

ISL78235

5A Automotive Synchronous Buck Regulator

FN8713

Rev 6.00

September 22, 2016

The **ISL78235** is a highly efficient, monolithic, synchronous step-down DC/DC converter that can deliver 5A of continuous output current from a 2.7V to 5.5V input supply. The device uses peak current mode control architecture to achieve very low duty cycle operation at high frequency with fast transient response and excellent loop stability.

The ISL78235 integrates a low ON-resistance P-channel (35mΩ, typical) high-side FET and N-channel (11mΩ, typical) low-side FET to maximize efficiency and minimize external component count. The 100% duty cycle operation allows less than 250mV dropout voltage at 5A output current. The operating frequency of the Pulse Width Modulator (PWM) is adjustable from 500kHz to 4MHz. The default switching frequency of 2MHz is set by connecting the FS pin high.

The ISL78235 can be configured for discontinuous (PFM) or forced continuous (PWM) operation at light load. Forced continuous operation reduces noise and RF interference, while discontinuous mode provides higher efficiency by reducing switching losses at light loads.

Fault protection is provided by internal hiccup mode current limiting during short-circuit and overcurrent conditions. The device also integrates output overvoltage and over-temperature protections. A power-good monitor indicates when the output is in regulation. The ISL78235 offers a 1ms Power-Good (PG) timer at power-up.

When in shutdown, the ISL78235 discharges the output capacitor through an internal 100Ω soft-stop switch. Other features include internal fixed or adjustable soft-start and internal/external compensation.

The ISL78235 is available in a 3mmx3mm 16 Ld Thin Quad Flat No-lead (TQFN) Pb-free package and in a 5mmx5mm 16 Ld Wettable Flank Quad Flat No-Lead (WFQFN) package with an exposed pad for improved thermal performance. The ISL78235 is rated to operate across the temperature range of -40 °C to +105 °C in the 3mmx3mm package and -40 °C to +125 °C in the 5mmx5mm package.

Features

- 2.7V to 5.5V input voltage range
- 2MHz default switching frequency
- 100ns guaranteed phase minimum on time for wide output regulation
- Adjustable switching frequency from 500kHz to 4MHz
- External synchronization from 1MHz to 4MHz
- Optional PFM mode for light-load efficiency improvement
- Very low ON-resistance HS/LS switches: 35mΩ/11mΩ
- Internal 1ms or adjustable external soft-start
- Soft-stop output discharge during disable
- OTP, OCP, output OVP, input UVLO protections
- 1% reference accuracy over-temperature
- Up to 95% efficiency
- AEC-Q100 qualified
- Common pinout family allows migration from 3A to 5A without PCB change:
 - ISL78233 3A
 - ISL78234 4A
 - ISL78235 5A

Applications

- DC/DC POL modules
- μC/μP, FPGA and DSP power
- Video processor/SOC power
- Automotive infotainment power

Related Literature

- [UG015](#), "ISL7823xEVAL1Z Evaluation Board User Guide"
- [ISL78233, ISL78234](#) Datasheet
- [UG062](#), "ISL7823xEVAL2Z Evaluation Board User Guide"

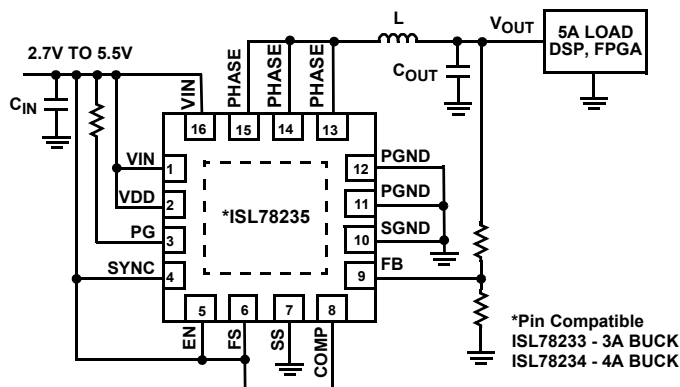


FIGURE 1. TYPICAL APPLICATION: 5A BUCK REGULATOR

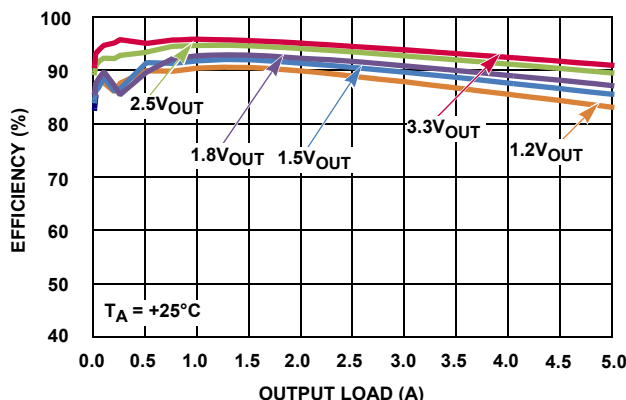


FIGURE 2. EFFICIENCY vs LOAD (VIN = 5V; fsw = 2MHz; SYNC = GND)

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Functional Block Diagram

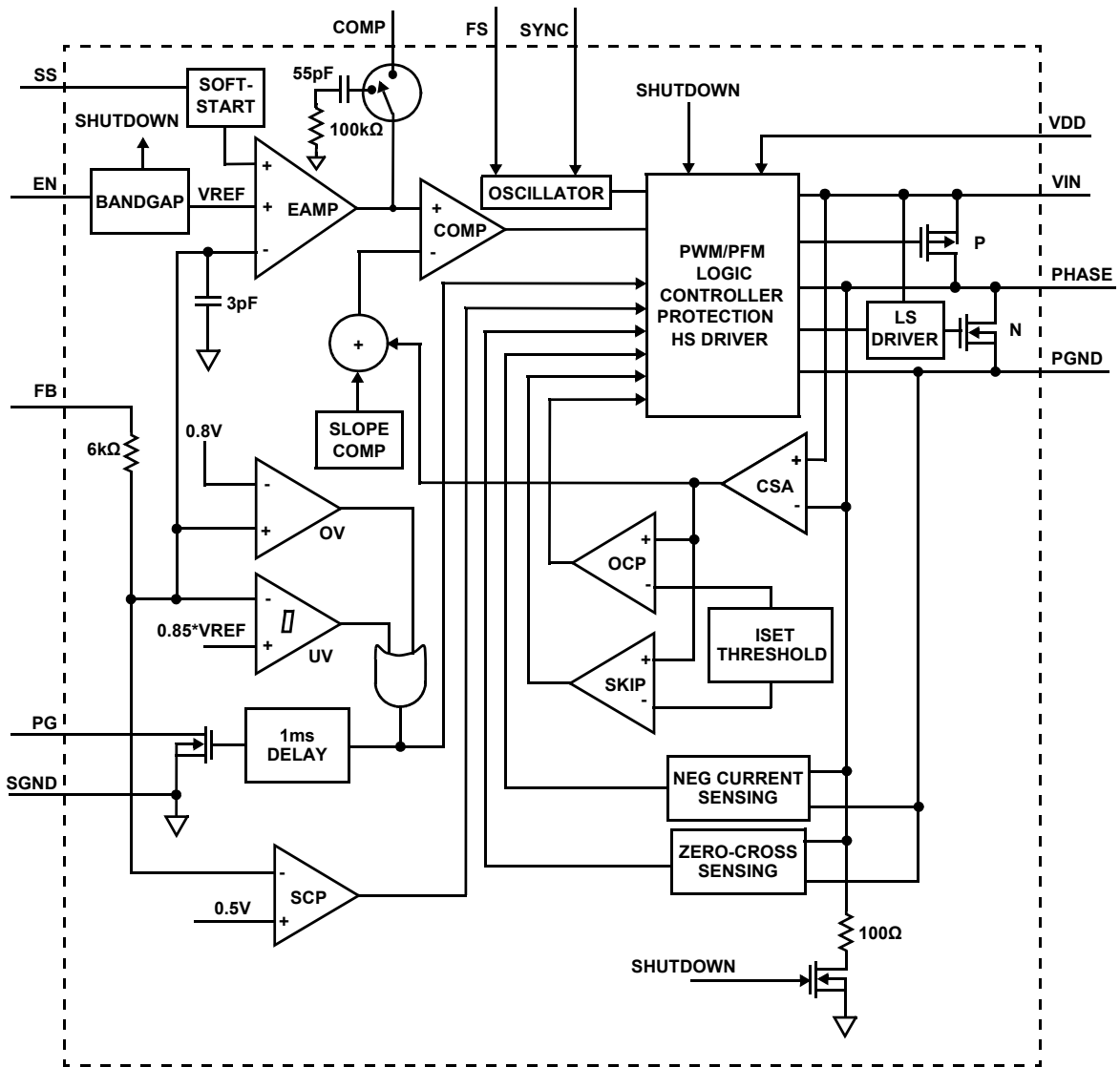
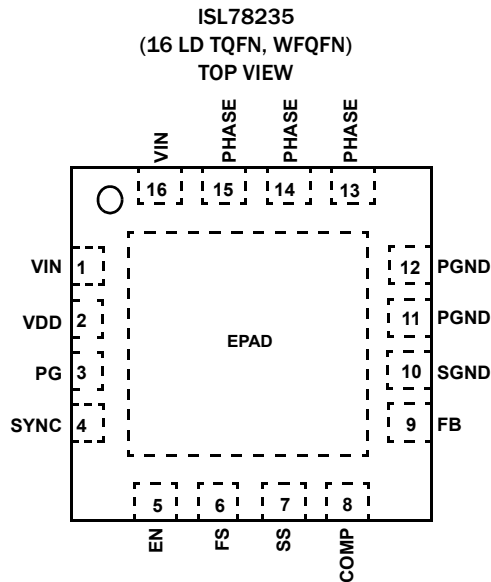


FIGURE 3. FUNCTIONAL BLOCK DIAGRAM

Pin Configuration



Pin Descriptions

| PIN NUMBER | PIN NAME | DESCRIPTION |
|-------------|----------|--|
| 1, 16 | VIN | Input supply voltage. Place a minimum of two 22 μ F low ESR ceramic capacitors from VIN to PGND as close as possible to the IC for decoupling. |
| 2 | VDD | Input supply voltage for the logic circuitry. A 0.1 μ F high frequency decoupling ceramic capacitor should also be placed close to the VDD and SGND pin. Connect to VIN pin. |
| 3 | PG | PG is an open-drain output for power-good indication. Use a 10k Ω to 100k Ω pull-up resistor connected from PG to VIN. At power-up or EN high, PG rising edge is delayed by 1ms upon output voltage within regulation. |
| 4 | SYNC | Mode selection pin. Connect to logic high or input voltage VIN for forced PWM mode. Connect to logic low or ground for PFM mode. Connect to an external function generator for synchronization with a positive edge trigger. In external synchronization the ISL78235 operates in forced PWM mode. The transition to and from internal oscillator to external synchronization is seamless and does not require disabling of the ISL78235. There is an internal 1M Ω pull-down resistor to SGND to prevent an undefined logic state if SYNC pin is floating. |
| 5 | EN | Regulator enable pin. Regulator is enabled when driven logic high. Regulator is shutdown and PHASE pin discharge output capacitor when enable pin is driven low. |
| 6 | FS | This pin sets the internal oscillator switching frequency using a resistor, R _{FS} , from the FS pin to GND. The frequency of operation may be programmed between 500kHz to 4MHz. The switching frequency is 2MHz if FS is connected to VIN. |
| 7 | SS | SS is used to adjust the soft-start time. Connect SS pin to SGND for internal 1ms soft-start time. Connect a capacitor from SS to SGND to adjust the soft-start time. Do not use more than 33nF on the SS pin. |
| 8 | COMP | COMP is the output of the error amplifier if COMP is not connected to VDD. An external compensation network must be used if COMP is not tied to VDD. If COMP is tied to VDD, the error amplifier output is internally compensated. External compensation network across COMP and SGND may be required to improve the loop compensation of the amplifier. |
| 9 | FB | The feedback network of the regulator, FB, is the negative input to the transconductance error amplifier. The output voltage is set by an external resistor divider connected to FB. With a properly selected divider, the output voltage can be set to any voltage between the power rail (reduced by converter losses) and the 0.6V reference. In addition, the regulator power-good and undervoltage protection circuitry use FB to monitor the regulator output voltage. |
| 10 | SGND | Signal ground, Connect to PGND. |
| 11, 12 | PGND | Power ground |
| 13, 14, 15 | PHASE | Switching node connections. Connect to one terminal of the inductor. This pin is discharged by a 100 Ω resistor when the device is disabled. See "Functional Block Diagram" on page 3 for more detail. |
| Exposed Pad | EPAD | The exposed pad must be connected to the SGND pin for proper electrical performance. Place as many vias as possible under the pad connecting to SGND plane for optimal thermal performance. |

Ordering Information

| PART NUMBER (Notes 1, 2, 3) | PART MARKING | OUTPUT VOLTAGE (V) | TEMP. RANGE (°C) | PACKAGE (RoHS Compliant) | PKG. DWG. # |
|--------------------------------|------------------------------|-----------------------|---------------------|-----------------------------|----------------|
| ISL78235ARZ | 8235 | Adjustable | -40 °C to +105 °C | 16 Ld 3x3mm TQFN | L16.3x3D |
| ISL78235AARZ | 78235A ARZ | Adjustable | -40 °C to +125 °C | 16 Ld 5x5mm WFQFN | L16.5x5D |
| ISL78235EVAL1Z | 3x3mm TQFN Evaluation Board | | | | |
| ISL78235EVAL2Z | 5x5mm WFQFN Evaluation Board | | | | |

NOTES:

1. Add "-T" suffix for 6k unit or "-T7A" suffix for 250 unit tape and reel options. Refer to [TB347](#) for details on reel specifications.
2. These Intersil Pb-free plastic packaged products employ special Pb-free material sets, molding compounds/die attach materials and 100% matte tin plate plus anneal (e3 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations). Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.
3. For Moisture Sensitivity Level (MSL), see the device information page for [ISL78235](#). For more information on MSL, see tech brief [TB363](#).

