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DATA SHEET



MOS INTEGRATED CIRCUIT μ PD168002

MONOLITHIC 6-CHANNEL H-BRIDGE DRIVER

DESCRIPTION

The μ PD168002 is a monolithic 6-channel H-bridge driver that consists of a CMOS control circuit and a MOS output stage. It can reduce the current consumption and the voltage loss at the output stage compared with conventional driver using bipolar transistors, thanks to employment of a MOS process. The μ PD168002 employs P-channel MOS FET in the output stage, and is eliminated the charge pump circuit. Therefore, the circuit current consumption during operation can be significantly reduced.

The package is a 48-pin TQFP that helps reduce the mounting area and height.

The μ PD168002 can be used to drive one stepping motor and four DC motors, and is suitable for the motor driver of CD-ROM/CD audios.

FEATURES

- Six H-bridge circuits employing power MOS FET
- Low current consumption due to elimination of charge pump circuit
- Input logic frequency: 100 kHz supported
- 3 V power supply supported for logic

Minimum operating supply voltage: 2.7 V

• 5 V, 10 V power supply supported for motor

ch1, ch2, ch5 and ch6: 10 V driving

ch3 and ch4: 5 V driving

• Undervoltage lockout circuit

Shuts down the internal circuit at VDD = 1.7 V TYP.

- · Overheat protection circuit
- 48-pin TQFP (□7 mm)

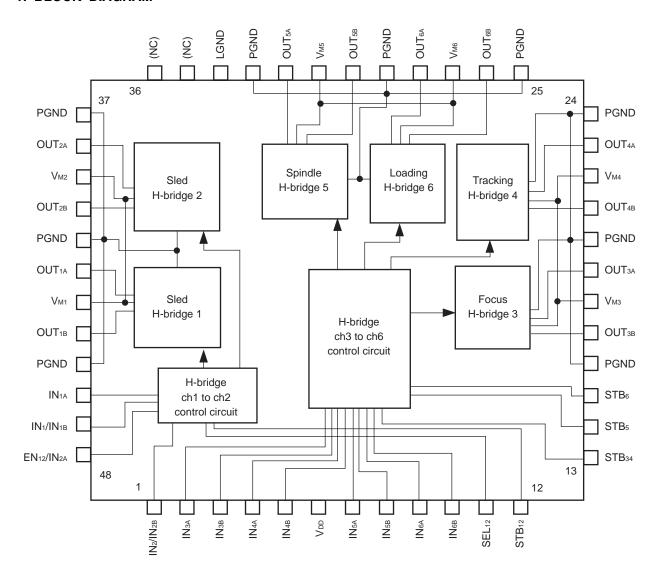
ORDERING INFORMATION

Part Number	Package
μ PD168002GA-9EU	48-pin plastic TQFP (fine pitch) (7 x 7)

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1. BLOCK DIAGRAM



Cautions 1. Be sure to connect all of the pins which have more than one.

- A pull-down resistor (50 to 200 kΩ) is internally connected to the logic input pins.
 Logic input pins: IN1A, IN1/IN1B, EN12/IN2A, IN2/IN2B, IN3A, IN3B, IN4A, IN4B, IN5A, IN5B, IN6A, IN6B, SEL12, STB12, STB34, STB5 and STB6
- 3. The power supply pins for motor, V_{M1} and V_{M2}, V_{M3} and V_{M4}, and V_{M5} and V_{M6}, are connected each other inside. These pins must be applied from the same potential.



2. PIN FUNCTIONS

Package: 48-pin plastic TQFP (fine pitch) (7 x 7)

(1/2)

