# VM147

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# 110mA, 10Bit Current Sinking VCM Driver with I<sup>2</sup>C Interface



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VM147

# 110mA, 10-Bit Current Sinking VCM Driver with I<sup>2</sup>C Interface

#### **General Specifications**

The VM147 is a VCM(Voice Coil Motor) driver IC with I<sup>2</sup>C interface control that is capable of programmable sinking output current. It has a built-in internal voltage reference and operates with a supply voltage range from 2.4V to 5.5V. The DAC is controlled by a signal transmit through a 2-wire I<sup>2</sup>C serial interface which operates in an I<sup>2</sup>C fast mode (400 kHz). The VM147 is designed for applications such as image stabilization, auto-focus, optical zoom in camera phones, and other portable module devices.

#### **Features and Benefits**

- Programmable sinking output current
- I<sup>2</sup>C serial interface
- DAC with 10-BIT resolution
- 2.4V 5.5V power source
- Selective Output Slew Rate Control(SRC)
- Low voltage control for digital pin PS, SDA, and SCL(i.e.,  $V_{H}$  = 1.68V @ VDD = 2.8V)
- Power saving mode leakage current 2.4uA max.
- Power saving mode
- Automatic power on reset
- Ultra small package: WLCSP (0.78\*1.27\*0.35mm)

#### **Ordering Information**

VM147 WLCSP WLCSP, 6Pin	7XX*

\*XX reserved for a data code



#### Terminology

#### **Resolution**

The DAC resolution is defined by the power factor of 2, which defines the number of

distinct digitized levels.

N-bit resolution -> 2<sup>N</sup> distinct digitized levels

#### Differential Nonlinearity (DNL) error

The variation in digitized step value away from 1 LSB by any two adjacent digitized levels,

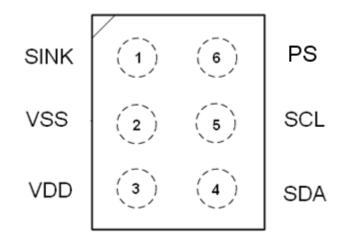
gain and offset errors removed.

#### Integral Nonlinearity (INL)

INL is a deviation of the actual transfer response from a straight line. Usually, INL error is referred to the maximum INL error.

#### Pin Assignment of WLCSP (0.78\*1.27\*0.35mm)

**TOP** View



Pin Number	Pin Name	Description		
1	SINK	Analog Output : Current Sink Pin		
2	VSS	Ground Input Pin		
3	VDD	Power Input Pin		
4	SDA	I <sup>2</sup> C Interface Data Line(Serial Data Line)		
5	SCL	I <sup>2</sup> C Interface Clock Line(Serial Clock Line)		
6	PS	Digital Input: Power saving control		
		(When PS=High ,chip is disabled)		
		(When PS=Low ,chip is enabled)		

#### **Absolute Maximum Ratings**

Unless otherwise noted,  $T_A$ = 25°C

Characteristic	Symbol	Rating	Unit
Supply Voltage	V <sub>DD</sub>	-0.4 ~ 5.5	V
Input Signal Voltage	V <sub>IN</sub>	-0.4 ~ V <sub>DD</sub> +0.4	V
Maximum Sink Current	I <sub>SINK</sub>	127	mA
Operating Temperature	T <sub>OPR</sub>	-40 ~ 85	°C
Storage Temperature	T <sub>STG</sub>	-55 ~ 150	°C

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#### **Electrical Characteristic**

Unless otherwise noted,  $T_A\text{=}25^\circ\!\!\mathbb{C}$  ,  $V_{DD}\text{=}2.8$  V and VCM  $\approx 18\Omega,\,460\text{uH}.$ 