TABLE 1. KEY DIFFERENCE BETWEEN FAMILY OF PARTS

| PART NUMBER | I _{OUT} MAX (A) |
|-------------|-----------------------------|
| ISL78233 | 3 |
| ISL78234 | 4 |
| ISL78235 | 5 |

Typical Application Diagram

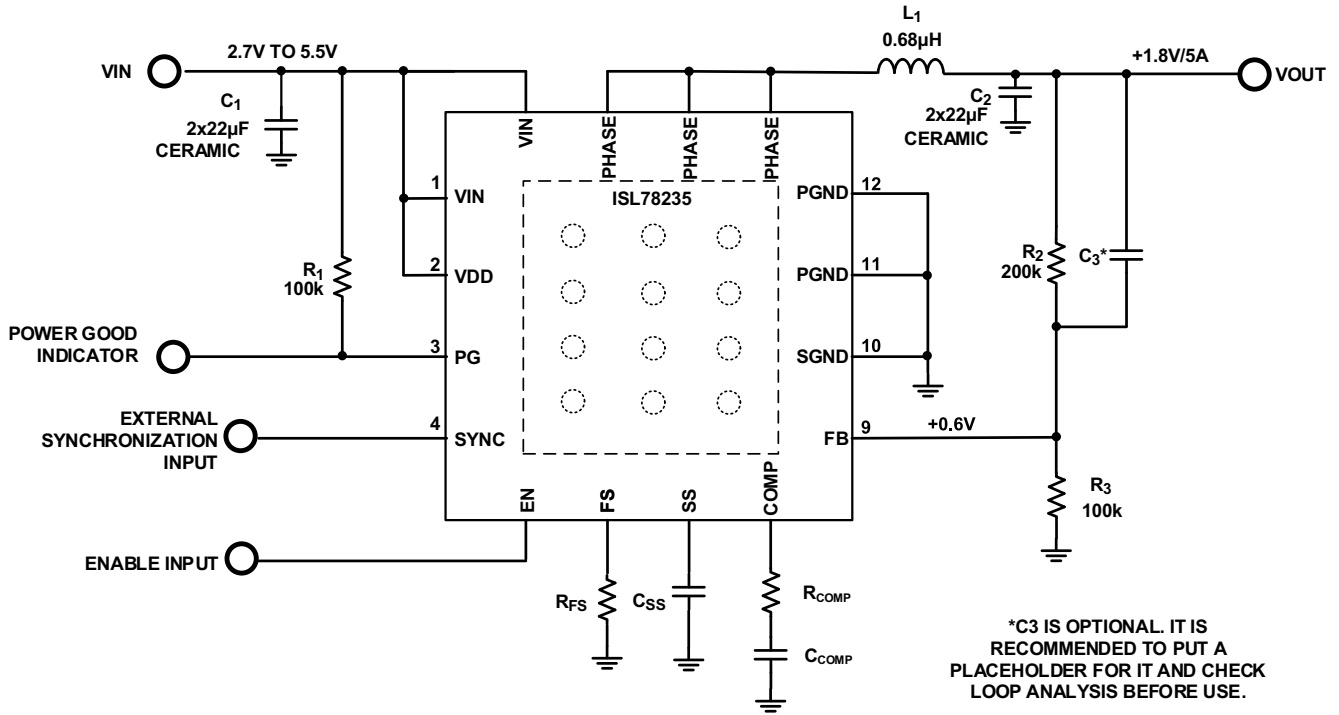


FIGURE 4. TYPICAL APPLICATION DIAGRAM

TABLE 2. COMPONENT SELECTION TABLE WITH INTERNAL COMPENSATION

| V _{OUT} | 1.2V | 1.5V | 1.8V | 2.5V | 3.3V |
|-------------------------|---------------|---------------|---------------|---------------|---------------|
| C ₁ | 2 x 22µF | 2 x 22µF | 2 x 22µF | 2x22µF | 2 x 22µF |
| C ₂ (Note 4) | 3 x 22µF | 3 x 22µF | 2 x 22µF | 2 x 22µF | 2 x 22µF |
| C ₃ | 22pF | 10pF | 10pF | 10pF | 10pF |
| L ₁ | 0.33µH-0.68µH | 0.33µH-0.68µH | 0.33µH-0.68µH | 0.47µH-0.78µH | 0.47µH-0.78µH |
| R ₂ | 100kΩ | 150kΩ | 200kΩ | 316kΩ | 450kΩ |
| R ₃ | 100kΩ | 100kΩ | 100kΩ | 100kΩ | 100kΩ |

NOTE:

4. C₂ values are minimum recommended values for ceramic capacitors. Higher capacitance may be needed based on system requirements.

Absolute Maximum Ratings (Reference to GND)

| | |
|---|--|
| VIN | -0.3V to 5.8V (DC) or 7V (20ms) |
| EN, FS, PG, SYNC, VFB | -0.3V to VIN + 0.3V |
| PHASE | -1.5V (100ns)/-0.3V (DC) to 6.5V (DC) or 7V (20ms) |
| COMP, SS | -0.3V to 2.7V |
| ESD Rating | |
| Human Body Model (Tested per AEC-Q100-002) | 5kV |
| Machine Model (Tested per AEC-Q100-003) | 300V |
| Charge Device Model (Tested per AEC-Q100-011) | 2kV |
| Latch-Up (Tested per AEC-Q100-004, Class II, Level A) | 100mA |

Thermal Information

| | | |
|--------------------------------------|---------------------------|----------------------|
| Thermal Resistance | θ_{JA} (°C/W) | θ_{JC} (°C/W) |
| 16 Ld TQFN Package (Notes 5, 6) | 43 | 3.5 |
| 16 Ld WFQFN Package (Notes 5, 6) | 33 | 3.5 |
| Operating Junction Temperature Range | -55°C to +125°C | |
| Storage Temperature Range | -65°C to +150°C | |
| Pb-Free Reflow Profile | see TB493 | |

Recommended Operating Conditions

| | |
|---------------------------|-----------------|
| VIN Supply Voltage Range | 2.7V to 5.5V |
| Load Current Range | 0A to 5A |
| Ambient Temperature Range | |
| 3x3mm TQFN | -40°C to +105°C |
| 5x5mm WFQFN | -40°C to +125°C |

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

NOTES:

- θ_{JA} is measured in free air with the component mounted on a high effective thermal conductivity test board with "direct attach" features. See Tech Brief [TB379](#).
- θ_{JC} , "case temperature" location is at the center of the exposed metal pad on the package underside.

Electrical Specifications Specification limits are established at the following conditions: $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$ or $T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$ depending on package, $V_{IN} = 3.6\text{V}$, $EN = V_{IN}$, unless otherwise noted. Typical values are at $T_A = +25^\circ\text{C}$. **Boldface limits apply across the operating temperature range specified in the Recommended Operating Conditions table for the specified package.**

| PARAMETER | SYMBOL | TEST CONDITIONS | MIN (Note 7) | TYP | MAX (Note 7) | UNIT |
|-------------------------------------|--------------|--|-----------------|-------|-----------------|---------------|
| INPUT SUPPLY | | | | | | |
| VIN Undervoltage Lockout Threshold | V_{UVLO} | Rising, no load | | 2.5 | 2.7 | V |
| | | Falling, no load | 2.20 | 2.45 | | V |
| Quiescent Supply Current | I_{VIN} | SYNC = GND, no load at the output | | 47 | | μA |
| | | SYNC = GND, no load at the output and no switches switching | | 47 | 60 | μA |
| | | SYNC = V_{IN} , $f_{SW} = 2\text{MHz}$, no load at the output | | 19 | 25 | mA |
| Shutdown Supply Current | I_{SD} | SYNC = GND, $V_{IN} = 5.5\text{V}$, EN = low | | 4 | 10 | μA |
| OUTPUT REGULATION | | | | | | |
| Reference Voltage | V_{REF} | | 0.594 | 0.600 | 0.606 | V |
| VFB Bias Current | I_{VFB} | VFB = 0.75V | | 0.1 | | μA |
| Line Regulation | | $V_{IN} = V_O + 0.5\text{V}$ to 5.5V (minimal 2.7V) | | 0.2 | | %/V |
| Soft-Start Ramp Time Cycle | | SS = SGND | | 1 | | ms |
| Soft-Start Charging Current | I_{SS} | $V_{SS} = 0.1\text{V}$ | 1.7 | 2.1 | 2.5 | μA |
| OVERCURRENT PROTECTION | | | | | | |
| Current Limit Blanking Time | t_{OCON} | | | 17 | | Clock pulses |
| Overcurrent and Auto Restart Period | t_{OCCOFF} | | | 8 | | SS cycle |
| Positive Peak Current Limit | I_{PLIMIT} | $T_A = +25^\circ\text{C}$ | 6.2 | 7.8 | 9.4 | A |
| | | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$ | 6.1 | | 11.0 | A |
| | | 5x5 mm WFQFN package $T_A = +105^\circ\text{C}$ to $+125^\circ\text{C}$ | | | 12.5 | A |
| Peak Skip Limit | I_{SKIP} | $T_A = +25^\circ\text{C}$ | 0.85 | 1.10 | 1.40 | A |
| | | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$ | 0.83 | | 1.60 | A |
| | | 5x5 mm WFQFN package $T_A = +105^\circ\text{C}$ to $+125^\circ\text{C}$ | | | 1.65 | A |

Electrical Specifications Specification limits are established at the following conditions: $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$ or $T_A = -40^\circ\text{C}$ to $+125^\circ\text{C}$ depending on package, $V_{IN} = 3.6\text{V}$, $EN = V_{IN}$, unless otherwise noted. Typical values are at $T_A = +25^\circ\text{C}$. **Boldface limits apply across the operating temperature range specified in the Recommended Operating Conditions table for the specified package. (Continued)**

| PARAMETER | SYMBOL | TEST CONDITIONS | MIN (Note 7) | TYP | MAX (Note 7) | UNIT |
|------------------------------------|--------------|--|-----------------|------|-----------------|------------------|
| Zero Cross Threshold | | | -275 | | 375 | mA |
| Negative Current Limit | I_{NLIMIT} | $T_A = +25^\circ\text{C}$ | -5.1 | -2.8 | -1.3 | A |
| | | | -6.0 | | -0.6 | A |
| COMPENSATION | | | | | | |
| Error Amplifier Transconductance | | COMP = VDD, internal compensation | | 125 | | $\mu\text{A/V}$ |
| | | External compensation | | 130 | | $\mu\text{A/V}$ |
| Transresistance | RT | $T_A = -40^\circ\text{C}$ to $+105^\circ\text{C}$ | 0.11 | 0.17 | 0.22 | Ω |
| | | 5x5 mm WFQFN package $T_A = +105^\circ\text{C}$ to $+125^\circ\text{C}$ | 0.1 | | | Ω |
| MOSFET | | | | | | |
| P-Channel ON-Resistance | | $V_{IN} = 5\text{V}$, $I_O = 200\text{mA}$ | 26 | 35 | 50 | $\text{m}\Omega$ |
| | | $V_{IN} = 2.7\text{V}$, $I_O = 200\text{mA}$ | 38 | 52 | 78 | $\text{m}\Omega$ |
| N-Channel ON-Resistance | | $V_{IN} = 5\text{V}$, $I_O = 200\text{mA}$ | 5 | 11 | 20 | $\text{m}\Omega$ |
| | | $V_{IN} = 2.7\text{V}$, $I_O = 200\text{mA}$ | 8 | 15 | 31 | $\text{m}\Omega$ |
| PHASE | | | | | | |
| PHASE Maximum Duty Cycle | | | | 100 | | % |
| PHASE Minimum On-Time | | SYNC = High | | | 100 | ns |
| OSCILLATOR | | | | | | |
| Nominal Switching Frequency | f_{SW} | FS = V_{IN} | 1730 | 2000 | 2350 | kHz |
| | | FS with $R_S = 402\text{k}\Omega$ | | 420 | | kHz |
| | | FS with $R_S = 42.2\text{k}\Omega$ | | 4200 | | kHz |
| SYNC Logic LOW to HIGH Threshold | | | 0.67 | 0.75 | 0.84 | V |
| SYNC Logic Hysteresis | | | 0.10 | 0.17 | 0.20 | V |
| SYNC Logic Input Leakage Current | | SYNC = 3.6V | | 3.7 | 5.0 | μA |
| POWER-GOOD (PG) | | | | | | |
| Output Low Voltage | | $I_{PG} = 1\text{mA}$ | | | 0.3 | V |
| PG Delay Time (Rising Edge) | | Time from V_{OUT} reached regulation | 0.5 | 1.0 | 2.0 | ms |
| PG Delay Time (Falling Edge) | | | | 6.5 | | μs |
| PG Pin Leakage Current | | PG = V_{IN} | | 0.01 | 0.10 | μA |
| OVP PG Rising Threshold | | | | 0.80 | | V |
| UVP PG Rising Threshold | | | 80 | 85 | 90 | % |
| UVP PG Hysteresis | | | | 5.5 | | % |
| EN | | | | | | |
| Logic Input Low | | | | | 0.4 | V |
| Logic Input High | | | 0.9 | | | V |
| EN Logic Input Leakage Current | | EN = 3.6V | | 0.1 | 1.0 | μA |
| OVER-TEMPERATURE PROTECTION | | | | | | |
| Thermal Shutdown | | Temperature rising | | 150 | | $^\circ\text{C}$ |
| Thermal Shutdown Hysteresis | | Temperature falling | | 25 | | $^\circ\text{C}$ |

NOTE:

7. Compliance to datasheet limits is assured by one or more methods: production test, characterization and/or design.

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = V_{DD} = 5\text{V}$,

$V_{OUT} = 1.8\text{V}$, $EN = V_{DD}$, $SYNC = V_{DD}$, $L = 0.68\mu\text{H}$, $f_{SW} = 2\text{MHz}$, $C_{IN} = 2 \times 22\mu\text{F}$, $C_{OUT} = 2 \times 22\mu\text{F}$, $I_{OUT} = 0\text{A to } 5\text{A}$.