	1		(1/2)
Pin No.	Pin Name	Function	
1	IN2/IN2B	ch2 input pin or ch2 input pin B	
2	INза	ch3 input pin A	
3	INзв	ch3 input pin B	
4	IN _{4A}	ch4 input pin A	
5	IN _{4B}	ch4 input pin B	
6	V _{DD}	Logic power supply pin	
7	IN _{5A}	ch5 input pin A	
8	IN _{5B}	ch5 input pin B	
9	IN _{6A}	ch6 input pin A	
10	IN _{6B}	ch6 input pin B	
11	SEL ₁₂	ch1 and ch2 input logic selection pin	
12	STB ₁₂	ch1 and ch2 standby pin	
13	STB ₃₄	ch3 and ch4 standby pin	
14	STB₅	ch5 standby pin	
15	STB ₆	ch6 standby pin	
16	PGND	GND pin	
17	OUT _{3B}	ch3 output B	
18	Vмз	ch3 power supply pin	
19	OUT _{3A}	ch3 output A	
20	PGND	GND pin	
21	OUT _{4B}	ch4 output B	
22	V _{M4}	ch4 power supply pin	
23	OUT _{4A}	ch4 output A	
24	PGND	GND pin	
25	PGND	GND pin	
26	OUT _{6B}	ch6 output B	
27	V м6	ch6 power supply pin	
28	OUT _{6A}	ch6 output A	
29	PGND	GND pin	
30	OUT _{5B}	ch5 output B	
31	V м5	ch5 power supply pin	
32	OUT _{5A}	ch5 output A	
33	PGND	GND pin	
34	LGND	GND pin	
35	(NC)	Unused	

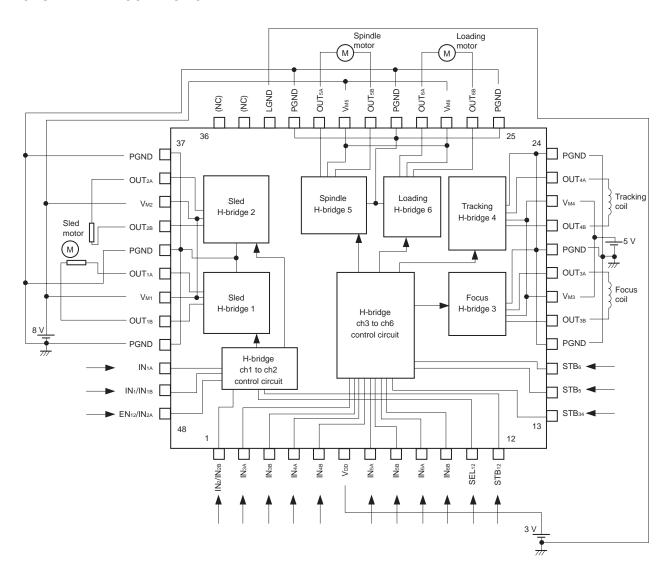
Caution Be sure to connect all of the pins which have more than one.

(2/2)

Pin No.	Pin Name	Function
36	(NC)	Unused
37	PGND	GND pin
38	OUT _{2A}	ch2 output A
39	V _{M2}	ch2 power supply pin
40	OUT _{2B}	ch2 output B
41	PGND	GND pin
42	OUT _{1A}	ch1 output A
43	V _{M1}	ch1 power supply pin
44	OUT _{1B}	ch1 output B
45	PGND	GND pin
46	IN _{1A}	ch1 input pin A
47	IN1/IN1B	ch1 input pin or ch1 input pin B
48	EN12/IN2A	ch1 and ch2 control pin or ch2 input pin A

Caution Be sure to connect all of the pins which have more than one.

3. STANDARD CONNECTION EXAMPLE



Caution This diagram is the example of connection and is not what was created as a purpose of mass production.

Data Sheet S16040EJ1V0DS

4. FUNCTION OPERATION TABLE

4.1 Relationship between SEL Pin and Input Pins

SEL pin	46-pin	47-pin	48-pin	1-pin	
L	Unused	ch1 input pin IN₁	ch1 and ch2 control pin EN ₁₂	ch2 input pin IN2	
Н	ch1 input pin IN _{1A}	ch1 input pin IN₁в	ch2 input pin IN₂A	ch2 input pin IN₂в	

Remark L: Low level, H: High level

4.2 ch1 and ch2 Input/output Truth Table

 $(1) SEL_{12} = L$

In	put	Out	tput	Output Status
EN ₁₂	IN	OUTA	OUT _B	
L	х	Z	Z	Stop (output high impedance)
Н	L	Н	L	Forward revolution (OUT _A \rightarrow OUT _B)
Н	Н	L	Н	Reverse revolution (OUT _B \rightarrow OUT _A)

