0	0	X ^{Note}	Х	1 ^{Note}	1

Bits 3 to 0

SS0n	Channel n operation start trigger					
0	rigger operation is not performed					
1	SE0n is set to 1, and a communication wait state is entered.					

Note For UART reception, wait for $4\,f_{CLK}$ clock cycles or more before setting SS0n to 1, after setting the RXE0n bit of the SCR0n register to 1.

5.7.10 INTSR0 Interrupt Service Routine

Figure 5.14 shows the flowchart for the INTSR0 interrupt service routine.

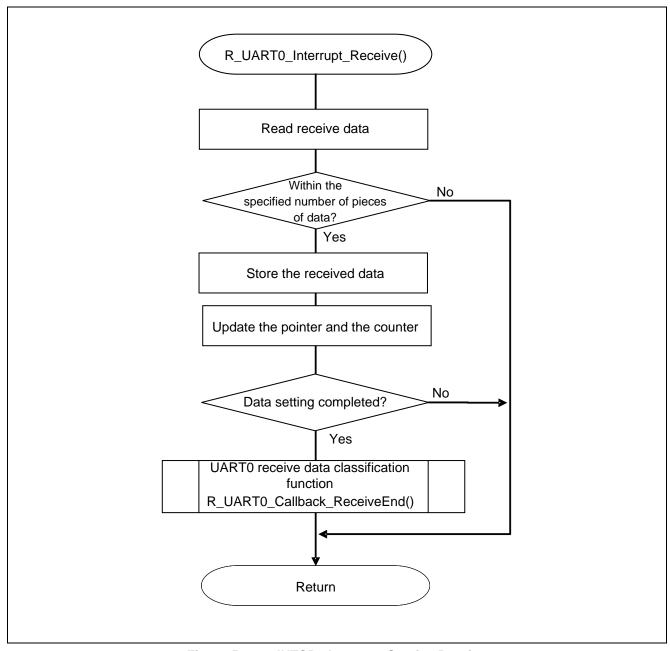


Figure 5.14 INTSR0 Interrupt Service Routine

5.7.11 UARTO Receive Data Classification Function

Figure 5.15 shows the flowchart for the UART0 receive data classification function.

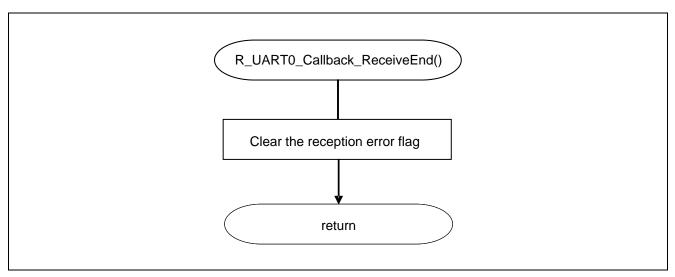


Figure 5.15 UARTO Receive Data Classification Function

5.7.12 UARTO Data Transmission Function

Figure 5.16 shows the flowchart for the UART0 data transmission function.

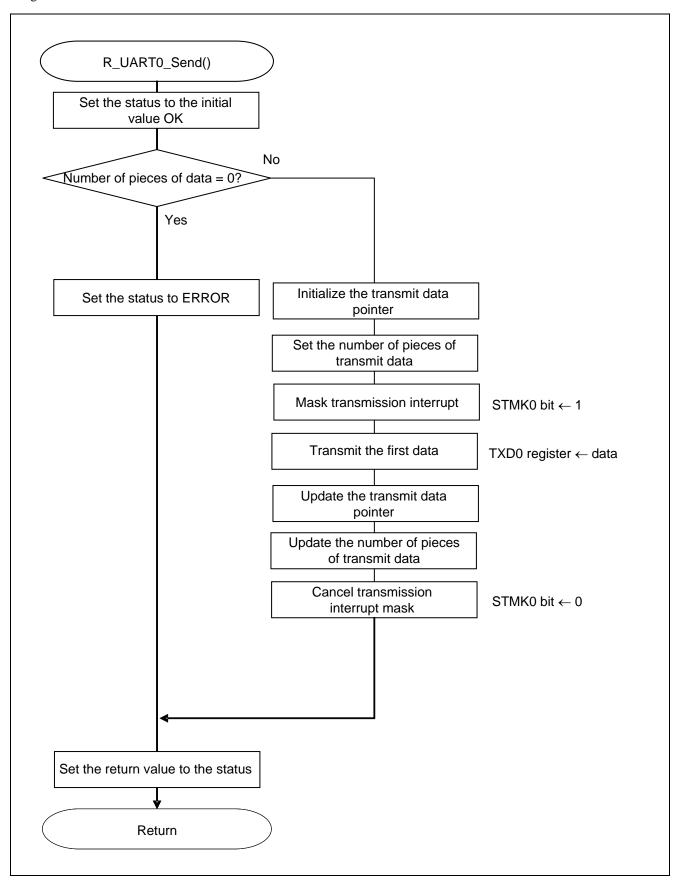


Figure 5.16 UARTO Data Transmission Function

5.7.13 UARTO Reception Error Interrupt Function

Figure 5.17 shows the flowchart for the UART0 reception error interrupt function.