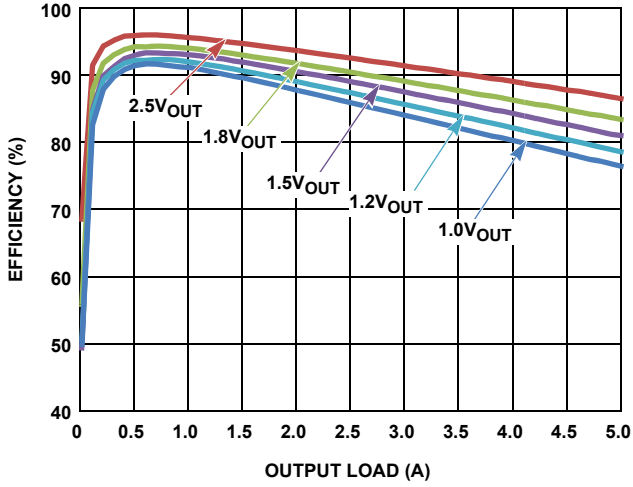


FIGURE 5. EFFICIENCY vs LOAD (3.3V_{IN} ; $SYNC = V_{DD}$)

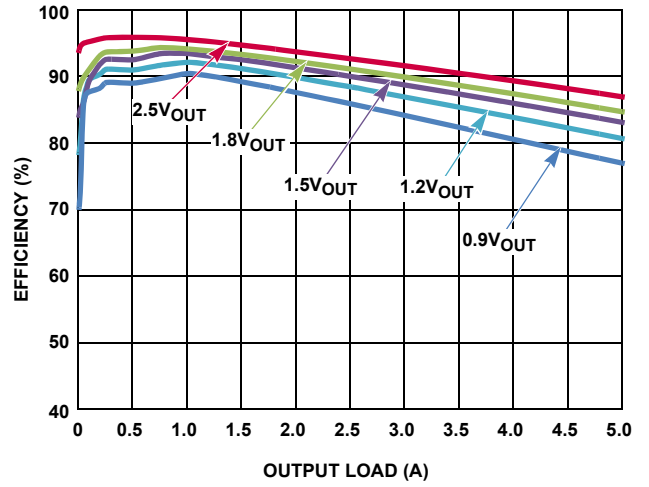


FIGURE 6. EFFICIENCY vs LOAD (3.3V_{IN} ; $SYNC = GND$)

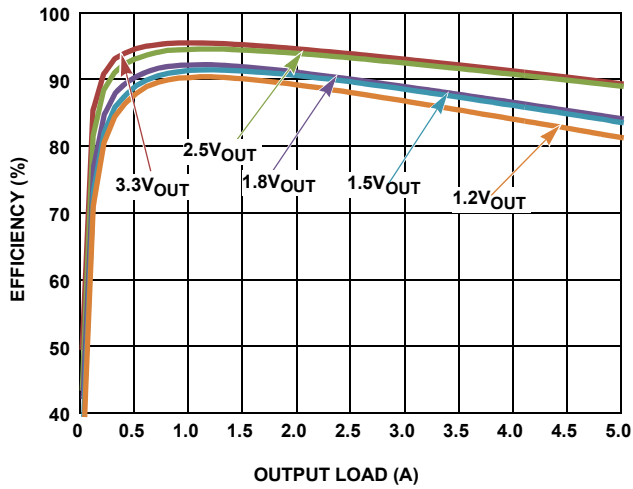


FIGURE 7. EFFICIENCY vs LOAD (5V_{IN} ; $SYNC = V_{DD}$)

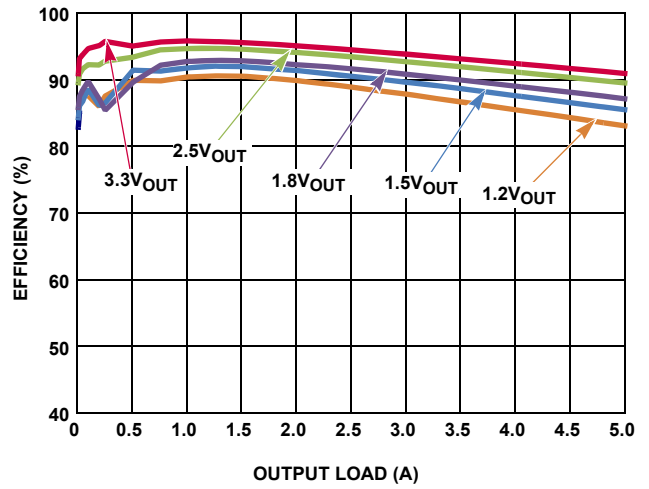


FIGURE 8. EFFICIENCY vs LOAD (5V_{IN} ; $SYNC = GND$)

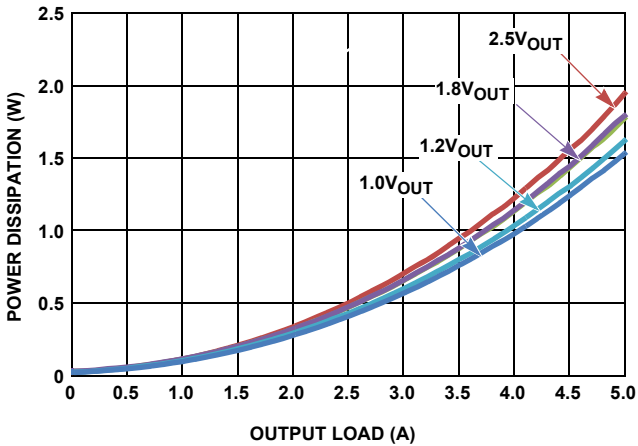


FIGURE 9. POWER DISSIPATION vs LOAD (3.3V_{IN} ; $SYNC = V_{DD}$)

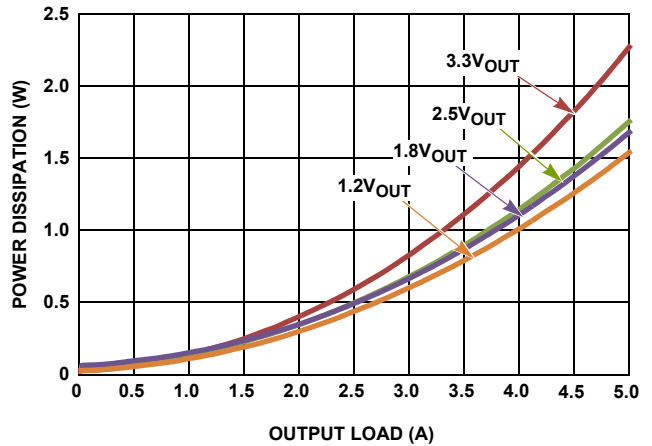


FIGURE 10. POWER DISSIPATION vs LOAD (5V_{IN} ; $SYNC = V_{DD}$)

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = V_{DD} = 5\text{V}$, $V_{OUT} = 1.8\text{V}$, $EN = V_{DD}$, $SYNC = V_{DD}$, $L = 0.68\mu\text{H}$, $f_{SW} = 2\text{MHz}$, $C_{IN} = 2 \times 22\mu\text{F}$, $C_{OUT} = 2 \times 22\mu\text{F}$, $I_{OUT} = 0\text{A}$ to 5A . (Continued)

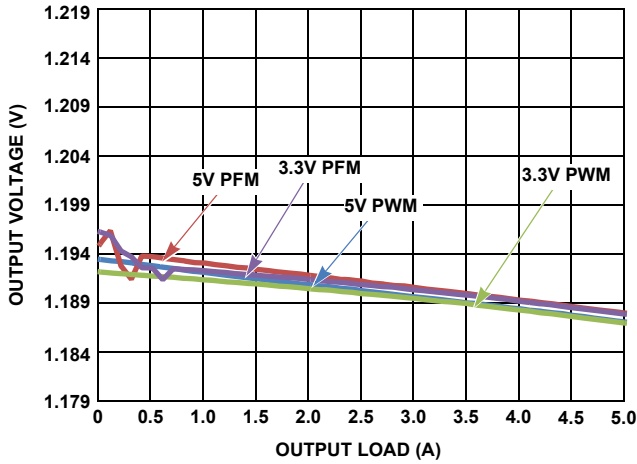


FIGURE 11. V_{OUT} REGULATION vs LOAD ($V_{OUT} = 1.2\text{V}$)

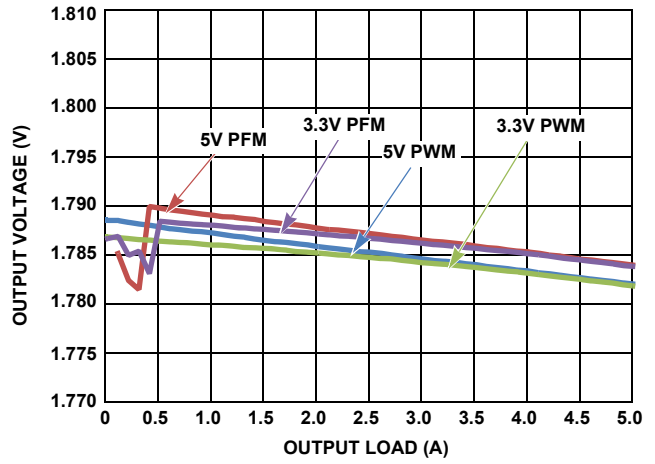


FIGURE 12. V_{OUT} REGULATION vs LOAD ($V_{OUT} = 1.8\text{V}$)

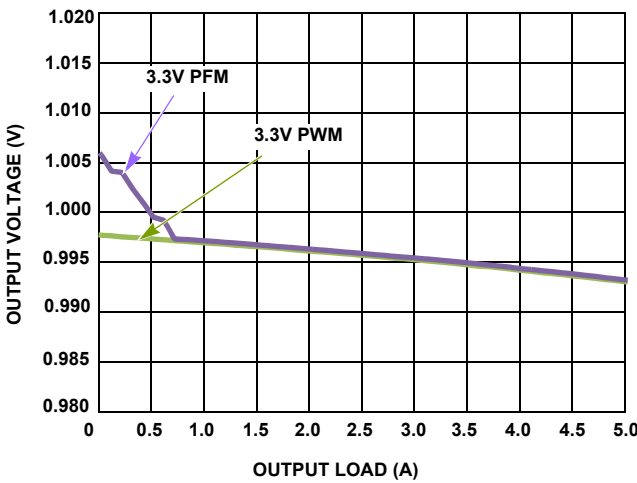


FIGURE 13. V_{OUT} REGULATION vs LOAD ($V_{OUT} = 1.0\text{V}$)

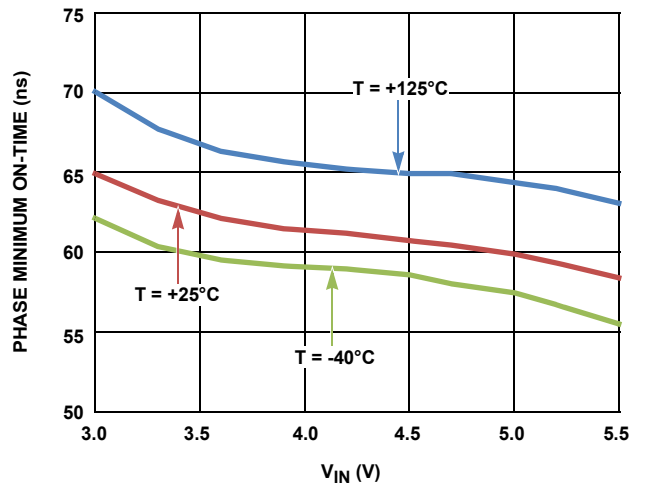


FIGURE 14. PHASE MINIMUM ON-TIME vs V_{IN}

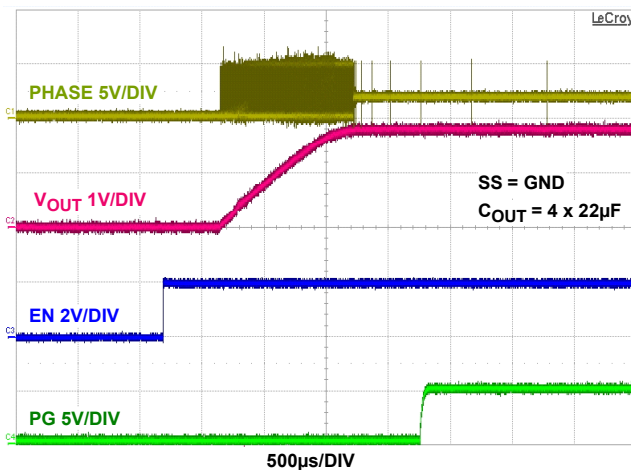


FIGURE 15. EN START-UP AT NO LOAD ($SYNC = GND$)

