

# 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications 

## General Description

The MAX1215N is a monolithic, 12-bit, 250Msps ana-log-to-digital converter (ADC) optimized for outstanding dynamic performance at high-IF frequencies beyond 300 MHz . The product operates with conversion rates up to 250 Msps while consuming only 886 mW .
At 250 Msps and an input frequency of 100 MHz , the MAX1215N achieves an 84.7 dBc spurious-free dynamic range (SFDR) with e6.7dB signal-to-noise ratio (SNR) that remains flat (within 2 dB ) for input tones up to 250 MHz . This makes it ideal for wideband applications such as communications receivers, cable-head end receivers, and power-amplifier predistortion in cellular base-station transceivers (BTS).
The MAX1215N operates from a single 1.8 V power supply. The analog input is designed for AC-coupled differential or single-ended operation. The ADC also features a selectable on-chip divide-by-2 clock circuit that accepts clock frequencies as high as 500 MHz . A low-voltage differential signal (LVDS) sampling clock is recommended for best performance. The converter provides LVDS-compatible digital outputs with data format selectable to be either two's complement or offset binary.
The MAX1215N is available in a 68-pin QFN package with exposed paddle (EP) and is specified over the industrial $\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$ temperature range.
See the Pin-Compatible Versions table for a complete selection of 8 -bit, 10-bit, and 12-bit high-speed ADCs in this family.

## Applications

Base-Station Power-Amplifier Linearization
Cable-Head End Receivers
Wireless and Wired Broadband Communications
Communications Test Equipment
Radar and Satellite Subsystems

Pin Configuration appears at end of data sheet.

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- 250Msps Conversion Rate <br> - Excellent Low-Noise Characteristics <br> SNR $=66.7 \mathrm{~dB}$ at $\mathrm{f} / \mathrm{N}=100 \mathrm{MHz}$ <br> SNR $=65.6 \mathrm{~dB}$ at $\mathrm{fIN}=\mathbf{2 5 0 M H z}$ <br> - Excellent Dynamic Range <br> SFDR $=84.7 \mathrm{dBc}$ at $\mathrm{f} \mathrm{N}=100 \mathrm{MHz}$ <br> SFDR $=80 \mathrm{dBc}$ at $\mathrm{f} \mathrm{IN}=\mathbf{2 5 0 M H z}$ <br> - Single 1.8V Supply <br> - 886mW Power Dissipation at fSAMPLE $=250 \mathrm{Msps}$ and $\mathrm{f} / \mathrm{N}=100 \mathrm{MHz}$ <br> - On-Chip Track-and-Hold Amplifier <br> - Internal 1.25V-Bandgap Reference <br> - On-Chip Selectable Divide-by-2 Clock Input <br> - LVDS Digital Outputs with Data Clock Output <br> - MAX1215NEVKIT Available
}

Ordering Information

| PART | TEMP RANGE | PIN- <br> PACKAGE | PKG <br> CODE |
| :---: | :---: | :--- | :--- |
| MAX1215NEGK-D | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 68 QFN-EP* | G6800-4 |
| MAX1215NEGK+D | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 68 QFN-EP* | G6800-4 |

*EP = Exposed paddle.
+Denotes lead-free package.
$D=$ Dry pack.

Pin-Compatible Versions

| PART | RESOLUTION <br> (BITS) | SPEED <br> GRADE <br> (Msps) | ON-CHIP <br> BUFFER |
| :--- | :---: | :---: | :---: |
| MAX1121 | 8 | 250 | Yes |
| MAX1122 | 10 | 170 | Yes |
| MAX1123 | 10 | 210 | Yes |
| MAX1124 | 10 | 250 | Yes |
| MAX1213 | 12 | 170 | Yes |
| MAX1214 | 12 | 210 | Yes |
| MAX1215 | 12 | 250 | Yes |
| MAX1213N | 12 | 170 | No |
| MAX1214N | 12 | 210 | No |
| MAX1215N | 12 | 250 | No |

### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications

## ABSOLUTE MAXIMUM RATINGS

| AVcc to AGND | -0.3V to +2.1V |
| :---: | :---: |
| OVCc to OGND | -0.3V to +2.1V |
| $\mathrm{AV}_{\mathrm{cc}}$ to $\mathrm{OV}_{\mathrm{Cc}}$ | -0.3V to +2.1V |
| AGND to OGND | -0.3V to +0.3V |
| Analog Inputs to AGND | .-0.3V to (AVCC +0.3 V ) |
| All Digital Inputs to AGND | .-0.3V to (AVCC + 0.3V) |
| REFIO, REFADJ to AGND | .-0.3V to (AVCC + 0.3V) |
| All Digital Outputs to OGN | .0.3V to (OVCC + 0.3V) |

 Current into Any Pin........................................................ $\pm 50 \mathrm{~m}$ ) 68-Pin QFN-EP (derate $41.7 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ )....3333mW Operating Temperature Range ........................... $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ Junction Temperature $+150^{\circ} \mathrm{C}$
Storage Temperature Range ........................... $60^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Lead Temperature (soldering, 10s) .................................. $+300^{\circ} \mathrm{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS

$(A V C C=O V C C=1.8 \mathrm{~V}, A G N D=O G N D=0, f S A M P L E=250 \mathrm{MHz}$, differential clock input drive, $0.1 \mu \mathrm{~F}$ capacitor on REFIO, internal reference, digital output pins differential $R_{L}=100 \Omega$. Limits are for $T_{A}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DC ACCURACY |  |  |  |  |  |
| Resolution |  |  | 12 |  | Bits |
| Integral Nonlinearity (Note 2) | INL | $\mathrm{f} / \mathrm{N}=10 \mathrm{MHz}$ | -3 $\pm 0.8$ | +3 | LSB |
| Differential Nonlinearity (Note 2) | DNL | No missing codes | -1.0 $\pm 0.4$ | +1.3 | LSB |
| Transfer Curve Offset | Vos | (Note 2) | -3.5 | +3.5 | mV |
| Offset Temperature Drift |  |  | $\pm 20$ |  | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| ANALOG INPUTS (INP, INN) |  |  |  |  |  |
| Full-Scale Input Voltage Range | $V_{\text {FS }}$ |  | 12501385 |  | $m V_{P-P}$ |
| Full-Scale Range Temperature Drift |  |  | $\pm 60$ |  | ppm $/{ }^{\circ} \mathrm{C}$ |
| Common-Mode Input Voltage | VCM | Internally self-biased | 0.7 |  | V |
| Differential Input Capacitance | CIN |  | 2.5 |  | pF |
| Differential Input Resistance | RIN |  | 1.8 |  | k $\Omega$ |
| Full-Power Analog Bandwidth | FPBW |  | 700 |  | MHz |
| REFERENCE (REFIO, REFADJ) |  |  |  |  |  |
| Reference Output Voltage | $V_{\text {REFIO }}$ | REFADJ = AGND | 1.181 .25 | 1.30 | V |
| Reference Temperature Drift |  |  | 90 |  | ppm $/{ }^{\circ} \mathrm{C}$ |
| REFADJ Input High Voltage | VREFADJ | Used to disable the internal reference | AVCC - 0.3 |  | V |
| SAMPLING CHARACTERISTICS |  |  |  |  |  |
| Maximum Sampling Rate | fsample |  | 250 |  | MHz |
| Minimum Sampling Rate | fSAMPLE |  | 20 |  | MHz |
| Clock Duty Cycle |  | Set by clock-management circuit | 40 to 60 |  | \% |
| Aperture Delay | $t_{\text {AD }}$ | Figures 5, 11 | 620 |  | ps |
| Aperture Jitter | $\mathrm{t}_{\mathrm{A}} \mathrm{J}$ | Figure 11 | 0.15 |  | pSRMS |

### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications

## ELECTRICAL CHARACTERISTICS (continued)

$\left(A V_{C C}=O V C C=1.8 \mathrm{~V}, \mathrm{AGND}=\mathrm{OGND}=0, \mathrm{fSAMPLE}=250 \mathrm{MHz}\right.$, differential clock input drive, $0.1 \mu \mathrm{~F}$ capacitor on REFIO, internal reference, digital output pins differential $R_{L}=100 \Omega$. Limits are for $T_{A}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CLOCK INPUTS (CLKP, CLKN) |  |  |  |  |  |  |
| Differential Clock Input Amplitude |  | (Note 3) | 200 | 500 |  | mVP-P |
| Clock Input Common-Mode Voltage Range |  | Internally self-biased |  | $1.15 \pm 0.25$ |  | V |
| Clock Differential Input Resistance | RCLK |  |  | $11 \pm 25 \%$ |  | k $\Omega$ |
| Clock Differential Input Capacitance | Cclk |  |  | 5 |  | pF |
| DYNAMIC CHARACTERISTICS (at AIN = -1dBFS) |  |  |  |  |  |  |
| Signal-to-Noise Ratio | SNR | $\mathrm{fin}^{\mathrm{N}}=10 \mathrm{MHz}$ | 64.5 | 67 |  | dB |
|  |  | $\mathrm{fin}=100 \mathrm{MHz}$ | 64.3 | 66.7 |  |  |
|  |  | $\mathrm{fIN}=200 \mathrm{MHz}$ |  | 66.1 |  |  |
|  |  | $\mathrm{fIN}=250 \mathrm{MHz}$ |  | 65.6 |  |  |
| Signal-to-Noise and Distortion | SINAD | $\mathrm{fIN}=10 \mathrm{MHz}$ | 63.5 | 66.8 |  | dB |
|  |  | $\mathrm{fin}=100 \mathrm{MHz}$ | 63.3 | 66.4 |  |  |
|  |  | $\mathrm{fin}^{\mathrm{N}}=200 \mathrm{MHz}$ |  | 65.9 |  |  |
|  |  | $\mathrm{fIN}=250 \mathrm{MHz}$ |  | 65.4 |  |  |
| Spurious-Free Dynamic Range | SFDR | $\mathrm{f} \mathrm{IN}=10 \mathrm{MHz}$ | 70 | 86 |  | dBc |
|  |  | $\mathrm{fIN}=100 \mathrm{MHz}$ | 70 | 84.7 |  |  |
|  |  | $\mathrm{fin}=200 \mathrm{MHz}$ |  | 83.4 |  |  |
|  |  | $\mathrm{fin}=250 \mathrm{MHz}$ |  | 80 |  |  |
| Worst Harmonics <br> (HD2 or HD3) |  | $\mathrm{fIN}=10 \mathrm{MHz}$ |  | -86 | -70 | dBc |
|  |  | $\mathrm{fiN}=100 \mathrm{MHz}$ |  | -84.7 | -70 |  |
|  |  | $\mathrm{f} / \mathrm{N}=200 \mathrm{MHz}$ |  | -83.4 |  |  |
|  |  | $\mathrm{fin}^{\mathrm{N}}=250 \mathrm{MHz}$ |  | -80 |  |  |
| Two-Tone Intermodulation Distortion | TTIMD | $\begin{aligned} & \mathrm{fIN1}=99 \mathrm{MHz} \text { at AIN1 }=-7 \mathrm{dBFS}, \\ & \mathrm{fIN2}=101 \mathrm{MHz} \text { at AIN2 }=-7 \mathrm{dBFS} \end{aligned}$ |  | -86.9 |  | dBc |
| LVDS DIGITAL OUTPUTS (D0P/N-D11P/N, ORP/N) |  |  |  |  |  |  |
| Differential Output Voltage | IVODI | $R_{L}=100 \Omega$ | 280 |  | 440 | mV |
| Output Offset Voltage | OVOS | $R_{L}=100 \Omega$ | 1.11 |  | 1.37 | V |

