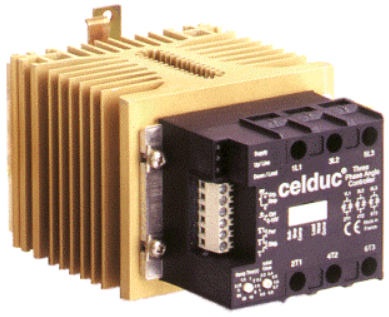
DIGITAL THREE PHASE ANGLE CONTROLLER

SWTA4631



- Allows to set the voltage applied to different sort of loads with 3 wires, 4 wires or inside the delta wiring:
  - Resistive (Bulbs, UV and IR lamps, ovens, ...),
  - Inductive (inductors, transformers, ...),
  - Motor (motorfan speed control (60 to 100% from the nominal speed),
  - Rectified (power supplies, ...).
- Small housing, easy and ready to use.
- Large mains frequency and voltage range.
- Fully optoisolated full cycle three phase phase angle controller (balanced currents, less harmonics, ...)
- Dynamic control voltage range according to the power factor of the load.
- Softstart and softstop functions (increase lifetime expectancy of the load).
- Adjustable filter regarding fast input voltage changes (ramps).
- Motor softstarting functions to control its speed within the stable area.
- Input-output transfert characteristic linearization function (resistive load).
- Diagnostic features : Status given on LED and AC/DC switches.

Proportionnal analog control input
Potentiometric (0-5VDC)
200->480VAC
32A AC-51 @25°C

Mains Voltage	Mains Frequency	Max AC-51 Current	Max AC-53a Current	Control Input	Status Ouputs	In / Out Insulation	Wire Size	Dimensions (WxHxD)	Weight
200 to 480VAC	40 to 65Hz	25A @40°C	25A @40°C	Potentiometric 0-5VDC	0 to 24VDC 1A AC/DC	4kV	In=2.5mm² Out=10mm²	110x110x180 (mm)	2000g