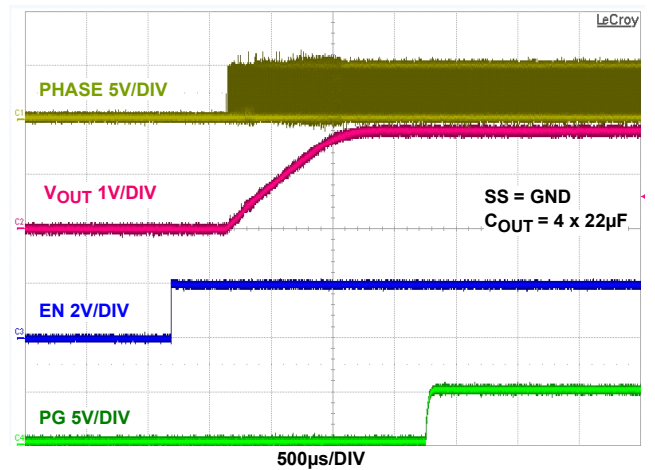


FIGURE 16. EN START-UP AT NO LOAD ($SYNC = V_{DD}$)

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = V_{DD} = 5\text{V}$, $V_{OUT} = 1.8\text{V}$, $\text{EN} = V_{DD}$, $\text{SYNC} = V_{DD}$, $L = 0.68\mu\text{H}$, $f_{\text{SW}} = 2\text{MHz}$, $C_{\text{IN}} = 2 \times 22\mu\text{F}$, $C_{\text{OUT}} = 2 \times 22\mu\text{F}$, $I_{\text{OUT}} = 0\text{A to } 5\text{A}$. (Continued)

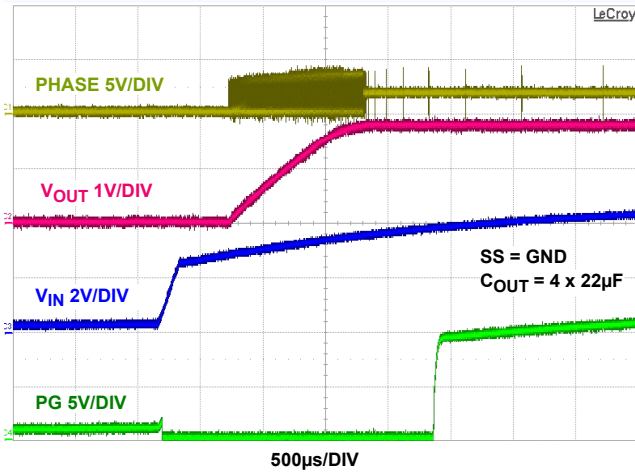


FIGURE 17. V_{IN} START-UP AT NO LOAD (SYNC = GND)

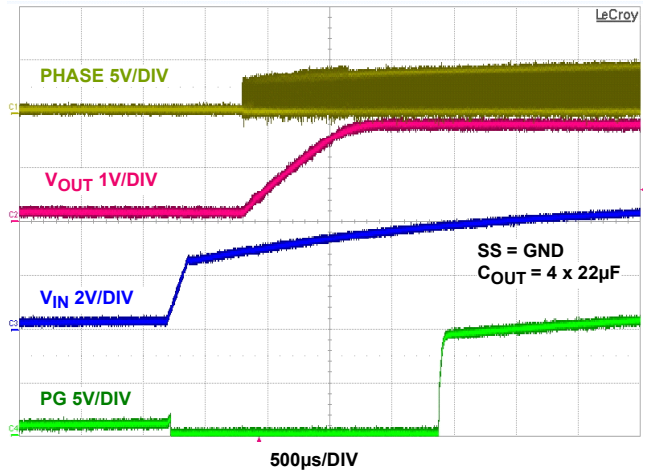


FIGURE 18. V_{IN} START-UP AT NO LOAD (SYNC = V_{DD})

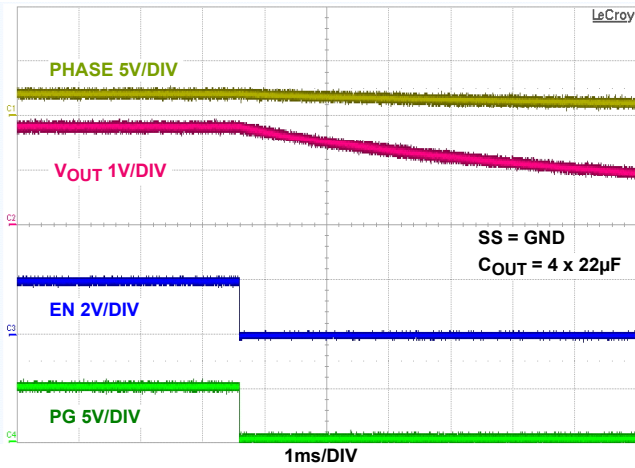


FIGURE 19. EN SHUTDOWN AT NO LOAD (SYNC = GND)

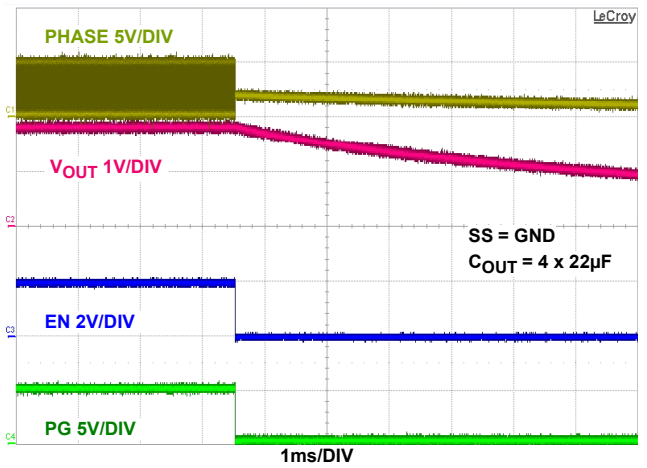


FIGURE 20. EN SHUTDOWN AT NO LOAD (SYNC = V_{DD})

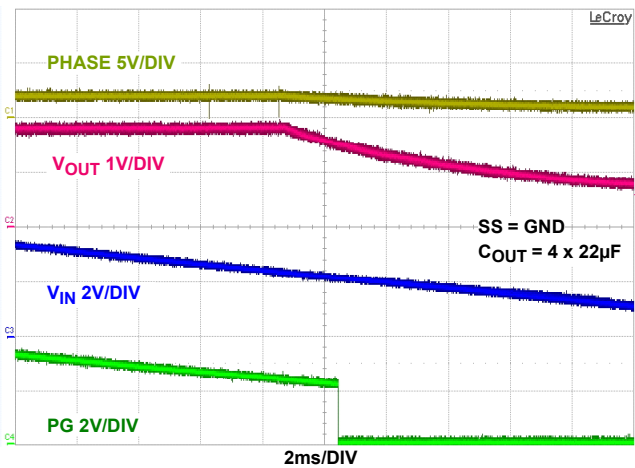


FIGURE 21. V_{IN} SHUTDOWN AT NO LOAD (SYNC = GND)

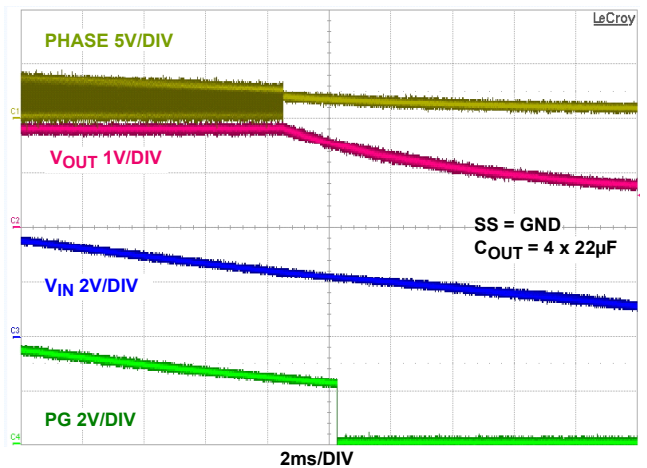


FIGURE 22. V_{IN} SHUTDOWN AT NO LOAD (SYNC = V_{DD})

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = V_{DD} = 5\text{V}$, $V_{OUT} = 1.8\text{V}$, $\text{EN} = V_{DD}$, $\text{SYNC} = V_{DD}$, $L = 0.68\mu\text{H}$, $f_{\text{SW}} = 2\text{MHz}$, $C_{\text{IN}} = 2 \times 22\mu\text{F}$, $C_{\text{OUT}} = 2 \times 22\mu\text{F}$, $I_{\text{OUT}} = 0\text{A to } 5\text{A}$. (Continued)

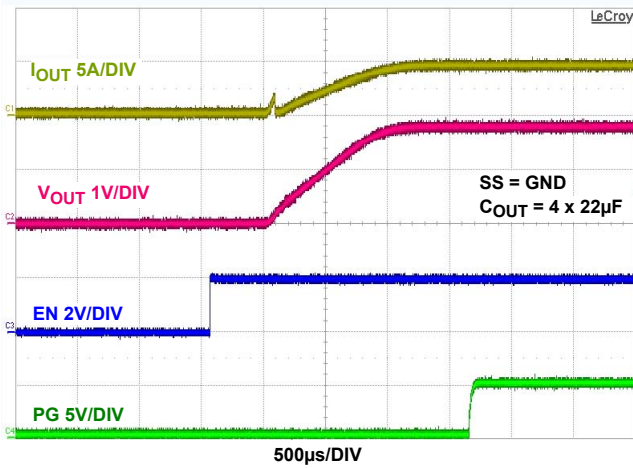


FIGURE 23. EN START-UP AT 5A LOAD (SYNC = GND)

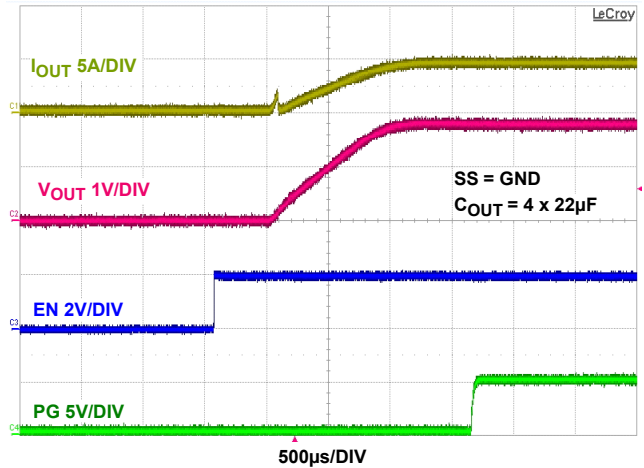


FIGURE 24. EN START-UP AT 5A LOAD (SYNC = VDD)

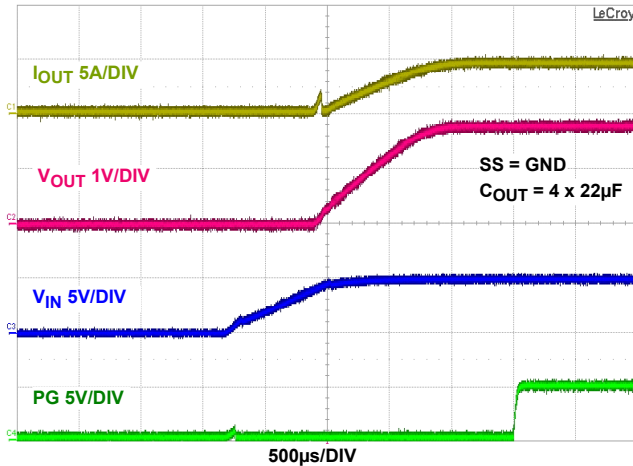


FIGURE 25. V_{IN} START-UP AT 5A LOAD (SYNC = GND)

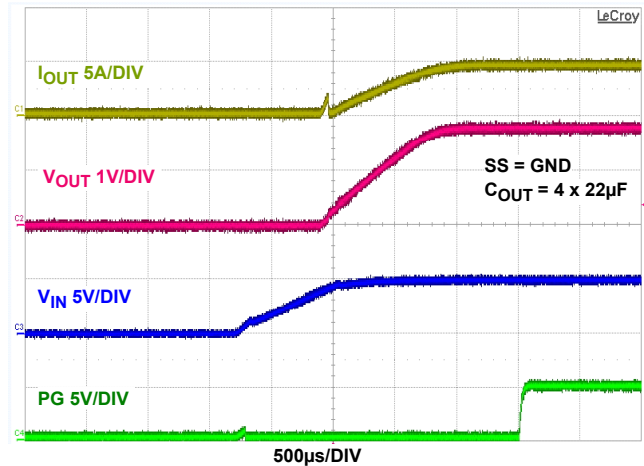


FIGURE 26. V_{IN} START-UP AT 5A LOAD (SYNC = VDD)

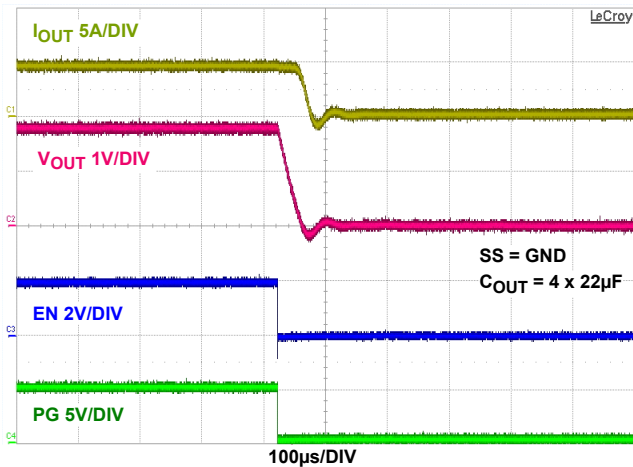


FIGURE 27. EN SHUT-DOWN AT 5A LOAD (SYNC = GND)

