

**MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®** 



MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®



Ordering information

Туре	Part no.
SFM60-HRAB4K02	On request

Other models and accessories → www.sick.com/SFS\_SFM60

Illustration may differ



### Detailed technical data

1 errormanee		
Number of sine/cosine periods per revolu- tion	1,024	
Number of the absolute ascertainable revo- lutions	4,096	
Total number of steps	134,217,728	
Measuring step	0.3 Winkelsekunden For interpolation of the sine/cosine signals with, e. g., 12 bits	
Integral non-linearity	$\pm45$ Winkelsekunden, Error limits for evaluating sine/cosine period, without mechanical tension of the stator coupling	
Differential non-linearity	$\pm$ 7 Winkelsekunden, Non-linearity within a sine/cosine period	
Operating speed	6,000 min <sup>-1</sup> , up to which the absolute position can be reliably produced	
Interfaces		
Type of code for the absolute value	Binary	
Code sequence	Rising, For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	
Communication interface	HIPERFACE®	
Available memory area	1,792 Byte	
Electrical data		
Supply voltage range	7 V DC 12 V DC	
Recommended supply voltage	8 V DC	
Operating power consumption (no load)	< 80 mA <sup>1)</sup>	
Output frequency for sine/cosine signals	0 kHz 200 kHz	
<sup>1)</sup> Without load.		
Mechanical data		
Shaft version	Blind hollow shaft	

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Shaft material	Stainless steel
Flange material	Zinc diecast
Housing material	Aluminum die cast
Flange type / stator coupling	Stator coupling

 $^{1)}$  Take into account self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

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Dimensions	See dimensional drawing
Weight	≤ 0.25 kg
Moment of inertia of the rotor	40 gcm <sup>2</sup>
Operating speed	≤ 9,000 min <sup>-1 1)</sup>
Angular acceleration	≤ 500,000 rad/s²
Operating torque	0.6 Ncm (+20 °C)
Start up torque	0.8 Ncm (+20 °C)
Permissible shaft movement, radial stat- ic/dynamic	± 0.3 mm / ± 0.1 mm
Permissible shaft movement, axial stat- ic/dynamic	± 0.5 mm / ± 0.2 mm
Life of ball bearings	3.6 x 10^9 revolutions
Connection type	Male connector M23, 12-pin, radial

 $^{(1)}$  Take into account self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

#### Ambient data

Operating temperature range	-40 °C +115 °C
Storage temperature range	-40 °C +115 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	20 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)
EMC	According to EN 61000-6-2 and EN 61000-6-3 $^{1)}$
Enclosure rating	IP65, with mating connector inserted (according to IEC 60529)

<sup>1)</sup> The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

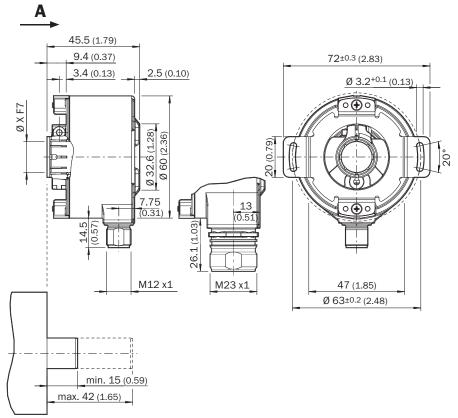
#### Classifications

ECI@ss 5.0	27270590
ECI@ss 5.1.4	27270590
ECI@ss 6.0	27270590
ECI@ss 6.2	27270590
ECI@ss 7.0	27270590
ECI@ss 8.0	27270590
ECI@ss 8.1	27270590
ECI@ss 9.0	27270590
ETIM 5.0	EC001486
ETIM 6.0	EC001486
UNSPSC 16.0901	41112113

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Dimensional drawing (Dimensions in mm (inch))

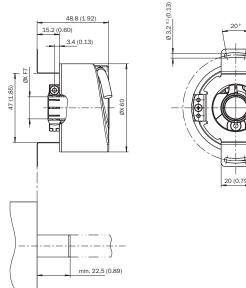
Blind hollow shaft, male connector connection - standard system

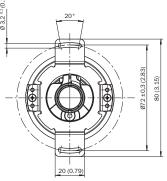


General tolerances according to DIN ISO 2768-mk

### **Proposed fitting**

Version 4





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### **PIN** assignment

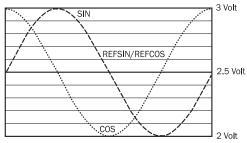
View of the M23 male connector plug-in face



PIN	Signal	Explanation	
1	REFCOS	Process data channel	
2	Data +	Parameter channel RS 485	
3	N. C.	Not assigned	
4	N. C.	Not assigned	
5	+ SIN	Process data channel	
6	REFSIN	Process data channel	
7	Data -	Parameter channel RS 485	
8	+ COS	Process data channel	
9	N. C.	Not assigned	
10	GND	Ground connection	
11	N. C.	Not assigned	
12	U <sub>S</sub>	Supply voltage	
Housing	Screen	Screen connected with encoder housing	

### Diagram

Signal specification of the process channel



Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period = 360 ° : 1024

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#### **Recommended accessories**

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	Brief description	Туре	Part no.
Flanges			
ШÇ,	Stator coupling, 16.5 mm high	BEF-DS05XFX	2057423
Ŵ	Stator coupling with hole circle diameter 63 mm	BEF-DS07XFX	2059368
Programming	and configuration tools		
	SVip® LAN programming tool for all motor feedback systems	PGT-11-S LAN	1057324
	SVip® WLAN programming tool for all motor feedback systems	PGT-11-S WLAN	1067474

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SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

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Online data sheet