Fig. 1 TYPICAL APPLICATIONS

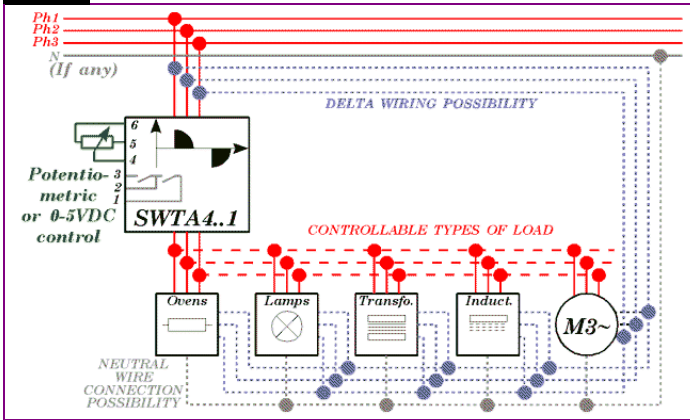


Fig. 2 WIRING DIAGRAM

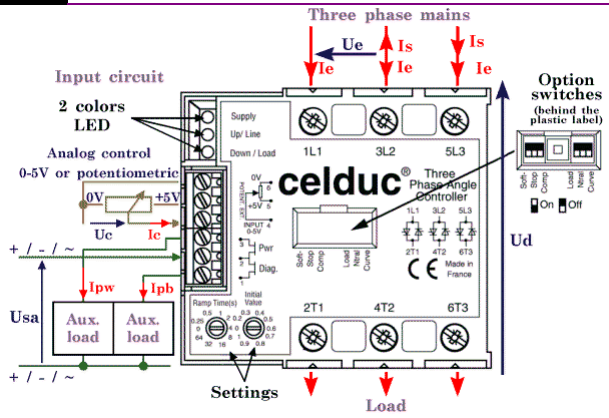


Fig. 3 PHASE ANGLE CONTROL DESCRIPTION

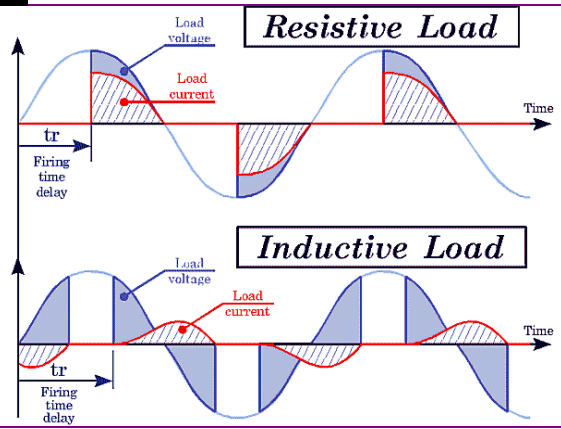
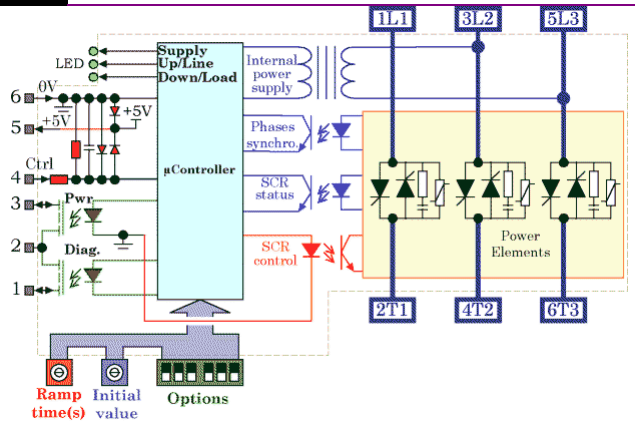


Fig. 4 INTERNAL DIAGRAM



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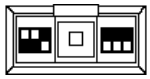
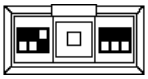
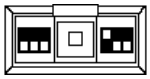
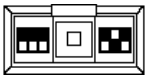
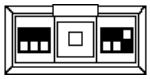
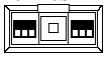
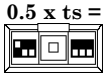
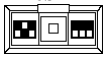
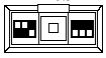
SETTINGS

SETTINGS AND OPTIONS

Label	"Ramp Time (s)"	"Initial Value"	"Soft Stop"	"Comp"	"Load"	"Ntrl"	"Curve"
Description							
Function	Ramp up time (Softstart and smooth transients)	Initial load voltage (footstep)	Ramp down time	Allows to adapt the control signal range whatever the power factor of the load	Ask the unit to make a softstart up to the max. before analog control.	Tells the unit the load star point is connected to the mains neutral	Tells the unit what kind of in-out response to use (angle or RMS voltage linearity)
Setting possibilities White squares = buttons Example :  = all switches down (OFF) (factory setting)	Ts= 0 to 64s	Vi=0 to 100 %	**0 x ts =**  **0.5 x ts =**  **ts =**  **2 x ts =** 	**On (Up)**	**On (Up)**	**On (Up)**	**On (Up)**
				Inductive load	Motor	Star wiring with neutral (4 wires)	RMS voltage control
				Off (Down)	**Off (Down)**	**Off (Down)**	**Off (Down)**
				Resistive load	Other loads than motors	Delta or star without neutral	Phase angle control

INPUT CHARACTERISTICS

INPUT CIRCUIT

CHARACTERISTIC	LABEL	VALUE	INFO.
Labels		**"0-5V"**	
Function		Analog control input	
Control type		DC control voltage	
Terminals		4, 5 & 6	
Control voltage range	**Uc**	0-5VDC	
Release and control threshold voltage	**Ucsmin**	0.15VDC	
Full power threshold control voltage	**Ucsmax**	4.85VDC	
Max. input voltage	**Ucmax**	30VDC	
Max. reverse voltage	**-Ucmax**	30VDC	
Input impedance	**Re**	1MΩ	**See fig. 5**
Best potentiometer choice		10kΩ linear	
Potentiometer range		1kΩ- >100kΩ	