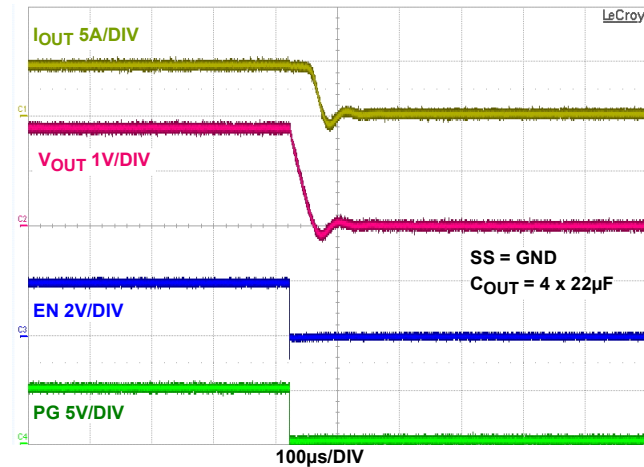


FIGURE 28. EN SHUT-DOWN AT 5A LOAD (SYNC = VDD)

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = V_{DD} = 5\text{V}$, $V_{OUT} = 1.8\text{V}$, $EN = V_{DD}$, $SYNC = V_{DD}$, $L = 0.68\mu\text{H}$, $f_{SW} = 2\text{MHz}$, $C_{IN} = 2 \times 22\mu\text{F}$, $C_{OUT} = 2 \times 22\mu\text{F}$, $I_{OUT} = 0\text{A}$ to 5A . (Continued)

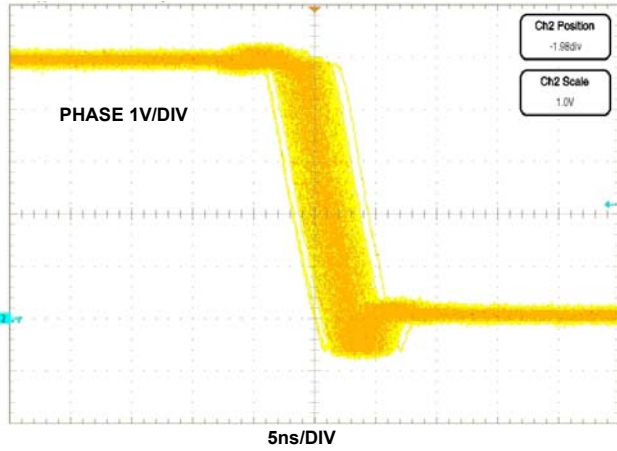


FIGURE 29. JITTER AT NO LOAD (SYNC = VDD)

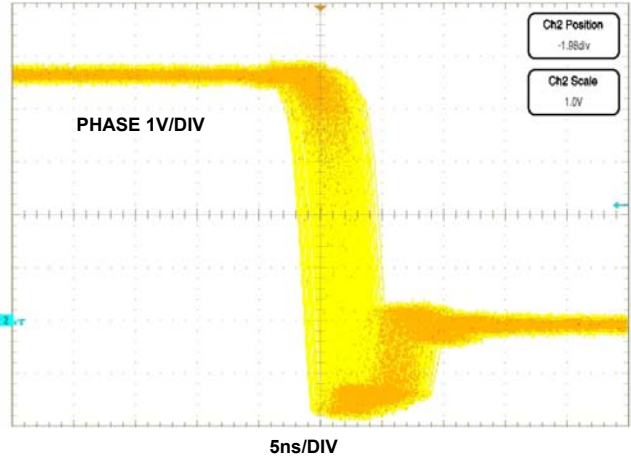


FIGURE 30. JITTER AT 5A LOAD (SYNC = VDD)

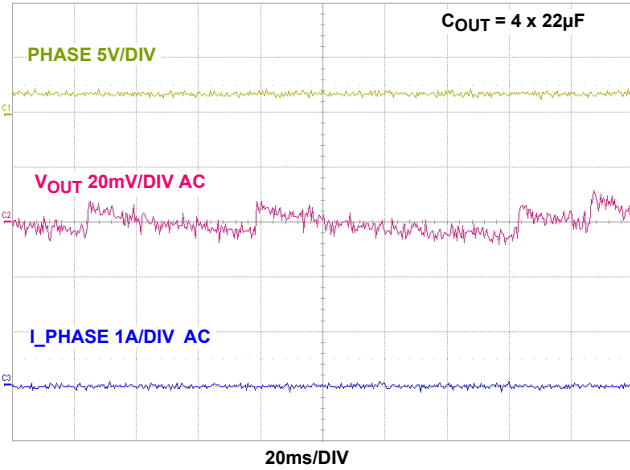


FIGURE 31. STEADY STATE AT NO LOAD (SYNC = GND)

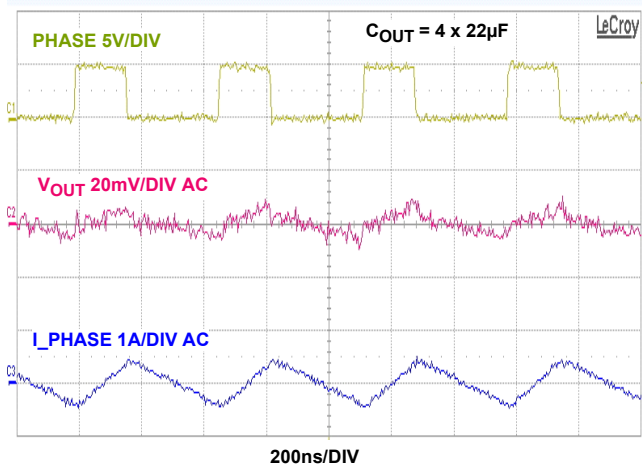


FIGURE 32. STEADY STATE AT NO LOAD (SYNC = VDD)

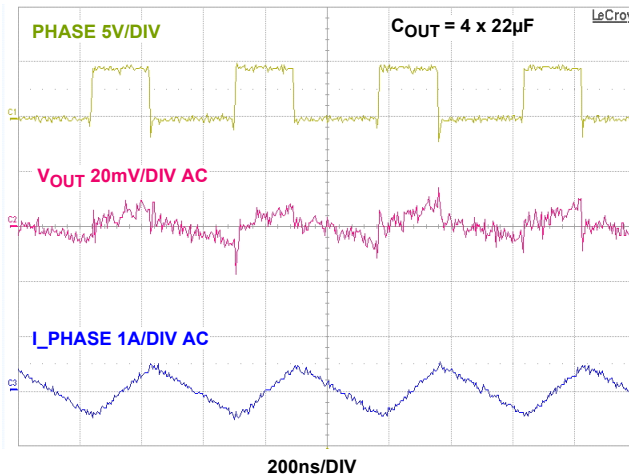


FIGURE 33. STEADY STATE AT 5A (SYNC = VDD)

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = V_{DD} = 5\text{V}$, $V_{OUT} = 1.8\text{V}$, $EN = V_{DD}$, $SYNC = V_{DD}$, $L = 0.68\mu\text{H}$, $f_{SW} = 2\text{MHz}$, $C_{IN} = 2 \times 22\mu\text{F}$, $C_{OUT} = 2 \times 22\mu\text{F}$, $I_{OUT} = 0\text{A to } 5\text{A}$. (Continued)

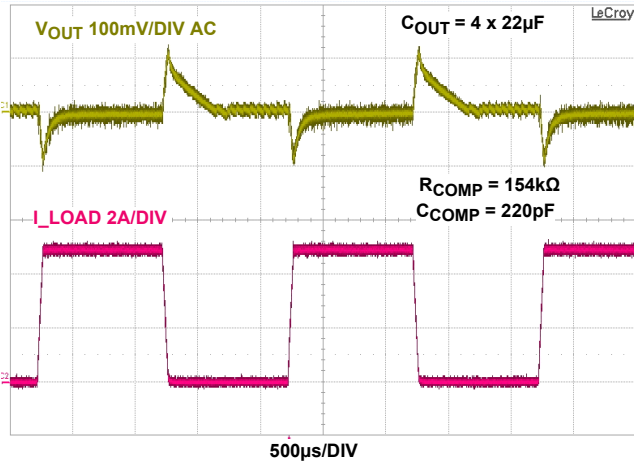


FIGURE 34. LOAD TRANSIENT 0A TO 5A; 0.5A/µs (SYNC = GND)

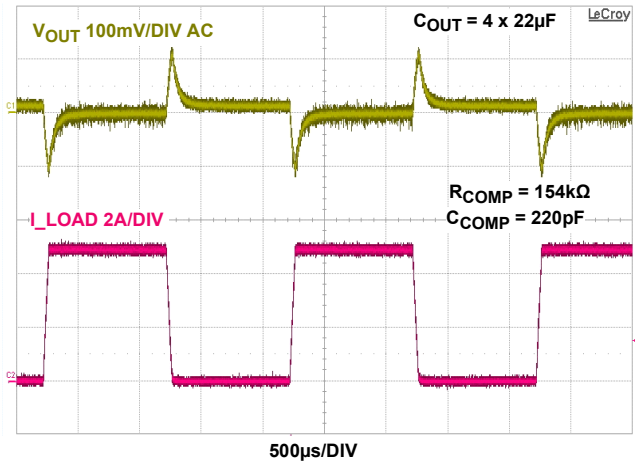


FIGURE 35. LOAD TRANSIENT 0A TO 5A; 0.5A/µs (SYNC = VDD)

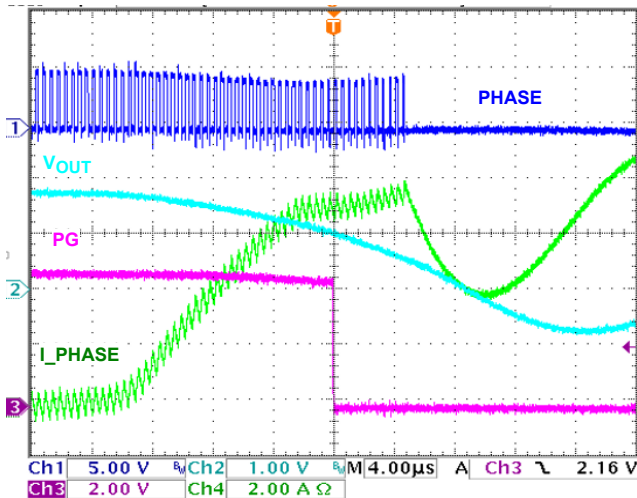


FIGURE 36. OUTPUT SHORT-CIRCUIT

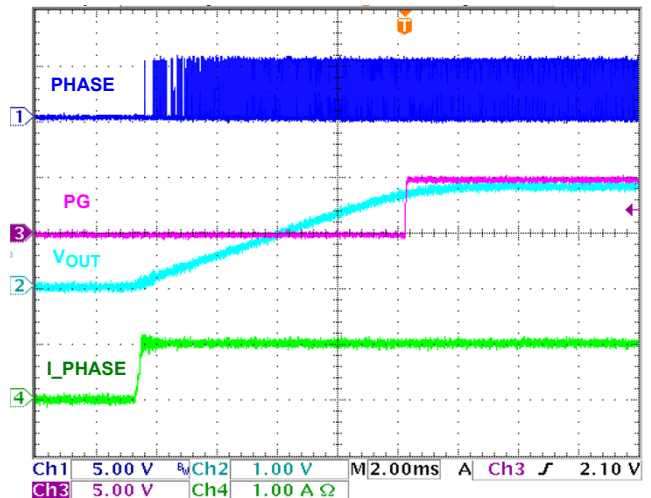


FIGURE 37. OUTPUT SHORT-CIRCUIT RECOVERY TO 1A LOAD

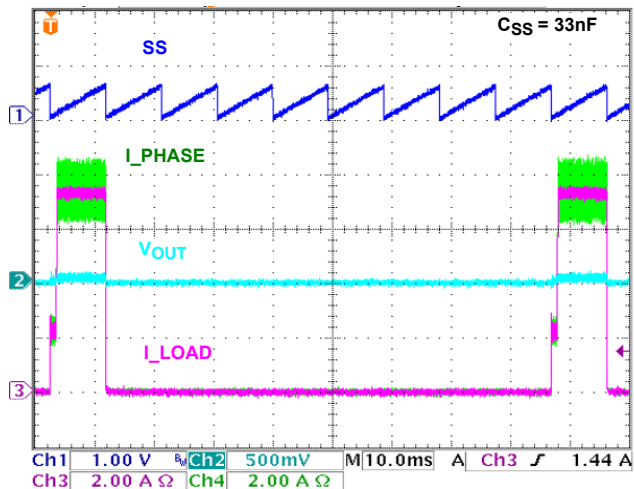


FIGURE 38. SHORT-CIRCUIT HICCUP WAVEFORM

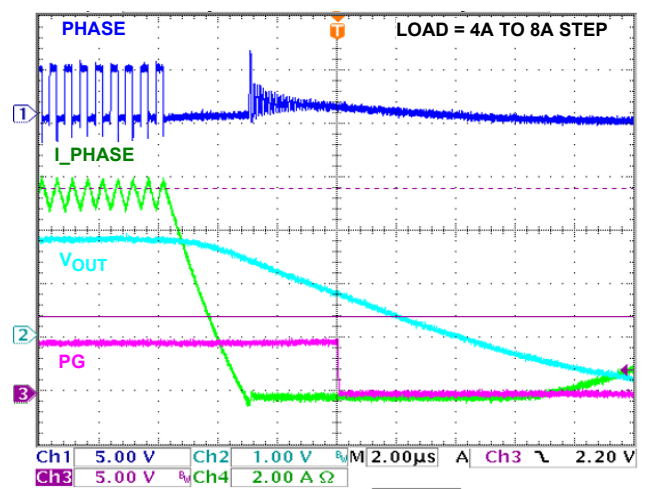


FIGURE 39. OVERCURRENT PROTECTION

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = V_{DD} = 5\text{V}$, $V_{OUT} = 1.8\text{V}$, $EN = V_{DD}$, $SYNC = V_{DD}$, $L = 0.68\mu\text{H}$, $f_{SW} = 2\text{MHz}$, $C_{IN} = 2 \times 22\mu\text{F}$, $C_{OUT} = 2 \times 22\mu\text{F}$, $I_{OUT} = 0\text{A to } 5\text{A}$. (Continued)