Remark x: High level or low level, Z: Output high impedance

(2) $SEL_{12} = H$

Ir	nput	Out	tput	Output Status
INA	INв	OUTA	OUT _B	
L	L	L	L	Stop (short brake)
L	Н	L	Н	Reverse revolution (OUT _B \rightarrow OUT _A)
Н	L	Н	L	Forward revolution (OUT _A \rightarrow OUT _B)
Н	Н	Н	Н	Stop (short brake)

4.3 ch3 to ch5 Input/output Truth Table

Inp	out	Out	put	Output Status
INA	INв	OUT _A OUT _B		
L	L	L	L	Stop (short brake)
L	Н	L	Н	Reverse revolution (OUT _B \rightarrow OUT _A)
Н	L	Н	L	Forward revolution (OUT _A \rightarrow OUT _B)
(H)	(H)	(H)	(H)	Stop (short brake)

Caution At ch3 to ch5, inputting IN $_{A}$ = H and IN $_{B}$ = H prohibits.

4.4 ch6 Input/output Truth Table

In	put	Out	tput	Output Status
INA	INв	OUTA	OUT _B	
L	L	L	L	Stop (short brake)
L	Н	L	Н	Reverse revolution (OUT _B \rightarrow OUT _A)
Н	L	Н	L	Forward revolution (OUT _A \rightarrow OUT _B)
Н	Н	Н	Н	Stop (short brake)

5. STANDBY FUNCTION

The μ PD168002 realizes a standby function by combination of an input signal.

The specified output is set to high impedance (Hi-Z) status by setting STB to low level.

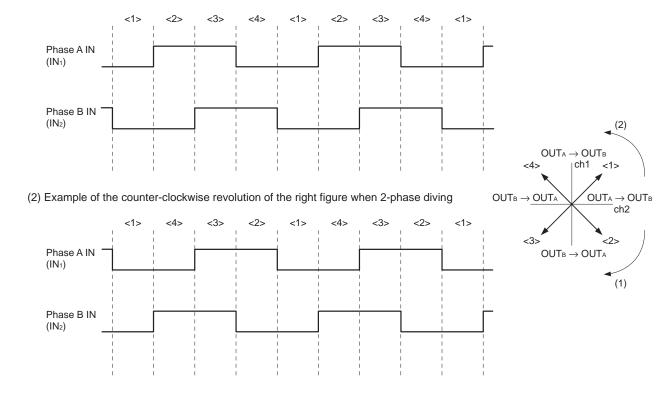
Each pin can be independently controlled, and can be set to standby status of the self current consumption of the IC reduced as much as possible by setting all pins to low level. In the standby status, the overheat protection circuit and the undervoltage lockout circuit do not operate.

Pin	Function	Output Status when Pin = L					
		ch1	ch2	ch3	ch4	ch5	ch6
STB ₁₂	Sled block standby	Hi-Z	Hi-Z	ON	ON	ON	ON
STB ₃₄	Focus and tracking block standby	ON	ON	Hi-Z	Hi-Z	ON	ON
STB₅	Spindle block standby	ON	ON	ON	ON	Hi-Z	ON
STB ₆	Loading block standby	ON	ON	ON	ON	ON	Hi-Z

Remark ON: Status which can turn on output, Hi-Z: High impedance

6. OPERATION WAVEFORM EXAMPLES

(1) Example of the clockwise revolution of the right figure when 2-phase diving



Remark $SEL_{12} = L$, $EN_{12} = H$



7. ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings

(T_A = 25°C, glass epoxy board of 100 mm x 100 mm x 1 mm with copper foil area of 15%)