STATUS OUTPUTS

Labels		**"Diag. "**	**"Pwr"**
Terminals		1 & 2	2 & 3
Function		Indicates a problem detected in the circuit configuration	Indicates the load is supplied
Nominal operating voltage	**Usan**	24VAC/DC	
Operating voltage range	**Usa**	0->28VAC/DC	
Max. peak voltage	**Usap**	60V	
Overvoltage protection		Built-in 25V size7 varistors	
Minimum load current	**Ipw/Ipb**	0A	
Maximum load current	**Ipw/Ipb**	1A AC/DC	**See fig. 6**
Maximum overload current	**Ipw/Ipb**	2.4A AC/DC	@100ms 10% of the cycle
On and off state switch resistance	**Ron / Roff**	500mΩ / 100MΩ	**See fig. 6**
On and off time delay	**Ton / Toff**	0.5ms / 2ms	

OUTPUT CHARACTERISTICS

POWER CIRCUIT

CHARACTERISTIC	LABEL	VALUE				INFO.
Mains voltage range	Ue	**200 -> 480VAC**				
Non-repetitive peak voltage	Uep	1200V				
Overvoltage protection	VDR	Built-in 510V size 14 varistors				
Maximum nominal currents	Ie	Resistive Ithmax AC51	Resistive Ith AC51	Motor Iemax AC53a	Motor Ie AC53a	**@40°C** **See fig. 7** Delta wiring : See installation manual
		25A	16A (EN60947-4-3)	25A	16A (EN60947-4-2)	
Maximum line currents in delta wiring	ILine	43A	28A (EN60947-4-3)	43A	28A (EN60947-4-2)	
Max motor power	Pe	11kW @400VAC star connection				**@40°C**
Non-repetitive peak overload current (1 cycle of 10ms)	ITSM	1500A				**See fig. 8**
Melting limit for choosing the protective fuses	I²t	11000A²s				@10ms
Minimum load current	Iemin	100mA				
Maximum leakage current	Ielk	7mA				@400VAC 50Hz
Power factor	Pf	0->1				
Mains frequency range	F	40->65Hz				
Max. off-state voltage rise	dv/dt	500V/µs				
Protection against fast voltage transients		Buit-in RC network				
Max. current rise	di/dt	50A/µs				
On-state voltage drop	Ud	1.4V				@Ith
Resistive part of the voltage drop	rt	3.5mΩ				@125°C
Potential part of the voltage drop	Vto	0.9V				@125°C
Maximum junction temperature	Tjmax	125°C				
Junction/case thermal resistance per power element	Rthjc	0.3K/W				Total = 3 power elements
Case heatsink thermal resistance	Rthcs	0.05K/W				
Built-in heatsink thermal resistance vertically mounted	Rthra	0.9K/W				@ΔTra=60°C
Heatsink thermal time constant	Tthra	35min				@ΔTra=60°C
Inputs/power ouputs insulation voltage	Uimp	4kV				
Input/status outputs insulation voltage	Uied	2.5kV				
Inputs/case insulation voltage	Uimp	4kV				
Status outputs/case insulation voltage	Uimp	4kV				
Isolation resistance	Rio	1GΩ				
Isolation capacitance	Cio	<8pF				
Storage ambient temperature	Tstg	-40->+100°C				
Operating ambient temperature	Tamb	**-40->+90°C**				**See fig. 7**
Max. heatsink temperature	Tc	**100°C**				

INTERNAL POWER SUPPLY

	CHARACTERISTIC	LABEL	VALUE	INFO.
INTERNAL POWER SUPPLY	Terminals		3L2 & 5L3	
	Mains voltage range	Ue	200->480VAC	
	Consumption	Is	1mA typical	
	Mains frequency range	F	40-65Hz	
	Turn-on time	tm	100ms	