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## ELECTRICAL CHARACTERISTICS (continued)

$(A V C C=O V C C=1.8 \mathrm{~V}, \mathrm{AGND}=\mathrm{OGND}=0, \mathrm{fSAMPLE}=250 \mathrm{MHz}$, differential clock input drive, $0.1 \mu \mathrm{~F}$ capacitor on REFIO, internal reference, digital output pins differential $R_{L}=100 \Omega$. Limits are for $T_{A}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LVCMOS DIGITAL INPUTS (CLKDIV, $\overline{\text { T/B) }}$ |  |  |  |  |  |  |
| Digital Input-Voltage Low | $\mathrm{V}_{\text {IL }}$ |  | $0.2 \times \mathrm{AV}$ CC |  |  | V |
| Digital Input-Voltage High | $\mathrm{V}_{\mathrm{IH}}$ |  | $0.8 \times \mathrm{AV}_{\text {cC }}$ |  |  | V |
| TIMING CHARACTERISTICS |  |  |  |  |  |  |
| CLK-to-Data Propagation Delay | tpDL | Figure 5 | 2.23 |  |  | ns |
| CLK-to-DCLK Propagation Delay | tCPDL | Figure 5 | 3.77 |  |  | ns |
| DCLK-to-Data Propagation Delay | tCPDL - tpd | Figure 5 (Note 3) | 1.47 | 1.54 | 1.63 | ns |
| LVDS Output Rise Time | trise | 20\% to 80\%, CL $=5 \mathrm{pF}$ | 155 |  |  | ps |
| LVDS Output Fall Time | tFALL | 20\% to 80\%, CL $=5 \mathrm{pF}$ | 145 |  |  | ps |
| Output Data Pipeline Delay | tLATENCY | Figure 5 | 11 |  |  | Clock cycles |
| POWER REQUIREMENTS |  |  |  |  |  |  |
| Analog Supply Voltage Range | $A V_{C C}$ |  | 1.7 | 1.8 | 1.9 | V |
| Digital Supply Voltage Range | OVCC |  | 1.7 | 1.8 | 1.9 | V |
| Analog Supply Current | IAVCC | $\mathrm{fin}=100 \mathrm{MHz}$ |  | 428 | 480 | mA |
| Digital Supply Current | Iovcc | $\mathrm{fIN}=100 \mathrm{MHz}$ |  | 64 | 74 | mA |
| Analog Power Dissipation | PDISS | $\mathrm{fiN}=100 \mathrm{MHz}$ |  | 886 | 965 | mW |
| Power-Supply Rejection Ratio | RR | Offset |  | 1.7 |  | $\mathrm{mV} / \mathrm{V}$ |
| (Note 4) | PSRR | Gain |  | 4.5 |  | \%FS/V |

Note 1: $\mathrm{T}_{\mathrm{A}} \geq+25^{\circ} \mathrm{C}$ guaranteed by production test, $\mathrm{T}_{\mathrm{A}}<+25^{\circ} \mathrm{C}$ guaranteed by design and characterization. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$
Note 2: Static linearity and offset parameters are computed from an endpoint curve fit.
Note 3: Parameter guaranteed by design and characterization: $T_{A}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$.
Note 4: PSRR is measured with both analog and digital supplies connected to the same potential.

# 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications 

## Typical Operating Characteristics

$\left(A V_{C C}=O V_{C C}=1.8 \mathrm{~V}, A G N D=O G N D=0, f S A M P L E=250 M H z, A_{I N}=-1 d B F S\right.$, see each TOC for detailed information on test conditions, differential input drive, differential sine-wave clock input drive, $0.1 \mu \mathrm{~F}$ capacitor on REFIO, internal reference, digital output pins differential $R_{L}=100 \Omega, T_{A}=+25^{\circ} \mathrm{C}$.)


### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications

## Typical Operating Characteristics (continued)

$\left(A V_{C C}=O V_{C C}=1.8 \mathrm{~V}, \mathrm{AGND}=O G N D=0, \mathrm{f}_{\mathrm{SAMPLE}}=250 \mathrm{MHz}, \mathrm{A}_{I N}=-1 \mathrm{dBFS}\right.$, see each TOC for detailed information on test conditions, differential input drive, differential sine-wave clock input drive, $0.1 \mu \mathrm{~F}$ capacitor on REFIO, internal reference, digital output pins differential $R_{L}=100 \Omega, T_{A}=+25^{\circ} \mathrm{C}$.)