$\begin{tabular}{ c c c c c c c c c c c } \hline Item & Sym. & Condition & Limit & Min. & Typ. & Max. \\ \hline Power Supply & \\ \hline Supply Voltage & V_{DD} & 2.4 & 2.8 & 5.5 \\ \hline Supply Current & I_{PS} & PS = High (chip is disabled) & - & 0.3 & 1 \\ \hline I_{DD} & PS = Low, & SPS(*1) = High & - & 0.3 & 0.5 \\ \hline I_{DD1} & PS = Low, & SPS(*1) = Low & - & 1.6 & 2.3 \\ \hline PS, SDA, SCL digital pin & & & & \\ \hline Input Voltage High & V_{IH} & - & 0.5^*V_{DD} & - & V_{DD}+0.4 \\ \hline Input Voltage Low & V_{IL} & - & -0.4 & - & 0.1^*V_{DD} \\ \hline Parameters & & & & \\ \hline \hline Data & Data & Data & Data & V_{DD} & & & \\ \hline \end{tabular}$	i									
Min.Typ.Max.Power SupplySupply Voltage $V_{DD}$ 2.42.85.5Supply Current ( $I_{DD}$ ) $I_{PS}$ PS = High (chip is disabled)-0.31 $I_{DD0}$ PS = Low, SPS(*1)= High-0.30.5 $I_{DD1}$ PS = Low, SPS(*1)= Low-1.62.3PS, SDA, SCL digital pinInput Voltage High $V_{IL}$ -0.5*V_{DD}- $V_{DD}$ +0.4Input Voltage Low $V_{IL}$ 0.4-0.1*V_{DD}Parameters	Unit									
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$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	uA									
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Input Voltage Low   V <sub>IL</sub> -   -0.4   -   0.1*V <sub>DD</sub> Parameters   -   -   -   -   -   -   -   -   -   -   -   -   -   -   -   -   -   -   0.1*V <sub>DD</sub> -   0.1*V <sub>DD</sub> -   -   0.1*V <sub>DD</sub> -										
Parameters	V									
	V									
	Parameters									
DAC Resolution - 10 -	Bits									
DNL - +/-0.7 +/-1	LSB									
INL - +/-1.5 +/-4	LSB									
Maximum Output Sink CurrentI I S,maxD[9:0]=3FF(*2)102	mA									
Zero Code Output Sink Current I <sub>S,min</sub> D[9:0]=000(*2) - 1 4	mA									
Output Offset Current   I <sub>OS</sub> PS = L, SPS(*1)= H   -   0.1   1	uA									
Voltage Drop $\Delta V = V_{SINK} - V_{MVSS} (*3)$ $(@I_{SINK} = 80 \text{ mA})$ $- 0.35  0.44$	V									

Note:

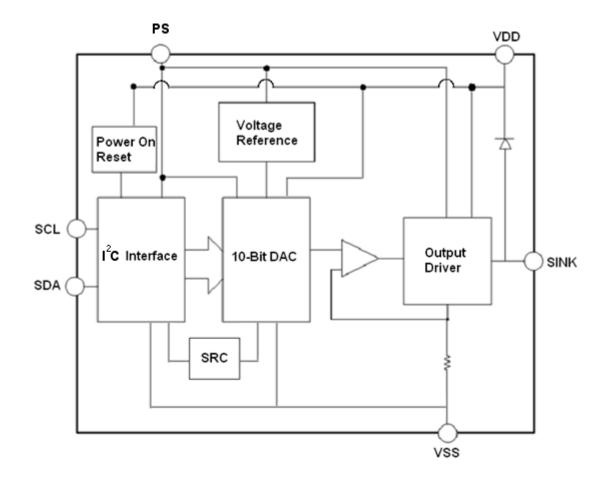
(\*1): SPS (Soft Power Saving, 2<sup>nd</sup> standby mode): IC power saving mode, controlled by software. (\*2): The value of sink current through pin SINK is set by D[9:0] linearly.

(\*3):  $V_{SINK}$  is the voltage of SINK pin, and  $V_{MVSS}$  is the voltage of motor driver VSS pin



### **Block Diagram**

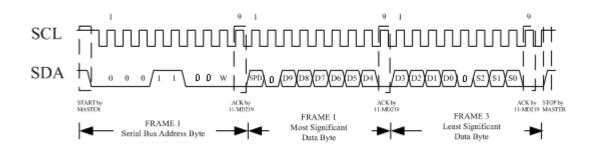
(WLCSP)



#### **Data Format**

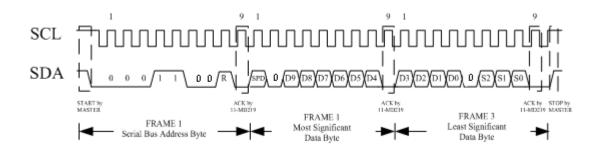
#### VM147 Write Mode

In the writing mode, data is written to the VM147 and shifted into a 16-bit input register. After all 16 bits of data have been shifted in, a STOP signal is generated by master controller. The data in the input register is transferred to the DAC at the same time.



#### VM147 Read Mode

In reading mode, data is read from IC to a master controller in the same bit order.



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#### <u>Table</u>

	MSB							LSB								
Serial Data Bits	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Input Register	R15	R14	R13	R12	R11	R10	R09	R08	R07	R06	R05	R04	R03	R02	R01	R00
Function	SPS	0	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	0	S2	S1	S0

#### • SPS (Soft Power Saving, 2<sup>nd</sup> standby mode): IC power saving, controlled by

software.