GENERAL INFORMATION

CONNEC-TIONS	Connections		Power	Input terminal block	
	Screwdriver advised		Posidriv 2 or 0.8 x 5.5mm	0.8 x 2mm	
	Min and max tightening torque		1.8->3N.m		
	Number and cross section of the wires		2 x 1.5->6mm^2 (10mm^2 without ferrule)	1 x 2.5mm^2	
	Screwdriver for settings		0.8 x 2mm		
MISC.	Housing		UL94V0		
	Mounting		Omega DIN rail (DIN50022) or screwed		
	Noise level		Low audible vibrations		
	Weight		2000g		

STANDARDS

GENERAL	Standards		EN60947-4-2 & EN60947-4-3	
	Protection level		IP2L0	
	Protection against direct touch		Accordin to V.D.E. 160 part 100 : Back hand and finger safety	
	CE marking		Yes	
	UL, cULUS and VDE approvals		Pending	

	TYPE OF TEST	STANDARD	LEVEL	EFFECT
E.M.C. IMMUNITY	E.S.D. (Electrostatic discharges)	EN61000-4-2	8kV (air) 4kV (touch)	No effect
	Radiated electromagnetic fields	EN61000-4-3	10V/m	No effect
	Fast transients bursts	EN61000-4-4	2kV direct coupling on the power side 2kV coupling by clamp on the input side	No effect
	Electric chocks	EN61000-4-5	1kV direct coupling differential mode (input and output) 2kV direct coupling common mode (input and output)	No effect
	Voltage drop	EN61000-4-11	-	

E.M.C. EMISSION	Radiated and conducted disturbances	NFEN55011	The conducted or radiated disturbances generated by solid state relays depend on the wiring and load configuration. The test method recommended by the European standards and concerning electromagnetic compatibility leading to results far from reality, we decided to advise our customer in order to adapt their filtering scheme to their application. **Please refer to the SVTA – SWTA installation manual.**	