INTEGRAL NONLINEARITY vs. DIGITAL OUTPUT CODE


HD2/HD3 vs. ANALOG INPUT AMPLITUDE
( f SAMPLE $=250 \mathrm{MHz}, \mathrm{f} / \mathrm{N}=\mathbf{6 5 . 0 3 3} \mathrm{MHz}$ )


HD2/HD3 vs. SAMPLE FREQUENCY ( $\mathrm{fIN}_{\mathrm{N}}=65 \mathrm{MHz}, \mathrm{A}_{\mathrm{IN}}=-1 \mathrm{dBFS}$ )


DIFFERENTIAL NONLINEARITY vs. DIGITAL OUTPUT CODE


SNR/SINAD vs. SAMPLE FREQUENCY
( $\mathrm{fin}_{\mathrm{IN}}=65 \mathrm{MHz}, \mathrm{A}_{\mathrm{IN}}=-1 \mathrm{dBFS}$ )


TOTAL POWER DISSIPATION vs. SAMPLE FREQUENCY ( $\mathrm{I}_{\mathrm{IN}}=65.033 \mathrm{MHz}, \mathrm{A}_{\text {IN }}=-1 \mathrm{dBFS}$ )


GAIN BANDWIDTH PLOT (fsAMPLE $=250 \mathrm{MHz}$, NORMALIZED TO OdB)


# 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications 

## Typical Operating Characteristics (continued)

$\left(A V_{C C}=O V_{C C}=1.8 \mathrm{~V}, \mathrm{AGND}=O G N D=0, \mathrm{fSAMPLE}=250 \mathrm{MHz}, \mathrm{A} I \mathrm{~N}=-1 \mathrm{dBFS}\right.$, see each TOC for detailed information on test conditions, differential input drive, differential sine-wave clock input drive, $0.1 \mu \mathrm{~F}$ capacitor on REFIO, internal reference, digital output pins differential $R_{L}=100 \Omega, T_{A}=+25^{\circ} \mathrm{C}$.)


### 1.8V, Low-Power, 12-Bit, 250Msps <br> ADC for Broadband Applications

Pin Description

| PIN | NAME | FUNCTION |
| :---: | :---: | :---: |
| $\begin{gathered} 1,6,11-14,20, \\ 25,62,63,65 \end{gathered}$ | AVCC | Analog Supply Voltage. Bypass AVCC to AGND with a parallel combination of $0.1 \mu \mathrm{~F}$ and $0.22 \mu \mathrm{~F}$ capacitors for best decoupling results. Connect all AVCc inputs together. See the Grounding, Bypassing, and Layout Considerations section. |
| $\begin{gathered} 2,5,7,10,15,16 \\ 18,19,21,24 \\ 64,66,67 \end{gathered}$ | AGND | Analog Converter Ground. Connect all AGND inputs together. |
| 3 | REFIO | Reference Input/Output. Pull REFADJ high to allow REFIO to accept an external reference. Pull REFADJ low to activate the internal 1.25 V -bandgap reference. Connect a $0.1 \mu \mathrm{~F}$ capacitor from REFIO to AGND for both internal and external reference. |
| 4 | REFADJ | Reference Adjust Input. REFADJ allows for FSR adjustments by placing a resistor or trim potentiometer between REFADJ and AGND (decreases FSR) or REFADJ and REFIO (increases FSR). Connect REFADJ to $A V_{C C}$ to override the internal reference with an external source connected to REFIO. Connect REFADJ to AGND to allow the internal reference to determine the FSR of the data converter. See the FSR Adjustment Using the Internal Reference section. |
| 8 | INP | Positive Analog Input Terminal. Internally self-biased to 0.7V. |
| 9 | INN | Negative Analog Input Terminal. Internally self-biased to 0.7V. |
| 17 | CLKDIV | Clock Divider Input. CLKDIV controls the sampling frequency relative to the input clock frequency. CLKDIV has an internal pulldown resistor. <br> CLKDIV $=0$ : Sampling frequency is at one-half the input clock frequency. <br> CLKDIV $=1$ : Sampling frequency is equal to the input clock frequency. |
| 22 | CLKP | True Clock Input. Apply an LVDS-compatible input level to CLKP. Internally self-biased to 1.15V. |
| 23 | CLKN | Complementary Clock Input. Apply an LVDS-compatible input level to CLKN. Internally selfbiased to 1.15 V . |
| 26, 45, 61 | OGND | Digital Converter Ground. Ground connection for digital circuitry and output drivers. Connect all OGND inputs together. |
| 27, 28, 41, 44, 60 | OVCc | Digital Supply Voltage. Bypass OVCC with a $0.1 \mu \mathrm{~F}$ capacitor to OGND. Connect all OVCC inputs together. See the Grounding, Bypassing, and Layout Considerations section. |
| 29 | DON | Complementary Output Bit 0 (LSB) |
| 30 | DOP | True Output Bit 0 (LSB) |
| 31 | D1N | Complementary Output Bit 1 |
| 32 | D1P | True Output Bit 1 |
| 33 | D2N | Complementary Output Bit 2 |
| 34 | D2P | True Output Bit 2 |
| 35 | D3N | Complementary Output Bit 3 |
| 36 | D3P | True Output Bit 3 |

### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications

Pin Description (continued)

| PIN | NAME | FUNCTION |
| :---: | :---: | :---: |
| 37 | D4N | Complementary Output Bit 4 |
| 38 | D4P | True Output Bit 4 |
| 39 | D5N | Complementary Output Bit 5 |
| 40 | D5P | True Output Bit 5 |
| 42 | DCLKN | Complementary Clock Output. This output provides an LVDS-compatible output level and can be used to synchronize external devices to the converter clock. |
| 43 | DCLKP | True Clock Output. This output provides an LVDS-compatible output level and can be used to synchronize external devices to the converter clock. |
| 46 | D6N | Complementary Output Bit 6 |
| 47 | D6P | True Output Bit 6 |
| 48 | D7N | Complementary Output Bit 7 |
| 49 | D7P | True Output Bit 7 |
| 50 | D8N | Complementary Output Bit 8 |
| 51 | D8P | True Output Bit 8 |
| 52 | D9N | Complementary Output Bit 9 |
| 53 | D9P | True Output Bit 9 |
| 54 | D10N | Complementary Output Bit 10 |
| 55 | D10P | True Output Bit 10 |
| 56 | D11N | Complementary Output Bit 11 (MSB) |
| 57 | D11P | True Output Bit 11 (MSB) |
| 58 | ORN | Complementary Out-of-Range Control Bit Output. If an out-of-range condition is detected, bit ORN flags this condition by transitioning low. |
| 59 | ORP | True Out-of-Range Control Bit Output. If an out-of-range condition is detected, bit ORP flags this condition by transitioning high. |
| 68 | $\overline{\mathrm{T}} / \mathrm{B}$ | Output Format Select Input. This LVCMOS-compatible input controls the digital output format of the MAX1215N. $\bar{T} / B$ has an internal pulldown resistor. <br> $\overline{\mathrm{T}} / \mathrm{B}=0$ : Two's-complement output format. <br> $\overline{\mathrm{T}} / \mathrm{B}=1$ : Binary output format. |
| - | EP | Exposed Paddle. The exposed paddle is located on the backside of the chip and must be connected to AGND. |

### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications



Figure 1. Block Diagram

## Detailed DescriptionTheory of Operation

The MAX1215N uses a fully differential pipelined architecture that allows for high-speed conversion, optimized accuracy, and linearity while minimizing power consumption.
Both positive (INP) and negative analog input terminals (INN) are centered around a 0.7 V common-mode voltage, and accept a differential analog input voltage swing of $\pm \mathrm{V}_{\text {FS }} / 4$ each, resulting in a typical $1.385 \mathrm{~V}_{\text {P-P }}$ differential full-scale signal swing. Inputs INP and INN are sampled when the differential sampling clock signal transitions high. When using the clock-divide mode, the analog inputs are sampled at every other high transition of the differential sampling clock.
Each pipeline converter stage converts its input voltage to a digital output code. At every stage, except the last, the error between the input voltage and the digital output code is multiplied and passed along to the next pipeline stage. Digital error correction compensates for

ADC comparator offsets in each pipeline stage and ensures no missing codes. The result is a 12-bit parallel digital output word in user-selectable two's-complement or offset binary output formats with LVDS-compatible output levels. See Figure 1 for a more detailed view of the MAX1215N architecture.

Analog Inputs (INP, INN) INP and INN are the fully differential inputs of the MAX1215N. Differential inputs usually feature good rejection of even-order harmonics, which allows for enhanced AC performance as the signals are progressing through the analog stages. The MAX1215N analog inputs are self-biased at a 0.7 V common-mode voltage and allow a 1.385 V P-p differential input voltage swing (Figure 2). Both inputs are self-biased through $900 \Omega$ resistors, resulting in a typical differential input resistance of $1.8 \mathrm{k} \Omega$. Drive the analog inputs of the MAX1215N in AC-coupled configuration to achieve best dynamic performance. See the TransformerCoupled, Differential Analog Input Drive section.

### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications



CS IS THE SAMPLING CAPACITANCE
Cp IS THE PARASITIC CAPACITANCE $\sim 1 \mathrm{pF}$


GND $\longrightarrow$

Figure 2. Simplified Analog Input Architecture and Allowable Input Voltage Range

# 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications 

## On-Chip Reference Circuit

The MAX1215N features an internal 1.25 V -bandgap reference circuit (Figure 3), which, in combination with an internal reference-scaling amplifier, determines the FSR of the MAX1215N. Bypass REFIO with a $0.1 \mu \mathrm{~F}$ capacitor to AGND. To compensate for gain errors or increase/decrease the ADC's FSR, the voltage of this bandgap reference can be indirectly adjusted by adding an external resistor (e.g., 100k $\Omega$ trim potentiometer) between REFADJ and AGND or REFADJ and REFIO. See the Applications Information section for a detailed description of this process.
To disable the internal reference, connect REFADJ to AVcc. Apply an external, stable reference at REFIO to set the converter's full scale. To enable the internal reference, connect REFADJ to AGND.

Clock Inputs (CLKP, CLKN)
Drive the clock inputs of the MAX1215N with an LVDS- or LVPECL-compatible clock to achieve the best dynamic performance. The clock signal source must be of high quality and low phase noise to avoid any degradation in the noise performance of the ADC. The clock inputs (CLKP, CLKN) are internally biased to 1.15 V , accept a typical 500mVP-P differential signal swing (Figure 4). See the Differential, AC-Coupled LVPECL-Compatible Clock Input section for more circuit details on how to drive CLKP and CLKN appropriately. Although not recommended, the clock inputs also accept a single-ended input signal.

The MAX1215N also features an internal clock-management circuit (duty-cycle equalizer) that ensures the clock signal applied to inputs CLKP and CLKN is processed to provide a $50 \%$ duty-cycle clock signal that desensitizes the performance of the converter to variations in the duty cycle of the input clock source. Note that the clock duty-cycle equalizer cannot be turned off externally and requires a minimum 20 MHz clock frequency to allow the device to meet data sheet specifications.