Parameter	Symbol	Condition	Rating	Unit
Power supply voltage	V _{DD}	Control block	-0.5 to +6.0	٧
	Vм	Motor block (ch3 and ch4)	-0.5 to +6.0	V
		Motor block (ch1, ch2, ch5 and ch6)	-0.5 to +12.0	V
Input voltage	VIN		-0.5 to V _{DD} + 0.5	V
Output pin voltage 1	V _{OUT1}	Motor block (ch3 and ch4)	6.2	V
Output pin voltage 2	V _{OUT2}	Motor block (ch1, ch2, ch5 and ch6)	12.2	V
DC output current 1	I _{D(DC)1}	DC (ch3 to ch5)	±0.3	A/ch
DC output current 2	I _{D(DC)2}	DC (ch1, ch2 and ch6)	±0.15	A/ch
Instantaneous output current 1	I _{D(pulse)1}	PW < 10 ms, Duty Cycle ≤ 20% (ch3 to ch5)	±0.6	A/ch
Instantaneous output current 2	I _{D(pulse)2}	PW < 10 ms, Duty Cycle ≤ 20% (ch1, ch2 and ch6)	±0.3	A/ch
Power consumption	Рт		1.0	W
Peak junction temperature	T _{ch(MAX)}		150	°C
Storage temperature	T _{stg}		−55 to +150	°C

Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

Recommended Operating Conditions

(T_A = 25°C, glass epoxy board of 100 mm x 100 mm x 1 mm with copper foil area of 15%)

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Power supply voltage	V _{DD}	Control block	2.7		5.5	V
	VM	Motor block (ch3 and ch4)	2.7		5.5	V
		Motor block (ch1, ch2, ch5 and ch6)	6.0		11.0	V
Input voltage	VIN		0		V _{DD}	V
DC output current 1	I _{D(DC)1}	DC (ch3 to ch5)	-0.2		+0.2	A/ch
DC output current 2	I _{D(DC)2}	DC (ch1, ch2 and ch6)	-0.1		+0.1	A/ch
Instantaneous output current 1	ID(pulse)1	PW < 10 ms, Duty Cycle ≤ 20% (ch3 to ch5)	-0.4		+0.4	A/ch
Instantaneous output current 2	D(pulse)2	PW < 10 ms, Duty Cycle ≤ 20% (ch1, ch2 and	-0.2		+0.2	A/ch
		ch6)				
Logic input frequency	fin				100	kHz
Operating temperature range	TA		-40		85	°C



Electrical Characteristics

(Unless otherwise specified, $T_A = 25$ °C, $V_{DD} = 3$ V, $V_M = 5$ V (ch3 and ch4), $V_M = 8$ V (ch1, ch2, ch5 and ch6))

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
VDD pin current in standby mode	I _{DD(STB)}	All control pin: Low level			1.0	μΑ
VDD pin current in during operation	IDD(ACT)				1.0	mA
Vм pin current in during operation	Ім	Output with no load, IN pin, EN pin: Low			100	μΑ
		level				
High-level input current	Іін	$V_{IN} = V_{DD}$			60	μΑ
Low-level input current	lı∟	V _{IN} = 0 V	-1.0			μΑ
Input pull-down resistance	RIND		50		200	kΩ
High-level input voltage	VIH	$2.7 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$	0.7 x V _{DD}			V
Low-level input voltage	VIL	$2.7 \text{ V} \leq V_{DD} \leq 5.5 \text{ V}$			0.3 x V _{DD}	V
H-bridge on-state resistance 1	R _{on1}	Iм = 0.1 A (ch1 and ch2), Iм = 0.2 A		2.0	3.0	Ω
(ch1, ch2 and ch5)		(ch5), sum of upper and lower stages				
H-bridge on-state resistance 2	Ron2	I _M = 0.2 A, sum of upper and lower		1.2	2.0	Ω
(ch3 and ch4)		stages				
H-bridge on-state resistance 3	Ron3	I _M = 0.1 A, sum of upper and lower		3.5	5.0	Ω
(ch6)		stages				
Output leakage current	I _{M(off)}	Per V _M pin, All control pin: Low level (V _M			10	μΑ
		= MAX. value in the recommended				
		range)				
Low-voltage detection voltage	V _{DDS}			1.7	2.5	V
Output turn-on time Note	ton2	I _M = 0.1 A (ch1, ch2 and ch6),	0.2	0.6	2.0	μs
Output turn-off time Note	toff2	Refer to Figure 7–1. H-bridge	0.05	0.3	1.0	μs
		Switching Waveform (when SEL ₁₂ = L)				
		and Figure 7-2. H-bridge Switching				
		Waveform (when SEL ₁₂ = H) .				
Output turn-on time Note	ton1	I _M = 0.2 A (ch3 to ch5),	0.05	0.15	1.0	μs
Output turn-off time Note	toff1	Refer to Figure 7–2. H-bridge	0.05	0.2	1.0	μs
		Switching Waveform (when SEL ₁₂ = H)				
		(only when V _{INB} = L) .				