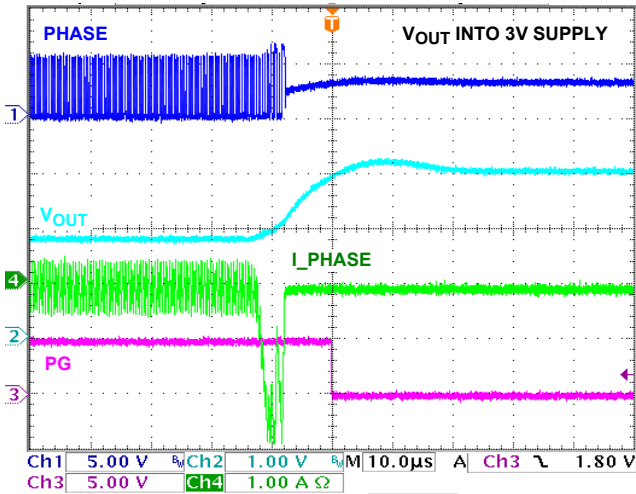


FIGURE 40. OVERVOLTAGE PROTECTION

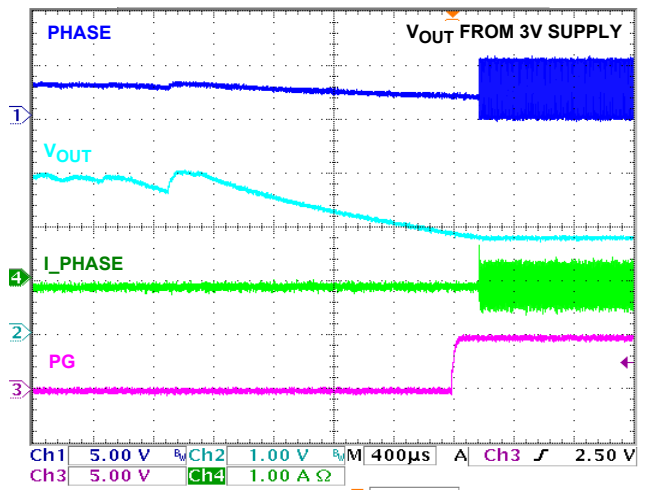


FIGURE 41. OVERVOLTAGE RECOVERY

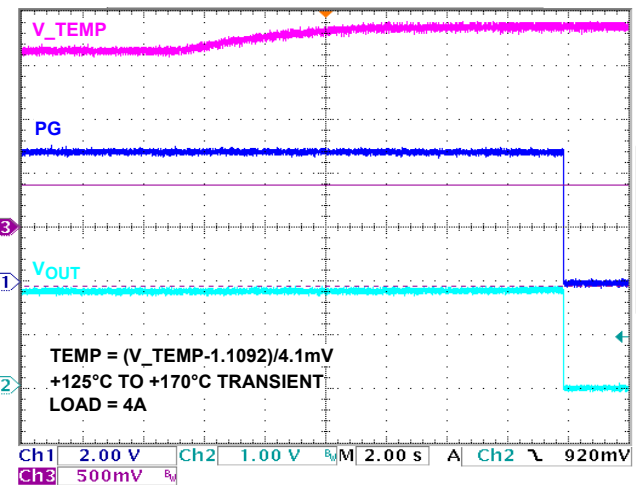


FIGURE 42. OVER-TEMPERATURE PROTECTION

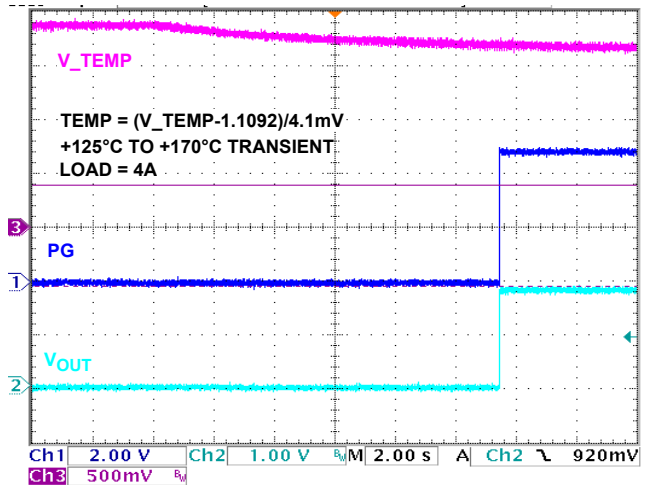


FIGURE 43. OVER-TEMPERATURE RECOVERY

Theory of Operation

The ISL78235 is a step-down switching regulator optimized for automotive point-of-load powered applications. The regulator operates at a 2MHz default switching frequency for high efficiency and smaller form factor while staying out of the AM frequency band. By connecting a resistor from FS to SGND, the operational frequency is adjustable in the range of 500kHz to 4MHz. At light load, the regulator reduces the switching frequency by operating in Pulse Frequency Modulation (PFM) mode, unless forced to operate in fixed frequency PWM mode, to minimize the switching loss and to maximize the battery life. The quiescent current when the output is not loaded is typically only 45µA. The supply current is typically only 3.8µA when the regulator is shut down.

PWM Control Scheme

Pulling the SYNC pin HI (>0.8V) forces the converter into PWM mode, regardless of output current, bypassing the PFM operation at light load. The ISL78235 employs the current-mode Pulse Width Modulation (PWM) control scheme for fast transient response and pulse-by-pulse current limiting (see [Figure 3 on page 3](#)). The current loop consists of the oscillator, the PWM comparator, current-sensing circuit and the slope compensation for the current loop stability. The slope compensation is 440mV/Ts (Ts is the switching period), which changes proportionally with frequency. The gain for the current-sensing circuit is typically 170mV/A. The control reference for the current loops comes from the Error Amplifier's (EAMP) output.

The PWM operation is initialized by the clock from the oscillator. The P-channel MOSFET is turned on at the beginning of a PWM cycle and the current in the MOSFET starts to ramp up. When the sum of the current amplifier CSA and the slope compensation reaches the control reference of the current loop, the PWM comparator COMP sends a signal to the PWM logic to turn off the PFET and turn on the N-channel MOSFET. The NFET stays on until the end of the PWM cycle. [Figure 44](#) shows the typical operating waveforms during the PWM operation. The dotted lines on V_{CSA} illustrate the sum of the slope compensation ramp and the current-sense amplifier's CSA output.

The output voltage is regulated by controlling the V_{EAMP} voltage to the current loop. The bandgap circuit outputs a 0.6V reference voltage to the voltage loop. The feedback signal comes from the VFB pin. The soft-start block only affects the operation during the start-up and is discussed separately. The error amplifier is a transconductance amplifier that converts the voltage error signal to a current output. The voltage loop is internally compensated with the 55pF and 100kΩ RC network. The maximum EAMP voltage output is precisely clamped to 2.5V.

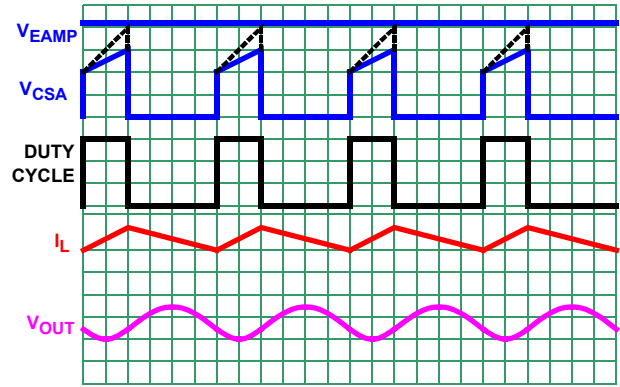


FIGURE 44. PWM OPERATION WAVEFORMS

SKIP Mode (PFM)

Pulling the SYNC pin low (<0.4V), forces the converter into PFM mode. The ISL78235 enters a pulse-skipping mode at light load to minimize the switching loss by reducing the switching frequency. [Figure 45 on page 17](#) illustrates the Skip mode operation. A zero-cross sensing circuit shown in [Figure 3 on page 3](#) monitors the NFET current for zero crossing. When 16 consecutive cycles are detected, the regulator enters the skip mode. During the sixteen detecting cycles, the current in the inductor is allowed to become negative. The counter is reset to zero when the current in any cycle does not cross zero.

Once the Skip mode is entered, the pulse modulation starts being controlled by the Skip comparator shown in [Figure 3 on page 3](#). Each pulse cycle is still synchronized by the PWM clock. The PFET is turned on at the clock's rising edge and turned off when the output is higher than 1.2% of the nominal regulation or when its current reaches the peak skip current limit value. Then, the inductor current is discharging to 0A and stays at zero (the internal clock is disabled), and the output voltage reduces gradually due to the load current discharging the output capacitor. When the output voltage drops to the nominal voltage, the PFET will be turned on again at the rising edge of the internal clock as it repeats the previous operations.

The regulator resumes normal PWM mode operation when the output voltage drops 1.2% below the nominal voltage.

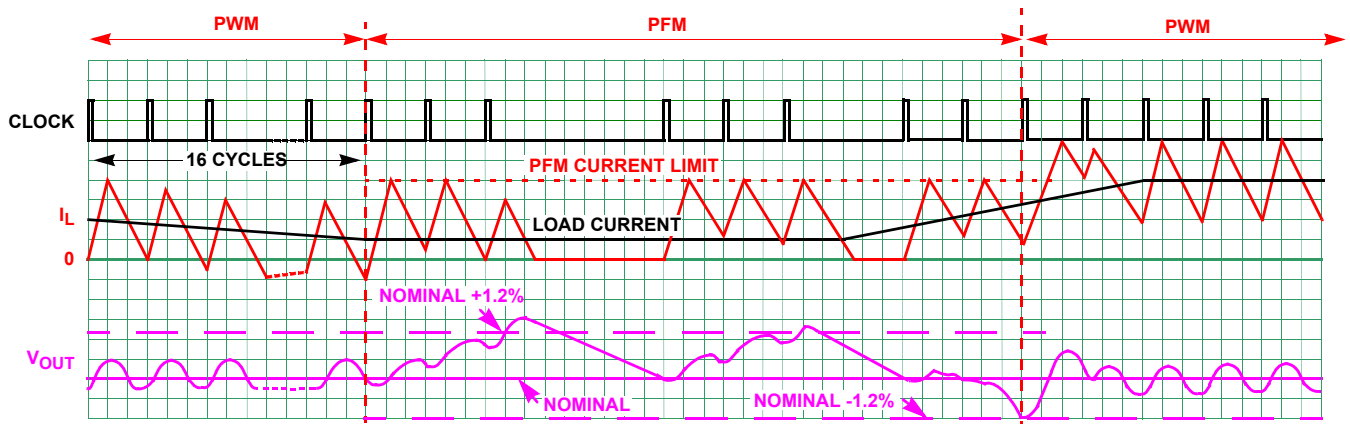


FIGURE 45. SKIP MODE OPERATION WAVEFORMS

Frequency Adjust

The frequency of operation is fixed at 2MHz when FS is tied to VIN. The switching frequency is adjustable in the range from 500kHz to 4MHz with a resistor from FS to SGND according to [Equation 1](#):

$$R_{FS}[k\Omega] = \frac{220 \cdot 10^3}{f_{OSC}[kHz]} - 14 \quad (\text{EQ. 1})$$

The ISL78235 also has frequency synchronization capability by connecting the SYNC pin to an external square pulse waveform. The frequency synchronization feature will synchronize the positive edge trigger and its switching frequency up to 4MHz. The synchronization positive pulse width should be 100ns or greater for proper operation. The minimum external SYNC frequency is half of the free running oscillator frequency (either the default 2MHz when FS tied to VIN or determined by the resistor from FS to SGND).

Overcurrent Protection

The overcurrent protection is realized by monitoring the CSA output with the OCP comparator, as shown in [Figure 3 on page 3](#). The current-sensing circuit has a gain of 170mV/A typical, from the PFET current to the CSA output. When the CSA output reaches the threshold, the OCP comparator is tripped to turn off the PFET immediately. The overcurrent function protects the switching converter from a shorted output by monitoring the current flowing through the upper MOSFET.

Upon detection of an overcurrent condition, the upper MOSFET is immediately turned off and is not turned on again until the next switching cycle. Upon detection of the initial overcurrent condition, the overcurrent fault counter is set to 1. If on the subsequent cycle another overcurrent condition is detected, the OC fault counter is incremented. If there are 17 sequential OC fault detections, the regulator is shut down under an overcurrent fault condition. An overcurrent fault condition results in the regulator attempting to restart in a hiccup mode within the delay of eight soft-start periods. At the end of the 8th soft-start wait period, the fault counters are reset and soft-start is attempted again. If the overcurrent condition goes away during the delay of 8 soft-start periods, the output will resume back into regulation point after hiccup mode expires.