## Data Clock Outputs (DCLKP, DCLKN)

The MAX1215N features a differential clock output, which can be used to latch the digital output data with an external latch or receiver. Additionally, the clock output can be used to synchronize external devices (e.g., FPGAs) to the ADC. DCLKP and DCLKN are differential outputs with LVDS-compatible voltage levels. There is a 3.77 ns delay time between the rising (falling) edge of CLKP (CLKN) and the rising (falling) edge of DCLKP (DCLKN). See Figure 5 for timing details.

Divide-by-2 Clock Control (CLKDIV)
The MAX1215N offers a clock control line (CLKDIV), which supports the reduction of clock jitter in a system. Connect CLKDIV to OGND to enable the ADC's internal divide-by-2 clock divider. Data is now updated at onehalf the ADC's input clock rate. CLKDIV has an internal pulldown resistor and can be left open for applications that require this divide-by-2 mode. Connecting CLKDIV to OVCC disables the divide-by-2 mode.


Figure 3. Simplified Reference Architecture

# 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications 



Figure 4. Simplified Clock Input Architecture

## System Timing Requirements

Figure 5 depicts the relationship between the clock input and output, analog input, sampling event, and data output. The MAX1215N samples on the rising (falling) edge of CLKP (CLKN). Output data is valid on the next rising (falling) edge of the DCLKP (DCLKN) clock, but has an internal latency of 11 clock cycles.

## Digital Outputs (D0P/N-D11P/N, DCLKP/N,

 ORP/N) and Control Input T/B Digital outputs D0P/N-D11P/N, DCLKP/N, and ORP/N are LVDS compatible, and data on D0P/N-D11P/N is presented in either binary or two's-complement format (Table 1). The $\bar{T} / B$ control line is an LVCMOS-compatible input, which allows the user to select the desired output format. Pulling $\overline{\mathrm{T}} / \mathrm{B}$ low outputs data in two's complement, and pulling it high presents data in offset binary format on the 12-bit parallel bus. $\bar{T} / B$ has an internal pulldown resistor and may be left unconnected in applications using only two's-complement output format. All LVDS outputs provide a typical 360mV voltage swing around a 1.24 V common-mode voltage, and must be terminated at the far end of each transmission line pair (true and complementary) with $100 \Omega$. Apply a 1.7 V to 1.9 V voltage supply at $\mathrm{OV}_{\mathrm{CC}}$ to power the LVDS outputs.The MAX1215N offers an additional differential output pair (ORP, ORN) to flag out-of-range conditions, where out-of-range is above positive or below negative full scale. An out-of-range condition is identified with ORP (ORN) transitioning high (low).
Note: Although a differential LVDS output architecture reduces single-ended transients to the supply and ground planes, capacitive loading on the digital outputs should still be kept as low as possible. Using LVDS buffers on the digital outputs of the ADC when driving larger loads may improve overall performance and reduce system-timing constraints.


Figure 5. System and Output Timing Diagram

### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications

Table 1. MAX1215N Digital Output Coding

| INP ANALOG INPUT VOLTAGE LEVEL | INN ANALOG INPUT VOLTAGE LEVEL | OUT-OF-RANGE ORP (ORN) | BINARY DIGITAL OUTPUT CODE (D11P/N-D0P/N) | TWO'S-COMPLEMENT DIGITAL OUTPUT CODE (D11P/N-D0P/N) |
| :---: | :---: | :---: | :---: | :---: |
| $>\mathrm{V}_{\mathrm{CM}}+\mathrm{V}_{\mathrm{FS}} / 4$ | $<\mathrm{V}_{\mathrm{CM}}-\mathrm{V}_{\mathrm{FS}} / 4$ | 1 (0) | 111111111111 (exceeds +FS, OR set) | 011111111111 (exceeds +FS, OR set) |
| $\mathrm{V}_{\mathrm{CM}}+\mathrm{V}_{\mathrm{FS}} / 4$ | $\mathrm{V}_{\mathrm{CM}}-\mathrm{V}_{\mathrm{FS}} / 4$ | 0 (1) | 111111111111 (+FS) | 011111111111 (+FS) |
| $\mathrm{V}_{\mathrm{CM}}$ | $\mathrm{V}_{\mathrm{CM}}$ | O (1) | 100000000000 or 011111111111 (FS/2) | $\begin{gathered} 000000000000 \text { or } \\ 111111111111 \text { (FS/2) } \end{gathered}$ |
| $\mathrm{V}_{\mathrm{CM}}-\mathrm{V}_{\mathrm{FS}} / 4$ | $V_{C M}+V_{F S} / 4$ | 0 (1) | 000000000000 (-FS) | 100000000000 (-FS) |
| $<\mathrm{V}_{\mathrm{CM}}+\mathrm{V}_{\mathrm{FS}} / 4$ | $>\mathrm{V}_{\mathrm{CM}}-\mathrm{V}_{\mathrm{FS}} / 4$ | 1 (0) | 000000000000 (exceeds -FS, OR set) | $\begin{gathered} 100000000000 \\ \text { (exceeds -FS, OR set) } \end{gathered}$ |



Figure 6a. Circuit Suggestions to Adjust the ADC's Full-Scale Range

## Applications Information <br> FSR Adjustments Using the Internal Bandgap Reference

The MAX1215N supports a $10 \%$ ( $\pm 5 \%$ ) full-scale adjustment range. To decrease the full-scale signal range, add an external resistor value ranging from $13 \mathrm{k} \Omega$ to $1 \mathrm{M} \Omega$ between REFADJ and AGND. Adding a variable resistor, potentiometer, or predetermined resis-
tor value between REFADJ and REFIO increases the FSR of the data converter. Figure 6a shows the two possible configurations and their impact on the overall full-scale range adjustment of the MAX1215N. Do not use resistor values of less than $13 \mathrm{k} \Omega$ to avoid instability of the internal gain regulation loop for the bandgap reference. See Figure 6b for the resulting FSR for a series of resistor values.