CHARACTERISTIC CURVES

Fig. 5 INPUT CHARACTERISTIC

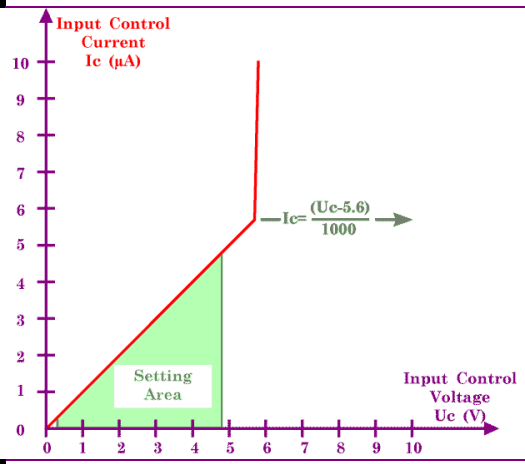


Fig. 6 CURRENT AND ON RESISTANCE VS TEMPERATURE

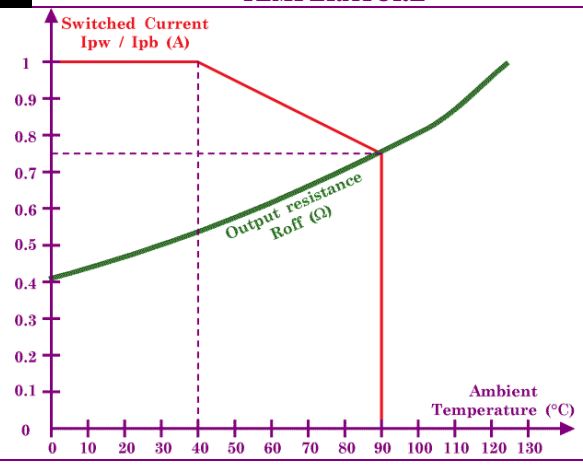
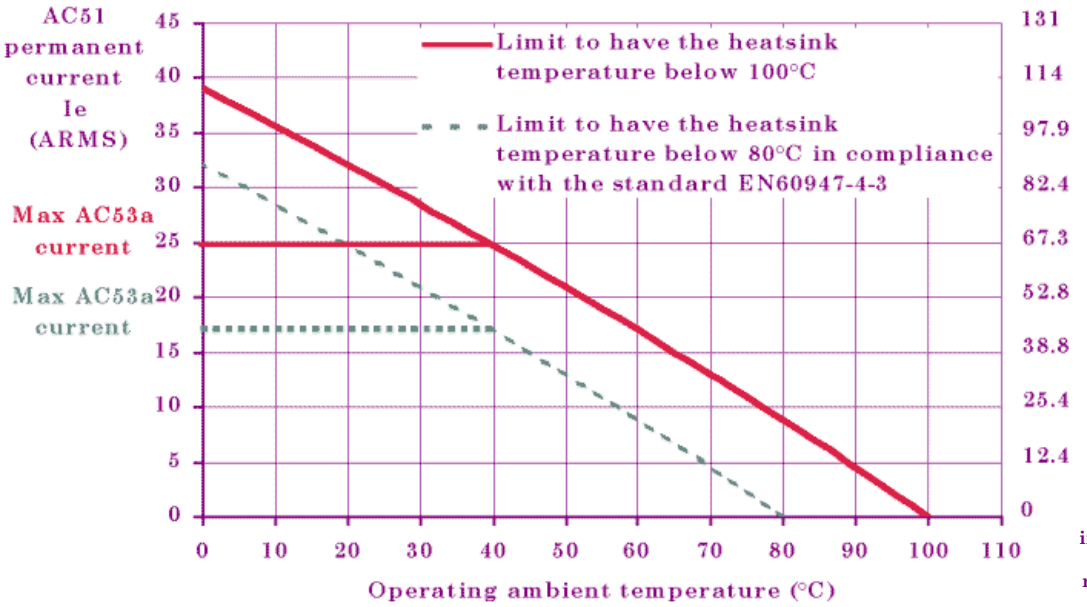
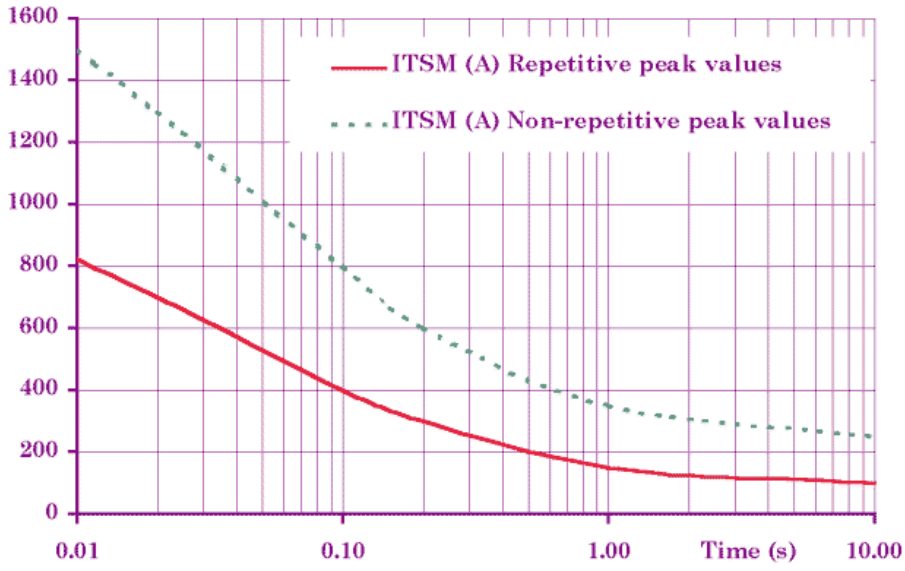