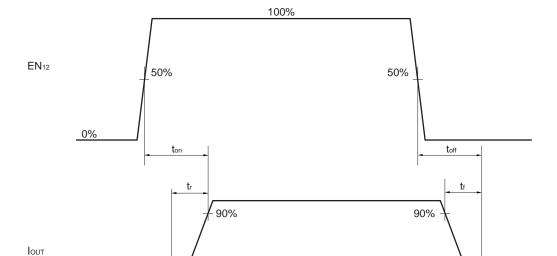
Note For the turn-on time and the turn-off time, to fix one of two input pins to low level is conditions.

Remark The overheat protection circuit operates under $T_{ch} > 150^{\circ}C$. All outputs goes high impedance in the protection status. Note that the overheat protection circuit and the undervoltage lockout circuit do not operate in the standby status.

Data Sheet S16040EJ1V0DS

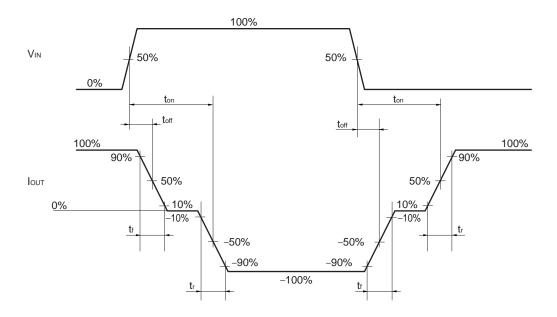
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Switching Characteristics Waveform



10%

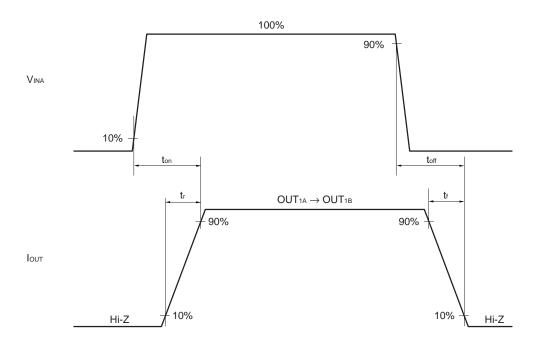
Figure 7–1. H-bridge Switching Waveform (when $SEL_{12} = L$)



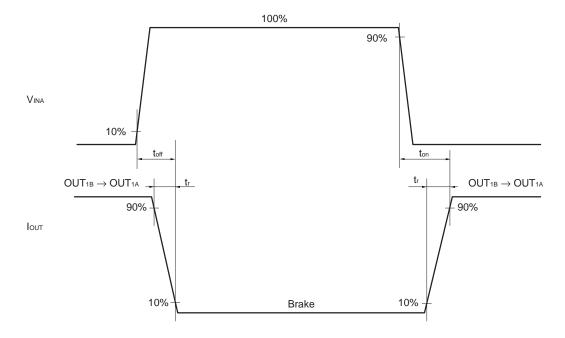
Remark The high impedance period of about 50 ns is prepared for the through-current prevention at the time of mode switching. The t_r (rise time) is designed as 50 ns, and the t_f (fall time) is designed as about 50 ns.