# 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications 


improving the SNR performance. To accomplish this, a $50 \Omega$ reverse-terminated clock signal source with low phase noise is AC-coupled into a fast differential receiver such as the MC100LVEL16 (Figure 7). The receiver produces the necessary LVPECL output levels to drive the clock inputs of the data converter.

## Transformer-Coupled,

Differential Analog Input Drive
The MAX1215N provides the best SFDR and THD with fully differential input signals and it is not recommended to drive the ADC inputs in single-ended configuration. In differential input mode, even-order harmonics are usually lower since INP and INN are balanced, and

The MAX1215N dynamic performance depends on the use of a very clean clock source. The phase noise floor of the clock source has a negative impact on the SNR performance. Spurious signals on the clock signal source also affect the ADC's dynamic range. The preferred method of clocking the MAX1215N is differentially with LVDS- or LVPECL-compatible input levels. The fast data transition rates of these logic families minimize the clock-input circuitry's transition uncertainty, thereby

## Differential, AC-Coupled, LVPECL-Compatible Clock Input

### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications

each of the ADC inputs only requires half the signal swing compared to a single-ended configuration.
Wideband RF transformers provide an excellent solution to convert a single-ended signal to a fully differential signal, required by the MAX1215N to reach its optimum dynamic performance. Apply a secondaryside termination of a $1: 1$ transformer (e.g., Mini-Circuit's ADT1-1WT) into two separate $24.9 \Omega$ resistors. Higher source impedance values can be used at the expense of degradation in dynamic performance. Use resistors with tight tolerance ( $0.5 \%$ ) to minimize effects of imbalance, maximizing the ADC's dynamic range. This configuration optimizes THD and SFDR performance of the ADC by reducing the effects of transformer parasitics. However, the source impedance combined with the shunt capacitance provided by a PC board and the ADC's parasitic capacitance limit the ADC's full-power input bandwidth.

To further enhance SFDR performance at high input frequencies (> 100 MHz ), place a second transformer (Figure 8) in series with the single-ended-to-differential conversion transformer. This transformer reduces the increase of even-order harmonics at high frequencies.

## Single-Ended, AC-Coupled Analog Inputs

Although not recommended, the MAX1215N can be used in single-ended mode (Figure 9). AC-couple the analog signals to the positive input INP through a $0.1 \mu \mathrm{~F}$ capacitor terminated with a $49.9 \Omega$ resistor to AGND. Terminate the negative input INN with a $49.9 \Omega$ resistor in series with a $0.1 \mu \mathrm{~F}$ capacitor to AGND. In single-ended mode, the input range is limited to approximately half of the FSR of the device, and dynamic performance usually degrades.


Figure 8. Analog Input Configuration with Back-to-Back Transformers and Secondary-Side Termination


Figure 9. Single-Ended AC-Coupled Analog Input Configuration

# 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications 

## Grounding, Bypassing, and Board Layout Considerations

The MAX1215N requires board layout design techniques suitable for high-speed data converters. This ADC provides separate analog and digital power supplies. The analog and digital supply voltage pins accept 1.7 V to 1.9 V input voltage ranges. Although both supply types can be combined and supplied from one source, it is recommended to use separate sources to cut down on performance degradation caused by digital switching currents, which can couple into the analog supply network. Isolate analog and digital supplies ( AVCC and $\mathrm{OV} C \mathrm{C}$ ) where they enter the PC board with separate networks of ferrite beads and capacitors to their corresponding grounds (AGND, OGND).
To achieve optimum performance, provide each supply with a separate network of a $47 \mu \mathrm{~F}$ tantalum capacitor and parallel combinations of $10 \mu \mathrm{~F}$ and $1 \mu \mathrm{~F}$ ceramic capacitors. Additionally, the ADC requires each supply pin to be bypassed with separate $0.1 \mu \mathrm{~F}$ ceramic capacitors (Figure 10). Locate these capacitors directly at the ADC supply pins or as close as possible to the MAX1215N. Choose surface-mount capacitors, whose preferred location should be on the same side as the converter to save space and minimize the inductance. If close placement on the same side is not possible, these bypassing capacitors may be routed through vias to the bottom side of the PC board.
Multilayer boards with separated ground and power planes produce the highest level of signal integrity. Consider the use of a split ground plane arranged to
match the physical location of analog and digital ground on the ADC's package. The two ground planes should be joined at a single point so the noisy digital ground currents do not interfere with the analog ground plane. The dynamic currents that may need to travel long distances before they are recombined at a com-mon-source ground, resulting in large and undesirable ground loops, are a major concern with this approach. Ground loops can degrade the input noise by coupling back to the analog front-end of the converter, resulting in increased spurious activity, leading to decreased noise performance.
Alternatively, all ground pins could share the same ground plane, if the ground plane is sufficiently isolated from any noisy, digital systems ground. To minimize the coupling of the digital output signals from the analog input, segregate the digital output bus carefully from the analog input circuitry. To further minimize the effects of digital noise coupling, ground return vias can be positioned throughout the layout to divert digital switching currents away from the sensitive analog sections of the ADC. This approach does not require split ground planes, but can be accomplished by placing substantial ground connections between the analog front-end and the digital outputs.
The MAX1215N is packaged in a 68-pin QFN-EP package (package code: G6800-4), providing greater design flexibility, increased thermal dissipation, and optimized AC performance of the ADC. The exposed paddle (EP) must be soldered down to AGND.
In this package, the data converter die is attached to an EP lead frame with the back of this frame exposed