Negative Current Protection

Similar to overcurrent, the negative current protection is realized by monitoring the current across the low-side NFET, as shown in [Figure 3 on page 3](#). When the valley point of the inductor current reaches -3A for 4 consecutive cycles, both PFET and NFET are off. A 100Ω discharge circuit in parallel to the NFET activates to discharge the output into regulation. The regulator resumes switching operation when output is within regulation. The regulator will be in PFM for 20μs before switching to PWM if necessary.

PG

PG is an open-drain output of a window comparator that continuously monitors the buck regulator output voltage. PG is actively held low when EN is low and during the buck regulator soft-start period. A 1ms delay after the soft-start period, PG becomes high impedance as long as the output voltage is within nominal regulation voltage set by VFB. When the voltage at FB pin drops 15% below 0.6V or rises above 0.8V, the ISL78235 pulls PG low. Any fault condition forces PG low until the fault condition is cleared and after soft-start completes. For logic level output voltages, connect an external pull-up resistor between PG and VIN. A 100kΩ resistor works well in most applications.

UVLO

When the input voltage is below the Undervoltage Lockout (UVLO) threshold (2.5V typical), the regulator is disabled.

Soft Start-Up

The soft start-up circuit reduces the inrush current during power-up. The soft-start block outputs a ramp reference to the input of the error amplifier. This voltage ramp limits the slew rate of inductor current as well as the output voltage, so that the output voltage rises in a controlled fashion. When VFB is less than 0.1V at the beginning of the soft-start, the switching frequency is reduced to 200kHz, so that the output can start-up smoothly at light load condition. During soft-start, the IC operates in the skip mode to support prebiased output condition.

Tie SS to SGND for internal soft-start (1ms typical). Connect a capacitor from SS to SGND to adjust the soft-start time. This capacitor, along with an internal 2.1μA current source, sets the soft-start interval of the converter, t_{SS} as shown by [Equation 2](#).

$$C_{SS}[\mu\text{F}] = 3.1 \cdot t_{SS}[\text{s}] \quad (\text{EQ. 2})$$

C_{SS} must be less than 33nF to insure proper soft-start reset after fault condition.

Enable

The Enable (EN) input allows the user to control the turning on or off of the regulator for purposes such as power-up sequencing or minimizing power dissipation when the output is not needed. When the regulator is enabled, there is typically a 600μs delay for waking up the bandgap reference and then the soft start-up begins.

Discharge Mode (Soft-Stop)

When a transition to shutdown mode occurs, (EN low or fault condition) or the V_{IN} UVLO is set, the output is discharged to GND through an internal 100Ω switch on the PHASE pin.

Power MOSFETs

The power MOSFETs are optimized for highest efficiency. The ON-resistance for the PFET is typically 35mΩ and the ON-resistance for the NFET is typically 11mΩ.

100% Duty Cycle

The ISL78235 features a 100% duty cycle operation to maximize the battery operation life and provide very low dropout down to the minimum operating voltage. When the battery voltage drops to a level that the ISL78235 can no longer maintain the regulation at the output, the regulator completely turns on the PFET. The maximum dropout voltage under the 100% duty cycle operation is the product of the load current and the ON-resistance of the PFET.

Thermal Shutdown

The ISL78235 has built-in over-temperature thermal protection. When the internal temperature reaches +150°C, the regulator completely shuts down. As the temperature drops to +125°C, the ISL78235 resumes operation after a soft-start cycle.

Applications Information

Output Inductor and Capacitor Selection

To consider steady state and transient operation, the ISL78235 typically uses a 0.33μH to 0.78μH output inductor. Higher or lower inductor values can be used to optimize the total converter system performance. For example, for a higher output voltage 3.3V application, in order to decrease the inductor current ripple and output voltage ripple, the output inductor value can be increased. It is recommended to set the ripple inductor current to approximately 30% of the maximum output current for optimized

performance. The inductor ripple current can be expressed as shown in [Equation 3](#):

$$\Delta I = \frac{V_{OUT} \cdot \left(1 - \frac{V_{OUT}}{V_{IN}}\right)}{L \cdot f_{SW}} \quad (\text{EQ. 3})$$

The inductor's saturation current rating needs to be larger than the positive peak current limit specified in the electrical specification table. The ISL78235 has a typical peak current limit of 7.5A. The inductor saturation current needs to be over 7.5A for proper operation.

The ISL78235 uses an internal compensation network for regulator stability and the output capacitor value is dependent on the output voltage. The recommended ceramic capacitors are low ESR X7R rated or better. The recommended minimum output capacitor values are shown in [Table 2 on page 6](#).

[Table 2](#), shows the minimum output capacitor value is given for the different output voltages to make sure that the whole converter system is stable. Additional output capacitance should be added for better performance in applications where high load transient or low output ripple is required. It is recommended to check the system level performance along with the simulation model.

Output Voltage Selection

The output voltage of the regulator is programmed with an external resistor divider that is used to scale the output voltage relative to the internal reference voltage (0.6V) and fed back to the inverting input of the error amplifier FB pin (see [Figure 46](#)).

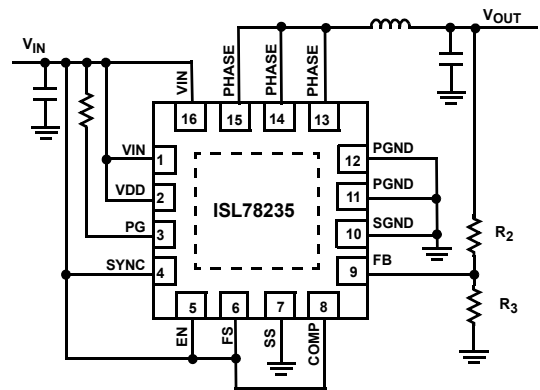


FIGURE 46. PROGRAMMING OUTPUT VOLTAGE WITH R_2 AND R_3

The output voltage programming resistor R_2 (from V_{OUT} to FB) will depend on the value chosen for the feedback resistor and the desired output voltage of the regulator. The value for the feedback resistor, R_3 (from FB to GND), is typically between 10kΩ and 100kΩ. R_2 is chosen as shown in [Equation 4](#). Where $V_{FB} = 0.6\text{V}$ and V_{OUT} is the output voltage.

$$R_2 = R_3 \left(\frac{V_{OUT}}{V_{FB}} - 1 \right) \quad (\text{EQ. 4})$$

There is a leakage current from VIN to PHASE. It is recommended to preload the output with 10µA minimum for accurate output voltage. For improved loop stability performance, add 10pF to 22pF in parallel with R₂. Check loop analysis before use in application. See “[Loop Compensation Design](#)” for more information.

Input Capacitor Selection

The main functions for the input capacitor are to provide decoupling of the parasitic inductance and to provide a filtering function to prevent the switching current flowing back to the input rail. Two 22µF low ESR X7R rated ceramic capacitors in parallel with a 0.1µF high frequency decoupling capacitor placed very close to the VIN/VDD and SGND/PGND pins is a good starting point for the input capacitor selection.

Loop Compensation Design

When COMP is not connected to VDD, the COMP pin is active for external loop compensation. The ISL78235 uses constant frequency peak current mode control architecture to achieve a fast loop transient response. An accurate current-sensing circuit in parallel with the upper MOSFET is used for peak current control signal and overcurrent protection. The inductor is not considered as a state variable since its peak current is constant and the system becomes a single order system. It is much easier to design a type II compensator to stabilize the loop than to implement voltage mode control. Peak current mode control has an inherent input voltage feed-forward function to achieve good line regulation. [Figure 47](#) shows the small signal model of the synchronous buck regulator.

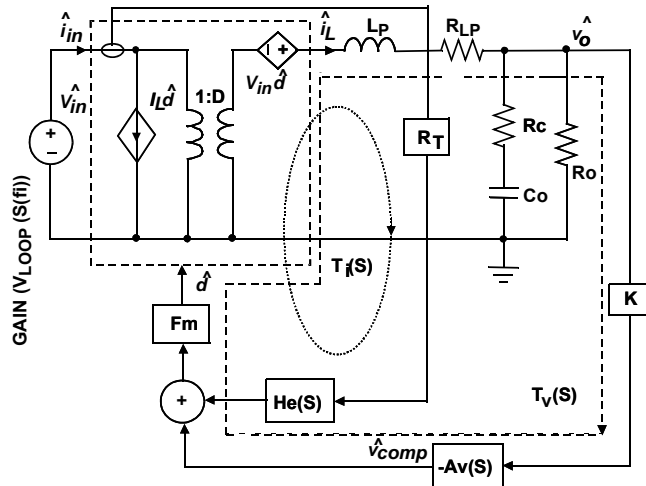


FIGURE 47. SMALL SIGNAL MODEL OF SYNCHRONOUS BUCK REGULATOR

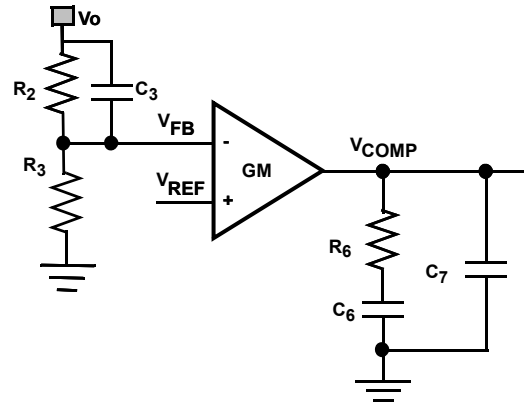


FIGURE 48. TYPE II COMPENSATOR

[Figure 48](#) shows the type II compensator and its transfer function is expressed as [Equation 5](#):

$$A_v(S) = \frac{\hat{v}_{comp}}{\hat{v}_{FB}} = \frac{GM \cdot R_3}{(C_6 + C_7) \cdot (R_2 + R_3)} \frac{\left(1 + \frac{S}{\omega_{cz1}}\right) \left(1 + \frac{S}{\omega_{cz2}}\right)}{S \left(1 + \frac{S}{\omega_{cp1}}\right) \left(1 + \frac{S}{\omega_{cp2}}\right)} \quad (EQ. 5)$$

Where,

$$\omega_{cz1} = \frac{1}{R_6 C_6}, \quad \omega_{cz2} = \frac{1}{R_2 C_3}, \quad \omega_{cp1} = \frac{C_6 + C_7}{R_6 C_6 C_7}, \quad \omega_{cp2} = \frac{R_2 + R_3}{C_3 R_2 R_3}$$

Compensator design goal:

- High DC gain
- Choose Loop bandwidth $f_c \sim 100\text{kHz}$ or less
- Gain margin: >10dB
- Phase margin: >40°

The compensator design procedure is as follows:

The loop gain at crossover frequency of f_c has a unity gain. Therefore, the compensator resistance R_6 is determined by [Equation 6](#).

$$R_6 = \frac{2\pi f_c V_o C_o R_t}{GM \cdot V_{FB}} = 13.7 \times 10^3 \cdot f_c V_o C_o \quad (EQ. 6)$$

Where GM is the transconductance, g_m , of the voltage error amplifier and R_t is the gain of the current sense amplifier. Compensator capacitors C_6 and C_7 are given by [Equation 7](#).

$$C_6 = \frac{R_o C_o}{R_6} = \frac{V_o C_o}{I_o R_6}, \quad C_7 = \max\left(\frac{R_c C_o}{R_6}, \frac{1}{\pi f_s R_6}\right) \quad (EQ. 7)$$

Put one compensator pole at zero frequency to achieve high DC gain, and put another compensator pole at either ESR zero frequency or half switching frequency, whichever is lower in [Equation 7](#). An optional zero can boost the phase margin. ω_{cz2} is a zero due to R_2 and C_3 .

Put compensator zero 2 to 5 times f_c :

$$C_3 = \frac{1}{\pi f_c R_2} \quad (EQ. 8)$$

Example: $V_{IN} = 5V$, $V_O = 1.8V$, $I_O = 5A$, $f_{SW} = 2MHz$, $R_2 = 200k\Omega$, $R_3 = 100k\Omega$, $C_O = 2 \times 22\mu F / 10m\Omega$, $L = 0.68\mu H$, $f_c = 100kHz$, then compensator resistance R_6 :

$$R_6 = 13.7 \times 10^3 \cdot 100kHz \cdot 1.8V \cdot 44\mu F = 108k\Omega \quad (EQ. 9)$$

It is acceptable to use 107kΩ as the closest standard value for R_6 .

$$C_6 = \frac{1.8V \cdot 44\mu F}{5A \cdot 107k\Omega} = 148pF \quad (EQ. 10)$$

$$C_7 = \max\left(\frac{10m\Omega \cdot 44\mu F}{107k\Omega}, \frac{1}{\pi \cdot 2MHz(107k\Omega)}\right) = (4.1pF, 1.5pF) \quad (EQ. 11)$$

It is also acceptable to use the closest standard values for C_6 and C_7 . There is approximately 3pF parasitic capacitance from V_{COMP} to GND. Therefore, C_7 is optional. Use $C_6 = 150pF$ and $C_7 = OPEN$.

$$C_3 = \frac{1}{\pi \cdot 100kHz \cdot 200k\Omega} = 16pF \quad (EQ. 12)$$

Use $C_3 = 10pF$. Note that C_3 may increase the loop bandwidth from previous estimated value. Figure 49 shows the simulated voltage loop gain. It is shown that it has a 120kHz loop bandwidth with a 58° phase margin and 8dB gain margin. It may be more desirable to achieve an increased phase and gain margin. This can be accomplished by lowering R_6 by 10% to 20%.