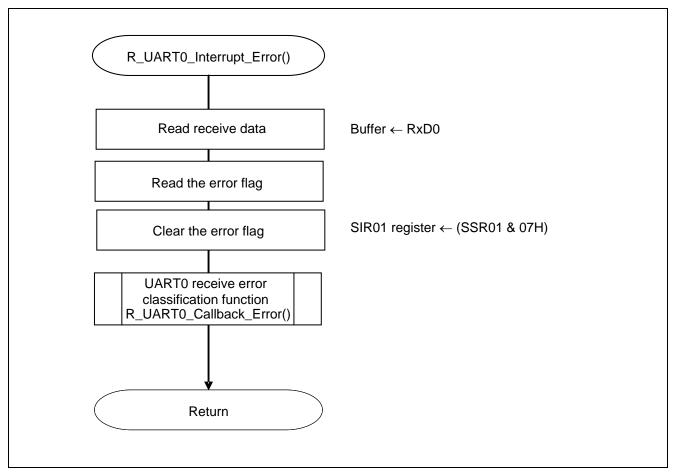


Figure 5.17 UARTO Reception Error Interrupt Function

5.7.14 UARTO Reception Error Classification Function

Figure 5.18 shows the flowchart for the UART0 reception error classification function.

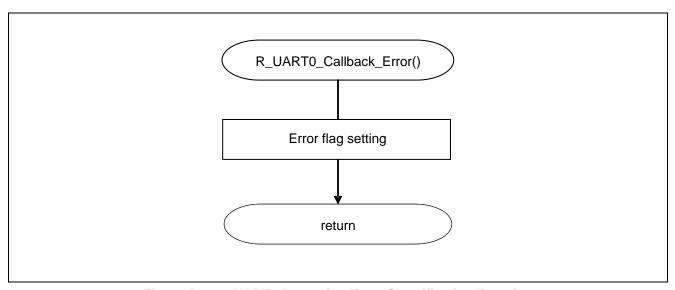


Figure 5.18 UART0 Reception Error Classification Function

5.7.15 INTST0 Interrupt Service Routine

Figure 5.19 shows the flowchart for the INTST0 interrupt service routine.

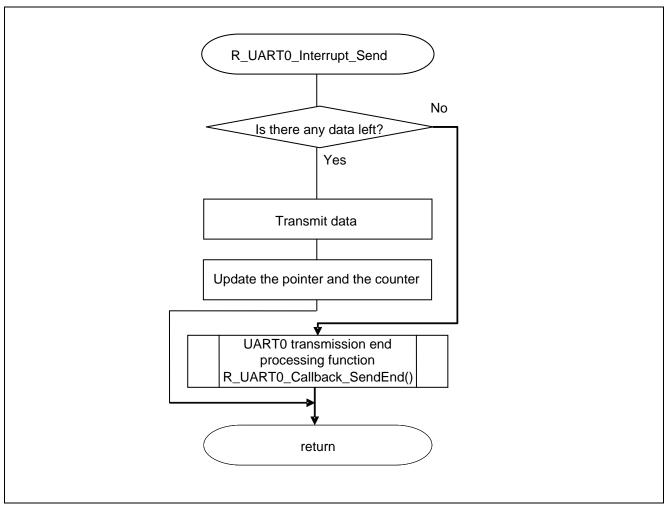


Figure 5.19 INTST0 Interrupt Service Routine

5.7.16 UARTO Transmission End Processing Function

Figure 5.20 shows the flowchart for the UART0 transmission end processing function.

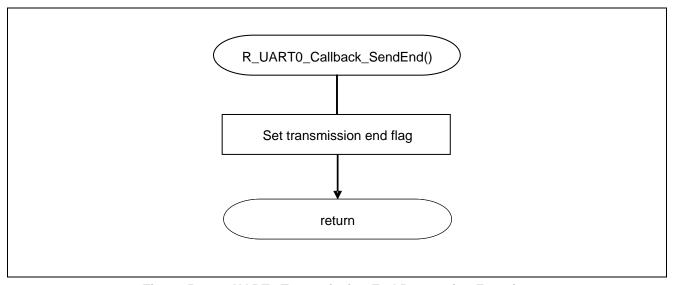


Figure 5.20 UARTO Transmission End Processing Function

6. Sample Code

The sample code is available on the Renesas Electronics Website.

7. Documents for Reference

RL78/G13 User's Manual: Hardware Rev.0.07 (R01UH0146EJ0007)

RL78 Family User's Manual: Software Rev.1.00 (R01US0015EJ0100)

(The latest versions of the documents are available on the Renesas Electronics Website.)

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Revision Record	RL78/G13 Serial Array Unit (UART Communication)
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Davi	Dete	Description					
Rev.	Date	Page	Summary				
1.00	2011.09.30	_	First edition issued				
2.00	2014.03.24	5 Table 2.1: Added e2studio and IAR version information					
		12	Figure 5.1, Figure 5.2: Added note				
			Figure 5.2: Fixed typo in a function name				
		13	Figure 5.3: Fixed typo in the function name				

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The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

1. Handling of Unused Pins

- Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.
 - The input pins of CMOS products are generally in the high-impedance state. In operation with unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

- The state of the product is undefined at the moment when power is supplied.
 - The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
 In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.
 In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.
- 3. Prohibition of Access to Reserved Addresses
- Access to reserved addresses is prohibited.
 - The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.
- 4. Clock Signals
- After applying a reset, only release the reset line after the operating clock signal has become stable.
 When switching the clock signal during program execution, wait until the target clock signal has stabilized.
 - When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.
- 5. Differences between Products
- Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.
 - The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

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