Figure7–2. H-bridge Switching Waveform (when SEL₁₂ = H)

When VINB = L



When $V_{INB} = H^{Note}$

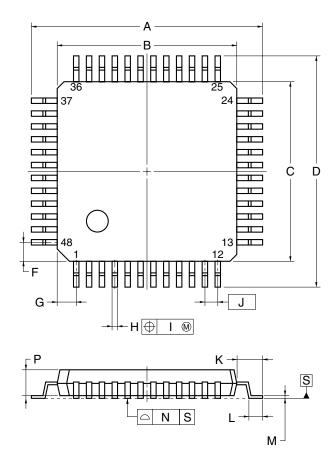


Note The conditions of $V_{INB} = H$ is valid only at ch1, ch2 and ch6. The through current may be flowed, if the switching operation is performed under the conditions of $V_{INB} = H$ at ch3 to ch5.

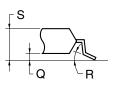
Remark The high impedance period of about 50 ns is prepared for the through-current prevention at the time of mode switching. The t_r (rise time) is designed as 50 ns, and the t_r (fall time) is designed as about 50 ns.

8. PACKAGE DRAWING

48-PIN PLASTIC TQFP (FINE PITCH) (7x7)



detail of lead end



NOTE

Each lead centerline is located within 0.10 mm of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	
Α	9.0±0.2	
В	7.0±0.2	
С	7.0±0.2	
D	9.0±0.2	
F	0.75	
G	0.75	
Н	$0.22^{+0.05}_{-0.04}$	
ı	0.10	
J	0.5 (T.P.)	
K	1.0±0.2	
L	0.5±0.2	
М	$0.145^{+0.055}_{-0.045}$	
N	0.10	
Р	1.0±0.1	
Q	0.1±0.05	
R	3°+7°	
S	1.27 MAX.	
	S48GA-50-9EU-2	

9. RECOMMENDED SOLDERING CONDITIONS

The μ PD168002 should be soldered and mounted under the following recommended conditions.

For soldering methods and conditions other than those recommended below, contact an NEC Electronics sales representative.

For technical information, see the following website.

Semiconductor Device Mount Manual (http://www.necel.com/pkg/en/mount/index.html)

Type of Surface Mount Device

 μ PD168002GA-9EU: 48-pin plastic TQFP (fine pitch) (7 x 7)

Process	Conditions	Symbol
Infrared reflow	Package peak temperature: 235°C, Time: 60 seconds MAX. (at 210°C or higher) ,	IR35-00-3
	Count: Three times or less, Exposure limit: None,	
	Flux: Rosin flux with low chlorine (0.2 Wt% or below) recommended.	

Caution Do not use different soldering methods together (except for partial heating).

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NOTES FOR CMOS DEVICES -

1) PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

2 HANDLING OF UNUSED INPUT PINS FOR CMOS

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

(3) STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.



Reference Documents

NEC Semiconductor Device Reliability/Quality Control System (C10983E)

Quality Grades on NEC Semiconductor Devices (C11531E)

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- While NEC Electronics endeavors to enhance the quality, reliability and safety of NEC Electronics products, customers agree and acknowledge that the possibility of defects thereof cannot be eliminated entirely. To minimize risks of damage to property or injury (including death) to persons arising from defects in NEC Electronics products, customers must incorporate sufficient safety measures in their design, such as redundancy, fire-containment and anti-failure features.
- NEC Electronics products are classified into the following three quality grades: "Standard", "Special" and "Specific".
 - The "Specific" quality grade applies only to NEC Electronics products developed based on a customer-designated "quality assurance program" for a specific application. The recommended applications of an NEC Electronics product depend on its quality grade, as indicated below. Customers must check the quality grade of each NEC Electronics product before using it in a particular application.
 - "Standard": Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots.
 - "Special": Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support).
 - "Specific": Aircraft, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems and medical equipment for life support, etc.

The quality grade of NEC Electronics products is "Standard" unless otherwise expressly specified in NEC Electronics data sheets or data books, etc. If customers wish to use NEC Electronics products in applications not intended by NEC Electronics, they must contact an NEC Electronics sales representative in advance to determine NEC Electronics' willingness to support a given application.

(Note)

- (1) "NEC Electronics" as used in this statement means NEC Electronics Corporation and also includes its majority-owned subsidiaries.
- (2) "NEC Electronics products" means any product developed or manufactured by or for NEC Electronics (as defined above).