PCB Layout Recommendation

The PCB layout is a very important converter design step to make sure the designed converter works well. For the ISL78235 the power loop is composed of the output inductor L_O , the output capacitor C_O , the PHASE pins and the PGND pin. It is necessary to make the power loop as small as possible and the connecting traces among them should be direct, short and wide. The switching node of the converter, the PHASE pins and the traces connected to the node are very noisy, so keep the voltage feedback trace away from these noisy traces. The input capacitor should be placed as close as possible to the VIN pin. The ground of the input and output capacitors should be connected as close as possible. The heat of the IC is mainly dissipated through the thermal pad. Maximizing the copper area connected to the thermal pad is preferable. In addition, a solid ground plane is helpful for better EMI performance. Refer to TB389 for via placement on the copper area of the PCB underneath the thermal pad for optimum thermal performance.

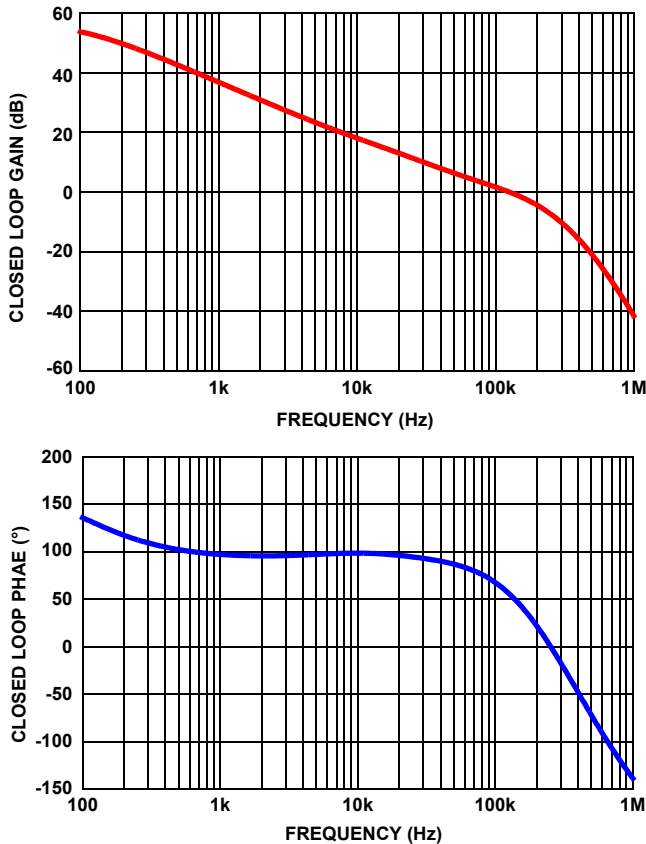


FIGURE 49. SIMULATED LOOP GAIN AND PHASE

Revision History

The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please visit our website to make sure you have the latest revision.

| DATE | REVISION | CHANGE |
|--------------------|----------|---|
| September 22, 2016 | FN8713.6 | Corrected shifted connection in Block Diagram on page 3. |
| April 1, 2016 | FN8713.5 | Updated Figure 10 title on page 9. |
| December 11, 2015 | FN8713.4 | Added a new User Guide to Related Literature section on page 1. Added ISL78235EVAL2Z to the ordering information table on page 5. Added table1 on page 5. |
| November 10, 2015 | FN8713.3 | Added 5x5mmWFQFN information throughout datasheet. Removed "Li-Ion Battery Powered devices" application bullet from page 1. Updated Note 1 on page 5 from "Add "-T*" suffix for tape and reel." to "Add "-T" suffix for 6k unit or "-T7A" suffix for 250 unit tape and reel options." On page 8, removed the test condition " $T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$ " for the I_{NLIMIT} specifications. On page 8, added " $T_A = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$ " to the test conditions of the Transresistance specification. In "PWM Control Scheme" on page 16 (last sentence) corrected a typo by changing "1.6V" to "2.5V". Updated the "PCB Layout Recommendation" section. |
| July 1, 2015 | FN8713.2 | Figures 15 through 28 changed "CSS = 33nF" to "SS = GND". |
| February 20, 2015 | FN8713.1 | Electrical Spec table, Oscillator section on page 8: Changed nominal switching frequency minimum from 1700kHz to 1730kHz. |
| February 3, 2015 | FN8713.0 | Initial Release |

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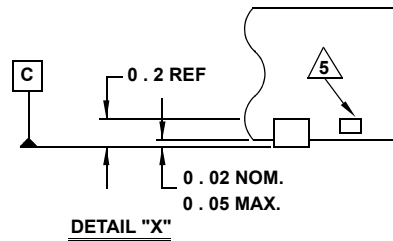
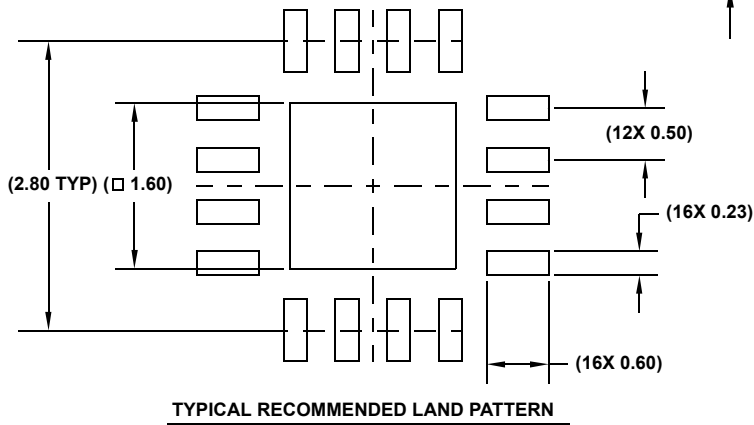
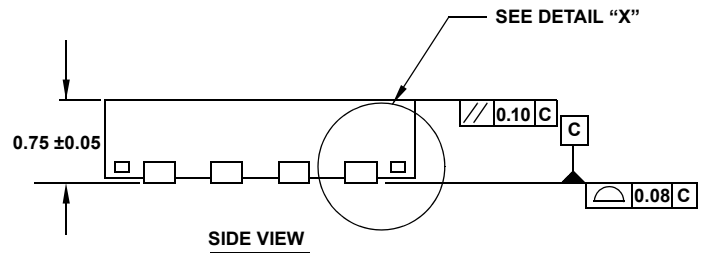
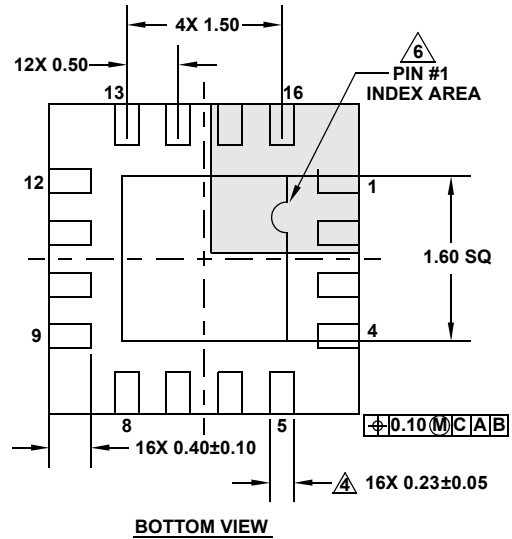
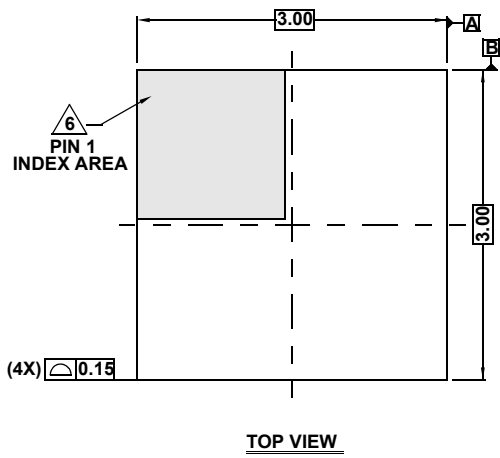
Package Outline Drawing

For the most recent package outline drawing, see [L16.3x3D](#).

L16.3x3D

16 LEAD THIN QUAD FLAT NO-LEAD PLASTIC PACKAGE

Rev 0, 3/10



NOTES:

1. Dimensions are in millimeters.
Dimensions in () for Reference Only.
2. Dimensioning and tolerancing conform to ASME Y14.5m-1994.
3. Unless otherwise specified, tolerance: Decimal ± 0.05
4. Dimension applies to the metallized terminal and is measured between 0.15mm and 0.25mm from the terminal tip.
5. Tiebar shown (if present) is a non-functional feature.
6. The configuration of the pin #1 identifier is optional, but must be located within the zone indicated. The pin #1 identifier may be either a mold or mark feature.
7. JEDEC reference drawing: MO-220 WEED.

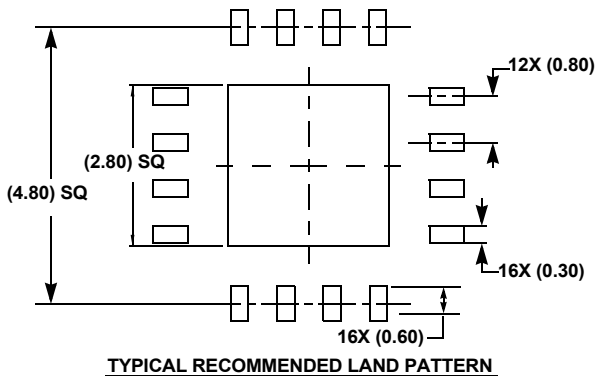
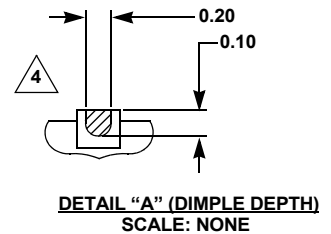
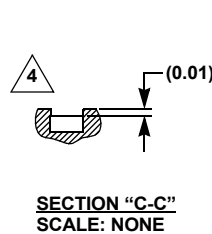
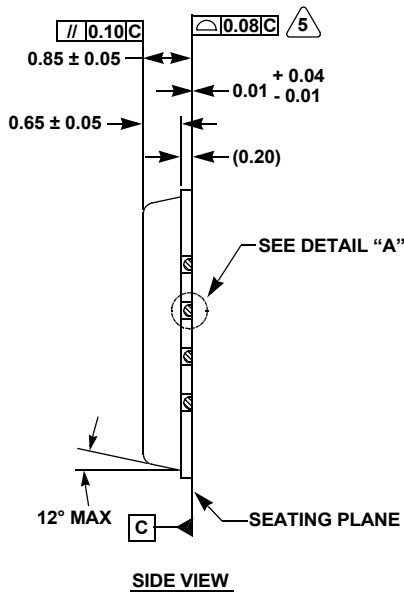
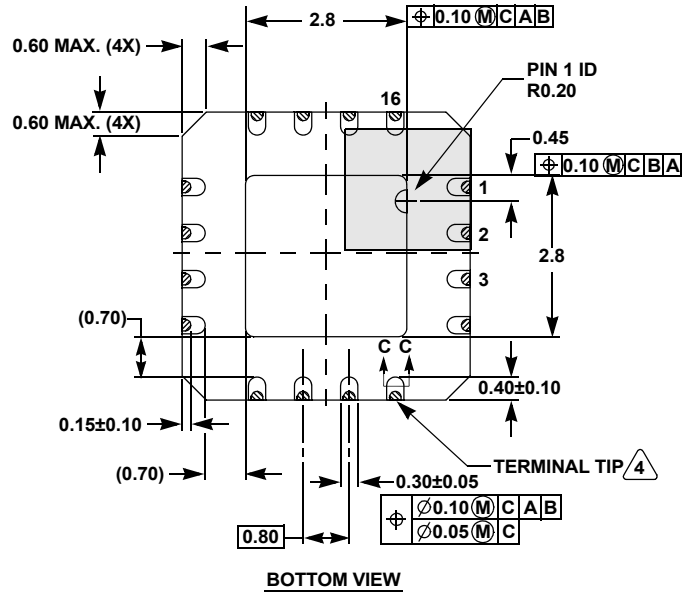
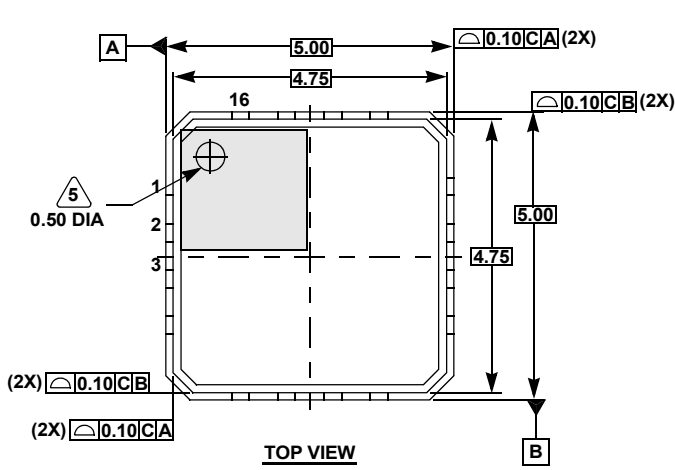
Package Outline Drawing

For the most recent package outline drawing, see [L16.5x5D](#).

L16.5x5D

16 LEAD QUAD FLAT NO-LEAD PLASTIC PACKAGE (PUNCH QFN WITH WETTABLE FLANK)

Rev 2, 5/14



NOTES:

- Dimensions are in millimeters. Dimensions in () are for Reference Only.
- Dimensioning and tolerancing conform to AMSE Y14.5m-1994.
- Unless otherwise specified, tolerance: Decimal ± 0.05
- Dimension applies to the plated terminal and is measured between 0.15mm and 0.30mm from the terminal tip.
- The configuration of the pin #1 identifier is optional, but must be located within the zone indicated. The pin #1 identifier may be either a mold or mark feature.
- Reference document: JEDEC M0220.