Fig. 7 POWER DISSIPATED AND LOAD CURRENT LIMIT VS TEMPERATURE



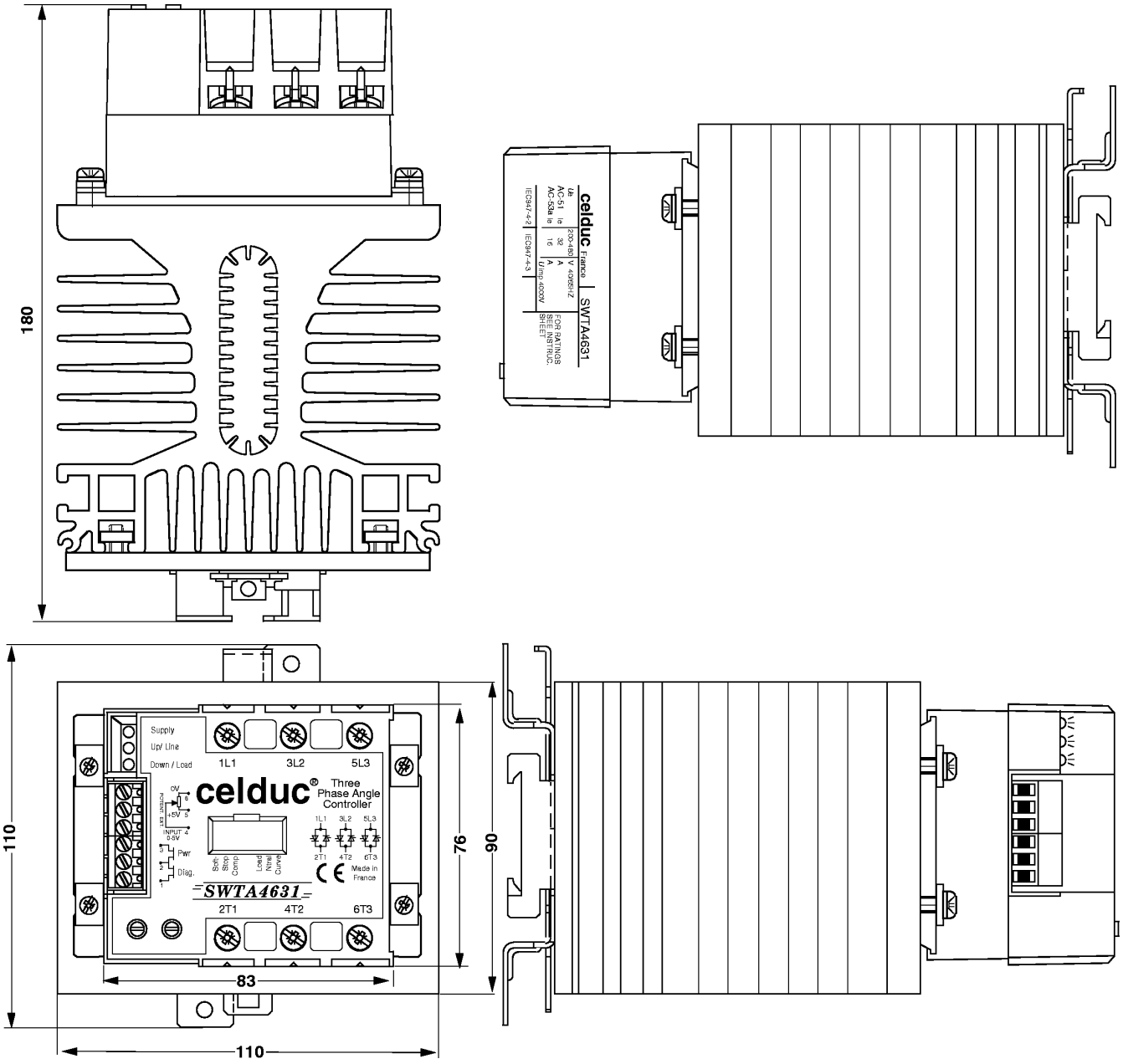
Please refere to the installation notice for precautions about mounting the device.

Fig. 8 CURRENT OVERLOAD CHARACTERISTIC (ITSM PER POWER ELEMENT)



DIMENSIONS AND ACCESSORIES

Fig. 9 DIMENSIONS



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