The operations are defined by the following table.

PS	SPS	IC status	
High	-	- Power saving	
Low	Low	Normal	
Low	High	Soft power saving	

If PS is at logic high level; the chip is forced to shut down all power. If PS is at logic low level, the chip will be controlled by the SPS bit(the R15 bit of the register) to perform normally(SPS=Low) or to softly power off the IC(SPS=High). It is recommended to keep PS at high level (PS = H) while the chip is in no operation mode to save power for all applications.

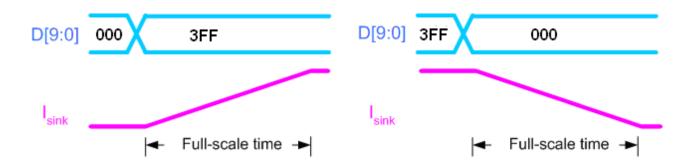
• **D[9:0]:** The level of sink current through pin SINK is set by D[9:0].

 S[2:0]: Output Current Slew Rate Control: The output current slew rate can be set by S[2:0] as defined below.

S[2:0]	Full Scal	Ratio			
3[2.0]	Min.	Тур.	Max.	i tatio	
000	1.16	1.57	1.99	1X	
0 0 1	37.2	50.2	64	32X	
010	55.8	75.3	96	48X	
011	74.3	100	128	64X	
100	92.9	126	159	80X	
101	111	151	191	96X	
110	130	176	223	112X	
111	149	201	255	128X	

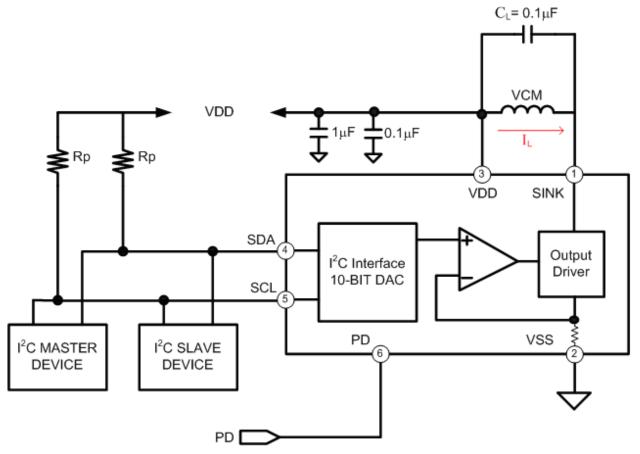
D[9:0]=000 → 3FF

D[9:0]=3FF → 000



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## **Application Circuit**



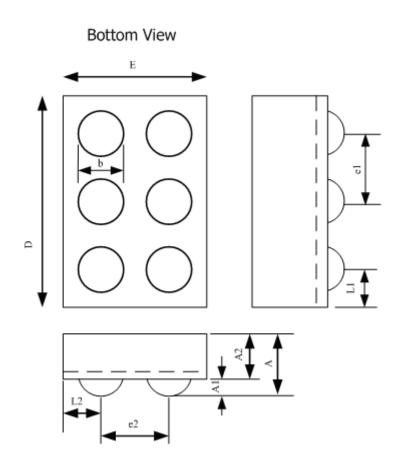
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#### **Application Notes**

- The VM147 is a constant current driving IC for applications in Auto-Focus. The supply voltage range VDD of VM147 is from 2.4V to 5.5V. The input range of digital control pin PS, and digital I/O pins SCL and SDA, are defined such that logic "High" is from 0.6\*VDD to VDD+0.4V and logic "Low" is from -0.4V to 0.1\*VDD. Therefore, the three digital pins are suitable controlled by 1.8V ISP.
- In order to ensure the stability of output current, a capacitance C<sub>L</sub> is suggested to be installed between the two terminals of VCM. The suggested value of C<sub>L</sub> is in the range of 0.1~0.22uF to match different VCMs.

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# Package Specifications (WLCSP1): (0.78\*1.27\*0.35mm)



SYMBOL	DIMENSION (mm)					
	MIN.	NOM.	MAX.			
A	0.325	0.350	0.375			
A1	0.090	0.100	0.110			
A2	0.235	0.250	0.265			
b	0.234	0.260	0.286			
D	1.255	1.270	1.285			
E	0.765	0.780	0.795			
e1	0.380	0.400	0.420			
e2	0.380	0.400	0.420			
L1	0.215	0.235	0.255			
L2	0.170	0.190	0.210			

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