Figure 10. Grounding, Bypassing, and Decoupling Recommendations for the MAX1215N

# 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications 

at the package bottom surface, facing the PC board side of the package. This allows a solid attachment of the package to the board with standard infrared (IR) flow soldering techniques.
Thermal efficiency is one of the factors for selecting a package with an exposed pad for the MAX1215N. The exposed pad improves thermal efficiency and ensures a solid ground connection between the ADC and the PC board's analog ground layer.
Considerable care must be taken when routing the digital output traces for a high-speed, high-resolution data converter. Keep trace lengths at a minimum and place minimal capacitive loading (less than 5 pF ) on any digital trace to prevent coupling to sensitive analog sections of the ADC. It is recommended running the LVDS output traces as differential lines with $100 \Omega$ matched impedance from the ADC to the LVDS load device.

## Static Parameter Definitions

## Integral Nonlinearity (INL)

Integral nonlinearity is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best straight-line fit or a line drawn between the end points of the transfer function, once offset and gain errors have been nullified. The static linearity parameters for the MAX1215N are measured using the histogram method with a 10 MHz input frequency.

Differential Nonlinearity (DNL) Differential nonlinearity is the difference between an actual step width and the ideal value of 1 LSB. A DNL error specification of less than 1 LSB guarantees no missing codes and a monotonic transfer function. The MAX1215N's DNL specification is measured with the histogram method based on a 10 MHz input tone.

Dynamic Parameter Definitions
Aperture Jitter
Figure 11 depicts the aperture jitter ( $\mathrm{t}_{\mathrm{AJ}}$ ), which is the sample-to-sample variation in the aperture delay.

## Aperture Delay

Aperture delay ( $\mathrm{t}_{\mathrm{AD}}$ ) is the time defined between the rising edge of the sampling clock and the instant when an actual sample is taken (Figure 11).

Signal-to-Noise Ratio (SNR)
For a waveform perfectly reconstructed from digital samples, the theoretical maximum SNR is the ratio of the fullscale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum ana-log-to-digital noise is caused by quantization error only and results directly from the ADC's resolution ( N bits):

$$
\mathrm{SNR}_{[\max ]}=6.02 \times \mathrm{N}+1.76
$$

In reality, other noise sources such as thermal noise, clock jitter, signal phase noise, and transfer function nonlinearities are also contributing to the SNR calculation and should be considered when determining the signal-to-noise ratio in ADC.

Signal-to-Noise Plus Distortion (SINAD) SINAD is computed by taking the ratio of the RMS signal to all spectral components excluding the fundamental and the DC offset. In the case of the MAX1215N, SINAD is computed from a curve fit.


Figure 11. Aperture Jitter/Delay Specifications

### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications

## Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio of RMS amplitude of the carrier frequency (maximum signal component) to the RMS value of the next-largest noise or harmonic distortion component. SFDR is usually measured in dBc with respect to the carrier frequency amplitude or in dBFS with respect to the ADC's full-scale range.

## Intermodulation Distortion (IMD)

IMD is the ratio of the RMS sum of the intermodulation products to the RMS sum of the two fundamental input tones. This is expressed as:
$I M D=20 \times \log \left(\frac{\sqrt{V_{I M 1}{ }^{2}+V_{I M 2}{ }^{2}+\ldots \ldots+V_{I M 3}{ }^{2}+V_{I M n}{ }^{2}}}{\sqrt{V_{1}^{2}+V_{2}^{2}}}\right)$

The fundamental input tone amplitudes (V1 and V 2) are at -7 dBFS . The intermodulation products are the amplitudes of the output spectrum at the following frequencies:

- Second-order intermodulation products: $\mathrm{f} / \mathrm{N} 1+\mathrm{f} / \mathrm{N} 2$, fin2-fin1
- Third-order intermodulation products: $2 \times$ fiN1-fiN2, $2 \times \mathrm{fIN} 2-\mathrm{fIN} 1,2 \times \mathrm{fIN} 1+\mathrm{fIN} 2,2 \times \mathrm{fIN} 2+\mathrm{fIN} 1$
- Fourth-order intermodulation products: $3 \times \mathrm{f} / \mathrm{N} 1$ - fiN2, $3 \times \mathrm{fIN} 2-\mathrm{fIN} 1,3 \times \mathrm{fIN} 1+\mathrm{fIN} 2,3 \times \mathrm{fIN} 2+\mathrm{fIN} 1$
- Fifth-order intermodulation products: $3 \times \mathrm{fIN} 1-2 \times \mathrm{fIN} 2$, $3 \times \mathrm{fI} \mathrm{N} 2-2 \times \mathrm{fIN} 1,3 \times \mathrm{fIN} 1+2 \times \mathrm{fI} \mathrm{N} 2,3 \times \mathrm{fIN} 2+2 \times \mathrm{fin} 1$

Full-Power Bandwidth
A large $-1 d B F S$ analog input signal is applied to an ADC and the input frequency is swept up to the point where the amplitude of the digitized conversion result has decreased by 3 dB . The -3 dB point is defined as the full-power input bandwidth frequency of the ADC.

Pin Configuration


### 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)

For the MAX1215N, the package code is G6800-4.


# 1.8V, Low-Power, 12-Bit, 250Msps ADC for Broadband Applications 

## Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)


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